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Screwworm Eradication Data System (SEDS) Applications Program Documentation

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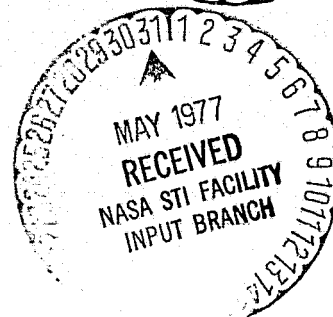
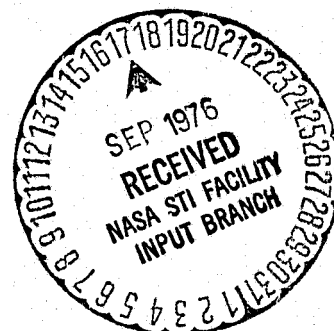
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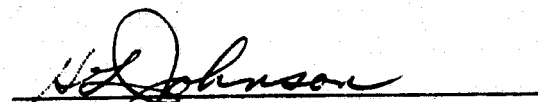


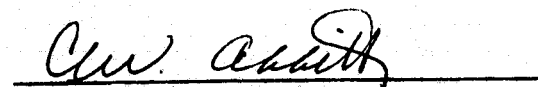
SCREWORM ERADICATION DATA SYSTEM (SEDS)
APPLICATIONS PROGRAM DOCUMENTATION

Contract NAS 9-1261
DRL LI No. 2.20

Prepared for
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FOREWORD

This document is provided by the Space Information Systems Operation (SISO) in accordance with the requirements of Task Order (TO) P-6Q00 as established under modification No. 201 of Contract NAS 9-1261, Schedule V, and DRL Line Item 2.20.

Parts III and IV of this document will be forthcoming under separate covers at a later date. They will deal with, respectively, the program operator's guide, and the SEDS program listings.

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SECTION 1

INTRODUCTION

1.1 SCREWORM ERADICATION DATA SYSTEM (SEDS) GENERAL DESCRIPTION

The primary purpose of this system is to convert National Oceanic and Atmospheric Administration (NOAA) satellite data, which is in analog tape form, into output data products. These products are used by investigators in determining optimum areas for airdrops of sterile screwworm flies over Mexico. The output product of SEDS takes the form of imagery data film slides showing Mexico and the lower southwest portion of the United States. The area covered is shown by the reference grid in figure 1-1.

The area analog preprocessing phase of the SEDS task is covered in Part I of this series. The application phase processing covered in this document (Part II) starts with the first 9-track computer-compatible tape (CCT of the NOAA data. Exclusive of the preprocessing phase, SEDS is composed of six major components or programs, which are pseudo-independent in that each is a standalone program, but each requires input and/or output data from the others. The four SEDS applications programs which are used daily during production are the SEDS Engineering Unit Conversion Program (SEU), the SEDS Registration Program (SRE), the Rainfall Algorithm Program (RAP, also called Data Base Update Sequence No. 1), and the Screwworm Survival Program (SSP, also called Data Base Update Sequence No. 2). The other two major programs are the Display and Product Generator (DPG) and Character Density Plot (CDP) Programs; these are executed on as as-needed basis. These six programs are described in Sections 2-7, respectively.

These six major components of SEDS are further linked by the System Resident Program, described in paragraph 1.2. Termination of one program, return to the system, and call-up of another program is done without program reinitialization.

The SEDS application hardware configuration is shown by figure 1-2. Except for system initialization, all user program control is via the VT05 display/keyboard. The user displays on the VT05 may be hardcopied out to the line printer by request at any time. For user convenience during production, remote VT05 and display terminals are available for program control and monitoring.

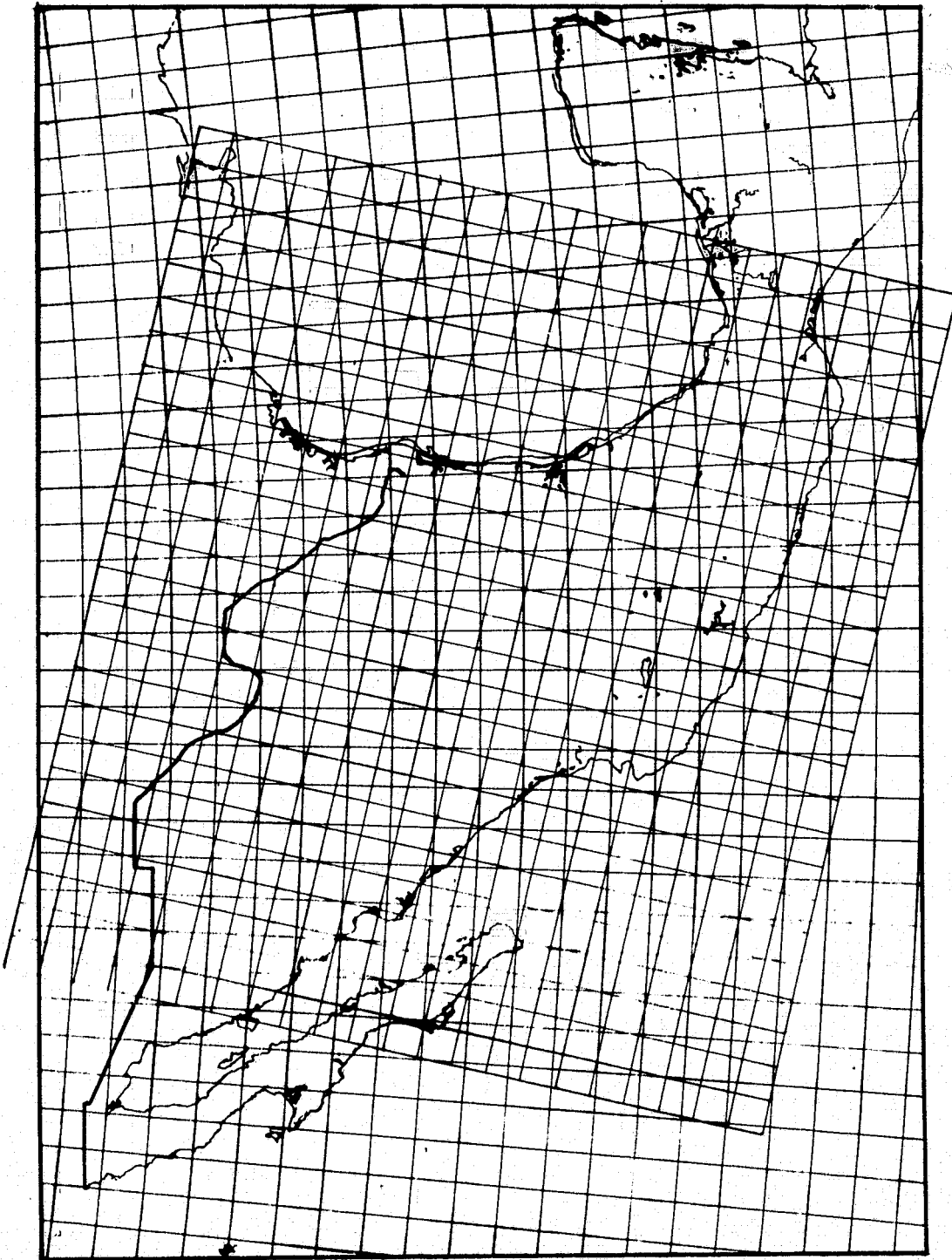


Figure 1-1 SEDS Reference Grid

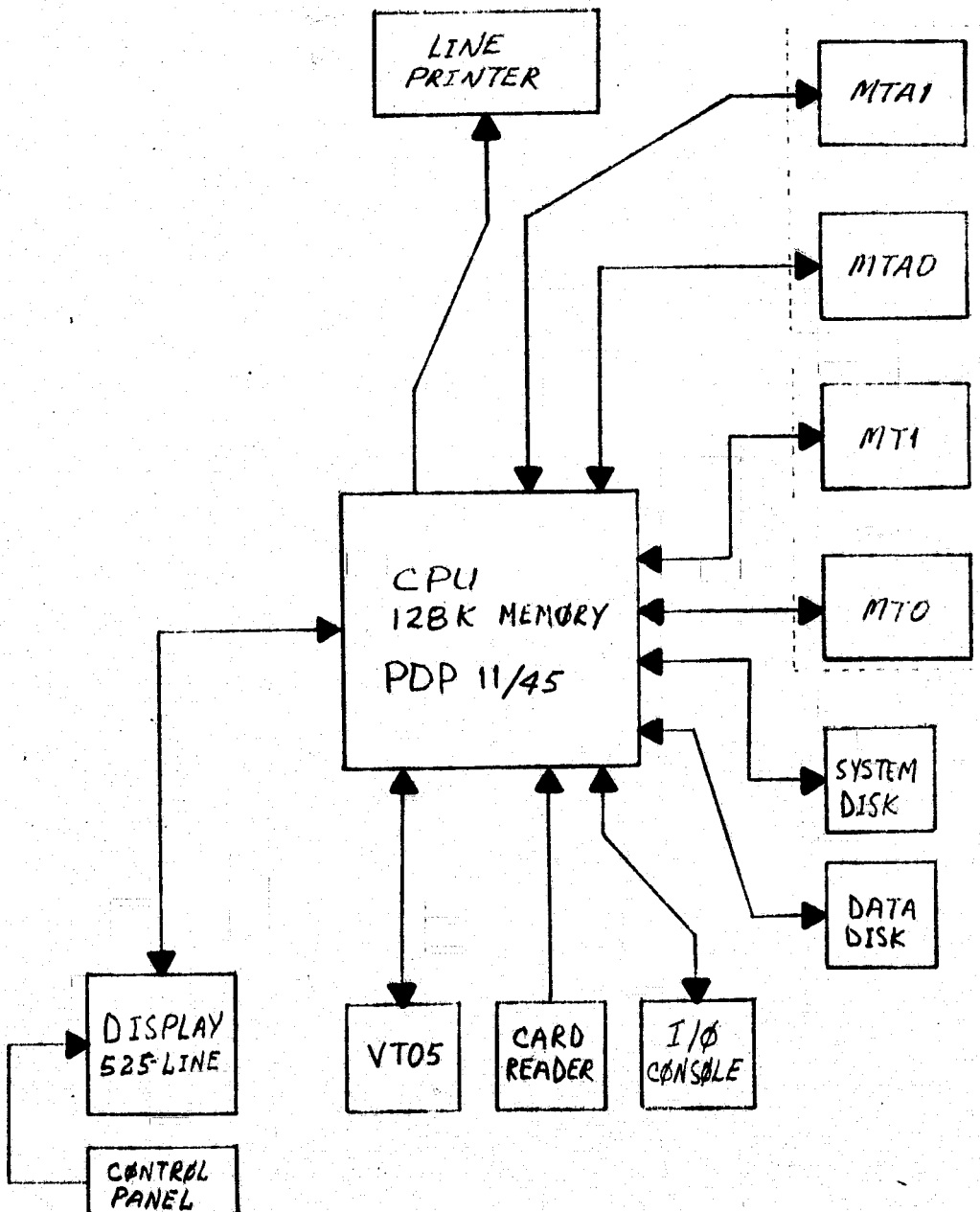


Figure 1-2 SEDS Application Hardware Configuration

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The independence of each program in SEDS is due to the function that it performs. Data from the NOAA satellite is processed daily through SEDS. Two passes per day are processed through the registration phase; one is the day pass with both visible and infrared (IR) channels, and the other is the night pass with IR data only. The day IR and visible data and night IR data is registered, compressed 4-to-1 in both picture element (PIXEL) and scan directions, and made disk-resident. Compression is done by selecting every fourth PIXEL of every fourth scan line, thereby compressing a 2500-PIXEL-by-2200-scan registered image into a 625-PIXEL-by-550-scan image. Then a single run is made through Data Base Update Sequences No. 1 and No. 2. The output product tapes suitable for film processing are isothermal day and night (OID/OIN), rainfall (ORC) and screwworm (OWC), as shown by figure 1-3. These image maps will be generated using false color assignments.

In summary, the initial digitized tape from the preprocessing phase is input to SEU for conversion of the IR data from engineering units (EU's) to temperature units. The visible data is not converted. The output tapes of SEU serve as input to SRE, which resections the data, using linear remapping coefficients, and registers it to the SEDS reference grid. When both day and night passes have been processed through registration and the data is compressed and disk-resident, the two data base update sequences are run. Data Base Update Sequence No. 1 (RAP) uses the registered day IR and visible data on disk in a two-channel "maximum likelihood" cloud classifier to detect cloud-contaminated day IR data. It then uses the registered day and night IR data on disk from SRE, and inputs ground truth and background image data to calculate a new daily mean air temperature for each PIXEL. The output tape from RAP, containing daily mean air temperature (DMAT) and crop moisture index (CMI) data, serves as one of the inputs to Data Update Sequence No. 2 (SSP). During data base initialization, the new update (SBC) tape is the only input to SSP. Each day's data base is generated and output to the new data base (OBC) tape. For the second (and subsequent) day's processing, the previous day's data base is input as the old OBC tape. The data in the data base is maintained in computational form as means, running averages, and accumulative values. The data base update is accomplished on an element-by-element basis. The several product images relating to the growth potential of the screwworm fly are output to the screwworm OWC tape.

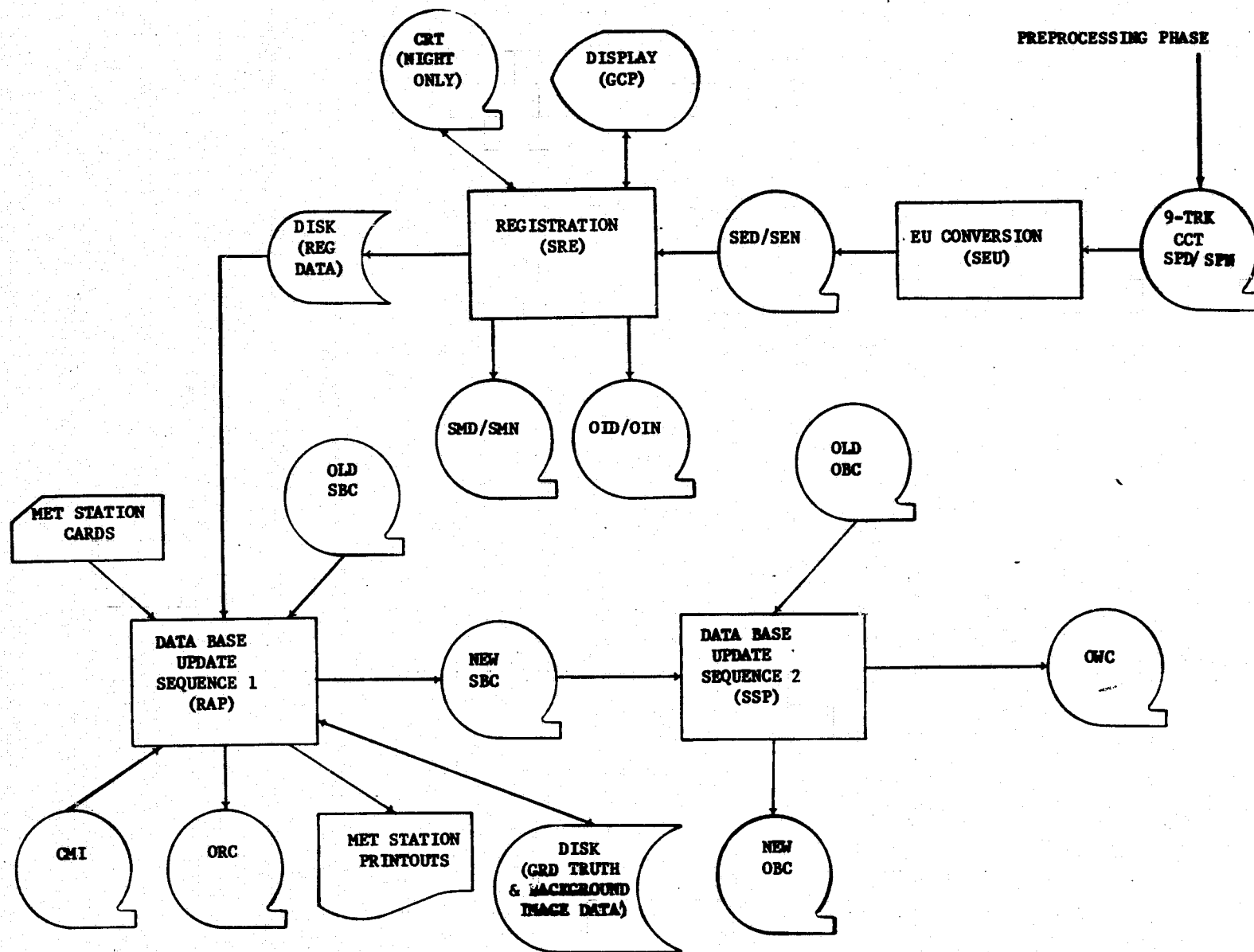


Figure 1-3 SEDS Data Flow

Details of program operations are found in the current SEDS Operations Manual (Part III of this series). However, SEDS initialization is accomplished through input via card reader of the cards shown by figure 1-4. The initial VT05 display reflecting system initialization is shown by figure 1-5.

1.2 ABBREVIATIONS

Letter abbreviations used in naming tapes described in this document are listed in table 1-1 for easy reference.

\$EOD

\$RUN SEDS

#/EXIT

\$RUN FLOADc100,100!

\$JOB SEDS QUICKYc210,050!

END-OF-FILE (0,1,6,7,8,9,11,12 MULTI-PUNCH IN COL. 1)

Figure 1-4 SEDS Initialization Card Deck

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SCREW WORM
ERADICATION
DATA
SYSTEM

PROGRAM CALL LETTERS

* * * * *

SYSTEM IDENTIFICATION

SEU = SEDS FU CONVERSION
SRE = SEDS REGISTRATION
RAP = RAINFALL ALGORITHM PROGRAM
SSP = SCREW WORM SURVIVAL PROGRAM
CDP = CHARACTER DENSITY PROGRAM
DPG = DISPLAY & PRODUCT GENERATOR

SEDS PRODUCTION DISK
VERSION 01
01-MAR-75

Figure 1-5 SEDS Initial VT05 Display

JSC-10019
Part II

TABLE 1-1
SEDS TAPE IDENTIFICATIONS

LETTER DESIGNATIONS

B	DATA BASE TAPE	N	NIGHT PASS TAPE
C	COMBINED TAPE	O	OUTPUT PRODUCT TAPE
D	DAY PASS TAPE	P	PCM TAPE
E	ENGINEERING UNIT TAPE	R	RAINFALL TAPE
I	ISOTHERMAL TAPE	S	UPDATE (INTERMEDIATE) TAPE
M	MAP TAPE	W	SCREWWORM TAPE

TAPE ID'S AND NAMES

CMI	CROP MOISTURE INDEX	SBC	UPDATE
CRT	REGISTERED INTERMEDIATE	SED	EU DAY
OBC	DATA BASE	SEN	EU NIGHT
OID	ISOTHERMAL DAY	SMD	REGISTERED DAY
OIN	ISOTHERMAL NIGHT	SMN	REGISTERED NIGHT
ORC	RAINFALL	SPD	RAW PCM DAY
OWC	SCREWWORM	SPN	RAW PCM NIGHT

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1.3 SEDS RESIDENT PROGRAM

1.3.1 General Program Characteristics. The principal function of this software is process control of the six major application programs in SEDS previously mentioned. The SEDS Resident Program remains in core from system initialization to termination. It occupies the area of core memory between disk operating system (DOS) and the active application program as described by figure 1-6. The functions performed by this program are program initialization, name recognition of the application program as requested by the user, program memory mapping, and program termination.

The SEDS Resident Program is composed of the application program controller, system routines for memory overlay and segmentation, and system service routines for interrupt handling. These components are linked together to form the program module named SEDS.LDA. This is the portion of SEDS which gets control when the card deck, shown by figure 1-4, is input during start of system initialization. The subcomponents which comprise this module consist of the following:

SEDS	CCTH*	NTRAND
GLOBS	CCTH2*	NTRAND
VTIN*	IDHIV*	CVP
VTOUT*	CCTCOM	SETEMT
SPCMD*	SEGRES	FATAL
VTOSH*	SEGOUT	FTNLIB

Those subcomponents marked with an asterisk are newly developed system software for SEDS, and are detailed in Section 8. (Part II) of this specification. The remaining software components listed above consist of standard DOS software or software previously developed by SISO for the PDP 11/45.

1.3.2 Program Flow Chart. See eight pages following figure 1-6.

1.3.3 Listings. See Part IV of this document published under separate cover.

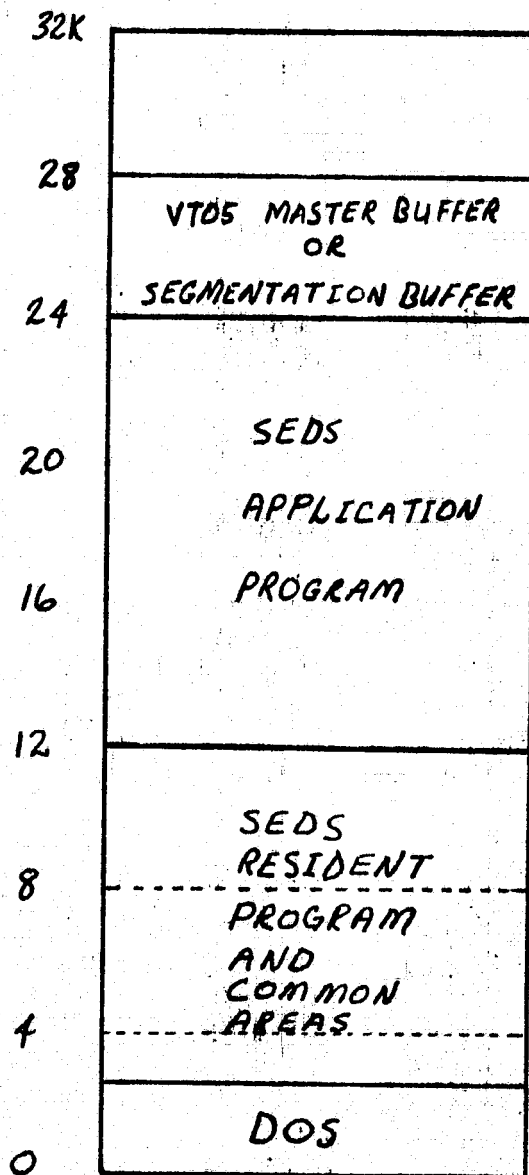
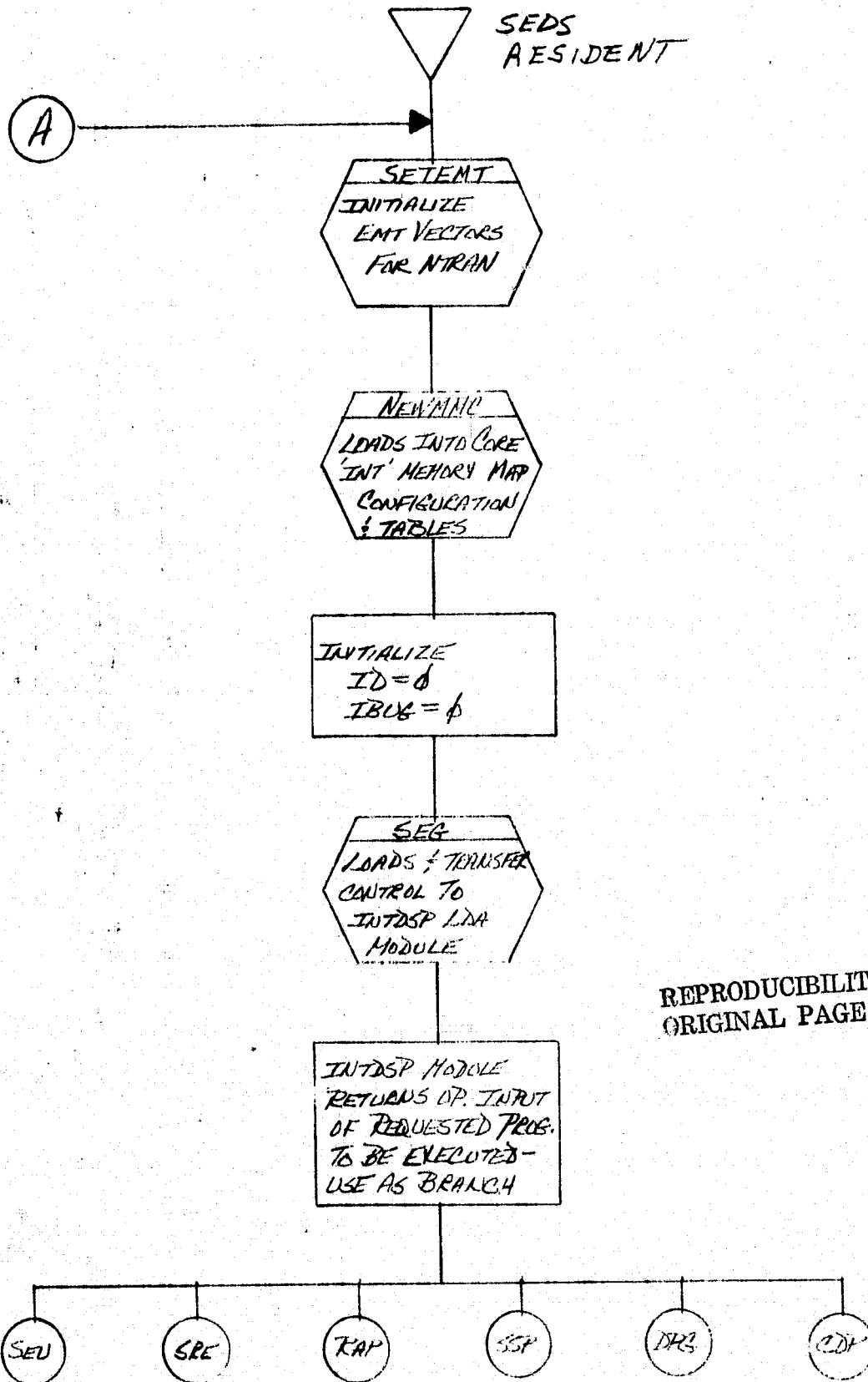
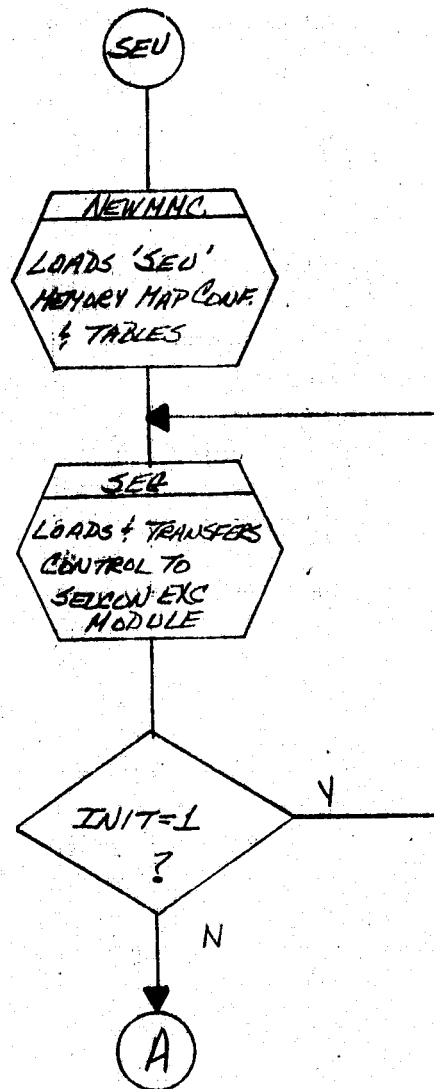
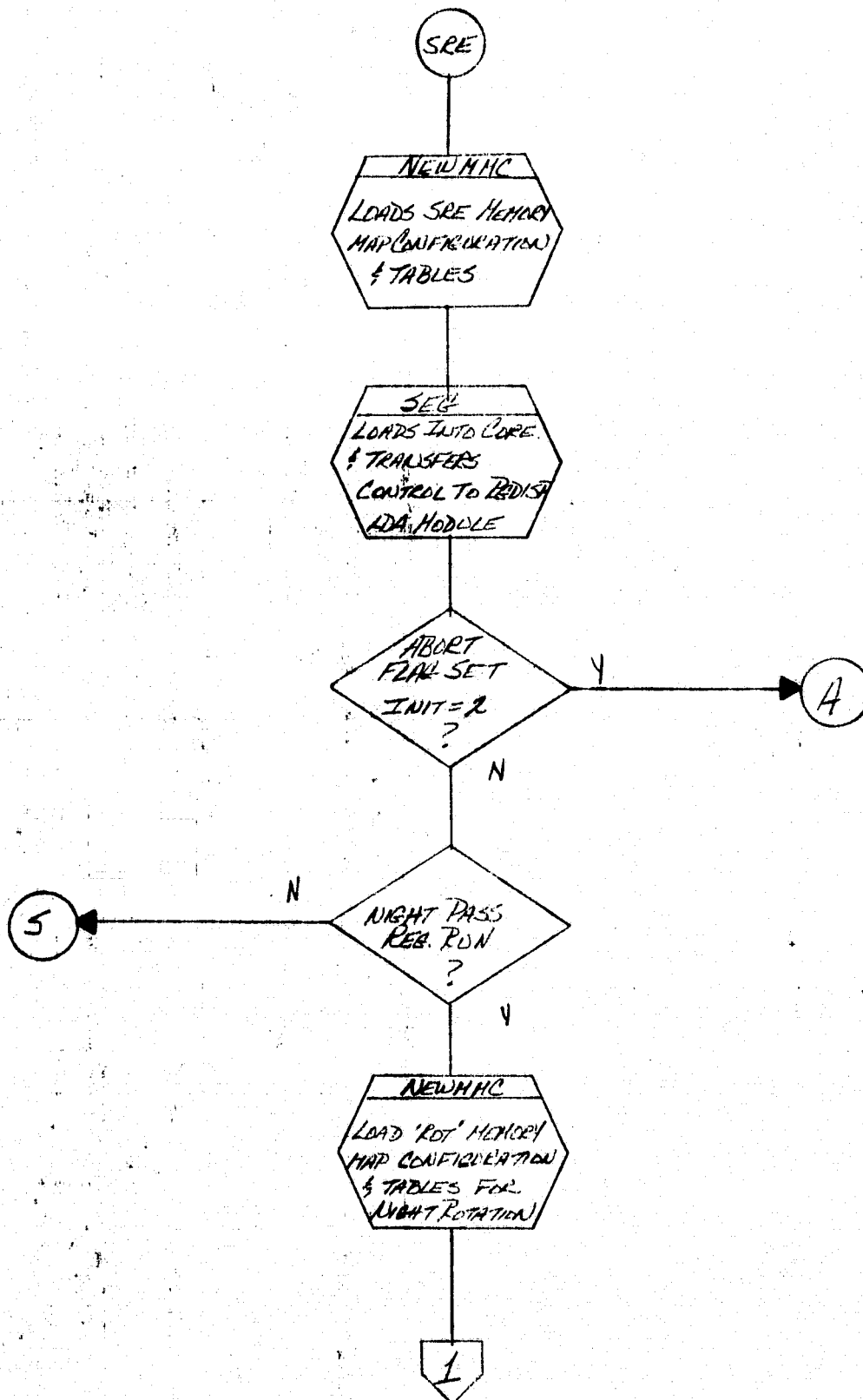


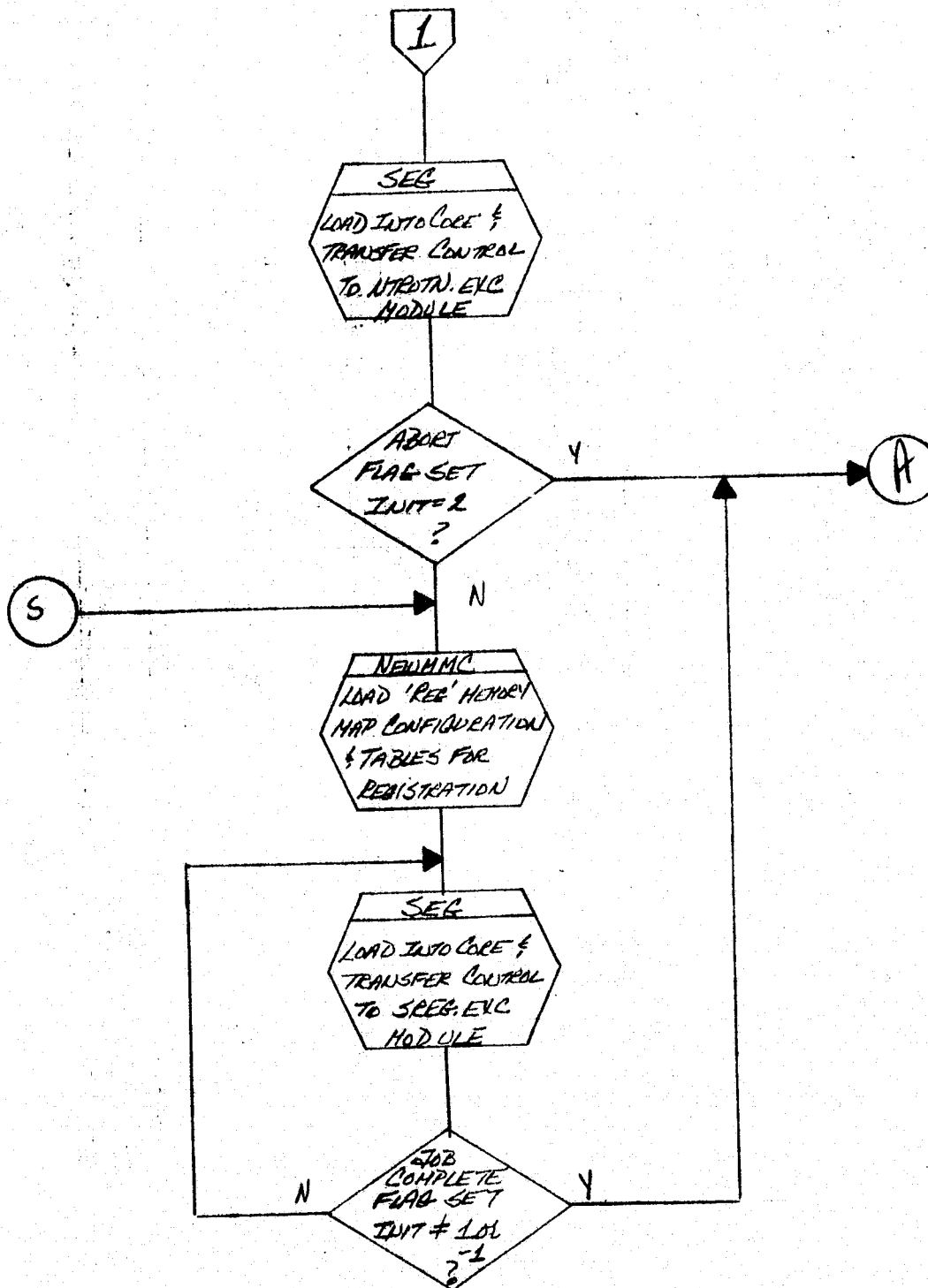
Figure 1-6 SEDS Storage Allocation



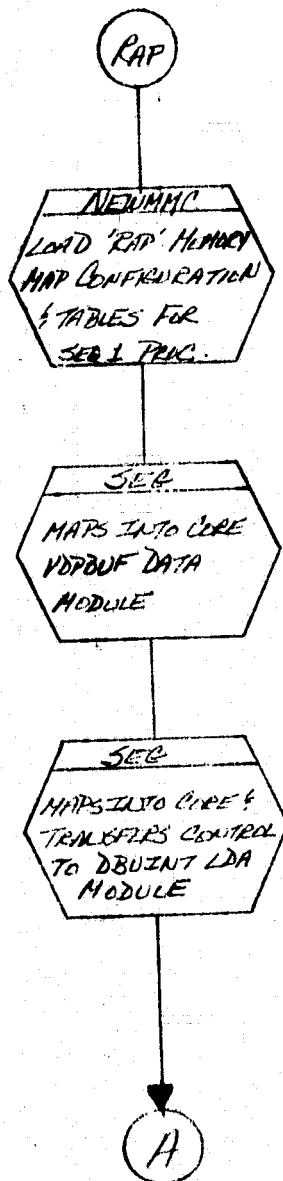
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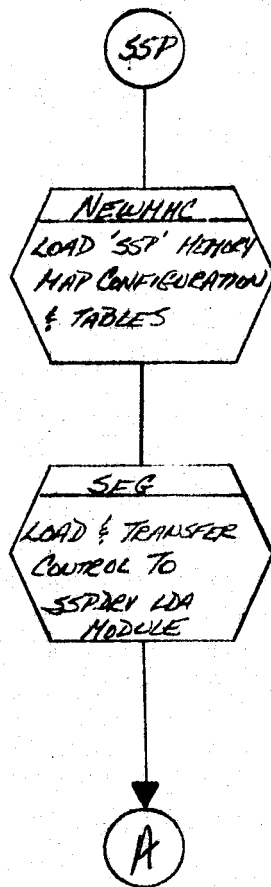


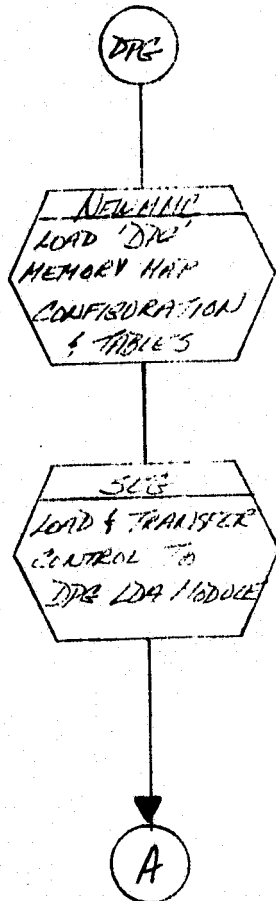


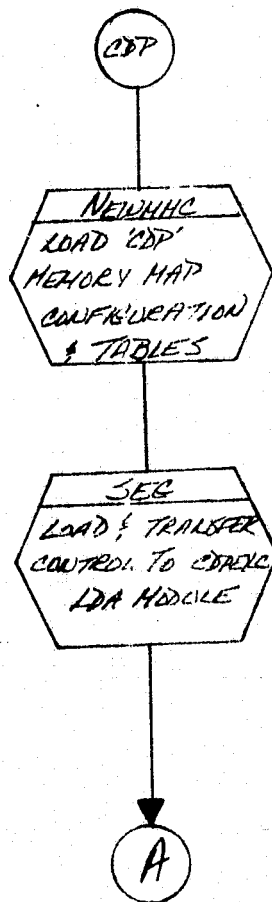


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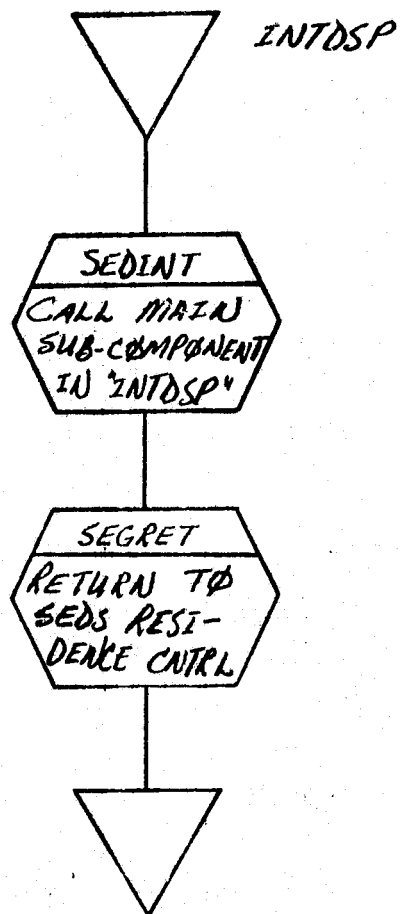
1.4 INITIALIZATION MODULE (INTDSP)

1.4.1 Subcomponent Descriptions. The SEDS initialization module is called by the SEDS Resident Program each time control is returned there for data processing change or termination. The module is composed of several subcomponents. The major subcomponent, SEDINT, is responsible for the set up of interrupt vectors, emulator trap (EMT) vectors, and device priority levels. Following call up of the initial VT05 display (see figure 1-5), control is given to the user to enter the program call letters to proceed. The subcomponents which comprise the INTDSP module consist of the following:

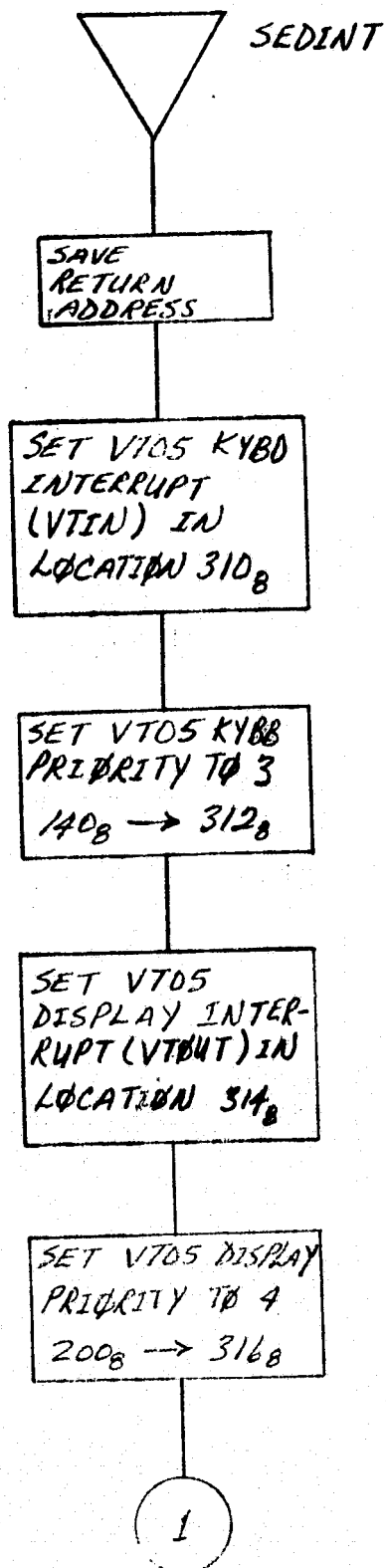
- "INTDSP"
- SEDINT
- DISKIO
- GDUMP
- VTLINK
- FTNLIB

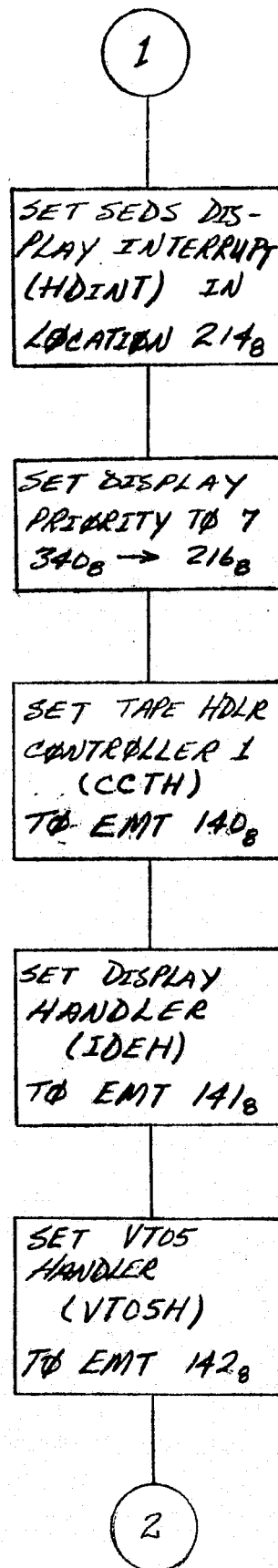
1.4.2 Flow Chart. See next nine pages.

1.4.3 Listings. See Part IV of this document, published under separate cover.

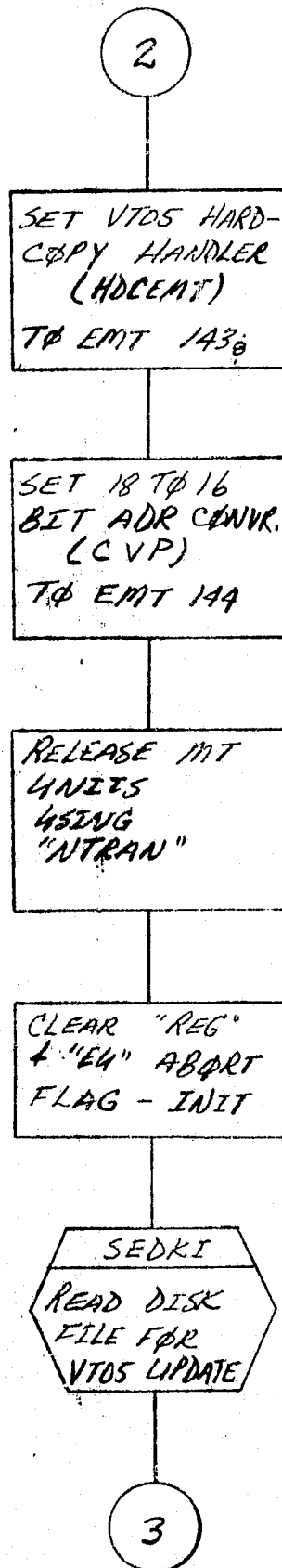


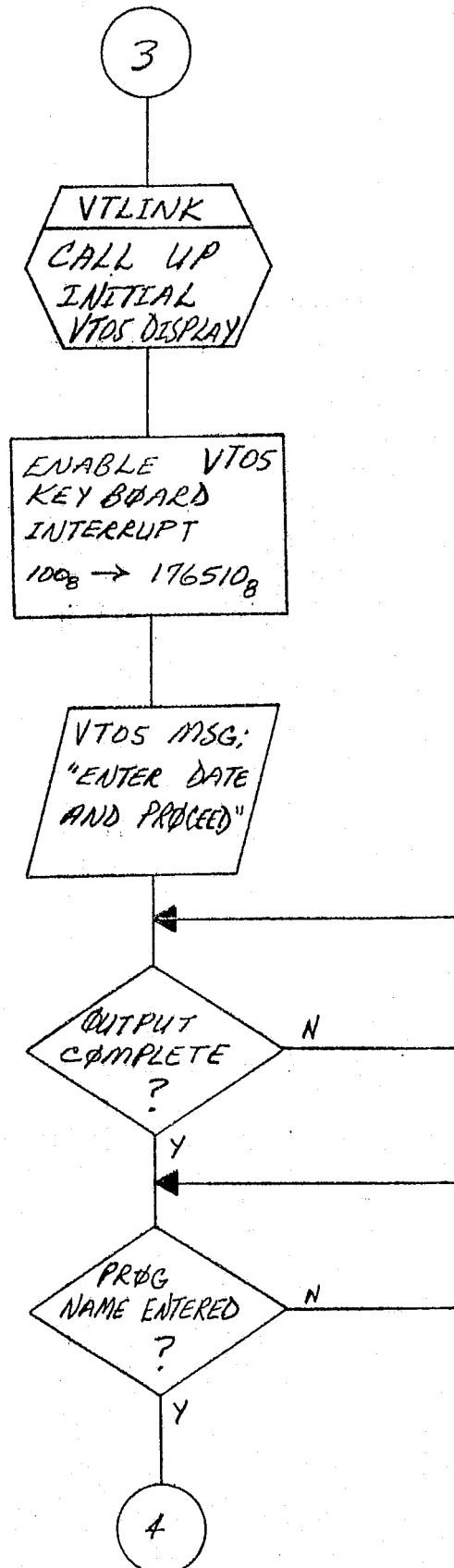
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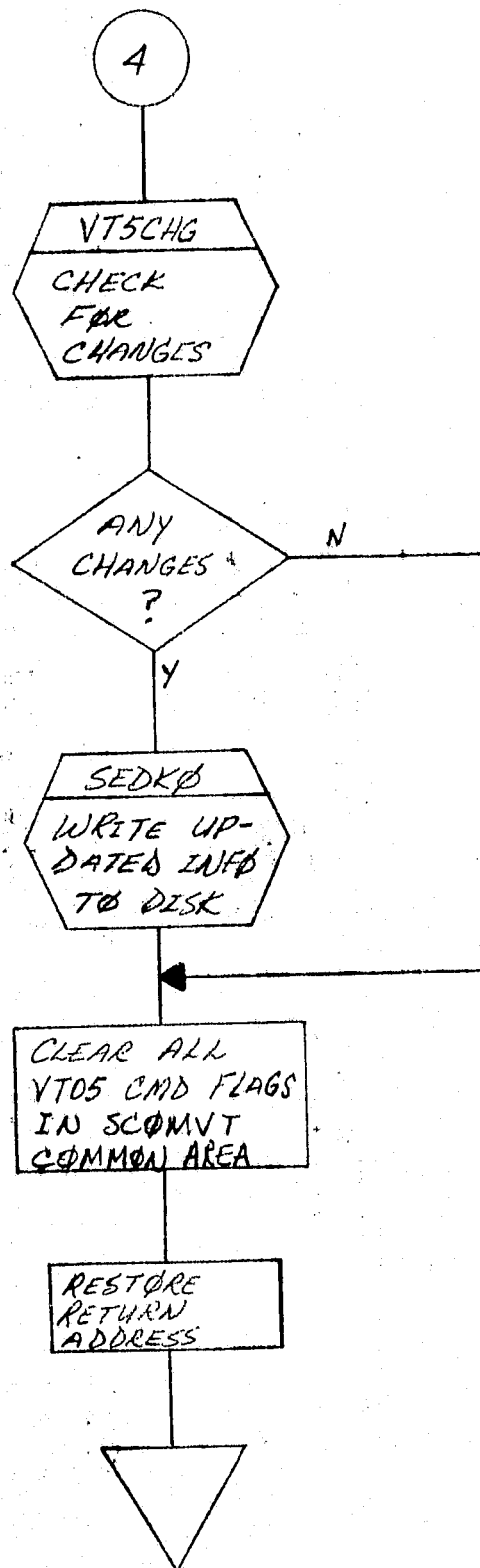




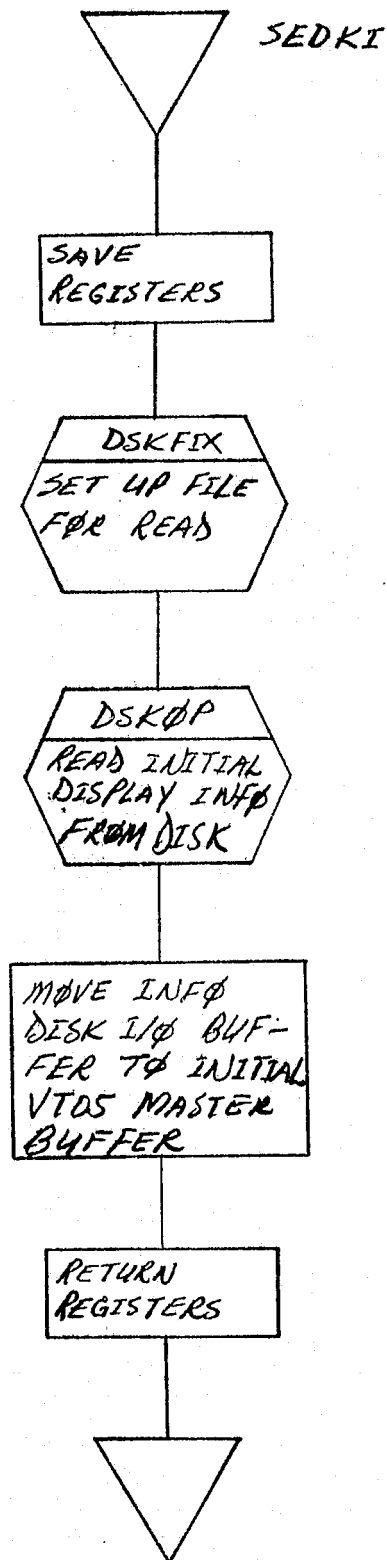
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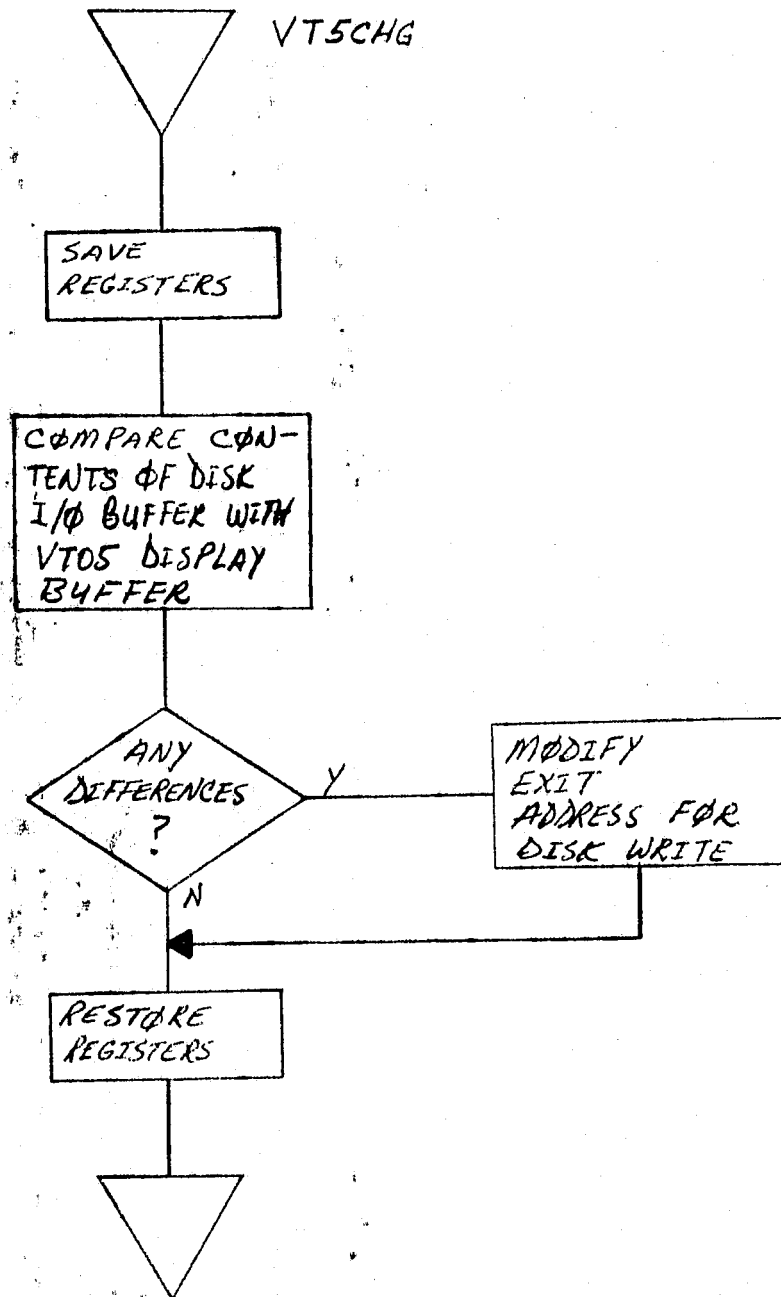




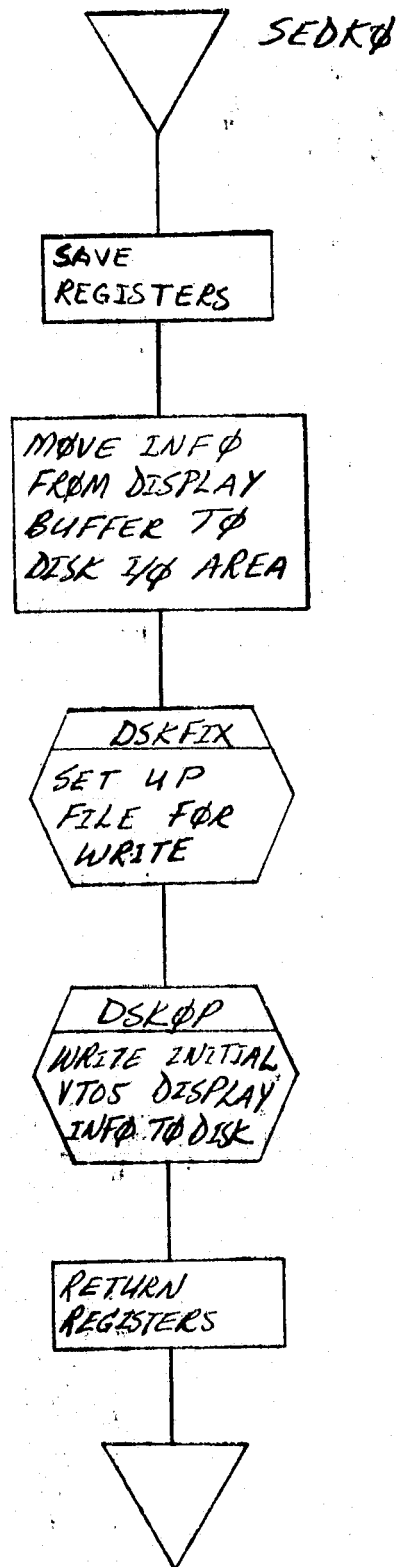
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SECTION 2

SEDS ENGINEERING UNIT CONVERSION PROGRAM (SEU)

2.1 GENERAL PROGRAM CHARACTERISTICS

The SEU Program is responsible for the function of taking raw pulse code modulated (PCM) data from an edited 9-track computer compatible tape (CCT) and converting the infrared (IR) channel data to corrected temperature units. This involves a calibration of the data and a correction for atmospheric attenuation. This results in a "best estimated surface temperature" in degrees Kelvin ($^{\circ}\text{K}$). The visible light (VIS) channel data is not processed since it is not required in radiometric units for the purposes of its use. The final output product of SEU is a 9-track CCT containing the resultant IR temperature units and the unaltered VIS data. This EU processed tape will be used as input to the registration processing phase SRE (discussed in paragraph 3.1).

The SEU Program consists of five major computer program components (CPC). Each major CPC is a separate load module that must be mapped into core and given program control by the memory segmentation module, SEG. This is due to the PDP 11/45 limitation of 32K core available at any one time for access. Figure 2-1 illustrates the SEU Program layout and the CPC's.

- A. SEUCON. This is the controlling EU executive CPC load module. Calls to the other four CPC's are made from this CPC. The actual EU processing and conversion of the data is performed in SEUCON.
- B. EUDISP. Performs the initialization tasks of EU and interfaces with the operator.
- C. HEDREC. Processes the PCM input tape header and builds the EU output tape header.
- D. CALDAT. Responsible for retrieving from disk storage the calibration data file used by SEUCON in processing the data.
- E. ERRDSP. Responsible for displaying of error conditions and operator advisories during job execution.

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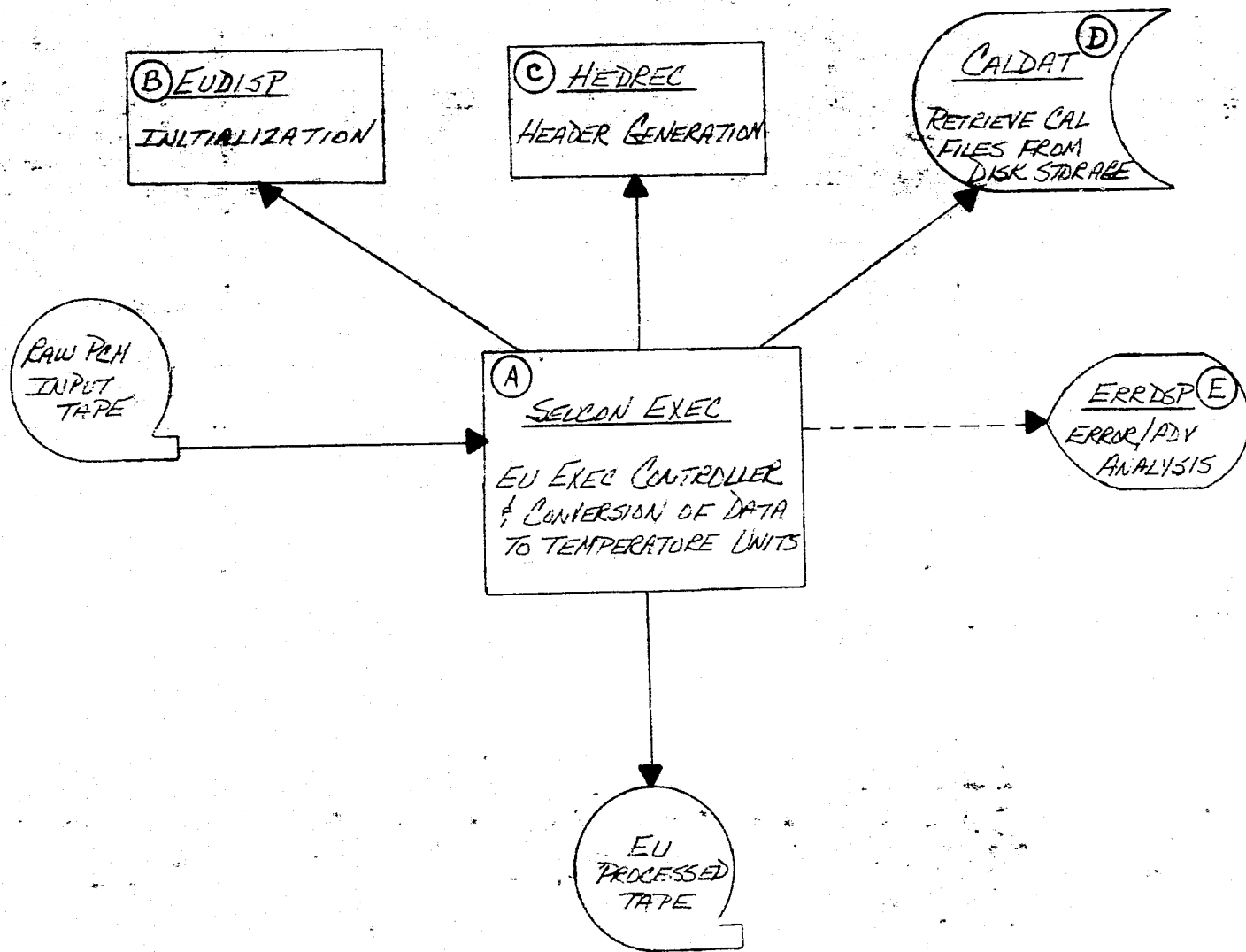


Figure 2-1 SEU Program Basic Layout

The following paragraphs explain in detail the functions of the CPC's, the storage allocations, program timing and sequencing, and data base characteristics of the SEU Program.

2.1.1 Functional Allocations. As stated in the SISO-TN734, the Functional Requirements Document, the purpose of the SEU Program is to convert raw PCM IR data to temperature units and output the corrected IR temperature and VIS data to a 9-track CCT. This includes calibration of each IR band data and correction for atmospheric attenuation using a function of the scan angle (θ) measured from the center of the video scan line. The conversions from PCM count to temperature units are accomplished by a table-lookup scheme.

The calibration of the IR data is done first. This means that the 8-bit digital IR video voltage samples (V) on the preprocessed tape are converted into 16-bit energy values E(V). This conversion needs to be done for each picture element (pixel) in a scan, so an E(V) table is set up just prior to processing a scan containing E(V) values for V, ranging from 0 to 255. Calibration data is extracted from the scan to be used in calculating the E(V)'s. This table must be recalculated for each scan, based on the calibration data received with each scan line of IR image data. The exact calculations are explained in paragraph 2.2.1.

The input PCM count is used as an index into the E(V) table to pick up its corresponding E(V) energy value. The next step in the processing is to take the "calibrated" E(V) values and calculate a "corrected" energy value E_c . This involves a table lookup in a table of 16-bit values computed by an offline FORTRAN program. The 16-bit corrected energy values are then converted to an 8-bit encoded temperature value (T) by means of a second table lookup. The result is a surface temperature expressed in degrees Kelvin. The IR temperature units and VIS data (as taken from the PCM preprocessed tape) are written out to 9-track CCT, creating the EU tape.

SEUCON is the CPC responsible for all of the above data conversion and processing requirements. The other four CPC's (EUDISP, HEDREC, CALDAT, and ERRDSP) are more or less service components called in from the SEUCON CPC. They are responsible for job initialization, error displaying and tape header generation.

2.1.2 Program Flow Chart. See figure 2-2 for a general flow of the SEU Program and its main functions.

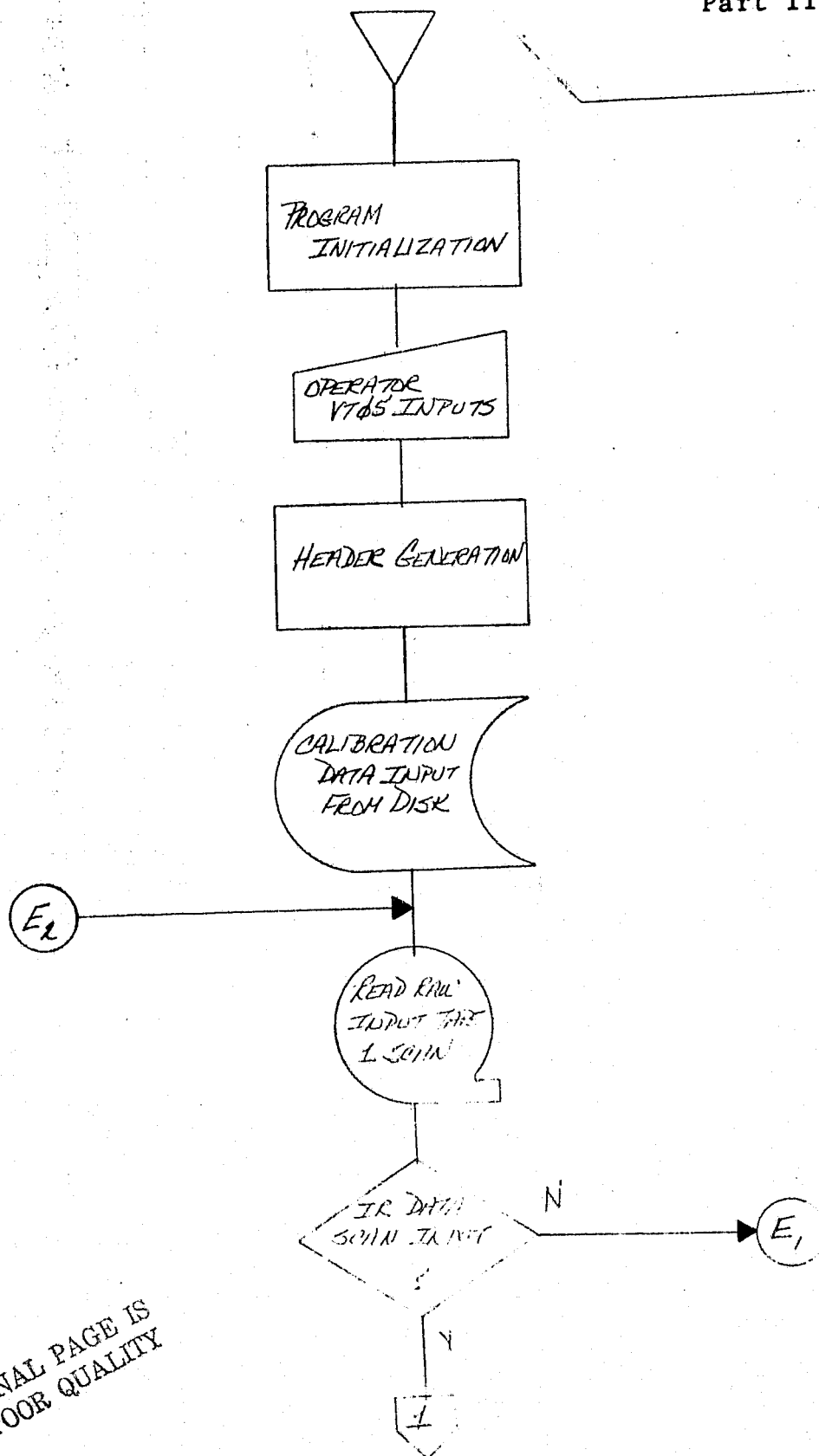
2.1.3 Timing and Sequencing. When the SEU Program is brought up for job execution, the SEUCON CPC is in main control of the operation sequencing and program control. SEUCON transfers control to the other CPC's by means of a call to the memory segmentation (management) module, SEG. SEG changes page address registers so as to "map" the requested CPC load module into the 32K portion of core for program execution. This also involves mapping in data areas if required, which might call for disk I/O transfers as well as transfers from program modules. Therefore, more time is involved than with a normal direct call (JSR) to a program.

SEUCON first makes a call to SEG to map in EUDISP to perform initialization procedures. This includes outputting data to the VT05 in form of a display and accepting operator inputs for job setup. A second call is made to SEG to map in HEDREC to read the input tape leader, extract information and build the EU output tape header. A third call to SEG is made to map in CALDAT. CALDAT utilizes disk I/O to retrieve the calibration data files permanently stored on disk. This calibration data is used by SEUCON in its calculations.

SEUCON reads in one scan line of data from the preprocessed 9-track CCT, performs the calibration processing of the scan, and converts the IR data to temperature units. The data is then written out to the EU tape. All tape reads and writes are accomplished by the Disk Operating System (DOS) I/O resident routine (NTRAN) and direct calls are made to this routine by SEUCON. Processing continues one scan at a time until all of the input data has been read in. ERRDSP is mapped in via SEG by SEUCON if an error condition occurs during processing, and also at the end of the job to signify to the operator that the job has completed. The entire processing from initialization to completion takes approximately 15 minutes of CPU time.

2.1.4 Storage Allocation. Figures 2-3 and 2-4 describe the storage allocation of the SEU Program and how the CPC's are situated in core, physical and virtual. As explained earlier, SEDS incorporated the use of a memory segmentation module to provide for the most efficient use of core during execution time, and also to allow more program capability in a somewhat limited addressable

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Figure 2-2 SEU Program Flow Chart

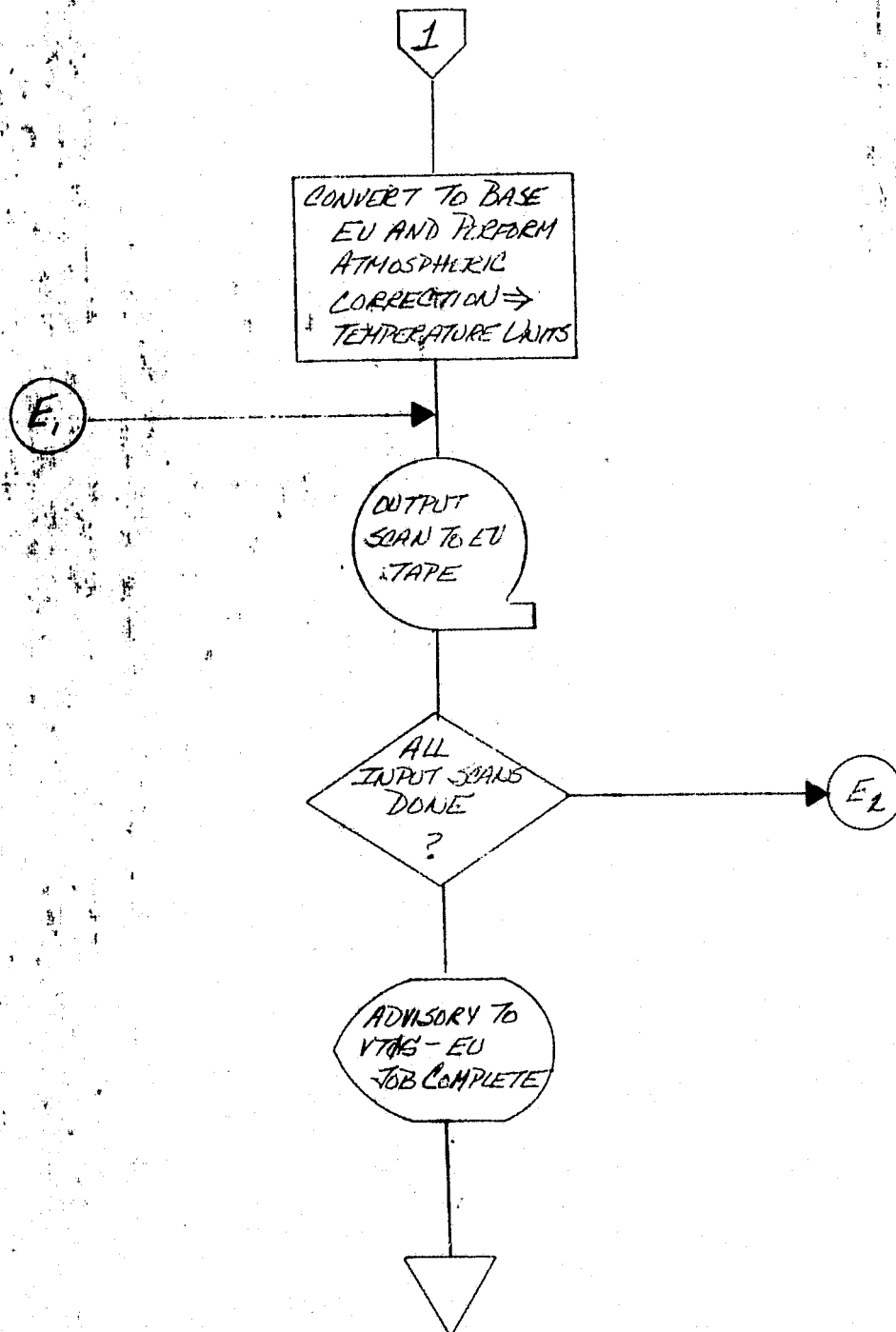


Figure 2-2 (Cont'd)

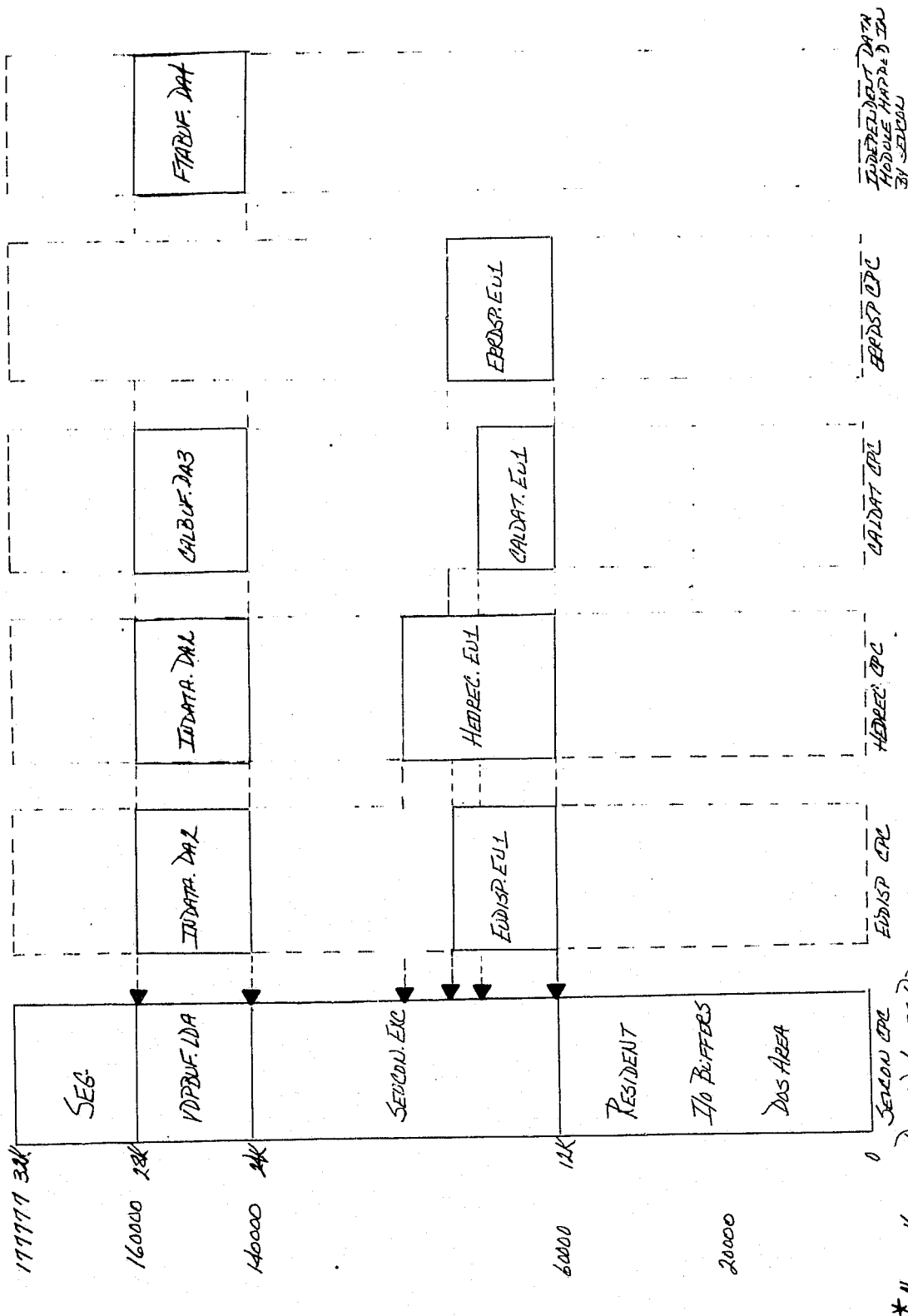
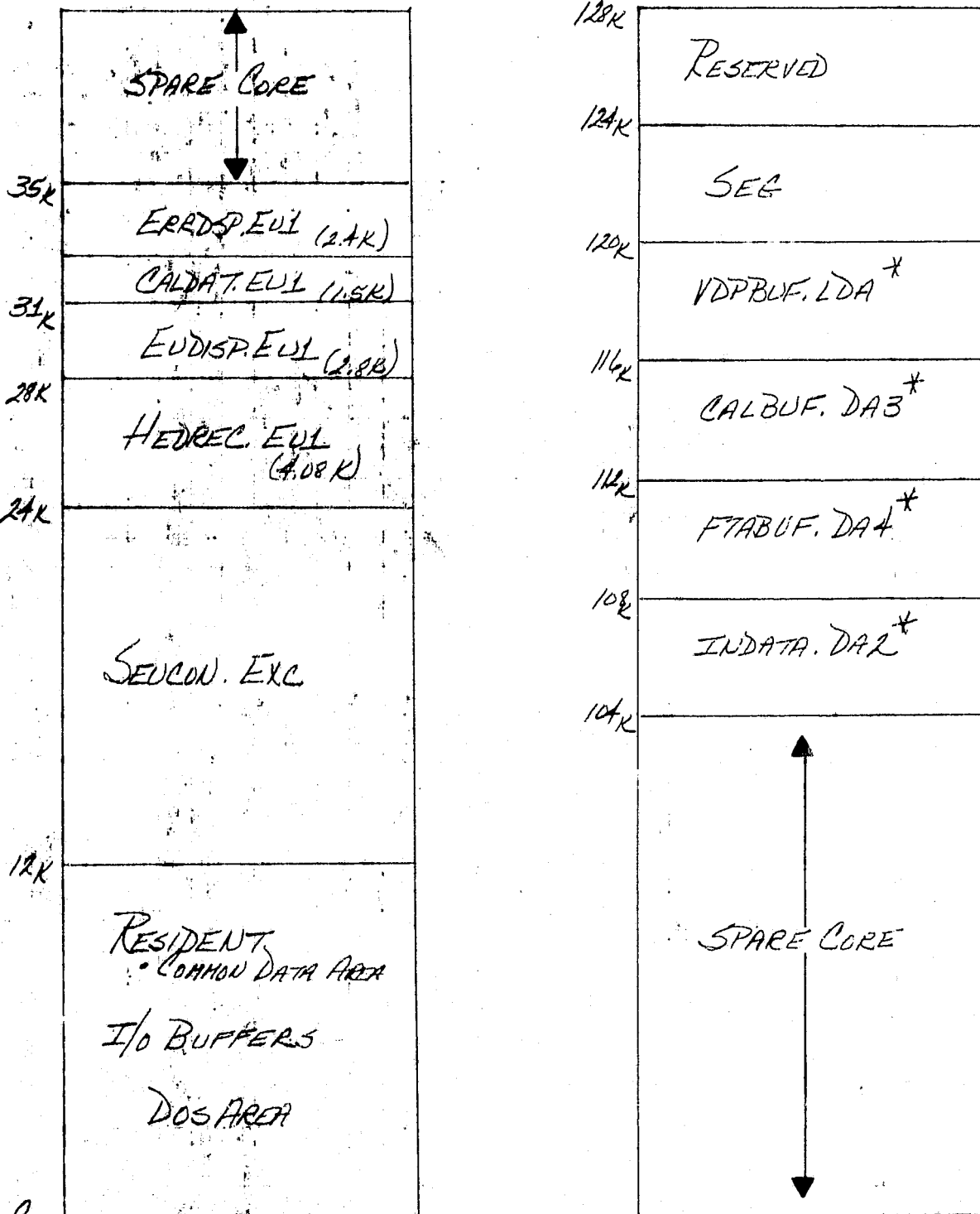


Figure 2-3 SEU 32K Virtual Memory Allocation

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*4K data buffers mapped in with load modules or separately when required

Figure 2-4 SEU Physical Memory Allocation

area of 32K core. Figure 2-3 is a layout of the 32K virtual memory during SEU. As each of the other CPC's are mapped into this 32K area, the program module is mapped in at 60000 for however much core it requires. Figure 2-3 shows that all of the other CPC's are much smaller than the SEUCON CPC. When each CPC has relinquished control to SEUCON, SEG remaps SEUCON to virtual 32K beginning again at 60000.

If a data module is associated with a particular CPC load module, it is mapped in with the CPC beginning at 140000, or from 24-28K. It is always mapped in at 4K blocks (no less). The resident and DOS area at 0-12K (0-60000) is never altered or overlaid in core, nor is SEG at 28-32K (160000-177777 virtual).

The SEU Program is situated in physical memory as seen in figure 2-4. Those modules with the same extensions are potentially overlays of each other; they would do so if the physical memory required was greater than the available 128K. However, in SEU, all programs are memory-resident since there is enough free physical core. If program overlay in physical memory had been necessary, those modules with the same extensions for which there was no free core would reside on disk and would be read in from disk as needed.

All data and tables used by two or more of the CPC's in SEU are contained in the resident area as common data so they can always be accessed. Each CPC may have its own data area associated with it, and may also have data flags and tables within the individual routines composing the CPC.

The SEU Program contains four separate data modules mapped in individually or with a particular CPC (VDPBUF, INDATA, CALBUF, and FTABUF). SEUCON uses FTABUF, INDATA and CALBUF data modules. INDATA is used as an internal data buffer for reading in data from the raw input tape. CALBUF and FTABUF contain calibration data read in from disk by CALDAT and used by SEUCON in the EU calculations. The EUDISP CPC uses the INDATA buffer to read in the input tape header to extract necessary data, for use later by HEDREC in generating the output header. VDPBUF is initially mapped in by SEUCON to set it up in physical core for later use in VT05 input/output requests.

2.1.5 Data Base Characteristics

A. File Description. As discussed previously, there are data files associated with the individual CPC's in the SEU Program (i.e., data areas mapped in at the same time with a CPC load module when called via SEG). Some of the data files are mapped in via SEG independently, and are not associated with one particular load module. These provide for a transfer of data from one CPC to another. There are also data files unique to a particular CPC and these are located internally in routines and/or subroutines in each CPC. These will be discussed in the CPC data organization paragraph for each CPC. Data files called in by SEG with or without a load module are mapped in at virtual memory address 140000-157777 (24-28K). Figure 2-4 illustrates the physical core layout of the data files.

1. INDATA. This is an integer array file 1530₁₀ words long mapped in with the EUDISP CPC. It is used for purposes of reading the input tape header in to gather information necessary for EU initialization. INDATA is then used by the HEDREC CPC to extract data from the header to build the EU output tape header. This data file is also utilized by the SEUCON CPC as an intermediate input buffer for the raw PCM input data (one scan at a time). HEDREC and SEUCON map INDATA independently when required.
2. CALBUF. This is a multifile containing three table arrays (two floating point and one integer) and consisting of a total of 3196₁₀ words. Figure 2-5 is a graphic description of CALBUF. The two floating point arrays, T and E(T), consist of predetermined temperature and energy values to be used by SEUCON in the calibration processes (see table 2-1). The integer array ITETAB contains predetermined corrected temperature values and is utilized as a "lookup table" by the SEUCON CPC in the final stages of the EU conversion. The CALBUF data file is mapped in with the CALDAT CPC, where the calibration and lookup tables are transferred from disk storage to the CALBUF file.

CALBUF:

T:

ABSOLUTE TEMPERATURES FROM
 $202.0^{\circ}\text{K} \rightarrow 315.0^{\circ}\text{K}$
 IN 0.5 DEGREE INCREMENTS
 (287 PLACE TABLE)

574₁₀ WORDS

ET:

ENERGY VALUES ASSOCIATED WITH
 ABSOLUTE TEMPERATURES IN
 T ABOVE

574₁₀ WORDS

32 BIT FLOATING POINT VALUES
 $ET(1) = 2078.386 \rightarrow 27013.929$

ITETAB:

8-BIT ENCODED SURFACE TEMPERATURE
 VALUES

USED AS TABLE LOOKUP IN
 LAST CONVERSION TO
 CORRECTED TEMPERATURE
 UNITS

2048₁₀ WORDS

INDEXED INTO BY 11 BIT
 CORRECTED ENERGY VALUES
 AS AN INDEX

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Figure 2-5 CALBUF Data File

TABLE 2-1
CONTENTS OF T AND E(T) ARRAYS ON CALBUF

T(°K)	E(T)	T(°K)	E(T)	T(°K)	E(T)	T(°K)	E(T)
202.0	2078.38686	225.0	3889.11133	248.0	5490.81250	271.0	9951.34766
202.5	2110.20271	225.5	3936.96851	248.5	6556.77734	271.5	10036.32813
203.0	2142.34370	226.0	3985.20386	249.0	6623.08984	272.0	10121.73438
203.5	2174.80803	226.5	4033.82251	249.5	6689.85938	272.5	10207.62109
204.0	2206.71635	227.0	4082.80859	250.0	6757.03906	273.0	10293.86719
204.5	2239.83546	227.5	4131.64844	250.5	6824.60156	273.5	10380.54297
205.0	2273.29376	228.0	4181.24219	251.0	6892.57813	274.0	10467.62891
205.5	2307.08047	228.5	4231.32422	251.5	6961.01563	274.5	10555.17969
206.0	2341.21955	229.0	4281.77734	252.0	7029.79688	275.0	10643.16406
206.5	2374.70506	229.5	4332.64453	252.5	7099.04688	275.5	10731.52344
207.0	2409.48822	230.0	4383.87500	253.0	7168.65234	276.0	10820.24219
207.5	2444.61960	230.5	4435.51172	253.5	7238.71484	276.5	10909.50391
208.0	2480.09914	231.0	4487.52344	254.0	7309.13281	277.0	10999.12109
208.5	2515.91147	231.5	4539.93750	254.5	7380.10156	277.5	11089.14453
209.0	2551.02282	232.0	4592.71875	255.0	7451.28125	278.0	11179.64844
209.5	2587.51841	232.5	4645.88281	255.5	7522.91406	278.5	11270.49219
210.0	2624.36018	233.0	4699.46875	256.0	7595.02344	279.0	11361.81250
210.5	2661.54711	233.5	4753.42578	256.5	7667.57031	279.5	11453.58984
211.0	2699.07918	234.0	4807.80073	257.0	7740.55078	280.0	11545.63281
211.5	2735.86405	234.5	4862.51172	257.5	7813.85938	280.5	11638.24609
212.0	2774.08933	235.0	4917.66016	258.0	7887.59766	281.0	11731.20703
212.5	2812.66794	235.5	4973.21875	258.5	7961.78516	281.5	11824.62109
213.0	2851.60091	236.0	5029.13281	259.0	8036.41406	282.0	11918.43750
213.5	2890.89138	236.5	5085.42578	259.5	8111.35156	282.5	12012.69141
214.0	2929.32767	237.0	5142.19531	260.0	8186.77344	283.0	12107.25391
214.5	2969.32132	237.5	5199.22656	260.5	8262.66016	283.5	12202.39453
215.0	3009.66479	238.0	5256.69531	261.0	8338.83203	284.0	12297.87500
215.5	3050.19507	238.5	5314.66797	261.5	8415.48438	284.5	12393.76563
216.0	3091.06299	239.0	5372.93359	262.0	8492.56641	285.0	12490.07813
216.5	3132.29932	239.5	5431.62500	262.5	8570.04688	285.5	12586.87109
217.0	3173.89233	240.0	5490.74219	263.0	8647.98828	286.0	12684.02734
217.5	3215.84497	240.5	5550.21484	263.5	8726.33594	286.5	12781.71875
218.0	3258.16406	241.0	5610.08203	264.0	8805.04297	287.0	12879.57422
218.5	3300.84204	241.5	5670.38281	264.5	8884.21875	287.5	12978.03125
219.0	3343.89136	242.0	5731.09766	265.0	8963.85938	288.0	13076.90234
219.5	3387.28931	242.5	5792.17969	265.5	9043.77734	288.5	13176.10547
220.0	3431.06323	243.0	5853.67188	266.0	9124.26563	289.0	13275.75391
220.5	3475.20435	243.5	5915.53906	266.5	9205.03906	289.5	13375.85156
221.0	3519.71191	244.0	5977.91797	267.0	9286.33203	290.0	13476.40234
221.5	3564.58228	244.5	6040.56250	267.5	9367.96875	290.5	13577.40625
222.0	3609.82837	245.0	6103.67188	268.0	9449.96484	291.0	13678.62500
222.5	3655.44604	245.5	6167.14453	268.5	9532.53125	291.5	13780.53516
223.0	3701.43115	246.0	6231.16797	269.0	9615.47656	292.0	13882.59375
223.5	3747.79004	246.5	6295.37500	269.5	9698.82813	292.5	13985.25781
224.0	3794.52075	247.0	6360.12500	270.0	9782.55469	293.0	14088.10156
224.5	3841.62305	247.5	6425.25000	270.5	9866.73047	293.5	14191.59766

TABLE 2-1 (CONT'D)
 CONTENTS OF T AND E(T) ARRAYS ON CALBUF

T(°K)	E(T)	T(°K)	E(T)	T(°K)	E(T)	T(°K)	E(T)
294.0	14295.39063	317.0	19518.45703	340.0	25594.10547		
294.5	14399.83594	317.5	19641.64844	340.5	25735.29688		
295.0	14504.49219	318.0	19765.12109	341.0	25876.95313		
295.5	14609.44141	318.5	19889.09375	341.5	26018.96875		
296.0	14715.07031	319.0	20013.29297	342.0	26161.43750		
296.5	14820.85156	319.5	20138.29688	342.5	26304.24219		
297.0	14927.24609	320.0	20263.27734	343.0	26447.39844		
297.5	15034.11719	320.5	20388.87109	343.5	26590.98828		
298.0	15141.25391	321.0	20514.89063	344.0	26734.91797		
298.5	15248.91797	321.5	20641.24609	344.5	26879.17969		
299.0	15356.78516	322.0	20767.90625	345.0	27023.92969		
299.5	15465.20313	322.5	20895.16016				
300.0	15574.03516	323.0	21022.62500				
300.5	15683.25000	323.5	21150.55078				
301.0	15792.93750	324.0	21278.92969				
301.5	15902.95313	324.5	21407.66797				
302.0	16013.47656	325.0	21536.82031				
302.5	16124.34375	325.5	21666.30859				
303.0	16235.66016	326.0	21796.26953				
303.5	16347.39844	326.5	21926.66797				
304.0	16459.50391	327.0	22057.36328				
304.5	16572.04297	327.5	22188.51172				
305.0	16684.99609	328.0	22320.03125				
305.5	16798.41797	328.5	22451.92188				
306.0	16912.07813	329.0	22584.25781				
306.5	17026.30469	329.5	22716.94531				
307.0	17140.87500	330.0	22850.04297				
307.5	17255.91406	330.5	22983.50000				
308.0	17371.26563	331.0	23117.41016				
308.5	17487.19922	331.5	23251.71875				
309.0	17603.31641	332.0	23386.44531				
309.5	17720.04297	332.5	23521.51953				
310.0	17837.08203	333.0	23656.92188				
310.5	17954.54688	333.5	23792.71094				
311.0	18072.36328	334.0	23928.93750				
311.5	18190.63281	334.5	24065.66797				
312.0	18309.37891	335.0	24202.55078				
312.5	18428.38281	335.5	24340.01172				
313.0	18547.95313	336.0	24477.82031				
313.5	18667.81641	336.5	24615.96875				
314.0	18788.10547	337.0	24754.56641				
314.5	18908.80859	337.5	24893.51172				
315.0	19029.99219	338.0	25032.88672				
315.5	19151.48438	338.5	25172.58984				
316.0	19273.44531	339.0	25312.63281				
316.5	19395.71094	339.5	25453.18359				

3. FTABUF. This data file contains 3523₁₀ 16-bit $F(\alpha_0, \theta)$ values in floating point (actually 7046₁₀ words). Pre-determined $F(\alpha_0, \theta)$ values are read from disk, stored in FTABUF by the CALDAT CPC, and used by SEUCON in the atmospheric correction algorithm. FTABUF is mapped in independently by the CALDAT and SEUCON CPC's.

B. Item Description. In the SEU Program are flag words and data stored in common, accessible to all of the CPC's. An area in RESIDENT is set up for this common data to enable a passing of flags or data between the individual load modules. All common data items are 16-bit integer values unless otherwise specified.

1. SEDCOM. This contains the following processing data words.
 - INIT, a flag for load module (CPC) communication (0=initialization, 1=continue processing, and 2=terminate).
 - IPASS, a flag to indicate the type of pass for the job (0=day pass and 1=night pass).
 - ILOUT, the output tape logical unit number
 - IDTAPE, and EBCDIC tape identification set up for the output tape (five integer words).
 - ISENSOR, sensor identification as reflected in the input tape header.
2. ERROR. This contains parameters for ERRDSP, the error display routine CPC, as follows.
 - IERR, the error message code (range of 1-300)
 - IUNIT, the logical unit on which the error occurred.
3. TPFRMT. This contains data extracted from the input header describing the tape format, as follows.

- IRCSET, records per data set
- NVIDEO, the number of video elements within a channel
- IRCSZE, the physical record size in words
- IANCSZ, the ancillary record size in bytes
- IFSPPIX, the starting pixel number on input tape
- IENPIX, the ending pixel number
- ICHSZE, the total bytes per scan, per channel.

2.2 SEU CPC CHARACTERISTICS

The following paragraphs contain detailed descriptions of the five computer program components outlined in paragraph 2.1. The instruction listings contained herein, by inclusion or reference, specify the exact configuration of the SEU Program. Each CPC will be discussed individually in the following sections as CPC No. 1, CPC No. 2, etc.

2.2.1 SEUCON (CPC No. 1). The SEUCON CPC is the major load module of the SEU Program. It acts as the controller of the EU processing utilizing the other four CPC's for purposes of initialization and to perform necessary services during the run. SEUCON is responsible for the actual data conversion of the raw data to temperature units as stated in paragraph 2.1.1. The majority of SEUCON load module routines are written in PDP 11/45 FORTRAN language. The routines and subroutines of SEUCON are described in the following paragraphs. The major interfaces include tape and disk I/O via an NTRAN resident routine, and internal subroutine interfaces to accomplish the table lookups and conversions of the data. See figure 2-6 for a virtual core layout of the SEUCON load module.

2.2.1.1 SEUCON Subcomponent Description. The SEUCON CPC contains a number of major subcomponents, the SEUCON main routine, EVCONV, ECCONV, TAGCHK, FIXDAT, FILSCN, FILTER, TBLOOK, TAPEIN, TPEOUT, and TBSRCH. This paragraph will discuss in detail the functions and design flow of SEUCON and the part that each subcomponent is responsible for to carry out these functions.

- A. SEUCON Main. This is the major subcomponent of the SEUCON load module. In fact, it is the routine responsible for controlling the sequence of processing and calling the other CPC's as well as its own subcomponents. The functions of each subcomponent are briefly described below, followed by a detailed writeup of the processing flow of SEUCON.
- B. EVCONV. This is a FORTRAN routine that performs the calibration processing, a scan at a time, creating calibrated E(V) "energy values" in a table for use in further conversions.

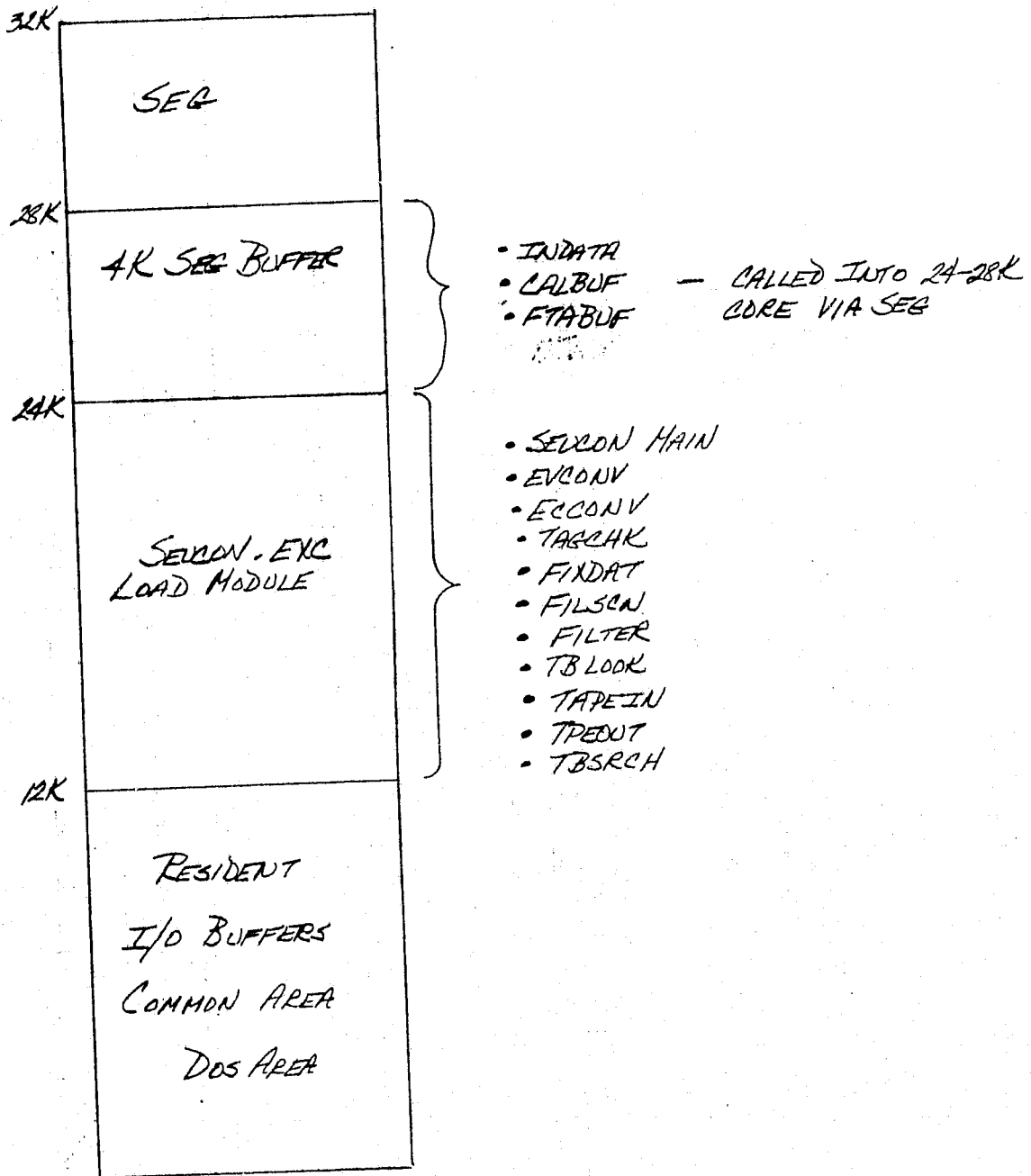


Figure 2-6 SEUCON CPC Virtual Core Map

- C. ECCONV. This is an assembly routine that takes the calibrated energy values $E(V)$ and converts them to temperature units to complete the EU conversion.
- D. TAGCHK. This performs checks on the incoming scan for a valid channel tag (FORTRAN)
- E. FIXDAT. When a tape read error occurs on the input tape, this FORTRAN subroutine corrects the scan and sets up its ancillary record, if necessary.
- F. FILSCN. This FORTRAN subroutine outputs zero-fill scans to the EU output tape when certain conditions occur (i.e., time discontinuity, data dropouts on raw input tape).
- G. FILTER. This calculates a "filtered" value for scan voltage values used in the calibration computations (FORTRAN).
- H. TBLOOK. This is an assembly subroutine that performs the actual table lookups using an input index table (set up by the calling routine) and a fixed value table of data entries to be picked up.
- I. TAPEIN. This is a FORTRAN routine that uses an I/O routine (NTRAN) residing in RESIDENT to read in the raw PCM input tape.
- J. TPEOUT. This is a FORTRAN routine that uses an I/O routine (NTRAN) residing in RESIDENT to write the EU output tape.
- K. TBSRCH. This is a FORTRAN subroutine used to compute $E(T_R)$ for a given absolute temperature (T_R) using interpolation and the $E(T)$ table. The $E(T_R)$ is used in the computation of $E(V)$.

SEUCON when first given control by the SEDS-resident routine uses SEG to map in the EUDISP CPC to perform the initialization set-up for processing. The HEDREC and CALDAT CPC's are next loaded into core to set up the EU output tape header and to read the calibration data and lookup table files from disk into their respective data files for later use.

Now the processing of the data is performed. SEUCON MAIN calls TAPEIN to read a scan line of data from the raw PCM tape into the INDATA buffer. Checks are made by TAGCHK to ensure validity on the IR or VIS scan. Checks are also made for data dropouts, time discontinuity, invalid calibration data and errors occurring on the tape read. FILSCN or FIXDAT is called if any of the above conditions occur, either to correct the scan or to insert zero fill to the output tape. SEUCON transfers the input data from the INDATA.SEG buffer to an internal buffer IPDATA, in which all processing of the data is to take place. If the scan read-in is VIS data, it is output directly to tape by TPEOUT. If the scan is IR data, the first step in processing the data is "calibration." This is a conversion of the IR data samples to 16-bit energy values, $E(V)$. This conversion is to be done for each pixel in a scan of IR data. The voltage data within each particular scan is used in the calculations. A table lookup approach has been implemented in the design of this phase to facilitate processing and more straightforward logic. The use of an assembly language subroutine to utilize these lookup tables provides more efficient use of time, and eases future program changes. So, for a scan of input IR data, SEUCON calls EVCONV to build a "lookup" table of $E(V)$'s by extracting the voltage data from the scan and calculating energy values $E(V)$ for every possible PCM value of 0 to 255_{10} .

The algorithm used by EVCONV in computing the $E(V)$'s is as follows.

$$E(V) = \frac{E(T_R)}{e^{(FVBB-FVSS)}} * (V-FVSS)$$

Where:

$E(V)$ = Energy value corresponding to a voltage (V), which is an 8-bit digital sensor output voltage value (0 to 255_{10}) for a given pixel of IR data. NOTE: If $V = 0$ or $V \geq FVSS$, $E(V)$ is set to 0.

$E(T_R)$ = Energy value corresponding to a perfect emitter or blackbody at an absolute reference temperature (T_R) in °K.

e = Assumed average emissivity of earth's surface in thermal IR band (ratio of the average surface emissivity to the emissivity of the onboard reference source). A value of $e = 0.975$ will be used.

FVSS = Filtered (for noise reduction) space scan sensor output voltage value corresponding to a time when the sensor was receiving deep space.

FVBB = Filtered (for noise reduction) blackbody sensor output voltage value corresponding to a time when the sensor was receiving the onboard reference source.

The procedures for calculating T_R , $E(T_R)$, FV_{SS} , FV_{BB} are as follows.

2.2.1.1.1 Calculation of Reference Temperature. The calculation of reference temperature T_R to use for each scan line of IR data is the only place in the calibration process where it makes any difference which satellite collected the data (NOAA-2, NOAA-3, or NOAA-4) and, if it was NOAA-3 or NOAA-4, which sensor (VHRR-1 or VHRR-2) was being used. In all cases, 8-bit digitized thermistor voltages in the scan, $V(T_1)$, $V(T_2)$, and $V(T_3)$, are used to calculate a filtered value of T_R for each scan line. See table 2-2 for a layout of the input IR scan and the position of $V(T_1)$, $V(T_2)$, $V(T_3)$, VSS, and VBB within the scan. These calculation procedures are defined below for each satellite and sensor.

A. NOAA-2 T_R Calculations (Both VHRR Sensors). All filtering of values is accomplished by a call to the subroutine FILTER.

If $V(T_2) < 50$ counts, then:

$$T_R = V(T_3) \cdot 0.080442433 + 263.73 \text{ } ^\circ\text{K}$$

If $V(T_2) > 201$ counts, then:

$$T_R = V(T_1) \cdot 0.081436796 + 291.32 \text{ } ^\circ\text{K}$$

If $50 \text{ counts} \leq V(T_2) \leq 201 \text{ counts}$, then:

$$T_R = V(T_2) \cdot 0.086611383 + 276.77 \text{ } ^\circ\text{K}$$

TABLE 2-2
RAW TAPE BLOCKS

ANCILLARY BLOCK (COUNTER = 1*)	
<u>BLOCK BYTE</u>	<u>DESCRIPTION</u>
1-4	CURRENT GMT AT START OF THIS DATA SET (TENTHS OF MILLISECONDS)
5-6	CHANNEL STATUS FOR THIS SCAN. LSB OF BYTES 5-6 (0 = CHANNEL IN SYNC, 1 = CHANNEL NOT IN SYNC), ONE BYTE PER CHANNEL
7-68	CHANNELS 3-64 NOT APPLICABLE; LSB OF EACH BYTE = 1
69-70	SCAN LINE NO. ARBITRARY BUT SEQUENTIAL FOR EACH SCAN LINE OF THIS DATA RUN
VIDEO BLOCK (COUNTER = 2*)	
<u>BLOCK BYTE</u>	<u>DESCRIPTION</u>
1-2514	CHANNEL OF DATA (VARIABLE)
1	SAMPLE AT SPACE SCAN MASK (VSS)
2-2501	VIDEO ELEMENTS (VARIABLE NO.) DURING EARTH SCAN
2502-2508	SEVEN VOLTAGE CALIBRATION STEPS (V_0 THRU V_6)
2510	A 300 °K BLACKBODY SAMPLE LEVEL (VBB)
2511-2513	THREE 300 °K TEMPERATURE SENSOR RANGE SAMPLES [$V(T_1)$, $V(T_2)$ AND $V(T_3)$]
2514	DATA TAG (7 = DATA IS IR; 6 = DATA IS VIS; 5, 4 = NOT USED; 3, 2, 1, 0 = HARDWARE STATUS INDICATORS)

*COUNTER IS IN THE FIRST TWO BYTES OF THE PHYSICAL RECORD

NOTE: BYTES OF ZERO FILL ARE REQUIRED TO COMPLETE THE PHYSICAL RECORD LENGTH SPECIFIED IN THE HEADER RECORD

If filtered value of T_R for the i^{th} scan line is $(FILTR)_i$, then:

$$(FILTR)_i = (FILTR)_{i-1} + \frac{1}{K} (TR_i - (FILTR)_{i-1})$$

where:

$K = 1-16$ for i (scan line) of $1-16$, respectively

B. NOAA-3 T_R Calculations

1. Temperature Conversions

a. VHRR - 1 (S/N 106)

$$T_1 = 0.084830896 \cdot V(T_1) + 284.548 \text{ } ^\circ K$$

$$T_2 = 0.083842795 \cdot V(T_2) + 284.863 \text{ } ^\circ K$$

$$T_3 = 0.1502448186 \cdot V(T_3) + 273.121 \text{ } ^\circ K$$

b. VHRR - 2 (S/N 109)

$$T_1 = 0.07521153240 \cdot V(T_1) + 284.275 \text{ } ^\circ K$$

$$T_2 = 0.07569783944 \cdot V(T_2) + 285.087 \text{ } ^\circ K$$

$$T_3 = 0.1537599103 \cdot V(T_3) + 272.012 \text{ } ^\circ K$$

2. Filtering. Let $FT1_{i-1}$, $FT2_{i-1}$, $FT3_{i-1}$, and FTR_{i-1} be the filtered T_1 , T_2 , T_3 , and T_R values for the last scan line ($i-1$). Let $T1_i$, $T2_i$, $T3_i$, and TR_i be the unfiltered temperatures for the current scan line (i). Find the following.

$$FT1_i = FT1_{i-1} + \frac{1}{K} (T1_i - FT1_{i-1})$$

$$FT2_i = FT2_{i-1} + \frac{1}{K} (T2_i - FT2_{i-1})$$

$$FT3_i = FT3_{i-1} + \frac{1}{K} (T3_i - FT3_{i-1})$$

Where:

K = scan line number when it is ≤ 16 , or 16 when it is > 16

Set $W_1 = 2$. Then:

If $|FT1_i - T1_i| > 1 \text{ } ^\circ\text{K}$

And $FT1_i < 287 \text{ } ^\circ\text{K}$ or $> 303 \text{ } ^\circ\text{K}$,

Set $W_1 = 0$

Set $W_2 = 2$. Then:

If $|FT2_i - T2_i| > 1 \text{ } ^\circ\text{K}$

And $FT2_i < 287 \text{ } ^\circ\text{K}$ or $> 303 \text{ } ^\circ\text{K}$,

Set $W_2 = 0$

Set $W_3 = 1$. Then:

If $|FT3_i - T3_i| > 1 \text{ } ^\circ\text{K}$

Set $W_3 = 0$.

Now, find the following.

$$TR_i = \frac{W_1 \cdot FT1_i + W_2 \cdot FT2_i + W_3 \cdot FT3_i}{W_1 + W_2 + W_3}$$

If $W_1 + W_2 + W_3 = 0$,

Set $TR_i = FTR_{i-1}$.

Then find the following.

$$FTR_i = FTR_{i-1} + \frac{1}{K} (TR_i - FTR_{i-1})$$

Where:

K = scan line number when it is ≤ 16 , or 16 when it is > 16

FTR_i is then the current filtered value of the reference temperature (T_R).

2.2.1.1.2 Calculation of Energy Value. The next processing task is to calculate $E(T_R)$. If the calculated value of T_R is > 310 °K or < 273 °K, this is an error condition and we must set $E(V) = 0$ for all 256 values of V . A call is made to TBSRCH to find, for any T_R between 273 °K and 310 °K, $E(T_R)$ by linear interpolation between the two nearest values from the $E(T)$ table, which contains hard-coded values of E for temperatures from 215 °K - 345 °K in 0.5 degree increments.

2.2.1.1.3 Calculation of FVSS and FVBB. The following calculations will be used by FILTER to find the filtered values FVSS and FVBB of VSS and VBB, respectively, for the current scan line (i).

If $234 \leq VSS_i \leq 255$ counts, then:

$$FVSS_i = FVSS_{i-1} + \frac{1}{K} (VSS_i - FVSS_{i-1})$$

Where:

K = 1-64 for scan line numbers 1-64, or 64 for a scan line number > 64

If VSS_i is outside the above range, this is an error condition and we must set $E(V) = 0$ for all V .

If $104 \leq VBB_i \leq 164$ counts, then:

$$FVBB_i = FVBB_{i-1} + \frac{1}{K} (VBB_i - FVBB_{i-1})$$

Where:

K = 1-32 for scan line numbers 1-32, or 32 for scan line numbers > 32

If VBB_i is outside the above range, this is an error condition and we must set $E(V) = 0$ for all V .

2.2.1.1.4 Setup of E(V) Table. If no error conditions were detected in the preceding calculations of T_R , $E(T_R)$, $FVSS$ or $FVBB$, then the following procedure is used by EVCONV to set up the 256-place table of 16-bit E(V) values:

For all $V \geq FVSS_i$ (rounded to eight bits) and for $V = 0$ counts, set $E(V) = 0$. For all $V \neq 0$ and $V < FVSS_i$ (rounded to eight bits), find the following as 16-bit (integer) words, and place these values in the E(V) table:

$$E(V) = \frac{E(T_R)_i}{e(FVBB_i - FVSS_i)} (V - FVSS_i)$$

2.2.1.1.5 Remainder of Processing. Having completed the E(V) table for the input scan, EVCONV calls TBLOOK to perform the table lookup. TBLOOK uses each PCM pixel value in the scan (IPDATA), beginning with the first pixel, as an index into the E(V) table to pick up the corresponding E(V). As they are picked up, the E(V)'s are put into the intermediate buffer (IPDATA) to replace the PCM value. For example, if the first pixel of the input scan = 170_{10} (PCM value), TBLOOK would index into E(V) table by 170 to get E(V), and put E(V) into the first pixel position of the IPDATA buffer.

SEUCON calls ECCONV to convert the energy values $[E(V)]$ now in the IPDATA buffer to corrected temperature units $T(E_C)$ to complete the EU conversion of the input scan. First, ECCONV applies an atmospheric correction to the "calibrated" E(V) values. Then the corrected energy values (E_C) are converted to encoded temperature units ($T(E_C)$). This is accomplished as follows. For each pixel a corrected energy value, E_C is found as follows:

$$E_C = E(V) + \Delta E$$

Where:

$$\Delta E = [E(V) - E(A)] \cdot F(\alpha_0, \theta)$$

If $E(V) = 0$, then:

$$E_C = 0; T = 0.$$

$E(A)$ corresponds to an effective atmospheric temperature of 230 °K and will have the integer value of 4384. The value of $F(\alpha_0, 0)$ is found from a table of 3523 fixed scale 16-bit values calculated by an off-line FORTRAN routine (FTABLE). This table (FTABUF) is mapped into core via a SEG call to be used in this portion of processing. The pixel number (not the value or position) of the input pixel is used as an index into FTABUF (i.e., if starting pixel number = 300 then pixel No. 1 of the scan uses an index of 300 into FTABUF; the second pixel would use 301 as an index, and so on).

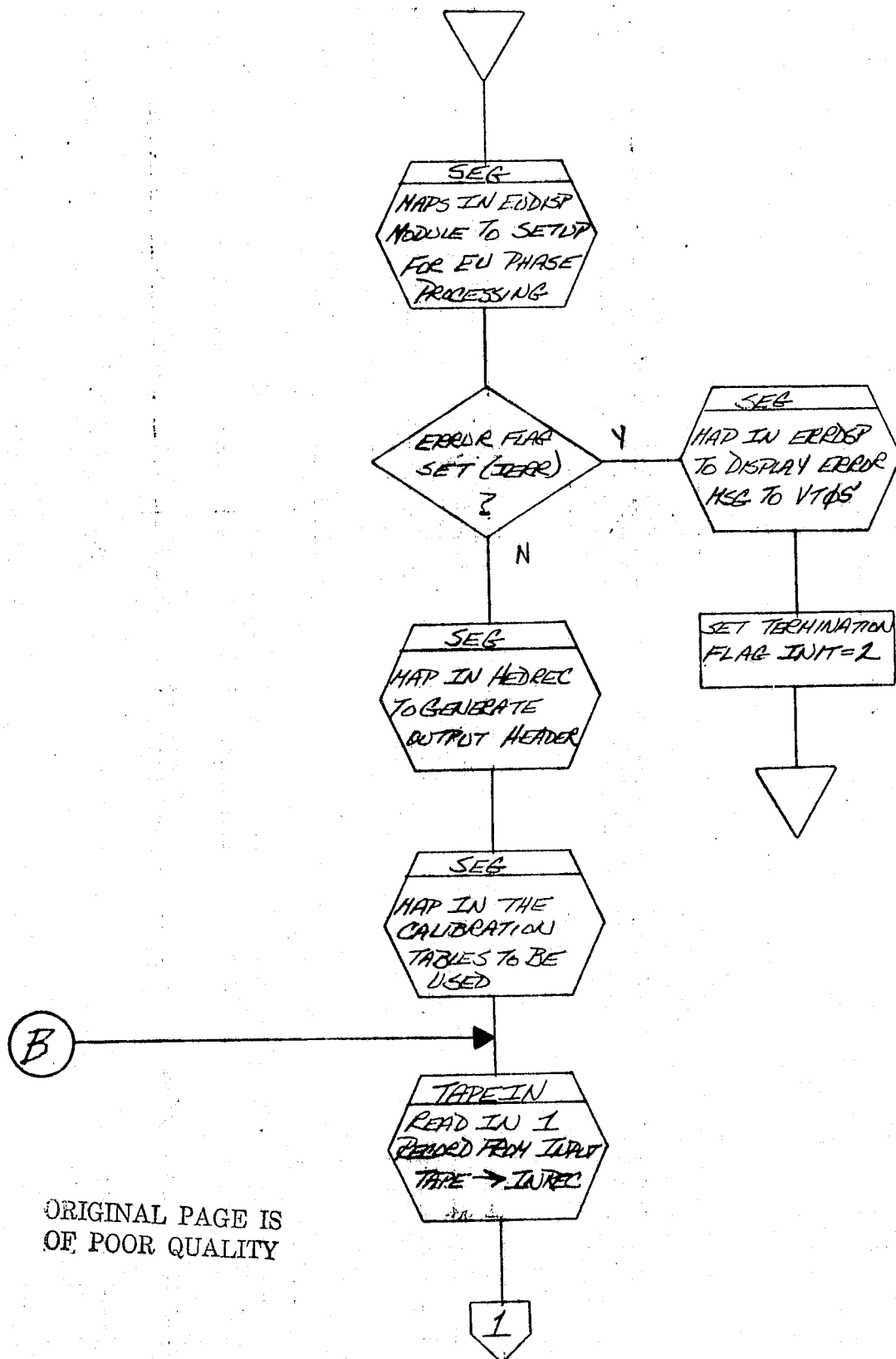
The 16-bit corrected energy value (E_C) is now rounded to an 11-bit integer (E'_C) as follows:

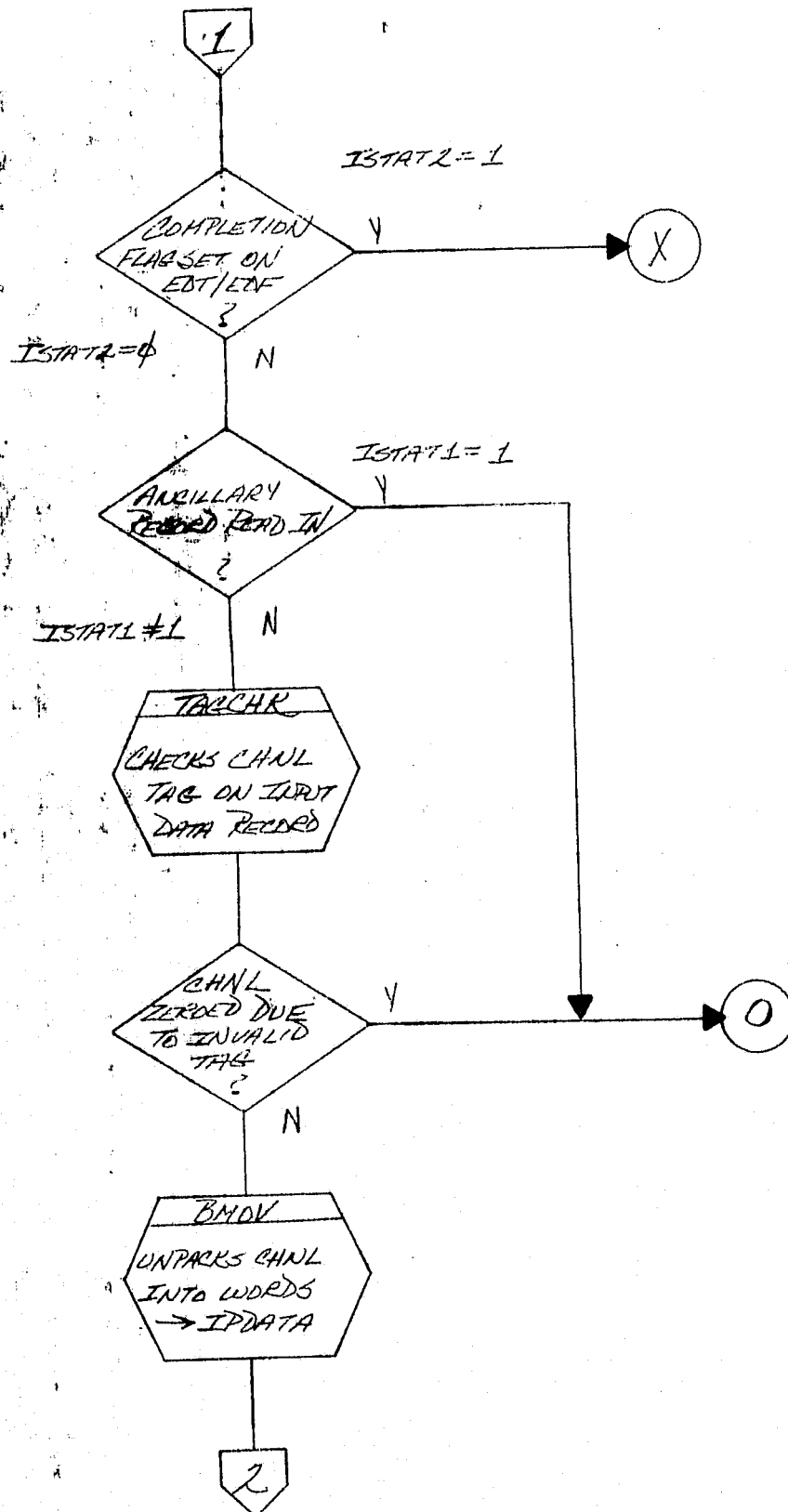
$$E'_C = \text{INT} \left[\frac{E_C + 8}{16} \right]$$

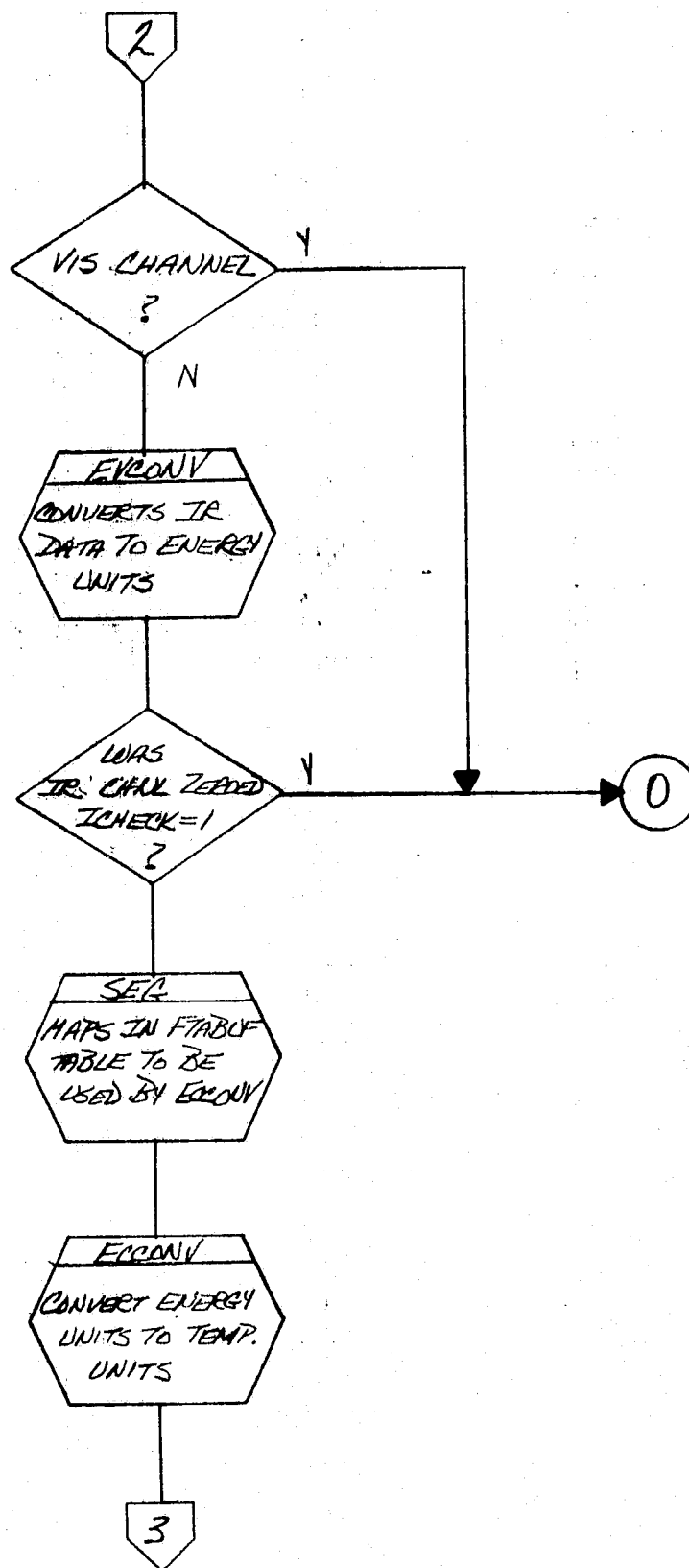
This process, going from $E(V)$ to E'_C , is done for each pixel in the input scan. When it is completed with all pixels, a call to TBLOOK is made. TBLOOK uses the E'_C values in IPDATA as indices into a 2048-place table of 8-bit temperature codes, $T(E'_C)$, to pick up the corrected temperature for each pixel and place in the IPDATA buffer. The $T(E'_C)$ table was generated by inverting the $E(T)$ table via an off-line FORTRAN program, ENTGEN, and was stored permanently on disk.

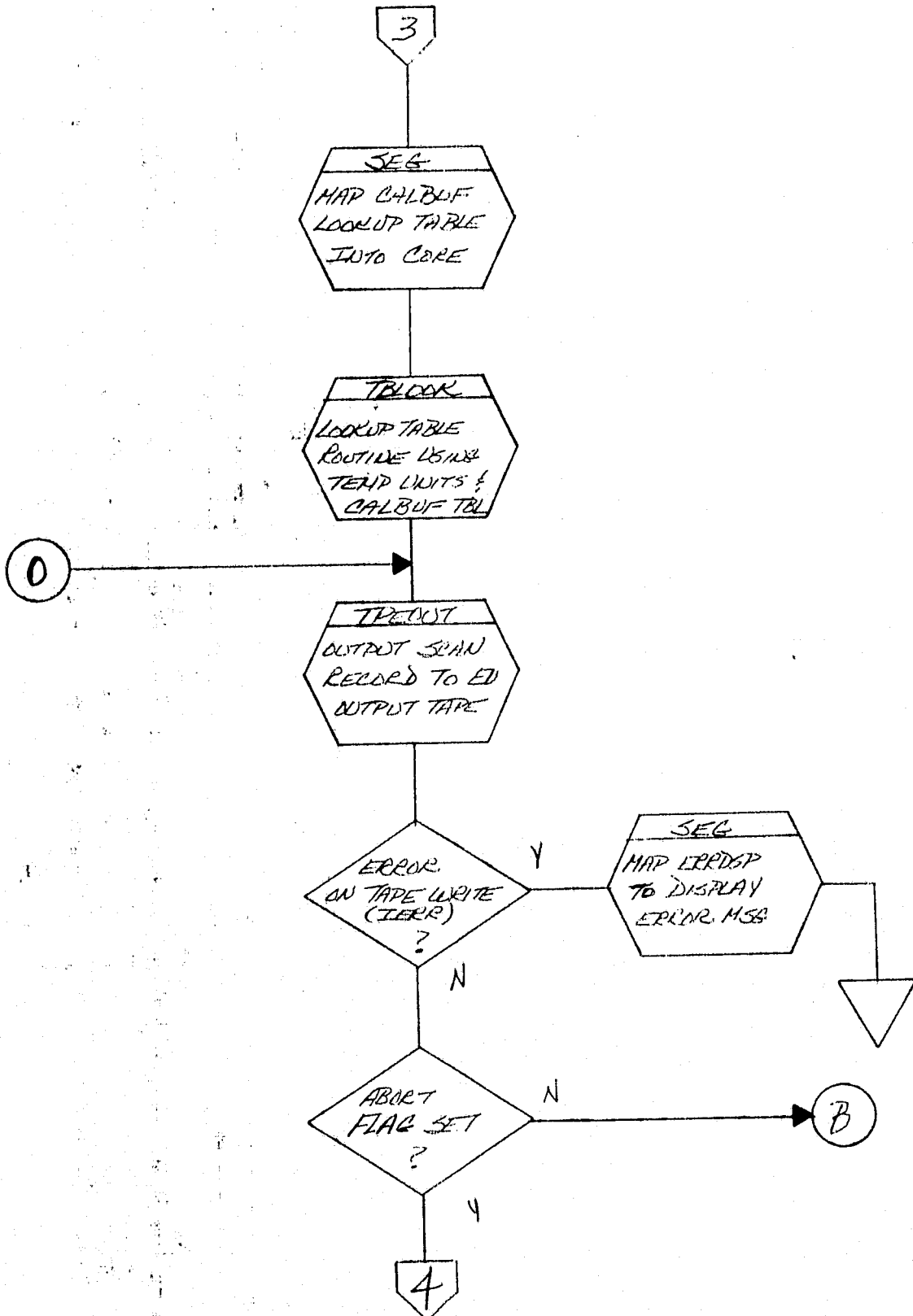
SEUCON now has a fully processed IR scan to be output. A call is made to TPEOUT to write the scan contained in the IPDATA buffer to the EU output tape. SEUCON continues the processing loop by reading in the next scan via TAPEIN and repeating all of the above calculations. When all of the input scans have been processed, SEUCON performs cleanup tasks, notifies operator of job completion, and returns program control to the SEDS-resident routine.

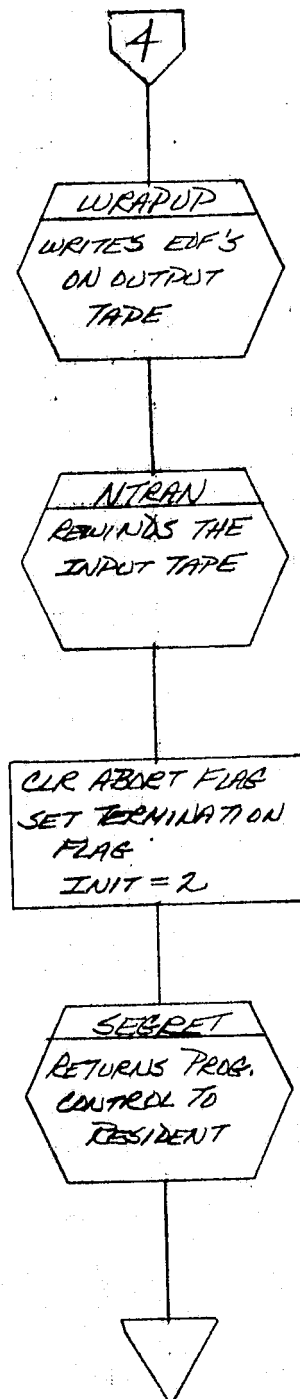
2.2.1.2 Flow Charts. See the following 47 pages.



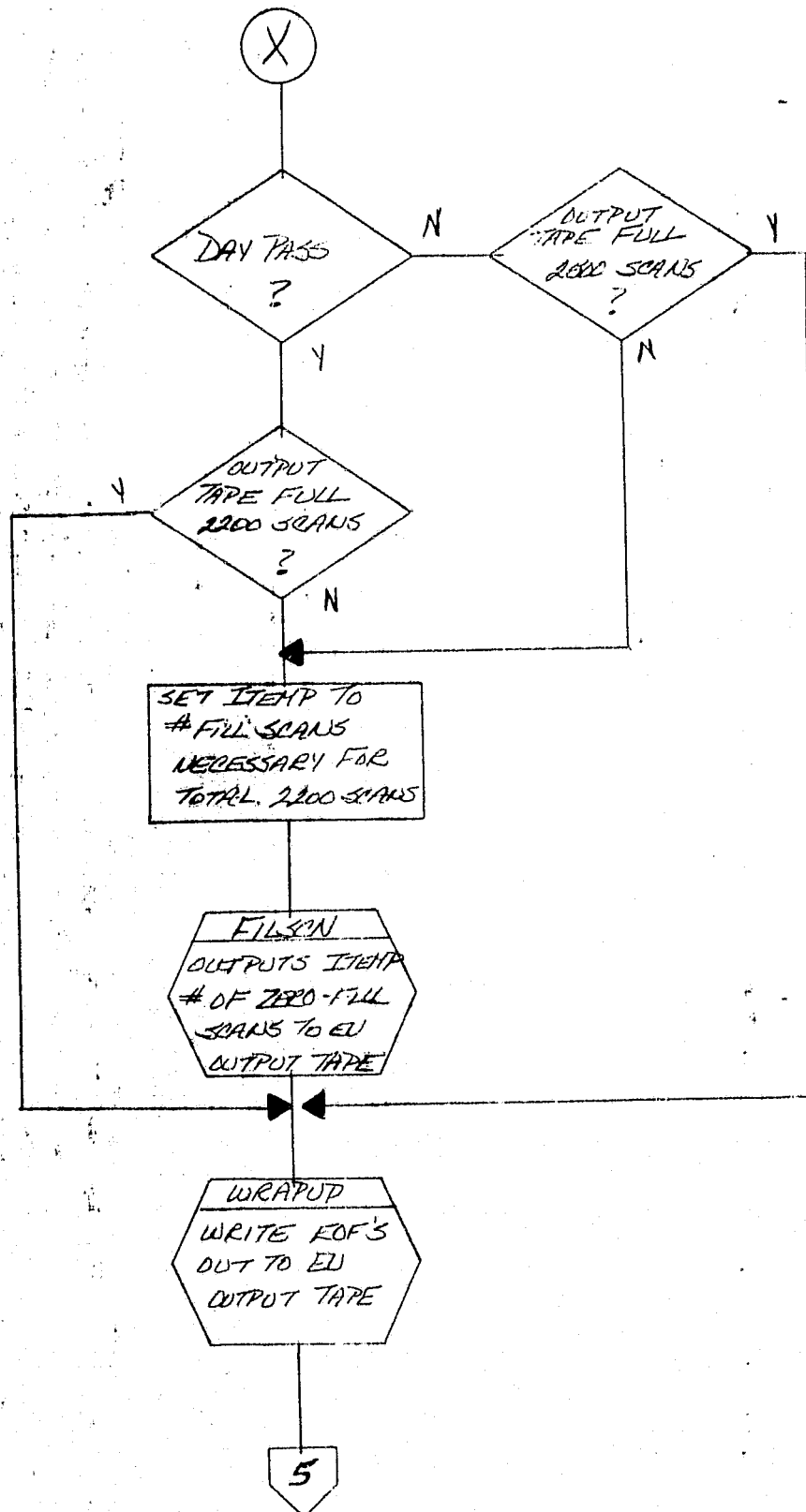


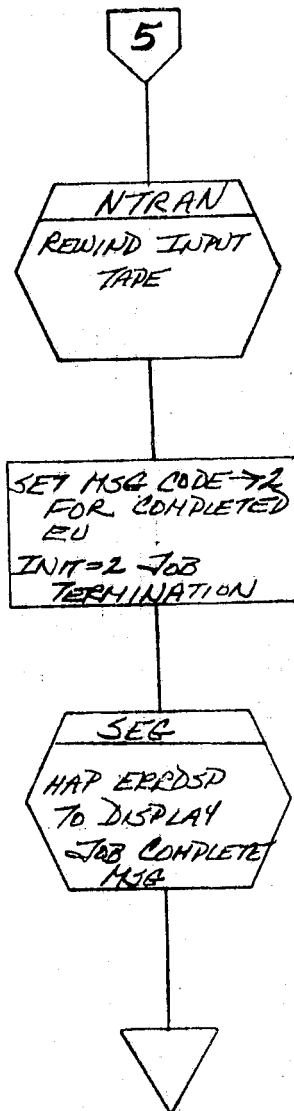


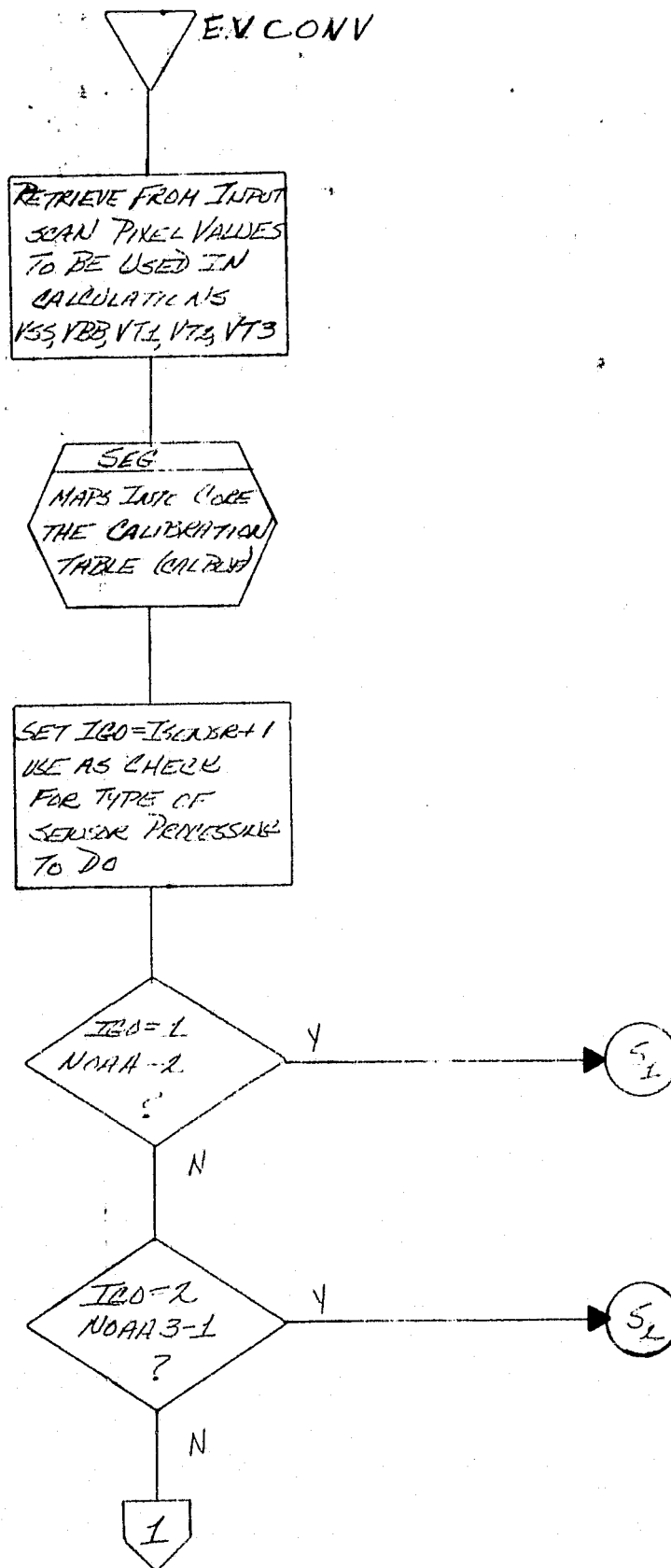




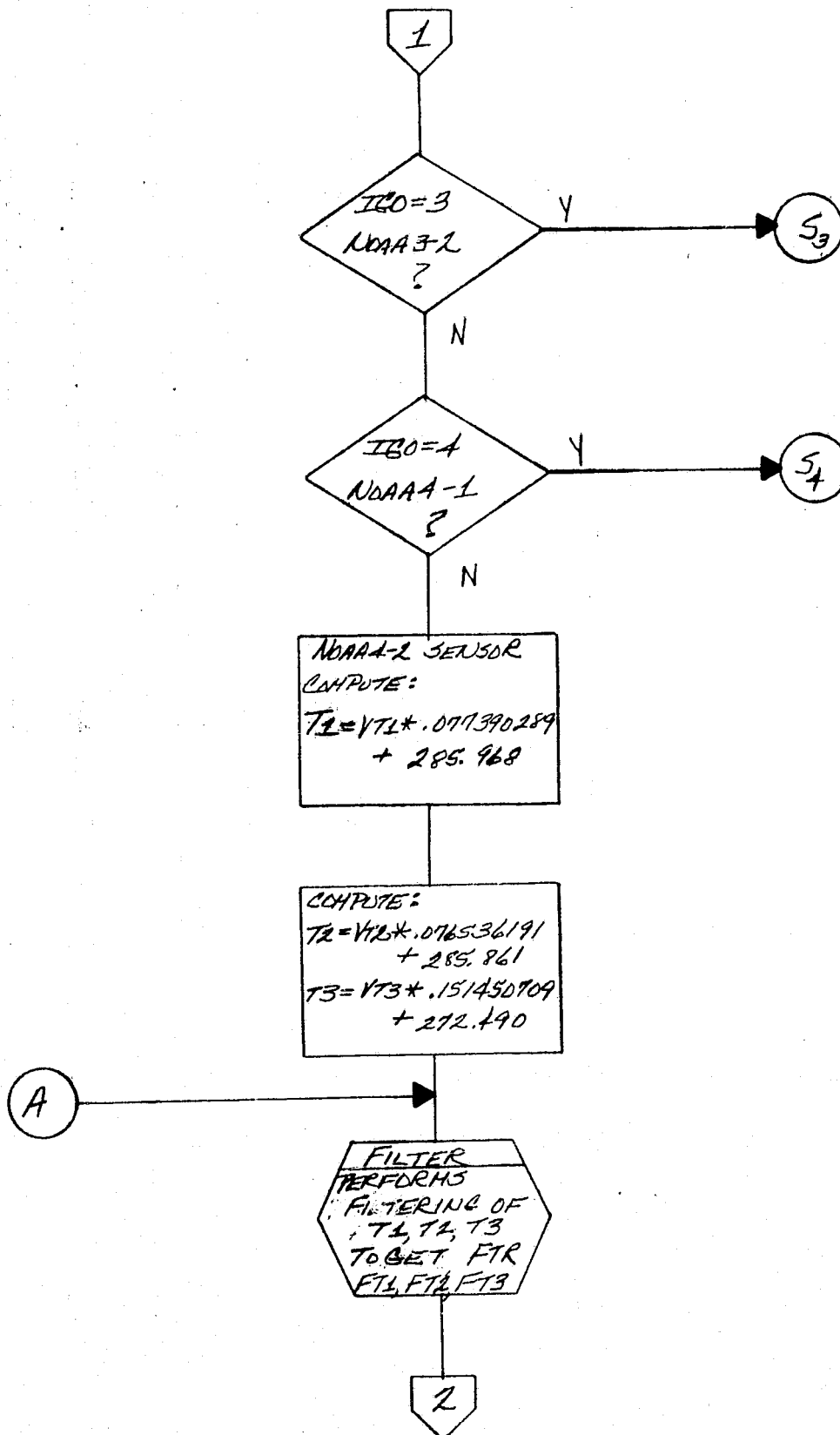
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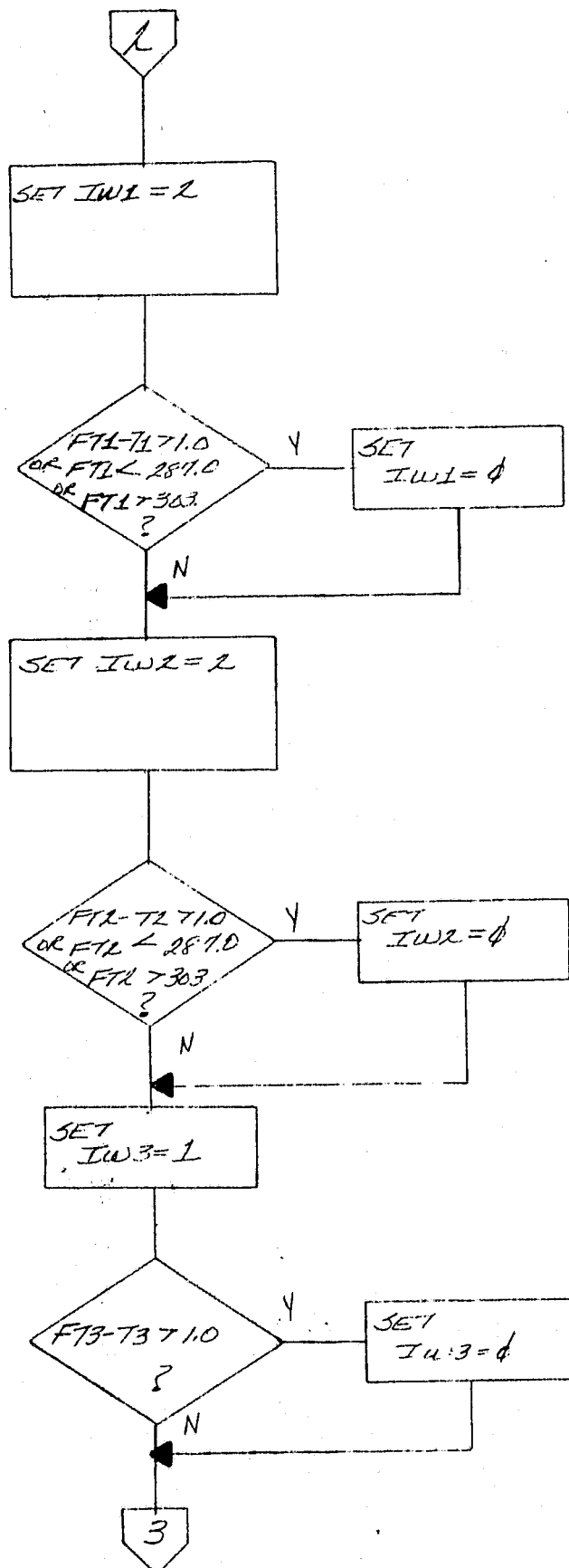


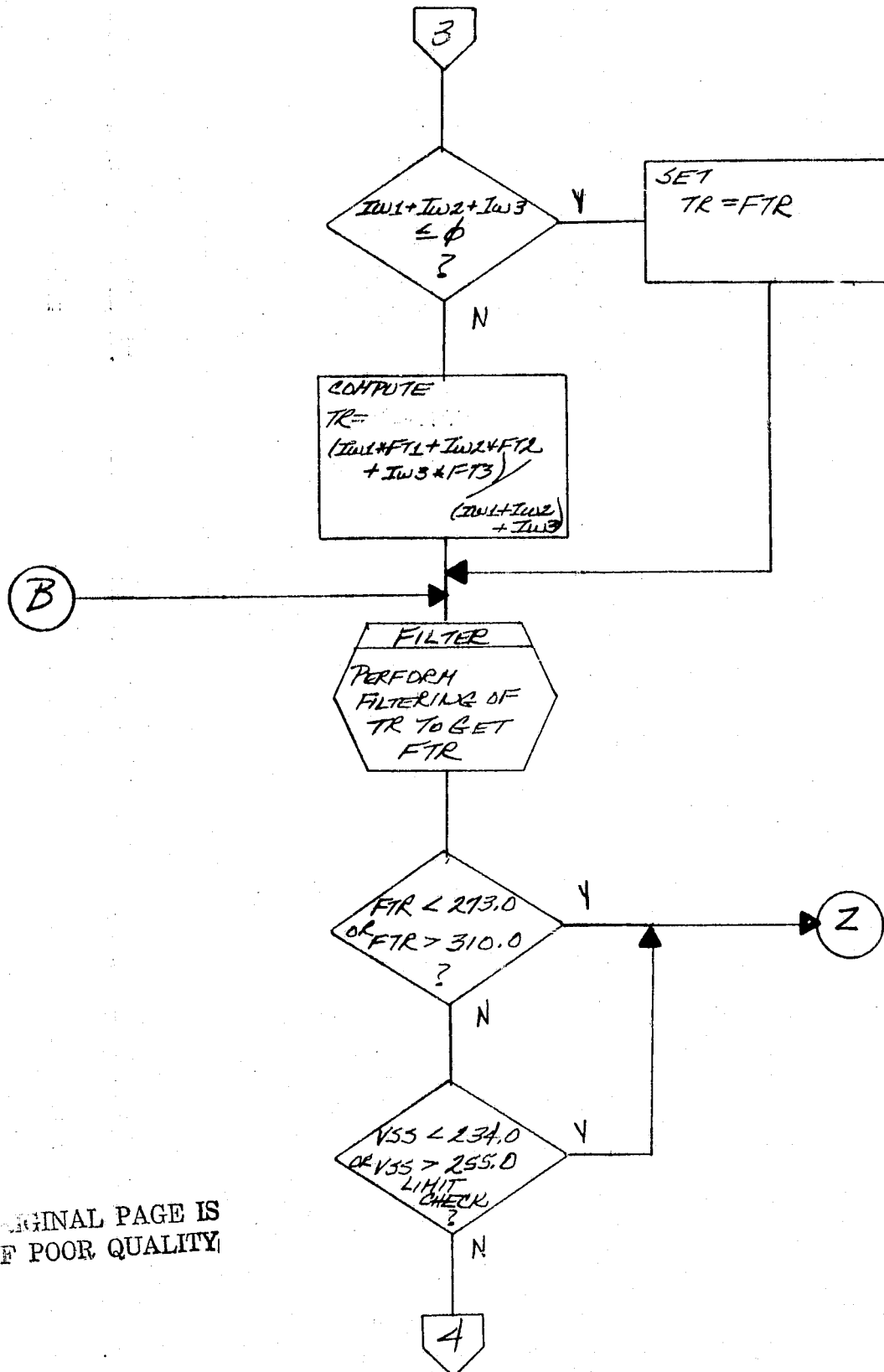




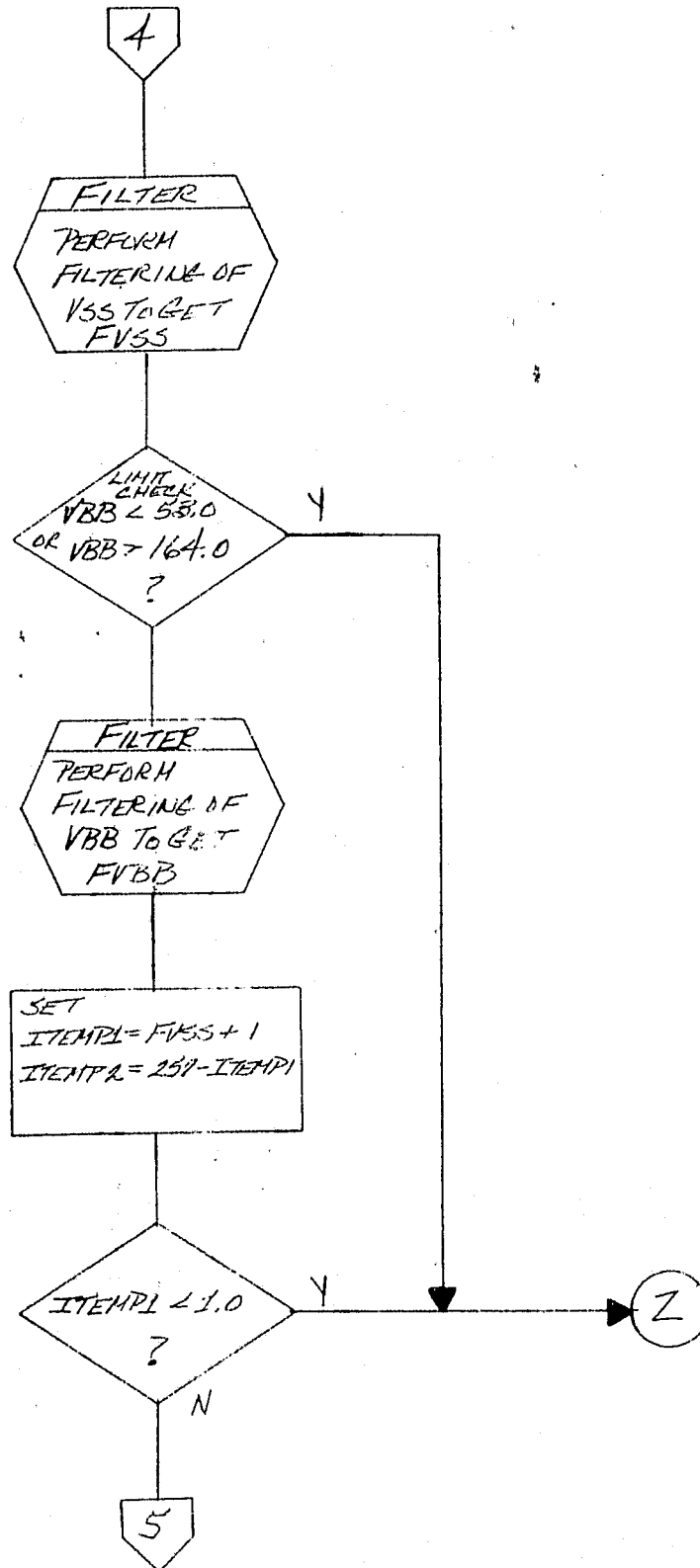
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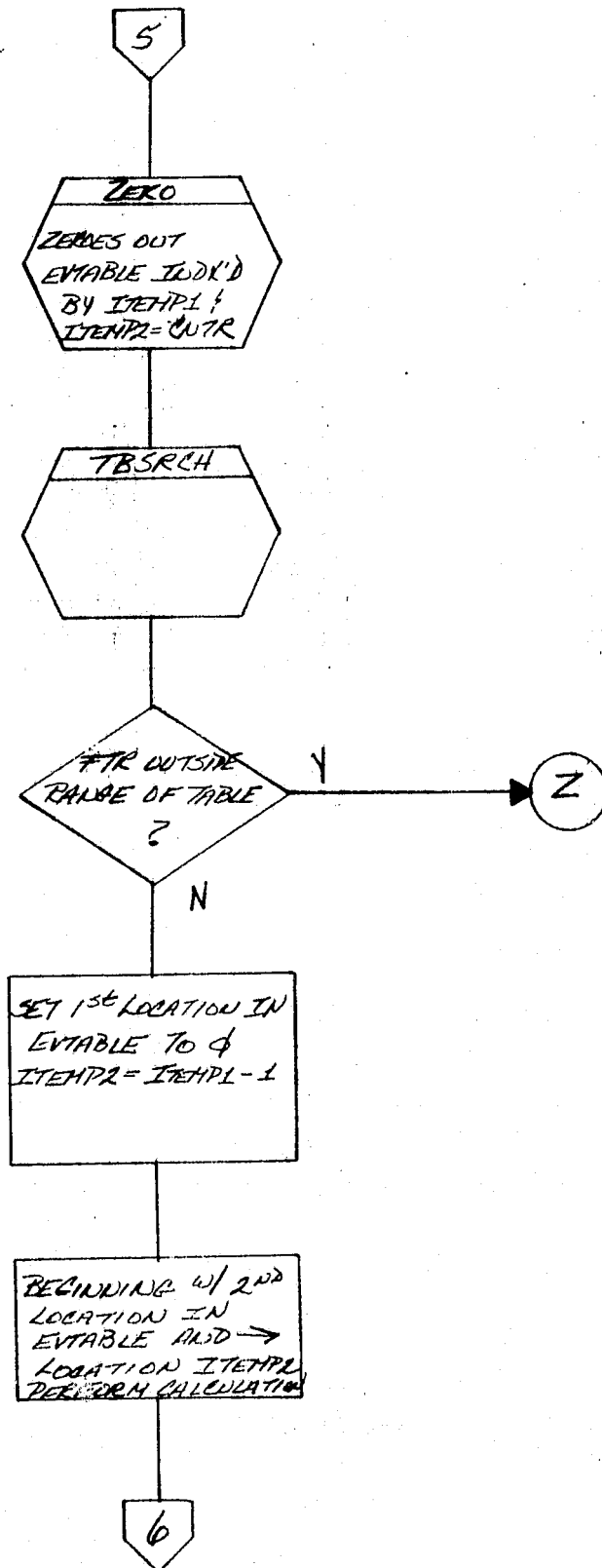


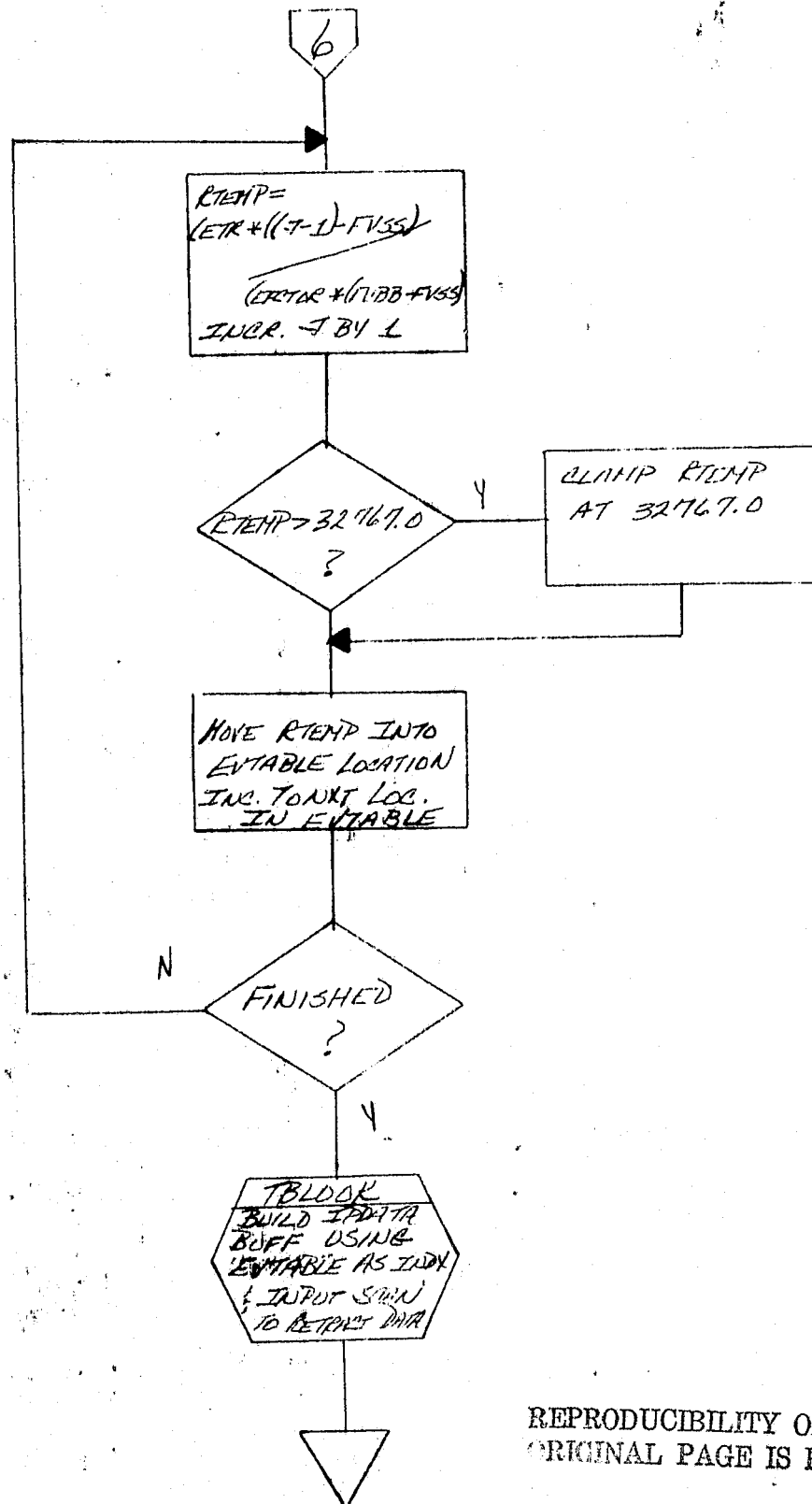




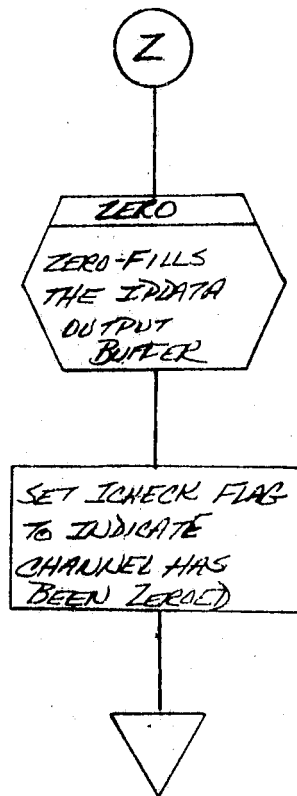
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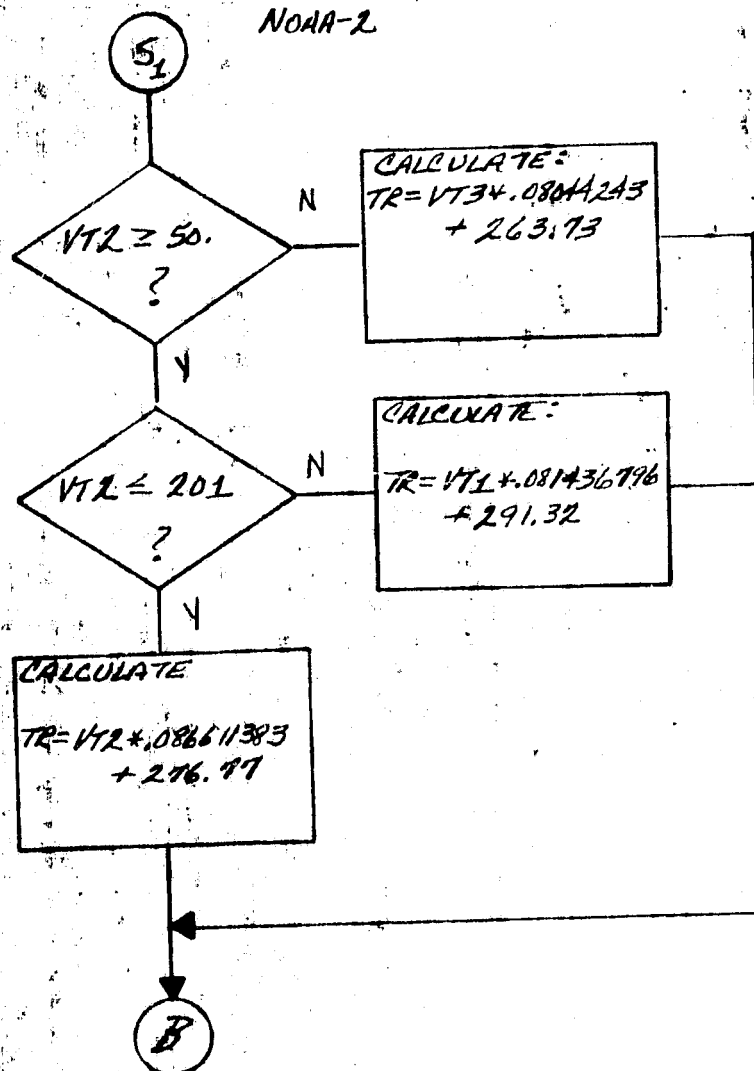




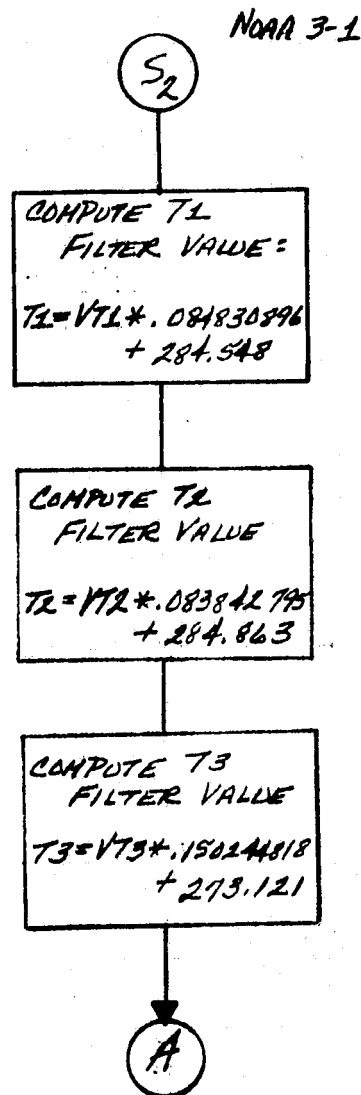


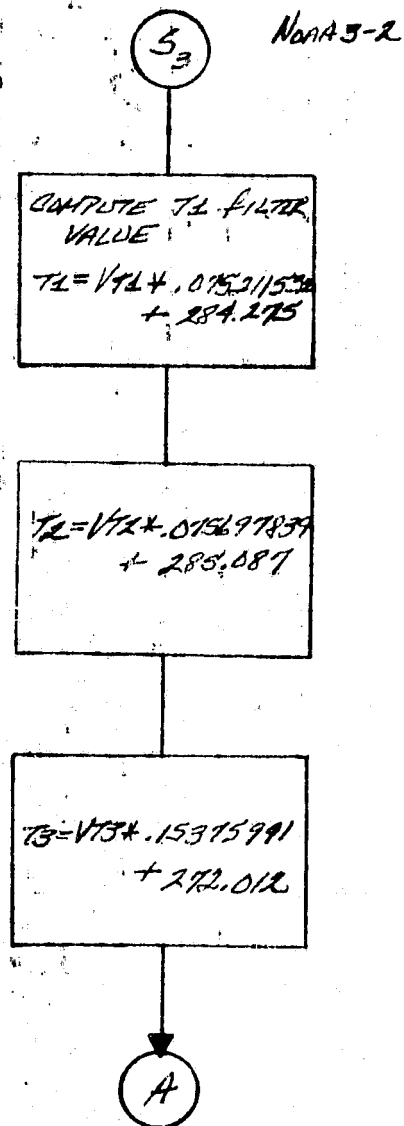
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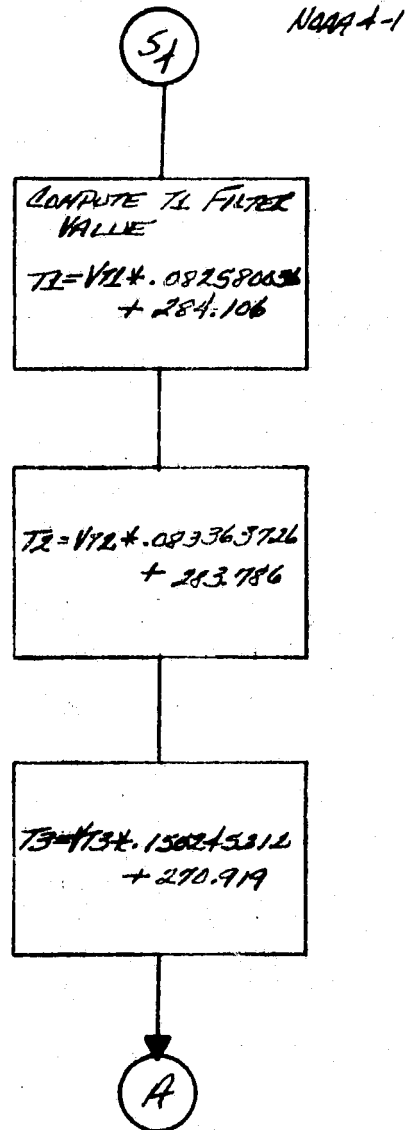


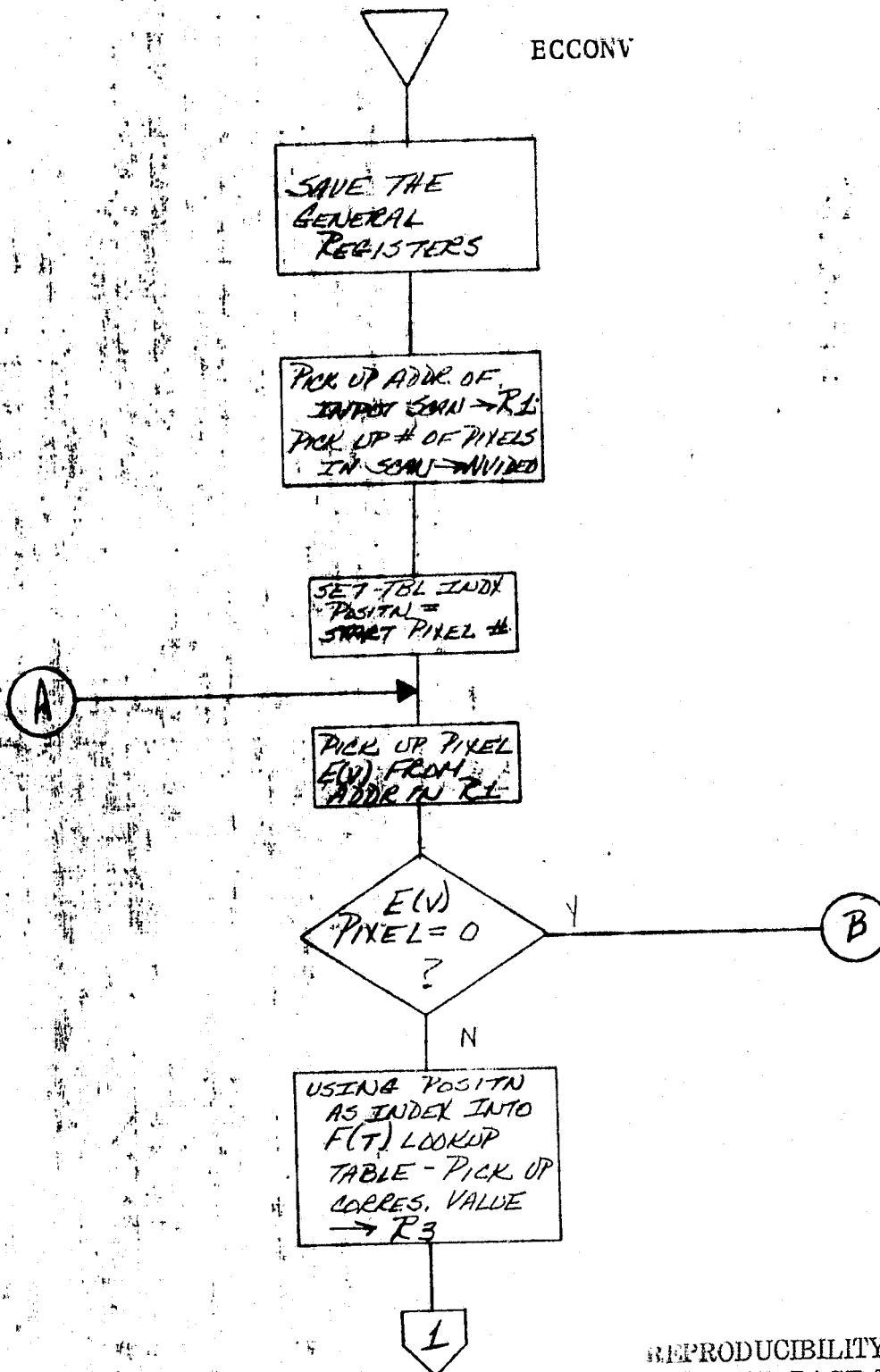


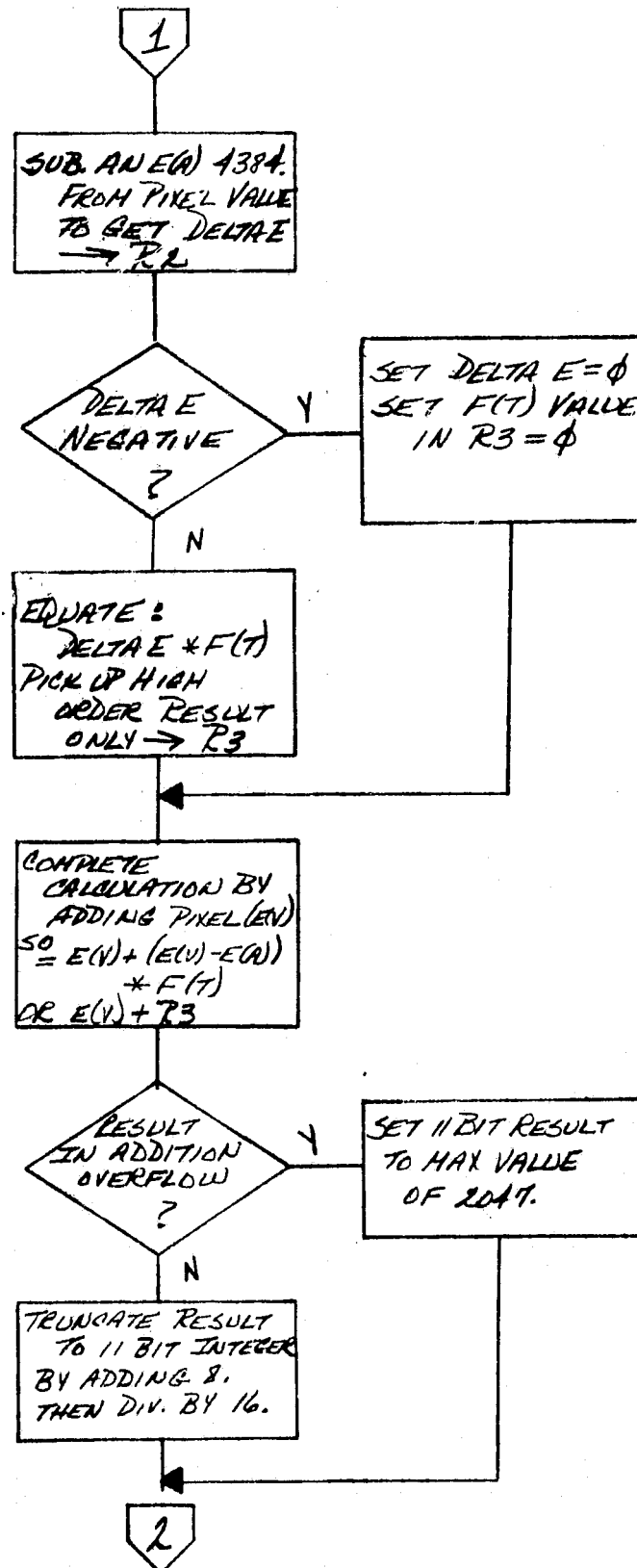
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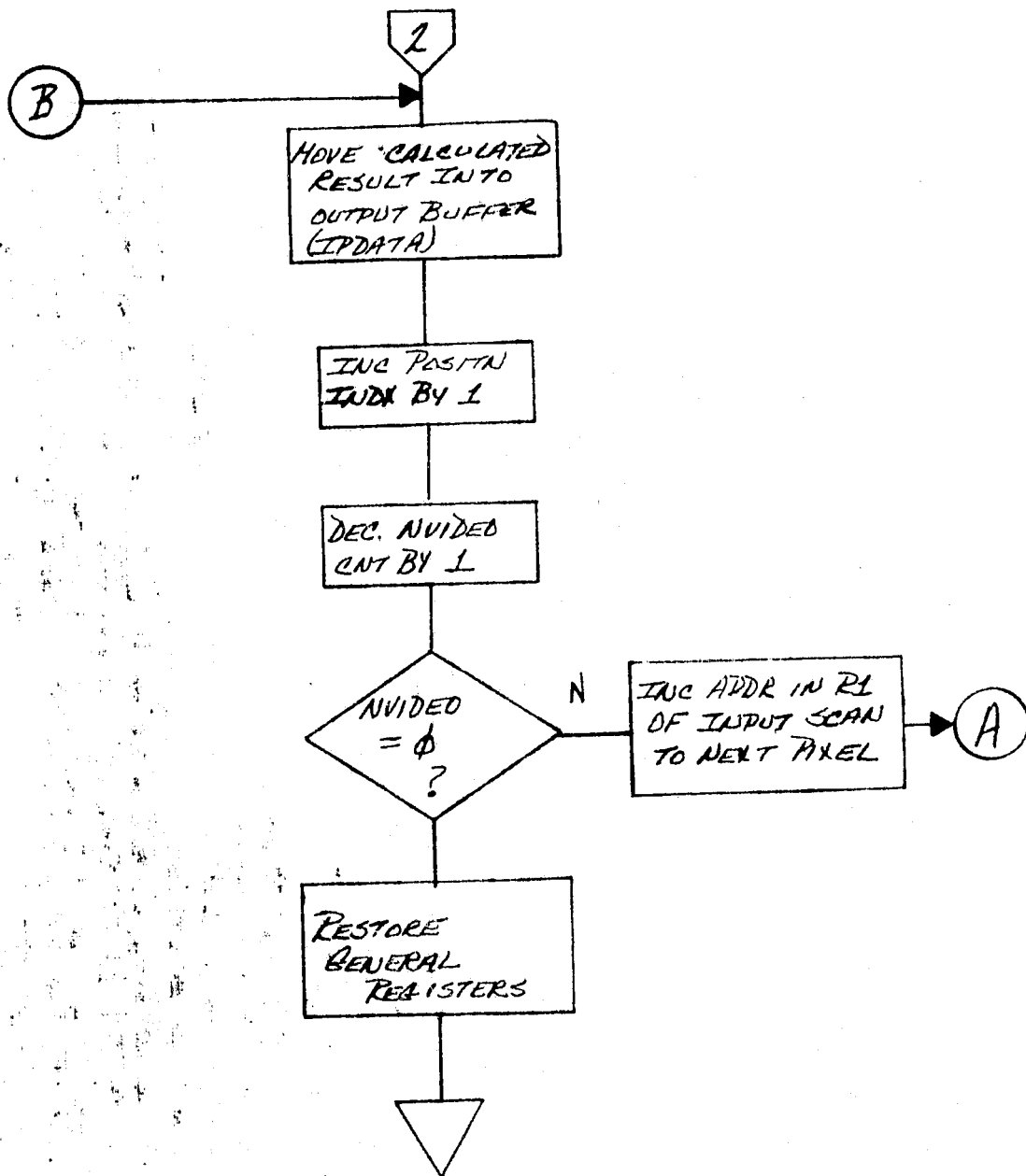


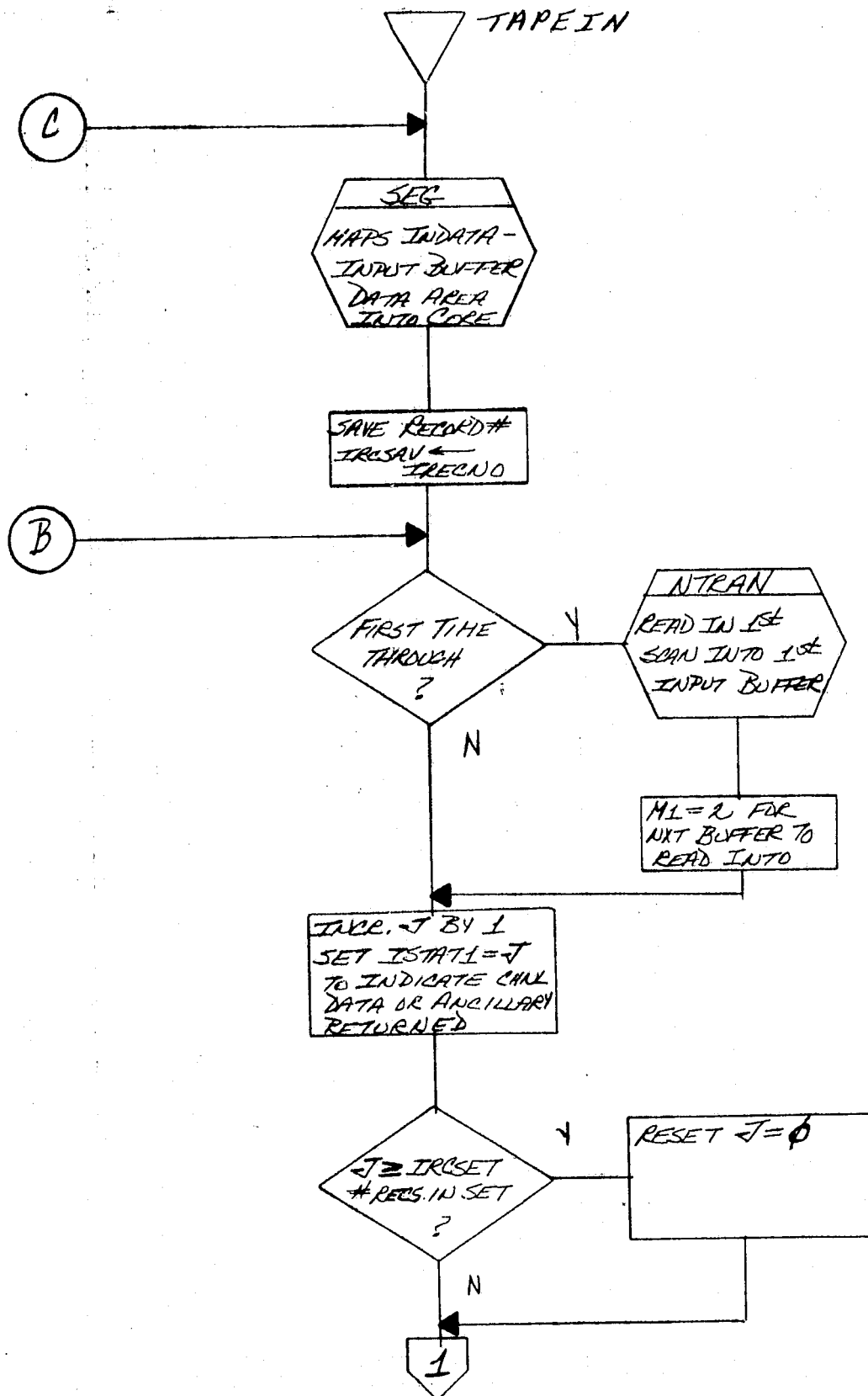


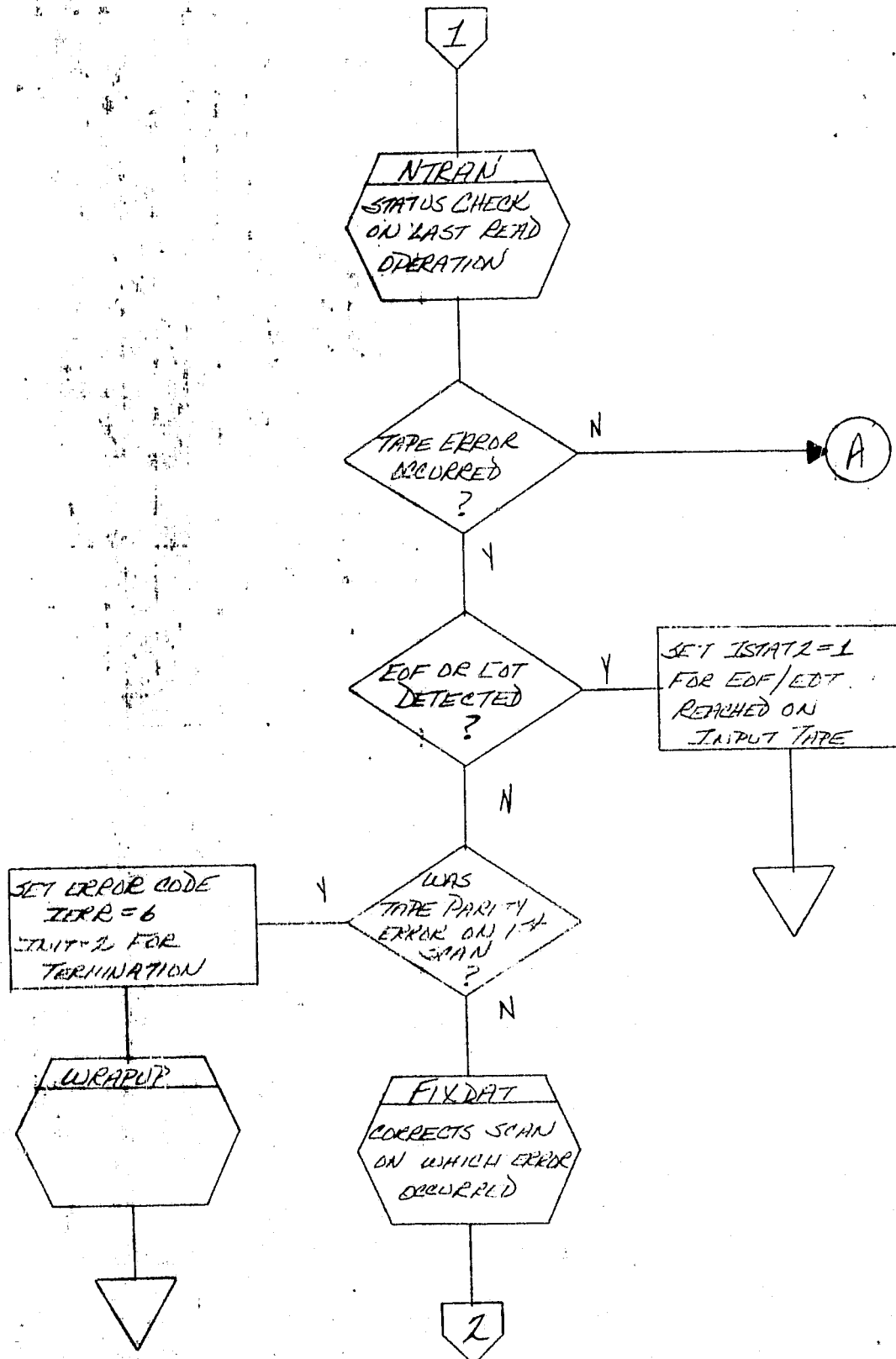


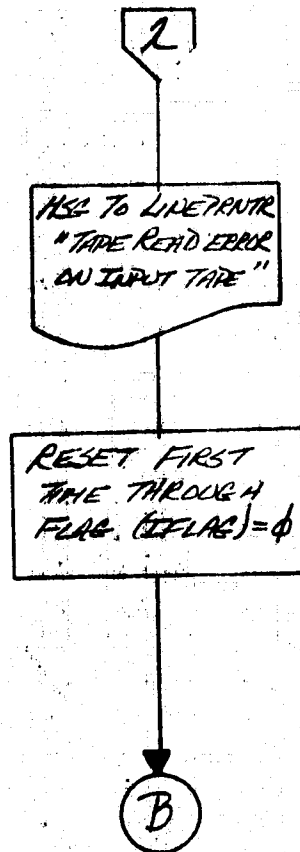




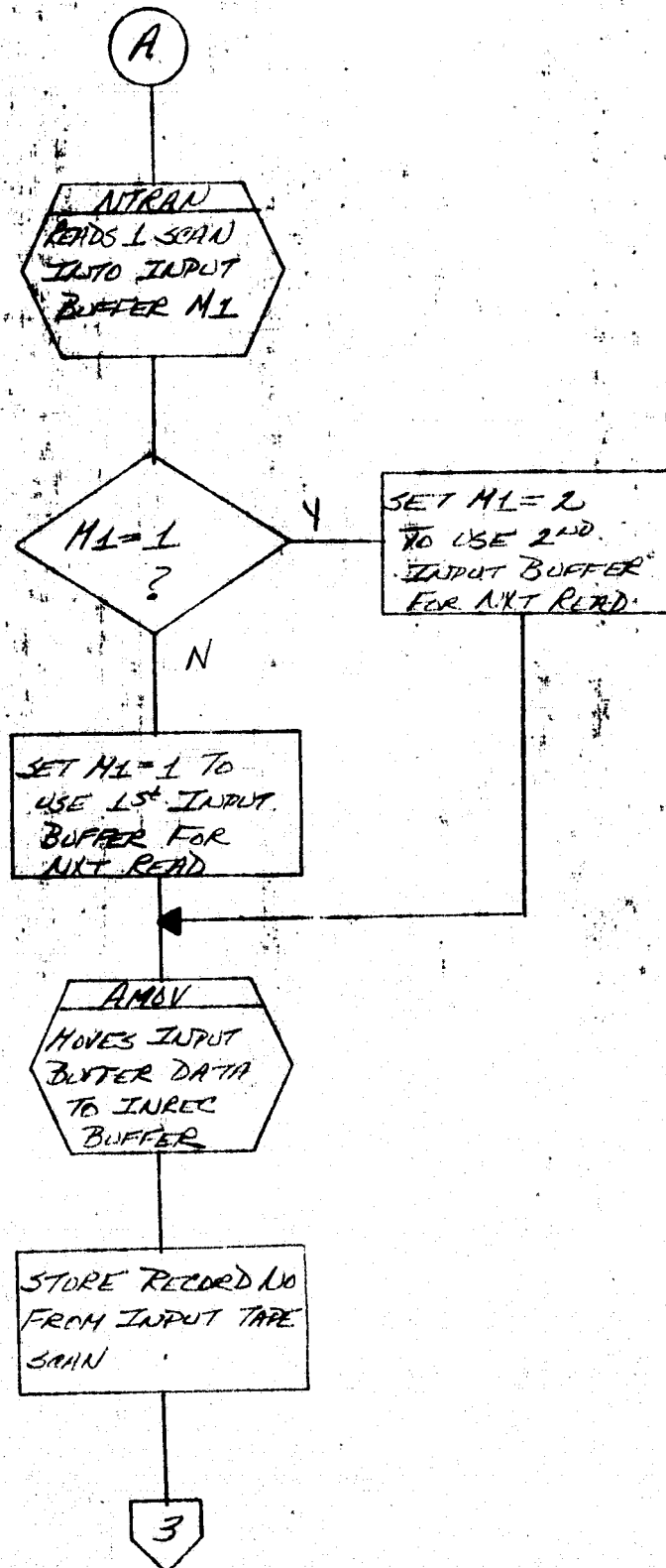




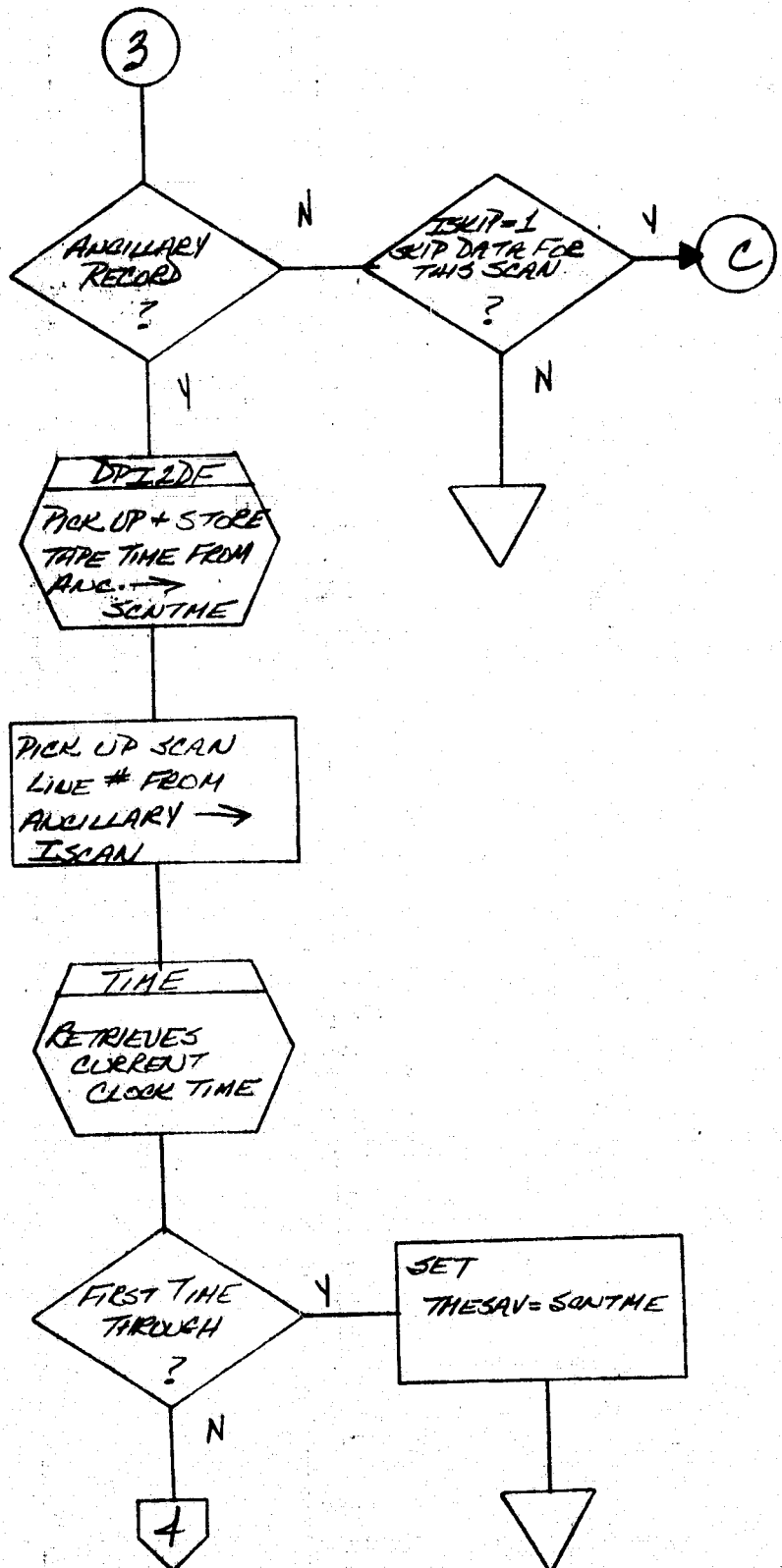




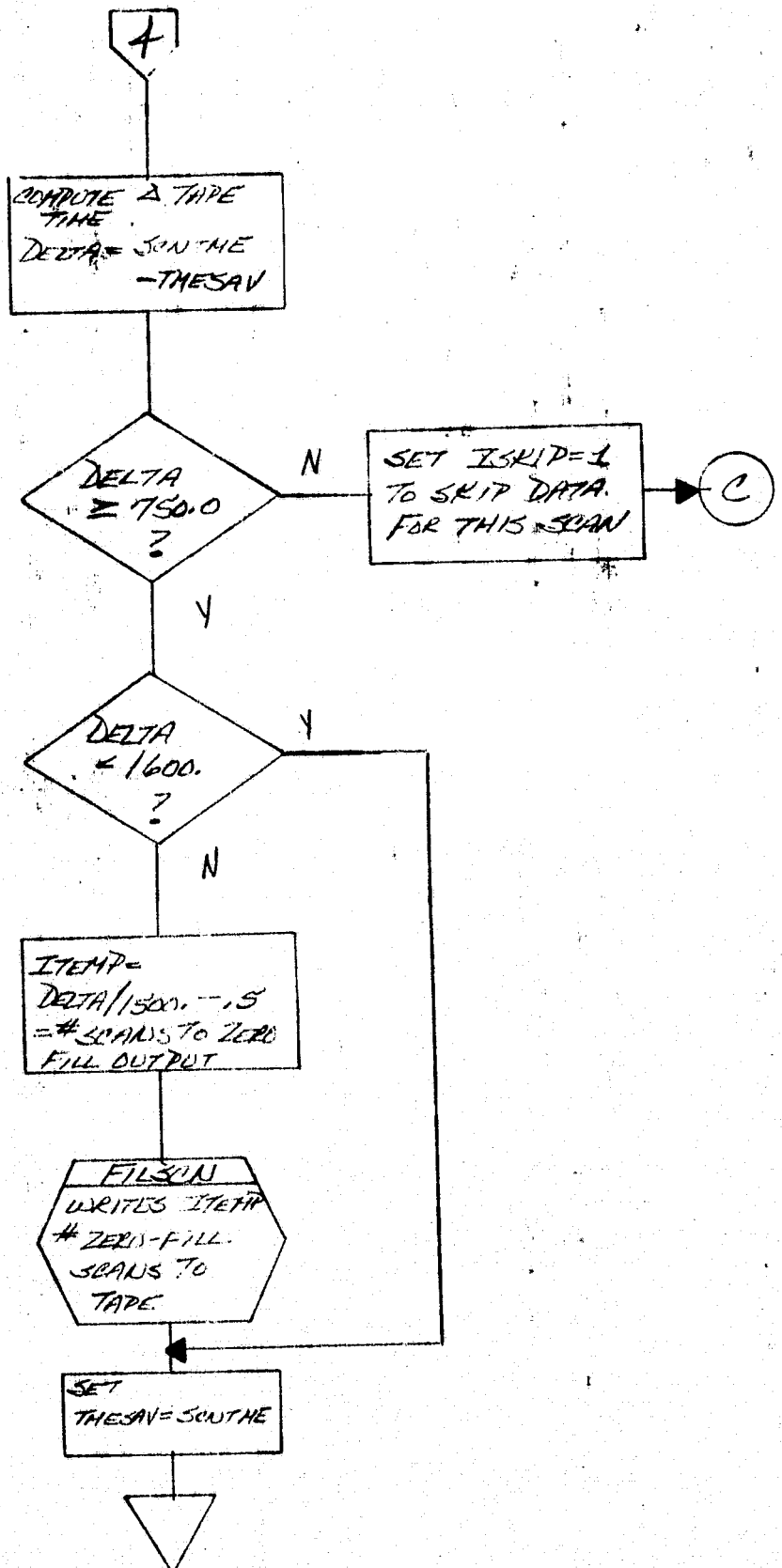
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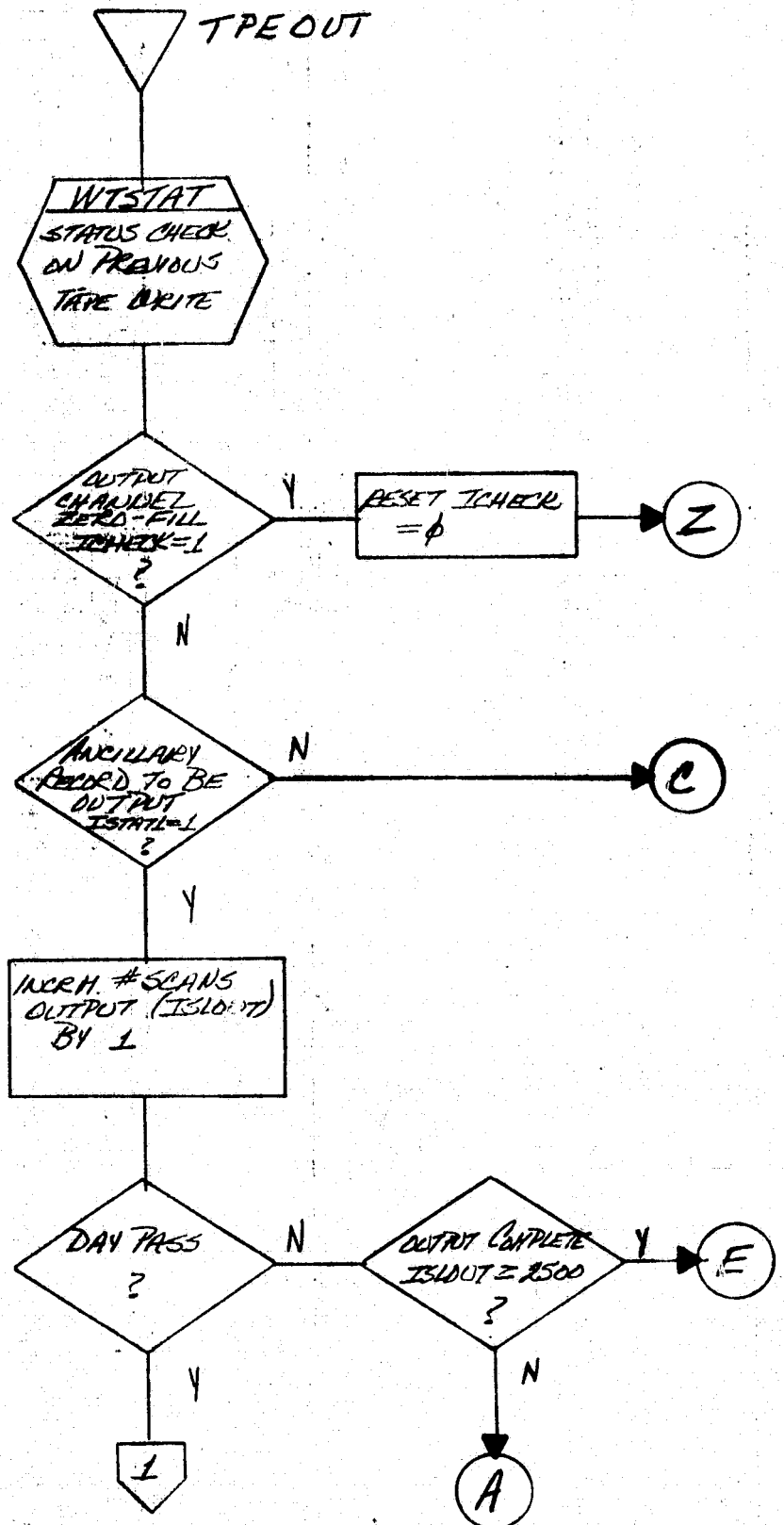


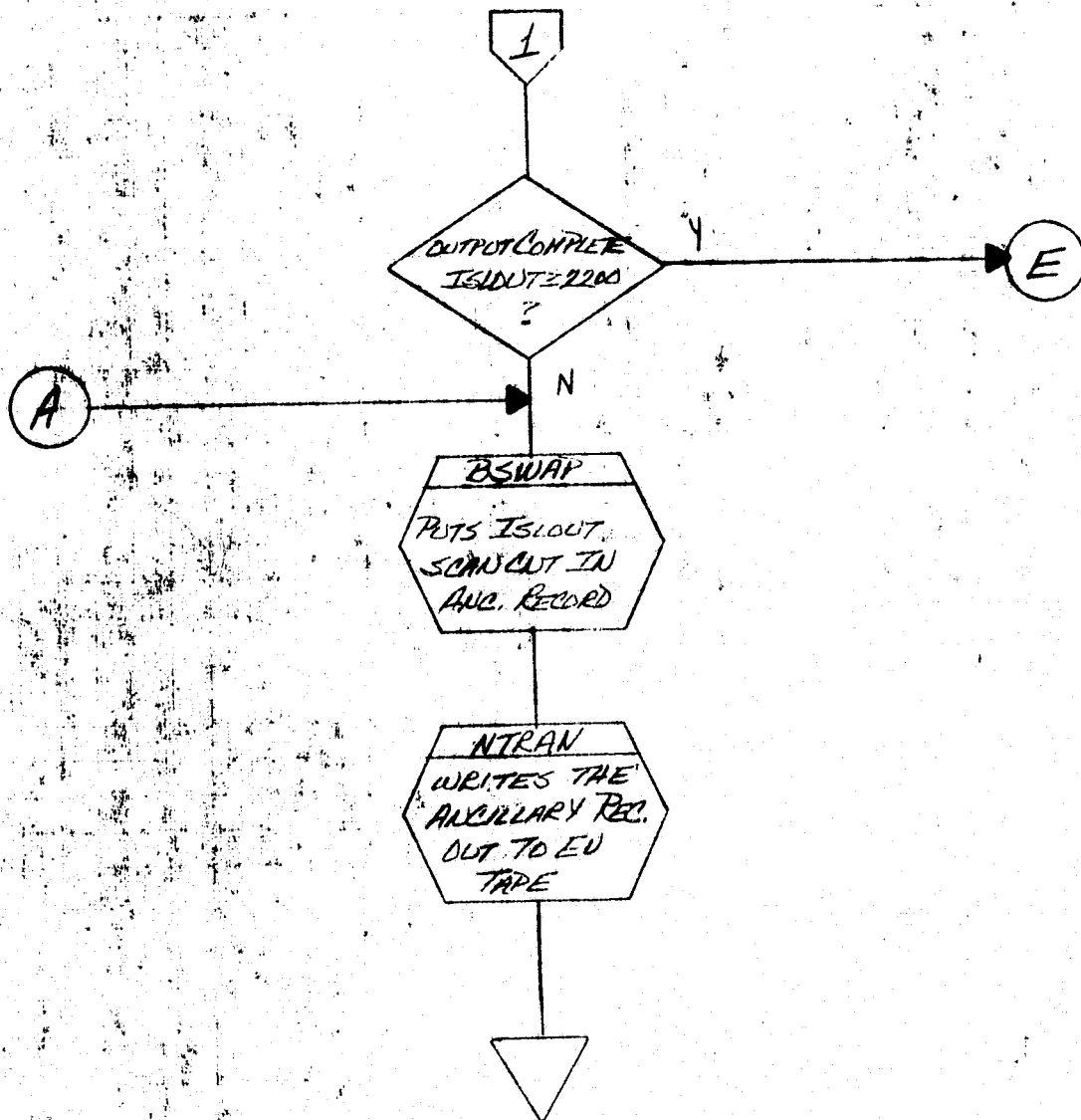
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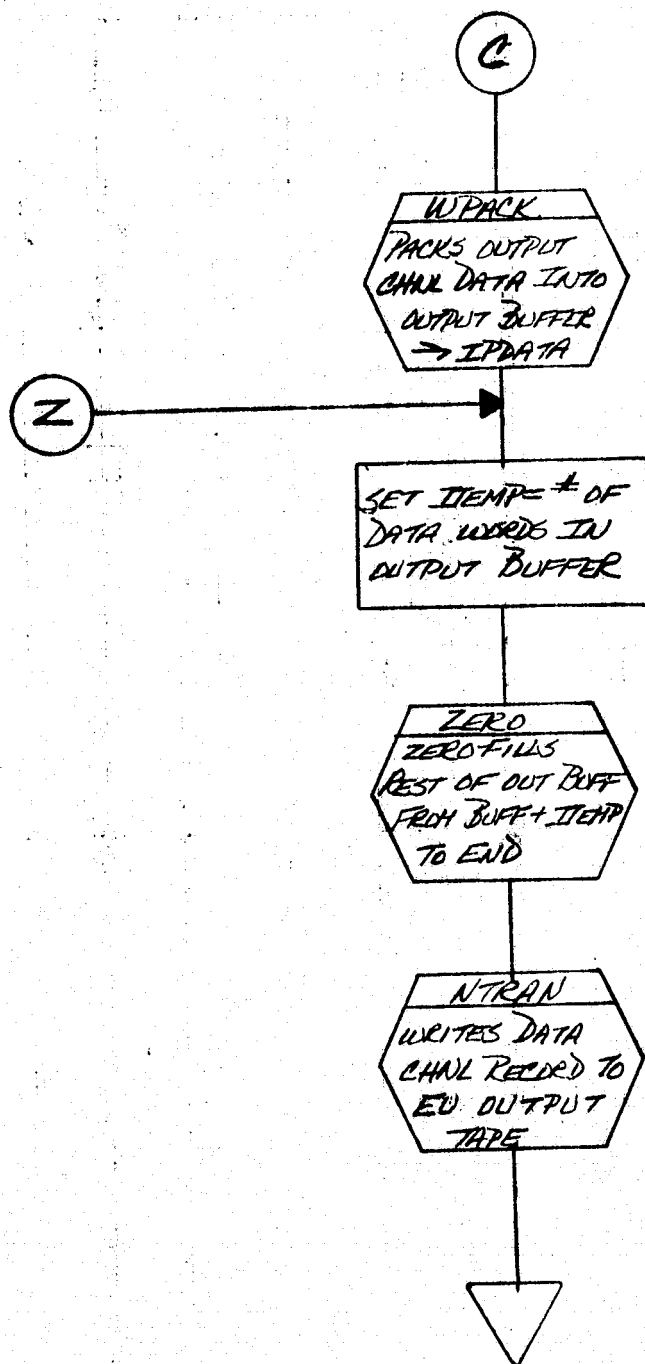


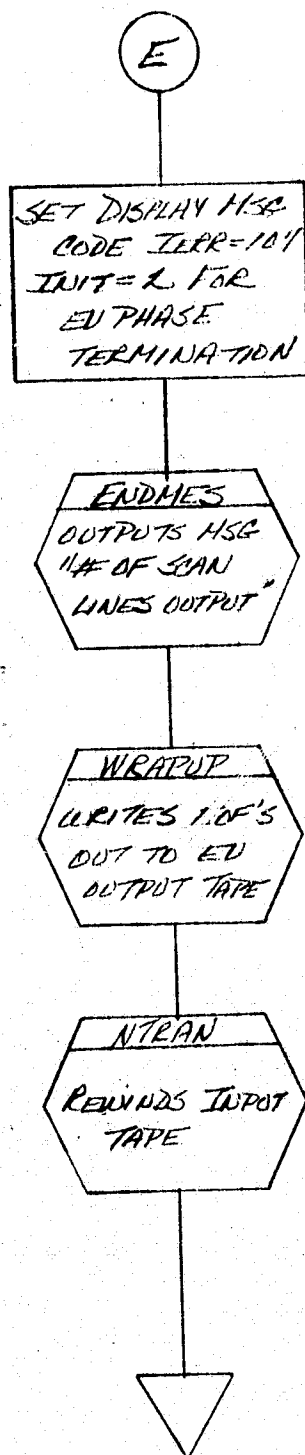
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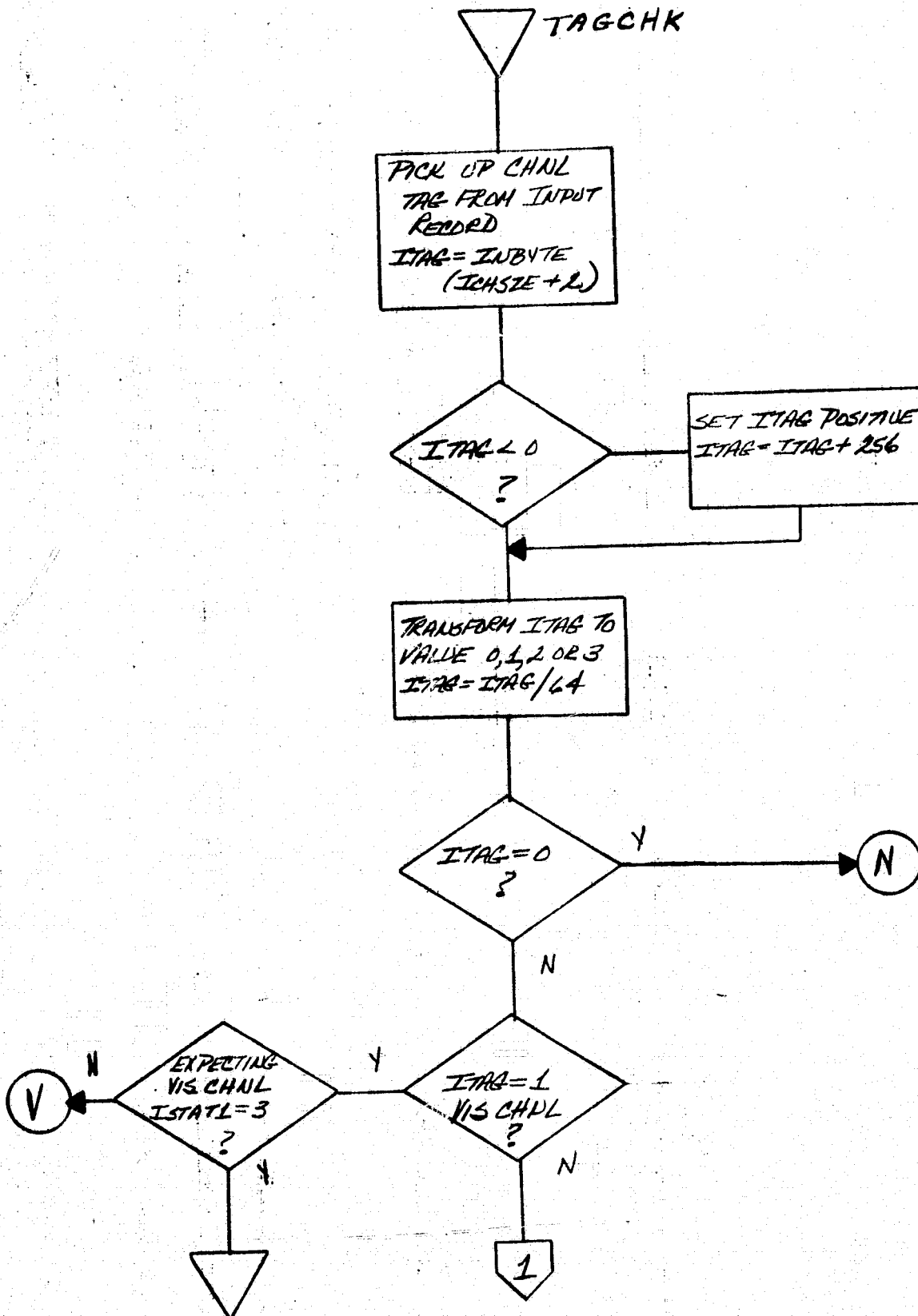


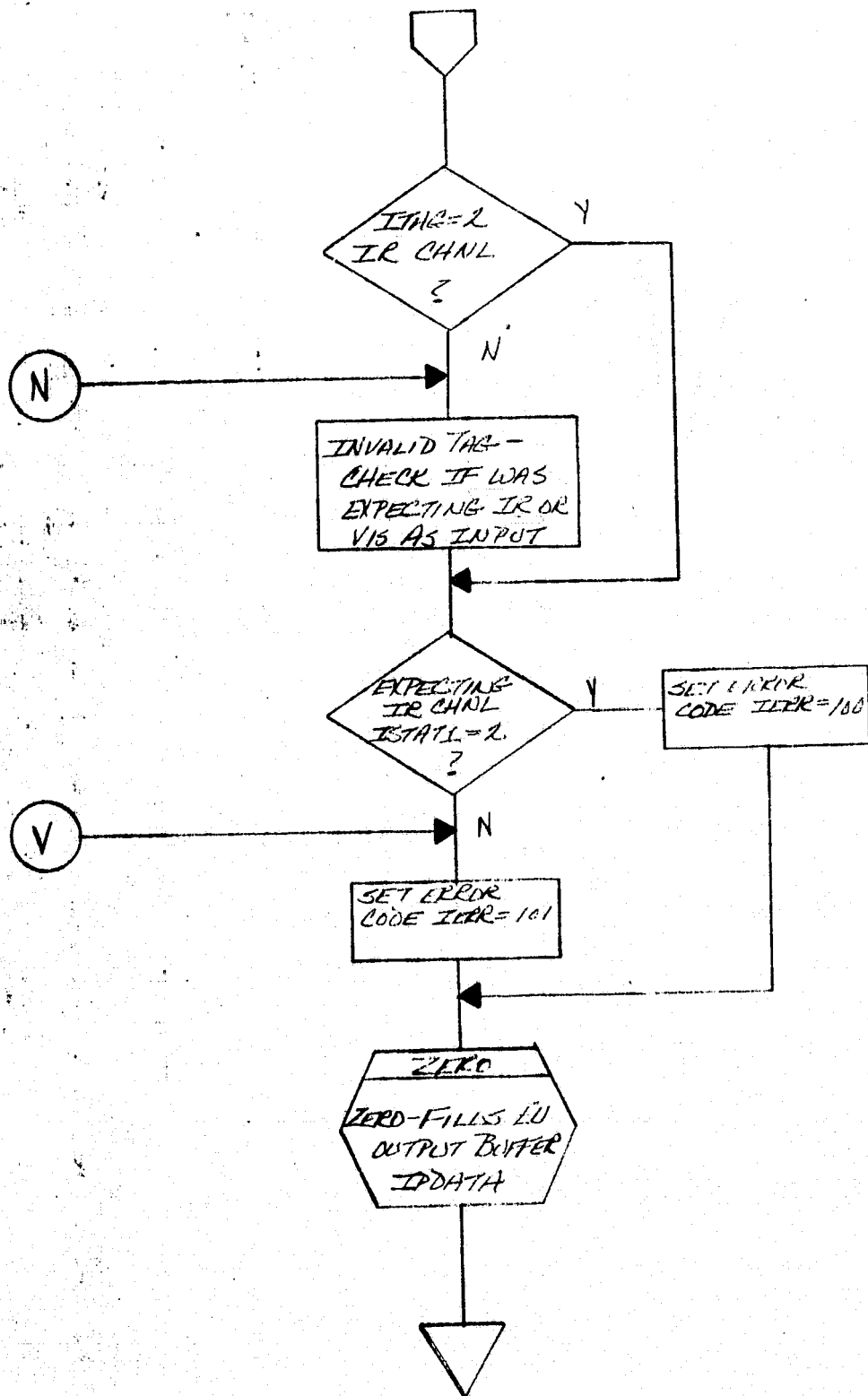


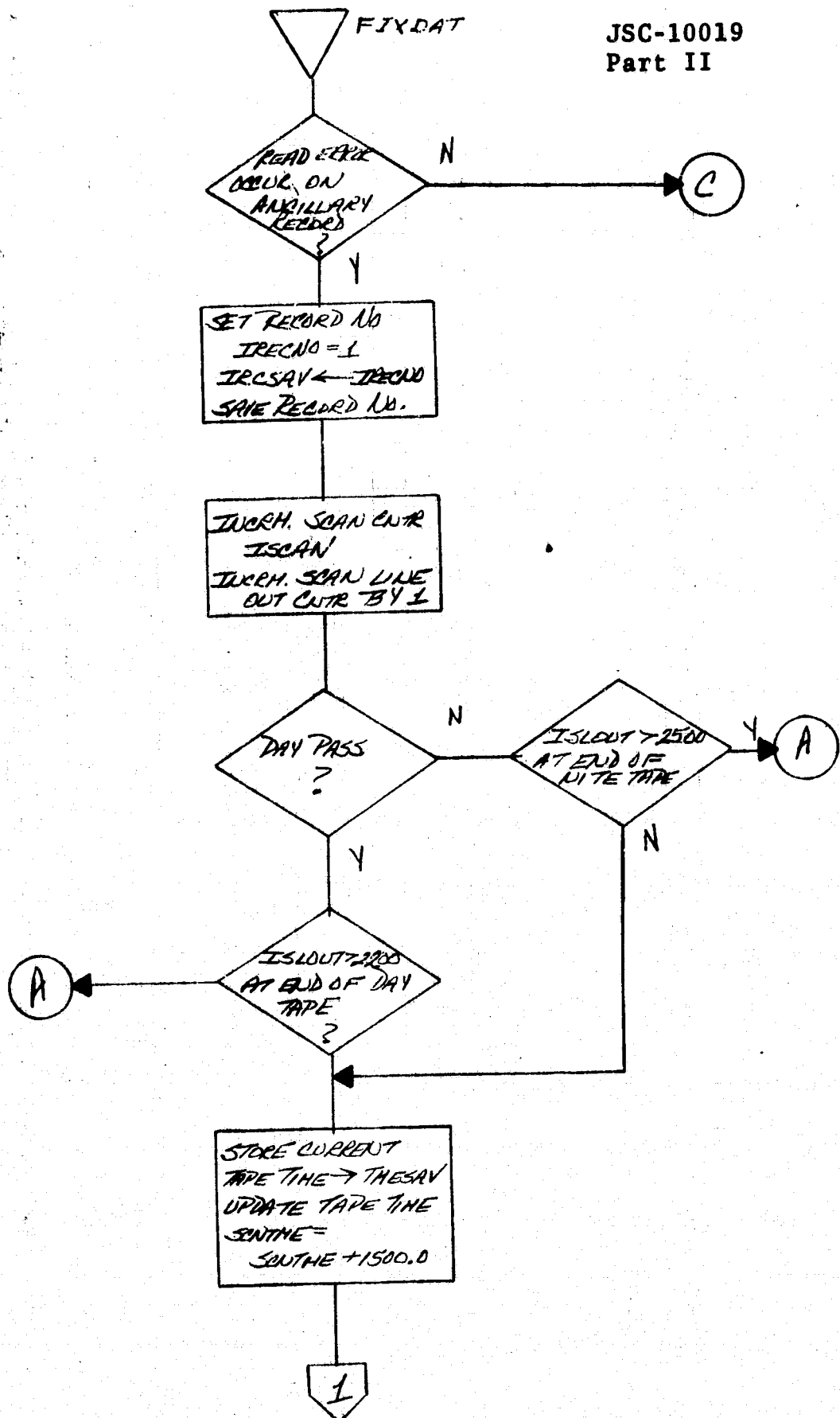




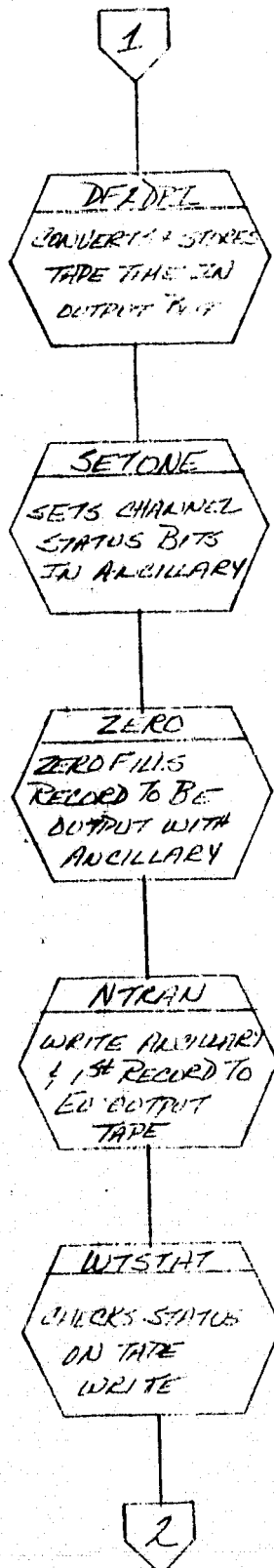
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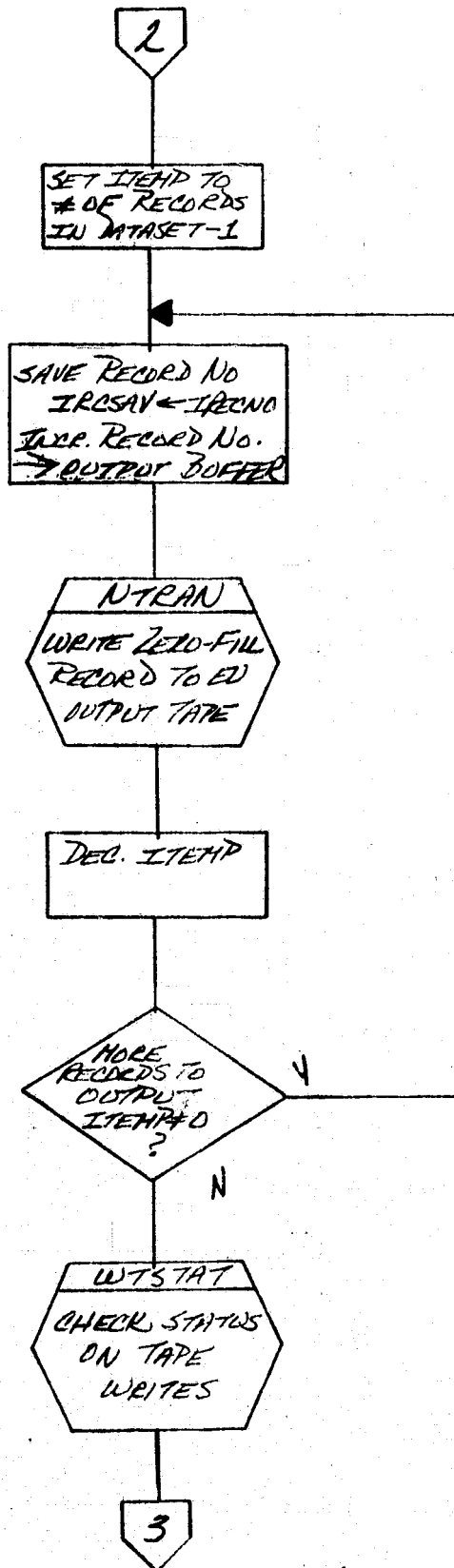


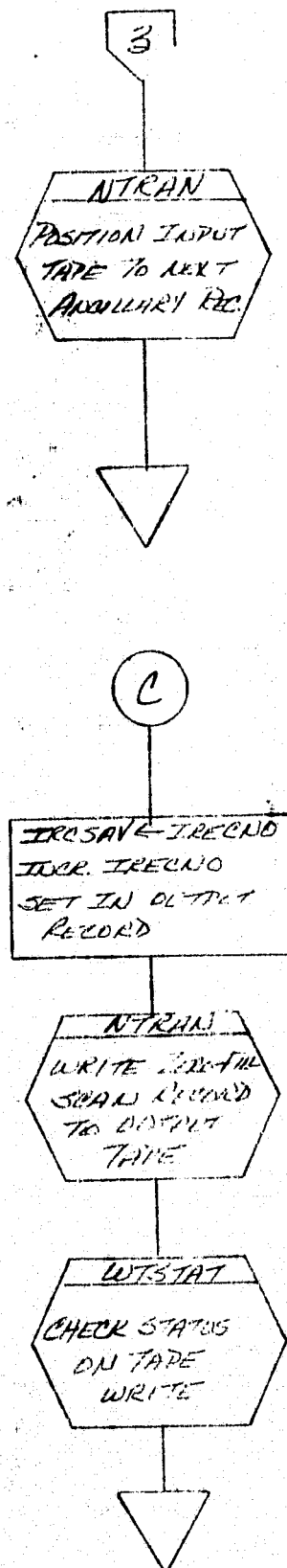


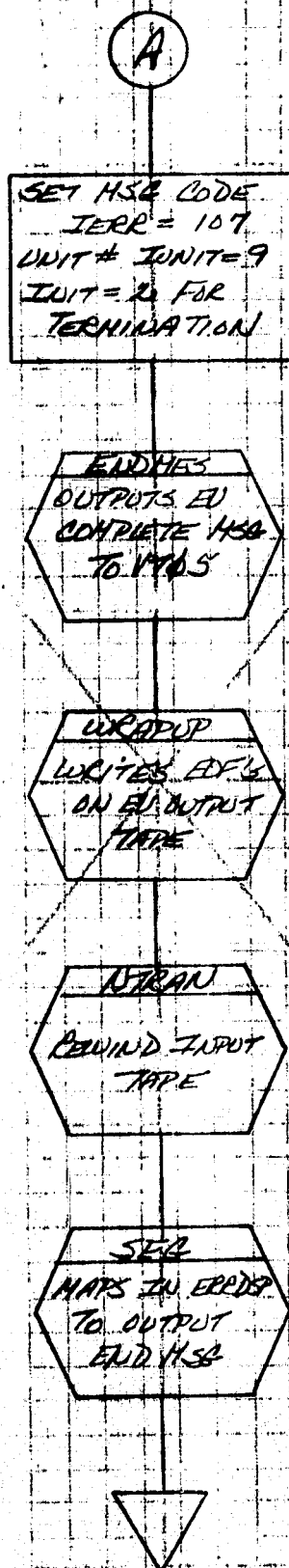


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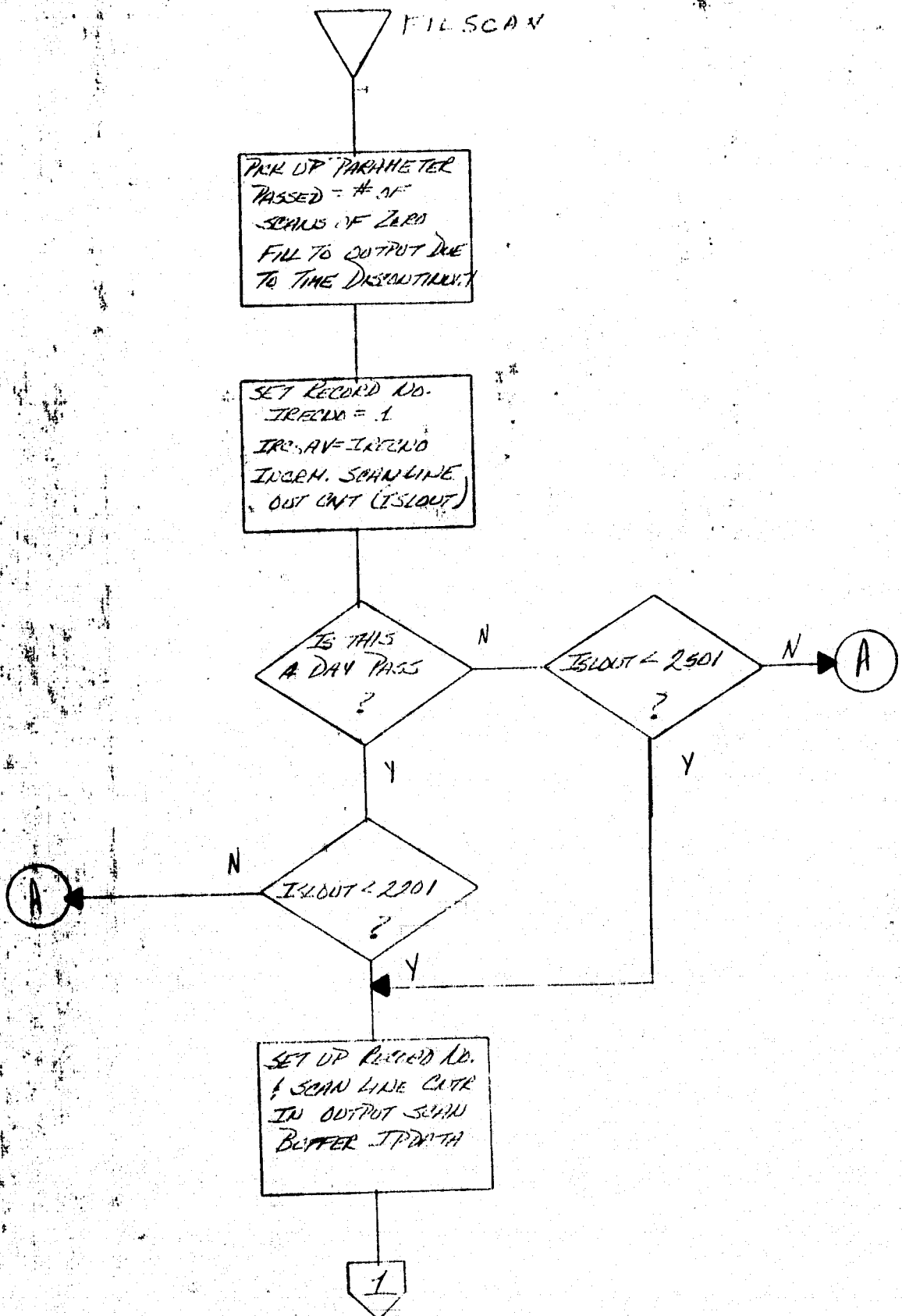


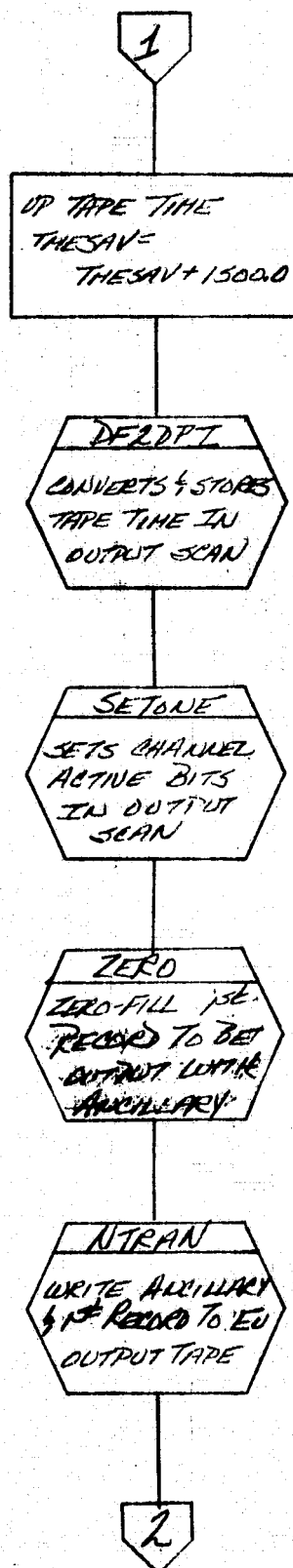


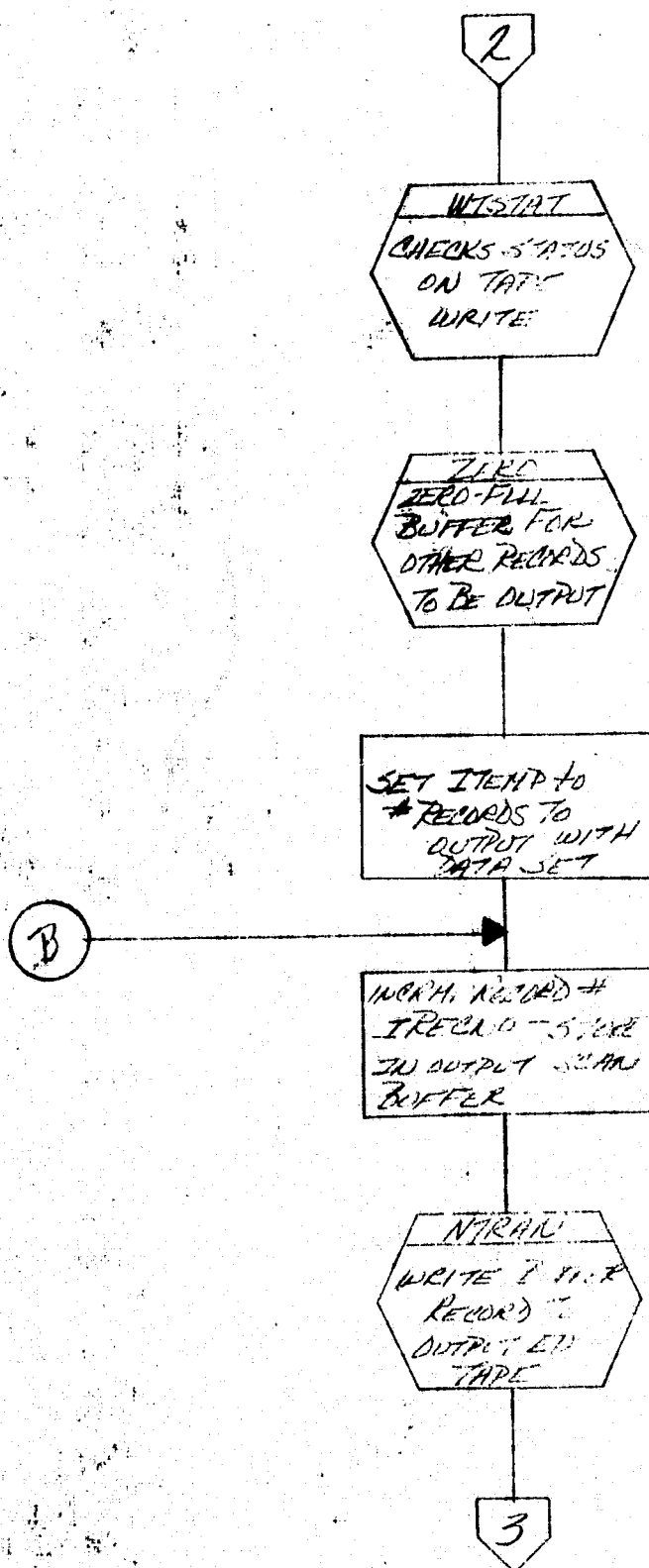


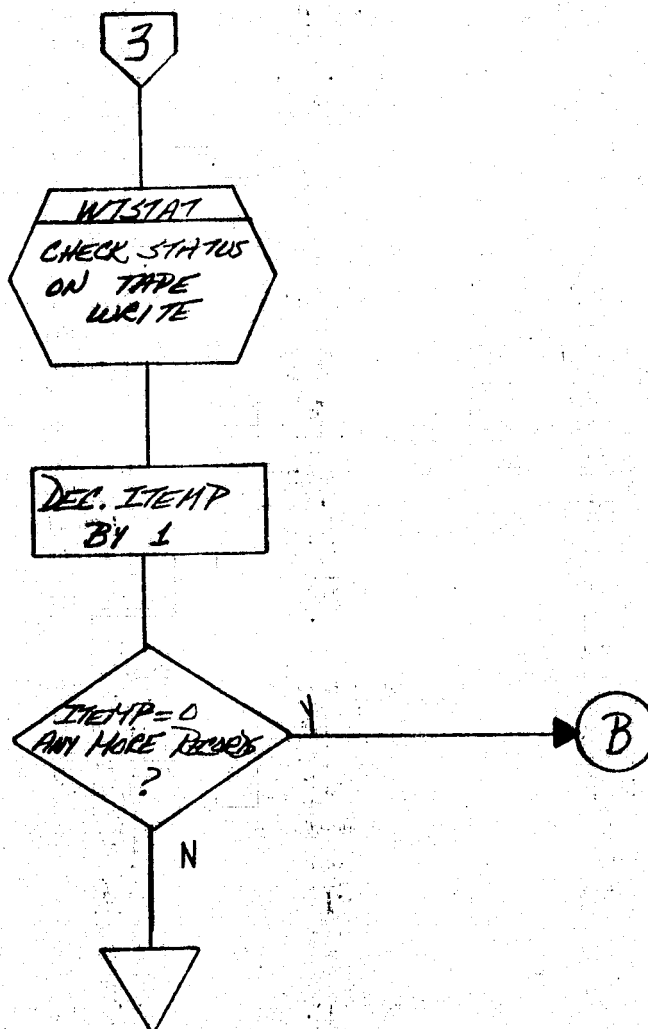


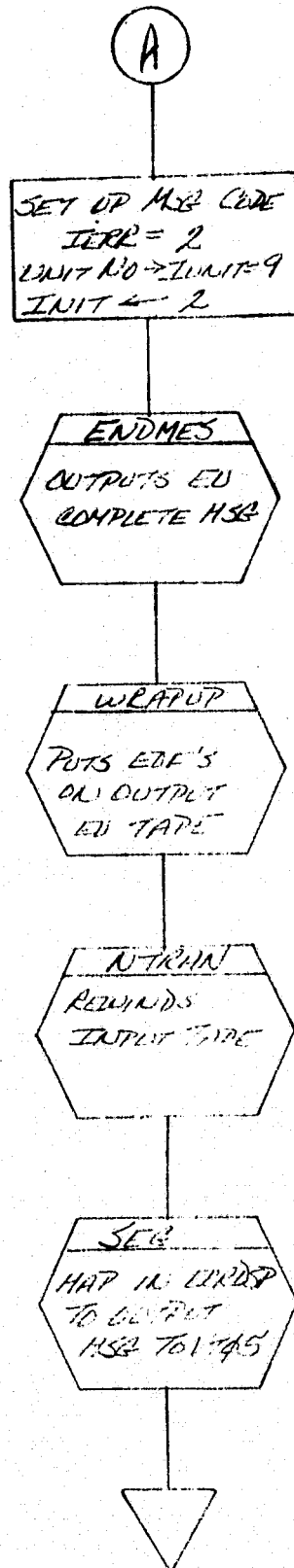
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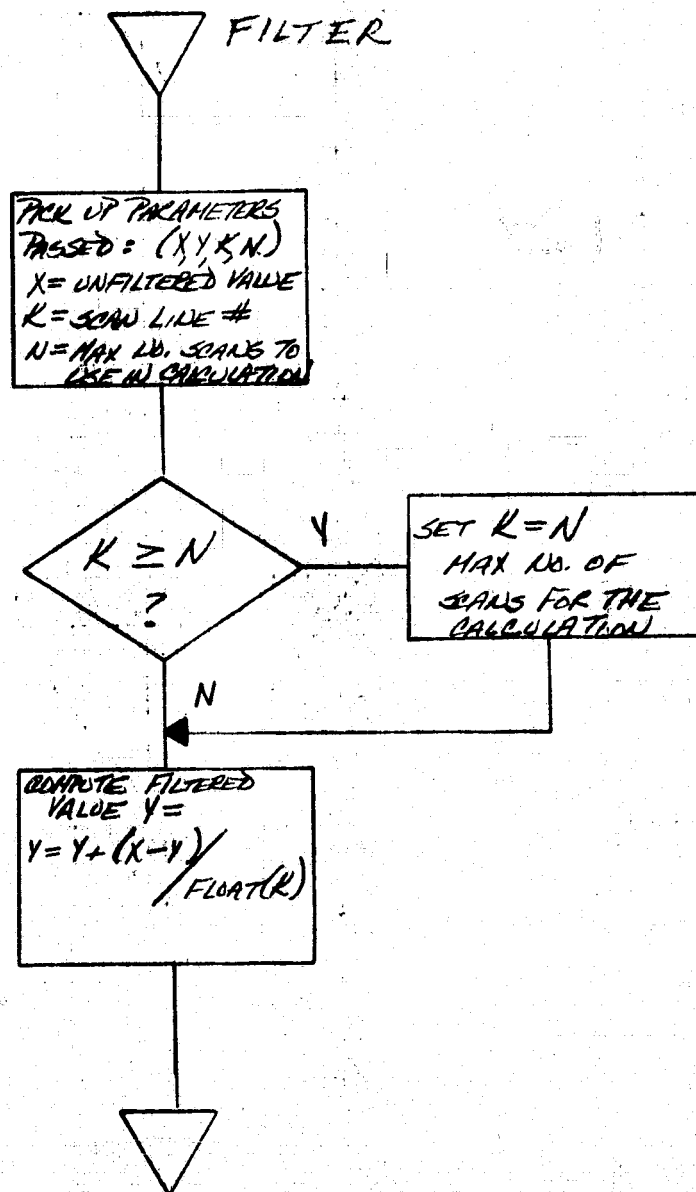


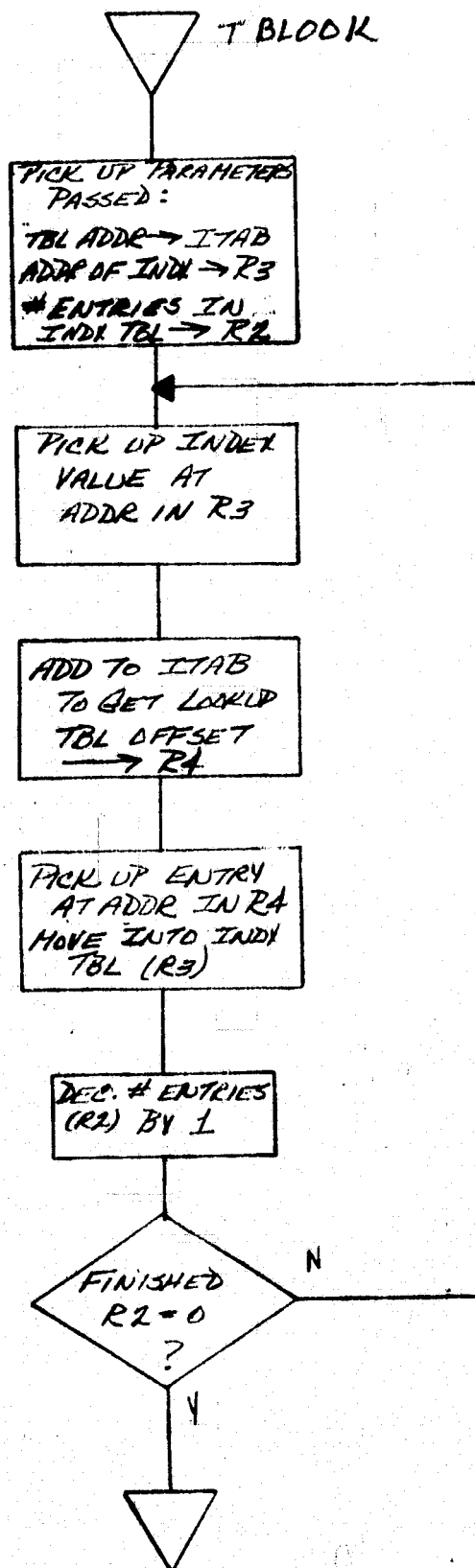


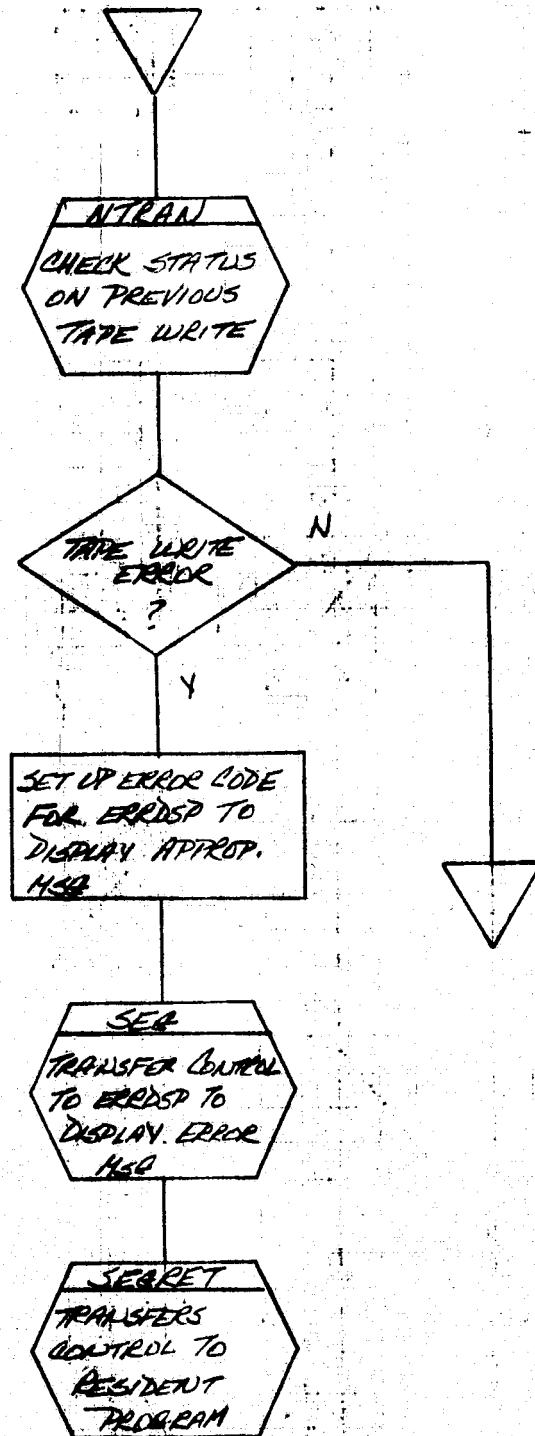












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2.2.1.3 Interfaces. This paragraph describes the interfaces of the SEUCON CPC with the other CPC's, the input and output data external to the CPC, and the interfaces of the CPC with its own subcomponents.

A. Input Data

1. Raw PCM 9-Track Tape. See figure 2-7 and table 2-2 for a description and content of the tape and format. The PCM input tape is read, one scan or record at a time, into the INDATA buffer. The ancillary record is read in, followed by the IR channel; if this is a day tape, the VIS channel is read in after the IR.
2. CALBUF. This is a three-table data file set up by CALDAT CPC that contains:
 - T table, absolute temperatures
 - E(T) table, energy values corresponding to the absolute temperatures (T)
 - ITETAB table, a 2048-place table of 8-bit temperature codes to be used as a table lookup.

See figure 2-5 for a layout of the CALBUF data file.

3. FTABUF. This is a 3523-place fixed-scale table containing 16-bit $F(\alpha_0, \theta)$ values to be used as a table lookup. This input data file is set up by the CALDAT CPC to be used in SEUCON processing.

- B. Output Data. The only output data of the SEUCON CPC is a 9-track EU processed tape. It contains 2200 data sets (or scans) for a day pass tape and 2500 data sets for a night pass tape. Each day pass data set includes an ancillary record, IR channel record (EU-converted), and VIS channel record. Each night pass tape contains an ancillary record and IR channel record (EU-converted). See figure 2-8 and table 2-3 for a format layout of the EU output tape. This EU processed tape will be used as input to the registration phase of SEDS (see paragraph 3.1).

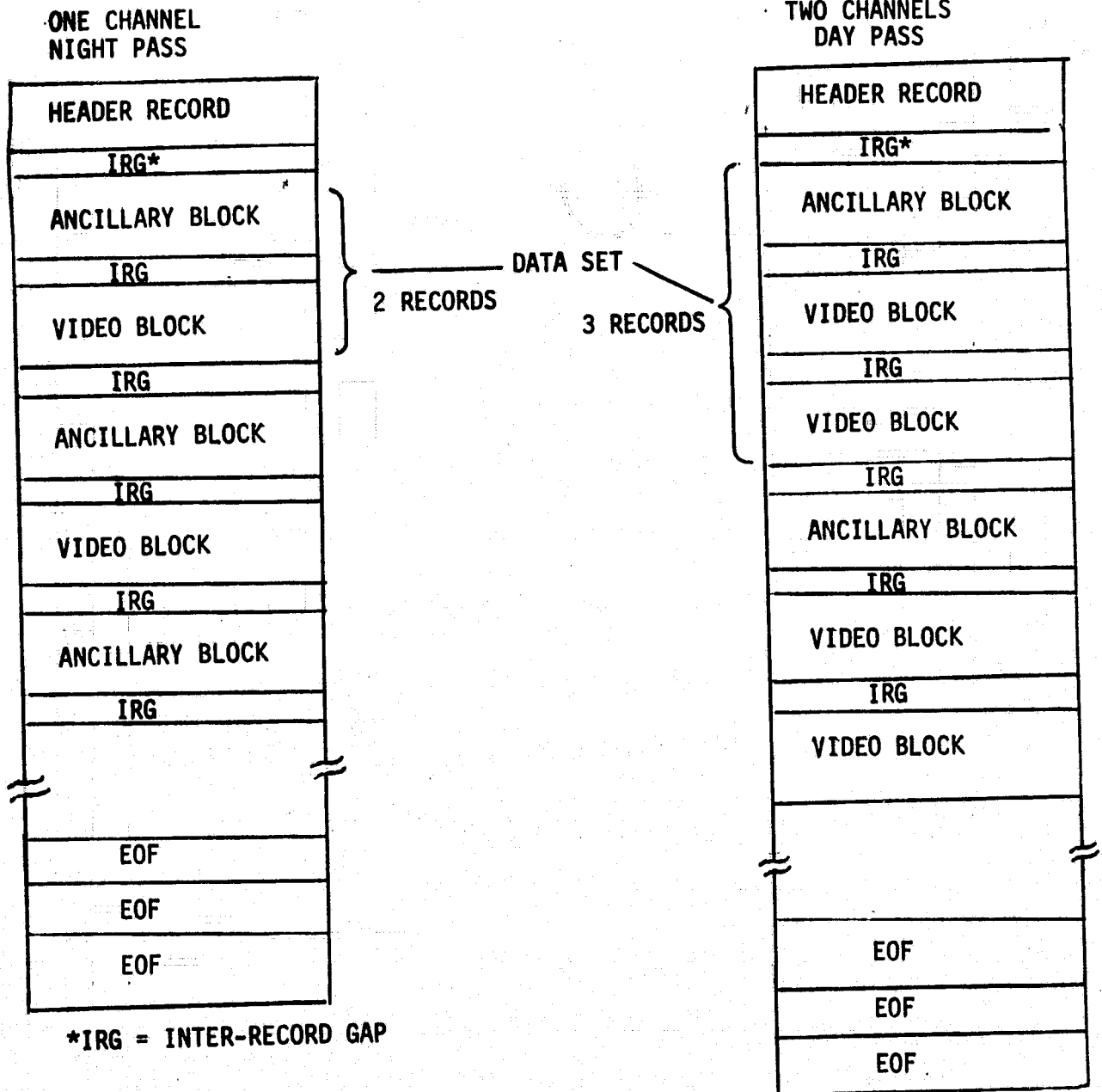
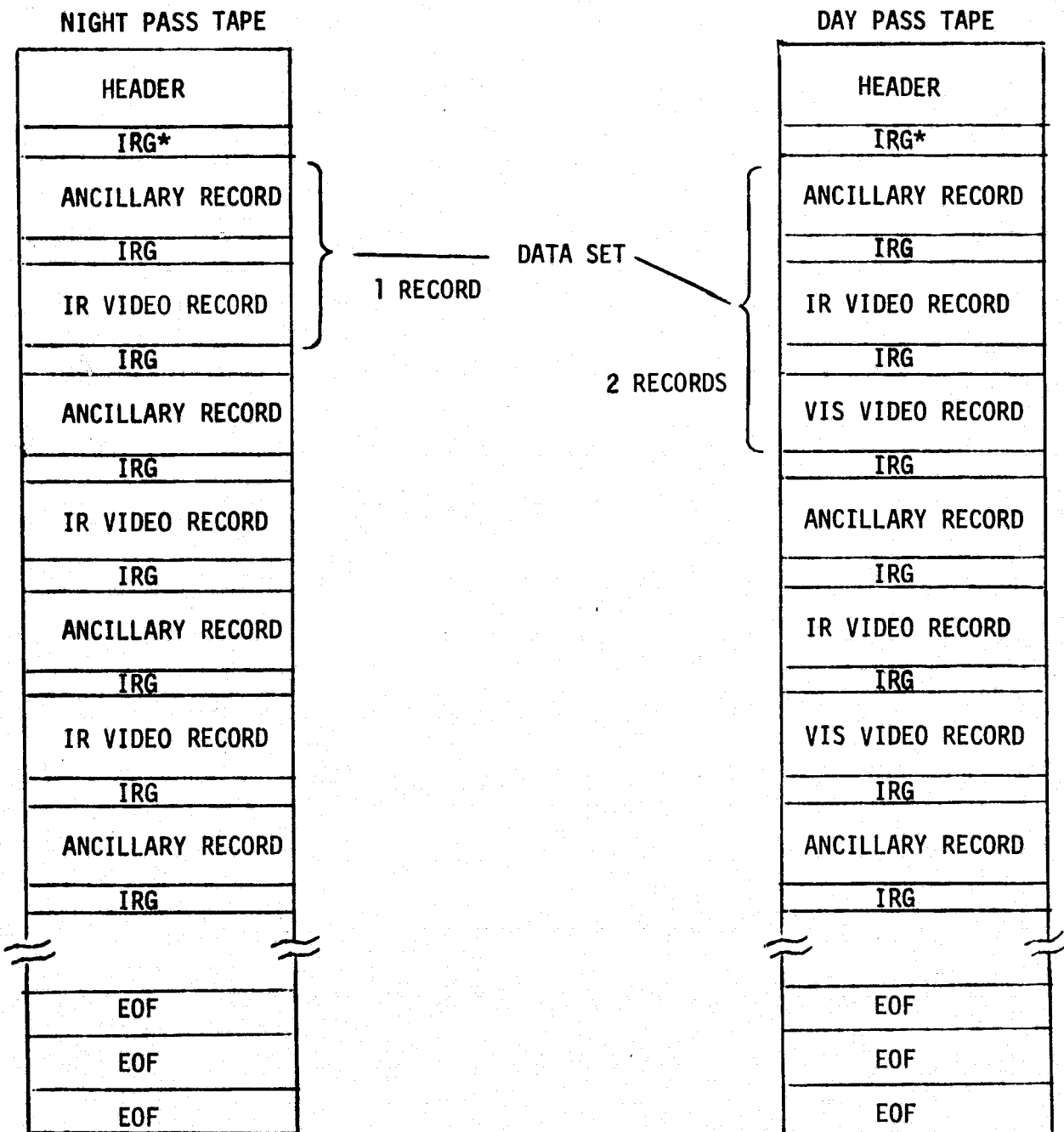


Figure 2-7 SEDS Raw 9-Track CCT Format



*IRG = INTER-RECORD GAP

Figure 2-8 EU Processed 9-Track Tape Format

TABLE 2-3
PROCESSED TAPE BLOCKS

ANCILLARY BLOCK (COUNTER = 1*)	
<u>BLOCK BYTE</u>	<u>DESCRIPTION</u>
1-4	CURRENT GMT AT START OF THIS DATA SET (TENTHS OF MILLISECONDS)
5-6	CHANNEL STATUS FOR THIS SCAN. LSB OF BYTES 5-6 (0 = CHANNEL IN SYNC, 1 = CHANNEL NOT IN SYNC), ONE BYTE PER CHANNEL
7-68	CHANNELS 3-64 NOT APPLICABLE. LSB OF EACH BYTE = 1
69-70	SCAN LINE NO.; ARBITRARY BUT SEQUENTIAL FOR EACH SCAN LINE OF THIS DATA RUN
VIDEO BLOCK (COUNTER = 2*)	
<u>BLOCK BYTE</u>	<u>DESCRIPTION</u>
1-2500 (OR LESS)	CHANNEL OF DATA, UP TO 2500 VIDEO ELEMENTS: <ul style="list-style-type: none"> ● NIGHT TAPE VIDEO BLOCK = 2500 SCANS (1-1800 ELEMENTS) ● DAY TAPE VIDEO BLOCK = 2200 SCANS (1-2500 ELEMENTS)

*COUNTER IS IN FIRST TWO BYTES OF PHYSICAL RECORDS

NOTE: BYTES OF ZERO FILL ARE REQUIRED TO COMPLETE PHYSICAL RECORD LENGTH SPECIFIED IN HEADER RECORD

C. Subroutines. The subroutines called by the SEUCON CPC are outlined in detail in paragraph 2.2.1.1.

D. CPC Interfaces. SEUCON is called directly from the SEDS-resident program and there is only one entry point to the routine. Interfacing with the other CPC's is accomplished by SEUCON calling them in for program control by a call to the memory segmentation module (SEG).

2.2.1.4 Data Organization. As previously stated, SEUCON maps data files into core via SEG at 24-28K. These files are available for access by the other CPC's, as well as the common data in RESIDENT. However, each CPC has data unique to the CPC and accessible only to that CPC and its subcomponents. This data (items, flags, tables, etc.) is contained within the subcomponents, so it is included in that area of memory set up for the CPC load module. Following is a list of data items and tables unique to the SEUCON CPC.

A. COMMON/STATUS FLAGS RETURNED BY TAPEIN Routine

1. ISTAT1. 1 = ancillary record returned; 2 = IR channel record returned, and 3 = VIS channel record returned.
2. ISTAT2. 0 = normal processing and 1 = EOF/EOT reached.
3. ICHECK. 0 = normal and 1 = channel zero-filled.

B. COMMON/FIXCOM. All flags are initially set to 0. They are:

- SCNTME, time of current scan (double precision floating point value, four words)
- ISCAN, current input scan number
- IRECNO, current record counter
- TMESAV, time of previous scan (double precision floating point value, four words)
- ISLOUT, output scan number
- IRCSAV, record counter of previous record.

- C. COMMON/CHBUF/IRCRD and IPDATA (2518). This includes:
- IRCRD, the record counter
 - IPDATA, a 2518 word internal buffer where the channel of data (from tape) is processed and output.
- D. COMMON/TWOBUF/INBUFF (1260, 2). INBUFF is a 2520-word double buffer used by TAPEIN to read the raw input data into prior to moving it to the INDATA SEG buffer for transfer of data to SEUCON.
- E. COMMON/FLSTOR. These are storage words for values calculated and filtered values to be used in the calibration process of computing the E(V)'s in EVCONV. They are: T1, T2, T3, TR, FT1, FT2, FT3, FTR, FVSS, FVBB, and ETR.
- F. EFCTOR. The "e" assumed average emissivity correction factor used in EVCONV for the E(V) calculations is 0.975.
- G. COMMON/EVTABL/IEV (256). IEV is a 256-word table, initially set to 0's, built by EVCONV to contain the calculated E(V) values for every PCM count (0-255). The IEV table is used later by TBLOOK as a table lookup to extract the E(V) corresponding to a particular input PCM count.
- H. K1, K2 and K3. These are counters used in the filtering process by FILTER; they are initially set to 0.
- I. ITAB. This is a temporary storage location used by TBLOOK to store the table address of the index values passed by the calling routine.
- J. EAVAL. The E(A) value corresponding to an effective atmospheric temperature of 230.0 °K is 4384. It is used by ECCONV in the calculation of E_c .

2.2.1.5 Limitations. As each scan is read off the raw input tape by TAPEIN, checks are made on the scan time contained in the ancillary. If there is a jump in time, zero-fill scans are output to the EU tape to ensure that a full tape (inserting for dropouts) is built for later use in registration. However, there is no capability to determine if the time track was out and was passing along bad time and good sequential data scans. So the SEU Program must assume there is good time with the data as this is its only means of correctly determining data scan dropouts.

2.2.1.6 CPC Listings. See Part IV of this document, published under separate cover.

2.2.2 EUDISP (CPC No. 2). This is the load module for the SEU Program that is responsible for initialization and operator setup prior to the actual processing of the data. EUDISP builds a VT05 display with information stripped from the input header, and receives and processes inputs to the VT05 made by the operations personnel. All of the routines except one in this CPC are written in PDP 11/45 assembly language. There is one FORTRAN routine serving as a driver. EUDISP interfaces with the resident VT05 handler input/output routines to accomplish its interaction with the VT05 display. Interfaces with the resident NTRAN routine are made for the required tape I/O to read the input tape header. See figure 2-9 for a virtual core layout of the EUDISP CPC.

2.2.2.1 Subcomponent Descriptions. EUDISP is one of the smaller load modules of SEU, so it contains relatively few subcomponents in comparison to SEUCON. The subcomponents are as follows:

- A. DSPDRV. This is a FORTRAN routine that acts as a "driver." It calls, initially, the main assembly language routine EUDISP. To provide for a valid linkage and proper calling between CPC's, those load modules written purely in assembly language must have a FORTRAN driver that is first given control to call up the main routine.
- B. EUDISP MAIN. This is the main subcomponent of the EUDISP CPC. It controls the logic flow and the calling of the other subcomponents to perform the interfacing with the VT05 and tape.

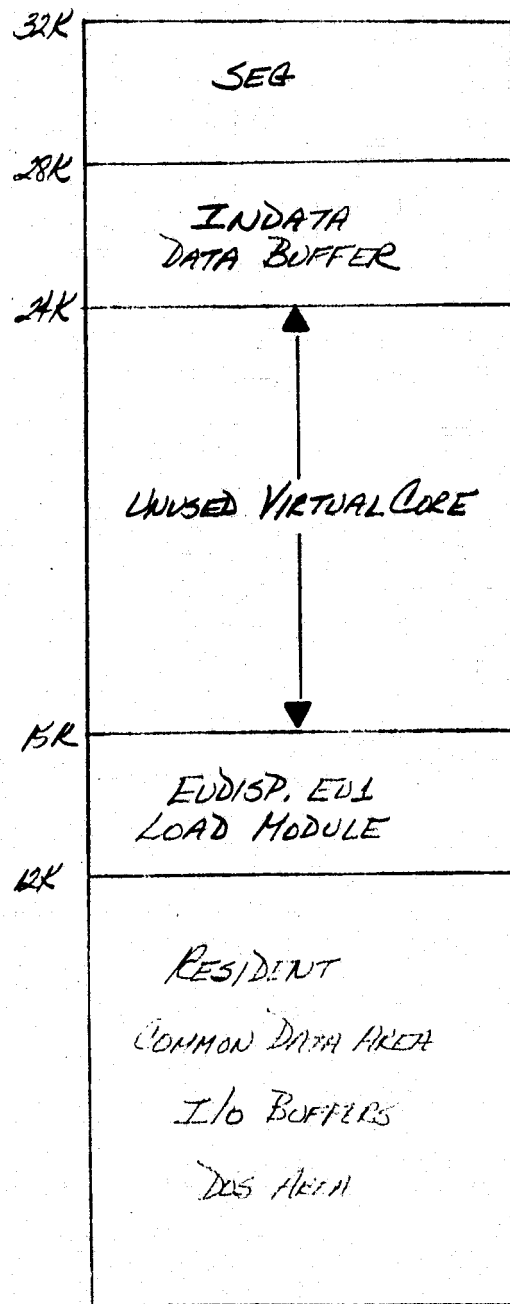


Figure 2-9 EUDISP CPC Virtual Core Map

- C. VTLINK. This is the VT05 routine that uses a defined command string table to output a display to the VT05 screen. This routine is called from EUDISP after all data has been collected for the EU initialization display.
- D. ERRDSP. This is an error and message displaying routine called by EUDISP if certain conditions occur, and to inform the operator of any advisories, etc.
- E. IWRITE. This routine is called by ERRDSP to log out to the requestor the error and/or advisory message that was currently displayed on the VT05.

The ERRDSP and IWRITE Routines are described in paragraph 2.2.5.

When the EUDISP load module (CPC) is called in from SEUCON CPC, DSPDRV has control. DSPDRV calls EUDISP MAIN to take over program control. EUDISP outputs a message to the VT05 display by means of an EMT (142) call to the resident VT05 handler (VT05H). The actual output and input of characters to the VT05 is handled by two interrupt service routines (VTIN and VTOUT). These are discussed in paragraph 8.2.1. EUDISP sits in a "wait" loop until the operator has responded with a GO command to the output message. A VT05 command special processor sets a defined flag word to indicate that a GO command was ordered by the operator. EUDISP now makes a call to NTRAN to read the input tape header into the IN-DATA buffer area. Data is picked up from INDATA, converted to ASCII and stored in the VT05 display command string buffer. A call is made to VTLINK, passing the display data formatted for output. The EU display is as follows:

COMPLETE EU OUTPUT TAPE ID; KEY IN 'GO'

PROGRAM: SEUCON-EU CONVERSION PROCESSING

DATE: 23:JAN:75

DAY PASS PROCESSING

RAW INPUT TAPE I.D.: SPD-SEDS T

*MT0

EU OUTPUT TAPE I.D.: SED-

*MT1

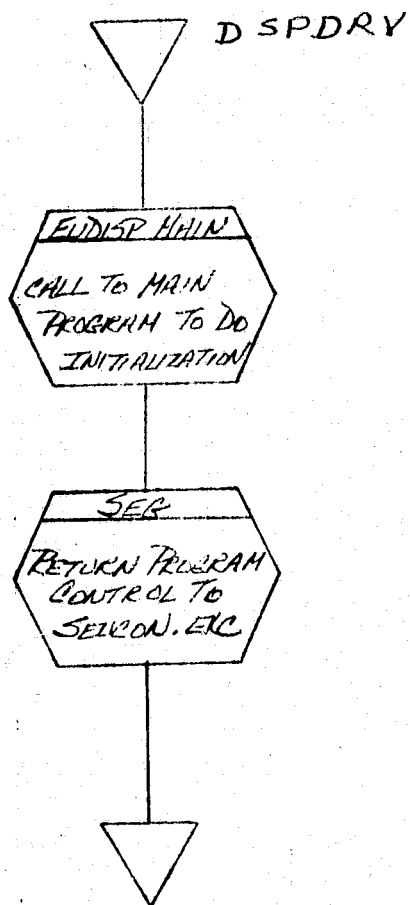
EUDISP waits in a loop until the operator has completed entries to the display and has keyed in the GO command.

EUDISP now sets up the SEDCOM data common in RESIDENT, using header data and operator VT05 entries to be used by SEUCON, as follows:

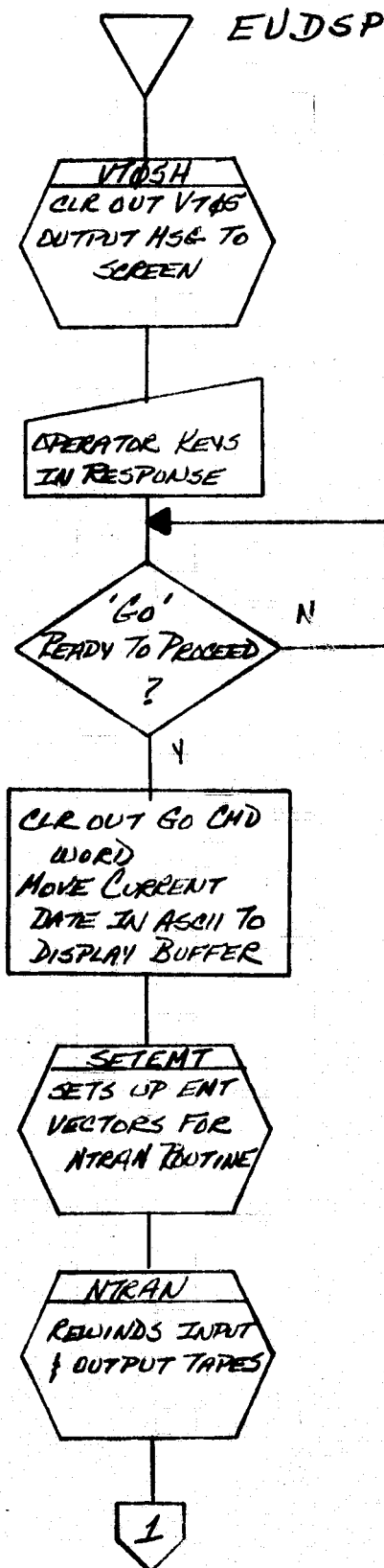
- ILOUT (EU output tape logical unit number)
- IDTAPE (output tape ID)
- ISENSR (flag indicating type of sensor data to process).

EUDISP has now completed the EU initialization phase and exits back to SEUCON via the DSPDRV Routine. If any error conditions occurred during the tape read (invalid header information, etc.) a call is made to ERRDSP to display the required error message on the VT05.

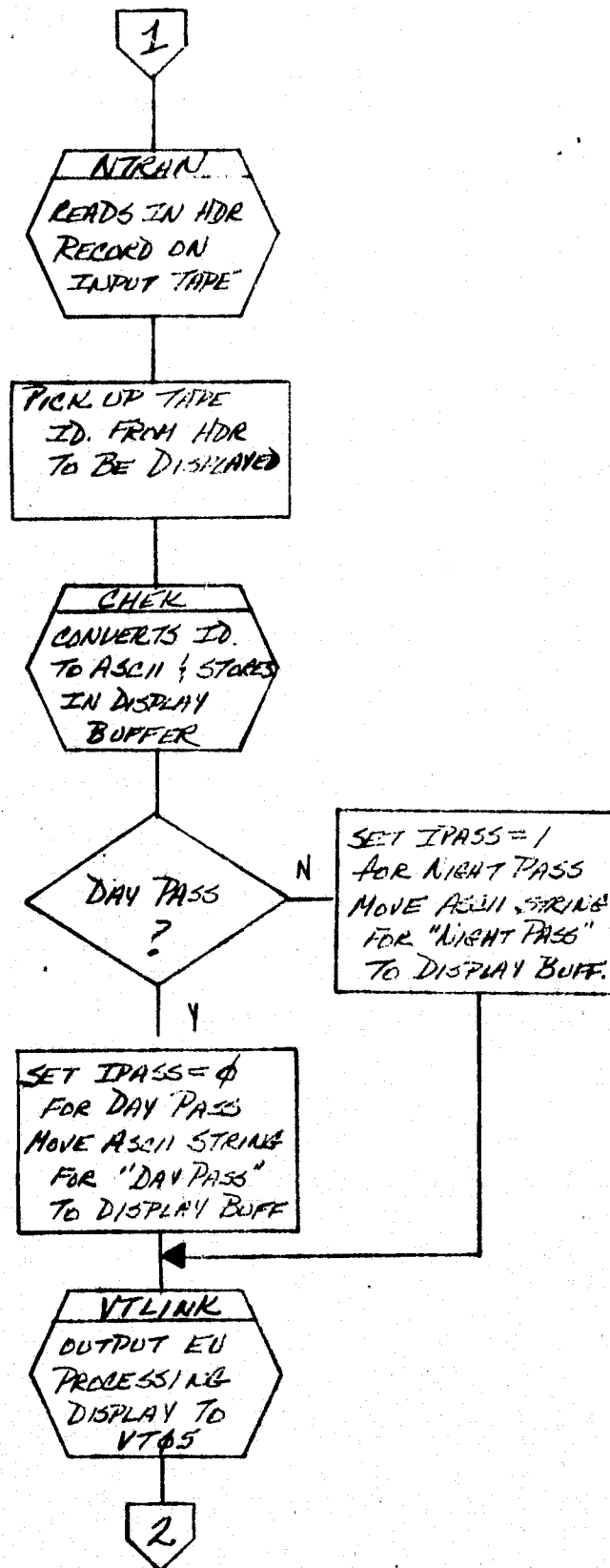
2.2.2.2 Flow Charts. See the following five pages.

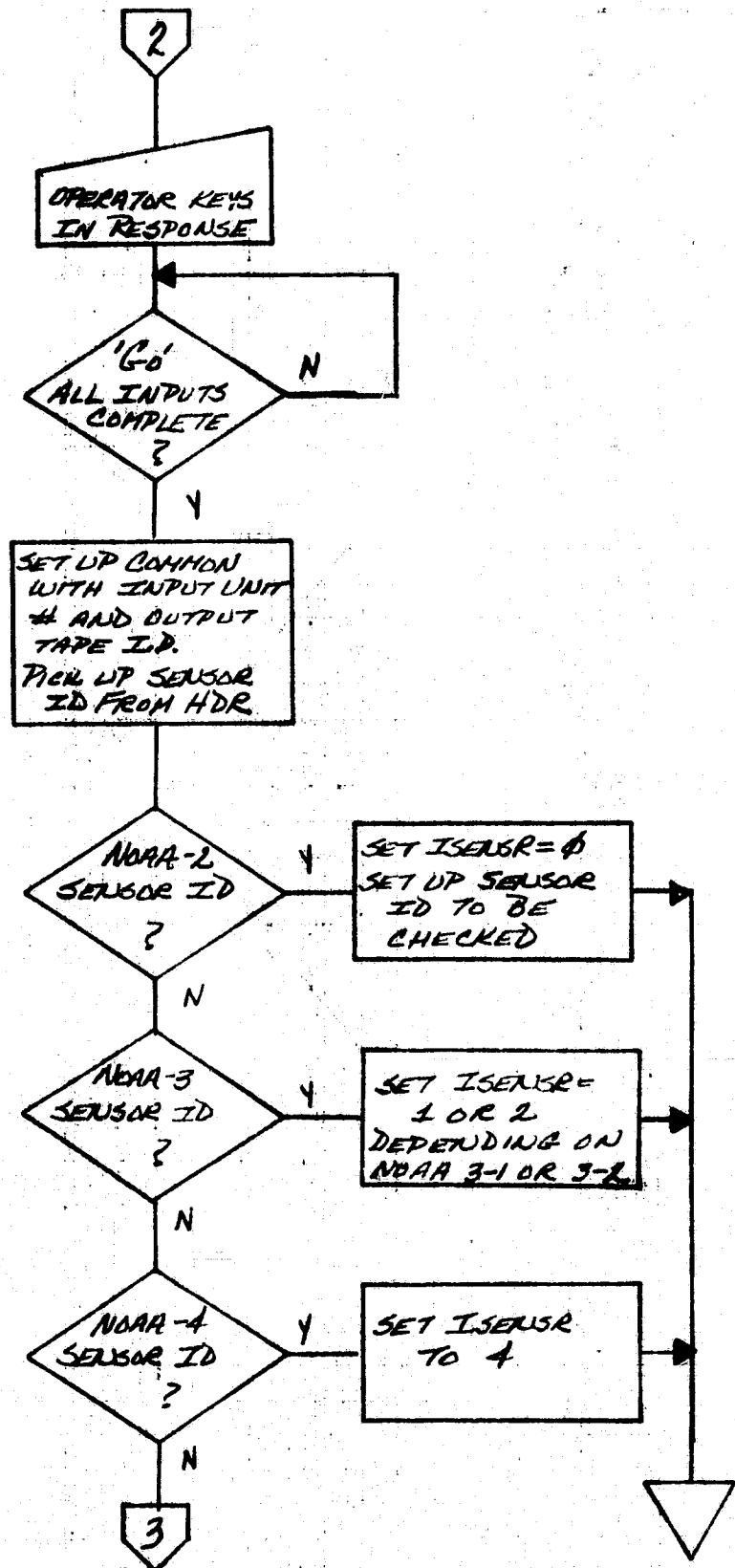


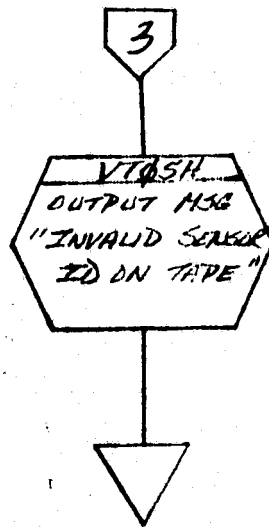
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2.2.2.3 Interfaces

- A. Input. The only input data to EUDISP is the raw PCM input tape header on the preprocessor 9-track CCT. Refer to table 2-4 for a layout and content description of the header record.
- B. Output. The data output from EUDISP is as follows:
1. ILOUT. This is a 16-bit word containing the logical unit number for the EU output tape. ILOUT is used by SEUCON for purposes of writing out the data to the output tape.
 2. IDTAPE. This is five words containing the EU output tape ID in EBCDIC as input to the VT05 by the operator. It is used by HEDREC in building the output tape header record.
 3. ISENSR. This is a flag word indicating the type of sensor data to be processed (0 = NOAA 2, 1 = NOAA 3-1, 2 = NOAA 3-2, 3 = NOAA 4-1, and 4 = NOAA 4-2). It is used by EVCONV to determine the particular calculation for the calibration.
- C. Call. EUDISP is called by SEUCON via a call to SEG to map in the EUDISP load module.

2.2.2.4 Data Organization. Each CPC has data that is related only to that particular CPC and is internally contained and defined. The data discussed in previous sections can be assessed by the other CPC's and for the most part is external to EUDISP. The following are tables and data items unique to EUDISP:

- A. MTUNIT. This is a predefined data word for the input tape logical unit number, the parameter passed to NTRAN I/O routine. It = 9.
- B. WRDCT. This is a predefined word count, the parameter passed to NTRAN as the number of words to read in for the header record. It = 1530.

TABLE 2-4

SEDS RAW 9-TRACK CCT IMAGERY UNIVERSAL FORMAT HEADER RECORD

BYTE	CONTENTS	DESCRIPTION
1-32	SEDS	COMPUTING SYSTEM ID (EBCDIC)
33-52		TAPE LIBRARY NO. (EBCDIC)
33-35		SPD FOR DAY, SPN FOR NIGHT
36-41		TAPE NO. (XXXXXX)
53-60		SENSOR ID - EBCDIC
	{NOAA 2 NOAA 3-1 & 3-2 NOAA 4-1 & 4-2}	
61-63		DATE OF THIS TAPE GENERATION (EXAMPLE)
61	07	DAY OF MONTH (BINARY)
62	11	MONTH NO. (BINARY)
63	74	LAST 2 DIGITS OF YEAR (BINARY)
64	1	TAPE SEQUENCE NO. (BINARY)
65-66	0	MISSION NO. (BINARY)
67-68	0	SITE (BINARY)
69	0	LINE (BINARY)
70	0	RUN (BINARY)
71-72		ORBIT (BINARY)
73-80		TIME OF FIRST SCAN IN THIS JOB (CONTENTS OF THESE BYTES SHOULD REMAIN CONSTANT THROUGHOUT JOB)
73-74	183	TENTHS OF MILLISECONDS (BINARY)
75	42	SECONDS (BINARY)
76	15	MINUTES (BINARY)
77	11	HOURS (BINARY)
78	21	DAY OF MONTH (BINARY)
79	09	MONTH NO. (BINARY)
80	72	LAST 2 DIGITS OF YEAR (BINARY)
81-88		CHANNELS ACTIVE IN THIS JOB, 1 BIT PER CHANNEL LEFT TO RIGHT (MSB TO LSB). VIDEO DATA ALWAYS APPEARS IN THE ORDER INDICATED HERE. 1 = ACTIVE
81	2008 OR 3008	CHANNELS 1-8
82	000	CHANNELS 9-16
83	000	CHANNELS 17-24
84	000	CHANNELS 25-32
85	000	CHANNELS 33-40
86	000	CHANNELS 41-48
87	000	CHANNELS 49-56
88	000	CHANNELS 57-64

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TABLE 2-4 (CONT'D)

BYTE	CONTENTS	DESCRIPTION
89	0	PROCESSING FLAG, BINARY (0 = RAW, 1 = PROCESSED)
90	1 OR 2	NO. OF CHANNELS IN THIS JOB, BINARY (SUM OF "ONES" IN BYTES 81-88)
91	8	PIXEL SIZE, BINARY (NO. OF BITS IN A PIXEL)
92-93	2	BYTE ADDRESS OF START OF VIDEO DATA, BINARY (GIVES LOCATION OF START OF VIDEO WITHIN SCAN)
94-95	VARIABLE	BYTE ADDRESS OF START OF FIRST CALIBRATION AREA WITHIN THE SCAN, BINARY
96-97		NO. OF VIDEO ELEMENTS PER SCAN WITHIN A SINGLE CHANNEL (BINARY) <ul style="list-style-type: none"> • DAY TAPE \leq 2500 • NIGHT TAPE \leq 1700
98-99	12	NO. OF CALIBRATION ELEMENTS IN THE FIRST CALIBRATION AREA WITHIN THE SCAN IN A SINGLE CHANNEL (BINARY)
100-101		PHYSICAL RECORD SIZE IN BYTES (BINARY) <ul style="list-style-type: none"> • DAY TAPE = 2520 OR A LESSER MULTIPLE OF 180 • NIGHT TAPE = 1800 OR A LESSER MULTIPLE OF 180
102	1	NO. OF CHANNELS PER PHYSICAL RECORD OF DATA SET STARTING WITH SECOND RECORD OF DATA SET (BINARY)
103	0	NO. OF PHYSICAL RECORDS/SCAN/CHANNEL (BINARY). ZERO UNLESS NO. OF ELEMENTS/CHANNEL > 3K
104	2 OR 3	NO. OF RECORDS TO MAKE A COMPLETE DATA SET; NEVER ZERO (BINARY)
105-106	70	LENGTH OF ANCILLARY BLOCK IN BYTES (BINARY)
107	0	DATA ORDER INDICATOR, BINARY (0 = VIDEO ORDERED BY CHANNEL, 1 = BY PIXEL)
108-109	1-3522 (AS INPUT)	START PIXEL NO. (ACTUAL ONBOARD PIXEL NO.); NO. OF FIRST PIXEL/SCAN ON THIS TAPE REFERENCED TO START OF SCAN (BINARY)
110-111	1-3522 (AS INPUT)	STOP PIXEL NO. (ACTUAL ONBOARD PIXEL NO.) NO. OF LAST PIXEL/SCAN ON THIS TAPE REFERENCED TO START OF SCAN (BINARY)

TABLE 2-4 (CONT'D)

BYTE	CONTENTS	DESCRIPTION
112-623		<p>COEFFICIENTS AND EXPONENTS-OF-TEN TO LINEARLY TRANS-LATE PARAMETER VALUES FROM AS MANY AS 64 CHANNELS TO EU'S; TWO BYTES PER COEFFICIENT OF EXPONENT WITH EACH PAIR OF BYTES EXPRESSED IN SIGNED BINARY. (MSB IS A SIGN BIT: 0 = PLUS, 1 = MINUS. REMAIN-ING 15 BITS ARE STRAIGHT BINARY. FORMULA IS:</p> $Y = A_0 * 10^{E_0} + C * A_1 * 10^{E_1}$ <p>WHERE:</p> <p>Y = EU'S FOR EACH BAND C = PARAMETER VALUE FOR EACH BAND</p>
112-115	0	A ₀ COEFFICIENTS FOR CHANNELS 1-2
116-239	0	CHANNELS 3-64 NOT APPLICABLE
240-243	0	E ₀ EXPONENTS OF 10 FOR CHANNELS 1-2
244-367	0	CHANNELS 3-64 NOT APPLICABLE
368-371	1	A ₁ COEFFICIENTS FOR CHANNELS 1-2
372-495	0	CHANNELS 3-64 NOT APPLICABLE
496-499	0	E ₁ EXPONENTS OF 10 FOR CHANNELS 1-2
500-623	0	CHANNELS 3-24 NOT APPLICABLE
624-687	0	COLOR CODE INFORMATION, ONE BYTE/BAND IN SAME ORDER AS CHANNEL-ACTIVE-ON-THIS-TAPE INDICATOR, BINARY (0 = NOT ACTIVE, 1 = RED, 2 = GREEN, 3 = BLUE)
688	0	OFFSET VALUE, (BINARY); USED WITH GAIN VALUES (BYTES 689-750)
689-750	0	GAIN VALUES, (BINARY) APPLIED TO SIGNAL LEVELS FROM CHANNELS 1-62 FOR LINEAR COMBINATION
751	0	PICTURE ELEMENT FIELD WIDTH (BINARY); SMALLEST MUL-TIPLE OF 8 WHICH ≥ NO. OF BITS IN A PIXEL (BYTE 91). ZERO IF PIXEL SIZE = 8 BITS
752	0	PIXEL REGISTRATION (BINARY); NO. OF BITS THAT LSB OF PIXEL IS DISPLACED FROM LSB OF PIXEL FIELD (RE-FER TO BYTE 751). ZERO IF PIXEL SIZE = PICTURE ELEMENT FIELD WIDTH. ANY NON-ZERO VALUE IN THIS BYTE WILL BE DISCOURAGED.
753	16	WORD SIZE OF GENERATING COMPUTER; SMALLEST QUANTITY IN BITS THAT COMPUTER CAN WRITE ON TAPE (BINARY)

TABLE 2-4 (CONT'D)

BYTE	CONTENTS	DESCRIPTION
754-1777		SHORTEST AND LONGEST WAVELENGTH OF EACH CHANNEL (EBCDIC); EIGHT BYTES/LIMIT, 16 BYTES/CHANNEL (MILLIMICRONS)
754-761	010500	CHANNEL 1 SHORTEST
762-769	012500	CHANNEL 1 LONGEST
770-777	000600	CHANNEL 2 SHORTEST
778-785	000700	CHANNEL 2 LONGEST
786-1777		FILL ZEROS
1778	0	NO. DATA SETS/PHYSICAL RECORD (BINARY)
1779-1780	0	BYTE ADDRESS OF START OF SECOND CALIBRATION WITHIN A SCAN (BINARY)
1781-1782	0	NO. CALIBRATION ELEMENTS IN THE SECOND CALIBRATION AREA WITHIN THE SCAN IN A SINGLE BAND (BINARY)
1783	0	CALIBRATION SOURCE INDICATOR (BINARY); LSB ~ SECOND SOURCE, LSB+1 ~ FIRST SOURCE (0 = LOW CALIBRATION SOURCE DATA, 1 = HIGH CALIBRATION SOURCE DATA)
1784	0	FILL ZERO
1785-1786	0	NO. CHANNELS IN FIRST RECORD OF DATA SET (BINARY)
1787-1788		TOTAL NO. ELEMENTS/SCAN/CHANNEL (BINARY) <ul style="list-style-type: none"> • DAY PASS ≤ 2514 • NIGHT PASS ≤ 1714
1789-1790	1	PIXEL SKIP FACTOR; QUANTITY TO BE ADDED TO THE NO. OF LAST PIXEL PROCESSED TO YIELD NO. OF NEXT PIXEL PROCESSED (BINARY). 1 = EVERY PIXEL PROCESSED
1791-1792	1	SCAN SKIP FACTOR; QUANTITY TO BE ADDED TO NO. OF LAST SCAN PROCESSED TO YIELD NO. OF NEXT SCAN PROCESSED (BINARY). 1 = EVERY SCAN PROCESSED
1793-3000	0	FILL ZEROS
3001-3060	0	FILL ZEROS; MAKES THE RECORD AN INTEGRAL NO. OF COMPUTER WORDS. THESE BYTES MUST NEVER CONTAIN DATA

TABLE 2-4 (CONT'D)

BYTE	CONTENTS	DESCRIPTION
754-1777		SHORTEST AND LONGEST WAVELENGTH OF EACH CHANNEL (EBCDIC); EIGHT BYTES/LIMIT, 16 BYTES/CHANNEL (MILLIMICRONS)
754-761	010500	CHANNEL 1 SHORTEST
762-769	012500	CHANNEL 1 LONGEST
770-777	000600	CHANNEL 2 SHORTEST
778-785	000700	CHANNEL 2 LONGEST
786-1777		FILL ZEROS
1778	0	NO. DATA SETS/PHYSICAL RECORD (BINARY)
1779-1780	0	BYTE ADDRESS OF START OF SECOND CALIBRATION WITHIN A SCAN (BINARY)
1781-1782	0	NO. CALIBRATION ELEMENTS IN THE SECOND CALIBRATION AREA WITHIN THE SCAN IN A SINGLE BAND (BINARY)
1783	0	CALIBRATION SOURCE INDICATOR (BINARY); LSB ~ SECOND SOURCE, LSB+1 ~ FIRST SOURCE (0 = LOW CALIBRATION SOURCE DATA, 1 = HIGH CALIBRATION SOURCE DATA)
1784	0	FILL ZERO
1785-1786	0	NO. CHANNELS IN FIRST RECORD OF DATA SET (BINARY)
1787-1788		TOTAL NO. ELEMENTS/SCAN/CHANNEL (BINARY) <ul style="list-style-type: none"> • DAY PASS ≤ 2514 • NIGHT PASS ≤ 1714
1789-1790	1	PIXEL SKIP FACTOR; QUANTITY TO BE ADDED TO THE NO. OF LAST PIXEL PROCESSED TO YIELD NO. OF NEXT PIXEL PROCESSED (BINARY). 1 = EVERY PIXEL PROCESSED
1791-1792	1	SCAN SKIP FACTOR; QUANTITY TO BE ADDED TO NO. OF LAST SCAN PROCESSED TO YIELD NO. OF NEXT SCAN PROCESSED (BINARY). 1 = EVERY SCAN PROCESSED
1793-3000	0	FILL ZEROS
3001-3060	0	FILL ZEROS; MAKES THE RECORD AN INTEGRAL NO. OF COMPUTER WORDS. THESE BYTES MUST NEVER CONTAIN DATA

- C. STATBF. This is a flag word in which NTRAN passes on the I/O status for error detection; it is initially set to 0.
- D. EUCMD2. This is the VT05 display command buffer string, and contains predefined command blocks for VTLINK to use in outputting the display. It also contains data set up by EUDISP from the header to be displayed.
- E. EB2ASC. This is a predefined table containing EBCDIC and ASCII representations of A-Z, 0-9, and special characters. It is used by EUDISP in conversions for display, etc.
- F. MTMSG. This is a message command string passed to VTLINK for VT05 display.

2.2.2.5 Limitations. None.

2.2.2.6 CPC Listings. See Part IV of this document published under separate cover.

2.2.3 HEDREC (CPC No. 3). HEDREC (EU1) is the CPC of the SEU Program responsible for building the EU output tape header record and outputting it to tape. Some of the information on the input tape header stored in the INDATA buffer is used in setting up the EU output header. HEDREC interfaces with NTRAN to write the output header to tape. The HEDREC load module is written in PDP 11/45 FORTRAN language and assembly language. Refer to figure 2-10 for a virtual core layout of the HEDREC CPC.

2.2.3.1 Subcomponent Description. HEDREC is composed of several subcomponents or subroutines, all used for the function of creating the output header and setting up the resident COMMON TPFRTM for use by SEUCON. The subcomponents are as follows:

- A. HEDREC MAIN. This is the main routine in the HEDREC load module. It is responsible for the logic control; setting up the TPFRTM common, partial build of the header, and outputting the header to tape.
- B. FIXWRD. This is an assembly language routine called by HEDREC MAIN to pick up data from the header, byte-swap the value, and store them in the TPFRTM common.

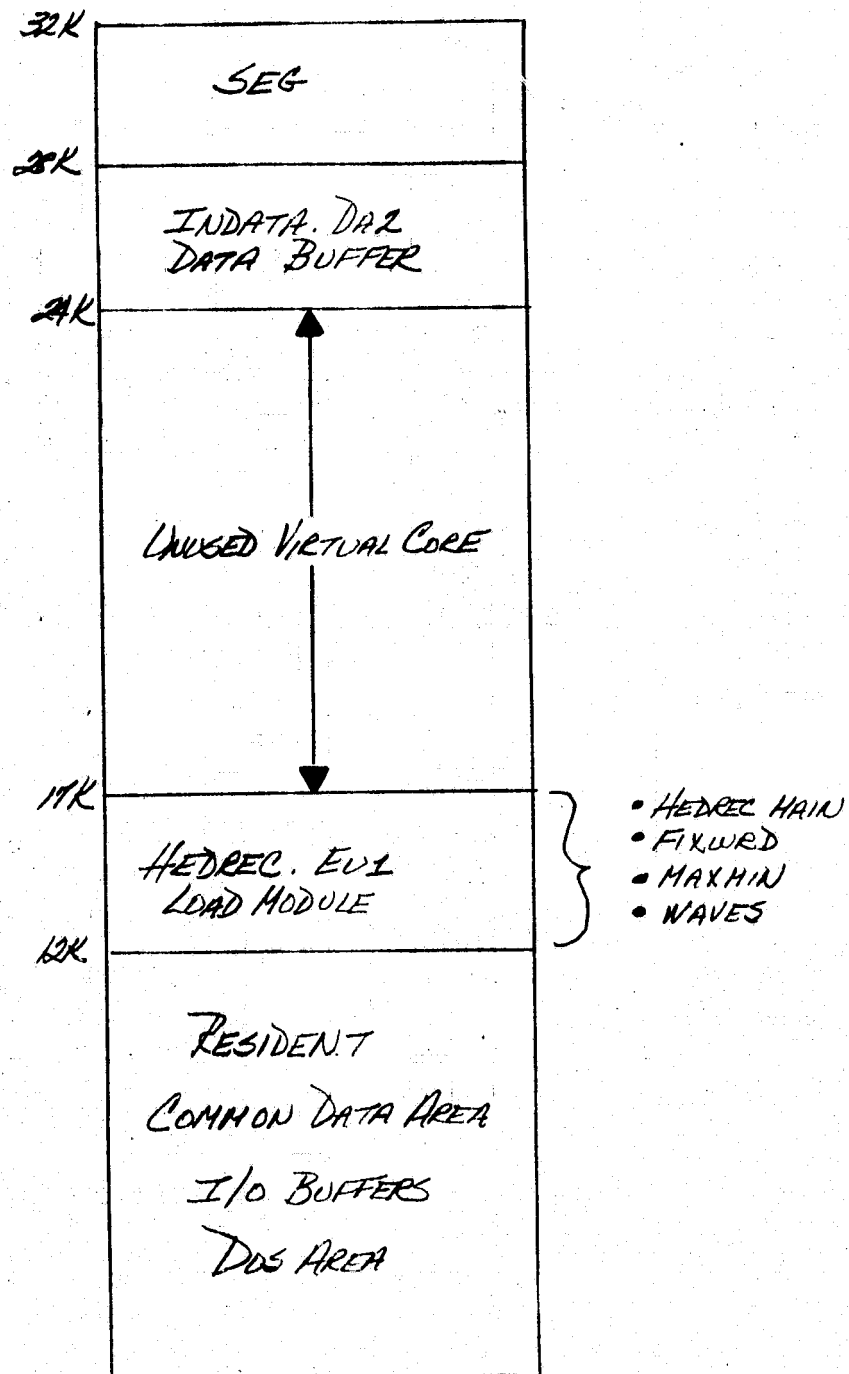
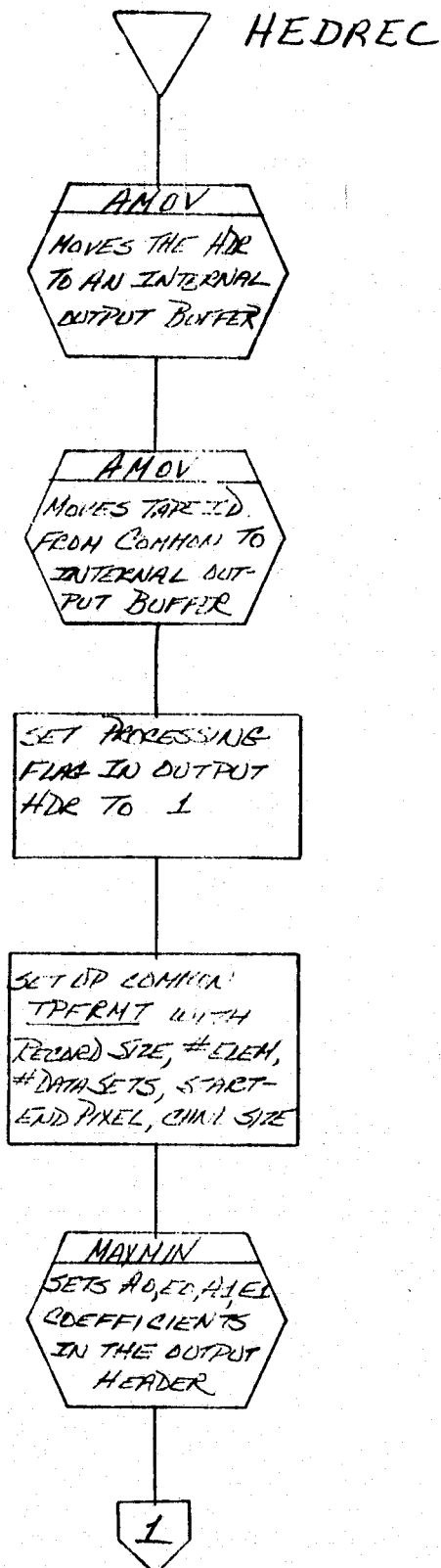


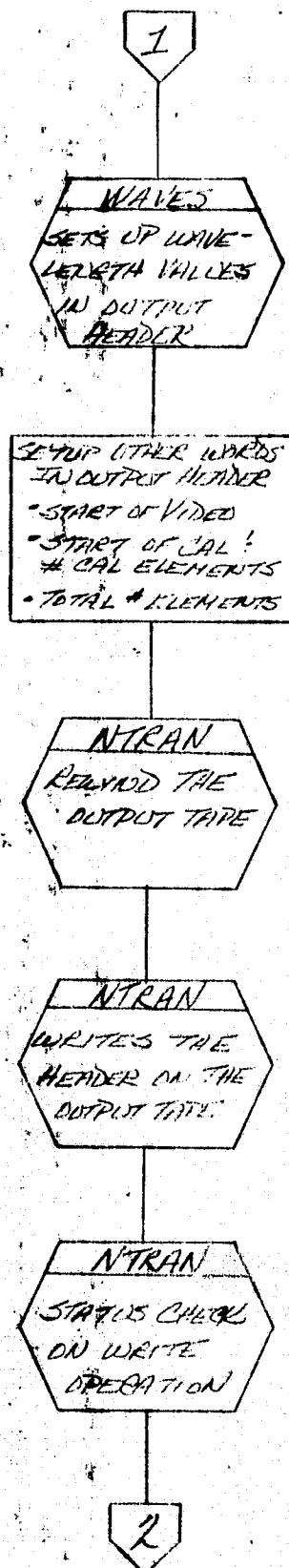
Figure 2-10 HEDREC CPC Virtual Core Map

- C. MAXMIN. This is an assembly language routine that sets the A_0 , E_0 , A_1 and E_1 coefficients into the output header.
- D. WAVES. This is an assembly language routine that sets up the wavelength values in the output header.

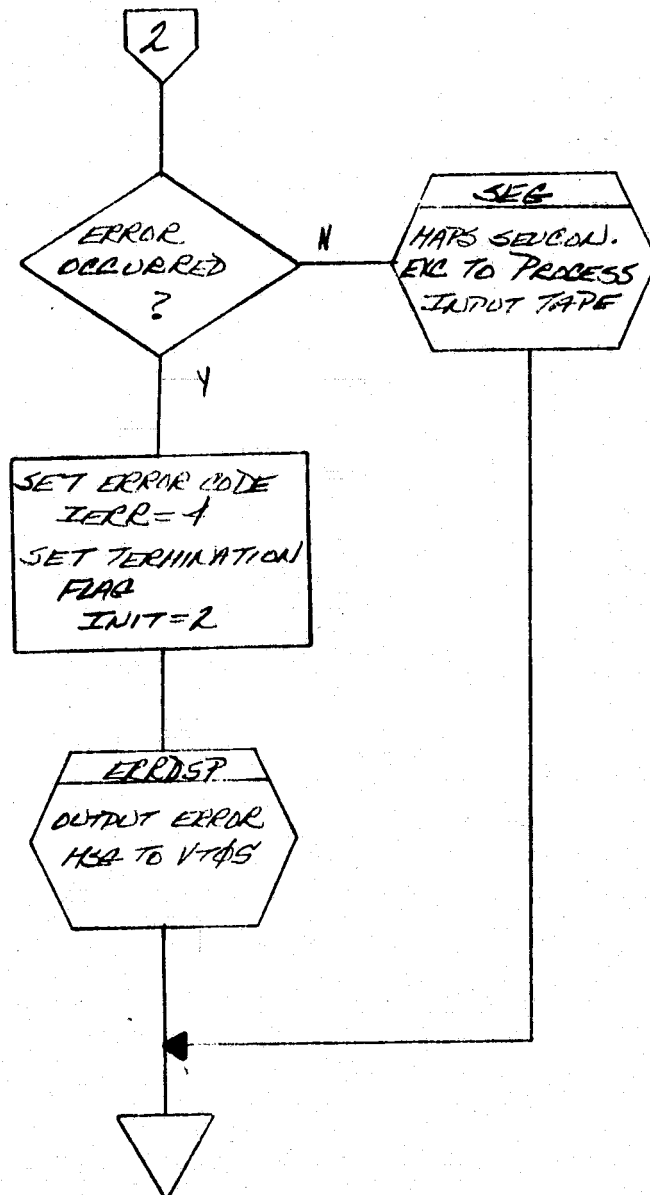
The HEDREC load module is called from the SEUCON CPC via SEG during the EU initialization phase to build the output header on the EU output tape. The input tape header had been previously read into the INDATA buffer by EUDISP, and HEDREC moves it to an internal working buffer (HEDBUF) to process and output from. HEDREC works with the input header record, making necessary modifications to it to create the header for output. The output tape ID (IDTAPE), set up by EUDISP by means of an operator VT05 entry, is now moved to an appropriate position in HEDBUF. HEDBUF then sets up the TPFRTM common, using data contained in the input header. Calls are made to FIXWRD when necessary to byte-swap a data value prior to moving it to the common data file. The TPFRTM common contains the following information from the header: number of video elements, record size, size of ancillary record, beginning pixel number, end pixel number, and channel size (see paragraph 2.1.5 for a layout of the TPFRTM common). HEDREC calls MAXMIN to set the A_0 , A_1 coefficients and E_0 , E_1 exponents-of-ten used in HEDBUF to linearly translate parameter values into engineering units. WAVES is then called by HEDREC to move predetermined wavelength values to their appropriate location in the output header. This consists of the shortest and longest wavelength of each channel in EBCDIC representation. HEDREC finishes the output header by setting the following information in the HEDBUF output buffer: start of video data, number of video elements on output, start of the calibration data, number of calibration elements, and total number of elements per scan per channel on output. A call to NTRAN is made to write HEDBUF (the output header record) to the EU output tape and HEDREC returns control to SEUCON.

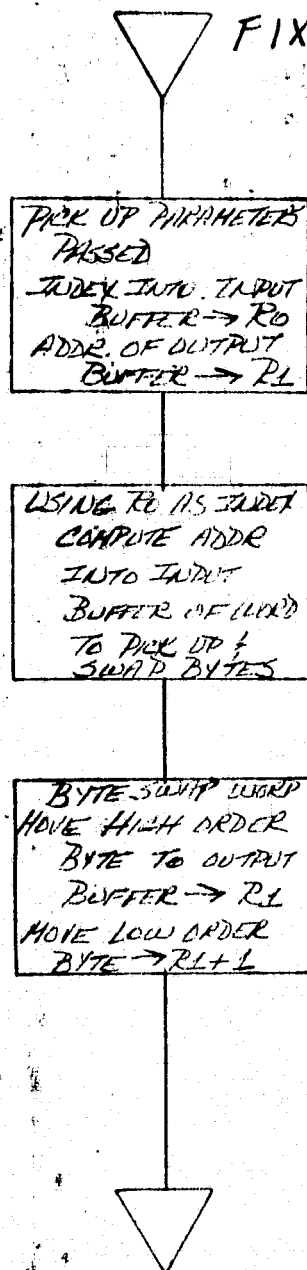
2.2.3.2 Flow Charts. See the following six pages.

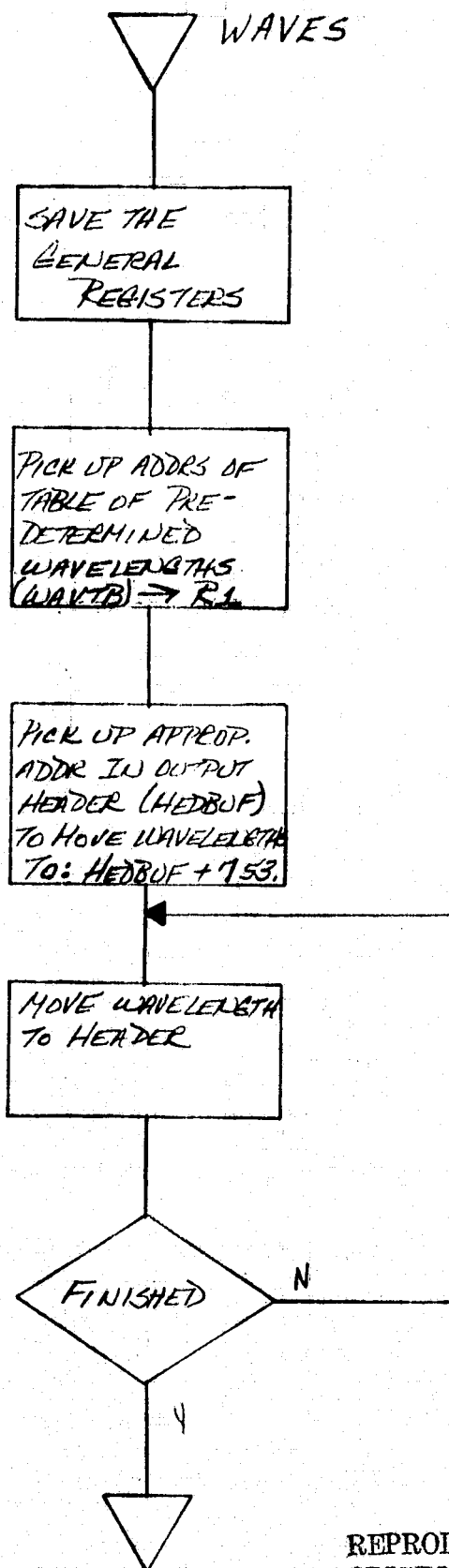




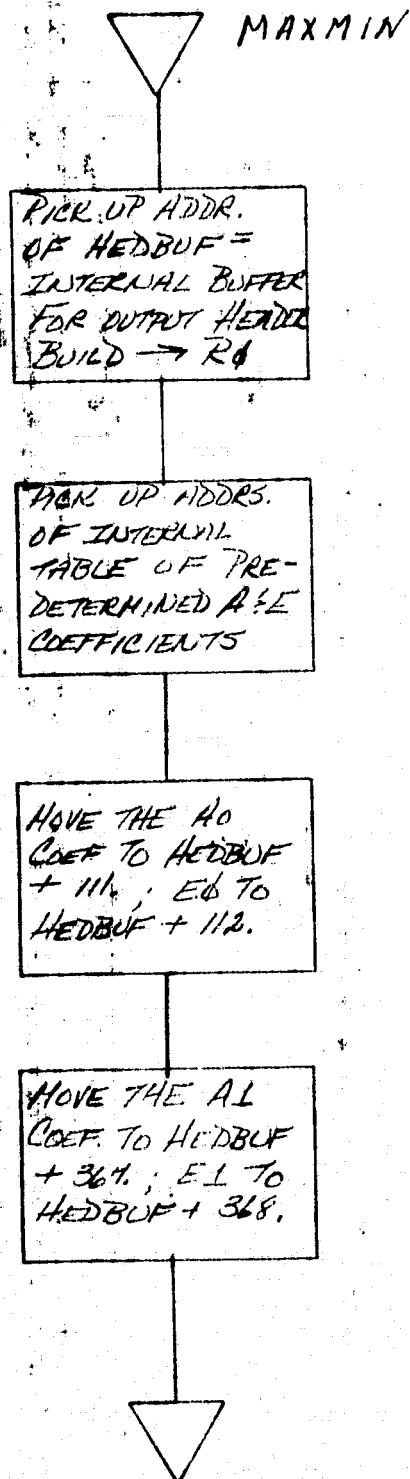
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2.2.3.3 Interfaces

- A. Input. The input data to HEDREC is the input raw PCM tape header record in the INDATA buffer read in by EUDISP. See table 2-4 for the layout and content description of the header.
- B. Output. The output of HEDREC is HEDBUF, containing the header output to the EU output tape. Essentially, it is the input header data with the modifications required to comply to the tape format and contents of the EU processed tape.
- C. Subroutines. HEDREC calls the WAVES, MAXMIN, FIXWRD, and NTRAN subroutines; their functions are outlined in paragraph 2.2.3.1.
- D. Called. As stated previously, HEDREC is called from SEUCON during the initialization phase of EU following the call to EUDISP. HEDREC is called once for each EU run and there is only one point of entry to the program.

2.2.3.4 Data Organization. Discussed in this paragraph are those data items and tables unique to HEDREC; those are internally defined and inaccessible to the other CPC's in SEU.

- A. COMMON/HEDBUF/IDAT(1530). HEDBUF or IDAT is a 1530-word integer table used as an internal header output buffer. Input header data is moved to this buffer and changes made to particular data entries within to set it up for output to the EU output tape.
- B. MASK. This is a 16-bit integer word containing the value 177776, used to AND with a data word to get the number of video elements to store in the header for output.
- C. A₀BYT. This is a 16-bit word containing the value 100624, used by MAXMIN for the A₀ and E₀ coefficient values to store in the output header. E₀ is in the high order byte; A₀ is in the low order byte.

- D. A₁BYT. This is a 16-bit word containing the value 2 used by MAXMIN for the A₁ and E₁ coefficient values to store in the output header. E₁ is in the high order byte; A₁ is in the low order byte.
- E. WAVTB. This is a 16-word byte table containing predetermined short and long wavelengths for Channel 1 and Channel 2 to be stored in the output header by the WAVES subroutine. These 8-bit values are represented in EBCDIC.

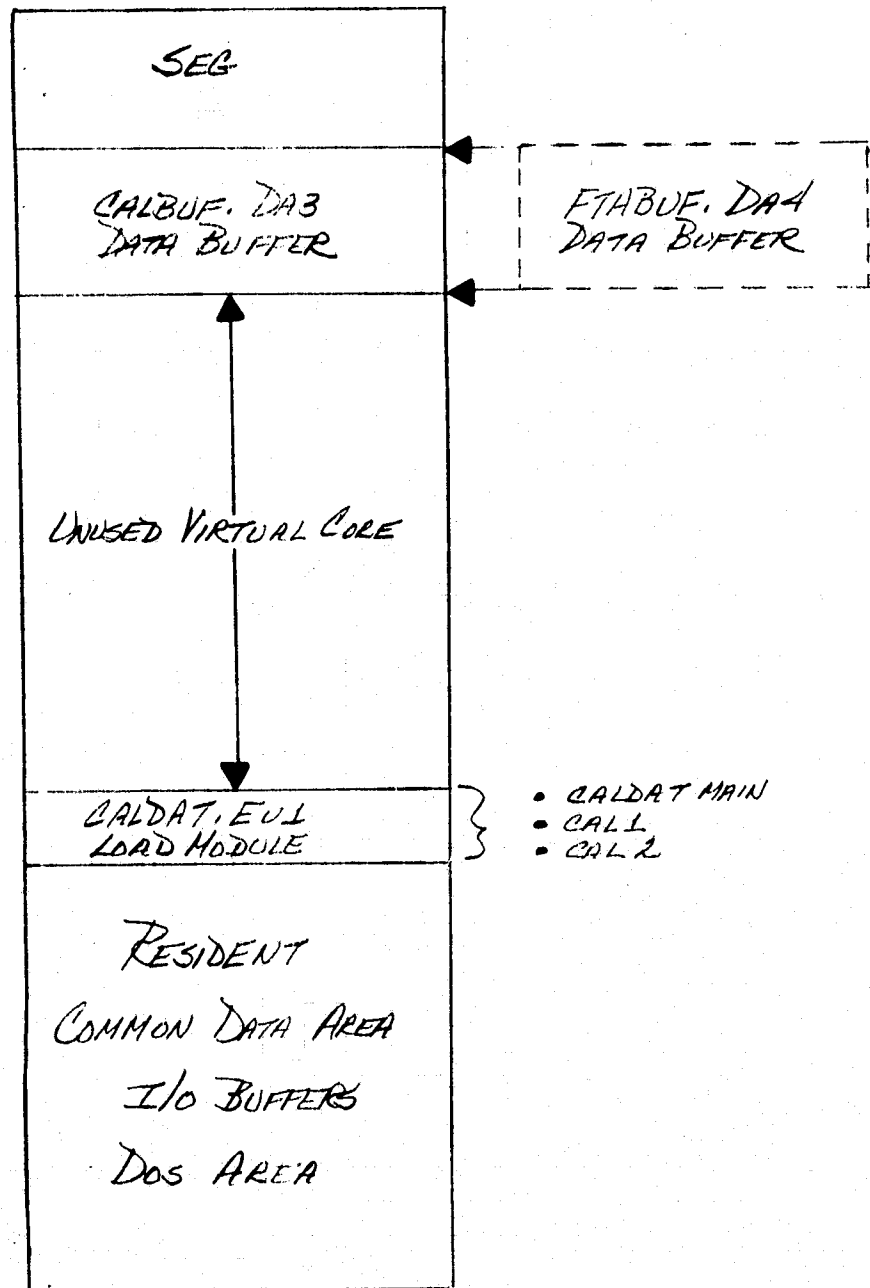
2.2.3.5 Limitations. None.

2.2.3.6 Listings. See Part IV of this document published under separate cover.

2.2.4 CALDAT (CPC No. 4). CALDAT(EU1) is the load module of the SEU Program responsible for retrieving calibration data in the form of data files and "lookup" tables, from the system disk for SEUCON CPC to use in the EU conversion calculations. This retrieval of data requires disk I/O interfaces utilizing DOS I/O available in the PDP 11/45 system. Three routines or subcomponents make up the CALDAT CPC; the main "driver" routine is written in FORTRAN; the other routines in assembly language. Refer to figure 1-10 for a virtual core layout of the CALDAT CPC.

2.2.4.1 Subcomponent Descriptions. Following is a description of the routines or subcomponents of the CALDAT CPC.

- A. CALDAT MAIN. This is a FORTRAN routine that controls the logic flow. Its function is to map into core, via SEG, the data areas into which the calibration data is to be stored and to call the routines that read the disk files into those data areas.
- B. CAL1. This is an assembly language routine that interfaces with the DOS-supplied disk I/O to read the calibration table EUTBLE.DA1 stored on disk into CALBUF data buffer.
- C. CAL2. This is an assembly language routine that interfaces with the DOS-supplied disk I/O to read the calibration table of F(α_0, θ) values (FTABLE.DAT) stored on disk into the FTA-BUF data buffer.



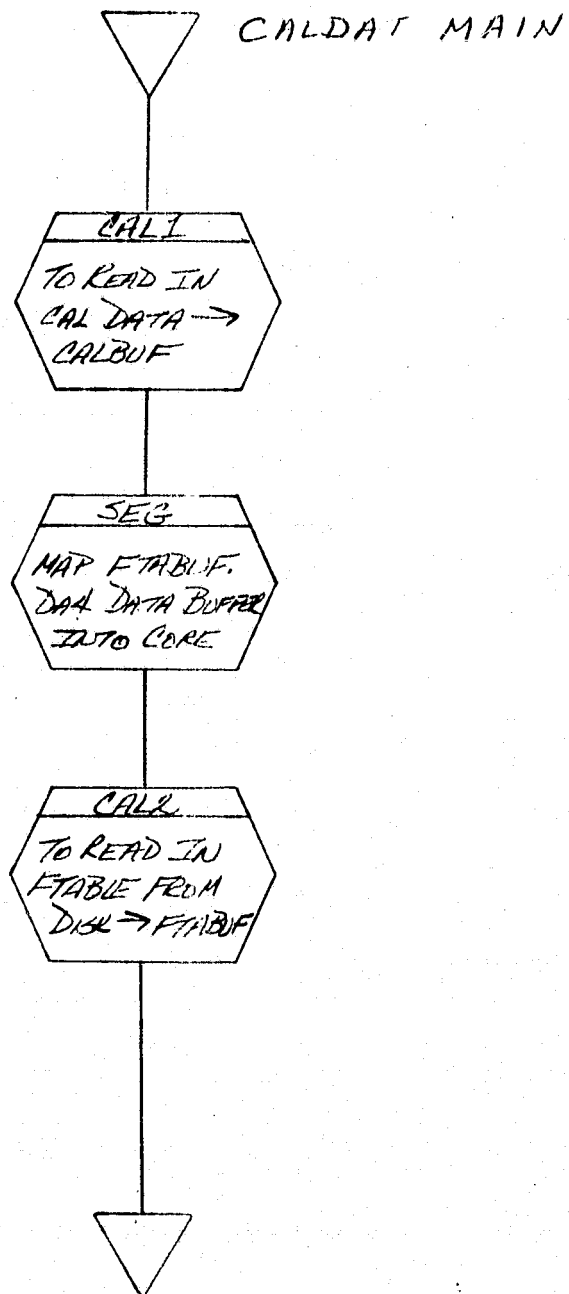
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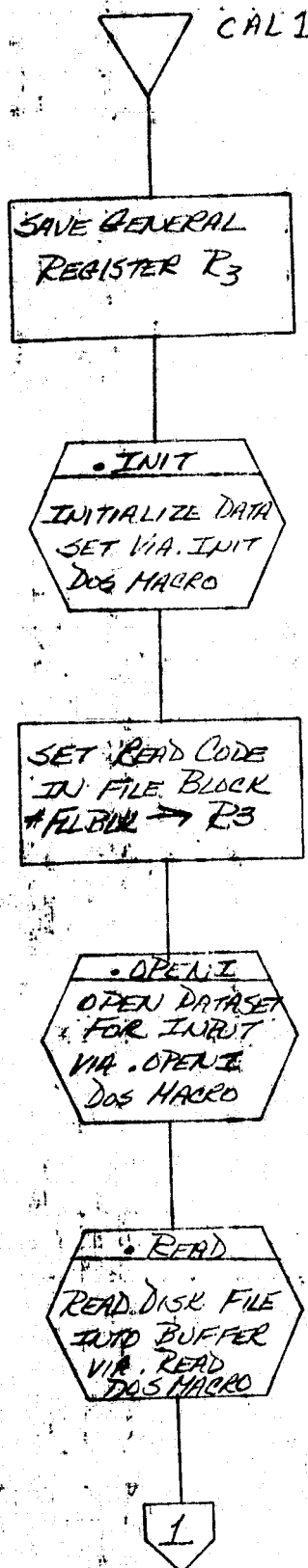
Figure 2-11 CALDAT CPC Virtual Core Map

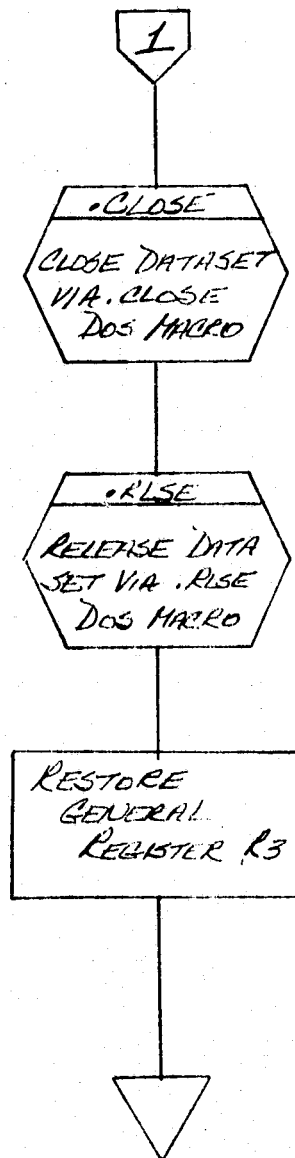
CALDAT is called from SEUCON just prior to processing the input data tape so that CALDAT can set up the calibration tables and lookup tables used by SEUCON in EU conversion processing. This is accomplished by a call from SEUCON to SEG to map into the 32K executable core the CALDAT load module and CALBUF data buffer. CALDAT MAIN is given control, and in turn makes a call to the CAL1 routine. The two routines (subcomponents) that perform the disk reads are written in assembly language to keep the execution time low. CAL1 performs the DOS I/O calls necessary to read the EUTBLE.DAT file from disk into CALBUF; that file contains T, E(T), and ITETAB tables. T represents absolute temperature values from 202.0 through 345.0 K increments; E(T) represents energy values corresponding to the temperatures contained in T; and ITETAB represents encoded surface temperature values set up as a "lookup" table. See figure 2-5 for a graphic description of the CALBUF data buffer as set up by CAL1.

CALDAT MAIN next maps the FTABUF data buffer into the virtual core area from 24-28K by a SEG call. CAL2 is called to perform the DOS I/O calls necessary to read the FTABLE.DAT file from disk into FTABUF. FTABLE contains 3523_{10} words of $F(\alpha_0, \theta)$ predetermined values to be used as a lookup table in the atmospheric correction algorithm in SEUCON. Having set up the two data buffers required in the EU conversion phase, CALDAT returns control to SEUCON.

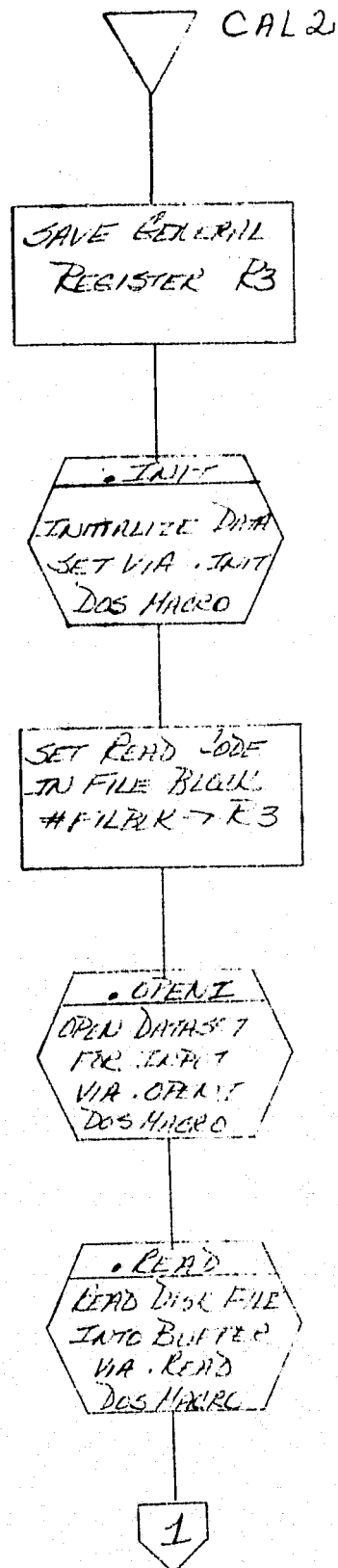
2.2.4.2 Flow Charts. See the following five pages.

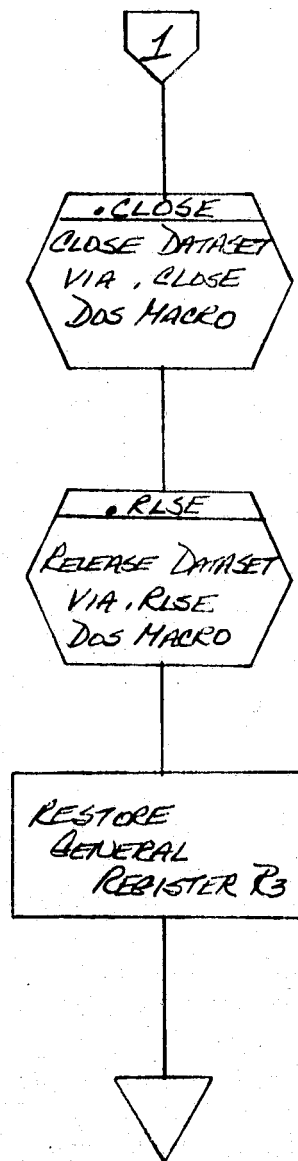






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2.2.4.3 Interfaces

- A. Input. There is essentially no input data external to CALDAT. The CALBUF and FTABUF data buffers, initially zero, are mapped into the 32K environment by CALDAT to use as input storage buffers.
- B. Output. The data output by CALDAT is the two data buffers described previously, formatted and filled with calibration data and lookup tables that are stored permanently on disk.
- C. Subroutines. The subroutines called by CALDAT are CAL1 and CAL2. These subroutines do the reading in of the disk data into the appropriate data buffers.
- D. Called. CALDAT is called by SEUCON only once during the initialization phase, just prior to processing the input data. CALDAT is called after EUDISP has completed its initialization functions and after HEDREC has generated the output header.

2.2.4.4 Data Organization. This paragraph describes the data items and tables unique only to this CPC, and that data internally located and defined in the CPC.

- A. LNK1. This is the link block table used by CAL1 in interfacing with DOS to perform the initializing, opening and reading of the specified data set files from disk. It is formatted as follows.

LO BYTE		HI BYTE	
-2	ERROR RETURN ADR (0 = RETURN TO DOS)		
LNK1: +0	LINKAGE ADR SET UP BY DOS		
+2	NAME OF DATA SET IN RAD50		
+4	NO. OF WDS TO FOLLOW	UNIT NO. OF DEVICE	
+6	NAME OF PHYS DEVICE TO LINK TO IN RAD50		

- B. FIL1. This is the file block table in CAL1 containing information for the data file to be read from the disk; it is used by DOS in performing the opening and reading of the disk file. It is formatted as follows.

	LO BYTE	HI BYTE
-4	ERROR RETURN ADR (0 = RETURN TO DOS)	
-2	FUNCTION CODE	ERROR CODE RETURNED
FIL1: +0	NAME OF DISK FILE IN	
+2	RAD50 AND EXTENSION	
+4	USER ID CODE (UIC): 0 = CURRENT UIC USED	
+6	PROTECT CODE (233)	

- C. BUF1. This is the buffer block table in CAL1 used by DOS to do the reading of the disk file. It contains information on the length of the file and the format in which to read the data. It is formatted as follows.

	LO BYTE	HI BYTE
BUF1: +0	SIZE OF DISK FILE IN BYTES	
+2	FORMAT BYTE	STATUS BYTE
+4	NO. OF BYTES TO TRANSFER ON READ	

- D. LNK2. This is the link block table in CAL2 used in interfacing with DOS to perform the initializing, opening and reading of the specified data set file from disk. It has the same format as LNK1 above.
- E. FIL2. This is the file block table in CAL2 containing information on the data file to be read from disk. It is used by DOS in performing the opening and reading of the disk file, and contains the same information as FIL1 above, in the same format.

- F. BUF2. This is the buffer block table in CAL2 used by DOS to do the reading (transferring) of the disk file. It contains information on the size of the disk file and the format in which to read the data. It has the same format as BUF1.

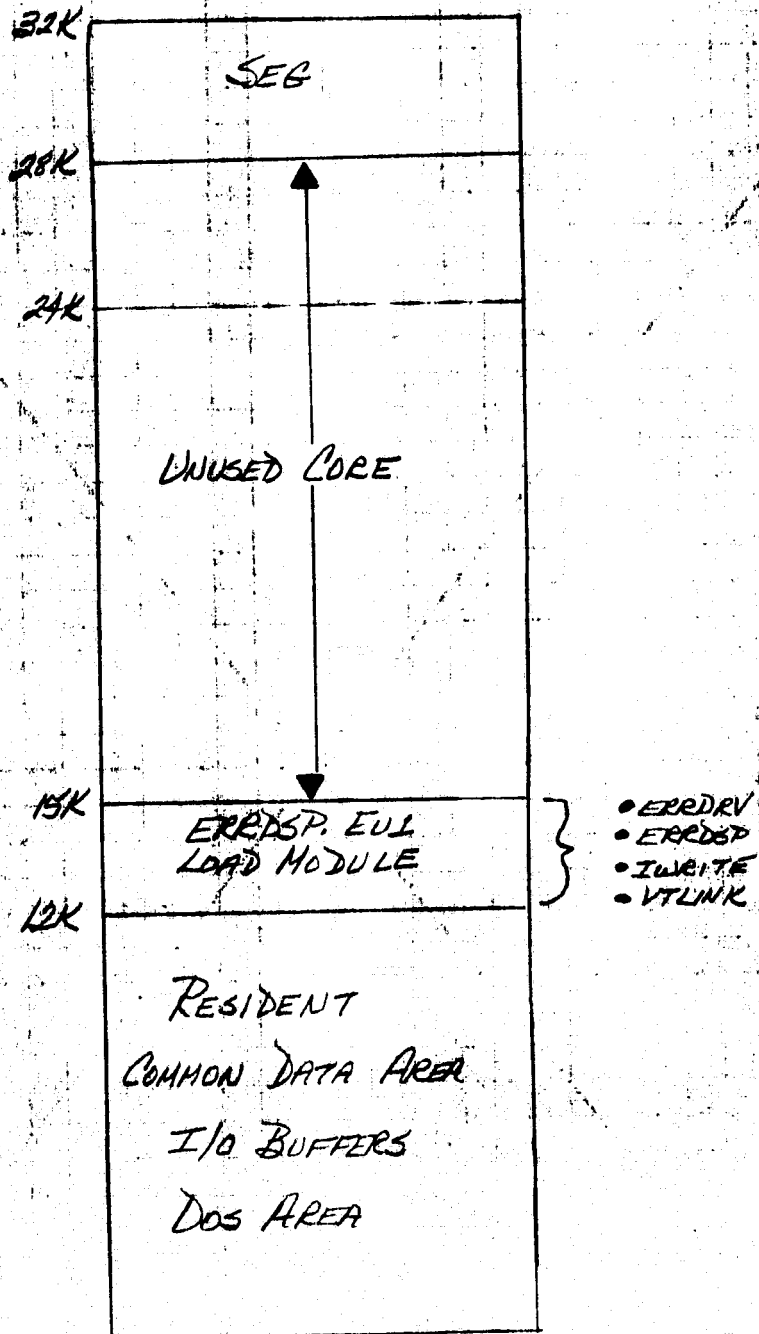
2.2.4.5 Limitations. None.

2.2.4.6 CPC Listings. See Part IV of this document, published under separate cover.

2.2.5 ERRDSP (CPC No. 5). ERRDSP is actually a service utility module for use by any CPC module in SEDS. Its function is to provide an error/advisory message displaying capability on the VT05 screen and the line printer for all of the CPC's in SEU. Its main purpose is to enable FORTRAN routines to communicate with the operator on the VT05, since the existing VT05 handler and input/output resident routines are not set up to be called by a FORTRAN routine. The major interfaces of ERRDSP are with the VT05 routine residing in RESIDENT in order to utilize the VT05 output features. ERRDSP is written mainly in PDP 11/45 assembly language with the exception of two routines. ERRDSP, being an assembly language load module, must have a FORTRAN driver in order to be called by the other CPC's via SEG. One of the service routines is also written in FORTRAN. See figure 2-12 for a virtual core layout of the ERRDSP CPC.

2.2.5.1 Subcomponent Descriptions. Following is a list and descriptions of the subcomponents comprising the ERRDSP CPC.

- A. ERRDRV. This a FORTRAN language routine used as a driver for calling the main routine of the load module. This routine is the linkage calling routine between the other CPC load modules and ERRDSP.
- B. ERRDSP MAIN. This assembly language routine is the main subcomponent and is responsible for setting up the messages and making calls for interfacing with the VT05 and line printer.



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Figure 2-12 ERRDSP CPC Virtual Core Map

- C. IWRITE. This is a FORTRAN routine called from ERRDSP MAIN that outputs a specified message to the line printer.
- D. VT05H. This is an assembly language VT05 handler routine in RESIDENT responsible for all outputs to the VT05. A command package is passed to VT05H when called to designate an output function and format.

ERRDSP is called whenever a CPC of SEU or any SEDS program has a need to notify the operator of an error condition, or to make a request for operator action by displaying on the VT05 a specific canned message. ERRDSP is called by a SEG call, and control is given to the FORTRAN driver ERRDRV. ERRDRV in turn calls ERRDSP to do the actual message handling. Prior to making a SEG call to the ERRDSP CPC, the calling routine must set up parameters in a data file residing in the resident common data area. The file is the ERROR COMMON, consisting of two parameters -- IERR, the error code, and INUIT, the unit on which the error occurred, if applicable. ERRDSP addresses to pick up the correct message to be displayed. Error codes are divided into two sets. Codes 1-99 are for messages that use the second parameter (IUNIT) to refer to the unit on which an error occurred or to which an advisory applies; that unit number is included in the displayed message. Codes 100-300 are messages for which the second parameter is not applicable. See table 2-5 for a list of canned messages available for output by ERRDSP.

ERRDSP picks up the address of the requested message by using the error code as an index into the MSGTB1 or MSGTB2 tables (depending on which of the two sets the error code belongs to). These two tables contain address pointers to the various messages in sequential, numerical order. The messages themselves are in the form of ASCII character strings, terminated by a line feed character (LF). ERRDSP transfers the character string to an output buffer (MSGBUF), inserting ASCII blanks if necessary to completely fill the buffer. If the error code is of set 1 (codes 0-99), ERRDSP inserts the unit number contained in the IUNIT parameter on the end of the canned message for output. A call to VT05H is made to display the message as formatted in the MSGBUF output buffer. The call is made from ERRDSP by means of an EMT142, passing the address of a command block in general register R0. The

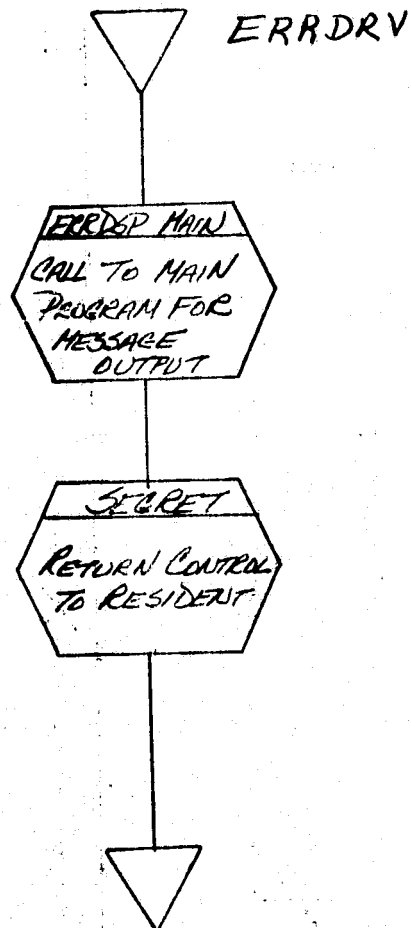
TABLE 2-5
ERRDSP ERROR AND ADVISORY MESSAGES

CODE	MESSAGE
1	***TAPE READ ERROR ON IMAGERY INPUT TAPE--MT_***
2	***EU PROCESSING STOPPED-EOF OR EOT REACHED--MT_***
3	***EOT OR EOF REACHED AFTER READING HEADER--MT_***
4	***HEADER TAPE OUTPUT ERROR--MT_***
5	***TAPE WRITE ERROR--MT_***
6	***JOB ABORTED-TAPE READ ERROR ON 1ST DATA SET--MT_***
7	***JOB ABORTED-TAPE READ ERROR ON HDR--MT_***
21	***EOT DETECTED; REGISTRATION TERMINATED--MT_***
100	***INVALID IR CHANNEL TAG-CHANNEL ZEROED***
101	***INVALID VIS CHANNEL TAG-CHANNEL ZEROED***
102	***SCAN COUNT DECREMENTED-PROCESSING ABORTED***
103	***INVALID CHANNEL TAG-CHANNEL ZEROED***
104	***TIME DISCONTINUITY***
105	***INVALID THUMBWHEEL OPERATOR INTERRUPT***
106	***INVALID INPUT TAPE-MOUNT CORRECT TAPE, TYPE 'CON'
107	***COMPLETED EU PROCESSING***
118	**DISK ALLOCATION ERROR ON COEF. FILE OUTPUT
119	**DISK ALLOCATION ERROR ON COEF. FILE INPUT
120	***EXCESSIVE ROTATION; JOB ABORTED
121	***NO DATA FOUND IN EPHEMERIS DISK FILE
122	***DISK FILE ALLOCATION ERROR; JOB ABORTED
123	***HEADER DISK FILE WRITE ERROR; JOB ABORTED
124	***DATA DISK FILE ERROR; JOB ABORTED
125	***EXCESS. TRANSLATION; ZERO FILL FOR THIS PASS
126	***REGISTRATION PHASE IN PROGRESS***
129	***DISPLAY TIMEOUT FAILURE-JOB ABORTED
130	***EMISSIVITY DISK FILE READ ERROR; JOB ABORTED***
131	***SKIP PROCESSING-COMPLETE IR OUTPUT OF ZERO FILL
132	***SKIP PROCESSING-COMPLETE VIS OUTPUT OF ZERO FILL
133	**DISK READ ERROR-NOT ABLE TO READ COEFFICIENTS
134	**DISK WRITE ERROR-COEFFICIENTS NOT SAVED ON DISK
201	***COMPLETED DAY IR CHANNEL REGISTRATION
202	***COMPLETED REGISTRATION PHASE

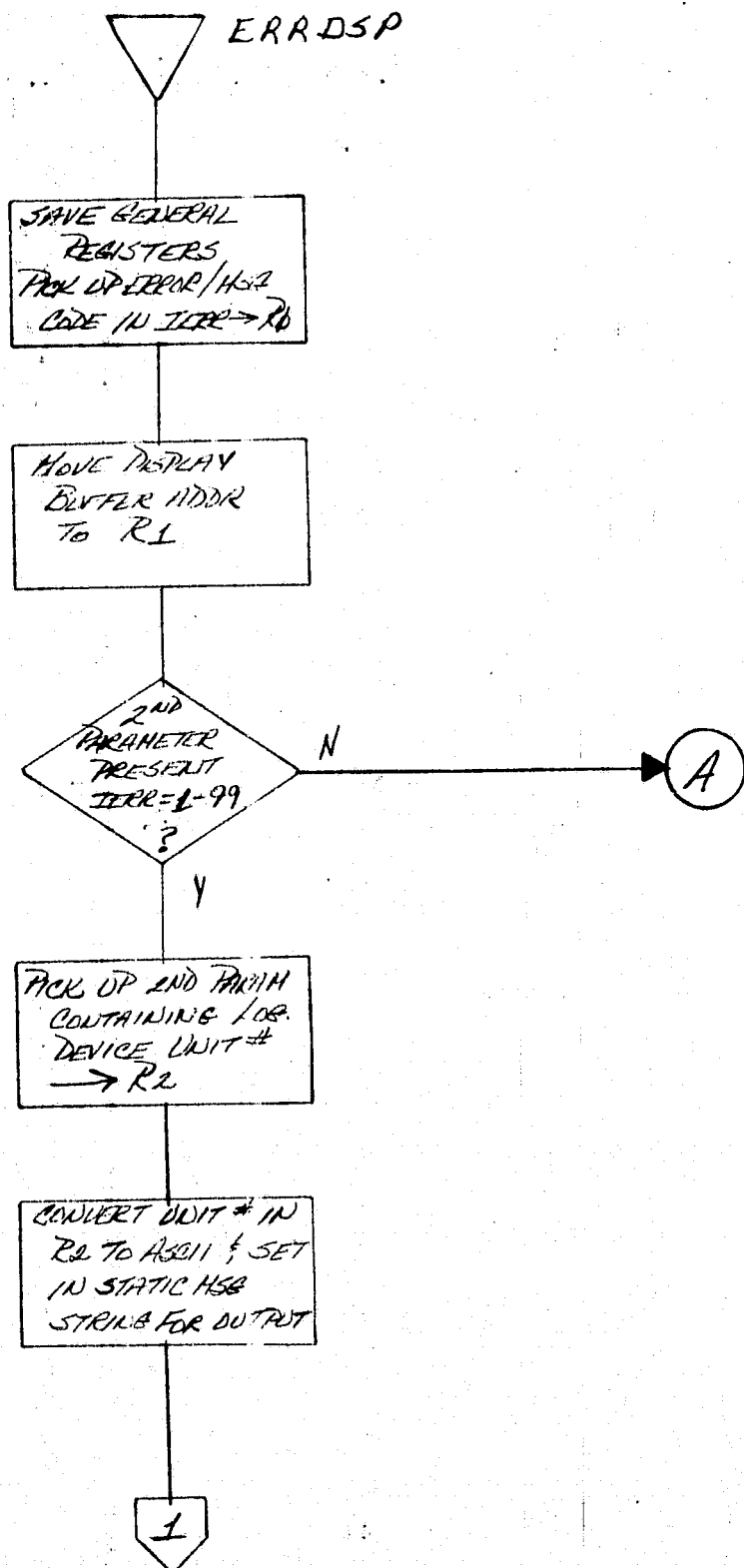
command block contains information used by VT05H, such as the address of the input buffer, the output line on the VT05 for the messages, and the format. VT05H outputs the message on the VT05 screen and returns to ERRDSP. ERRDSP calls IWRITE to log the same output message on the line printer. IWRITE is a FORTRAN subroutine and is included in the ERRDSP CPC since I/O interfaces with the line printer are accomplished more easily from a FORTRAN routine than they are from an assembly routine means of a WRITE statement. ERRDSP then returns control to the calling routine.

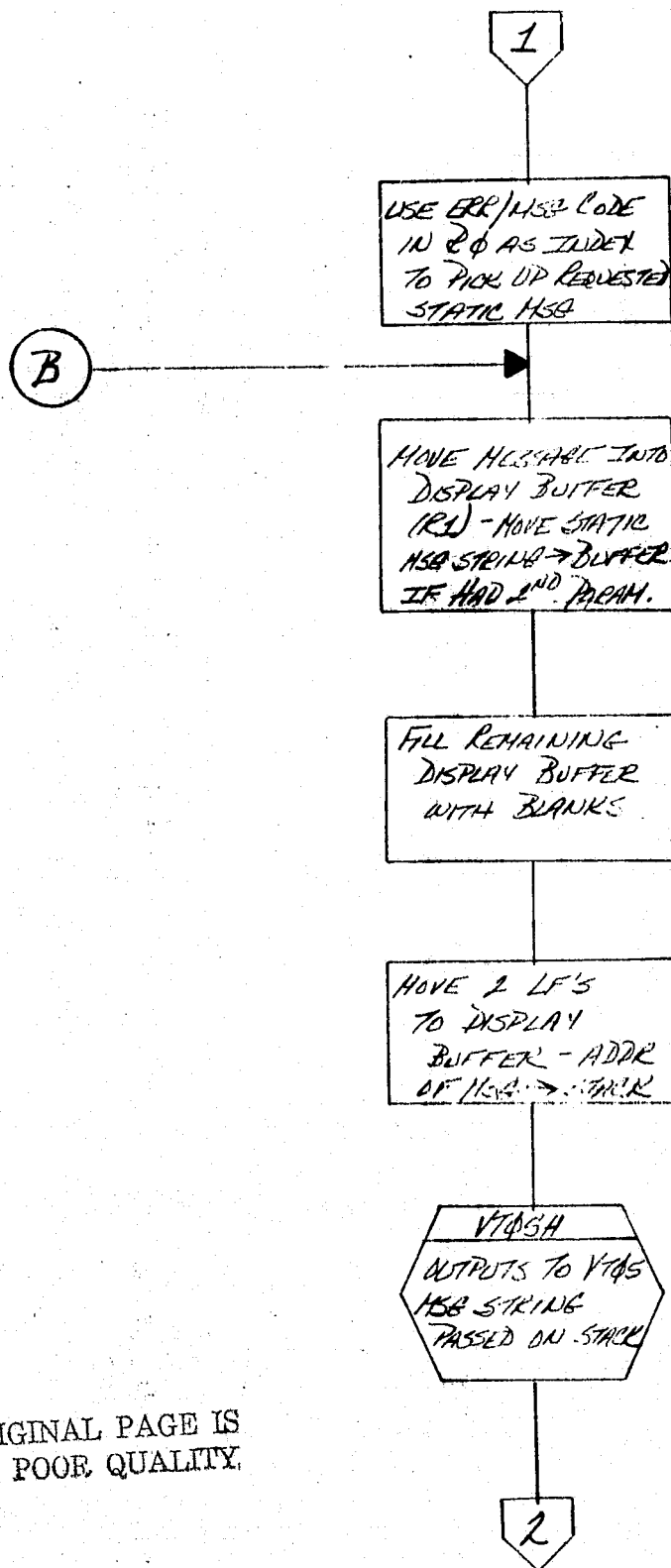
Since ERRDSP is used purely in a service capacity, any CPC load module in the SEDS system can use this routine. It is not limited to any one program such as SEU, SRE, etc. It is set up as a load module to be accessed by means of a SEG call, or it can be linked in with other routines in a particular load module if there is enough free core in that load modules virtual map. In this latter case, a direct call or JSR is sufficient to call ERRDSP. As will be noted in the section on SRE, the ERRDSP module is used in the CPC's in both of the above setups. It was designed to enable a load module to link ERRDSP in with it or call ERRDSP load module via a SEG call.

2.2.5.2 Flow Charts. See the following five pages.

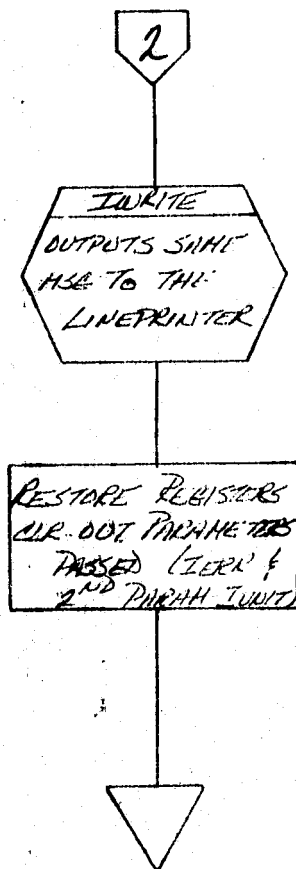


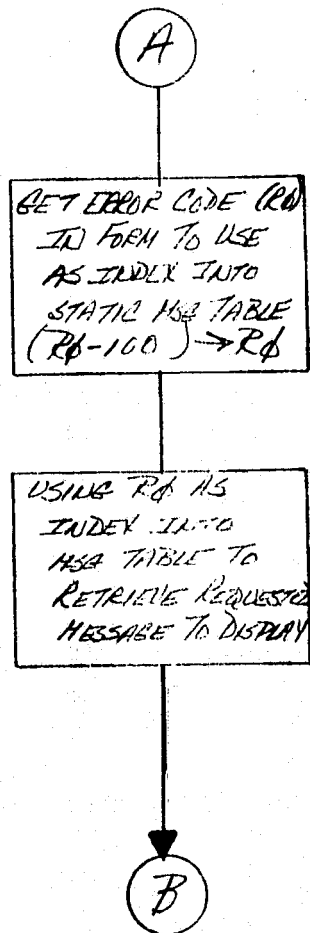
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2.2.5.3 Interfaces

- A. Input. The only input data to ERRDSP is the error data common in RESIDENT, set up by the calling routine, COMMON/ERROR/IERR, IUNIT. IERR is a 16-bit integer word representing an error code of 1-300, while IUNIT is a 16-bit integer word containing the unit number on which the error occurred, set up only if applicable.
- B. Output. The output data from ERRDSP is a command block and the formatted message to be displayed via VT05H on the VT05.
- C. Subroutines. The subroutines called by ERRDSP CPC are ERRDRV, ERRDSP MAIN, IWRITE, AND VT05H. These are discussed in paragraph 2.2.5.1.
- D. Called. ERRDSP is called by any CPC in the SEDS system that requires the VT05 message displaying services. The call is made by a SEG call to the load module or by a JSR or CALL Statement from a module that has ERRDSP linked to it.

2.2.5.4 Data Organization. ERRDSP contains unique data items and tables defined internally and contained within its subcomponents. This data is for purposes of being accessed and used only by those routines contained in the ERRDSP CPC.

- A. VTMSG\$. This is the command block passed to VT05H describing the output requested. It is formatted as follows.

	BYTE 1	BYTE 0
VTMSG\$: +0	OUTPUT REQUEST	SPARE
+2	COL NO.	LINE NO.
+4	ADR (MSGBUF) OF OUTPUT MSG BUFFER	

- B. MSGBUF. This is the output buffer table of 58₁₀ bytes. The canned message is placed in this buffer for output by VT05H.

- C. MSGTB1. This is a predetermined table of addresses for the messages with codes of 1-99. ERRDSP uses the error code value as an index into this table to set the address of the message to be displayed. The format is as follows.

ADR OF MSG 1
ADR OF MSG 2
ADR OF MSG 3
...
ADR OF MSG 99

- D. MSGTB2. This is a predetermined table of addresses for the messages with codes of 100-300. ERRDSP first subtracts 100₁₀ from the code and uses it as an index into this table. The format is as follows.

ADR OF MSG 100
ADR OF MSG 101
ADR OF MSG 102
...
ADR OF MSG 300

- E. MSG1, MSG2, MSG3, Etc. Contained within the ERRDSP MAIN routine, these are the ASCII character strings of canned messages with the labels MSG 1 through MSG 99 and MSG 100 through MSG 300. Each message is terminated with a line feed (LF) character in the ASCII string.

2.2.5.5 Limitations. When ERRDSP is called via SEG, since it is a multiuser program, it has no way of knowing what the calling program is. Therefore, it exits via SEG to the resident routine. This limitation requires careful attention when using ERRDSP to output an advisory or error message when the user wishes to continue at the next instruction after the SEG call.

2.2.5.6 Listings. See Part IV of this document published under separate cover.

SECTION 3

SEDS IMAGE REGISTRATION PROGRAM (SRE)

3.1 GENERAL PROGRAM CHARACTERISTICS

SRE is the program of SEDS which is responsible for the image registration of the EU converted NOAA-satellite data output from the SEU Program. In general, this involves inputting an EU processed tape and "mapping" the data image to a predefined SEDS reference grid of Mexico. This registration process consists of four steps as follows.

- A. Locating preassigned ground control points from the input image to provide a means of obtaining coefficients for mapping the image to the reference grid.
- B. Coarse-rotating the image, if the EU tape is a night pass, to conform to a day pass.
- C. Using the mapping coefficients to determine the amount of scaling, translation, and rotation needed to apply to the data in order to achieve correct registration.
- D. Building a registered disk file with the night IR, day IR and visible channels of registered data.

The SRE Program also provides, as optional output products, a registered IR tape and isothermal images.

Mapping coefficients used to register the data are obtained during an initial phase of SRE referred to as the GCP phase. The operator is provided a means of screening the input tape and manually selecting ground control points (GCP's) recognized in the image. These key points relate to the coordinate points in the reference grid image. By using these corresponding sets of coordinates in the two images, coefficients are calculated for mapping one image to the other.

For a night pass tape, the SRE Program enters a separate phase of processing where the data is rotated clockwise 25.8 degrees and the scans and PIXEL's reversed. This is done prior to the actual registration so that the image looks like a day pass.

The last step of SRE is the registration of the image. One by one, data scans are read from tape into a buffer in core. The translation and scaling is performed on each scan as indicated by specific mapping coefficients. This continues until the required number of scans have been placed in the buffer to begin rotation (resectioning) of the "corrected" data. A precomputed number of PIXEL's is extracted from each scan in the buffer to build one output "registered" scan. This scan is then written to the registered disk file which will eventually contain the entire registered image, and will be used as input to the RAP Program.

Since SRE is a complex program, we will refer to each unique phase of the registration processing as a computer program component (CPC). There are essentially three phases of SRE as outlined previously:

- Initialization and GCP phase
- Night coarse rotation phase
- Data image registration and disk build phase.

SRE is broken down into three memory mapping configurations (MMC), each representing a 128K physical core assignment. Each MMC contains load modules (LDA) consisting of routines and subroutines that perform the functions of SRE. The SEDS resident module relinquishes control to each MMC in a predefined processing sequence by first mapping in the MMC via CALL NEWMCMC ('AAA'). This sets up the memory mapping for a particular MMC in core. Next, a SEG call is made to give program control to a specific load module within that MMC by CALL SEG ('XXXXXX.LDA',N,N). Figure 3-1 represents the MMC layout of the SRE Program and the load modules of each MMC.

The three major CPC's and the phase of processing performed by each are:

- SRE CPC - Initialization, job setup, GPC processing
- ROT CPC - Night coarse rotation of data to prepare image for registration
- REG CPC - Data image registration to include translation and scaling corrections and rotation (resectioning) of the data to register it to a predefined reference grid.

3.1.1 Functional Allocation. As stated in the PHO-TN734, SRE performs the image registration requirement of mapping NOAA satellite day pass or rectified night pass data onto the SEDS reference grid. In mapping the data, a Lambert Conformal Conic projection map is utilized as a reference grid. The registration of an image data array (E,S) from the NOAA satellite to the planar reference grid coordinates (X,Y) is accomplished via six remapping coefficients. These coefficients are calculated during the GCP phase (SRE CPC). The coefficients include translational scaling and rotational corrections. A "least-squares fit" approach is used to determine these coefficients by locating a sufficient number of GCP's. The location of GCP's from the IR data is accomplished by use of the interactive color display (ICD) system. Image data is output to the ICD and the operator can identify key points in the image by a manual capability (discussed in paragraph 3.2.1). The (E,S) coordinate of the identified point is determined and the corresponding (X,Y) point in the reference grid is picked up to perform a fit of $(E,S) \rightarrow (X,Y)$. For night data, each identified GCP (E,S) is first rotated through a predetermined angle to reflect it in the day pass coordinate plane. This is necessary since the calculations for determining the coefficients are done on the assumption that coordinates of points be in the day pass coordinate plane. Now the mapping coefficients are computed using all GCP's identified. Statistics on the GCP's located, their fit, and the mapping coefficients are displayed on the VT05 for GCP identification accuracy and to determine when enough points have been located. The GCP phase is terminated via the operator when a sufficient number of points have been identified and the coefficients are approximately what they should be for a correct fit.

If the data is a night pass image, the program enters the night coarse rotation phase (ROT CPC). The input data is first compressed 4 to 1 in each direction by averaging 4×4 PIXEL arrays together. The compressed image is output to disk and read back in reverse scan line order into a buffer. The image is rotated 25.8 degrees clockwise by resectioning buffered lines at that angle, creating rotated compressed scan lines. In each scan line prior to output, the PIXEL's are reversed; and the entire image is decompressed 1 to 4 by repeating PIXEL's and scan lines four times each. Each resultant scan line is written to a 9-track CCT (CRT tape) to be used as input to the registration phase.

The program next enters the actual registration phase (REG). The remapping coefficients obtained during the GCP phase are applied to map the input image array (E,S) to the reference grid array (X,Y), as follows:

$$X = A_1 + A_2E + A_3S$$

$$Y = B_1 + B_2S + B_3E$$

Where:

(A_1, B_1) = translational corrections

(A_2, B_2) = scaling corrections

(A_3, B_3) = rotational corrections

"Nearest neighbor" radiometric value assignments are used to map the input PIXEL's to the reference grid locations. The scaling and translational corrections are applied to each scan line as it is input for the registration pass. An adequate number of corrected scan lines are then buffered so that they can be resectioned at an angle as indicated by the rotational correction coefficient. These resectioned scan lines are now registered to the reference grid and are output to the registered disk file. Figures 3-2 through 3-4 are graphic portrayals of the general functions of each CPC of SRE.

3.1.2 Program Flow Chart. See figure 3-5.

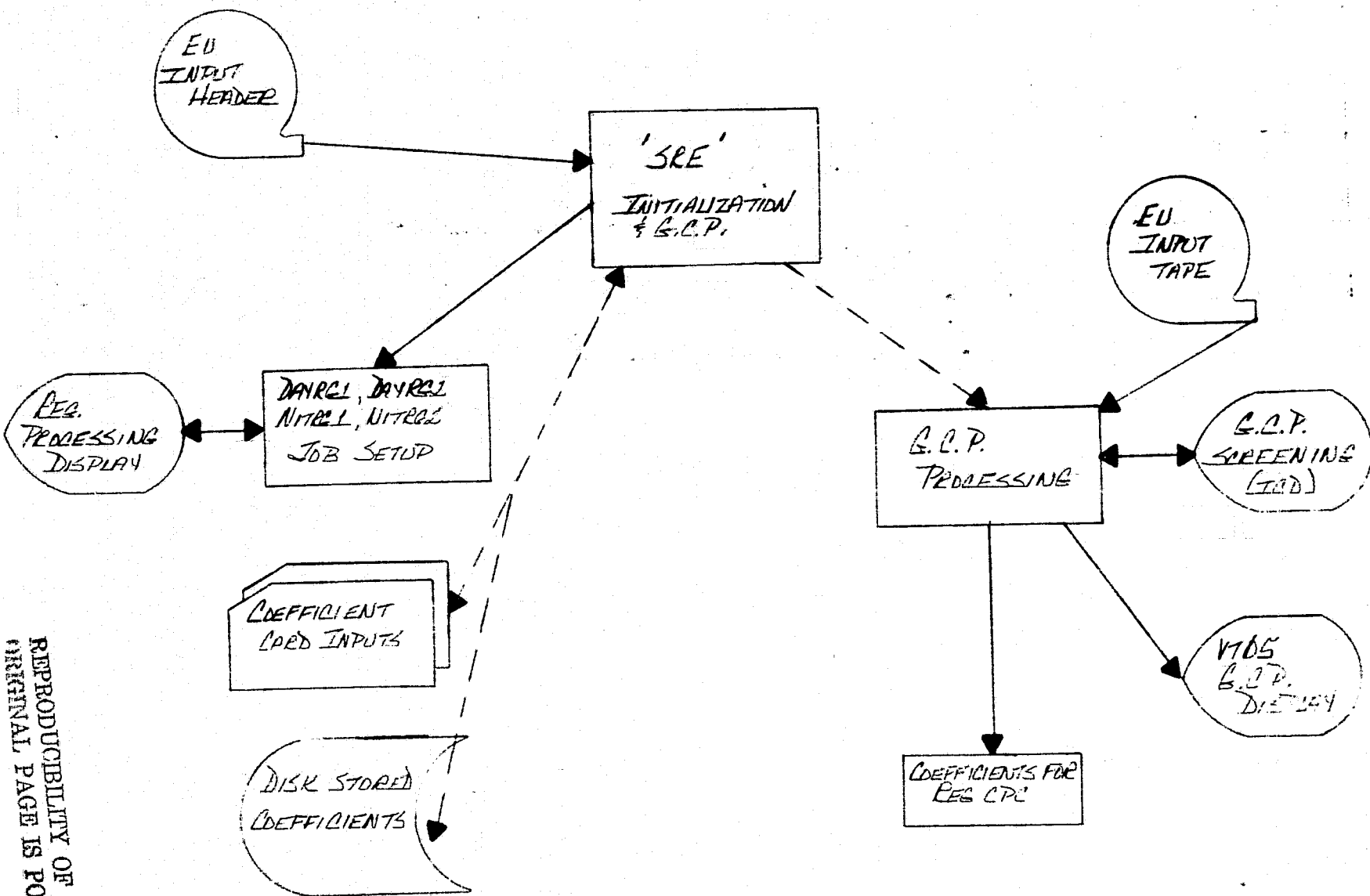


Figure 3-2 SRE (CPC No. 2) Basic Configuration

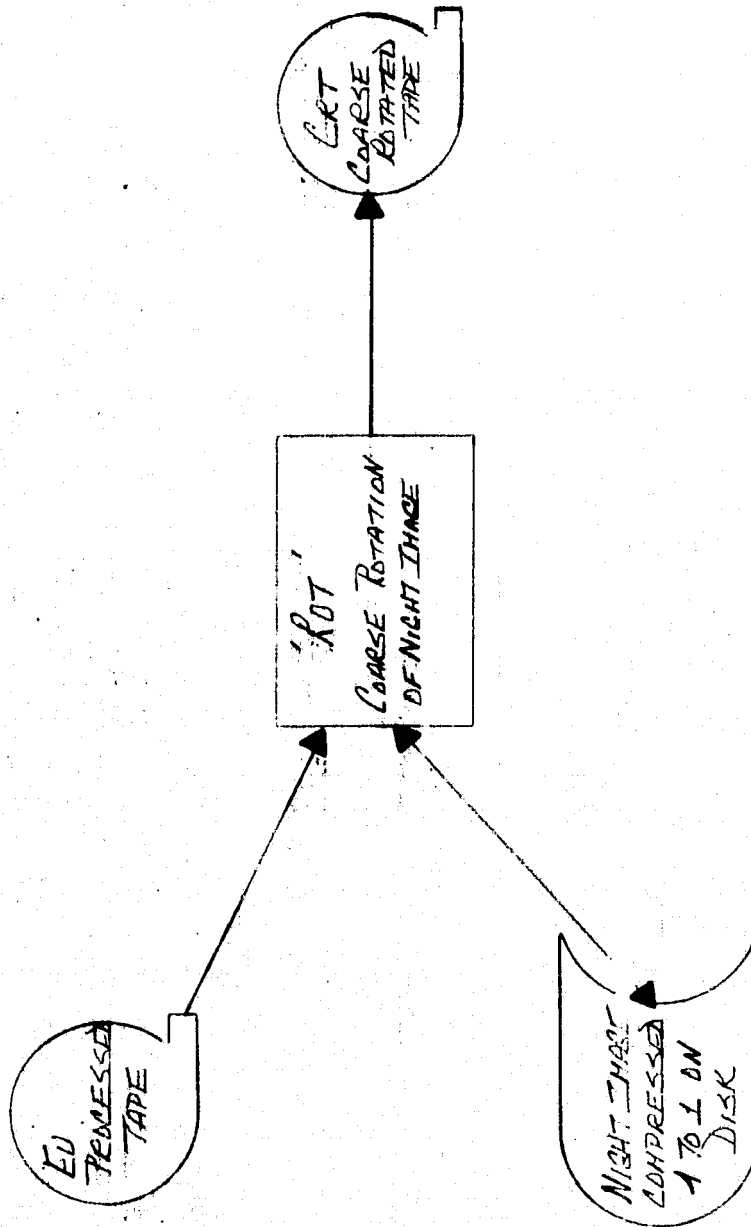


Figure 3-3 ROT (CPC No. 2) Basic Configuration

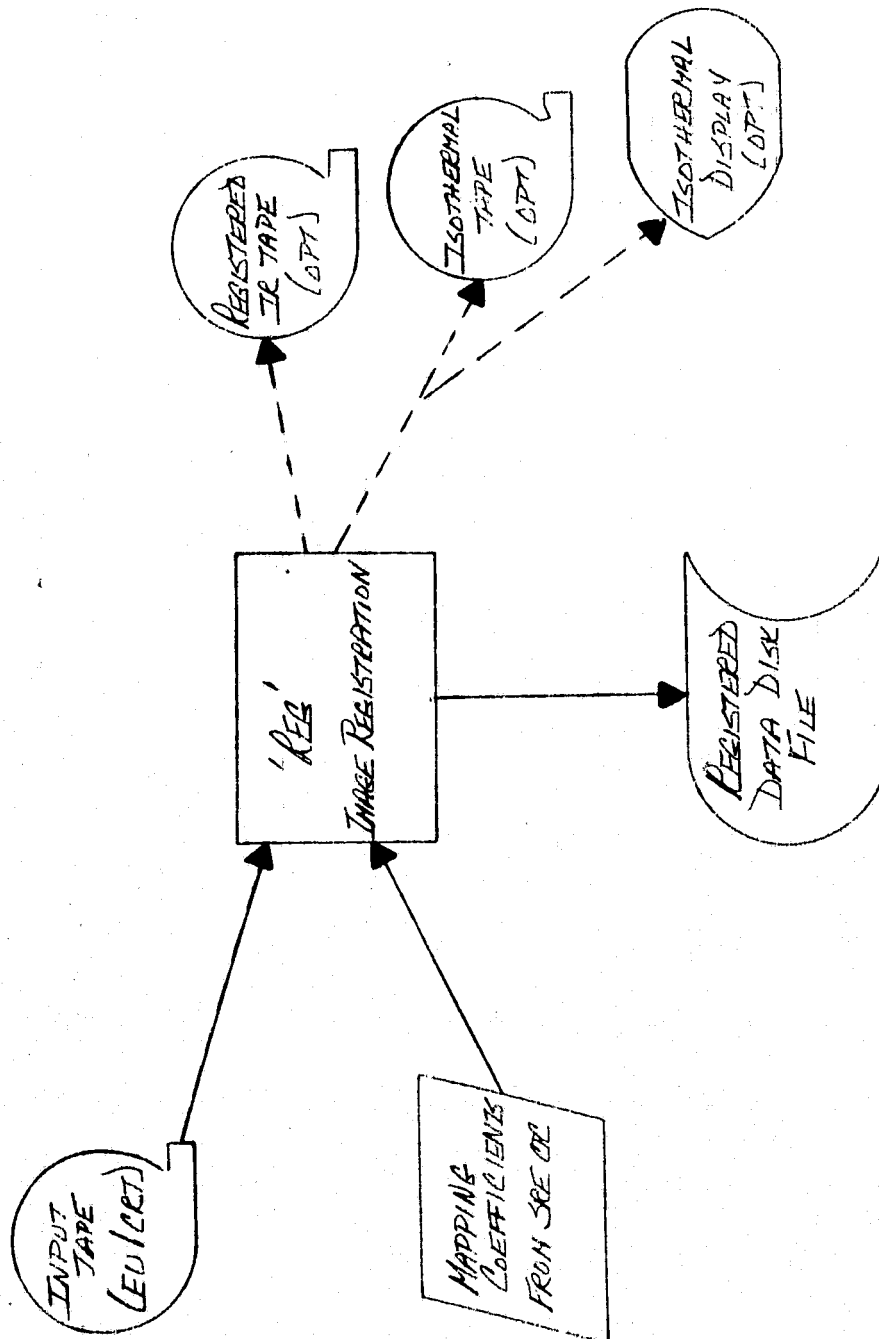


Figure 3-4 REG (CPC No. 3) Basic Configuration

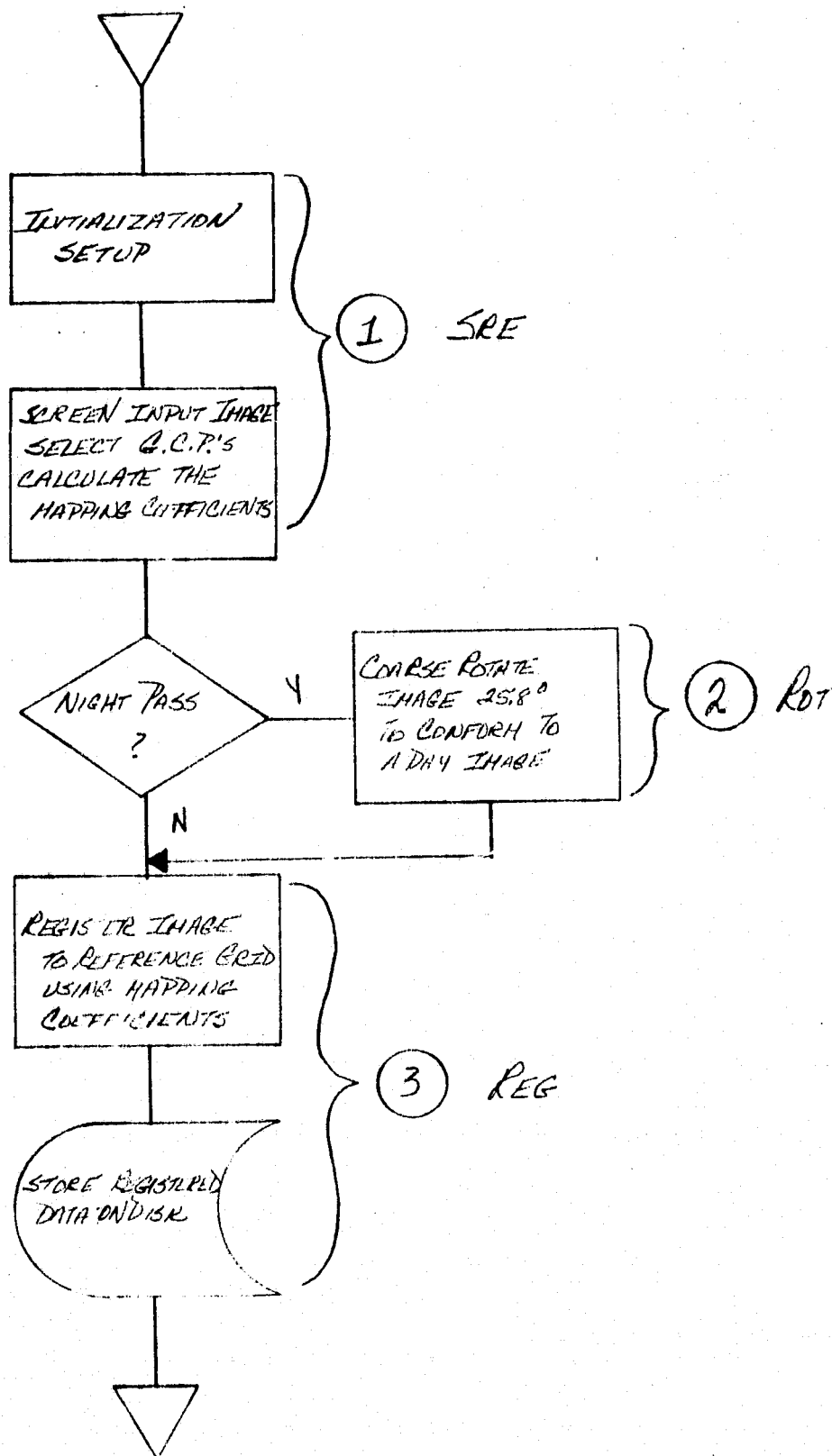


Figure 3-5 General Program Flow

3.1.3 Timing and Sequencing. As the SRE Program unit is called up for the registration processing following SEU, program control is given to the SRE CPC for initialization and job setup. The SRE CPC's interface with the VT05 handlers to output registration initialization displays and handle operator inputs. The mapping coefficients can be entered via cards or from disk storage in cases of job returns. In this case, the coefficients are entered into the system and a tabout is output to the line printer containing the input coefficients. The SRE CPC then returns to the SEDS resident routine to proceed to the next appropriate phase. If this is not a rerun, the SRE CPC enters the GCP phase where it interfaces with the VT05 and the ICD system to provide screening of the data and the location of GCP's via the operator. This involves a multipass screening to enable receiving the entire image. The sequence consists of reading a scan of IR data from the EU input tape and interfacing with a routine which schedules an interrupt-driven routine to output the scan line data to the ICD. The SRE CPC routine must wait for a complete flag before proceeding to the next scan line. The GCP process cannot be definitely time-tagged, because it depends on the number of passes necessary to view the image and collect enough points for adequate registration. The operator is able to halt temporarily the screening of the data to identify GCP's. For each identified point, the SRE CPC computes a "fit," mapping coefficients, and other statistics. This data is then refreshed on the VT05 display via the VT05 routines. When finished with the GCP phase, the SRE CPC returns to the SEDS resident routine for the next phase of the registration program to be called up.

If this is a day pass, the SEDS resident routine calls in the REG CPC modules to begin registration processing. If this is a night pass, the SEDS resident routine calls in the ROT CPC modules to perform the night coarse rotation. ROT modules interface with NTRAN to accomplish the necessary tape and disk I/O. As each scan is read in from the EU input tape, each set of four PIXEL's is averaged, as well as each set of four scans. The compressed scans are written to disk. When the program is finished with all scans, the compressed data on disk is read back into a core buffer in reverse order; (i.e., scan lines reversed). The data is resectioned (rotated), PIXEL's reversed, decompressed and written out to tape. This tape is to be used in the last phase of SRE as the input to registration. ROT CPC returns to the SEDS resident routine to call up the registration processing modules (REG CPC). The night coarse rotation phase takes approximately 15-20 minutes.

REG CPC modules now perform the registration of the input data (EU or CRT tape). Each scan is read into core via the NTRAN tape I/O routine and scaling and translational corrections are done. The corrected scan is put into the rotation buffer, where resectioned scan lines are taken out to build a registered scan for output. The REG CPC then writes the scan to the disk using the NTRAN disk I/O routine. If the output products are selected, the REG CPC writes the scan to the IR tape via NTRAN and interfaces with the product generator routines (paragraph 5.2.3) to build the isothermal products. The REG phase takes approximately 40-50 minutes for a day pass, which includes visible and IR channels, and approximately 27 minutes for a night pass, which includes only the IR channel. However, if no output products are requested, the execution time is significantly reduced. The interfacing and output to the ICD for isothermal products uses a significant amount of CPU time, since there is a "wait-for-completion" for each scan line output.

3.1.4 Storage Allocation. Figures 3-6 through 3-11 represent graphically the storage allocations of the SRE Program. Also illustrated are the physical and virtual core layouts of each CPC (or memory map configuration).

The virtual core layout represents each 32K load module within each CPC. During program execution, only 32K of core can be accessed at any one time. That is the reason for the division of MMC's into load modules when the MMC unit is too large for 32K. Each MMC or CPC represents a 128K physical core map. SRE has three MMC's, since the entire SRE Program unit is larger than 128K. In a given MMC (e.g., REG), when the program and data core required is greater than 128K, the MMC resorts to an overlay scheme. Load modules having the same extensions are potential overlays should the core required for an MMC be greater than the 128K available physical core of the PDP 11/45. Of these load modules with the same extension, the largest one is set in physical core to allocate the necessary memory space. The overlay load modules are stored on disk. When needed for program execution, the load module is read from disk by SEG and placed in physical core, overlaying the load module of the same extension. The load module previously residing in physical core is saved on disk.

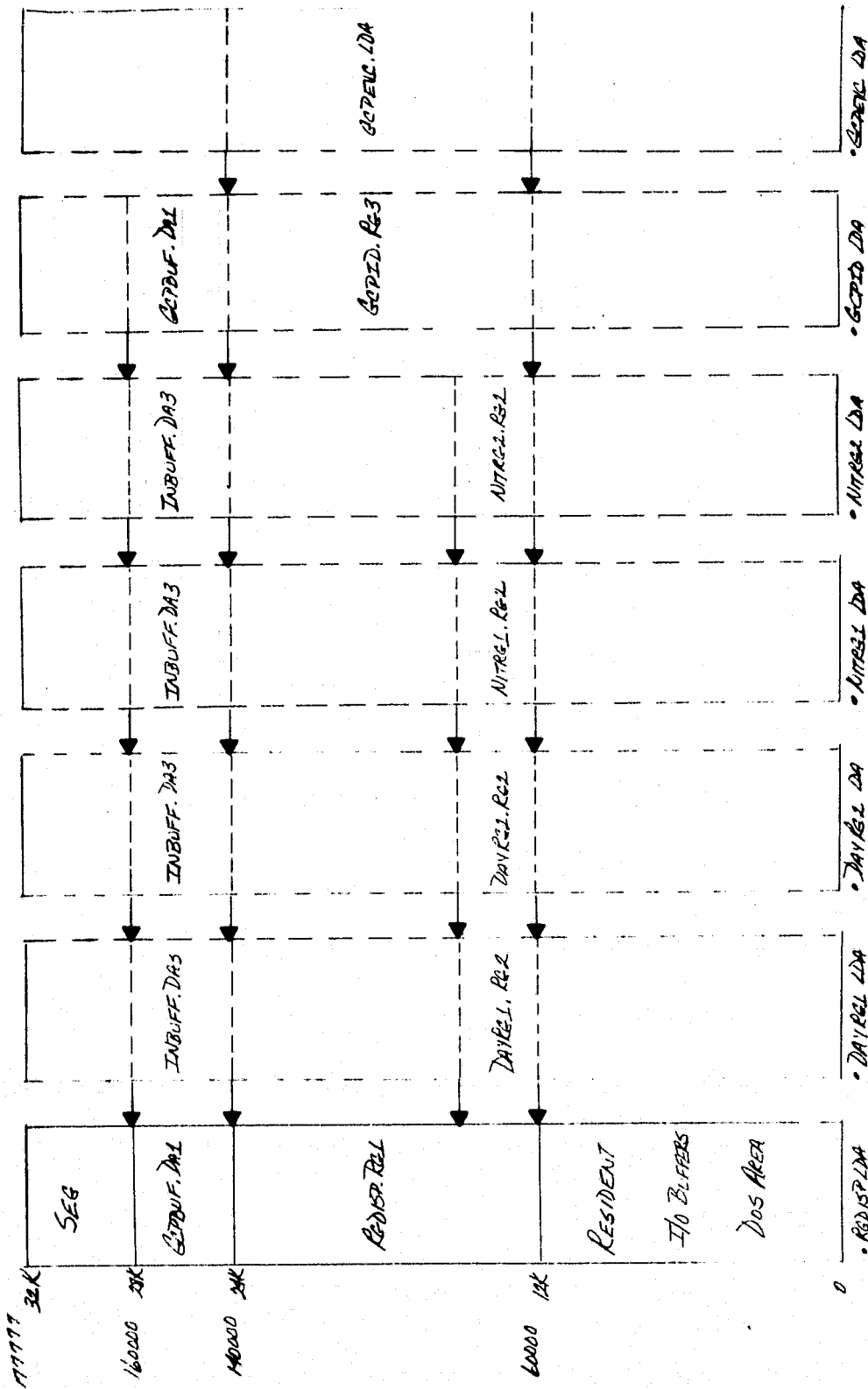


Figure 3-6 SRE CPC 32K Virtual Core Allocation

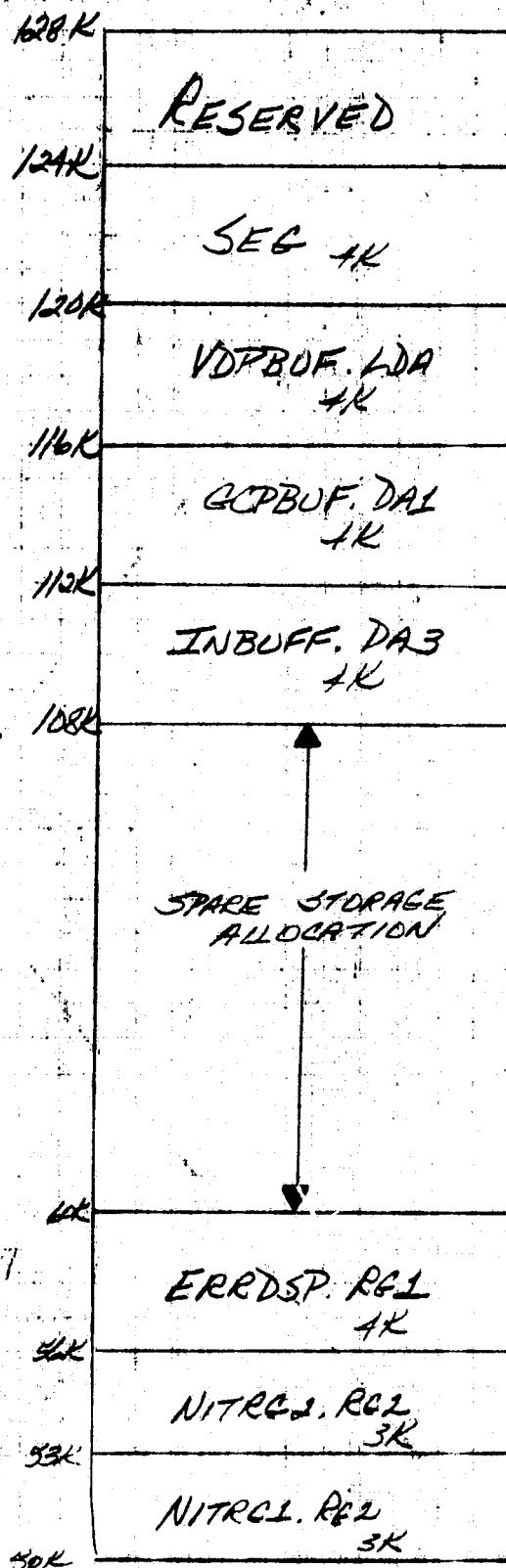
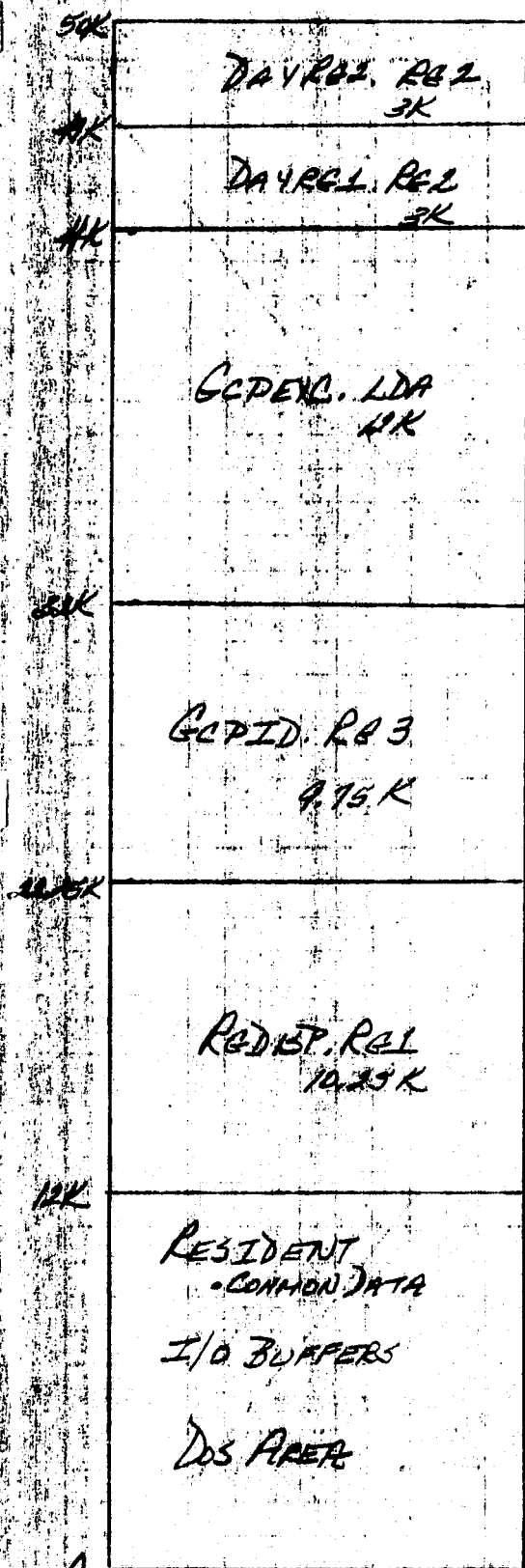


Figure 3-7 SRE CPC Physical Core Allocation

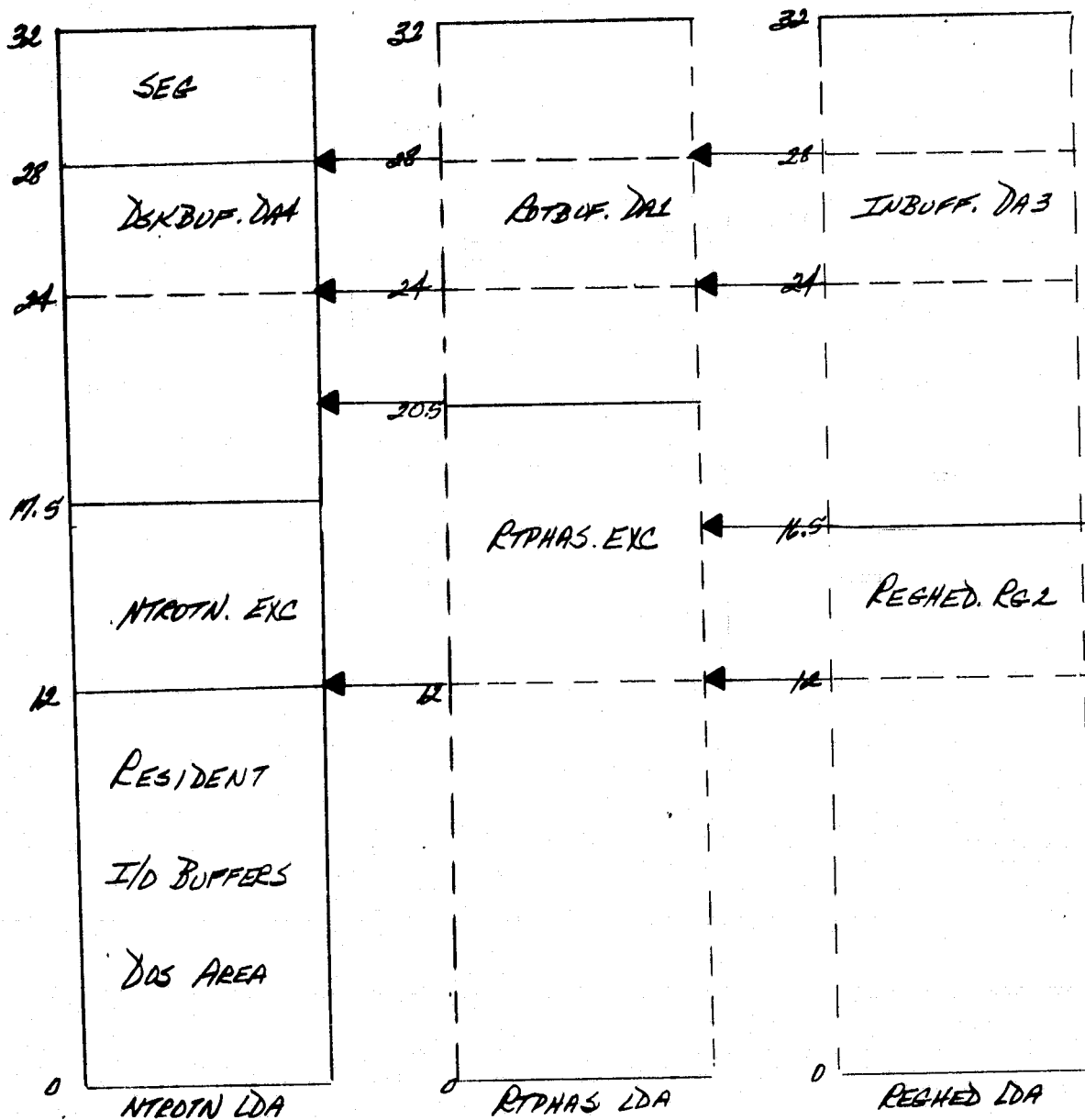


Figure 3-8 ROT CPC 32K Virtual Core Allocation

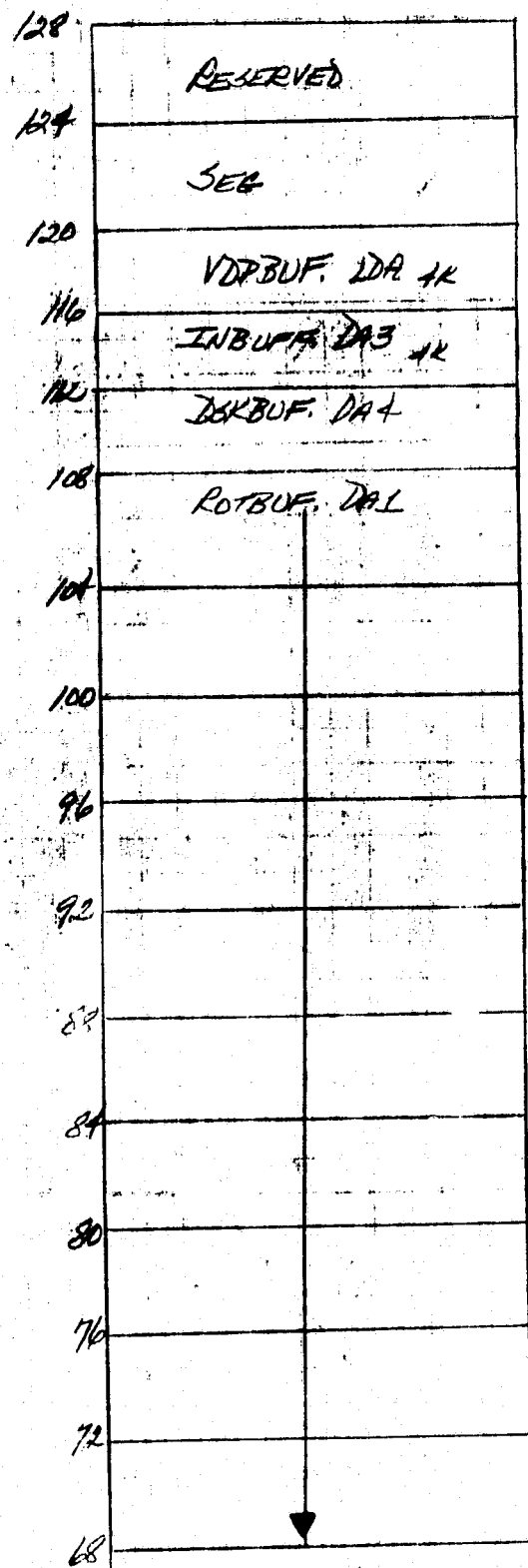
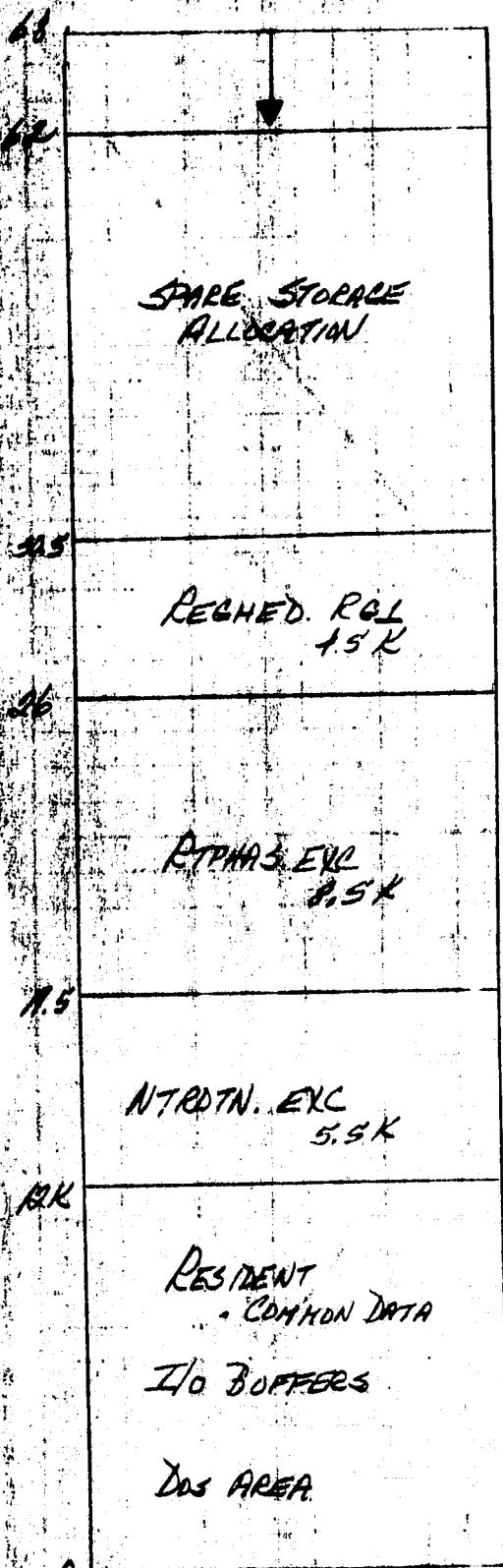


Figure 3-9 ROT CPC Physical Core Allocation

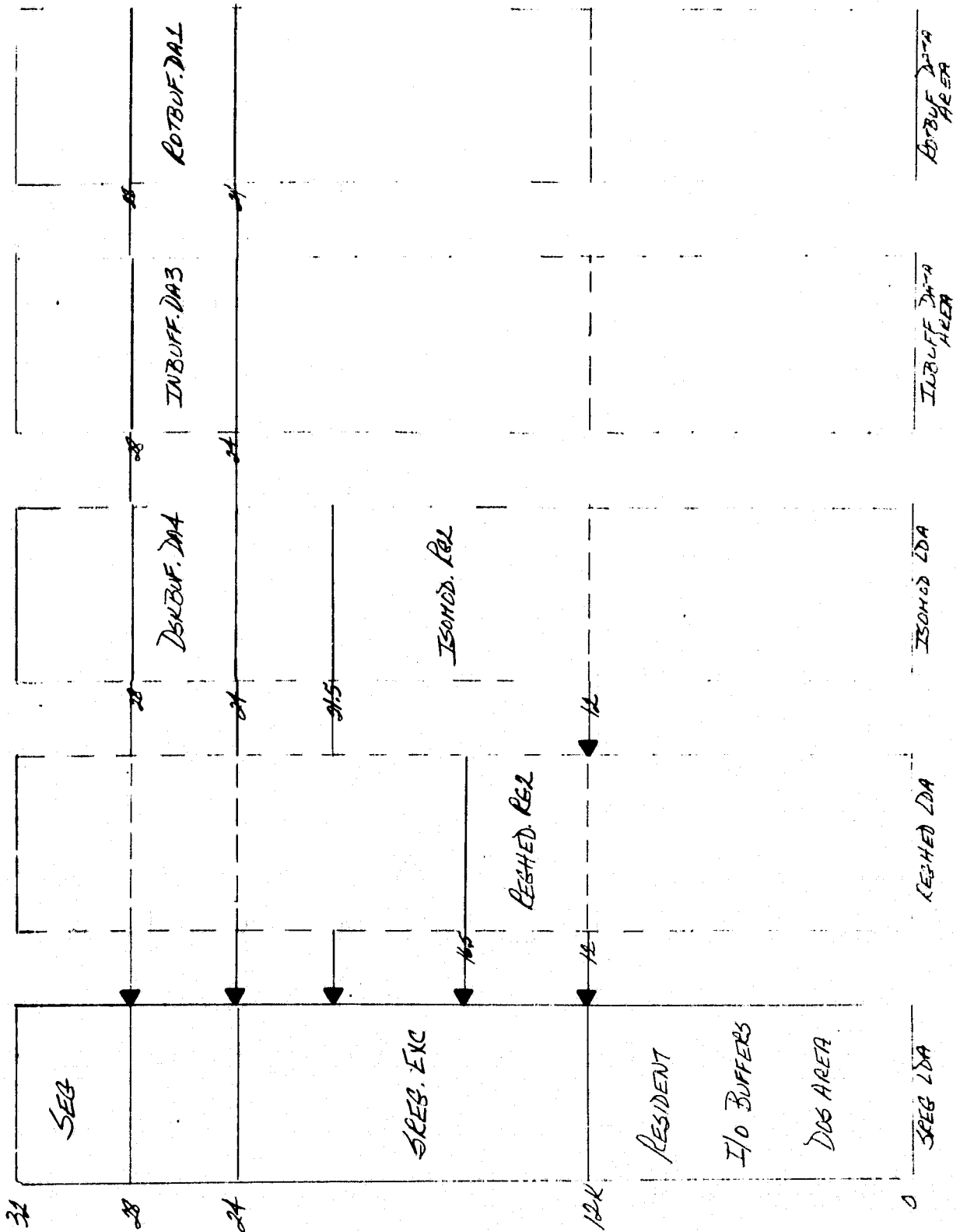


Figure 3-10 REG CPC 32K Virtual Core Allocation

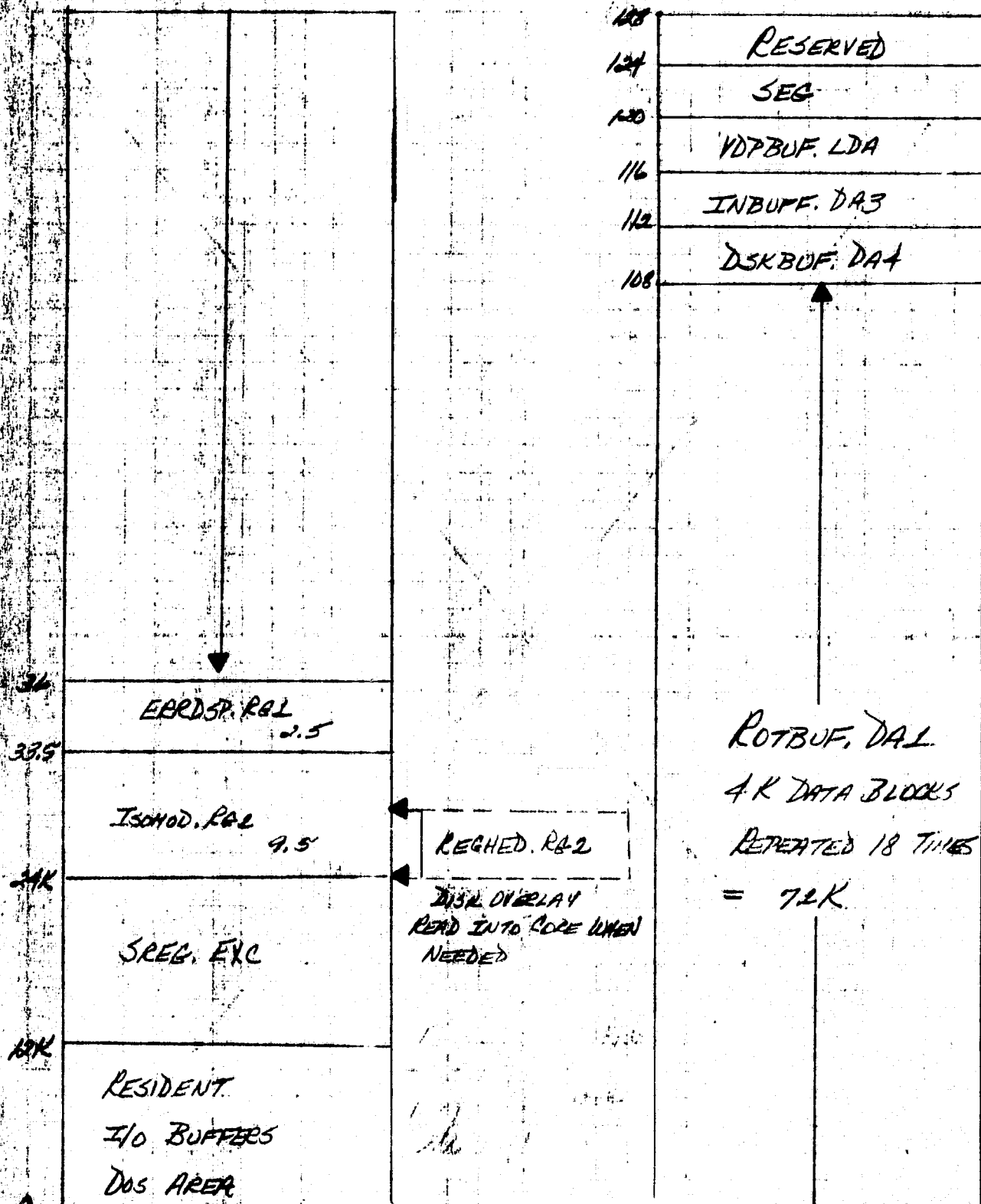


Figure 3-11 REG CPC Physical Core Allocation

This overlay system, with the swapping of load modules in and out of core, is a time-consuming process, so one should be very careful in selecting potential overlays. For the case in REG CPC, the load module selected as an overlay is called at the very first of the registration processing to build the output headers and is called only once during an entire SRE Program run.

If a data module is set up in a virtual core layout with a load module, it is mapped in with the load module via a SEG call at 140000 or 24-28K. The resident and DOS area at 0-12K (0-57777) is never altered or overlayed, nor is SEG at 28-32K or 160000-177777. The program load modules are always mapped in beginning at 60000 (12K to 24K).

Data modules can also be mapped in separately by a call to SEG, which results in the data module being mapped at 24-28K while no other areas of the 32K core map are altered

3.1.5 Data Base Characteristics. The data base of the SRE Program consists of data modules, a common data area and data contained in individual routines or load modules.

As discussed previously, data modules (4K blocks) are associated with load modules or they can be mapped in by themselves at 24-28K. This provides for a transfer of data from one load module to another in a CPC.

A common data area resides in the SEDS resident module, which can be accessed by all CPC's (MMC's) and load modules. That way, data flags can be referenced by all programs during a job, since the resident area (at 0-12K) is never overlayed or remapped.

The data residing in individual routines within CPC's will be discussed in paragraphs 3.2.1.4, 3.2.2.4, and 3.2.3.4, called "Data Organization." Also refer to these paragraphs for descriptions of the data modules of each CPC. Since the CPC's are broken down into various MMC's, each has a unique data base, so the description of the entire data bases will not be done in this section.

Below is a list of tables, items and data words in the resident common area associated with the SRE Program:

A. COMMON/GCOEFF/. This common is set up during the GCP phase by the SRE CPC to be used during registration by the REG CPC.

1. A₁, A₂, A₃, B₁, B₂, B₃, RA₁, RA₂, RA₃, RB₁, RB₂, RB₃. These are mapping and inverse mapping coefficients (two words allocated for each floating point data word).
2. I1SCAN. Start scan number (one 16-bit word).
3. ISCLST. Stop scan number (one 16-bit word).
4. IPXONE. Start PIXEL number (one 16-bit word).
5. IPXLST. Last PIXEL number (one 16-bit word).
6. ICNTSN. Center scan (one 16-bit word).
7. ICNTPX. Center PIXEL (one 16-bit word).
8. EBAR, SBAR. Input image average values (each two words in floating point).
9. XBAR, YBAR. Reference grid average values (each two words in floating point).
10. NUMGCP. Number of GCP's identified during screening pass.

B. COMMON/SEDCOM/. This common is used and set during all phases of the registration.

1. INIT. Termination flag (0 = initialization, 1 = continue processing, 2 = terminate this phase of SEDS processing, -1 = finished day IR registration -- proceed to day visible registration).

2. IPASS. Night/day/restart flag (0 = day registration, 1 = night registration, 2 = night restart after coarse rotation, 3 = day restart after IR registration).
 3. IRST. Restart flag.
 4. ISCRN. GCP screening option flag used by RGDISP (SRE CPC).
- C. COMMON/PRFLGS/. This contains three flag words of 16 bits each.
1. ISOTPE. Isothermal output tape selection (0 or 1).
 2. ISODSP. Isothermal color display selection (0 or 1).
 3. IRTAPE. IR registered tape selection (0 or 1).
- D. COMMON/CORNRS/. This common contains four 16-bit integer words -- ICA, ICB, ICC, and ICD, which are coordinates of the four corners of the reference grid.
- E. COMMON/TAPEID/. This common is set up in SRE CPC initialization from operator entries to the job setup display.
1. IDINT. Tape ID in EBCDIC for the night coarse rotated intermediate tape (five 16-bit words, e.g., CRT-XXXXXX)
 2. IDISO. Tape ID in EBCDIC for the isothermal output tape (five 16-bit words, e.g., OID-XXXXXX)
 3. IDREG. Tape ID in EBCDIC for the IR registered output tape (five 16-bit words, e.g., SMD-XXXXXX)
- F. COMMON/TPFRMT/. This common is set up by the REG and ROT CPC's (module REGHED) from the input tape header data. It contains seven words.
1. IRCSET. Records per data set.
 2. IRCSZE. Record size.

3. IANCSZ. Ancillary size.
 4. IFSPIX. Start PIXEL on tape.
 5. IENPIX. End PIXEL on tape.
 6. ICHSE. Total bytes per scan per channel.
 7. ICH1ST. Number of channels in first record of data set.
- G. COMMON/SCOMVT/. This common contains flag words set by the VT05 resident program on receiving operator VT05 command inputs.

The rest of this common contains data words set up from the input header information by U9TRD.

	.CSECT	SCOMVT
PROGID:	.BLKW 1	
DAY:	.BLKW 1	
MONTH:	.BLKW 2	
YEAR:	.BLKW 1	
INTFLG:	.BLKW 1	
GOFLAG:	.BLKW 1	
ADVFLG:	.BLKW 1	
BCKFLG:	.BLKW 1	
CONFLG:	.BLKW 1	
DSPFLG:	.BLKW 1	
ENDFLG:	.BLKW 1	
HDCFLG:	.BLKW 1	
KILFLG:	.BLKW 1	
RSTFLG:	.BLKW 1	
REWFLG:	.BLKW 1	
HLTFLG:	.BLKW 1	
ABTFLG:	.BLKW 1	
	.BLKW 82.	
; RESERVED STORAGE FOR CURRENT ANCILLARY BLOCK.		
ANMSSI:	.WORD 0	; BYTES 1&2 OF TIME FROM CURRENT ANCILLARY BLK
ANLSSI:	.WORD 0	; BYTES 3&4 OF TIME FROM CURRENT ANCILLARY BLK
SLNO:	.WORD 0	; CURRENT SCAN LINE NBR FROM ANCILLARY BLK

; RESERVED STORAGE FOR HEADER RECORD INFORMATION

CSID:	.BLKW	16.	; (1-32) COMPUTING SYSTEM ID
TLID:	.BLKW	10.	; (33-52) TAPE LIBRARY ID
SNID:	.WORD	0,0,0,0	; (53-60) SENSOR ID
TGDT:	.WORD	0,0,0	; (61-63) DATE OF THIS TAPE GENERATION
TSNO:	.WORD	0	; (64) TAPE SEQUENCE NO.
TIST:	.WORD	0,0,0,0,0,0,0	; (73-80) TIME OF FIRST SCAN ON TAPE
CACT:	.WORD	0,0,0,0	; (81-88) CHANNELS ACTIVE ON TAPE
PRFL:	.WORD	0	; (89) PROCESSING FLAG (1=PROC, 0=RAW)
NOCH:	.WORD	0	; (90) NBR CHANNELS ON TAPE
NOBP:	.WORD	0	; (91) NBR BITS/PIXEL
VADR:	.WORD	0	; (92-93) ADR OF START OF VIDEO DATA W/I CHANNEL
CADR:	.WORD	0	; (94-95) ADR OF START OF CAL DATA W/I CHANNEL
NOVE:	.WORD	0	; (96-97) NBR PIXELS/SCAN/CHANNEL
NOCE:	.WORD	0	; (98-99) NBR CAL ELEMENTS/SCAN/ CHANNEL
RSIZ:	.WORD	0	; (100-101) RECORD SIZE IN BYTES
OPRR:	.WORD	0	; (102) NBR CHANNELS/RECORDIN 2ND, AND SUB, REC,=0, IF PIXELS/ CHANNEL<3K
PRPC:	.WORD	0	; (103) NBR REC/SCAN/CHANNEL = 0 UNLESS NBR OF PIXELS/ CHANNEL<3K
RPRS:	.WORD	0	; (104) NBR RECORDS TO MAKE A COMPLETE DATA SET
ANCL:	.WORD	0	; (105-106) LENGTH OF ANCILLARY BLOCK IN BYTES
DORD:	.WORD	0	; (107) DATA ORDER INDICATOR (0= CHAN, 1=PIXEL)
FPNO:	.WORD	0	; (108-109) START PIXEL NBR
LPNO:	.WORD	0	; (110-111) STOP PIXEL NBR
SPRR:	.WORD	0	; (1778) NBR DATA SETS PER RECORD
CANL:	.WORD	0	; (1785-1786) NBR CHANNELS IN THE PHYSICAL RECORD
CURSLN:	.BLKW	26.	; FILL
	.WORD	0	; CURRENT SCAN LINE NBR
	.BLKW	12.	; FILL
RORBIT:	.BLKW	1	; ORBIT NBR
RDATE:	.BLKW	3	; DATE OF DATA

3.2 SRE CPC Characteristics. The following paragraphs contain detailed descriptions of the three CPC's outlined in paragraph 3.1. The instruction listing contained herein, by inclusion or reference, specifies the exact configuration of the SRE Program. Each CPC will be discussed individually in the following paragraphs as SRE (CPC No. 1), ROT (CPC No. 2), and REG (CPC No. 3).

3.2.1 SRE (CPD No. 1). The SRE CPC performs the initialization setup and GCP processing. It is the first CPC to receive program control after the SRE Program is called up via the operator. The SRE CPC consists of eight load modules; six of these are made up primarily of assembly language routines, while the other two are primarily in FORTRAN with some assembly language. See figure 3-6 for a graphic core layout of the SRE CPC and its load modules. Some of the major functional interfaces include interfacing with U9TRD (universal read routine) and DISPL to perform the screening of the input tape on the ICD during GCP identification. Other interfaces include VT05 displays and operator communication for job setup via the resident VT05 handlers and routines (VT05H, VTIN, VTOUT, SPCMD, and VTLINK). Disk and tape I/O is accomplished via NTRAN, a resident routine that performs requested DOS I/O.

3.2.1.1 Description. This paragraph discusses in detail the actual design flow and functions of the SRE CPC, including the role each of the eight load modules performs to carry out these functions. Topics discussed are, in order of discussion, load modules, program flow, the GCP display, and the GCP tabout.

3.2.1.1.1 Load Modules. The SRE CPC consists of eight load modules, each comprising a 32K virtual core map; they are mapped in by a call to SEG when required for a specific phase of GCP or initialization processing. They are listed below.

- RGDISP
- DAYRG1
- DAYRG2
- NITRG1

- NITRG2
- GCPID
- GCPEXC
- ERRDSP

A brief description of the load modules and subroutines follows.

- A. RGDISP. This is the main controller load module, which sets up the initial job and calls the other load modules as necessary. It is also responsible for providing a statistical data tabulation of the GCP phase and retrieval and/or storage of the mapping coefficients on disk. RGDISP controls the program flow for all of the initialization setup phase of SRE. Its routines and subroutines are as follows.
1. INTDSP. Outputs initial registration display (assembly).
 2. GCPCHK. Provides display via COFDSP of coefficients computed during GCP phase and a means of changing them at the end of the GCP phase (assembly).
 3. COEFCK. On GCP phase bypass, responsible for obtaining the coefficients from disk and/or cards.
 4. COFDSP. An assembly routine that outputs a display of the mapping coefficients taken from disk storage or those just calculated in the GCP phase; enables the operator to modify the entries via the VT05.
 5. STCHEK. Performs status checks (assembly).
 6. CNVREL. Converts the coefficients on the display (COFDSP) from ASCII to real values and moves them to the GCOEFF common.

7. CNVASC. Converts coefficients as in the GCOEFF common from floating point to ASCII for purposes of displaying (FORTRAN).
 8. DSKIN, DSKOUT. Responsible for disk I/O involved in retrieving and storing coefficients on disk (FORTRAN).
 9. CRDTAB. Coefficient card input processor (FORTRAN).
 10. GCPSTT and TABGCP. These routines tabulate GCP statistics at the completion of the SRE CPC run (FORTRAN).
- B. DAYRG1. Called in by RGDISP for a normal day registration run. It outputs a processing display to the VT05, to which the operator keys in processing actions and output product selection. It sets up common flag words from information input via operator. Its routines and subroutines are as follows.
1. DAYRG1. Main routine (assembly).
 2. DATIT. Retrieves current date for display (assembly).
 3. TAPES. Reads header data from EU input tape (assembly).
 4. CHEK. Performs EBCDIC-to-ASCII conversion.
 5. TPTIM. Strips date of data from header for STTIME common (assembly).
 6. VTUNK. VT05 routine used to output display to VT05 (assembly).
- C. DAYRG2. This module is the same as DAYRG1 except that it is for a day restart run.
- D. NITRG1. This module is the same as DAYRG1 except that it is for a night run.

- E. NITRG2. This module is the same as DAYRG1 except that it is for a night restart after coarse rotation run.
- F. GCPID. This module is called by RGDISP when the GCP screening phase is selected, and is the main controller of the GCP identification process. It screens input data and provides operator control for screening selections and identifying points in the image. Its routine and subroutines are as follows.
1. GCPID. Main routine (assembly).
 2. PRCID. Routine to process each ID selected; calls GCPEXC for computations, and is responsible for GCP display (assembly).
 3. DISPL. Routine which interfaces with ICD handler to display input image.
 4. U9TRD. Universal 9-track tape read/write routine; reads input tape (assembly).
 5. NNCODE. Converts display outputs from floating point to ASCII prior to be output to GCP display (FORTRAN).
 6. CNVTES. Computes a corresponding E&S in the input image from the GCP display coordinates XPOS and YPOS returned in the ICD monitor packet (FORTRAN).
 7. VTLINK. VT05 routine that sets up a VT05 requested display.
- G. GCPEXC. This module is called by the GCPID load module for each GCP identified or deleted. It is responsible for calculating the fit of the GCP's to the reference grid points, calculating the mapping and inverse transformation coefficients, and calculating delta errors reflecting the difference between where the point was located via the operator and where the point was computed to be. Its routines and subroutines are as follows.
1. GCPEXC. Main routine (FORTRAN).

2. GRDINT. Initializes the reference grid preassigned GCP coordinates (FORTRAN).
 3. PMMGCP. Uses ephemeris data to calculate longitude and latitude of a point, the coordinates of which are E = 1762, S = center scan; finds the corresponding reference grid coordinates (FORTRAN).
 4. ROTE. Rotates a point (X,Y) clockwise through 25.8 degrees (FORTRAN)
 5. ROTATE. Calculates the coarse rotation of night pass operator-identified GCP's; GCP represented in the day pass coordinate field (FORTRAN).
 6. INVROT. Computes the inverse of the projected rotated points (pre-image points) in a night pass to get them back in the night coordinate field prior to calculating the delta errors (FORTRAN).
 7. GCPNTS. Computes the pre-image points from reference grid coordinates. Using inverse mapping coefficients, it obtains the calculated GCP coordinates in the input image. For night passes, it reflects the pre-image in the rotated image (FORTRAN).
 8. PHMPTS. Computes the ephemeris generated GCP's from the reference grid coordinates (FORTRAN).
 9. SUMSQR, R1SUM, R2SUM, ISUMDX, and RSUMDX. These sub-routines or functions compute the sums of squares, sums, sums of two arrays, etc.
- H. ERRDSP. This service load module is used to output advisory or error messages to the VT05 and line printer. See paragraph 2.2.5 for a description of ERRDSP.

3.2.1.1.2 Program Flow. See figure 3-12 for the general SRE CPG flow. The registration programs are called in for execution by the operator keying in the mnemonic SRE on the VT05 SEDS initialization displays. The SEDS resident routine then maps the SRE

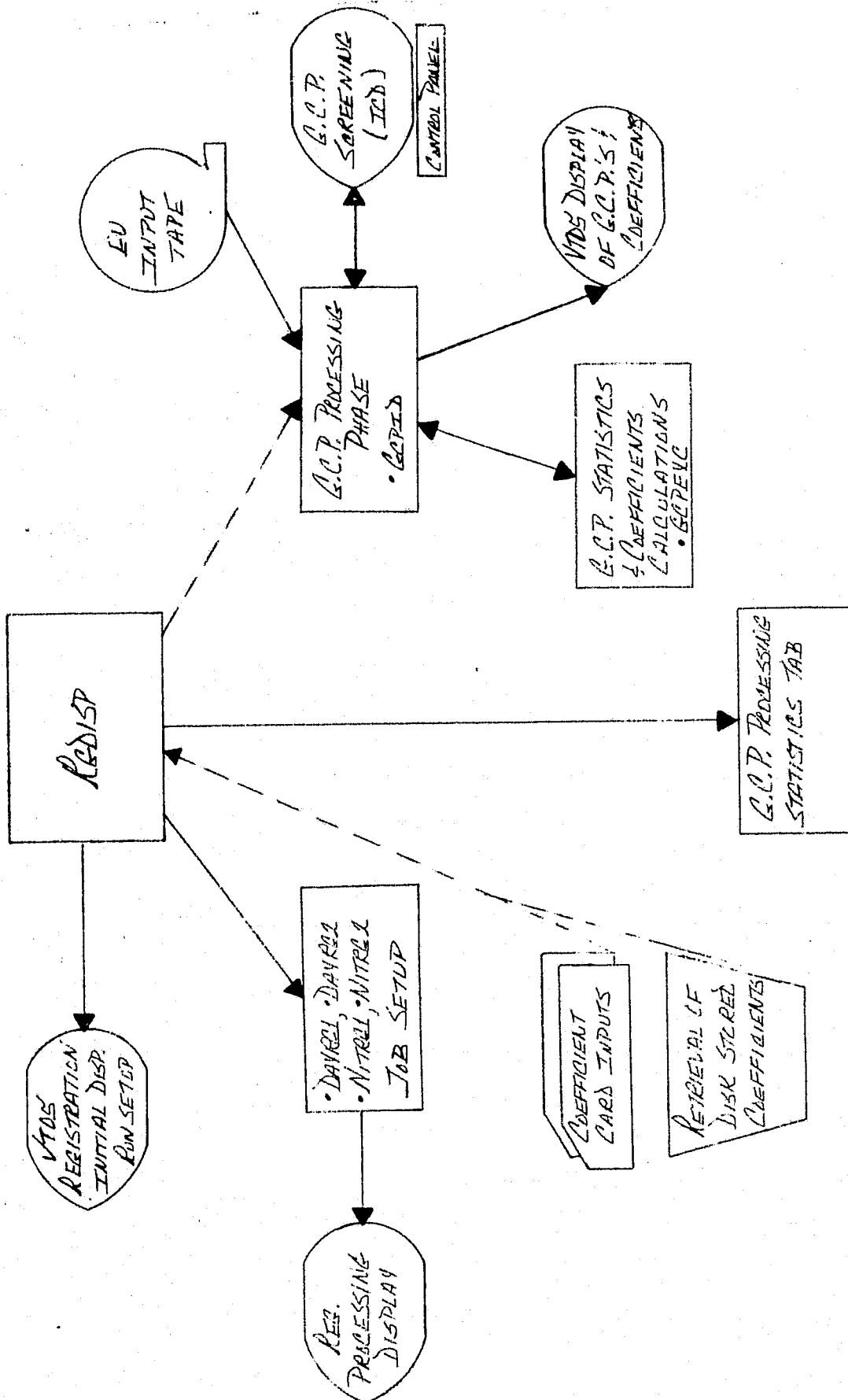


Figure 3-12 SRE CPC General Flow

MMC into physical core and gives program control to the RGDISP load module. RGDISP calls the subroutine INTDSP to output the registration initialization display (see figure 3-13) to the VT05 on which the operator selects the type of run, (day, night, day restart, night restart). Depending on the run selection keyed in, RGDISP maps in, via SEG, the appropriate load module (DAYRG1, DAYRG2, NITRG1, or NITRG2). Each of the four load modules has a specific processing display which is output to the VT05 (see figures 3-14 through 3-17 for the display formats). The purpose of this display is to enable the operator to set the run up as desired, and select output products and options available for each run. Depending on the options selected, the load module sets flag words in the resident data common to be used later by the REG CPC. The operator also keys in output tape ID's which are to be put in the tape header for identification. After all entries are made, RGDISP is called back in for control. A check is made to determine if the GCP screening option was selected. As stated previously, the GCP phase can be bypassed as long as the mapping coefficients can be entered into the system. There are two approaches available -- the operator can input the coefficients via cards, or the coefficients for the last previously run day and night registration passes, which are saved on disk for purposes of retrieval on a restart, can be used.

RGDISP calls the routine COEFCK to determine which input method is to be used. If card inputs are to be used, COEFCK calls a FORTRAN subroutine, CRDTAB, to read the cards, set up the GCOEFF common with the input data, and provide a tabout of the coefficients as read in. CRDTAB also computes the inverse transformation coefficients from the input data, and places them in GCOEFF, and in the tabout. See figures 3-18 and 3-19 for the input card formats and line printer tabout. If the coefficients on disk are to be used, COEFCK calls DSKIN to read the data from disk and COFDSP to output the coefficients on the VT05 display. Figure 3-20 is a sample coefficient VT05 display. The operator can manually change any of the displayed coefficients via the VT05. The coefficient data, as displayed, is set up in the GCOEFF common and then written back to the REGCOF disk file, via DSKOUT; a tabout of the coefficients is also supplied (see figure 3-21). After the mapping coefficients are input to the system by either of the above methods, RGDISP exits to the SEDS resident routine.

PROGRAM: SREG-REGISTRATION PROCESSING

1 - DAY REGISTRATION PROCESSING

2 - DAY REGISTRATION-RESTART AFTER IR REGISTRATION

3 - NIGHT REGISTRATION PROCESSING

4 - NIGHT REGISTRATION-RESTART AFTER COARSE ROTATION

PROCESSING OPTION: 0 *

SELECT DESIRED OPTION BY KEYING IN NUMBER CODE ABOVE

Figure 3-13 Registration Initialization Display

PROGRAM: SREG-DAY REGISTRATION PROCESSING

DATE: 25:JUN:75

INPUT TAPE SENSOR ID: NOAA 3 1

TAPE:

I.D.:

LOGICAL UNITS

EU DAY INPUT TAPE

SED=00021

1

REG. IR OUTPUT TAPE(OPT)

SMD=

*

2

ISOTHERMAL OUTPUT TAPE(OPT)

OID=

*

0

TO DISABLE OPTIONS TYPE 'X' OVER CORRESPONDING LETTER CODE

OPTIONS REQUEST: TCDRS *

T=ISOTHERMAL TAPE

C=ISOTHERMAL COMPRESSION

D=ISOTHERMAL DISPLAY

R=REGISTERED IR TAPE

S=C.C.P. SCREENING (DISABLED-READY CARD INPUTS)

Figure 3-14 DAYRG1 Processing Display

PROGRAM: SREG-DAY REG, RESTART AFTER IR REGISTRATION
DATE: 20 MAY 1975 INPUT TAPE SENSOR ID: NOAA 3 1

TAPE: I.D.: LOGICAL UNITS
EU DAY INPUT TAPE SED-00021 1

★★READY COEFFICIENT CARD INPUTS

Figure 3-15 DAYRG2 Processing Display

PROGRAM: SREG-NIGHT REGISTRATION PROCESSING

DATE: 03:JUN:75

INPUT TAPE SENSOR ID: NOAA4- 2

TAPE:	I.D.:	LOGICAL UNITS
EU NIGHT INPUT TAPE	SEN=NITRDN	1
INT. COARSE ROTATED TAPE	CRT= *	3
REG. IR OUTPUT TAPE(OPT)	SMN= *	2
ISOTHERMAL OUTPUT TAPE(OPT)	QIN= *	0

TO DISABLE OPTIONS TYPE 'X' OVER CORRESPONDING LETTER CODE

OPTIONS REQUEST: TCDRS *

T=ISOTHERMAL TAPE

C=ISOTHERMAL COMPRESSION

D=ISOTHERMAL DISPLAY

R=REGISTERED IR TAPE

S=G.C.P. SCREENING (DISABLED-READY CARD INPUTS)

Figure 5-16 NITRG1 Processing Display

PROGRAM: SREG-NIGHT REG., RESTART AFTER COARSE ROTATION
DATE: 031JUN:75 INPUT TAPE SENSOR ID: NOAA4- 2

TAPE:	I.D.:	LOGICAL UNITS
COARSE ROTATED INPUT TAPE	CRT-NITRUN	3
REG. IR OUTPUT TAPE(OPT)	SMN- *	2
ISOTHERMAL OUTPUT TAPE(OPT)	OIN- *	0

TO DISABLE OPTIONS TYPE 'X' OVER CORRESPONDING LETTER CODE

OPTIONS REQUEST: TCDR *

T=ISOTHERMAL TAPE

C=ISOTHERMAL COMPRESSION

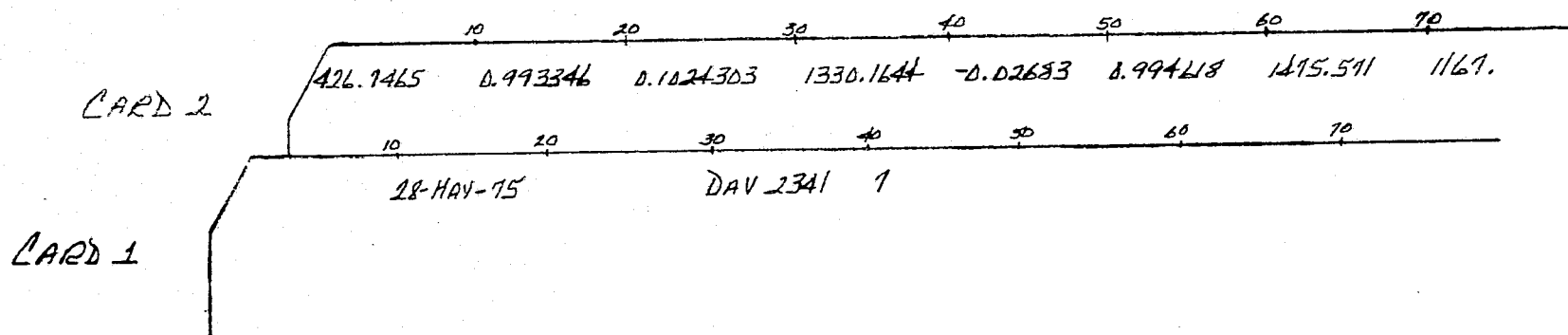
D=ISOTHERMAL DISPLAY

P=REGISTERED IN TAPE

**READY COEFFICIENT CARD INPUTS

JSC-10019
Part II

Figure 3-17 NITRG2 Processing Display



CARD 1 - COLUMN
10-19
30-39
40-41

CURRENT DATE
FREE FIELD (-JOB IDENT)
NO. OF G.C.P.'S

CARD 2 - COLUMN
1-10
11-20
21-30
31-40
41-50
51-60

A1 COEFFICIENT
A2 "
A3 "
B1 "
B2 "
B3 "

COLUMN
61-70
71-80
EBAR
SBAR

Figure 3-18 Coefficient Card Input Format

*****MAPPING COEFFICIENTS--CARD INPUTS*****

DATE: 28-MAY-75

TIME: 00:01:22

DAY 2341

NO. OF GROUND CONTROL POINTS IDENTIFIED= 7

COEFFICIENTS:

A1= 426.74648 A2= 0.99334598 A3= 0.102430001

B1= 1330.16394 B2= 0.026830001 B3= 0.99461800

EBAR= 1475.57104 SBAR= 1167.00000

Figure 3-19 Coefficient Line Printer Tabout

-REGISTRATION COEFFICIENTS-

NO. OF GCP'S=12

A3= 0.166968808★

B3= 0,98981738*

SHAR= 1474.41665*

Figure 2-20 Sample Coefficient VT05 Display

*****REGISTRATION COEFFICIENTS*****

*AS READ IN FROM DISK FILE /R UPDATED VIA THE VT05 AFTER G,L,P, PHASE

ORBIT NO.: 3318

DAY PASS

NO. OF GROUND CONTROL POINTS IDENTIFIED= 12

MAPPING COEFFICIENTS:

A1= -37.38383 A2= 0.98413241 A3= 0.166968808 RA1= 271.58185 RA2= 1.00017095 RA3=-0.168715328

B1= 1388.08752 B2=-0.093052104 B3= 0.98981738 RB1= -1376.83600 RB2= 0.094025441 RB3= 0.99442655

EBAR= 1997.50000 SBAR= 1474.41663 XBAR= -37.38383 YBAR= 1388.08752

Figure 3-21 Tabout of Disk-Stored Coefficients

If the GCP screening option is selected, RGDISP maps in the GCPID load module via a SEG call. GCPID first outputs the initial GCP display to the VT05 (figure 3-22) on which the operator selects the first portion of the input image to screen by entering START SCAN, START PIXEL. GCPID interfaces with U9TRD to read the designated data off the EU input tape and with DISPL to interface with the ICD display handler, IDEH, to output each scan to the interactive color display screen. See paragraph 4.2.3 for a description of U9TRD and paragraph 5.2.3 for an explanation of interfacing with DISPL. Call packets must be set up and passed with the calls to U9TRD and DISPL, describing the particular function to perform; these call packets and formats are shown in figures 3-23 and 3-24, respectively.

There is a control panel on the ICD which enables the operator to control the screening via software, to color-enhance the data, and to magnify the displayed image to facilitate locating key points. The control panel contains a thumbwheel switch and an INTERRUPT button. The thumbwheel switch is a two-digit dial which can be set 00 to 99. When the INTERRUPT button is depressed, IDEH sets up a common data packet containing the thumbwheel dial entry, the X and Y positions of the screen cursor, and a flag set to indicate that an operator interrupt has occurred. GCPID constantly monitors the packet for interrupts. Following are the dial controls as set up.

- A. 00. Signifies a request from the operator to halt screening temporarily to identify GCP's in the displayed image.
- B. 01-98. Valid ID entries for GCP's.
- C. 99. Signifies a request from the operator to continue with screening of the data where it was last halted.

To identify a point, the operator first halts the screening process. He positions the screen cursor directly under the GCP to be identified, sets the thumbwheel dial to the correct ID for that point, and depresses the INTERRUPT button. The common packet is set up as described above. Upon acknowledging that a GCP has been identified, GCPID calls subroutine PRCID. PRCID handles all

GROUND CONTROL POINT COMPUTATIONS													
***SCREENING REQUEST:				STSCN: 0000		SPSCN: 0000		STPIX: 0000					
TIMEOUTS: 0				TAPE START PIXEL: 1696		SCAN NO.: 0000							
N=				A1=		B1=							
SIGMA E=				A2=		B2=							
SIGMA S=				A3=		B3=							
ID			DELT E		DELT S		ID			DELT E		DELT S	
DELETE ID:				CLOSE ID ENTRY WITH A 11									

Figure 3-22 Initial GCP VT05 Display

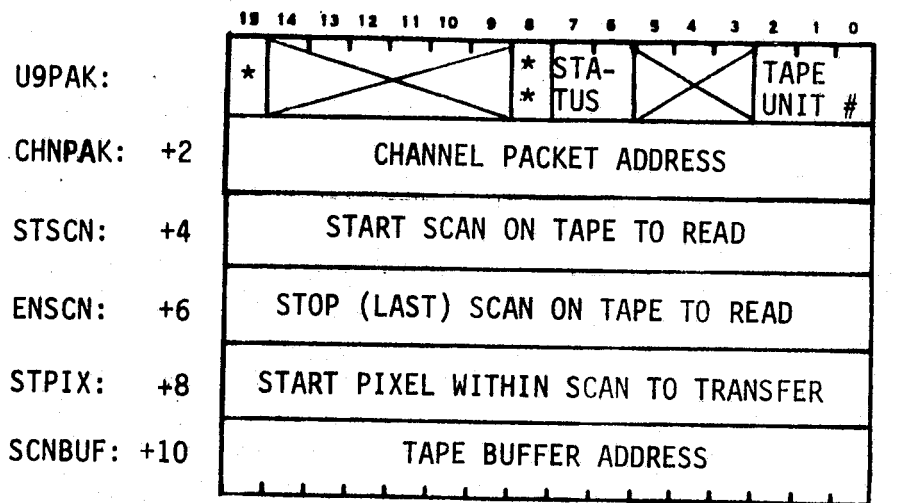
CALL TO U9TRD:

```

JSR    R5,@#U9TRD
BR     A
.WORD  U9PAK
.WORD  ADRTN
.WORD  U9STAT

```

A:



*BIT SET INDICATES NO BYTE REORDERING
 **BIT SET INDICATES TO WRITE HEADER RECORD

STATUS (BITS 6-7):

6 - SET IF WRITE IS COMPLETE
 7 - SET IF TAPE ERROR

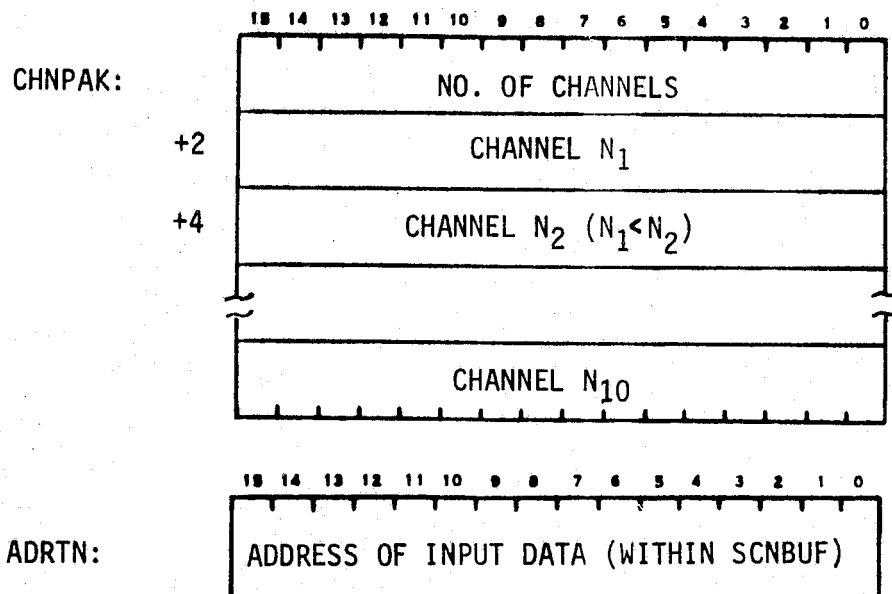
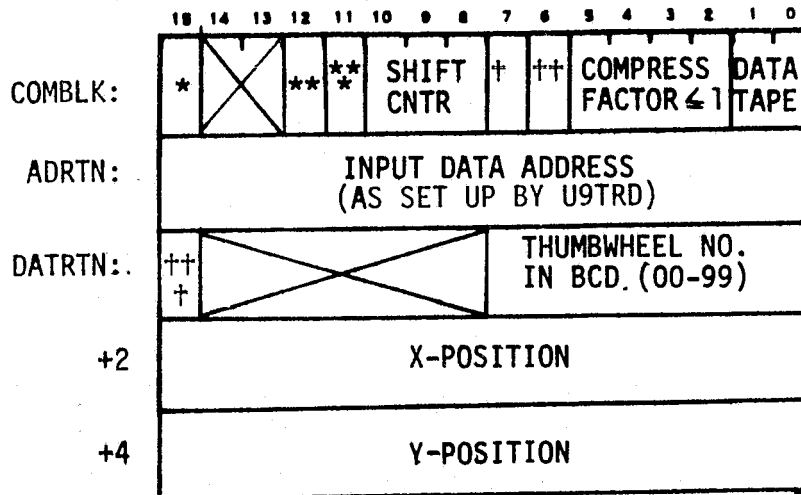


Figure 3-23 U9TRD Calling Sequence
and Packet Format

CALL TO DISPL:

```
JSR    R5,@#DISPL
BR     A
.WORD  COMBLK    ; INPUT COMMAND
.WORD  ADRIN     ; DATA ADDRESS
.WORD  DATRTN    ; MANUAL INTERRUPT PK.
```

A:



*SET IF DISPLAY TIMEOUT
 **SET IF BYPASS INTERRUPT COMPLETE
 ***SET IF PRODUCT IMAGE
 +SET IF FIRST TIME THRU
 ++SET IF RESTART
 +++SET IF INTERRUPT

DATA TYPE (BITS 0-1):

00 = DAY
 01 = NIGHT
 10 = ANNOTATION

REPRODUCIBILITY OF THE
ORIGINAL PAGE IS POOR

Figure 3-24 DISPL Calling Sequence
and Packet Format

identified GCP's and any "delete" requests for the previously entered points. PRCID calls a FORTRAN subroutine, CNVTES, to compute the corresponding E,S in the input image from the XPOS, YPOS coordinates in the displayed image portion. CNVTES moves the computed E,S into the EP and SP arrays of the GCPTAB common residing in the GCPBUF data module. GCPBUF is a data module mapped in via SEG to transfer and receive GCP data between load modules during the GCP phase. PRCID then maps in the GCPEXC load module via SEG.

GCPEXC is called for each GCP identified, to perform the functions of fitting the operator-identified GCP to the corresponding point (X,Y) in the reference grid. Mapping coefficients are computed using a relationship of the identified GCP coordinates to the reference grid coordinates for all identified points. In the case of night data, the coordinates are rotated to put them in the day pass coordinate system prior to determining the coefficients. GCPEXC also computes delta errors for each GCP and combined errors for E and S. All mentioned data is stored in the GCPTAB and GCOEFF commons for use by PRCID in updating the GCP display, and later by the REG CPC. The exact flow and computations performed by GCPEXC will be discussed in more detail later in this paragraph.

GCPEXC returns control to PRCID via a return SEG call. PRCID takes the data from GCPTAB and sets it up to be output to the GCP VT05 display. PRCID calls a FORTRAN subroutine, NNCODE, to do necessary conversions of data for display purposes. The display is refreshed with the new data from GCPEXC (see figure 3-25). The operator can tell from the data displayed how accurate the fit was, and whether he identified a point significantly off-course, and he can get an idea of when enough points have been identified to get a good registration of the image.

3.2.1.1.3 GCP Display. Sigma E and Sigma S represent the average error deltas of E and S of those GCP's identified. They will increase drastically when a point has been incorrectly located. There are six mapping coefficients displayed -- A_1 , A_2 , A_3 , B_1 , B_2 , and B_3 . Of the six, the most significant one to watch is B_2 . Enough GCP's should be located to make B_2 fairly constant, and in particular, enough GCP's should be located so that B_2 does not change sign when a new GCP is entered. As more GCP's are entered,

GROUND CONTROL POINT COMPUTATIONS

***SCREENING REQUEST: ① STSCN: 0500 ② SPSCN: 0000 ③ STPIX:1600
④ TIMEOUTS:0003 ⑤ TAPE START PIXEL: 0990 ⑥ SCAN NO.: 1243

⑦ N=07
⑧ SIGMA E= 1.52
SIGMA S= 0.53
AT= 426.75 BT= 1330.16
A2= 0.9926 B2= -0.0295
A3= 0.1005 B3= 0.9970 ⑨

ID	DELT E	DELT S	ID	DELT E	DELT S	ID	DELT E	DELT S
⑩ 043	-00002	+00000	046	+00002	+00000	051	+00000	+00000
038	+00000	+00000	049	+00000	+00000	048	+00000	+00000
050	+00000	+00000						

DELETE ID:

CLOSE ID ENTRY WITH A 'I'

Figure 3-25 Refreshed GPC VT05 Display

each of the coefficients A_2 , A_3 , B_2 , and B_3 should tend to stabilize -- A_2 and B_3 to numbers near 1, and A_3 and B_2 to numbers near 0. A_1 and B_1 are parts of the translation, and cannot be expected to stabilize.

A_2 is a scale factor in the PIXEL direction, and should be expected to be close to 1. Numbers below 1 represent a compression in the PIXEL direction; numbers larger than 1 represent a stretch. For example, $A_2 = 0.95$ is about a 5 percent compression of each scan line in the registered image. $A_2 = 1.05$ is about a 5 percent stretch of each scan line in the registered image.

A_3 is a vertical skew. If it is positive, the registered image is skewed to the right (clockwise), and if it is negative, the registered image is skewed to the left (counter-clockwise).

B_2 is a rotation from the horizontal. This is the buffer-critical value. A value of ± 0.017 is a reasonable maximum. If B_2 is positive, horizontal lines in the registered image are rotated counter-clockwise; if it is negative, they are rotated clockwise.

B_3 is a scale factor in the downtrack direction, which should be expected to be close to 1. As in the case of A_2 , it is unreasonable to have B_3 outside the limits 0.95 to 1.05. Numbers below 1 represent a compression in the downtrack direction; numbers larger than 1 represent a stretch. For example, $B_3 = 0.95$ will result in about 5 percent of the scan lines being deleted in the registered image. $B_3 = 1.05$ will result in about 5 percent of the scan lines being repeated in the registered image. $B_3 = 0.5$ will result in a registered image about half as long as the unregistered image.

The way the program is currently working, if a 0 or 1 ground control point is used, A_1 and B_1 are the only calculated values. A_2 is automatically set to 1, A_3 to 0, B_2 to 0, and B_3 to 1, so that the user gets no rotation, skew, or scale change.

If two ground control points are used, A_3 and B_2 are both set to 0 so that the user gets no rotation and skew. However, a scale change in both the PIXEL and scan directions is calculated.

The same situation holds for three ground control points. If three ground control points are used, all of the coefficients are calculated, but if the ground control points are close together, the calculated coefficients cannot be expected to be accurate.

The Delta E and Delta S are displayed as an aid to detecting when a ground control point has been identified incorrectly. If three or fewer ground control points are entered, the Delta E and Delta S are comparisons of the entered locations with ephemeris data. For four or more ground control points, it is a comparison of the entered location with the calculated locations based on the calculated coefficients. Thus, in no case do the Delta E and Delta S represent an absolute error or deviation from a known location.

When an adequate number of GCP's have been identified, the GCP phase is terminated by the operator. GCPID returns control to the RGDISP load module. RGDISP calls subroutine GCPCHK to see if the operator wishes to view the coefficients calculated and change any to their offline predicted values for this particular orbit pass. If so the coefficients are displayed via COFDSP and the operator is free to make changes via the VT05. The coefficients are then moved back into GCOEFF common for use by the REGCPC, and then written onto the REGCOF disk file. RGDISP then calls two FORTRAN subroutines, GCPSTT and TABGCP, to tabulate on the line printer all statistical data accumulated by GCPEXC load module in the GCPTAB common data module. RGDISP then exits to the SEDS resident routine to proceed to the next phase of registration.

3.2.1.1.4 GCP Tabout Description. Figure 3-26 shows an example of the GCP tabout, which is described below.

The first page of the printout (figure 3-26, 1 of 2) contains the coordinates of the four corners and center of the input image, reflected as (E,S), and the four corners and center of the reference grid, reflected as (X,Y), as defined by the fit performed on the input image. The corresponding latitude and longitudes are also given for each (E,S) point.

*****INPUT IMAGE COORDINATES*****

DATE: 28-MAY-79
TIME: 00:30:24
CREDIT NO: 2341
START TIME (DAY-MON-YR HRS:MIN:SEC) 105-21-75 10:00:10

PAGE: / 1

DAY PASS			
E=	990	S=	2200
X=	49	Y=	2374
LAT=	0.350511E 02		
LON=	-0.1105305E 03		

E=	3490	S=	2200
X=	2530	Y=	2300
LAT=	0.3047401E 02		
LON=	-0.8803567E 02		

E=	2240	S=	1100
X=	1179	Y=	1241
LAT=	0.2522038E 02		
LON=	-0.1023314E 01		

E=	990	S=	1
X=	-171	Y=	142
LAT=	0.1876491E 02		
LON=	-0.1153735E 03		

E=	3490	S=	1
X=	2310	Y=	108
LAT=	0.1423419E 02		
LON=	-0.9541114E 02		

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Figure 3-26 GCP Tabout and Description (1 of 2)

*****GROUND CONTROL POINT LOCATION TABULATIONS***** PAGE: 1

DATE: 28 MAY 75
 TIME: 00130126
 ORBIT NO: 2301 DAY PASS
 START TAPE TIME (DAY-MON-YR WRSIMINISC) 105-21-75 16:06:30

MAPPING COEFFICIENTS:

A1 = 426.74658	A2 = 0.99262625	A3 = 0.100452118	RA1 = -294.01791	RA2 = 1.00442243	RA3 = -0.101202480
B1 = 1330.14443	B2 = -0.029484788	B3 = 0.99697518	RB1 = -1342.89539	RB2 = 0.029705035	RB3 = 1.00004101

ARCTAN A3 = 5.736240 ARCTAN R2 = -1.688865 DVALUE = 0.18878467E 12 OFFSET = 767.80

DEVIATION = 421.67 FBAR = 1475.14285 SBAR = 1167.14282 XBAR = 426.74658 YBAR = 1330.14443

NO. OF GROUND CONTROL POINTS IDENTIFIED: 7

ID	E	S	F ERROR	S ERROR	COMBINED ERROR
	INPUT IMAGE				
43	1003.0	1300.0	-2.2563	-0.5829	2.3299
46	1037.0	1293.0	-2.6545	0.2948	2.6711
51	1453.0	970.0	-0.6754	-0.3707	0.7704
38	1326.0	874.0	0.1790	0.6135	0.6390
49	1802.0	1296.0	-0.8582	-0.2543	0.8956
48	1771.0	1367.0	0.2976	0.7013	0.7618
50	1934.0	1078.0	0.6583	-0.4028	0.7718

SIGMA F = 1.5212 SIGMA S = 0.5258 SIGMA COMBINED = 1.6095

Figure 3-26 (2 of 2)

The second page of the printout (figure 3-26, 2 of 2) contains the following:

A. Mapping Coefficients (Forward and Inverse Transformation)

1. A_1 is a part of the translation of the image. This value is not expected to stabilize.
2. A_2 is a scale factor in the PIXEL (E) direction, which should be close to 1 (0.95 - 1.05); < 1 represents a compression in the PIXEL direction, and > 1 represents a stretch in the PIXEL direction.
3. A_3 is the vertical skew factor. If it is positive (+), the registered image is skewed to the right; if it is negative (-), the registered image is skewed to the left. The value should stabilize to near 0.
4. B_1 is a part of the translation of the image.
5. B_2 is the rotation from the horizontal. A value of ± 0.017 is a reasonable maximum. If B_2 is positive (+), horizontal lines in the registered image are rotated counter-clockwise; if it is negative (-), they are rotated clockwise.
6. B_3 is the scale factor in the downtrack direction. This value should be close to 1 (0.95 - 1.05); < 1 represents a compression in the downtrack direction, and > 1 represents a stretch in the downtrack direction. For example, $B_3 = 0.95$ will result in about 5 percent of the scan lines being deleted in the registered image. $B_3 = 0.05$ will result in about 5 percent of the scan lines being repeated in the registered image.
7. $RA_1, RA_2 \dots RB_2, RB_3$ are the corresponding mapping coefficients for the inverse transformation.

- B. Arctan A₃. This is approximately the angle, measured in degrees, of vertical skew. A positive angle will result in a registered image skewed clockwise; a negative angle will result in a registered image skewed counter-clockwise.
- C. Arctan B₂. This is approximately the angle, measured in degrees, of horizontal rotation. A positive angle will result in a registered image rotated counter-clockwise; a negative angle will result in a registered image rotated clockwise.
- D. DVALUE. This is a measure of linear independence of the GCP's. If they are all in a line, DVALUE is smaller than if they are dispersed.
- E. OFFSET. This is a measure of the distance of the average of the ground control points (EBAR, SBAR) from the center of the input image.
- F. DEVIATION. This is a measure of the spread of the ground control points.
- G. EBAR. This is the average PIXEL element (E) in the input image of the GCP's identified. This will be mapped, during the registering of the data, onto the corresponding point XBAR, which is the average PIXEL of the points selected as defined in the reference grid.
- H. SBAR. This is the average scan line (S) in the input image of the input GCP's identified. This will be mapped, during the registering of the data onto the corresponding point YBAR, which is the average scan of the points selected as defined in the reference grid.
- I. XBAR. This is the value obtained by taking the average of the X coordinates in the reference grid corresponding to the GCP's identified from the input image.
- J. YBAR. This is the value obtained by taking the average of the Y coordinates in the reference grid corresponding to the GCP's identified from the input image.

- K. GCP's. The remainder of the printout's second page reflects the GCP's identified, giving the (E,S) coordinate of the point as selected from the input image, the E and S errors of each point identified, and a combined error. Sigma E Sigma S are the averages of the E errors and S errors, respectively, of the GCP's identified. Sigma combined is the average of the sum of the E and S errors.

3.2.1.1.5 GCPEXC Functions. The following narrative is a technical description of the functions of the GCPEXC load module in computing mapping coefficients and the image fit of each GCP identified.

GCPEXC is responsible for computing mapping coefficients $A_1, A_2, A_3, B_1, B_2,$ and B_3 for use in mapping the operator-identified points (EP, SP) onto the corresponding (X,Y) coordinates in the reference grid. Also computed are the inverse transformation coefficients $RA_1, RA_2, RA_3, RB_1, RB_2,$ and RB_3 for use in mapping the (X,Y) coordinates in the reference grid onto the (EP, SP) of the GCP's identified. GCPEXC calculates a computed PIXEL and scan value (E,S) for each GCP. Pre-image (or inverse) points (E1, S1) are found by using the inverse coefficients on the (X,Y) reference grid coordinates. By comparing the pre-image points with the computed points, a delta error is obtained for each identified point in the input image. All of this information is used in the GCP display.

GCPEXC first checks to see if it is working with night data. If so the operator-identified point in the input image (EP, SP) is coarse rotated clockwise 25.8 degrees to put it in the day pass coordinate system, for purposes of the computations to be performed. This is accomplished by a call to a FORTRAN subroutine, ROTATE, which performs the calculations below.

Assuming this is night pass data, let E_c denote the center picture element in the input image and S_c denote the center scan line. Let (EP, SP) denote a GCP identified in the input image. Let:

$$E''_i = EP - E_c$$

$$S''_i = SP - S_c$$

Then reset:

$$EP = (E_c / \cos 25.8^\circ) + \text{int} (E''_i \cos 25.8^\circ - S''_i \sin 25.8^\circ + 0.5)$$

$$SP = S_c \cdot \cos 25.8^\circ + \text{int} (E''_i \sin 25.8^\circ + S''_i \cos 25.8^\circ + 0.5)$$

Now (EP,SP) will be treated the same as a day pass ground control point.

GCPEXC then calculates an average \bar{E}, \bar{S} for the GCP's located for night or day pass and an "estimated" E,S for each GCP in the input image. Let:

$$\bar{E} = \frac{1}{N} \sum E_{Pi}$$

$$\bar{S} = \frac{1}{N} \sum S_{Pi}$$

Then let:

$$E_i = E_{Pi} - \bar{E}$$

$$S_i = S_{Pi} - \bar{S} \quad i = 1, \dots, N$$

Note that:

$$\sum E_i = \sum S_i = 0$$

The next step is to compute the mapping coefficients.

Let E denote a PIXEL and S denote a scan line number in the input image. On a day pass, assume that the value of E increases from left to right, and S increases from bottom to top. Suppose a point in the reference grid is denoted by (X,Y). The operator wants to map from the input image into the reference grid. He must find constants $A_1, A_2, A_3, B_1, B_2,$ and B_3 so that given a point (E,S) in the input image:

$$X = A_1 + A_2 E + A_3 S$$

$$Y = B_1 + B_2 E + B_3 S$$

The operator also wants the constants $RA_1, RA_2, RA_3, RB_1, RB_2,$ and RB_3 , for the inverse transformation, so that given (X,Y) in the reference grid, its pre-image (EI, SI) is given by:

$$EI = RA_1 + \bar{E} + RA_2 \cdot X + RA_3 \cdot Y$$

$$SI = RB_1 + \bar{S} + RB_2 \cdot X + RB_3 \cdot Y$$

Essentially, A_1 and B_1 are translation, A_2 and B_3 are scaling, and A_3 and B_2 are rotation parameters. The operator can expect A_2 and B_3 to be near 1 and A_3 and B_2 near 0.

- A. Case With More Than Three GCP's. Let (E_i, Si) , $i = 1, \dots, N$, $N > 3$, denote N computed GCP's in the input image located by the operator, and let (X_i, Y_i) be the corresponding known locations in the reference grid. A "least squares fit" will be obtained using the Penrose inverse. The detailed derivations of the formula are omitted in this document. Coefficients are found by the following formulas.

$$A_1 = \frac{1}{N} \sum X_i$$

$$A_2 = \frac{1}{D} [(\sum Si^2)(\sum X_i Ei) - (\sum EiSi)(\sum X_i Si)]$$

$$A_3 = \frac{1}{D} [(\sum Ei^2)(\sum X_i Si) - (\sum EiSi)(\sum X_i Ei)]$$

Also:

$$(M^T M)^{-1} M^T \vec{Y} = \vec{B}$$

So that:

$$B_1 = \frac{1}{N} \sum Y_i$$

$$B_2 = \frac{1}{D} [(\sum Si^2)(\sum Y_i Ei) - (\sum EiSi)(\sum Y_i Si)]$$

$$B_3 = \frac{1}{D} [(\sum Ei^2)(\sum Y_i Si) - (\sum EiSi)(\sum Y_i Ei)]$$

So, solving the system:

$$X = A_1 + A_2 E + A_3 S$$

$$Y = B_1 + B_2 E + B_3 S$$

for E and S, we get:

$$E = \left(\frac{A_3 B_1 - A_1 B_3}{A_2 B_3 - A_3 B_2} \right) + \bar{E} + \left(\frac{B_3}{A_2 B_3 - A_3 B_2} \right) X - \left(\frac{A_1}{A_2 B_3 - A_3 B_2} \right) Y$$

$$S = \left(\frac{A_1 B_2 - A_2 B_1}{A_2 B_3 - A_3 B_2} \right) + \bar{S} + \left(\frac{B_2}{A_2 B_3 - A_3 B_2} \right) X + \left(\frac{A_2}{A_2 B_3 - A_3 B_2} \right) Y$$

Now let:

$$RA_1 = \frac{A_3 B_1 - A_1 B_3}{A_2 B_3 - A_3 B_2}$$

$$RA_2 = \frac{B_3}{A_2 B_3 - A_3 B_2}$$

$$RA_3 = \frac{-A_3}{A_2 B_3 - A_3 B_2}$$

$$RB_1 = \frac{A_1 B_2 - A_2 B_1}{A_2 B_3 - A_3 B_2}$$

$$RB_2 = \frac{-B_2}{A_2 B_3 - A_3 B_2}$$

$$RB_3 = \frac{A_2}{A_2 B_3 - A_3 B_2}$$

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So that:

$$E = RA_1 + \bar{E} + RA_2 \cdot X + RA_3 \cdot Y$$

$$S = RB_1 + \bar{S} + RB_2 \cdot X + RB_3 \cdot Y$$

- B. Three GCP's. The method described in paragraph A will be used to find the mapping coefficients in case N is at least 3. If N is 3 the operator will get an exact, not a least squares, solution.
- C. Two GCP's. Suppose $N = 2$. Let (EP_1, SP_1) and (EP_2, SP_2) be the GCP in the input image corresponding to (X_1, Y_1) , and (X_2, Y_2) respectively, in the reference grid. In the equations:

$$X = A_1 + A_2 E + A_3 S$$

$$Y = B_1 + B_2 E + B_3 S$$

Set:

$$A_3 = B_2 = 0$$

Define:

$$\bar{E} = \frac{1}{2} (EP_1 + EP_2)$$

$$\bar{S} = \frac{1}{2} (SP_1 + SP_2)$$

$$E_i = EP_i - \bar{E}$$

$$S_i = SP_i - \bar{S}$$

Where:

$$i = 1, 2$$

Solving:

$$X_1 = A_1 + A_2 E_1$$

$$X_2 = A_1 + A_2 E_2$$

for A_1 and A_2 , the operator gets:

$$A_1 = \frac{X_1 E_2 - X_2 E_1}{E_1 - E_2}$$

$$A_2 = \frac{X_1 - X_2}{E_1 - E_2}$$

If $E_1 - E_2 = 0$, let $A_2 = 1.0$ and find A_1 as per $N = 1$.

Similarly, solving:

$$Y_1 = B_1 + B_3 S_1$$

$$Y_2 = B_1 + B_3 S_2$$

for B_1 and B_2 , the operator gets:

$$B_1 = \frac{Y_1 S_2 - Y_2 S_1}{S_1 - S_2}$$

$$B_3 = \frac{Y_1 - Y_2}{S_1 - S_2}$$

If $S_1 - S_2 = 0$, let $B_3 = 1.0$ and find B_1 as $N = 1$

Then, for each (E,S) in the input image:

$$X = A_1 + A_2 E + 0 \cdot S$$

$$Y = B_1 + 0 \cdot E + B_3 S$$

For the inverse transformation, given (X,Y) in the reference grid:

$$E = \frac{-A_1}{A_2} + \left(\frac{1}{A_2} \right) X$$

$$S = \frac{-B_1}{B_3} + \left(\frac{1}{B_3} \right) Y$$

- D. One GCP. Suppose $N = 1$. Let (EP_1, SP_1) be the identified GCP and let (X_1, Y_1) be its reference grid location. Let:

$$A_1 = X_1 - EP_1$$

$$B_1 = Y_1 - SP_1$$

Let A_2 and B_3 both = 1, and let B_2 and A_3 both = 0.

Then, for each (EP,SP):

$$X = A_1 + A_2 EP + A_3 SP$$

$$Y = B_1 + B_2 EP + B_3 SP$$

This reduces simply to:

$$X = A_1 + EP$$

$$Y = B_1 + SP$$

Having calculated the mapping and inverse transformation coefficients, GCPEXC performs the last step, computing the delta errors and sigmas for each GCP, where the delta error for PIXEL E = pre-image of E - operator-identified point E.

First, we must find the pre-image of each X,Y in the reference grid of all identified GCP's. GCDEXC calls a FORTRAN subroutine, GCPNTS, to compute the pre-image points (EI, SI) from the reference grid coordinates.

$$EI_i = RA1 + \bar{E} + RA2 * X_i + RA3 * Y_i$$

$$SI_i = RB1 + \bar{S} + RB2 * X_i + RB3 * Y_i$$

Where:

X_i, Y_i = reference grid points of the GCP's

\bar{S}, \bar{E} = means of the operator-identified GCP's (EP_i, SP_i)

If the operator is working with night data, he wants the delta errors and sigmas that are to be displayed to be reflected in the night pass coordinate plane. As defined previously, the night points (EP, SP) had been rotated to lie in the day pass coordinated plane since all computations of coefficients and fit are performed in this coordinate plane. So, GCPEXC calls a FORTRAN subroutine, INVROT, to perform inverse rotation on the night rotated points (EP_i, SP_i). The pre-image points (EI_i, SI_i) calculated above, are also inverse rotated by INVROT. This results in the night points (to be used in calculating the deltas and sigmas) to be defined back in the night coordinate plane.

Note that after rotation, the new center PIXEL element and center scan line, denoted by E_c^R and S_c^R respectively, will be $E_c \cdot \cos 23.4^\circ$ and $S_c \cdot \cos 23.4^\circ$.

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If (EP,SP) is a point in the rotated image, then its inverse rotated point in the input image is given by the following equations:

$$EP_i = Ec + (EP_i - Ec^R) \cos 25.8^\circ + (SP_i - Sc^R) \sin 25.8^\circ$$

$$SP_i = Sc - (EP_i - Ec^R) \sin 25.8^\circ + (SP_i - Sc^R) \cos 25.8^\circ$$

Where:

$$i = 1, N$$

Also:

$$EI_i = Ec + (EI_i - Ec^R) \cos 25.8^\circ + (SI_i - Sc^R) \sin 25.8^\circ$$

$$SI_i = Sc - (EI_i - Ec^R) \sin 25.8^\circ + (SI_i - Sc^R) \cos 25.8^\circ$$

Where:

$$i = 1, N$$

Now GCPEXC computes the delta errors (EDELTA, SDELTA) for each GCP to reflect the relationship of the entered point (EP,SP) in comparison with its calculated location (EI,SI) as defined by the pre-image of reference grid location (X,Y).

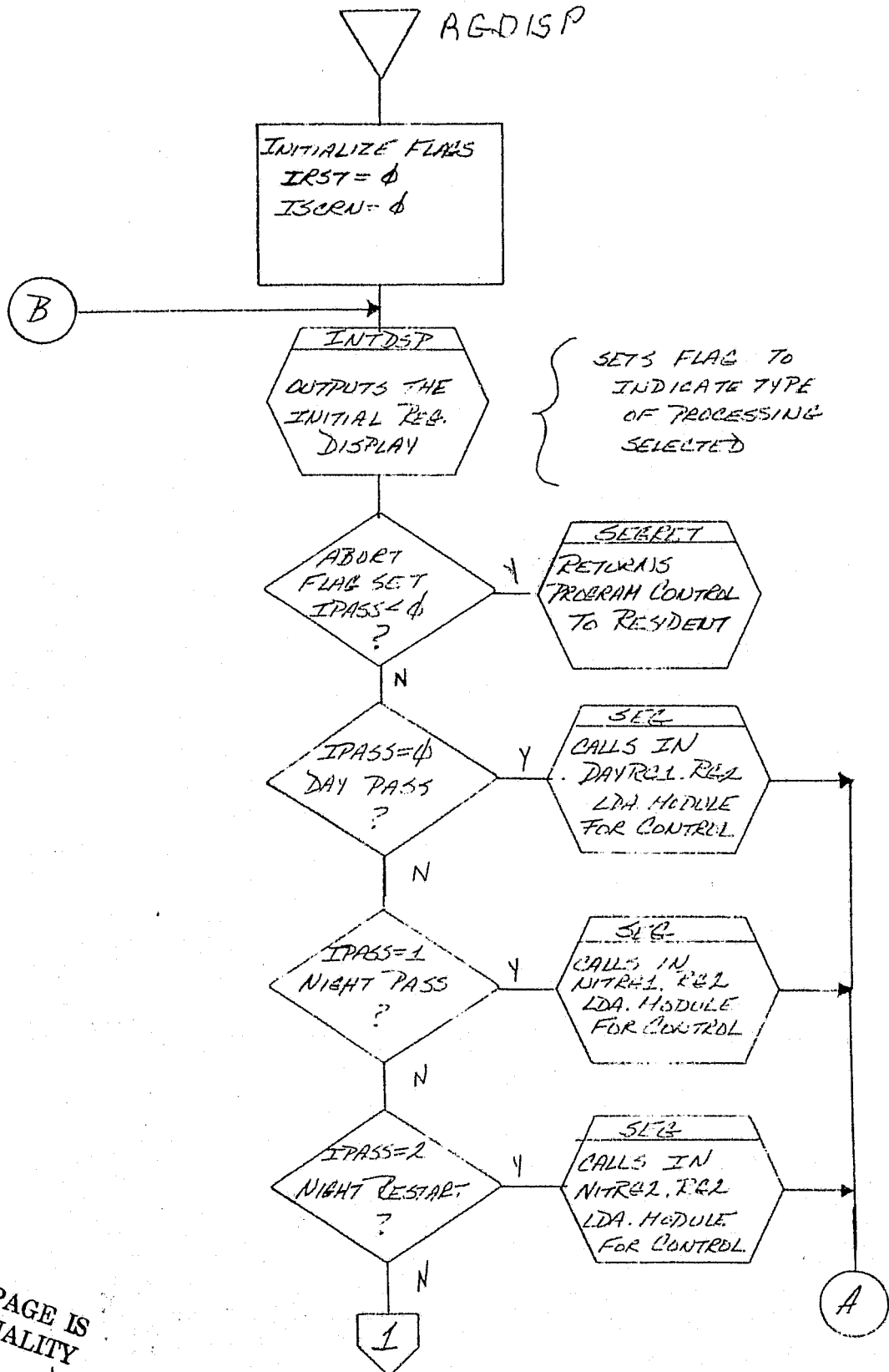
$$EDELTA_i = EI_i - EP_i$$

$$SDELTA_i = SI_i - SP_i$$

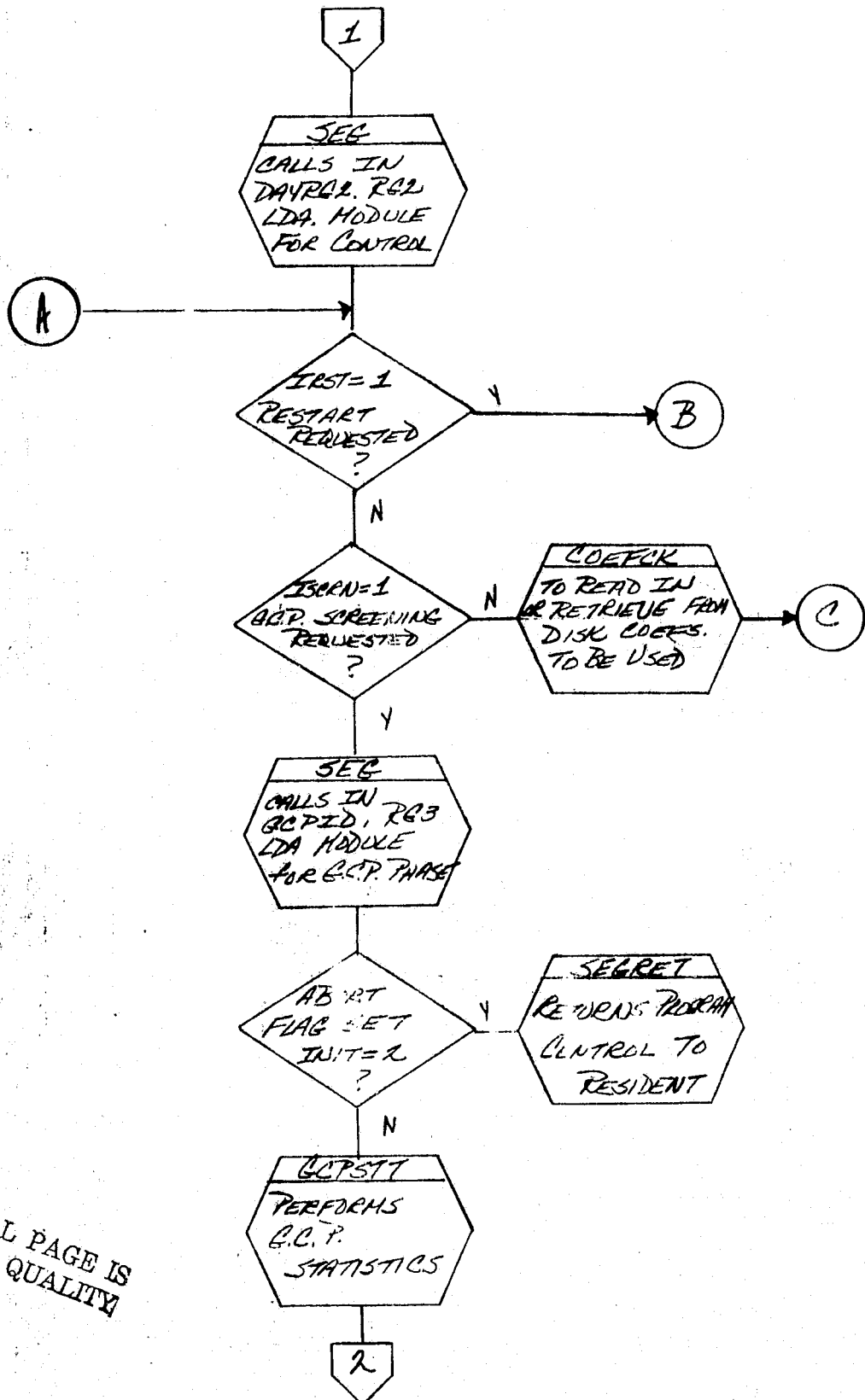
ESIGMA and SGIGMA are then computed to reflect to average delta errors of all identified GCP's.

GCPEXC has now completed its functions and returns to GCPID, where these calculations will be picked up from the GCPTAB common and displayed to the operator on the GCP VT05 display. GCPEXC will be called again after the next GCP has been identified via the operator.

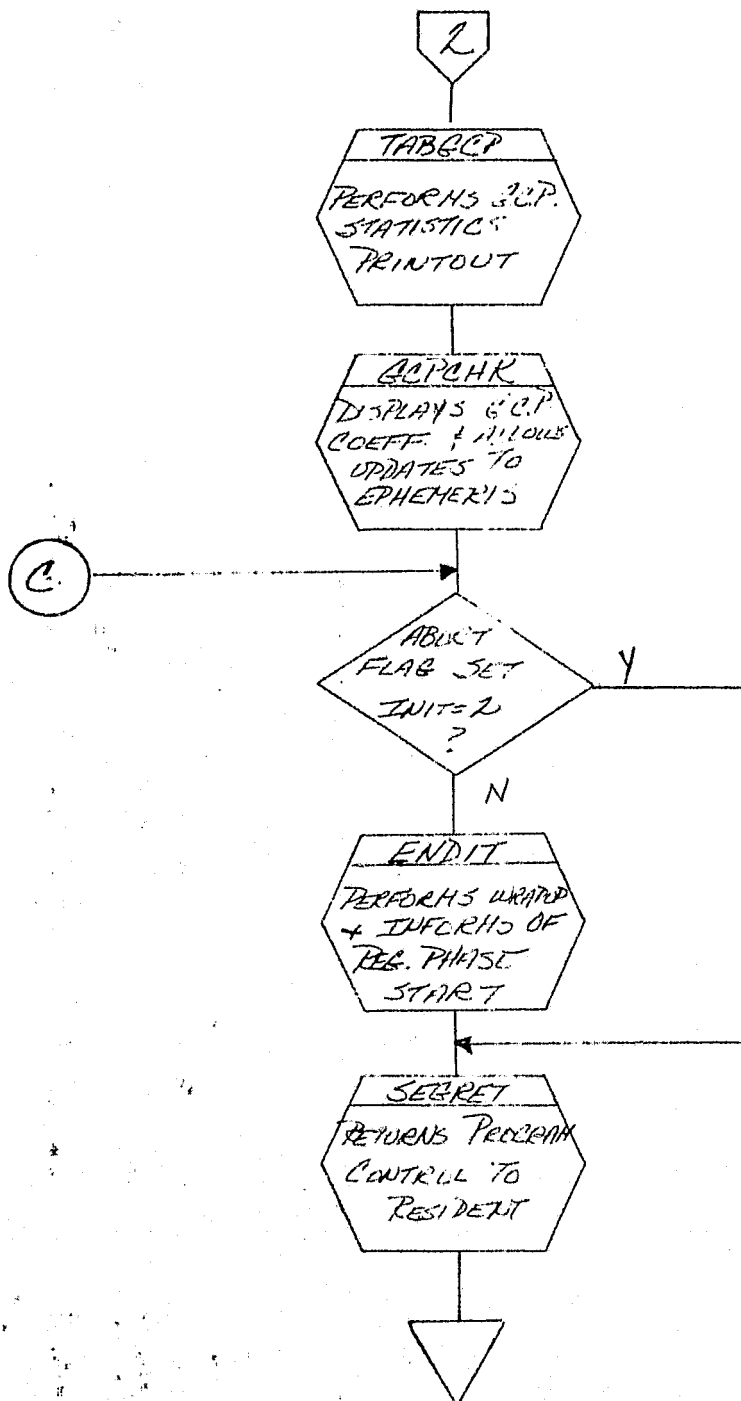
3.2.1.2 Flow Charts. See the following 99 pages.

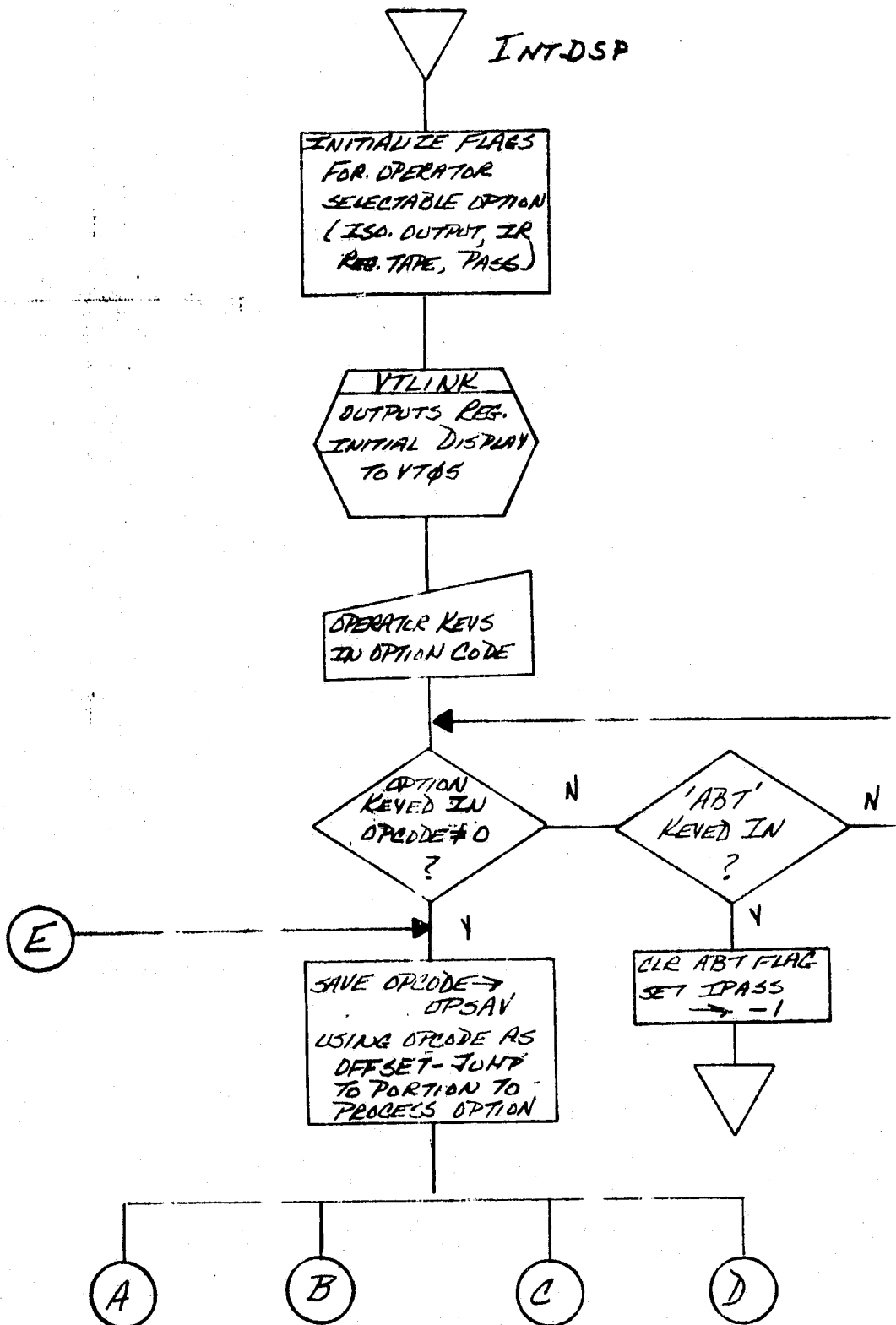


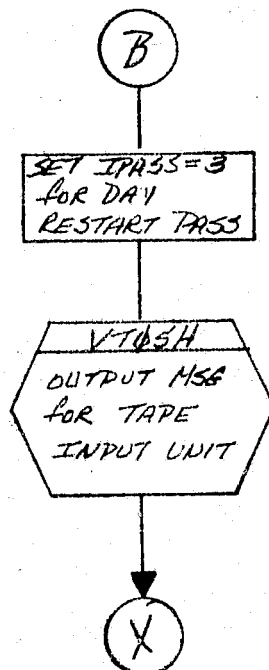
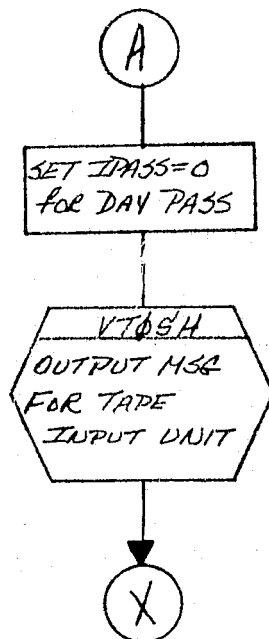
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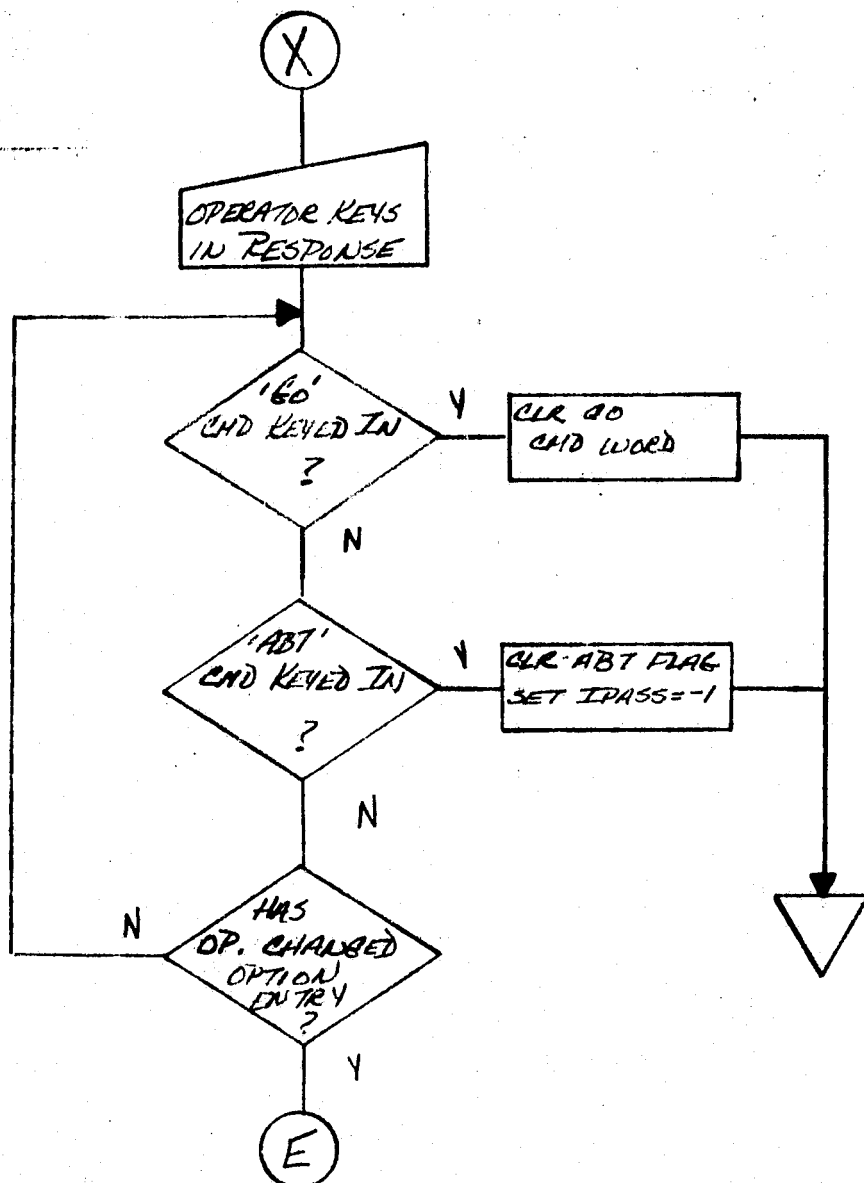


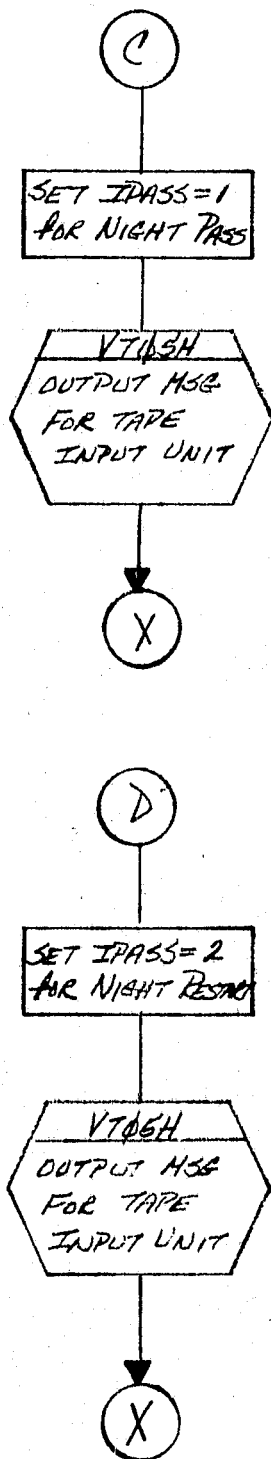
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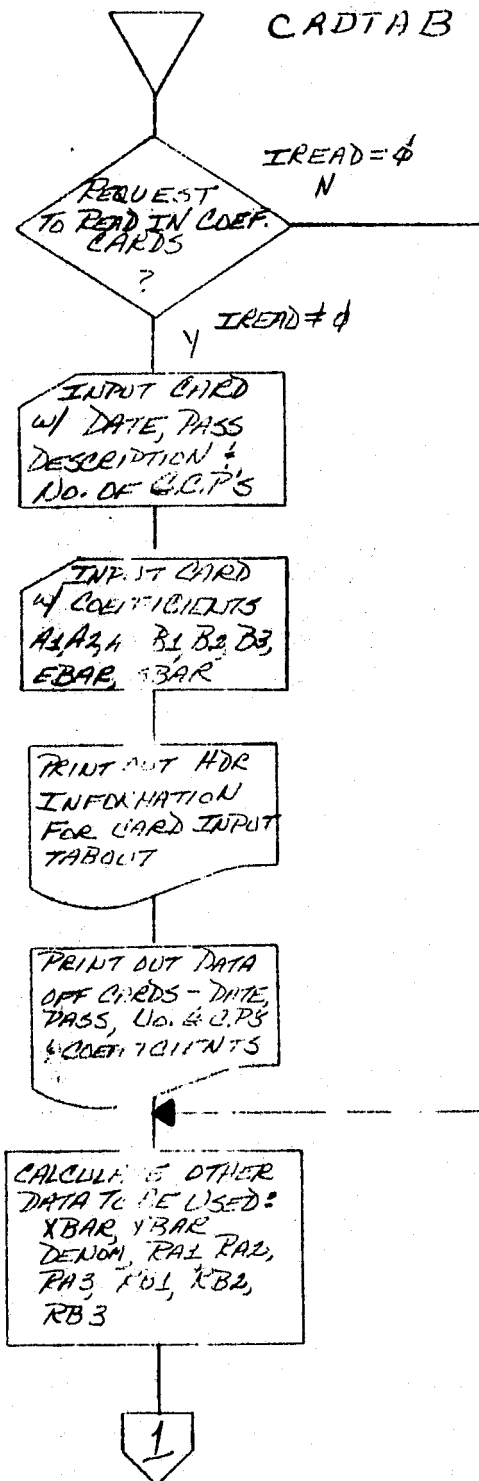


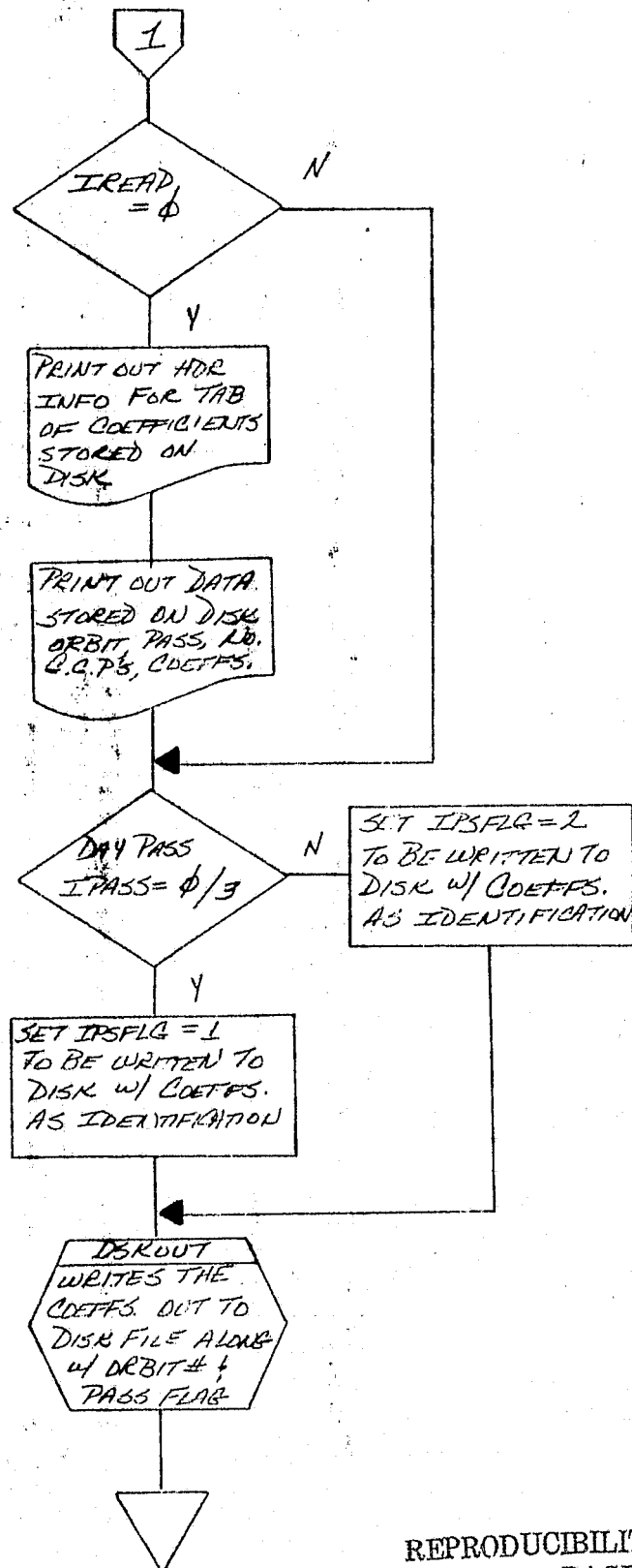




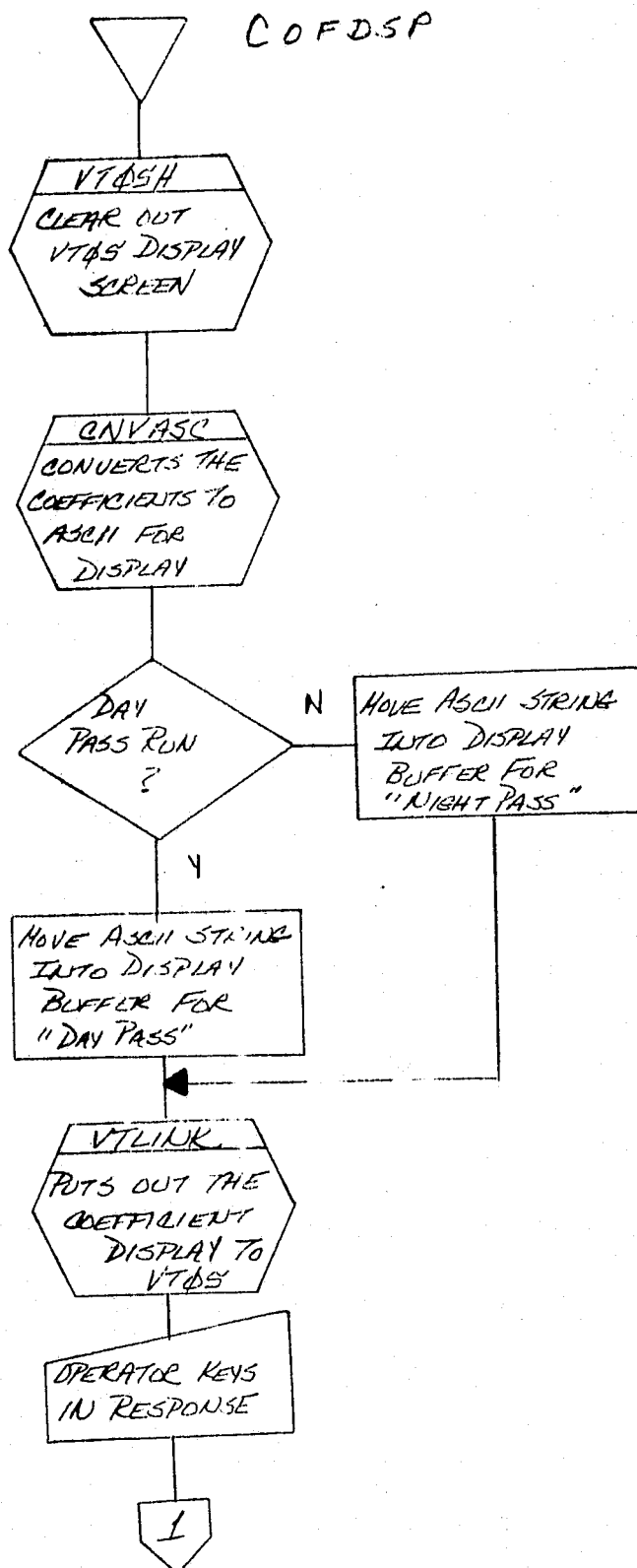


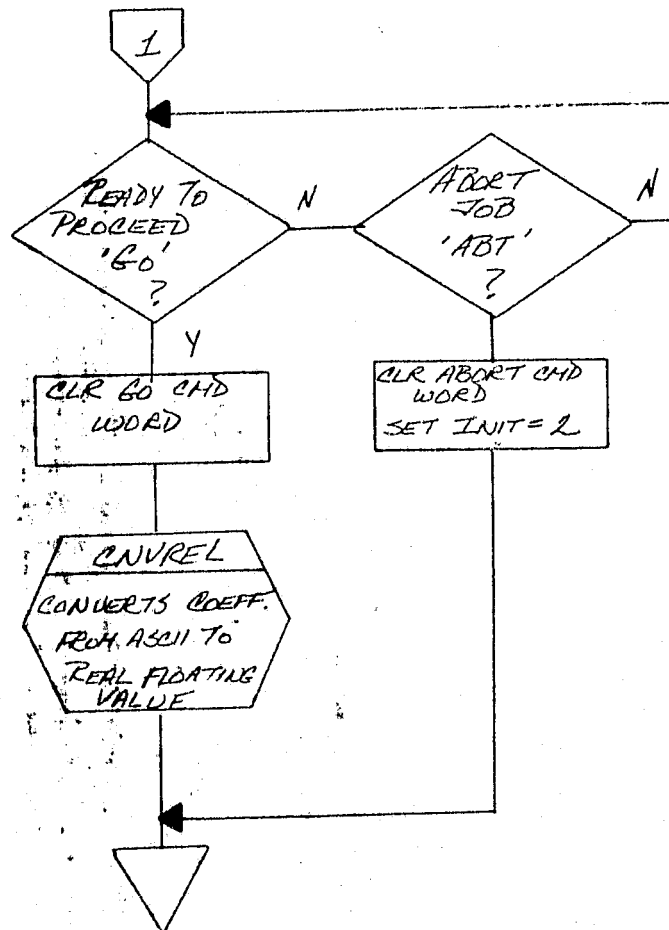


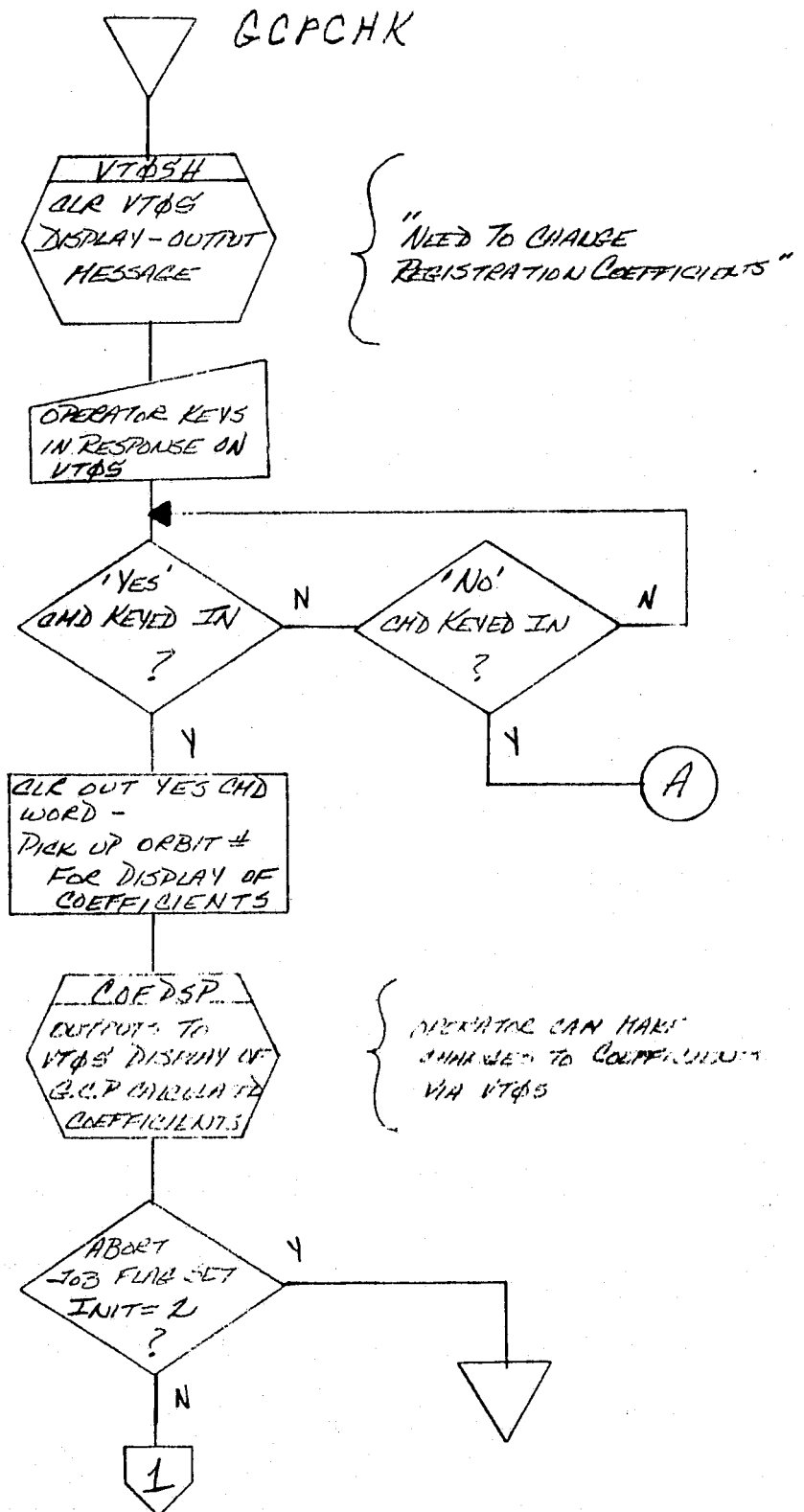


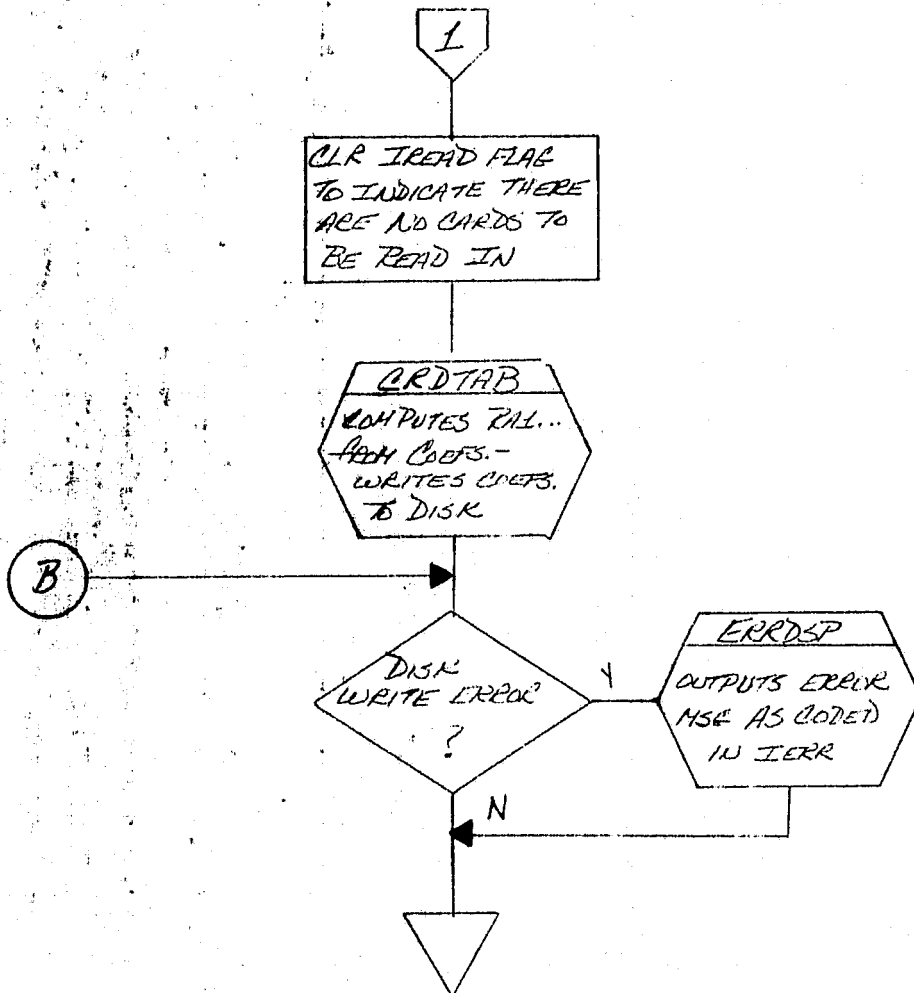


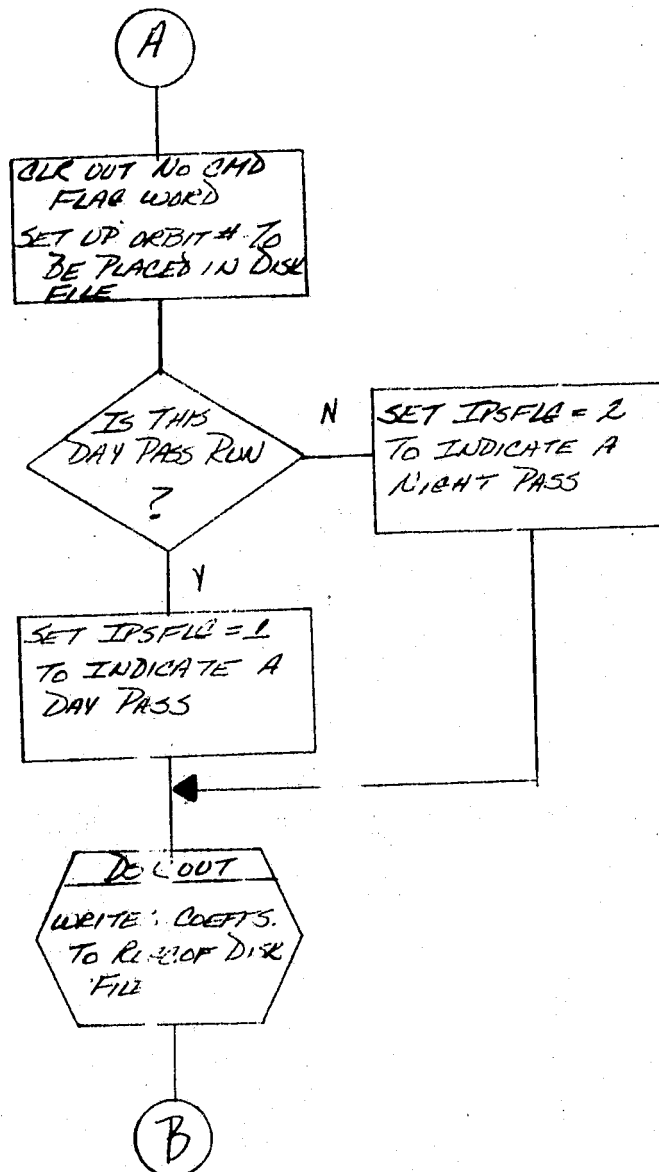
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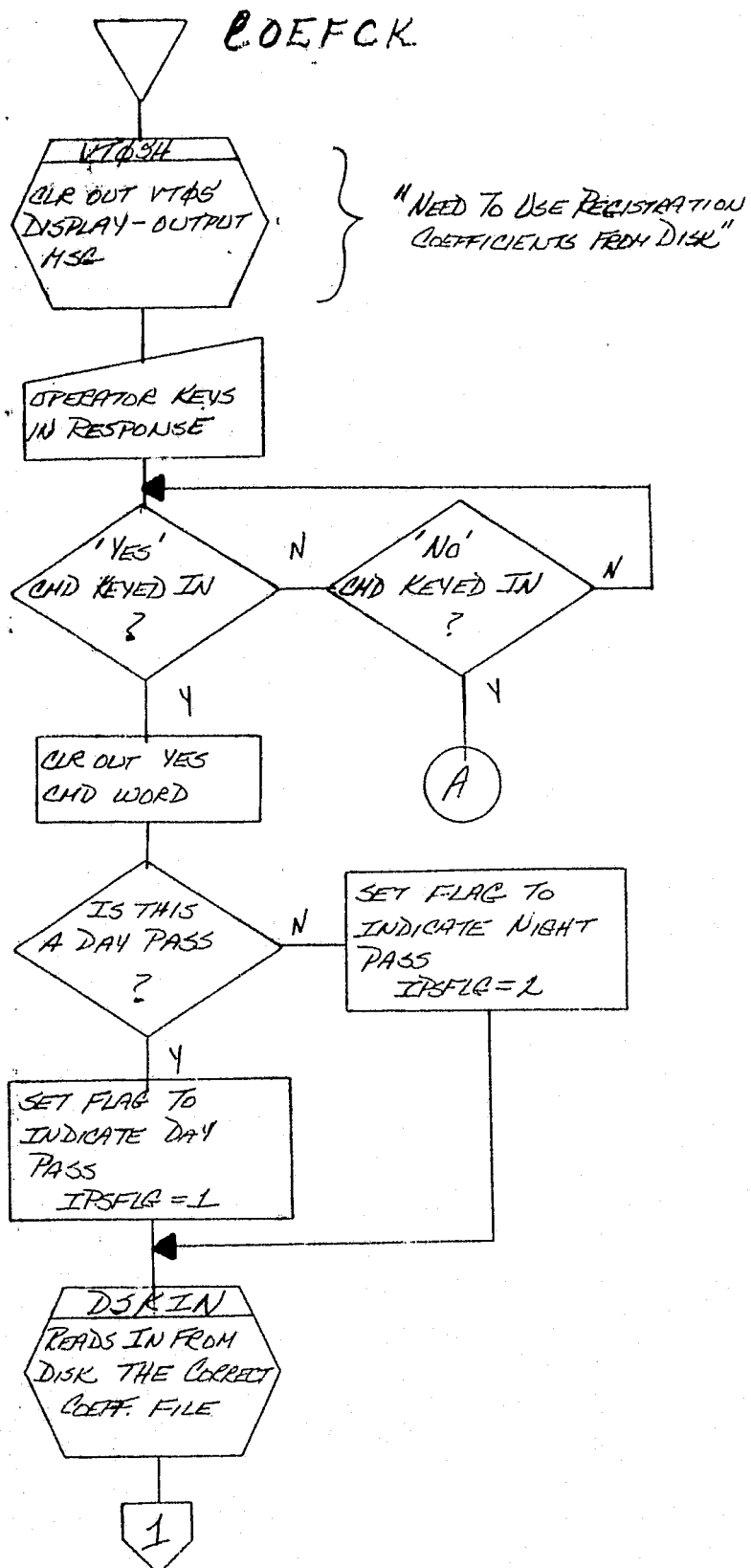


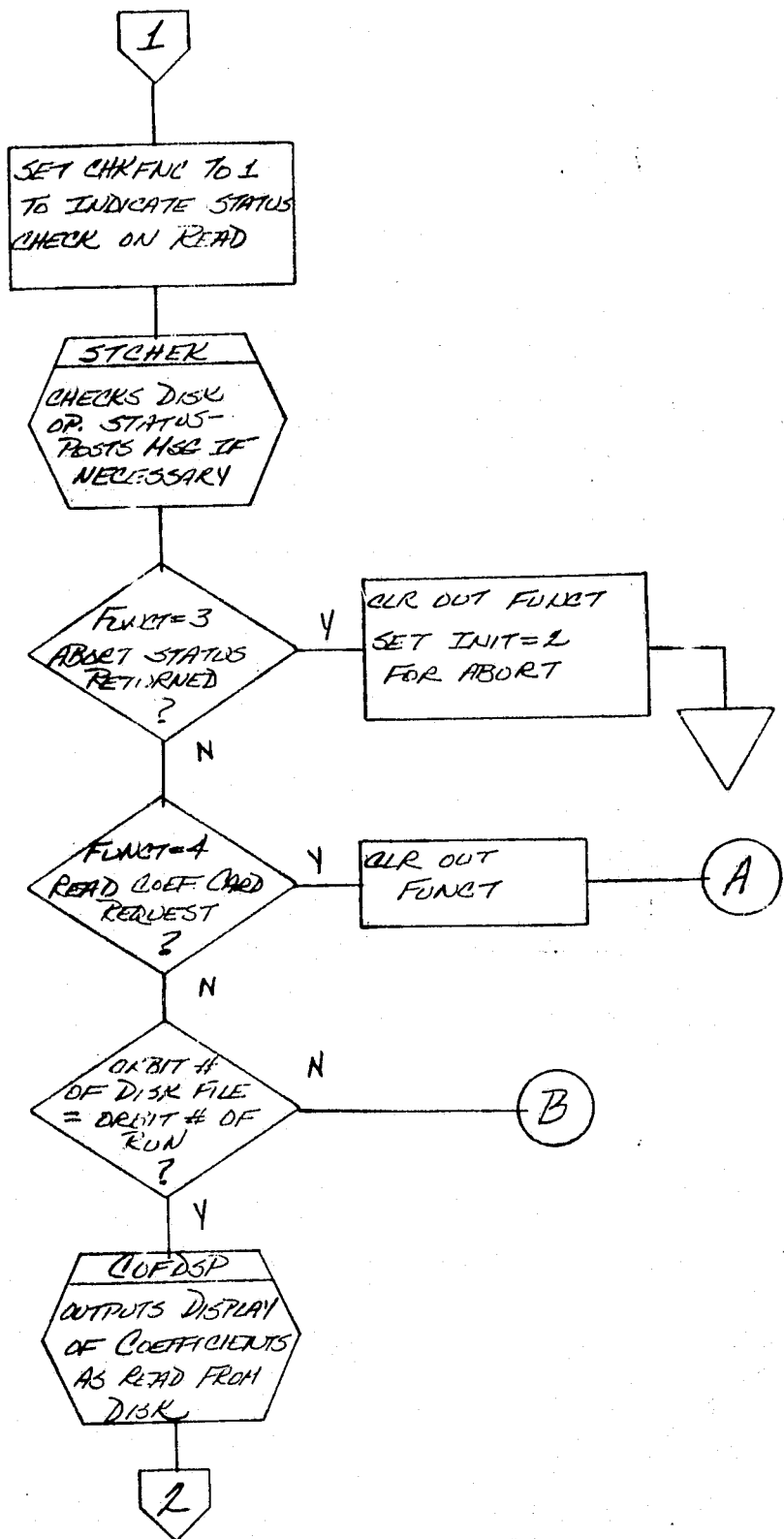




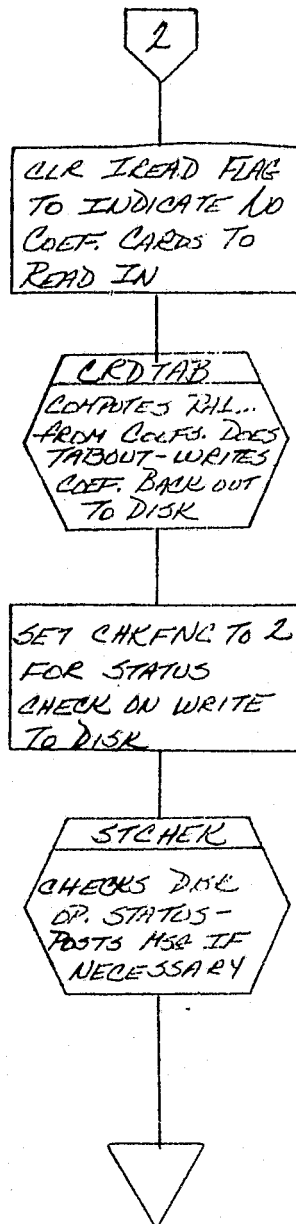


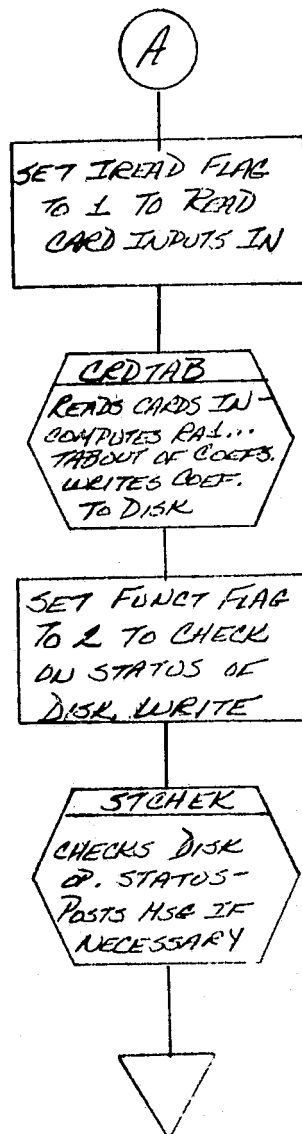
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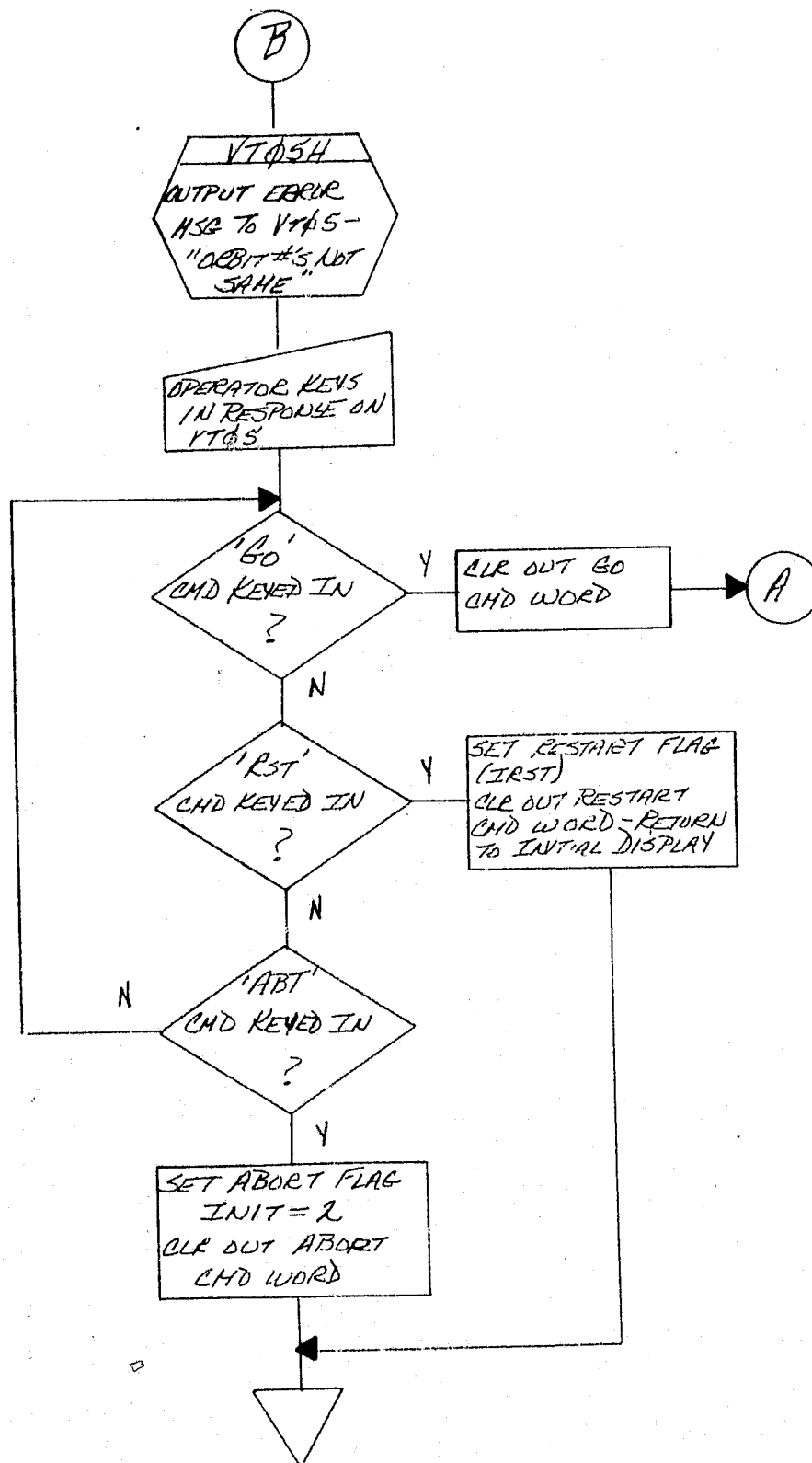




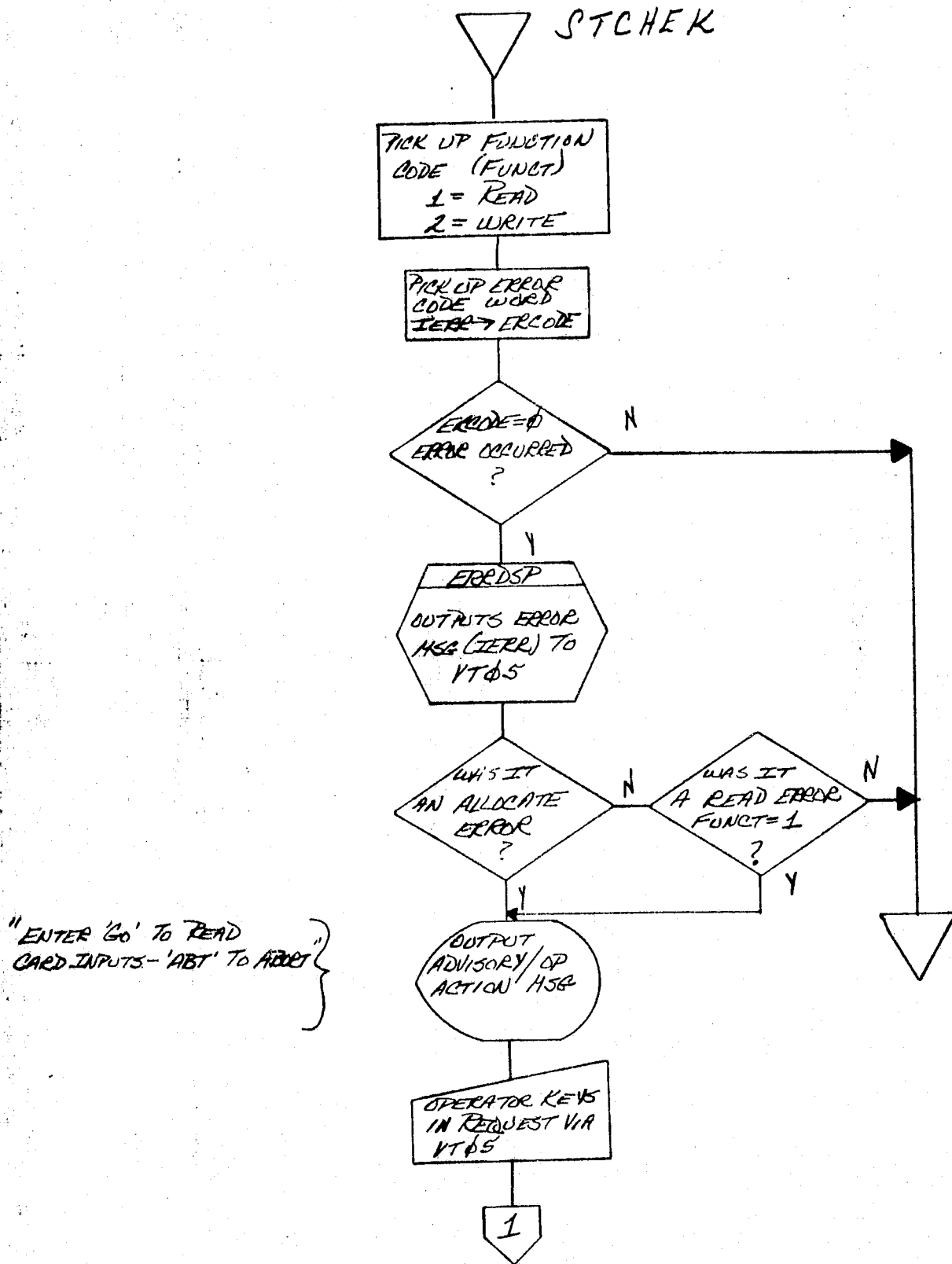
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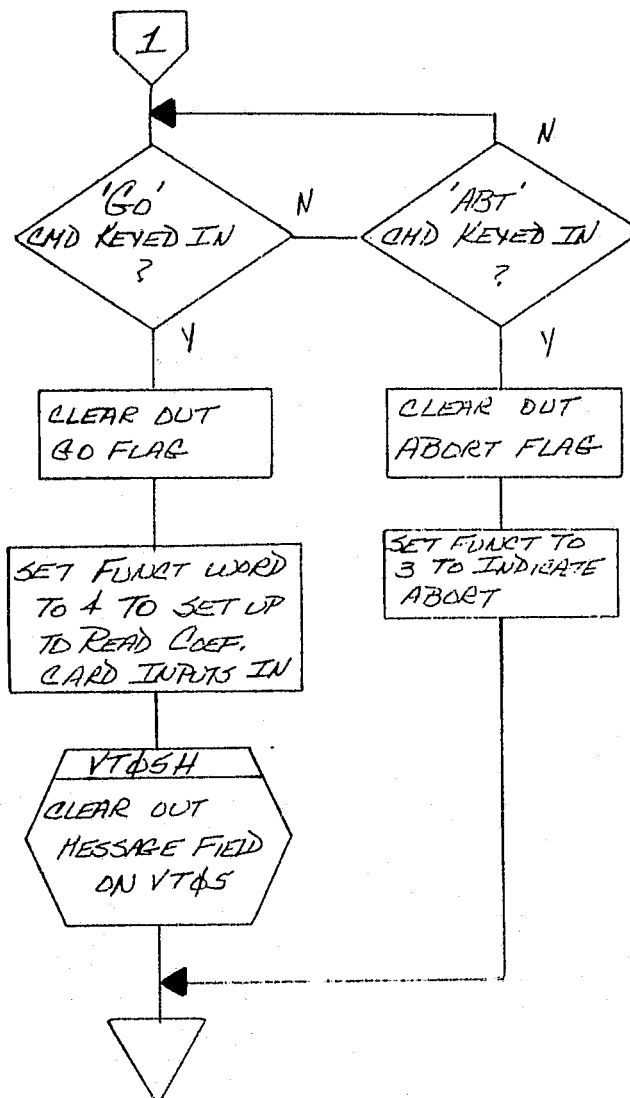


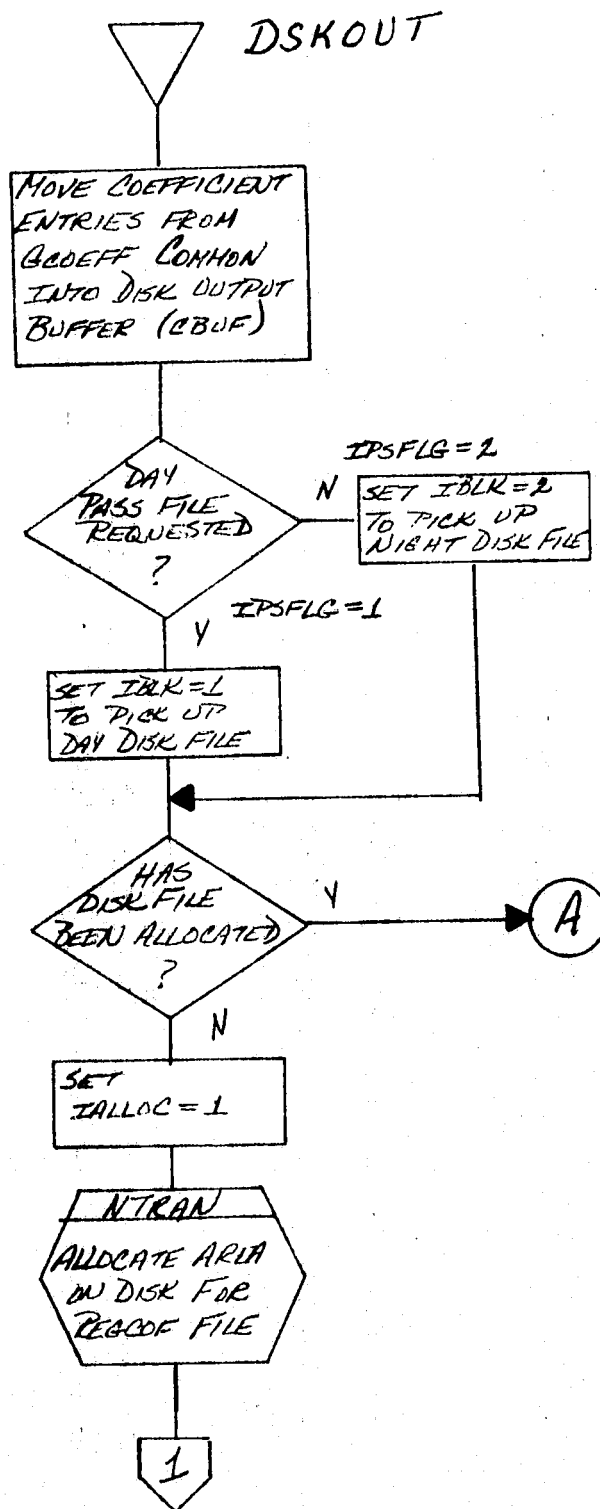


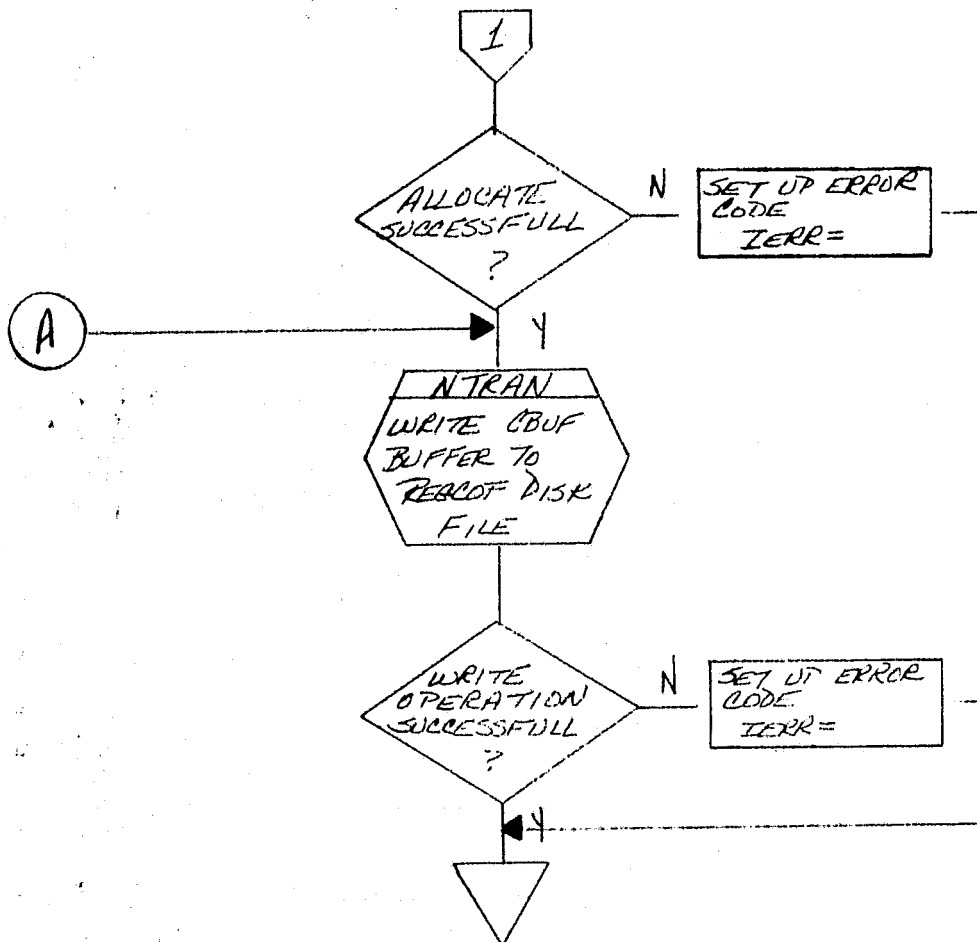


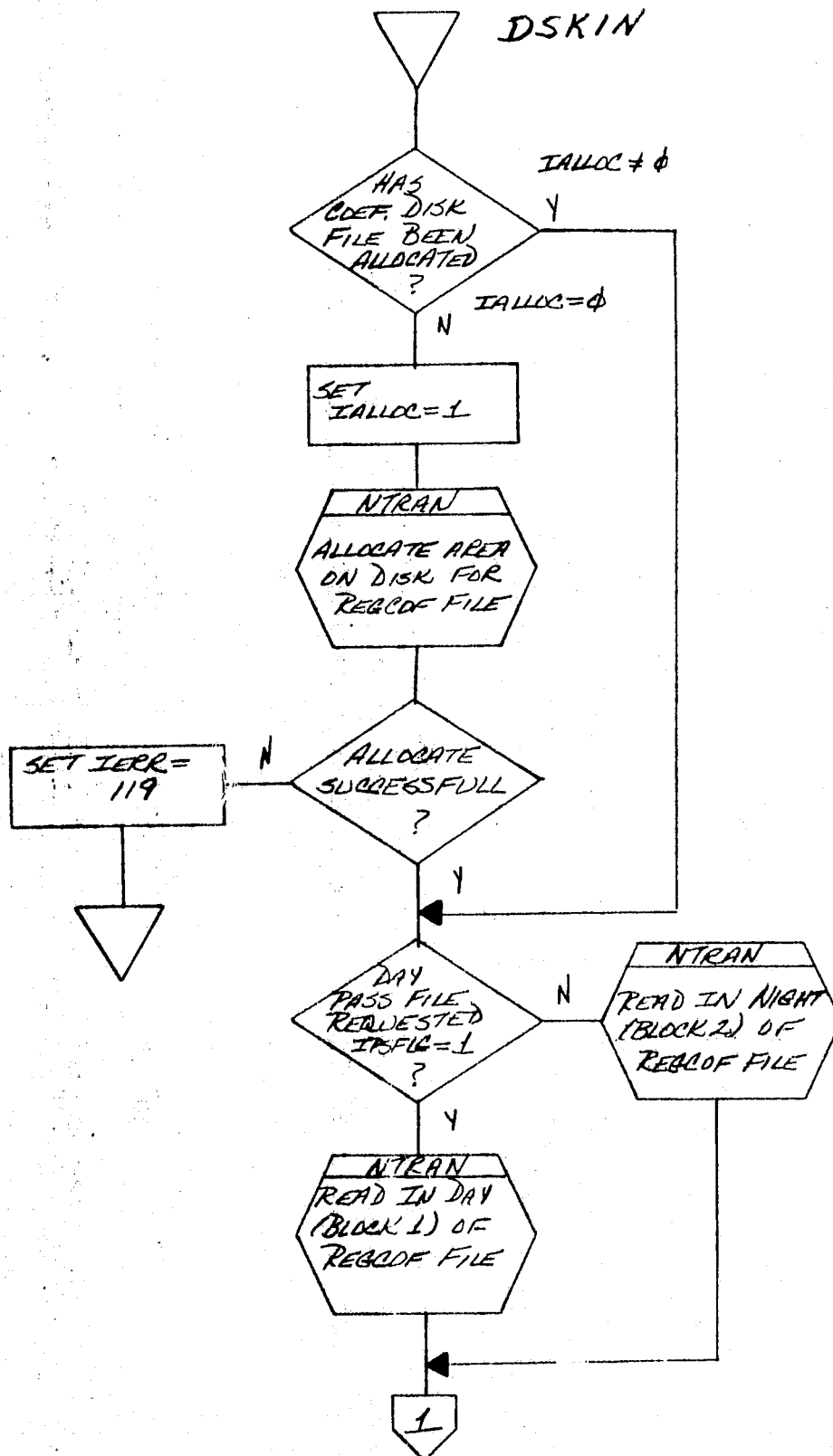
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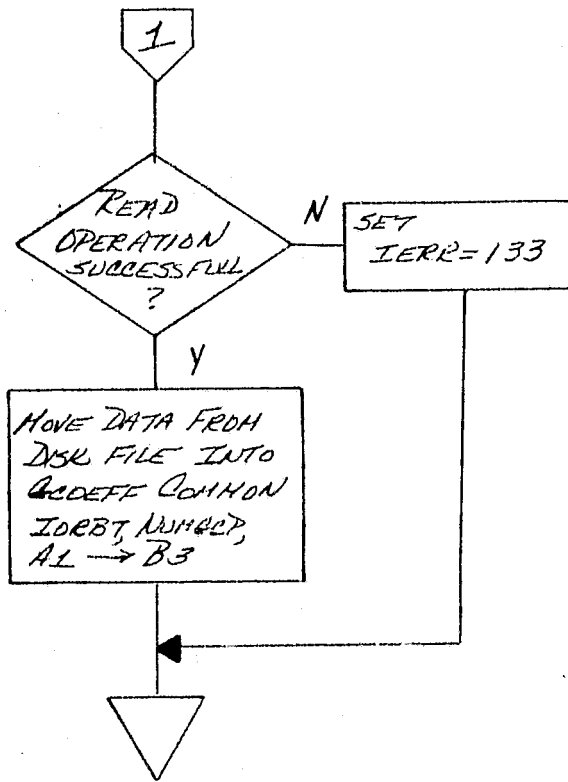




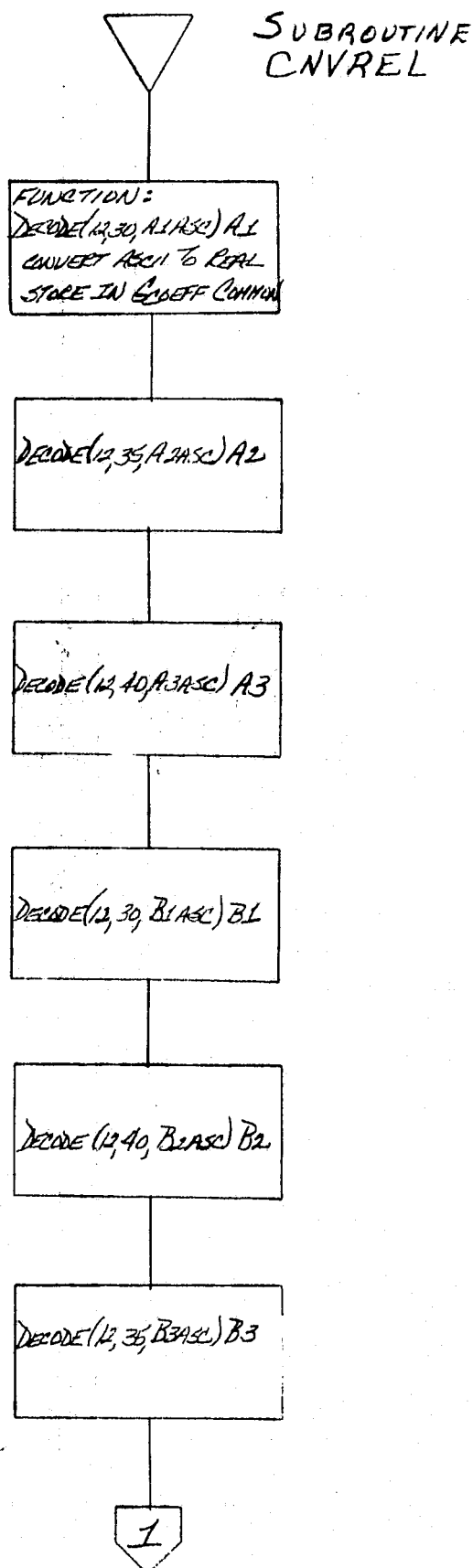


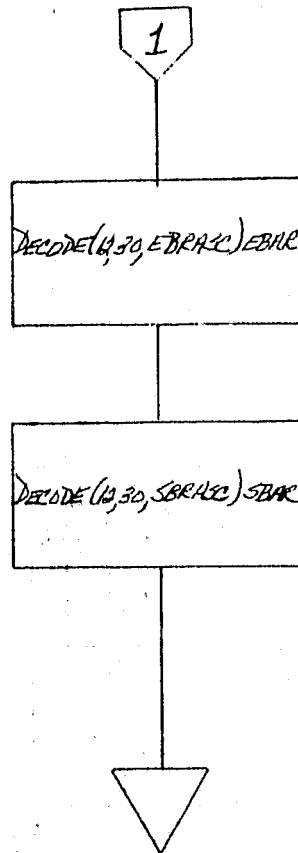




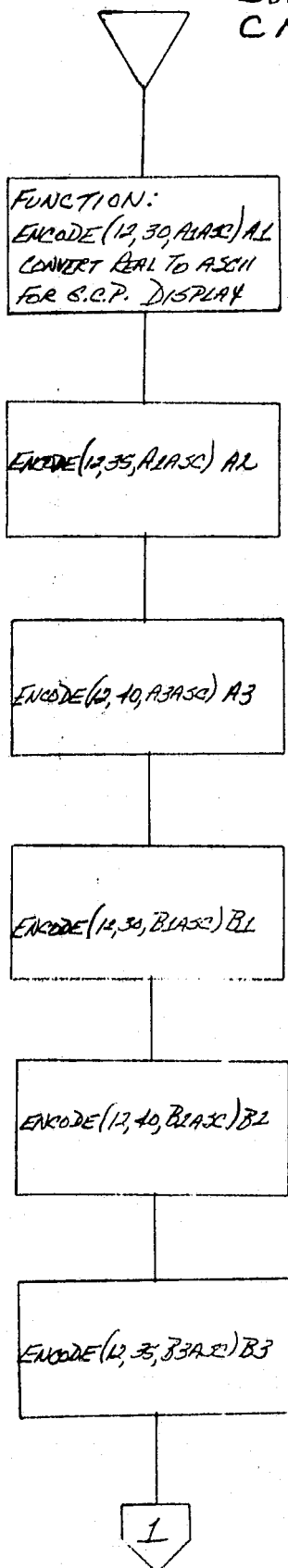


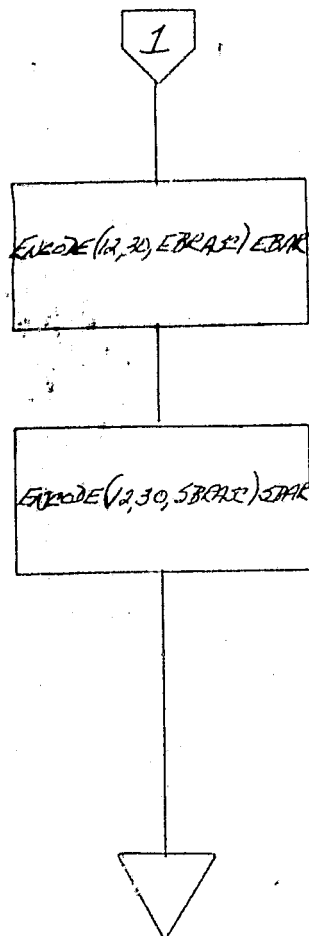
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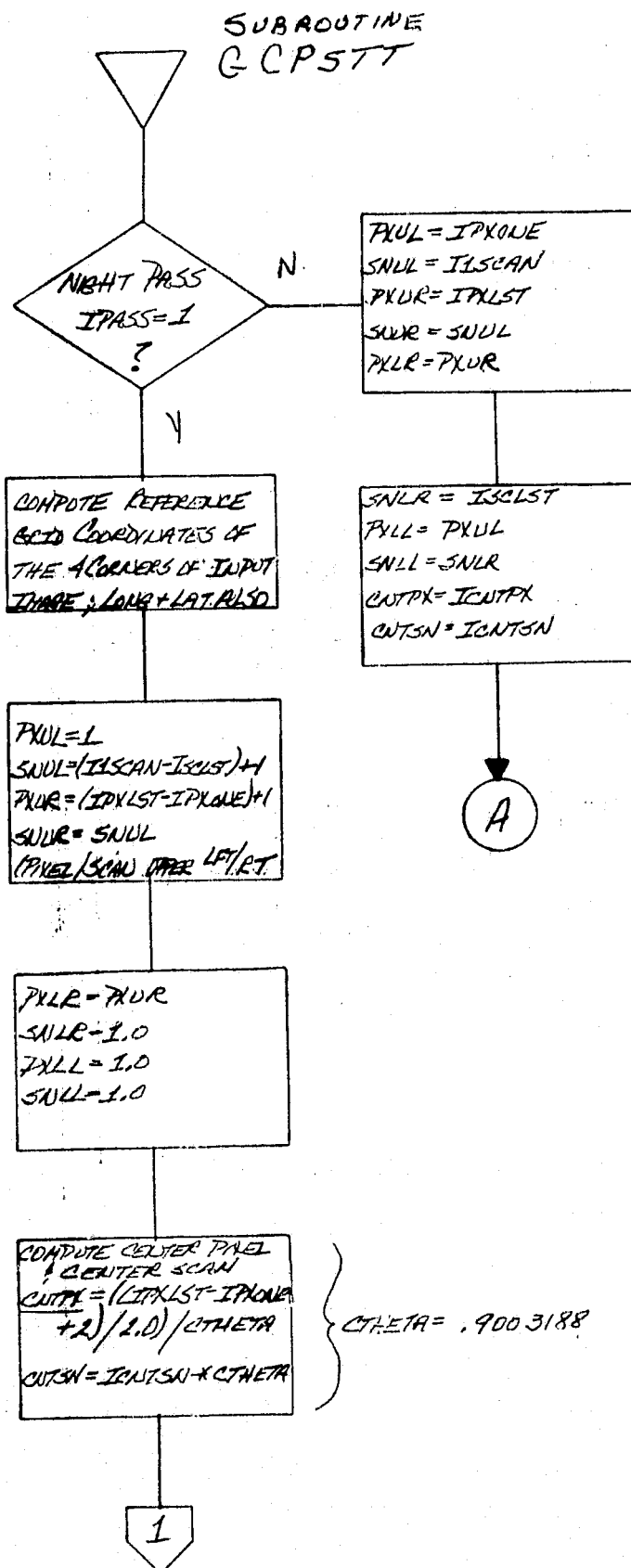


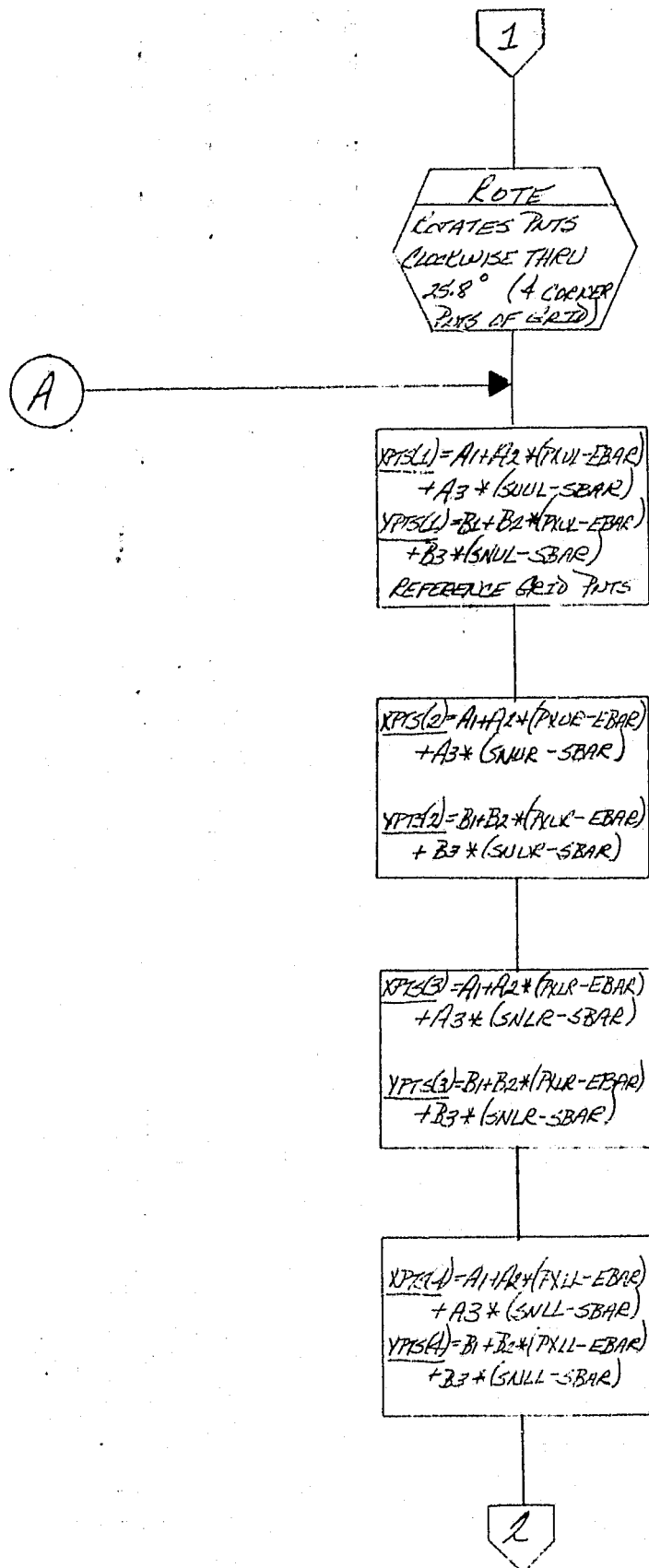


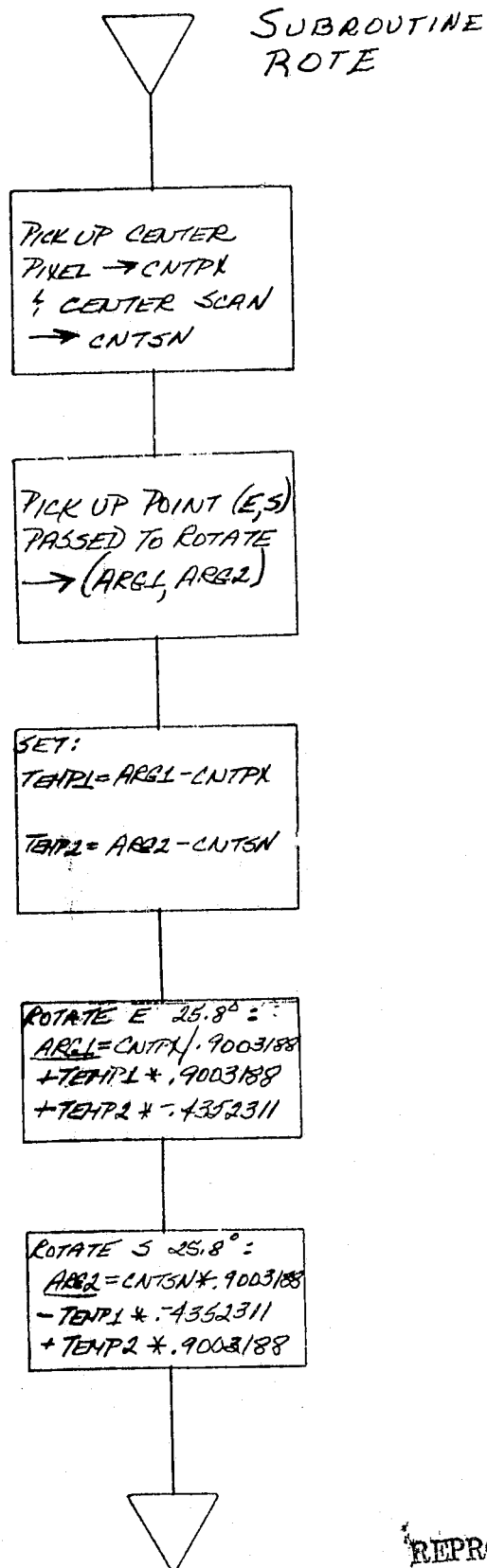
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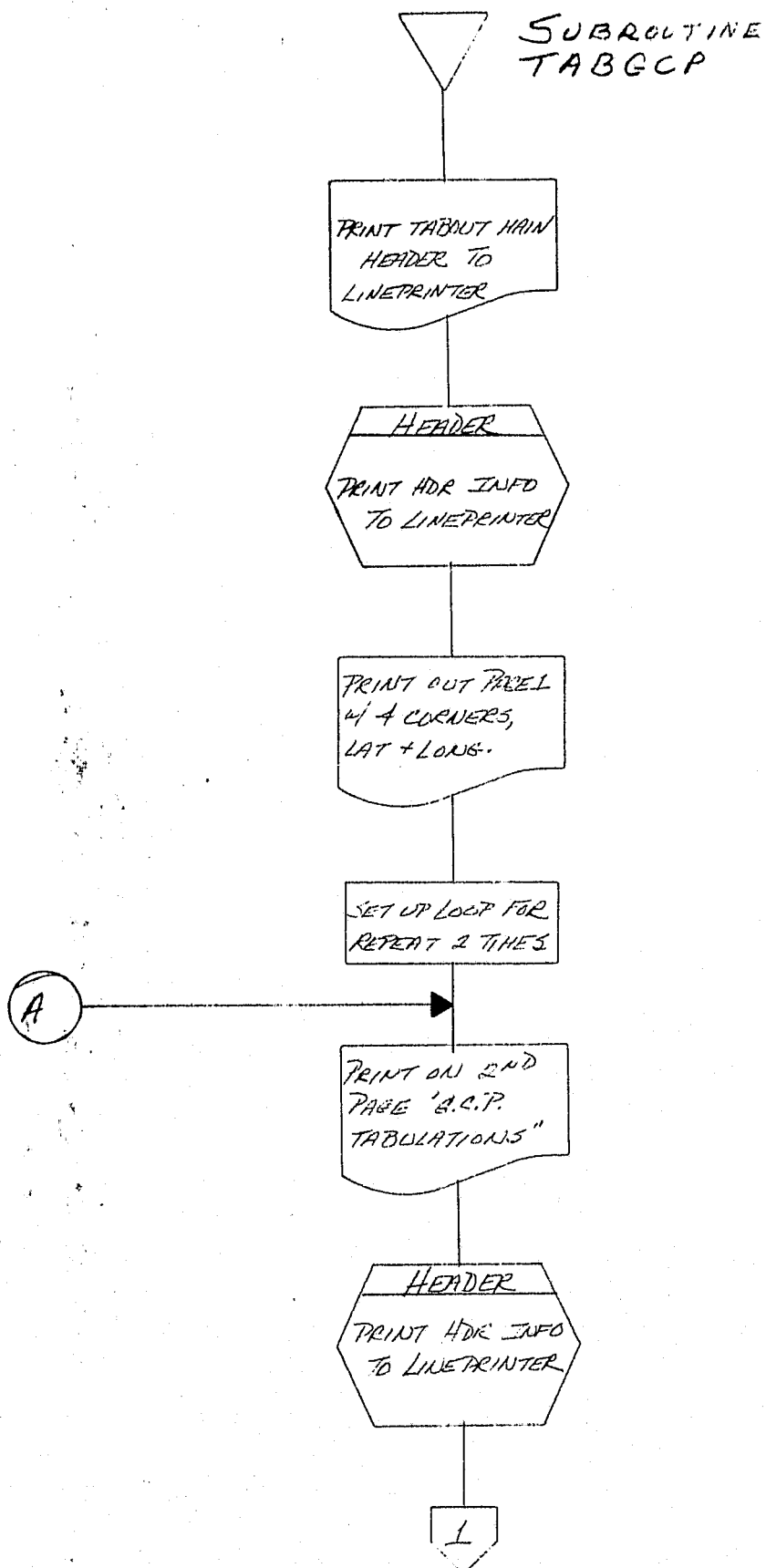


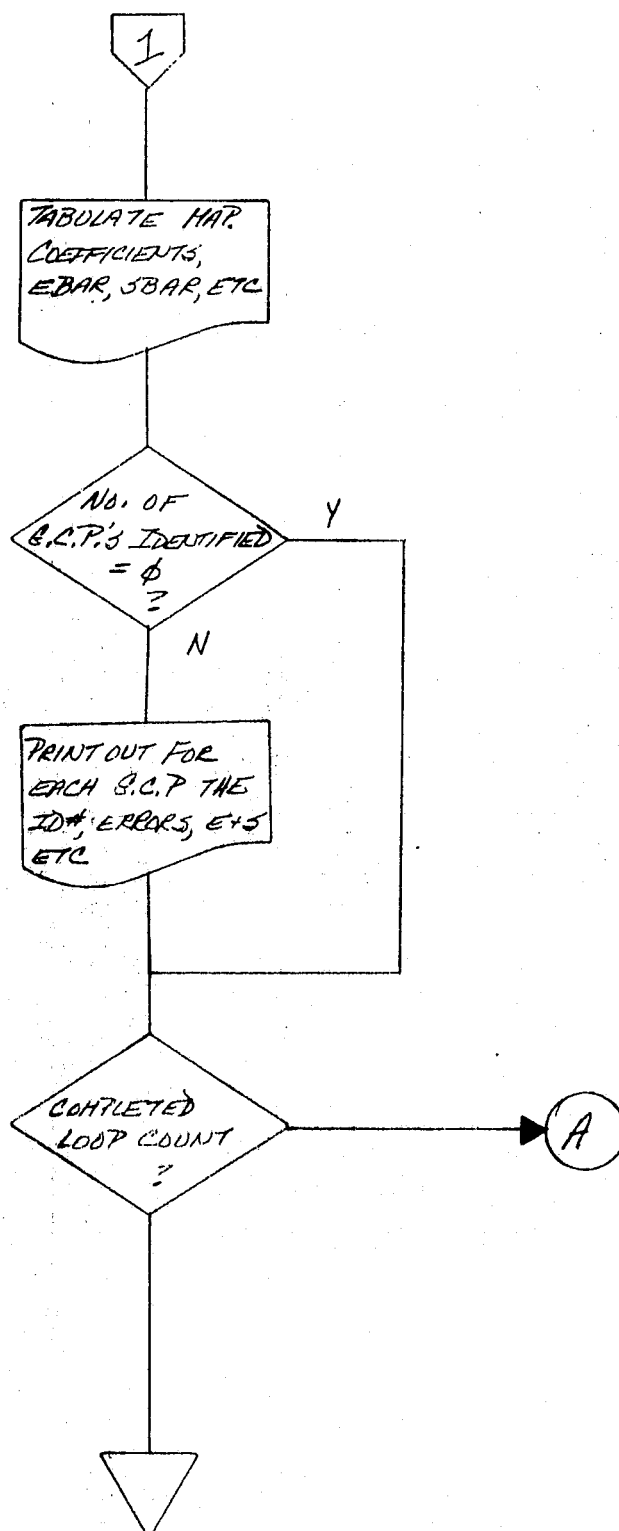


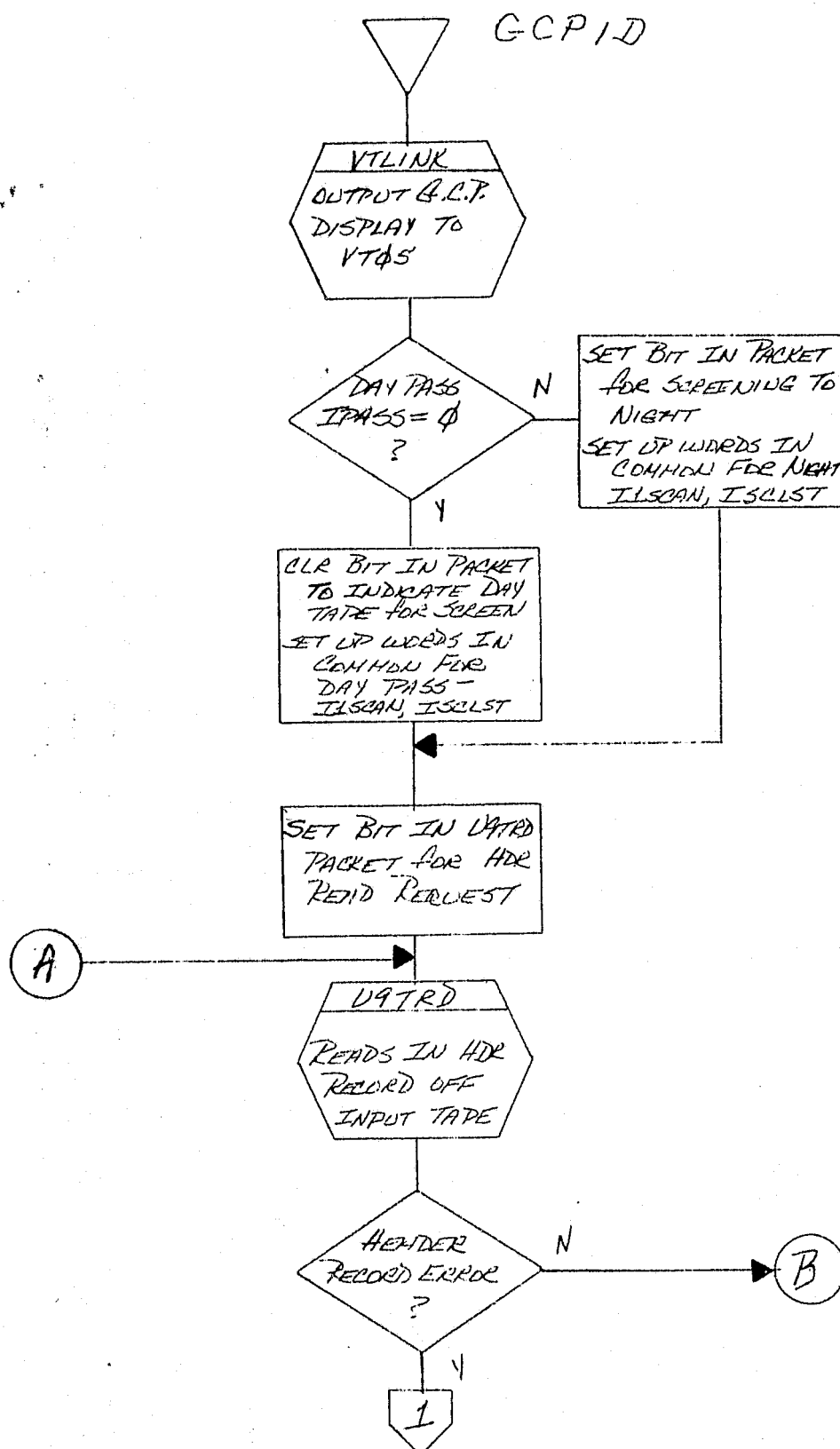


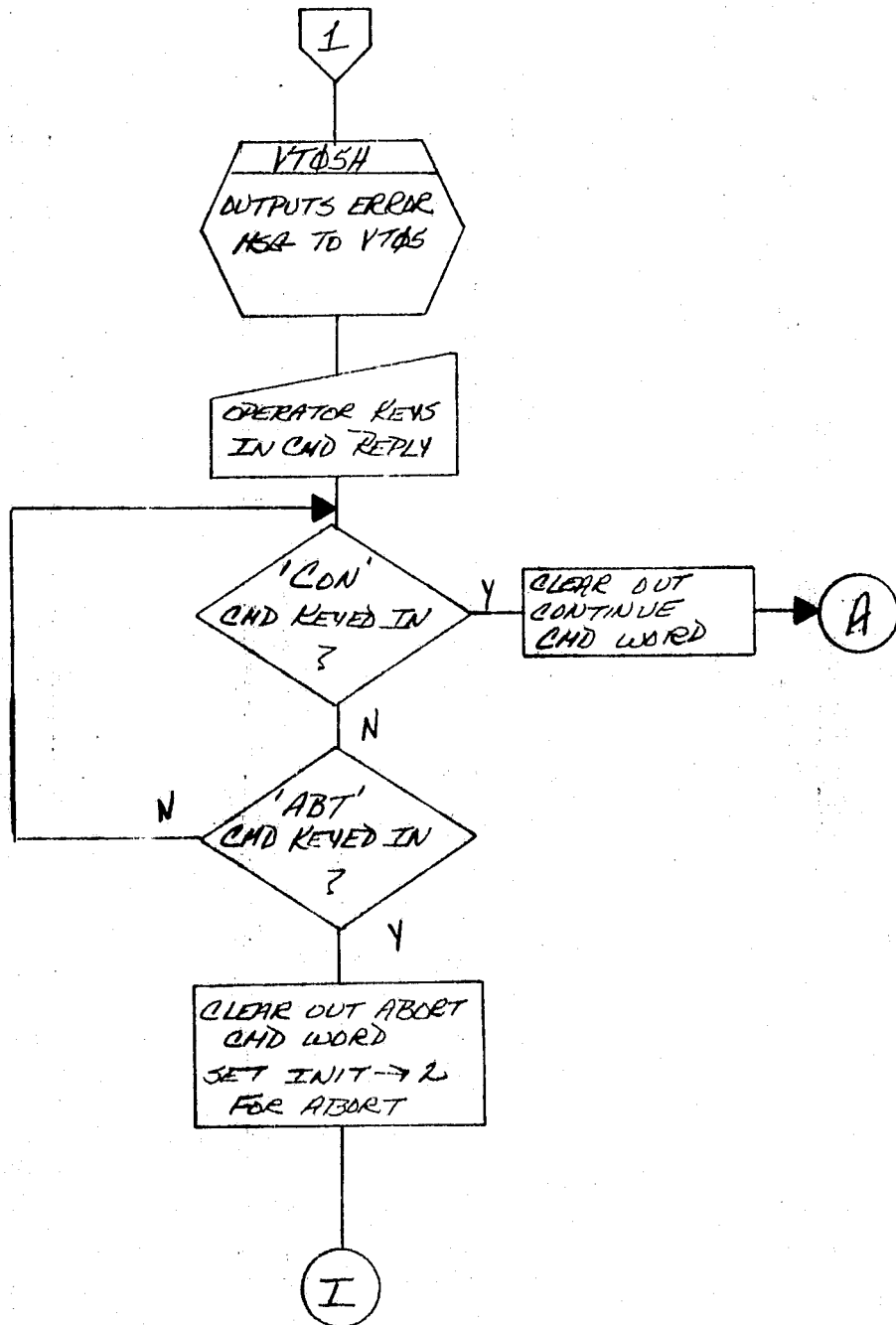


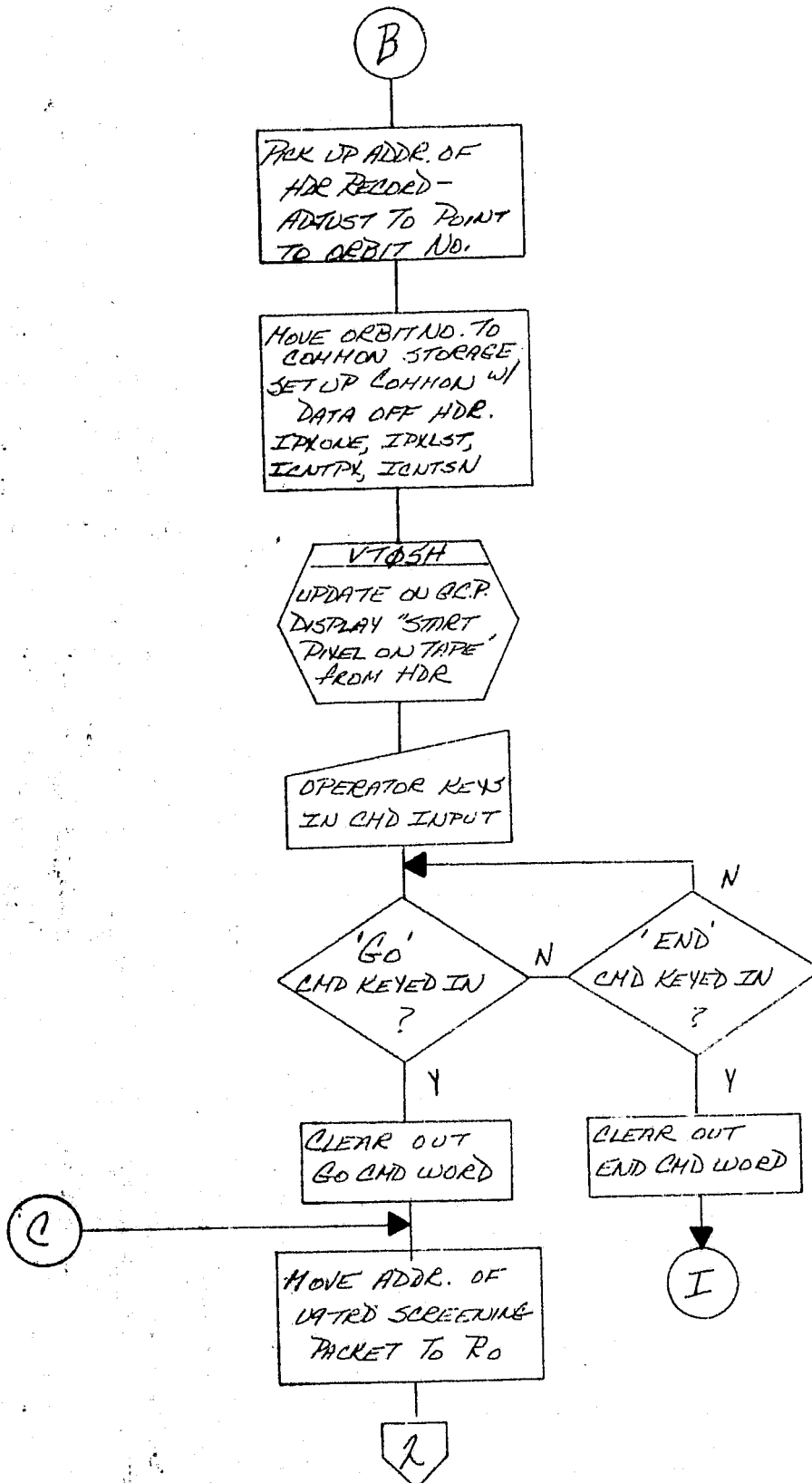
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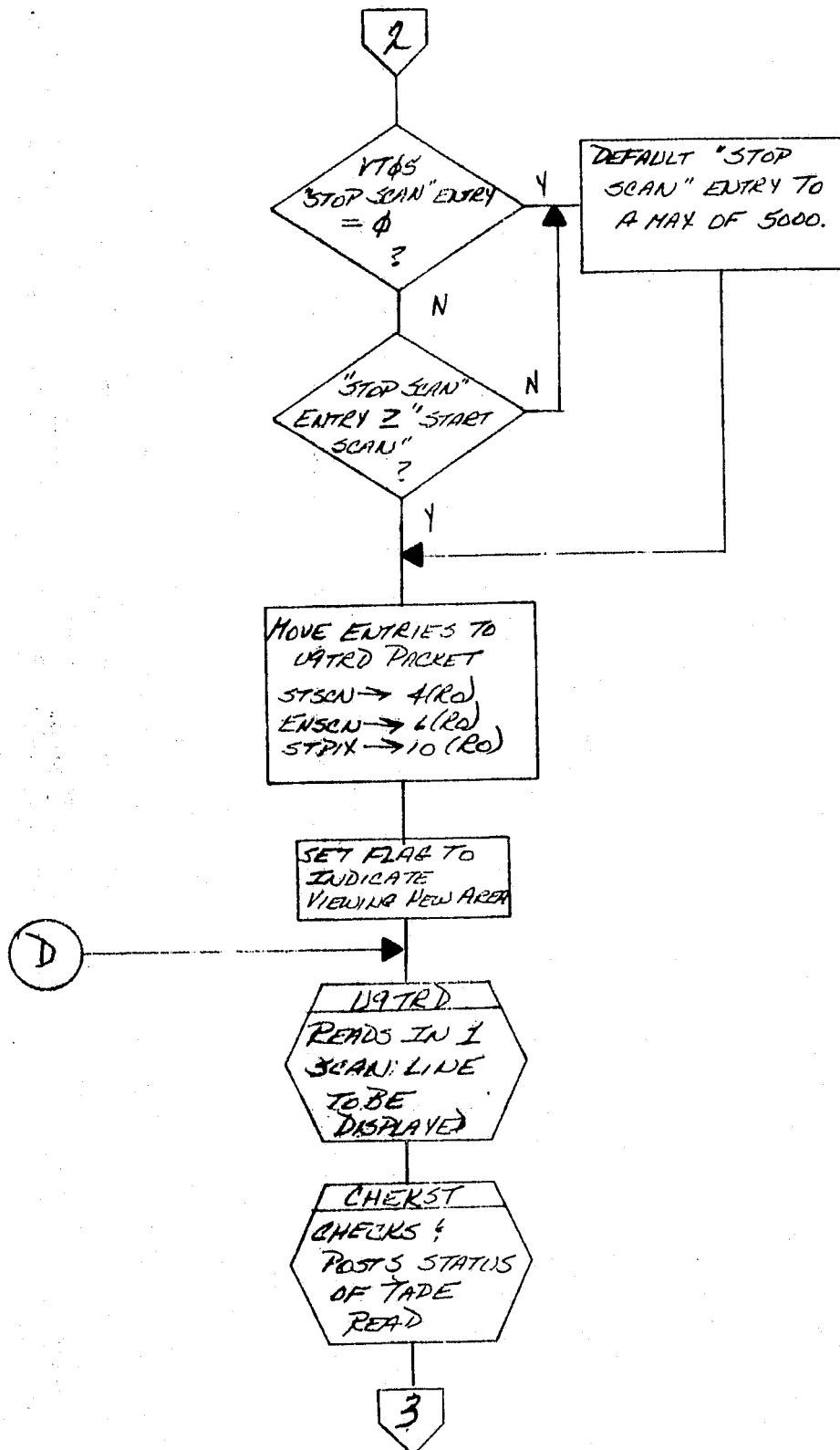


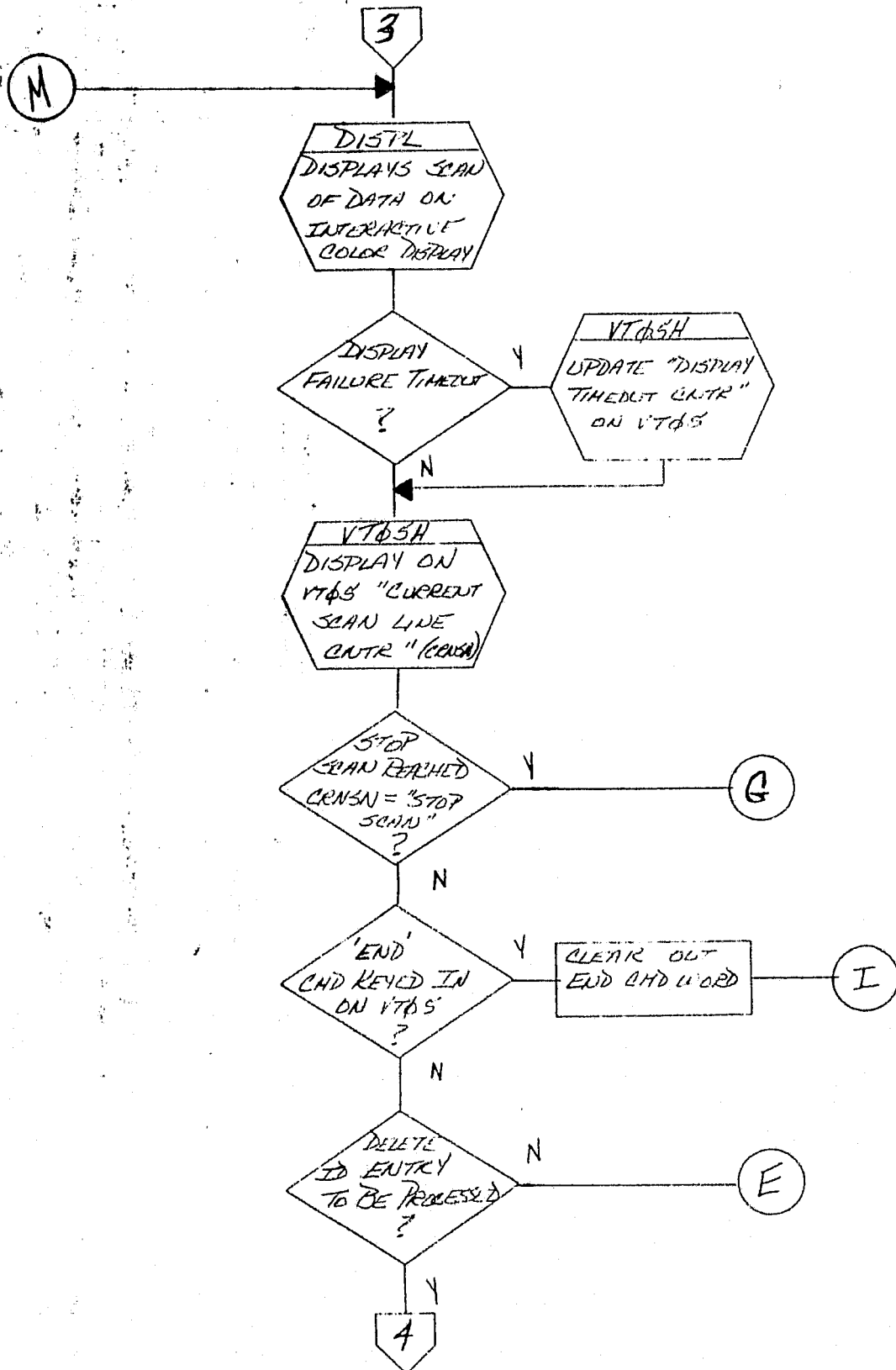


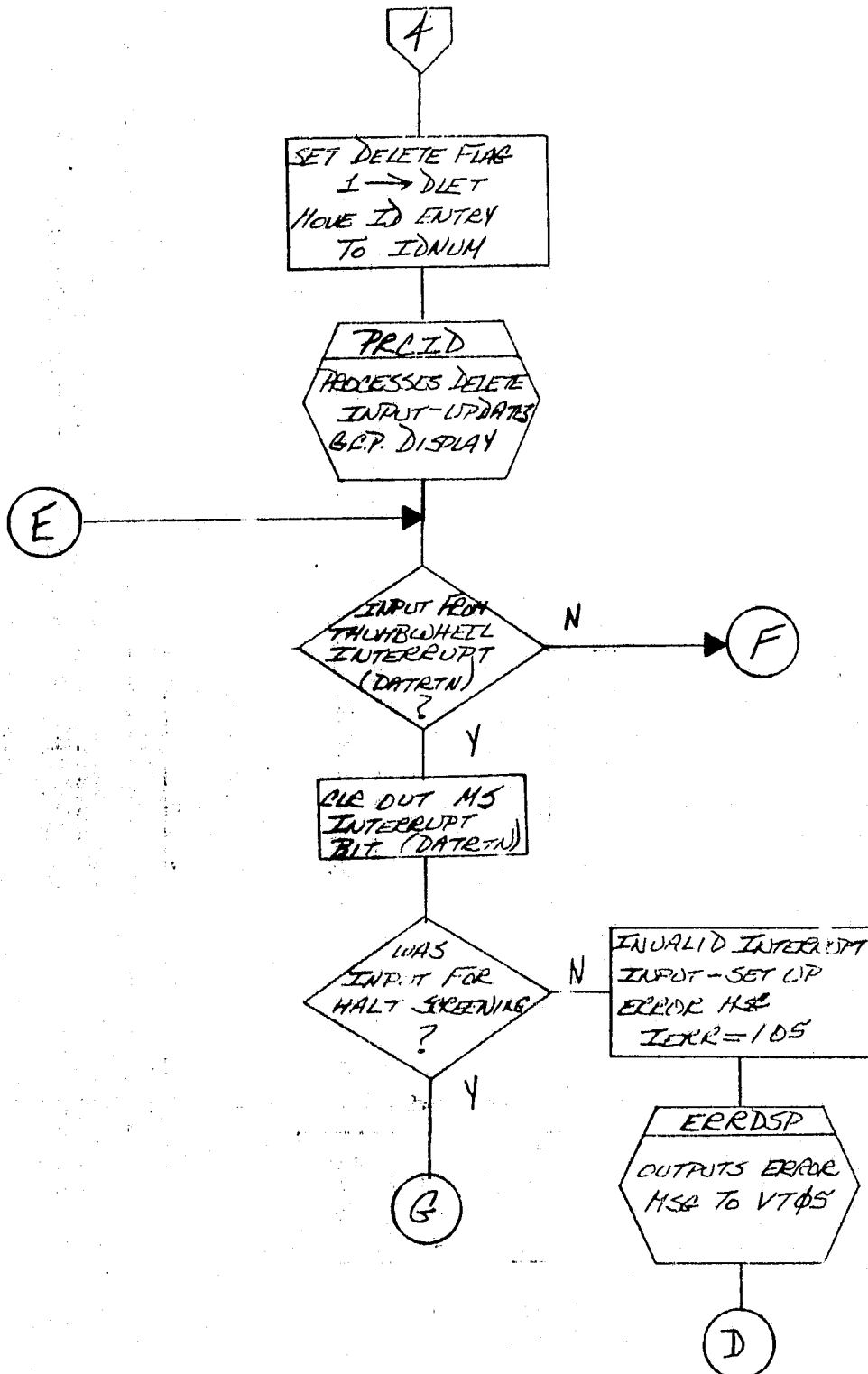


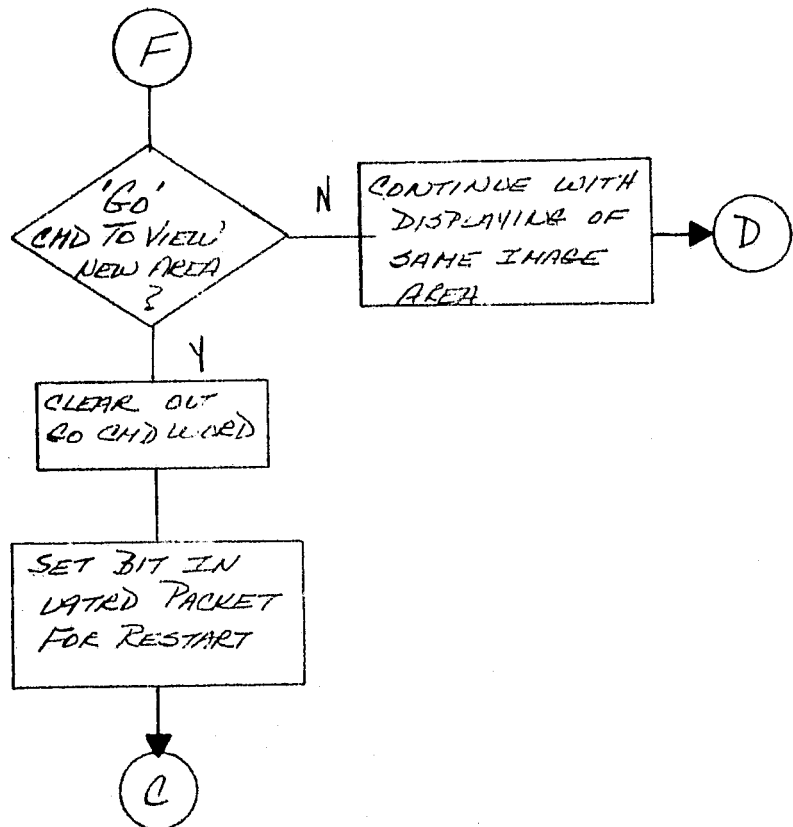


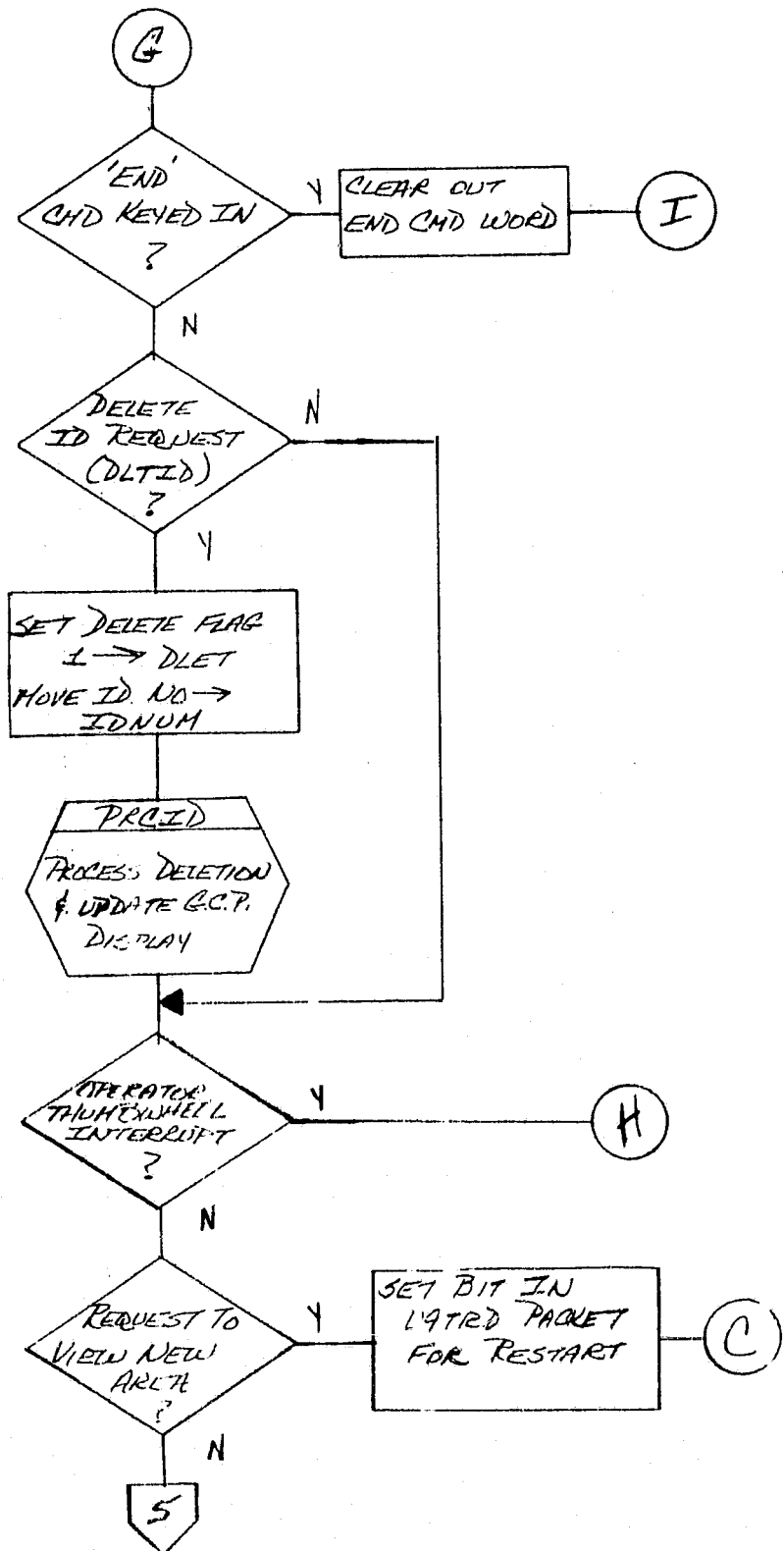


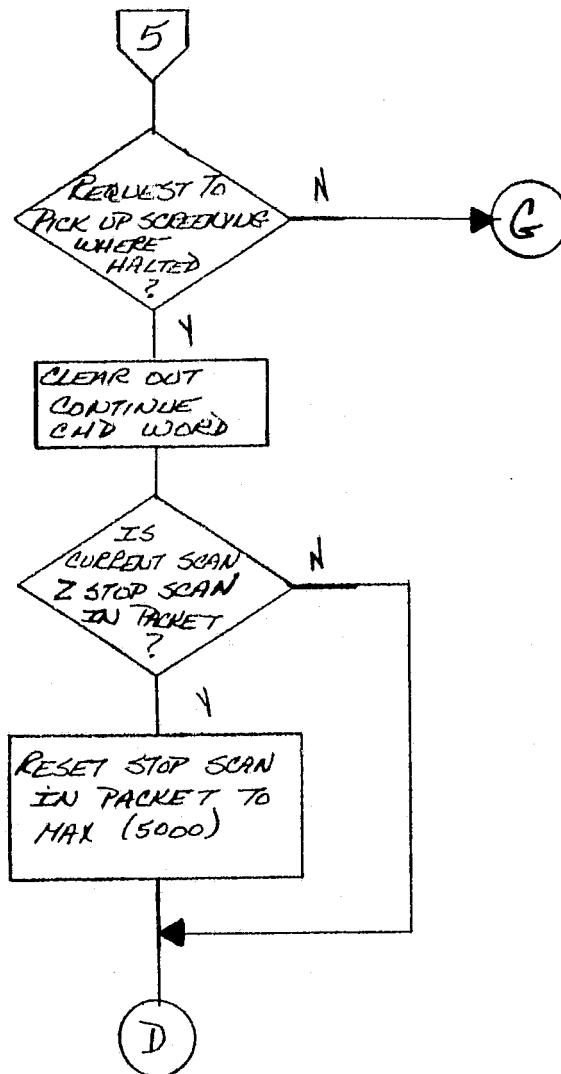


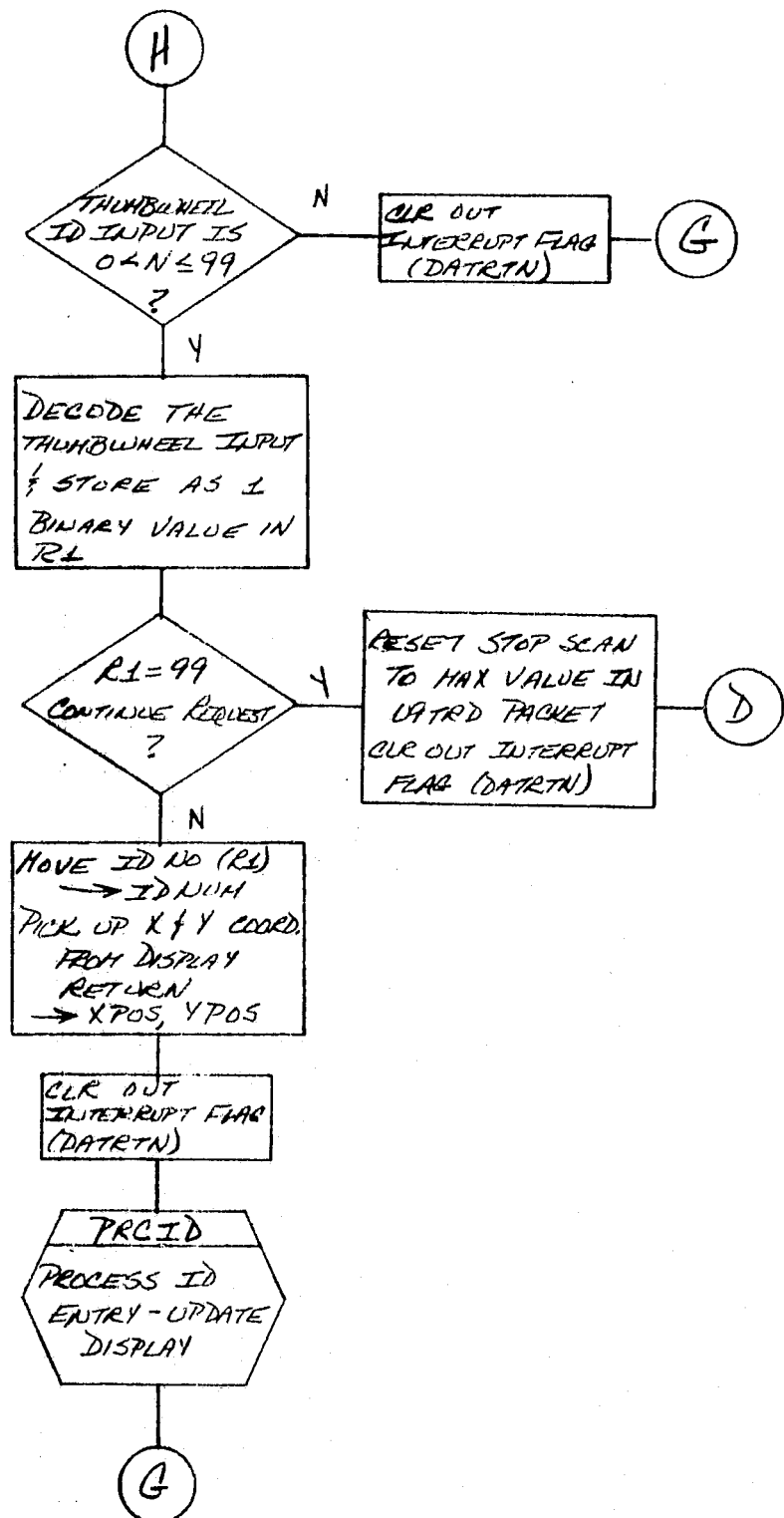


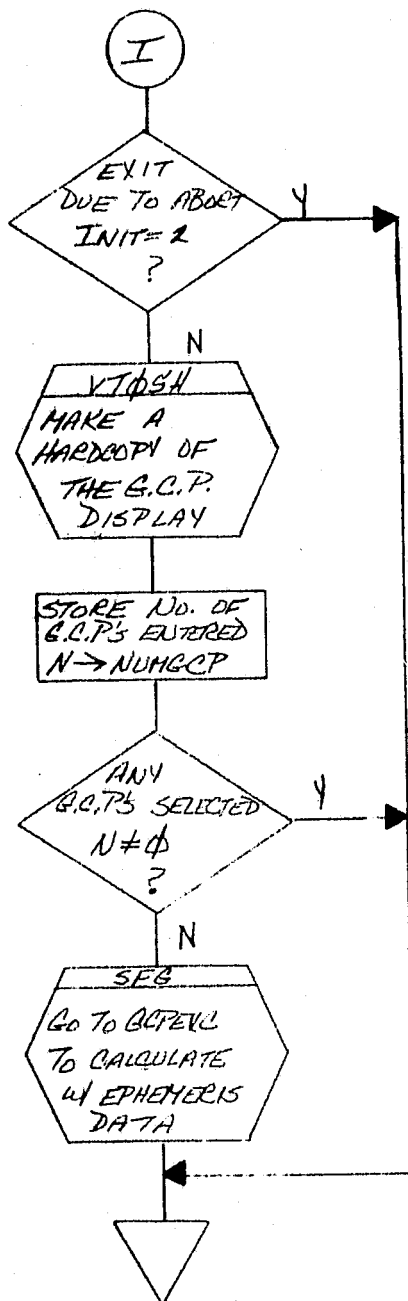




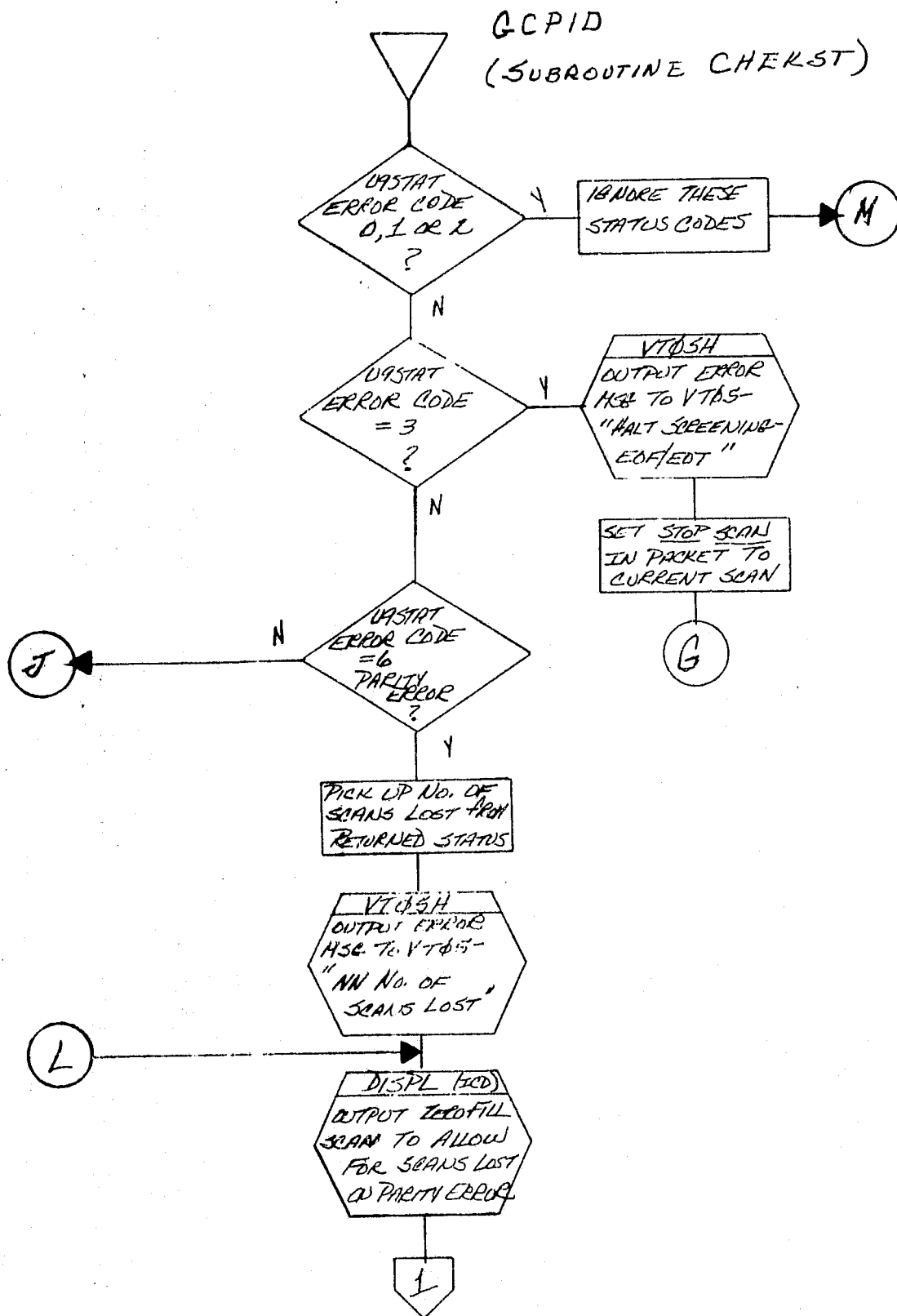


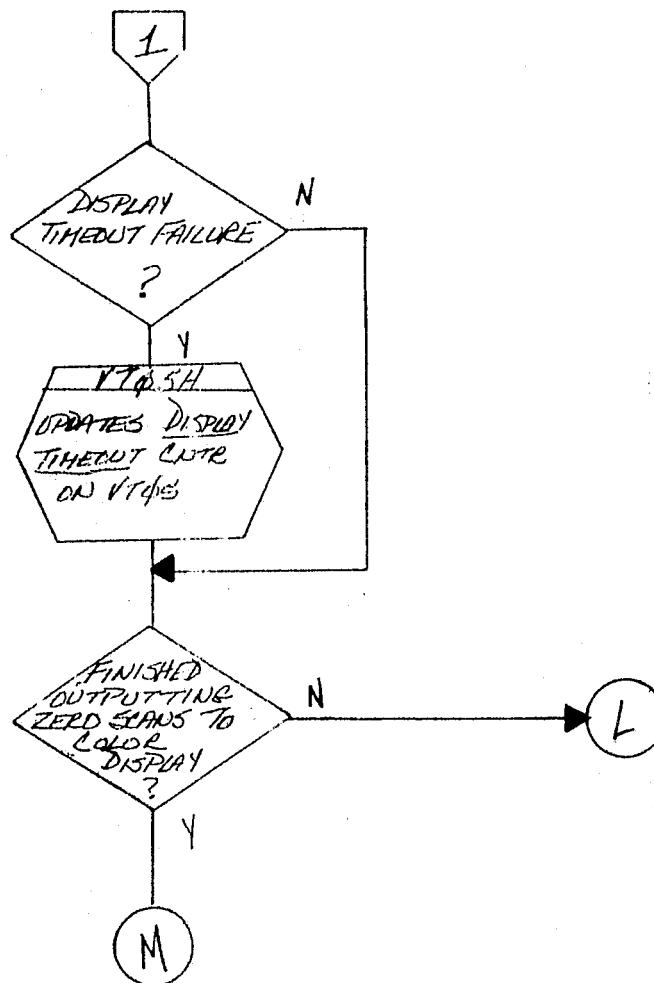


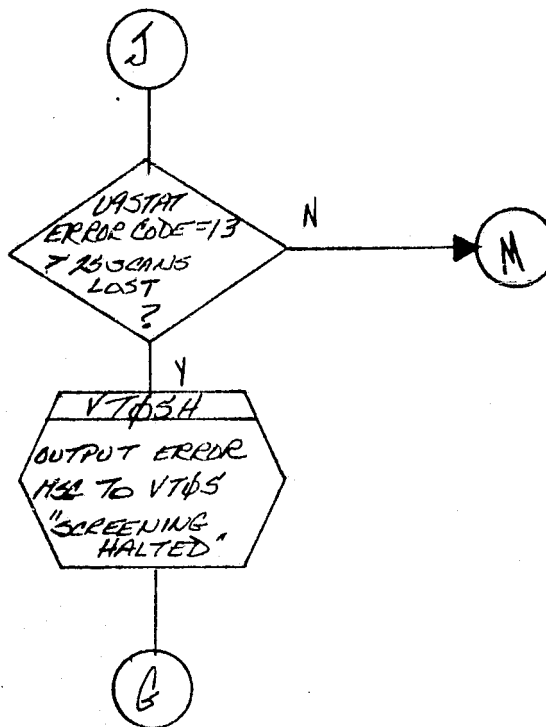


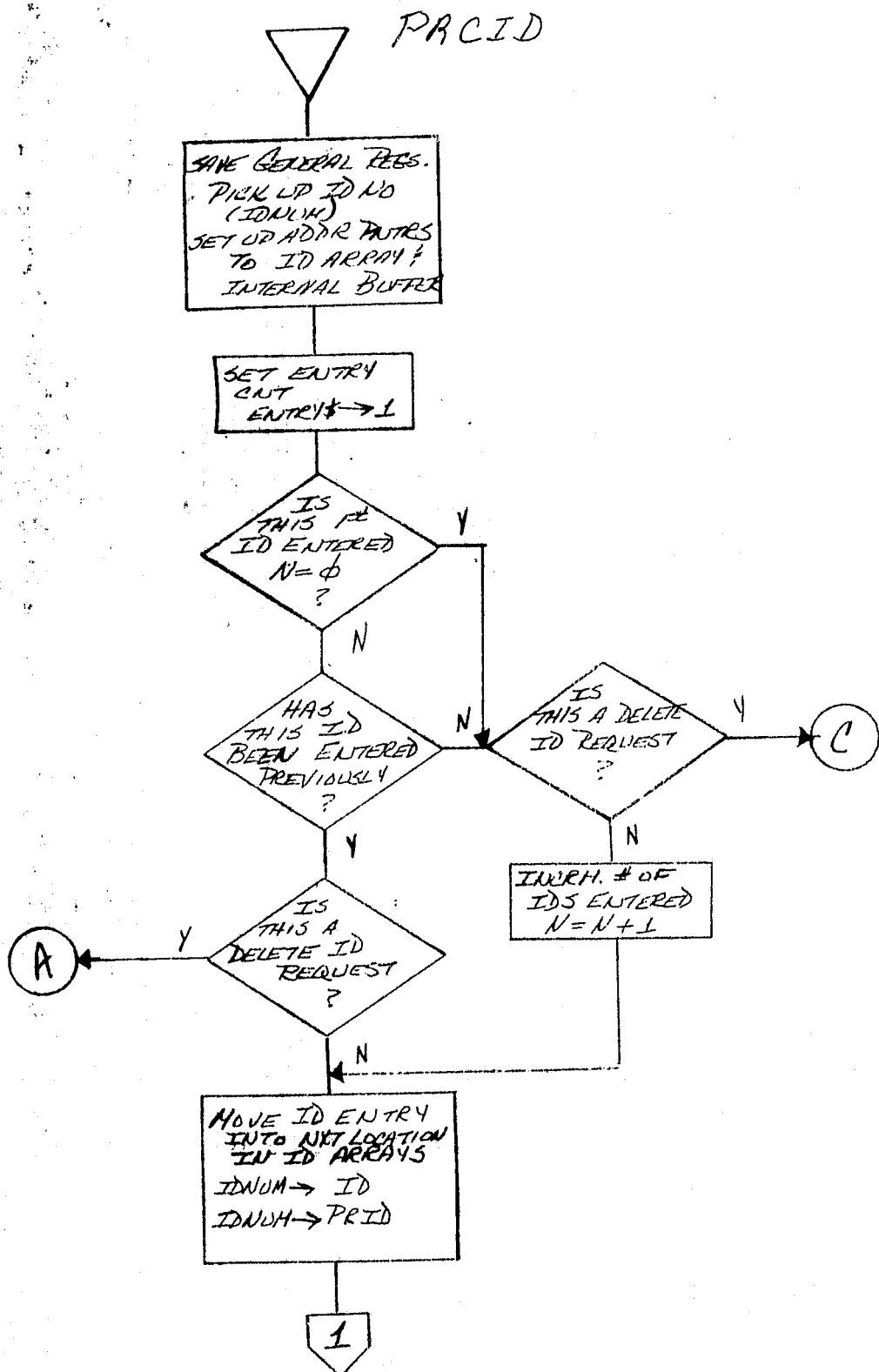


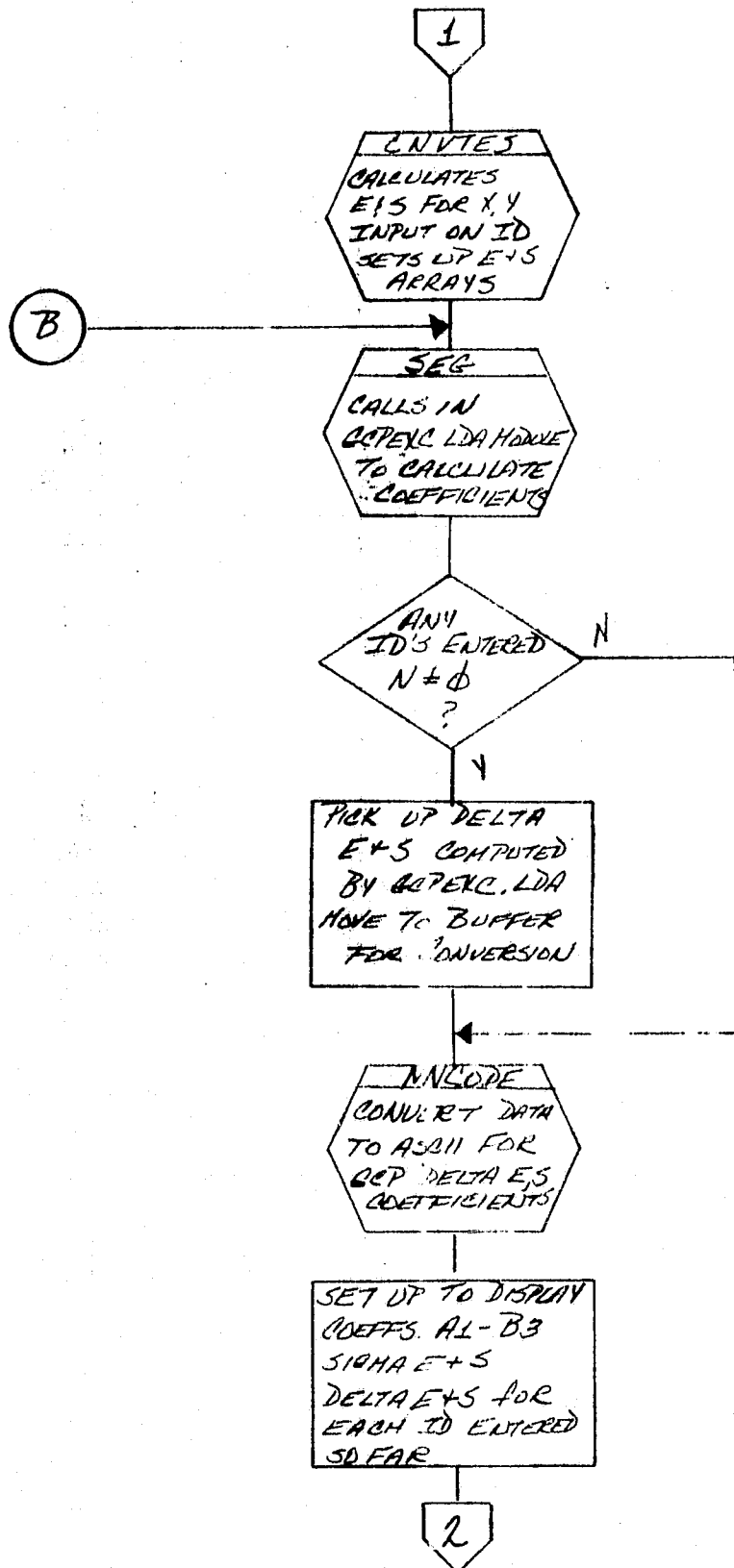
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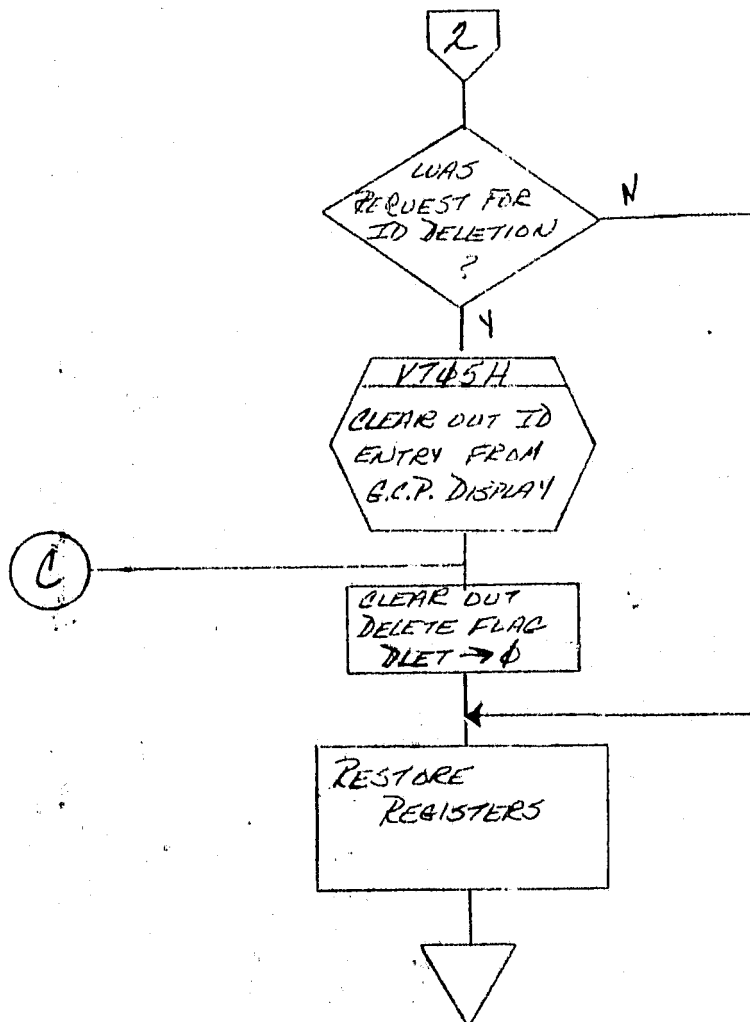


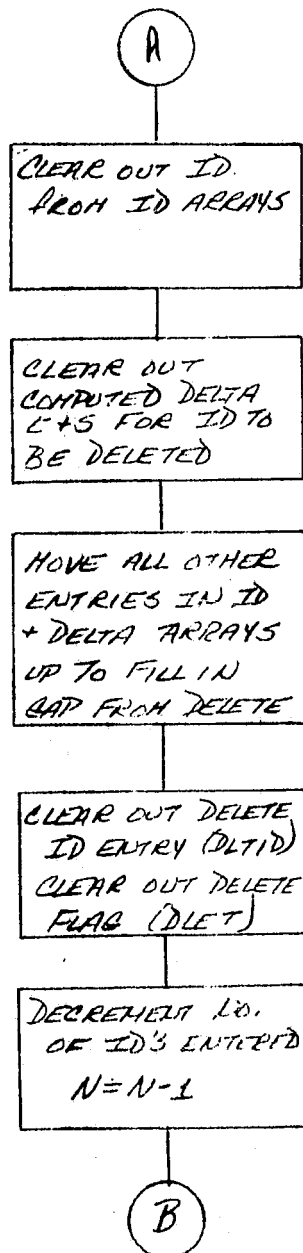


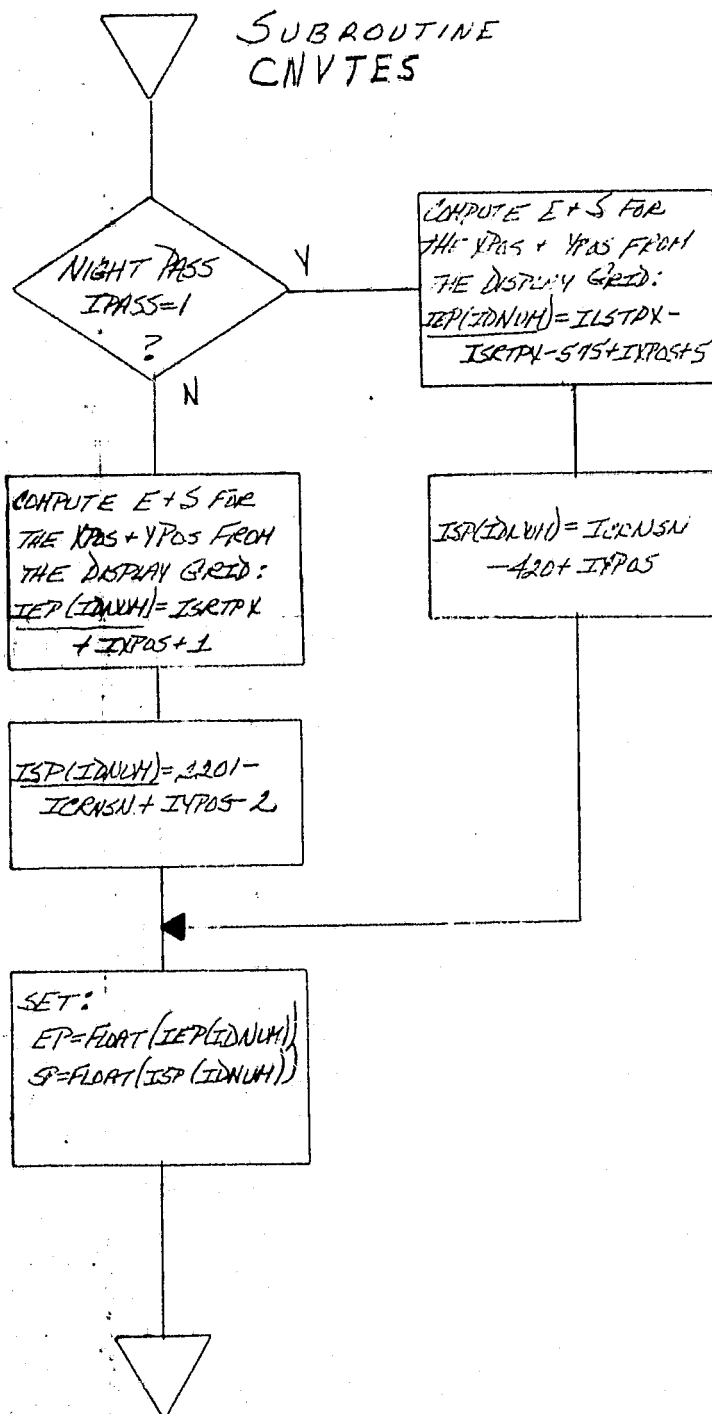


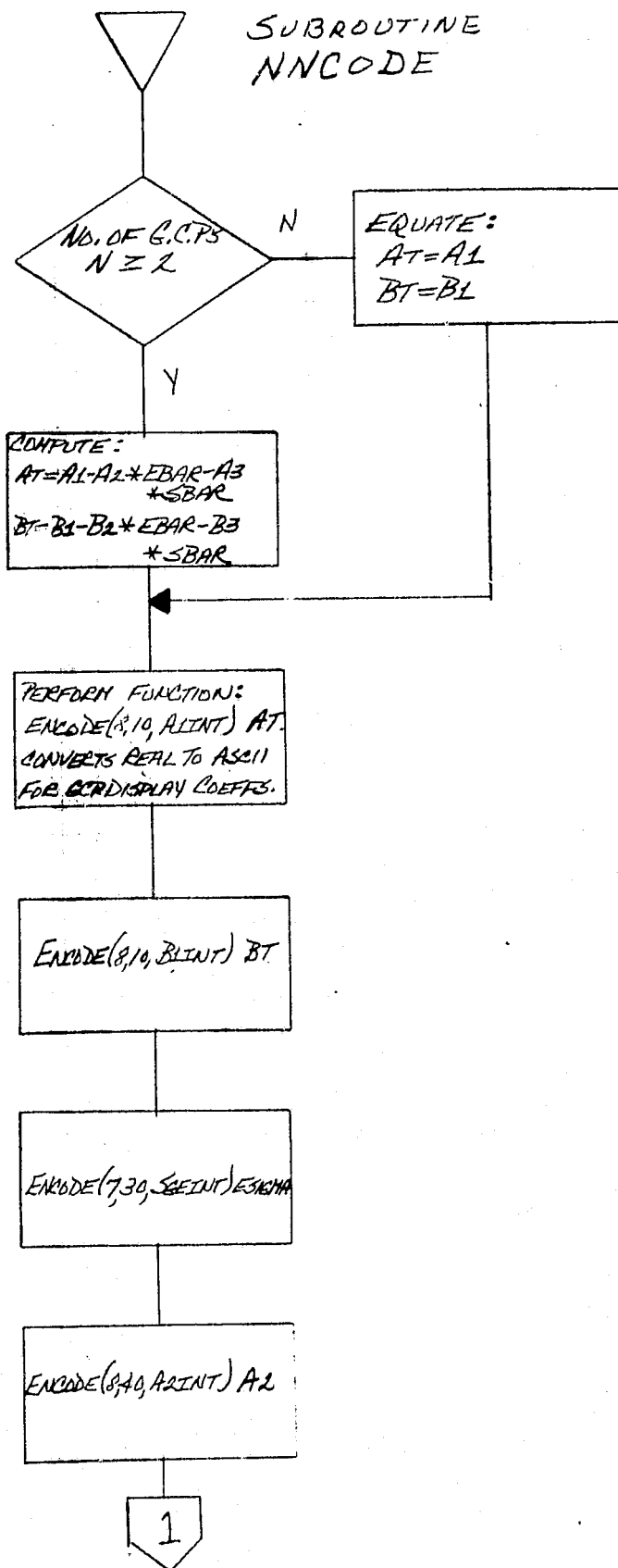


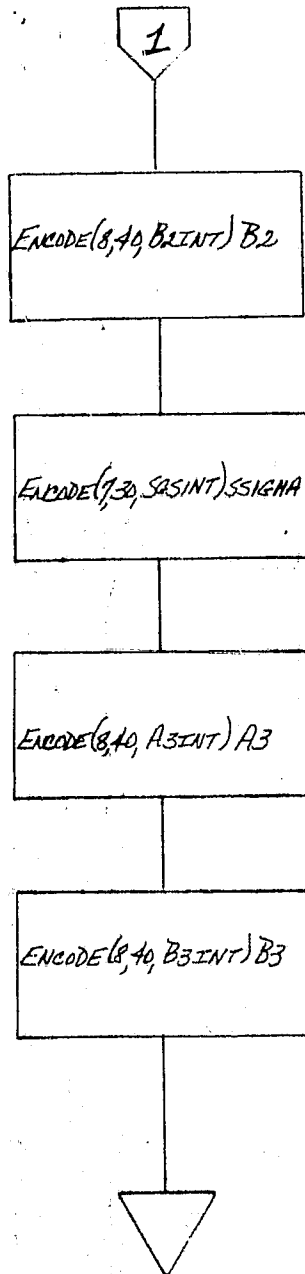


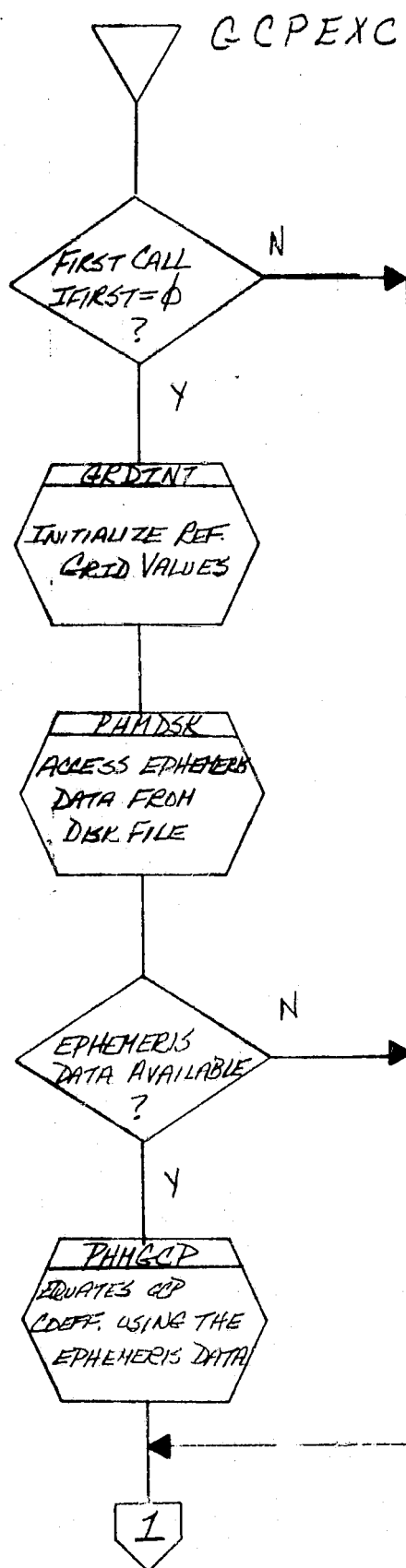




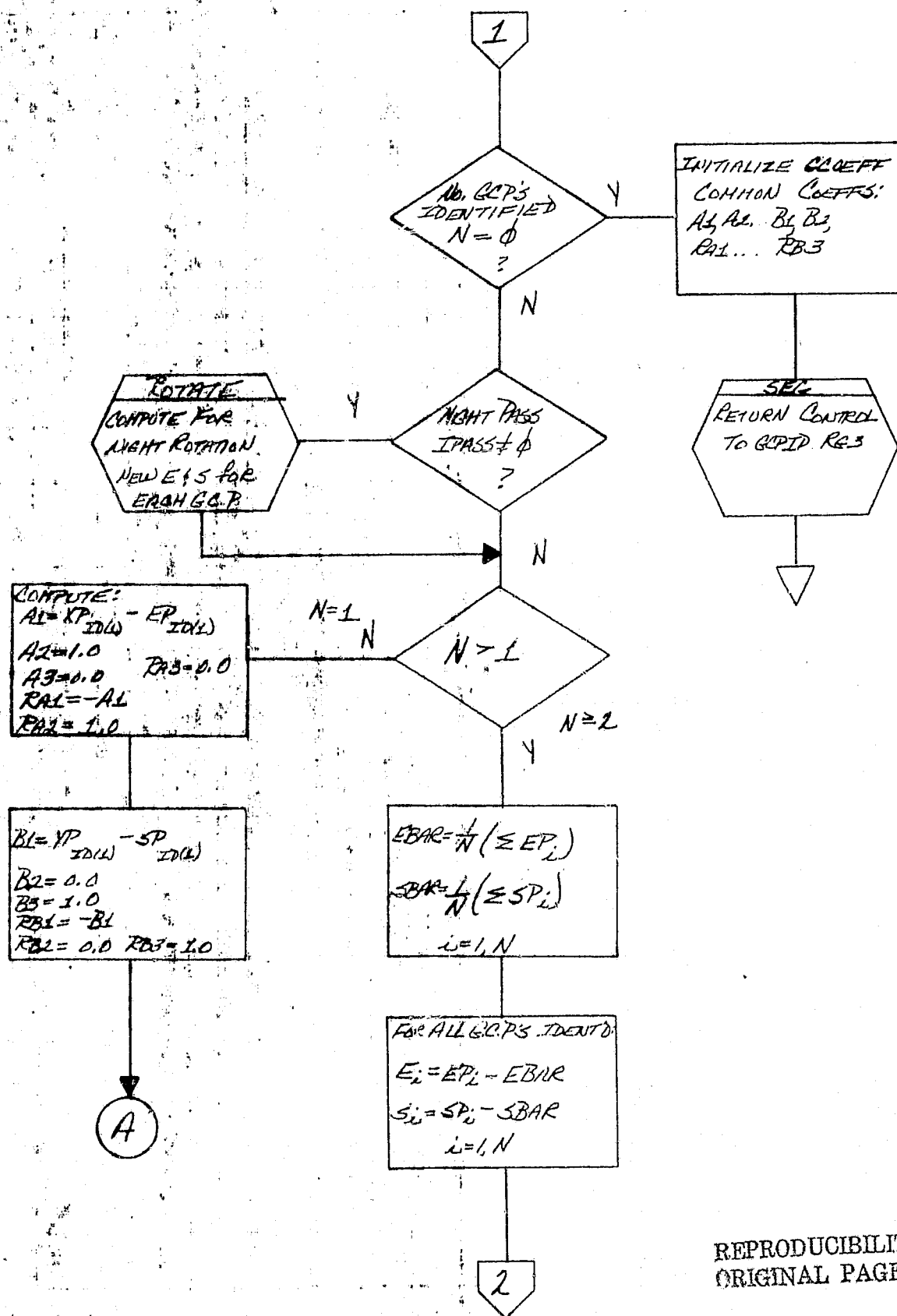




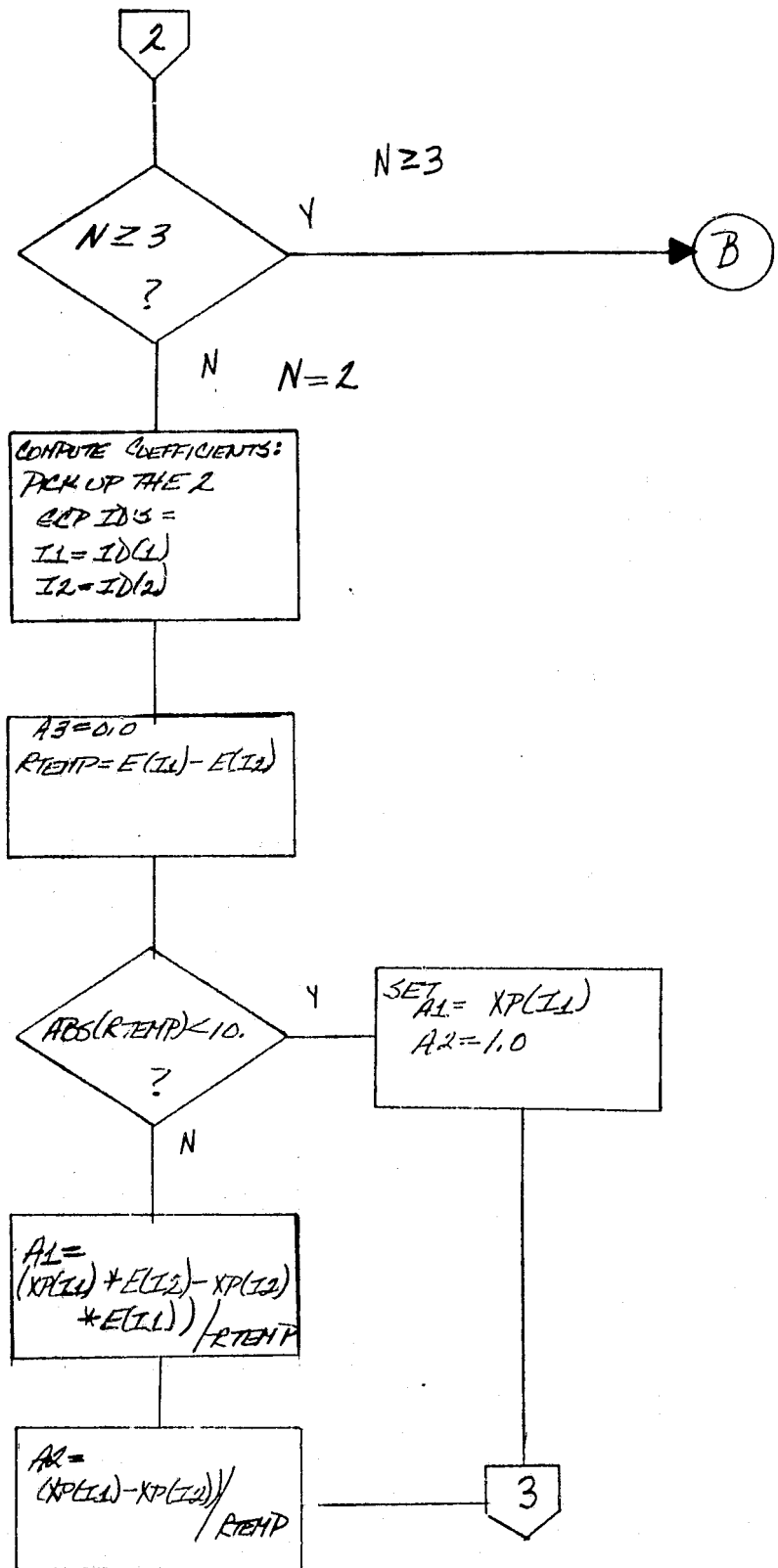




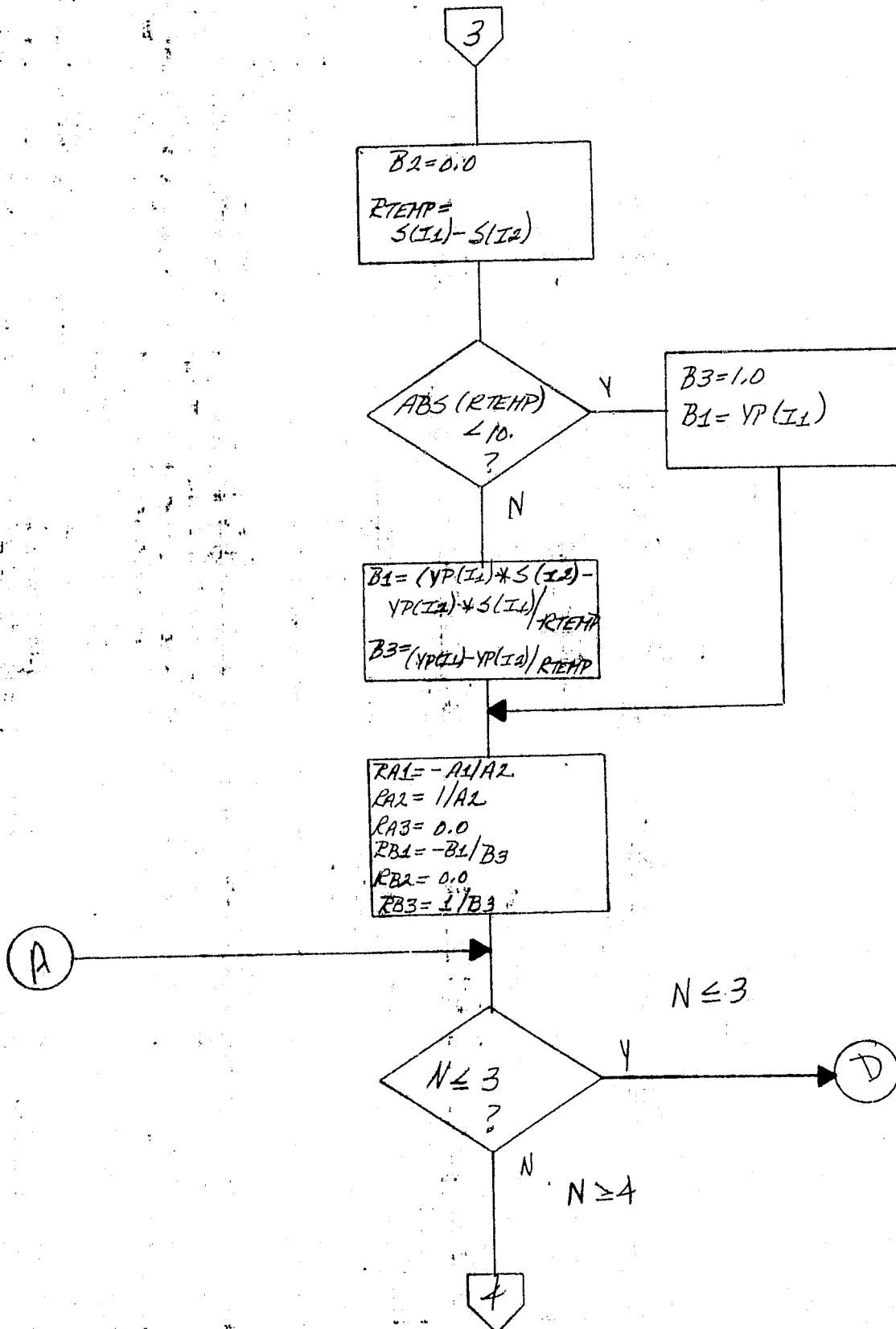
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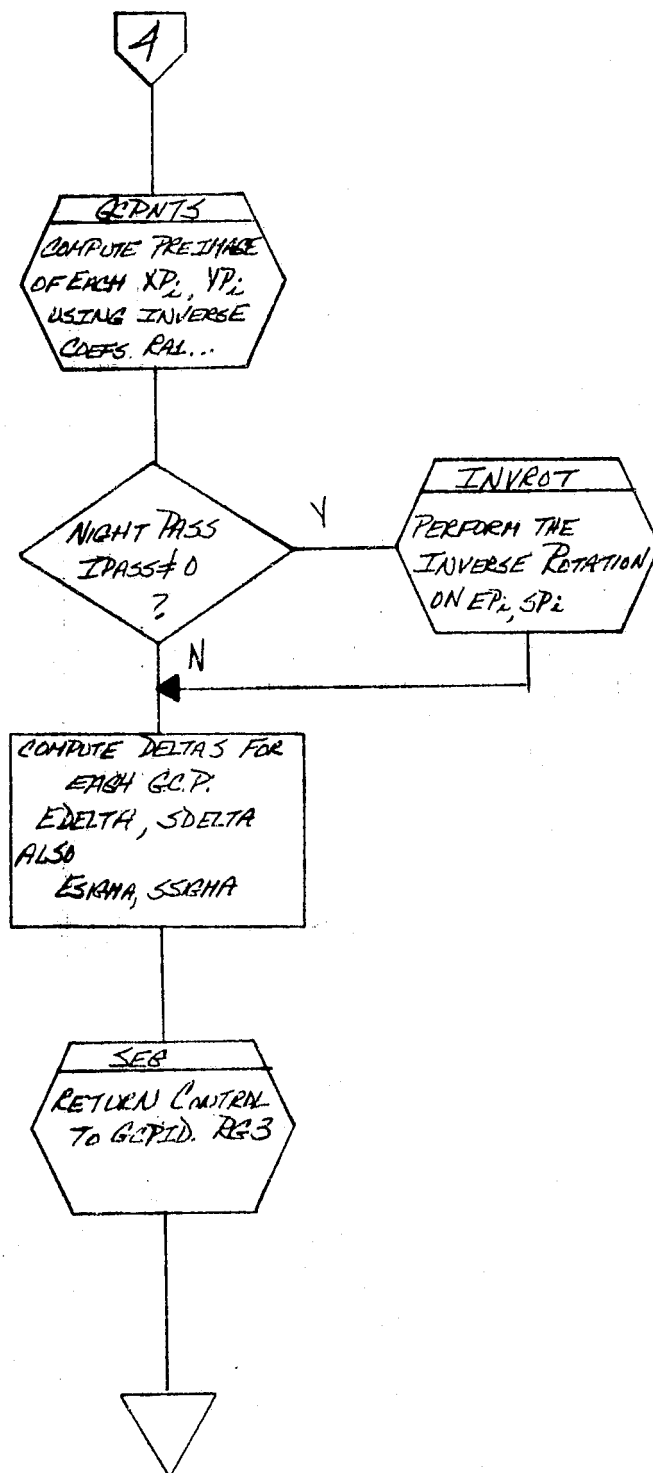


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(B) $N=3$

$$D = \sum_{i=1}^N E_i^2 * Z S_i^2 - \left(\sum_{i=1}^N E_i S_i \right)^2$$

$i=1, N$

COMPUTE:

$$A1 = \sum_{i=1}^N X P_i$$

$$A2 = \frac{1}{D} \left[\left(\sum_{i=1}^N E_i^2 \right) \left(\sum_{i=1}^N X P_i E_i \right) - \left(\sum_{i=1}^N E_i S_i \right) \left(\sum_{i=1}^N X P_i S_i \right) \right]$$

$$A3 = \frac{1}{D} \left[\left(\sum_{i=1}^N E_i^2 \right) \left(\sum_{i=1}^N X P_i S_i \right) - \left(\sum_{i=1}^N E_i S_i \right) \left(\sum_{i=1}^N X P_i E_i \right) \right]$$

$$B1 = \sum_{i=1}^N Y P_i$$

$$B2 = \frac{1}{D} \left[\left(\sum_{i=1}^N S_i^2 \right) \left(\sum_{i=1}^N Y P_i E_i \right) - \left(\sum_{i=1}^N E_i S_i \right) \left(\sum_{i=1}^N Y P_i S_i \right) \right]$$

$$B3 = \frac{1}{D} \left[\left(\sum_{i=1}^N E_i^2 \right) \left(\sum_{i=1}^N Y P_i S_i \right) - \left(\sum_{i=1}^N E_i S_i \right) \left(\sum_{i=1}^N Y P_i E_i \right) \right]$$

$$RTEMP = A2 * B3 - A3 * B2$$

$$RA1 = (A3 * B1 - A1 * B3) / RTEMP$$

$$RA2 = B3 / RTEMP$$

$$RA3 = -A3 / RTEMP$$

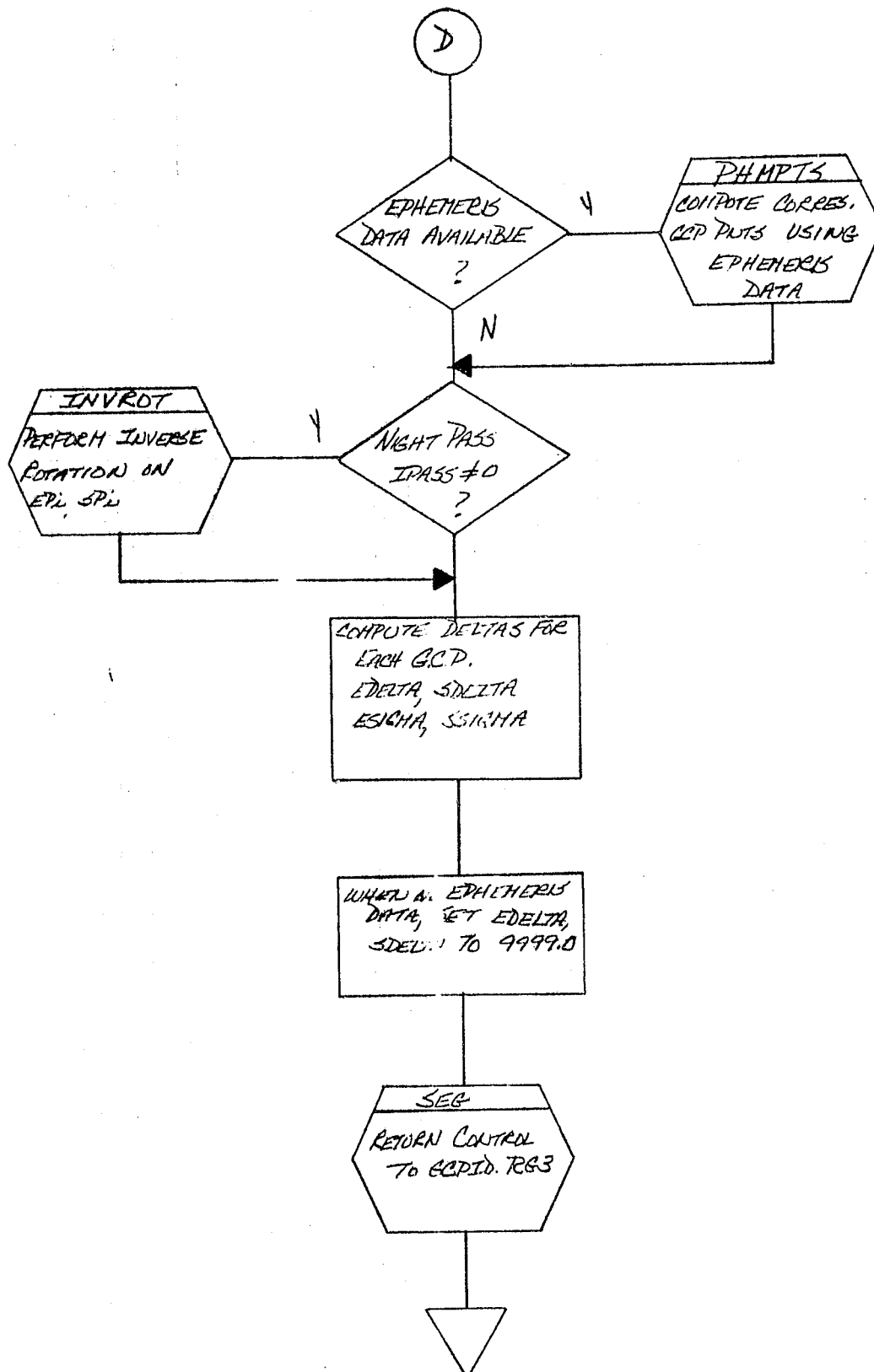
$$RB1 = (A1 * B2 - A2 * B1) / RTEMP$$

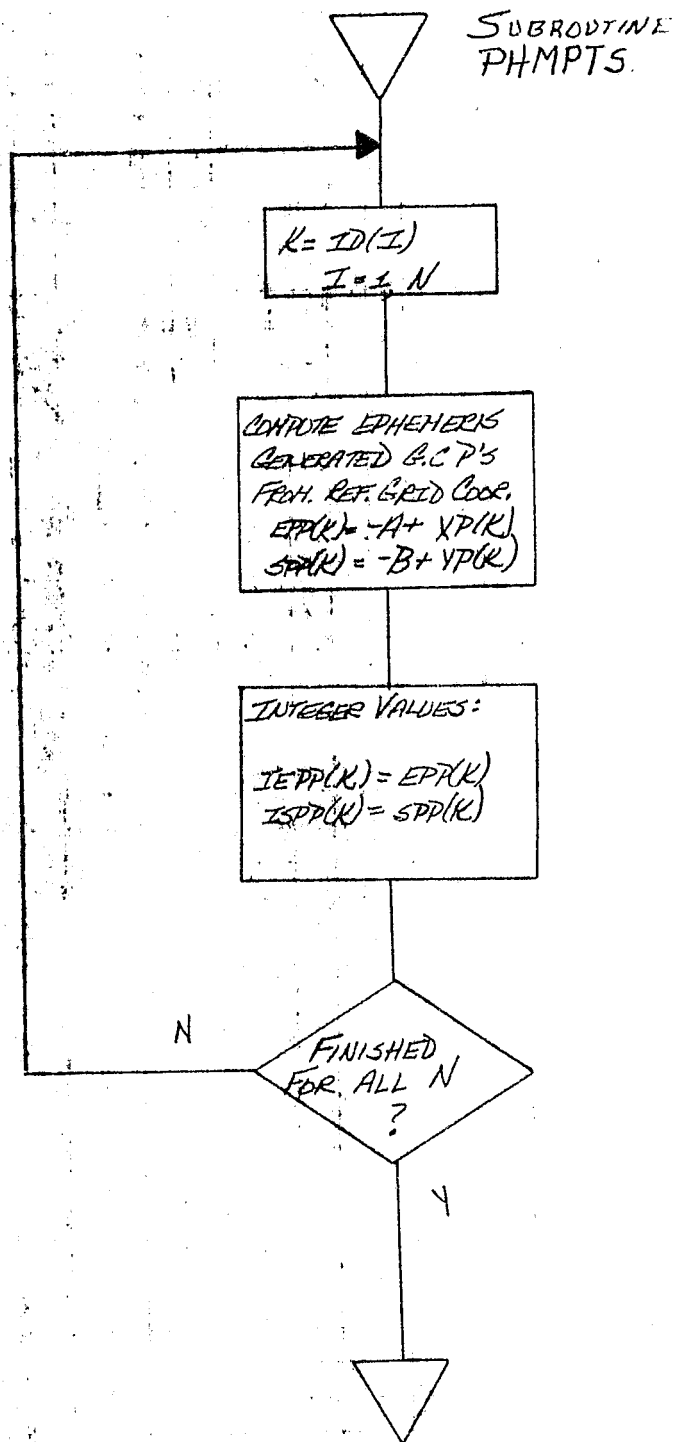
$$RB2 = -B2 / RTEMP$$

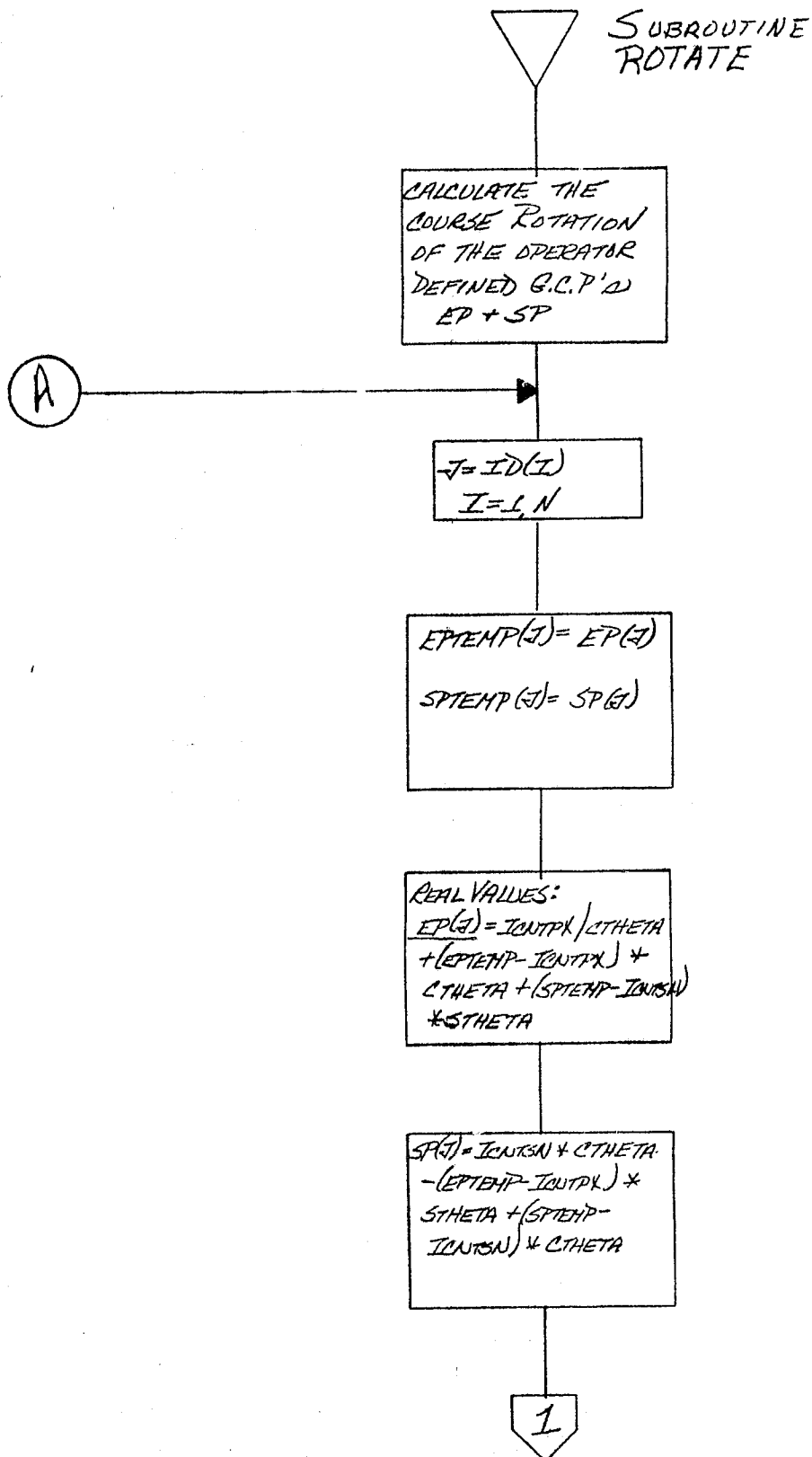
$$RB3 = A2 / RTEMP$$

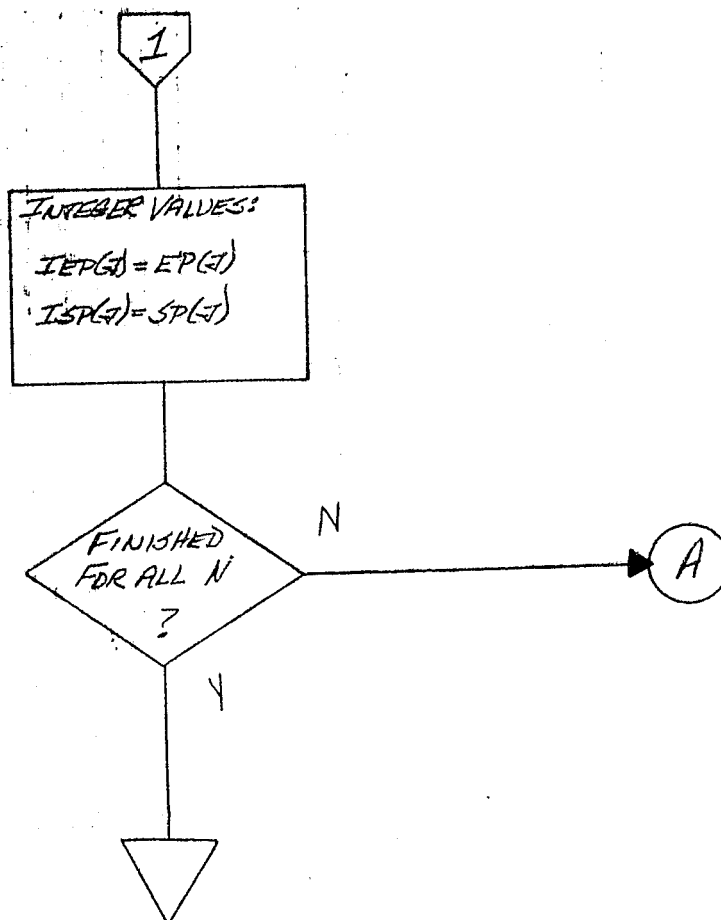
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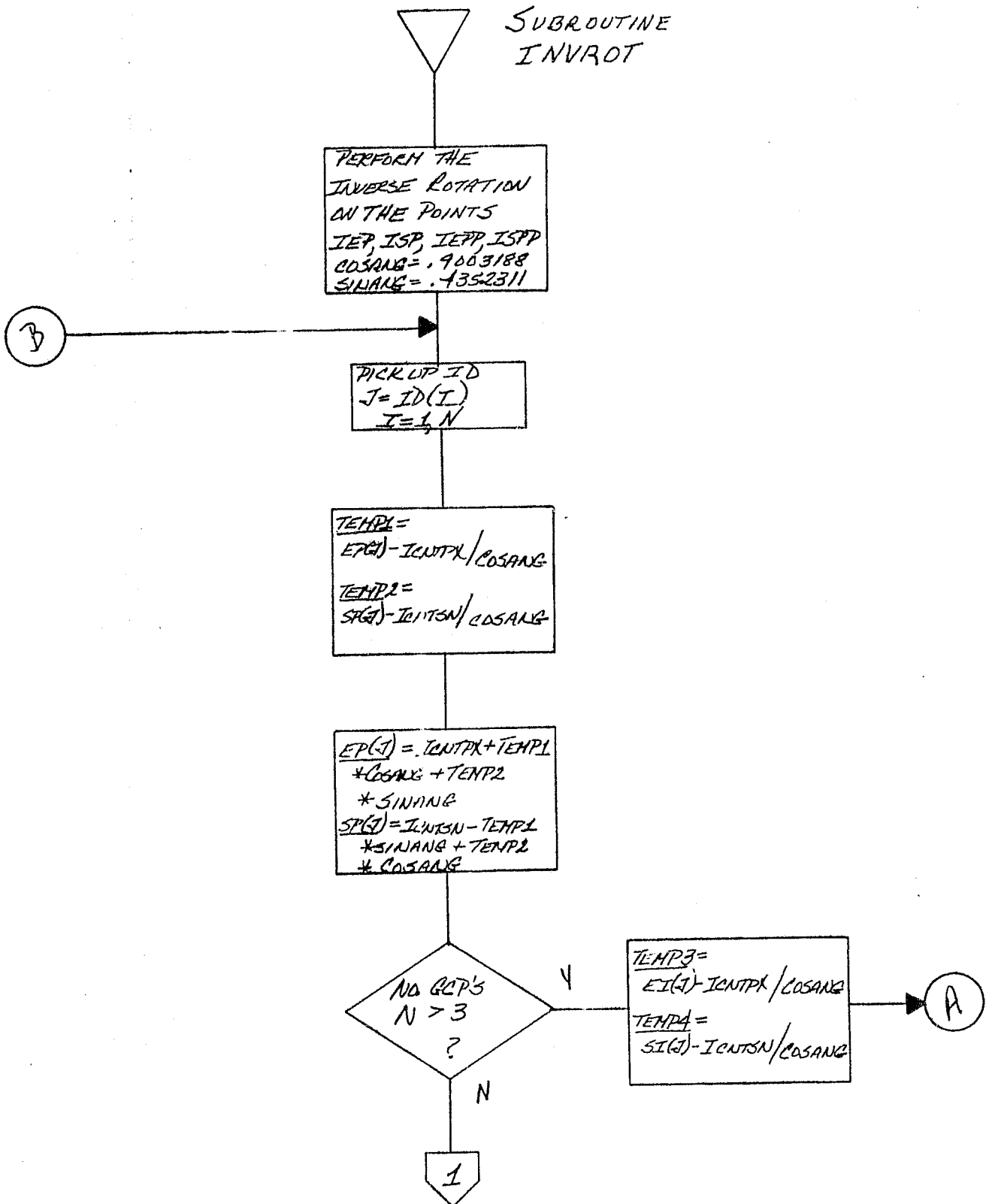


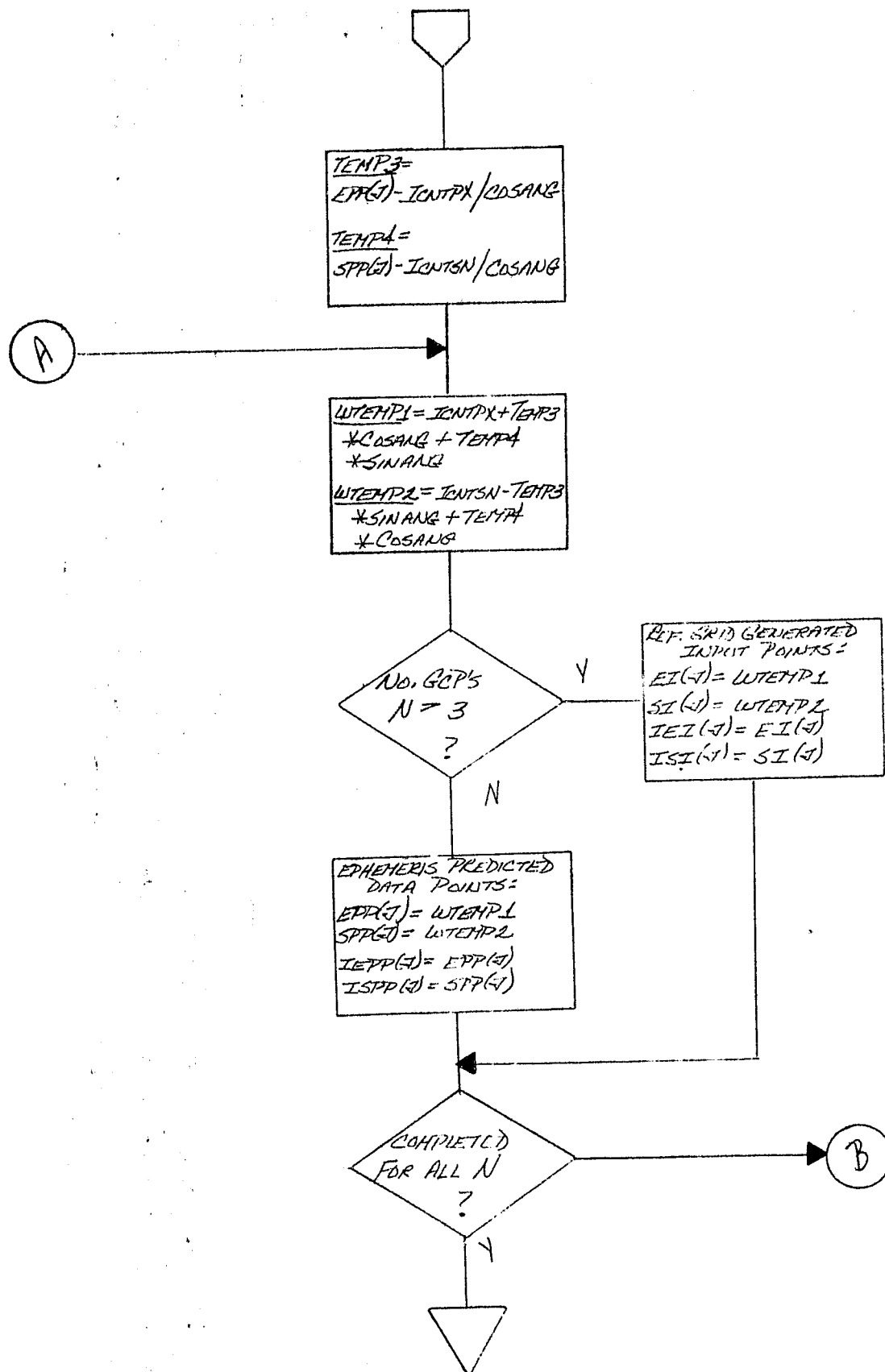


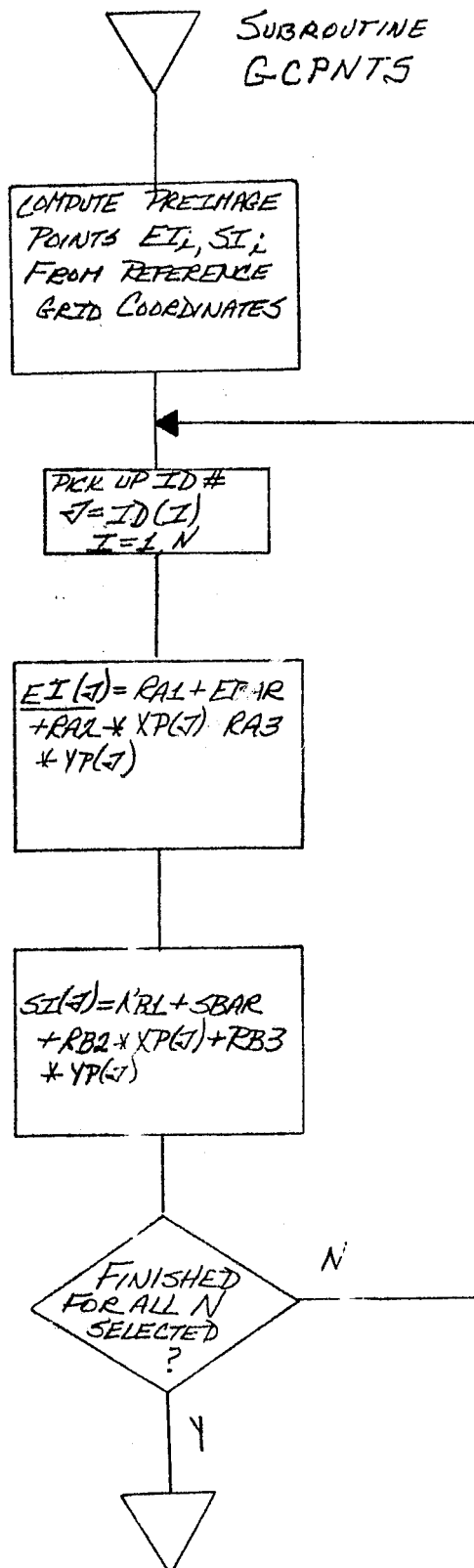


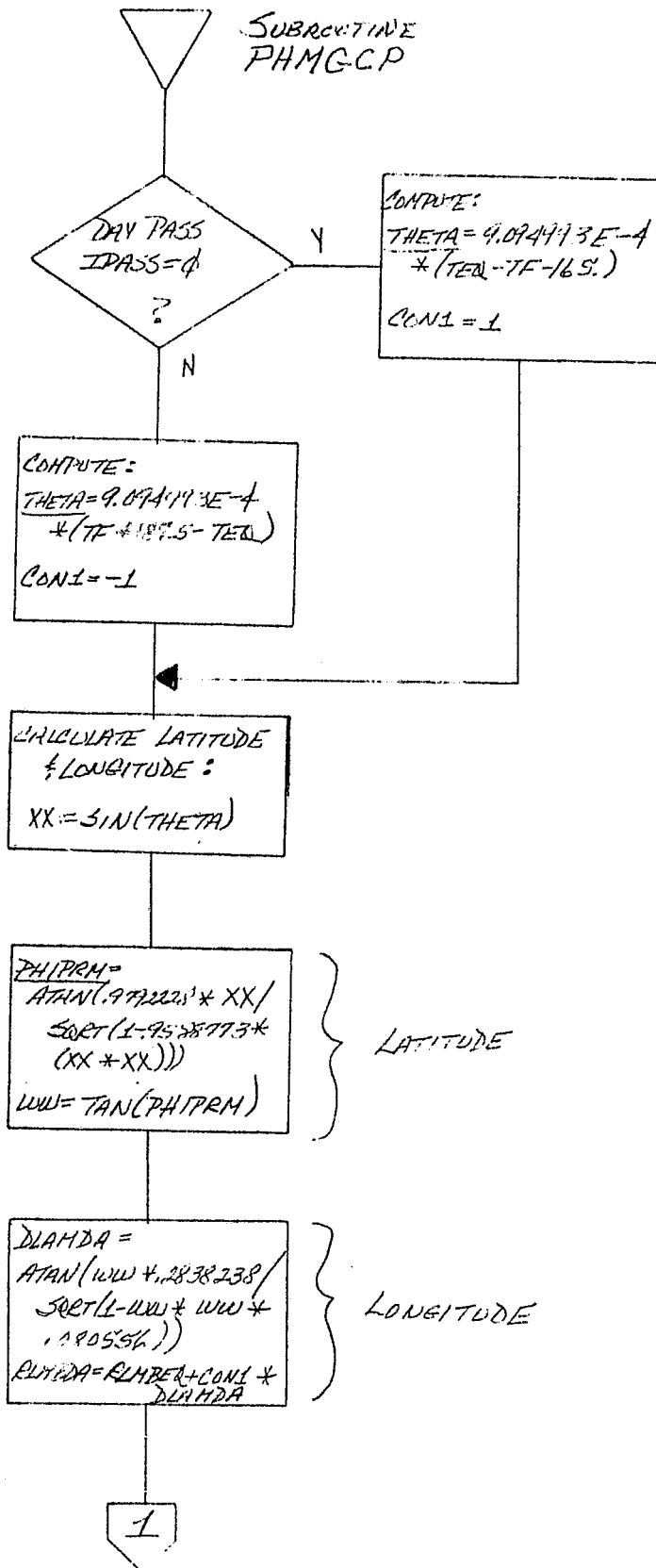


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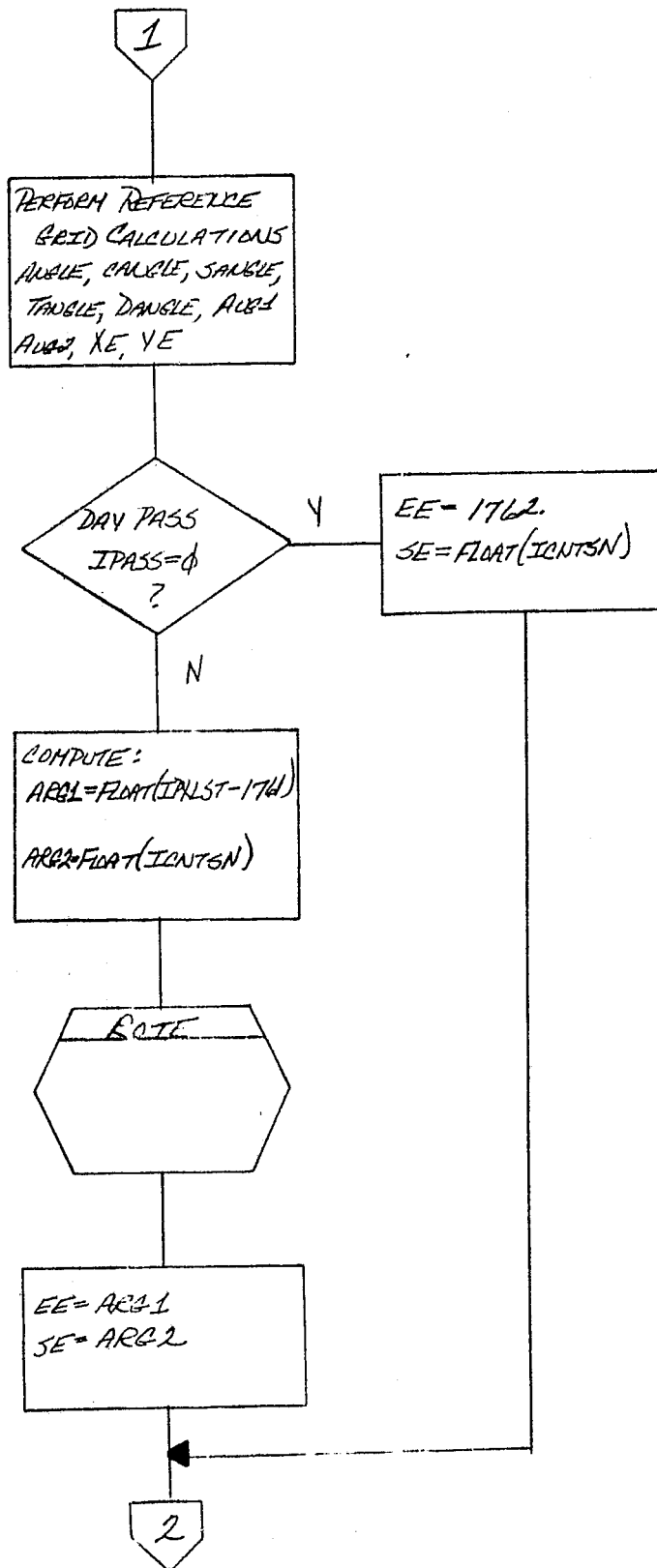


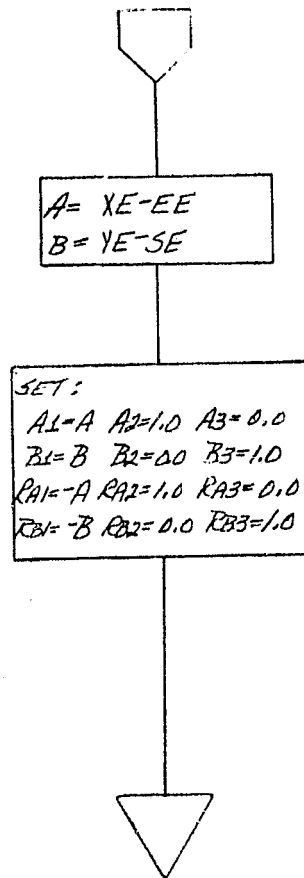


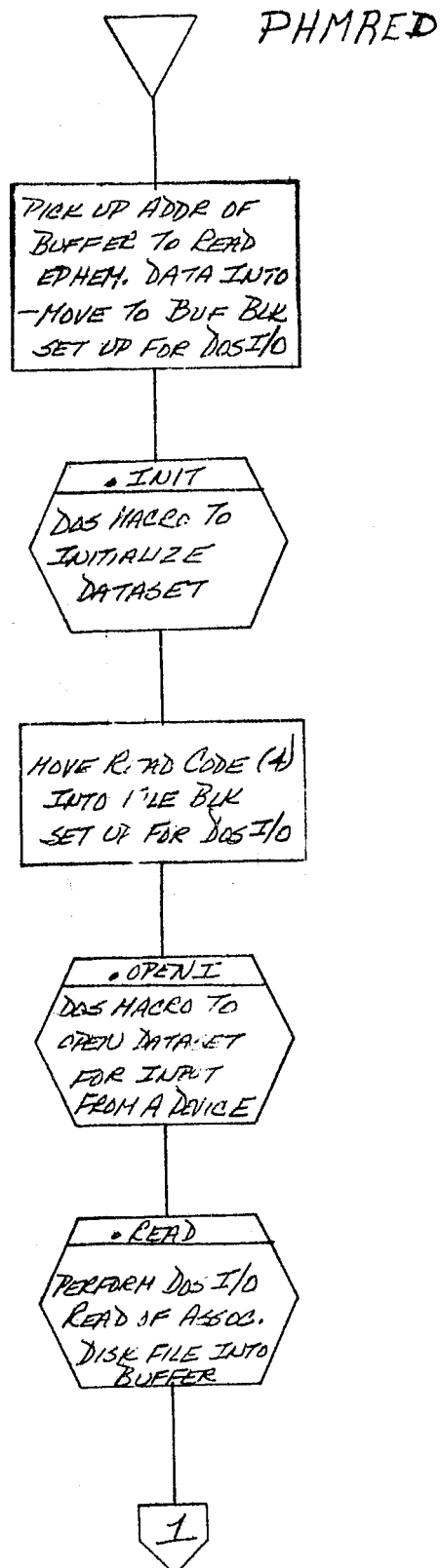


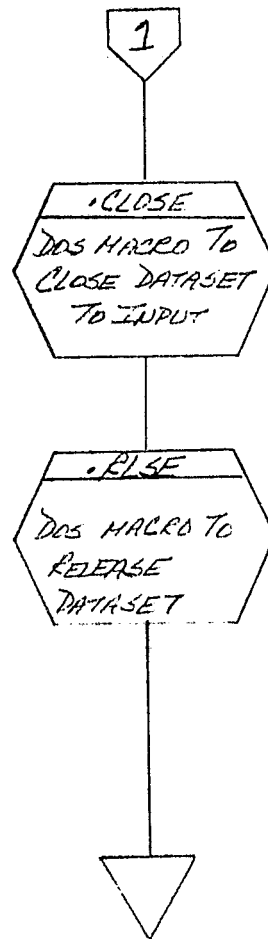


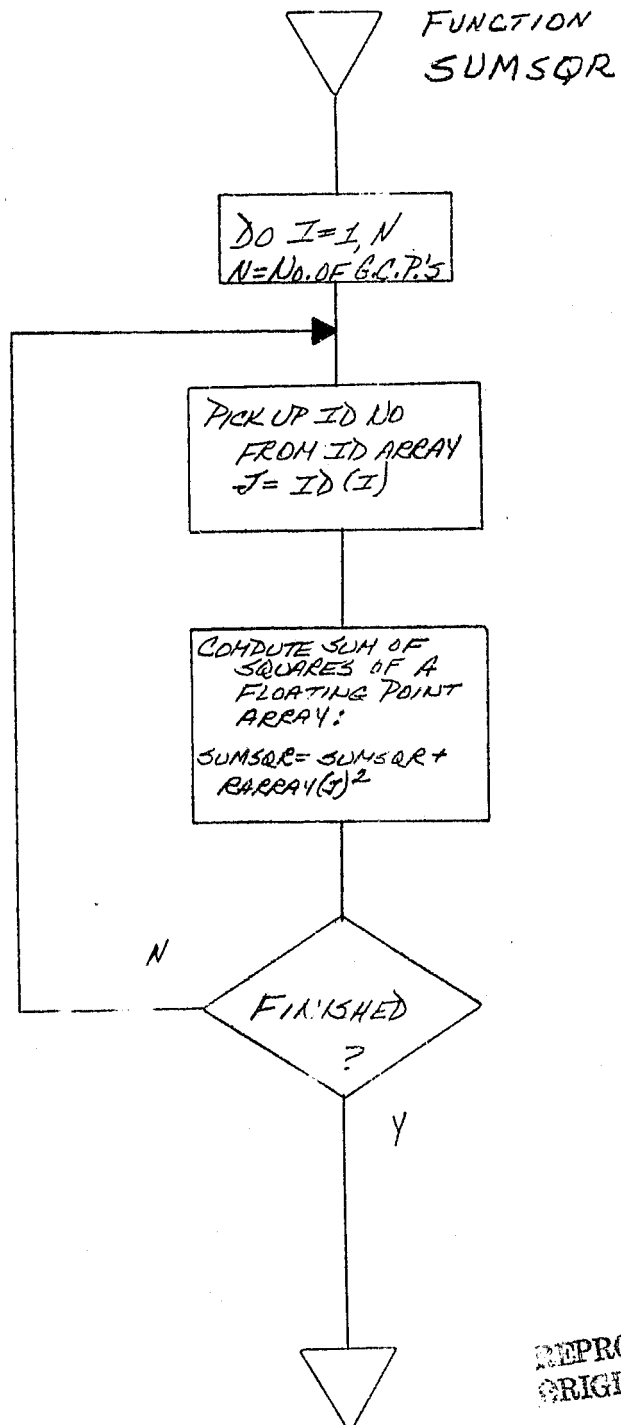
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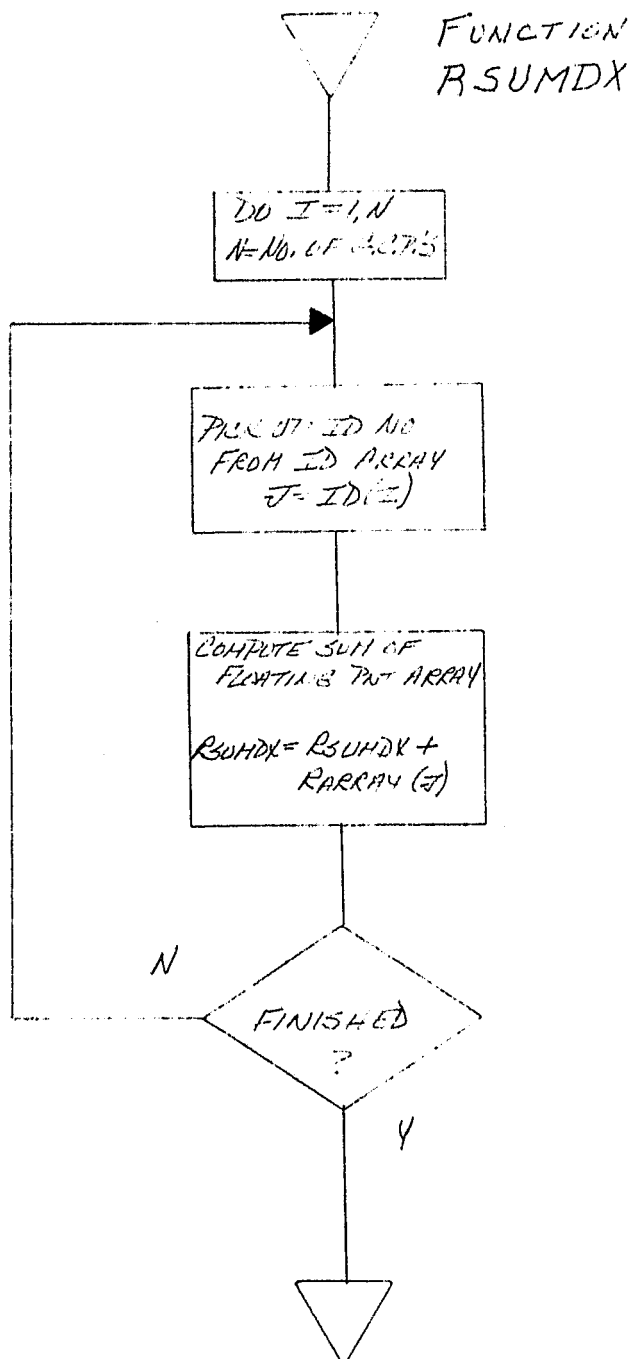


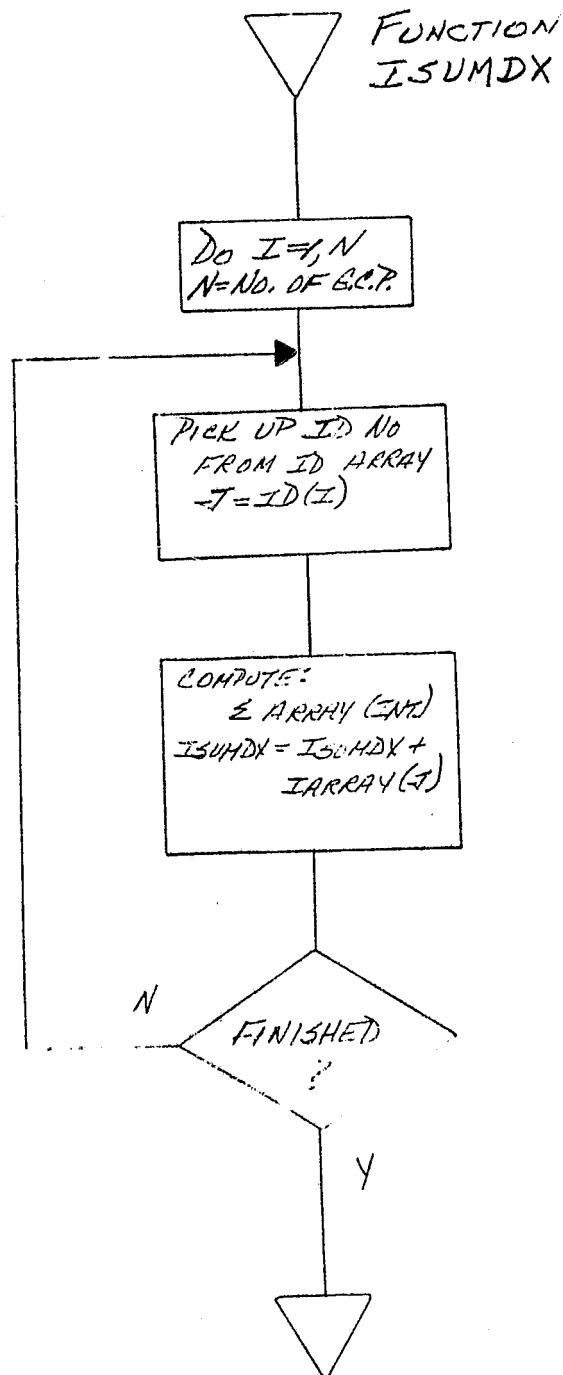


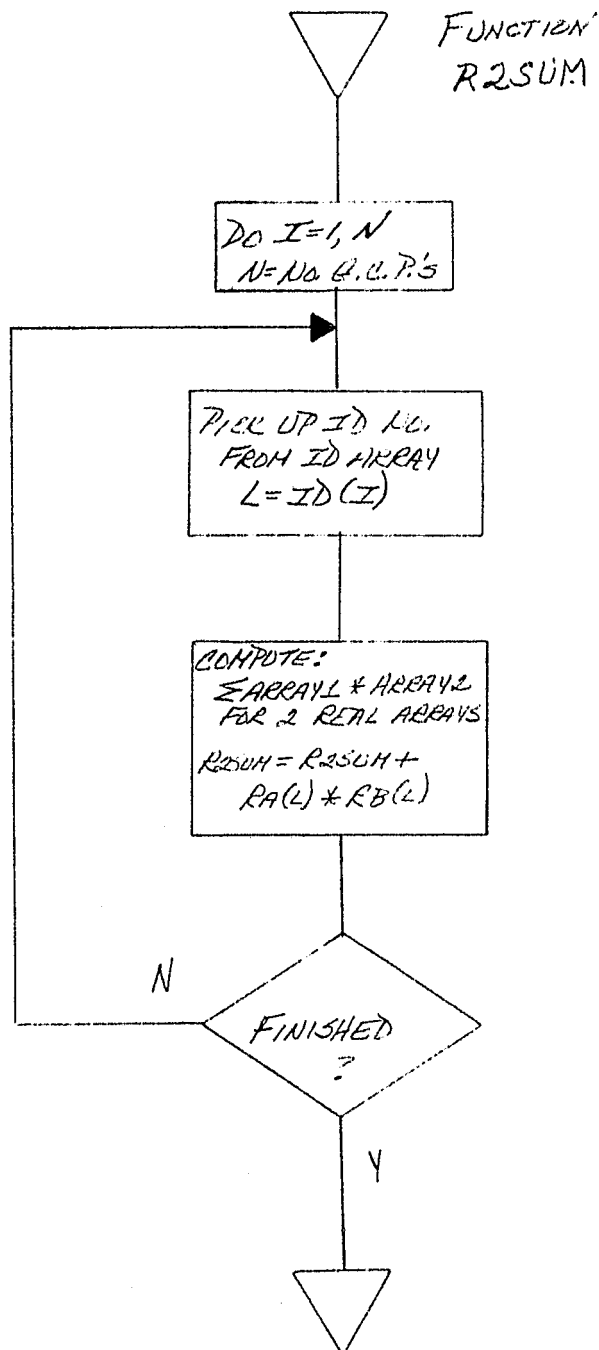


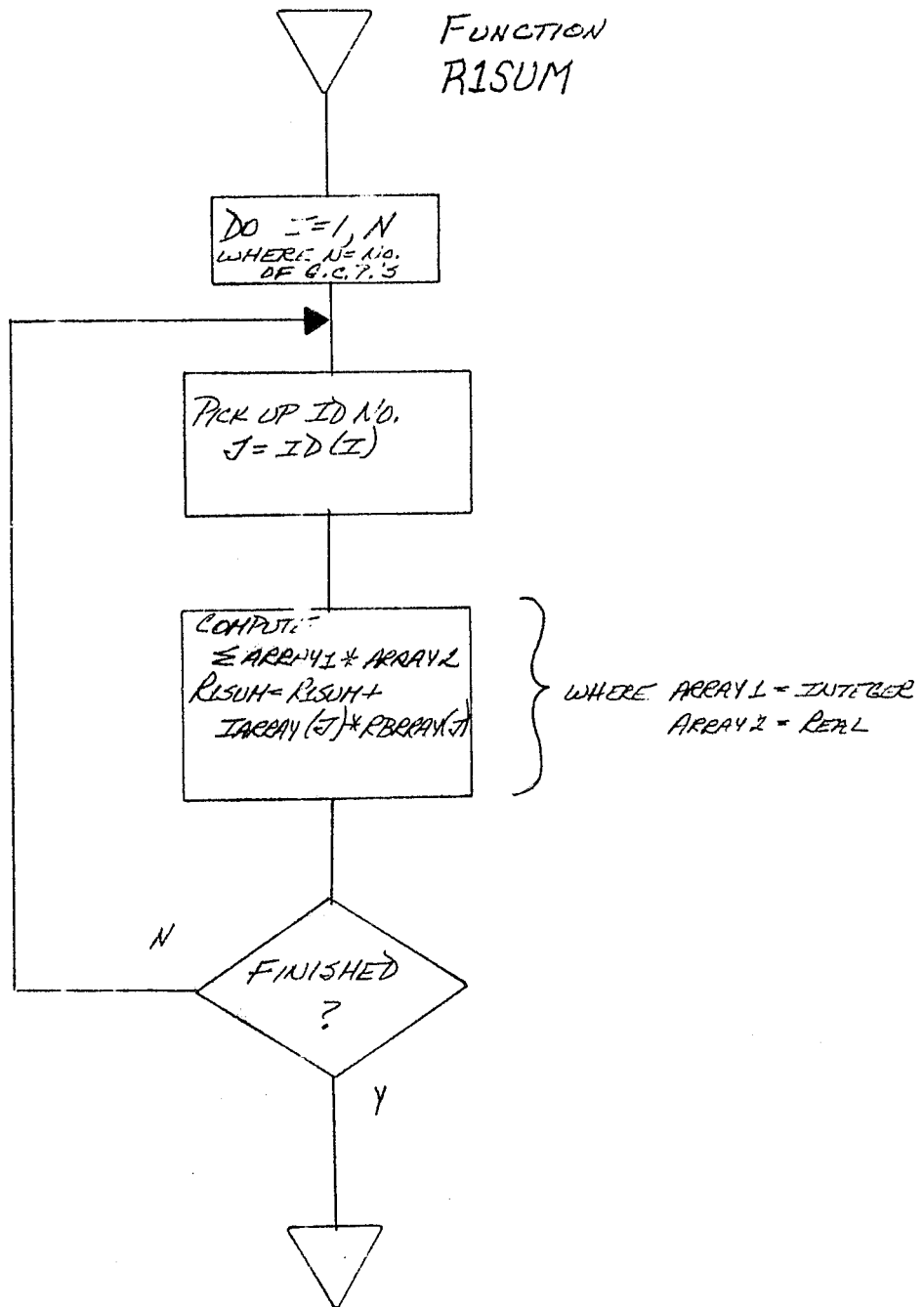


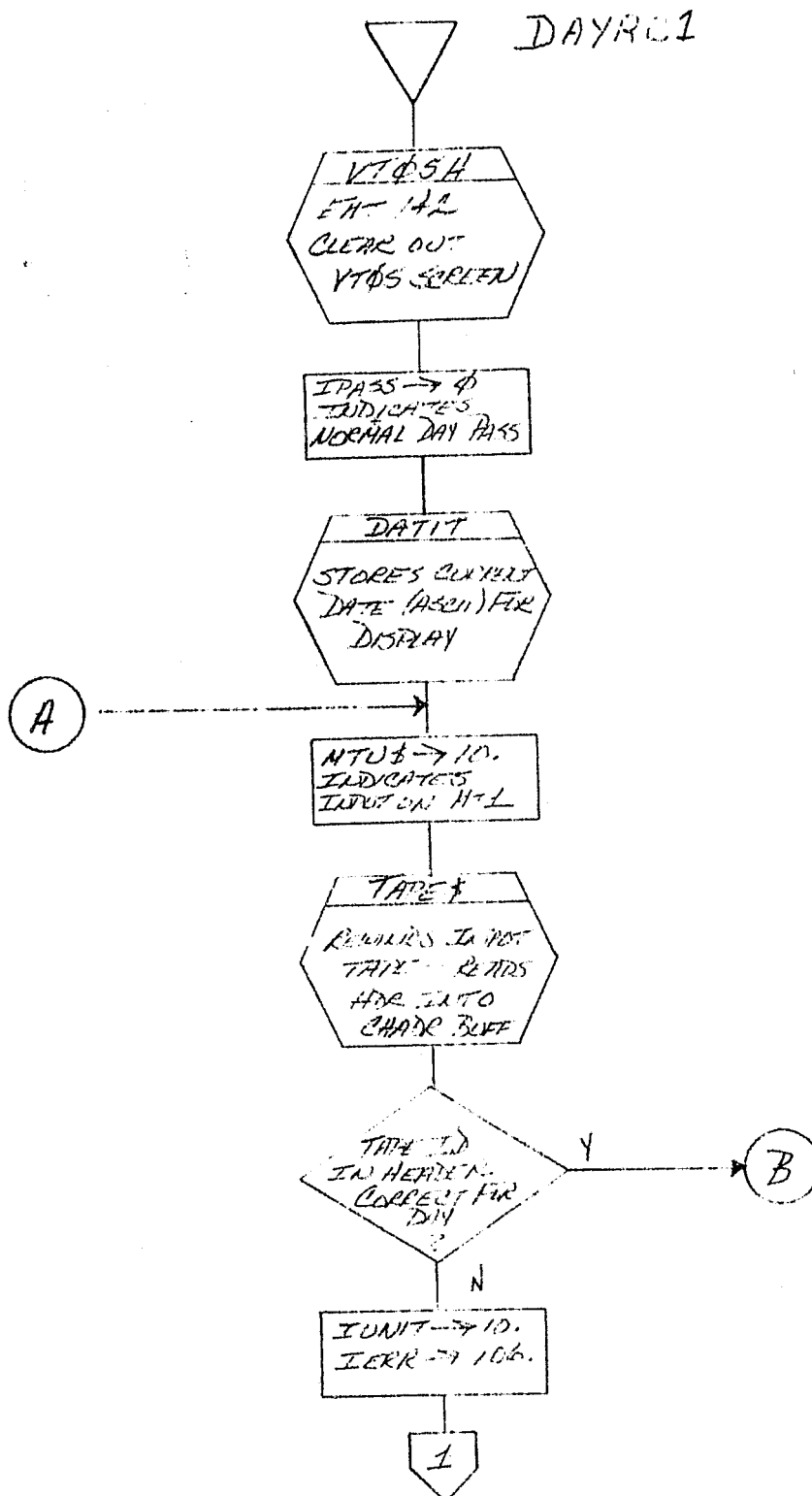
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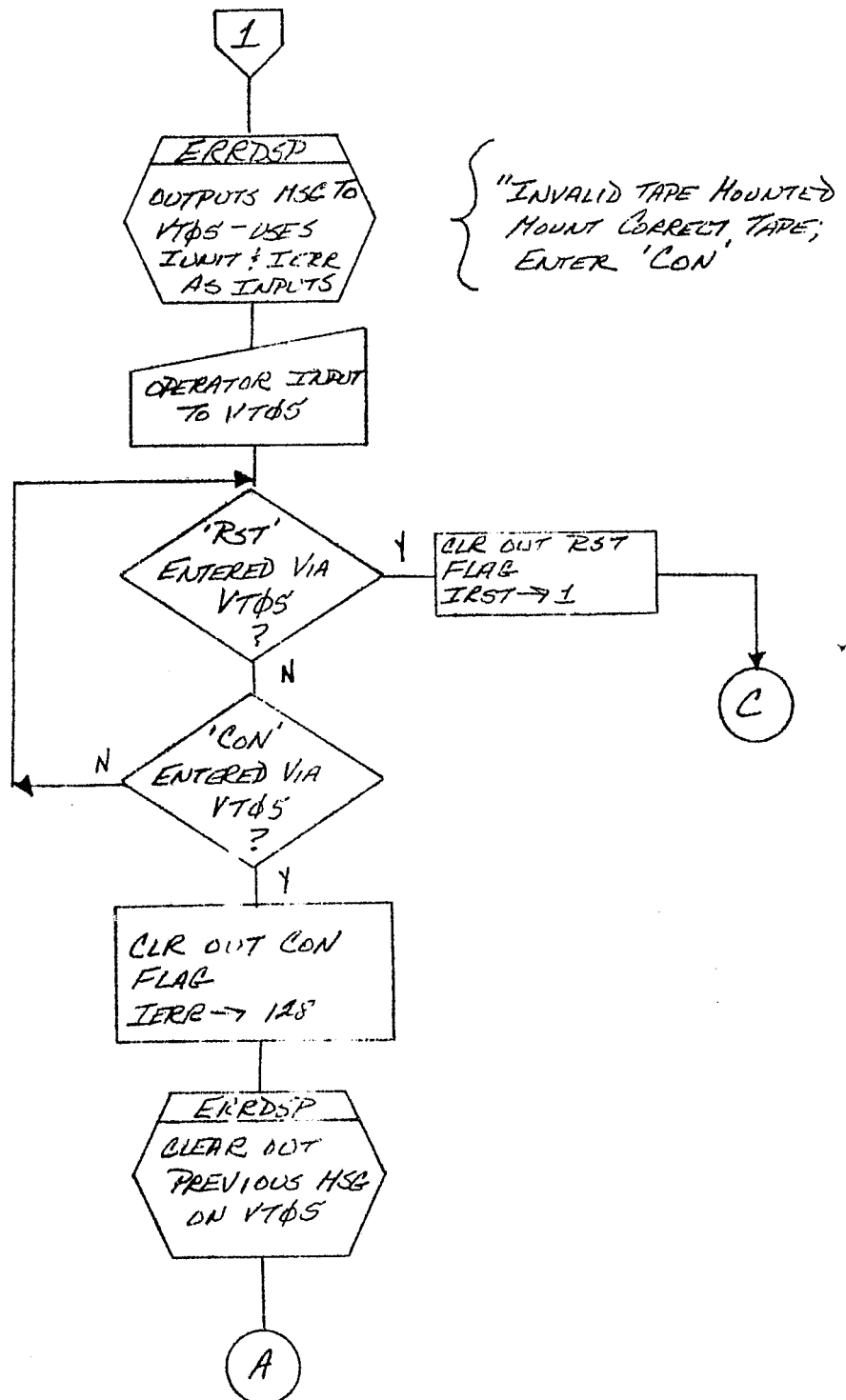


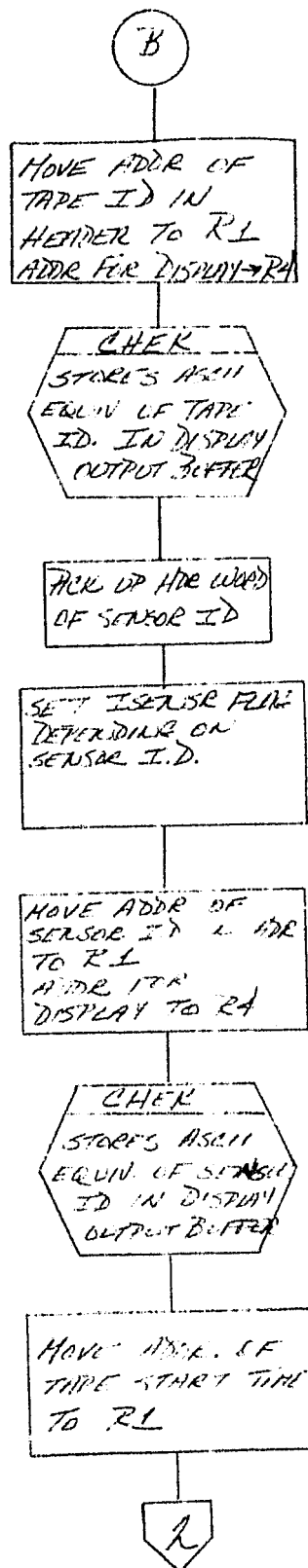


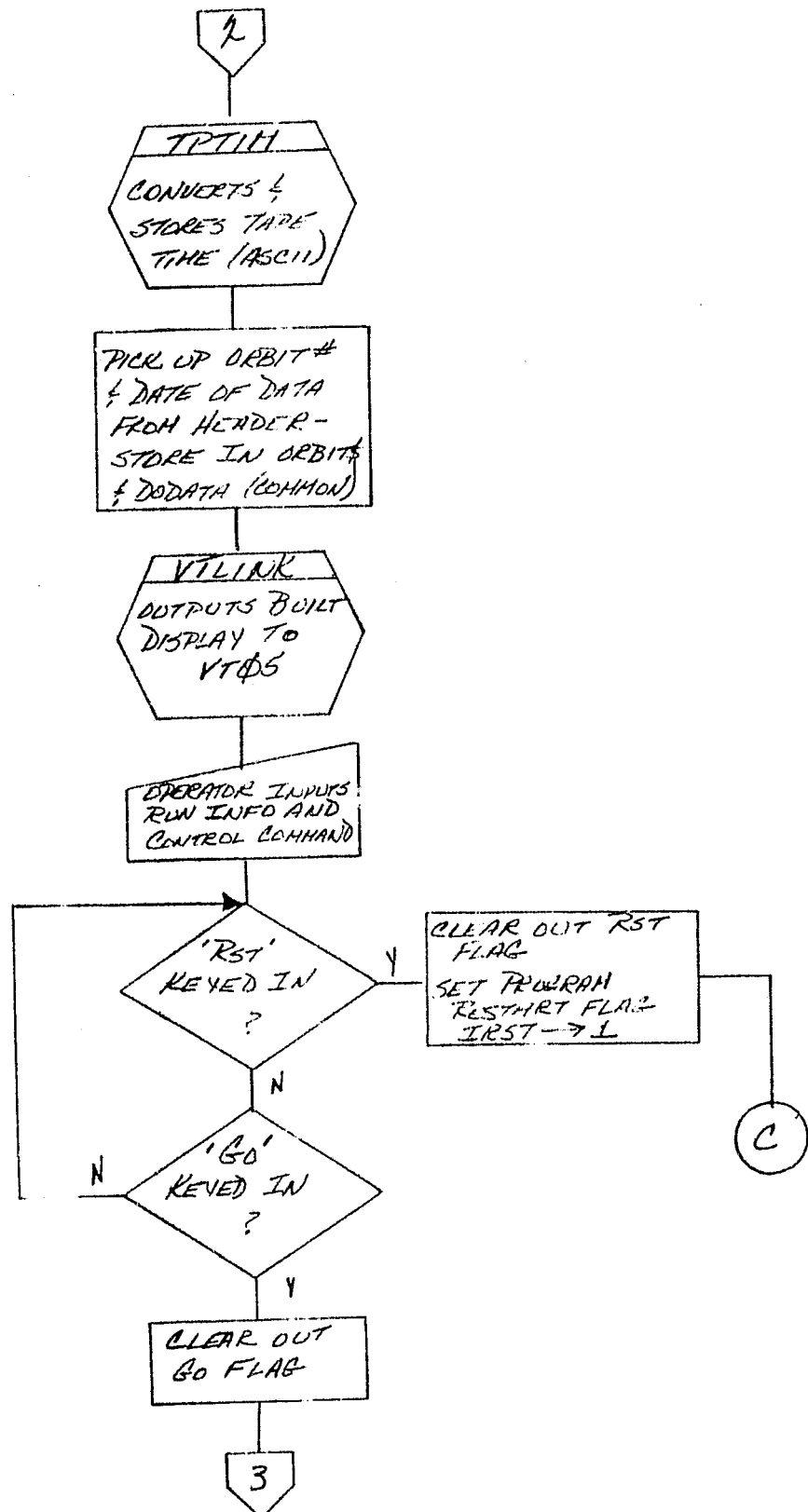


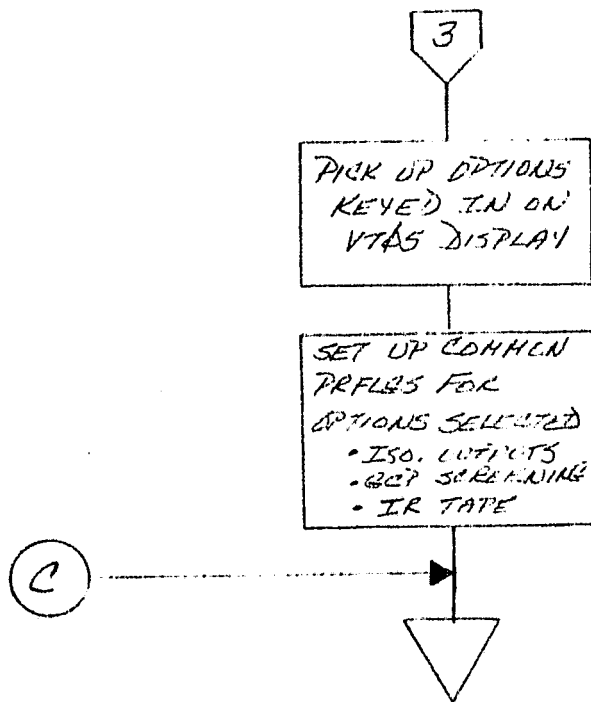


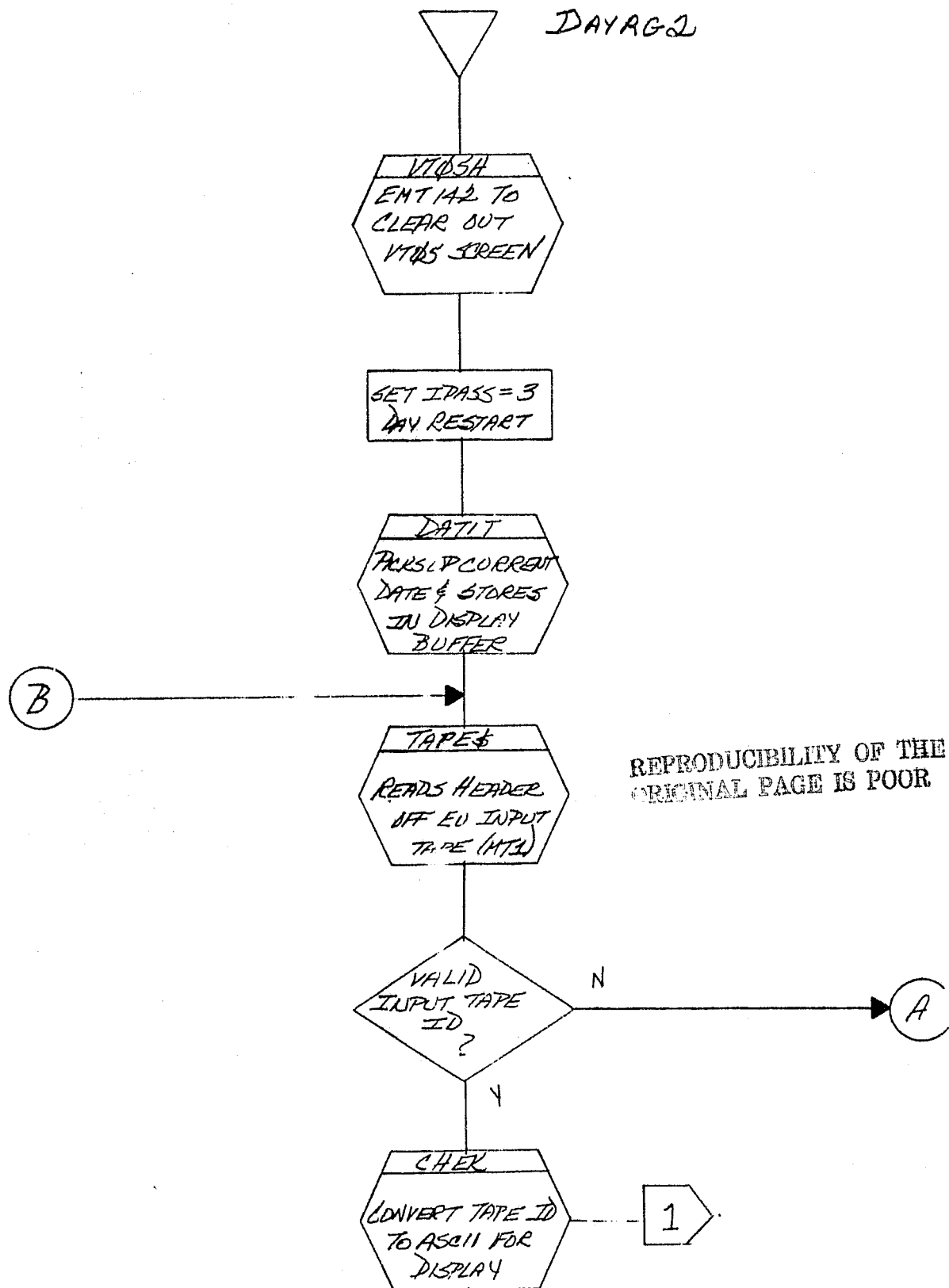
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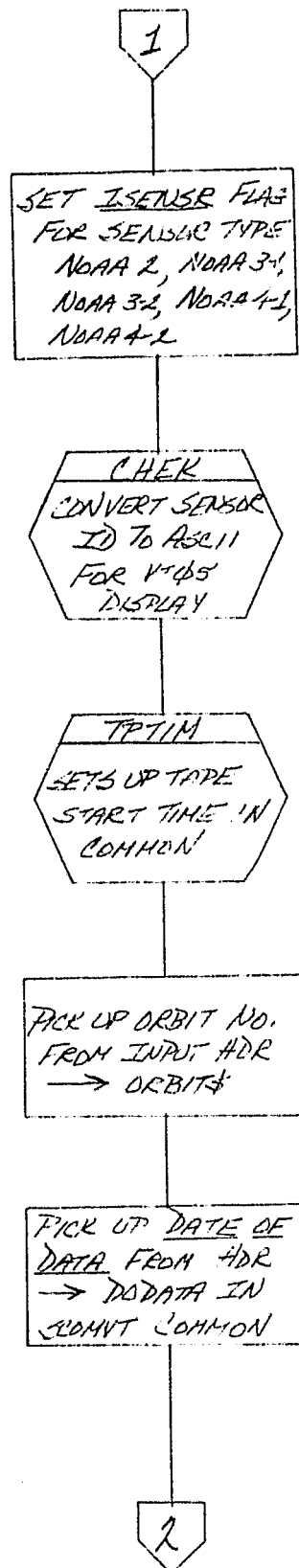


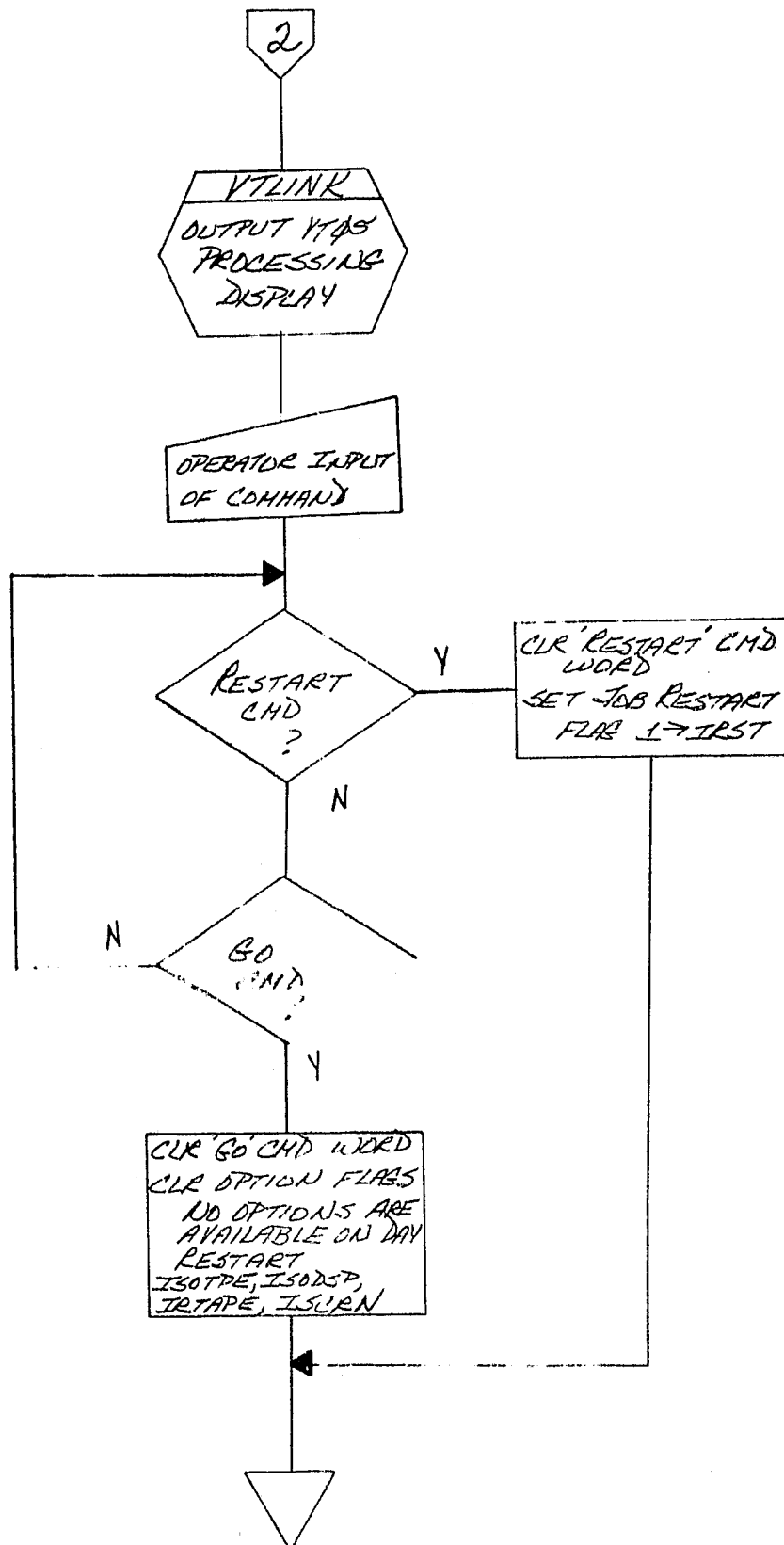


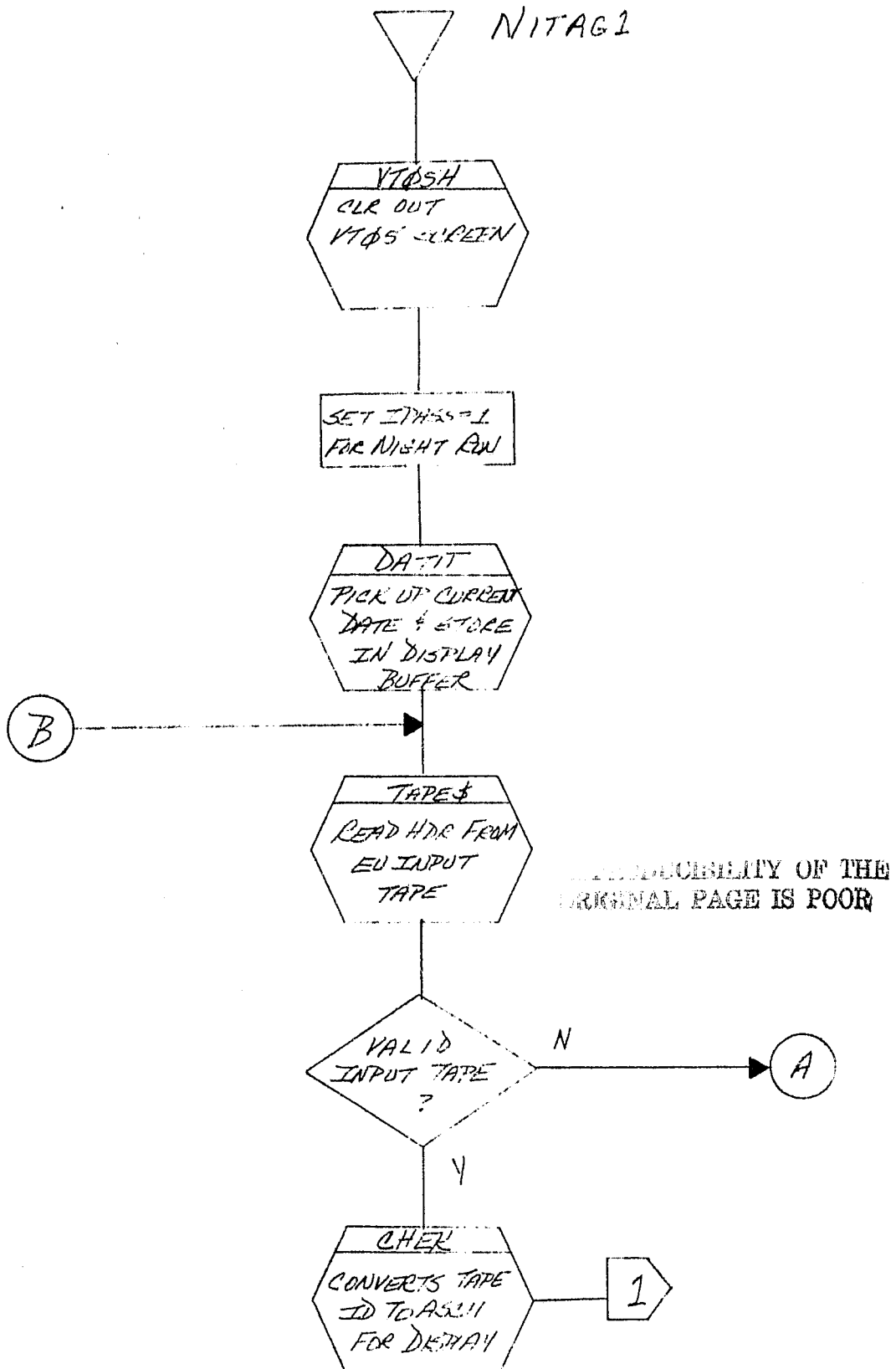


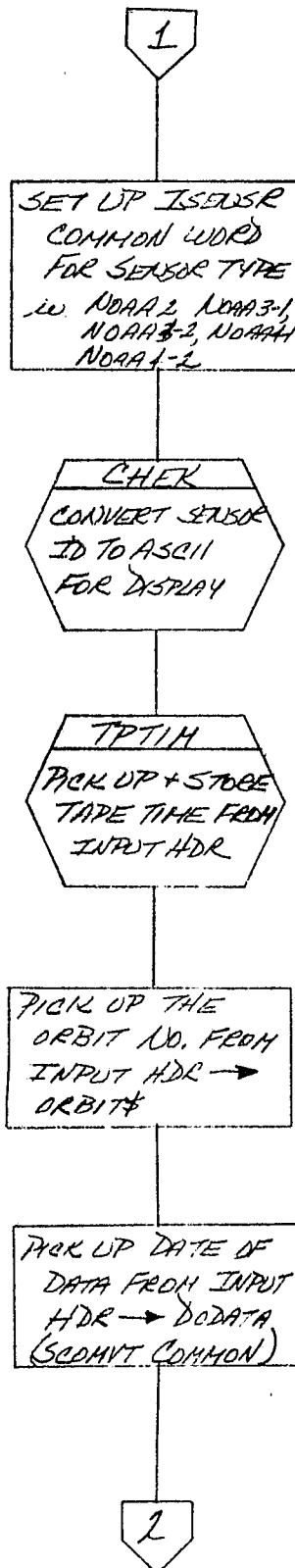


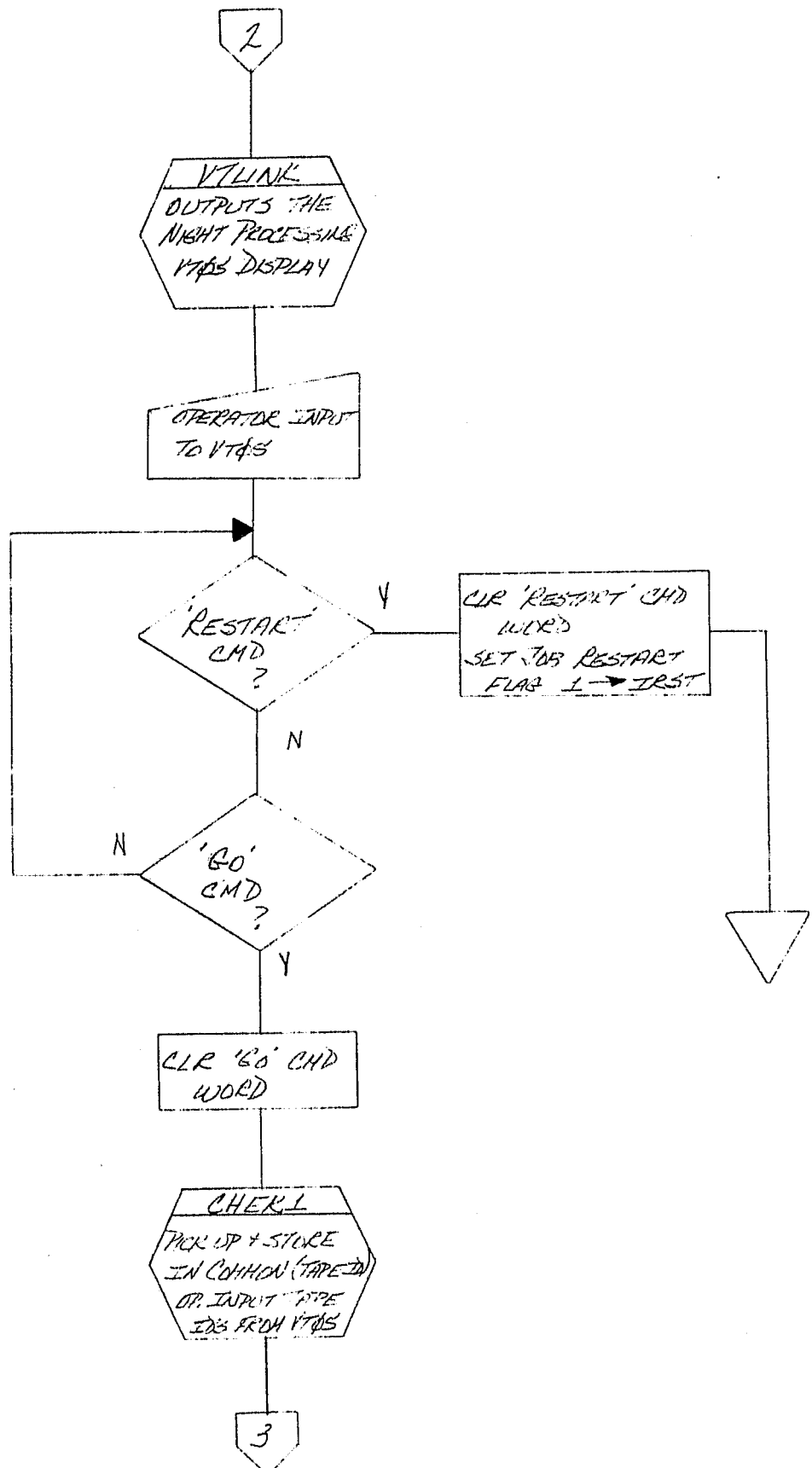


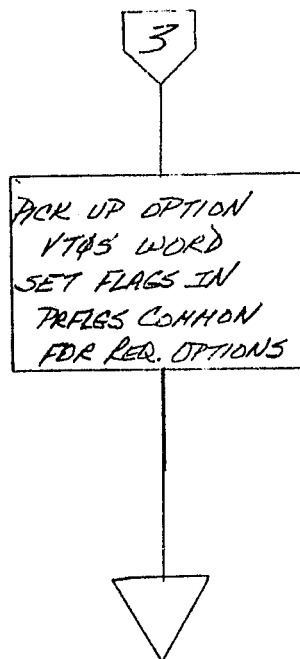


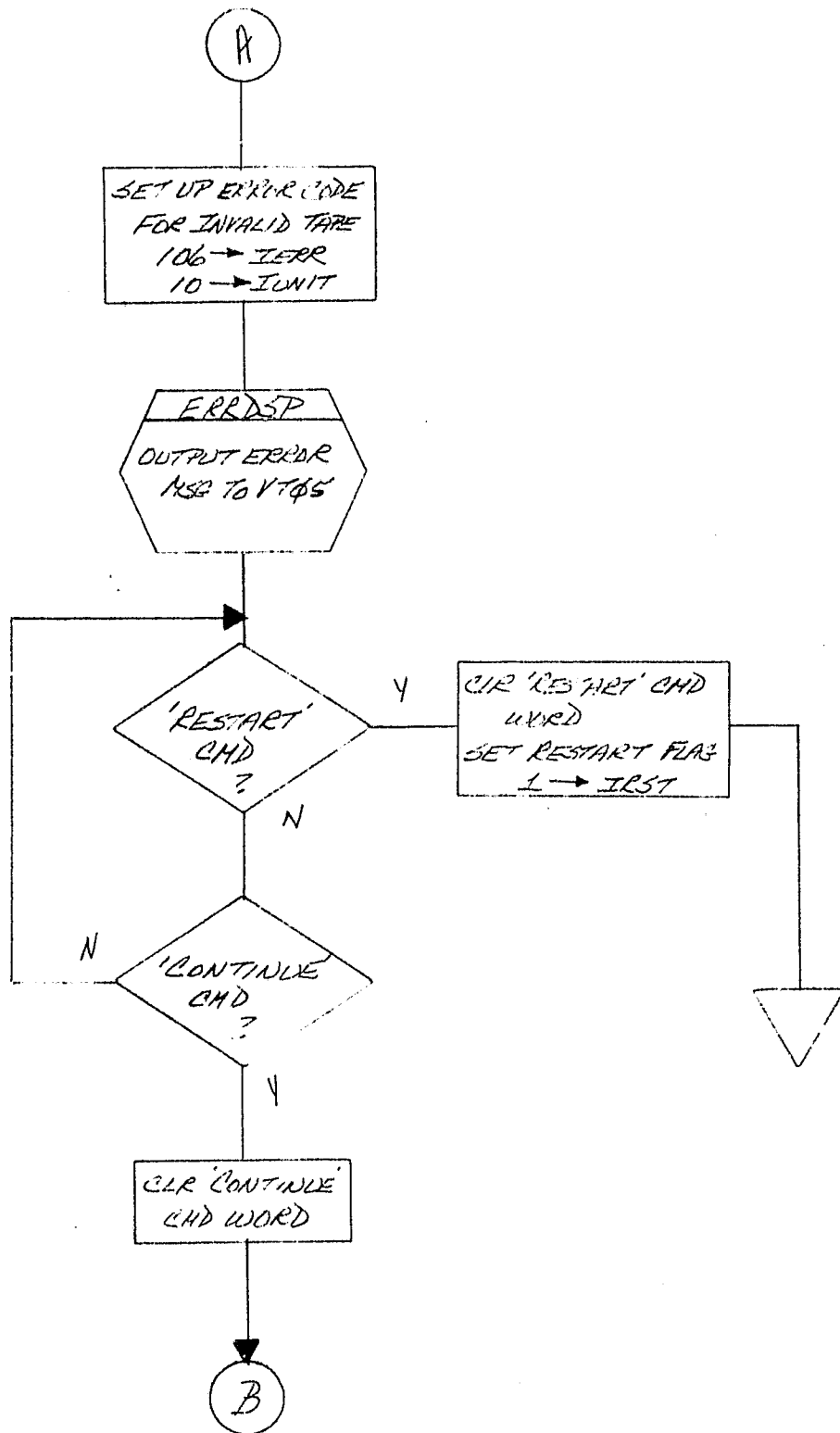


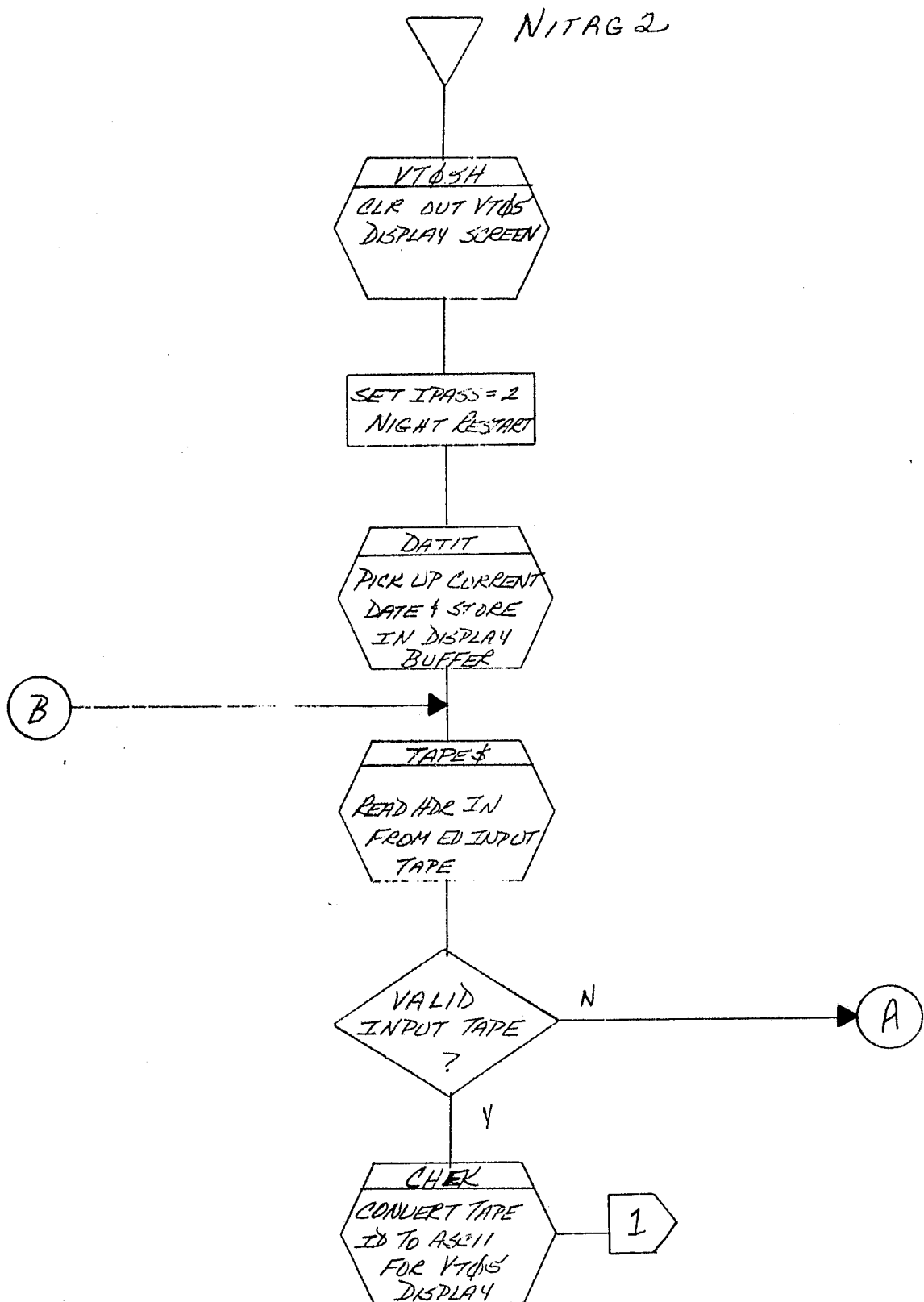


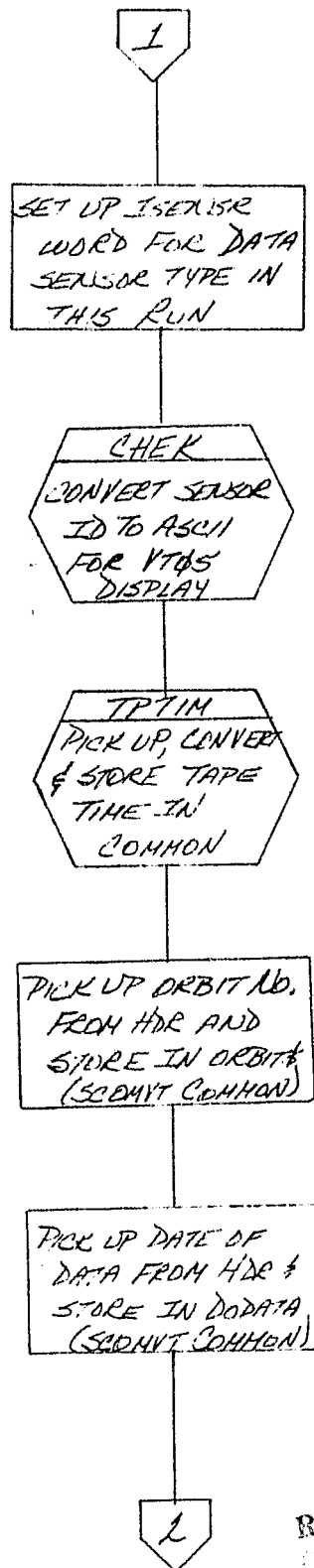




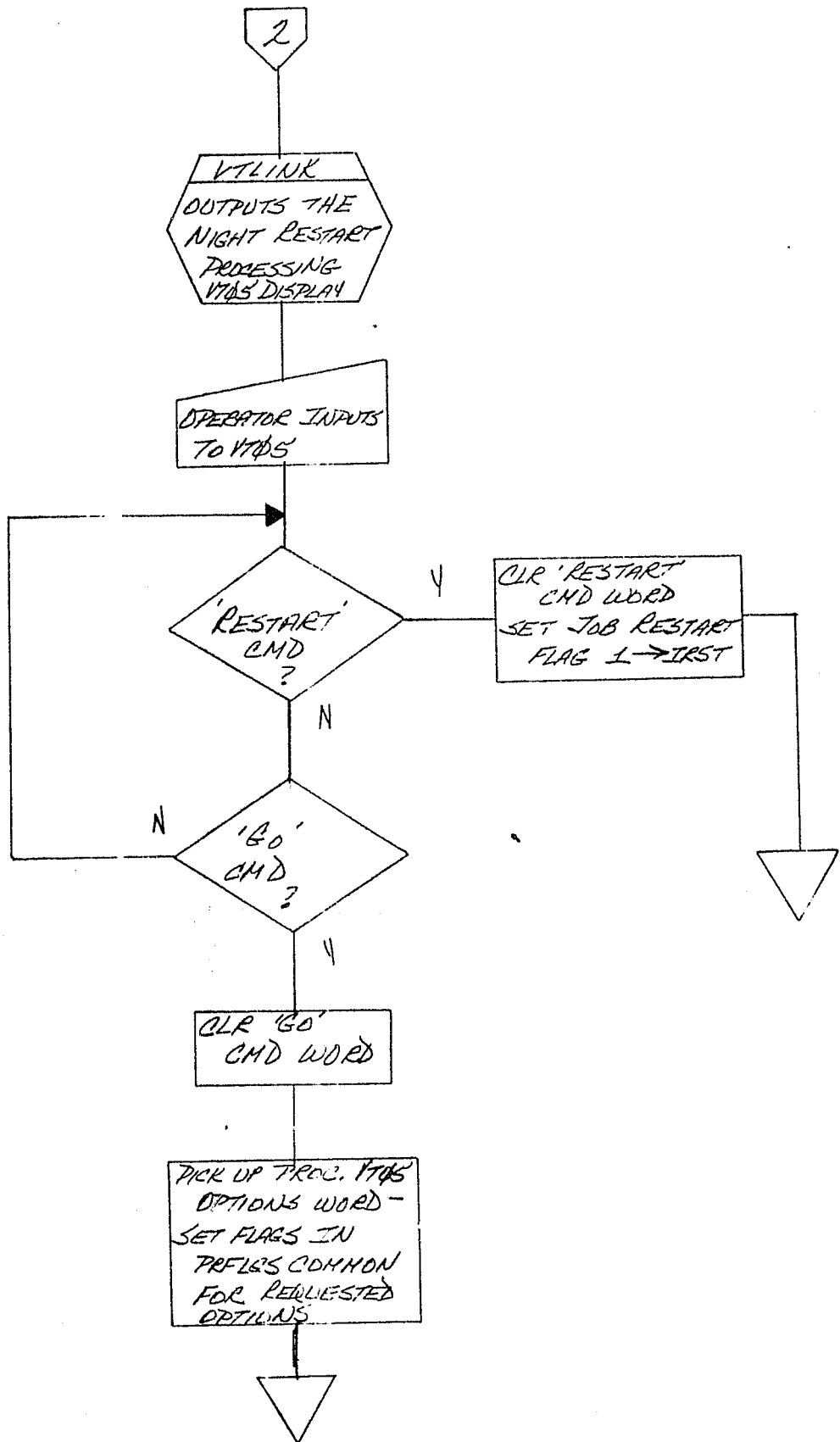


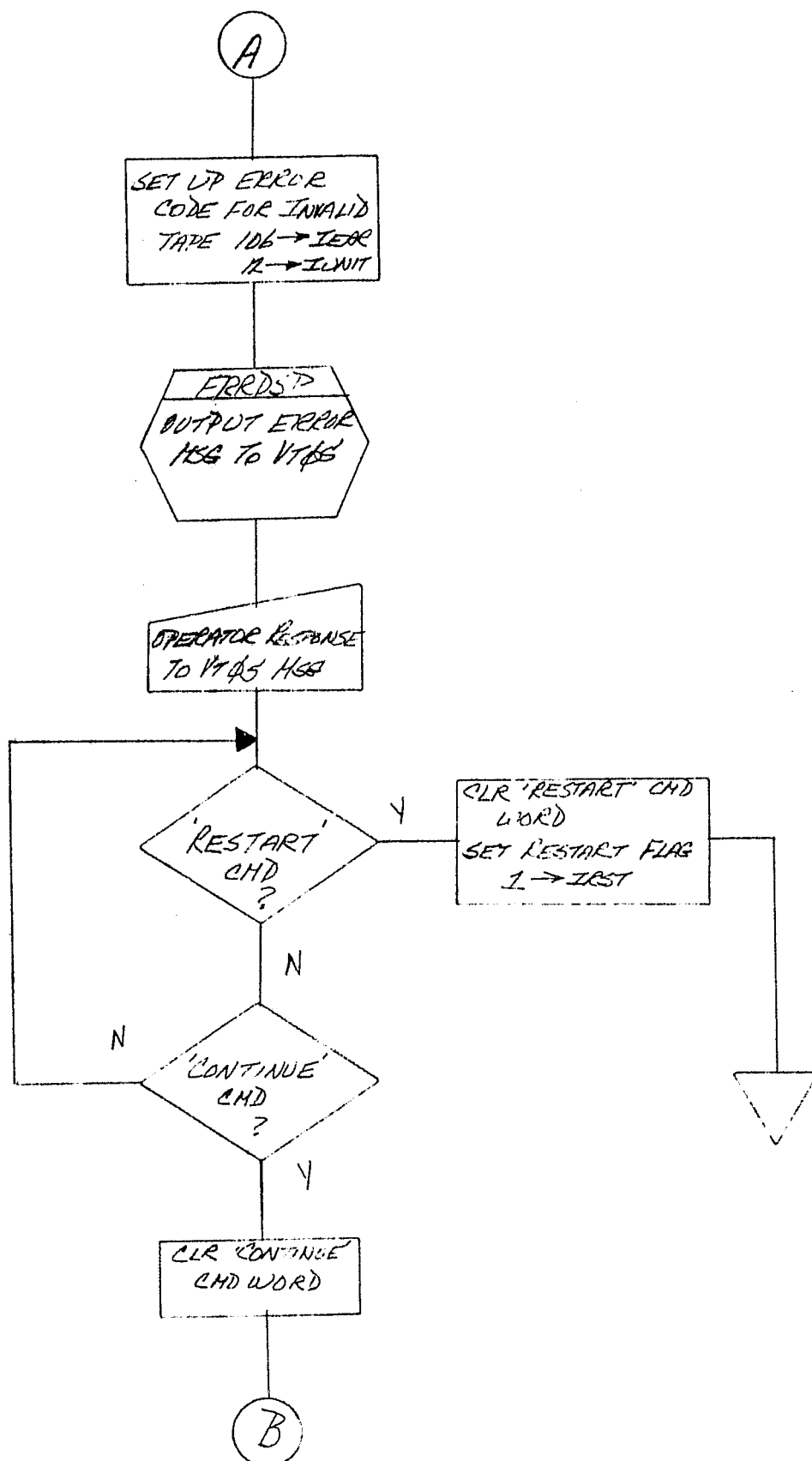


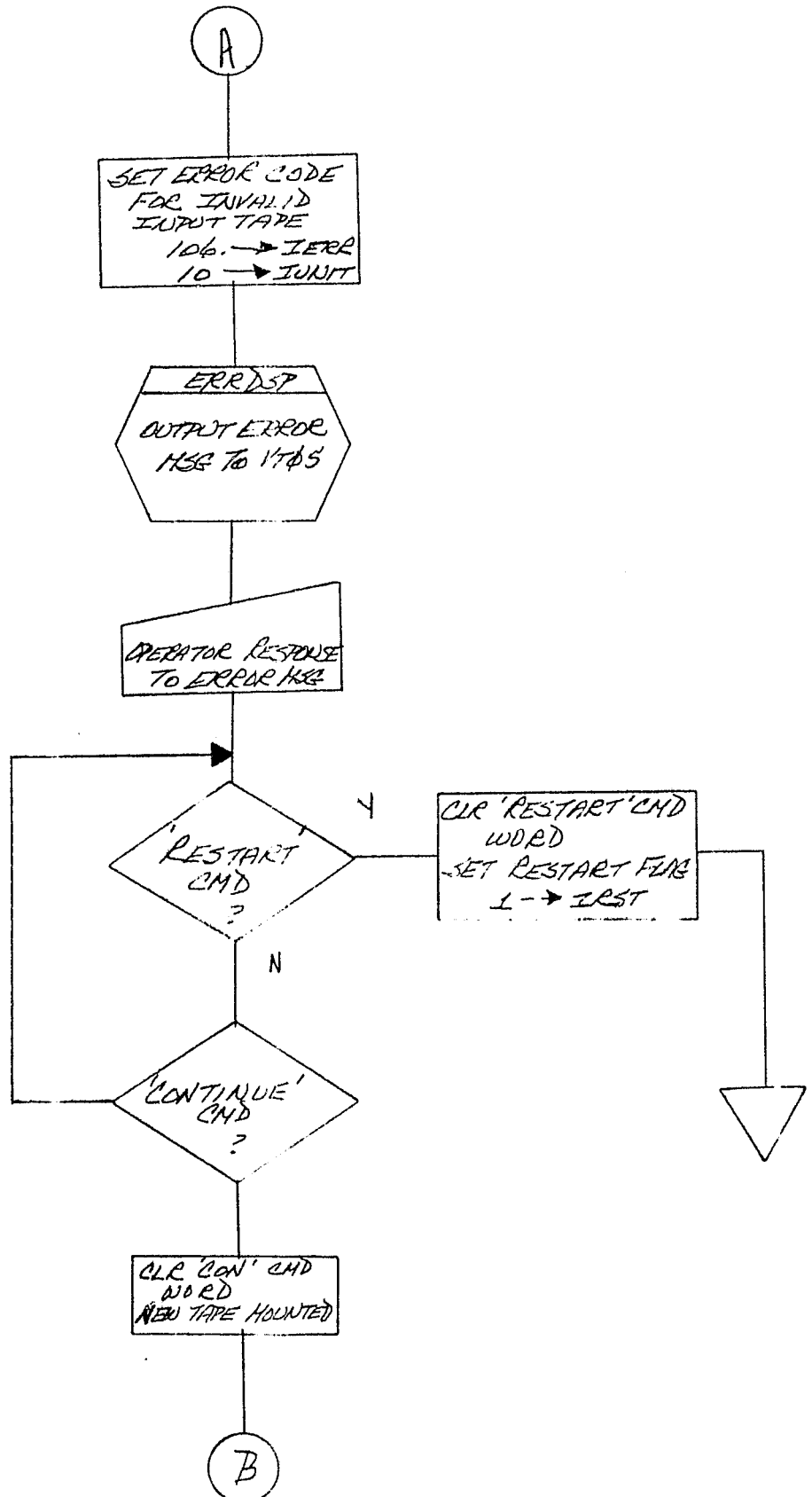


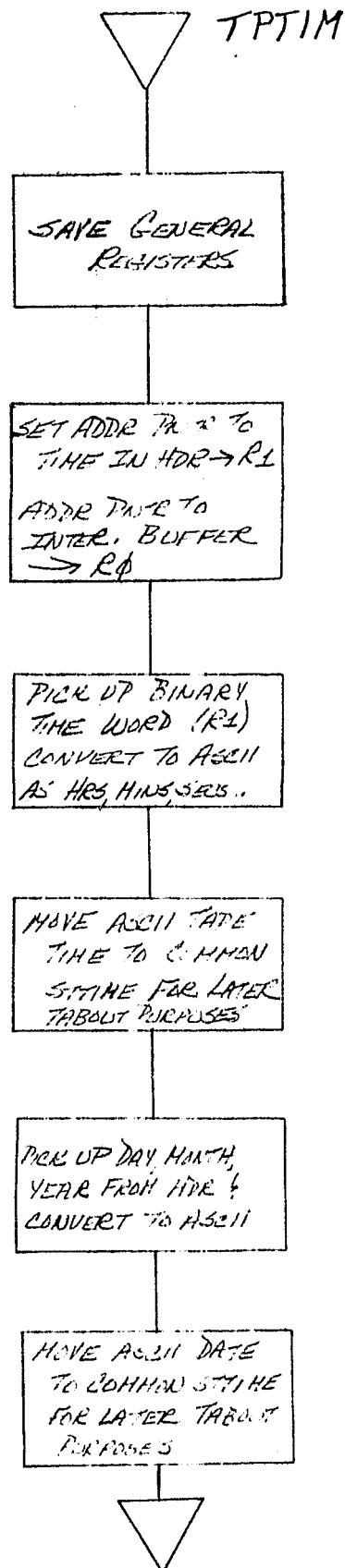


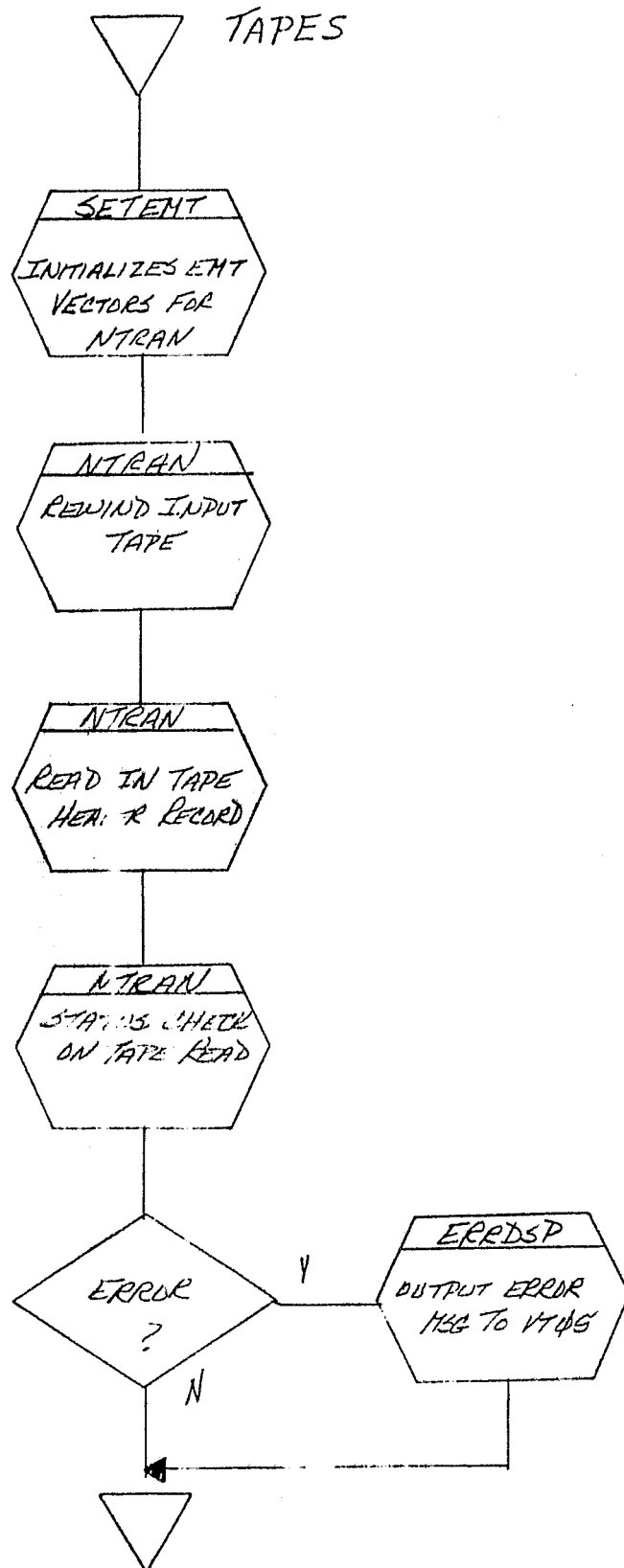
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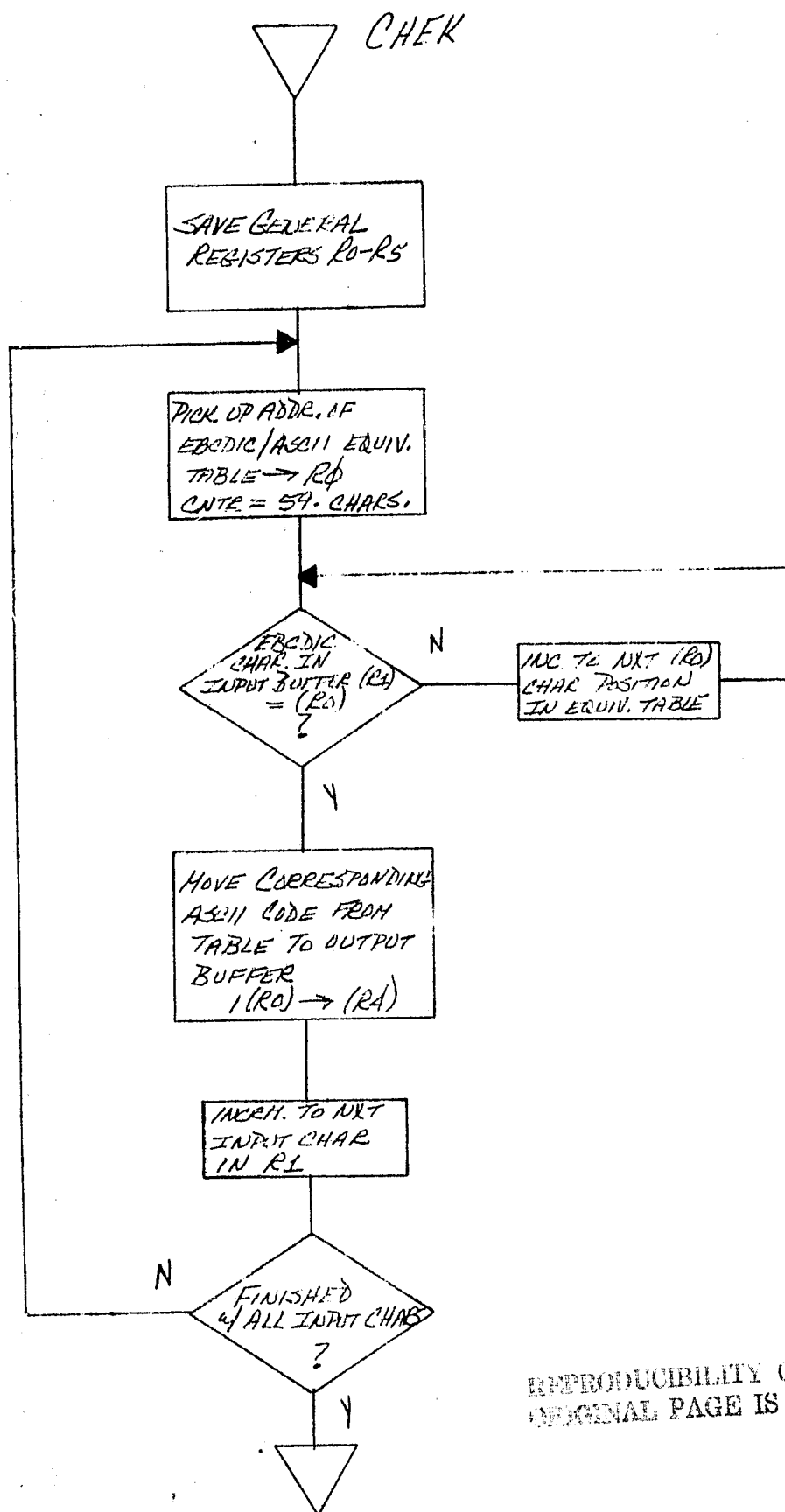












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3.2.1.3 Interfaces. This paragraph describes the interfaces between the SRE CPC and the other CPC's in the SRE Program, the input and output data, and the interfaces between the SRE CPC and its subcomponents or routines.

A. Input Data. The input data to the SRE CPC is as follows.

1. EU Input Tape Header Record. The job processing load modules (DAYRG1, etc.) read the input header to extract data for the processing display.
2. EU Input Tape. This tape is used by GCPID (U9TRD) in the data image screening during the GCP phase. See figure 3-27 and table 3-1 for the format of the EU tape and EU data channels.
3. Coefficient Card Inputs. Input to the SRE CPC if GCP phase is by-passed. See figure 3-18 for a format of the card deck.
4. Disk-Saved Coefficients. The REGCOF.TBL disk file, containing coefficients for the last day and night registration runs, is read into the system for restarts. See figure 3-28 for the format of the coefficient disk file.

B. Output Data. The output data of the SRE CPC is as follows.

1. Mapping Coefficients and GCP Phase Data. The coefficients completed during the GCP screening are stored in the GCOEFF common in the resident common data area to be used by REG CPC in the registration of the data image. See paragraph 3.1.5 for a description of the GCOEFF common.
2. Processing Flags. Flags are set up by DAYRG1, DAYRG2, etc. according to the operator entries on the processing display for the output options selected. See paragraph 3.1.5 for a description of the PRFLGS common, used by the ROT and REG CPC's.

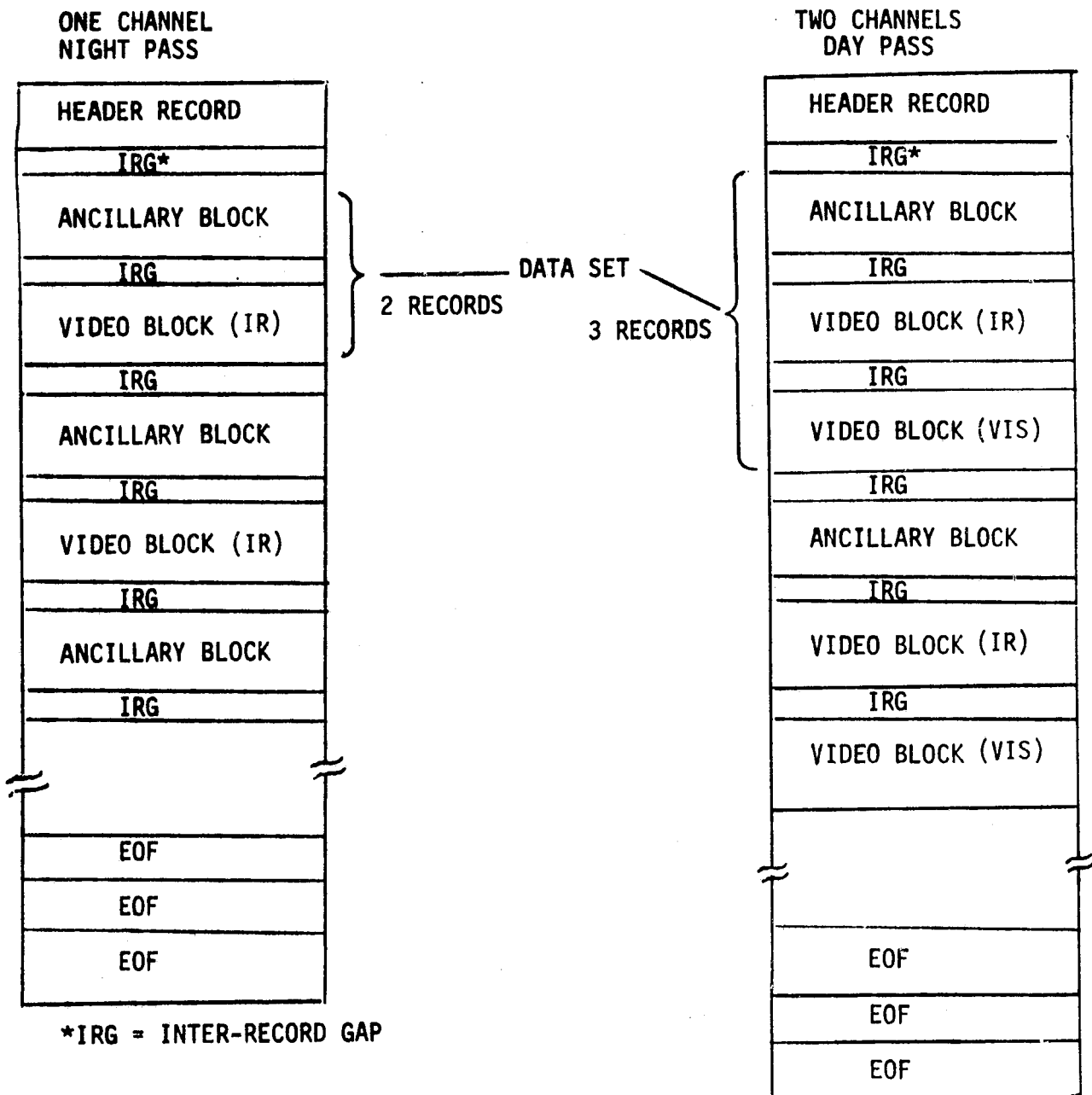


Figure 3-27 SEDS Processed 9-Track CCT Format

TABLE 3-1
PROCESSED TAPE BLOCKS

ANCILLARY BLOCK (COUNTER = 1*)	
<u>BLOCK BYTE</u>	<u>DESCRIPTION</u>
1-4	CURRENT GMT AT START OF THIS DATA SET (TENTHS OF MILLISECONDS)
5-6	CHANNEL STATUS FOR THIS SCAN. LSB OF BYTES 5-6 (0 = CHANNEL IN SYNC, 1 = CHANNEL NOT IN SYNC), ONE BYTE PER CHANNEL
7-68	CHANNELS 3-64 NOT APPLICABLE. LSB OF EACH BYTE = 1
69-70	SCAN LINE NO.; ARBITRARY BUT SEQUENTIAL FOR EACH SCAN LINE OF THIS DATA RUN
VIDEO BLOCK (COUNTER = 2*)	
<u>BLOCK BYTE</u>	<u>DESCRIPTION</u>
1-2500 (OR LESS)	CHANNEL OF DATA, UP TO 2500 VIDEO ELEMENTS: <ul style="list-style-type: none"> ● NIGHT TAPE VIDEO BLOCK = 2500 SCANS (1-1800 ELEMENTS) ● DAY TAPE VIDEO BLOCK = 2200 SCANS (1-2500 ELEMENTS)

*COUNTER IS IN FIRST TWO BYTES OF PHYSICAL RECORDS

NOTE: BYTES OF ZERO FILL ARE REQUIRED TO COMPLETE PHYSICAL RECORD LENGTH SPECIFIED IN HEADER RECORD

DAY DEBIT NO.	BLOCK 1 18 WORDS 10
NO. OF GROUND CONTROL PNTS	
A1 COEFFICIENT (FLOATING POINT)	
A2 COEFFICIENT	
A3 COEFFICIENT	
B1 COEFFICIENT	
B2 COEFFICIENT	
B3 COEFFICIENT	
EBAR	
SBAR	
NIGHT DEBIT NO.	BLOCK 2 18 WORDS 10
NO. OF GROUND CONTROL PNTS	
A1 COEFFICIENT (FLOATING POINT)	
A2 COEFFICIENT	
A3 COEFFICIENT	
B1 COEFFICIENT	
B2 COEFFICIENT	
B3 COEFFICIENT	
EBAR	
SBAR	

Figure 3-28 REGCOF Disk File

3. TAPEID Common. This common, residing in the resident common data area, contains the output tape ID's for the coarse rotated tape, registration IR, and isothermal tapes, as input on the processing display via the operator. See paragraph 3.1.5 for a description of the TAPEID common, used by the REG and ROT CPC's.

- C. Calling Sequence. The SRE CPC is called from the SEDS resident module and control is always given to the RGDISP load module. There are no direct calls made from SRE to the other two CPC's. Each CPC has a specialized phase of processing to accomplish for the overall registration process. The only communication or interfacing of CPC's is via data commons in the resident module or data SEG modules.

3.2.1.4 Data Organization. As discussed previously, data modules of 4K size are mapped in with load modules via SEG. These data modules can be accessed by another CPC, and it, too, can have these data modules mapped into core at 140000 or 24-28K in the virtual map. Each CPC also has data, tables, and buffers unique to its own modules which cannot be referenced by the other CPC's.

3.2.1.4.1 Data Modules

- A. GCPBUF. This is a 4K segment block data module which is associated with the GCPID and GCPEXC load modules of the SRE CPC. See table 3-2 for a format of the GCPBUF data module. GCPBUF is used only for GCP phase processing to collect statistics and GCP ID's located via the operator. This data module allows a transfer of this data between GCPID and GCPEXC, since they reside in separate 32K vertical core. GCPBUF contains three common blocks -- GCPTAB, EPHEMR, and REFGRD. Two are discussed below.
 1. GCPTAB. This block contains the data accumulated from identifying GCP's, such as the ID's selected, the delta errors, signals, computed (E,S)'s, etc.
 2. REFGRD. This block contains the preassigned X and Y coordinates of the GCP's in the reference grid. It is initialized by GRDINT prior to performing any calculations in GCPEXC.

TABLE 3-2

GCPBUF BLOCK DATA MODULE

GCPTAB COMMON: IORBIT, N, ID(98), IE(98), E(98), IS(98), S(98), IEP(98), EP(98), ISP(98), SP(98), IEDELTA(98), EDELTA(98), ISDELTA(98), SDELTA(98), ESIGMA, SSIGMA, DVALUE, OFFSET IE1(98), EI(98), ISI(98), SI(98), DVIATN, ERRCMD(98) SIGCMB, IEPP(98), ISPP(98), EPP(98), SPP(98), IXPTS(5) IYPTS(5), XPTS(5), YPTS(5), RLAT(5), RLONG(5) ATANA3, ATANB2

IORBIT - ORBIT NO.

N - NO. OF GCP's IDENTIFIED

ID - GCP ID's IDENTIFIED (1-98)

IE, E - ARRAY OF COMPUTED PIXEL VALUES FOR EACH GCP (REAL & INTEGER)

IS, S - ARRAY OF COMPUTED SCAN VALUES FOR EACH GCP (REAL & INTEGER)

IED, EP, ISP, SP - IDENTIFIED COORDINATES OF GCP'S (VIA OPERATOR)

IEDELTA, EDELTA - DELTA E (ΔE) FOR EACH GCP (REAL & INTEGER)

ISDELTA, SDELTA - DELTA S (ΔS) FOR EACH GCP (REAL & INTEGER)

ESIGMA, SSIGMA - AVERAGE ERROR DELTAS OF THE PIXELS (E) AND SCANS (S) OF THOSE GCP'S IDENTIFIED

DVALUE - LINEAR INDEPENDENCE OF GCP'S IDENTIFIED

OFFSET - MEASURE OF DISTANCE OF THE MEAN GCP (EBAR, SBAR) FROM THE CENTER OF THE INPUT IMAGE

IE1, EI, ISI, SI - PREIMAGE COORDINATES OF EACH GCP IDENTIFIED, COMPUTED BY USING INVERSE MAP COEFFICIENT ON THE (X,Y) REFERENCE POINTS

DVIATN - MEASURE OF THE SPREAD OF THE GCP'S IDENTIFIED

ERRCMB - ARRAY OF COMBINED ERRORS (EDELTA + SDELTA) OF GCP'S IDENTIFIED

SIGCMD - AVERAGE OF SUM OF E ERRORS + S ERRORS COMBINED (ERRCMB)

IEPP, EPP, ISPP, SPP - EPHEMERIS-GENERATED GCP COORDINATES COMPUTED FROM REFERENCE GRID COORDINATES

IXPTS, XPTS, IYPTS, YPTS - THE COMPUTED REFERENCE GRID COORDINATES OF THE FOUR CORNERS + CENTER OF THE INPUT IMAGE

RLAT, RLONG - LATITUDE + LONGITUDE OF THE FIVE POINTS

ATANA3 - ANGLE, MEASURED IN DEGREES, OF VERTICAL SKEW

ATANB2 - ANGLE, MEASURED IN DEGREES, OF HORIZONTAL ROTATION

TABLE 3-2 (CONT'D)

REFGRD COMMON: (XP(98), YP(98))

XP - ARRAY OF X(PIXEL) COORDINATES OF THE PREASSIGNED GCP's IN THE REFERENCE GRID

YP - ARRAY OF Y (SCAN) COORDINATE VALUES OF THE PREASSIGNED GCP's IN THE REFERENCE GRID

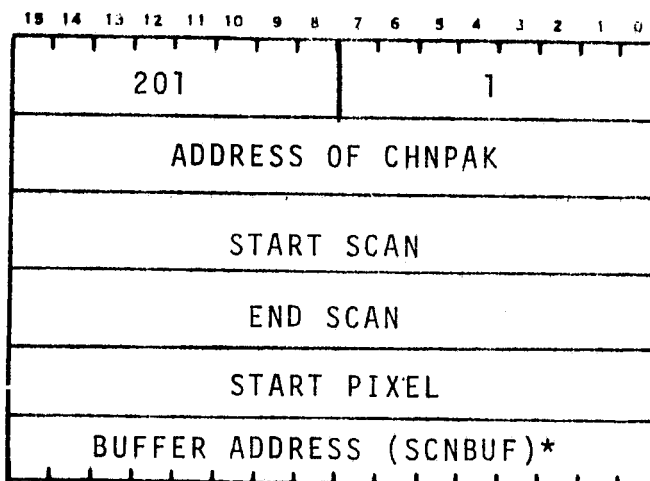
EPHEMR COMMON: TF, TEQ, RLMBER, PHIPRM, RLMBDA, IVE, IYE, IEE, ISE, A, B

COMMON CONTAINS EDPHEMERIS DATA READ FROM THE EPHEMERIS DISK FILE BY ORBIT; LONGITUDE AND LATITUDE CALCULATIONS DONE BY PHMGCP, AND REFERENCE GRID COORDINATE CALCULATIONS

- B. INBUFF. This module is a 4K segment block data module associated with the processing load modules DAYRG1, NITRG1, etc. It is used to read the EU input tape header record into.

3.2.1.4.2 Data Tables and Items. The following data is used only in the SRE CPC. Some is used as storage locations, some as internally defined symbols, and some as data commons used in transferring data between assembly and FORTRAN routines.

- A. Common/COEFTS/A1INT, A2INT, A3INT, B1INT, B2INT, B3INT, SGEINT, SGSINT. This common contains the mapping coefficients for the GCP VT05 display in ASCII form. The FORTRAN routine NNCODE converts the required coefficients contained in the GCOEFF common and GCPTAB common to ASCII so PRCID can output them to the VT05 display. Each variable consists of eight bytes (four words).
- B. U9PAK. This is a packet passed to U9TRD which is necessary for reading the input tape for the GCP screening process.



*Where to store data scan read in

- C. CHNPAK. This is a table listing channels to be read in.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NO. OF CHANNELS															
CHANNEL NO.															

- D. STSCN, ENSCN, STPIX. These are entries on the VT05, input via the operator in selecting the start scan, end scan and start PIXEL for the image screening during GCP phase.
- E. SCNBUF. This is a 1530₁₀ word buffer used by U9TRD to store a data scan record read in from the input tape for the GCP screening.
- F. COMBLK. A packet passed to DISPL in outputting a scan of data to the ICD screen.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0								204							

- G. DLTID. This is a two-word location in which to store "delete ID" inputs from the VT05. PRCID uses the input in DLTID to process GCP deletion requests from the operator.
- H. ACTPIX. GCPID picks up the start tape PIXEL number from the input header and stores it in this one-word location to be displayed on the GCP display.
- I. CRNSN. GCPID keeps a counter of the current scan output to ICD. This one-word entry is output and updated on the GCP display.
- J. IDNUM. The current GCP ID is stored here for transfer from GCPID to PRCID to process the ID located.
- K. XPOS and YPOS. These are the X and Y positions of a GCP returned in the monitor packet by IDEH, and stored for transfer to the FORTRAN subroutine CNVTES.

- L. DELTE and DELTS. These 2210 word buffers contain the delta E and delta S for each identified point, computed by GCPEXC. PRCID transfers the delta E and S entries from the GCPBUF data module common to DELTE and DELTS for purposes of displaying them on the GCP display.
- M. DISTM. This GCP coefficient VT05 display command block contains background display and commands describing each input/output field on the display, and where the entry values are to be stored or picked up for displaying. This command block is passed in the call to VTLINK to output the display.
- N. RGCMD1, RGCMD2, RGCMD3, and RGCMD4. These are the four processing display command blocks contained in the load modules DAYRG1, DAYRG2, NITRG1, and NITRG2, respectively. They contain the display background and commands describing each input/output field on the display. These commands are passed in the calls to VTLINK to output the displays when necessary.
- O. RGCHD. This is the registration initialization display command block in INTDSP (RGDISP load module). It contains the display background and commands describing each input/output field and is passed to VTLINK to output the display.
- P. EB2ASC. This is a table residing in the CHEK Routine, containing ASCII and EBCDIC representations of the characters A-Z and 0-9, used in converting header data and tape ID's.
- Q. SINANG (= 0.4352311) and COSANG (= 0.9003188). These are values assigned in the subroutine INVROT to compute the inverses for the night data.
- R. GCPDIS. This is the GCP statistics display command block in GCPID. It contains the display background and commands describing the input/output fields. It is passed to VTLINK to output the display.

- S. REGCOF. This is the registration coefficient disk file containing the mapping coefficients for the previous day and night registration runs. See figure 3-28.

3.2.1.5 Limitations. The major limitations of the SRE CPC concern the GCP phase. Due to the magnitude of input data to be screened for operator identification of points, several passes must be made. This results in reading of the entire input tape several times to extract the designated scans. With a larger disk, it would be possible to set up, for example, four display image sections with one tape read operation. Upon request, a specified image section could be shipped directly to the ICD screen for operator viewing. This would result in a speed-up of data screening and do away with numerous tape rewinds and read operations.

Another limitation of the SRE CPC is the time in which GCP location is performed in the sequence of processing NOAA data. Because the GCP phase is located in the registration processing module, after EU conversion of the data has been completed, there is a loss of resolution in the data the operator is viewing. If the GCP phase was located in the SEU Program prior to the EU conversion, the resolution of the image for screening would be better, and key points would be more readily identifiable by the operator.

There is room on the VT05 GCP display for only 21 operator-identified point entries with ID, DELTA E, and DELTA S entries for each. So, if over 21 points are selected via the operator, not all can be displayed on the VT05.

- 3.2.1.6 Listings. See Part IV of this document, published under separate cover.

3.2.2 ROT (CPC No. 2). ROT is the night coarse rotation CPC. The word "coarse" refers to a fixed 25.8-degree rotation of the night pass scan lines to orient them to conform approximately with the orientation of the day pass scan lines; following coarse rotation, the scan lines undergo a fine rotation in the REG CPC just as do those from the day pass. The reader is therefore cautioned not to confuse the word "coarse" (as opposed to "fine") with the word "course."

ROT consists of three load modules -- NTROTN.LDA, RTPHAS.LDA, and REGHED.LDA -- and three major programs -- NTROTN.EXC, RTPHAS.EXC, and REGHED, written in FORTRAN. (Some assembly language subroutines are used for the byte move operations.)

ROT inputs a night EU tape (SEN) and outputs a coarse-rotated tape (CRT). The CRT has the scan lines resectioned at an angle of 25.8 degrees, and has the image inverted. ROT also selects 1800 PIXEL's per scan from the EU tape.

A detailed description of the ROT CPC follows.

3.2.2.1 Description. The night pass image must be rotated clockwise through an angle θ (currently θ is 25.8°), have the order of the scan lines reversed, and have the order of the PIXEL's within each scan line reversed.

The scan lines are read from the EU tape into an input buffer. From here, the data is compressed 4:1 in each direction into an intermediate buffer. The number of scan lines is also reduced by a factor of $\cos \theta$ ($\theta = 25.8^\circ$) by deleting some lines. Of those left, four lines at a time are compressed 16:1 by averaging. Groups of four PIXEL's in a scan line are added together, the shortened line put into the intermediate buffer, and the next three shortened scan lines added to it. Each of these sums is then divided by 16, and the line is read onto disk. When the entire image has been compressed and read onto disk, it is read in reverse order into the rotation buffer (i.e., the last line read in is the first line read out). When the rotation buffer is half full, the first resectioned line is taken out, and thereafter one line is taken out for each line put in. After all the data is input, another half buffer of lines are output.

The data is prescaled in the downtrack direction and postscaled in the crosstrack direction. Each resectioned line is reversed left to right, decompressed 1:4, and expanded by a factor of $\sec \theta$ as it is assembled in the output buffer. Each line is always repeated exactly four times when written from the output buffer onto tape. The scaling in S (downtrack) direction by $\cos \theta$ is done by NTROTN.EXC.

The 16:1 compression, and the writing of the compressed scans to disk, is done by the assembly language routine CMPRES in the NTROTN load module.

Reading the compressed lines from disk in reverse order is done by the assembly routine READSK in the RTPHAS load module. The line resectioning (scan line rotation), reversal of PIXEL order, scaling in E (crosstrack) direction by $\sec \theta$, and expansion by 1:4 in each of E and S directions, is also done in the RTPHAS load module.

The calculations for selecting the "best" 1800 PIXEL's are done in REGHED. REGHED also reads the header of the SEN tape and writes the header of the CRT tape.

3.2.2.1.1 Scan Line Deletion Procedure (NTROTN.EXC). After each scan line is read from tape into the input buffer, a decision must be made whether or not to use the line in the 16:1 compression step. The number of scan lines is reduced by a factor of $\cos \theta$ by a deletion procedure which employs the method shown in figure 3-29 for deciding whether or not to use an input scan line. In figure 3-29, I refers to the number of scan lines read off the input tape (i.e., the first line read off the tape is $I = 1$, the second line read off is $I = 2$, etc.)

3.2.2.1.2 16:1 Compression Procedure (CMPRES). Starting with the first selected scan line of a group of four, the first four PIXEL's are added and the sum written into the first position of an intermediate buffer; the second four are added and the sum written into the second position of the intermediate buffer, and this is continued until the entire line has been processed (the 1800 PIXEL's currently used make 450 sums). For the second scan line of the group of four scan lines, first four PIXEL's are added and this

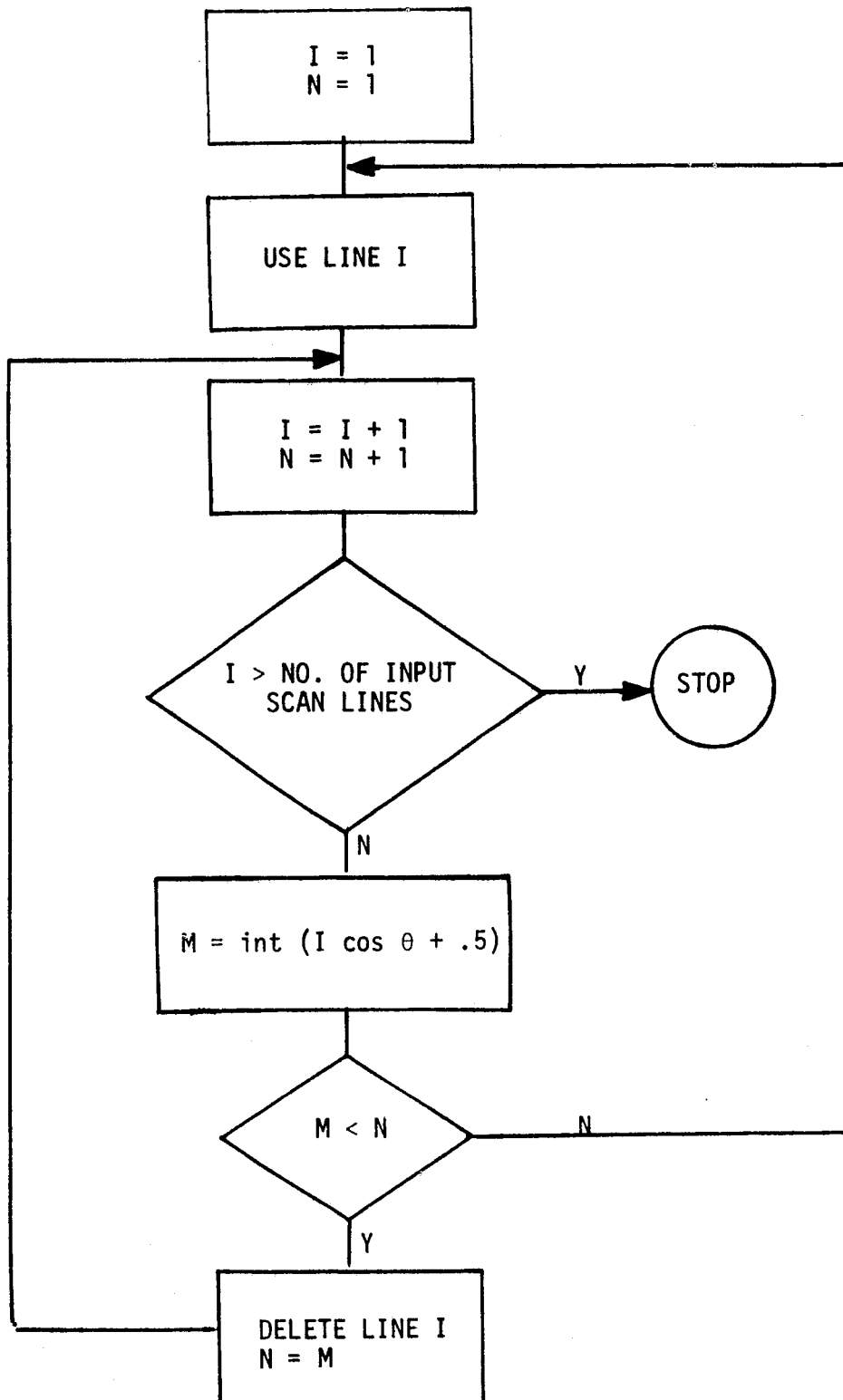


Figure 3-29 Scan Line Deletion Logic

sum is added to the contents of the first position in the intermediate buffer. Similarly, the third and fourth lines are added. Then a binary 1000 is added to each word of the intermediate buffer and it is right shifted 4 bits. This serves to round and divide by 16. Now the compressed line is written on disk and the next four selected lines are compressed. This continues until 2248 lines have been compressed and stored on disk. The 2500 scans on the input tape reduce to 2250 when scaled by $\cos 25.8^\circ$. The last two are deleted, since 2250 is not divisible by 4.

3.2.2.1.3 Line Resectioning Procedure (RTPHAS.EXC). A variable called IZ defines for each output line how many elements of compressed zero fill to use at one end of the output line, and a variable called IB defines how many elements of compressed image data to use from the buffer. In figure 3-30, cases 1 and 2 will have the output buffer filled from right to left, and cases 3 and 4 will have the output buffer filled from left to right. Output of resectioned lines from the rotation buffer starts after ISTART lines have been input. ISTART is computed as follows:

$$\text{ISTART} = \text{Int} \left(\frac{E_c \sin \theta}{4} + 0.5 \right)$$

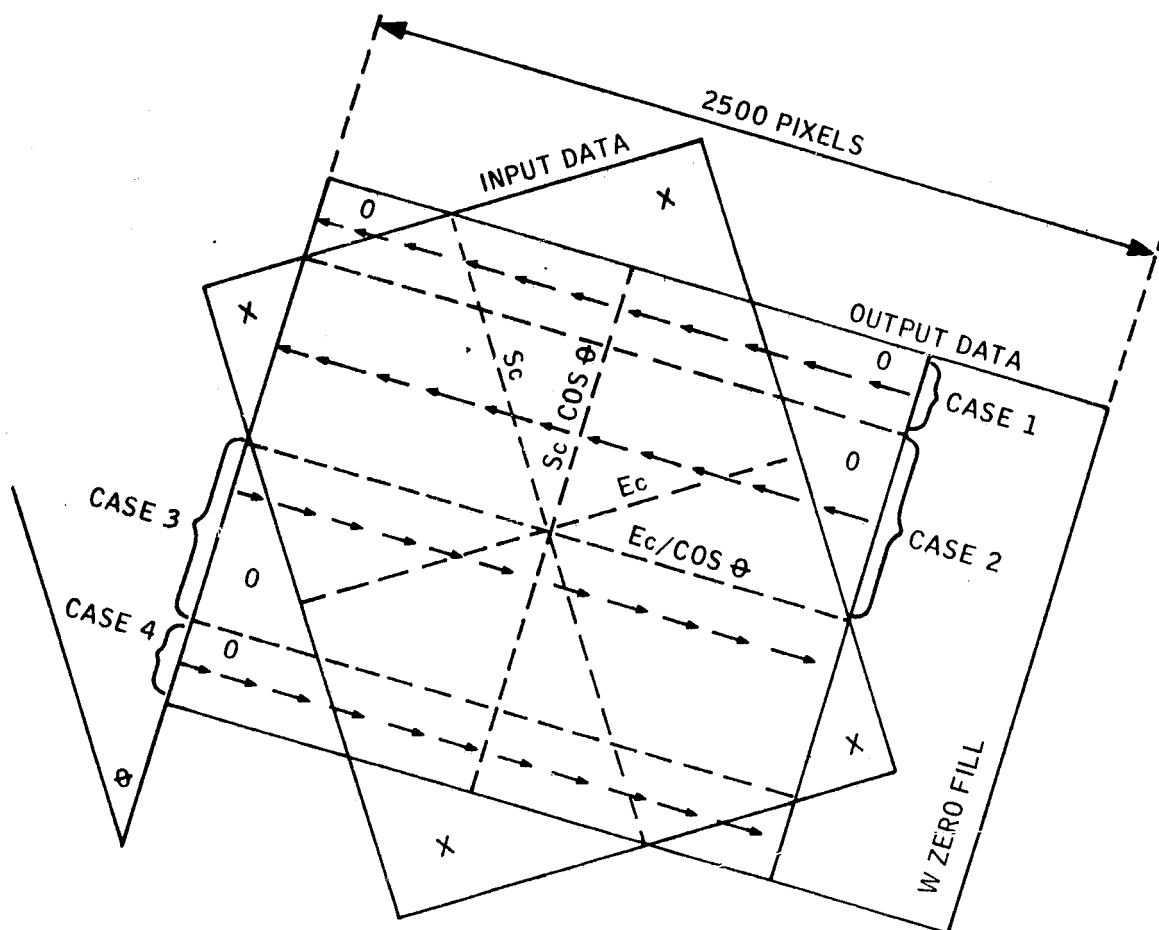
For an input line of 1800 PIXEL's and for which $\theta = 25.8^\circ$, ISTART = 98. In figure 3-30, we stay in case 1 and case 4 for a number of lines computed by:

$$\text{Int} \left[\frac{\tan \theta}{4} \left(\frac{E_c}{\cos \theta} - S_c \sin \theta \right) + 0.5 \right]$$

For $\theta = 25.8^\circ$, $E_c = 900$ and $S_c = 1250$, case 1 and case 4 are each 55 lines long. In figure 3-30, we stay in case 2 and case 3 for a number of lines computed by:

$$\text{Int} \left[\frac{1}{4 \cos \theta} \left(S_c - E_c \tan \theta + 0.5 \right) \right]$$

Case 2 and case 3 are each 226 lines long.



X DENOTES UNUSED INPUT DATA
 0 DENOTES ZERO FILL IN OUTPUT DATA
 E_c DENOTES HALF THE LENGTH OF A SCAN LINE IN THE INPUT TAPE IMAGE (900 PIXELS)
 S_c DENOTES HALF THE NUMBER OF SCAN LINES IN THE INPUT TAPE IMAGE (1250 SCANS)

Figure 3-30 Line Resectioning Procedure (Cases 1-4)

For cases 1 and 2, the formula for IZ is:

$$IZ = \text{Int} \left[\frac{\sin \theta}{4} \left(Sc \cos \theta - 4N \right) + 0.5 \right]$$

Where N = the number of resectioned lines that have already been output.

For case 1, the formula for IB is:

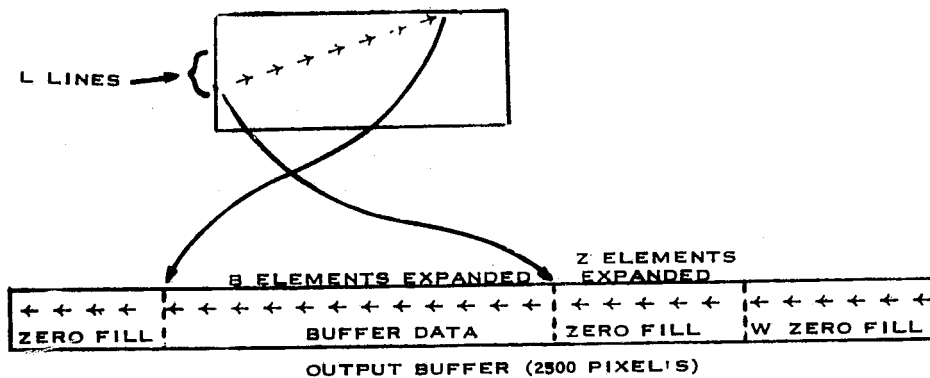
$$IB = \text{Int} \left[\frac{1}{4} \left(\frac{4N}{\sin \theta} + Ec \right) + 0.5 \right]$$

For case 2, the formula for IB is:

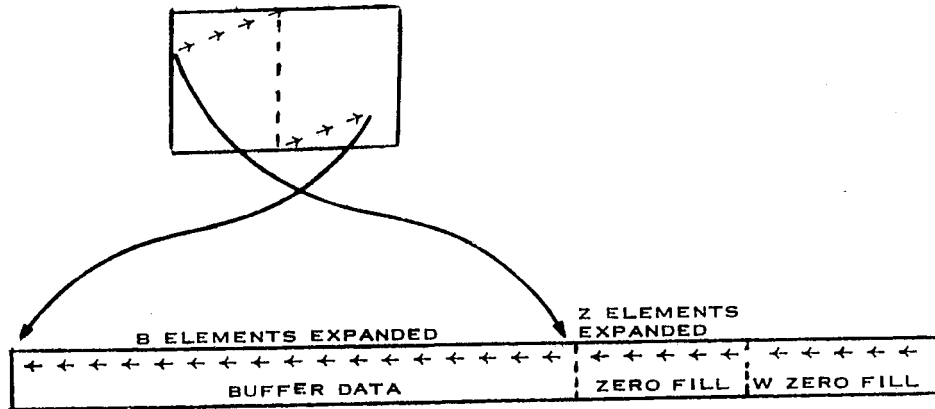
$$IB = (\text{buffer width}) - IZ$$

Formulas are needed only for cases 1 and 2, because the formulas are used backward for cases 3 and 4. Each case is described as follows.

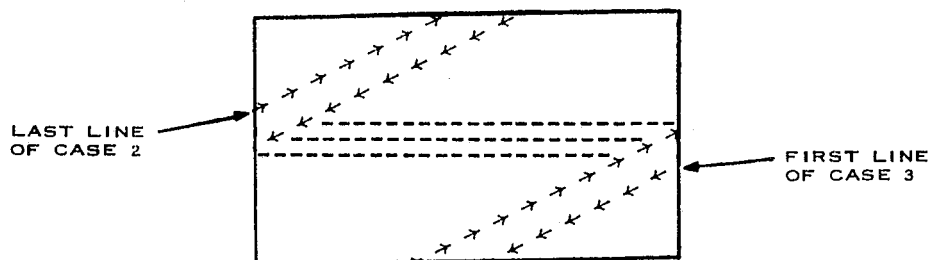
- A. Case 1. In the example below, we are resectioning the L'th line, and for line L the formulas say to take z elements of zero fill and b elements from the buffer. The order of the PIXEL's must be reversed, so the data is taken from the buffer in the proper way to accomplish this during the resectioning step. The top figure below is the rotation buffer; the bottom figure is the output buffer.



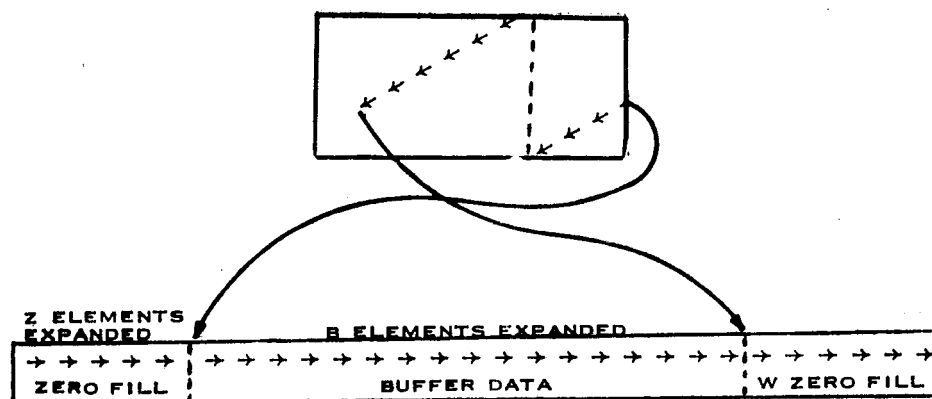
- B. Case 2. In this example, the L'th line is a case 2 line, and the formulas say to take z elements of zero fill and b elements from the buffer.



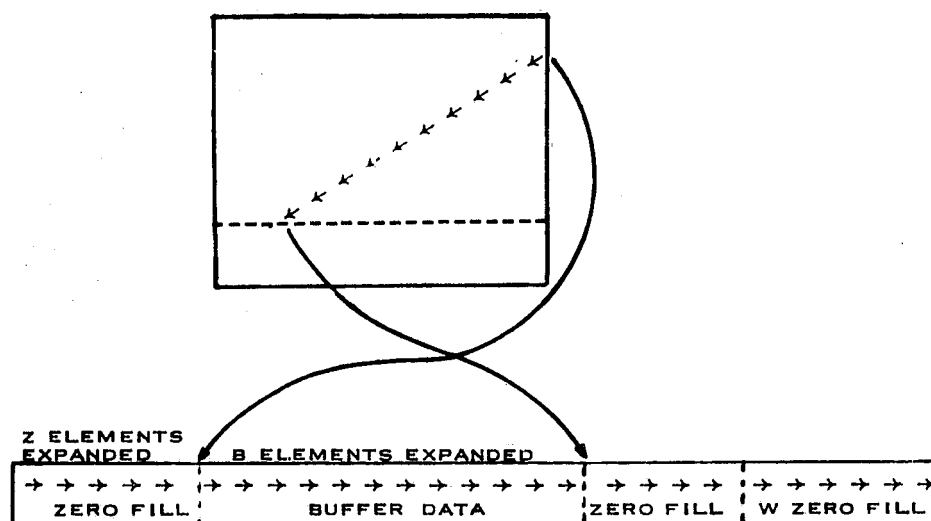
- C. Transition Between Case 2 and Case 3. In cases 1 and 2, data is always taken from the buffer beginning at the left edge of the buffer; in cases 3 and 4, it is always taken beginning at the right edge of the buffer. The last line of case 2 should use every buffer line. The last element of this last line of case 2 will be taken from the right edge of a buffer line. The next buffer line will be the one from which the first element of the first line of case 3 is taken.



- D. Case 3. In this example, the L'th line is a case 3 line. Let H denote case 1 + case 2 length (i.e., 281), ($1 \leq L \leq 2H$). The values we will use for line L will be $2H - L + 1$. Assume that the formulas say to take z elements of zero fill and b elements from the buffer.



- E. Case 4. In this example, the L'th line is a case 4 line. Let H denote the case 1 + case 2 length ($1 \leq L \leq 2H$). The values we will use for line L will be $2H - L + 1$. Suppose the formulas say to take z elements of zero fill and b elements from the buffer.



3.2.2.1.4 Scaling of Resectioned Line. When assembling the resectioned line in the output buffer, the elements in the buffer lines are repeated an average of $4/\cos \theta$ times. This serves to decompress the line 1:4 and scale by a factor of $1/\cos \theta$. A table called ITABLE is made, telling how many times each element is repeated when assembling the resectioned line. Another table called JTABLE, is made, telling how many elements to take from each buffer line. Let w denote the buffer width and ℓ denote the buffer length. Let $R = w/\ell$. Then we will be taking an average of R elements from each buffer line.

For an angle of 25.8° and input scan line length of 1800 PIXEL's, the rotation buffer is 196 lines long and 450 elements wide. R is approximately 2.3, which means that sometimes two and sometimes three elements are taken from each scan line. In general, if E_c denotes half the number of PIXEL's in each input scan line, then $w = \text{int} [(2 E_c/4) + 0.5]$ and $\ell = \text{int} [(2 E_c/4) \sin \theta + 0.5]$.

As mentioned previously, JTABLE is a table set up to tell how many elements to take out of each of the ℓ buffer lines in assembling the resectioned line in the output buffer. ITABLE is a table set up to tell how many times each of the elements is to be repeated in assembling the resectioned line in the output buffer.

We continue to output one half buffer-full of resectioned lines after the last buffer line has been put in from the disk. The last line put out is the line which equals case 1 + case 2 + case 3 + case 4 = 562.

3.2.2.1.5 Editing the EU Image to 1800 PIXEL's per Scan. Because of buffer limitations for the resectioning at the 25.8° -degree angle, the coarse rotation can be done only on scan lines of 1800-PIXEL length. The SEN tape has scan lines 1801 to 2501 PIXEL's long, and these must be edited to 1800 PIXEL's before the scan line resectioning in the RTPHAS load module.

Registration coefficients are generated to register the entire EU image. When the scan lines are shortened in coarse rotation, the editing must be taken into account during the registration phase.

To build the header of the CRT tape, NTROTN does a SEG call to REGHED. The load module REGHED is also part of the registration (REG) CPC, and will be discussed in more detail in paragraph 3.2.3.1. Discussion in this paragraph is limited to those functions of REGHED specifically pertaining to coarse rotation.

REGHED reads IFSPPIX (the start PIXEL number) and IENPIX (the end PIXEL number) from the SEN tape header, and then calculates the correct header information to write on the header of the CRT tape. A discussion of these calculations follows.

The operator picks a point in the reference grid that he wants to be on the left edge of the registered night pass image. (Assume that the scan lines in the reference grid are numbered from 1 at the bottom to 2200 at the top.) Let the chosen point have coordinates (X,Y). The operator defines the values of X and Y in a DATA statement in REGHED. The current choice of (X,Y) is (375,1200), chosen in an attempt to optimize coverage of south Texas.

In REGHED, the position in the input image of the point (X,Y) is located by the formula:

$$\begin{aligned}\text{EDGEPIX} &= \text{RA1} + \text{EBAR} + \text{RA2} * \text{X} + \text{RA3} * \text{Y} \\ \text{EDGESN} &= \text{RB2} + \text{SBAR} + \text{RB2} * \text{X} + \text{RB3} * \text{Y}\end{aligned}$$

Assuming that the entire EU image will be coarse rotated, (EDGEPIX, EDGESN) would be the point in the coarse rotated image which would be mapped into (X,Y) at registration.

Now, (EDGEPIX, EDGESN) must be inverse-rotated to find the inverse rotated EDGEPIX. In REGHED, the same name (EDGEPIX) is used after the inverse rotation. Let CNTPIX be half the width of the EU image; then:

$$\text{CNTPIX} = \text{FLOAT} (\text{IPXLST} - \text{IPXONE} + 2) / 2$$

Let CNTSN be half the length of the EU image (i.e., 1250). Then:

$$\begin{aligned}\text{EDGEPIX} &= \text{CNTPIX} + (\text{EDGEPIX} - \text{CNTPIX} / \cos 25.8^\circ) * \cos 25.8^\circ \\ &\quad + (\text{EDGESN} - \text{CNTSN} * \cos 25.8^\circ) * \sin 25.8^\circ\end{aligned}$$

This inverse-rotates EDGEPIX.

Now EDGEPIX is the PIXEL number of the point in the input EU image which would map into (X,Y). This assumes the start PIXEL number is 1 in the input EU image, which is the same assumption made in the GCP location phase and in the generation of the registration coefficients. Since EDGEPIX+1799 may be outside the input image, the start PIXEL must be recalculated to get the best 1800 PIXEL's. Let IRTPIX = min (width of input image, EDGEPIX+1799). Then:

$$\text{IRTPX} = \text{MIN} (\text{IPXLST}-\text{IPXONE}+1, \text{EDGEPIX}+1799)$$

Then, let ILFTPX = MAX (1, IRTPIX-1799). Now ILFTPX marks the left edge of the 1800-PIXEL-wide portion to be taken from the EU image for actual coarse rotation. REGHED puts the value of ILFTPX in COMMON/GCOEFF/ to be used in the NTROTN load module.

Now REGHED calculates the start PIXEL number of the coarse rotated tape, to be written in the header. Consider the point in the EU input image defined by:

$$\begin{aligned} E &= \text{ILFTPX} \\ S &= 1250 + 900 * \tan 25.8^\circ \end{aligned}$$

The point (E,S) should appear on the left edge of the registered coarse rotated image. Thus, to find the start PIXEL number of the coarse rotated tape, (E,S) must be rotated. So, let:

$$\begin{aligned} \text{ER} &= \text{CNTPIX} / \cos 25.8^\circ + (E - \text{CNTPIX}) * \cos 25.8^\circ \\ &\quad - (S - \text{CNTSN}) * \sin 25.8^\circ \\ \text{SR} &= \text{CNTSN} * \cos 25.8^\circ + (E - \text{CNTPIX}) * \sin 25.8^\circ \\ &\quad + (S - \text{CNTSN}) * \cos 25.8^\circ \end{aligned}$$

Note that in the REGHED program listing, ER and SR are named E and S. ER is the start PIXEL number that REGHED writes in the header of the coarse rotated tape. This is IFSPPIX in COMMON/TPFRMT/.

The center of the actual coarse rotated image is not the same as the center would be if the entire EU input image were coarse rotated. The number of scan lines ($2500 * \cos 25.8^\circ$) is the same in each case. The center of the actual coarse rotated image is on scan line SR of the hypothetical coarse rotated entire EU image. This results in a displacement of scan lines (i.e., scan line 1

of the actual coarse rotated image would not be scan line 1 of the image obtained if the entire EU input image were coarse rotated. The registration formulas assume that the entire EU image is coarse rotated; therefore, an adjustment must be added for the scan line displacement. This adjustment is called IDEL in REGHED. Let:

$$IDEL = SR - (2500 * \cos 25.8^\circ) / 2$$

IDEL is written by REGHED in bytes 117-118 of the header. It will be read by REGHED during the registration phase, when the REGHED load module is called from the SREG module. IDEL is in COMMON/TPFRMT/.

After writing the coarse rotated tape header, REGHED returns to NTROTN, which uses ILFTPX to calculate the actual PIXEL in the input tape at which to begin taking the 1800 PIXEL's. ILFTPX cannot be used directly because it was calculated assuming that the left-to-right reversal of the night image had already been done. However, at the beginning of the night coarse rotation processing, each scan line is still reversed left-to-right. Let:

$$ISHIFT = (1PXLST-IPXONE) - (ILFTPX+1799)$$

The subroutine CMPRES will add ISHIFT to the address of the first PIXEL in the input buffer to get the address at which to begin taking the 1800 PIXEL's.

3.2.2.2 Flow Charts. See table 3-3 for a definition of symbols used in the flow charts on the following 39 pages.

TABLE 3-3
DEFINITION OF SYMBOLS FOR ROT FLOWS

ICAS (I) - NUMBER OF LINES TAKEN FROM ROTATION BUFFER FOR EACH OF FOUR CASES

ISTR = 98 - START OUTPUTTING RESECTIONED LINES AFTER ISTR LINES HAVE BEEN
PUT INTO ROTATION BUFFER

IW = $1800/4 = 450$ - ROTATION BUFFER WIDTH (WIDTH OF LINE)

IBFLTH = $2 \times \text{ISTR} = 196$ - ROTATION BUFFER LENGTH (NUMBER OF LINES)

IPIXL - LENGTH OF OUTPUT LINE

IS - ROTATION BUFFER INPUT SCAN LINE POINTER (1 to 196)

LP - BUFFER LINE POINTER; INCREMENTS IN CASES 1 AND 2, DECREMENTS IN CASES 3
AND 4

MPIXLC - COMPRESSED PIXEL COUNTER

ITABLE(MPIXLC) - NUMBER OF TIMES TO REPEAT COMPRESSED PIXEL IN BUILDING OUT-
PUT LINE

IBUFPX - ROTATION BUFFER PIXEL POINTER

JTABLE (LP) - NUMBER OF BUFFER PIXELS TO TAKE FROM BUFFER LINE LP TO BUILD
OUTPUT LINE

EC - $1800/2 = 900$

SC - $2500/2 = 1250$

IPIXLC - OUTPUT BUFFER POINTER; DECREMENTS IN CASES 1 AND 2, INCREMENTS IN
CASES 3 AND 4

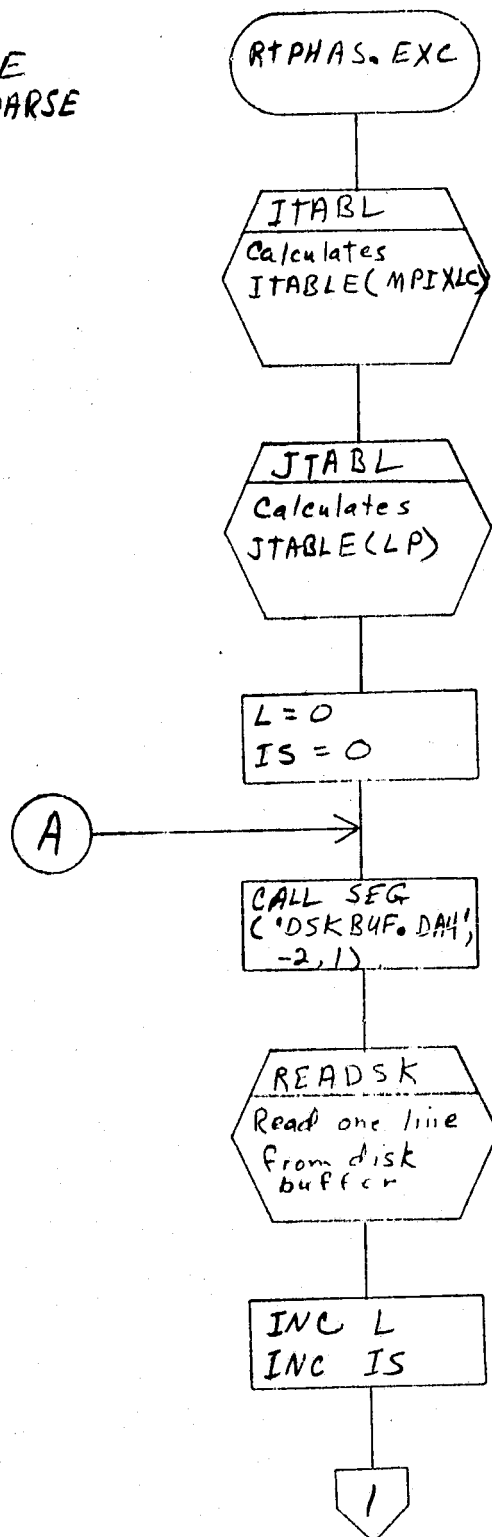
IZ - COMPRESSED ZERO FILL PIXELS

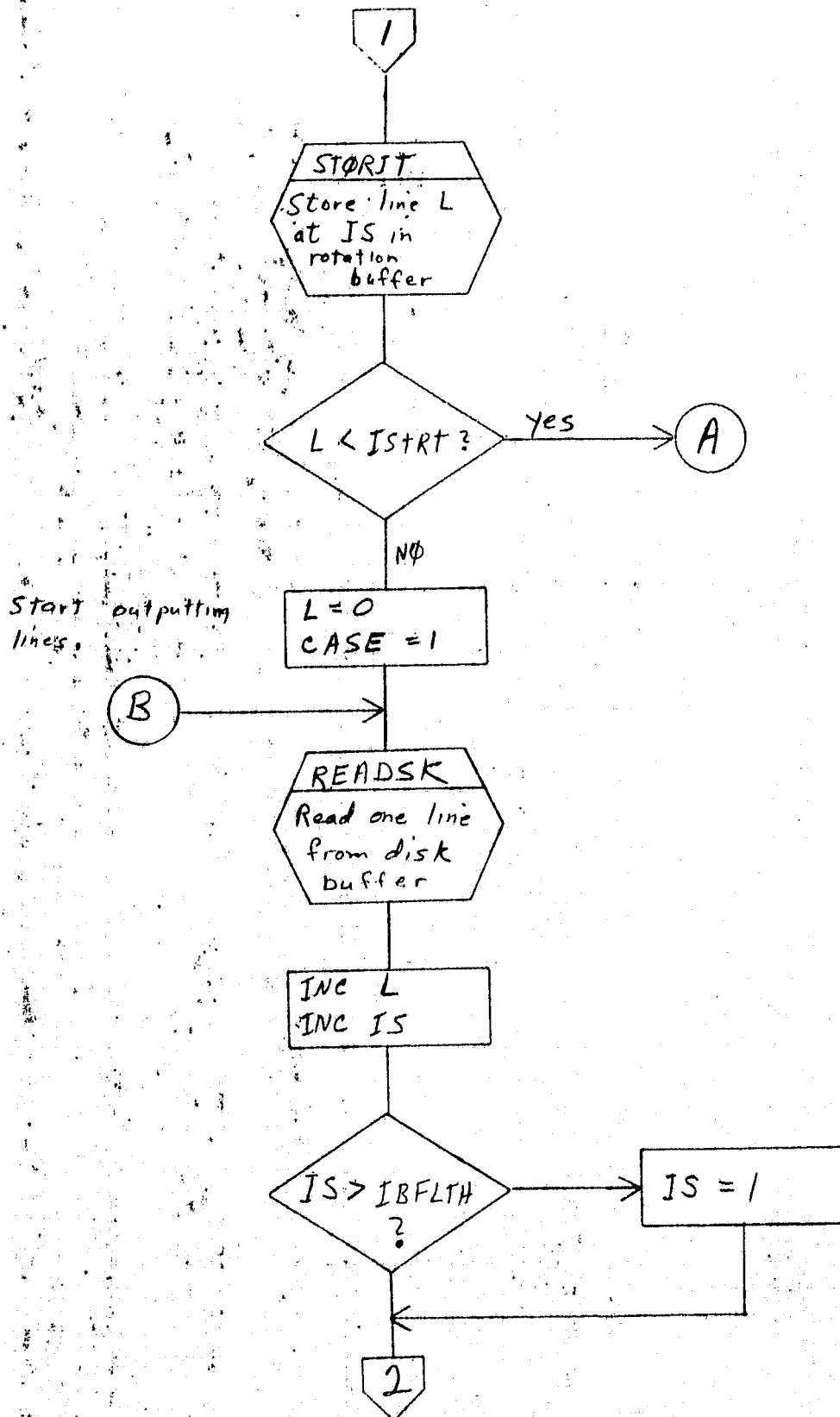
IB - NUMBER OF ROTATION BUFFER PIXELS NEEDED TO BUILD OUTPUT LINE

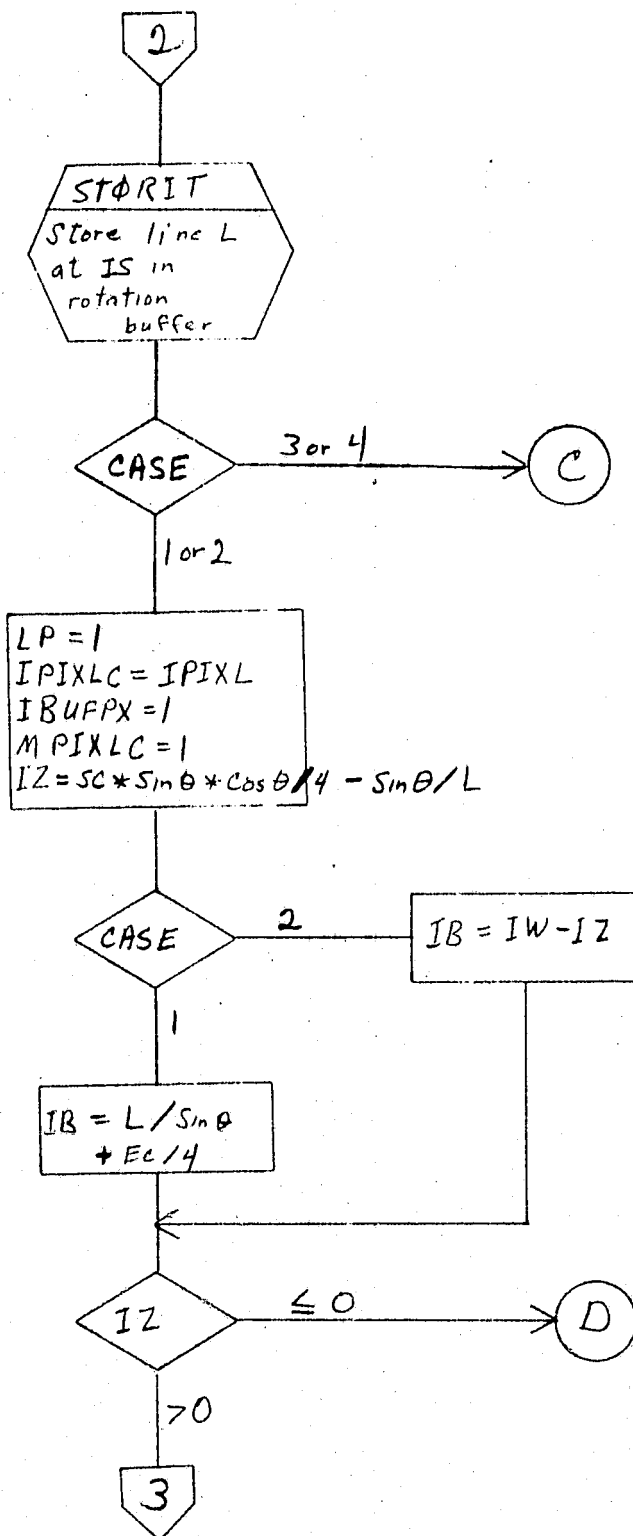
JTABLC - COUNTER FOR JTABLE(LP) (i.e., COUNTS BUFFER PIXELS USED FROM BUFFER
LINE LP TO BUILD OUTPUT LINE)

IH - HALF THE NUMBER OF OUTPUT LINES TAKEN FROM ROTATION BOFFER, [i.e., ICAS(1)
+ ICAS(2) = 281]

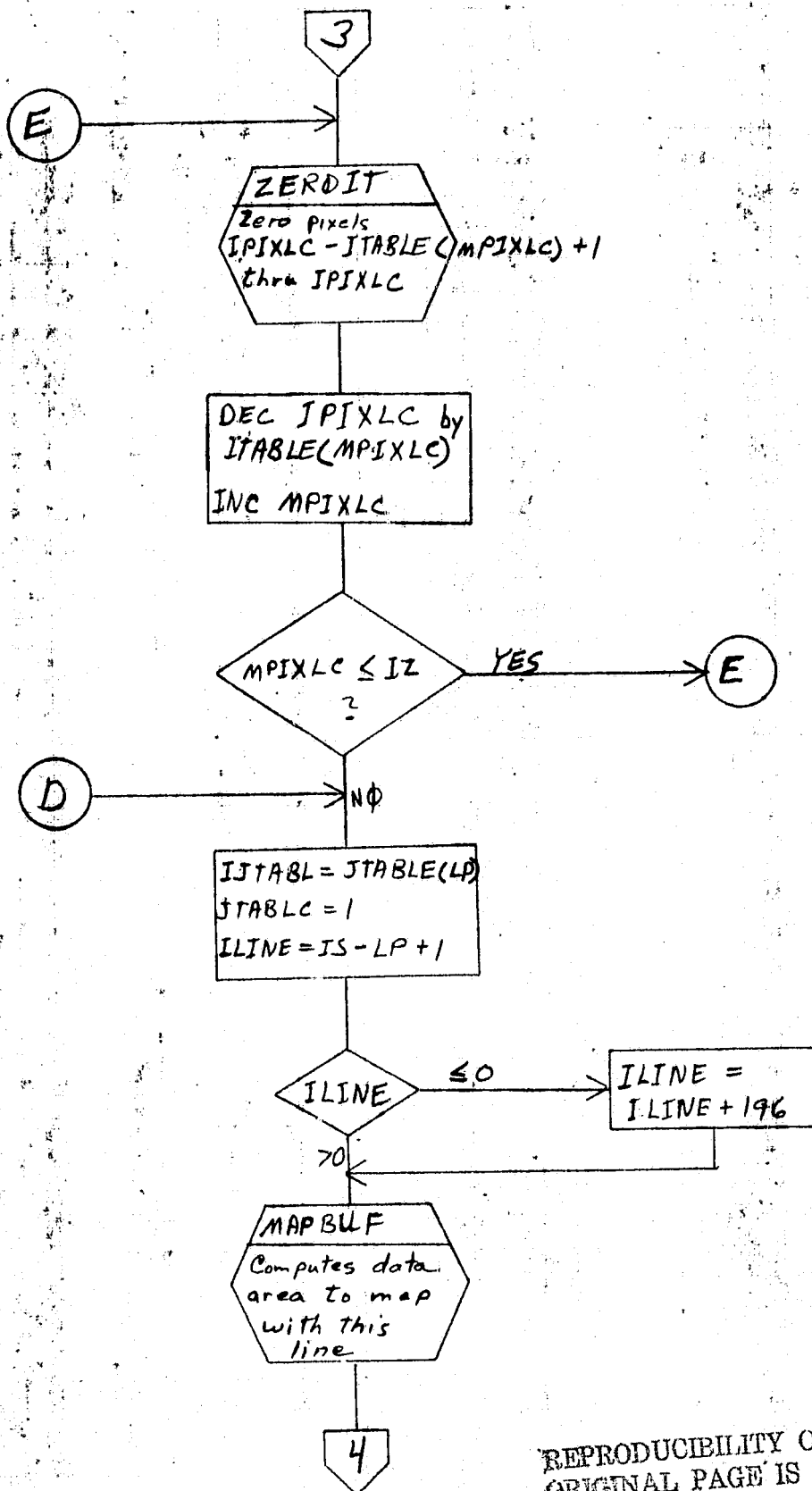
ROTATION PHASE
OF NIGHT COARSE
ROTATION



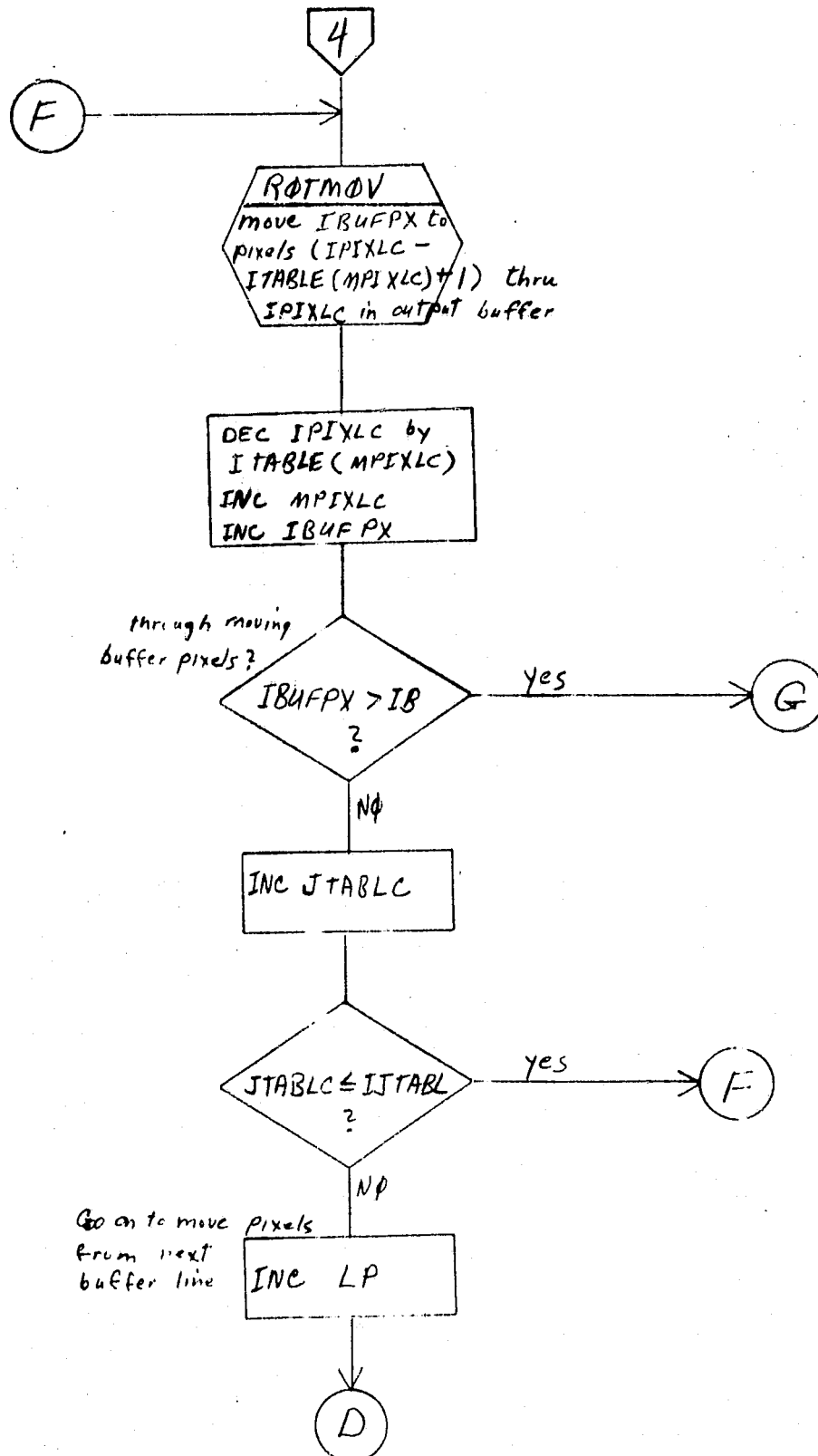


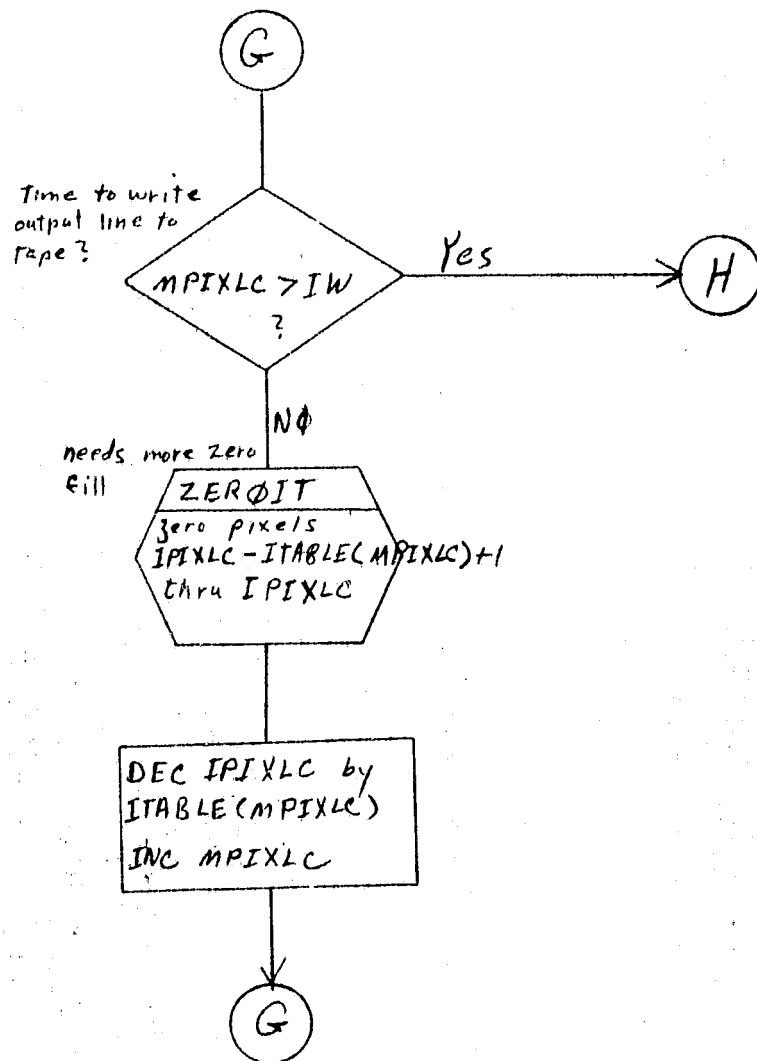


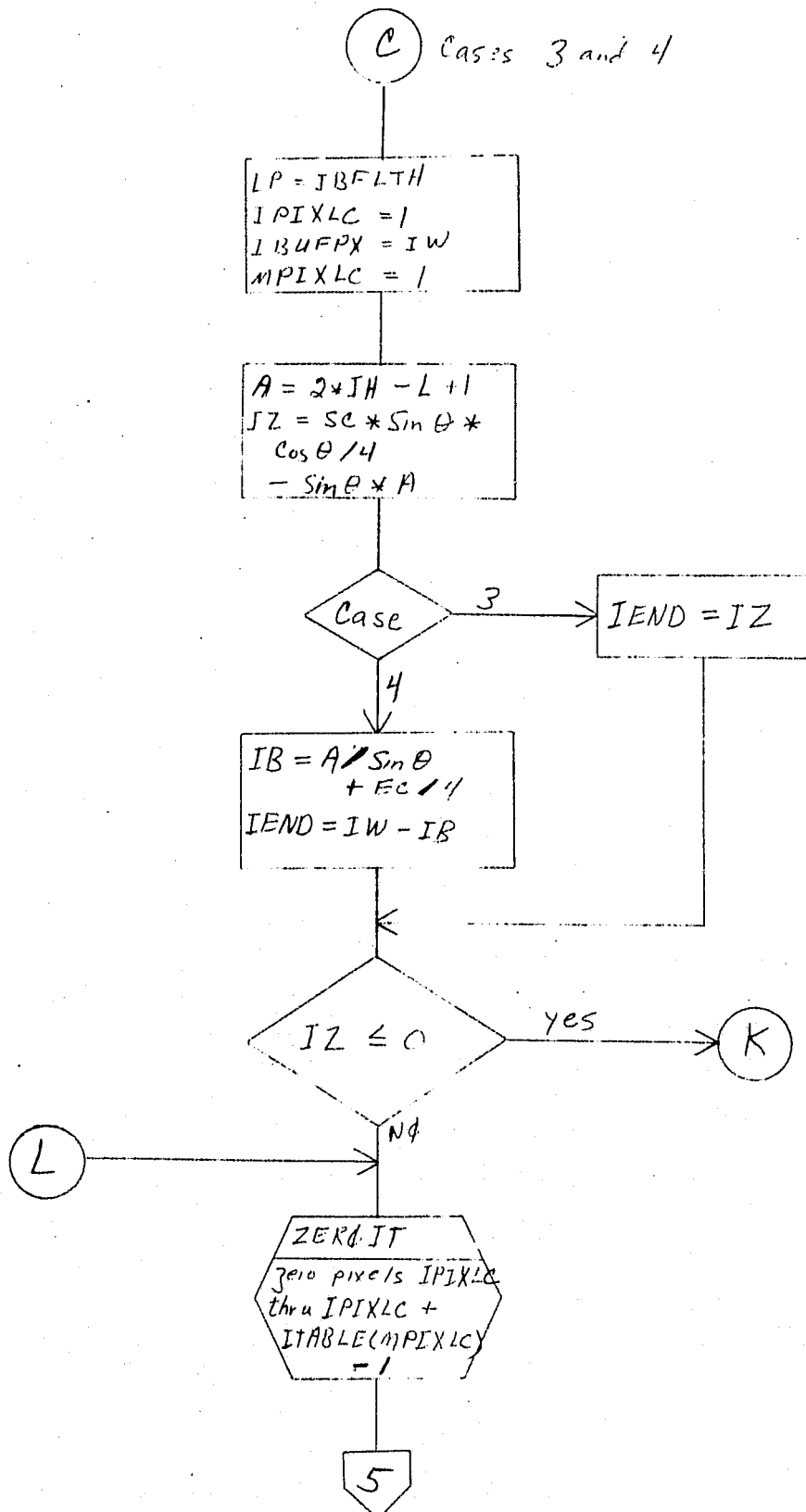
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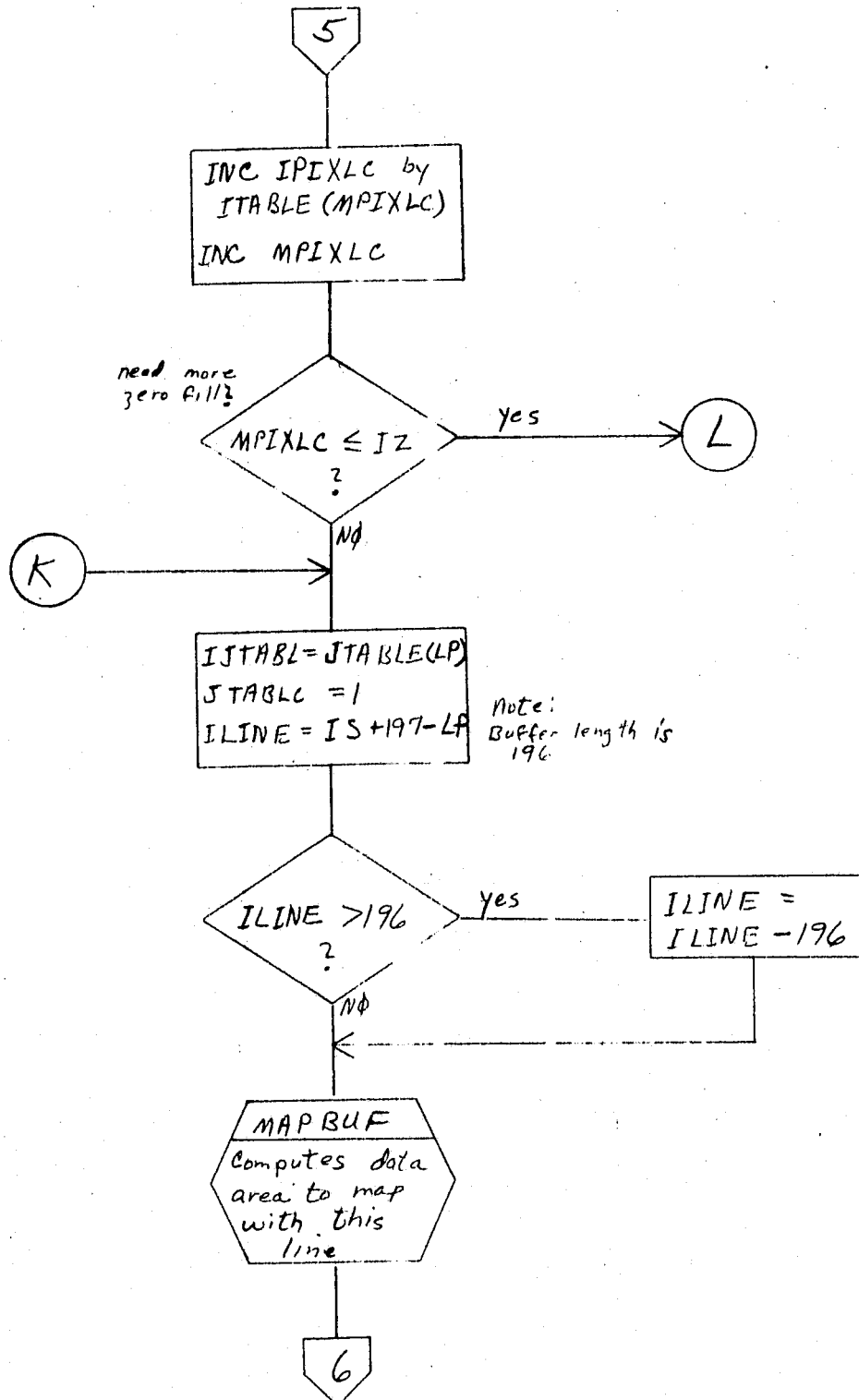


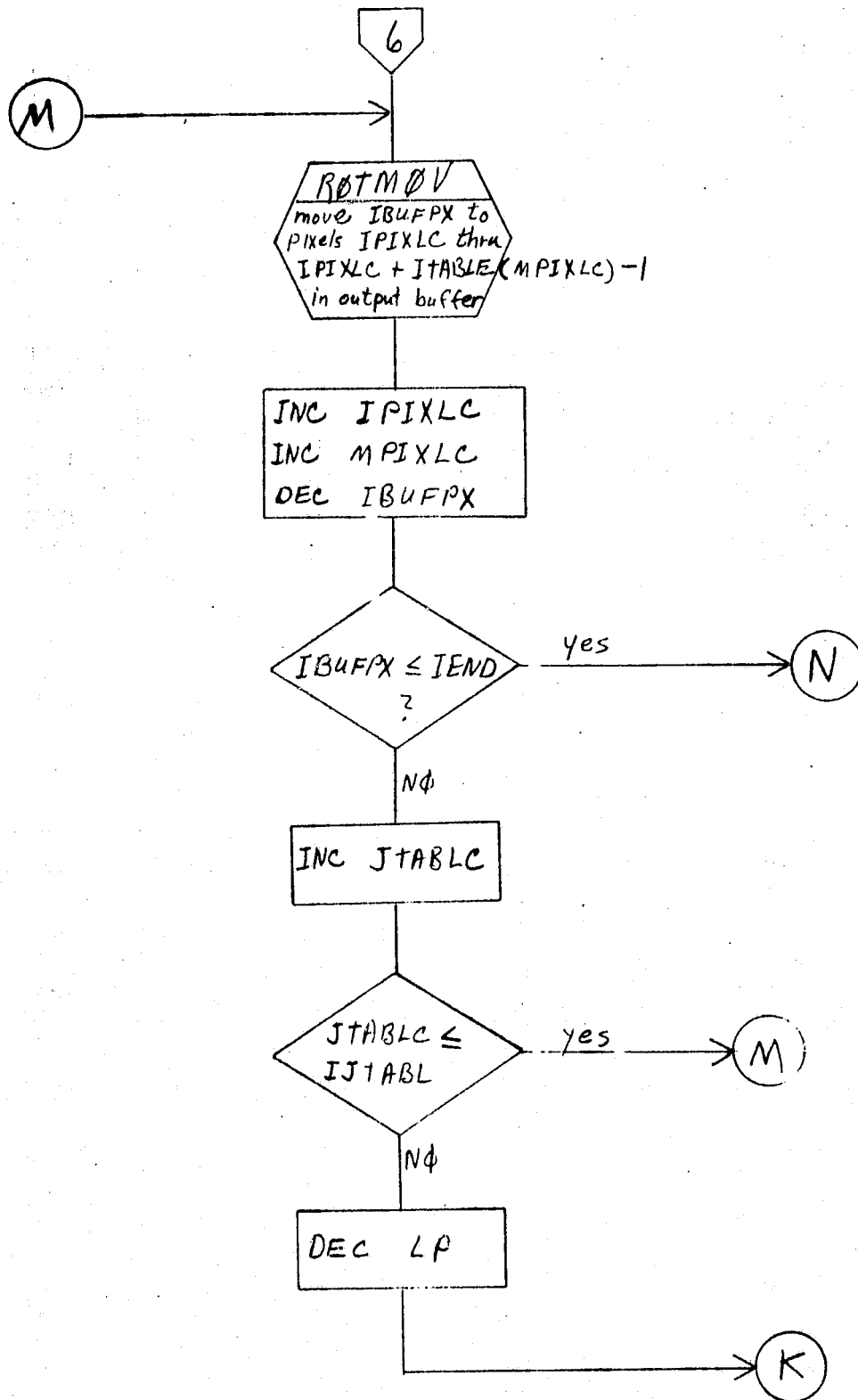
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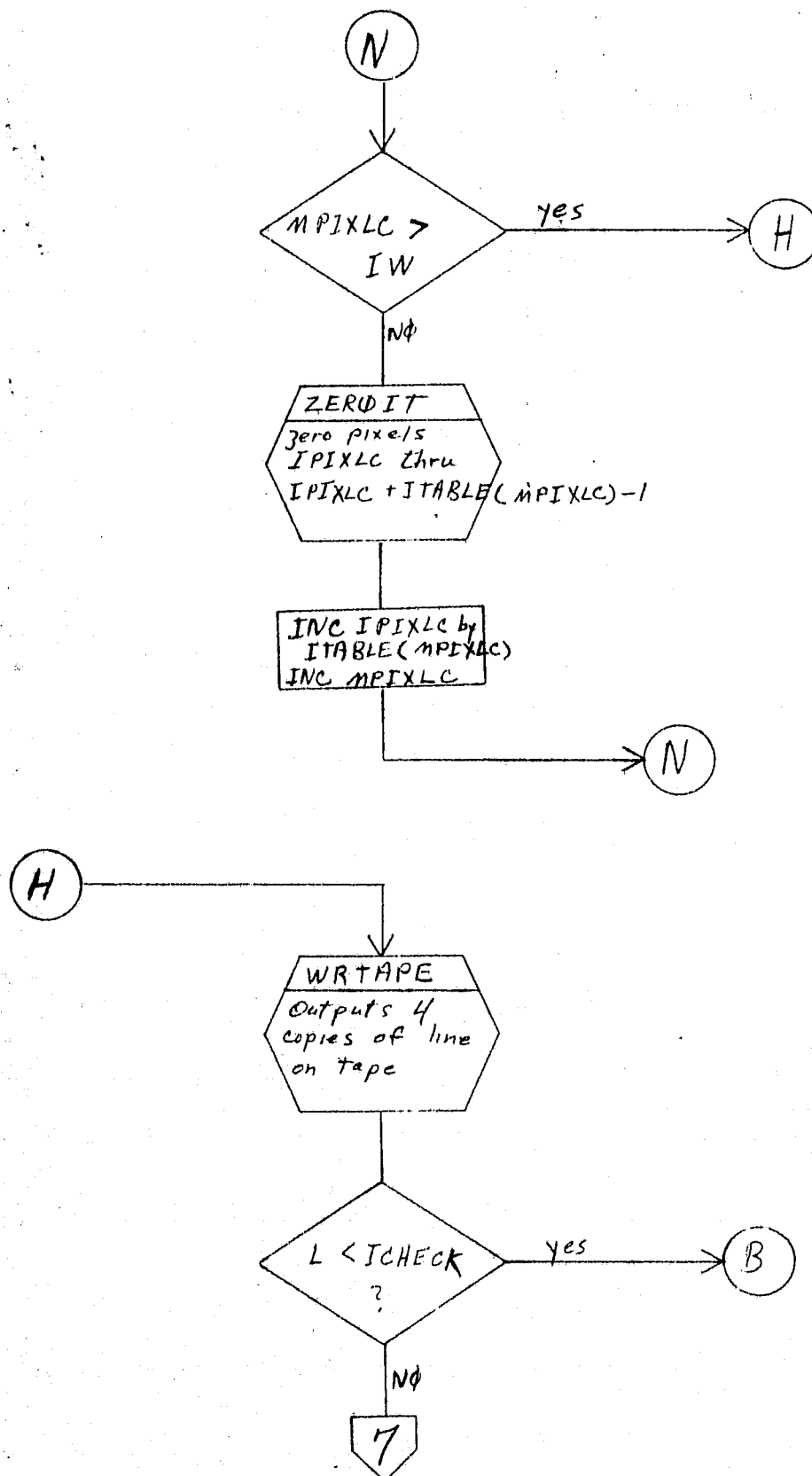


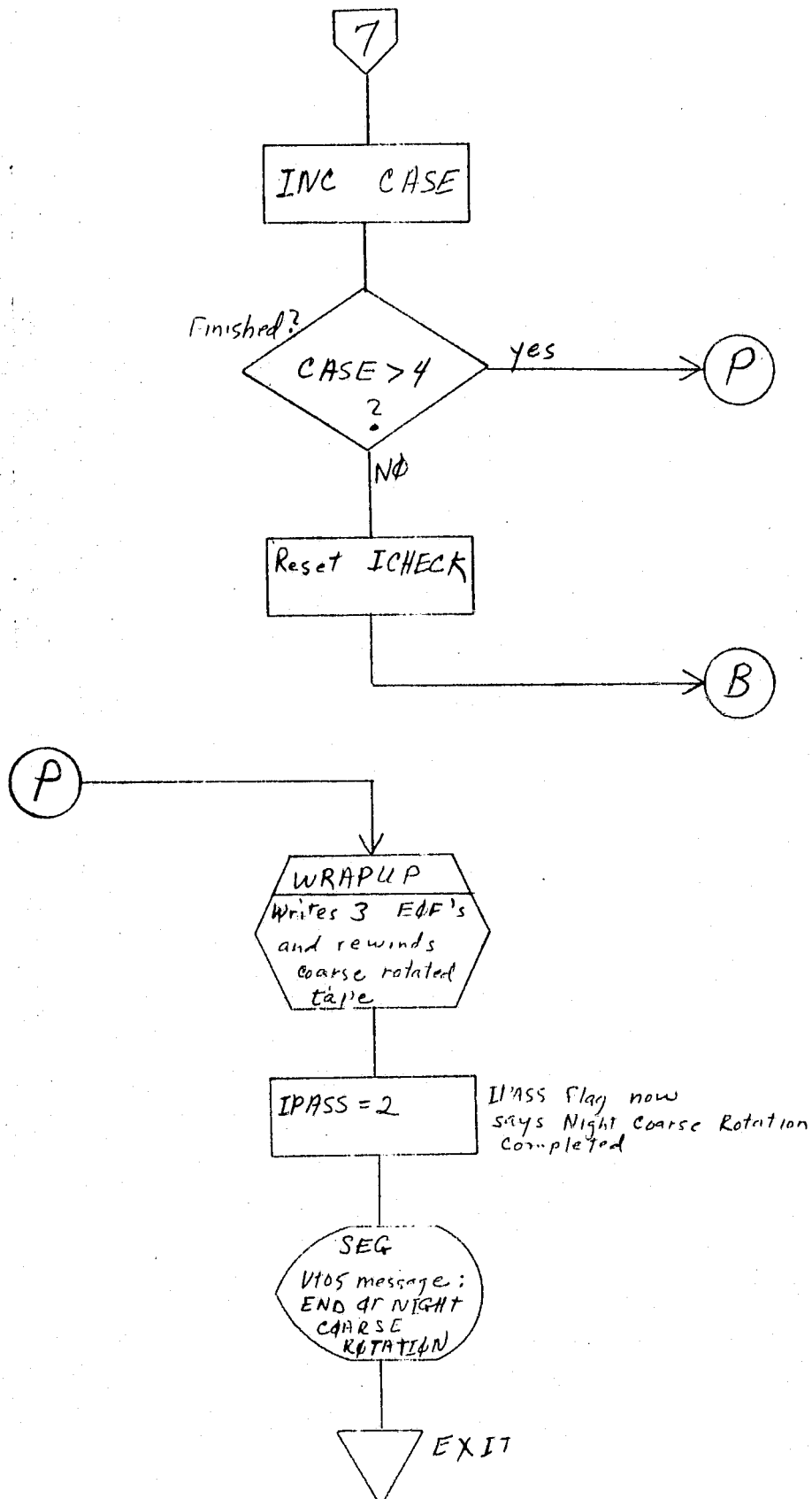


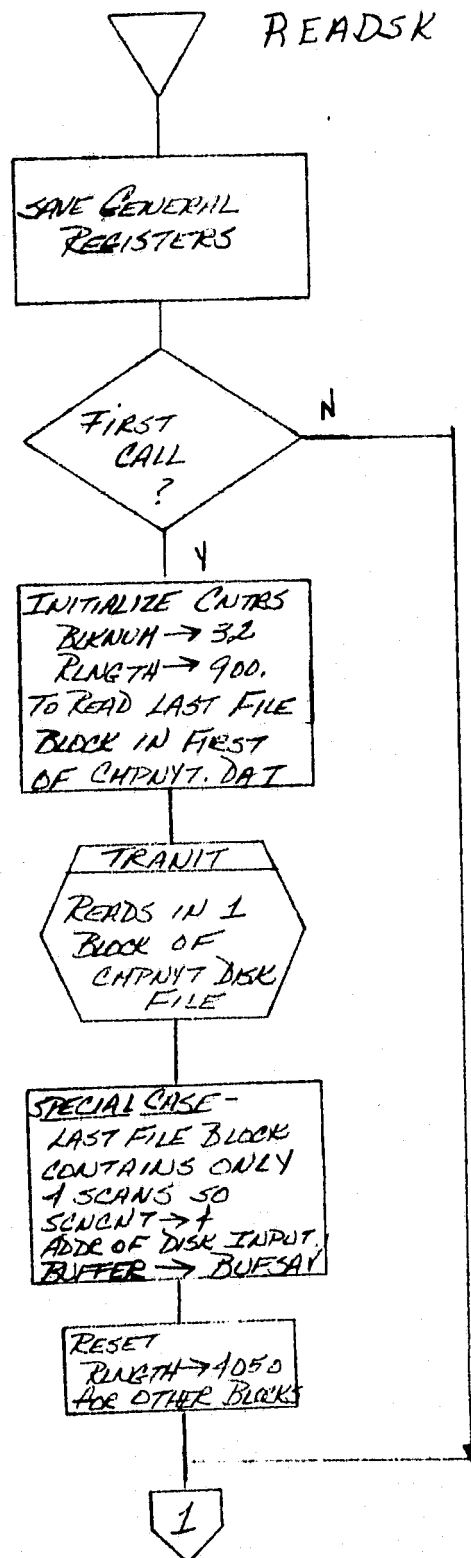


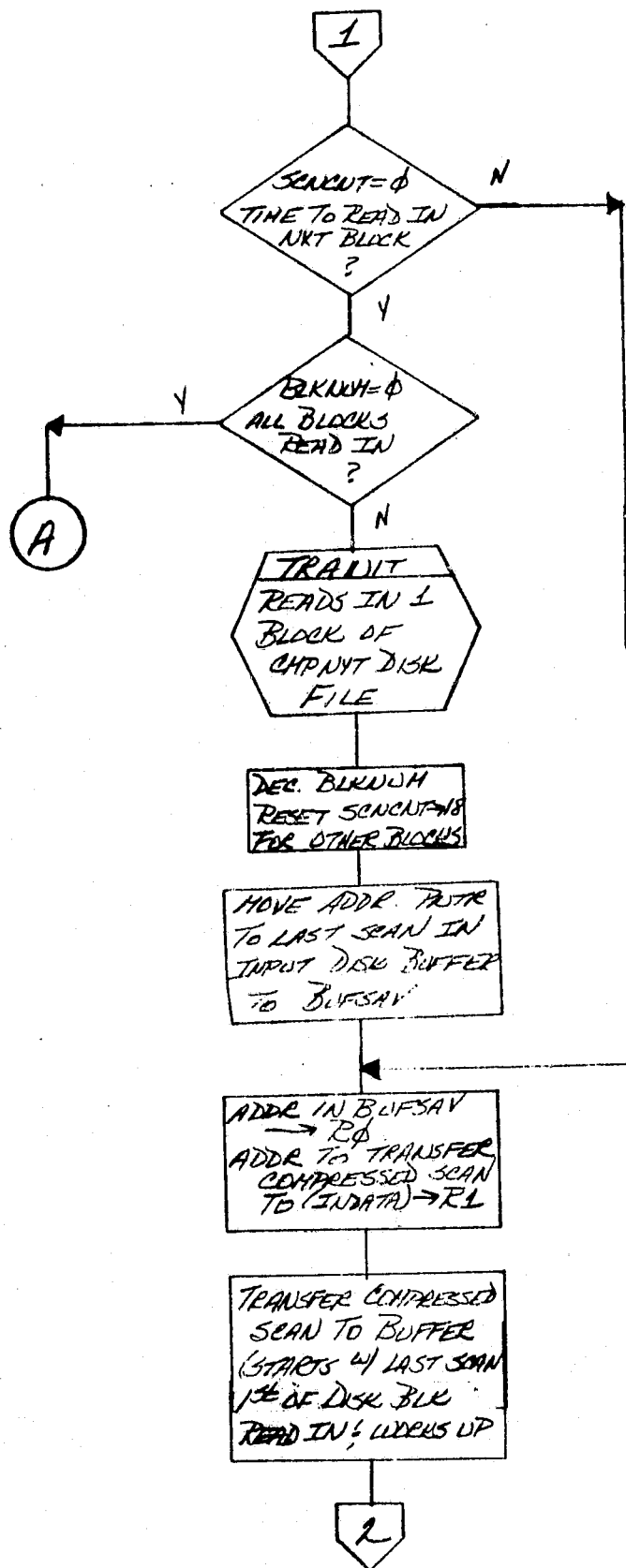


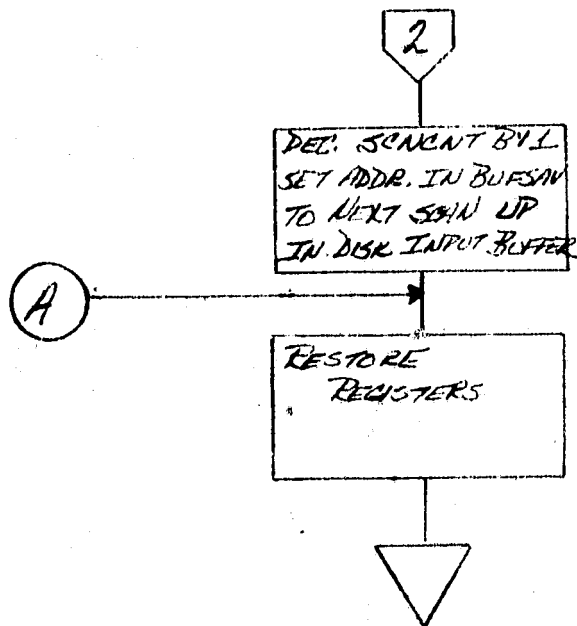


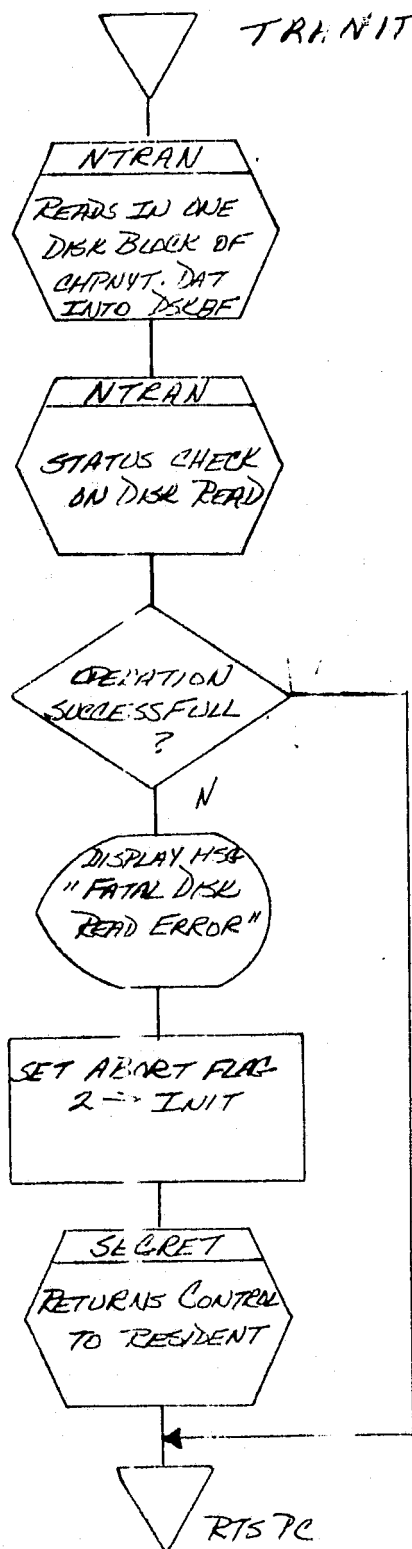


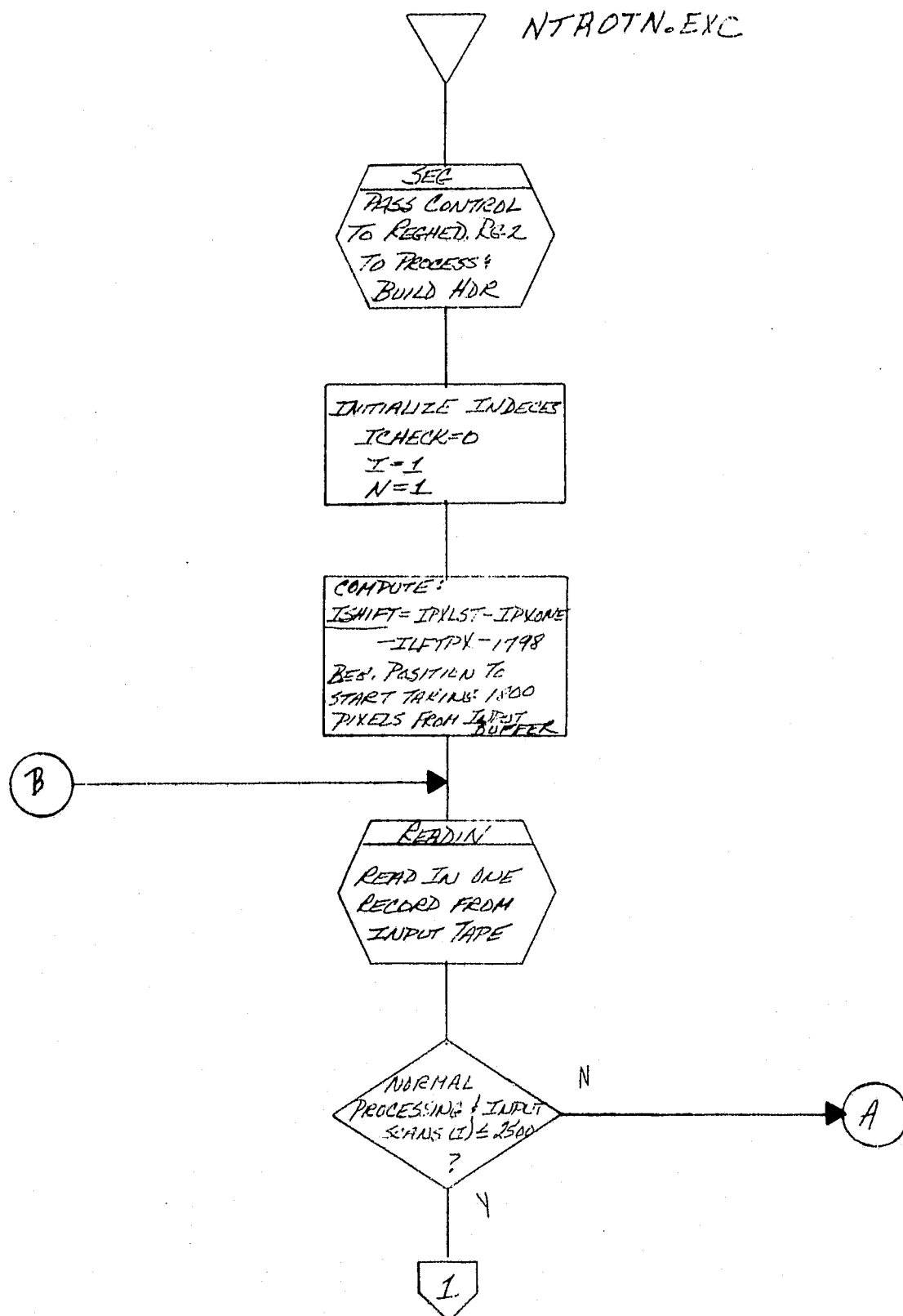




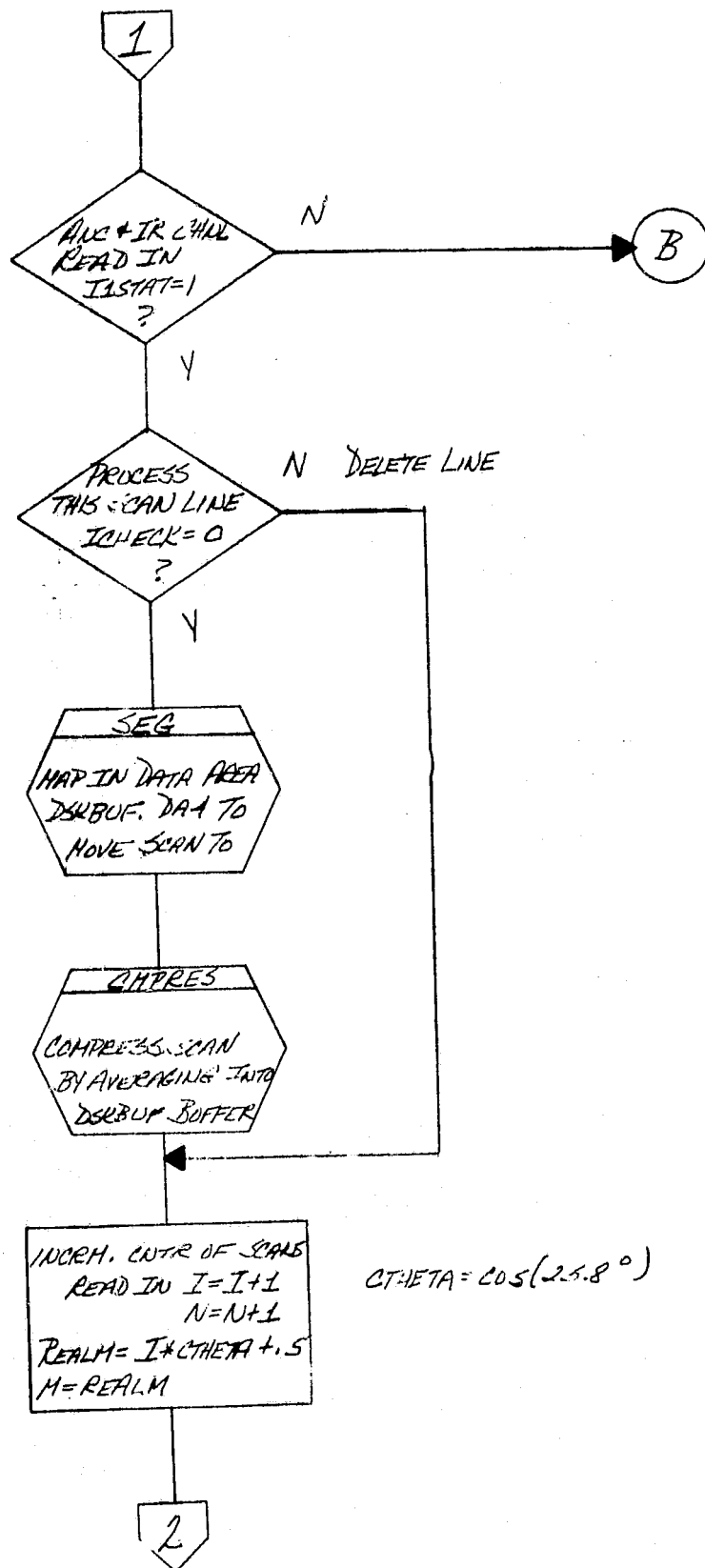


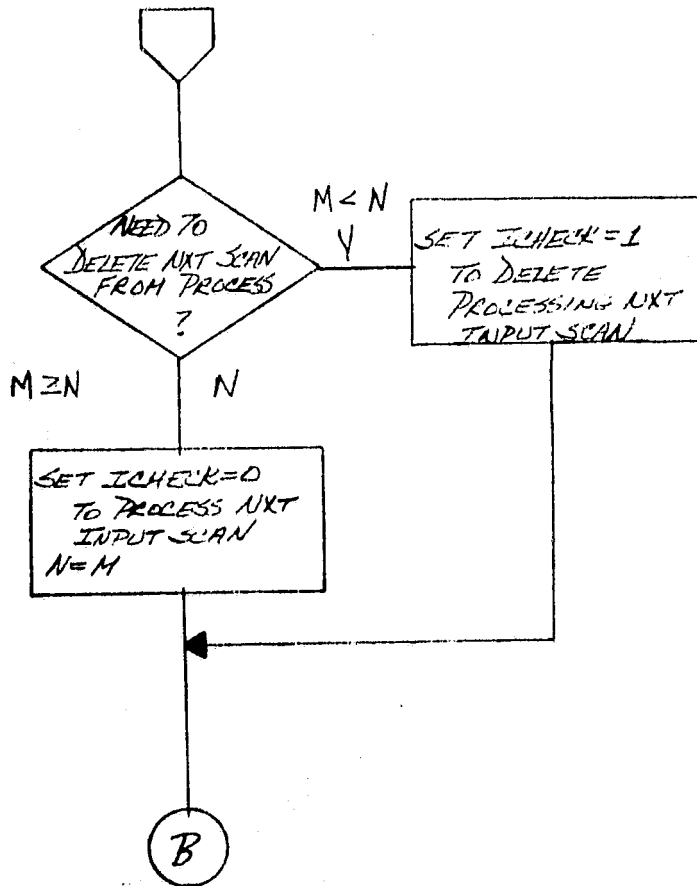


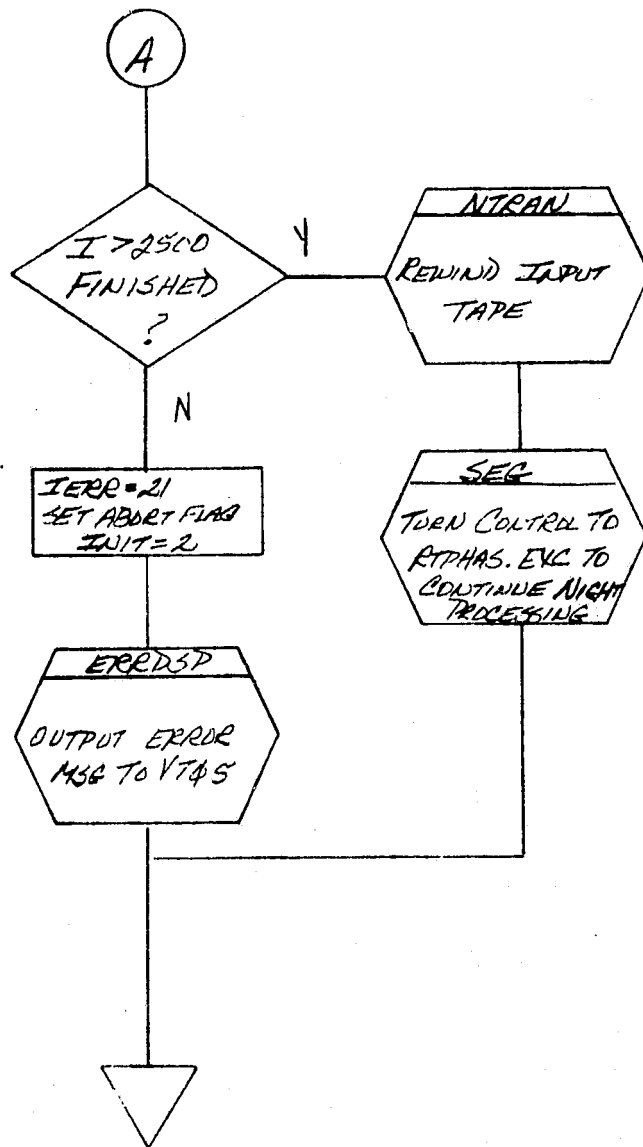


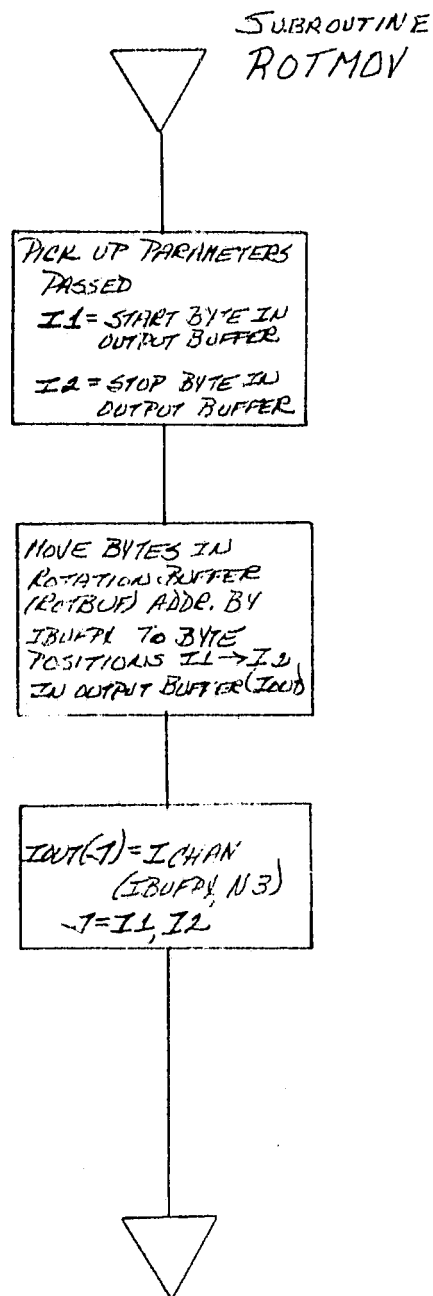


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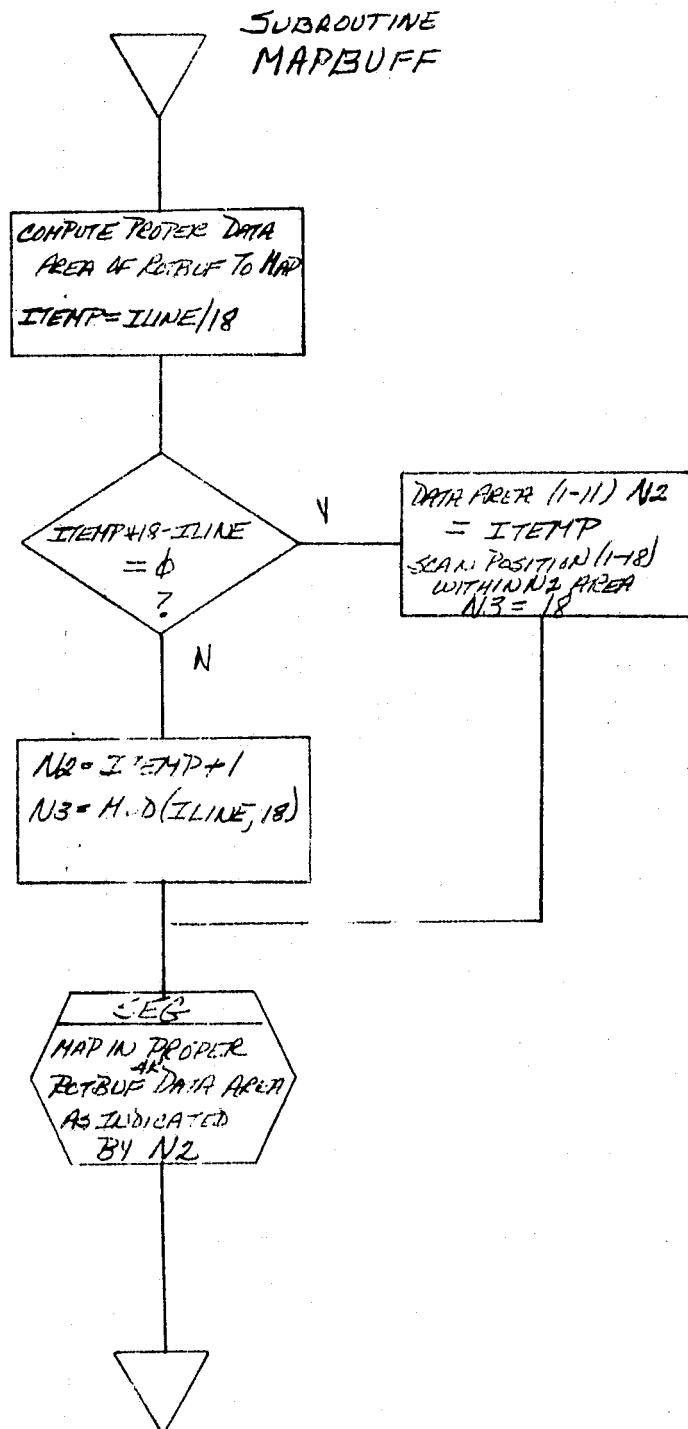


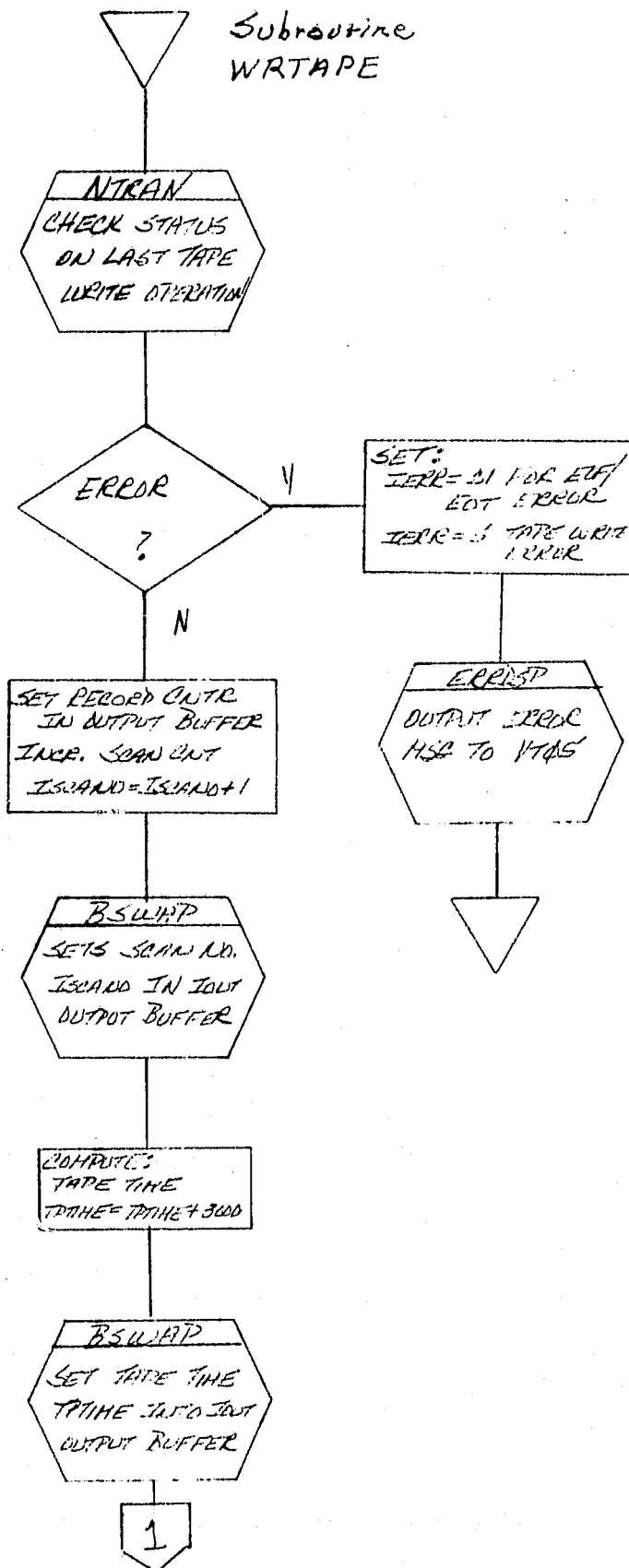


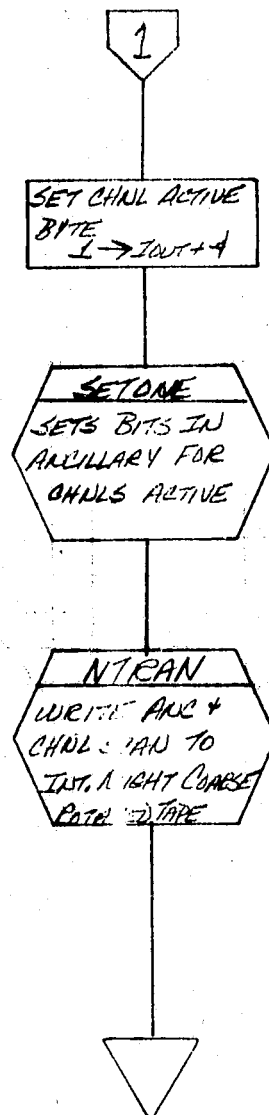


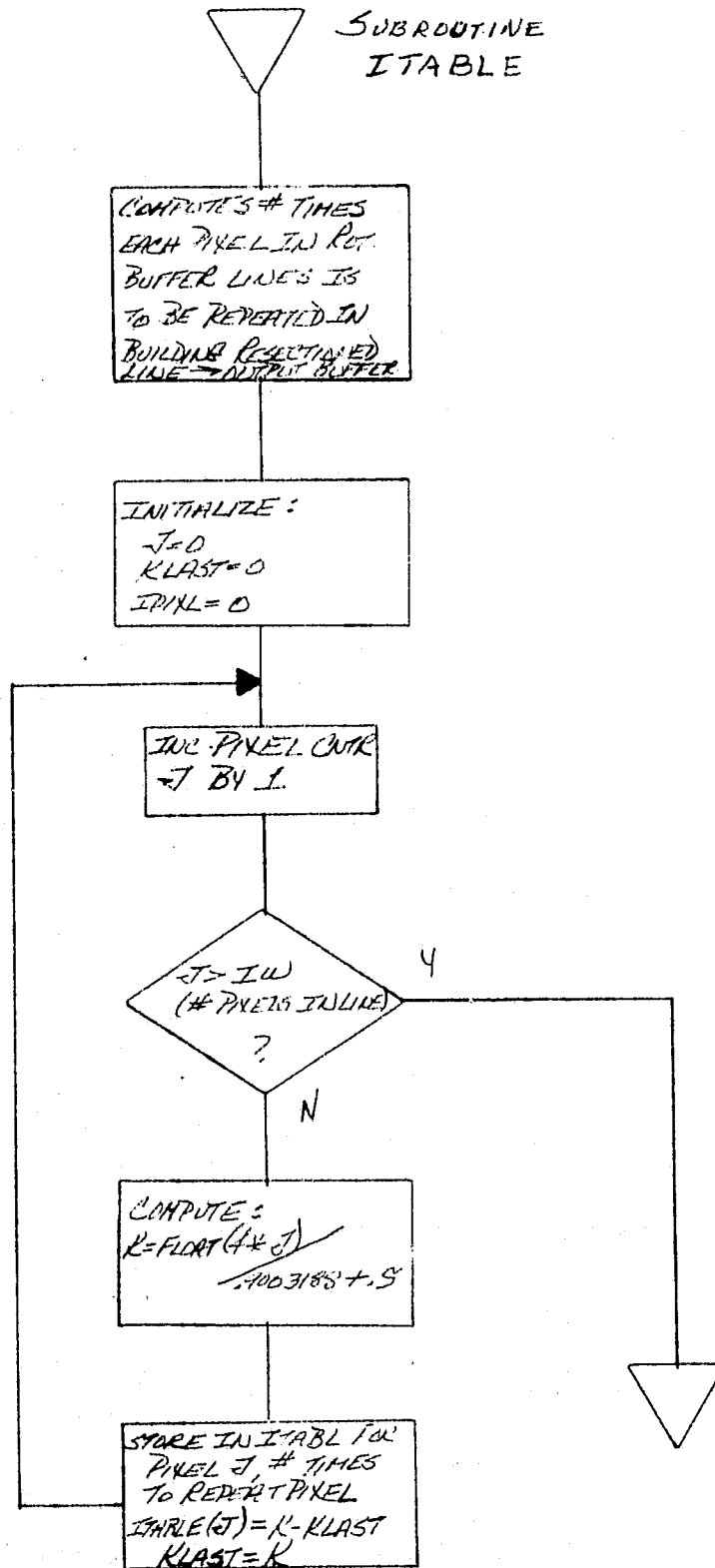


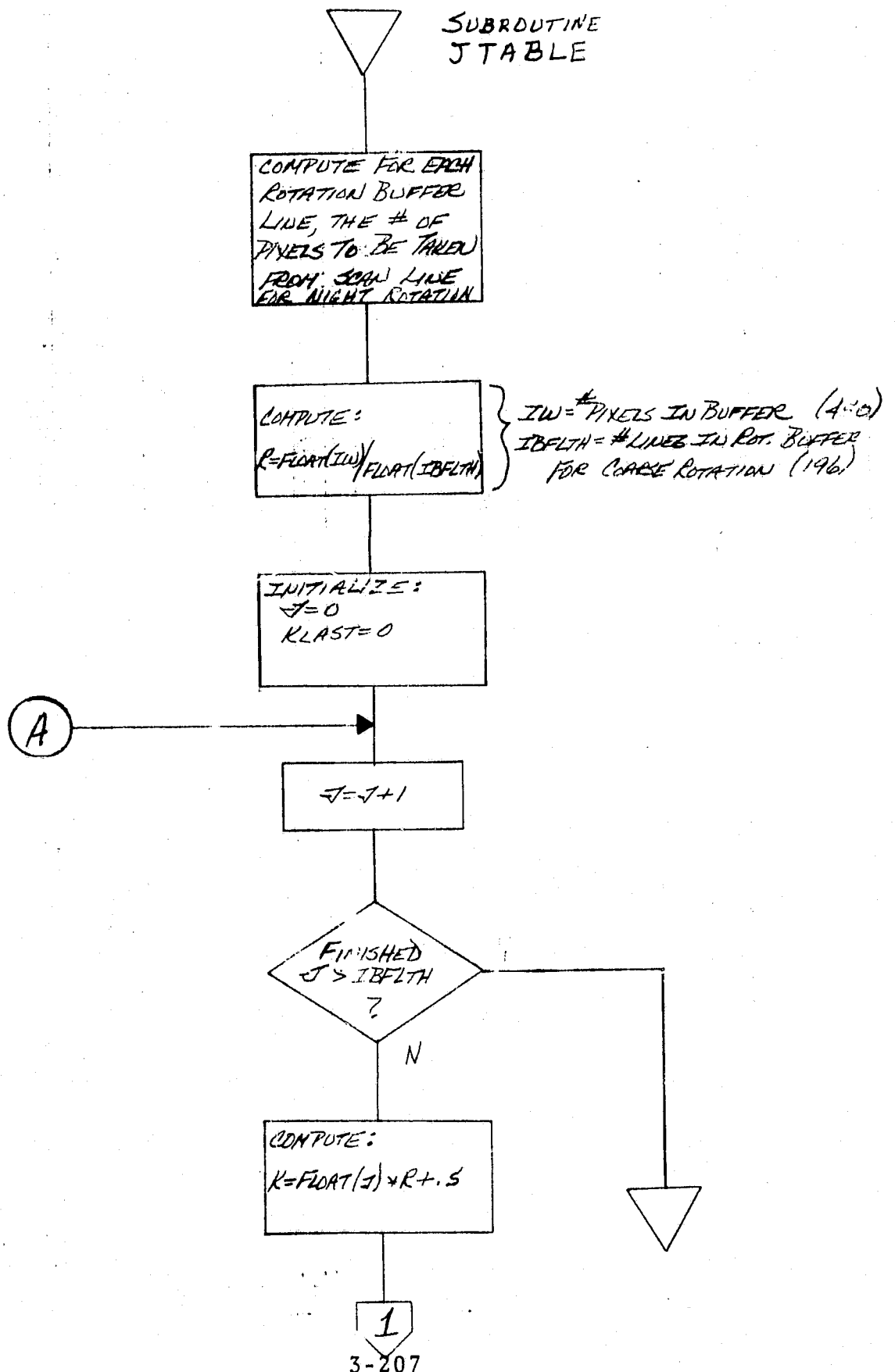
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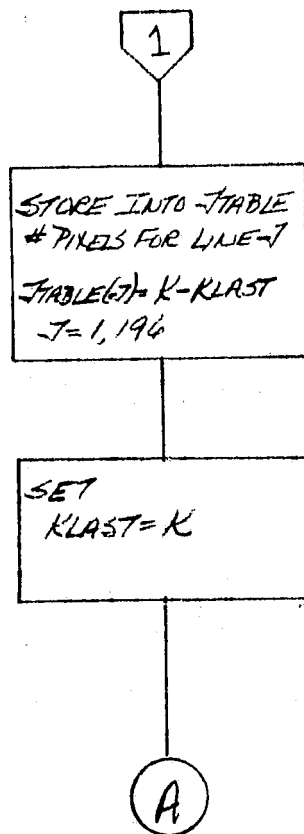


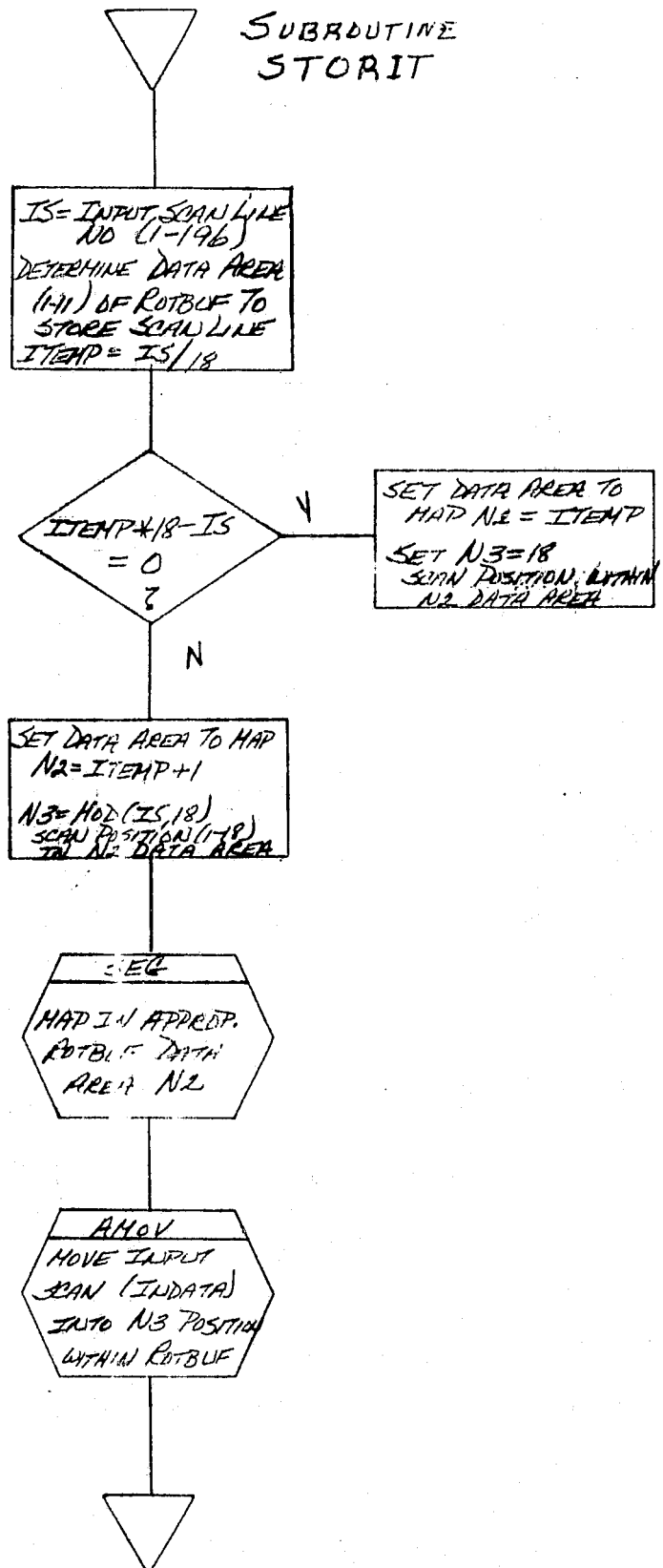


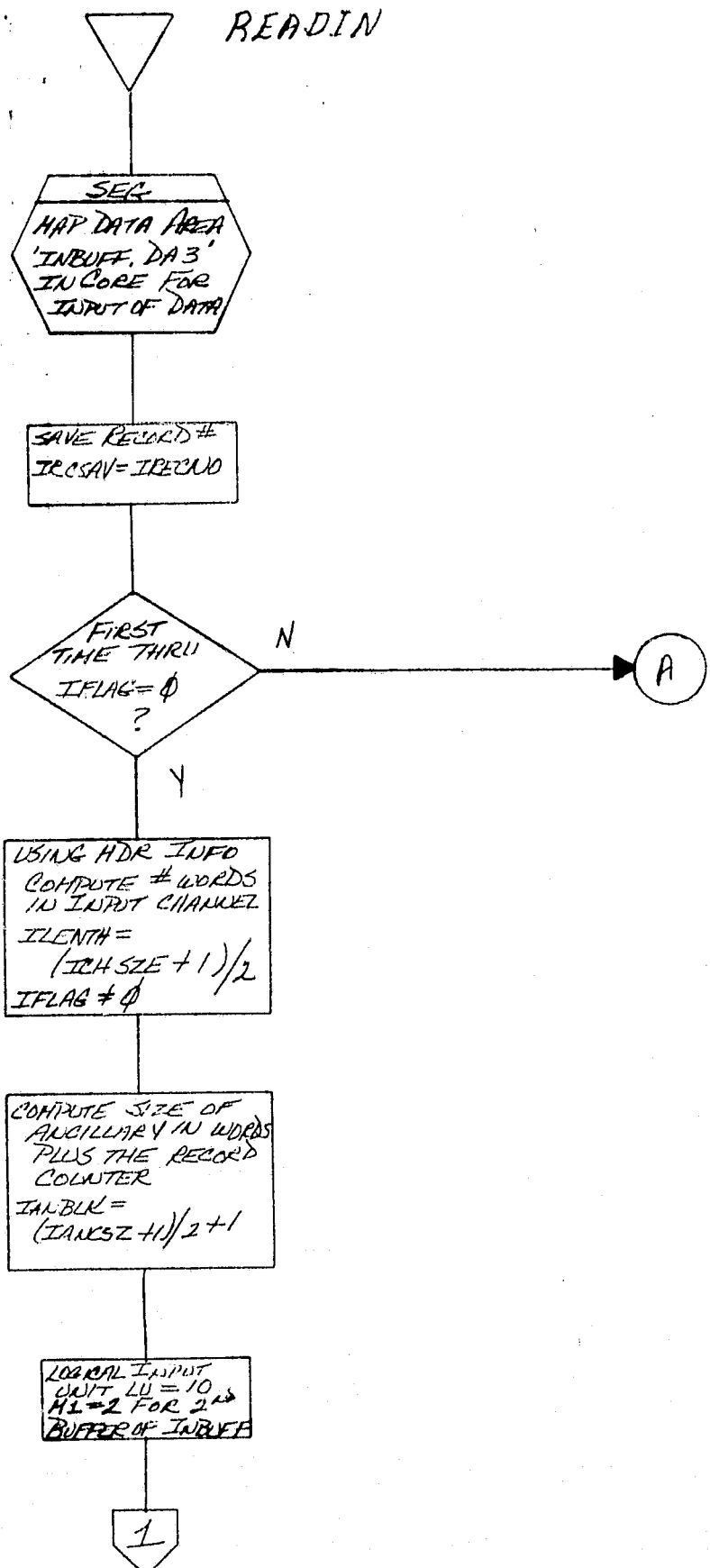


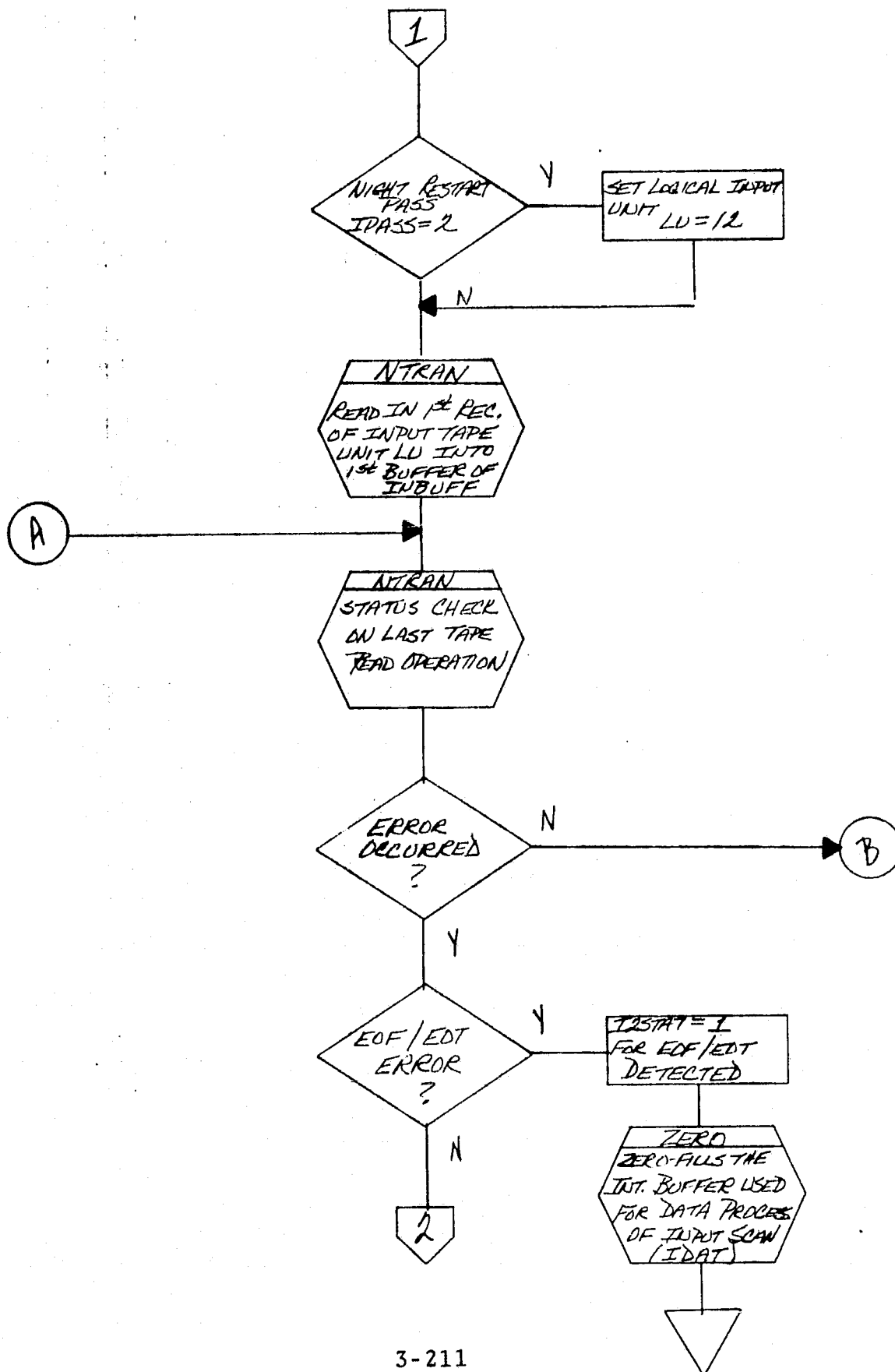


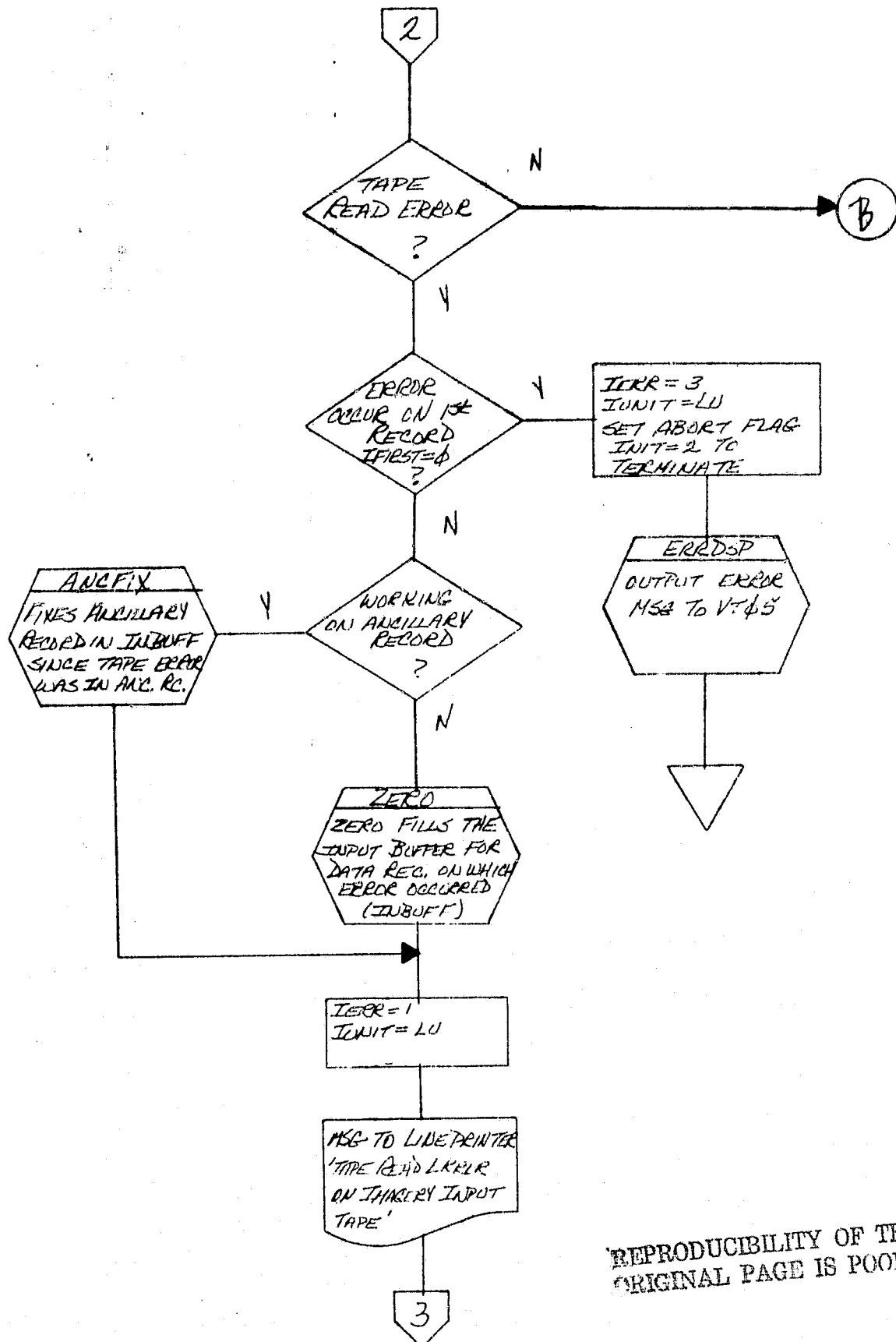




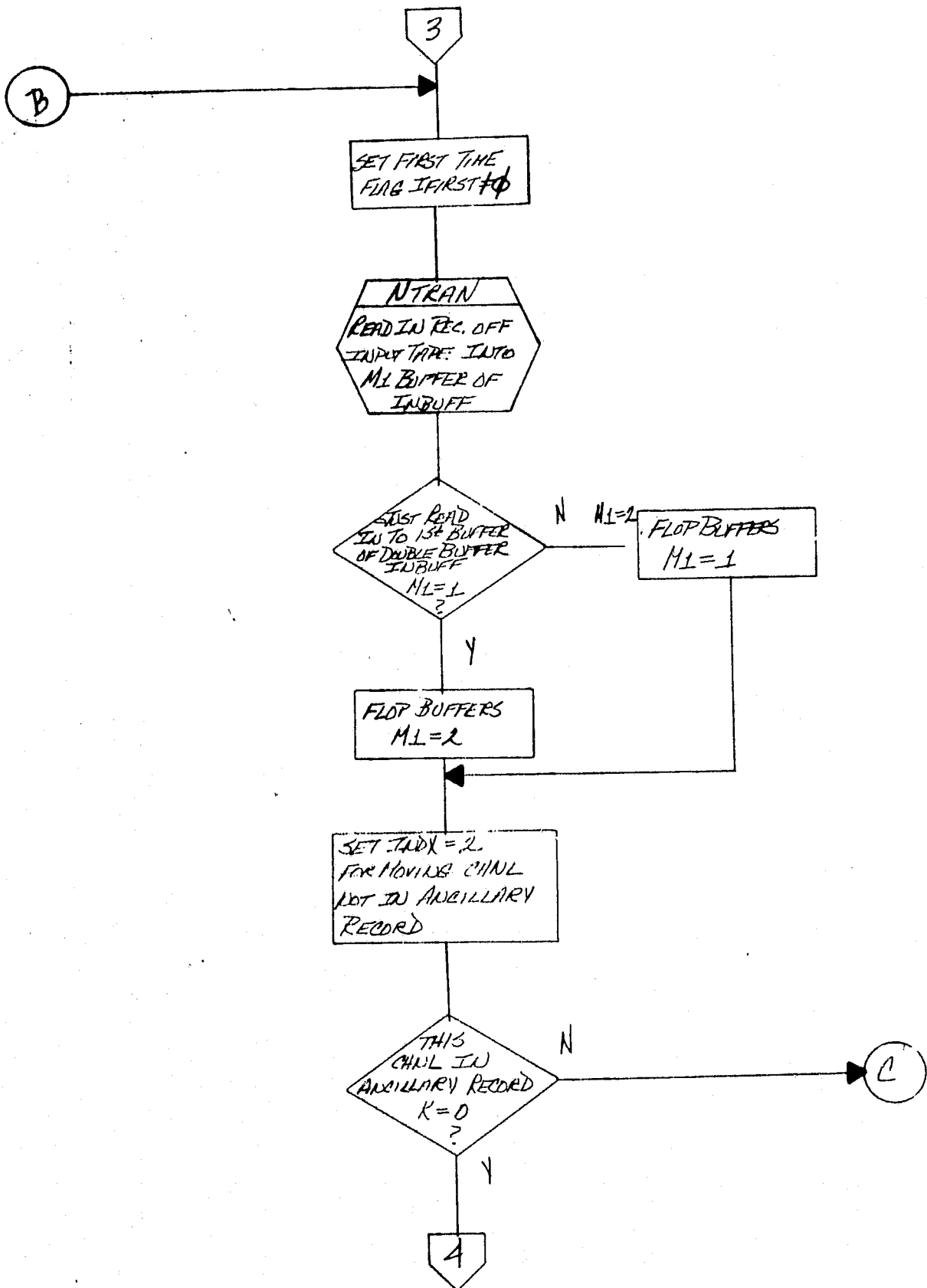


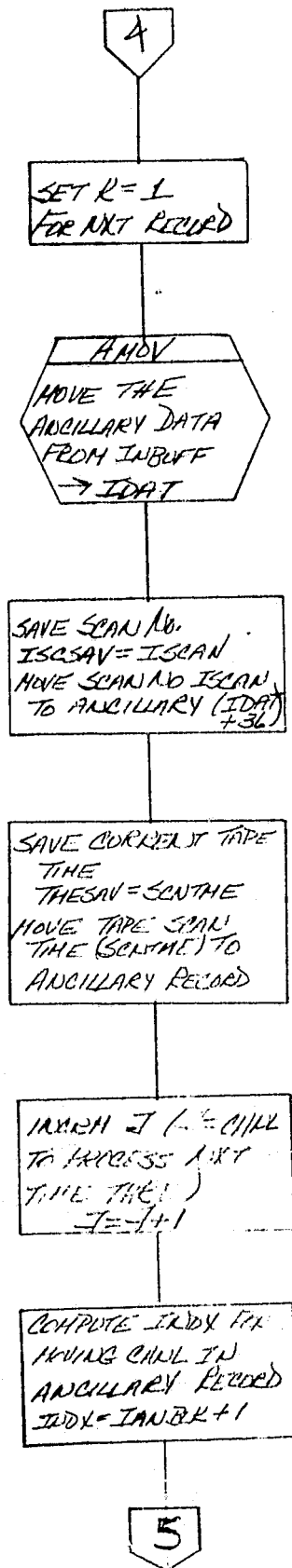


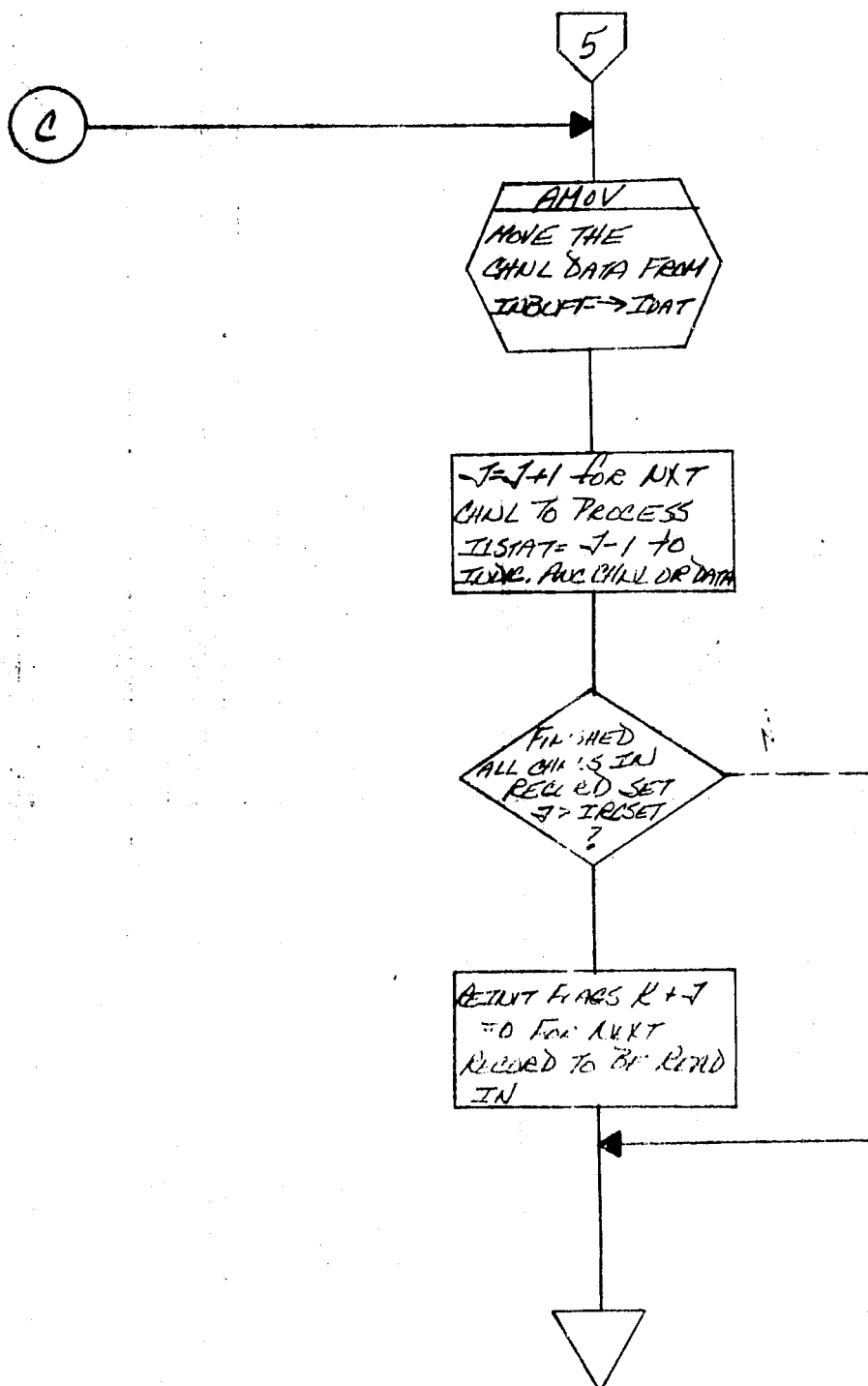


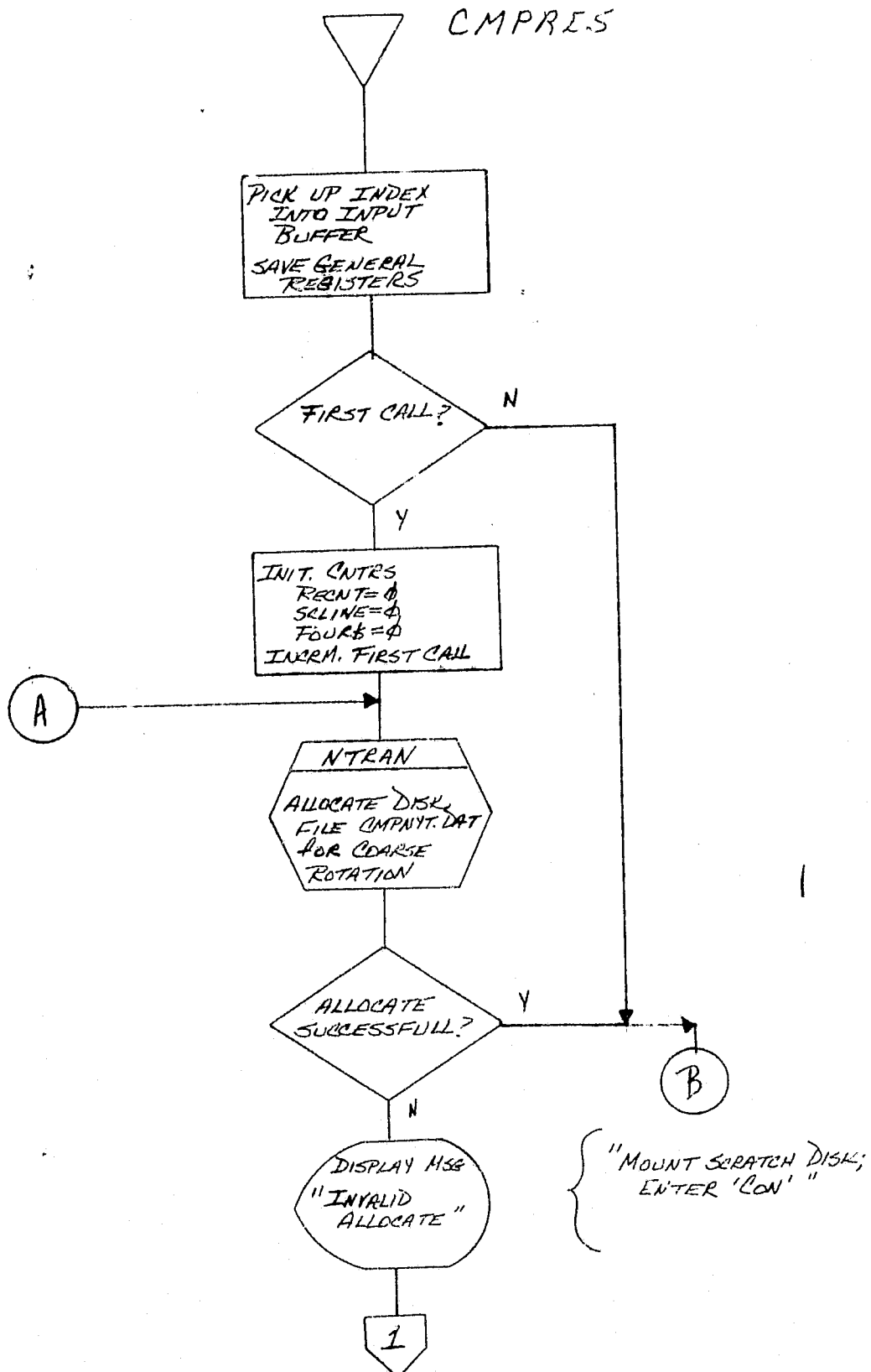


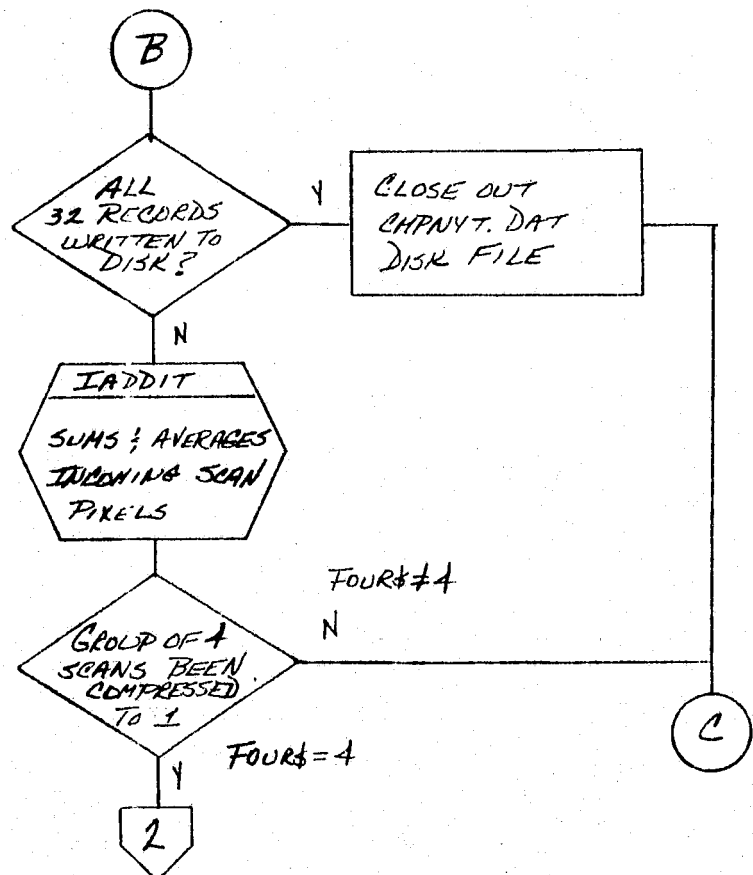
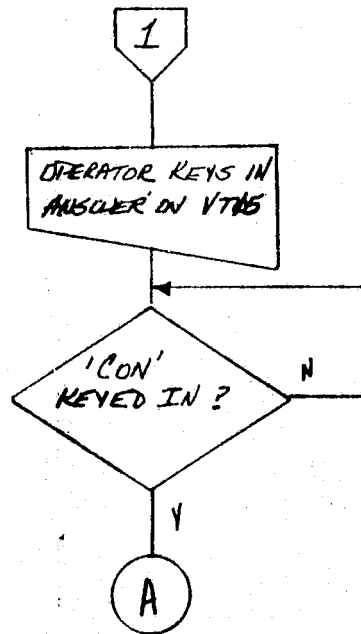
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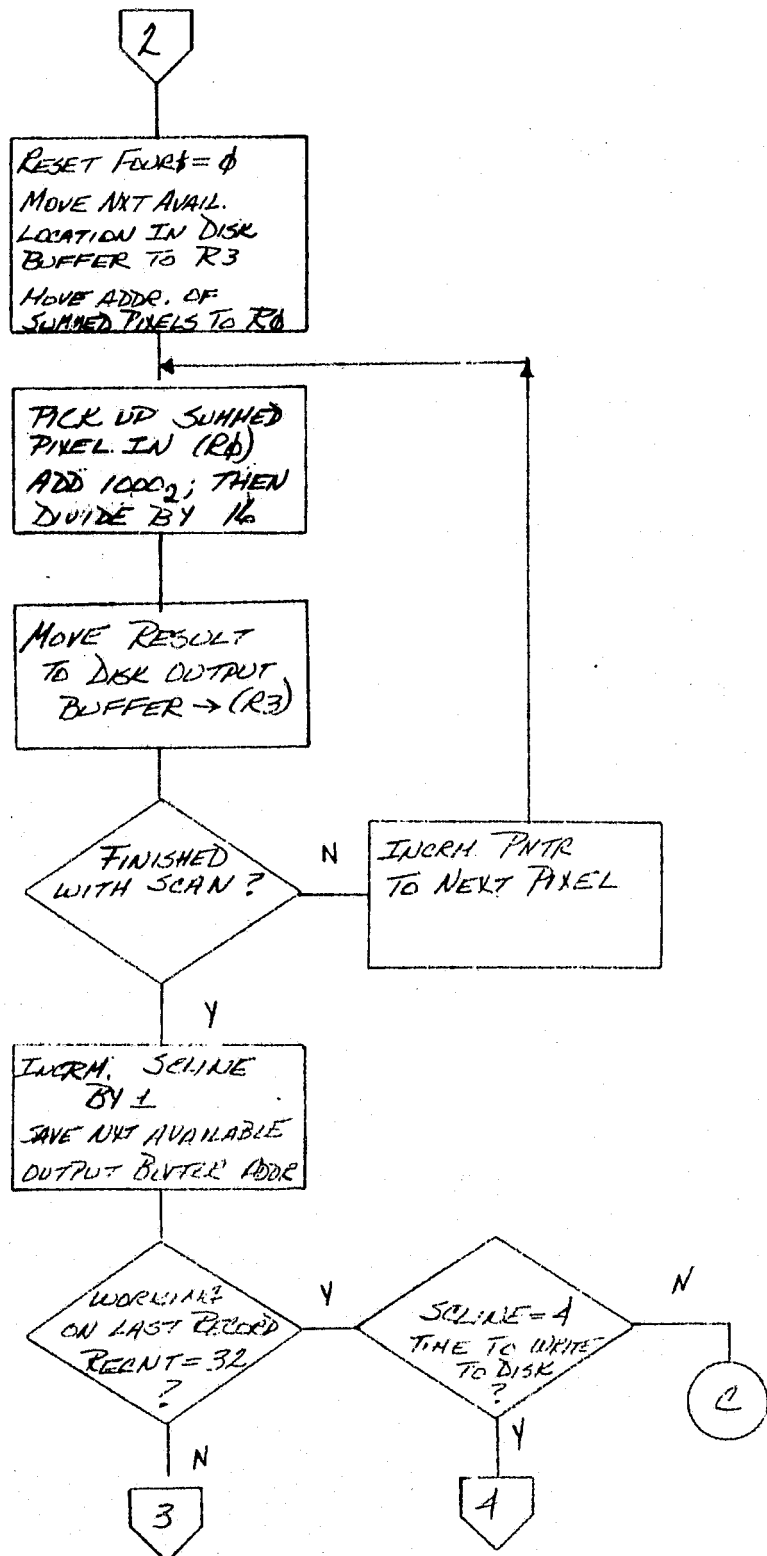


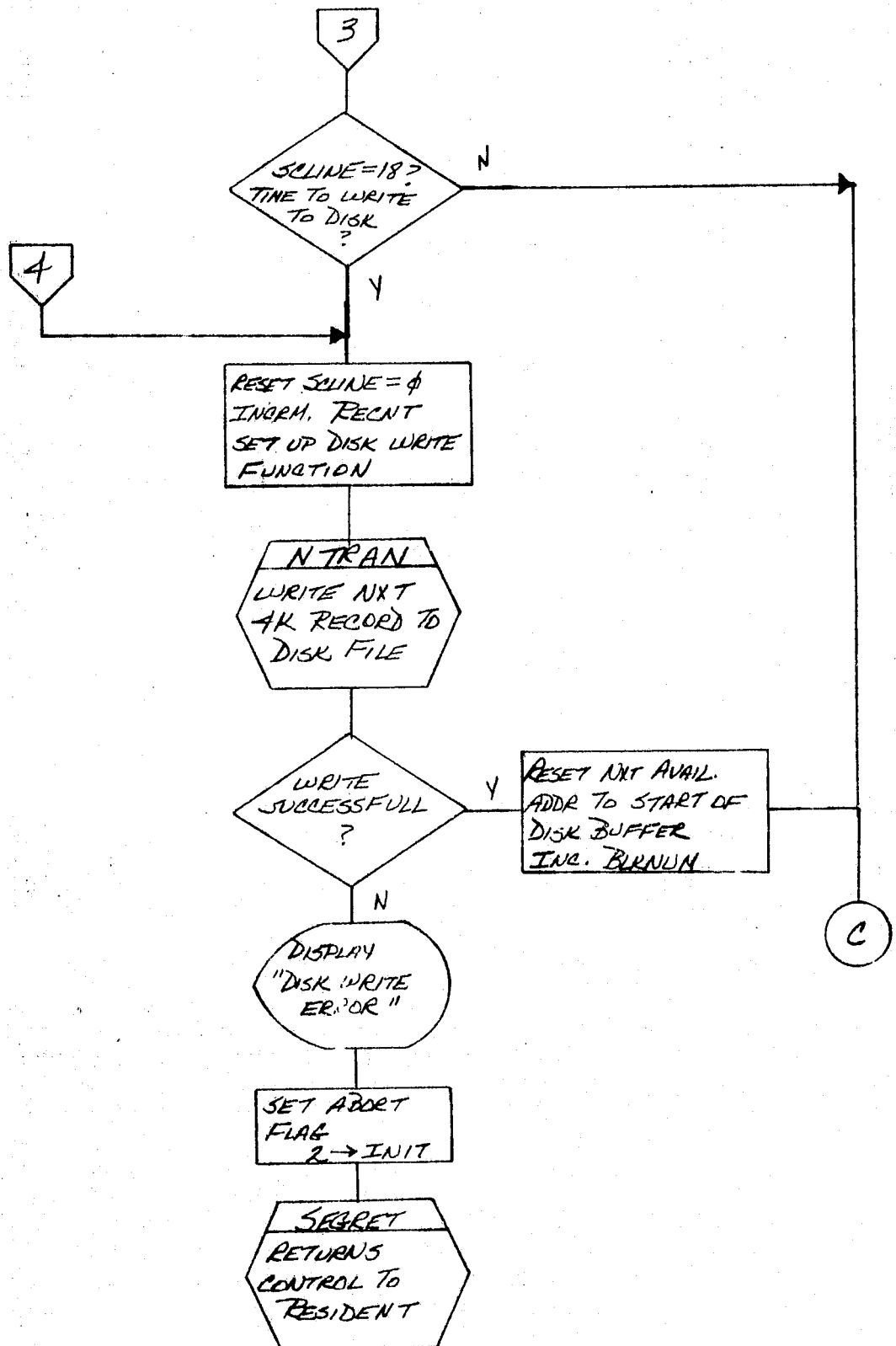


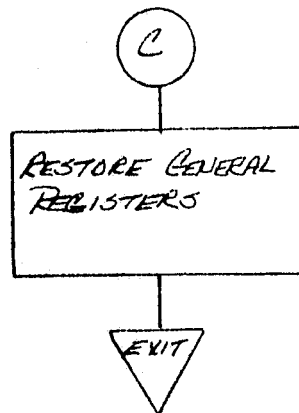


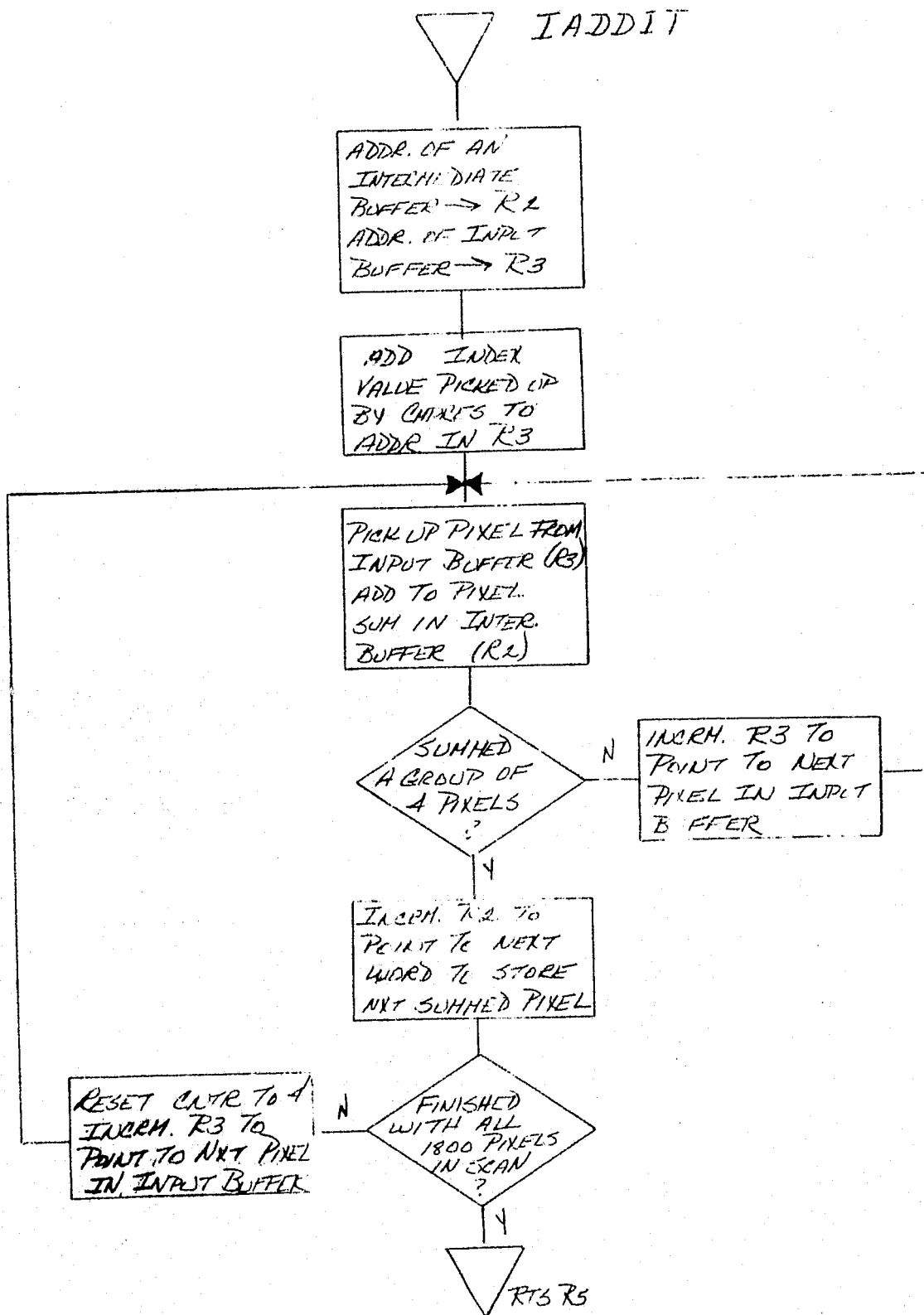












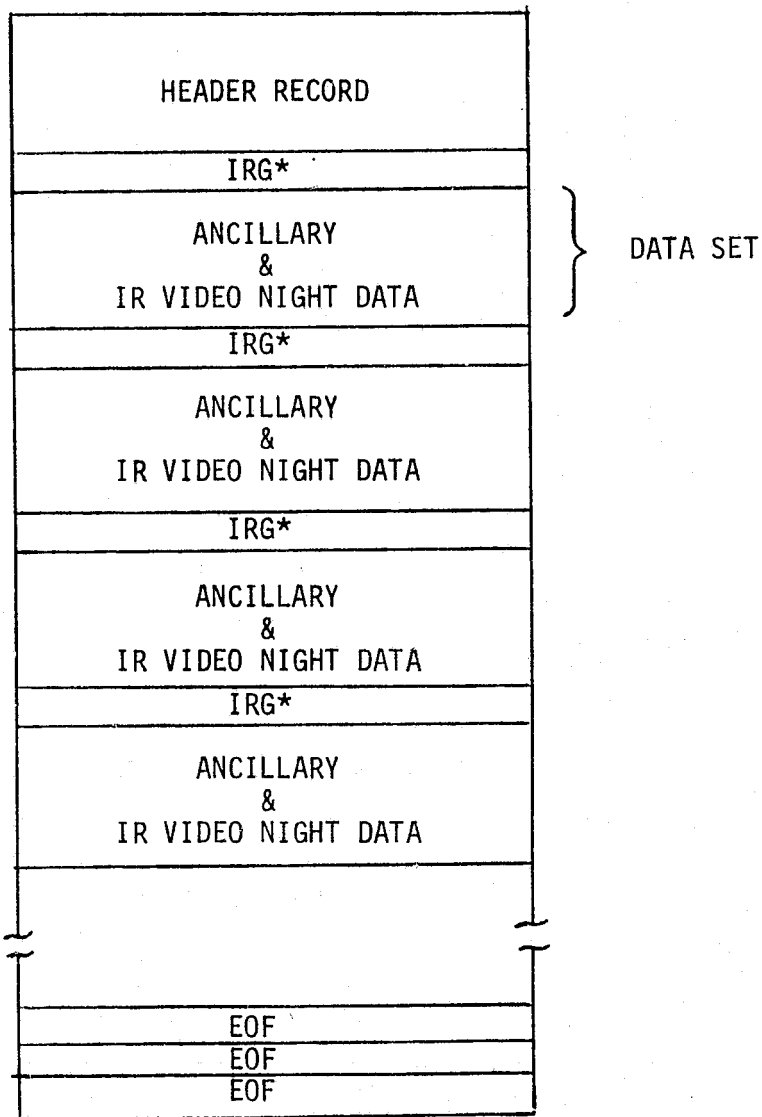
3.2.2.3 Interfaces. Input data consists of one 9-track EU tape called SEN. Output data consists of one 9-track night coarse rotated tape, or CRT. See figure 3-31.

The ROT MMC is called from the SEDS Resident Program. It has only one entry point, and is self-contained in that it does not use any input data except the information in the SEN tape header to process the SEN data, and it does not output any information other than that written in the CRT tape header.

3.2.2.4 Data Organization.

3.2.2.4.1 Data Organization During NTROTN Phase. One scan line at a time is read from the EU tape by READIN. A line is first read into the double buffer INBUFF, and then moved to CHBUFF, where it is located when READIN returns to NTROTN.EXC. In NTROTN, the number of scan lines is reduced by a factor of $\cos 25.8^\circ$, so that some of the scan lines are not used. If a line is used, it is compressed by CMPRES in the intermediate buffer INTBUF, and when four input lines have been compressed in INTBUF, the compressed line is written to a disk buffer called CMPNYT.DAT (see paragraph 3.2.2.1). CMPNYT.DAT is organized into 32 4K blocks. Each of the first 31 4K blocks has 18 compressed lines of 450 bytes each for a total of 558 compressed lines. When the 2500 input lines are scaled by a factor of $\cos 25.8^\circ$, 2250 lines are left, of which only the first 2248 are used because that is the largest multiple of 4 in 2250. Then, compressing the 2248 lines by 4 leaves 562 compressed lines. Thus, the 32nd block contains only four compressed lines. During the RTPHAS phase, these blocks are read out in reverse order.

3.2.2.4.2 Data Organization During RTPHAS Phase. The assembly language program READSK reads the blocks of 18 scan lines (the last has only four lines) from the disk file CMPNYT.DAT in reverse order, (last in, first out). A block is read into the buffer BLKLNT, which has 4050 words. From there, the scans are put into the buffer CHBUFF, one at a time in reverse order. One scan is put into CHBUFF each time READSK is called by RTPHAS.EXC. Then RTPHAS calls STORIT to store the line in the rotation buffer ROTBUF. ROTBUF is 196 lines long (see paragraph 3.2.2.1) and is organized into 11 4K blocks. Each of the first 10 blocks has 18 scan lines, and the 11th block has 16 lines (see figure 3-8).



* IRG = INTER RECORD GAP

Figure 3-31 SEDS Night Coarse Rotated Tape (CRT) Format

The counter IS counts from 1 to 196, and is carried into STORIT to tell STORIT which scan is being stored. When the 197th line is moved to the rotation buffer, IS is reset to 1, and the 197th line overlays, the first line in the buffer. STORIT uses two words, M2 and M3, to determine from IS where in ROTBUF to store the incoming line. M2 is used by SEG to map in the correct 4K data block. $M2 = IS/18$ if 18 divides IS; otherwise $M2 = INT(IS/18) + 1$. Then, the formula $M3 = MOD(IS, 18)$ is used by AMOV to find the correct one of the 18 positions in the M2nd data block.

After 98 lines have been stored in the rotation buffer, one re-sectioned line is built after each new line is stored. The output line is built in the buffer OUTBUF. To build this line, the program uses the following pointers, counters, etc.

- LP - Buffer line pointer which increments in cases 1 and 2, and decrements in cases 3 and 4.
- MPIXLC - Compressed PIXEL counter
- ITABLE (MPIXLC) - Number of times to repeat compressed PIXEL in building the output line.
- JTABLC - Counter for JTABLE (LP); it counts buffer PIXEL's used from buffer line LP to build the output line.
- J2 - Number of compressed zero-fill PIXEL's.
- IB - Number of rotation buffer PIXEL's needed to build this output line.
- IBUFPX - Rotation buffer PIXEL pointer
- IPIXL - Length of output line
- IPIXLC - Output buffer pointer which decrements in cases 1 and 2, and increments in cases 3 and 4.

The subroutine MAPBUF uses LP to calculate M2 in a similar manner to that in which STORIT uses IS to calculate M2. SEG uses M2 to map in the correct 4K data block. Then M3 points to the

correct scan line in this block of 18 scan lines. M3 is also calculated in MAPBUF using LP, just as M3 was found in STORIT using IS. The parameters M2 and M3 are in common in ROTMOV, which picks up one buffer PIXEL at a time and writes it into the output buffer as often as ITABLE (MPIXLC) indicates. See paragraph 3.2.2.1 and the flow charts following paragraph 3.2.2.2 for more details on how the output scans are built. When night coarse notation is finished, the flag IPASS is changed from 1 to 2 to indicate that coarse rotation is over.

3.2.2.5 Limitations. The coarse rotated tape will not be registered correctly if the EU tape has scan lines of less than 1800 PIXEL's each. The coarse rotation program requires an EU tape with exactly 2500 scan lines, and with 1800 to 2500 PIXEL's per scan.

3.2.2.6 Listings. See Part III of this document, published under separate cover.

3.2.3 REG (CPC No. 3). The REG CPC performs the image registration of the EU converted input data, mapping NOAA satellite day pass or inverted night pass data onto the SEDS reference grid of Mexico and the southwest position of the United States. The REG CPC is the last phase of the SRE Program. It is called from the SEDS resident immediately after initialization and the GCP phase if a day pass is being processed, and after the night coarse rotation phase if a night pass is being processed. It uses the data calculated by the GCP phase or input via cards and disk to register the input data image tape. It interfaces with NTRAN to write the registered data to disk and tape. REG also provides isothermal products (ICD screening and tape) by interfacing with the Product Generator Modules discussed in paragraph 5.2.3. REG consists of three load modules -- REGHED.LDA, ISOMOD.LDA, and SREG.LDA--which are written primarily in PDP 11/45 FORTRAN except for the ISOMOD module routines, which are written in PDP 11/45 assembly language.

3.2.3.1 Description. As stated previously, REG consists of three load modules, each being defined in a 32K virtual core map and each called in via SEG to perform its varied functions where necessary. This paragraph discusses the design flow and functions of REG, including the role of each load module in performing these functions. A brief description of the three load modules follows.

A. SREG. This is the main executive load module of REG, controlling the processing sequence flow and responsible for mapping in the other two load modules. SREG modules perform the actual processing of the input data, such as the translation, scaling and resectioning required to register the image. SREG is responsible for the output of the registered data to tape and disk. Its routines and subroutines are as follows.

1. SREG. This is the main routine (FORTRAN).
2. READIN. The input tape read routine (FORTRAN).
3. SCNFIL. A routine to write out zero-fill scans (FORTRAN).

4. TRNSCL. A routine to translate and scale the input data (FORTRAN).
 5. TSHIFT. This routine moves the translated data into the rotation buffer (assembly).
 6. TODISK. This routine writes the registered data scan to disk (FORTRAN).
 7. TOTAPE. This routine writes the registered IR data scans to tape for optional output (FORTRAN).
 8. RTATON. This routine generates an output registered scan by rotating the translated and scaled input data (FORTRAN).
 9. CALCIT and EMISIT. These routines perform emissivity correction to the 4:1 compressed registered data prior to its being written to disk.
 10. PXTBLE. This routine computes the number of PIXEL's to be taken from each line of the rotation buffer in the resectioning (rotation) of the data (FORTRAN).
 11. MOVBTS. This routine moves specified bytes from one array to the same location in an output array (assembly).
- B. REGHED. This load module is responsible for decoding the input tape header and for building the output header for the registered data output to disk and tape. Called by SREG prior to any data processing, REGHED is also called by NTROTN to build the output header for the coarse rotated tape in the ROT CPC. Its routines and subroutines are as follows.
1. REGHED. This is the main routine (FORTRAN)
 2. HD2DSK. This subroutine writes the registered data header record (SEDREG.HDR) to disk (FORTRAN).

3. BLDHED. This routine builds the output header for the registration disk file (SEDREG.HDR) and for the coarse rotated tape.
4. BSWAP and AMOV. These are utility routines to perform byte-swapping and byte moves.

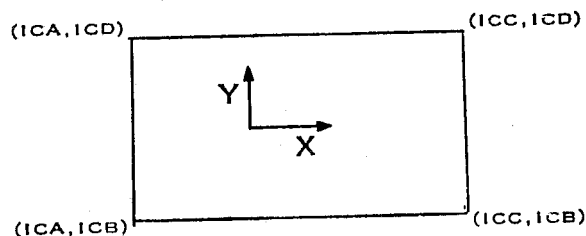
C. ISOMD. This load module is responsible for interfacing with PDGEN to build an isothermal output product tape and/or provide isothermal screening of compressed or full-scale IR registered data to the interactive color display (ICD). It is called by SREG if isothermal products are requested. Its main routine is ISOMOD, written in assembly language. Its other routines -- OPNOT, ANNOT, PDGEN, U9WRT, FCGEN, FCTBL, and DISPL -- are described in paragraph 5.2.3.1. They are all part of the product generation component of SSP.

3.2.3.1.1 Program Flow. REG is called up from the SEDS resident module by making a call to NEWMMC to map in the REG physical memory map configuration as portrayed in figure 3-11. Then a SEG call is made to load the SREG load module into the 32K virtual core executable area. See figure 3-10. SREG gains program control and calls the REGHED load module first to process and build the necessary output headers.

REGHED uses NTRAN to read the header off the input tape (EU tape for day, CRT tape for night). Input tape values are picked up from the header and stored in the TPFRTM common to be used by SREG later. See paragraph 3.1.5 for a description of the TPFRTM common. REGHED transfers the registered IR tape ID, input via the operator on the VT05 (COMMON TAPEID), to the output header buffer INDAT. A call is made to BLDHED to complete the output header in the INDAT buffer. If the IR registered tape output was selected via the operator, REGHED writes the completed header buffer INDAT to the output tape on MT2 and then calls the subroutine HD2DSK to output the header to the SEDREG.HDR disk file on DK1. REGHED exits to SREG via a SEG call.

SREG is now ready to begin processing the input data. For a day registration run, two passes are made through SREG, the first to register the IR channel data and the second to register the VIS data. Any additional output products (i.e., isothermal, etc.) are processed during the IR channel pass. For a night registration run, there is only one pass through SREG to register the IR channel.

First a preliminary explanation of registration is given. In the registration phase, it must be considered that the reference grid is a rectangle with 2200 scan lines of 2500 PIXEL's each, and is here a right-handed coordinate system. The corners are defined in COMMON/CORNRS/ as ICA = 1, ICB = 1, ICC = 2500, and ICD = 2200. If X is defined as the PIXEL number and Y as the scan number in the reference grid (output image of SRE), the following schematic is produced:



The input image will have scan lines denoted by S (or IS for the integer part), and PIXEL's denoted by E (or IE for the integer part). For each point (X,Y) in the reference grid, it is necessary to place in the output image the correct PIXEL (E,S) in the input image according to the formulas:

$$E = RA1 + EBAR + RA2 * X + RA3 * Y$$

$$S = RB1 + SBAR + RB2 * X + RB3 * Y$$

The coefficients RA1, EBAR, RA2, etc. were calculated in the SRE CPC, and are available in COMMON/GCOEFF/.

Basically, in SREG, data moves from an input data module (INBUFF) to an internal buffer (CHBUFF). READIN reads an input data scan from tape (SEN or CRT) into the double-buffered INBUFF. From here, the

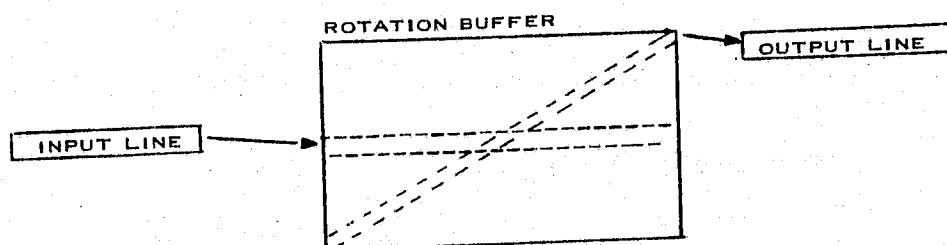
scan is moved to CHBUFF to be processed. Meanwhile, INBUFF is receiving the next scan to process. From CHBUFF, the data is moved into the rotation buffer ROTBUF, where a number of scans are collected to be resectioned. From the rotation buffer, the resectioned scan lines are built one at a time in the output buffer OUTBUF. As the last step, TODISK takes every fourth PIXEL of every fourth scan line in OUTBUF and builds a compressed registered scan in DSKBUF for output to the disk file.

Processing is from the top of the image on down (i.e., scan Y = 2200 is the first scan line to be resectioned from the rotation buffer to OUTBUF).

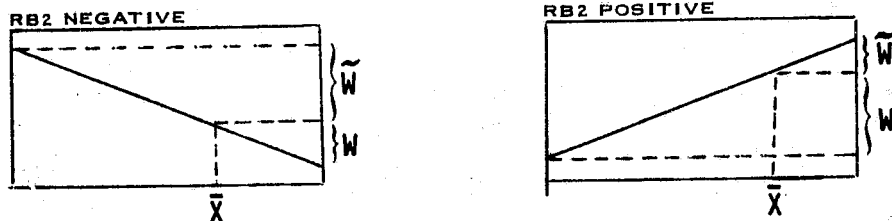
Approximately, translation in the downtrack (Y) direction is accomplished by choosing which input scan line (CHBUFF) to start from as the first line into the rotation buffer. If the input image starts at a point higher than the top of the reference grid, the program must start further into the input tape to get the first scan for the rotation buffer. If the input image starts at a point lower than the top of the reference grid, some zero fill lines must be put in the rotation buffer via the SCNFIL routine. Scaling in the downtrack (Y) direction is accomplished either by repeating some input lines in the rotation buffer or by deleting some input lines.

Translation in the crosstrack (X) direction and also performance of the skew correction is accomplished by choosing the PIXEL of the input line to place in the first PIXEL position in the rotation buffer. This PIXEL is recalculated for each input scan line, thus accomplishing the skew correction. The scaling in the crosstrack direction is done by repeating some of the input line PIXEL's when writing a line into the rotation buffer, or by deleting some PIXEL's.

Rotation in the crosstrack direction is accomplished by putting as many input scans as are needed into the rotation buffer, and then resectioning to form one output line, as shown below.



3.2.3.1.2 Scan Line Calculations. There are two cases involving such calculations, depending on the sign of RB2. Schematically, an output line in the rotation buffer is as shown below:



NOTE - \tilde{W} IS CALLED WTILDE AND \bar{X} IS CALLED XBAR IN THE SREG MODULE

If $RB2 \leq 0$, let:

$$\tilde{W} = (ICA - \bar{X}) * RB2 / RB3$$

If $RB2 > 0$, let:

$$\tilde{W} = (ICC - \bar{X}) * RB2 / RB3$$

In SREG, Y is called YSCAN, and S is called SD. To find the scan of the input tape to put first into the rotation buffer, set $YSCAN = ICD$, and let:

$$SD = RB1 + SBAR + RB2 * XBAR + RB3 * YSCAN + WTILDE + 0.5$$

All the rotation and scaling will be done in the X direction, about the \bar{X} PIXEL.

Now, SD must be compared with the first line on the input tape. The first scan on the input tape is numbered 1 in the ancillary. The numbers must be inverted from a top-to-bottom system to a bottom-to-top system. Let ISCAN be the scan number in the ancillary. Then let:

$$ISNCOR = 2201 - ISCAN \text{ for a day pass}$$

$$ISNCOR = 2249 - ISCAN + IDEL \text{ for a night pass}$$

The day pass input tape (SED) has 2200 lines and the night pass input tape (CRT) has 2248 lines. For a discussion of IDEL see paragraph 3.2.2.1.

Suppose the first SD and first ISNCOR have been found. If $SD < ISNCOR$, the input tape is read through via READIN until $ISNCOR = SD$. If $SD > ISNCOR$, SREG.EXC calls SCNFIL to put zero fill lines into the rotation buffer. Each time a zero fill line is written by SCNFIL, it recalculates SD. Zero lines are written in the rotation buffer until $SD = ISNCOR$. SCNFIL then returns to SREG.EXC and the first scan line is read in from the input tape by READIN, and is put into the internal buffer CHBUFF.

SD is recalculated according to the formula:

$$(new) SD = (old) SD - RB3$$

Each time a line is written into the internal buffer, SREG calculates the PIXEL number of the input line to put into the first PIXEL position of the rotation buffer. This PIXEL is called ED in SREG. Note that the first time a line was written to the rotation buffer, YSCAN was set to ICD. Each time a line is written, YSCAN is decremented by 1. ED is calculated as follows:

If $RB2 \leq 0$,

$$ED = RA1 + EBAR + RA2 * ICA + RA3 * YSCAN + 0.5$$

If $RB2 > 0$,

$$ED = RA1 + EBAR + RA2 * ICA + RA3 * (YSKAN + 2500 * RB2 / RB3) + 0.5$$

SREG now calls TRNSCL to perform the translation and scaling of the input data from CHBUFF into the rotation buffer ROTBUF.

The PIXEL's are moved by TSHIFT, which is called from TRNSCL. In TSHIFT, each time a PIXEL is moved to the rotation buffer, the PIXEL number of the next PIXEL to move is recalculated according to the formula:

$$(new) ED = (old) ED + RA2 - RA3 * RB2 / RB3$$

This formula serves to properly scale in the X direction.

The number of scan lines which must be input to the rotation buffer in order to take one resectional line out is called NSETS and was calculated previously in SREG. The formula is:

$$\text{NSETS} = 2500 * \text{ABS} (\text{RB2}/\text{RB3}) + 1.5$$

The rotation buffer as set up in physical core has room for 54 scan lines. If NSETS is larger than 54, SREG compresses in the downtrack direction by deleting some scan lines on input to the rotation buffer and then expands on output by repeating some scan lines.

The compression factor, CMPRS, is calculated from the formula:

$$\text{CMPRS} = 53. * \text{RB3} / [2500.*\text{ABS}(\text{RB2})]$$

The expansion factor, EXPAND, is $1/\text{CMPRS}$.

NSETS is reset to 54, and lines are resectioned from the rotation buffer as though NSETS had always been 54.

The logic shown in figure 3-32 is used for the compression on input to the rotation buffer. Let ICOUNT be the number of scan lines read off the input tape. Begin with ICOUNT = 0 and NCOUNT = 0.

Once NSETS lines are put in the rotation buffer by TRNSCL, resectioning the line for output is quite straightforward. An equal number of PIXEL's from each buffer line must be taken for a total of 2500 PIXEL's. Thus, an average of $\text{RB3}/\text{RB2}$ PIXEL's must be taken from each rotation buffer line. Since this is not an integer, more lines than this are sometimes taken and less than this are sometimes taken. Before resectioning any lines, SREG calls PXTBLE to set up the table (TBLEPX) telling how many PIXEL's to take from each line. Refer to the PXTBLE flow chart for the scheme of building the table.

To build a resectioned line from ROTBUF into the output buffer OUTBUF, RTATON is called by SREG. The most recent line input to the buffer is the first line from which PIXEL's are moved to the output buffer. If RB2 is negative, the line is built backward, starting at the right and working down to the left. If RB2 is positive, the line is built from left to right, with PIXEL 1 output first and PIXEL 2500 output last.

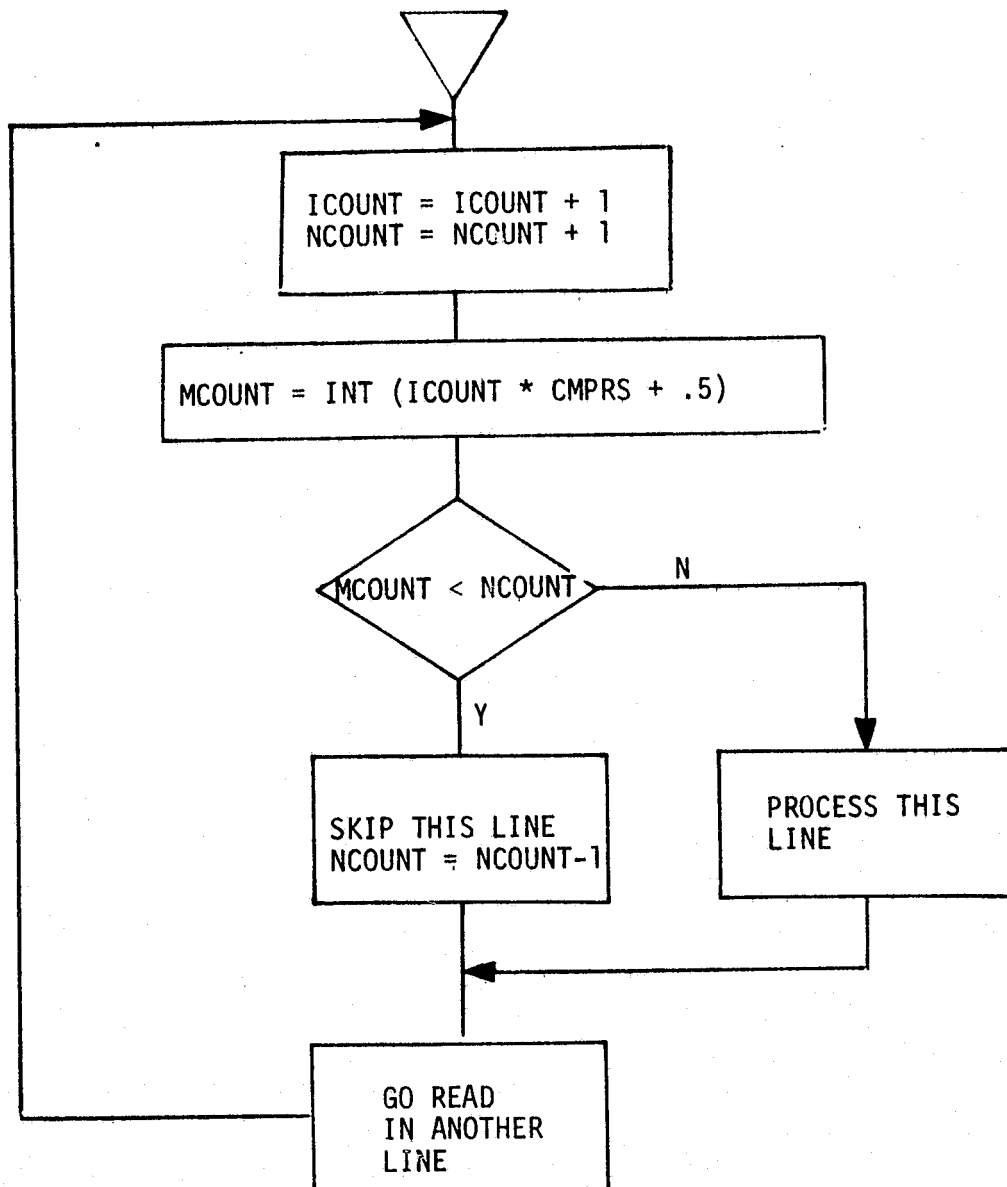


Figure 3-32 Compression Logic for Input to Rotation Buffer

ROTBUFF is set up into a 4K data block repeated 18 times in physical core to equal 72K. Each 4K block can contain up to three scan lines of corrected data as input by TRNSCL. So, for the 18 repeated 4K blocks, ROTBUFF can hold up to a maximum of 54 scan lines from which RTATON performs the resectioning to build one output registered scan. The data is resectioned from the last scan line in ROTBUFF upwards, so that RTATON calls SEG to map in the last of the 4K blocks (N1) which was written into. RTATON picks up the number of PIXEL's to use as an entry in TBLEPX for the particular scan line, and calls MOVBTs to move the designated PIXEL's from the ROTBUFF scan to the output buffer OUTBUF. As each 4K block of ROTBUFF is required, RTATON calls SEG to map in the N1-1 4K block, relieves the TBLEPX entry, and so on to collect the necessary PIXEL's for output. This continues until RTATON has built one output scan line from all the data scans in ROTBUFF. RTATON then exits to SREG. SREG enters the expansion logic to determine how many times to write the resultant output line from OUTBUF to tape and disk. The logic is as follows (see figure 3-33).

Begin with JCOUNT = 0 and NN = 0. Let JCOUNT count the number of times the write loop is entered. When the write loop is entered, there is an output line in OUTBUF, which will be written to tape as often as necessary, as determined by the logic in the write loop.

The logic for downtrack scaling, and the logic for the compression on input and expansion on output from the rotation buffer that is in SREG.EXC, is duplicated in SCNFIL, so that the zero fill lines at the top of the image are mapped as though they were real data. SREG now calls TOTAPE to write the full-scaled IR scan to tape (MT2) if the IR registered output tape was requested by the operator in the SRE phase and SREG is currently working with the IR data. SREG then calls TODISK to output the registered scan to disk. The data output to disk is compressed (i.e., every fourth output scan is picked up by TODISK and then every fourth PIXEL in that scan is moved to the disk output buffer, DSKBUF). This results in a total output of 550 scan lines, each with 625 PIXEL's. When TODISK determines it is to use a scan of data (i.e., every fourth scan, it calls BLDBUF to build the compressed scan in DSKBUF. At this point, an emissivity correction is applied to each PIXEL in the output scan if the program is working on IR

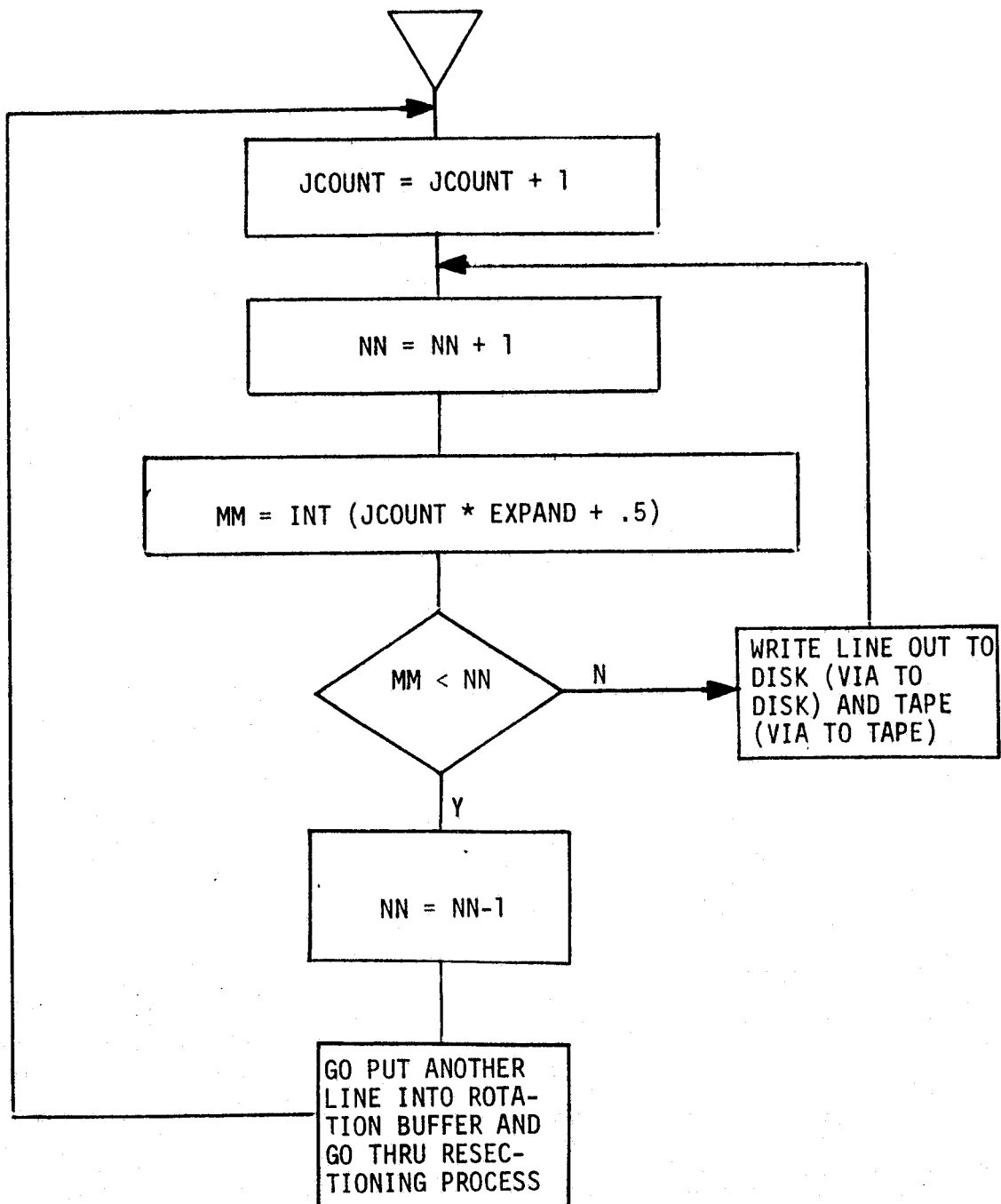


Figure 3-33 SREG Expansion Logic

channel data. A background emissivity image map resides permanently on DK1: the registration background map disk. TODISK reads in the corresponding scan of emissivity correction data from disk. BLDBUF calls an assembly routine, EMISIT, to take every fourth PIXEL in the output scan, do the emissivity correction, and place the result in the output buffer DSKBUF. The formula for this correction is:

$$\text{RESULT} = (\text{IOVAL}-80) * (\text{IPIX}+404) * 0.000274838 + 0.5$$

Where:

IPIX = PIXEL value in the output buffer (OUTBUF)

IOVAL = Emissivity correction factor PIXEL value as picked up from the background image map for PIXEL IPIX.

Then:

$$\text{NEWPIX} = \text{IPIX} + \text{RESULT}$$

Where NEWPIX = 0, 255

TODISK exits to SREG to process the next output scan. When TODISK has accumulated four compressed registered scans in DSKBUF, the buffer is written to the disk file SEDREG. So, for every 16 output scans built in OUTBUF (i.e., every 16th call to TODISK), four compressed scans are built and output to disk via NTRAN DOS I/O.

TODISK is also responsible for setting up isothermal output (IR channel only) as requested by the operator in the SRE phase. If isothermal output is selected, TODISK checks to see whether normal or four-to-one compression was requested. If normal compression was requested, for each call to TODISK via SREG, the full-scale registered scan in OUTBUF is moved to the second half of DSKBUF (i.e., DSKBUF + 2500). See figure 3-34 for the format of the DSKBUF data module. DSKBUF is mapped in via a SEG call when necessary for data scan transfer for isothermal output and/or disk output. TODISK then calls the isothermal output module ISOMOD via SEG.

COMMON/DSKBUF/IWORD (1250), IDATA (1250)

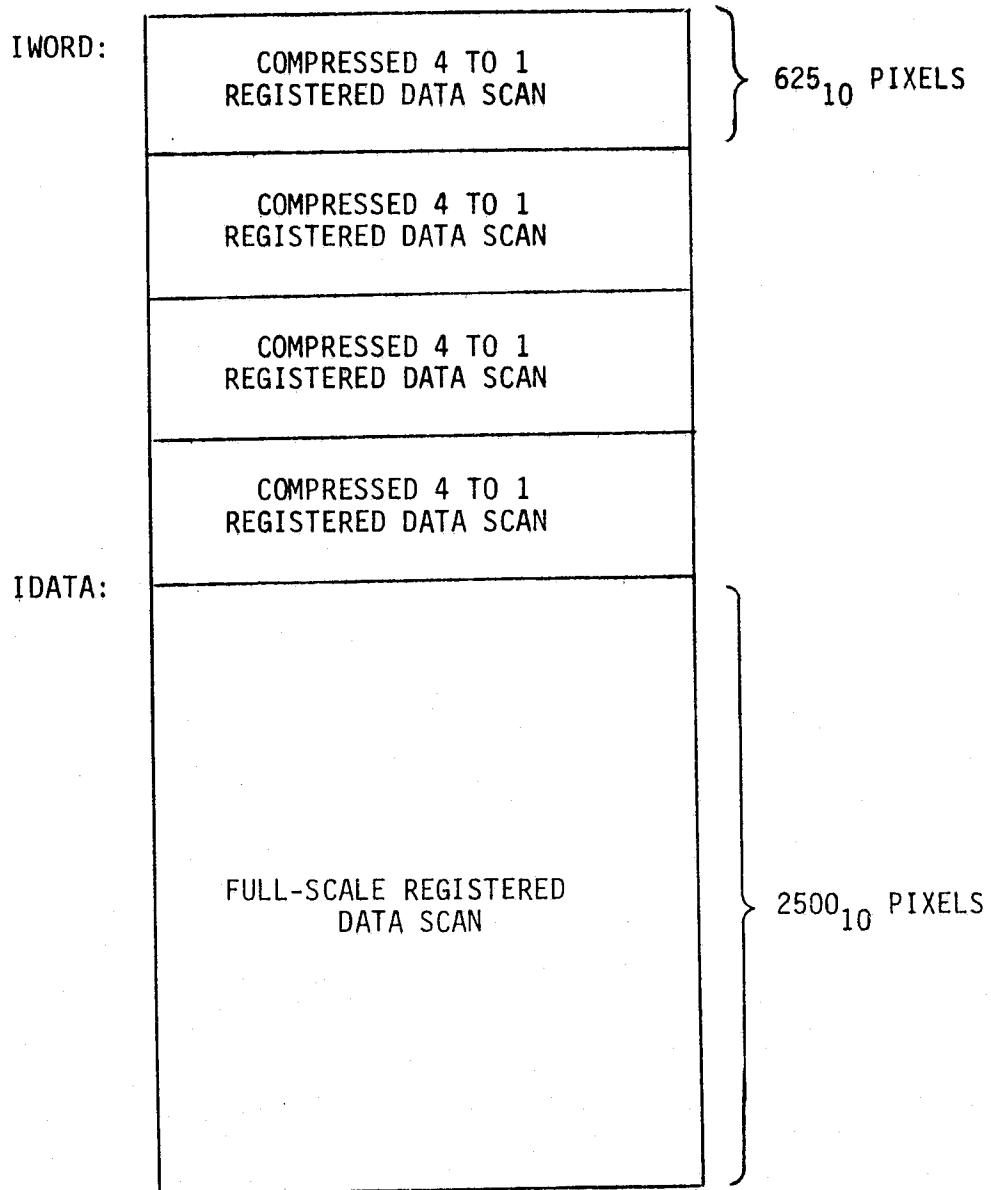


Figure 3-34 DSKBUF Data Module

ISOMOD retrieves the scan from DSKBUF and calls PDGEN to output the data to tape (MT0) and/or display on the ICD (interactive color display). PDGEN and other assembly routines linked within the ISOMOD load module accomplish all isothermal products generation. These routines are available for generation of various SEDS products and are discussed in paragraph 5.2.3.1. ISDMOD's main function is to pick up the data for output and provide logic to interface with the product generation routines. If compressed output is selected, TODISK calls the ISOMOD load module when it has built four compressed scans in DSKBUF (first half). ISOMOD makes four calls to PDGEN, passing one compressed scan for output for each call. ISOMOD returns to TODISK via a return SEG call. The call packet set up for PDGEN passed with each call is outlined in figure 3-35.

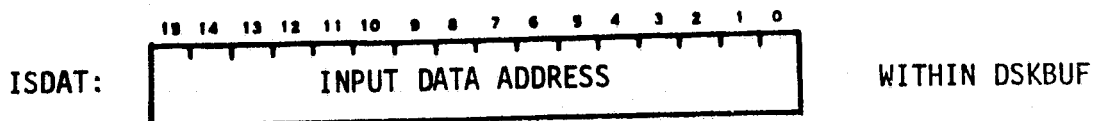
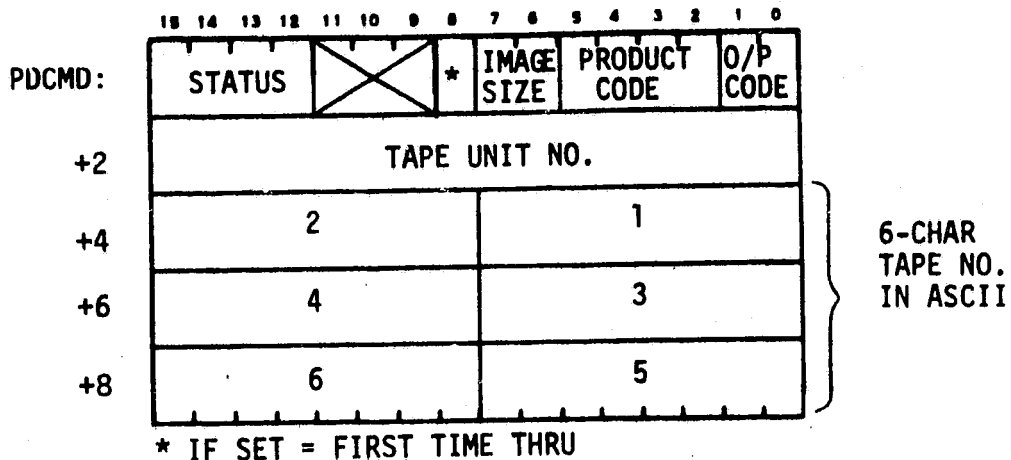
When it has completed registering the IR and VIS channels on a day pass or the IR channel on a night pass, SREG performs wrapup procedures such as rewinding all input and output tapes, calling ERRDSP to output a JOB COMPLETE message to the VT05, and exiting to the SEDS resident.

3.2.3.2 Flow Charts. See 60 pages following figure 3-35.

NORMAL CALL TO PDGEN:

JSR R5,@#PDGEN
BR A
.WORD PDCMD
.WORD ISDAT

A:



OUTPUT CODE (BITS 0, 1):

00 = NONE
01 = DISPLAY
10 = TAPE ONLY
11 = BOTH

PRODUCT CODE (BITS 2-5):

1000 = ISO DAY (OID)
1001 = ISO NIGHT (OIN)
1010 = CMI
1011 = RAINFALL (ORC)
1100 = SCREWORM (OWC)
1101 = SPECIAL

IMAGE SIZE (BITS 6-7):

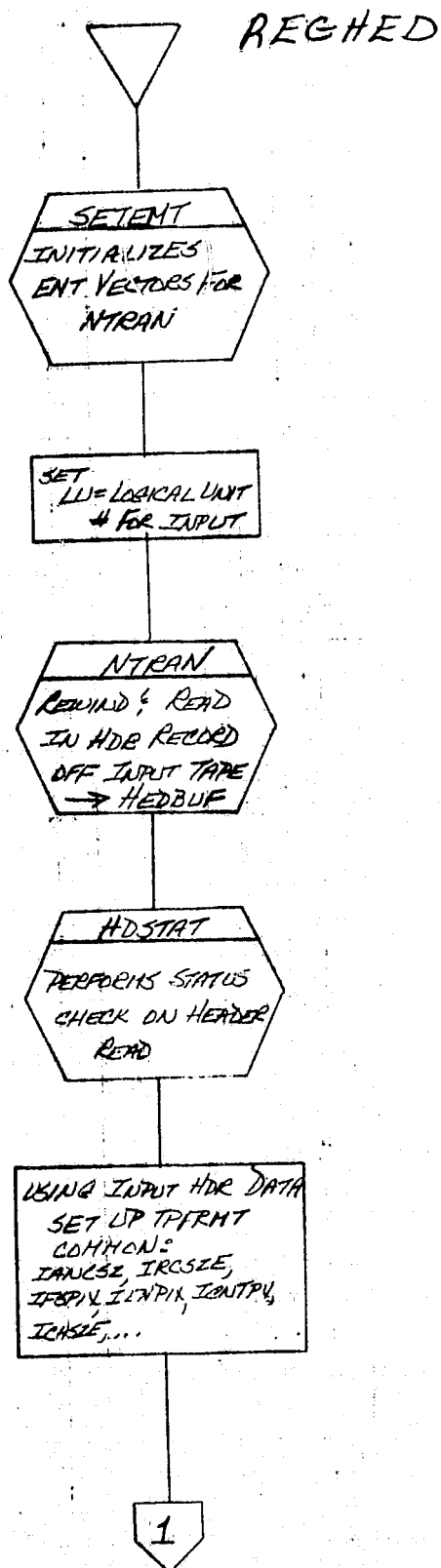
00 = COMPRESSED (625 PIXELS, 525 SCAN LINES)
01 = NORMAL (2500 PIXELS, 2200 SCAN LINES)

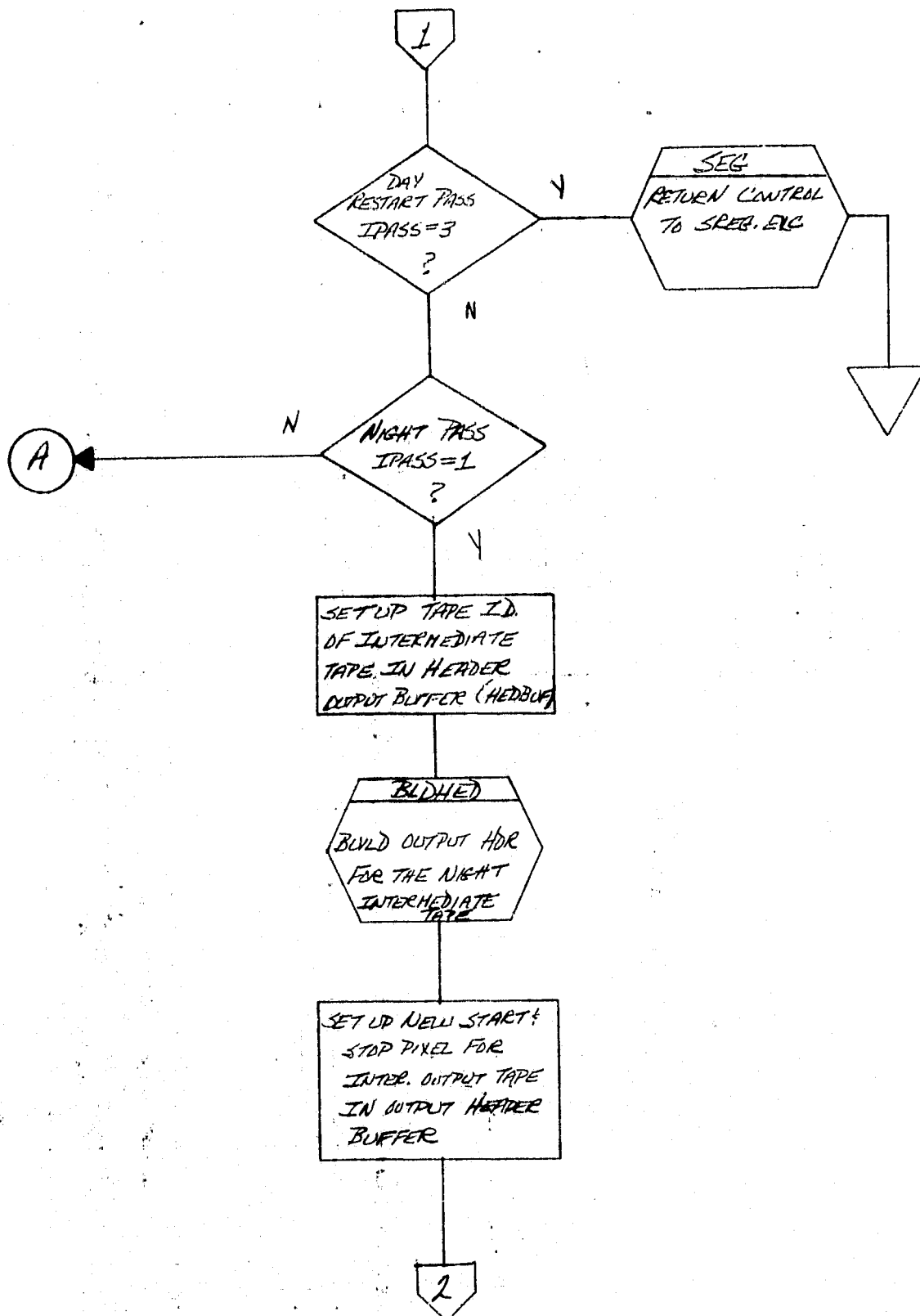
STATUS (BITS 12-15):

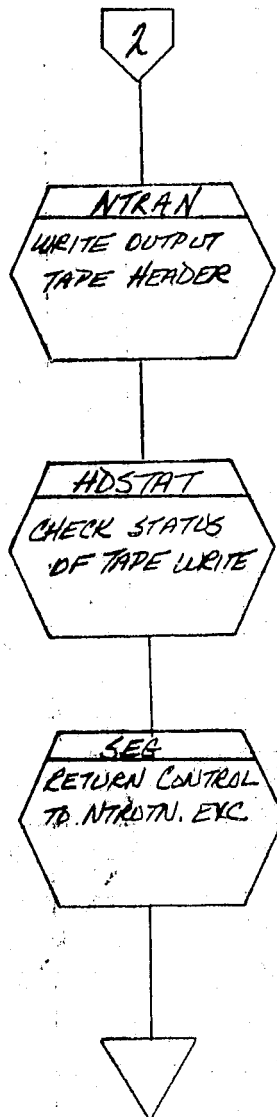
12 - IF SET, DISPLAY TIME OUT
13 - IF SET, MANUAL ABORT
14 - IF SET, OPERATION COMPLETE
15 - IF SET, INVALID TAPE WRITE

Figure 3-35 Normal PDGEN Calling Sequences
and Packet Format

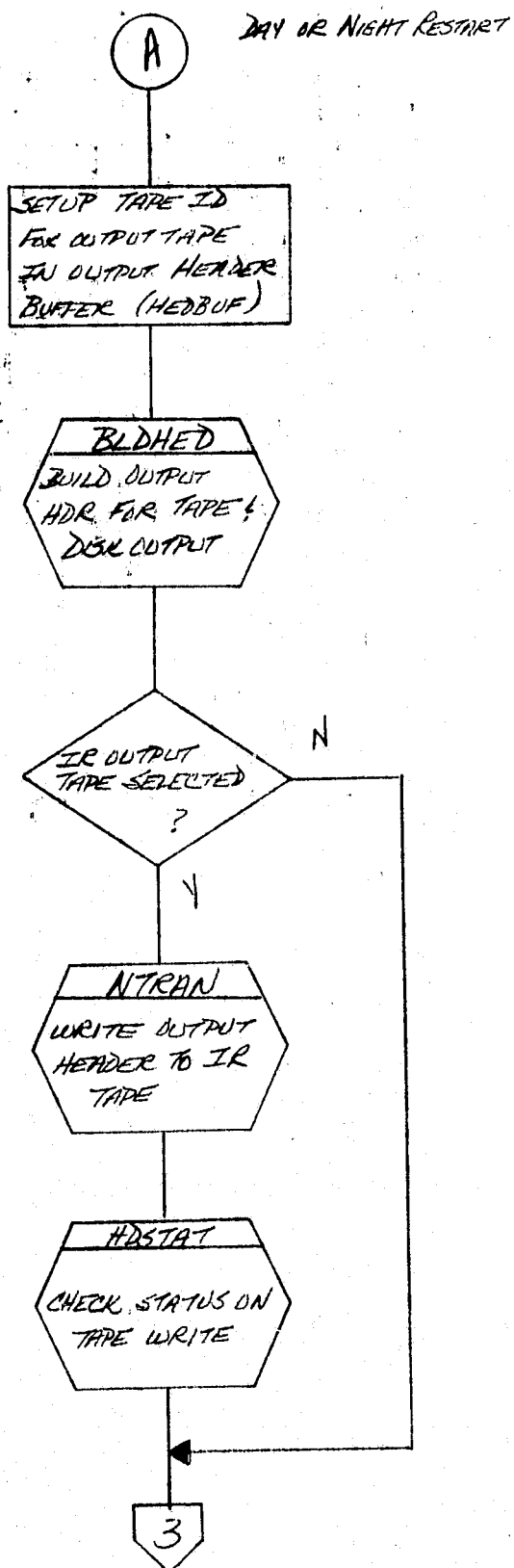
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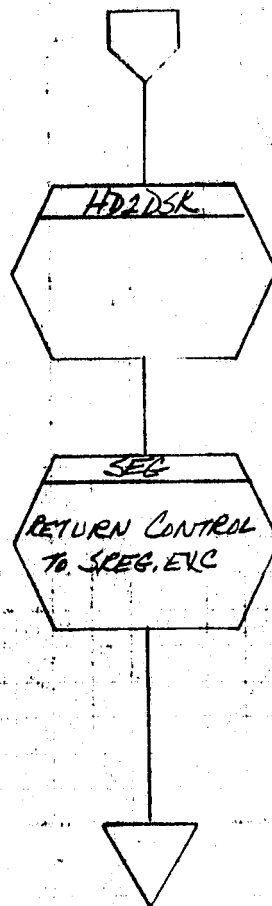




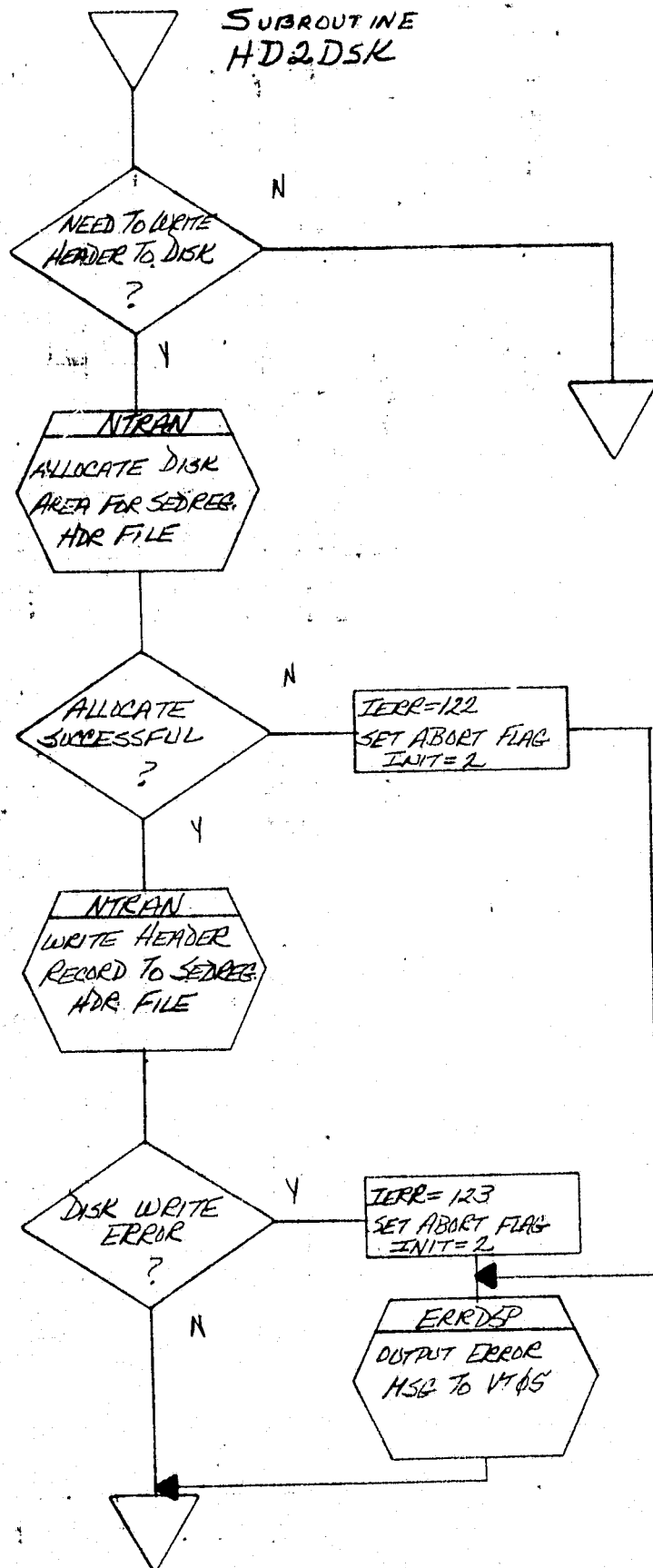


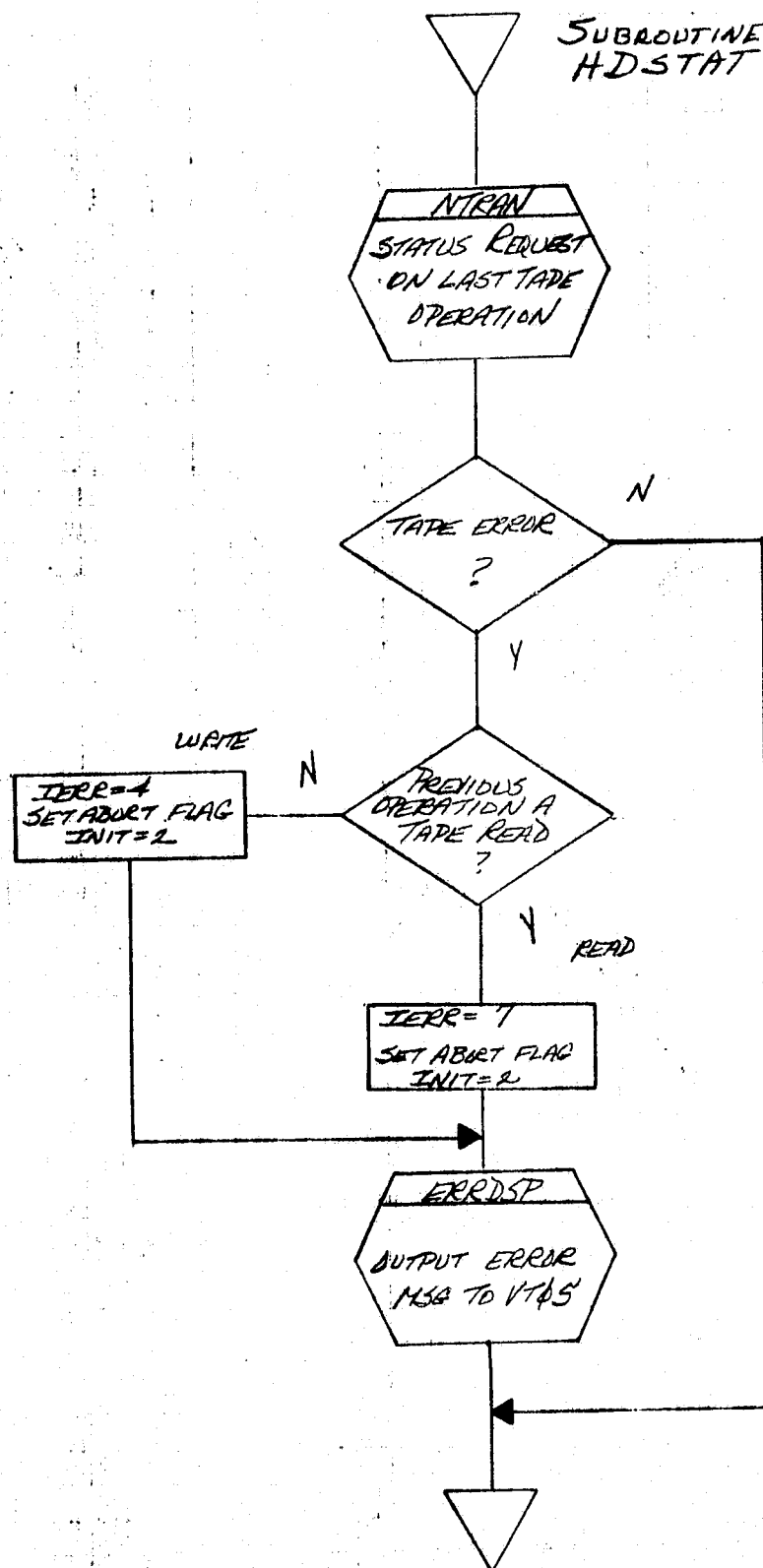
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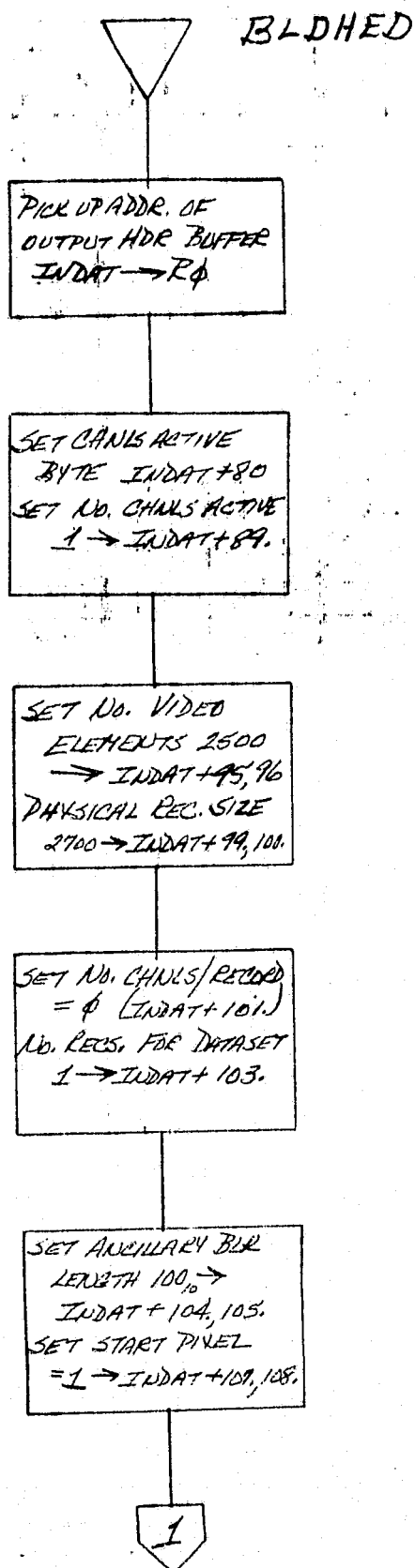


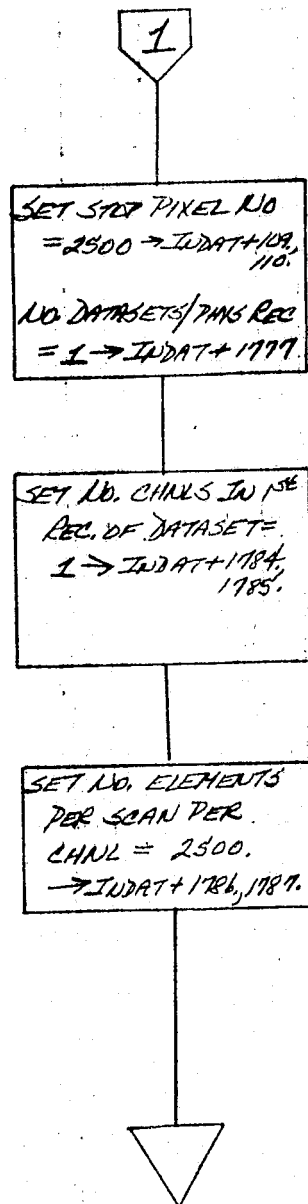


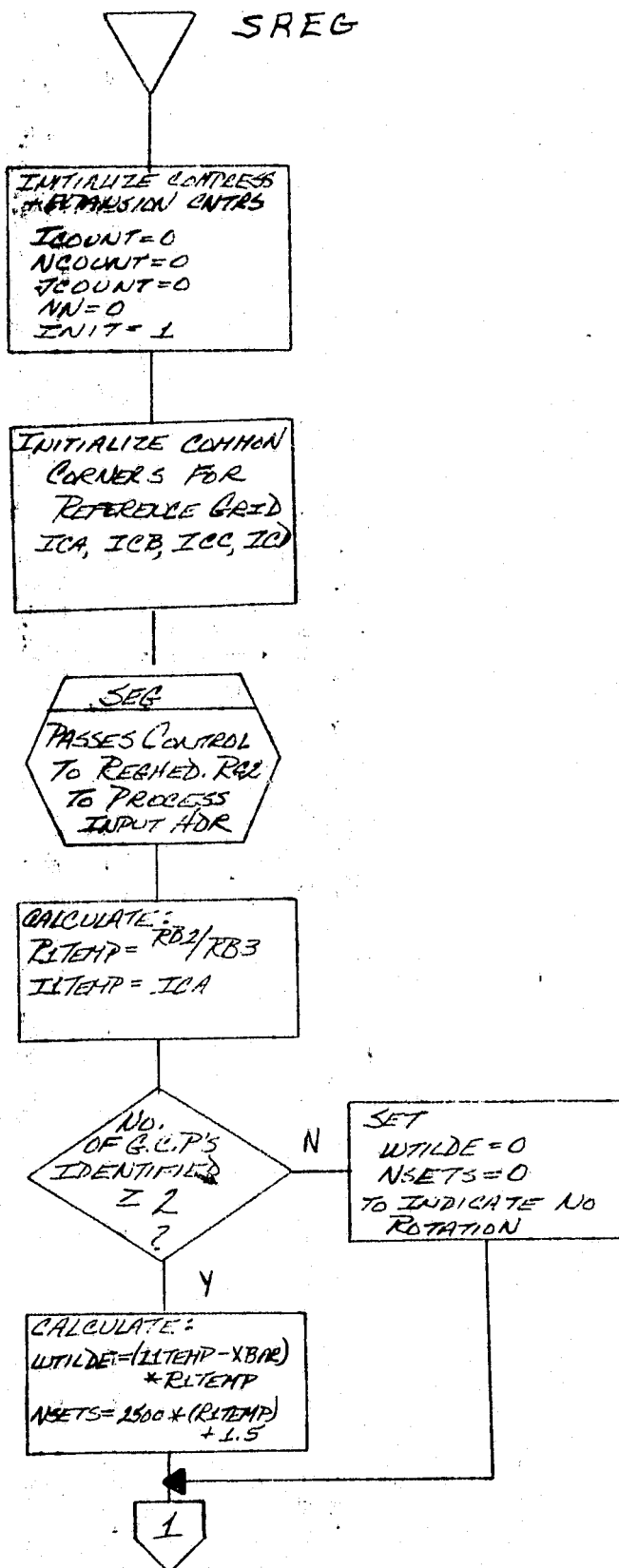
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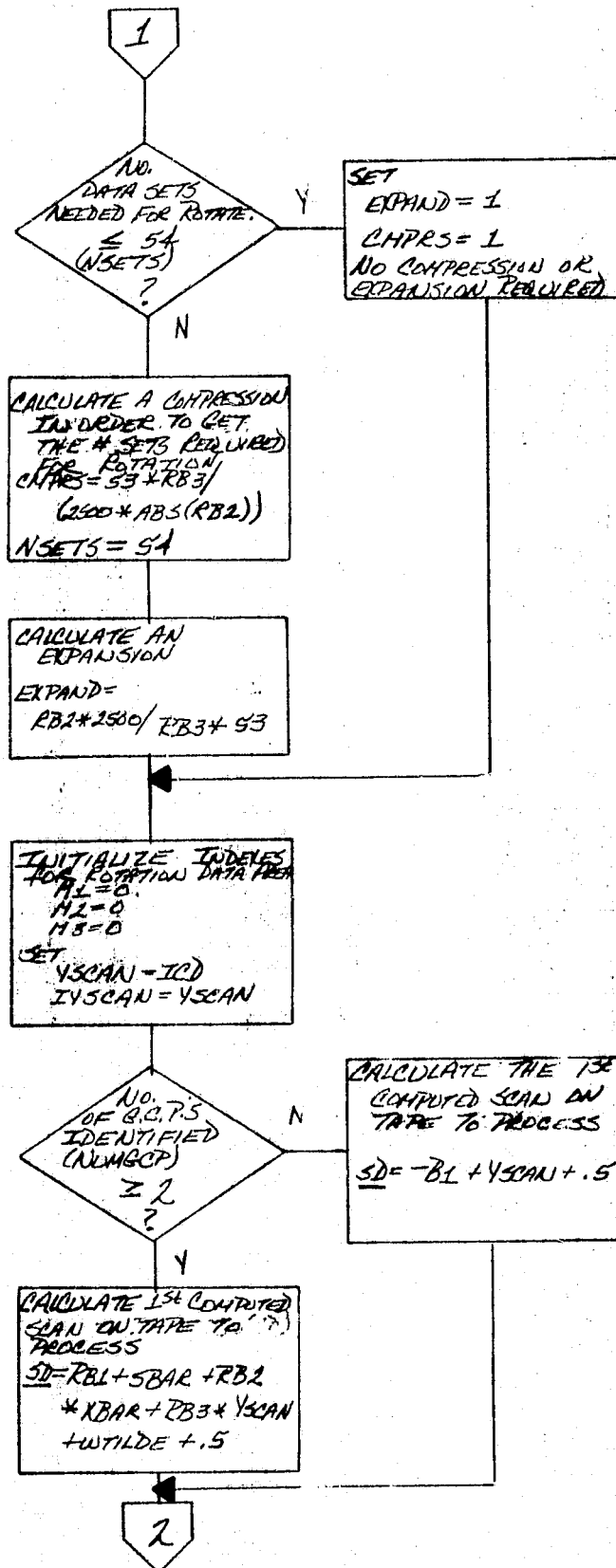




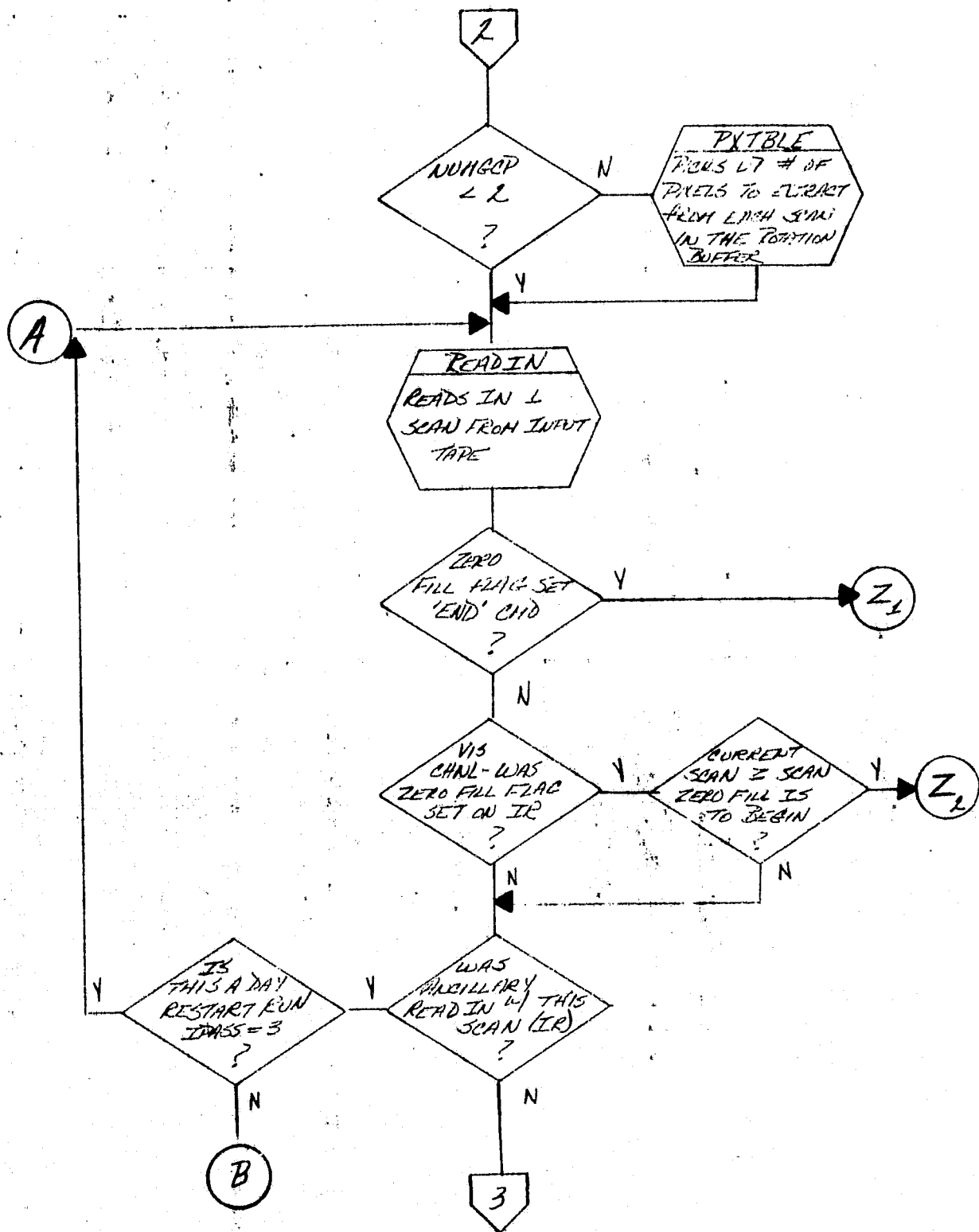




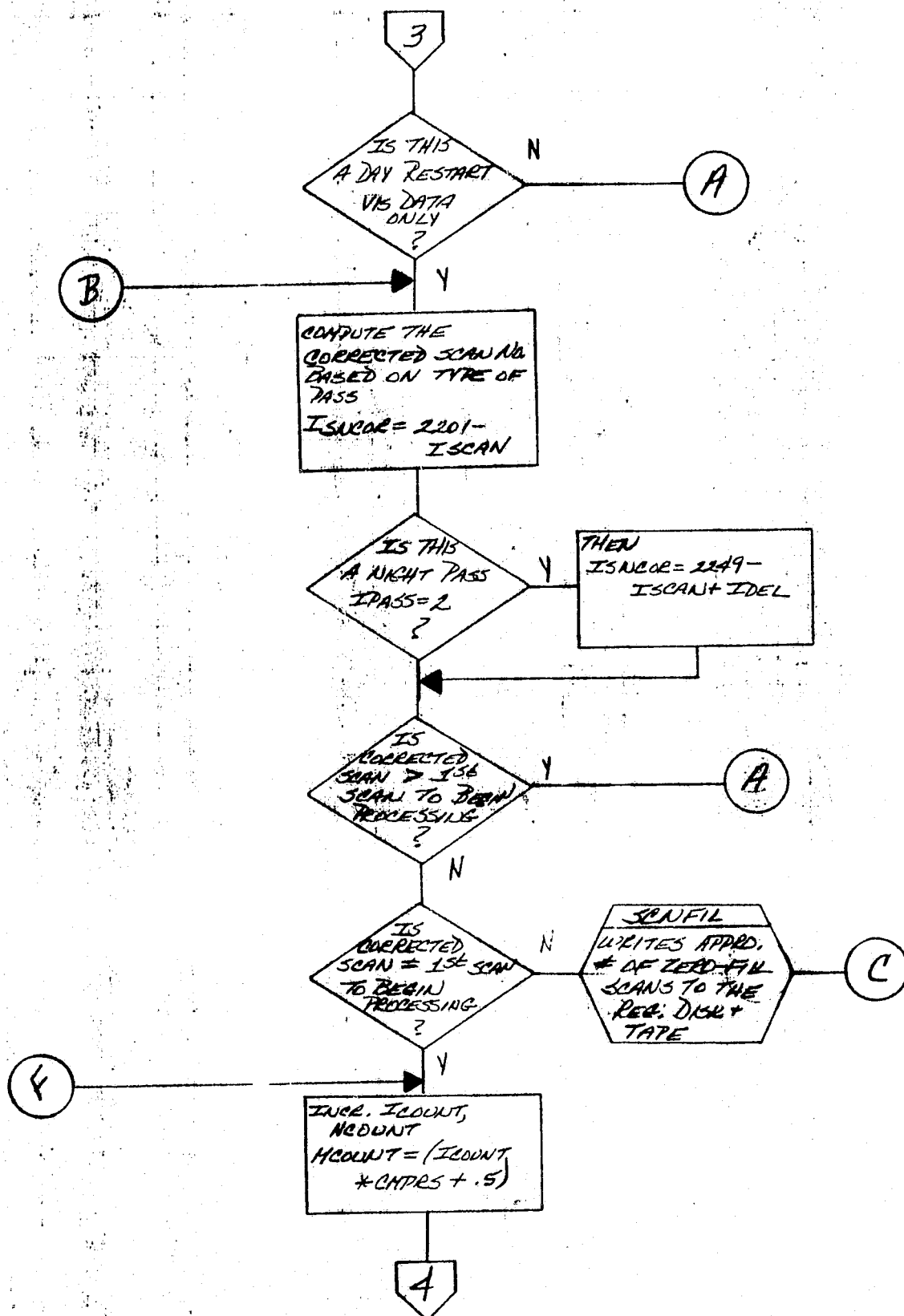


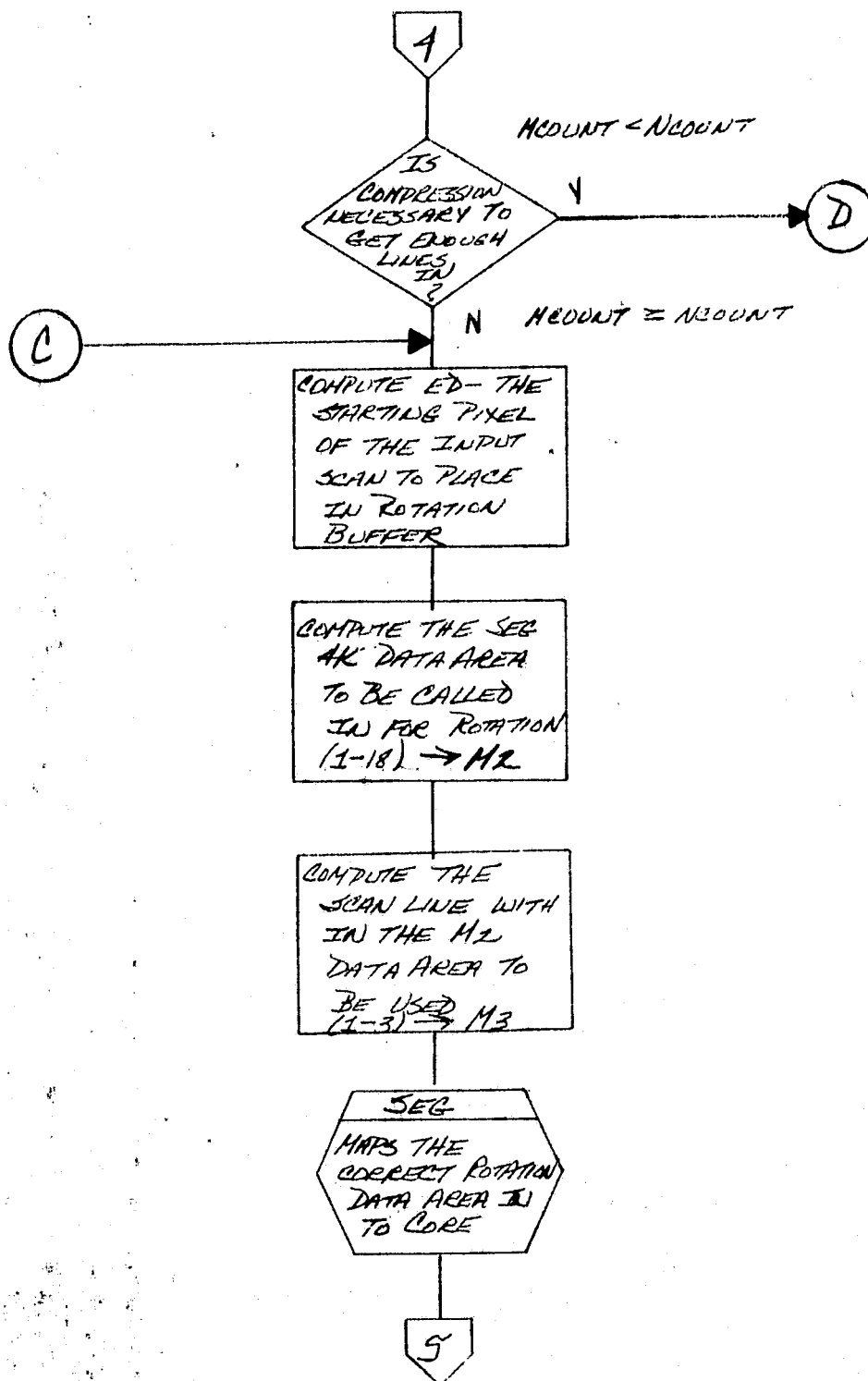


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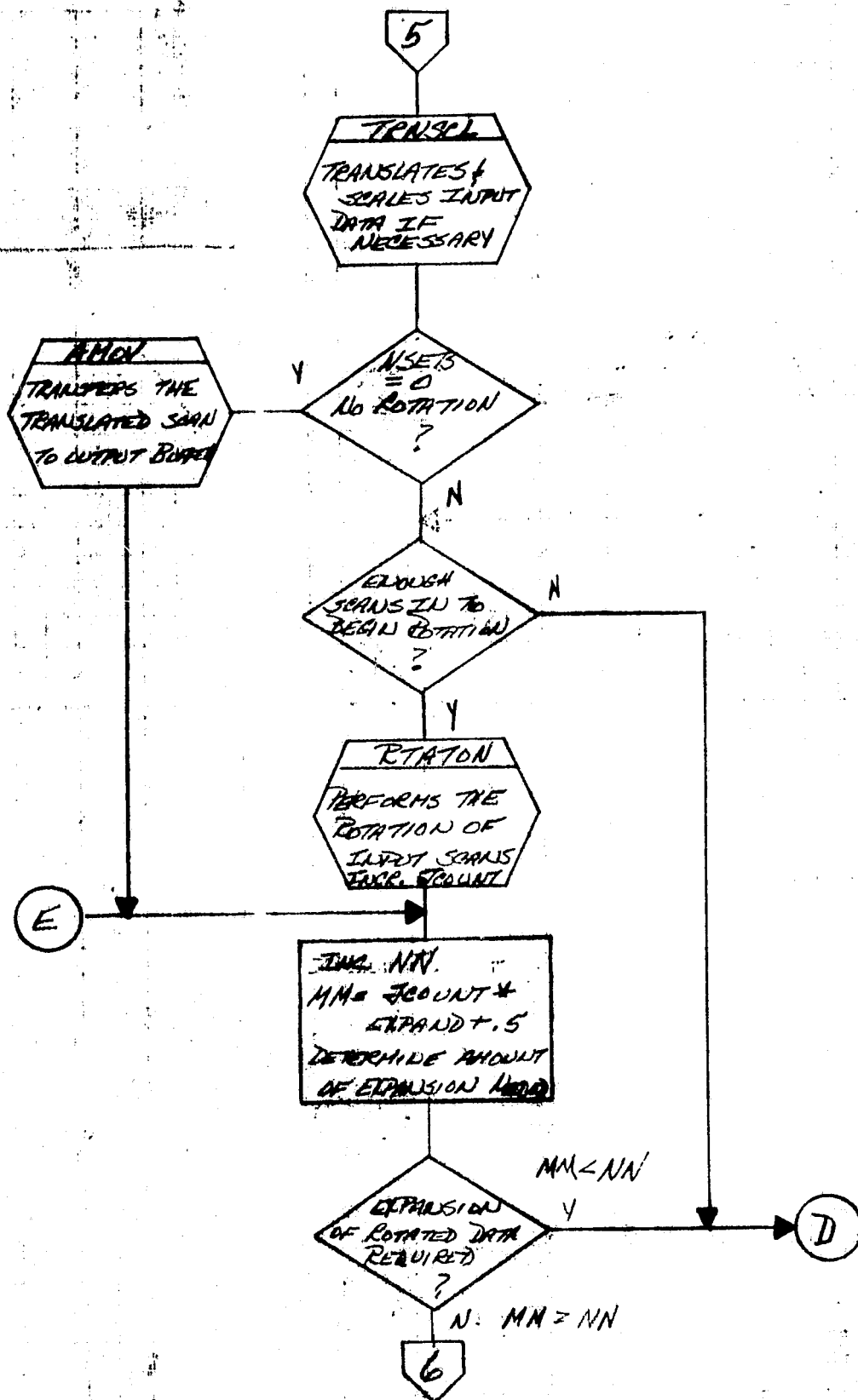


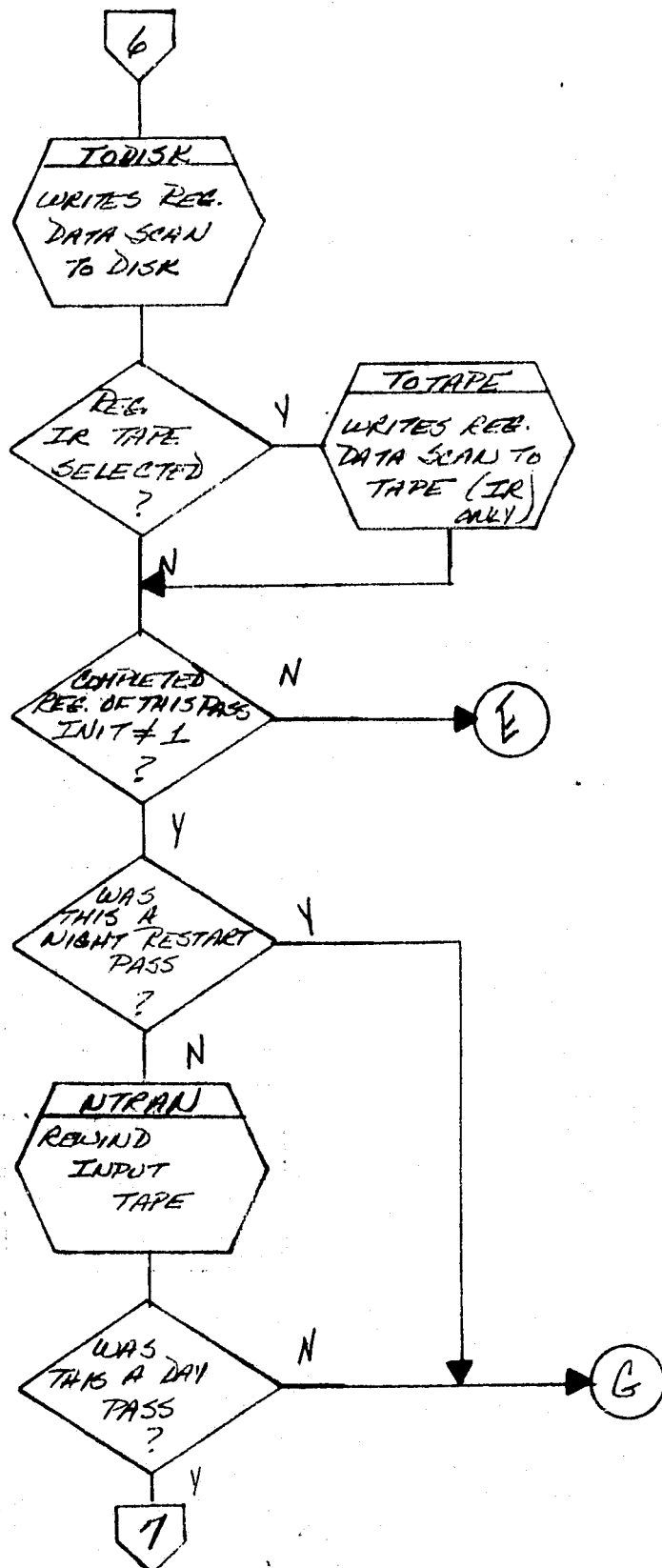
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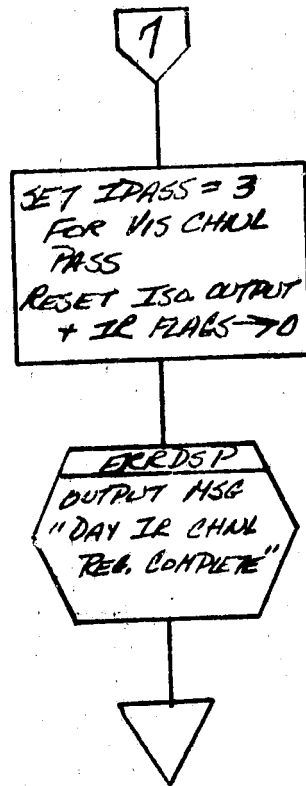


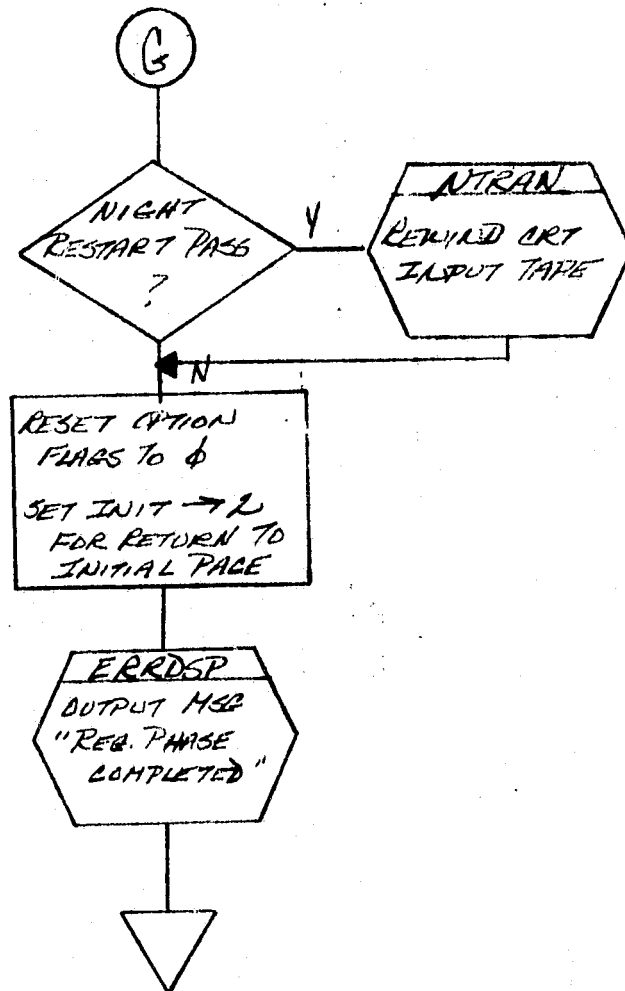
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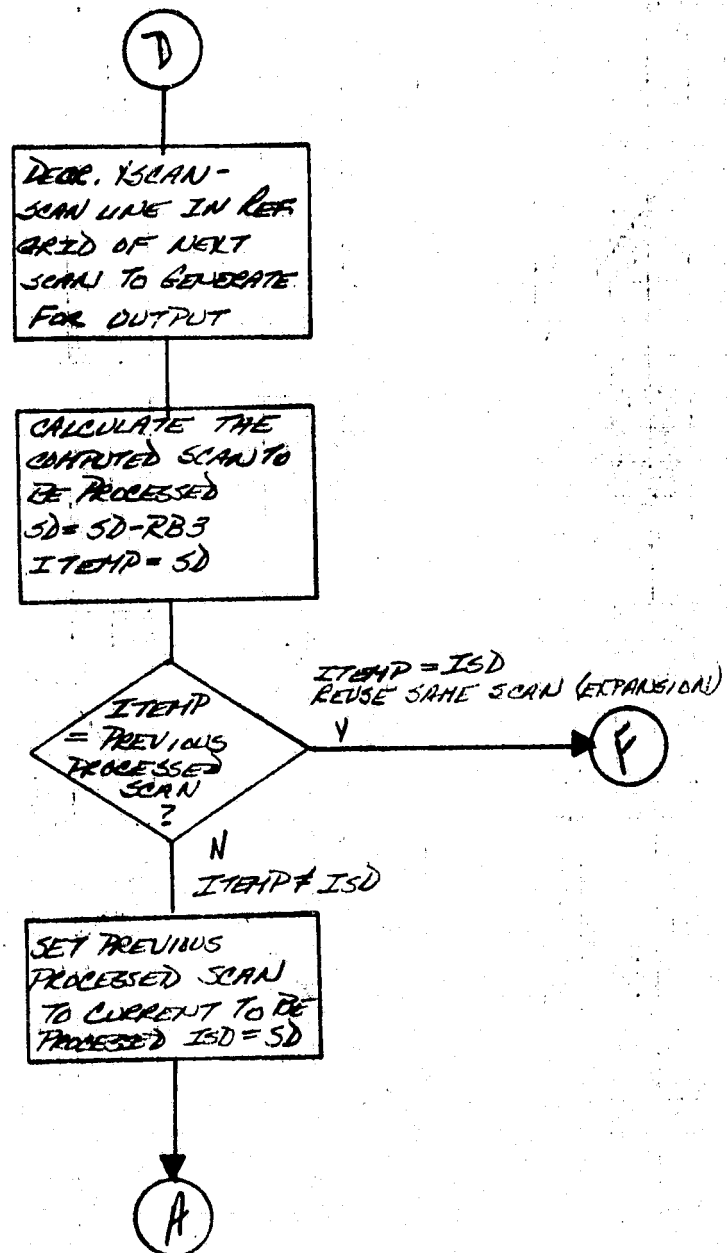


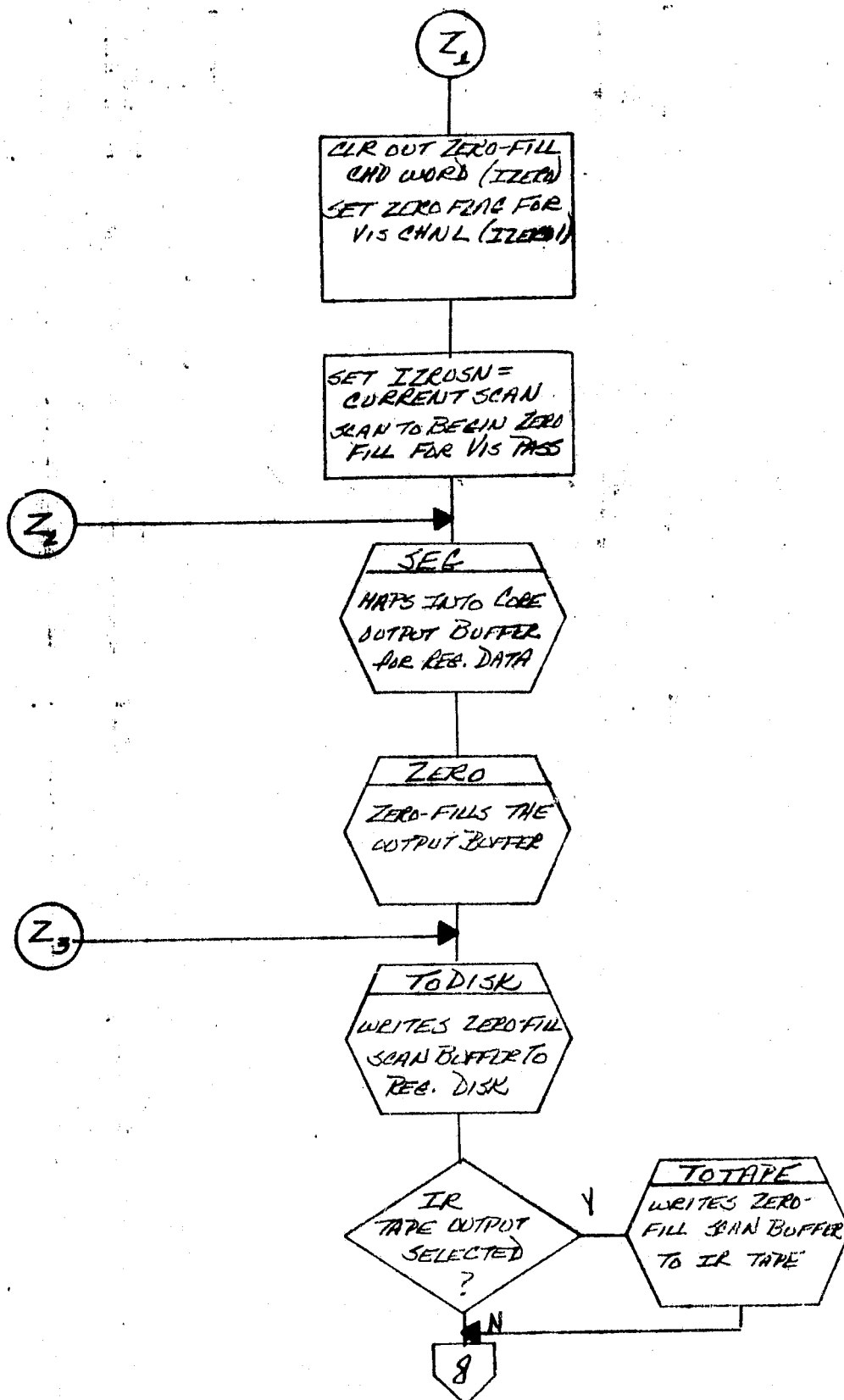
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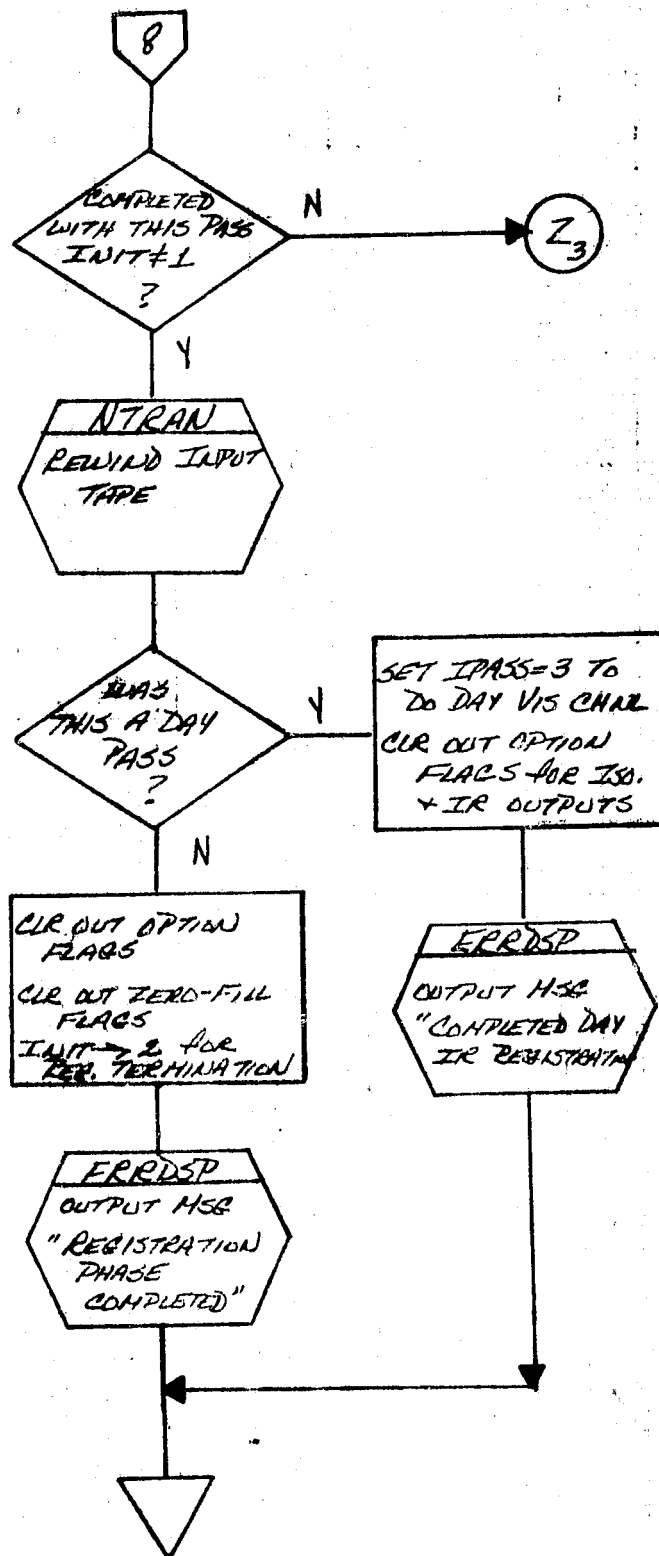


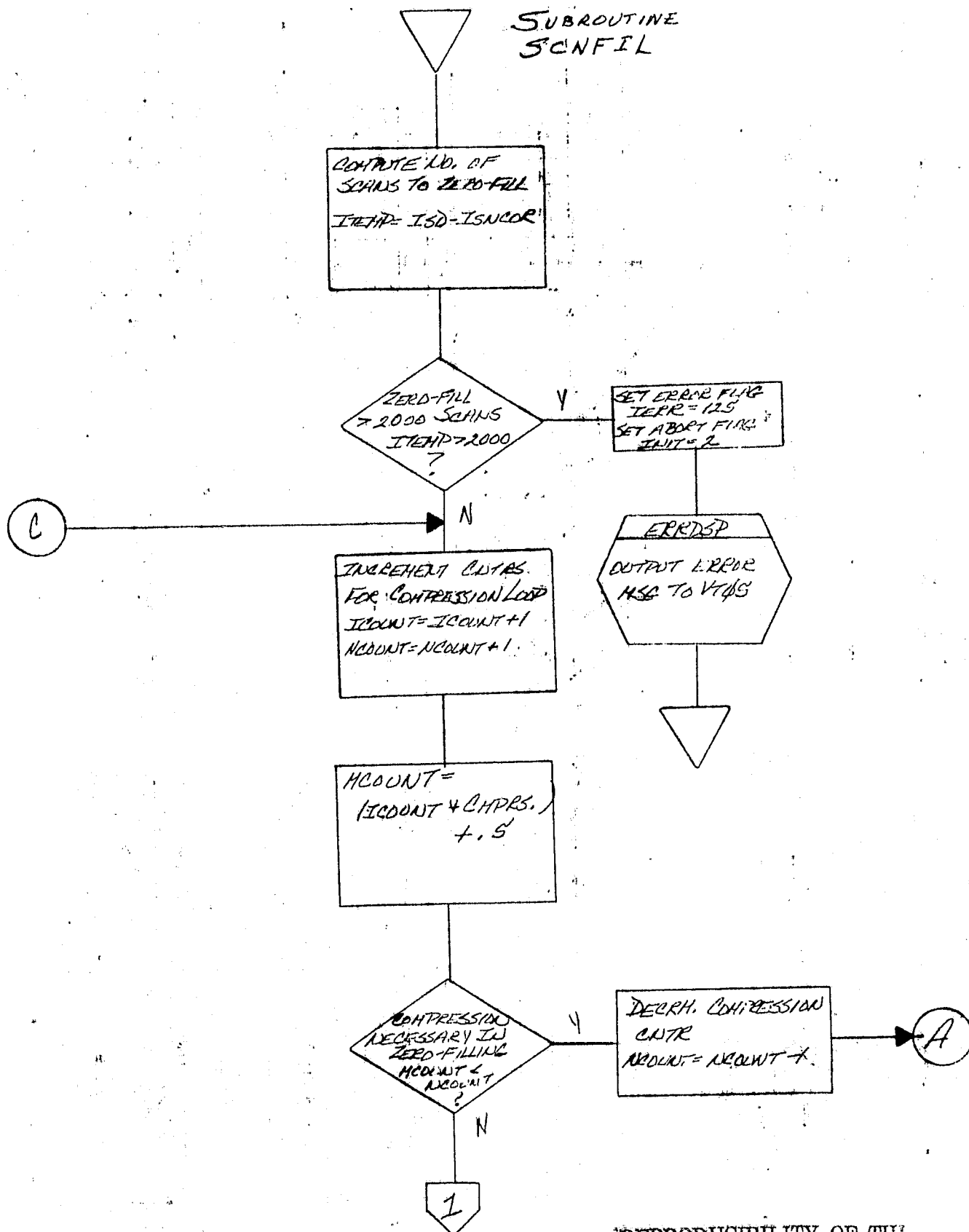


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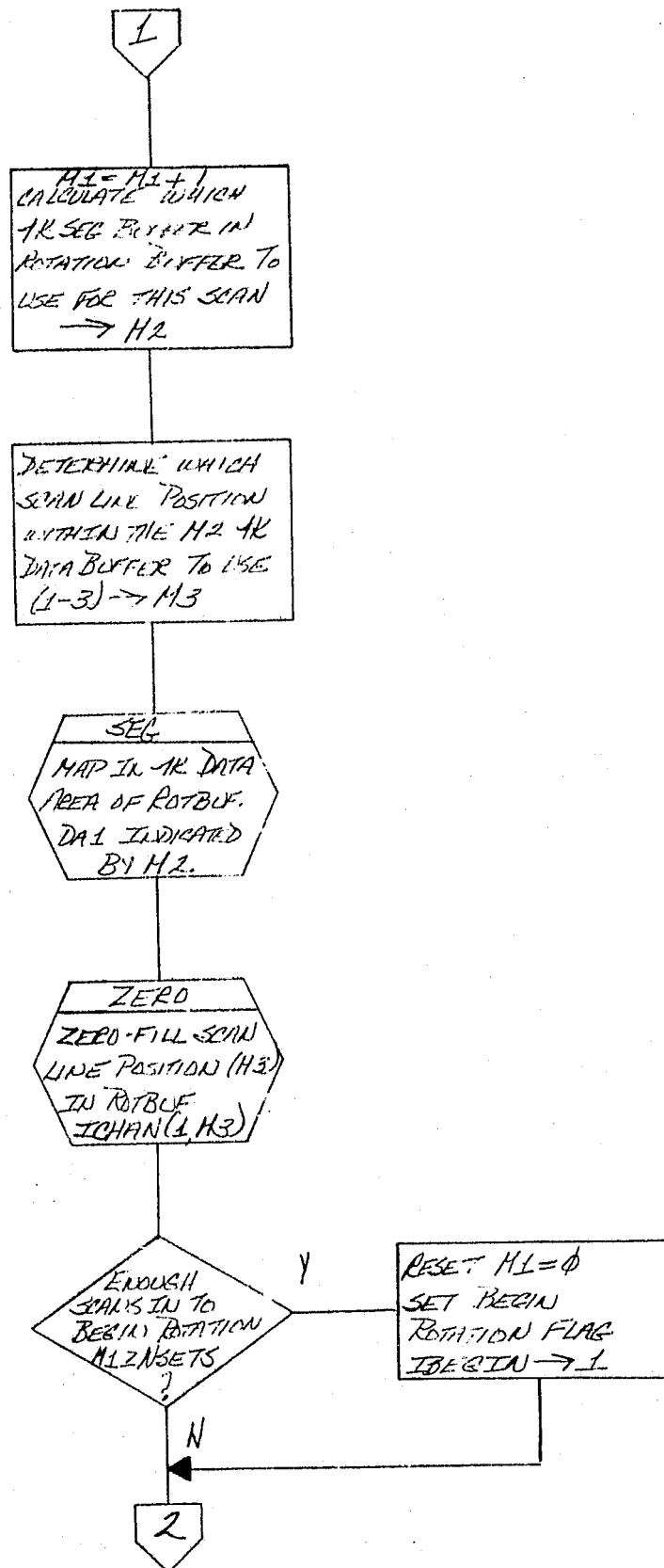


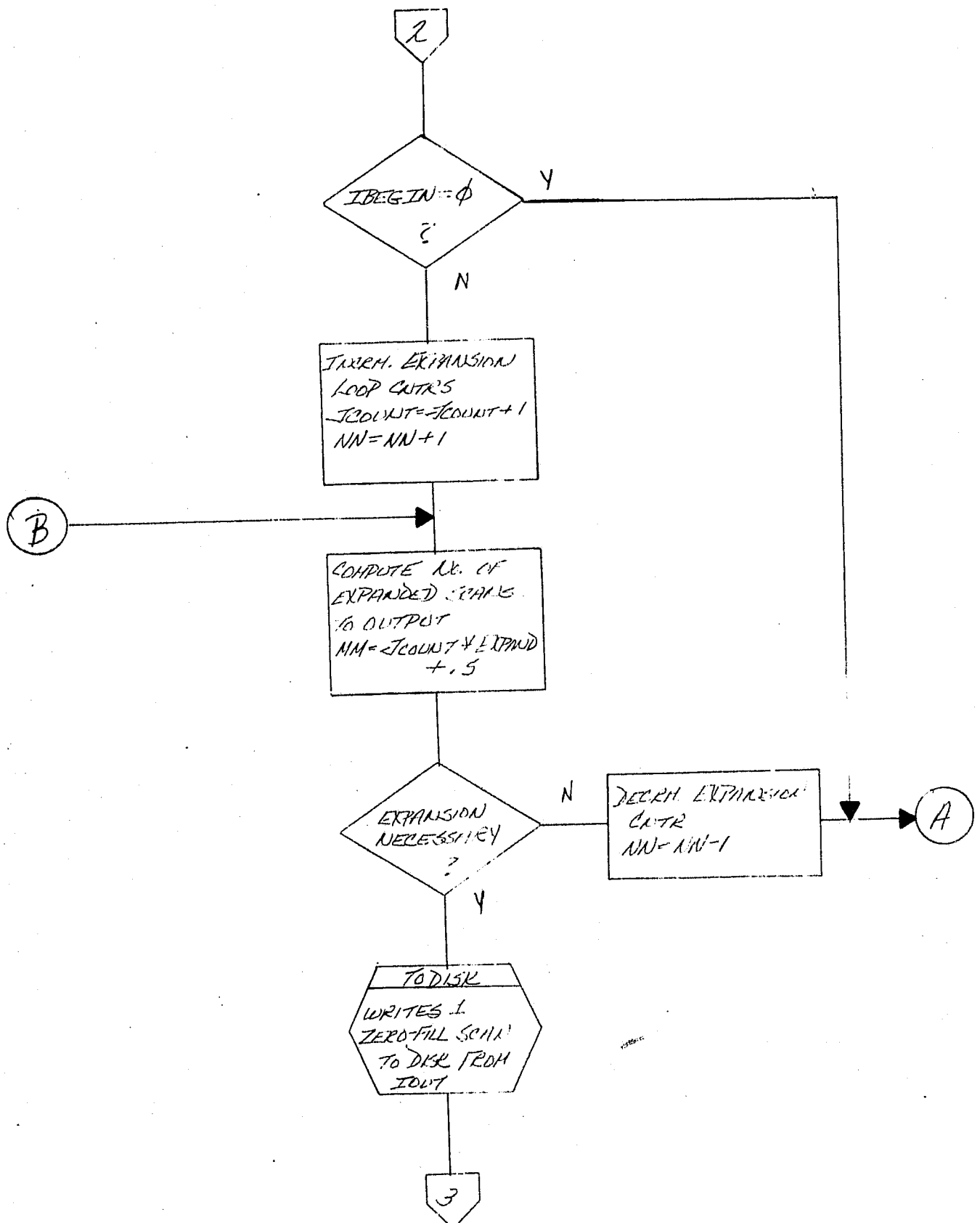


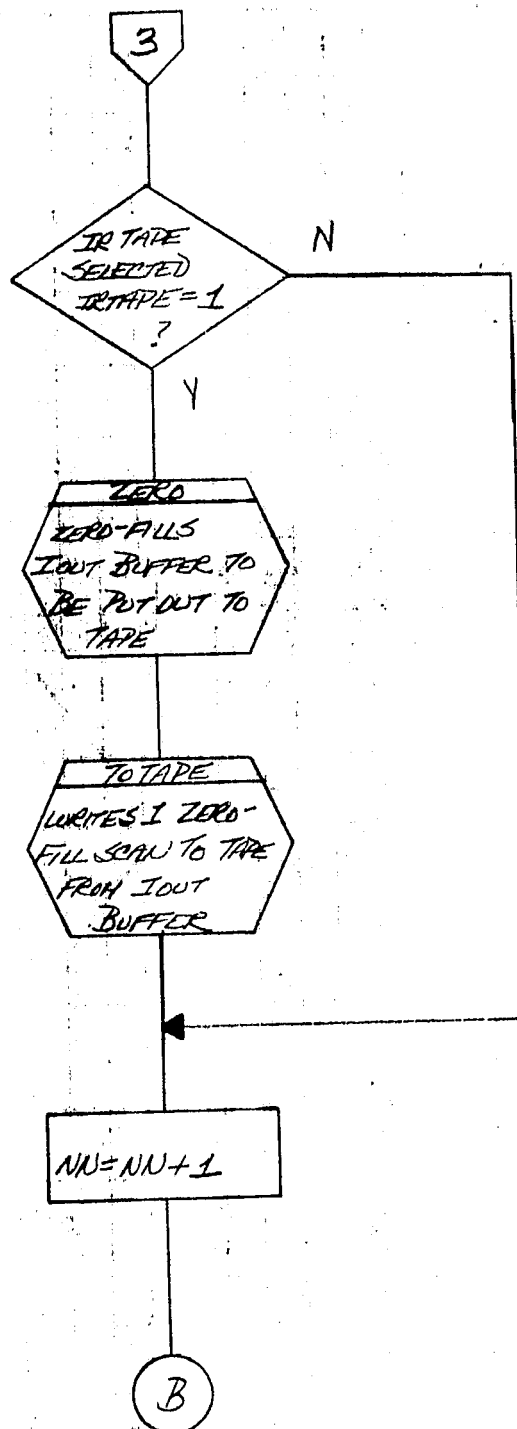


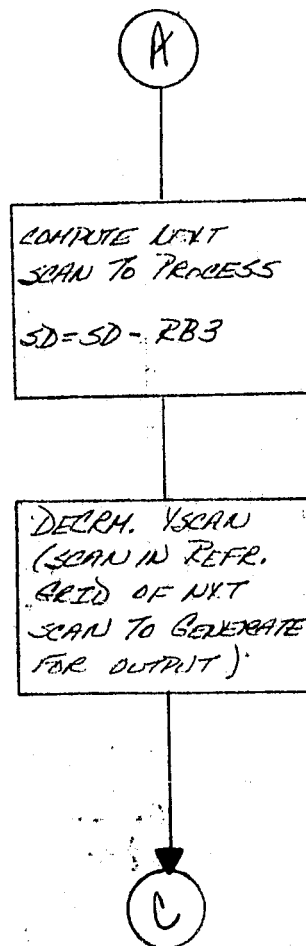


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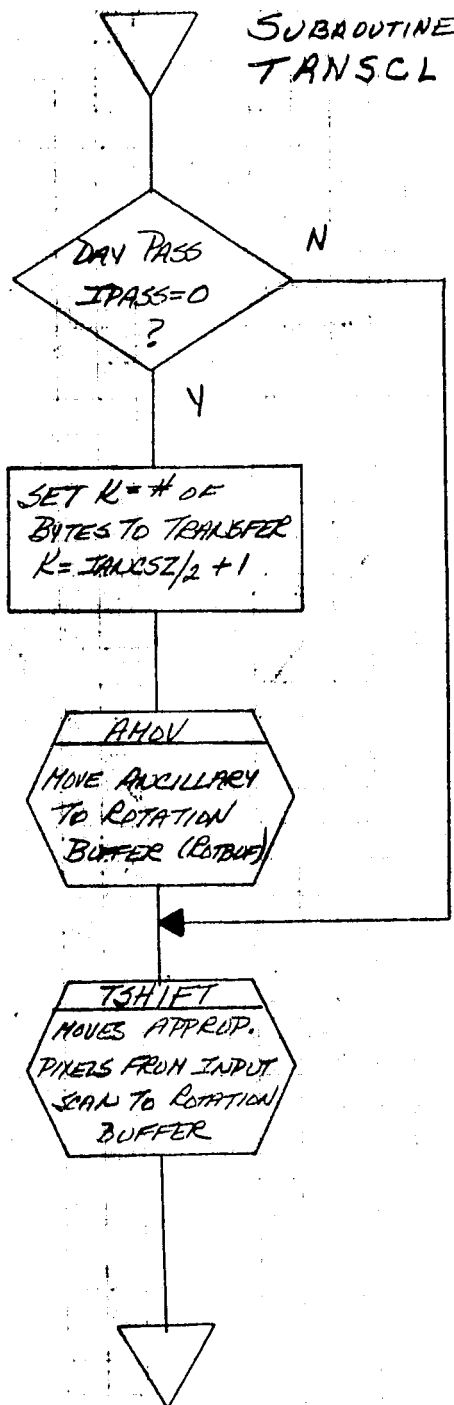


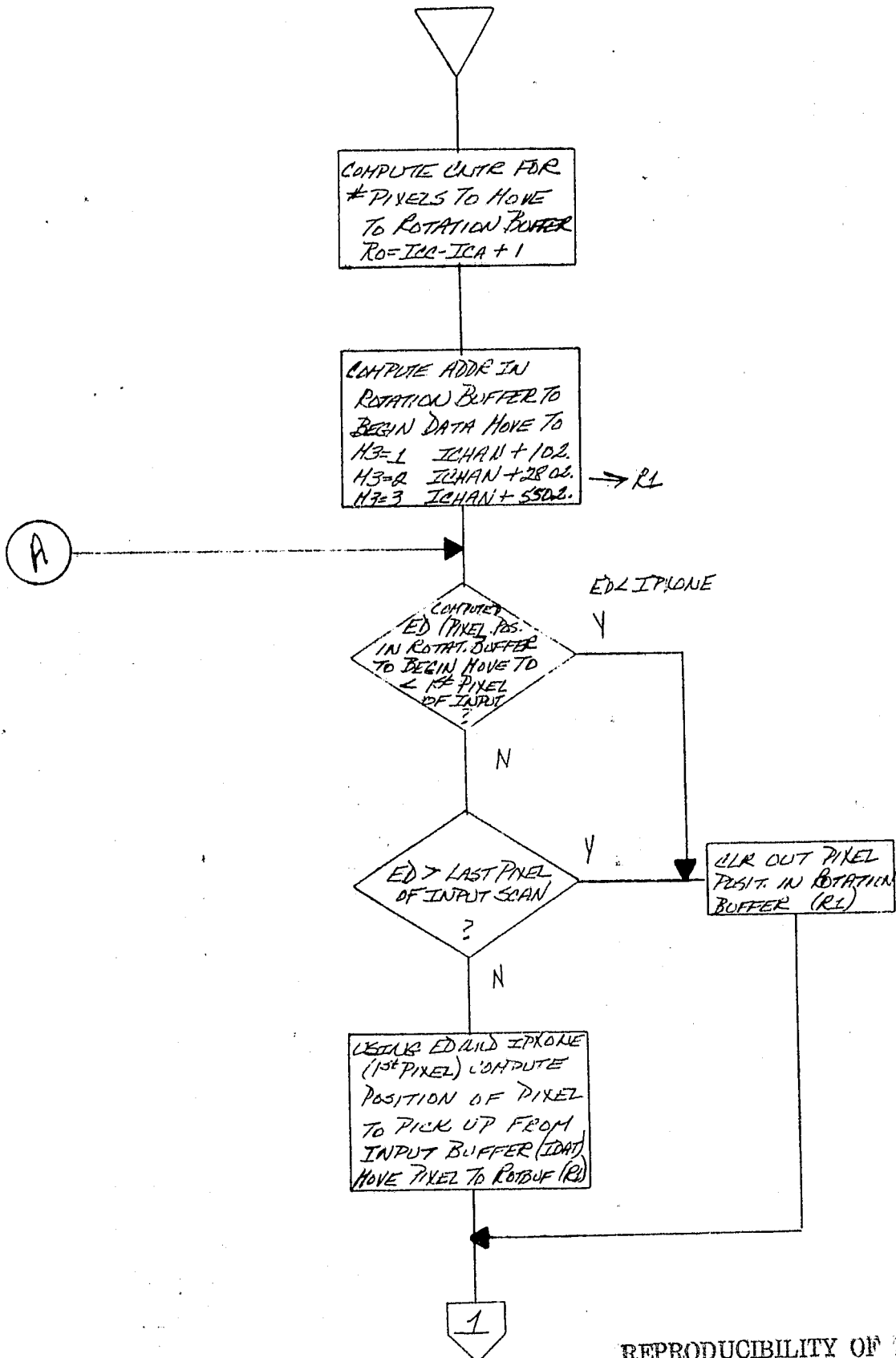




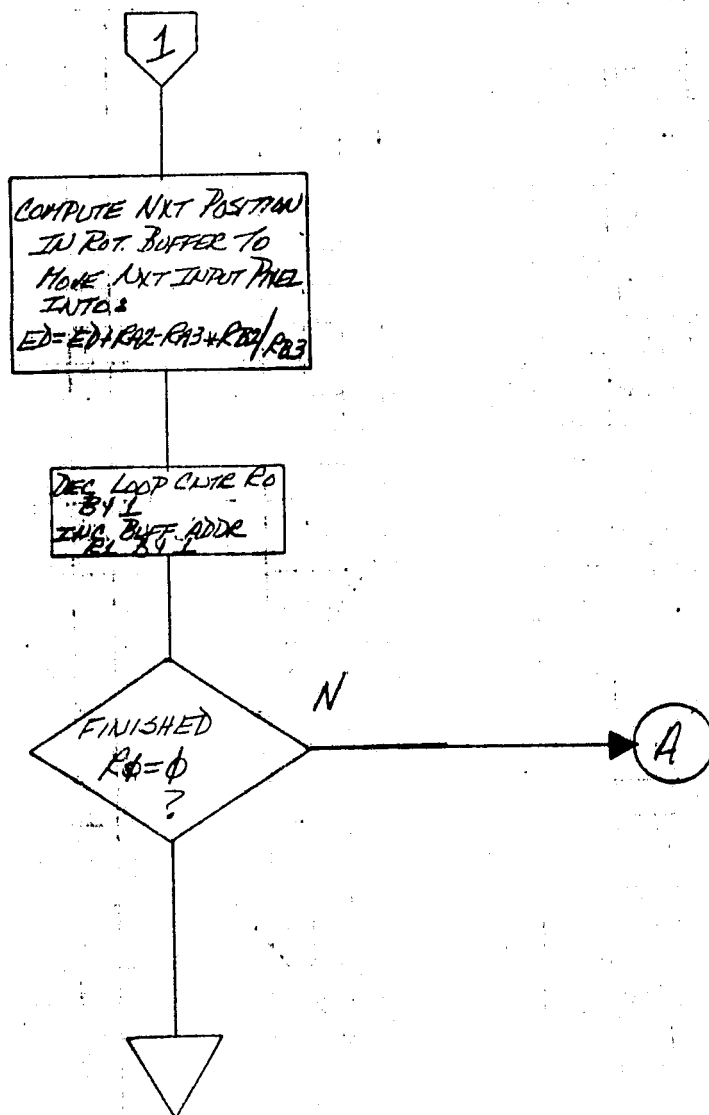


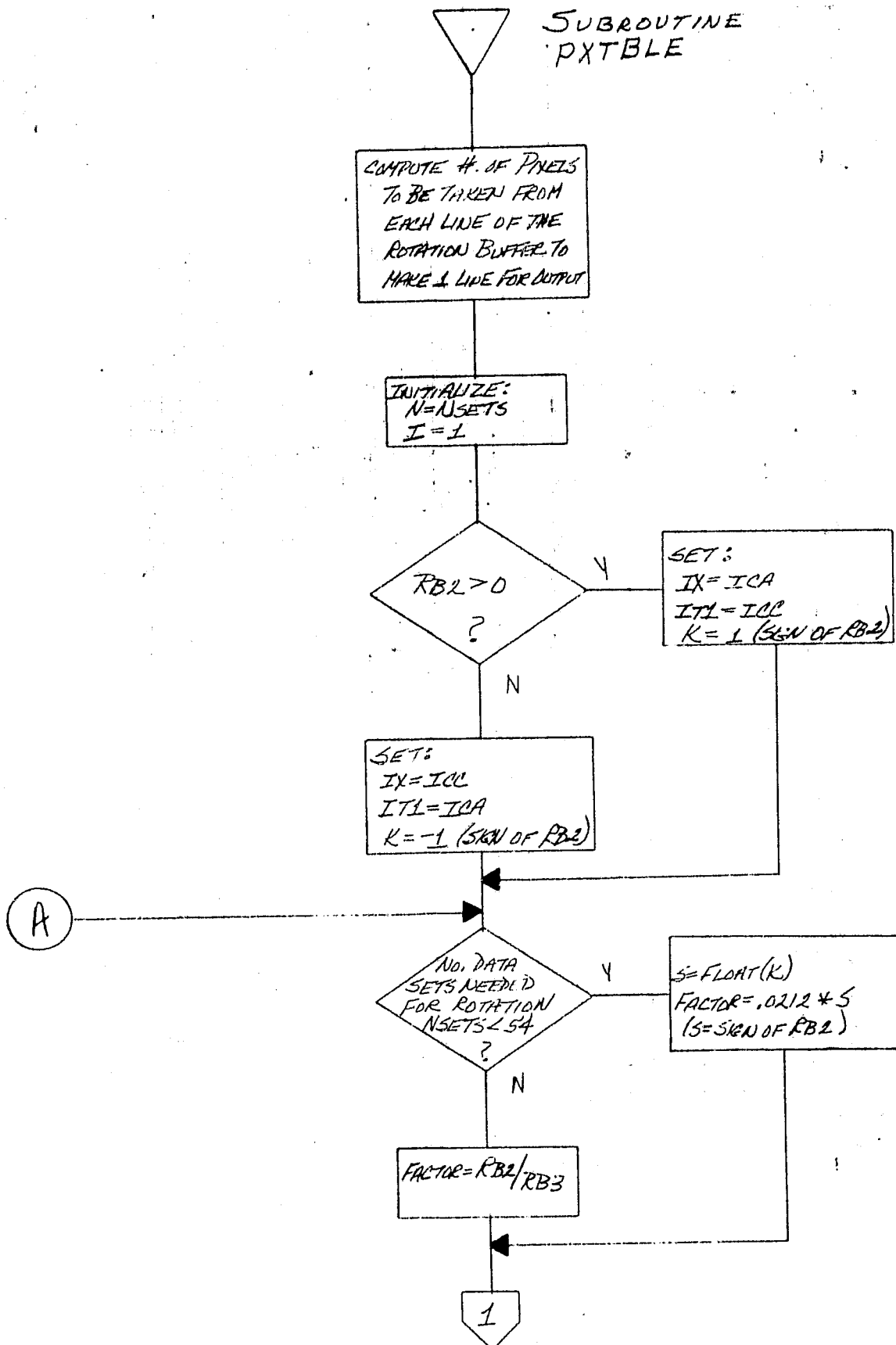
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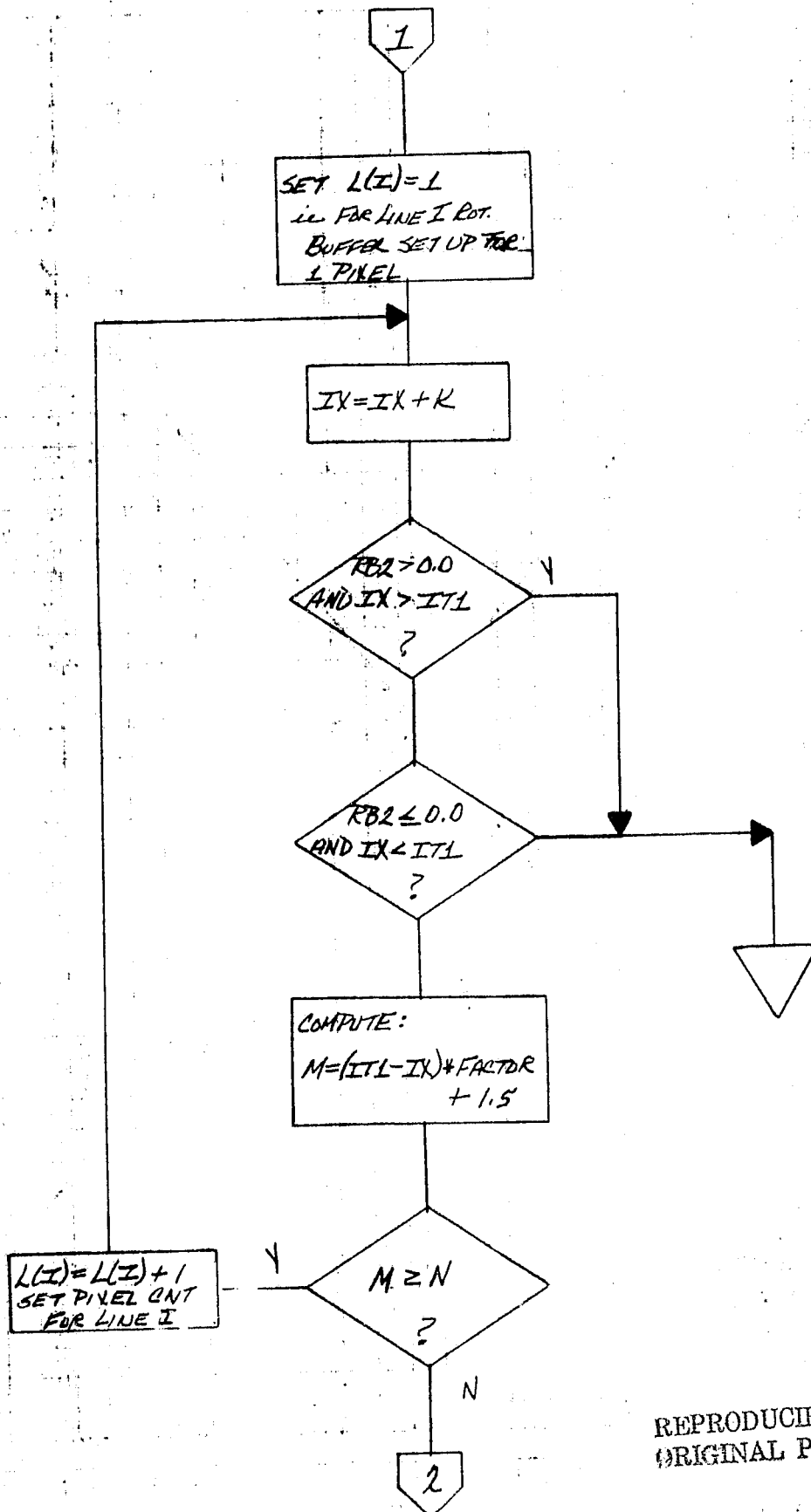




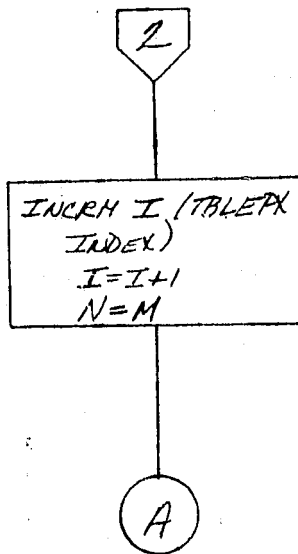
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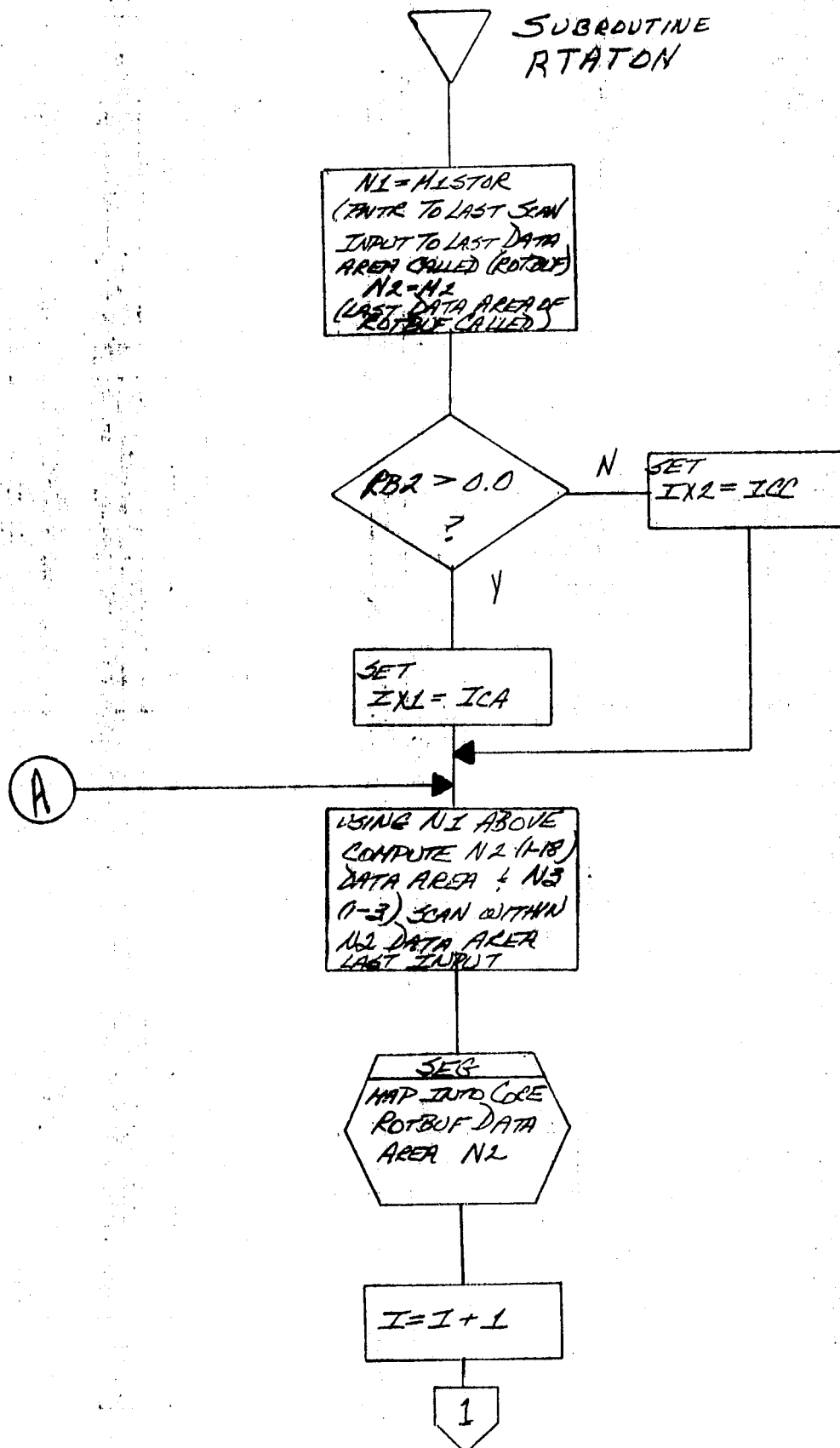


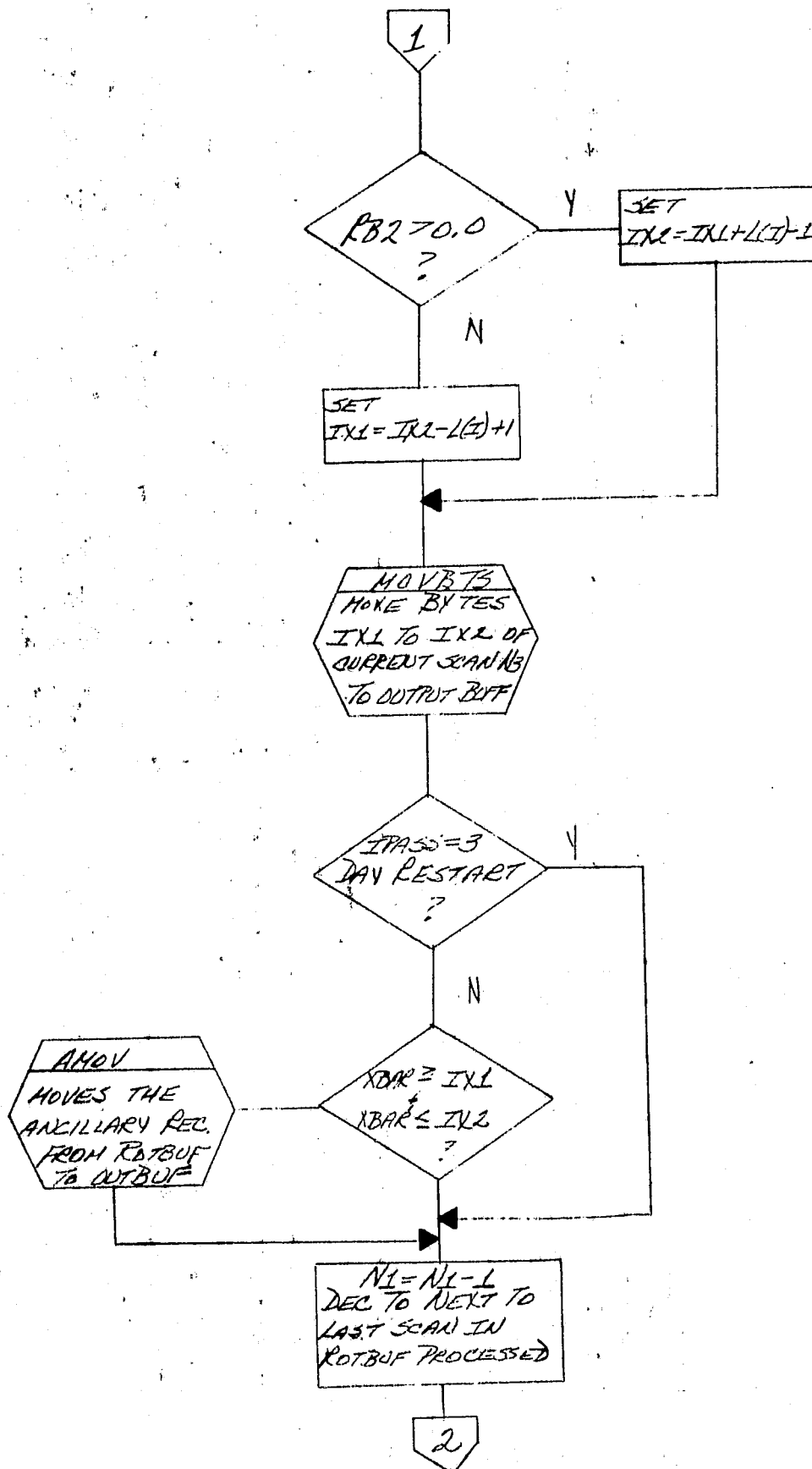


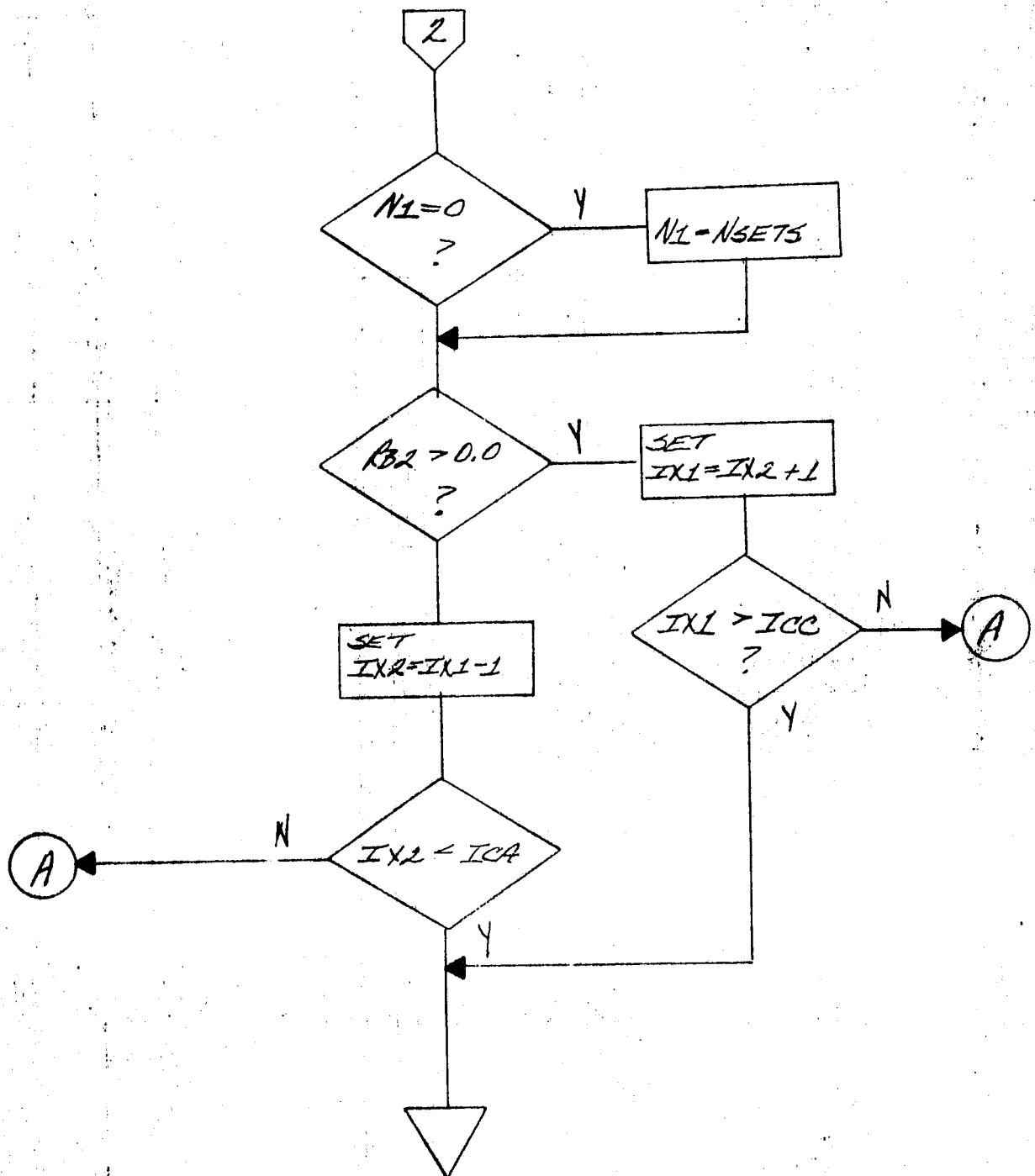


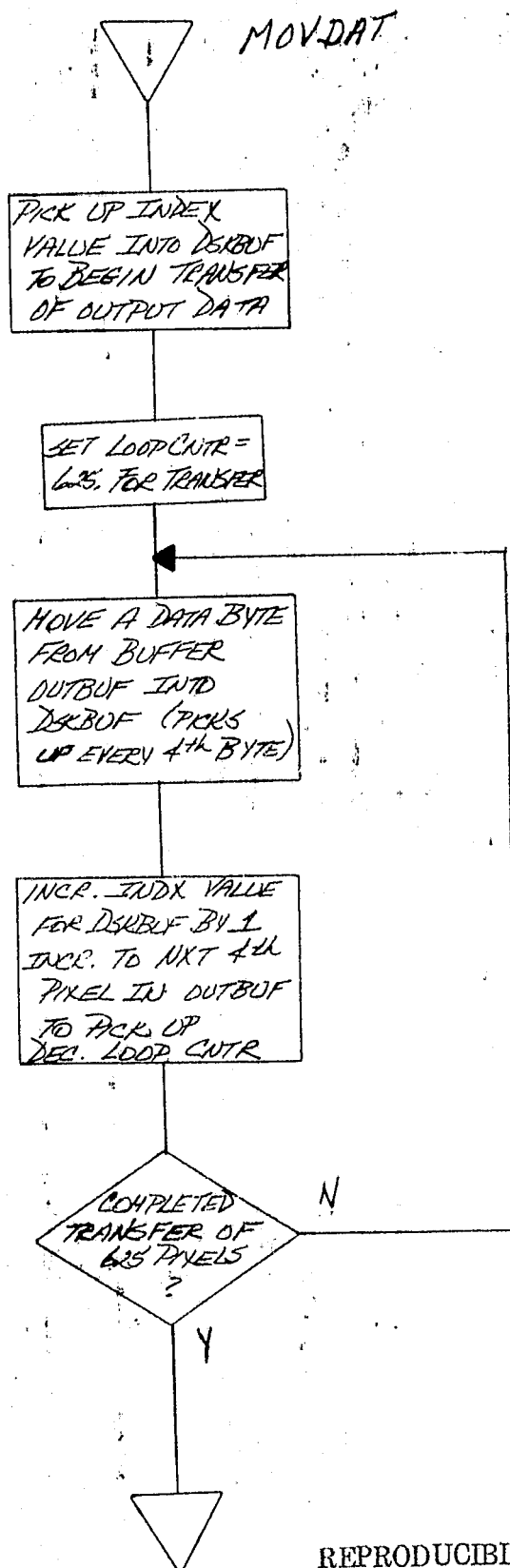
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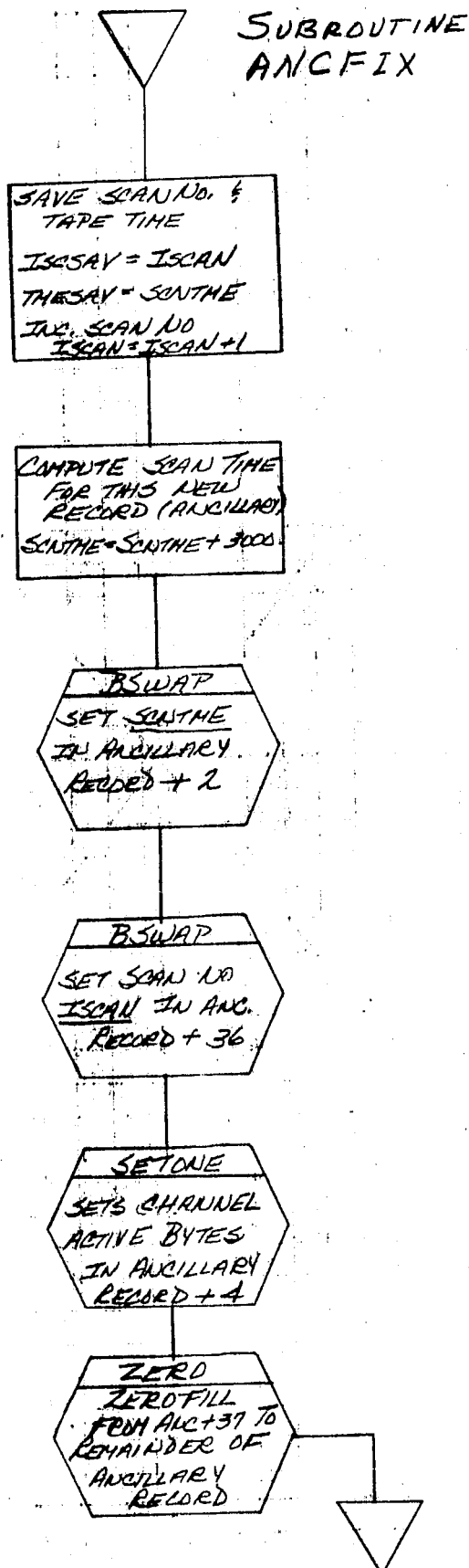


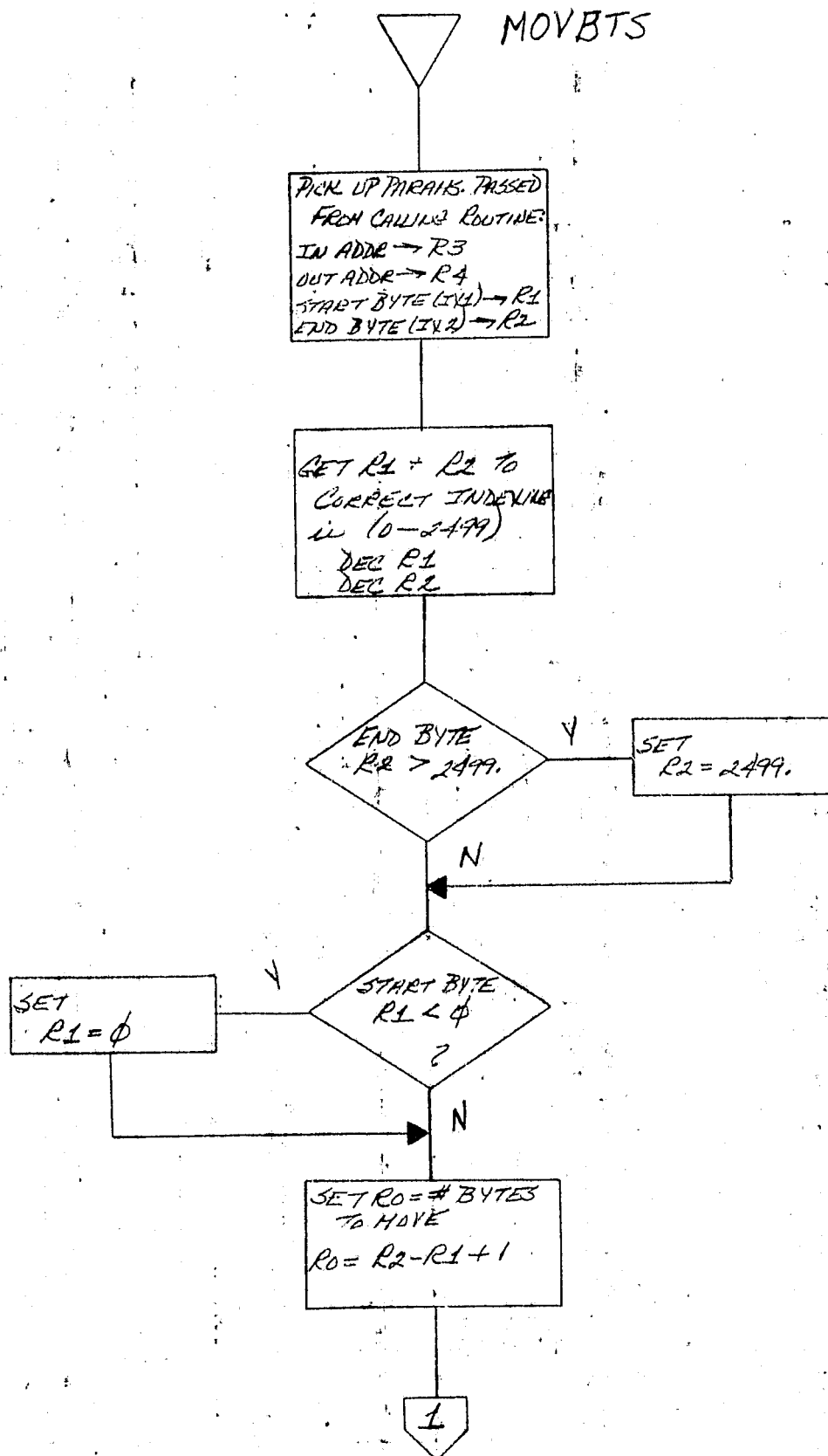


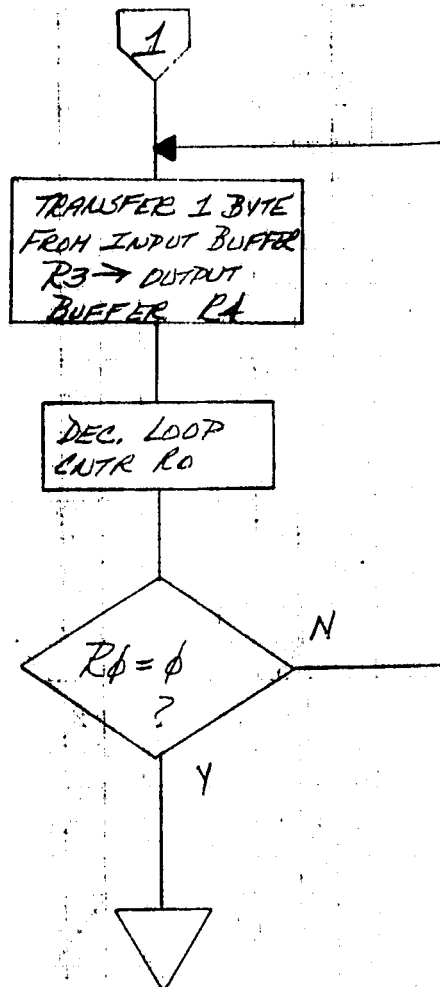


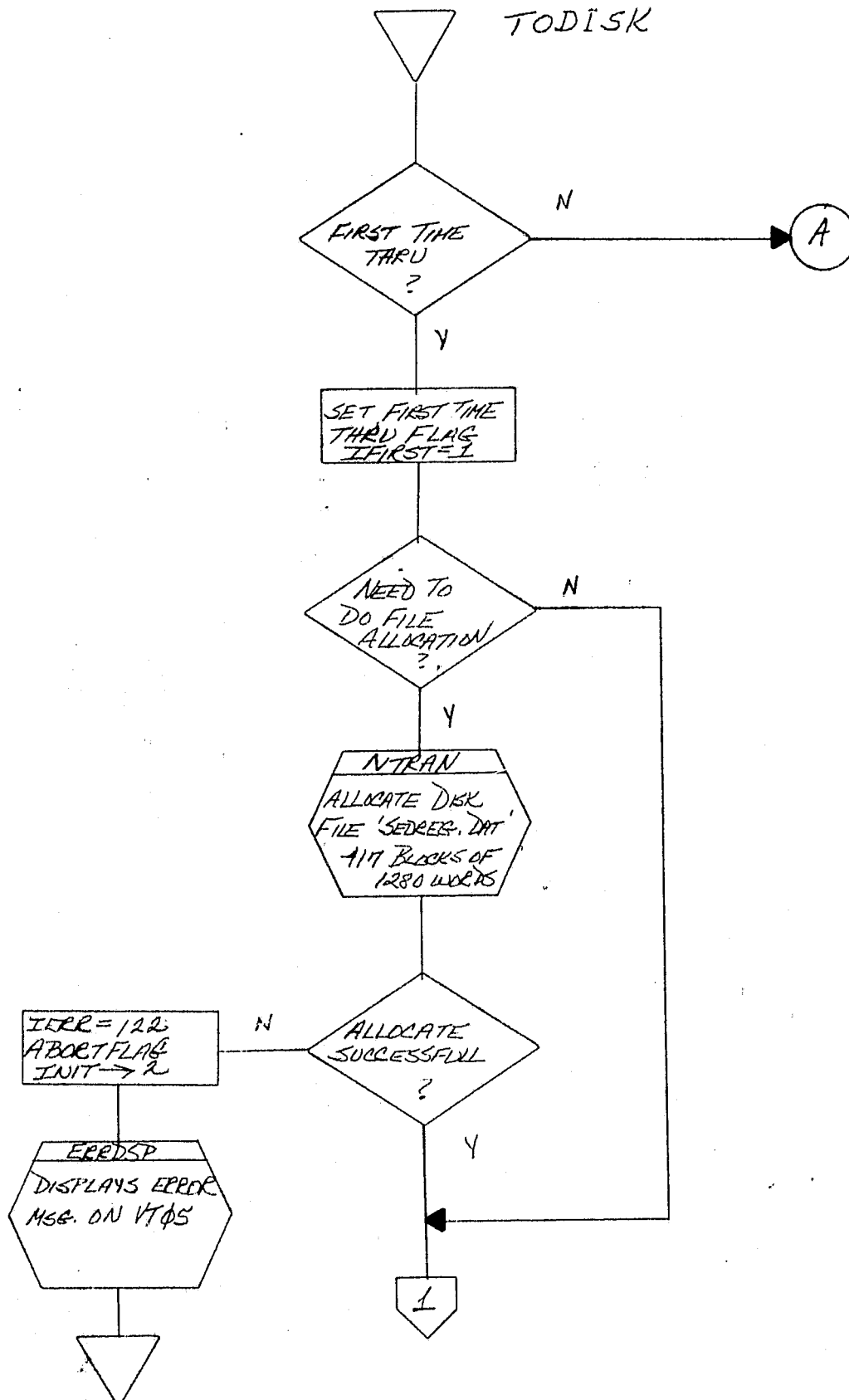


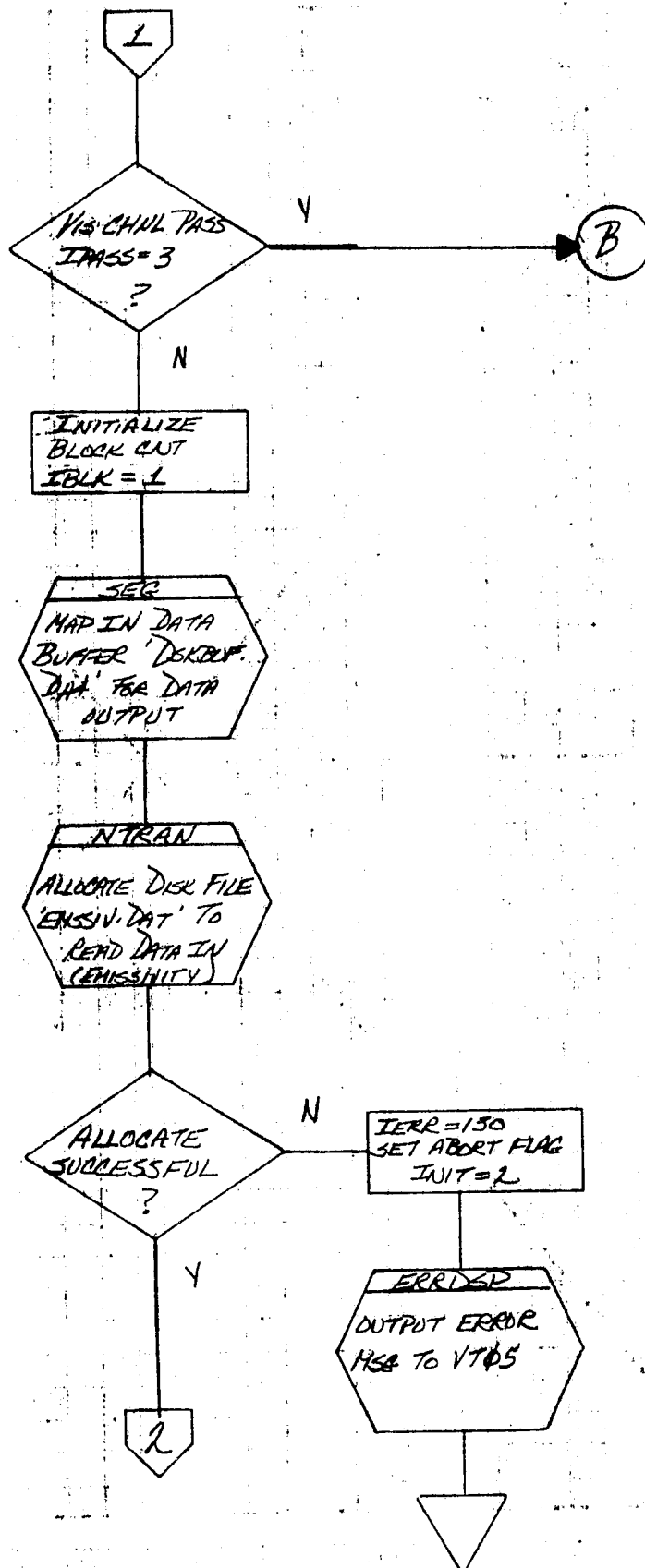
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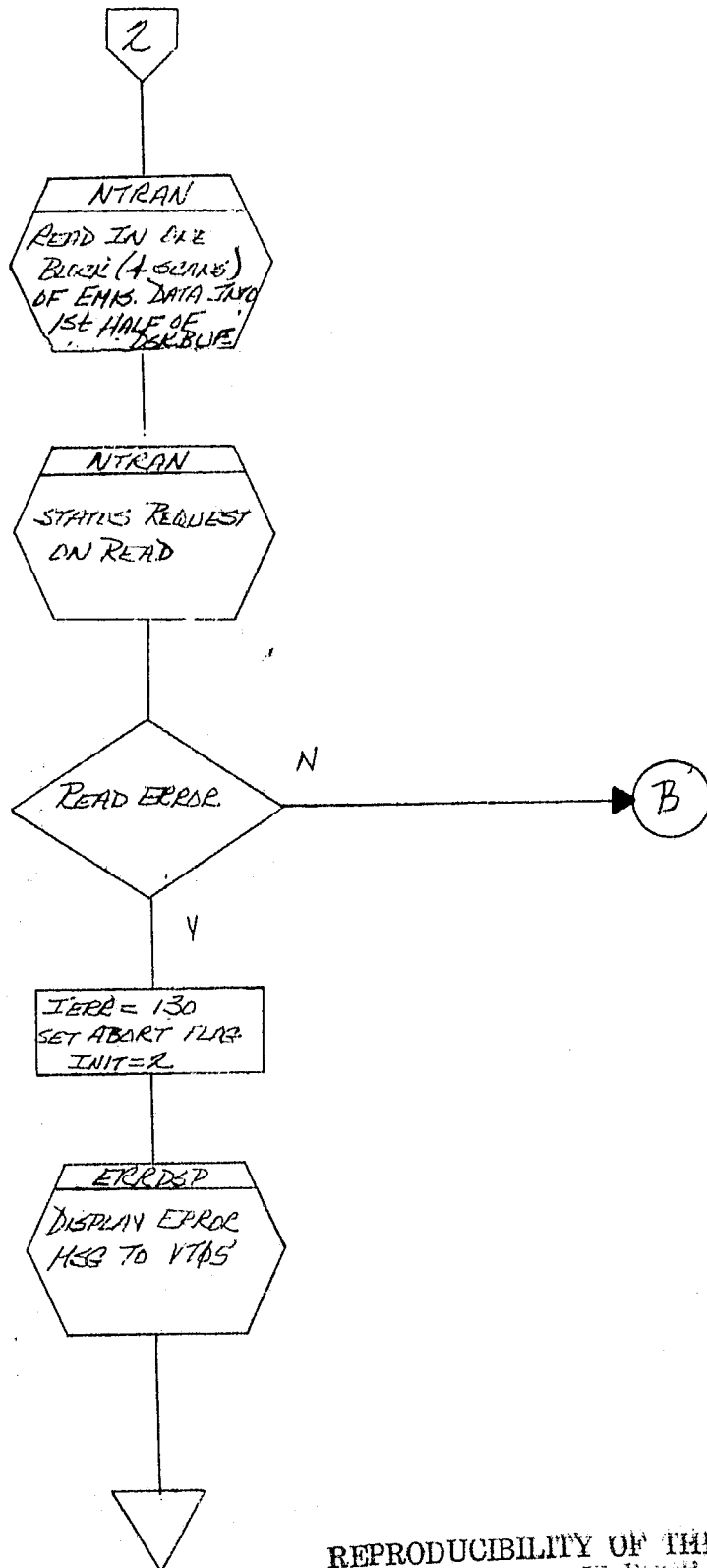




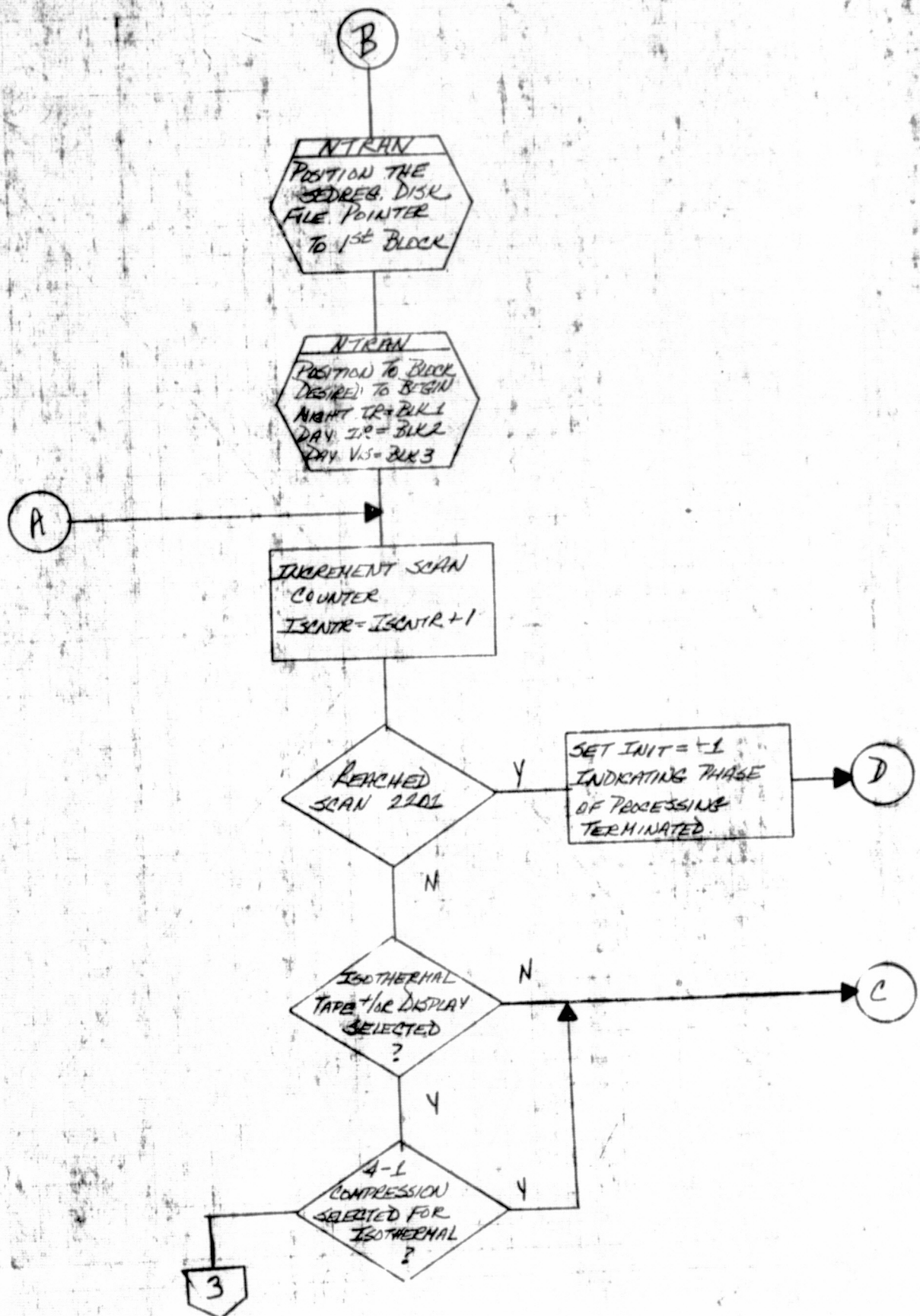


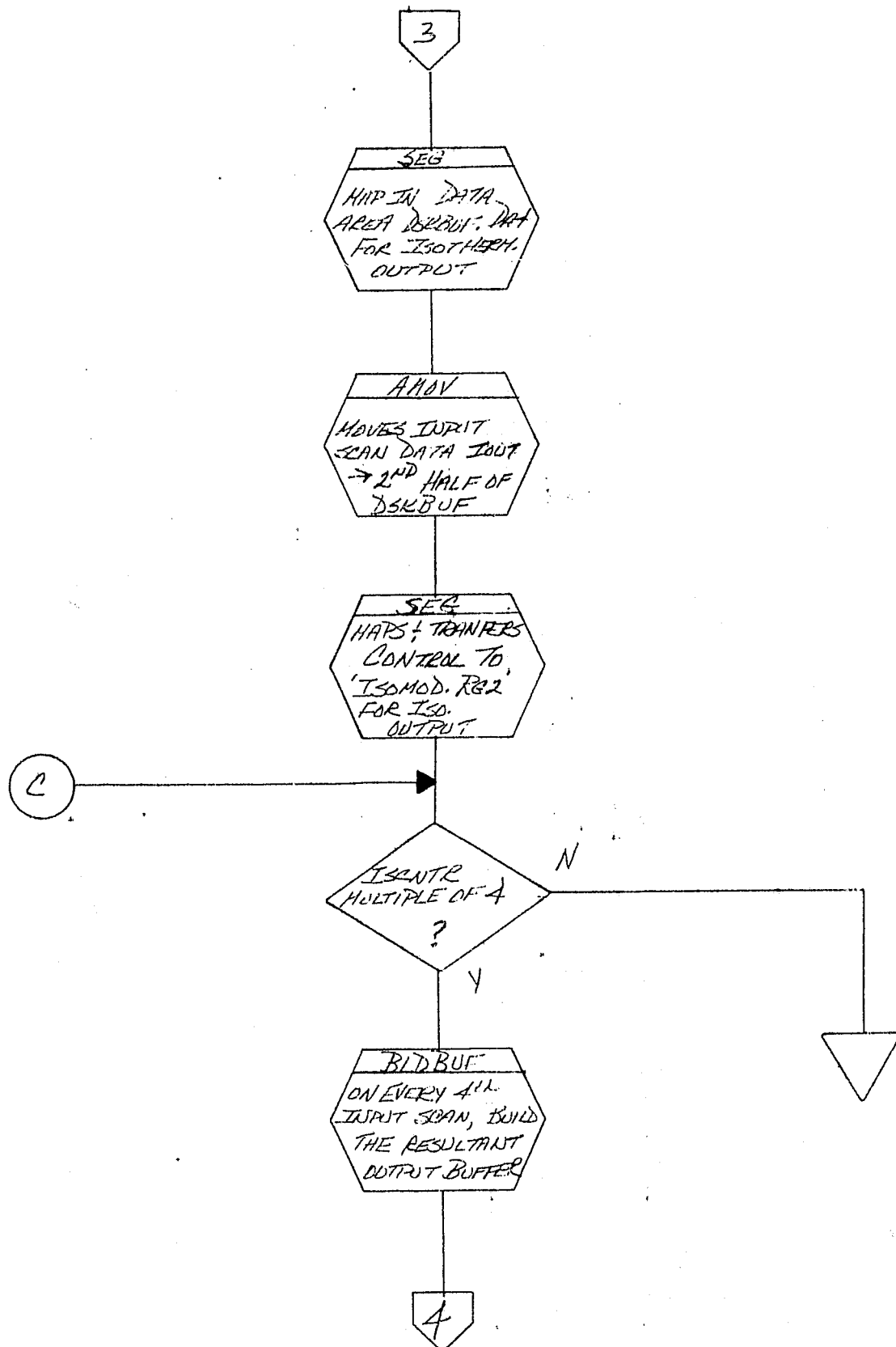


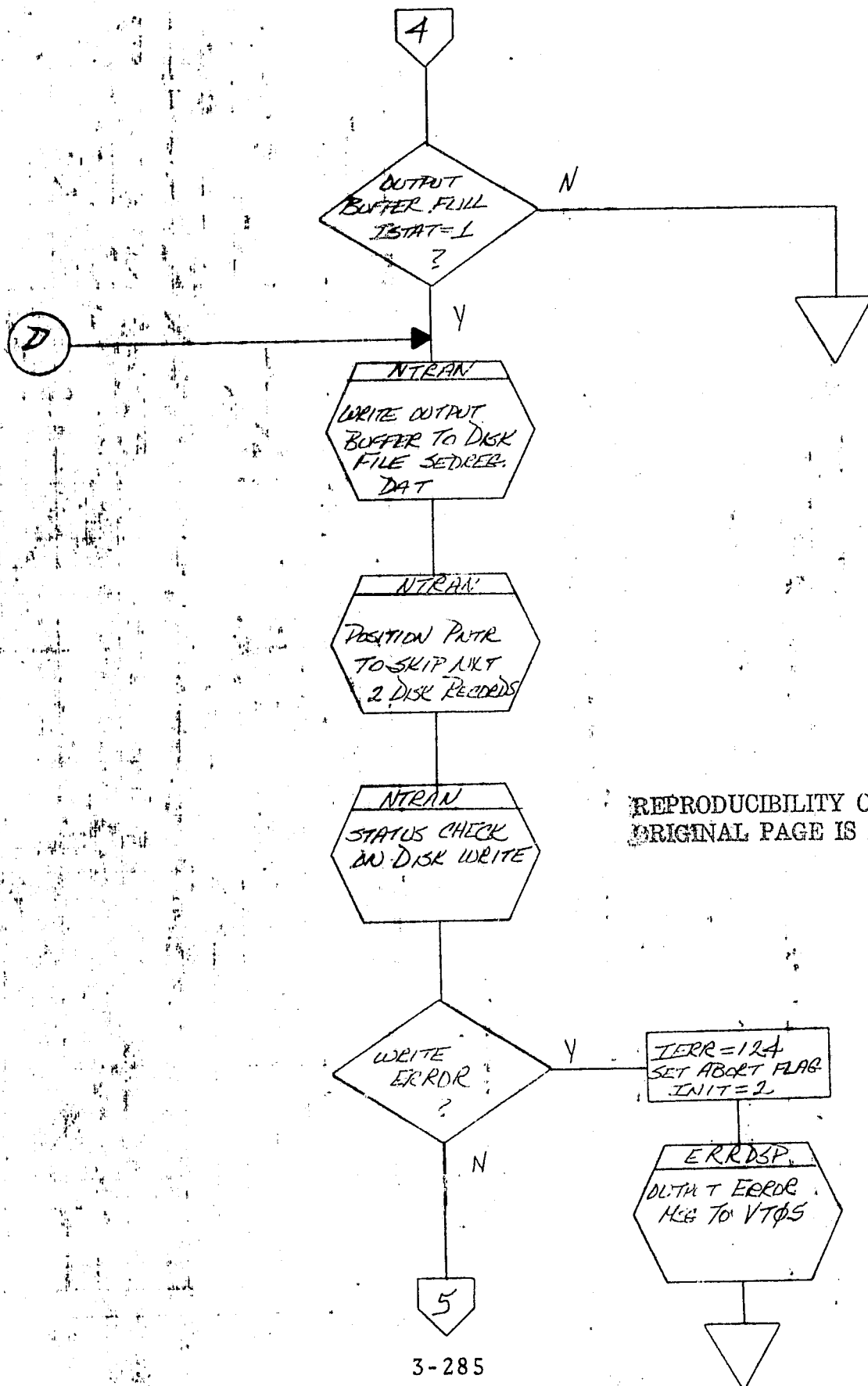


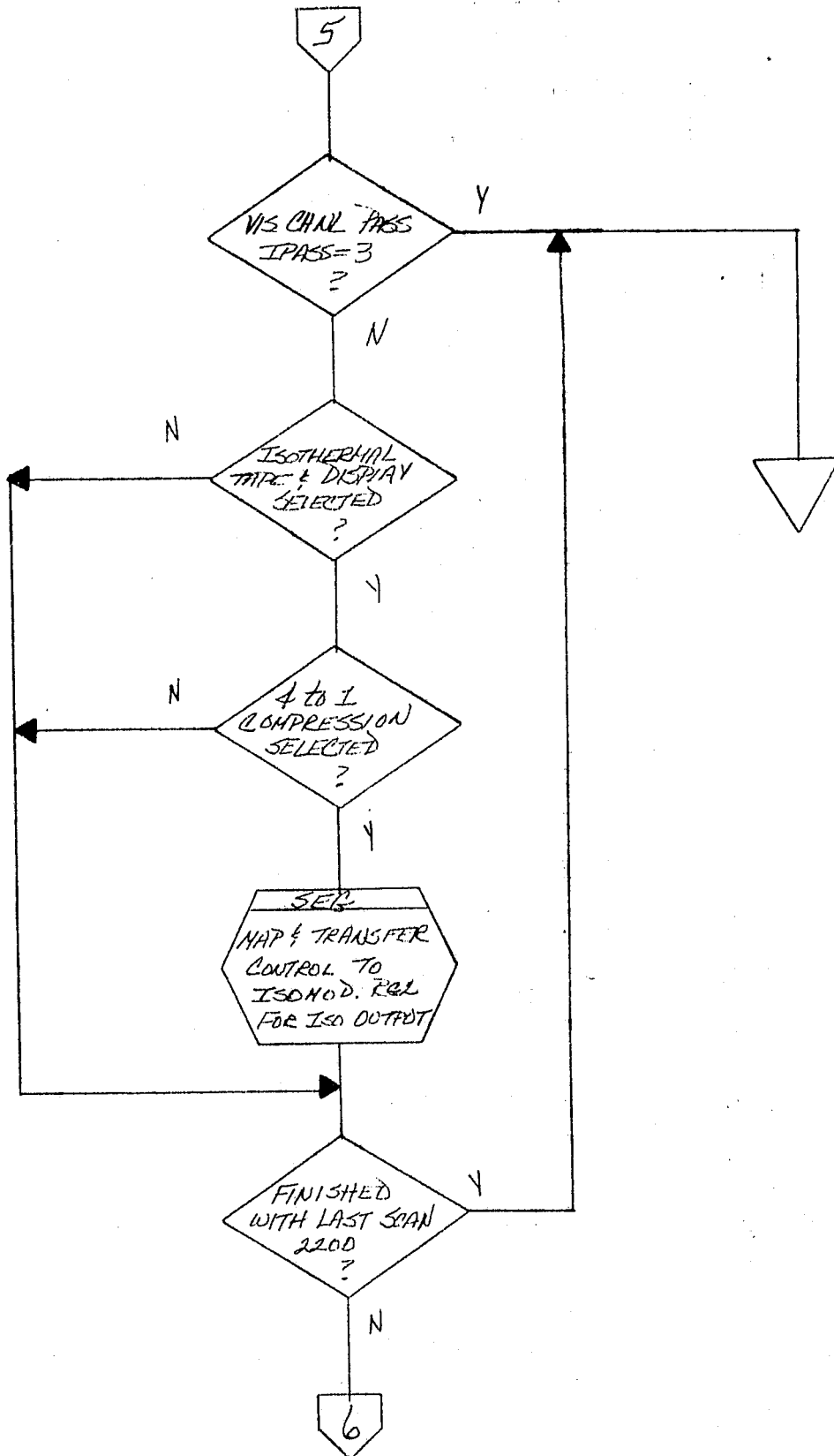


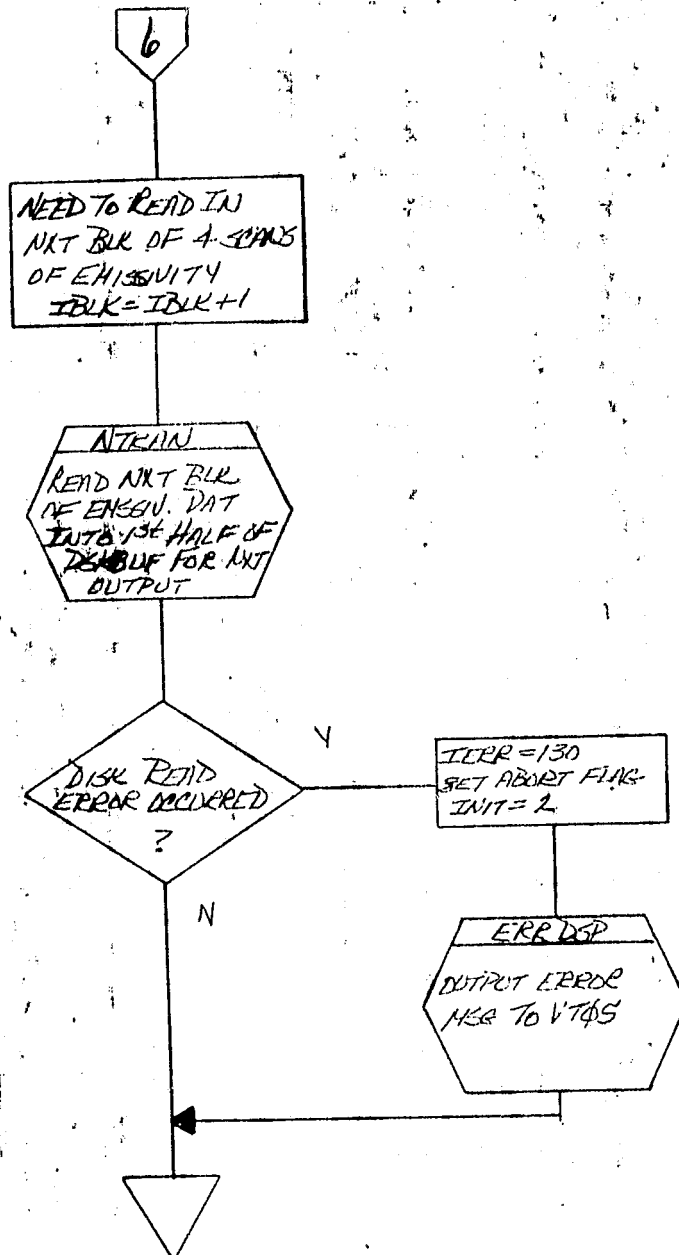
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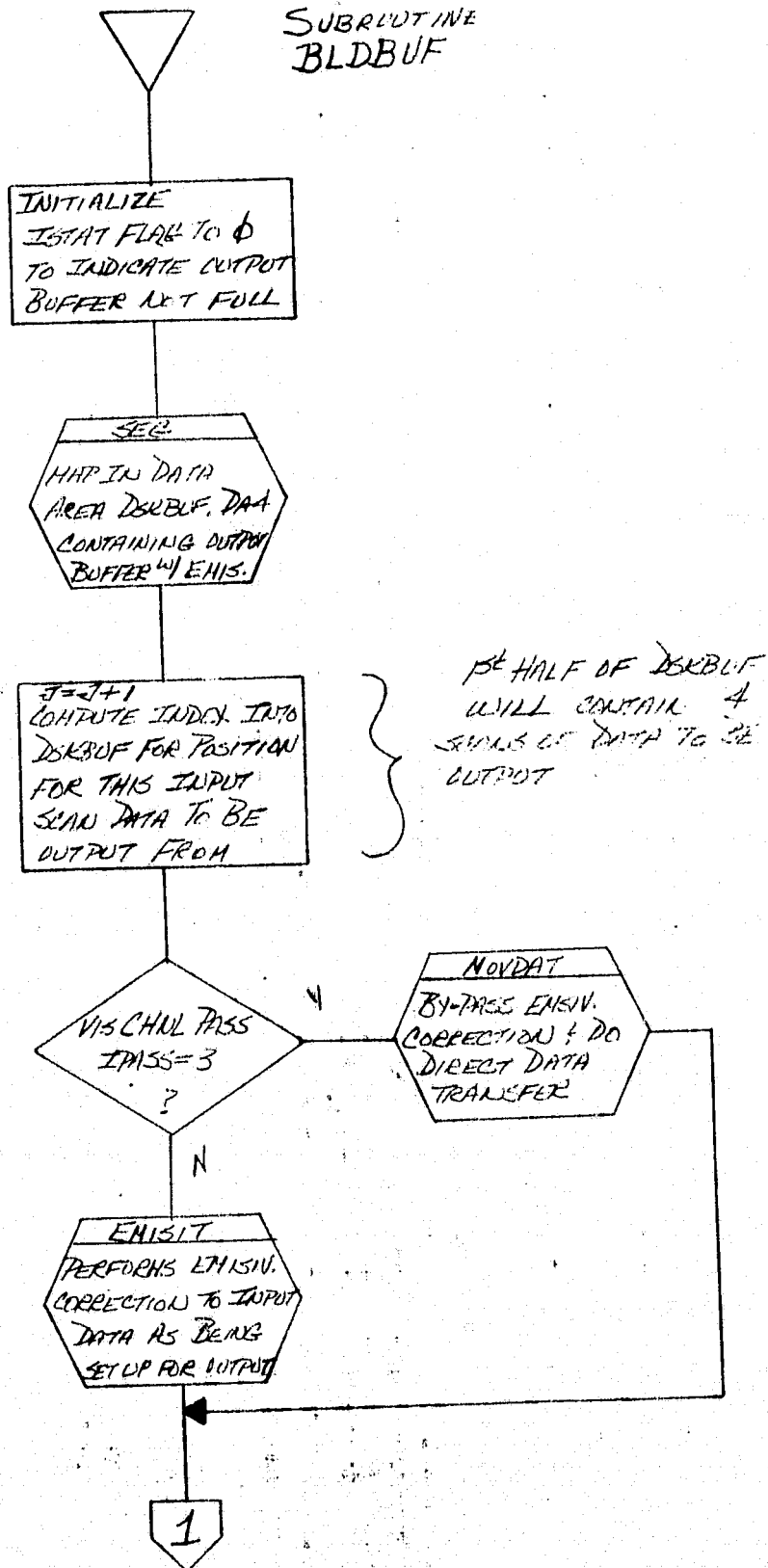


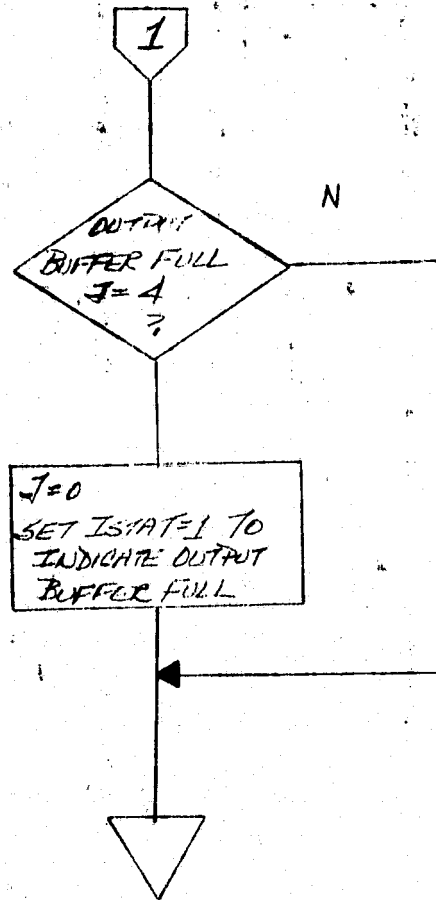


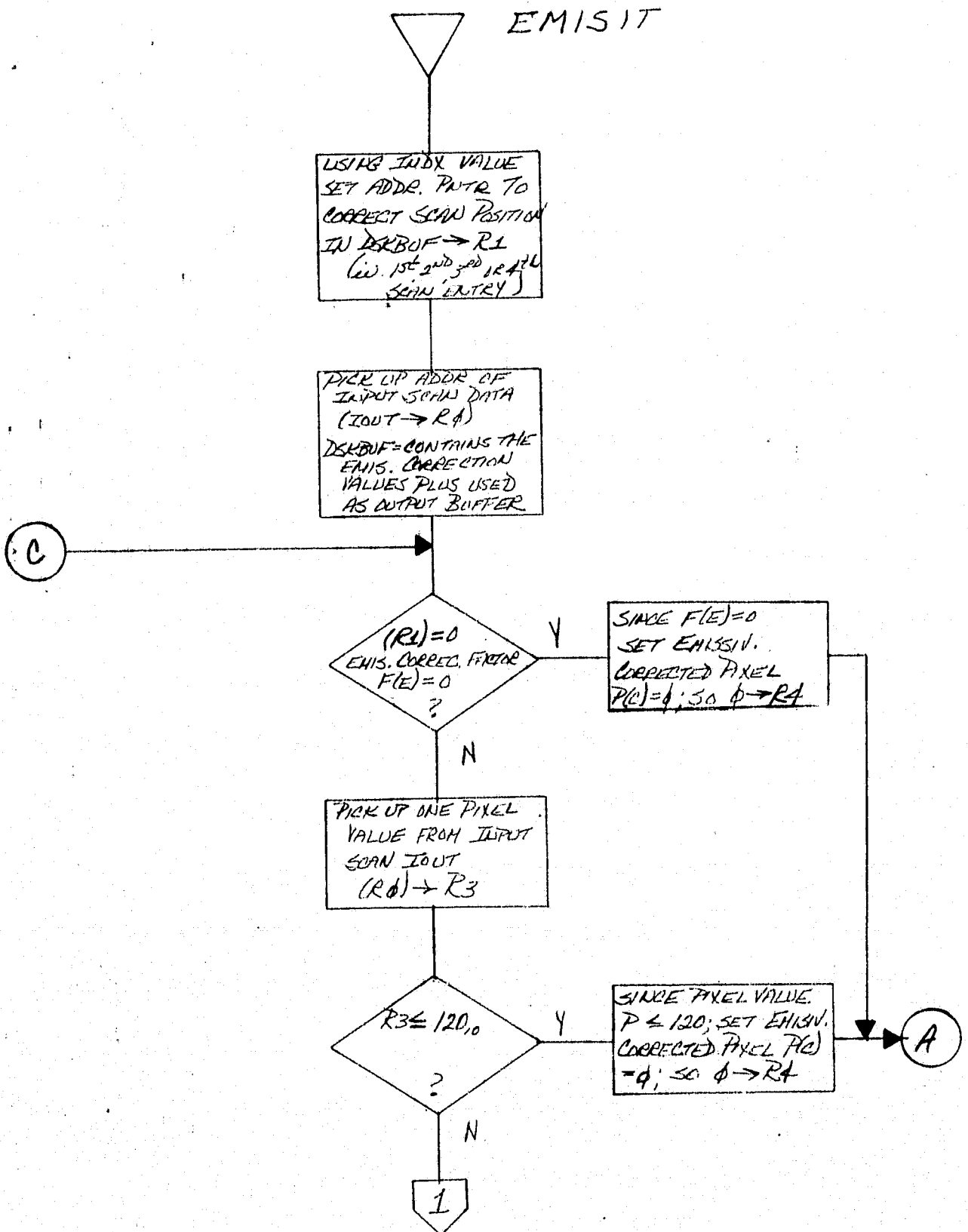


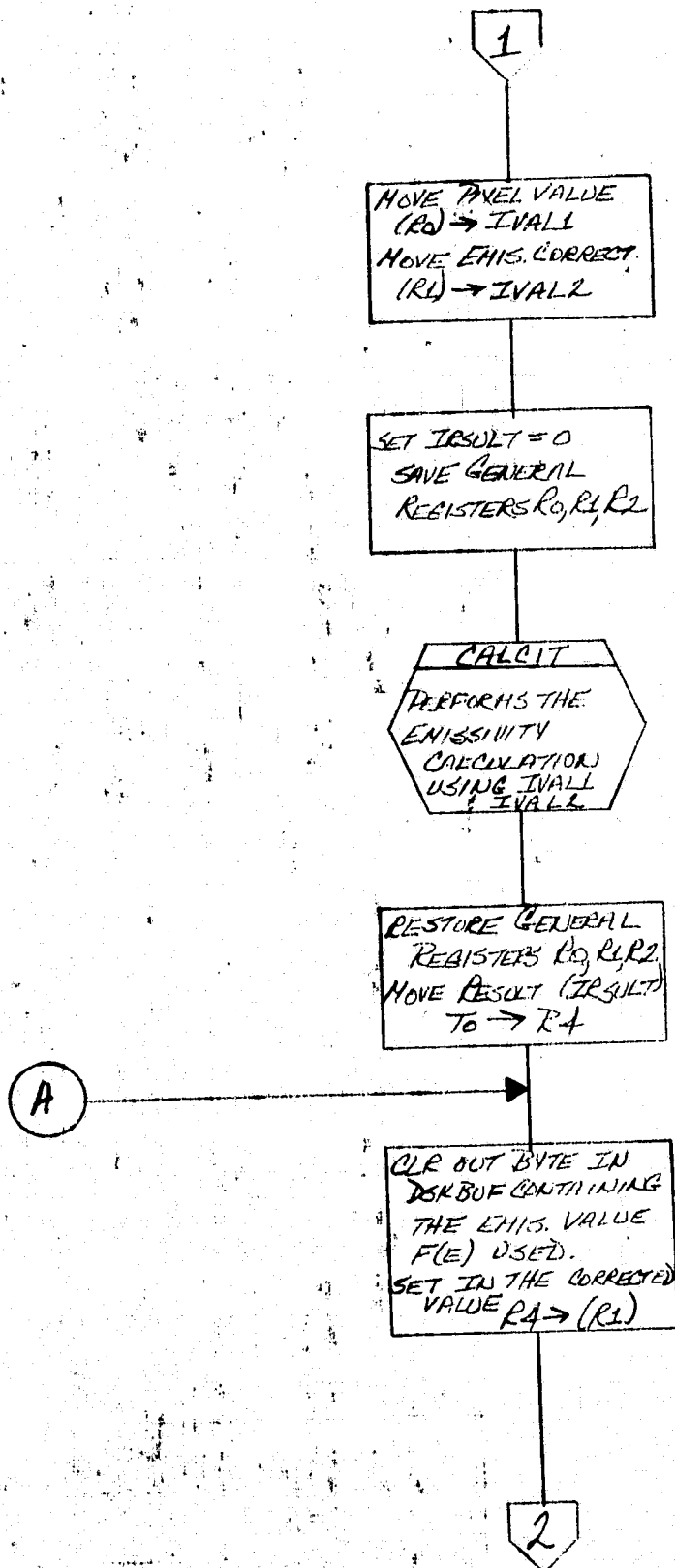


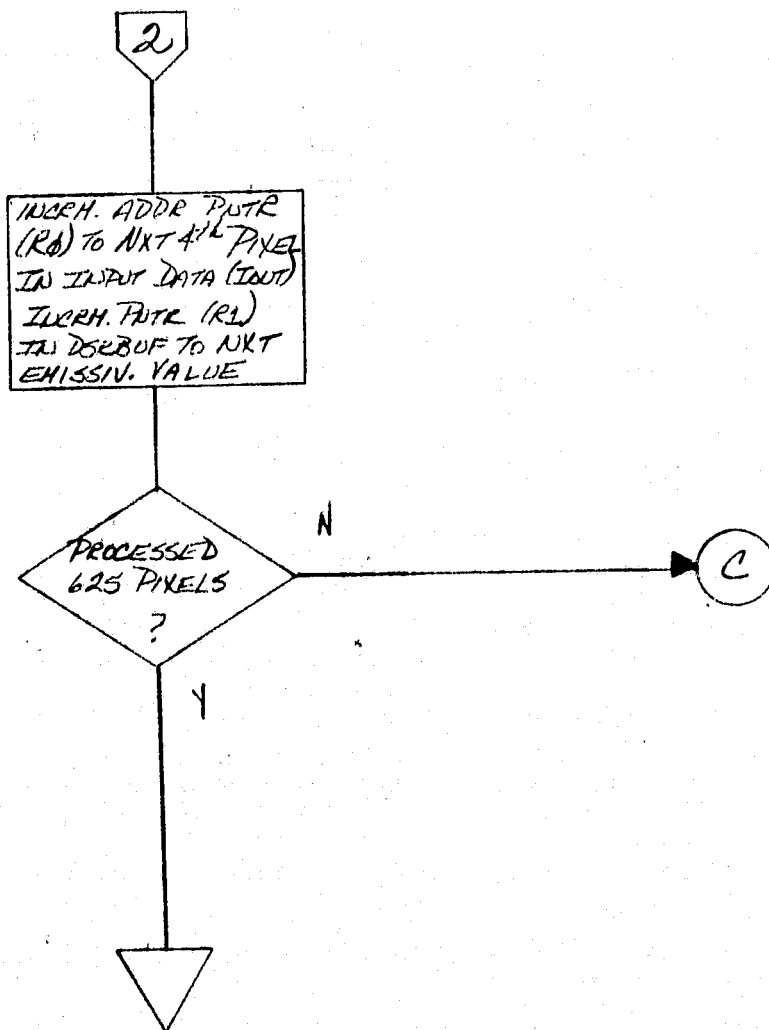




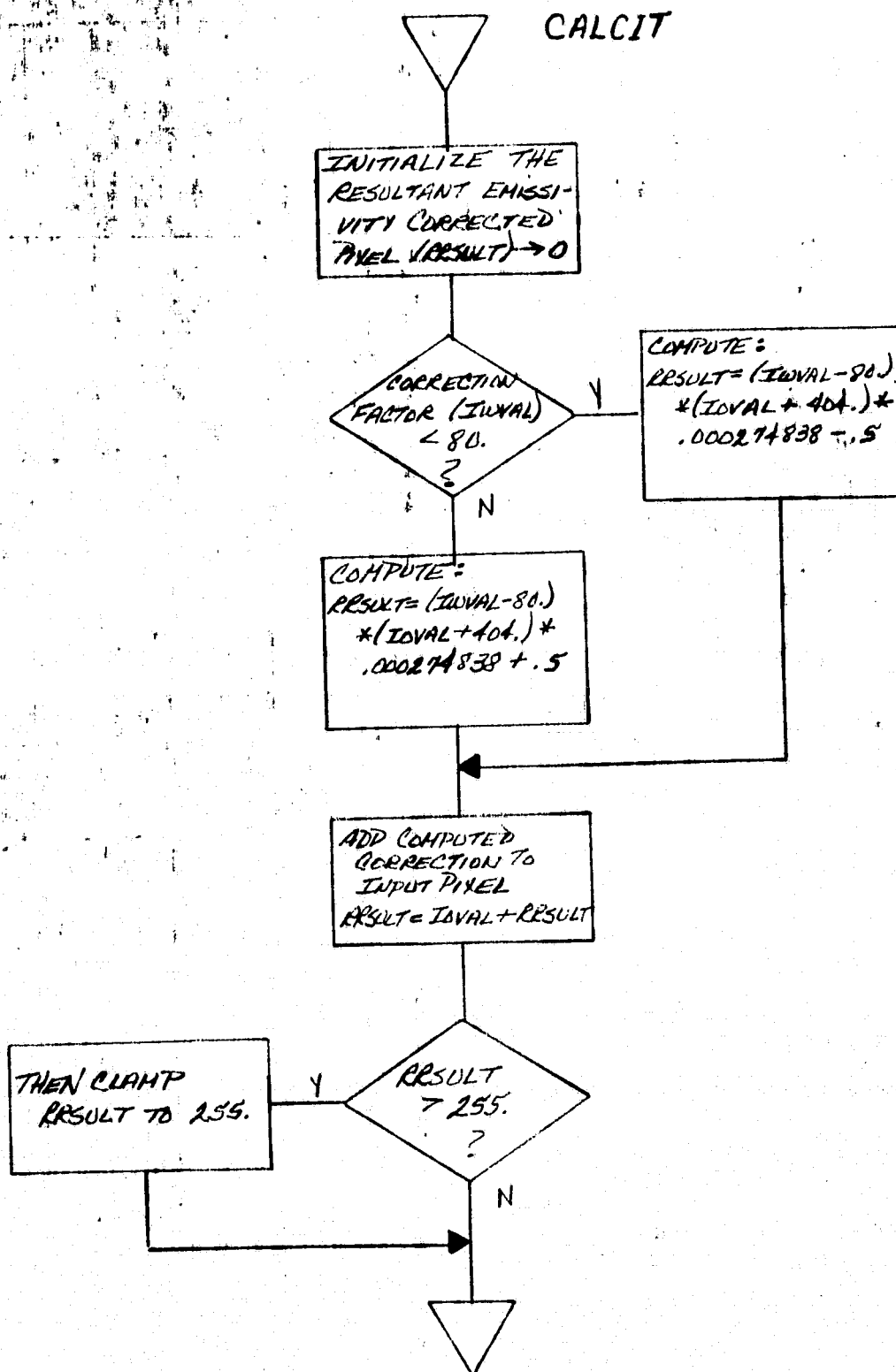


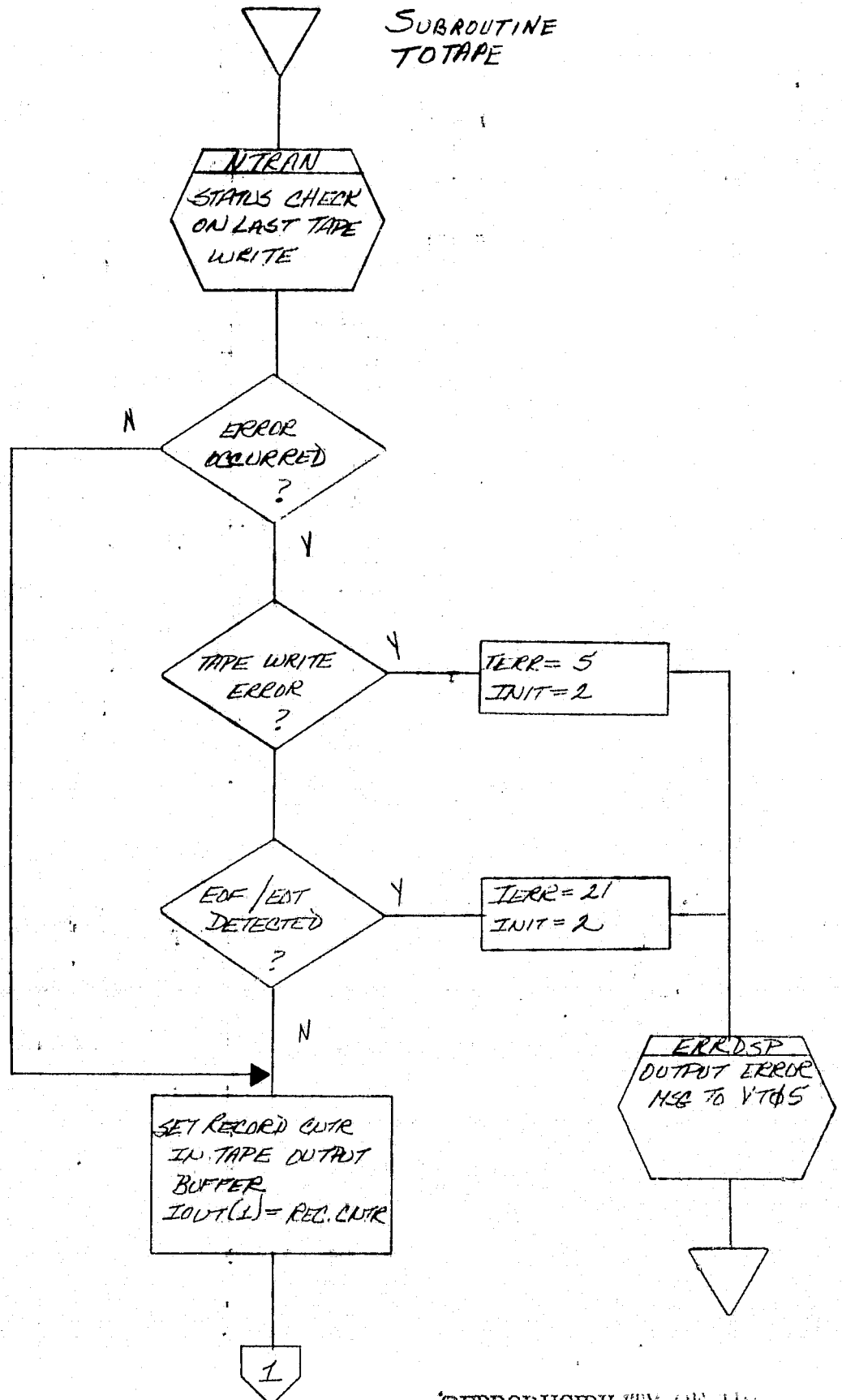


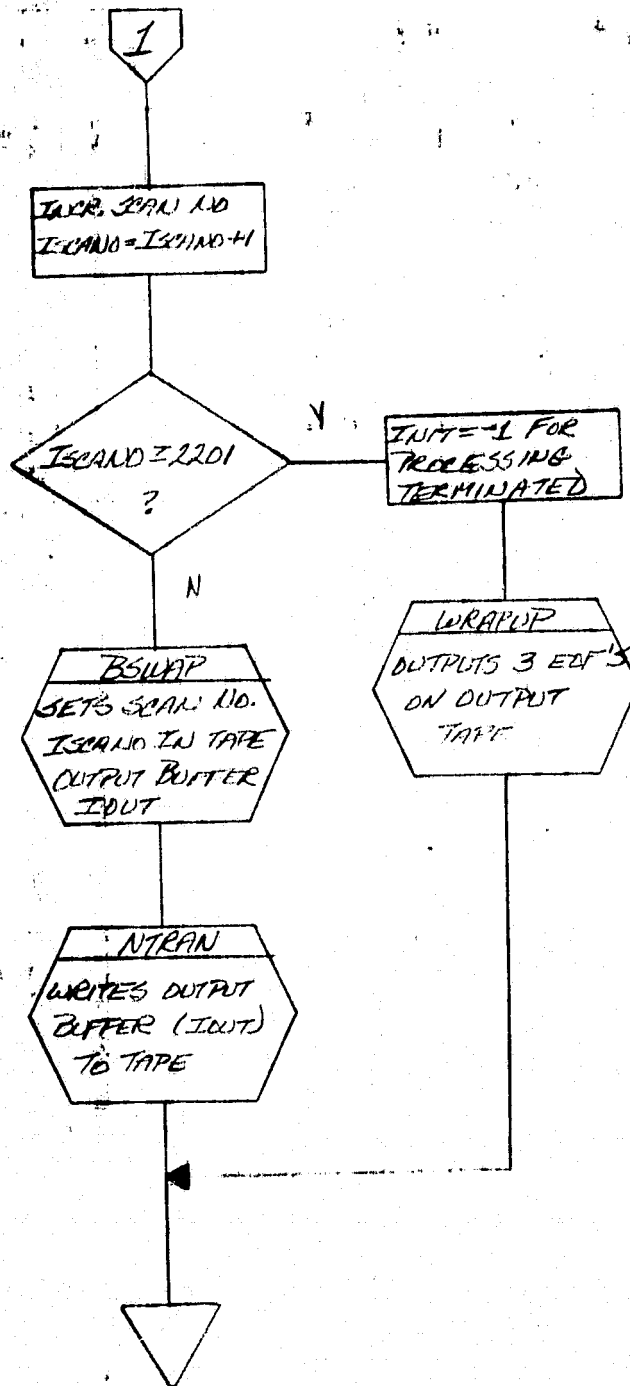


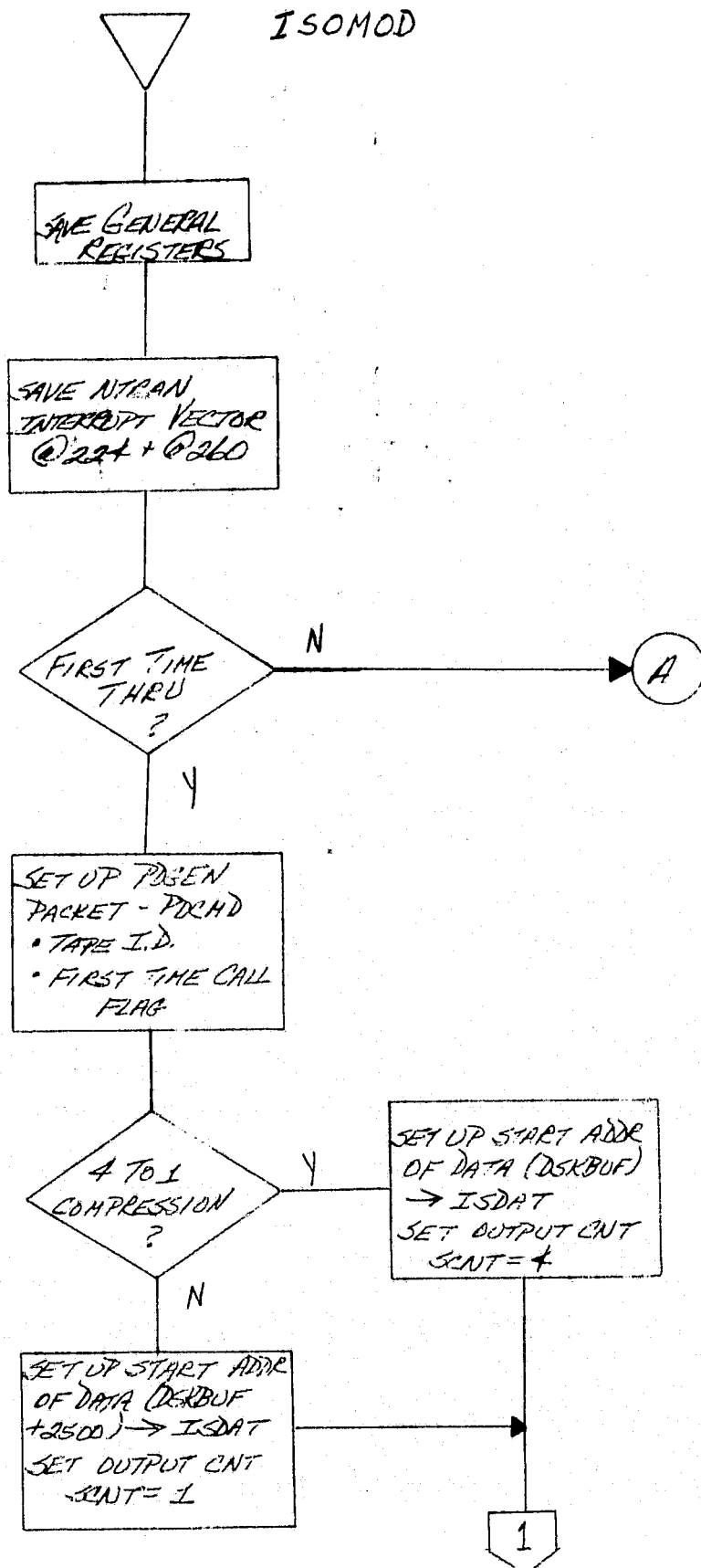


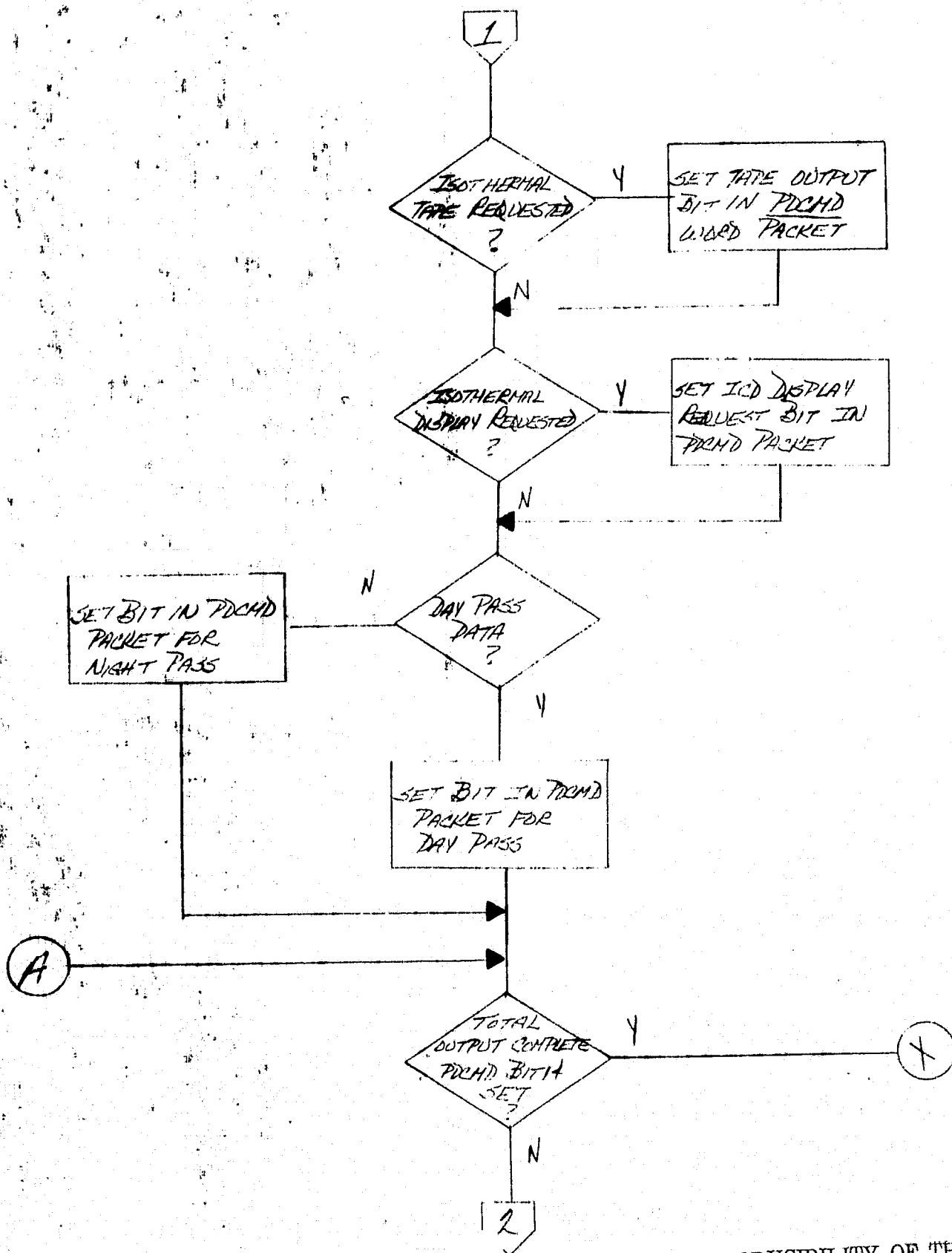
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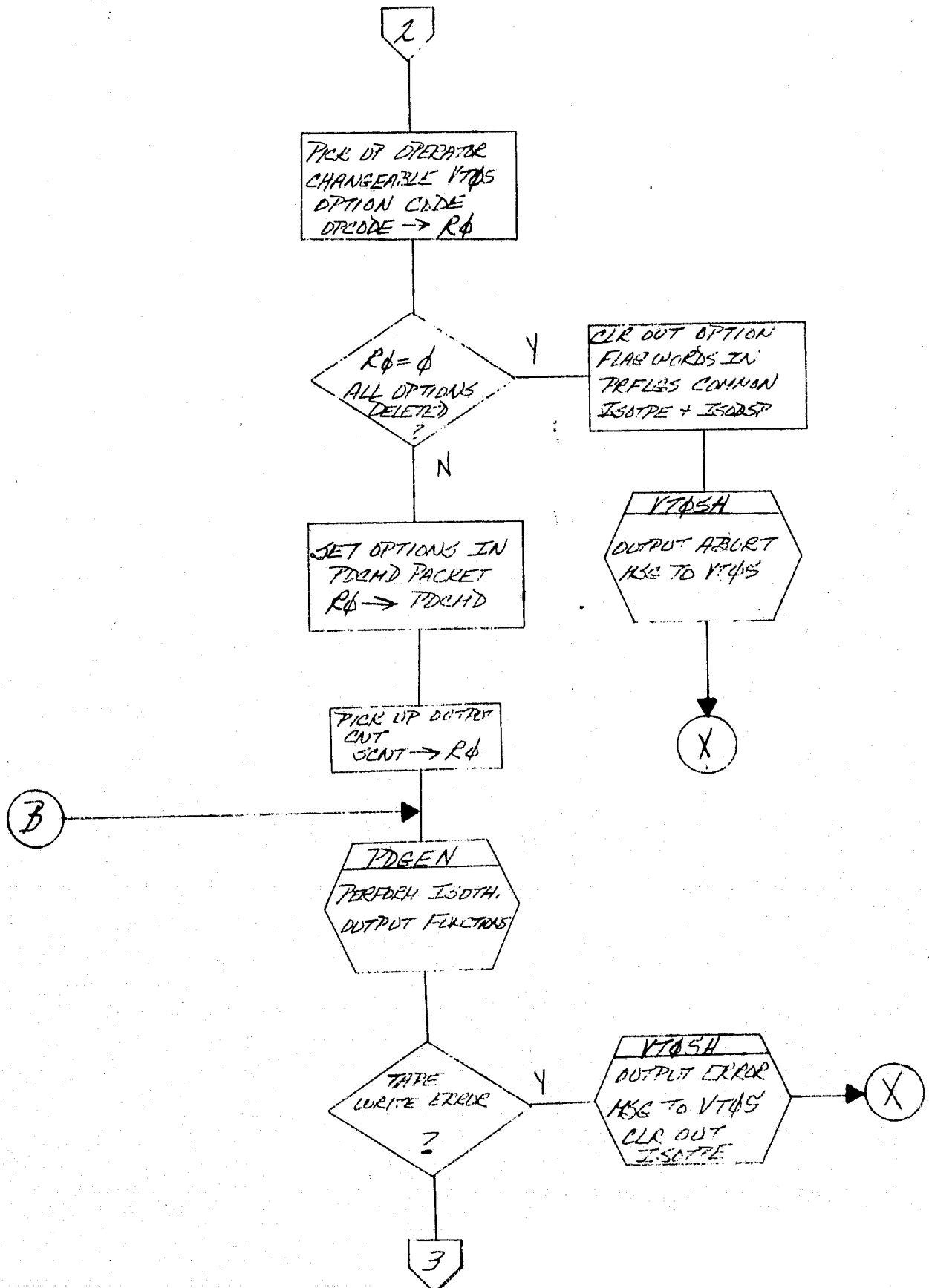


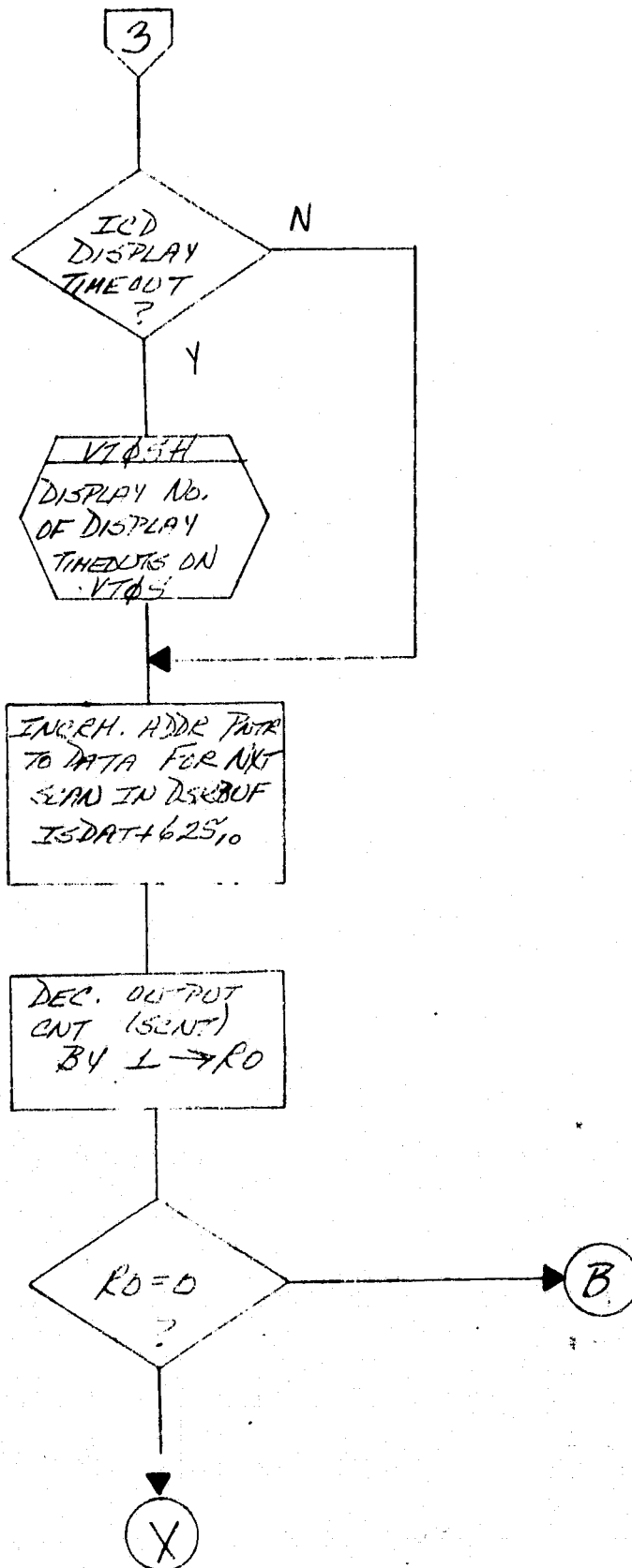


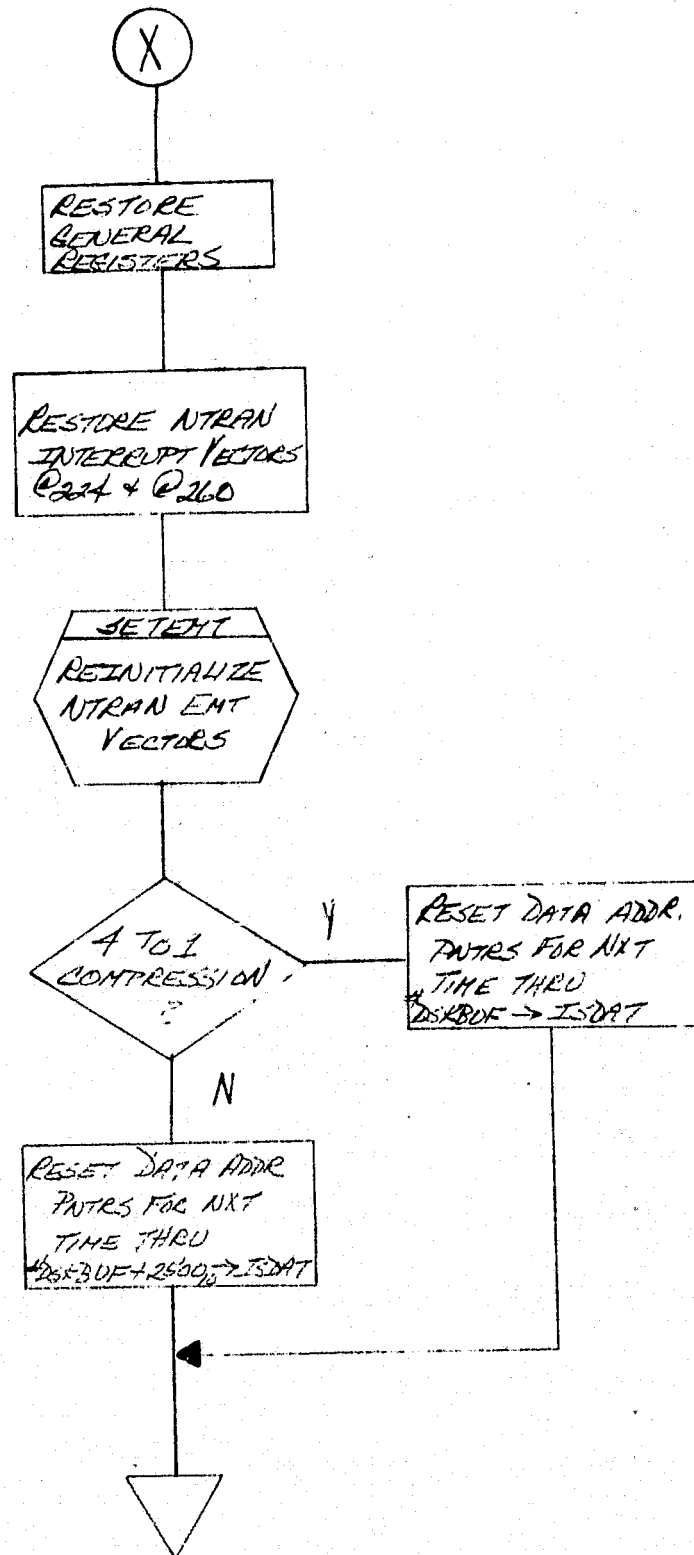












3.2.3.3 Interfaces

A. Input Data. Following is the input data to REG which is external to the CPC.

1. The input image tape to be registered is the primary input, and is one of two tapes:
 - EU processed tape (SED)
 - Night coarse rotated tape (CRT).
2. The input tape header record is read in to use in building the output header for the registration products by REGHED.
3. The COMMON/GCOEFF/ is a resident common containing GCP information and mapping coefficients to be used by SREG in the image registration. See paragraph 3.1.5 for a description of this common.
4. COMMON/TAPEID/ is a resident common with the operator-entered tape ID's for the output products (see paragraph 3.1.5). These ID's are placed in the output tape header record.
5. COMMON/PRFLGS/ is a resident common containing processing selection flags indicating what output options were selected via the operator (see paragraph 3.1.5).

B. Output Data. The output data of REG is as follows:

1. The primary output of REG is the registered disk file, containing registered data for the day IR and VIS channels and the night IR channel for a particular day's run (two passes). Figure 3-36 is a graphic portrayal of the disk file illustrating its format.
2. REG outputs a registered IR tape containing the IR full-scale registered data scans. See figure 3-37 for the format of the IR registered data.
3. REG outputs an isothermal tape containing the isothermal registered scan data either in full-scale or compressed 4:1.

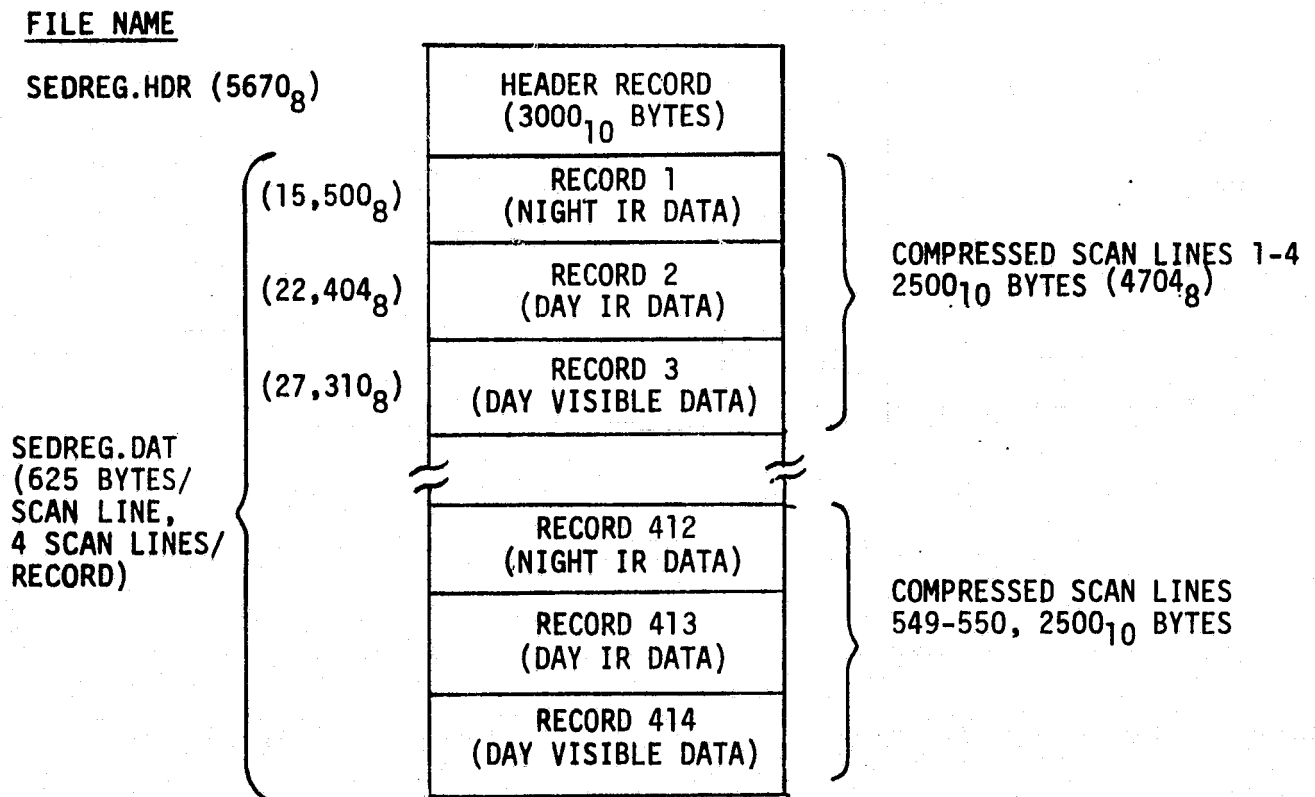
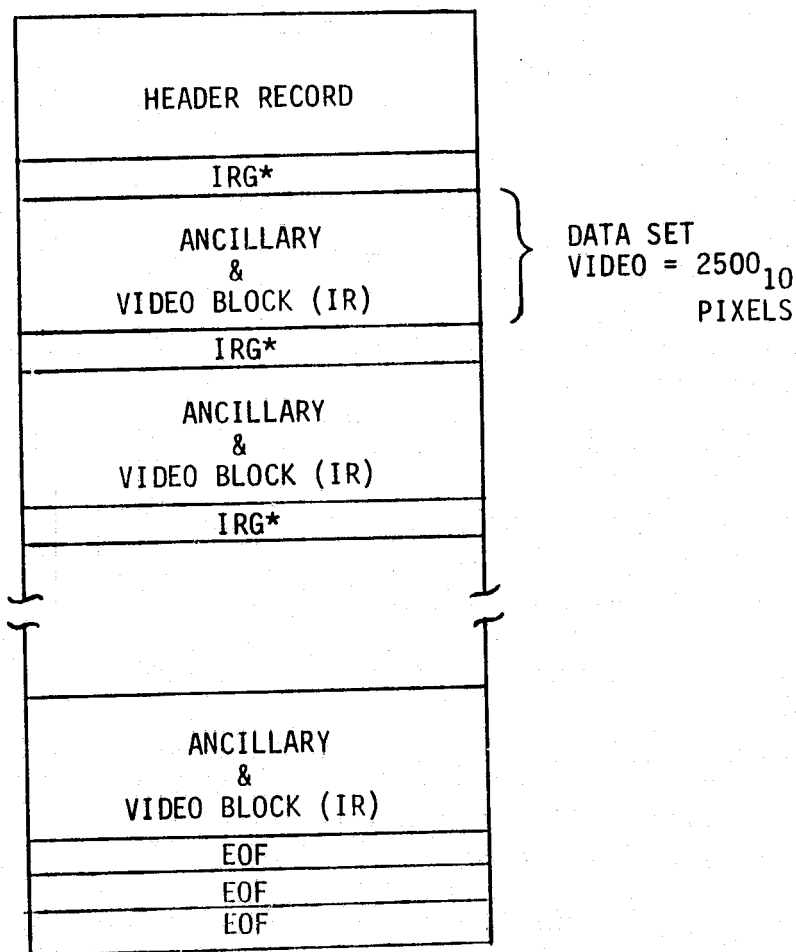


Figure 3-36 Registered Disk File



*IRG = INTER RECORD GAP

Figure 3-37 SEDS Registered 9-Track CCT Format

- C. Call Sequence. REG is called from the SEDS resident module after the SRE CPC and, if applicable, the ROT CPC, have executed. REG is called by SEDS once during the run of the entire Registration Program.

3.2.3.4 Data Organization. REG contains various types of data in the form of data modules, commons unique to REG for use in transferring data between routines and subroutines, and resident commons unique to REG but residing in resident to enable the transfer of data between the load modules of REG. Also included are internally defined variables in the various routines of REG.

- A. Data Modules. These are 4K data block areas allocated and mapped into core via SEG. Any load module can map in any of these data modules, thereby allowing them to use data from another 32K virtual memory mapping (i.e., load module LDA). In REG, there are the following data modules.

1. INBUFF. This is a 2700₁₀ integer word data buffer residing in a 4K area of the virtual core map. It is set up as a double buffer in which the input tape scan data or ancillary data is read into by READIN one scan at a time. The double buffering enables the program to read in another scan while processing is performed on the first one.
2. DSKBUF. This is a two-part data module in which the registered data is moved for output of disk and isothermal products. It contains the registered data in both full-scale and 4:1 compressed form. For output to disk, four compressed scan lines are gathered by the TODISK Routine. The full-scale scan is transferred to TDSKBUF by TODISK if the isothermal outputs are requested. See figure 3-34 for the format of DSKBUF.
3. ROTBUF. This rotation buffer consists of the array ICHAN, which is dimensioned (1350,3), using 4050 words of a 4K block. The 4K block with the array ICHAN is repeated 18 times in physical core, for a total buffering capacity of 54 scan lines. Flags and pointers regulating data movement through the rotation buffer are contained in COMMON/REGWRK and are as follows.

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- a. NSETS. This is the number of scans needed in the rotation buffer to resection one output line. After NSETS lines have been stored in the rotation buffer, the program begins outputting lines, one line out for each line in. The NSETS + 1 line to be written in the rotation buffer is written where line 1 was previously, thus making the buffer rotate.
- b. IBEGIN. This flag is set to 1 in SCNFIL or SREG when NSETS lines have been stored in the rotation buffer, to indicate that output can begin because the rotation buffer is full enough.
- c. M1. This is the scan line pointer with a range of 1 to NSETS, where $NSETS \leq 54$.
- d. M2. This is the data area pointer, with a range of 1-18.
- e. M3. This is a pointer to the scan line within data area M2. It has a range of 1-13.
- f. MISTOR. This is the previous value of M1, used on input to the rotation buffer.

When inputting a line to the rotation buffer, the value M1, M2, and M3 are set in SREG (or SCNFIL). The actual data movement is done in TSHIFT as discussed earlier. M1 increments from 1 to NSETS, then is reset to 1 and increments again. M1 points to which one of the NSETS lines is being input. $M2 = M1/3$ if 3 divides M1, and $M2 = \text{int}(M1/3) + 1$ if 3 does not divide M1. $M3 = \text{MOD}(M1, 3)$. M2 is used by SEG to map in the correct data area. Then M3 finds the correct one of the three scan lines in that data area. When outputting a resectioned line, the subroutine RTATON uses pointers N1, N2, and N3 in a manner similar to that in which M1, M2, and M3 are used on input. M1, M2, and M3 are in COMMON/REGWRK/ and are available to RTATON. Suppose that line M1 has just been stored in the rotation buffer. M1 is stored in MISTOR. Now suppose RTATON has been called to output a resectioned line. The resectioned line will have

some PIXEL's from each of the NSETS lines in the rotation buffer. The line that was just put in, line MISTOR, will be used first. N1 is set to MISTOR, $N2 = N1/3$ if 3 divides N1, and $N2 = \text{int}(N1/3) + 1$ if 3 does not divide N1. $N3 = \text{MOD}(N1, 3)$.

area N2 according to PXTBLE. N1 is decremented, and the process is repeated until the output scan is completed.

B. Buffers and Commons Unique to REG

1. HEDBUF (INDAT). This is 1530₁₀-word integer buffer used to build and output the registered disk header file by the REGHED load module.
2. CHBUFF (IDAT). This is a 1350₁₀-word integer buffer. Input scan data is moved to this internal buffer by READIN to be processed by SREG.
3. COMMON/STATUS/. If the flag I1STAT = 0, ancillary and the first data channel is read in by READIN. If I1STAT = 1, the second data channel is read in. If the flag I2STAT = 0, normal processing is performed. If I2STAT = 1, an EOF/EOT has been encountered and processing is stopped. These flags are set by READIN and checked by SREG to control the sequence of processing.
4. COMMON/FIXCOM/. This common contains the following.
 - a. SCNTME. A four-word entry for the time of the current input scan.
 - b. ISCAN. A one-word entry for the current input scan number.
 - c. IRECNO. A one-word entry for the current record number of this data set (as input).
 - d. TMESAV. A four-word entry for the time of the previous scan.

- e. ISCSAV. A one-word entry of the scan number of the previous scan.
 - f. IRCSAV. A one-word entry of the record number of the previous record.
5. OUTBUF. This is a 1350₁₀ integer word buffer used as the output buffer for the registered data scan. It contains:
- IRCRD - a one-word entry record counter
 - IANCIL - a 50-word ancillary block
 - ICHOUT - a 1299-word data block.

The resectioned data scan is built from ROTBUF to OUTBUF, one scan at a time.

6. TBLEPX. This 54-word integer table contains entries for each line in the rotation buffer specifying the number of PIXEL's to extract from each scan in the rotation buffer to build one output resectioned scan. This table is initially set up by the FORTRAN subroutine PXTBLE.
7. COMMON/REGWRK/. This common contains information set up and used by SREG in the data manipulation from ROTBUF (discussed previously), and data words used elsewhere in the registration process. These are as follows.
- a. NSETS. The computed number of scans needed to store in the rotation buffer (1-54).
 - b. M1. The scan line pointer in ROTBUF (1-54).
 - c. M2. A 4K data area pointer (1-18) used by SEG to map in the appropriate 4K data area (ROTBUF) from physical core to the virtual 32K core map.

- d. M3. A pointer to the scan line within data area M2 (1-13).
 - e. SD, ISD. The computed scan to be processed.
 - f. YSCAN. The scan line in the reference grid of the next scan line to generate for output.
 - g. ED, IED. The starting PIXEL value of scan SD to place in the rotation buffer.
 - h. MISTOR. This contains the scan number of the last scan that was scaled and translated and is used by RTATON subroutine.
 - i. ISNCOR. The corrected scan number.
 - j. IBEGIN. A flag indicating that resectioning is to begin because the rotation buffer is full.
 - k. CMPRS. A compression factor in the downtrack direction (computed by SREG) used on input of data to the rotation buffer.
 - l. EXPAND. A expansion factor to restore the image to 2200 lines, used on output from the rotation buffer.
 - m. ICOUNT, NCOUNT. These counters are used by SREG for the compression loop.
 - n. TCOUNT, NN. These counters are used by SREG for the expansion loop.
8. EMSSIV.DAT. This is a disk file (550 scans by 625 PIXEL's) containing emissivity correction factors to be applied to a formula for each PIXEL of the compressed registered IR data image. The disk file resides under UIC 200,200 on the DK1 background image disk. TODISK reads the data in from the file for EMISIT to use in performing the correction of the IR registered data.

3.2.3.5 Limitations. The registration module, due to core availability, is limited to a 54-scan line capacity in the rotation buffer ROTBUF. Depending on the amount of rotation required, it is sometimes necessary to compress the data going into the rotation buffer, and then expand it on output. This results in some loss of data resolution.

3.2.3.6 Listings. See Part IV of this document, published under separate cover.

SECTION 4

RAINFALL ALGORITHM PROGRAM (RAP)

4.1 PROGRAM CHARACTERISTICS

The Rainfall Algorithm Program (RAP, or Data Base Update Sequence No. 1) is used to perform daily rainfall estimation calculations and daily mean air temperature (DMAT) calculations to build a data base update (delete) tape, to build an imagery tape containing six images suitable for filming, and to output to the line printer pertinent information pertaining to Mexican and U.S. meteorological (MET) weather stations. The input sources to RAP are as follows:

- A disk file containing three channels of registered satellite data
- A crop moisture index (CMI) tape of Mexico
- Input cards of MET station data
- Disk files containing background and ground truth temperature information
- An old data base update (delete) tape from N days ago, where N is the length of the data base maintained in SSP (Data Base Sequence No. 2).

The data base update tape generated by RAP with each day's processing serves as one of the input tapes to SSP. This tape contains four channels of old and new CMI and DMAT information; its format will be detailed elsewhere in this document. The imagery tape output by RAP contains six images and is defined in paragraph 5.2.3.3 and by figure 5-24.

RAP consists of five major components or modules. The first module, DBUINT, performs initialization and user control of card inputs. The second module, RAP (not to be confused with the

overall program name), has additional user control through the VT05. It serves as the controlling module for input/output functions during processing, as well as the sequencing and scheduling of the remaining three modules of the overall RAP Program, which are U9TRD, RFTGEN, and METPRT. Due to the large amount of instruction and buffer space required to accomplish the many tasks defined in RAP, the use of segmentation and program overlay features were fully utilized. The function of the last three modules are therefore somewhat specialized. U9TRD performs input buffering and tape control of the CMI data; RFTGEN performs product generation of the six images output to the ORC tape; and METPRT performs MET station data save on disk and line printer output. In addition, RFTGEN allows one of the six images output to tape to be monitored via the SEDS display. The basic configuration of RAP is described by figure 4-1.

4.1.1 Functional Allocation. As defined in the functional requirements for SEDS (PHO-TN734), RAP performs the output processing product No. 5: maps of recent rainfall. The first phase of the data base update and maintenance processing is performed. The new data base update tape generated daily by RAP contains CMI and DMAT information necessary for the complete data base computations and archive processing accomplished in SSP. When the data base length is set at a fixed value (N), the new update tape contains four channels. Channels 1 and 2 are current values of CMI and DMAT. Channels 3 and 4 are old values of CMI and DMAT from the old data base update tape of N days ago. The CMI data is not changed by RAP, but is carried forth to be put on the update tapes in appropriate channels. Design and hardware limitations made RAP the convenient place to input the CMI information. The calculations of the SEDS DMAT values are performed exclusively in RAP. All DMAT information is in the form of 8-bit values with a range of 0-255. The 256-place increments represent $1/4$ °K temperature steps. One count = 260.25 °K, and 255 counts = 323.75 °K. The DMAT for each day's processing is color-coded and is processed as OWC product No. 6 in SSP. The DMAT will be determined for each PIXEL from the current day's day IR and night IR data retrieved from the disk files built by the SEDS registration program.

4.1.2 Program Flow Chart. See figure 4-2.

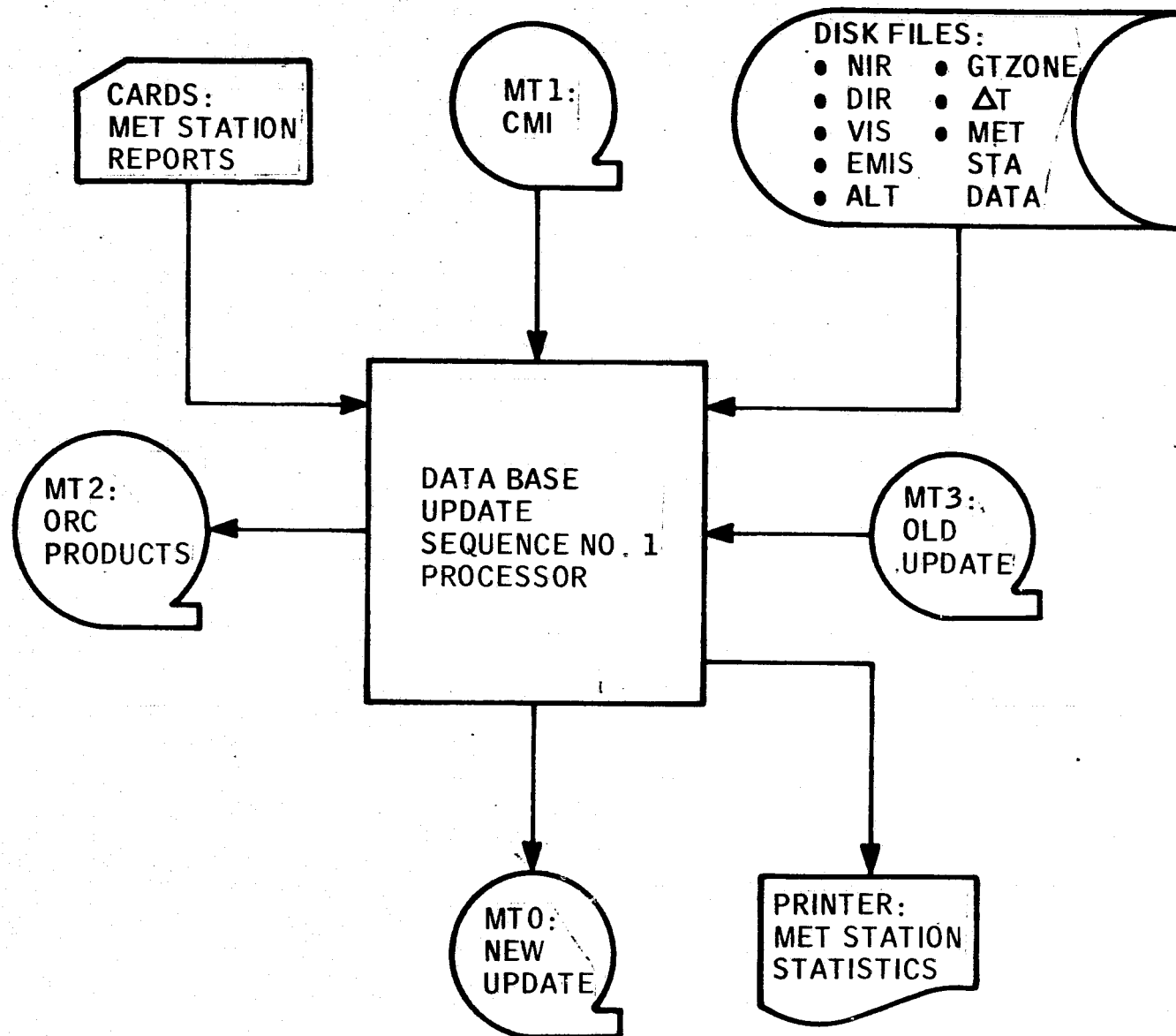


Figure 4-1 RAP Basic Configuration

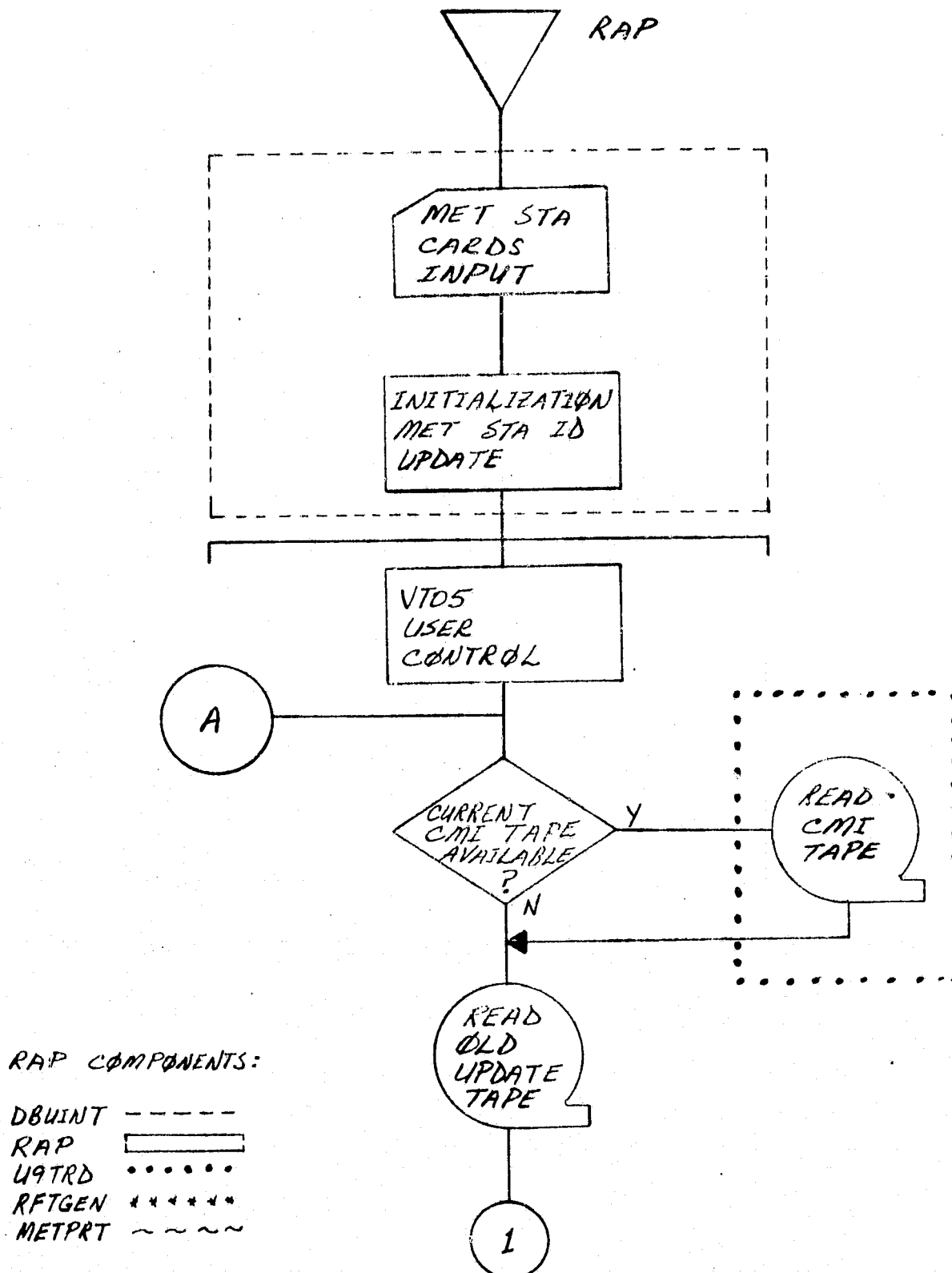


Figure 4-2 RAP Program Flow Chart

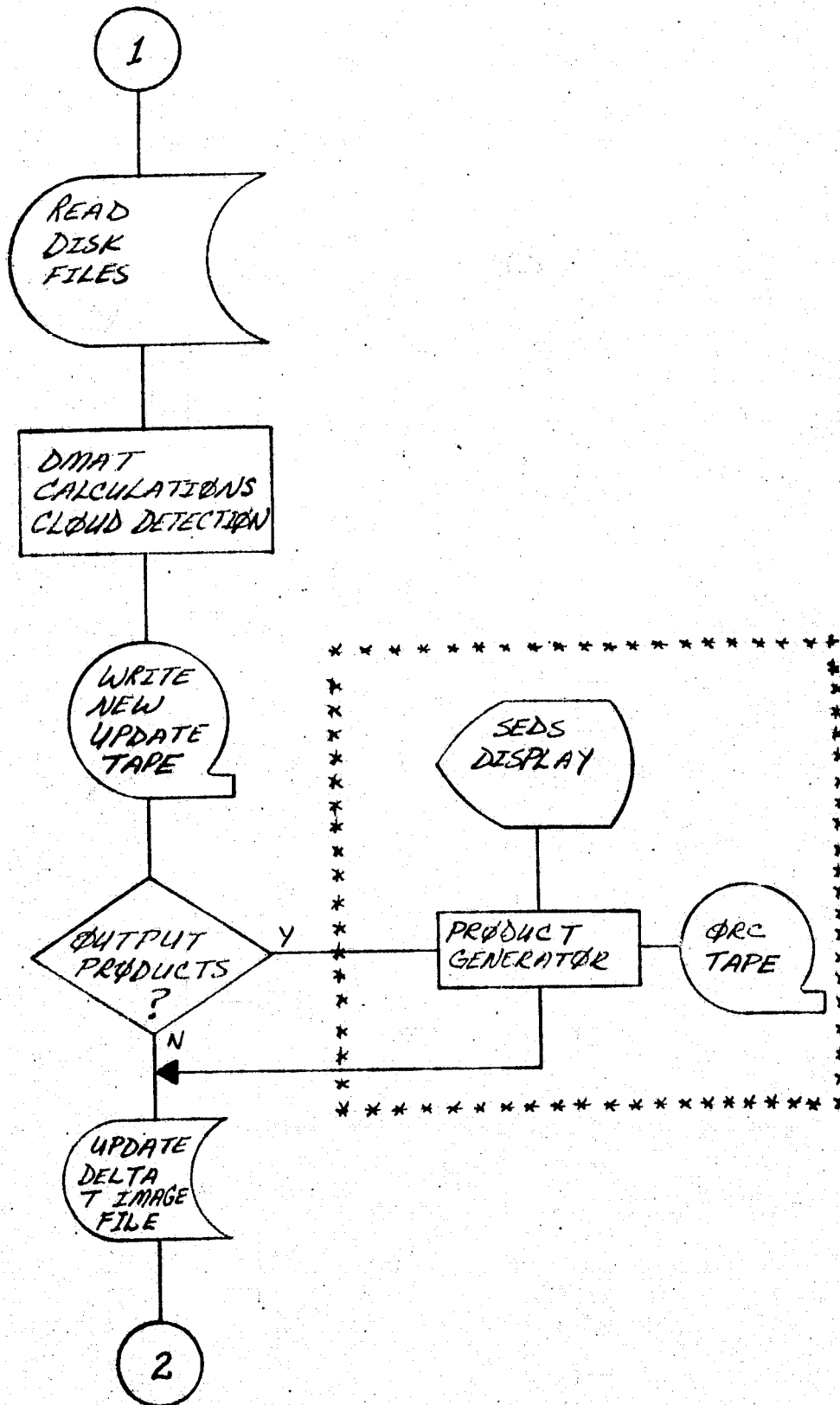


Figure 4-2 (Cont'd)

C.6

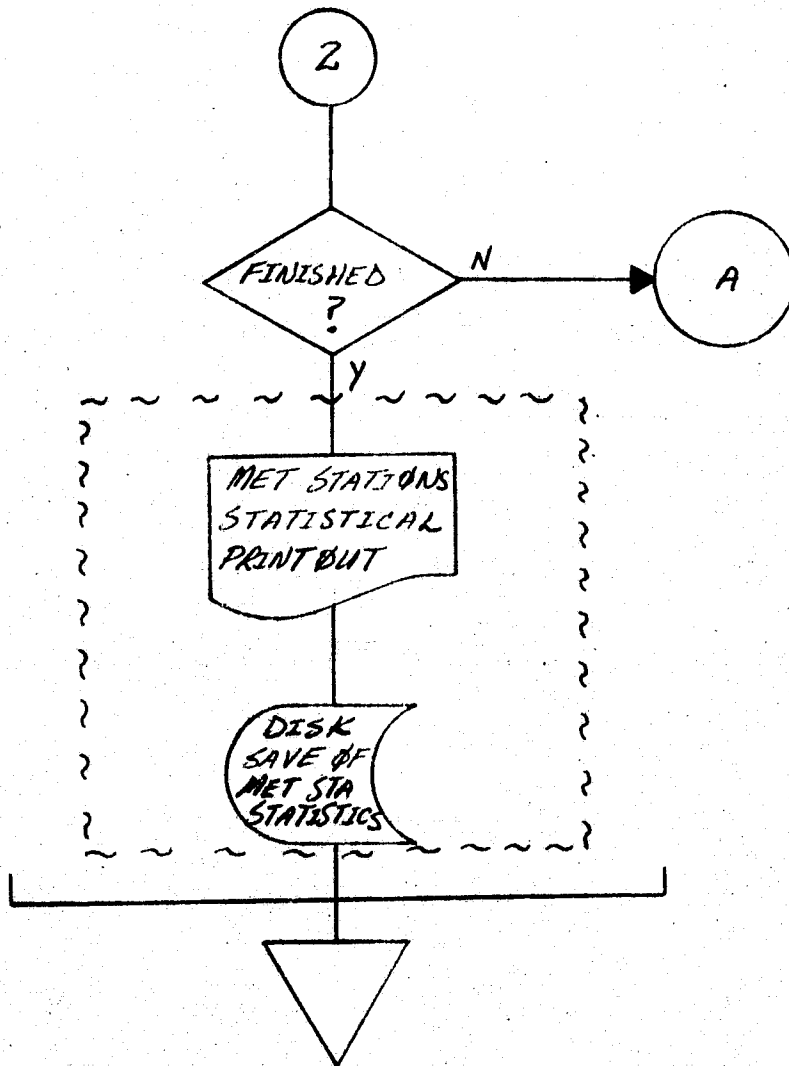


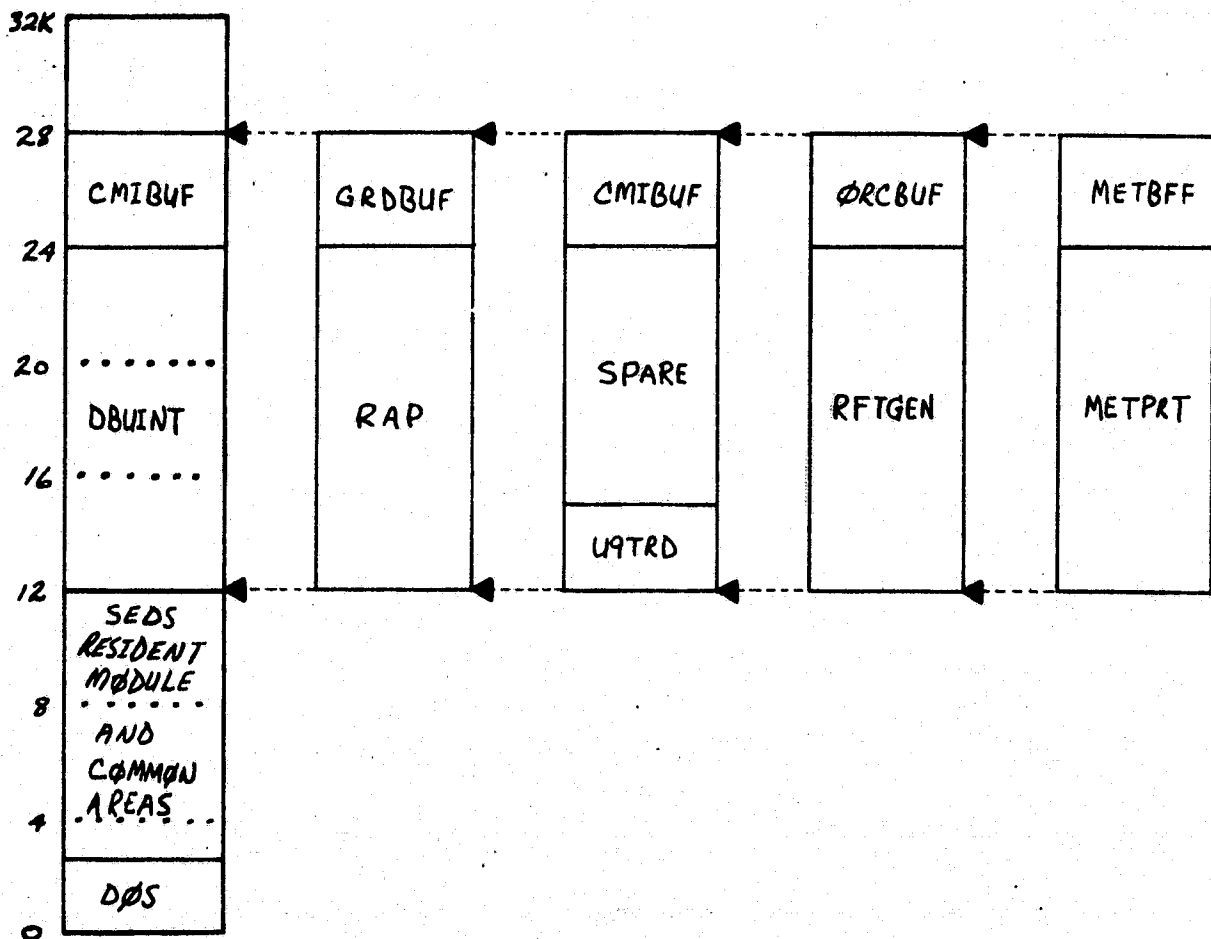
Figure 4-2 (Cont'd)

4.1.3 Timing and Sequencing. RAP is designed to be executed following the registration of both night and day passes. In the normal day's production cycle, the registered data on disk from registration serves as one of the inputs to RAP. Following SEDS initialization of RAP, the user is required to properly configure before starting RAP. This includes such items as having the disk containing registered and static data ready, all MET station cards available, and input and output tapes mounted on designated tape drives. Additional program setup may be made through selected VT05 entries. Once initialization and setup is complete, program execution is started and continues for about 20 minutes. The source data is from cards, disk, and tapes containing CMI and old DMAT information. The disk files and input tapes contain 550 scan lines of information. Each scan line has 625 PIXELS. sequence of tape input/output and disk reads and writes. Data is read and written to disk four scan lines at a time. The data to be color-coded and formatted for product output is passed to RFTGEN for product generation for each scan line. Following 550 cyclic operations, the MET station reports are output to the line printer and pertinent data saved on disk. The new update tape has now been generated and SSP processing may be started.

4.1.4 Storage Allocations. The storage requirements for RAP are illustrated by figure 4-3. As shown by the diagram, all component modules except U9TRD require 12K core storage for instruction space and internal buffers and constants. All five modules use one or several 4K segmentation buffers for passing data from one module to the other. The 4K buffers used by RAP, REGBUF and GRDBUF, contain four scan line blocks of registered imagery, and four scan line blocks of background data used in maintaining the current ground truth temperature when satellite data is missing. The layout of REGBUF and GRDBUF is shown in figure 4-4. The 4K buffer ORCBUF is used as the products calculations transfer buffer and work area for the six ORC images.

4.1.5 Data Base Characteristics

- A. **File Description.** The common files of RAP consist of two common storage blocks, SCOMVT and DBDAT1. The first area is used by most programs and modules in SEDS because



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Figure 4-3 RAP Storage Allocation

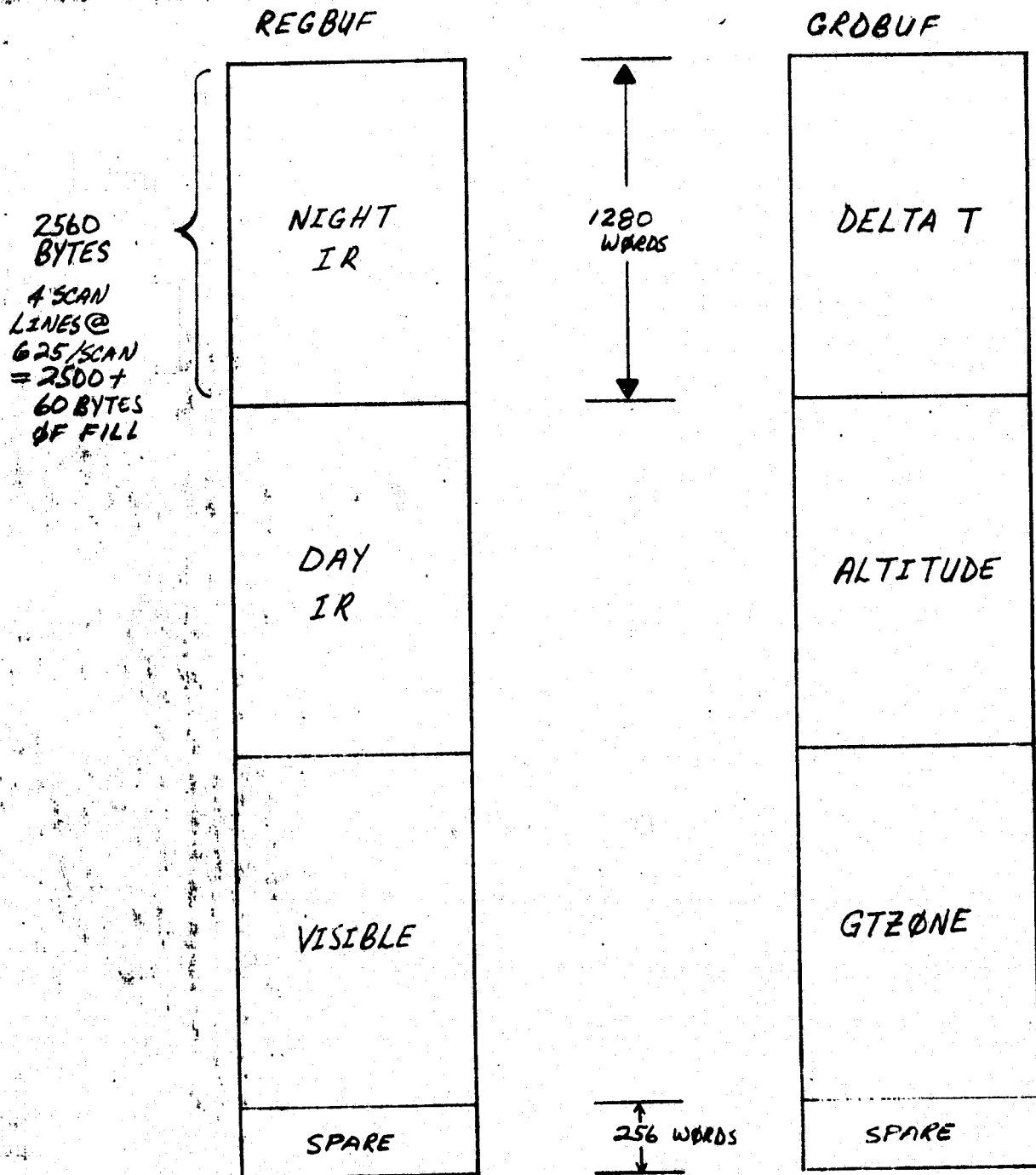


Figure 4-4 4K Buffers Layout

it contains VT05 and universal format tape read flags and constants. The common area DBDAT1 is unique to RAP. It is a 583-word block initialized and set up in DBUNIT, and is referenced and/or modified by all succeeding components of RAP. The exact content of this data block is shown by the listing printout of the subcomponent called "DBUINT."

- B. Program Constants. Several sets of program constants reside in RAP, ranging in size and number from the rainfall coefficients to the complex DMAT constants. Some are simple, such as threshold values for various temperature conditions or the number of MET station statistical printouts. These groups of program constants are further explained in this section and in the computer program listings (Part IV).

4.2 RAP CPC CHARACTERISTICS

This paragraph contains a detailed technical description of the computer program components (CPC's) identified in paragraph 4.1. The instruction listings contained herein, by inclusion or reference specify the exact configuration of RAP.

4.2.1 DBUINT. The initialization and first execution component of RAP is DBUNIT. User control of card inputs and VT05 entry of MET station ID updates is accomplished in this module, as well as normal and abnormal program termination. The module is comprised of several separate and distinct subcomponents. Two of these (DBUDRV and METCRD) are written in PDP-11 FORTRAN. The other subcomponents are written in PDP-11/45 assembly language.

4.2.1.1 Subcomponent Descriptions

- A. DBUDRV. This is the RAP driver routine of SEDS, and exists because of the system segmentation and overlay software utilized by SEDS.
- B. "DBUINT." This is the primary subcomponent of the RAP module DBUNIT. Initialization, card input control, and termination are the primary functions of the DBUINT module. User control is through the VT05 terminal. RAP utilizes specially developed VT05 input/output software. Card input and MET station ID update control are accomplished through "yes" or "no" responses to advisory messages output to the VT05. The MET station ID update display and the RAP initialized VT05 control display are shown in figures 4-5 and 4-6, respectively. Through VT05 user response, program control is passed on to the second RAP module (RAP) for processing. Program termination is back through DBUINT which, via user response, returns to the SEDS residence control portion.
- C. DBURT1 and DBURT2. These are two source/object subcomponents which contain several subroutines used for disk and line printer interfacing and conversion functions. Included are the subroutines DSKFIX and OUTDSK/INDISK.

REP 00-0000,0000*

SCAN\PIXEL	SCAN\PIXEL	SCAN\PIXEL	SCAN\PIXEL	SCAN\PIXEL	SCAN\PIXEL	ID
0076 0174	0169 0036	0158 0171	0202 0039	0046 0209	0238 0262	* 5
0207 0348	0219 0078	0282 0157	0291 0238	0326 0194	0264 0394	* 11
0257 0420	0120 0210	0301 0442	0369 0248	0361 0342	0325 0384	* 17
0387 0299	0370 0433	0336 0465	0438 0293	0399 0332	0396 0426	* 23
0394 0429	0399 0457	0380 0516	0123 0241	0397 0593	0454 0431	* 29
0448 0518	0479 0424	0463 0567	0000 0000	0094 0237	0000 0000	* 35
0342 0318	0090 0259	0213 0072	0065 0141	0067 0259	0431 0296	* 41
0452 0565	0375 0490	0083 0293	0030 0284	0460 0348	0188 0423	* 47
0021 0338	0400 0366	0403 0571	0353 0489	0153 0358	0102 0024	* 53
0053 0339	0398 0243	0123 0321	0189 0402	0325 0358	0229 0009	* 59
0369 0444	0428 0623	0314 0418	0415 0344	0087 0389	0389 0618	* 65
0466 0370	0000 0000	0000 0000	0000 0000	0074 0021	0088 0039	* 71
0089 0060	0055 0105	0662 0142	0093 0315	0105 0304	0122 0356	* 77
0184 0400	0189 0424	0065 0418	0079 0429	0039 0441	0034 0252	* 83
0042 0300	0004 0314	0042 0460	0029 0385	0112 0399	0152 0357	* 89
0153 0380	0158 0406	0179 0416	0084 0368	0056 0382	0012 0384	* 95
0131 0408	0094 0415	0049 0447	0039 0482			

Figure 4-5 MET Stations ID Display


```

***** DATA BASE UPDATE - SEQ 1 *****
UPDATE PHASE MODE = U                      DATE: 01-MAR-75
CURRENT DATA BASE SIZE: 14 DAYS
DELTA T: 00-XXX-00                        MET STA COPIES=02

REGISTERED DISK = A
DATE-OF-DATA: 00-00-00    * DAY ORBIT NO.=0000
                          * NIGHT ORBIT NO.=0000

TAPE I-O ASSIGNMENTS
NEW UPDATE (XXXXXX)=MT0    CURRENT CMI (-----)=MT1 = Y
ORC TAPE   (XXXXXX)=MTA0= Y OLD UPDATE  (-----)=MTA1= Y

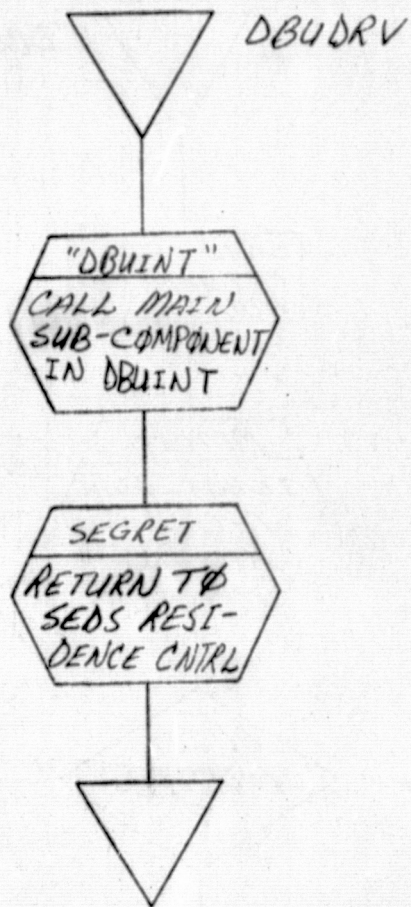
CONSTANTS & COEFFICIENTS
A10=-17533 * A20=-16774 * A30=-09800 * A40=-14584 * A50=-24621 *
A11=+00098 * A21=+00122 * A31=+00137 * A41=+00230 * A51=+00295 *
A12=+00157 * A22=+00148 * A32=+00097 * A42=+00065 * A52=+00130 *
THRLD = -28000 TTHN = 142 TTMD = 164
KDAY = +020 KNIGHT = +040 MINDLT = 120 DDT = 002

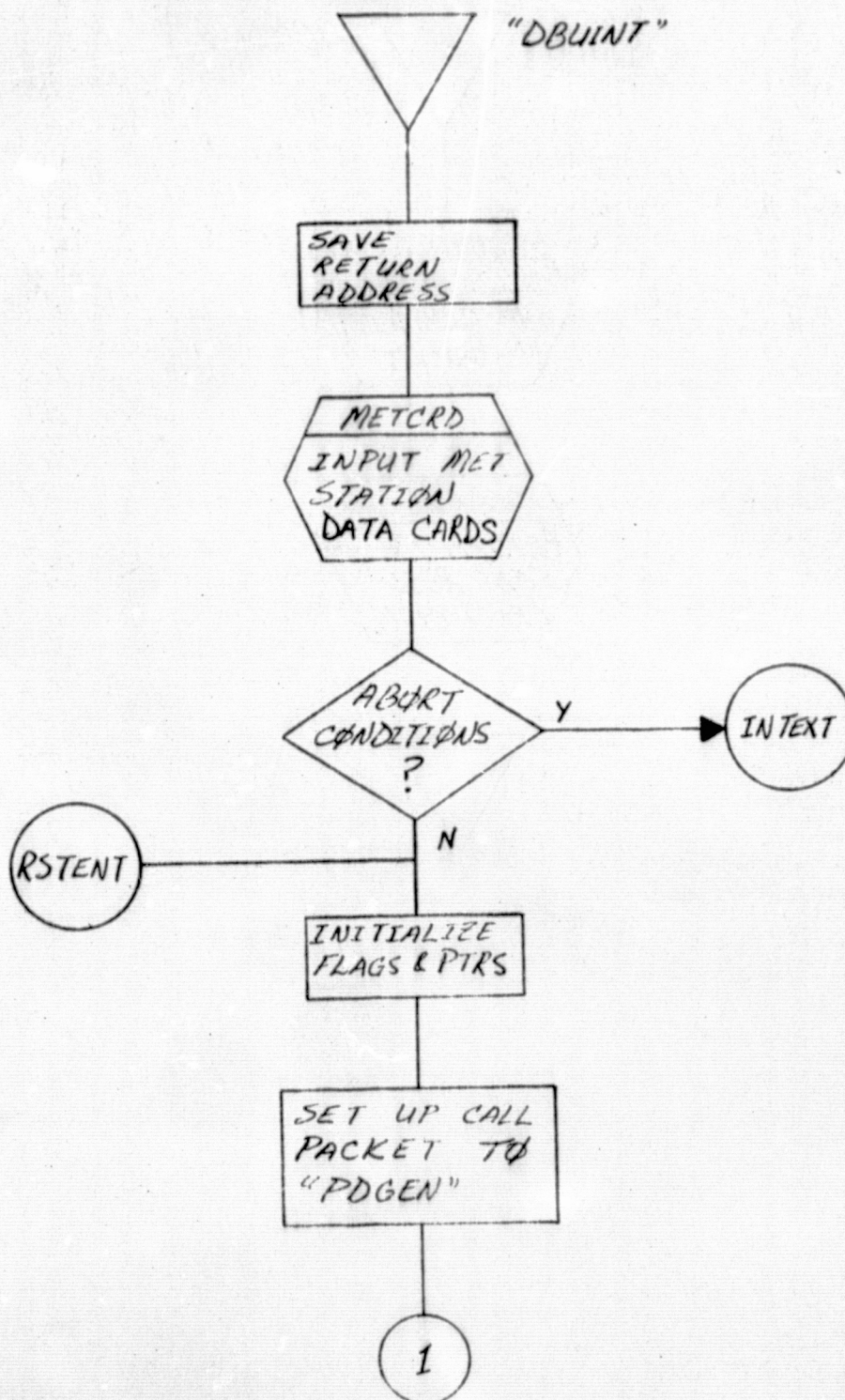
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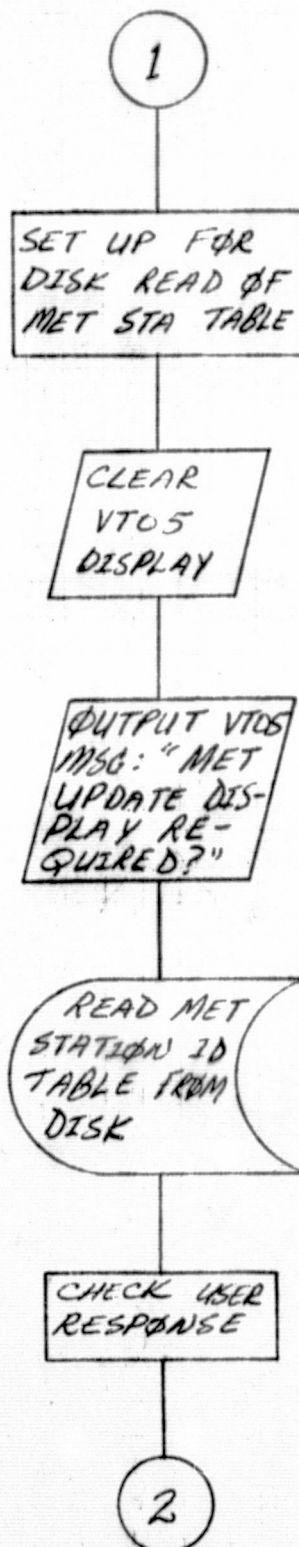
Figure 4-6 RAP Initialized VT05 Display

- D. DBUMSG. This is the source/object subcomponent which contains predefined VT05 and line printer messages.
- E. METSP. This is the source/object subcomponent which contains the special VT05 processors used in updating the MET station ID display.
- F. METTBL. This is the buffer which contains the MET station ID's.
- G. METDSP. This is the coded VT05 buffer which results in the output of the MET display shown in figure 4-5.
- H. DBUDSP. This is the coded VT05 buffer shown in figure 4-6.
- I. RFCOEF. This is the core-resident buffer showing where the rainfall coefficients reside as they are input from disk.
- J. METCRD. This is the MET station data card input controlling routine for table setup for RAP processing.
- K. TBINIT. This subcomponent initializes the tables used in METCRD for line printer tabouts.
- L. CKDATE. This subcomponent checks the input card date against the date of the registered data date on disk.
- M. TABMET. Tabs out the stations reporting and their input DMAT/PRECIP values in degrees Kelvin and millimeters.
- N. GONOGO. Informs user via the VT05 the status of card inputs and request further direction.
- O. BLDTMT. Builds the TMET table used in RAP processing, and calculates the integer encoded values for the card input DMAT values.

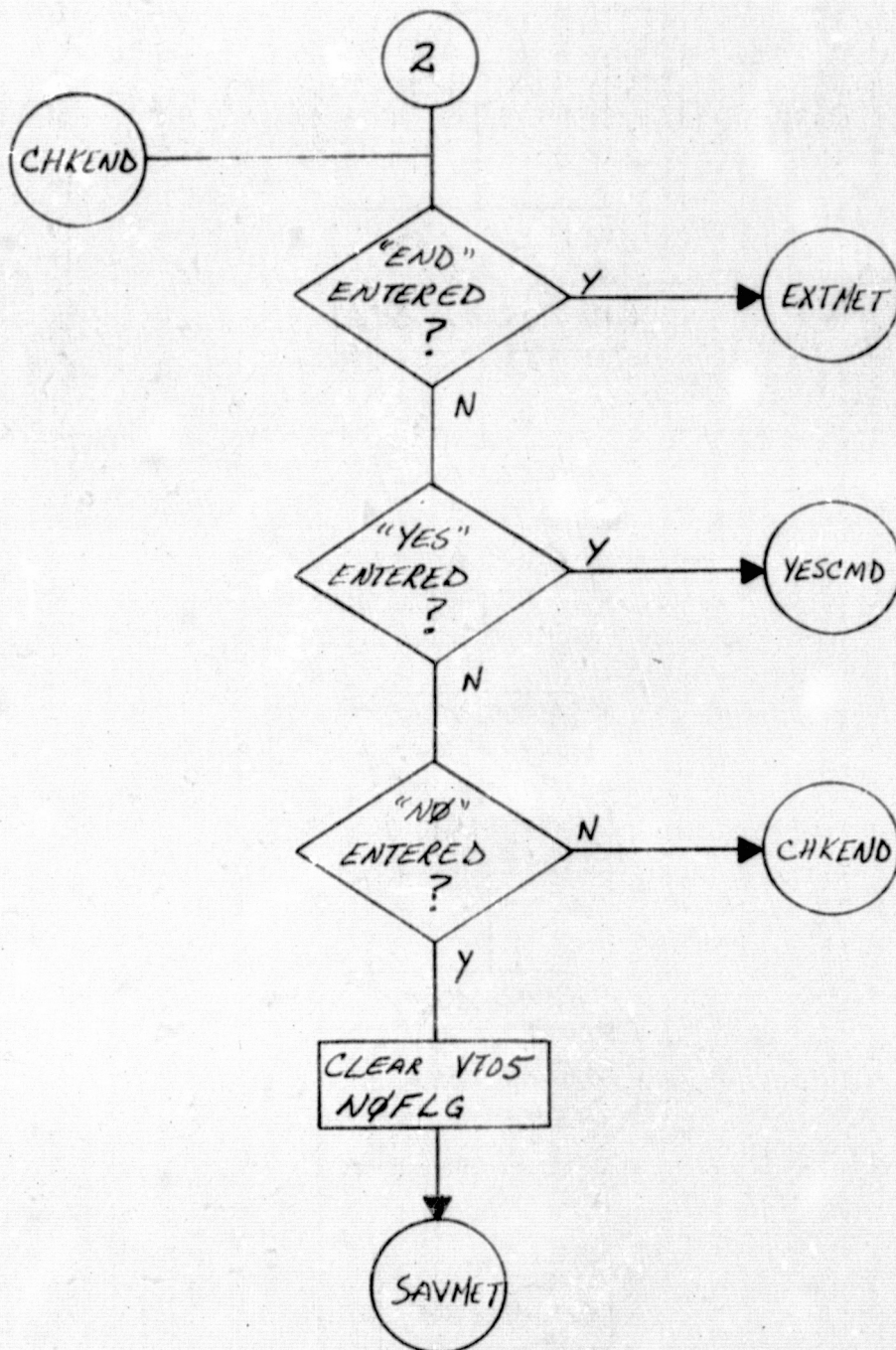
4.2.1.2 Flow Charts. See the following 26 pages.

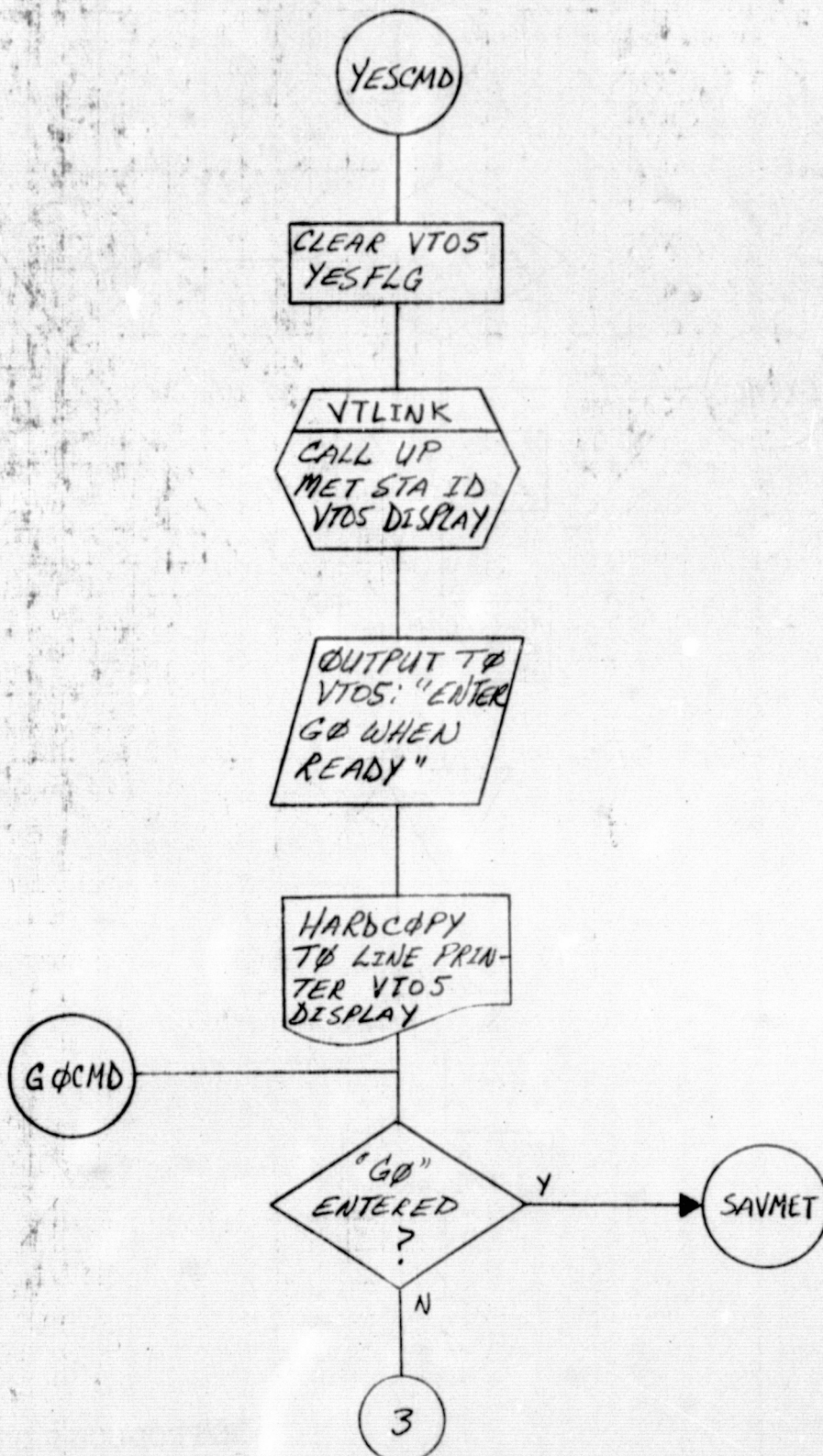


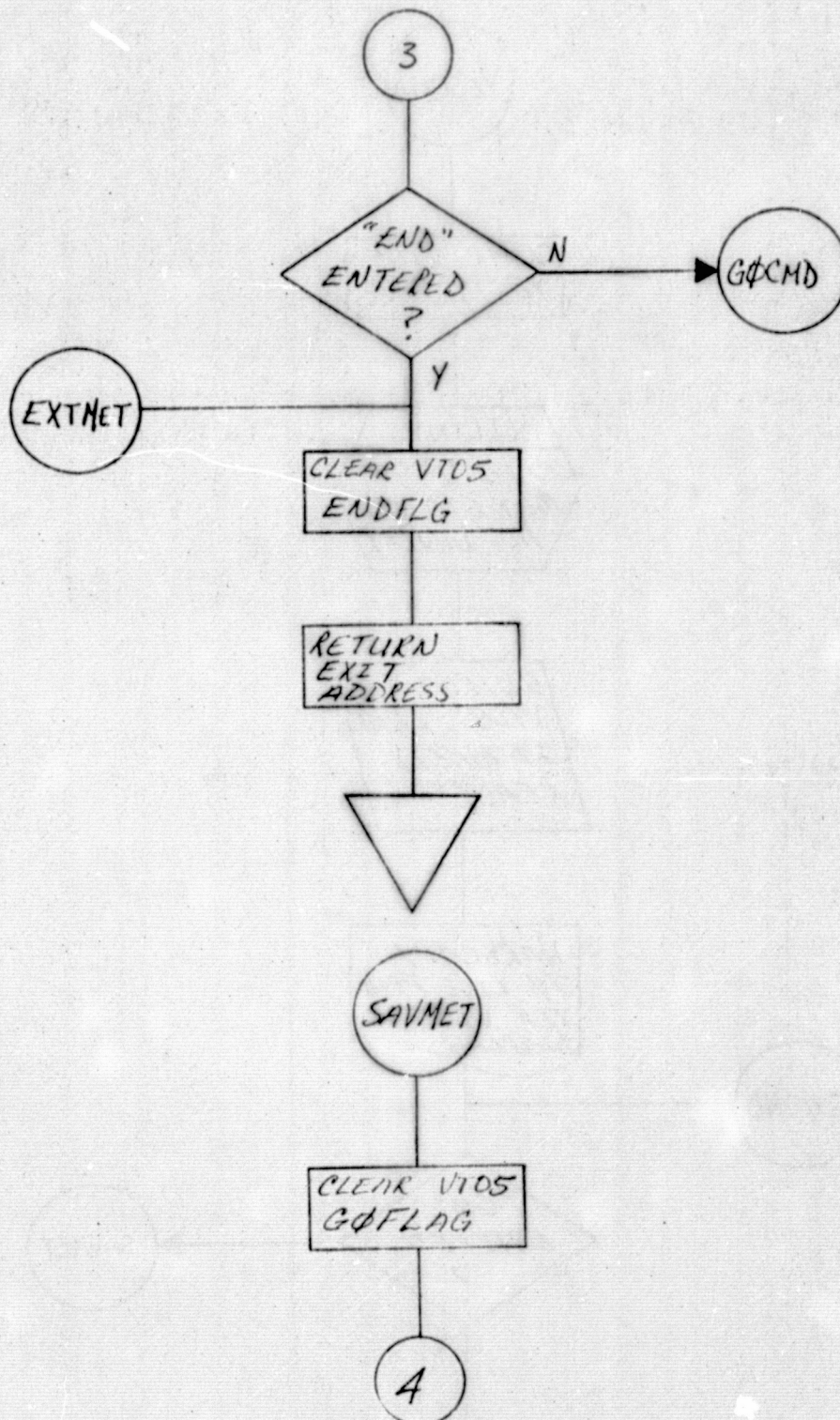




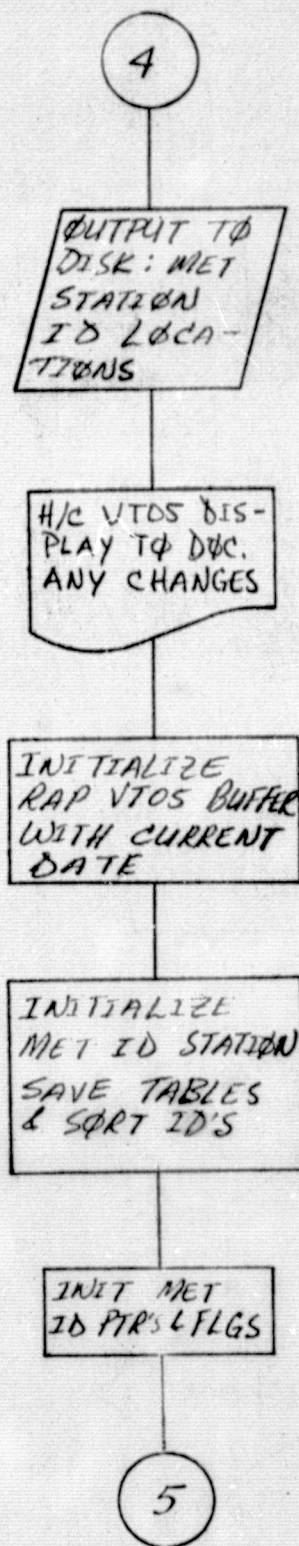
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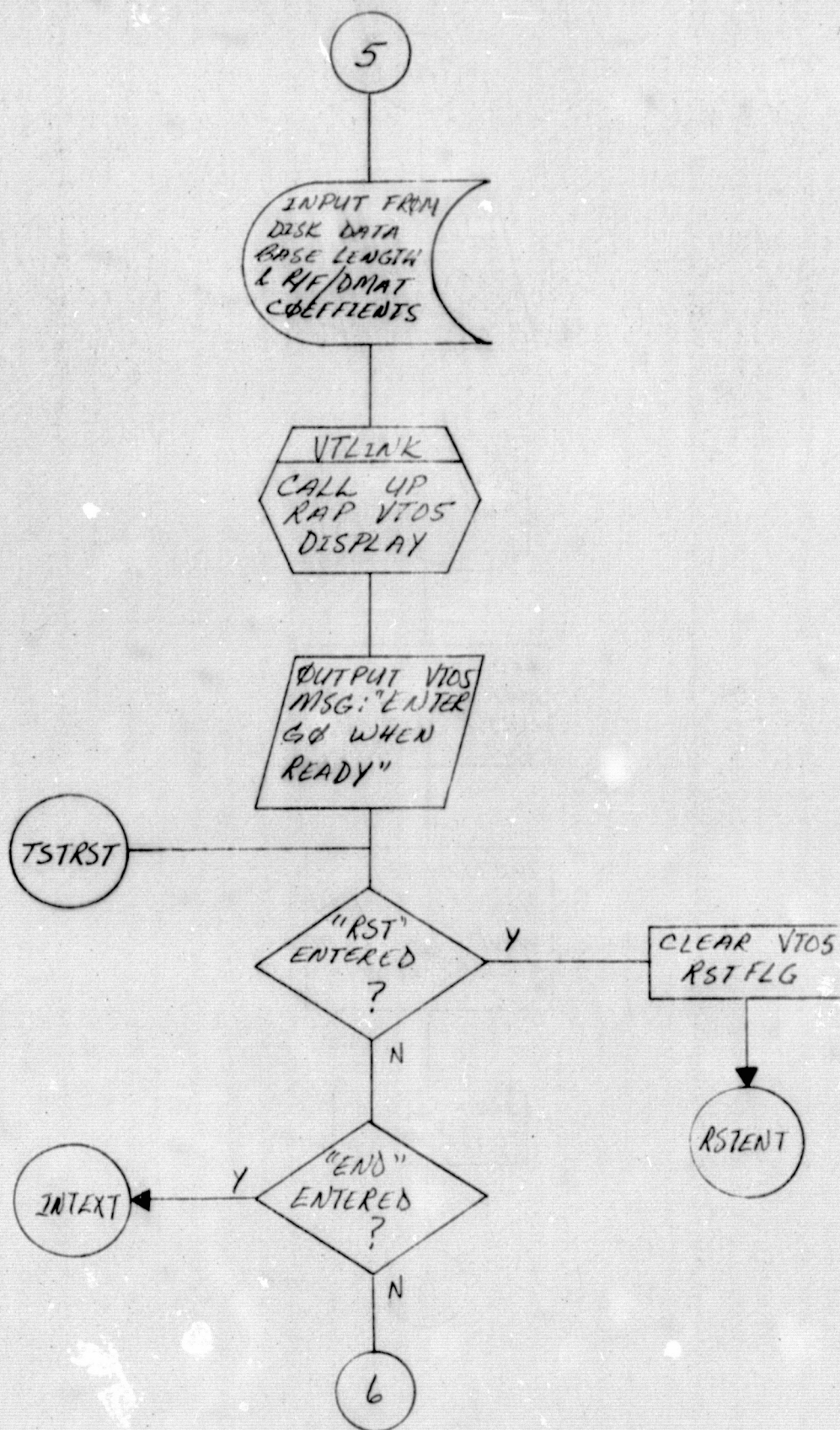


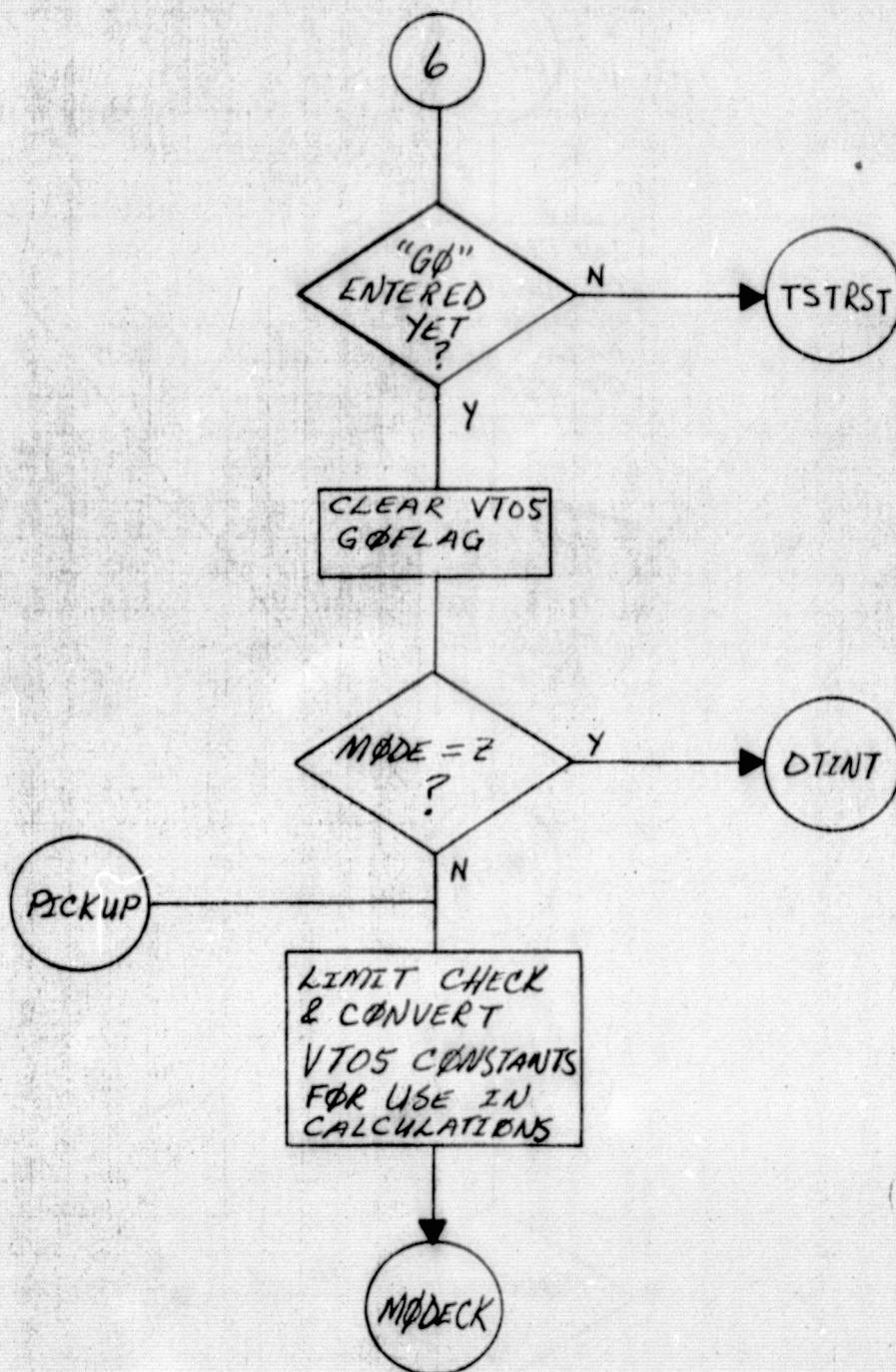


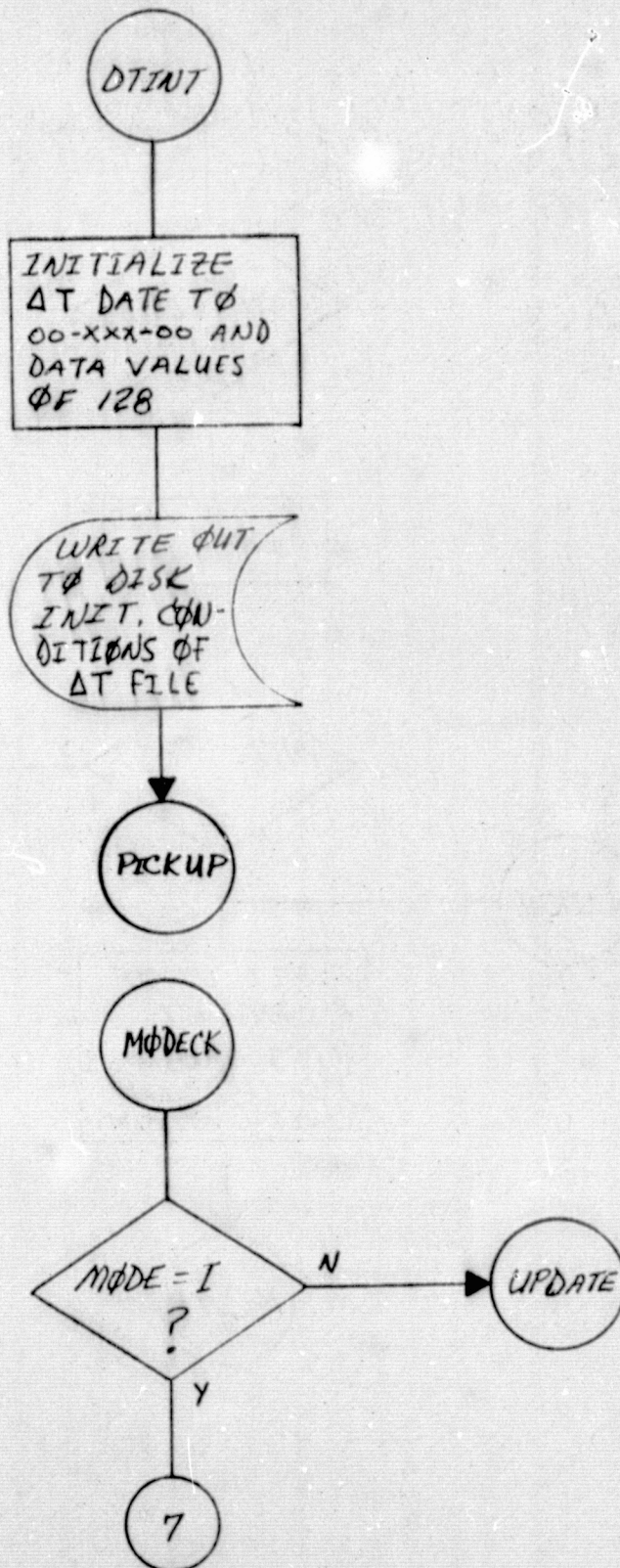


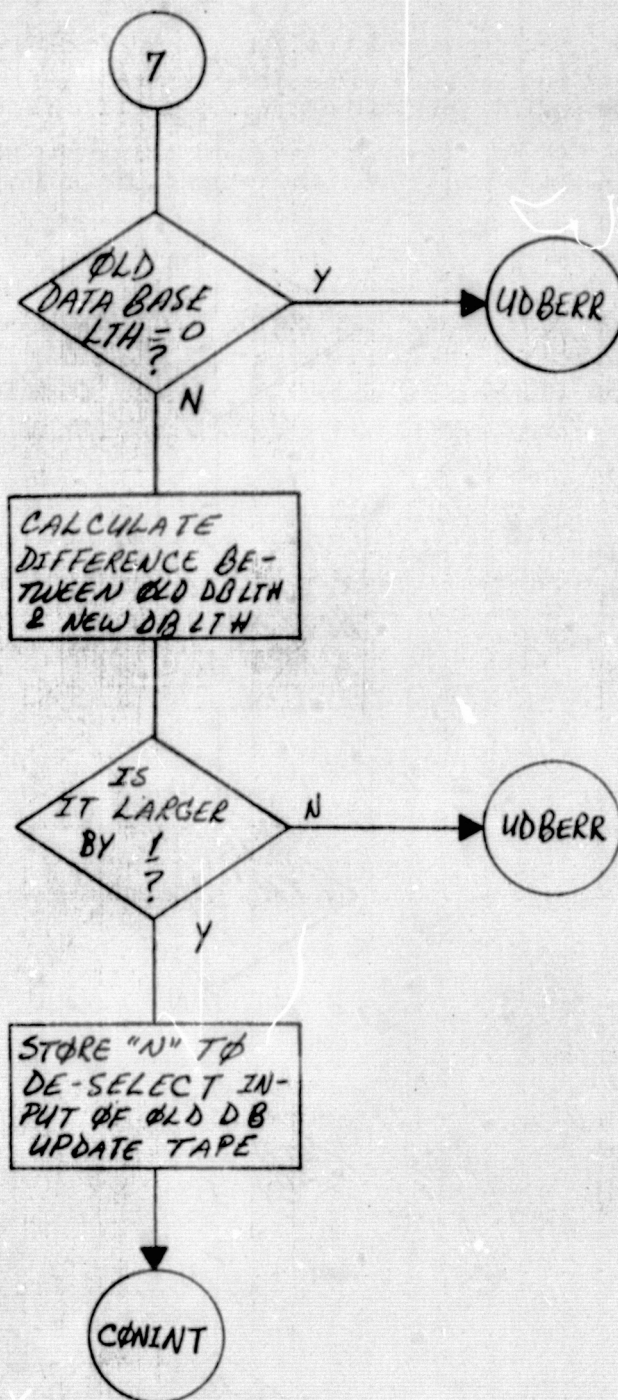
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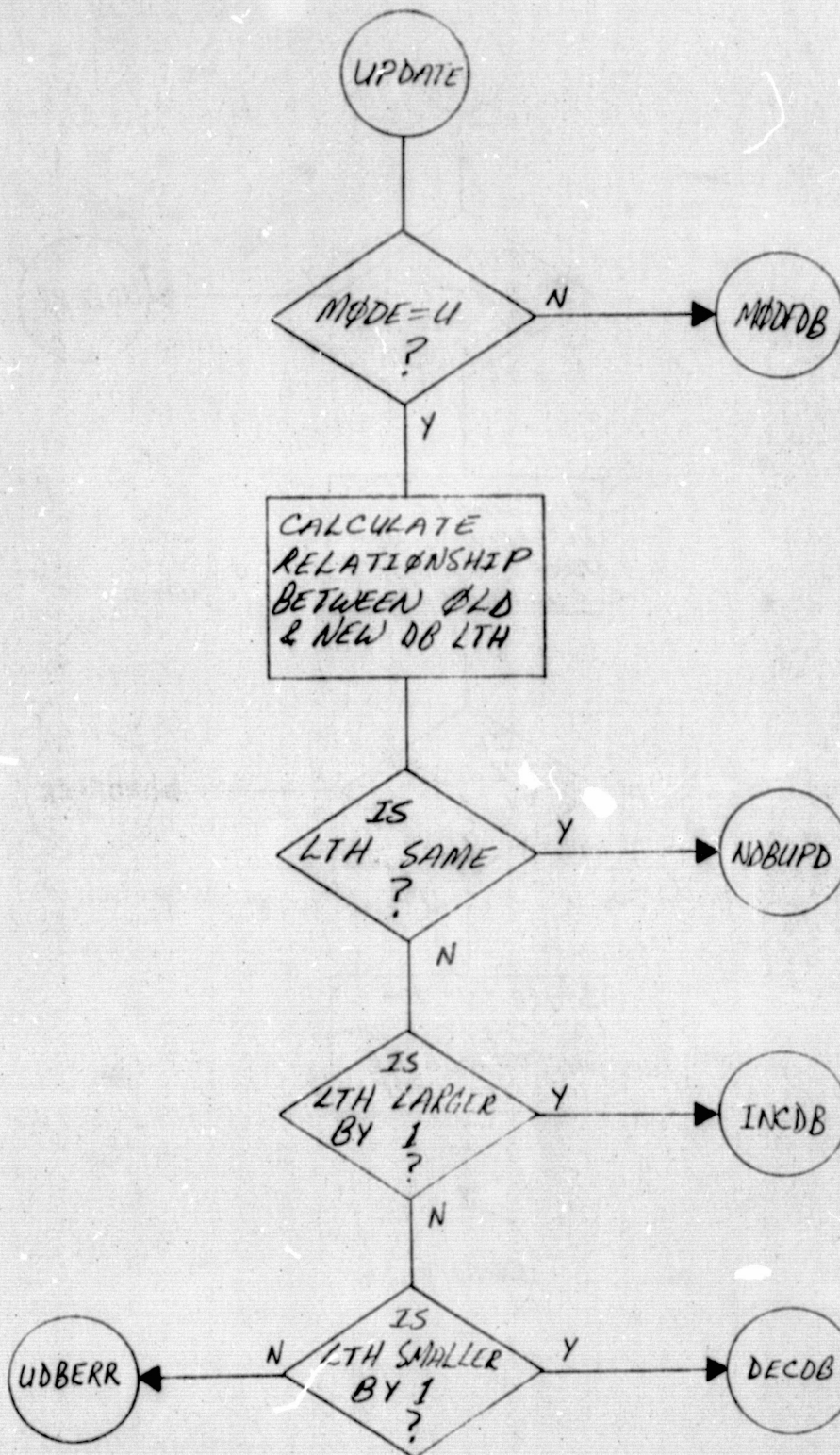


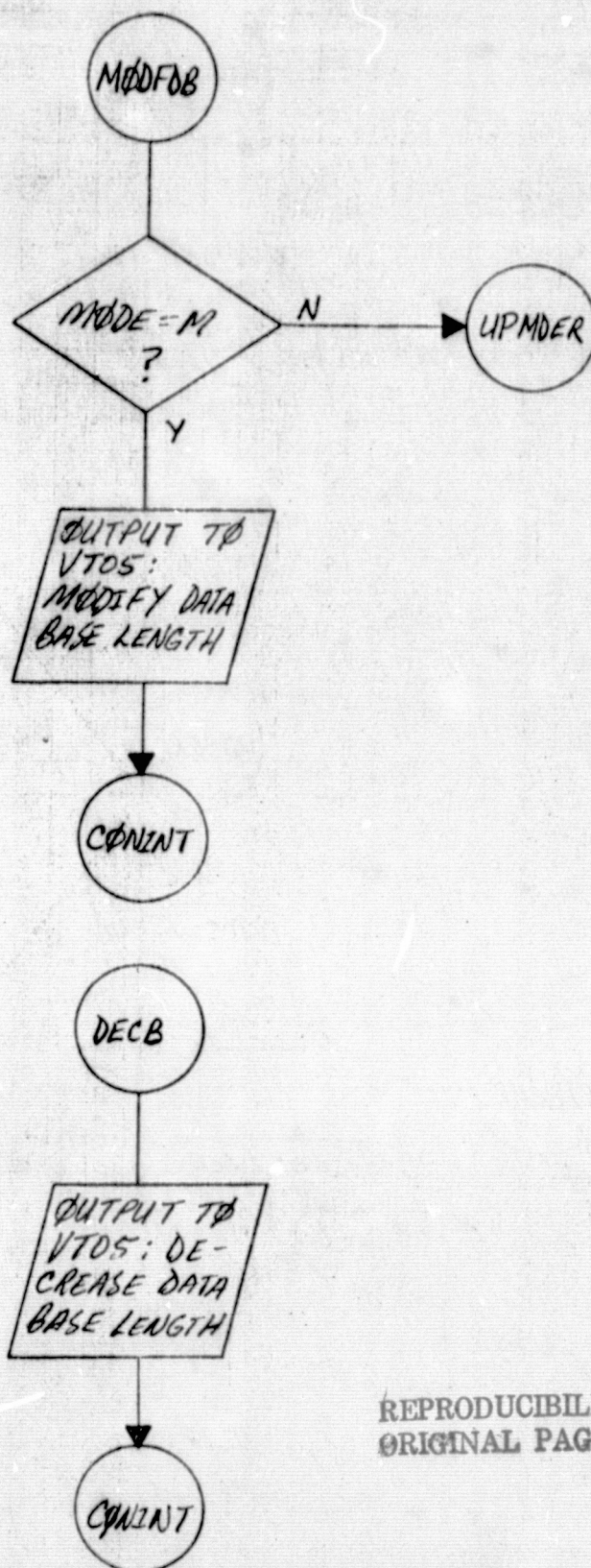




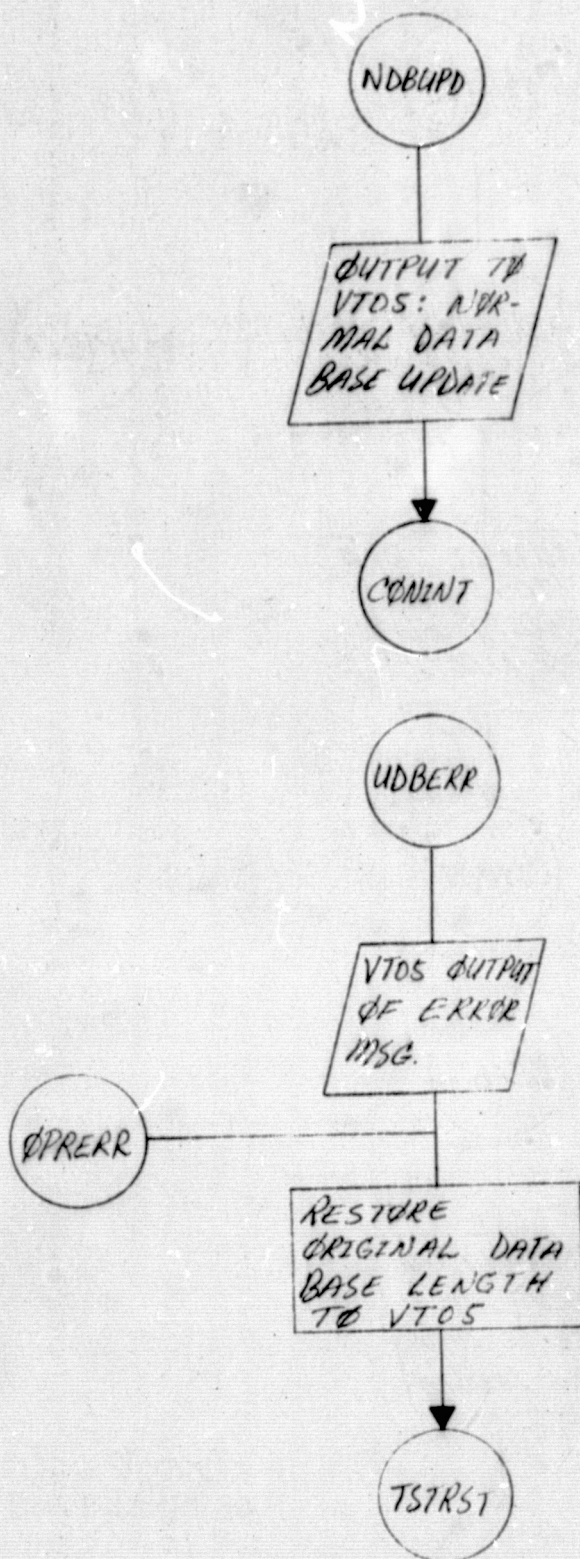


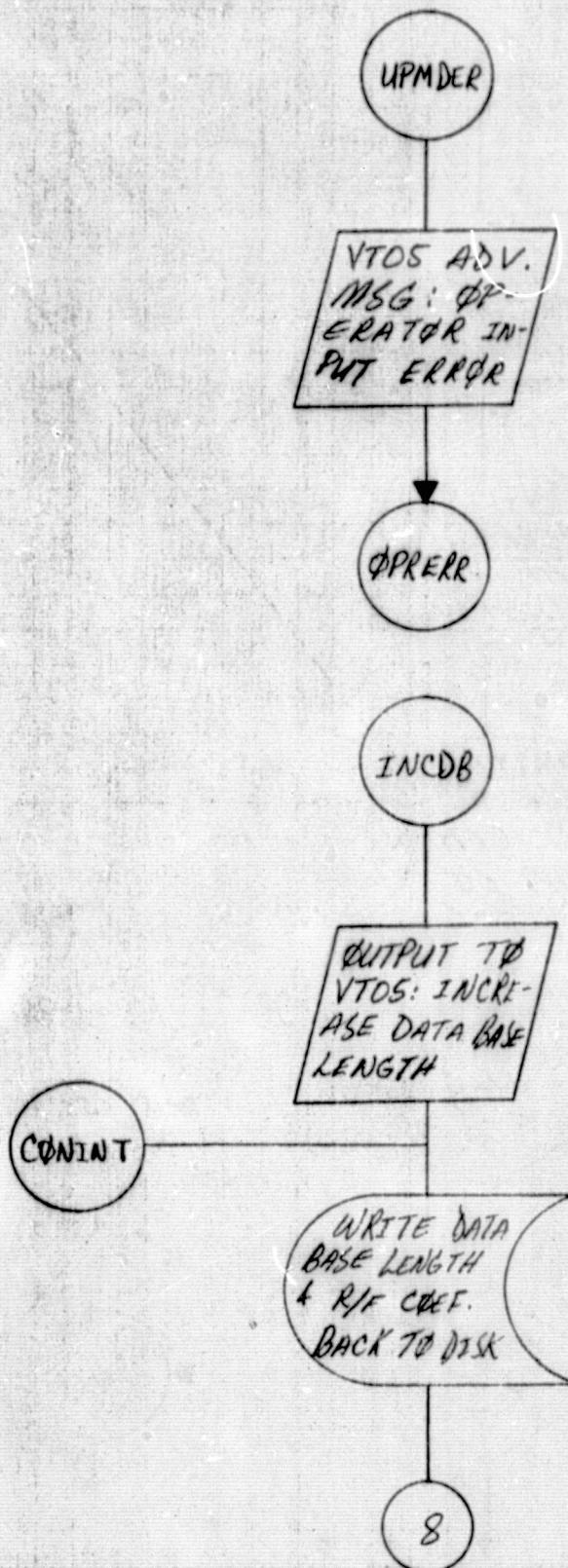
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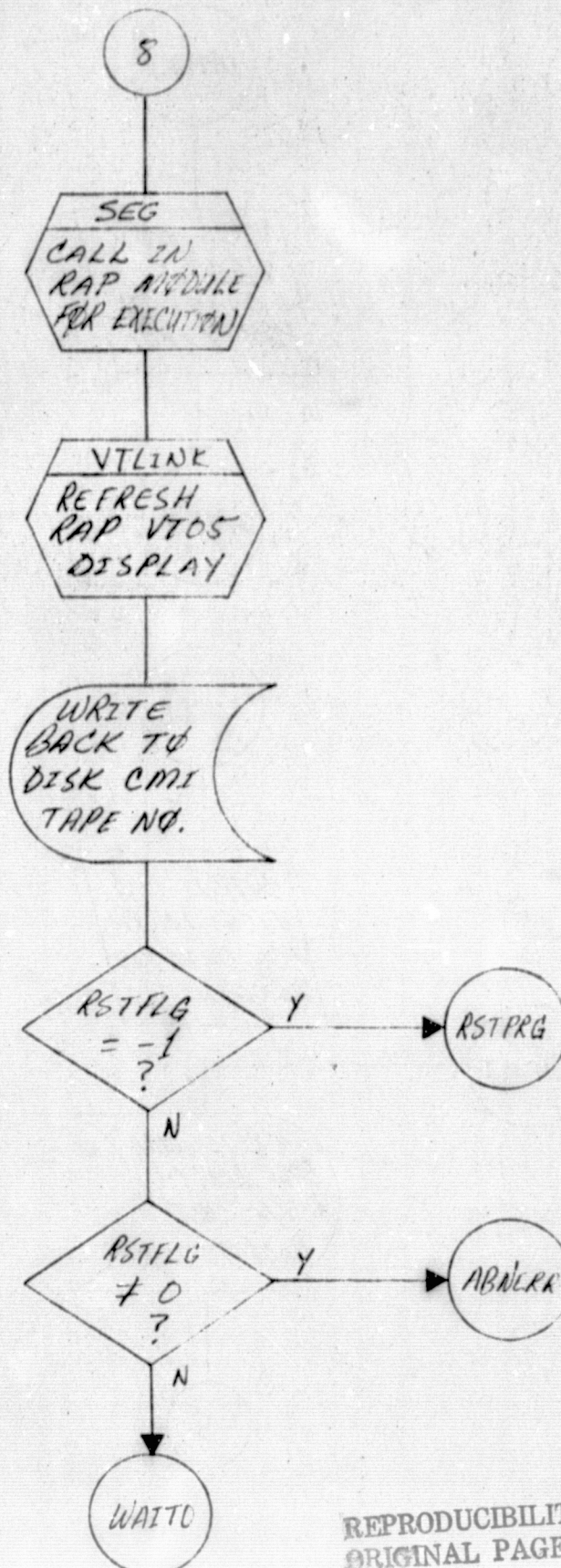




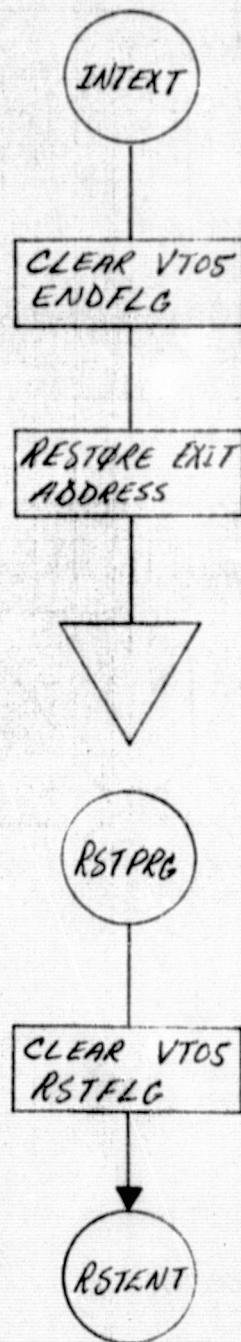
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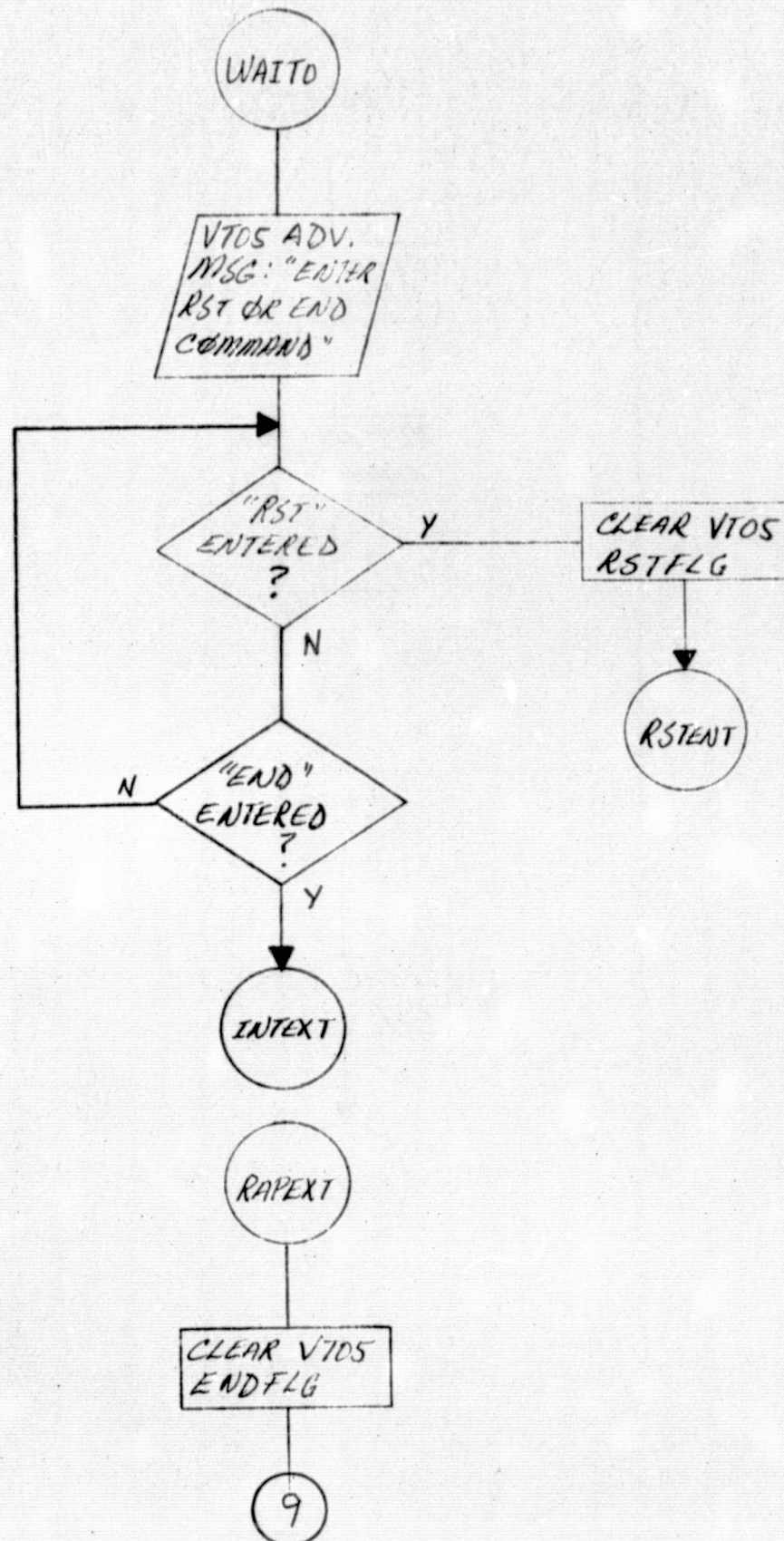


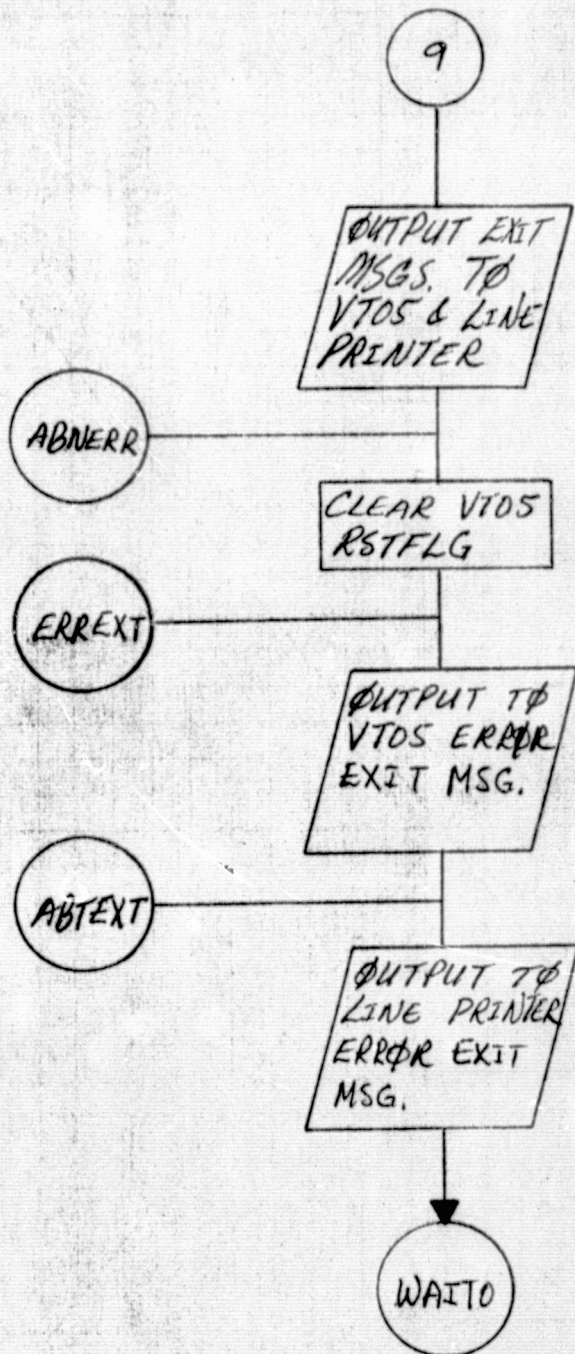


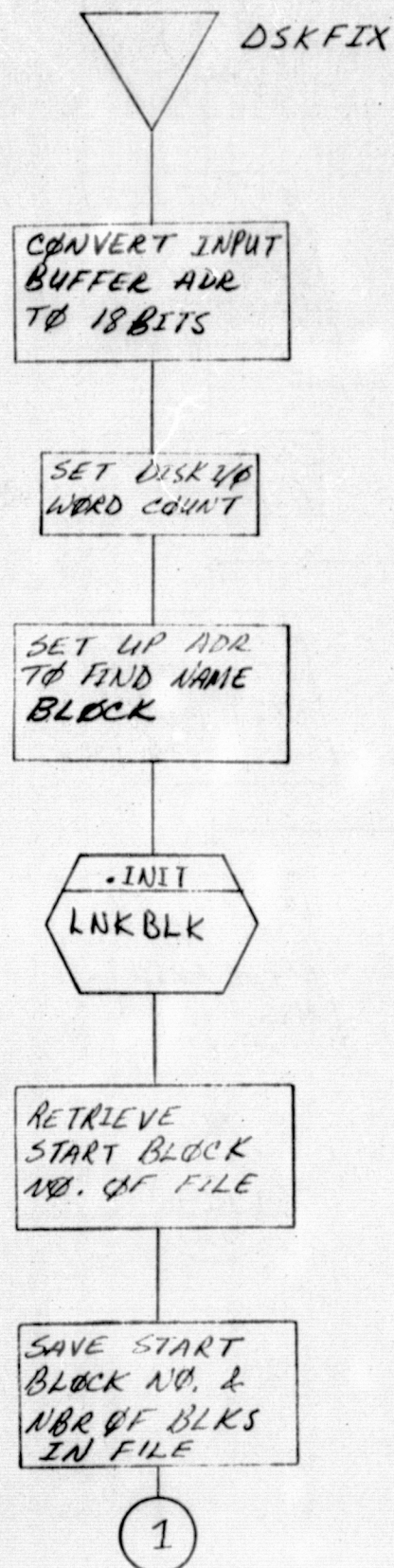


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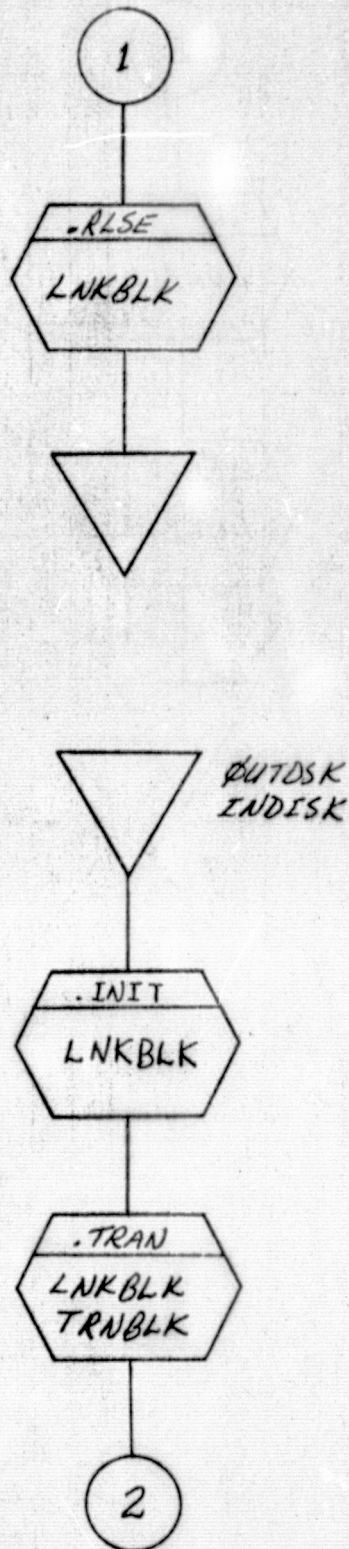


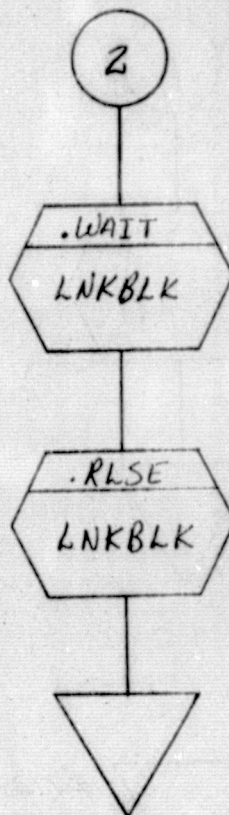


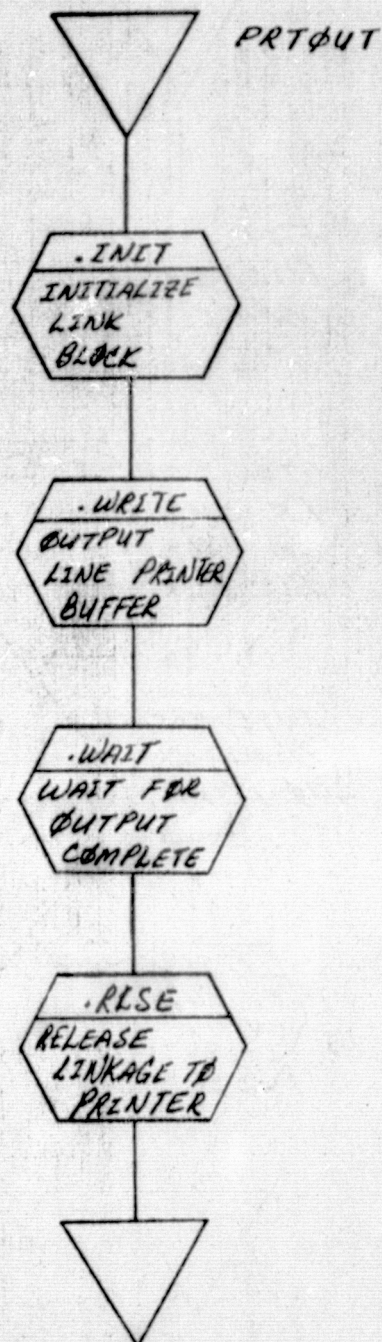


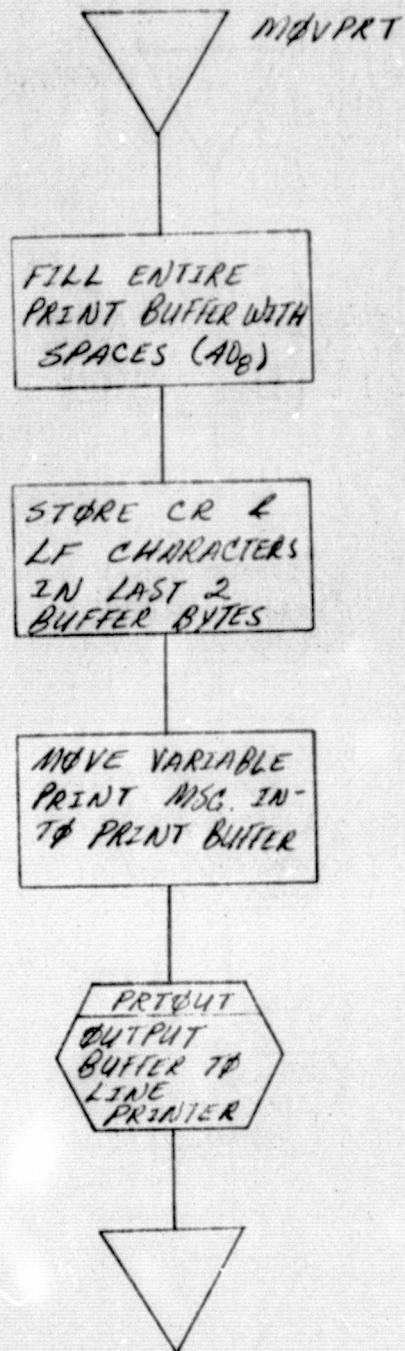


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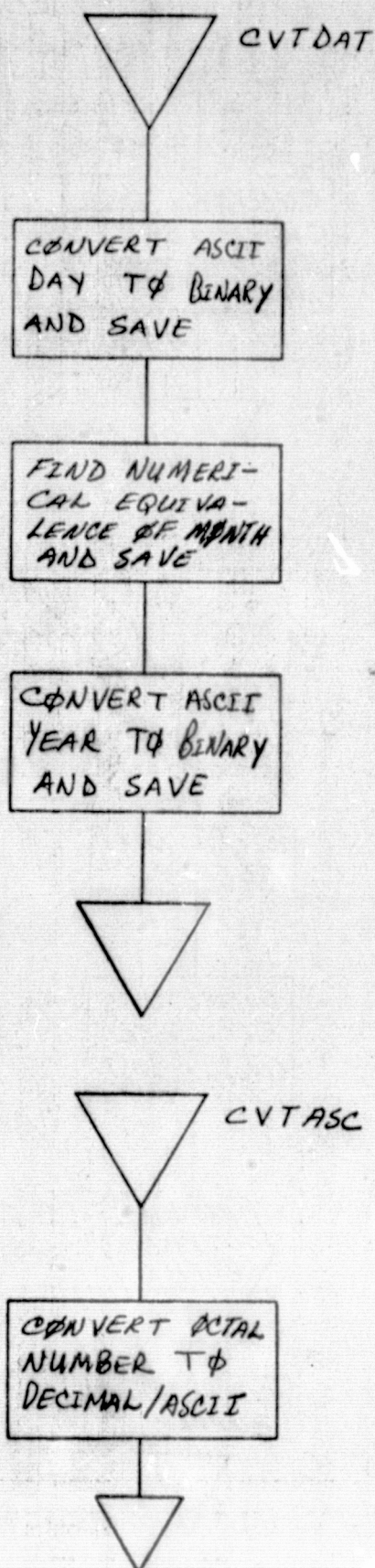


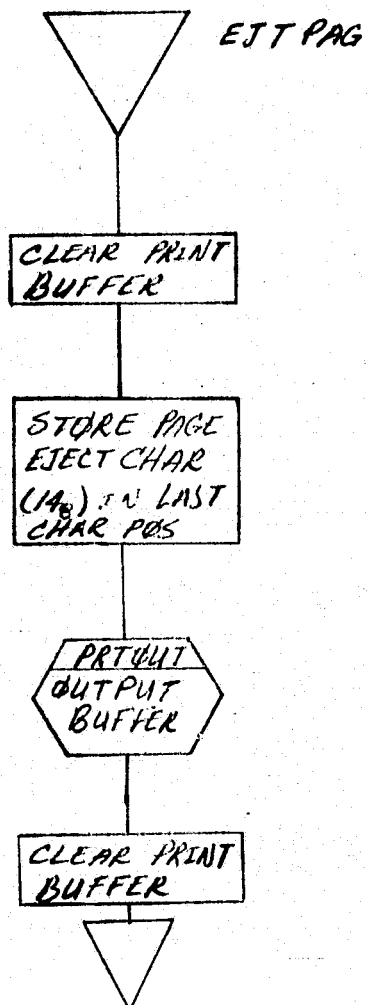
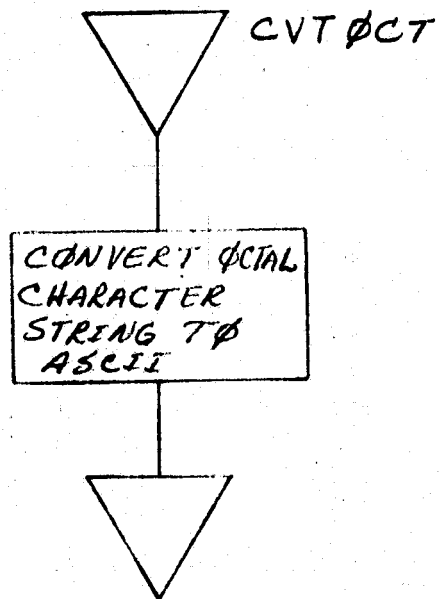






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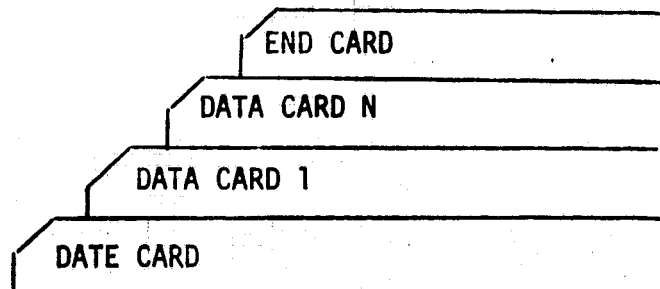
4.2.1.3 Interfaces

- A. Input Data. Input data to DBUINT comes from three sources--card input, user control through the VT05, and disk. Card inputs of MET station data are from selected U.S. and Mexican weather stations. The lead card contains the date (MM-DD-YY) of the MET data. The following data cards contain a MET station ID number (1-100), a daily mean air temperature in °C or °F, and a 24-hour total precipitation measurement in inches or millimeters. The MET station input card format is shown in figure 4-7. User inputs are made via the VT05 keyboard for changeable fields, allowing greater flexibility and control. The ALT key is used to position the cursor as such fields. The disk files referenced by the DBUINT module reside on the system disk (DK0) under users identification code (UIC) 300,300. The three disk files are METLOC.TBL, DBINFO.TBL, and RFCOEF.TBL and each file is one block (256 words) or less in length. The detailed format of these files may be determined from the program listings provided in Part IV of this document.
- B. Output Data. The output of the DBUINT module consists only of the internally generated messages and data output to the VT05 and line printer for user control.

4.2.1.4 Data Organization. The principle internally defined items of DBUINT are those associated with the VT05 changeable input fields. These variables are discussed in paragraph 4.2.2.4.

4.2.1.5 Limitations. Operational restraints and disk input/output error analysis limit the complete execution of DBUINT. The operations procedure defined by the current SEDS Operations Manual require the user to follow instructions closely. Interrogation of disk I/O errors is not always complete, and care should be taken to ensure that the proper system and data disks are used.

4.2.1.6 Listings. See Part IV of this document, published under separate cover.

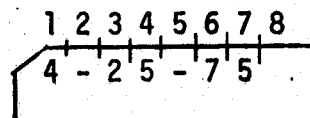


DATE CARD

COLS

CONTENT

1-8 DATE OF MET DATA IN THE FORMAT MM-DD-YY OR MM DD YY; INPUT DOES NOT HAVE TO RIGHT OR LEFT JUSTIFIED. FOR EXAMPLE:



DATA CARDS (1-N)

- 3-5 MET STATION ID; MUST BE RIGHT-JUSTIFIED BUT NO LEADING ZEROS NEED BE INPUT
- 10-19* DMAT; CAN BE INPUT IN EITHER OF TWO FORMATS:
- INTEGER - INPUT MUST BE RIGHT-JUSTIFIED; LEADING ZEROS OR DECIMAL POINT ARE NOT NECESSARY
 - FLOATING POINT - CAN BE INPUT ANYWHERE IN THE ALLOTTED FIELD; MUST CONTAIN A DECIMAL POINT
- 20 ALPHA CODE; C = CENTIGRADE INPUT OF DMAT, F = FAHRENHEIT INPUT OF DMAT, AND A BLANK DEFAULTS TO CENTIGRADE
- 25-34* TOTAL 24 HOUR PRECIPITATION; CAN BE INPUT IN EITHER OF TWO FORMATS, SAME FORMATS AS LISTED UNDER DMAT ABOVE
- 35-36 ALPHA CODE; IN = INCHES OF PRECIPITATION INPUT, MM = MILLIMETERS OF PRECIPITATION INPUT, AND A BLANK DEFAULTS TO MILLIMETERS

END CARD

1 CHARACTER E TO INDICATE THE END OF THE DATA CARDS IN THE CARD DECK

* DMAT OR PRECIPITATION FIELD CAN BE LEFT BLANK IF THE INPUT IS NOT AVAILABLE

Figure 4-7 MET Station Data Card Format

4.2.2 RAP. The second module of the RAP Program in SEDS is also called RAP. This module provides for additional user control through the VT05, and serves as the processing controller of all data input and output during the cyclic operation. The data calculations, as well as sequencing and scheduling of disk and tape devices, are performed in the RAP module. The processing order of magnitude is about 625 PIXEL's of 550 scan lines. DMAT and product images are calculations which require PIXEL-by-PIXEL control. Tape reads and writes are performed at the single scan line level. Disk input/output operations are done in groups of four scan lines. The RAP module is composed of several separate and distinct subcomponents. For arithmetic convenience, some routines are written in PDP-11 FORTRAN, but most are written in PDP-11/45 assembly language.

4.2.2.1 Subcomponent Descriptions

- A. RAPDRV. This subcomponent serves as the linking driver between the RAP and DBUINT modules.
- B. "RAP." This is the primary subcomponent of the RAP module. User control not completed through the VT05 in the DBUINT module is continued in the "RAP" subcomponent. Available input and output tapes and tape numbers are designated. The user is also required to enter day and night orbit numbers. Changes to the various program constants and coefficients are made at this time. When the operator keys in the CON command to proceed, the cyclic operation of the RAP module begins. Tape and disk I/O and data calculations are performed for 550 scan lines. At program termination, control is returned by this subcomponent to the DBUINT module for further user direction to end or restart.
- C. DBSUB1. This source/object module contains the subroutine called RAG, which performs the rainfall estimation algorithm. The primary function of the subroutine is to determine (by temperature evaluation) if a specified PIXEL is cloud-covered, and if so, to determine the prediction of the rainfall class to which it belongs. One of five

rainfall class codes will be determined for each PIXEL ranging from dry (Class 1) to heavy rain (Class 5). The visible data and day IR bands for the same pass are used with a series of coefficients to determine these rainfall classes.

D. DBSUB2. This subcomponent is called by RAP via the label DMATRT once per PIXEL, immediately after the rainfall classifier in DBSUB1 has written the rainfall color code for this PIXEL in the rainfall map buffer. The primary function of DBSUB2 is to calculate the daily mean air temperature. It selects day IR, night IR, or both, as inputs for the DMAT calculation, based on a series of tests. It then calls a FORTRAN subroutine to do the actual calculation. If neither day IR or night IR passes all the tests, DBSUB2 uses ground truth data for calculating DMAT. DBSUB2 performs the following steps.

1. DBSUB2 checks the color code in the rainfall map buffer to see if day IR is rainfall Class 1 (clear).
2. If so, DBSUB2 does the day IR threshold test. If the data fails the threshold test, DBSUB2 changes the color code in the rainfall map buffer to Class 6.
3. If night IR data is present, DBSUB2 checks it against threshold and, if it fails the threshold test, writes color code 6 in night cloud map buffer.
4. If all tests have been passed so far, DBSUB2 checks against the ground truth threshold.
5. DBSUB2 then sets FLAG1 (the ground truth threshold flag) for use in the MET printout.
6. If the day IR data failed the ground truth threshold test, DBSUB2 changes the color code in the rainfall map buffer to Class 7.
7. If the night IR data failed the ground truth threshold test, DBSUB2 writes color code 7 in the night cloud map buffer.

8. If the night IR data passed all the tests, DBSUB2 writes color code 1 (clear) in the night cloud map buffer.
 9. If both day IR data and night IR data failed the ground truth threshold test, DBSUB2 decrements PDELTA (the delta T value) by the value of DDT.
 10. If either day IR data or night IR data (or both) passed all the tests, DBSUB2 calls one of three FORTRAN subroutines for the DMAT calculation. It calls DMTCAL if both day and night data passed, DCASE2 if only day IR data passed, and DCASE3 if only night IR data passed.
 11. DBSUB2 sets FLAG2 (DMAT source flag) for use in the MET printout.
 12. If DMAT is not calculated from the IR data, and if ground truth data is present, DBSUB2 calculates DMAT from the ground truth data.
 13. DBSUB2 sets the QUAL flag in the most significant byte of DMAT.
 14. DBSUB2 updates delta T (PDELTA) for disk storage.
 15. DBSUB2 then writes TGT, QUAL, TMET, and PDELTA in their respective color image buffers.
- E. DBSUB3. This is the source/object module that contains the subroutines DSKFIX, OUTDSK/INDISK, RHEAD, and RECRD. The first two subroutines, which deal with disk file communication, have been previously described in paragraph 4.2.1.1. The last two subroutines serve to call in the CMI universal format module for tape input. RHEAD is called during the first time through or to read the header record. RECRD is called repeatedly for each scan line from the CMI tape.

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- F. DBSUB4. This is the source/object module that contains the subroutines METSAV, PRTOUT, MOVPR, CVTDAT, CVTASC, CVTOCT, and EJTPAG. The last six subroutines were described with detailed flow charts under the DBUINT module, paragraph 4.2.1. The subroutine METSAV is called for each PIXEL for MET station verification. If a PIXEL is determined to be a MET station, pertinent information is saved for line printer output at the end of the RAP execution run.
- G. DMTCAL. This is a FORTRAN subroutine called by DBSUB2 to calculate DMAT when both day IR and night IR data is usable. Parameters passed to DMTCAL are day IR and night IR values (integers), the altitude for this PIXEL (an integer which DBSUB2 has gotten from the altitude background map), the floating point regression constant A0COE, and three floating point regression coefficients--A1COE, A2COE, and A3COE. DMAT is calculated in floating point in DMTCAL, converted to integer, and returned to DBSUB2 as an integer word, with a value between 0 and 255.
- H. DCASE2. This subroutine is similar to DMTCAL, except that it is called when only day IR data is useable. The regression constant and two coefficients here are B0COE, B1COE, and B2COE.
- I. DCASE3. This subroutine is similar to DMTCAL except it is called when only night IR data is usable. The regression constant and two coefficients here are C0COE, C1COE, and C2COE.
- J. COREBF. This source/object subcomponent defines and reserves the core space for most of the core-resident buffers required by the RAP module. Details of the layout are shown in figure 4-8.
- K. DBUMSG, METTBL, STOC1, STOC2, and EB2CVT. These subcomponents of the RAP module have been previously described in detail in other sections of this document.

4.2.2.2 Flow Charts. See 43 pages following figure 4-8.

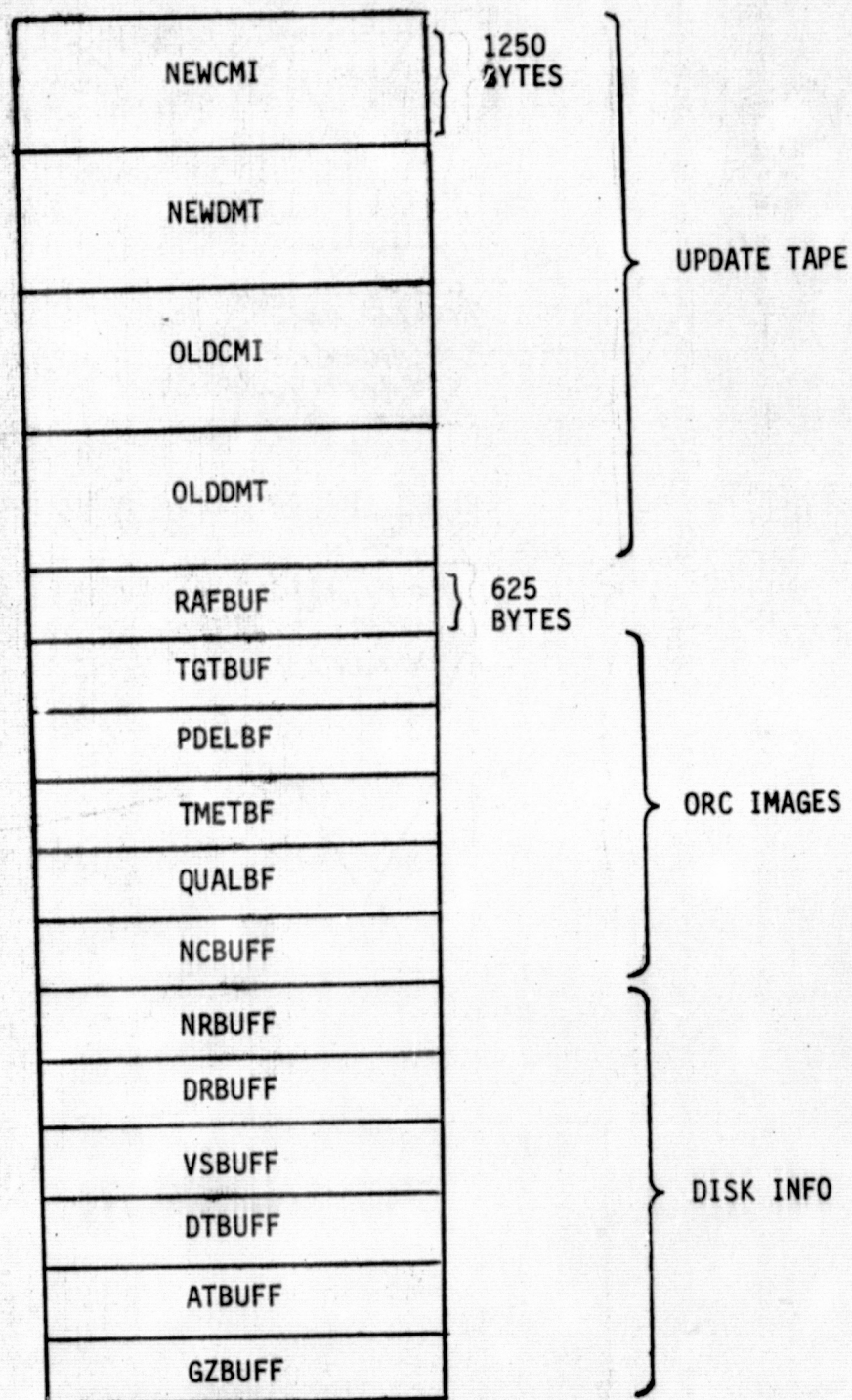
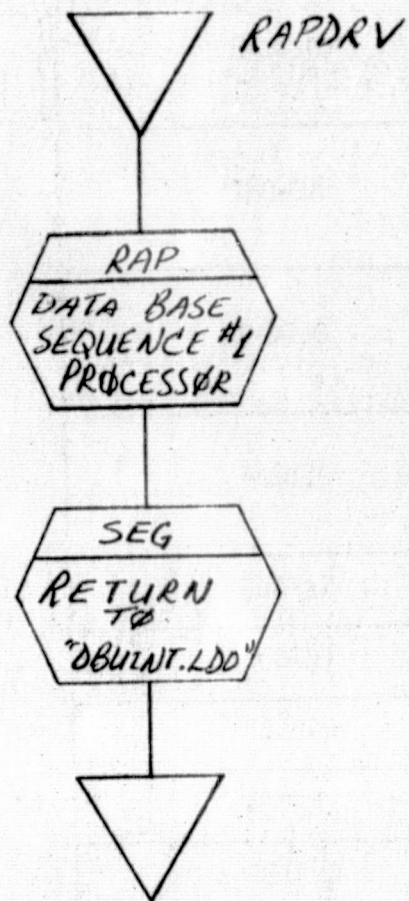
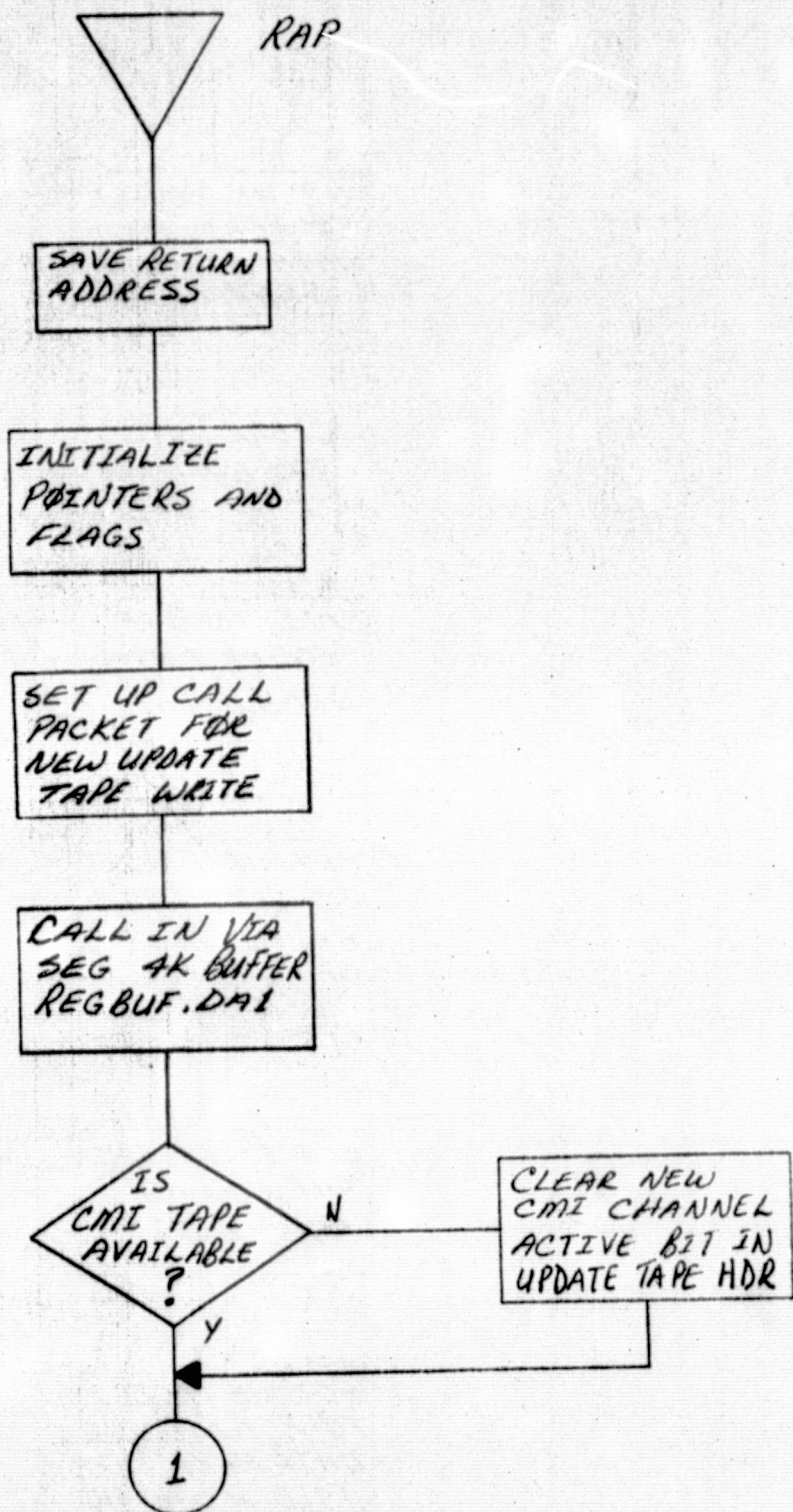
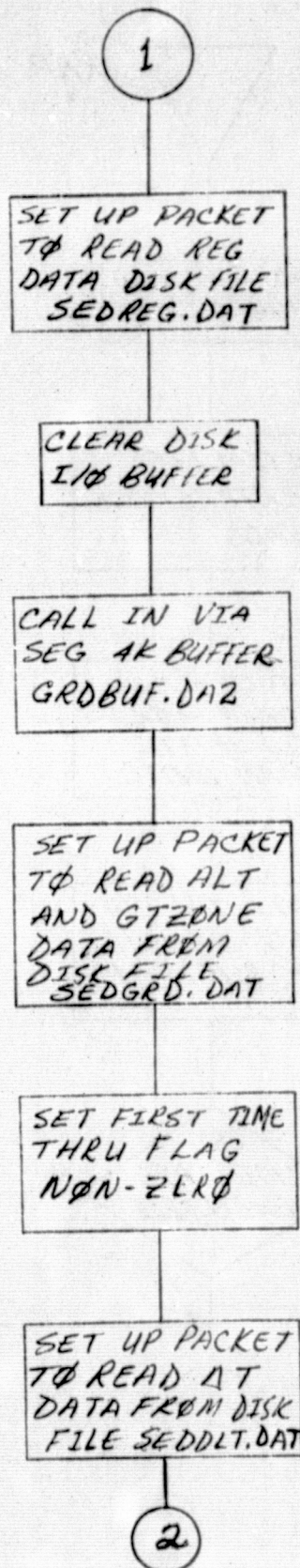


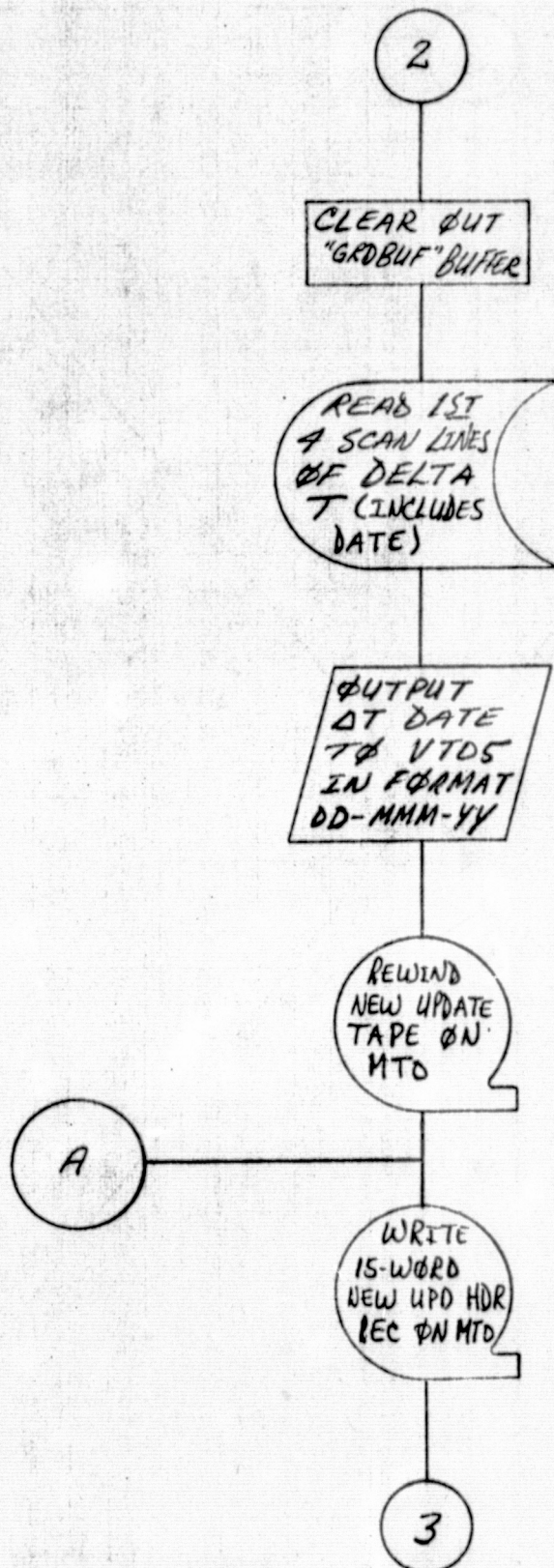
Figure 4-8 RAP Module Core-Resident Buffers

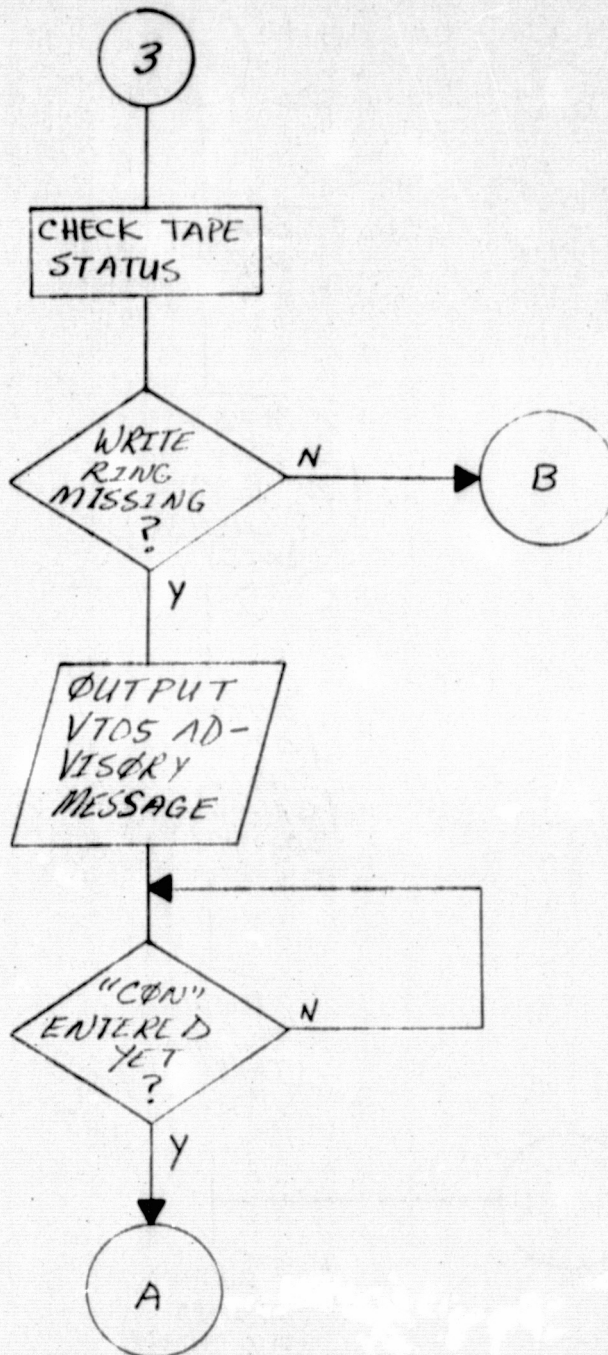




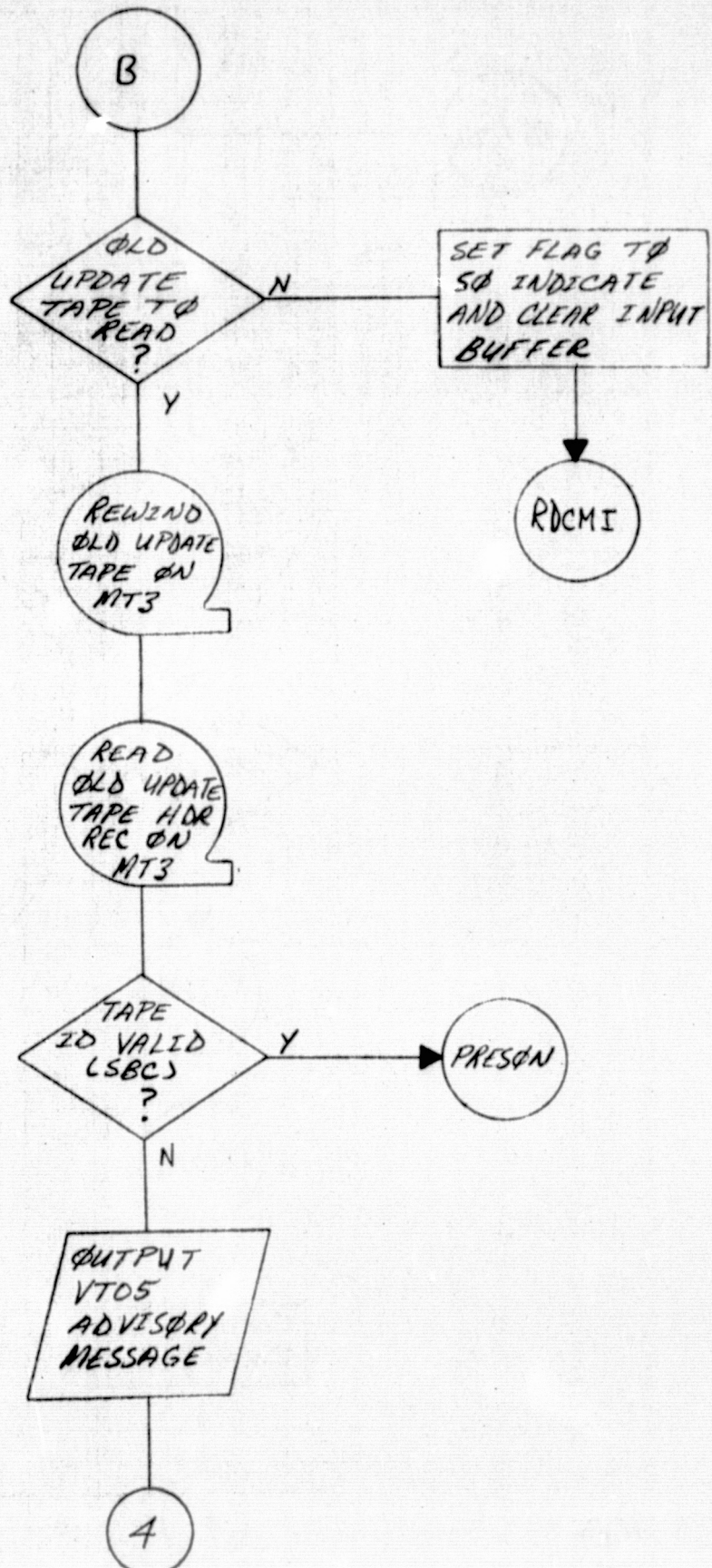
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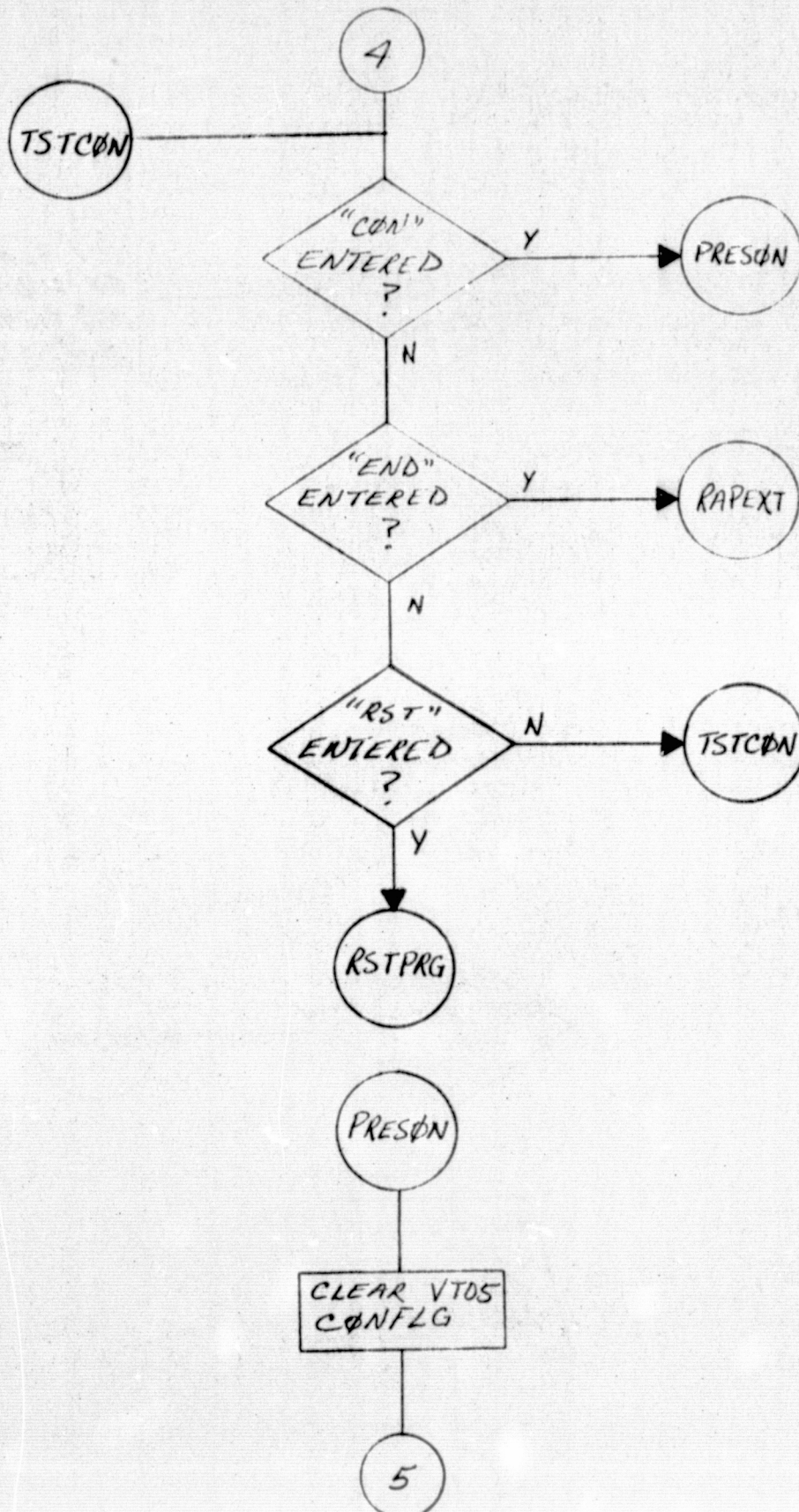


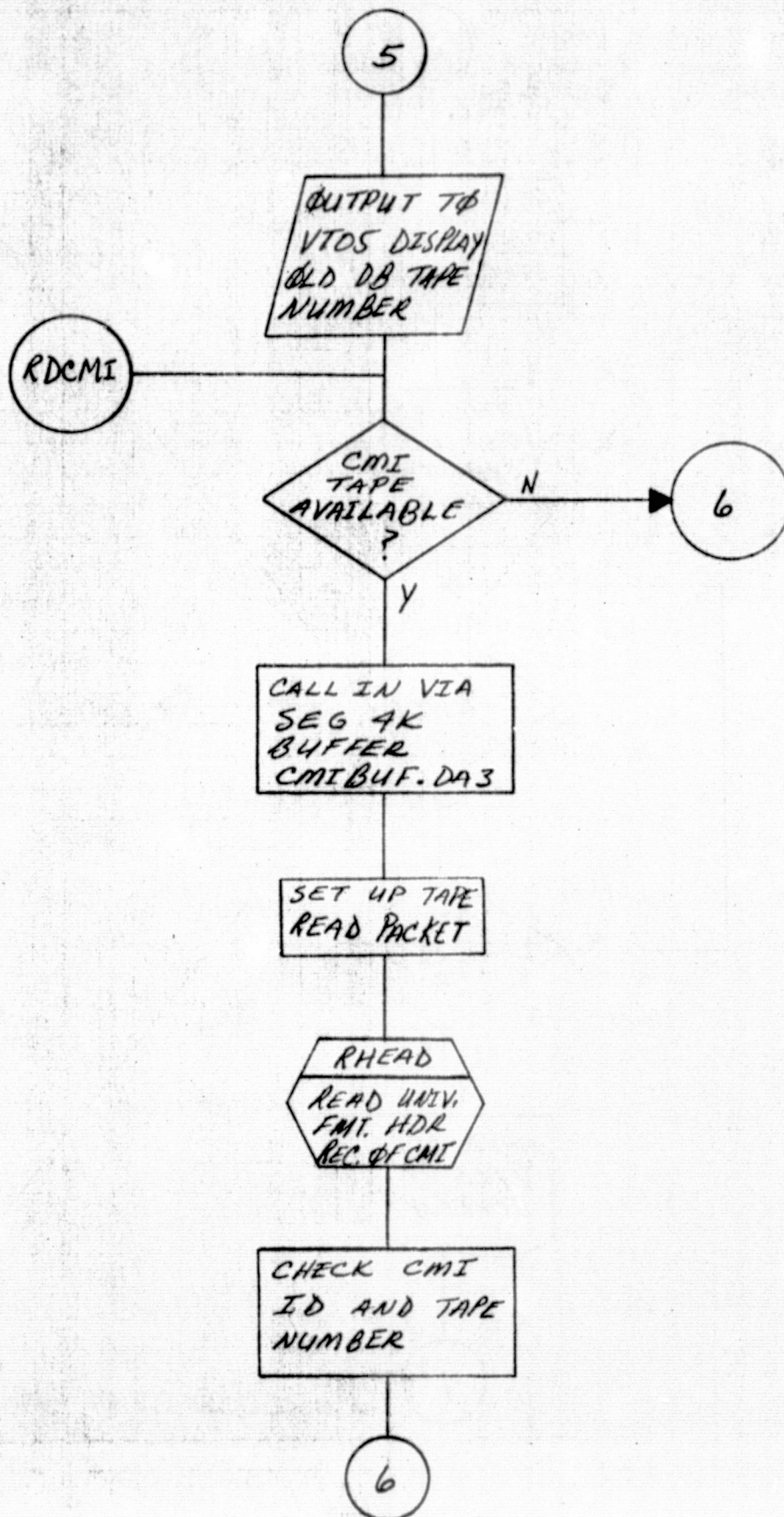


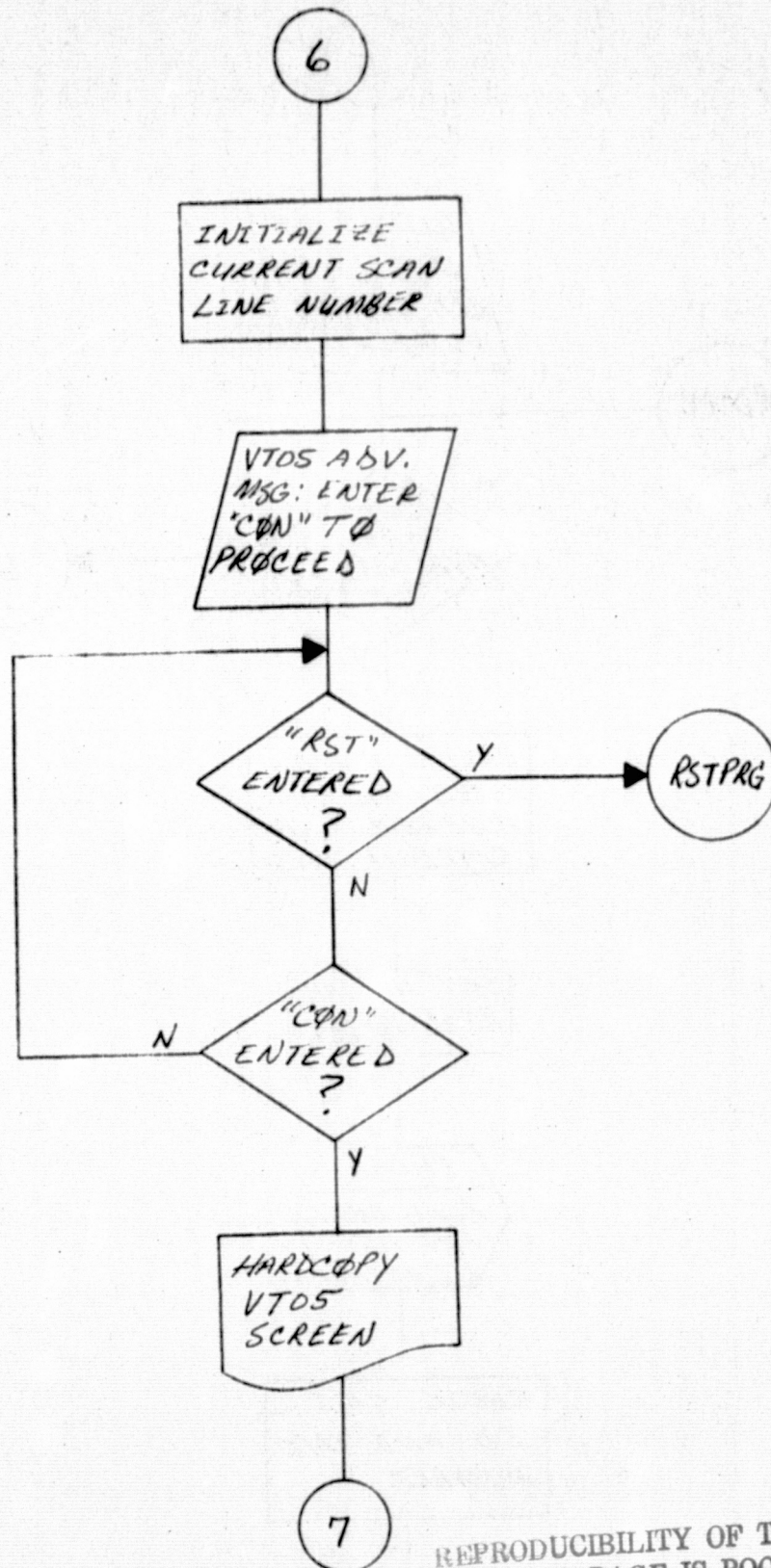


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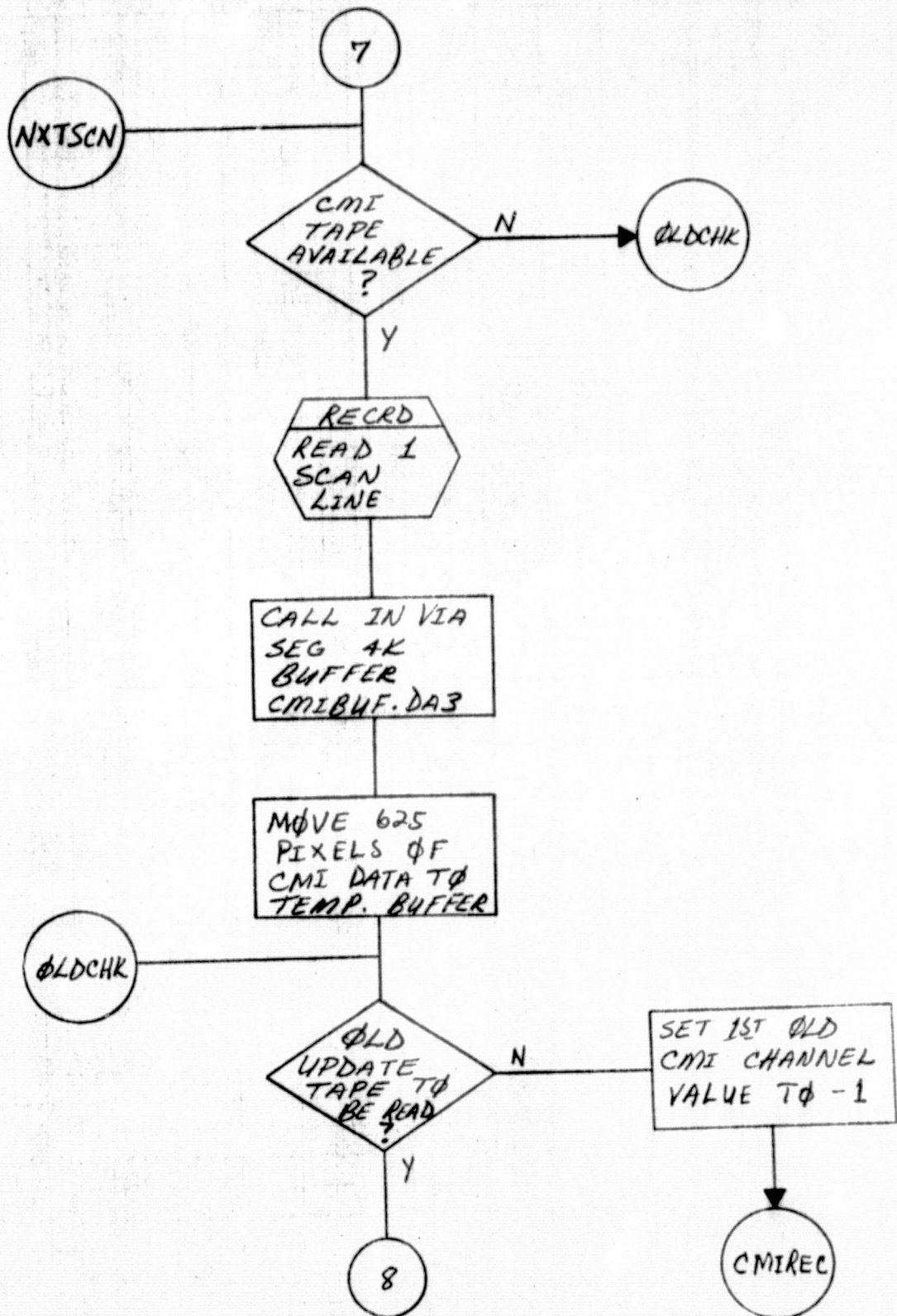


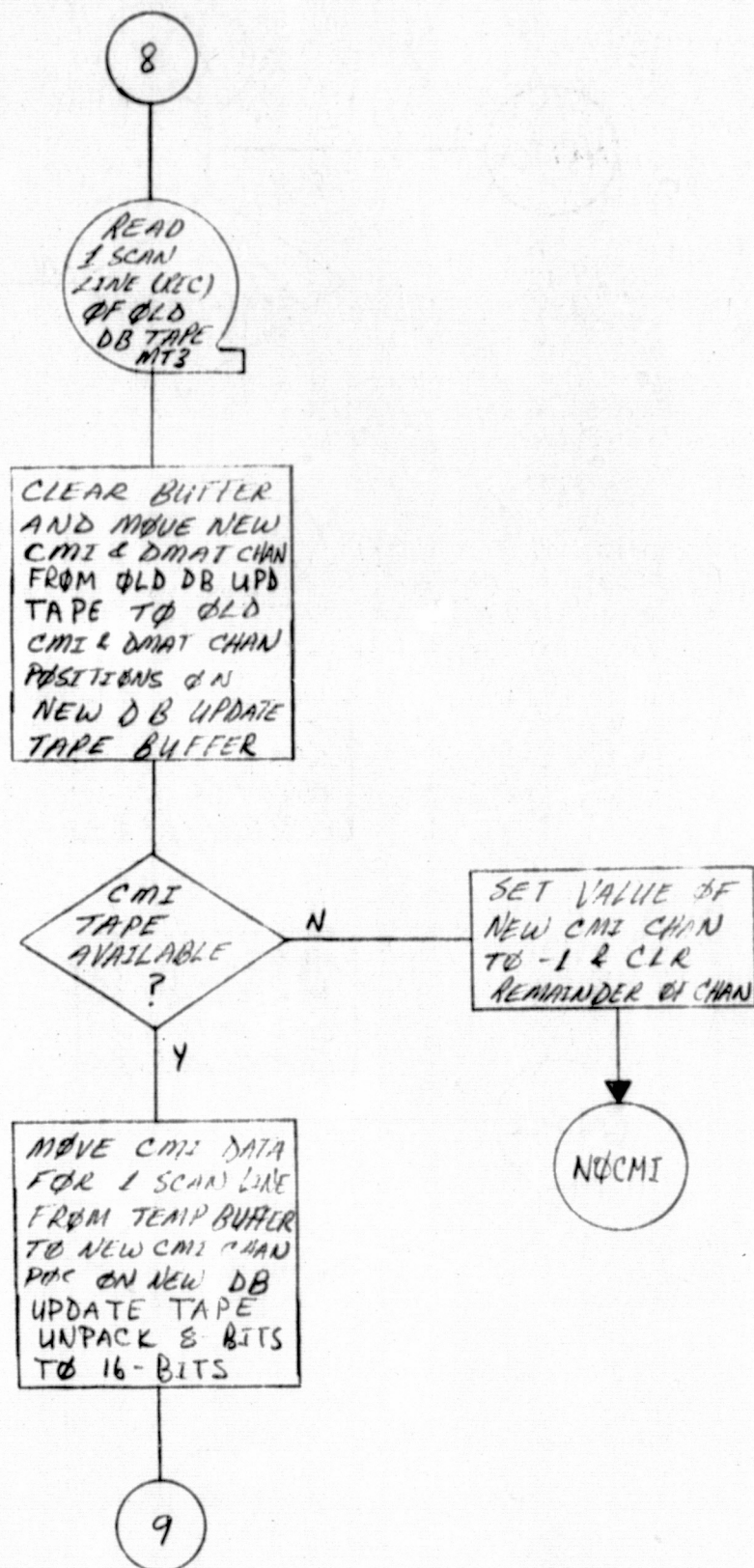




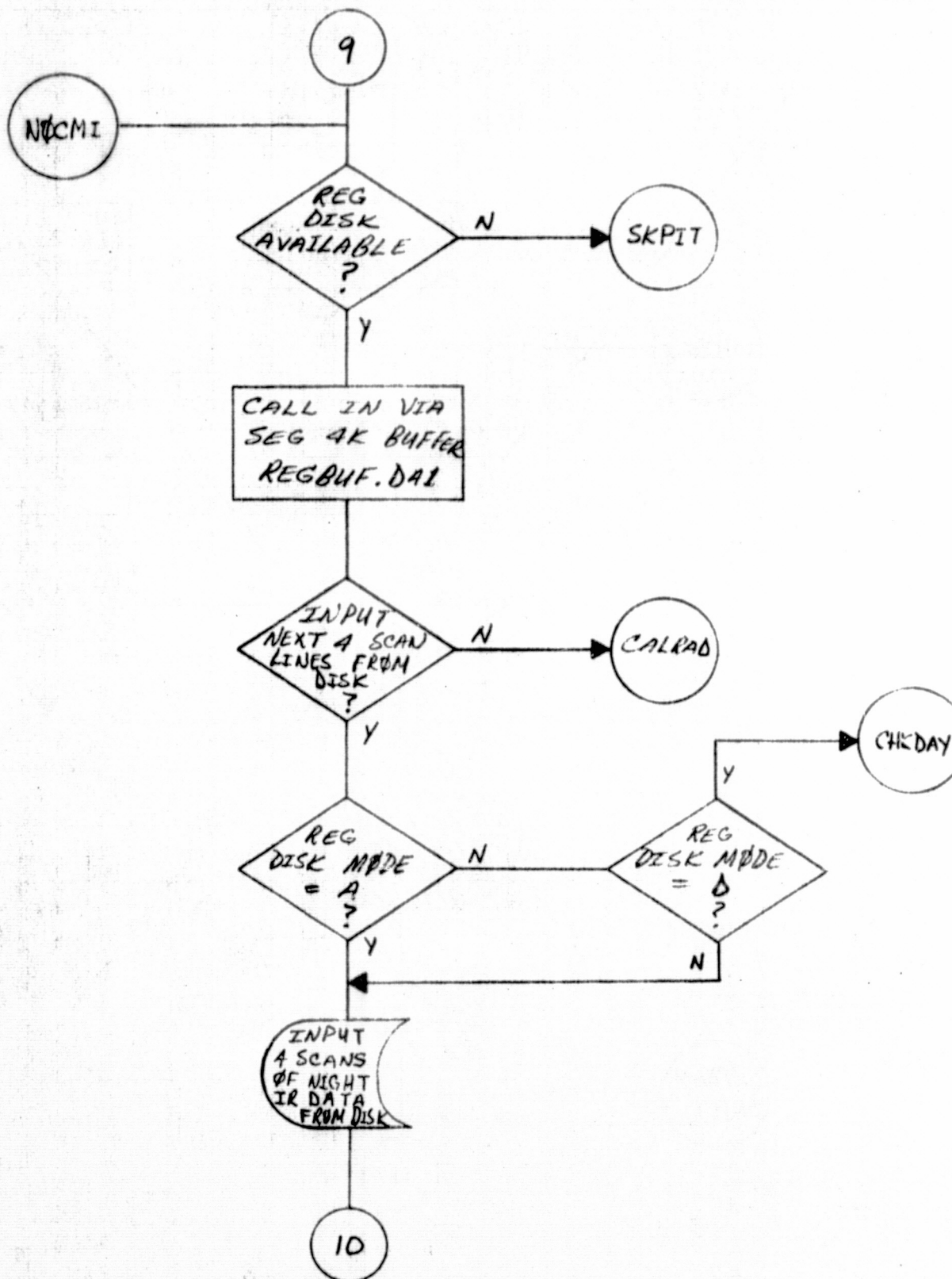


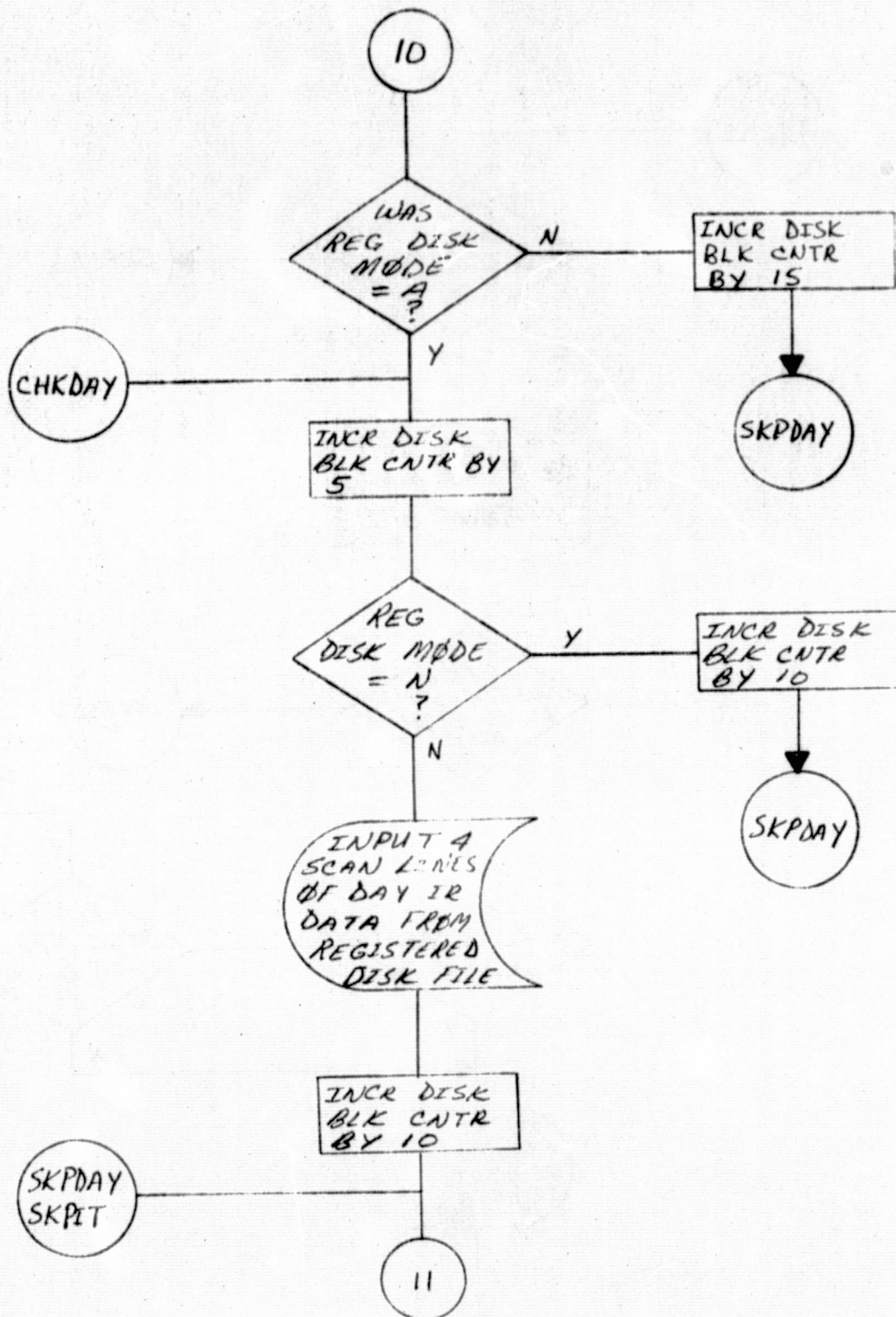
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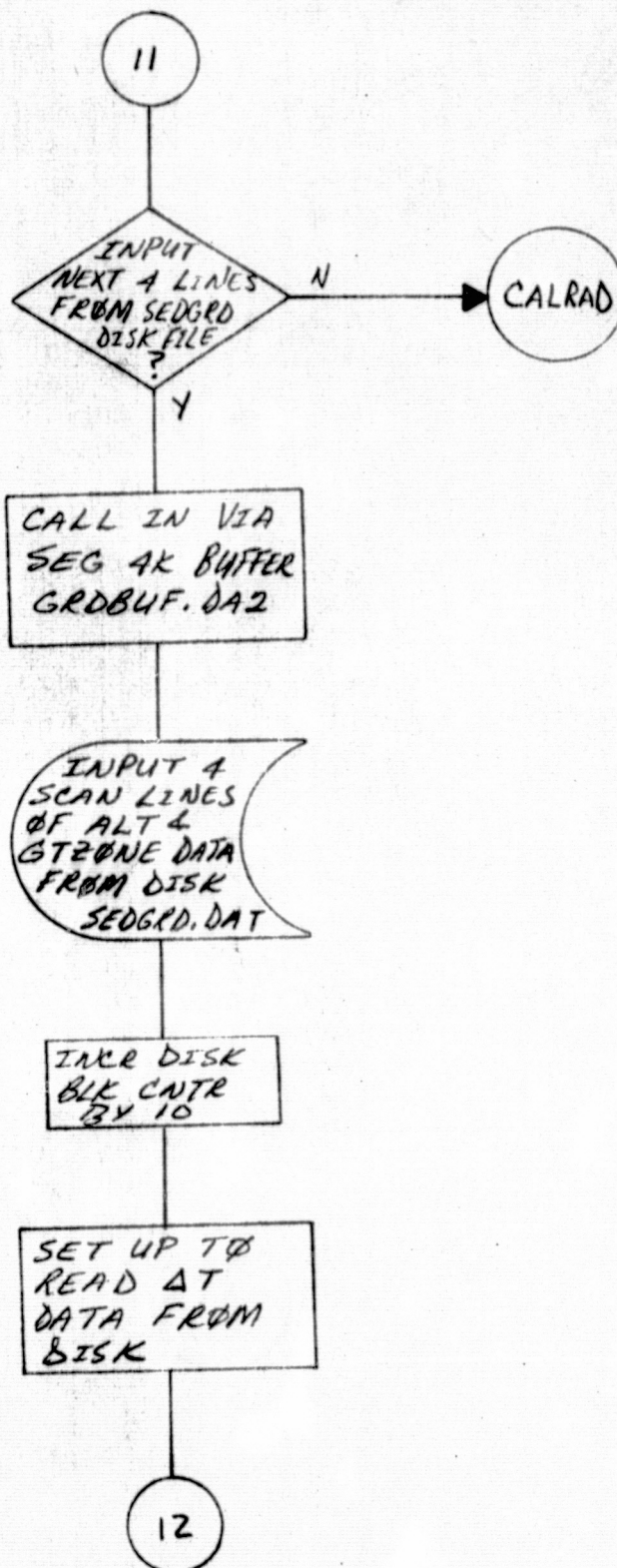


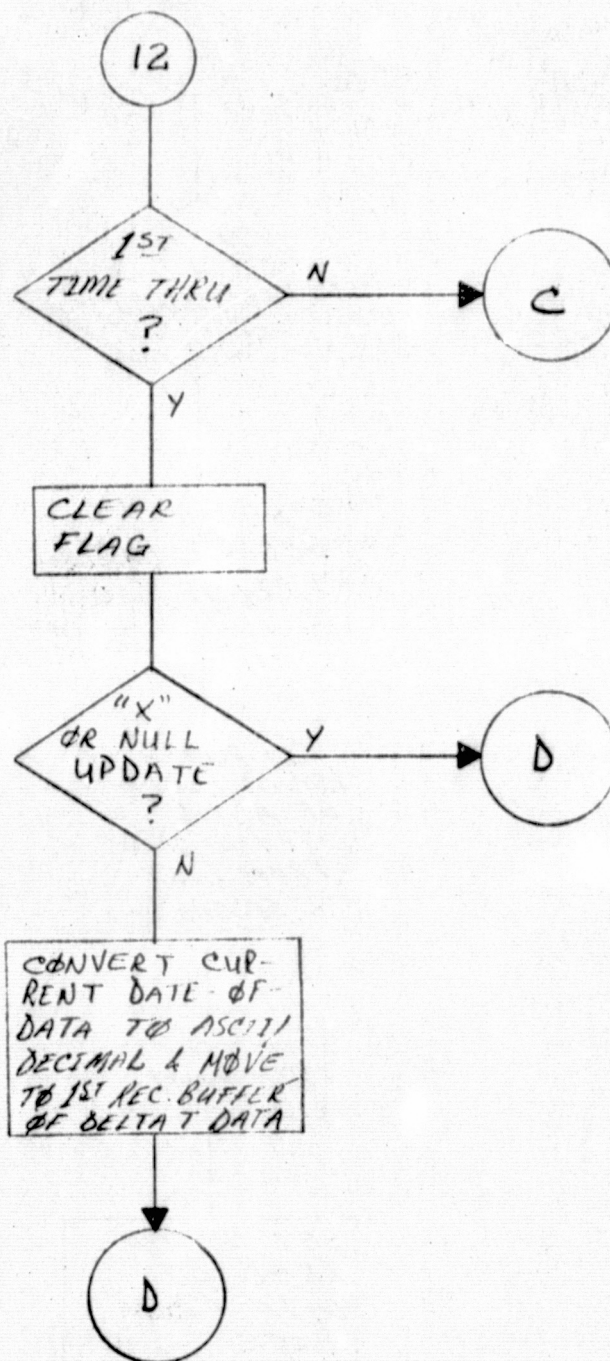


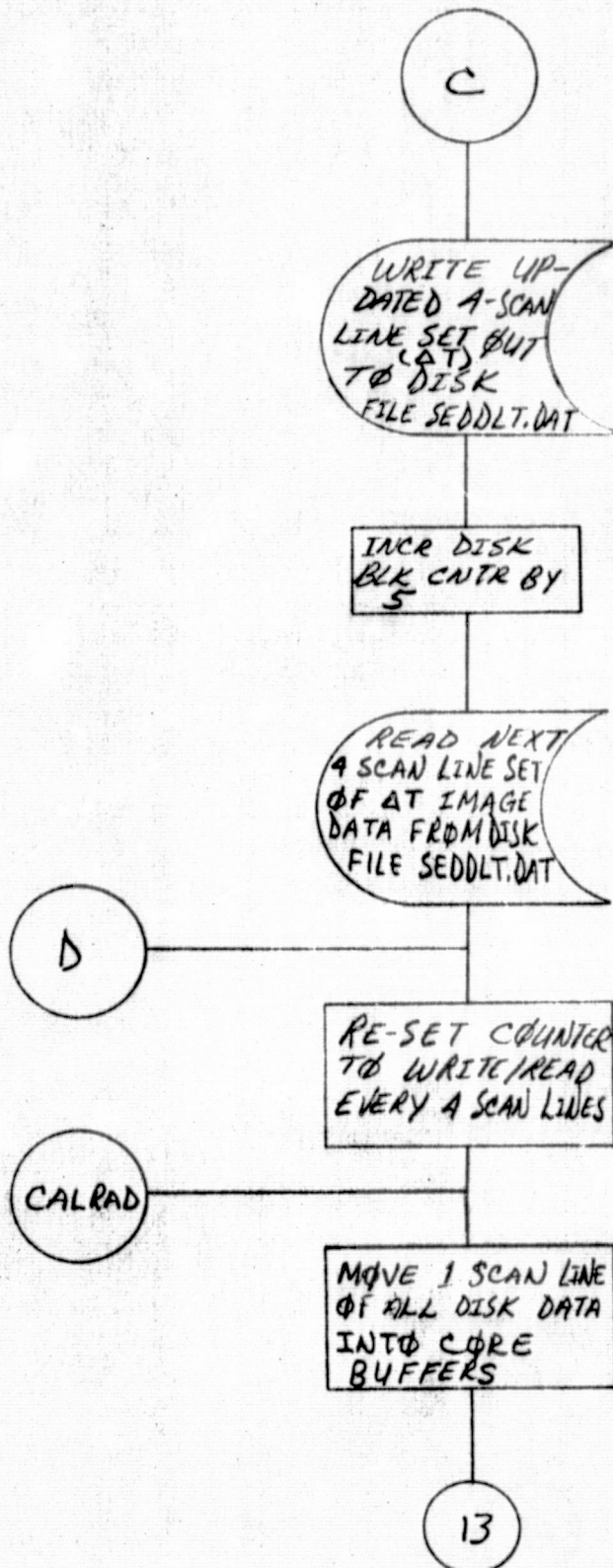
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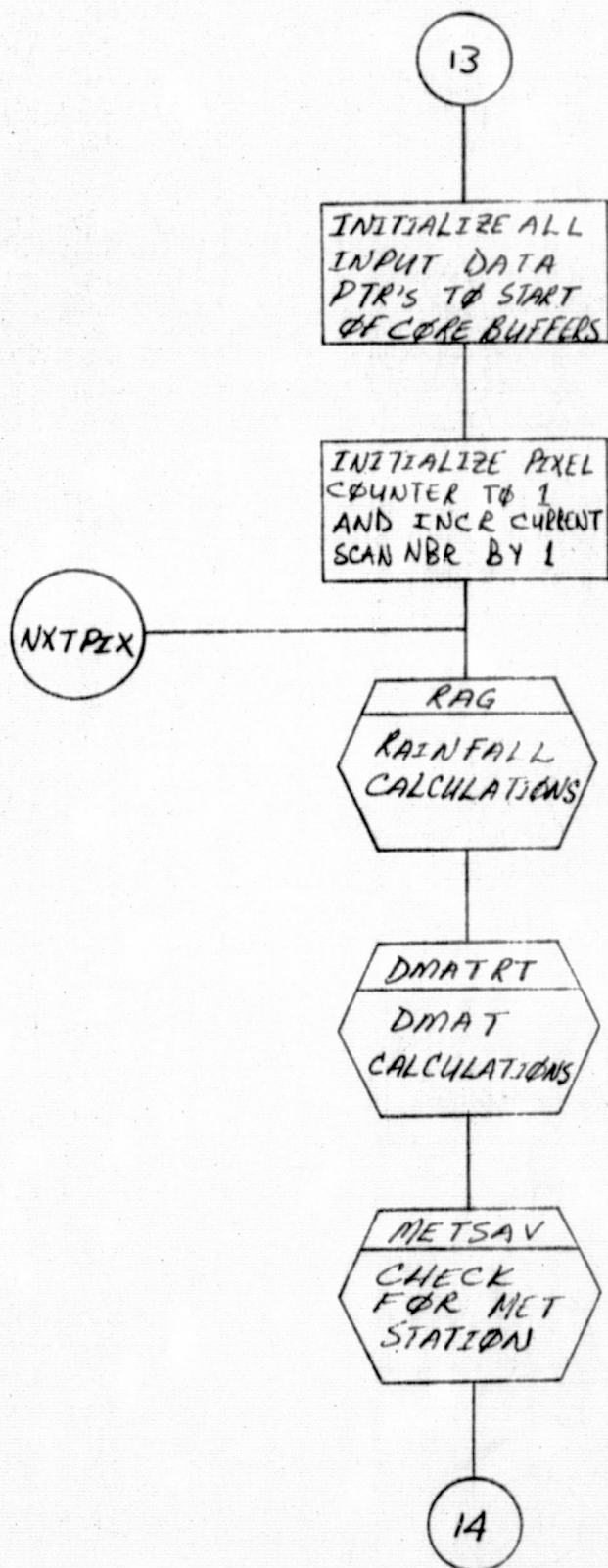


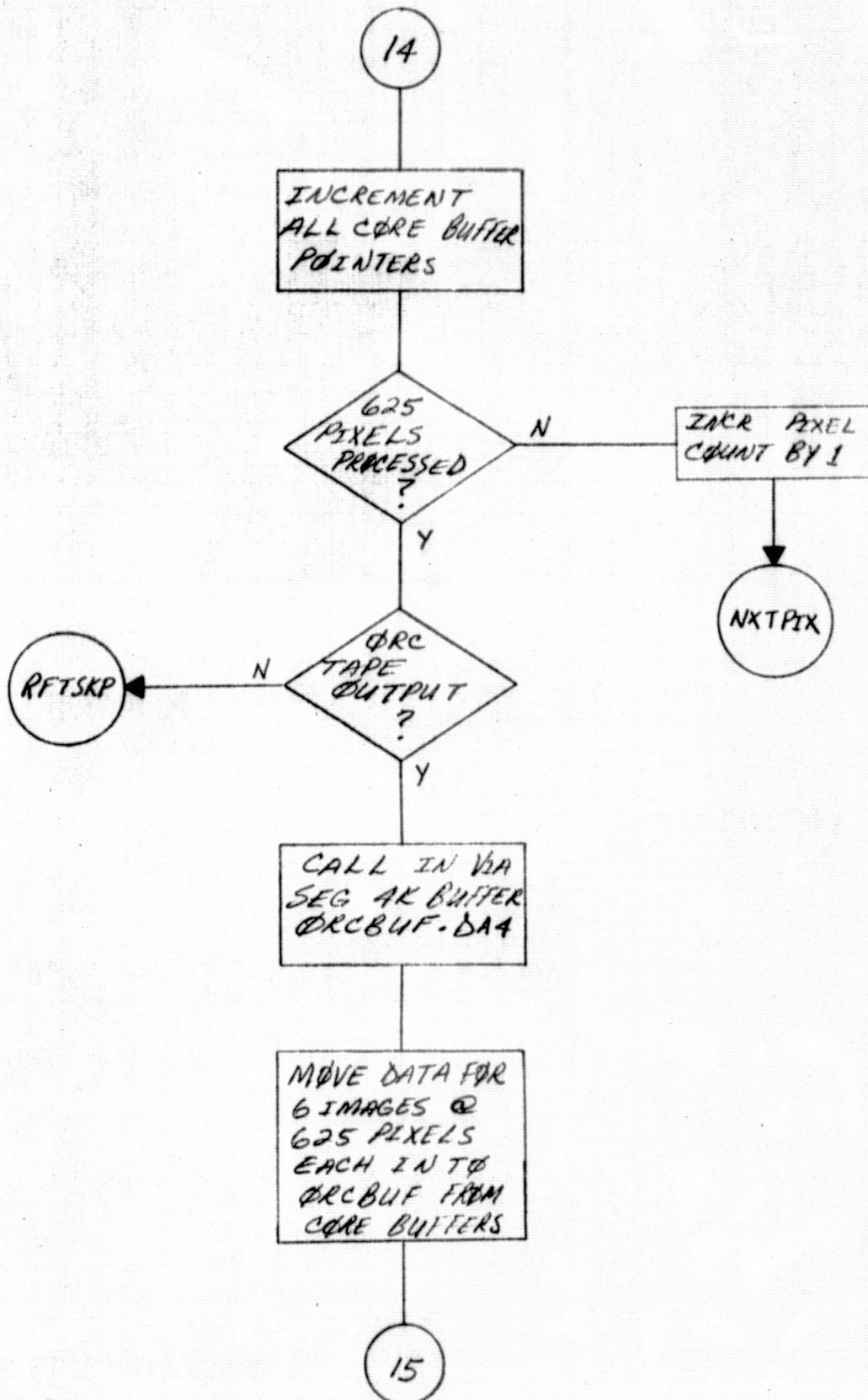


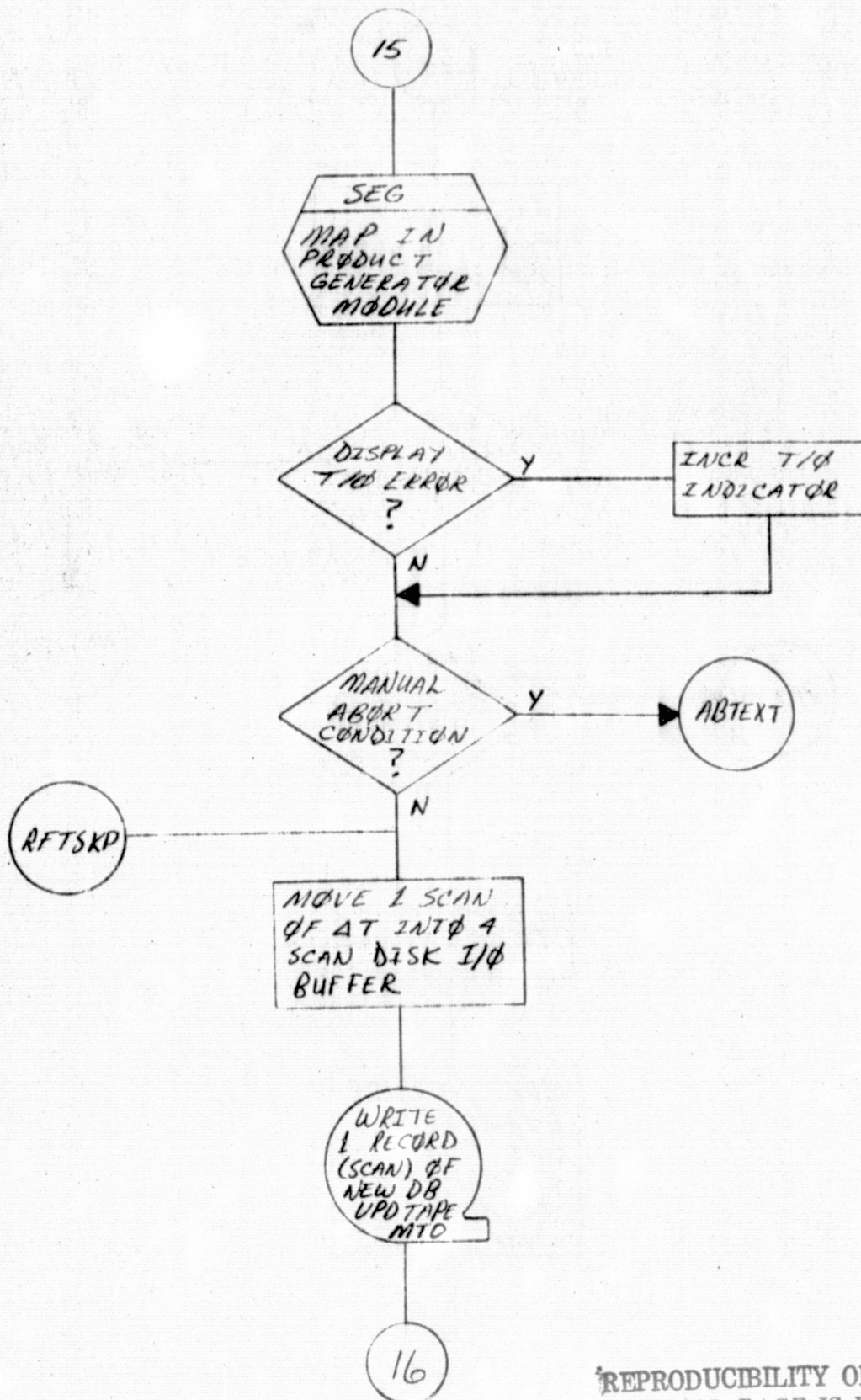




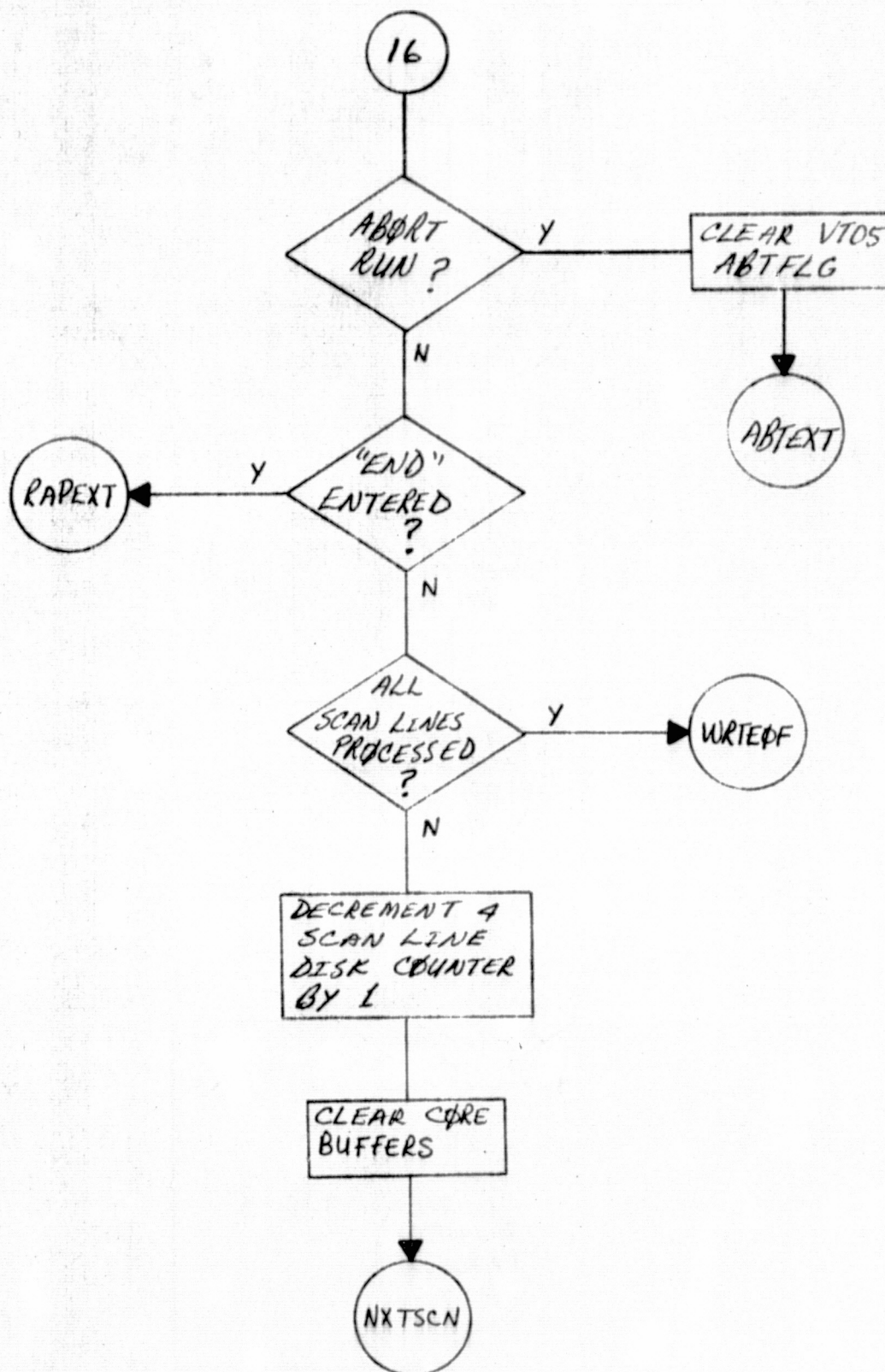


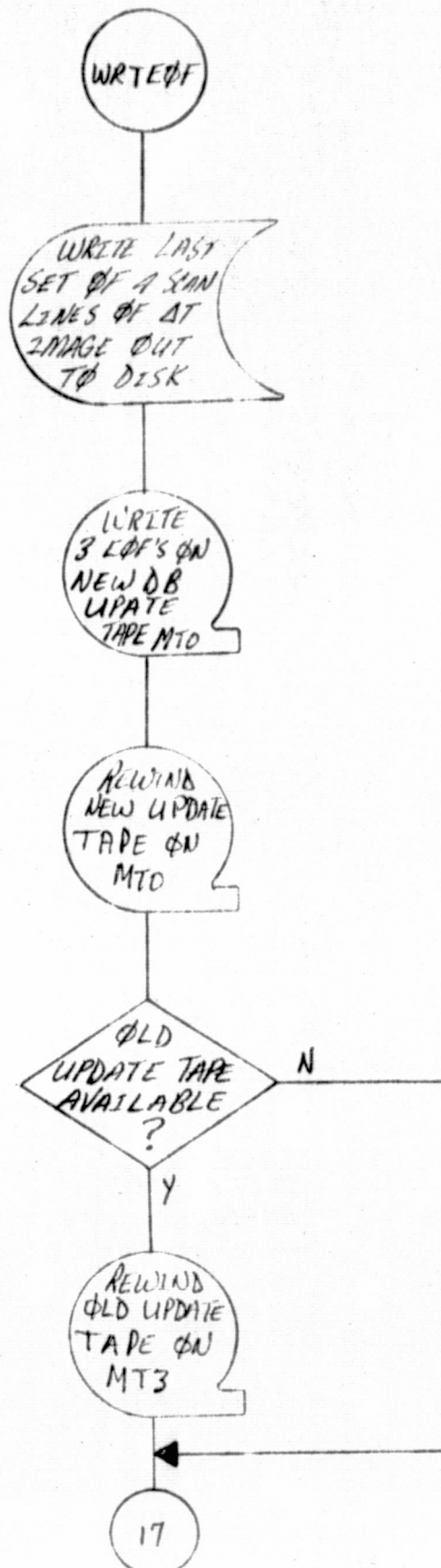


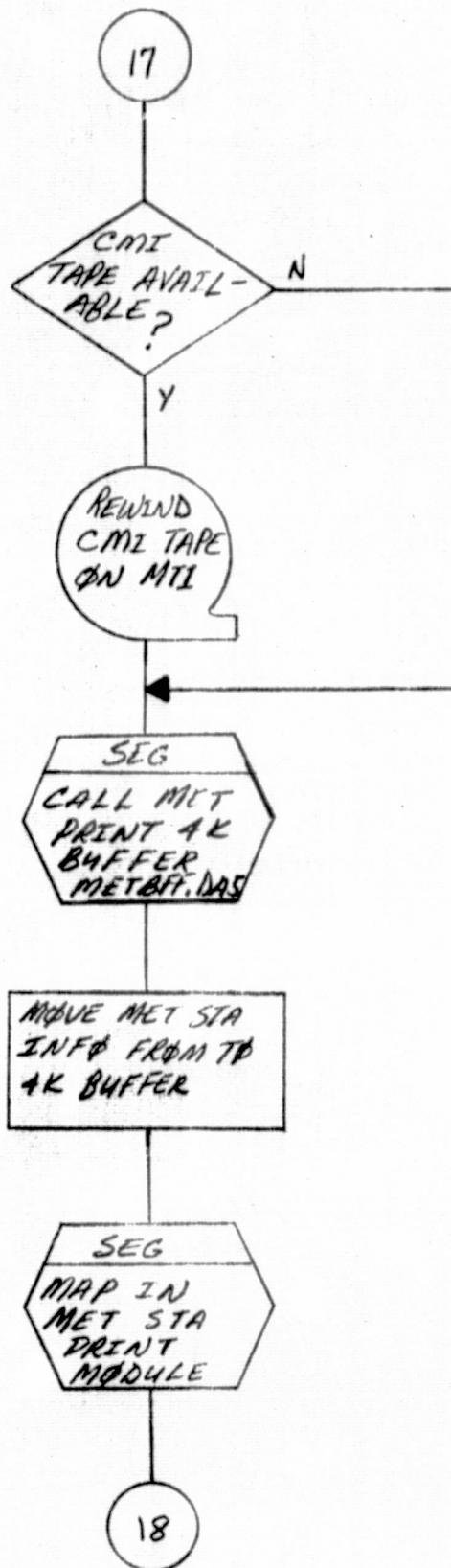


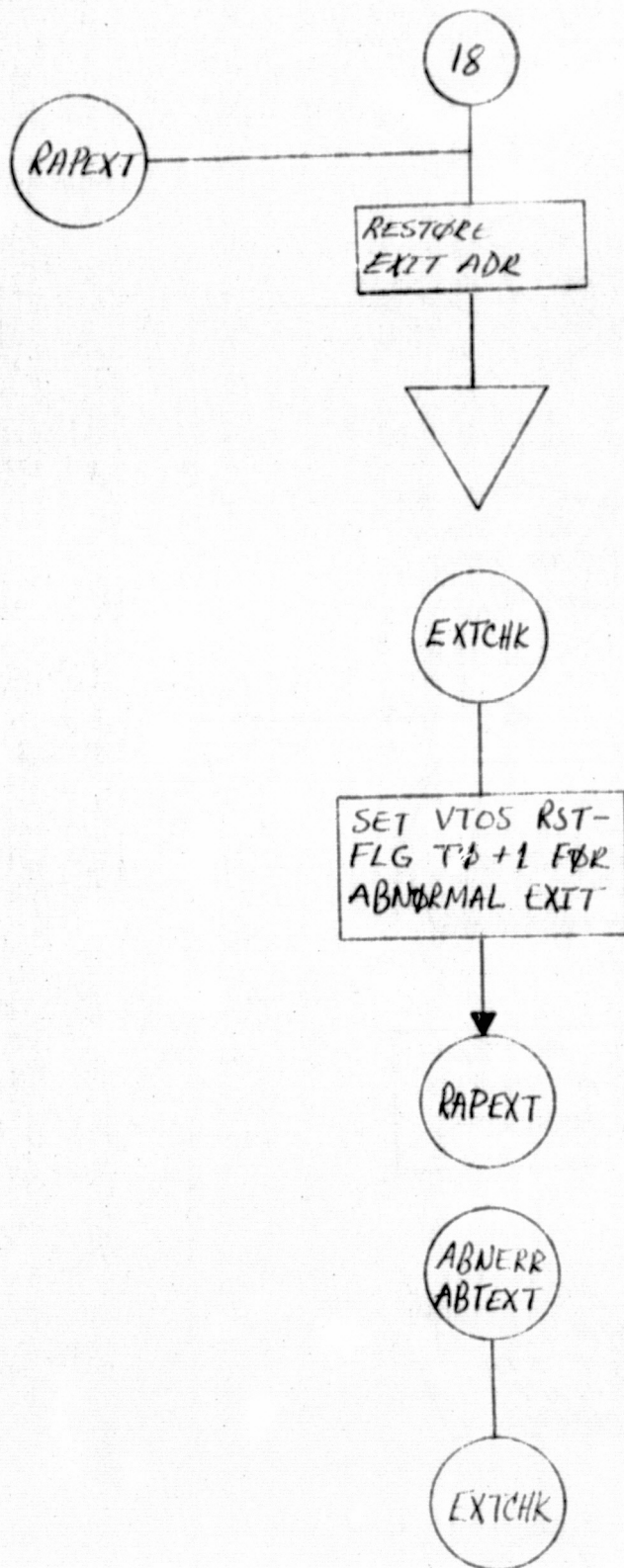


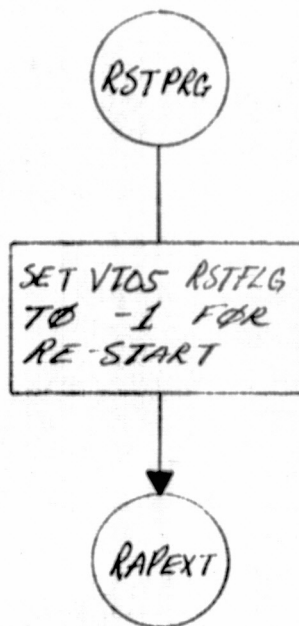
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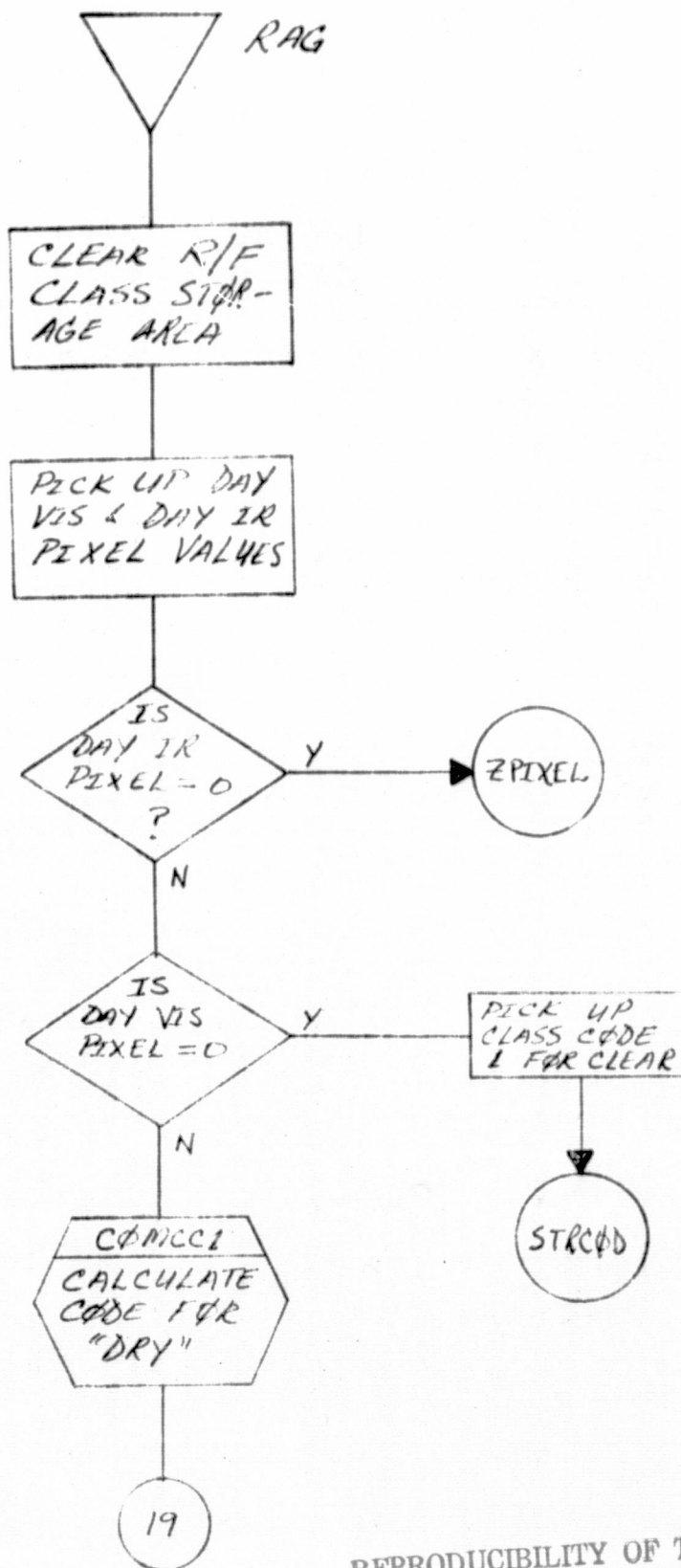




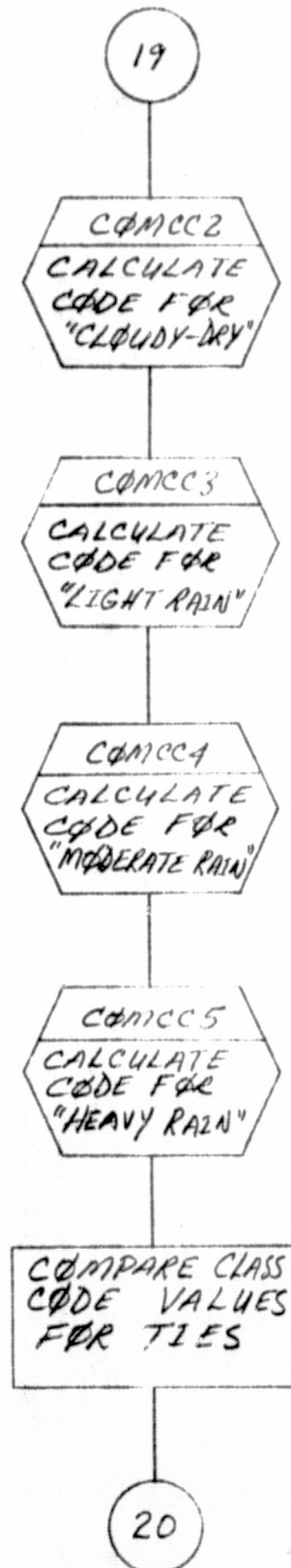


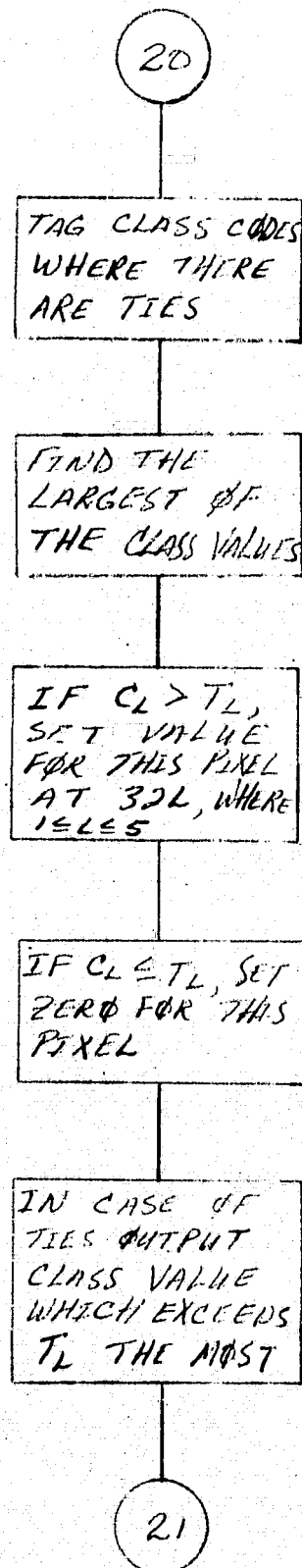


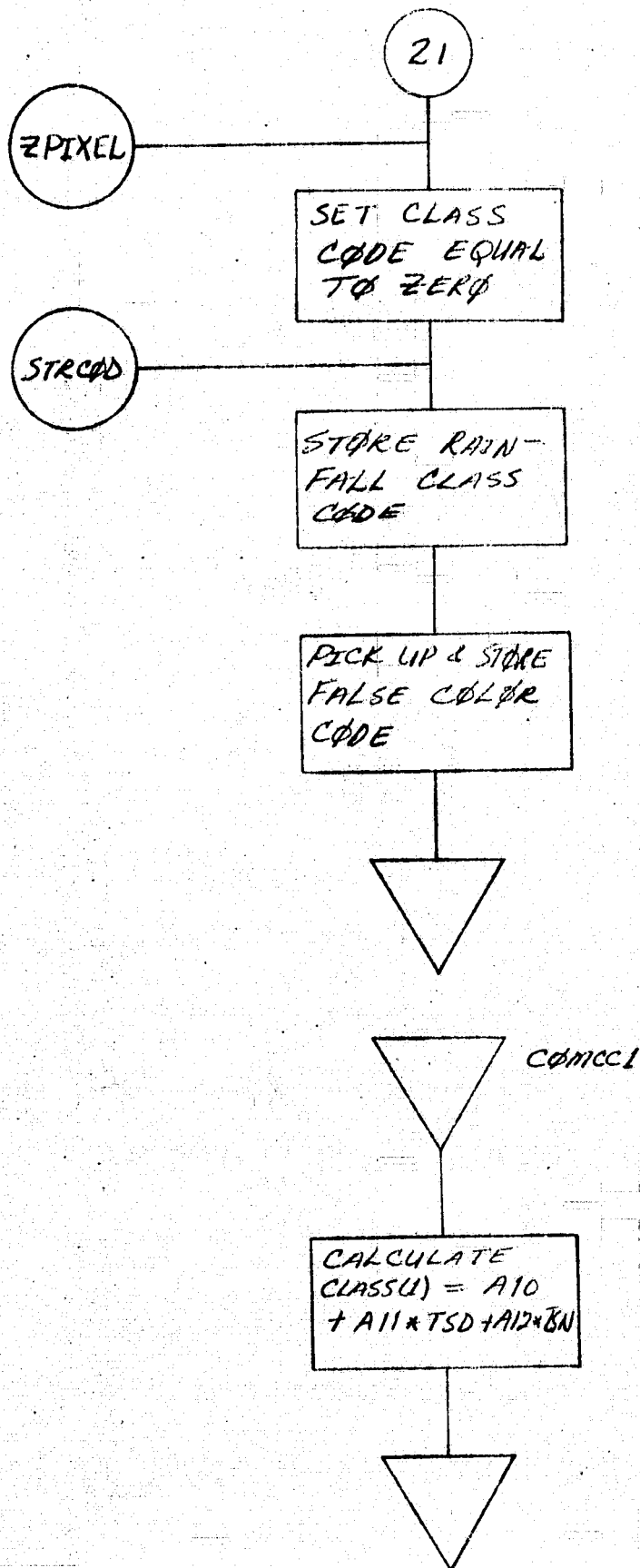


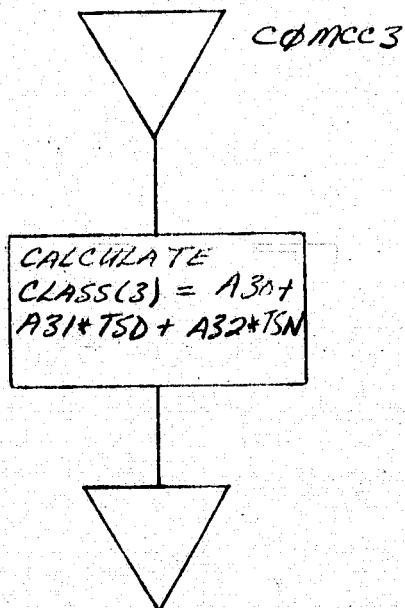
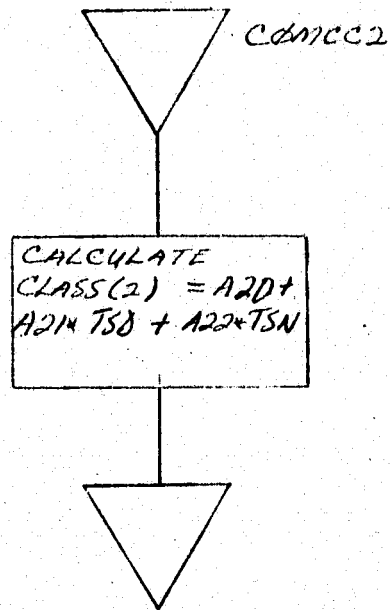


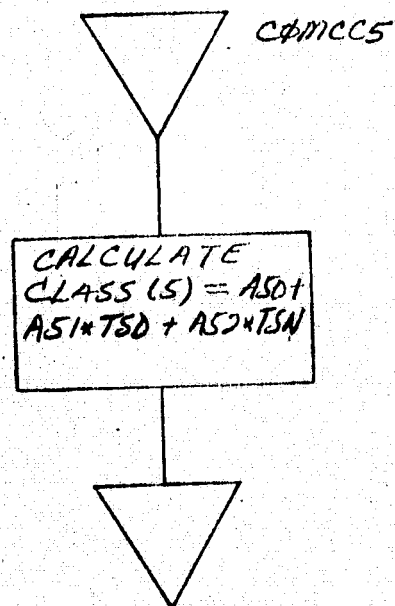
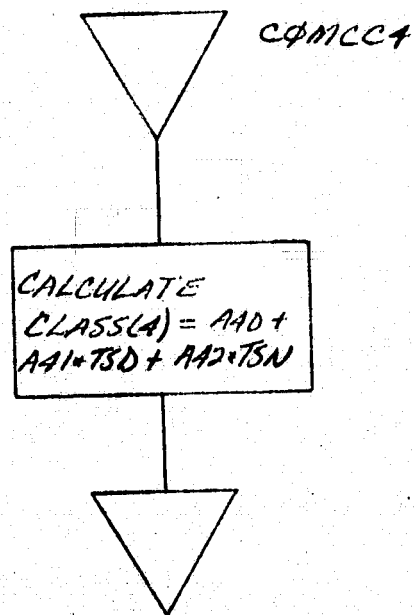
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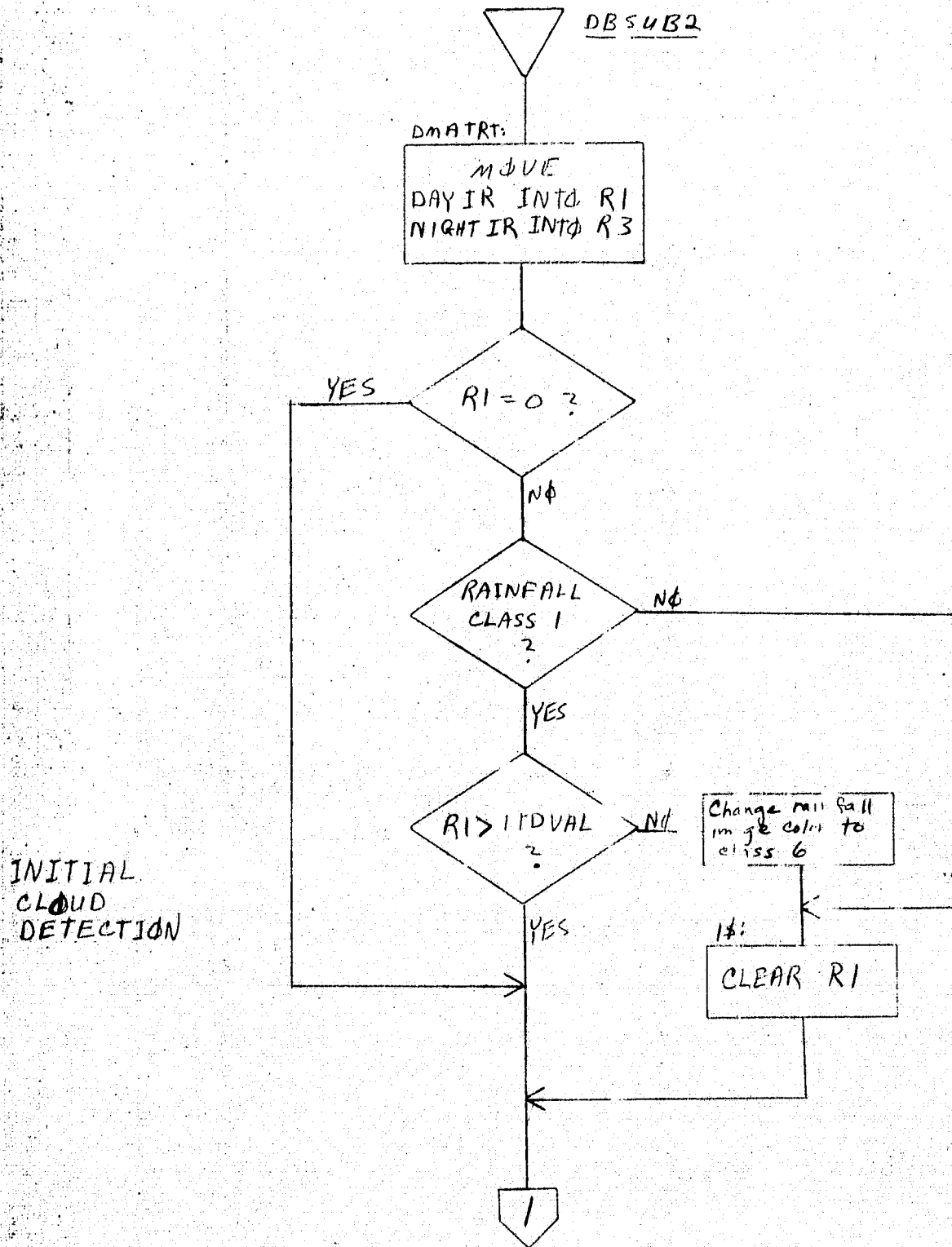




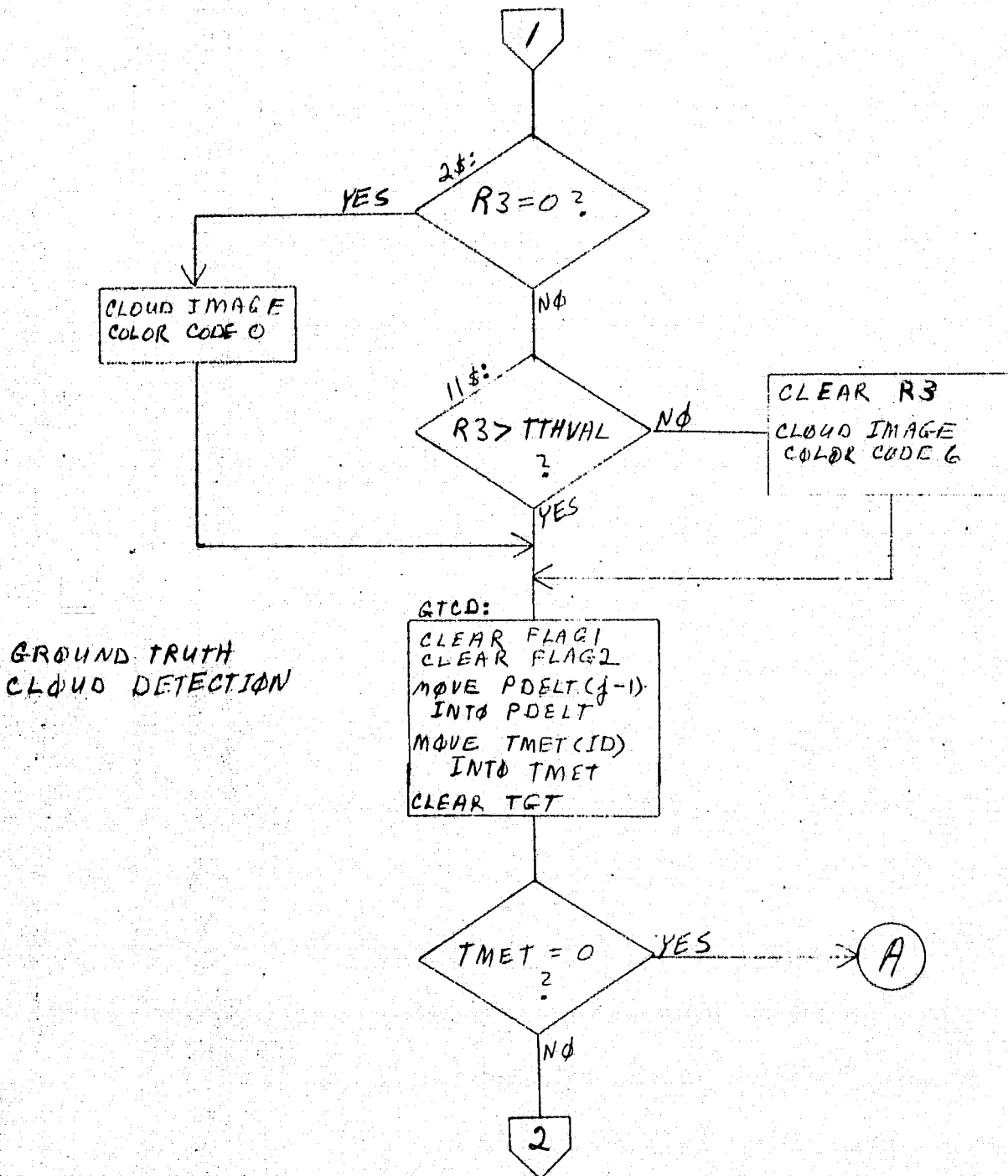


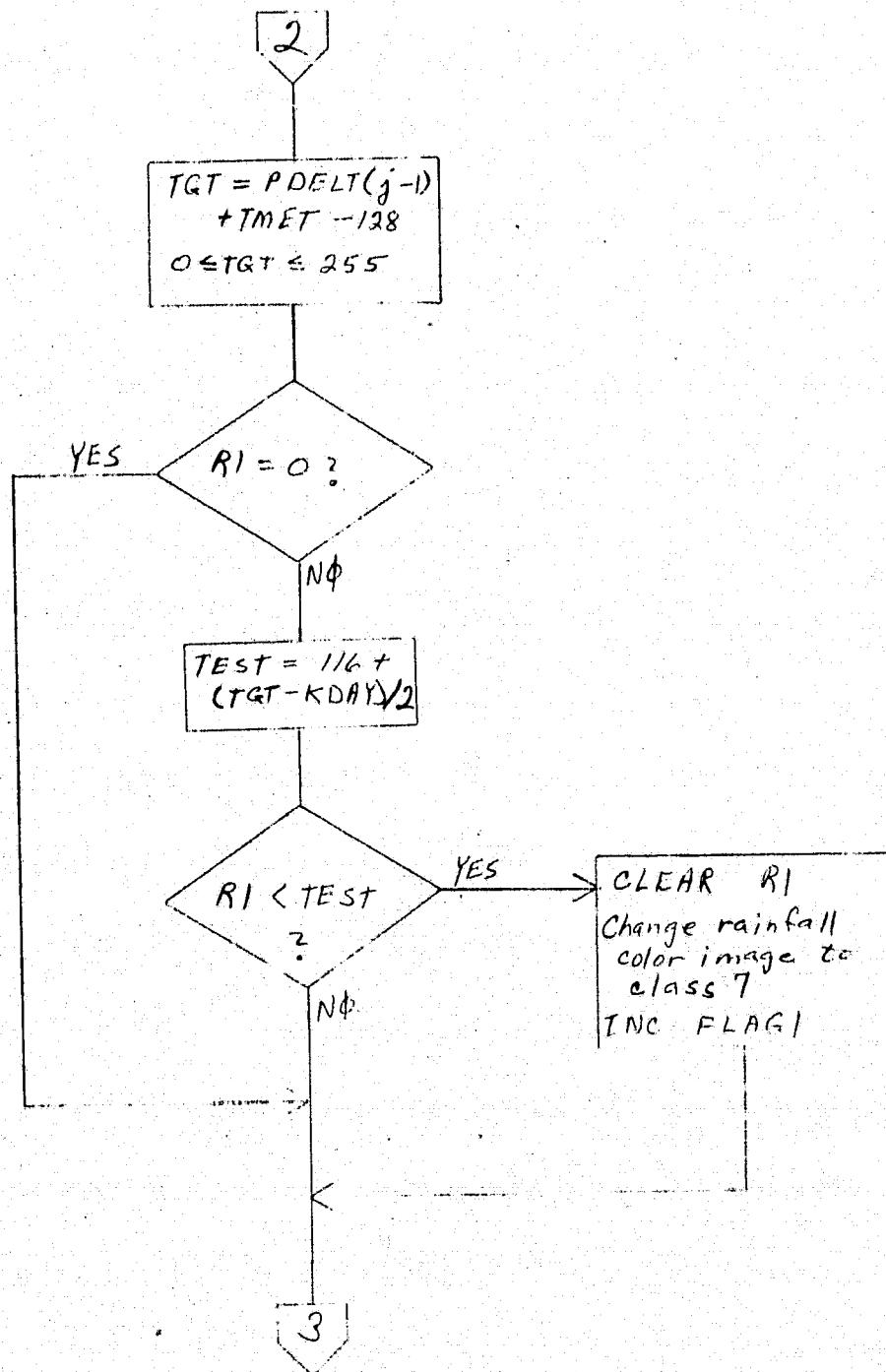


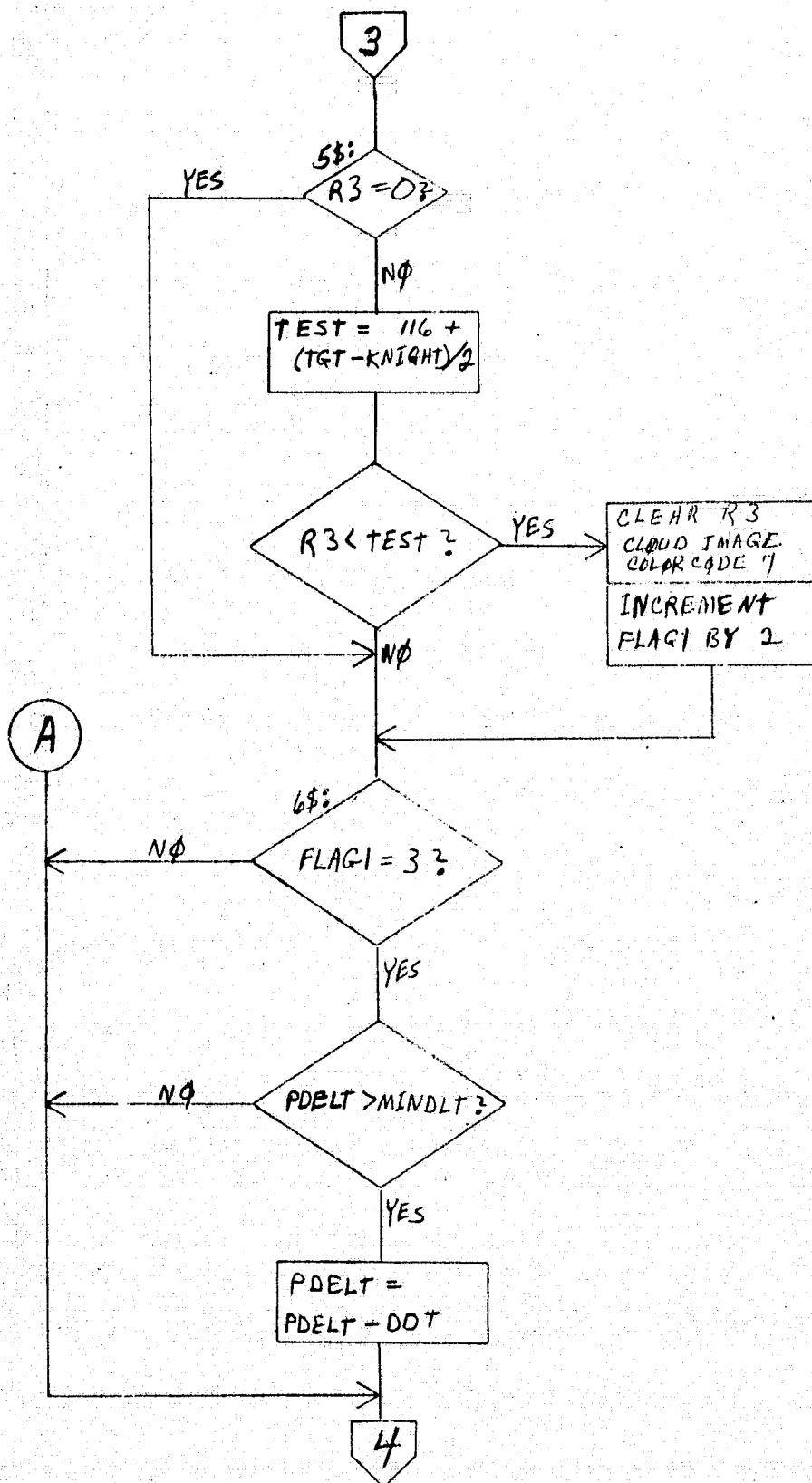




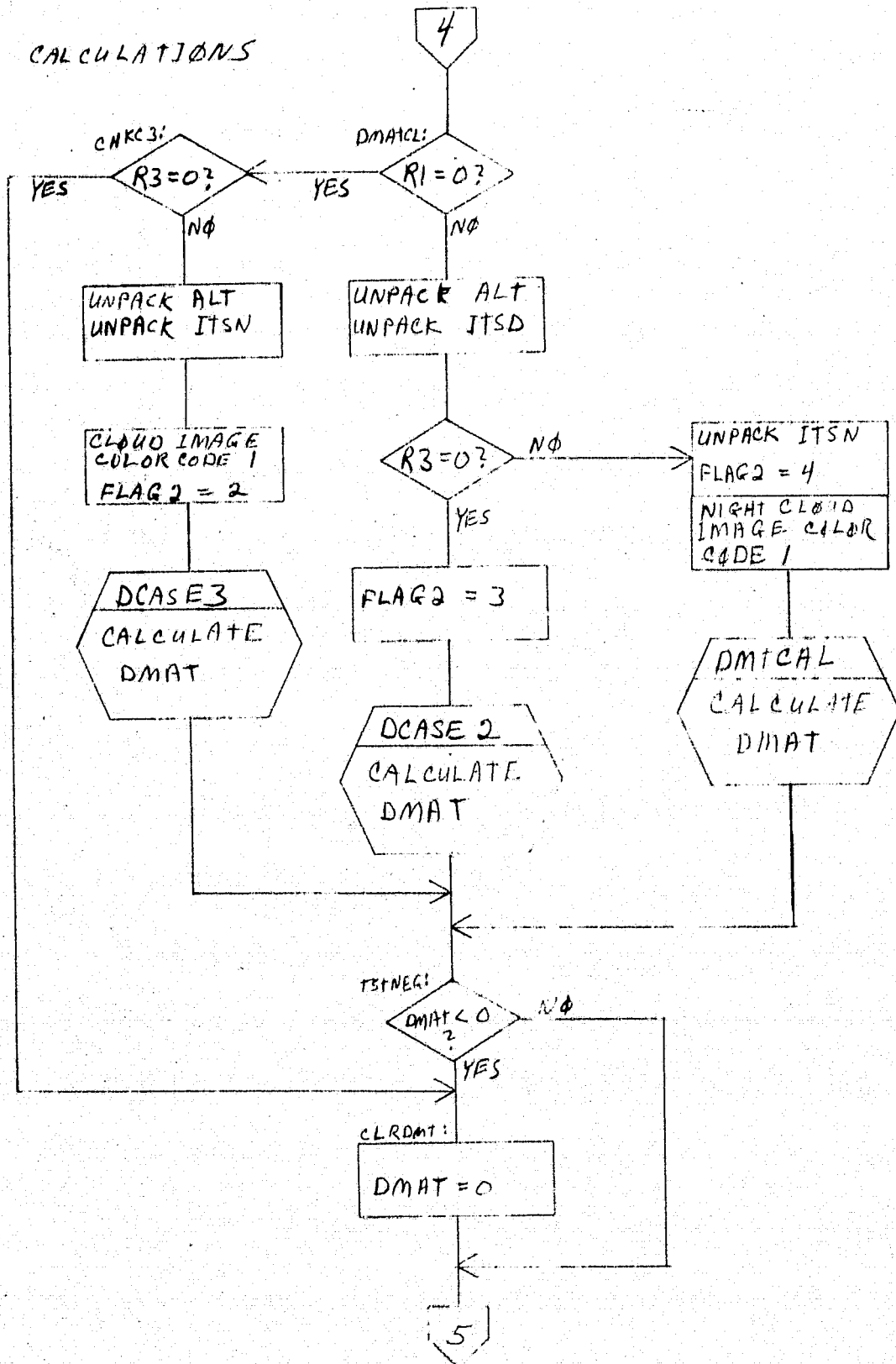
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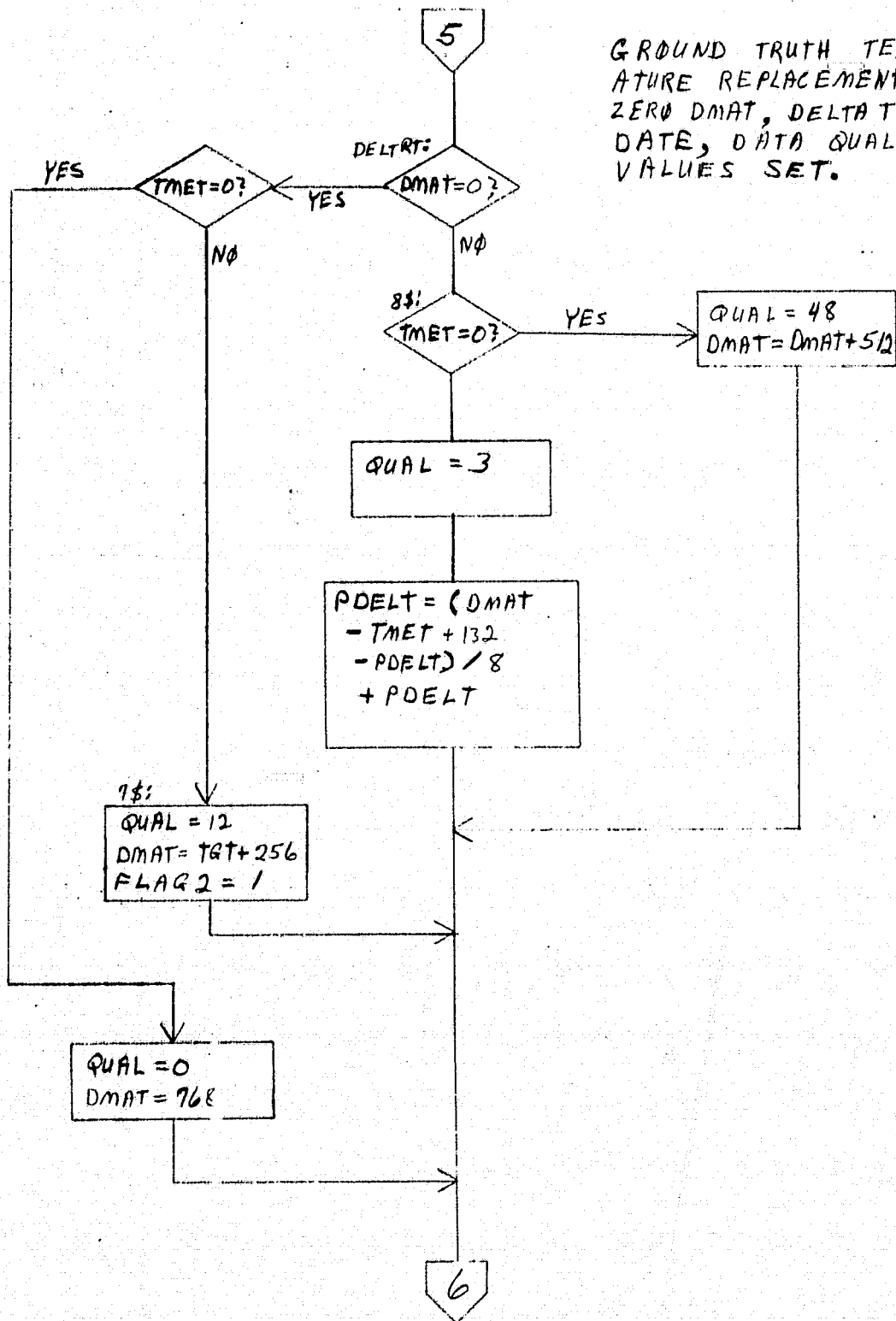


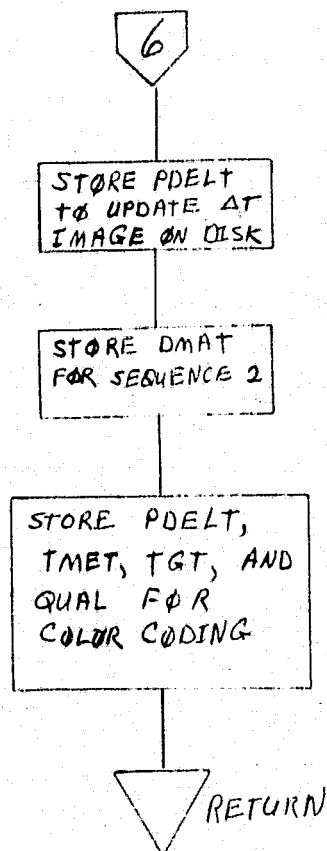


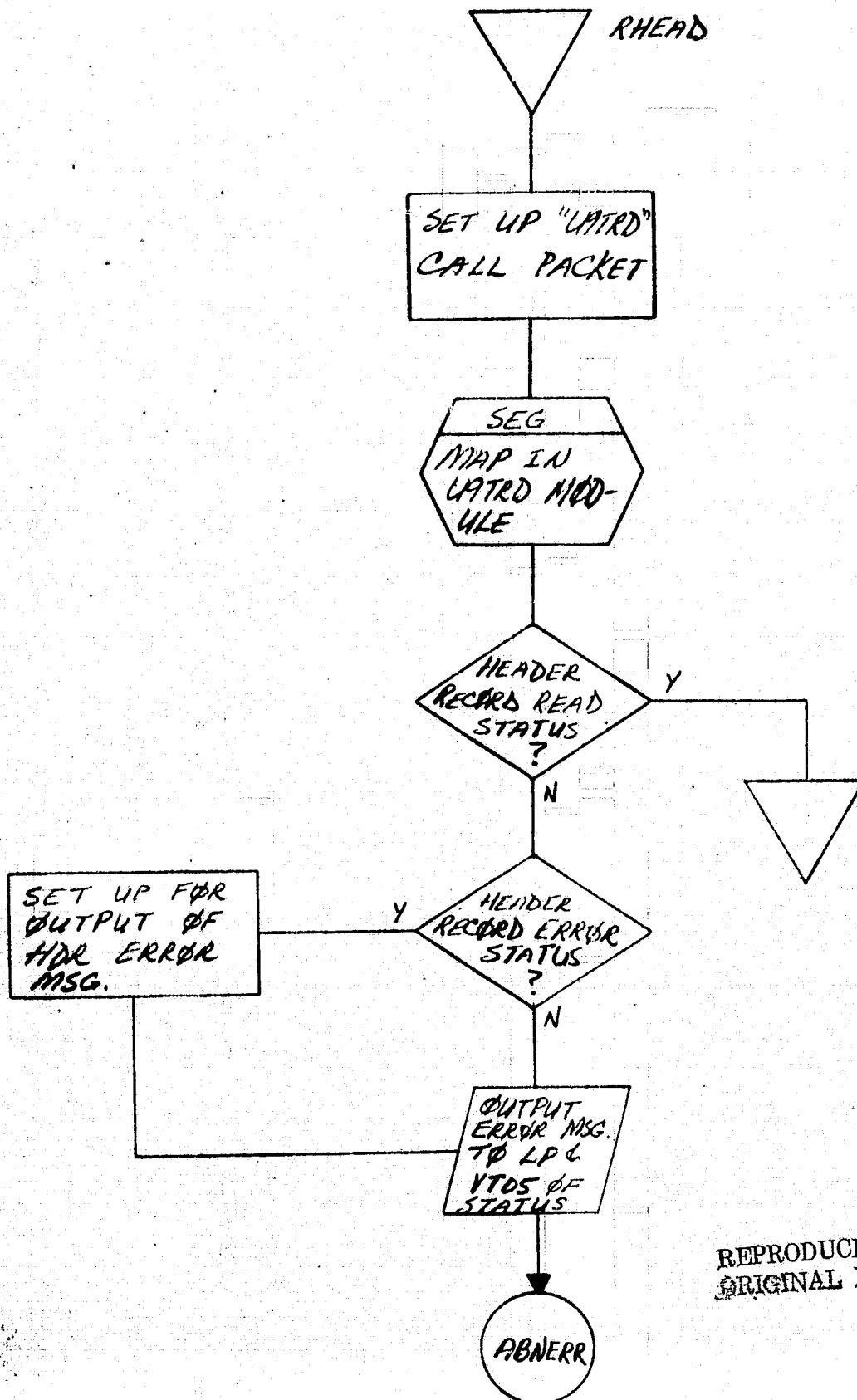


DMAT CALCULATIONS

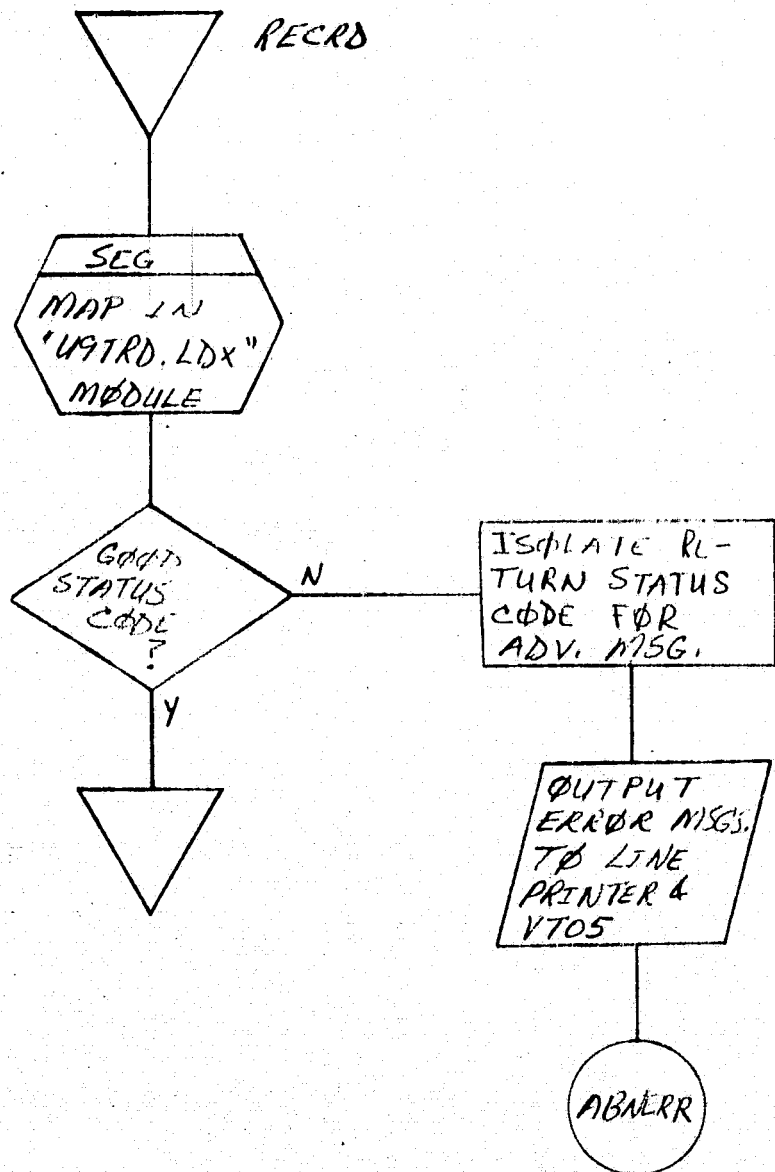


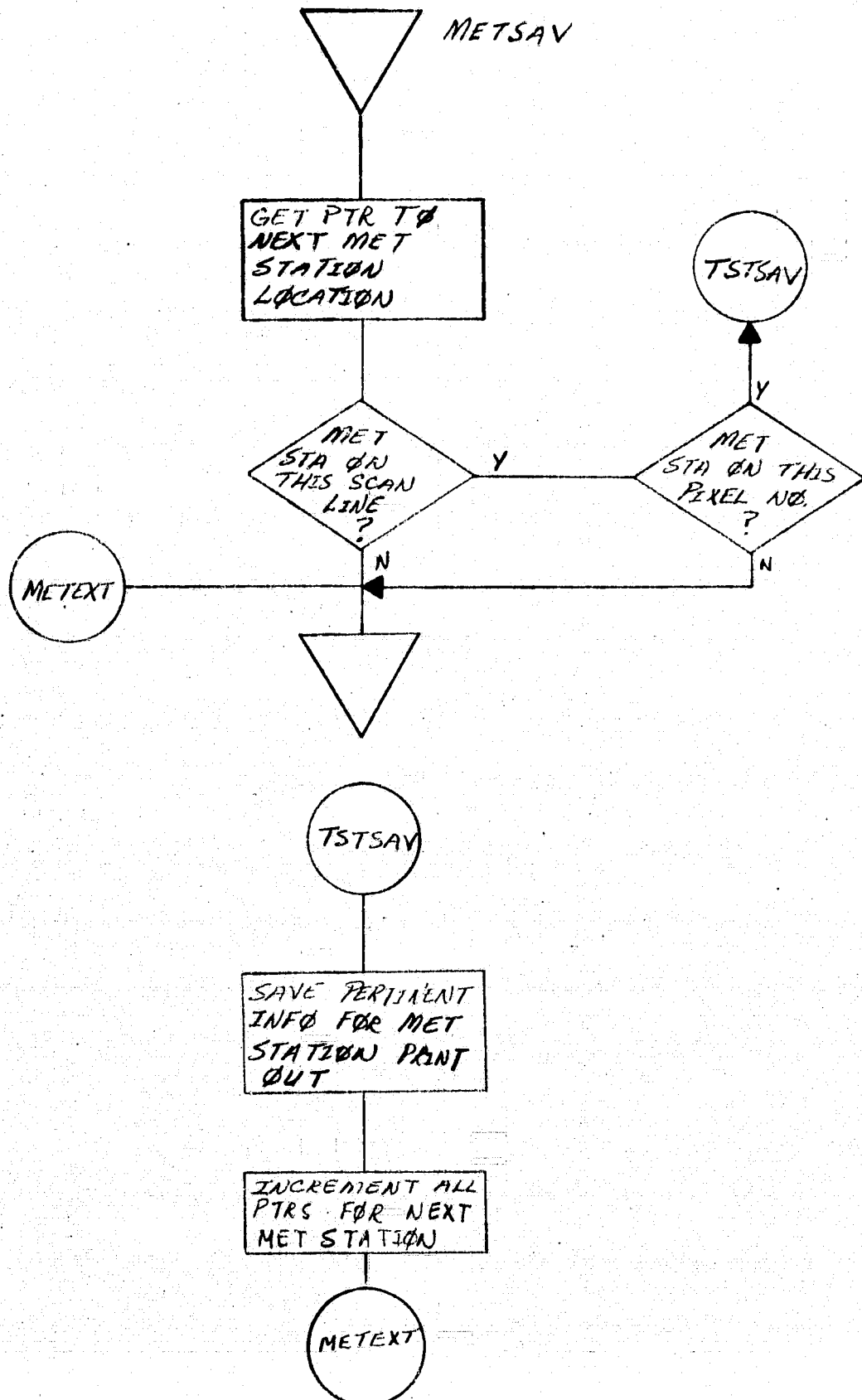




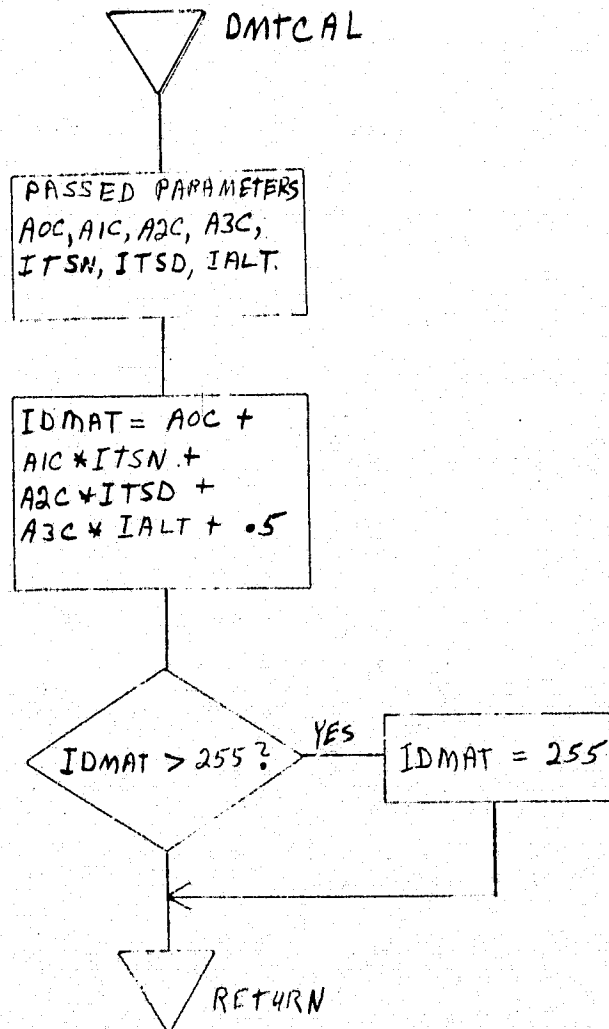


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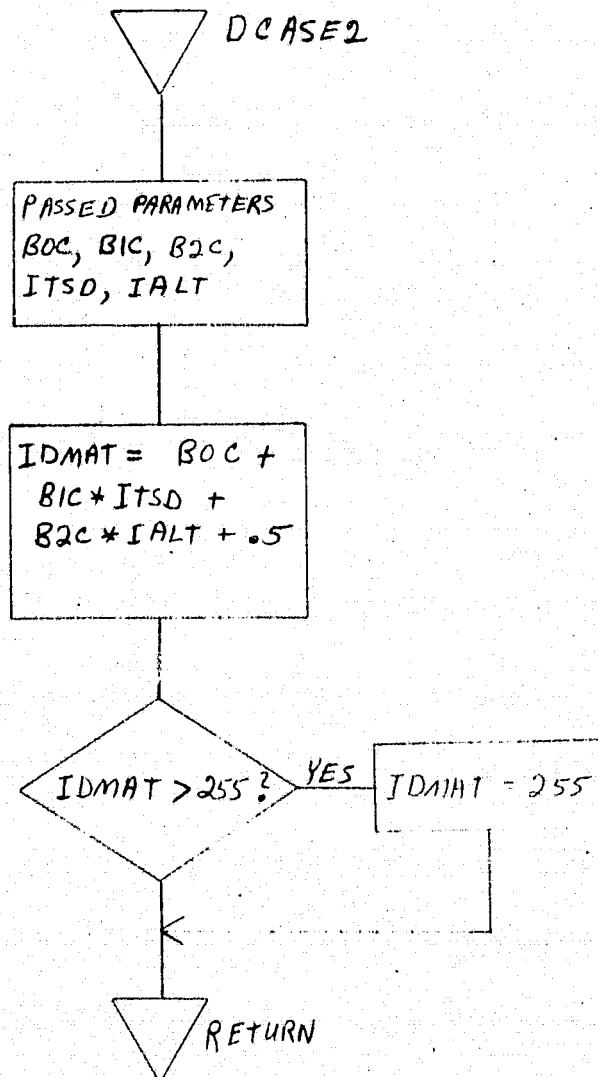




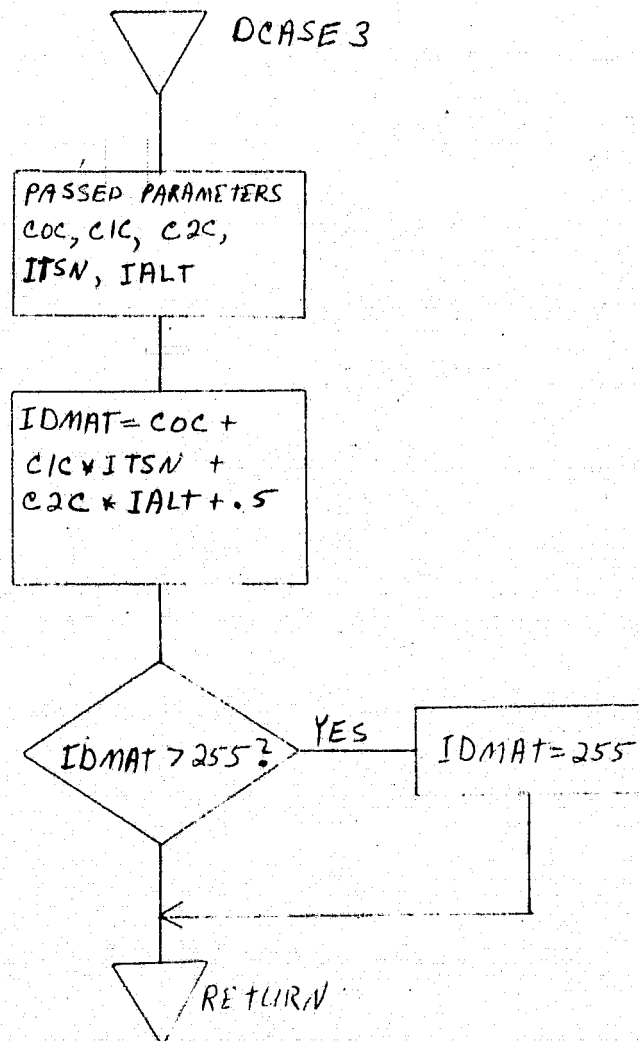
CALCULATES DMAT
AND RETURNS IT TO
DBS4B2



CALCULATES DMAT
AND RETURNS IT TO
DBSUB2



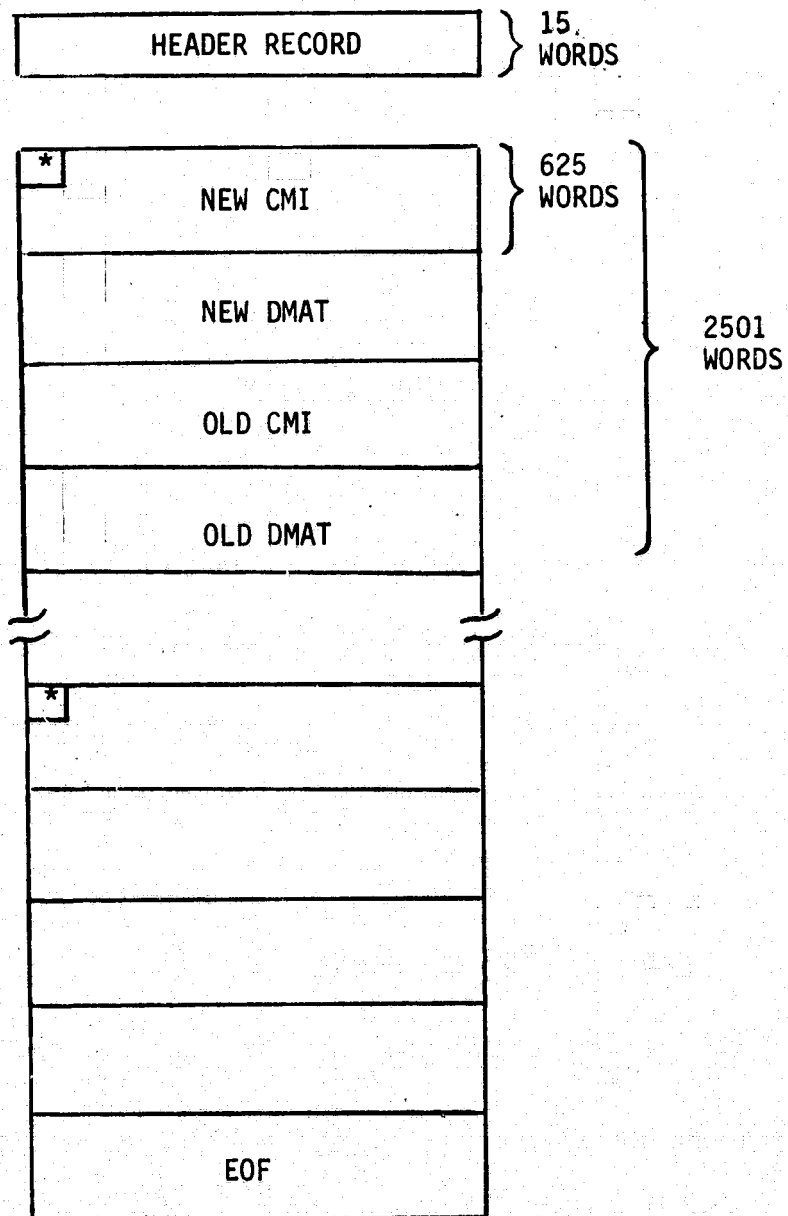
CALCULATES DMAT
AND RETURNS IT
TO DB SUB2



4.2.2.3 Interfaces

- A. Input Data. The input data to the RAP module of the RAP Program comes from three sources -- user input via the VT05, 9-track magnetic tapes, and static and dynamic disk files. The user inputs are made via the VT05 keyboard into changeable fields. The ALT key is used to position sequentially to these entry positions. The tape inputs are from the old data base update and the CMI tapes. The CMI tape is in the universal format, containing one channel of 625 PIXELS for 550 scan lines. The tape format of the data base update tape is unique to SEDS and is defined by figure 4-9. The tape contains 551 records. The 15-word header record (see figure 5-5) is followed by 550 data records containing 2501 words. The first word of each data record contains a scan line counter of 1 to 550. Four channels, each consisting of 625 words, make up the remainder of each data record. The disk files referenced by the RAP module are the same files mentioned as input data to the DBUINT module.
- B. Output Data. The output data of the RAP module consists of the calculated DMAT values from the day IR and night IR registered data for each PIXEL. The newly generated DMAT values are output to the new update tape as the "new" DMAT channel. The "new" CMI channel is the same data input from the CMI tape. The "old" channels on the new update are the "new" channels of the old update tape generated L days ago, where L is the data base length. The delta T disk file is updated daily for each RAP execution run. The values from the delta T disk file are used in the estimation of the DMAT for a given PIXEL when the satellite data is missing due to cloud cover or no data. The six images output to the ORC tape are calculated PIXEL-by-PIXEL in the RAP module.

4.2.2.4 Data Organization. One set of internally defined items in the RAP module are those associated with the VT05 changeable fields. The list of items, described in table 4-1, shows the initialized or defaulted conditions, as well as the range. There



* DENOTES ONE-WORD RECORD (SCAN LINE)
COUNTER WITH RANGE 1-550

Figure 4-9 RAP Data Base Update Tape Format

TABLE 4-1
RAP VT05 PARAMETERS

NAME	TYPE	DEFAULT	LIMIT	DESCRIPTION
UMODE	ASCII	U	I,M,U,Z	DATA BASE UPDATE PROCESS MODE D
ODBSIZ	NUMERIC	-----	0-99	DATA BASE LENGTH
PRTCNT	NUMERIC	-----	0-99	NO. OF COPIES OF MET STATION P/O
REGAVL	ASCII	A	A,D,N,X	REGISTERED DISK DATA
RDATE	ASCII/NUM.	00-XXX-00	DD-MMM-YY	DATE OF DELTA T IMAGE
DORBIT	NUMERIC	00000	0-32767	DAY PASS ORBIT NO.
NORBIT	NUMERIC	00000	0-32767	NIGHT PASS ORBIT NO.
ODBTNO	ASCII	-----	6 CHARS	NEW UPDATE TAPE NO.
RFTNO	ASCII	-----	6 CHARS	OWC TAPE NO.
AXX	NUMERIC	CURRENT	-----	15 RAINFALL COEFFICIENTS
RTHSIG	ASCII	CURRENT	+ OR -	RAINFALL THRESHOLD SIGN
THRLD	NUMERIC	CURRENT	±32766	RAINFALL THRESHOLD
NIRTH	NUMERIC	CURRENT	0-999	NIGHT IR THRESHOLD
DIRTH	NUMERIC	CURRENT	0-999	DAY IR THRESHOLD
KDAYSG	ASCII	CURRENT	+ OR -	DAY TEMPERATURE THRESHOLD SIGN
KDAYIN	NUMERIC	CURRENT	0-120	DAY TEMPERATURE THRESHOLD
KNITSG	ASCII	CURRENT	+ OR -	NIGHT TEMPERATURE THRESHOLD SIGN
KNITIN	NUMERIC	CURRENT	0-120	NIGHT TEMPERATURE THRESHOLD
MINDLX	NUMERIC	CURRENT	0-255	DELTA T IMAGE UPDATE CONSTANT
DDX	NUMERIC	CURRENT	0-255	DELTA T IMAGE UPDATE CONSTANT

are many other internally defined symbols in the RAP module, and they are described by the program listings provided in Part IV of this document.

4.2.2.5 Limitations. The configuration setup, as shown by figure 4-1, is definitive in that specified input and output tapes must be mounted on the designated tape drives. To assist the user and keep him informed of program execution status, a series of advisory messages output to the VT05 and/or line printer are listed in table 4-2.

4.2.2.6 Listings. See Part IV of this document, published under separate cover.

4.2.3 U9TRD. The third execution module of RAP is U9TRD, not to be confused with its subcomponent "U9TRD." All interfaces with this module in RAP are by internal software. Basically, the module provides the function of tape read input of the CMI universal format CCT. Only two subcomponents comprise this module. U9TRD is written in PDP-11 FORTRAN, and "U9TRD" is written in PDP-11/45 assembly language.

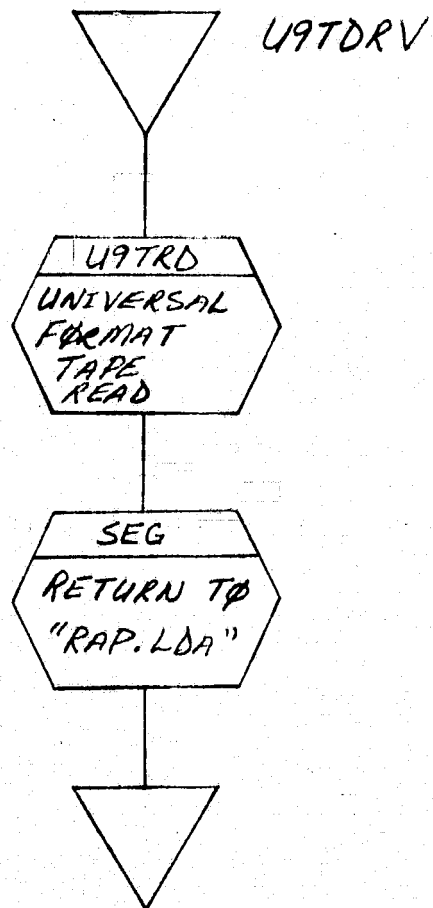
4.2.3.1 Subcomponent Descriptions

- A. U9TDRV. This subcomponent serves as the linking driver to the RAP and U9TRD modules.
- B. "U9TRD." This is the primary subcomponent of the module U9TRD, and is a universal format tape read routine. It is described in paragraph 6.2.1.1,C.

4.2.3.2 Flow Chart. See page following table 4-2.

TABLE 4-2
RAP ADVISORY MESSAGES

NAME	MESSAGE	NAME	MESSAGE
IPMSG	INITIALIZATION PHASE	DBLENT	DUPLICATE -MET- STATION ENTRIES!
IPBMSG	INCREASE DATA BASE	NOWRTM	WRITE RING MISSING ON MTO
DDBMSG	DECREASE DATA BASE	CONM	ENTER -CON- TO PROCEED
NDBMSG	NORMAL DATA BASE UPDATE	IVCMID	****ILLEGAL CMI ID FOUND ON MT1
RDNA	REGISTERED DISK NOT AVAILABLE	IVUPID	****ILLEGAL SBC TAPE ID ON MTA1
MUDMSG	MET UPDATE DISPLAY REQUIRED?	READPE	****READ PARITY ERROR ON MTA1
TAPERM	TAPE ERROR ON HEADER RECORD!	WRTEPE	****WRITE PARITY ERROR ON MTO
HDRERM	HEADER RECORD ERROR	XPCMI	EXPECTED CMI TAPE NO. (XXXXXX), OVERRIDE REQUESTED?
UDBERM	DATA BASE SIZE ERROR!	DLTMG1	DELTA T IMAGE INITIALIZATION
OPIERR	OPERATOR INPUT ERROR!	DLTMG3	DELTA T RE-INIT, -GO- TO PROCEED
TSCERM	TAPE STATUS CODE ERROR	DLTMG4	CHANGE MODE & ENTER -GO-
UPTERM	OLD UPDATE TAPE READ ERROR!	MODFMG	MODIFY DATA BASE LENGTH
LOSERM	LOST TOO MANY SCAN LINES!		
DEVERM	TAPE READ DEVICE ERROR		
ENDMSG	END-OF-RUN: NORMAL COMPLETION		
GOMSG	ENTER A-GO-COMMAND WHEN READY!		
UDTMSG	UPDATE TAPE AVAILABLE?		
RESTEND	ENTER -RST- OR -END- COMMAND!		
EOJMSG	END-OF-JOB: NORMAL COMPLETION		
EOJERR	END-OF-RUN: ABNORMAL EXIT!		
DSKERR	DISK READ-WRITE!!!		
LPERRM	LINE PRINTER ERROR!!!		



4.2.3.3 Interfaces

- A. Input Data. The input data to the U9TRD module comes via the RAP module as the call packet to the subcomponent "U9TRD."
- B. Output Data. The output data of the U9TRD module is a buffer address pointing to the start PIXEL number of the current scan line from the CMI tape.

4.2.3.4 Data Organization. The calling packet to the U9TRD module is placed in specified memory locations in the SEDS common area named SCOMVT. When the first word of the "U9TPAK" is set nonzero, it signals the U9TRD module that control for input and output parameters is located in the designated locations of SCOMVT. With the exception of "U9TPAK," entries in the call packet are explained by figure 6-4 of this document. The "U9TPAK" packet is shown below.

	.CSECT	SCOMVT	
	.BLKW	80.	
U9TPAK:	.BLKW	1	(set nonzero by user)
	.BLKW	3	(used by U9TRD)
PACKET:	.BLKW	6	(tape read control info)
DATADR:	.BLKW	1	(return adr of start PIXEL No.)
STATUS:	.BLKW	1	(status code returned)
CHADR:	.BLKW	8	(channel packet)
	.CSECT		

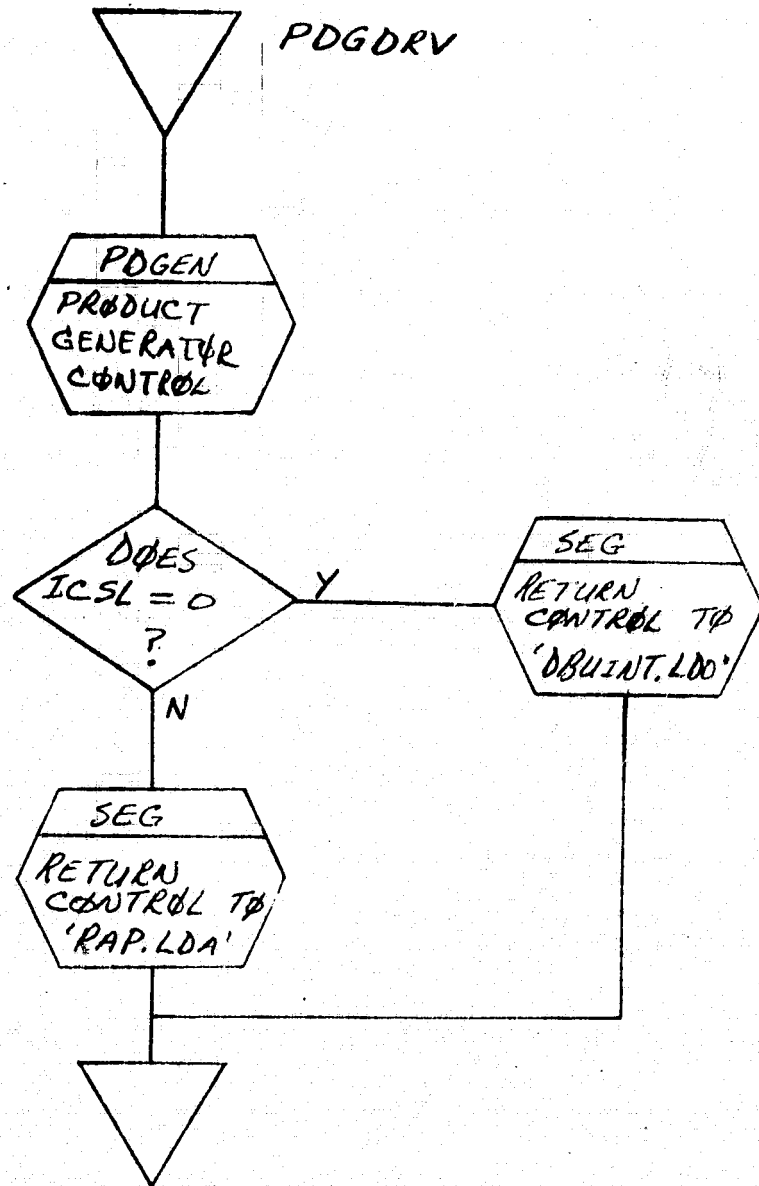
4.2.3.5 Limitations. The primary limitation of the U9TRD component of RAP is that extra time is required for the tape input function because of the segmentation feature of the core overlay with each scan line.

4.2.3.6 CPC Listings. See Part IV of this document, published under separate cover.

4.2.4 RFTGEN. The fourth and product generation module of RAP is RFTGEN. Its function is the product generation of the six images output to the ORC tape. The module is composed of several separate and distinct subcomponents. With the exception of the FORTRAN linking driver, PDGDRV, all subcomponents are written in PDP-11/45 assembly language.

4.2.4.1 Subcomponent Descriptions. All of the subcomponents of the RFTGEN module except PDGDRV are discussed in paragraph 5.2.3.1, under the SWPGEN module of SSP. (They include PDGEN, FCGEN, OWCPRO, OWCTBL, U9WRT, DISPL, FCTBL, OPNOT, and ANNOT.) PDGDRV is the linking driver between the RAP module and the RFTGEN module.

4.2.4.2 Flow Chart. See following page for a PDGDRV flow. Detailed flow charts for other subcomponents of RFTGEN are shown in paragraph 5.2.3.2.



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4.2.4.3 Interfaces. The basic interface of the various product generation subroutines is shown by figure 5-22. One call to the product generation module (RFTGEN for RAP) is made for each scan line. The buffering is set up so that the data from all six images (as detailed in figure 4-8) is moved into a 4K buffer area, ORCBUF, for communication with RFTGEN. The tape format for the ORC products is illustrated by figure 4-10.

4.2.4.4 Data Organization. The principle internally defined items of the RAP product generator module are those associated with the VT05 display (see figure 4-11). A list of VT05 variable fields with initialized values is shown in table 5-16.

4.2.4.5 Limitations. The limitation of the ORC product generation capability is the output to tape of all six images. No selection is available to permit the output of only one or two of the images. The only recovery capability is complete restart feature for processing from scan line 1 to scan line 550, sequentially.

4.2.4.6 CPC Listings. See Part IV of this document, published under separate cover.

4.2.5 METPRT. The fifth and last component of RAP is METPRT. Selected PIXEL positions within given scan lines are defined as MET stations. This module in RAP performs specific calculations on this data and outputs to the line printer a user-defined number of MET station report copies. Two of the three subcomponents -- "METPRT" and STNDEV -- are written in PDP-11 FORTRAN. CODIT is written in PDP-11/45 assembly language.

4.2.5.1 Subcomponent Descriptions

- A. "METPRT." This is the primary subcomponent of the METPRT module. The entire MET station report is keyed off of the predefined identification number. MET station ID's may also be defined in the GTZONE background file, which is defined on disk. In addition, information reported via cards input in the DBUINT module is reflected in the MET station report printouts. The principle purpose of the reports has been for the use of SEDS evaluation and validation.

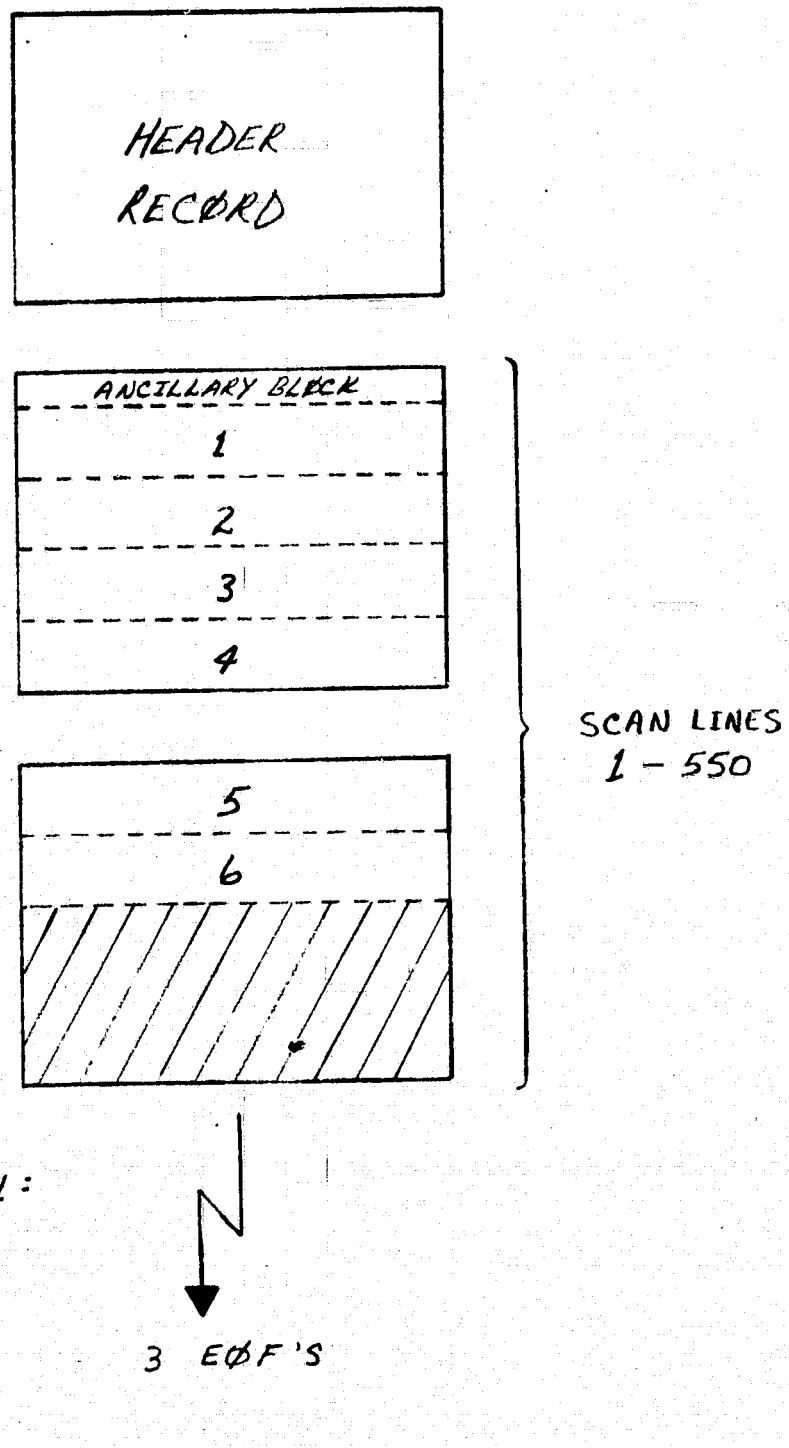


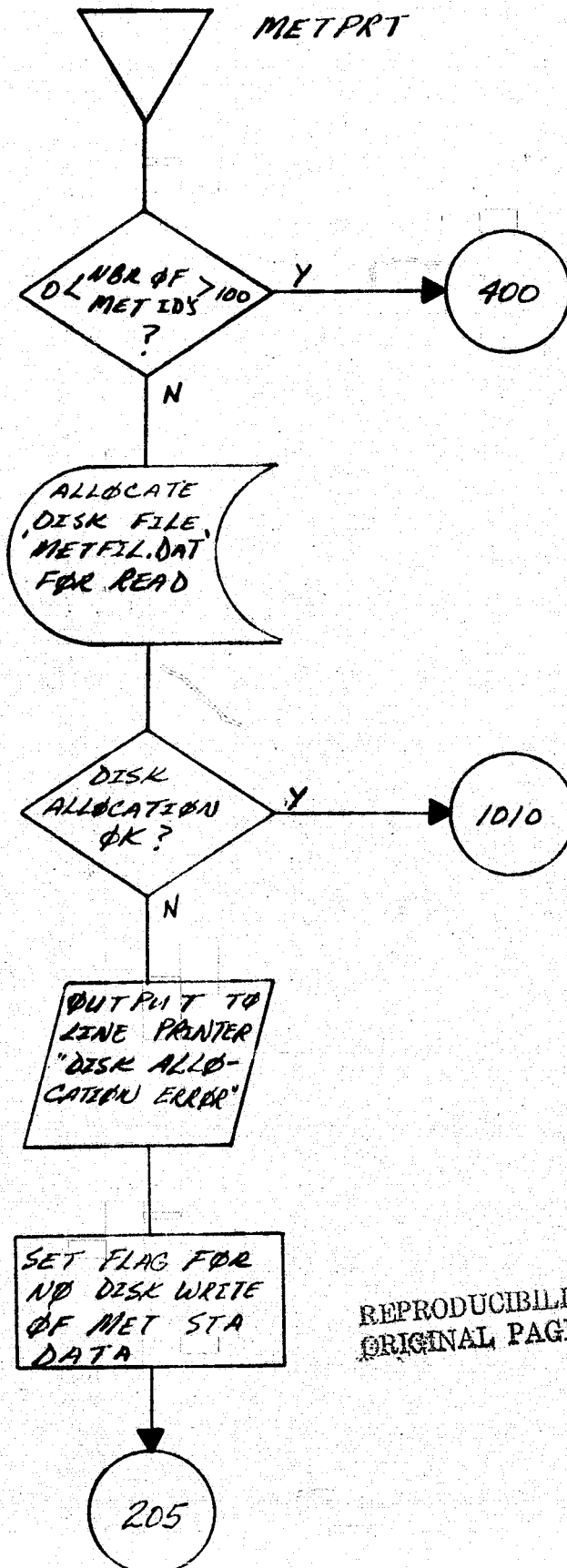
Figure 4-10 RAP PFC Tape Format (ORC)

SEDS PRODUCT GENERATION		
MODE=3	DISPLAY IMAGE=1	DATE: 01-MAR-75 MTU=2
		COMPRESSED
0=NONE	CURRENT SCAN LINE=0001	
1=DISPLAY	1=RAINFALL	4=TMET(ID)
2=TAPE	2=TGT	5=QUAL
3=BOTH	3=DELTA T	6=NIGHT CLD
SYS ID=SEDS	TAPE ID=ORC	SEQ. NO.=01
SEN ID=NOAA	GEN DATE=01-03-75	TAPE NO=123456
JOB ID=SEDS IMAGE	RAINFALL	ORBIT=12345
		DATE OF DATA=02-28-75
FILM ANNOTATION COMMENT		
FCT=01 A=+01.00 B=+000		

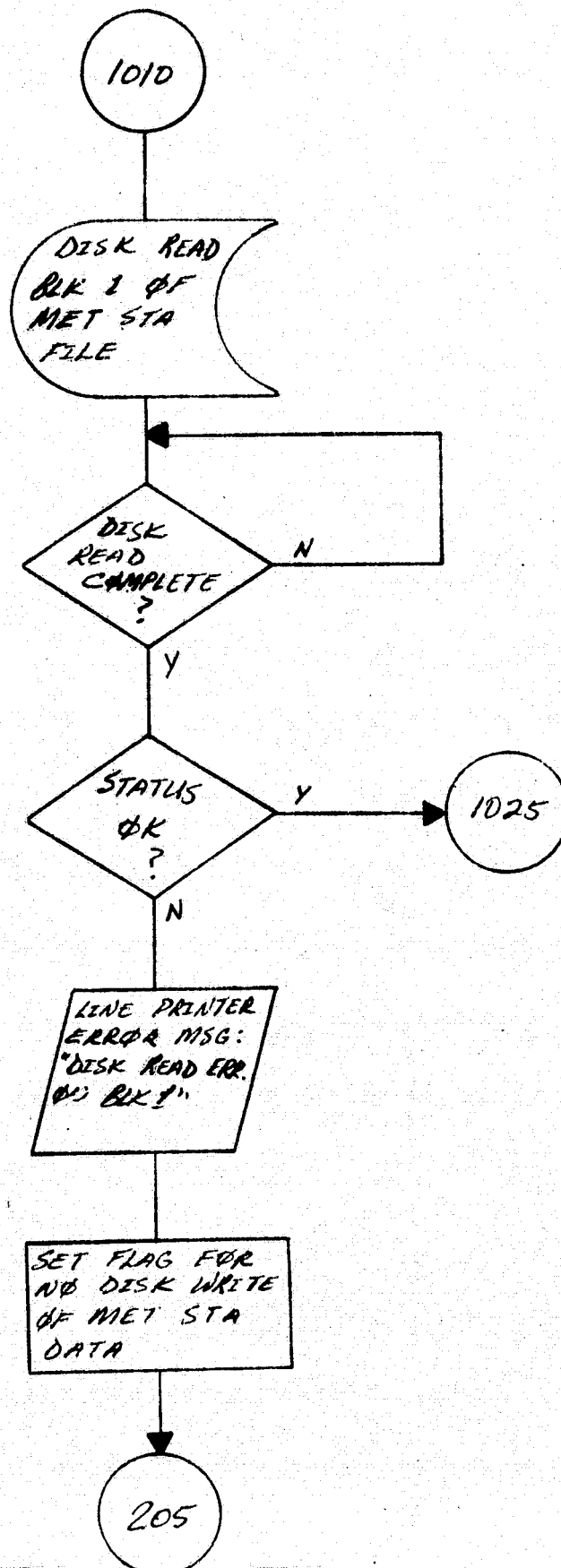
Figure 4-11 RAP Product Generator Display

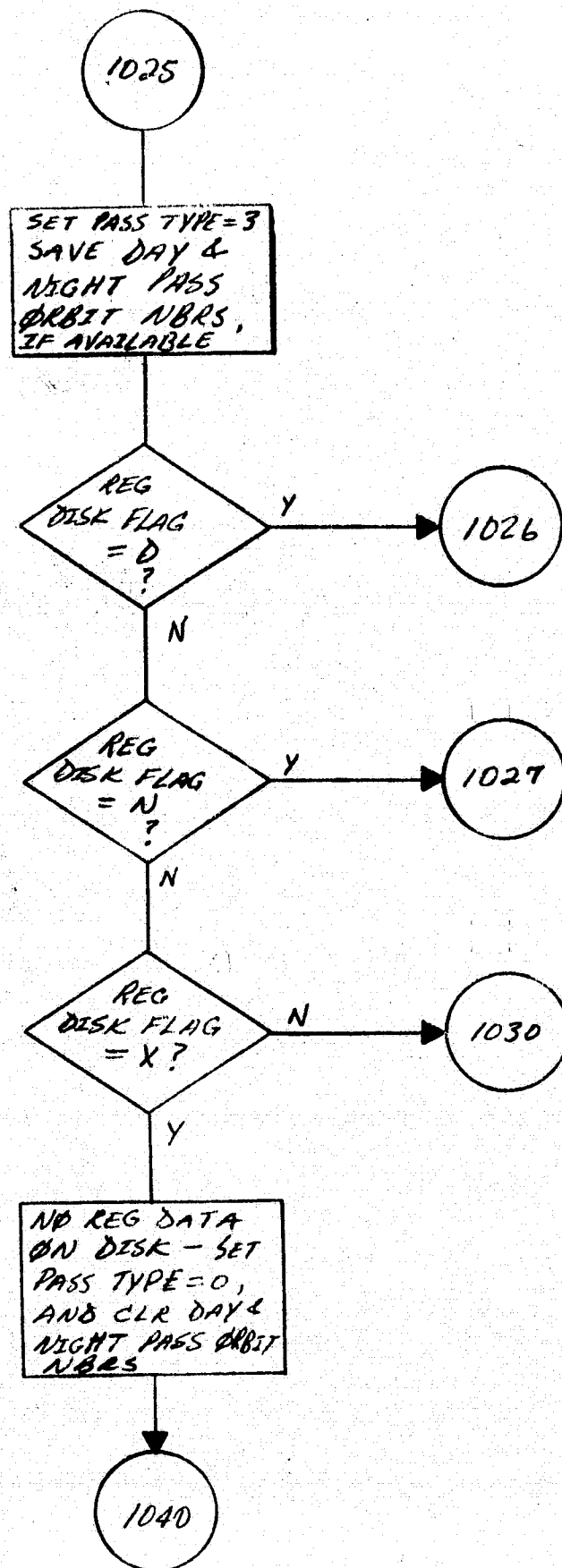
- B. CODIT. This is a short subcomponent for the purpose of getting the rainfall code printed out on the report.
- C. STNDEV. This is the subcomponent that calculates the DMAT standard deviation that is reflected in the DMAT error statics summary at end of the printout.

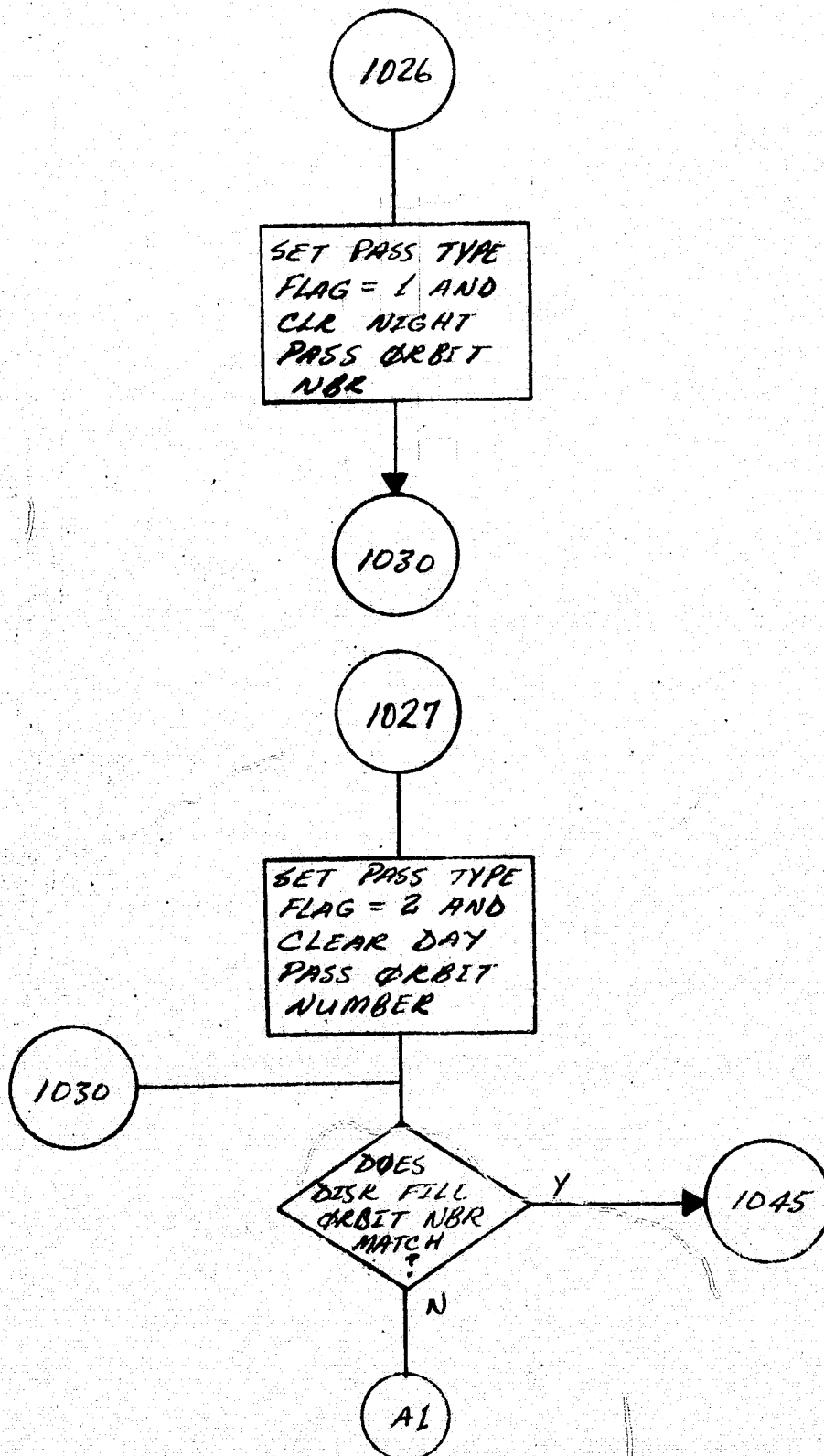
4.2.5.2 Flow Chart. See following 21 pages.

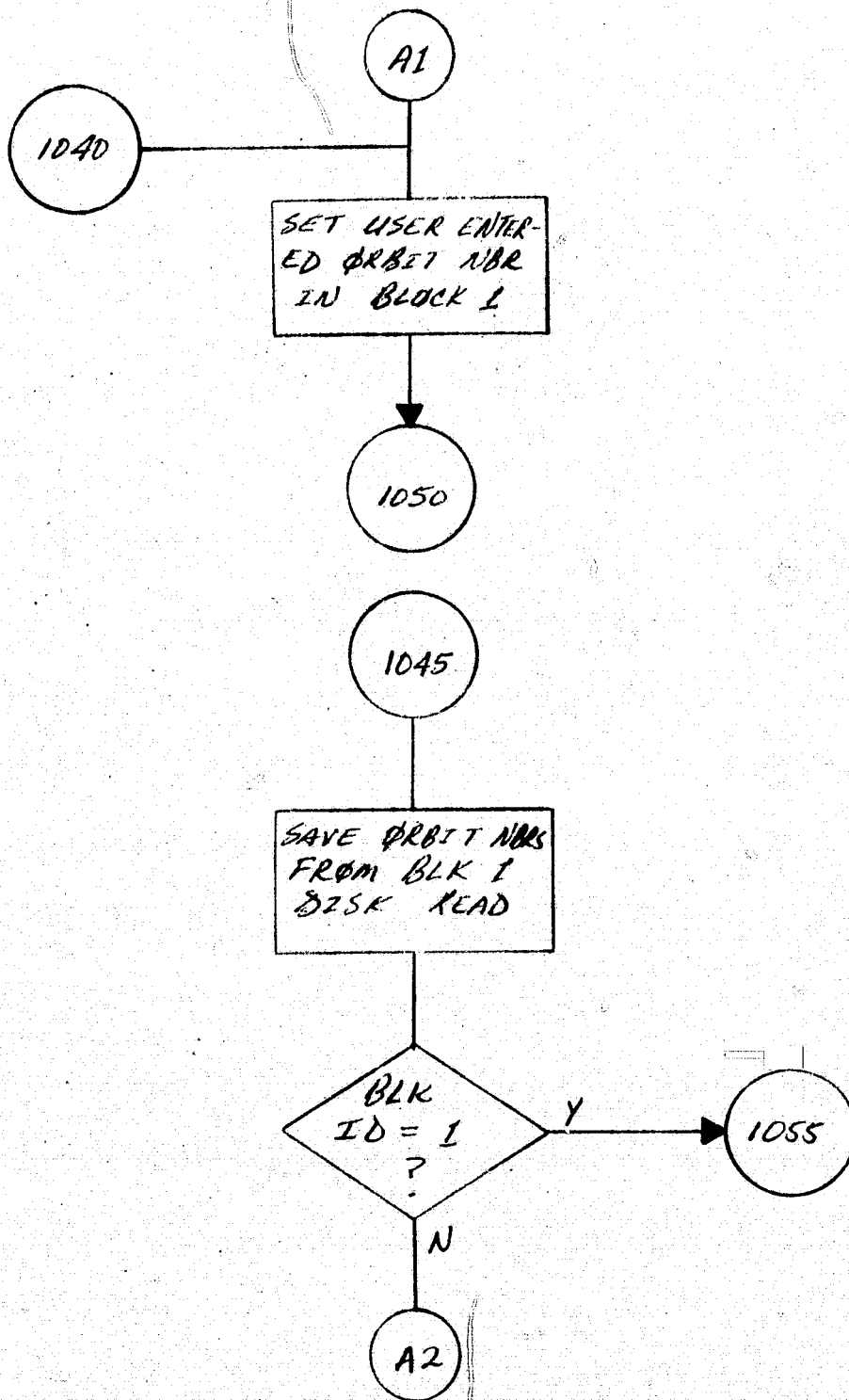


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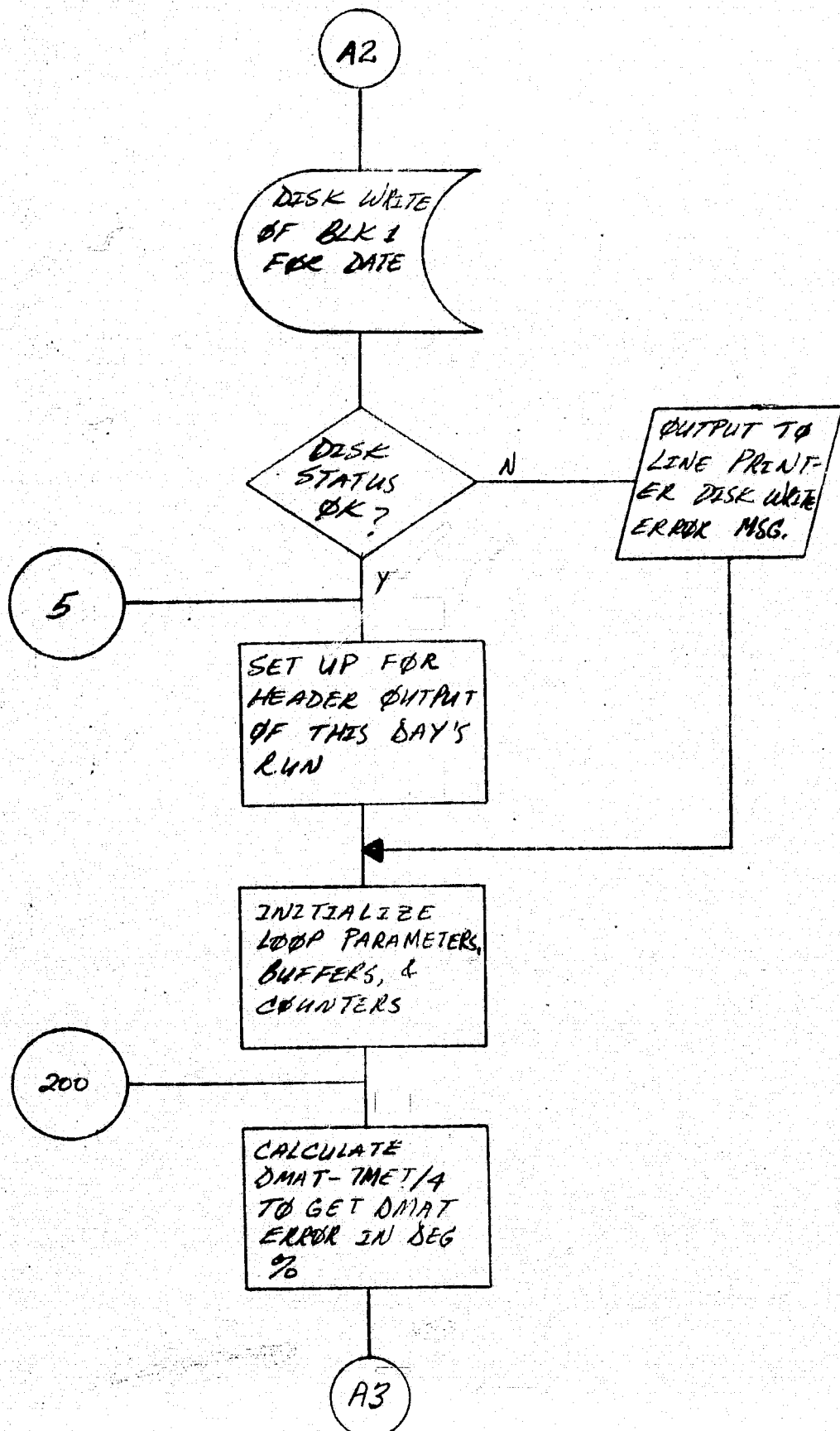


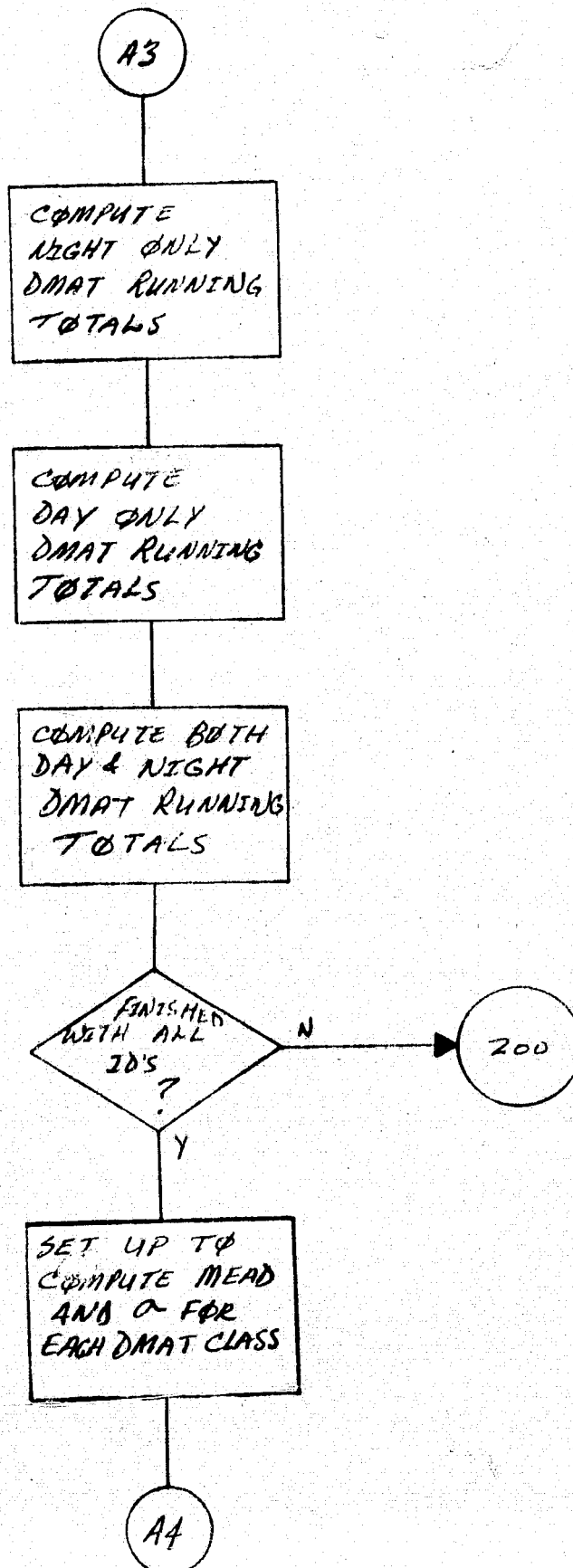


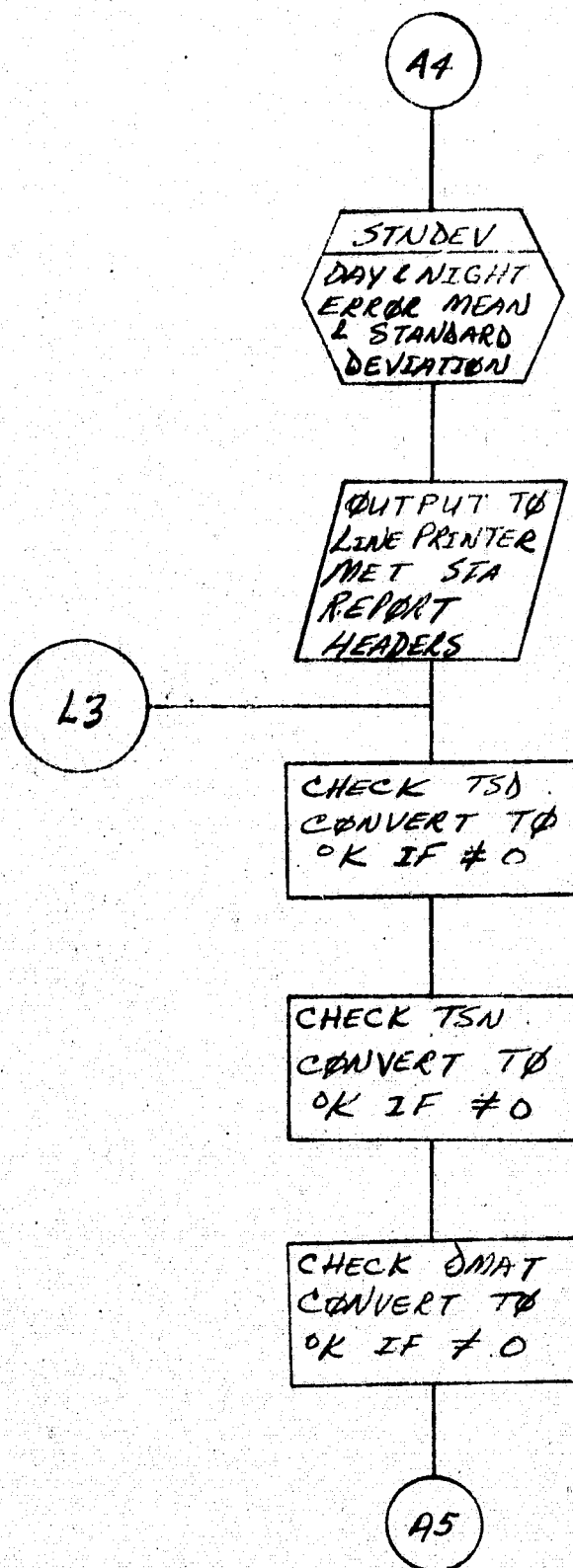


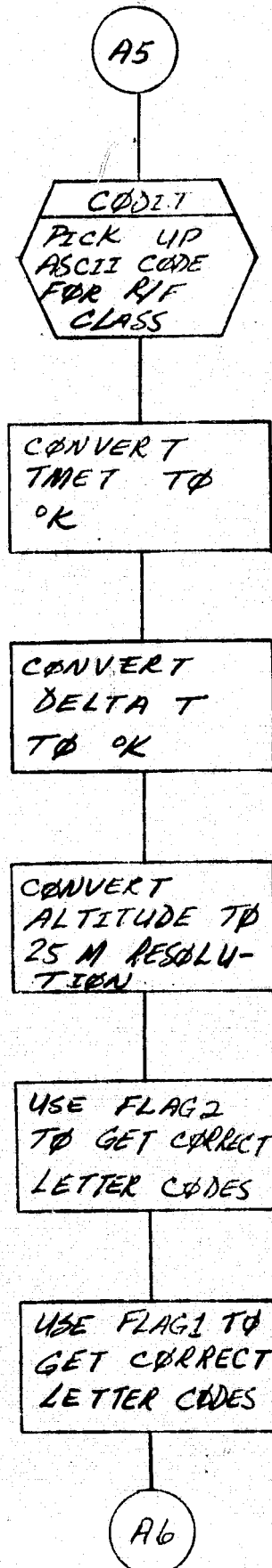


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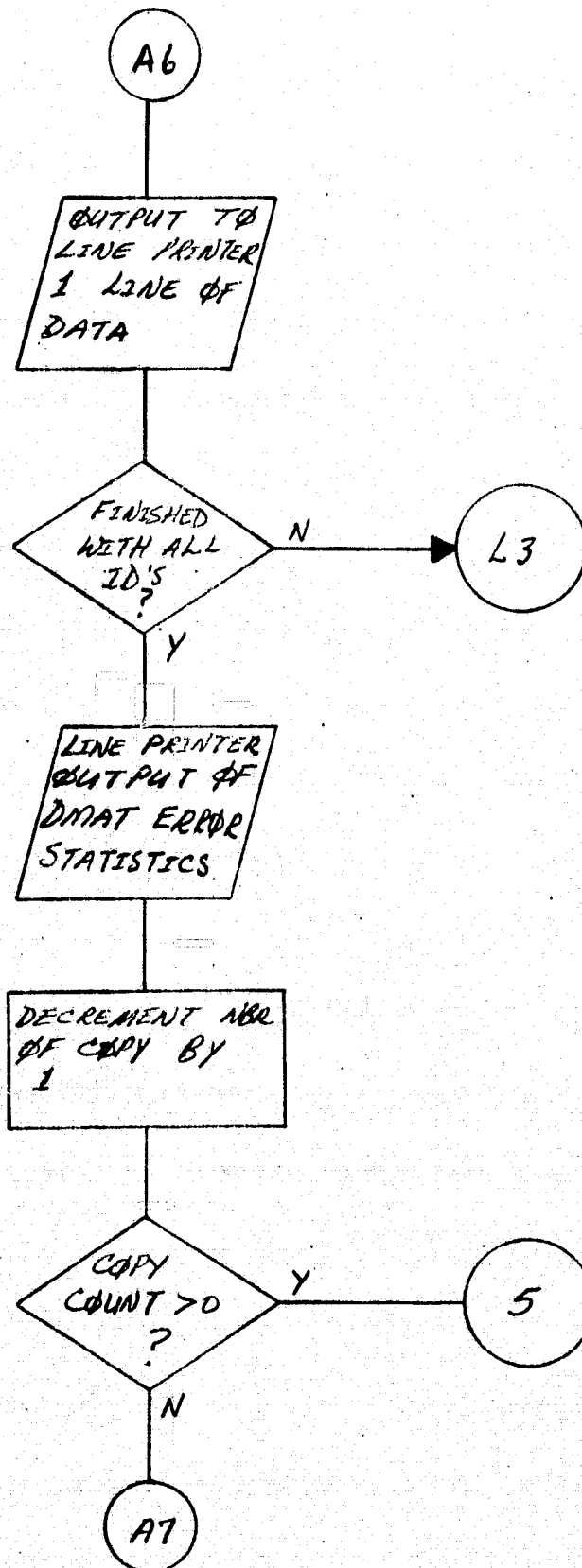


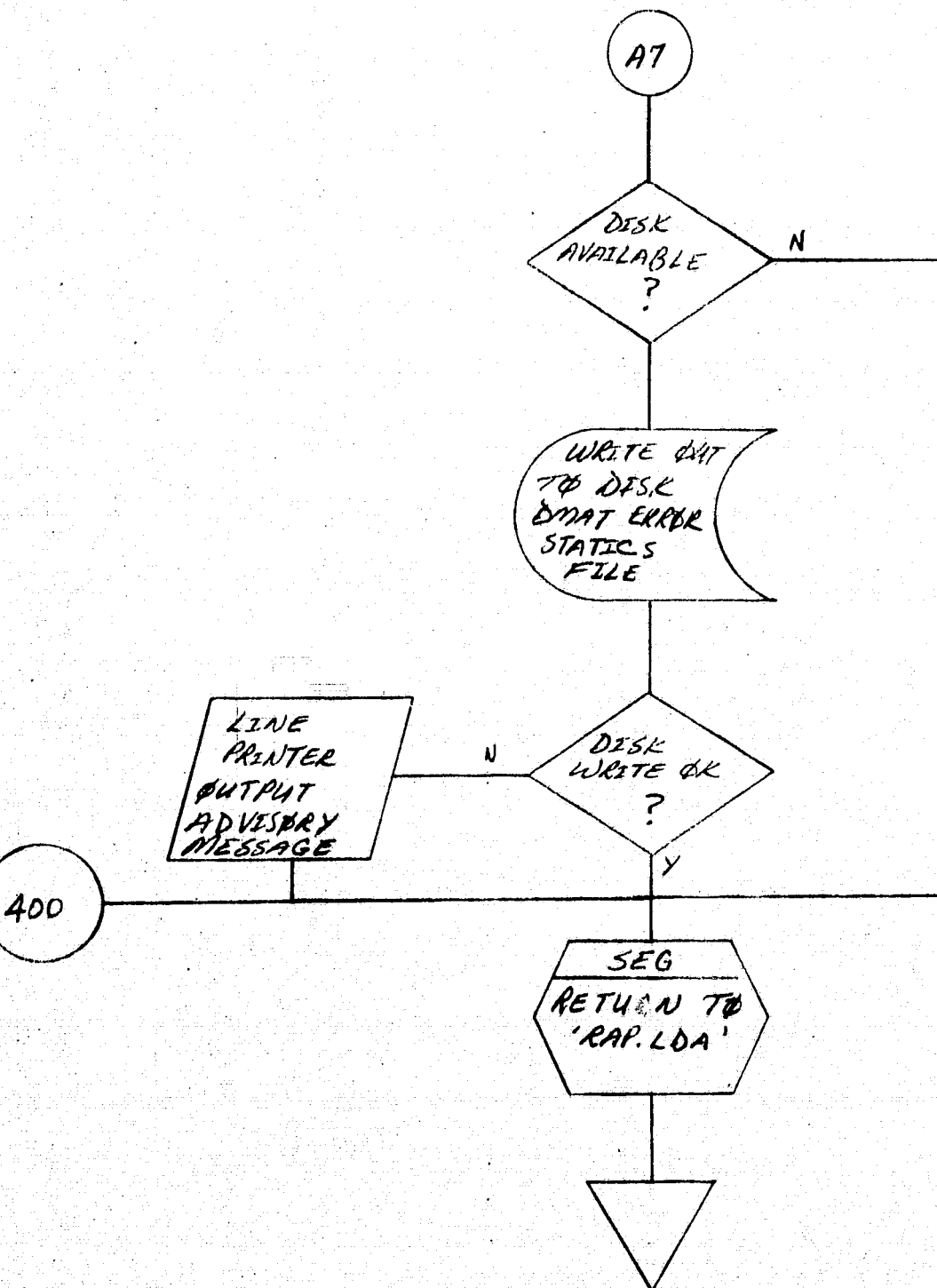




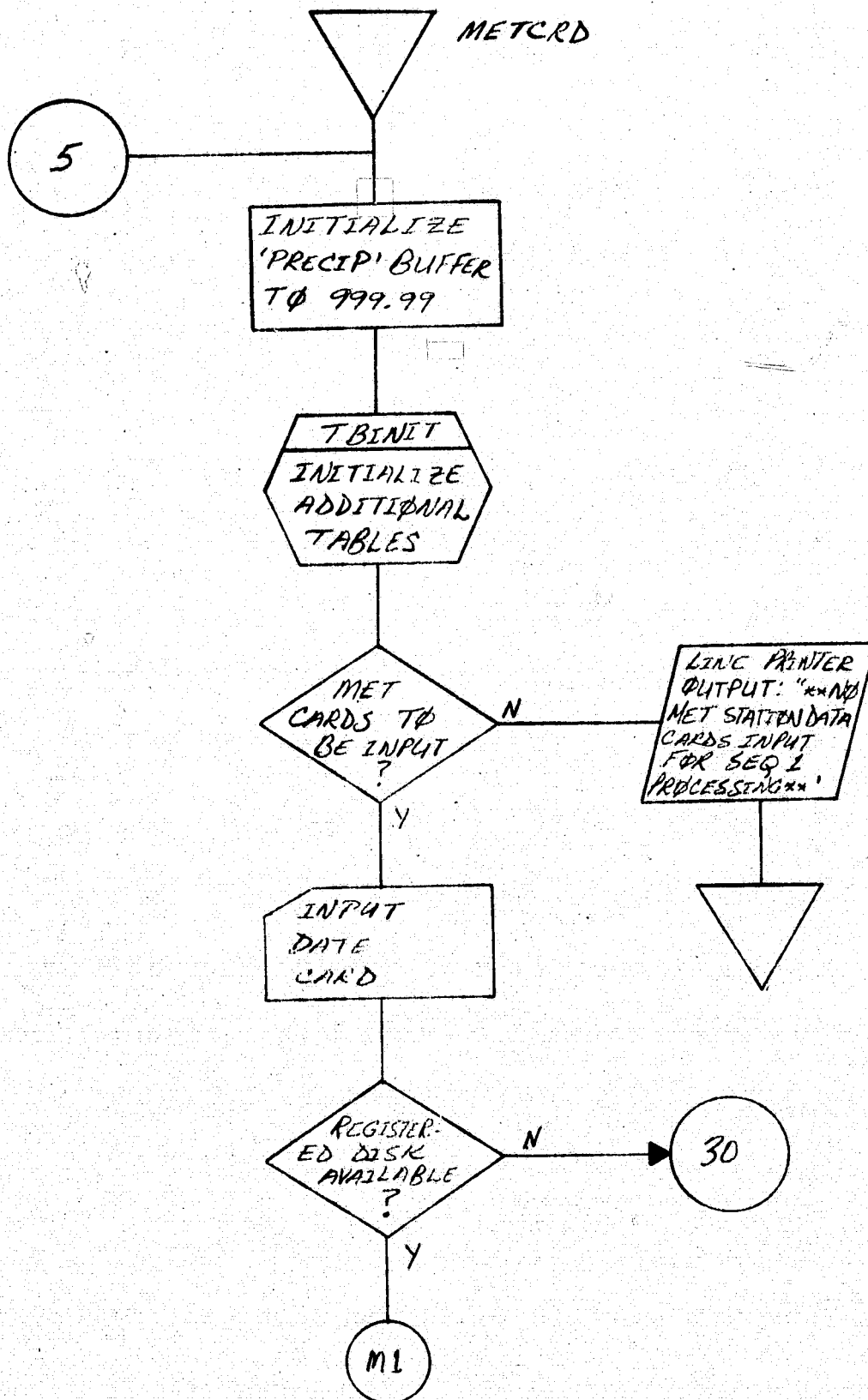


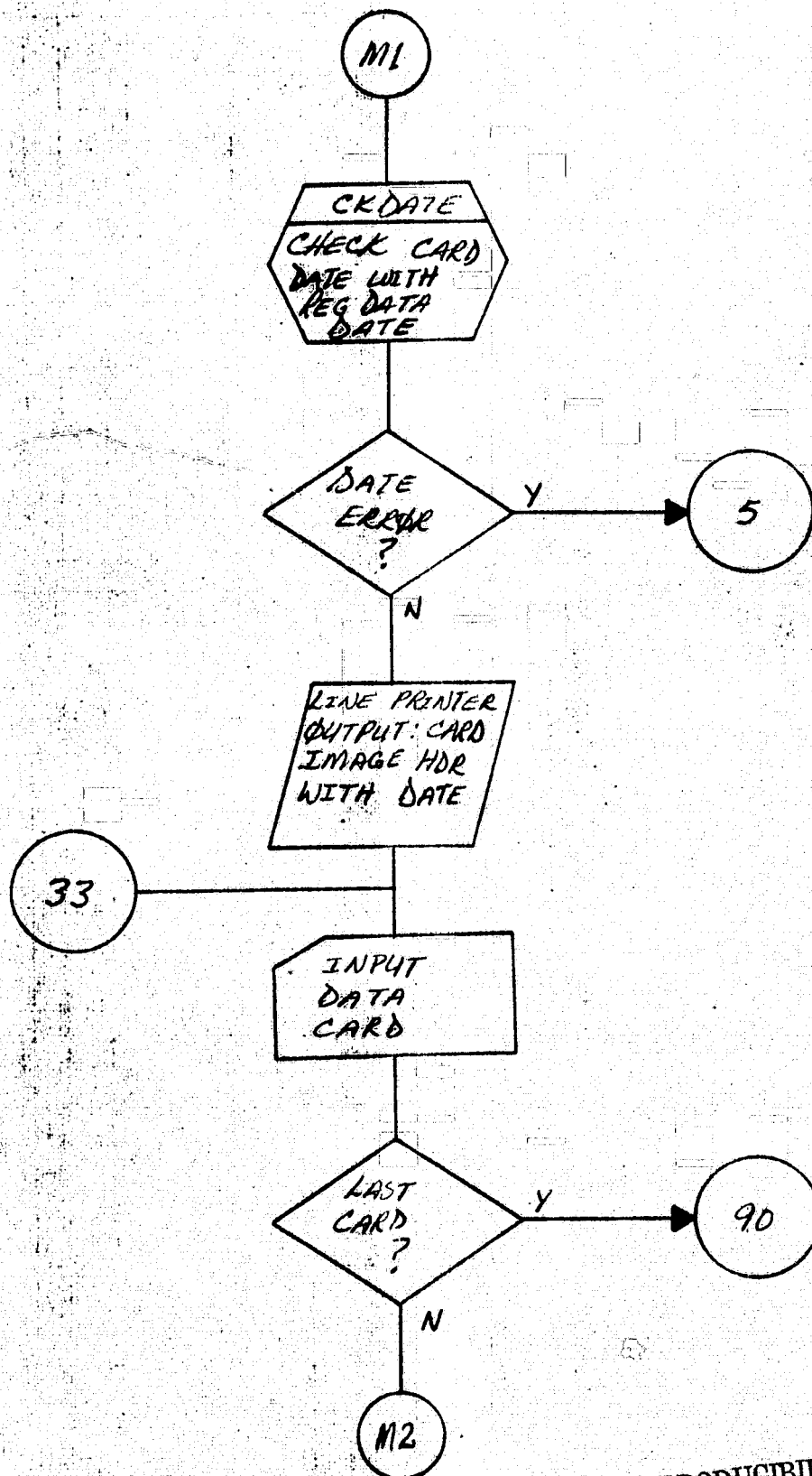
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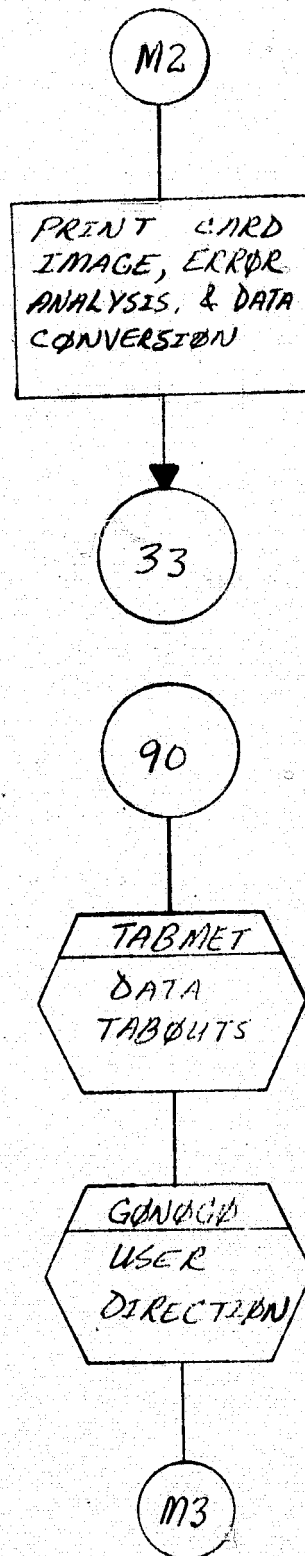


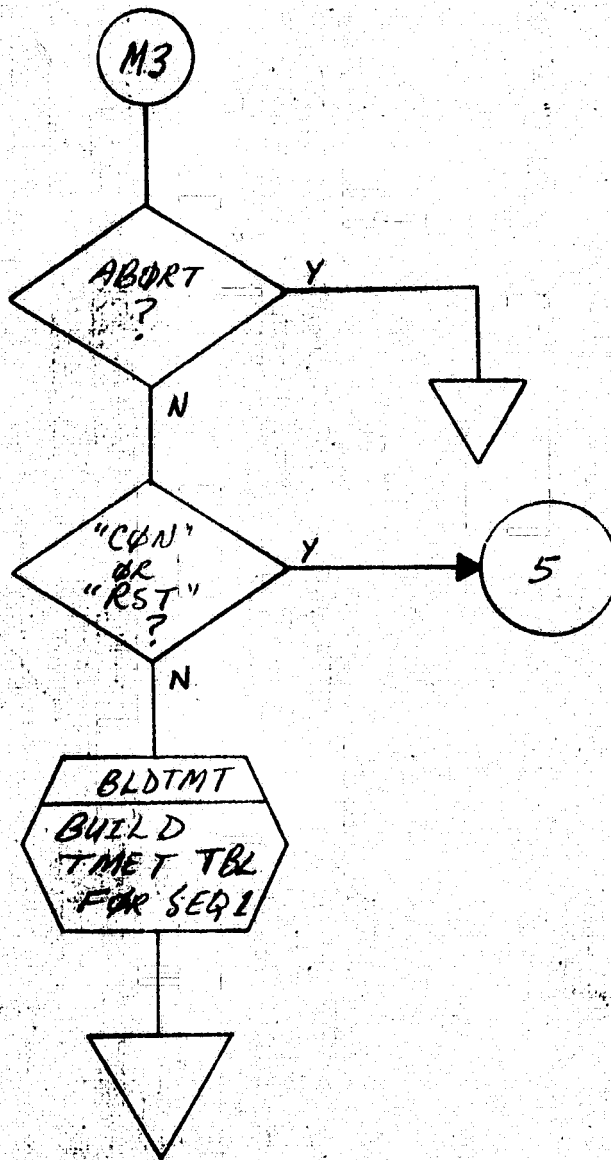




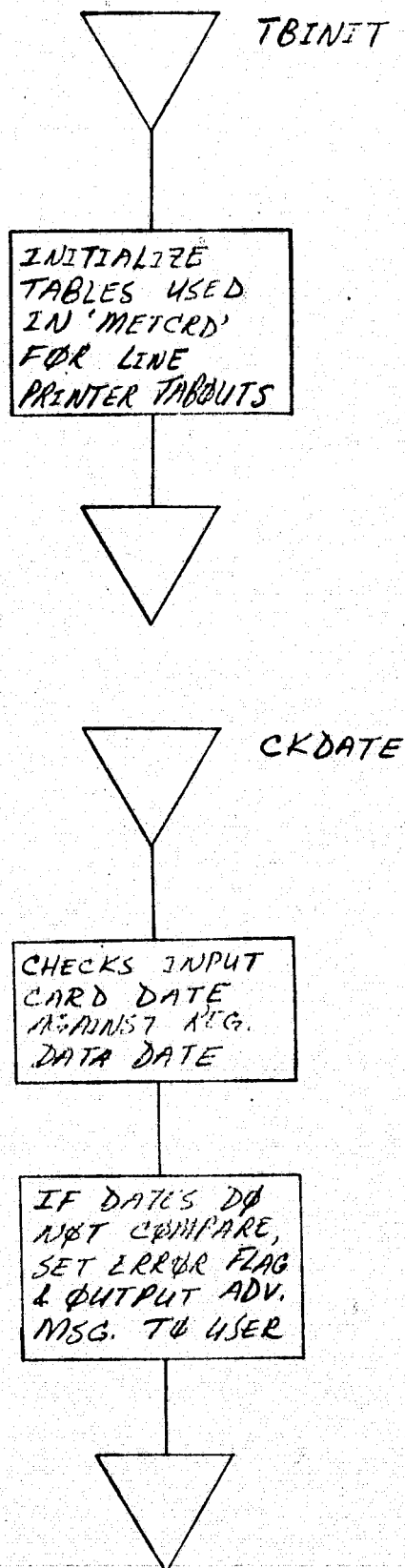


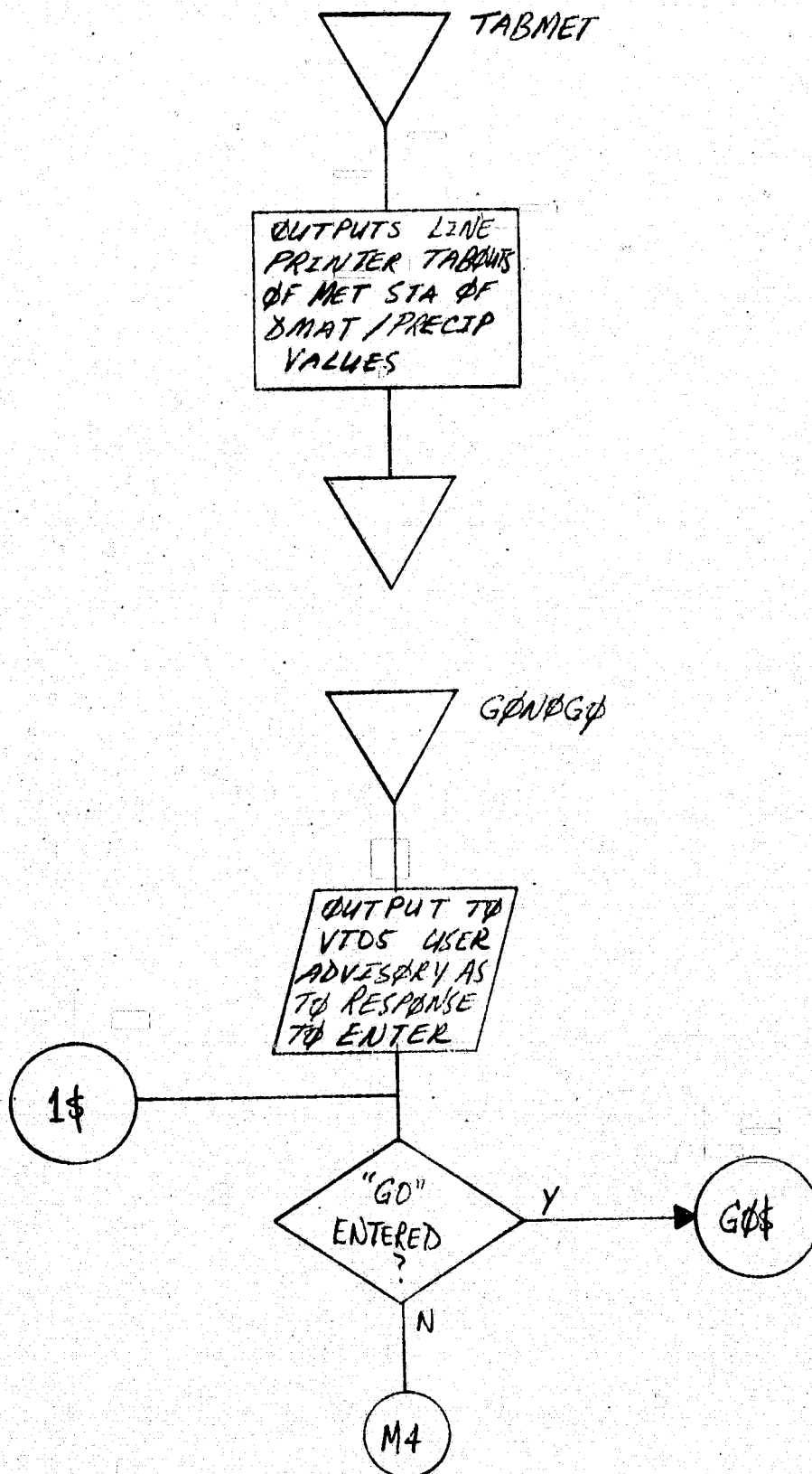
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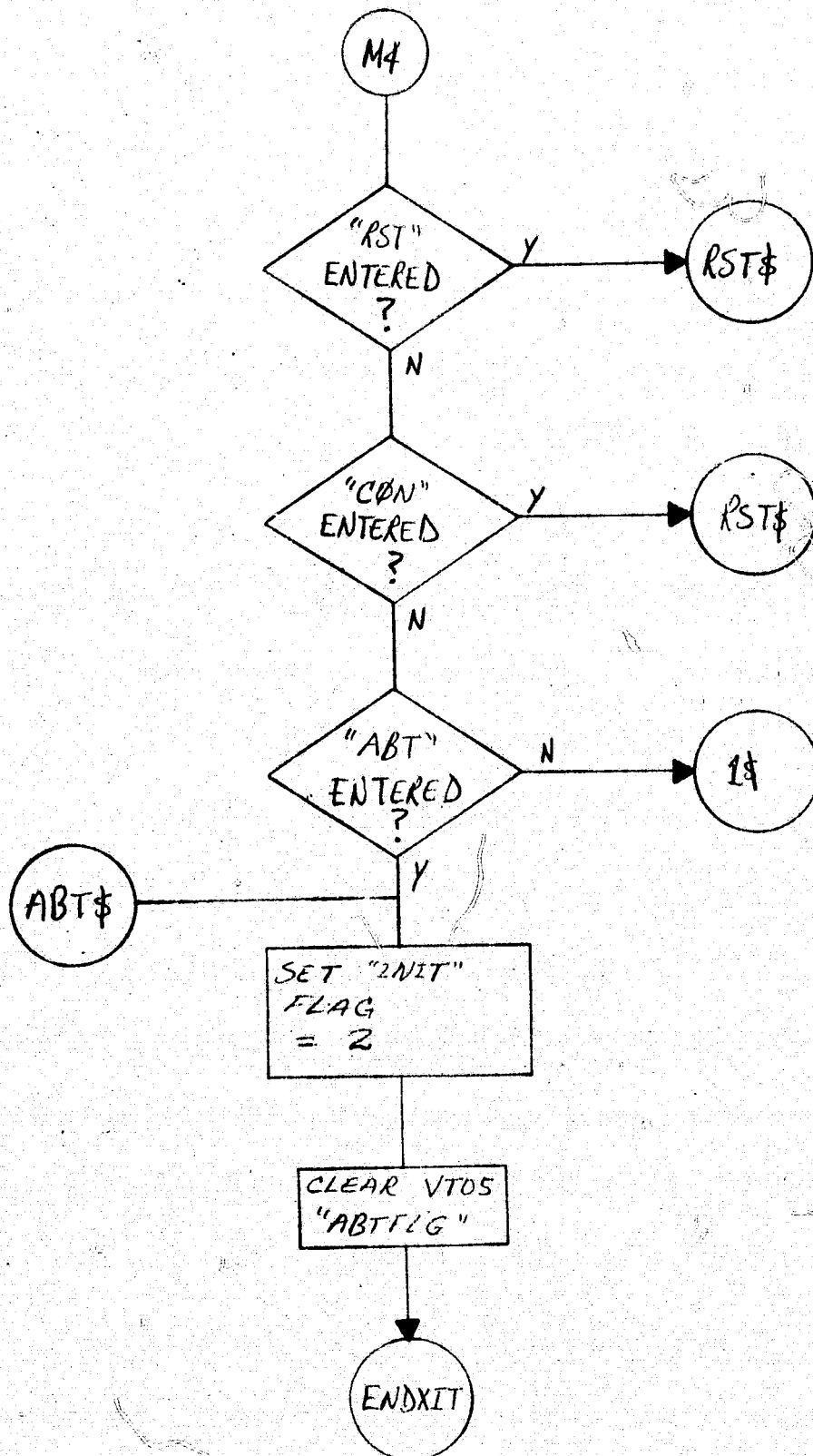


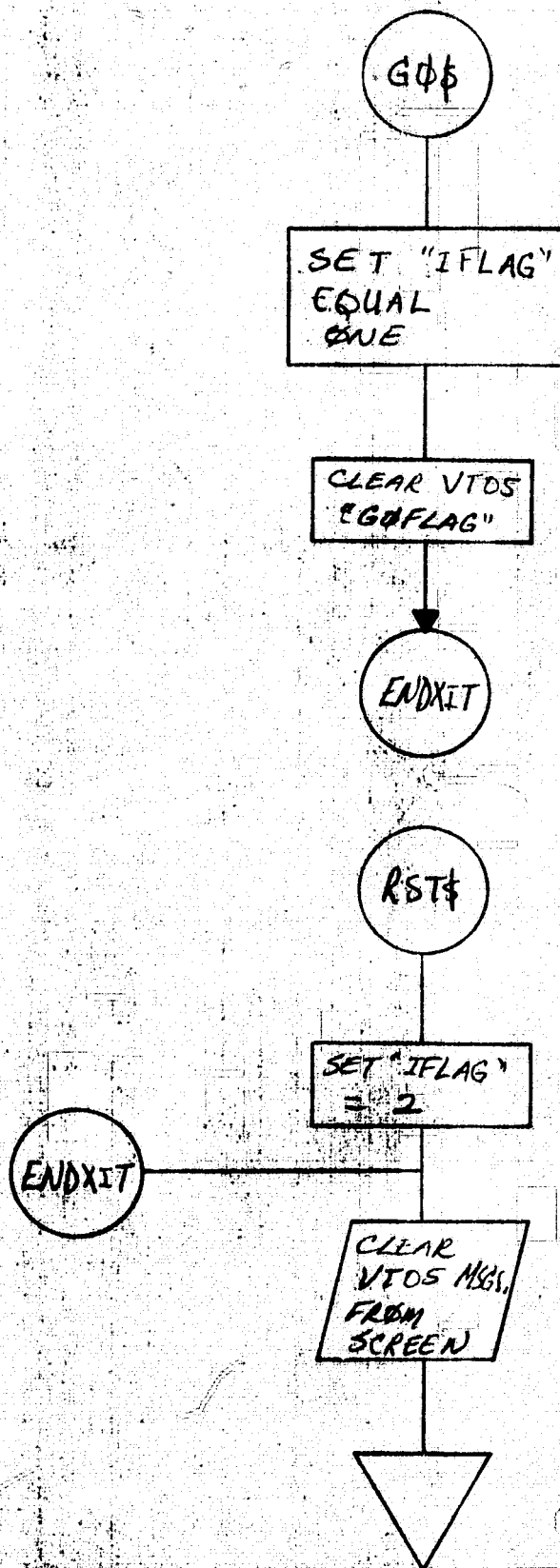


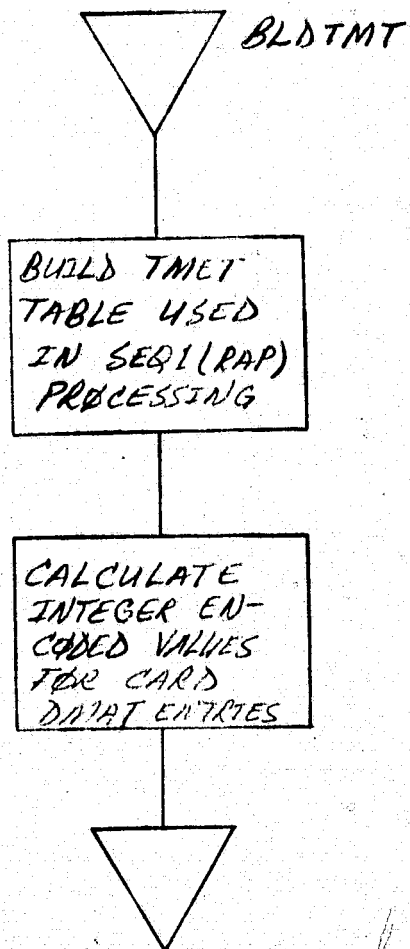
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4.2.5.3 Interfaces

- A. Input Data. The input data for the METPRT component is from two original sources, disk files and input cards. However, most of the information reflected on the printout is computed information from these sources.
- B. Output Data. The output data is routed to the line printer as hardcopies. A disk file is also created and updated to reflect the MET station report information. This disk file is for historical purposes for analysis use. Figure 4-12 is a sample copy of the SEDS MET station report.

4.2.5.4 Data Organization. The data organization of the METPRT module is based on the number of MET station ID's currently defined in SEDS. The upper limit of the number of ID's has been 100, with the ID's ranging from 0 to 99. Basically, the MET station report is keyed to the ID number. Internally defined tables and constants are detailed in the program listings provided as Part IV of this document.

4.2.5.5 Limitations. The principle limitation of the MET station report generation is the point at which the printout occurs. The complete RAP execution cycle must be finished before any of the report is output to the line printer.

4.2.5.6 CPC Listings. See Part IV of this document, published under separate cover.

DATE OF DATA (MM=DD=YY): 12- 9-75

TO CODE	Y GRID	X GRID	TSD K	DAY VIS	N CODE	TBN K	ALT M	DMAT SRCE	DMAT K	TCARD K	DMAT ERROR C	DELT T K	TGT K	GT TSHLD	CHI CODE
05	4	314	280.0	27	CD	285.0	750.0	N	287.75	283.75	4.00	2.50	286.00	0	-0.12
05	12	304	283.5	23	C	282.5	50.0	N	288.25	284.25	4.00	1.50	287.75	0	0.18
05	21	338	281.5	28	CD	285.0	450.0	N	288.25	0.00		3.50	287.00	0	-0.12
07	29	385	284.5	24	C	283.0	50.0	B	281.25	0.00		2.25	287.25	0	-0.12
05	30	384	282.5	22	C	280.0	750.0	N	285.50	0.00		1.00	284.50	0	-0.12
03	34	352	289.0	25	C	281.5	750.0	B	281.50	283.75	-2.25	0.50	288.75	0	-0.12
02	39	441	275.5	28	CD	282.5	50.0	N	286.25	0.00		3.00	288.75	0	0.12
09	39	482	290.0	25	C	283.5	50.0	B	283.25	284.25	-1.00	3.25	285.00	0	-0.12
04	42	500	286.0	24	C	283.5	750.0	B	281.50	283.75	-2.25	2.50	287.00	0	-0.37
06	42	460	290.0	20	C	284.0	50.0	B	283.50	0.00		6.00	290.75	0	0.12
04	46	307	281.5	28	CD	283.5	1225.0	N	286.00	0.00		2.00	285.75	0	0.12
08	49	447	284.5	23	C	283.5	50.0	B	281.75	283.75	-2.00	4.25	288.75	0	0.12
04	53	339	272.0	27	L	283.5	450.0	N	287.75	0.00		3.75	287.50	0	-0.37
03	55	105	287.5	28	C	0.0	1225.0	D	281.25	284.25	-3.00	-0.25	284.50	0	-0.12
04	56	382	283.5	27	C	286.5	50.0	D	290.00	286.00	4.00	4.25	290.25	0	-0.12
04	62	142	285.0	30	C	0.0	1225.0	D	279.25	282.00	-2.75	4.50	287.50	0	-0.12
04	65	141	284.5	23	C	0.0	1225.0	D	278.75	0.00		4.25	287.25	0	-0.12
00	65	418	281.5	27	C	282.5	50.0	N	288.25	0.00		4.75	291.00	0	0.12
40	67	357	282.0	26	C	284.5	1225.0	N	289.25	0.00		1.50	285.00	0	-0.12
00	74	21	293.5	35	C	0.0	750.0	D	288.25	291.00	-4.75	-0.25	291.25	0	-0.12
00	76	174	291.0	29	C	283.0	1225.0	B	282.50	0.00		2.50	284.75	0	-0.12
01	79	429	290.0	25	C	277.5	50.0	D	284.50	0.00		2.75	290.00	N	0.12
04	83	293	290.0	27	C	284.5	450.0	B	283.50	0.00		1.00	287.00	U	-0.75
03	84	368	287.5	41	L	287.0	50.0	N	290.25	0.00		7.00	0.00	0	-0.12
04	87	388	280.0	50	L	280.0	50.0	D	289.25	0.00		2.75	289.25	0	-0.12
01	88	39	290.5	20	C	0.0	1225.0	D	283.50	286.50	-3.00	0.50	287.50	0	-0.12
02	89	60	283.5	28	C	0.0	1225.0	D	288.50	283.25	3.25	3.25	288.50	0	-0.12
03	90	359	284.5	27	C	287.5	750.0	B	283.25	0.00		6.75	288.50	0	-0.12
05	93	215	289.0	32	C	280.0	1225.0	B	280.25	279.25	1.00	5.50	285.25	0	0.12
04	94	237	287.0	31	C	283.0	1225.0	B	281.25	0.00		4.25	283.75	0	-0.12
07	94	415	218.5	47	C	279.5	50.0	D	290.75	286.50	4.25	4.25	290.75	N	0.12
03	102	24	294.0	24	C	0.0	600.0	D	287.00	0.00		0.00	291.50	0	-0.12
04	104	304	289.5	26	C	285.5	450.0	B	284.00	283.50	-1.50	1.75	287.75	0	-0.75
00	112	397	0.0	32	C	285.5	50.0	N	289.50	0.00		3.75	290.25	0	-0.12
13	120	210	288.0	32	C	286.5	1225.0	B	283.50	288.50	-1.50	1.25	288.25	U	-0.37
07	122	356	292.5	30	C	285.5	50.0	B	285.00	288.50		7.00	286.50	0	-0.12
07	123	241	290.5	29	C	284.5	750.0	B	283.50	0.00		3.75	289.75	0	-0.75
06	123	321	292.0	30	C	286.0	50.0	B	285.25	0.00		0.50	287.25	U	-0.12
06	131	408	292.5	24	C	286.5	50.0	B	285.75	286.50	-0.75	2.00	289.00	0	-0.37
09	152	357	293.0	29	C	286.0	50.0	B	285.50	0.00		1.50	290.50	U	-0.37
02	153	356	292.5	27	C	289.5	50.0	B	287.25	0.00		0.75	287.25	0	-0.12
00	153	388	290.5	27	C	288.0	50.0	B	287.25	0.00		0.75	287.25	0	-0.37
02	158	171	287.0	32	C	282.0	2500.0	B	279.75	283.25	-3.50	-0.75	282.75	0	-0.37
01	158	406	293.5	24	C	286.0	50.0	B	285.75	0.00		1.25	288.00	0	0.12
01	169	34	296.0	31	C	0.0	600.0	D	288.50	293.25	-4.75	-1.75	292.00	U	-0.37
02	179	416	293.5	33	C	288.5	50.0	B	287.00	0.00		0.50	289.00	0	0.12
02	184	400	295.0	25	C	290.5	50.0	B	288.50	288.75	-0.25	0.75	289.75	0	-0.12
07	187	424	295.5	25	C	287.5	50.0	B	287.00	288.25	-1.25	0.75	289.25	0	-0.12
07	188	423	295.5	27	C	290.0	50.0	B	288.25	0.00		1.50	290.00	0	-0.12
07	189	402	296.0	27	C	289.5	50.0	B	288.25	0.00		1.25	290.25	0	-0.12
03	202	39	295.0	25	C	0.0	0.0	D	288.25	291.25	-3.00	0.00	291.75	0	0.12
06	207	344	295.0	25	C	289.5	600.0	B	287.50	0.00		1.75	288.25	0	-0.37
08	213	72	294.5	26	C	0.0	100.0	D	287.75	0.00		-1.00	290.50	0	0.12
09	229	9	296.5	23	C	0.0	0.0	D	289.50	0.00		-0.25	291.25	U	-0.12
09	238	262	292.5	29	C	290.0	1500.0	B	286.50	0.00		2.50	290.25	0	-0.37
12	257	420	296.0	22	C	290.5	100.0	B	288.75	290.25	-1.50	0.00	290.50	0	-1.25
11	264	394	296.0	24	C	291.0	600.0	B	288.75	288.25	2.50	3.50	290.00	0	-0.37
08	282	157	287.5	29	C	0.0	600.0	D	289.50	0.00		-1.75	293.00	0	-0.75
09	291	238	294.0	35	C	281.5	600.0	B	283.00	287.25	-4.25	3.00	291.25	0	-0.37
14	301	442	298.0	19	C	294.5	100.0	B	291.50	292.25	-0.75	0.00	292.25	U	-1.25
02	314	418	296.5	27	C	294.0	100.0	B	290.75	0.00		3.50	293.25	0	-0.75
07	317	78	288.5	31	C	0.0	100.0	D	283.25	291.25	-8.00	0.00	292.25	0	-0.37
04	325	355	0.0	0	0	287.0	1500.0	D	286.5	0.00		-1.50	290.25	0	-0.37
17	325	384	0.0	0	0	291.0	1500.0	N	288.50	291.25	-2.75	-1.50	290.00	0	-0.37
10	326	194	297.0	48	CD	0.0	100.0	G	295.00	294.25	0.75	0.75	295.00	0	-1.25
20	336	465	0.0	0	0	293.5	100.0	N	293.00	294.25	-1.25	-0.75	293.50	0	-0.12
34	342	319	0.0	0	0	289.0	600.0	N	289.75	0.00		0.50	292.00	0	-0.37
51	353	689	0.0	0	0	281.0	0.0	G	294.50	0.00		0.25	294.50	N	-0.37
16	361	382	0.0	0	0	287.5	600.0	N	289.00	0.00		0.00	288.25	0	-0.37

Figure 4-12 Sample SEDS MET Station Report

JSC-10019
Part II

• 15	369	248	0.0	0	0	0.0	600.0	G	292.50	293.25	-0.75	-0.75	292.50	0	-1.25
• 20	369	404	0.0	0	0	285.5	2500.0	N	282.75	0.00	-1.00	-1.00	281.00	0	-0.37
• 19	370	433	0.0	0	0	282.5	2500.0	N	282.50	282.25	0.25	-0.75	281.45	0	-0.75
• 43	375	400	0.0	0	0	275.5	600.0	G	290.25	0.00	-6.00	-6.00	290.25	N	-0.12
• 26	380	516	0.0	0	0	294.5	0.0	N	293.50	296.25	-2.75	-1.00	295.50	0	-0.75
• 18	387	297	0.0	0	0	289.0	2500.0	N	285.25	288.25	-3.00	-3.75	284.50	0	-0.37
• 65	389	616	0.0	0	0	296.5	100.0	N	294.25	0.00	-1.50	-1.50	294.75	0	-0.12
• 24	394	427	0.0	0	0	289.5	2500.0	N	285.50	0.00	-1.25	-1.25	283.75	U	-0.37
• 23	396	426	0.0	0	0	290.5	2500.0	N	288.00	285.25	0.75	-1.00	284.00	0	-0.37
• 28	397	473	0.0	0	0	296.0	0.0	N	294.25	0.00	-1.75	-1.75	294.50	0	-0.75
• 99	398	243	0.0	0	0	0.0	100.0	G	295.50	0.00	2.25	2.25	295.50	0	-1.25
• 22	399	332	0.0	0	0	288.0	1500.0	N	287.25	0.00	-1.00	-1.00	287.25	0	-0.37
• 79	399	457	0.0	0	0	287.5	2500.0	N	284.50	285.25	-0.75	-1.50	283.75	0	0.12
• 49	400	366	0.0	0	0	290.5	2500.0	N	286.00	0.00	-2.25	-2.25	284.00	0	-0.75
• 80	403	571	0.0	0	0	296.0	100.0	N	294.00	0.00	-3.50	-3.50	284.75	0	-0.75
• 63	415	344	0.0	0	0	289.0	2500.0	N	285.25	0.00	7.25	7.25	289.25	0	-0.12
• 61	428	623	0.0	0	0	294.0	600.0	N	292.00	0.00	-6.75	-6.75	292.50	U	-0.75
• 41	431	296	0.0	0	0	298.5	1500.0	N	291.75	0.00	-4.00	-4.00	295.25	0	-1.25
• 21	434	293	0.0	0	0	0.0	600.0	G	295.25	0.00	-4.00	-4.00	283.25	U	-1.25
• 30	444	516	0.0	0	0	264.0	2500.0	G	283.25	287.25	-4.00	-9.00	288.50	0	-0.75
• 42	452	565	0.0	0	0	290.0	2500.0	N	285.75	0.00	-9.75	-9.75	293.75	U	-1.25
• 29	454	431	0.0	0	0	293.0	600.0	N	291.50	0.00	-2.25	-2.25	297.25	0	-1.25
• 46	460	348	0.0	0	0	296.5	100.0	N	294.25	0.00	-2.75	-3.50	293.50	U	-0.75
• 32	463	567	0.0	0	0	300.0	600.0	N	294.50	297.25	-2.75	-1.50	298.00	0	-1.25
• 66	466	370	0.0	0	0	300.0	100.0	N	295.75	0.00	-6.50	-3.00	296.75	0	-1.75
• 31	479	424	0.0	0	0	296.0	600.0	N	292.75	299.25	-6.50	-3.00	296.75	0	-1.75

DMAT ERROR STATISTICS (IN DEGREES C)

CASE	NUMBER	MEAN	STD. DEV.
----	-----	----	-----
DAY ONLY	7	-4.179	1.891
NIGHT ONLY	12	-0.562	3.315
BOTH	15	-1.283	1.636
COMBINED(D,N&B)	34	-1.425	2.701
GT ONLY	5	0.700	3.290
COMBINED(D,N,>)	39	-1.327	2.845

Figure 4-12 (Cont'd)

SECTION 5

SCREWORM SURVIVAL PROGRAM (SSP)

5.1 GENERAL PROGRAM CHARACTERISTICS

The Screwworm Survival Program (or Data Base Update Sequence No. 2) is used to update and maintain the SEDS data base. Each days processing uses the new update tape generated from Data Base Update Sequence No. 1 and the previous day's data base tape. SSP produces a new data base and a screwworm products tape (OWC), which is suitable for film processing. The screwworm products are optional and may or may not be generated daily. SSP consists of three major components. The function of the first module, SSPDRV, is control, including user initialization, tape I/O, data base calculation sequencing, output image sequencing, and program termination. The second module, ISCREW, contains the data base maintenance algorithms used in calculating the new data base. The third component, SWPGEN, generates the product, eight images output to the OWC tape. In addition, the processing allows one of the eight images to be monitored via the SEDS display. The basic configuration of SSP is described by figure 5-1.

5.1.1 Functional Allocation. As defined in PHO-TN734, *Screwworm Eradication Data System Functional Requirements*, dated 8 May 1974, SSP performs the data base update and maintenance processing. Data base computations and archive processing are accomplished through the use of a four-to-one compression scheme, using every fourth element (pixel) of every fourth scan line. Five categories, called channels, of information are maintained as the SEDS data base. The information is stored on 9-track, 800 bpi magnetic tapes. The five channels of data are short-term mean air temperature (STMAT), long-term mean air temperature (LTMAT), long-term mean crop moisture index (LTMCMi), degree-day sum (DDSUM), and data quality channel (DQC). Each channel represents 16-bit calculations or running sums for each pixel over the last N days, where N is the data base length.

5.1.2 Program Flow Chart. See figure 5-2.

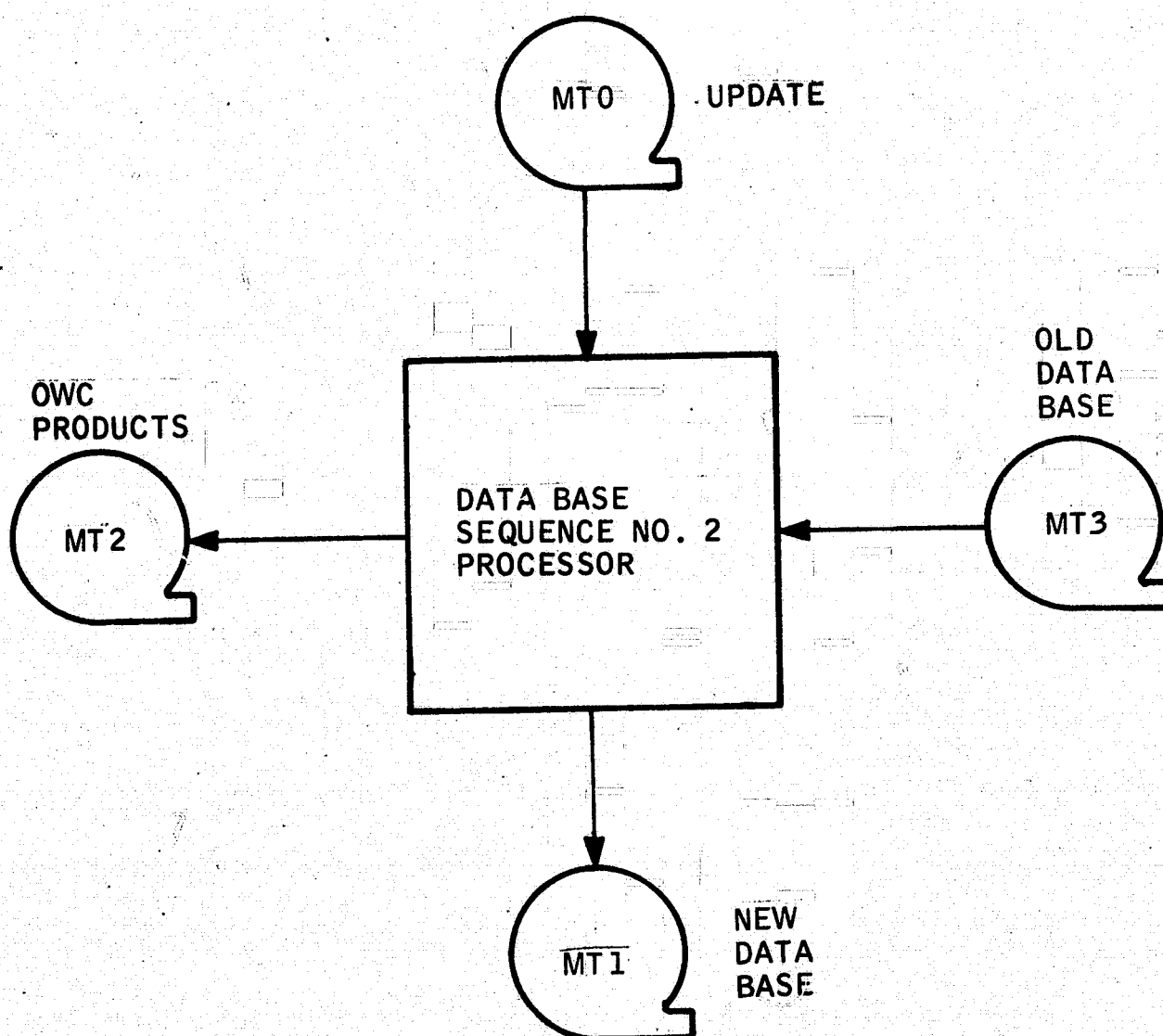


Figure 5-1 SSP Basic Configuration

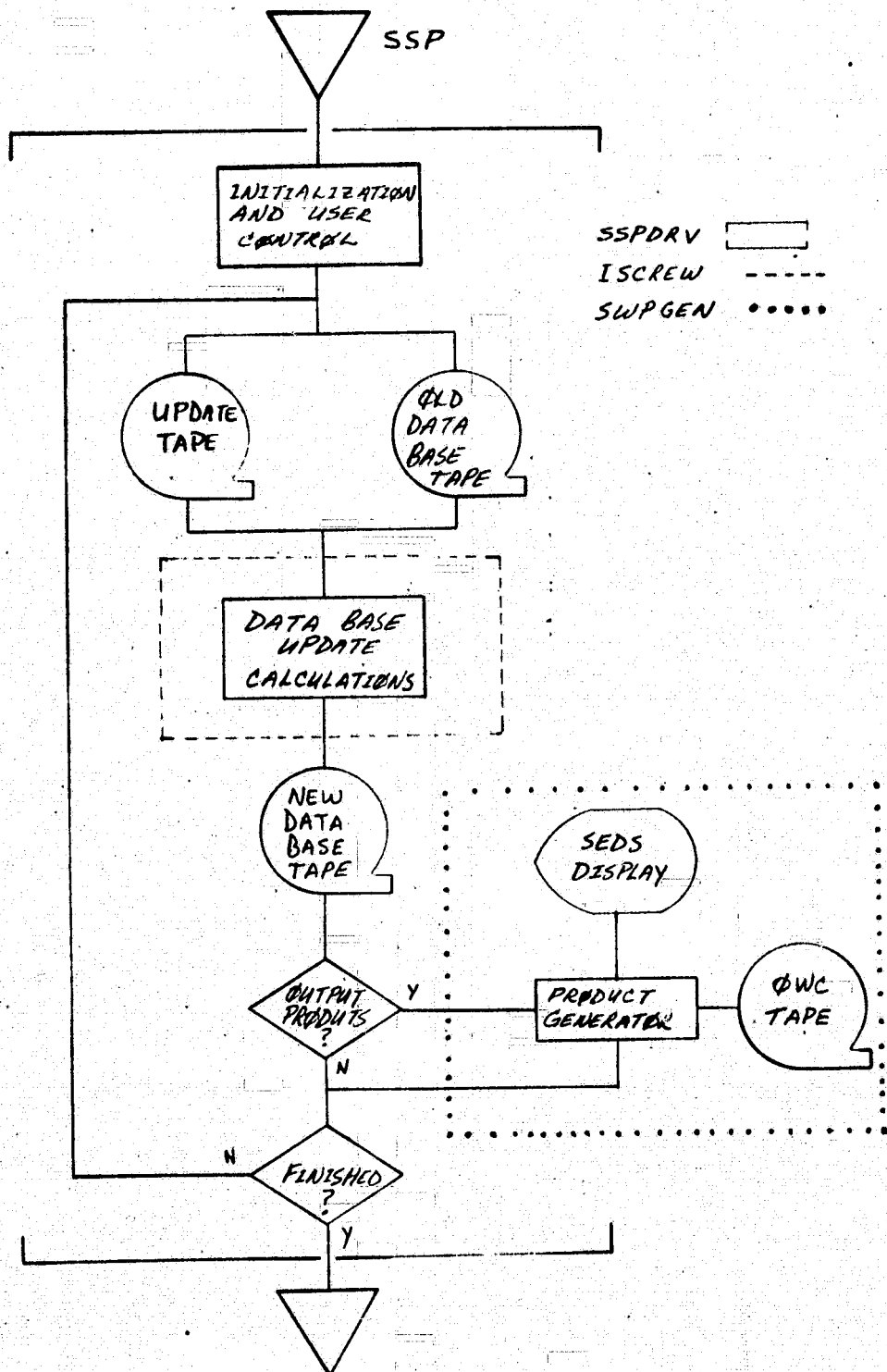


Figure 5-2 SSP Flow Chart

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5.1.3 Timing and Sequencing. SSP is designed to be run following Data Base Sequence No. 1 (RAP) execution. In the normal days production cycle, the new data base update tape from RAP is one of the inputs to SSP. Following SEDS initialization of SSP, the user is required to properly configure before starting SSP. This includes such items as mounting the correct old data base tape and blank tapes on designated tape drives and making selected VT05 entries. Once initialization and setup is complete, program execution is started and continues for about 30 minutes. The source data is the new data base update tape and the previous day's data base tape. These tapes contain similar header records followed by 550 data records, each of which contains information for one scan line. A data record from each tape, representing the same scan line and pixels, is input by the SSP controlling module, SSPDRV. The data is read into memory from tape and passed on to the data base calculations module, ISCREW. Predefined algorithms calculate new running sums, based on the SSP execution mode, old data base, and update tape data. After a data record representing one scan line of new information is generated, control is returned to SSPDRV for the writing of a single record on the new data base tape. Optional control is then passed on to the product generator, SWPGEN. From the information contained in the five channels of the new data base, eight imagery products are calculated and formatted as color maps. The images are output to tape, with one of them being viewed on the SEDS display monitor. Control is returned to SSPDRV, which inputs the next data records from the update and old data base tapes. This sequence continues for 550 cycles until termination.

5.1.4 Storage Allocation. The storage requirements for SSP are illustrated by figure 5-3. As shown by the diagram, the instruction space required by both the controlling module, SSPDRV, and the data base calculations module, ISCREW, is approximately 8K of core storage. The 8K buffer ABUFF is used for update and data base tape input and output. The execution space of the product generation module, SWPGEN, is about 12K of core storage. The 4K buffer, DBUFF, is used as the products calculations transfer buffer and work area for the eight generated images.

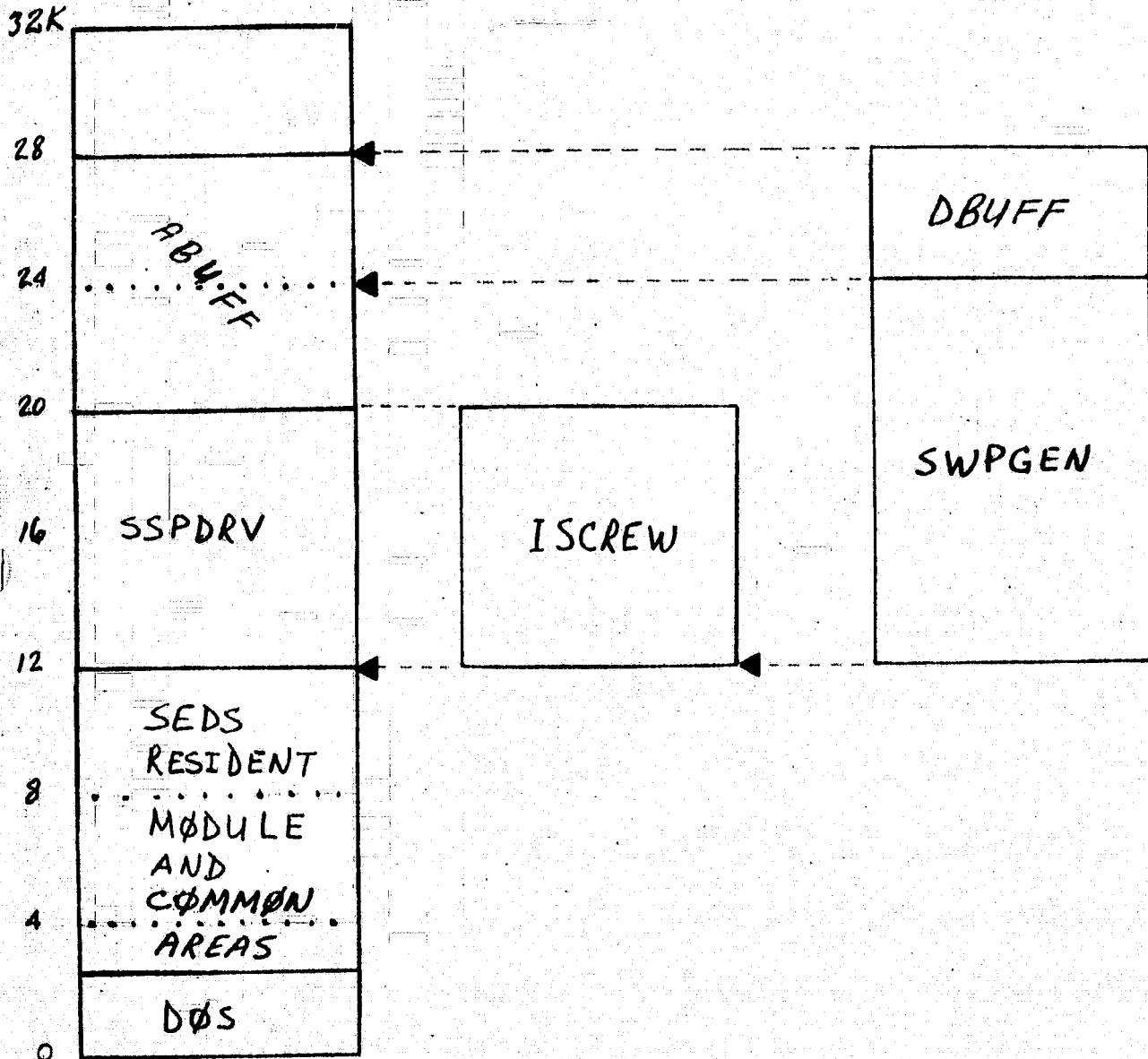


Figure 5-3 SSP Storage Allocation

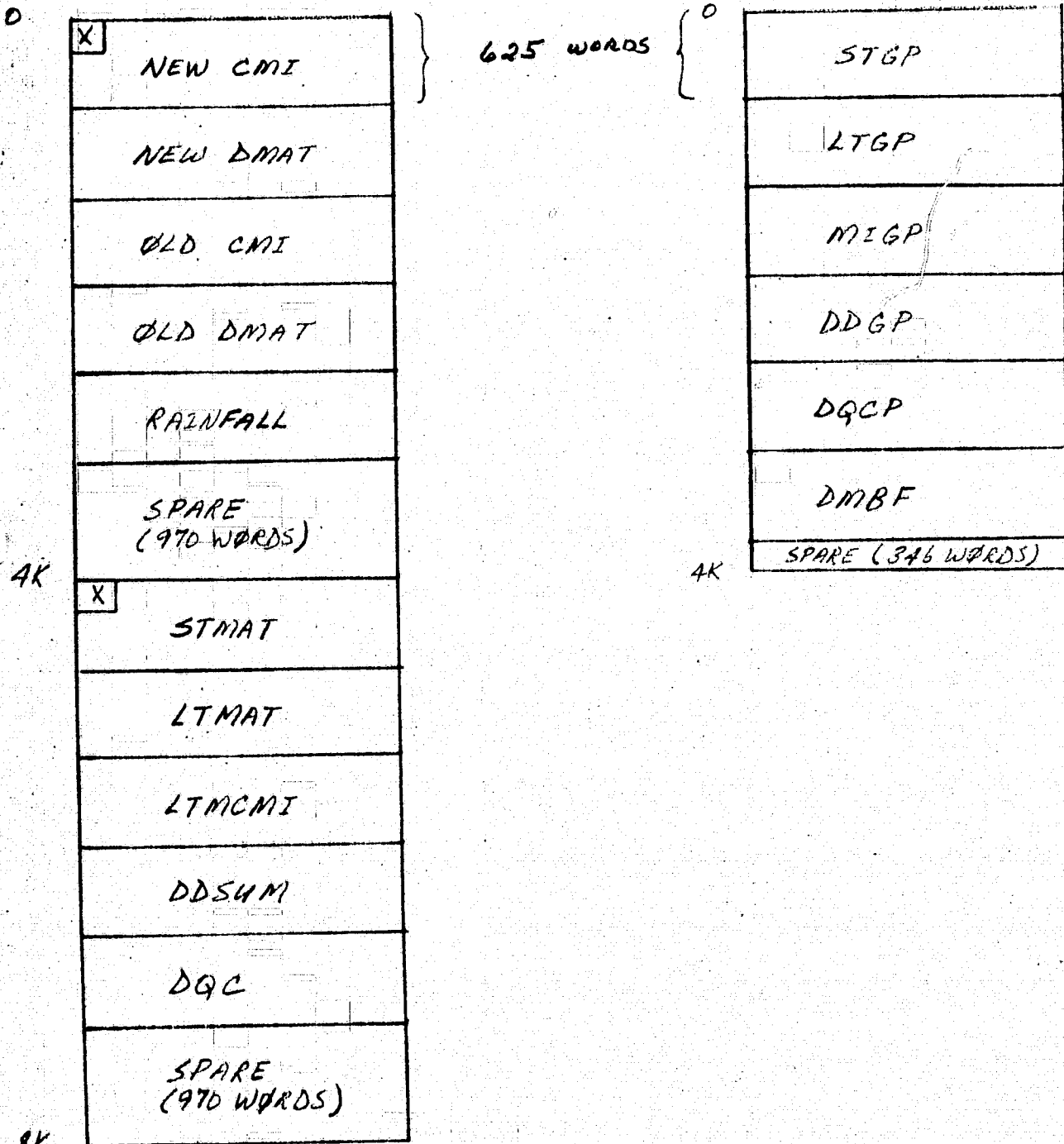
5.1.5 Data Base Characteristics

- A. File Description. The common files of SSP are ABUFF and DBUFF. ABUFF is an 8K storage buffer used for tape input/output sequencing between SSPDRV and ISCREW. The format of ABUFF will assume the data record formats of both the update and data base tapes. DBUFF serves as a linking storage area between ISCREW and SWPGEN. The format of each is described in figure 5-4.
- B. Item Description. ISCREW's processing is determined by user initialization and the parameters set up by SSPDRV. Two factors determine a legal processing mode of SSP, the active channels on the update tape, and the long-term averaging period (N) specified in the header records of both input tapes. The header record format is shown in figure 5-5.
- C. Program Constants. The following seven parameters serve as linkage between SSPDRV and ISCREW.
- DELETE - Delete code (1-4)
 - ADD - Add code (1-6)
 - PRODC - Product code (1 = yes, 2 = no)
 - NOLD - Old data base length (N)
 - NNEW - New data base length (N)
 - CMIOF - Old CMI channel on update tape (NZ = not active)
 - CMINF - New CMI channel on update tape (NZ = not active)

The values of program constants DELETE, ADD, NOLD and NNEW are determined by table 5-1.

ABUFF

DBUFF



[X] - DENOTES 1-WORD COUNTER (1 to 550)

Figure 5-4 ABUFF and DBUFF Files

WORD NO.	15	8 7	0		
1	B		S	TAPE ID(3 CHAR ASCII CODE; SBC = UPDATE, OBC = DATA BASE)	
2	NOT USED		C		
3	2		1		
4	4		3	TAPE NO. (6 DIGITS IN ASCII)	
5	6		5		
6	NO. OF CHANNELS			BINARY CHANNELS ACTIVE(0=NOT ACTIVE, 1=ACTIVE)	
7	1	2	3		4
8	MONTH		DAY		CURRENT DATE (BINARY)
9	NOT USED		YEAR(LAST 2 DIGITS)		
10	DATA BASE LENGTH (N)			BINARY	
11	ORBIT NUMBER				
12	DAY		MONTH		DATE OF DATA (BINARY)
13	NOT USED		YEAR(LAST 2 DIGITS)		
14	SPARE				
15	SPARE				

- DATA BASE UPDATE TAPE (SEQ. NO. 1 - RAP)
- DATA BASE TAPES (SEQ. NO. 2 - SSP)

Figure 5-5 Header Record Format

TABLE 5-1

PROGRAM CONSTANTS DELETE, ADD, NOLD AND NNEW

SSP PROCESSING MODE	UPDATE TAPE CHANNELS ACTIVE				RUN FLAGS		DATA+ BASE LENGTH (N)
	NEW		OLD		ADD	DELETE	
	CMI	DMAT	CMI	DMAT			
NORMAL (ADD AND DELETE) ALL DATA PRESENT	YES	YES	YES	YES	1	1	NNEW=NOLD
NORMAL (OLD DATA MISSING)	YES	YES	NO	NO	2	2	NNEW=NOLD
ADD	YES	YES	NO	NO	3	4	NNEW=NOLD+1
ZERO* (NEW DATA MISSING)	YES	YES	NOT CHECKED		4	3	NNEW=NOLD
DELETE*	YES	YES	NOT CHECKED		5	3	NNEW=NOLD-1
INITIAL	YES	YES	NO	NO	6	4	NNEW=1

* UPDATE TAPE USED IS THE DELETE TAPE USED AS INPUT TO RAP. (NEW CHANNELS BECOME OLD)

* NOLD = DATA BASE LENGTH (N) FROM OLD DATA BASE TAPE.
NNEW = DATA BASE LENGTH (N) OF NEW DATA BASE TAPE.

5.2 SSP CPC CHARACTERISTICS

This paragraph contains a detailed technical description of the CPC's identified in paragraph 5-1. The instruction listings contained herein, by inclusion or reference, specify the exact configuration of SSP.

5.2.1 SSPDRV. SSPDRV is the controlling or driving component of SSP. Its functions have been previously defined in paragraph 5.1. The module is composed of several separate subcomponents. One subroutine, called "SSPDRV," is written in PDP-11 FORTRAN and acts as the driver linking SSP with the SEDS control. The other subcomponents are written in PDP-11/45 assembly language. They are described in the following paragraphs.

5.2.1.1 Subcomponent Descriptions

- A. "SSPDRV". This subcomponent of the component SSPDRV is the SSP driver routine of SEDS. "SSPDRV" is necessary because of the system segmentation and overlay software utilized by SEDS.
- B. "SSP". This is the title given to the main subcomponent of the component SSPDRV. As previously stated, user control and processing sequencing are the primary functions of the SSPDRV component. User control is accomplished through the VT05B alphanumeric display terminal, consisting of a CRT display and self-contained keyboard. "SSP" utilizes special SEDS VT05 input/output software. VTLINK is the "SSP" routine called directly for linkage to the VT05. VTLINK is discussed elsewhere in this document; however, it should be stated that VTLINK allows the SSP VT05 display to be initialized and sets up user-changeable input fields. The SSP-initialized VT05 display is shown in figure 5-6. Error messages and operator advisory instructions are output to the VT05. Tape input and output control is performed through interface with two subroutines, STOC1 and STOC2. "SSP" makes segmentation and core overlay calls to bring in ISCREW and SWPGEN. Program termination and return to SEDS residence control are other functions of "SSP."

SCREWORM SURVIVAL PROGRAM
 *** DATA BASE UPDATE SEQN #2 *** DATE: 09-DEC-75
 MORE ENT
 DATA BASE PRODUCTS 01=LONG TERM AVERAGING PERIOD
 A=ADD 0=NONE (NEW DATA BASE LENGTH)
 D=DELETE 1=DISPLAY 1=EMPIRICAL FUNCTION SET
 I=INITIAL 2=TAPE (CHANGE FROM ONGOING TO SET 2 AT SCAN 551)
 N=NORMAL 3=BOTH
 Z=ZERO

SCREWORM GROWTH
 IUPDATE=(0)(00) C=100 A1=+0.46 A3=+0.36
 OLD DR=(0)(00) A0=+0.00 A2=+0.22 A4=+0.40

 * ORBIT NBR=00000
 * DATE OF DATA=00=00=00

TAPE I-O ASSIGNMENTS

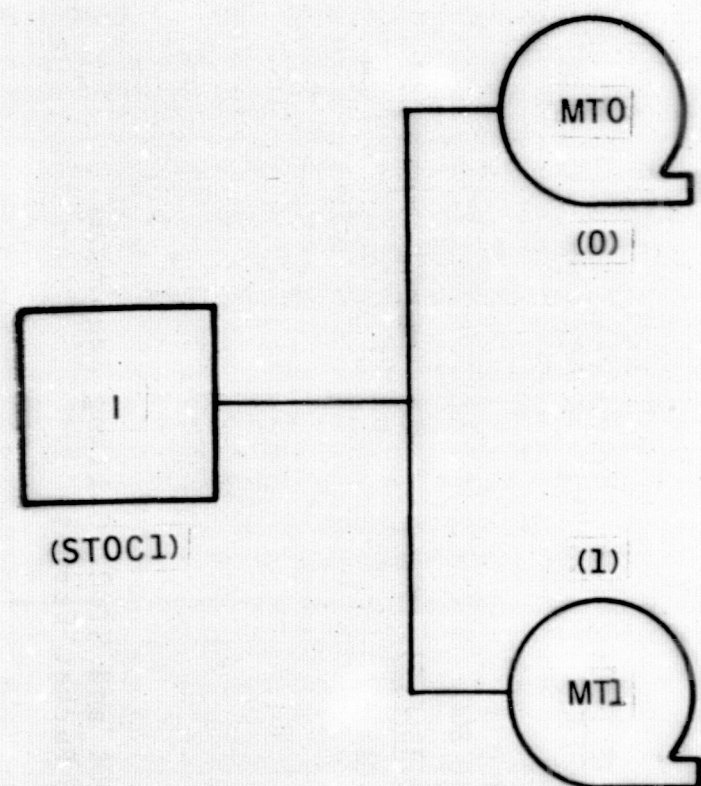
IUPDATE TAPE ()=MT0 NEW DATA BASE(XXXXXX)=MT1
 CWE PRODUCTS (XXXXXX)=MTA0 OLD DATA BASE()=MTA1

Figure 5-6 SSP Initialized VT05 Display

- C. STOC1. This is the subcomponent called by "SSP" to perform various tape input/output functions for the tape units of tape controller 1.
- D. STOC2. This is the subcomponent called by "SSP" to perform the various tape functions of tape controller 2. The existing Bucode tape drive configuration for SEDS is shown in figure 5-7. The calling sequences and packet format are detailed in figure 5-8.
- E. GNDATE. This is a subroutine that converts the ASCII date stored in the SEDS-resident locations DAY, MONTH, and YEAR to binary.
- F. DQCAL. This is an assembly language subroutine that updates and calculates the fifth data base channel. The channel is called the data quality channel or DQC, and consists of two 8-bit subchannels per 16-bit channel word. The two subchannels are NGOOD and STQUAL. NGOOD is the number of days of good satellite data out of the last N days of data for each pixel. The determination of NGOOD for each pixel is the value of DQFLAG, which is placed in the most significant byte of the DMAT channel of the data base update tape. Figure 5-9 details the logic of the NGOOD subchannel update. The second subchannel is the short-term mean quality value, STQUAL.

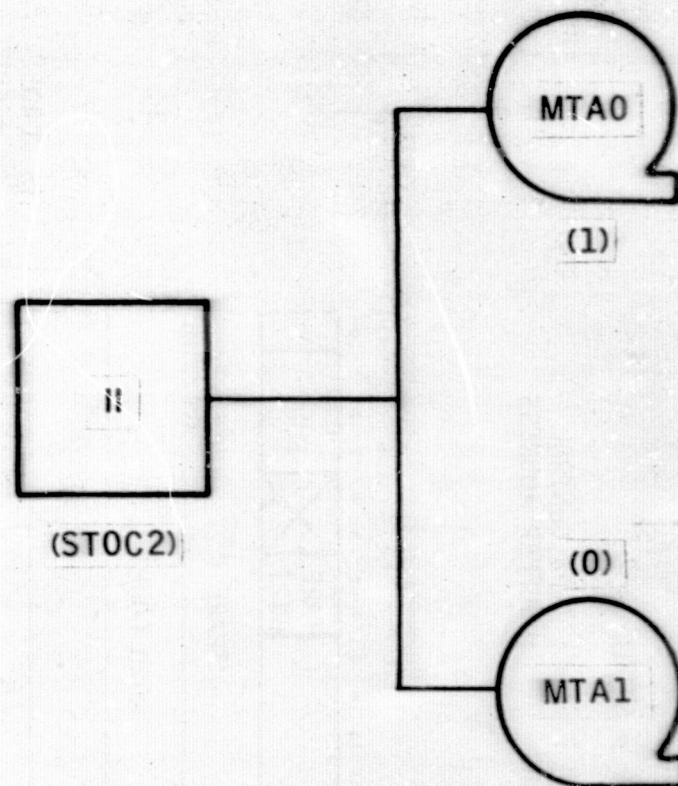
This 8-bit value is stored in the most significant byte of the DQC word for each pixel. It is updated from the DQFLAG of the new DMAT channel on the data base update tape. A new parameter, QVALUE, is set for each pixel as follows.

<u>DQFLAG</u>	<u>QVALUE</u>	<u>EXPLANATION</u>
0	255	All data ok
1	128	MET data only
2	192	Satellite data only
3	0	No data



EMT 140

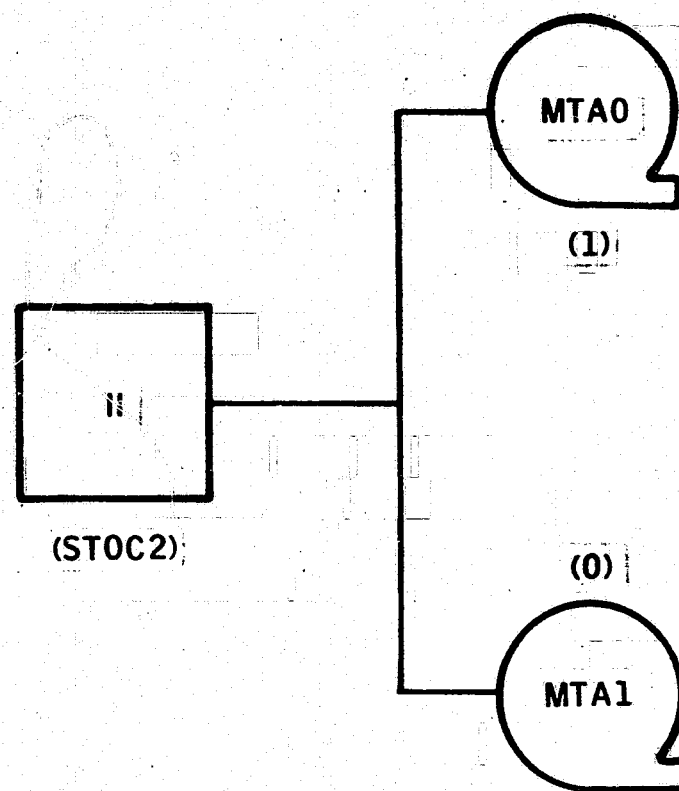
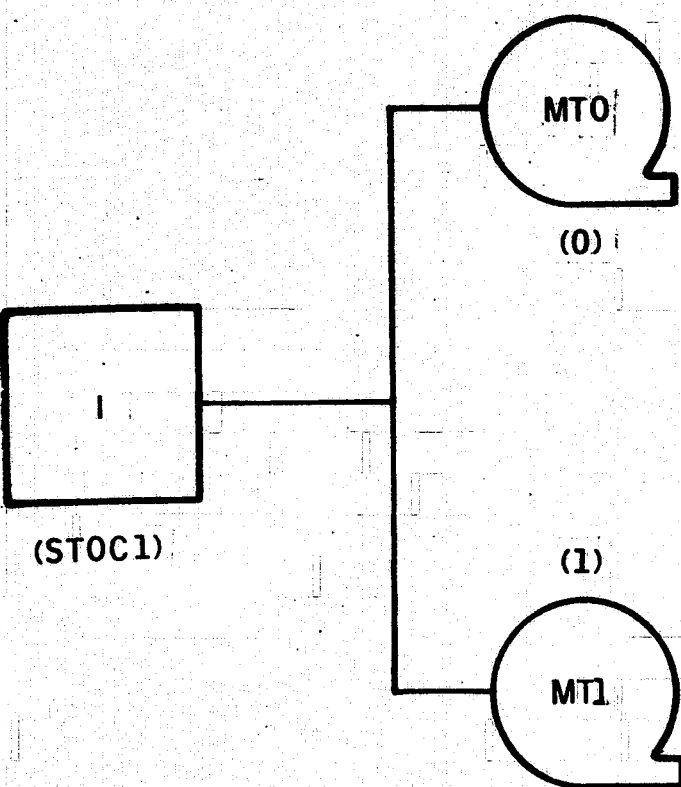
- INTERRUPT VECTOR - 224₈
- PRIORITY - 226 (240)



EMT 145

- INTERRUPT VECTOR - 260
- PRIORITY - 262 (240)

Figure 5-7 BUCODE Tape Drive Configuration



EMT 140

- INTERRUPT VECTOR - 224₈
- PRIORITY - 226 (240)

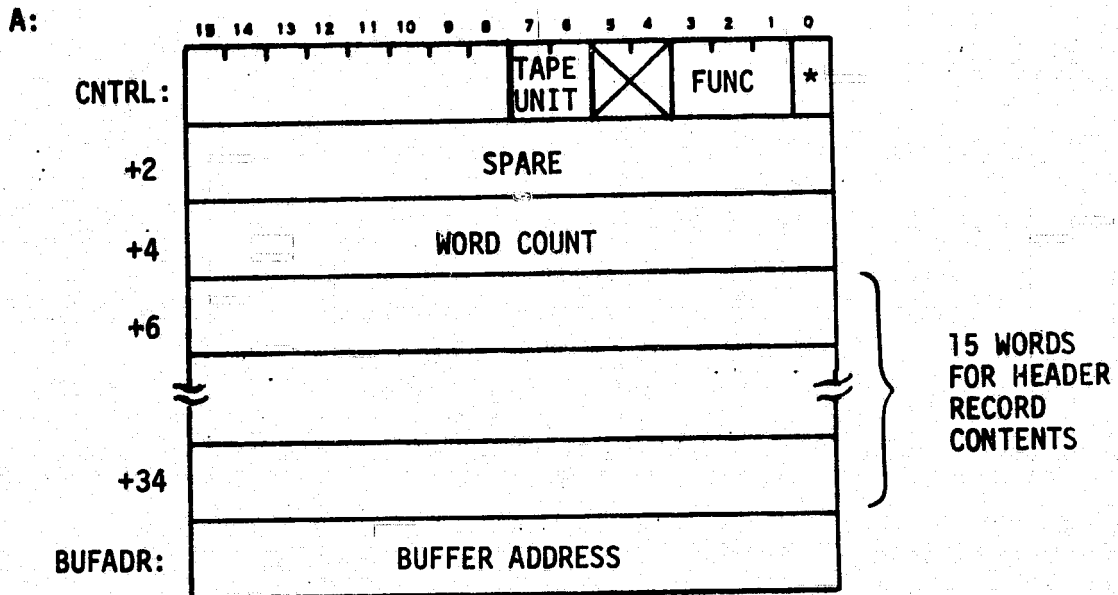
EMT 145

- INTERRUPT VECTOR - 260
- PRIORITY - 262 (240)

Figure 5-7 BUCODE Tape Drive Configuration

CALL TO STOC1 AND STOC2:

```
JSR    R5, @ # STOC1 OR 2
BR     A
.WORD  CNTRL      ; TAPE CONTROL
.WORD  BUFADR     ; BUFFER ADDRESS
```



*FIRST TIME THRU

FUNCTION (BITS 1-3):

001 = READ
010 = WRITE
111 = REWIND
011 = WRITE EOF

TAPE UNIT (BITS 6,7):

NO. 00 OR 01

Figure 5-8 STOC1 and STOC2 Calling Sequences
and Packet Format

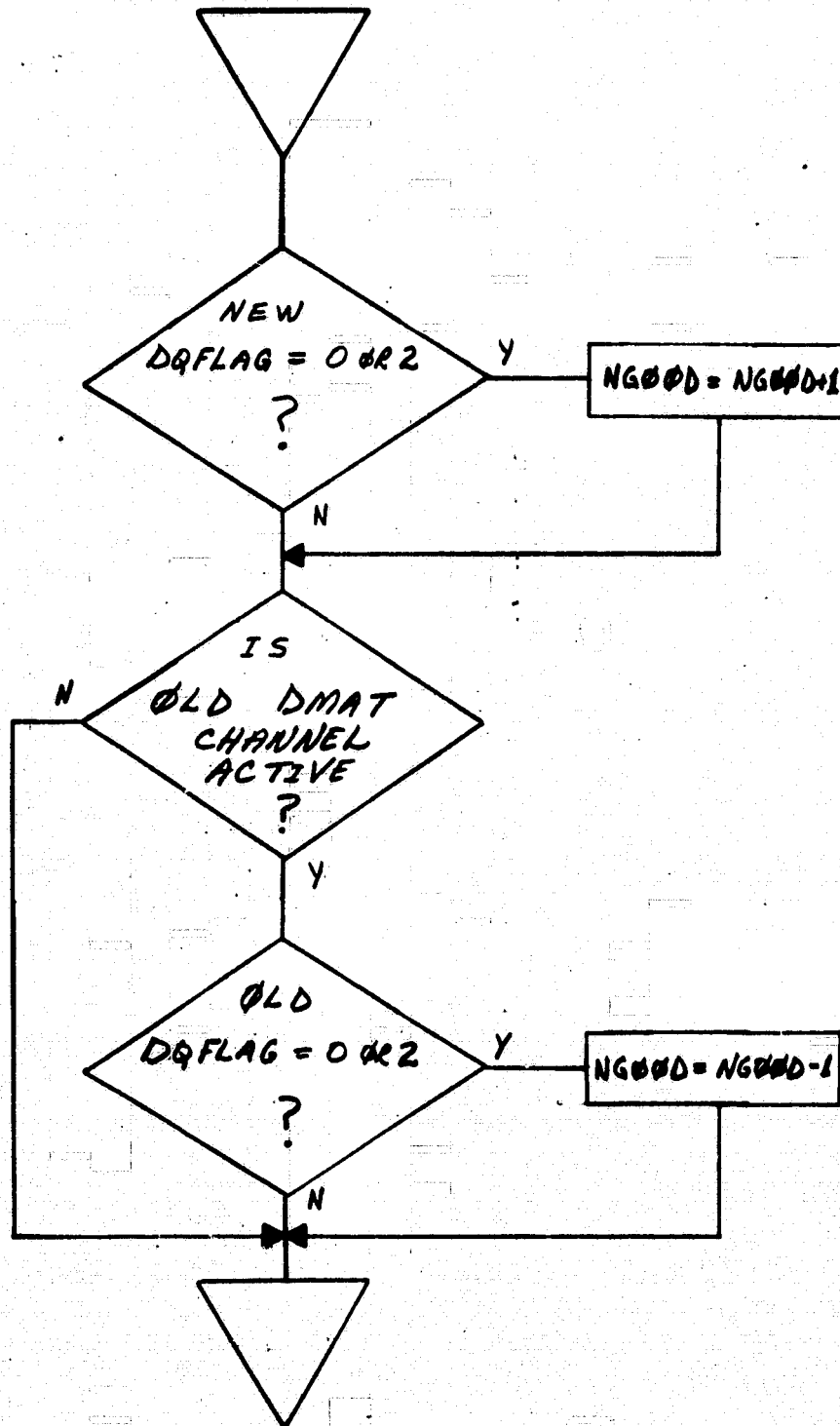


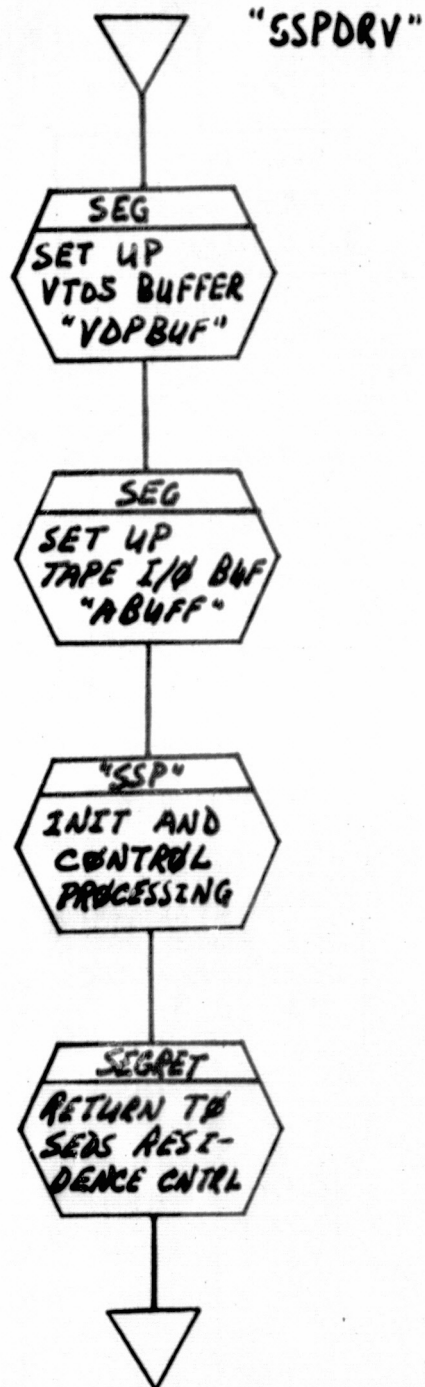
Figure 5-9 NGOOD Subchannel Update Logic

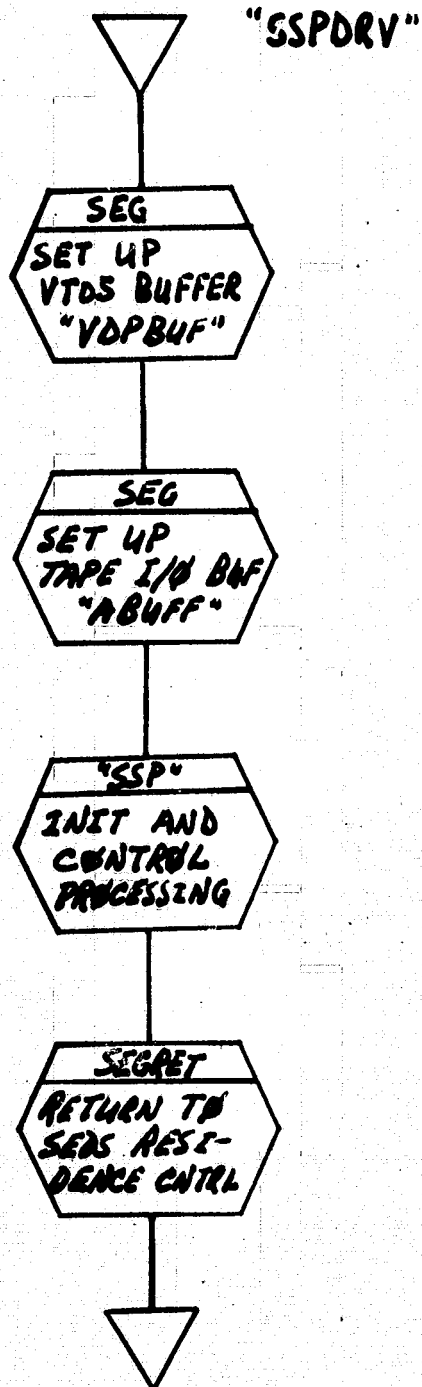
Using the STQUAL value from the old data base tape, the following formula is used to calculate the new STQUAL subchannel:

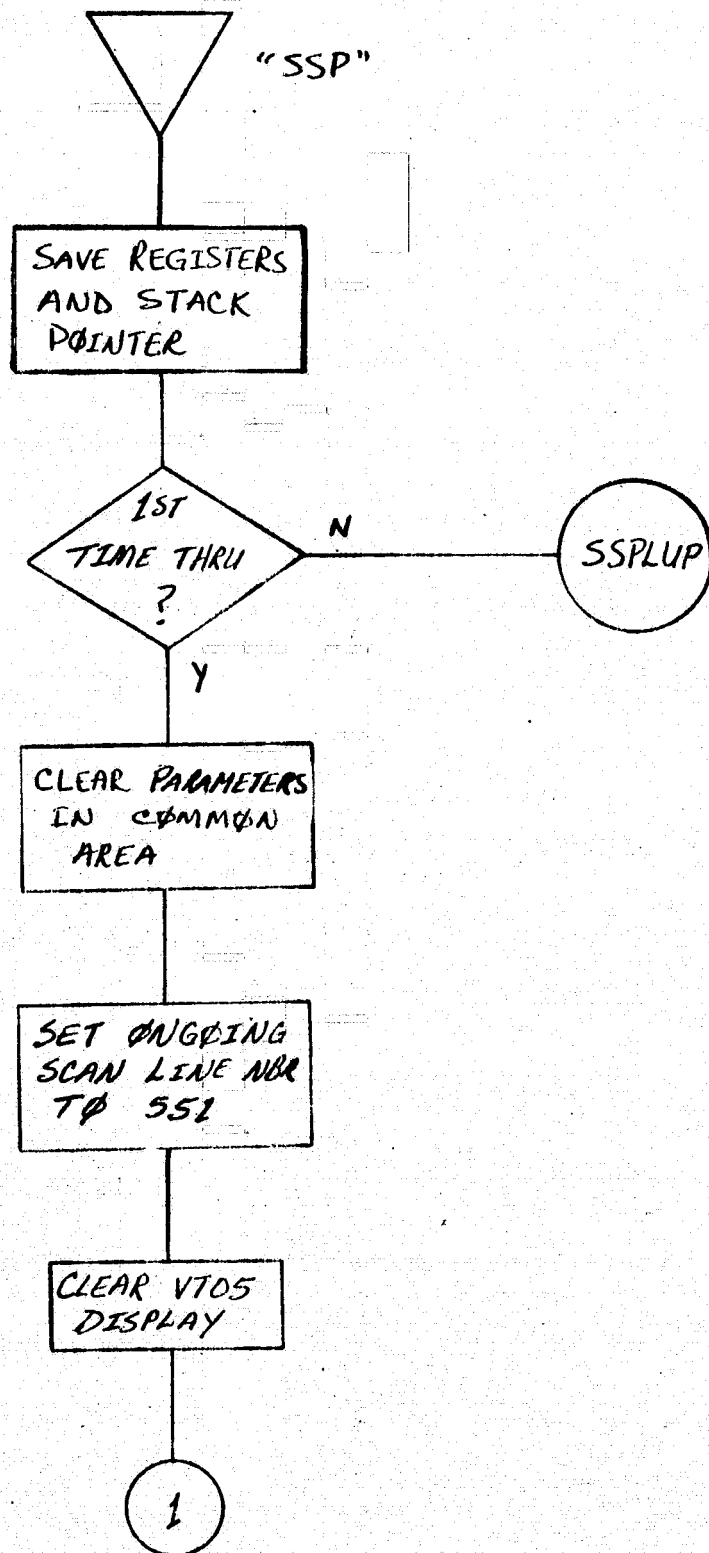
$$\text{STQUAL}_{(\text{NEW})} = [(0.44) * \text{QVALUE} + (0.56) \text{STQUAL}_{(\text{OLD})} + 0.5]$$

- G. SSPDKI. This is an assembly language subroutine called by "SSP" to read from disk the six screwworm growth constants used in calculating the combined screwworm product. The product is output as the fifth product on the OWC tape. The data resides in the file AIKSWP.TBL on DK0 under the user's identification code (UIC) 200,200. The 36-word disk file contents is in ASCII code which is used as a default condition of the SSP VT05 display. The exact format and layout of the file is specified in paragraph 5.2.1.3.
- H. SSPDKO. This is an assembly language subroutine called by "SSP" to write back to disk the six screwworm constants. This subroutine is the write counterpart of SSPDKI.
- I. RETRY1. This is an assembly language subroutine called by "SSP" if read parity errors are encountered on tape controller No. 1 tape drives. The configuration of SSP dictates that the data base update tape be input from device MT0. When read parity errors are detected for a given record, 10 attempts are made to read the record error-free. If all are unsuccessful, a VT05 advisory message is output, and an abort condition exists.
- J. RETRY2. This subroutine is identical to RETRY1 except that it processes read parity errors on tape controller No. 2 tape drives. The old data base tape is input from device MT3.
- K. DQCMOV. This subroutine transfers 625 16-bit data words from DQCBUF into another buffer specified by R2.
- L. REFRSH. This subroutine refreshes the initial VT05 display for SSP.

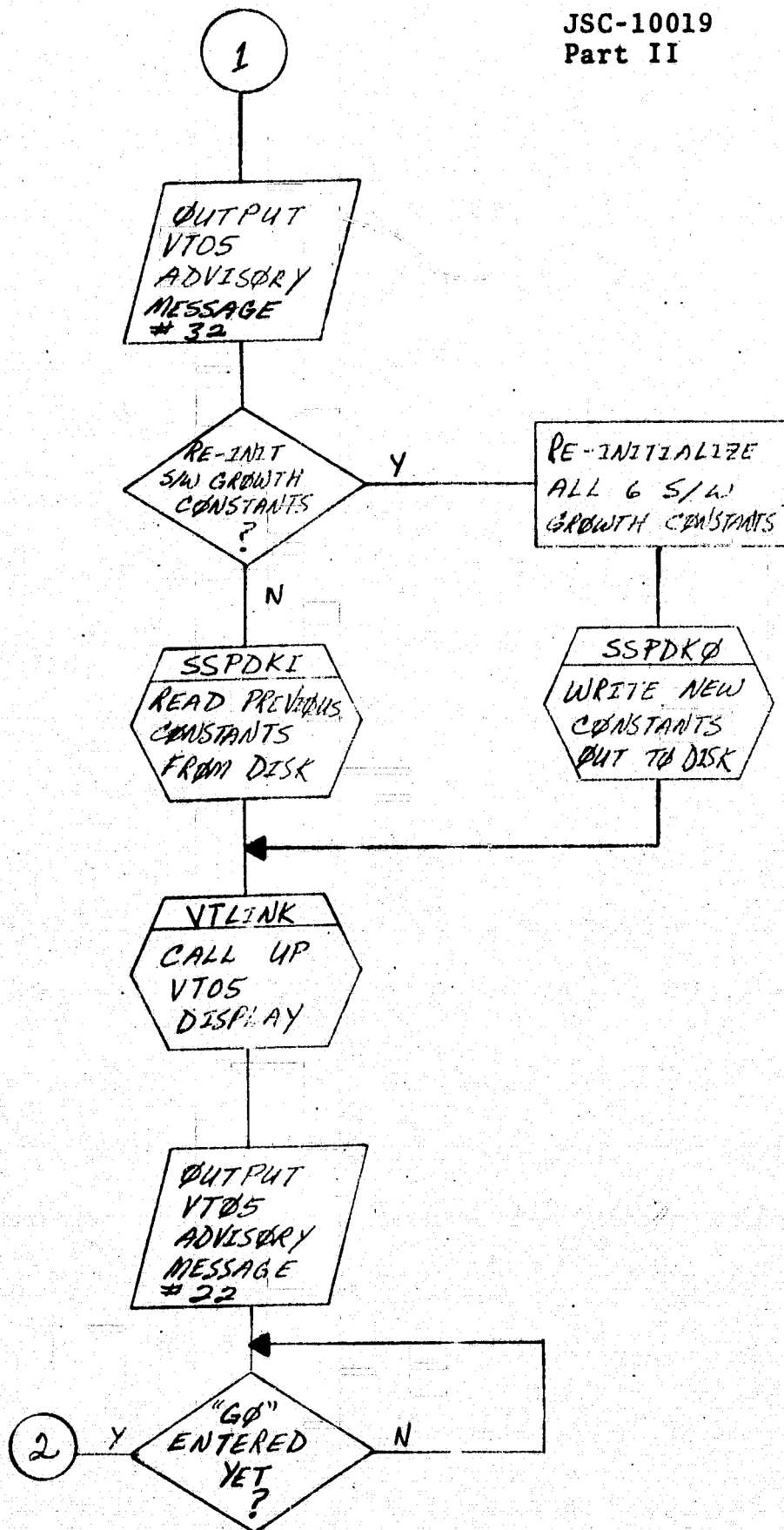
5.2.1.2 Flow Charts. See following 44 pages.

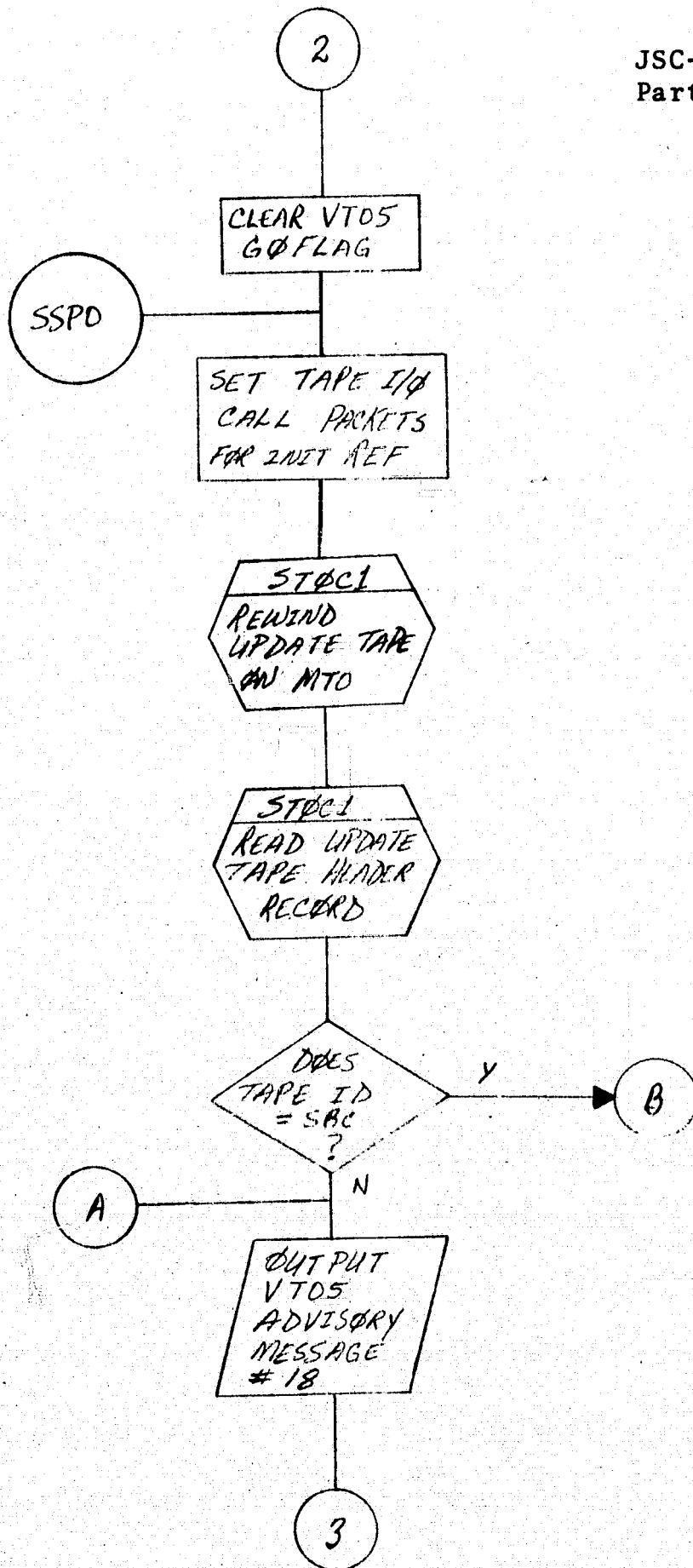


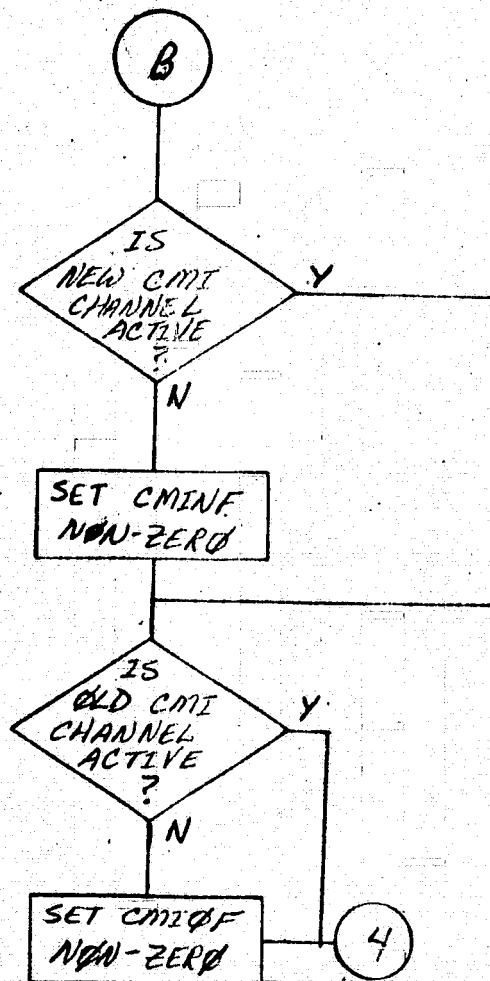
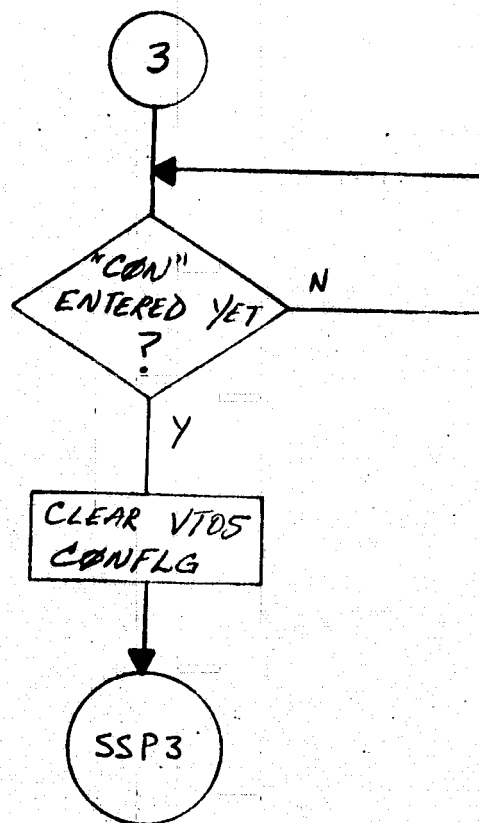


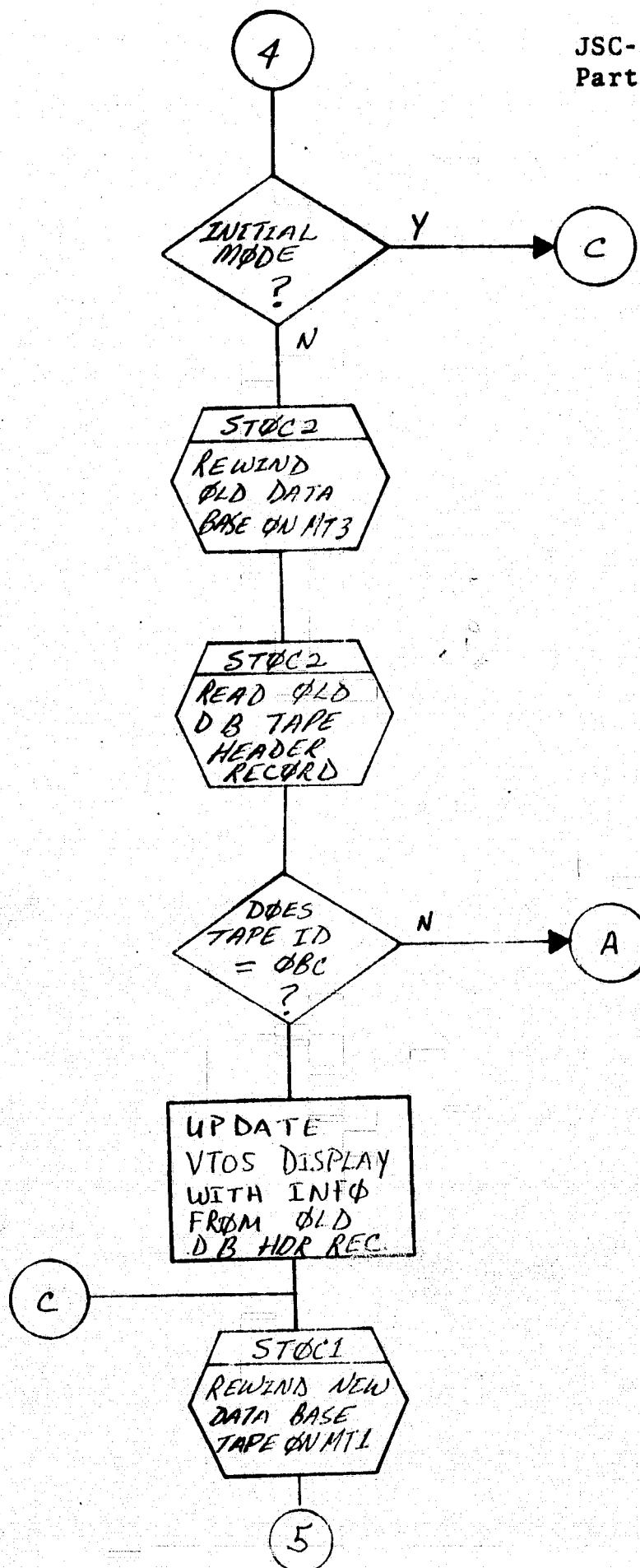


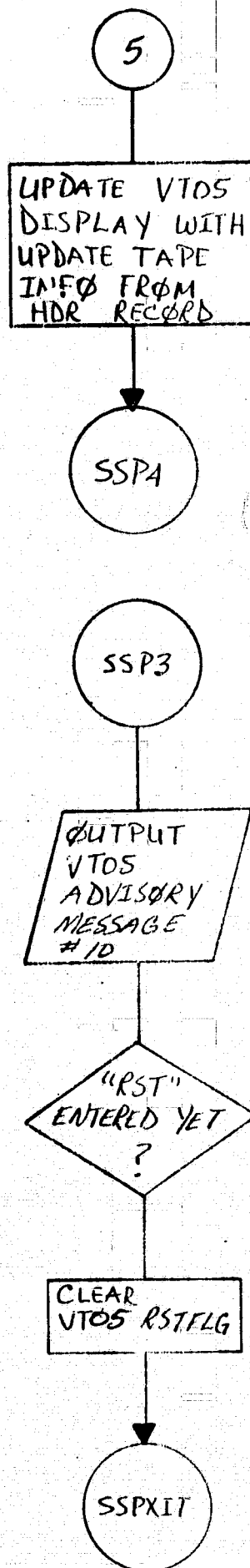
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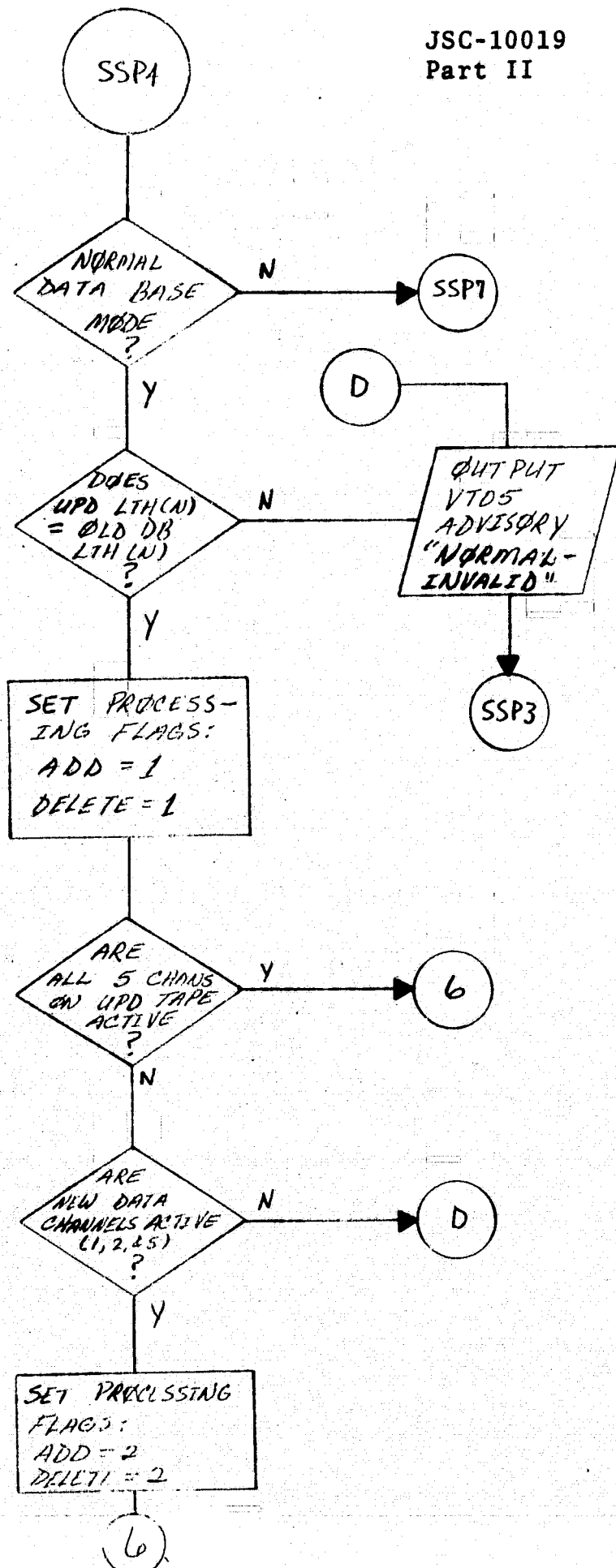


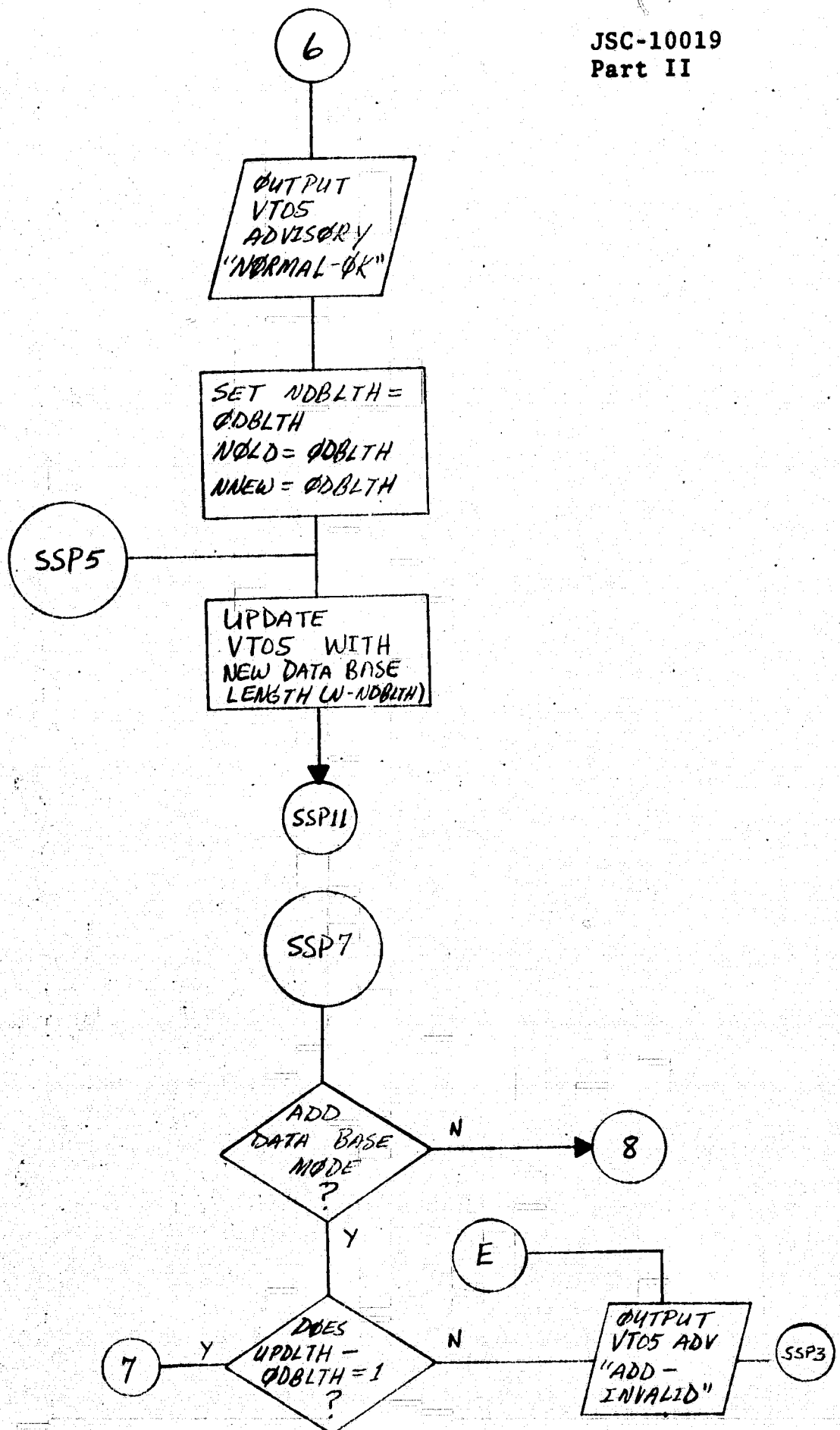


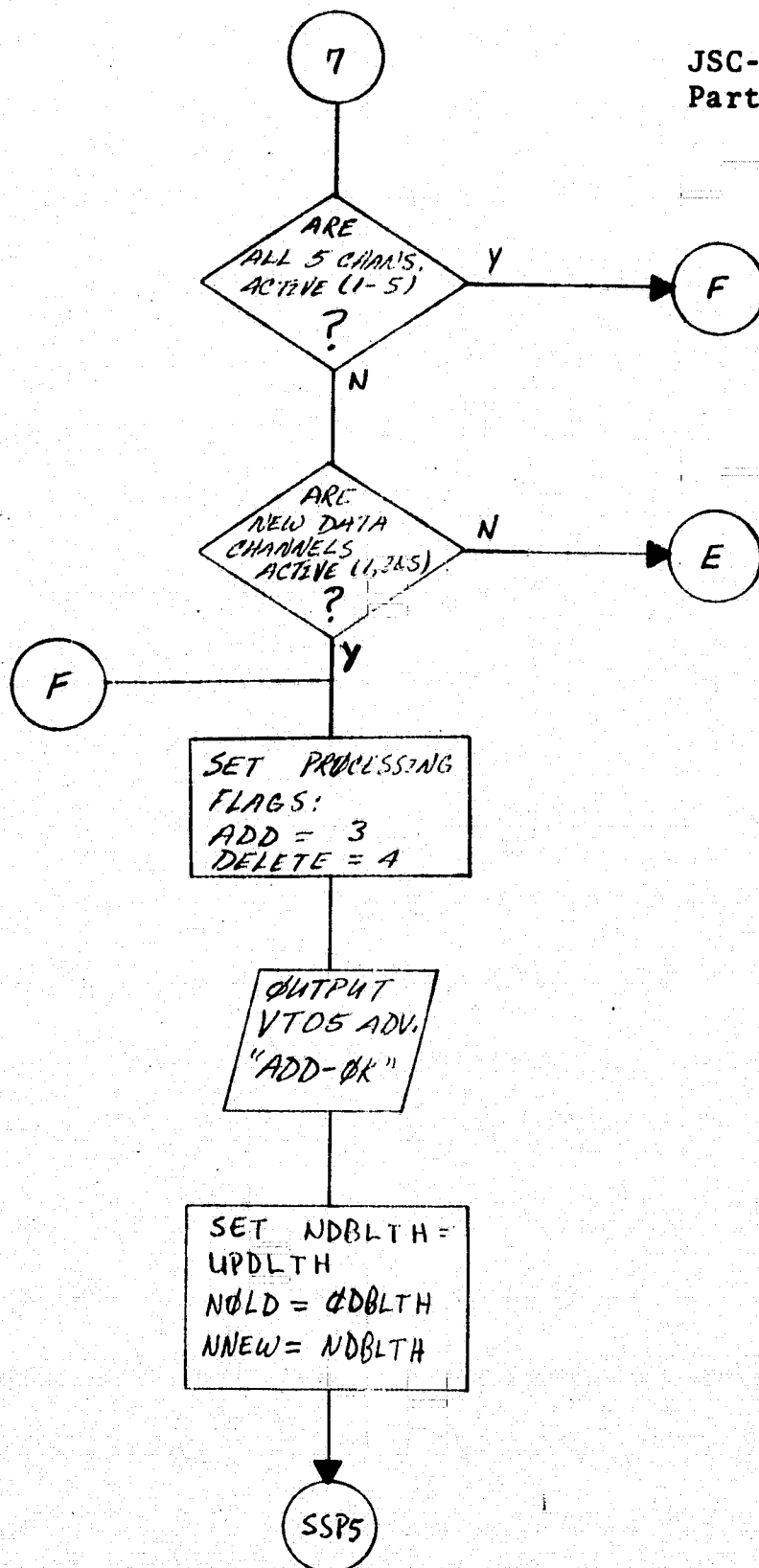


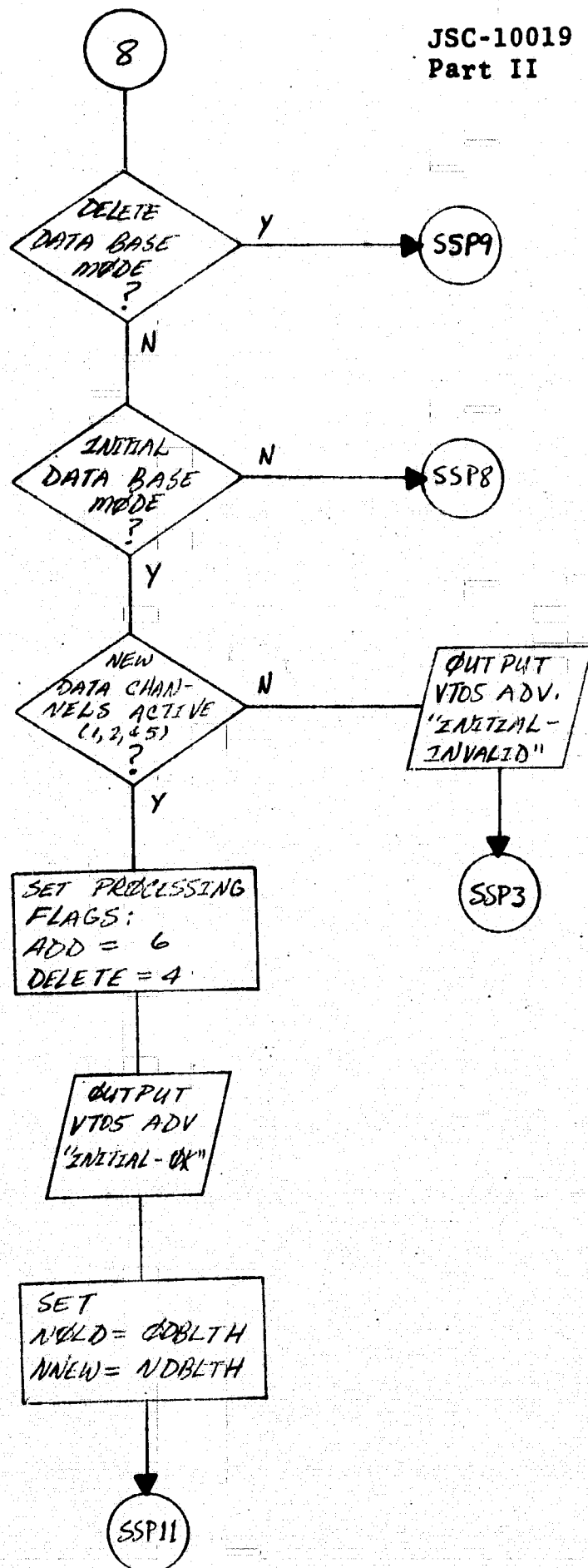


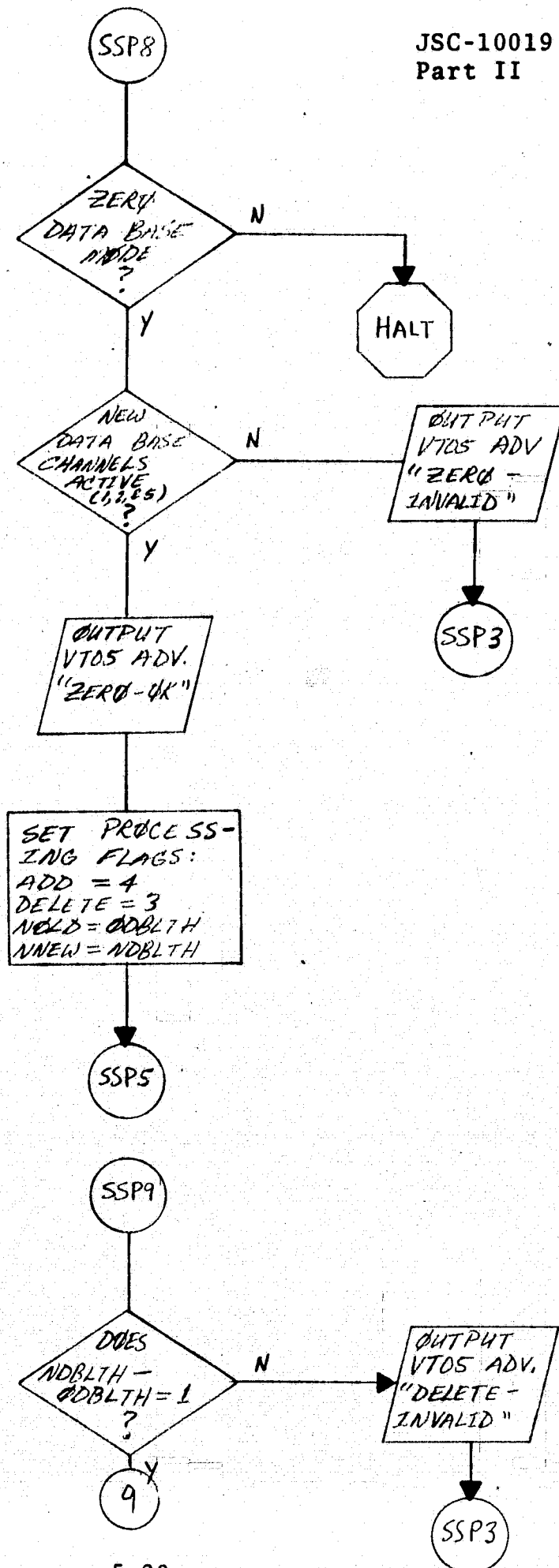
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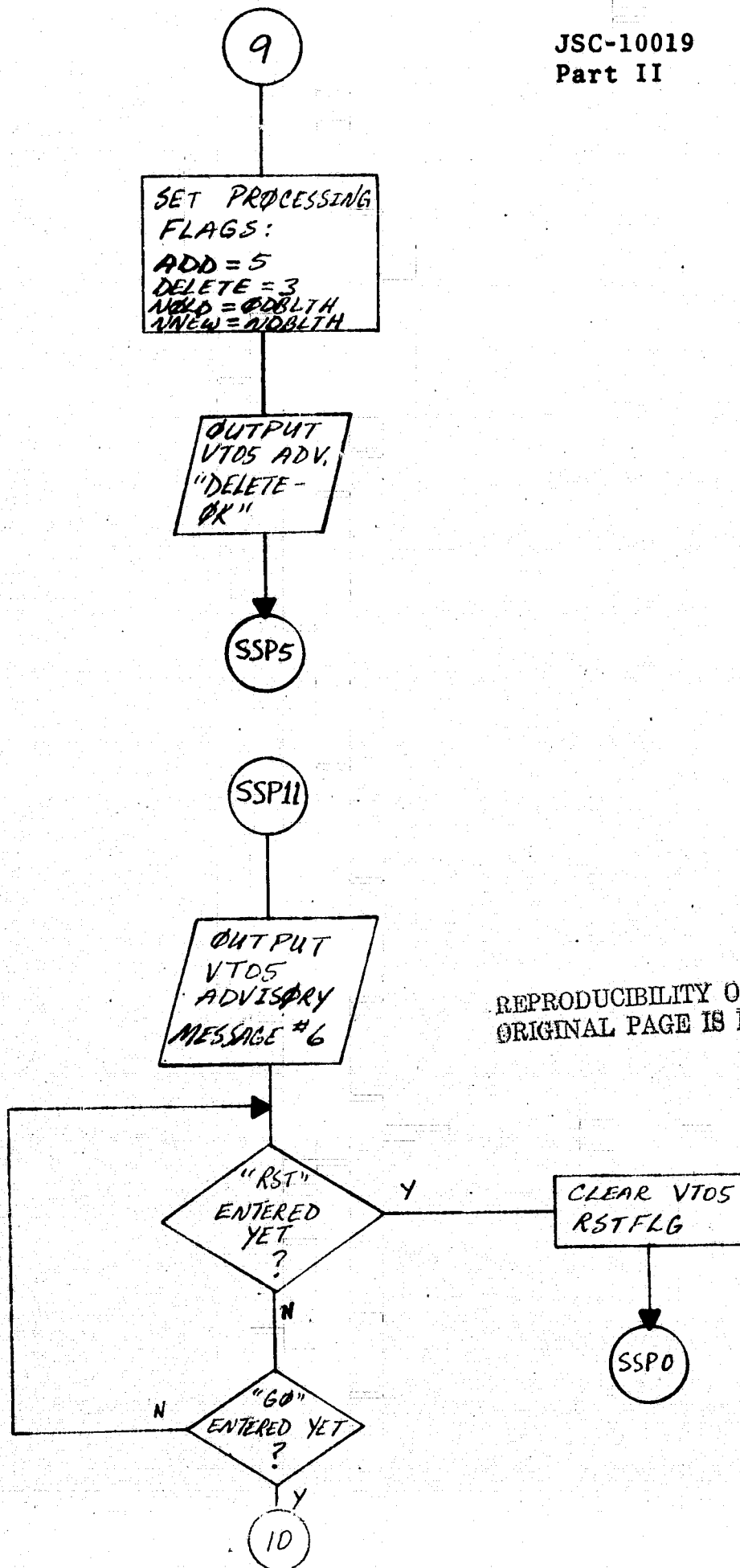




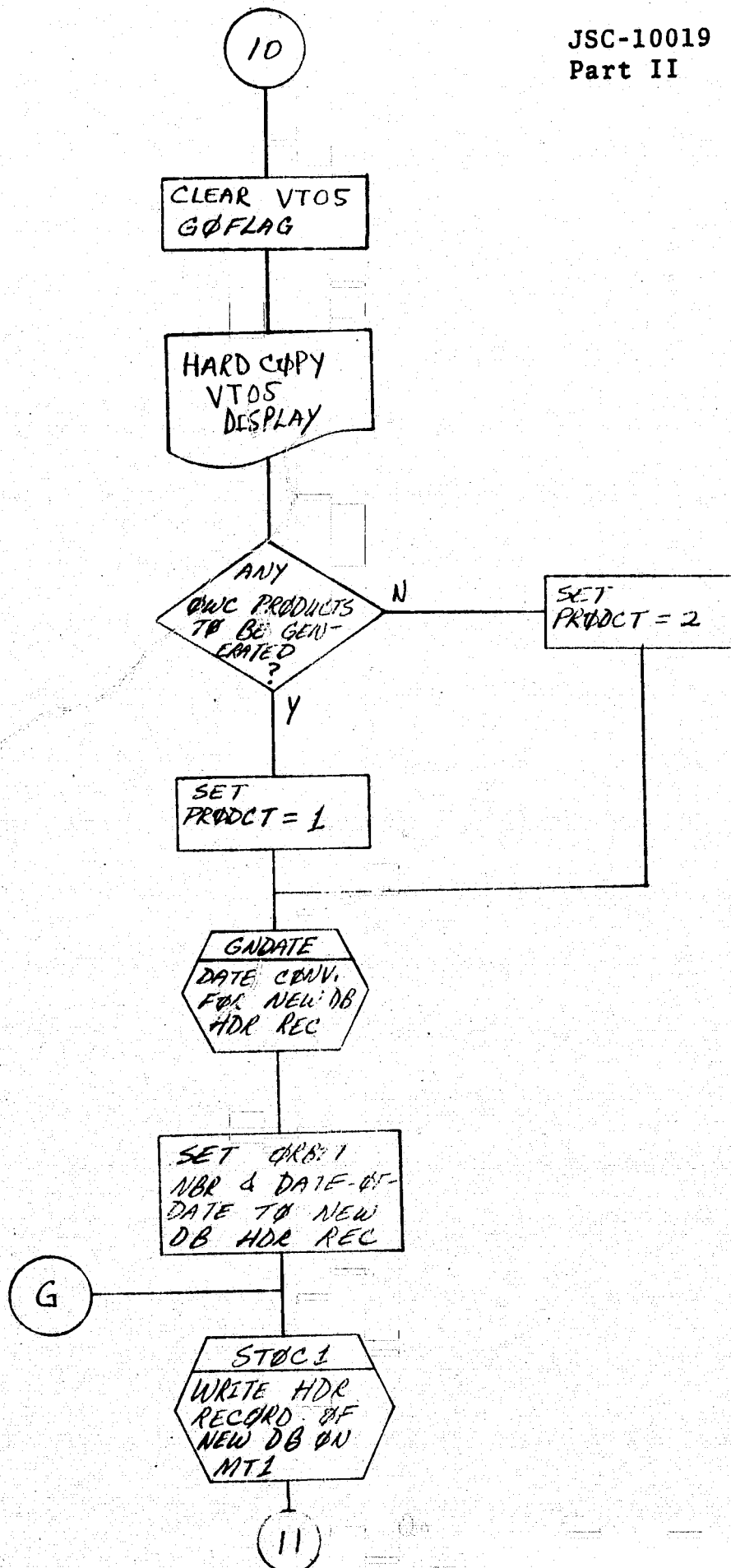


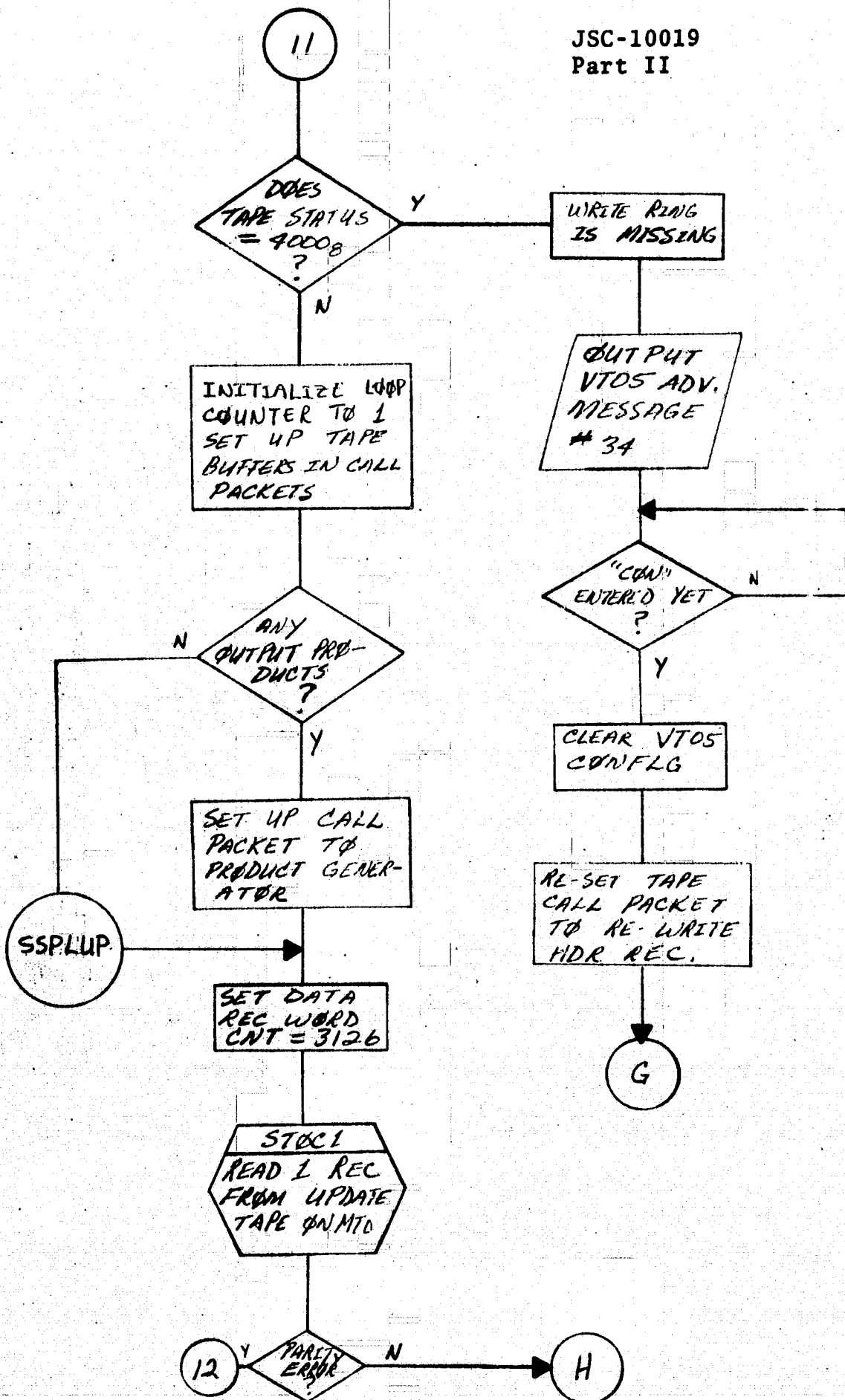


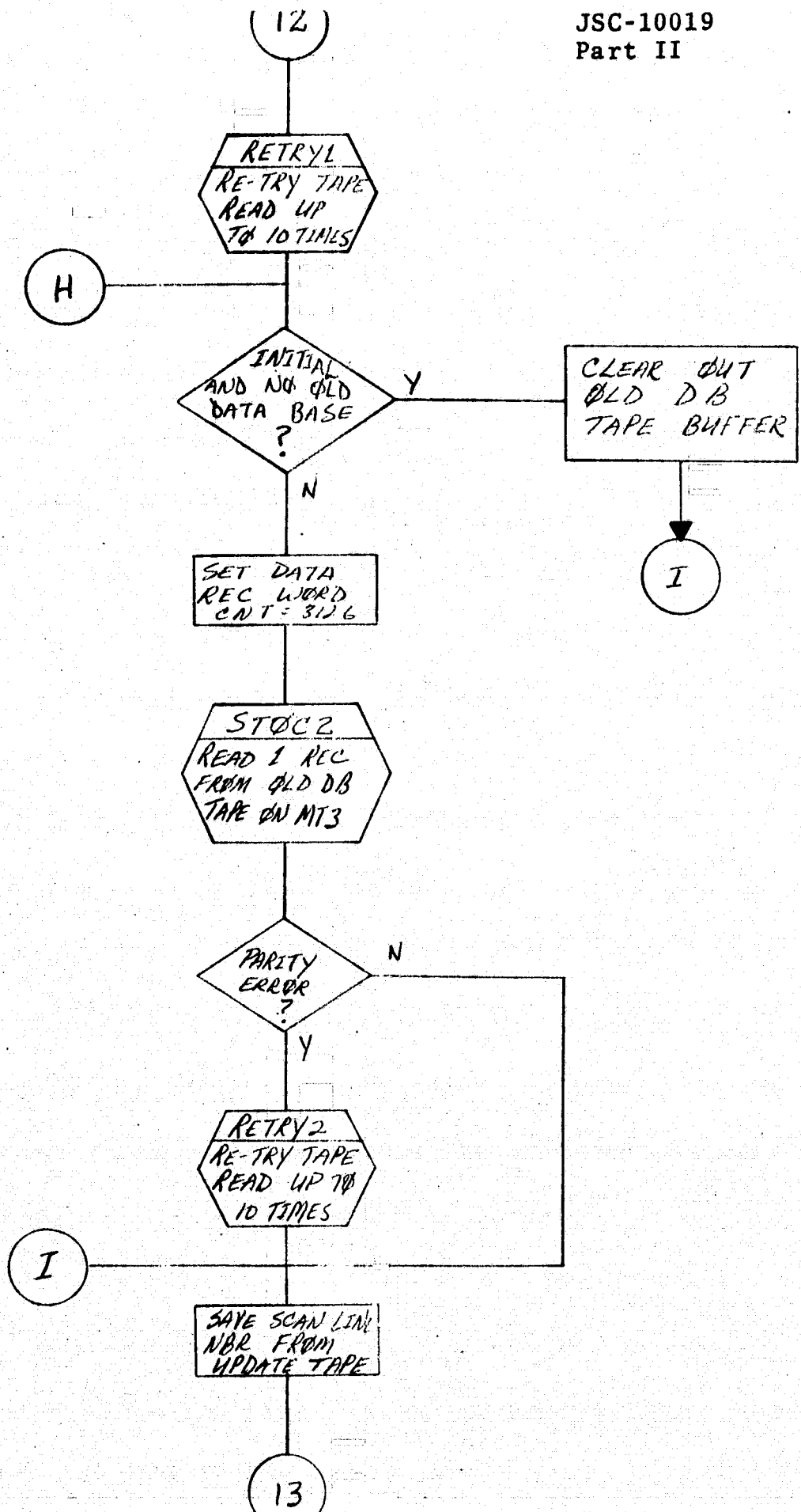


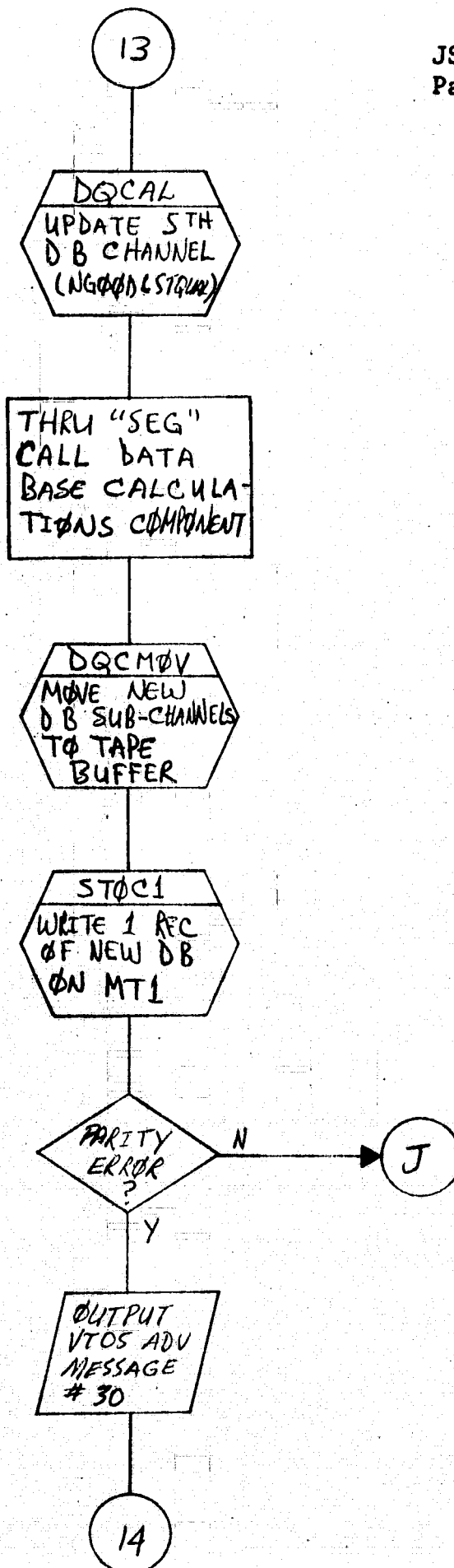


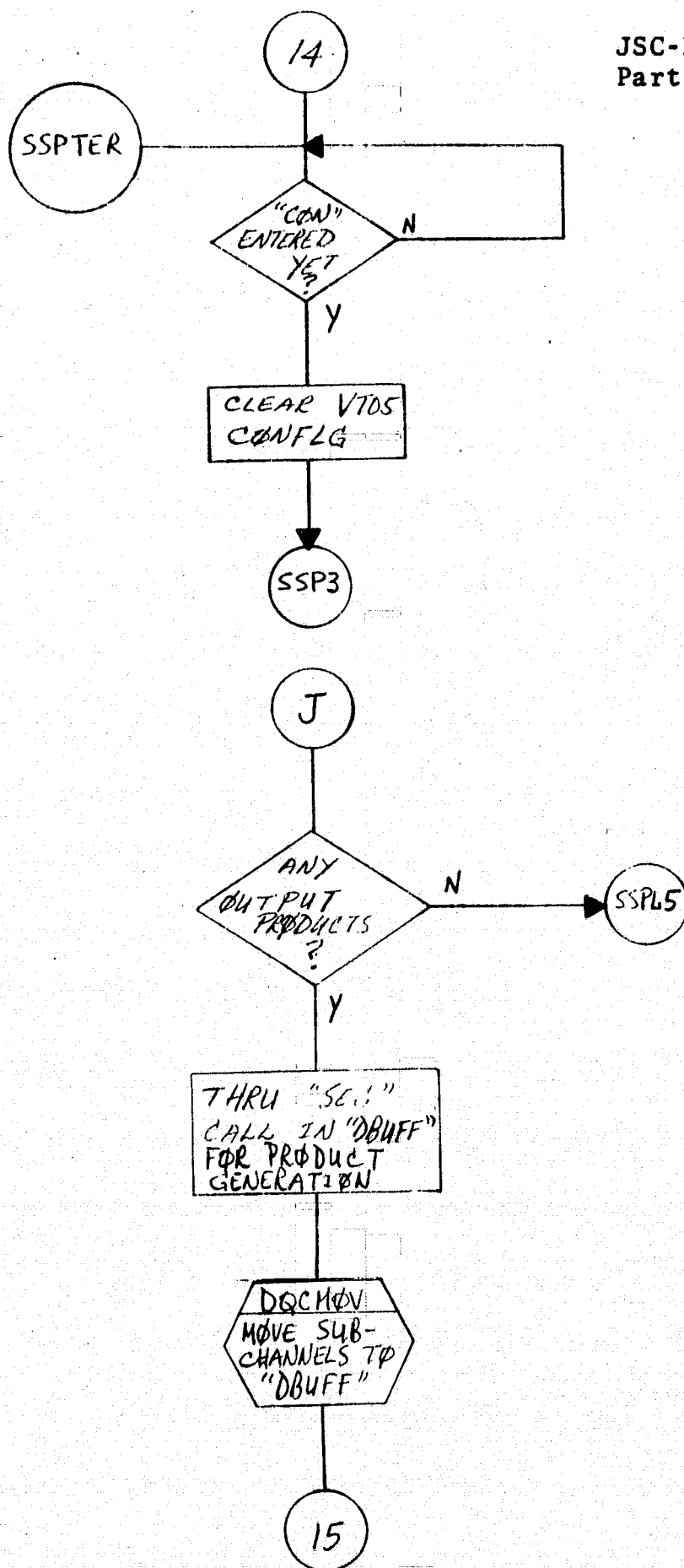
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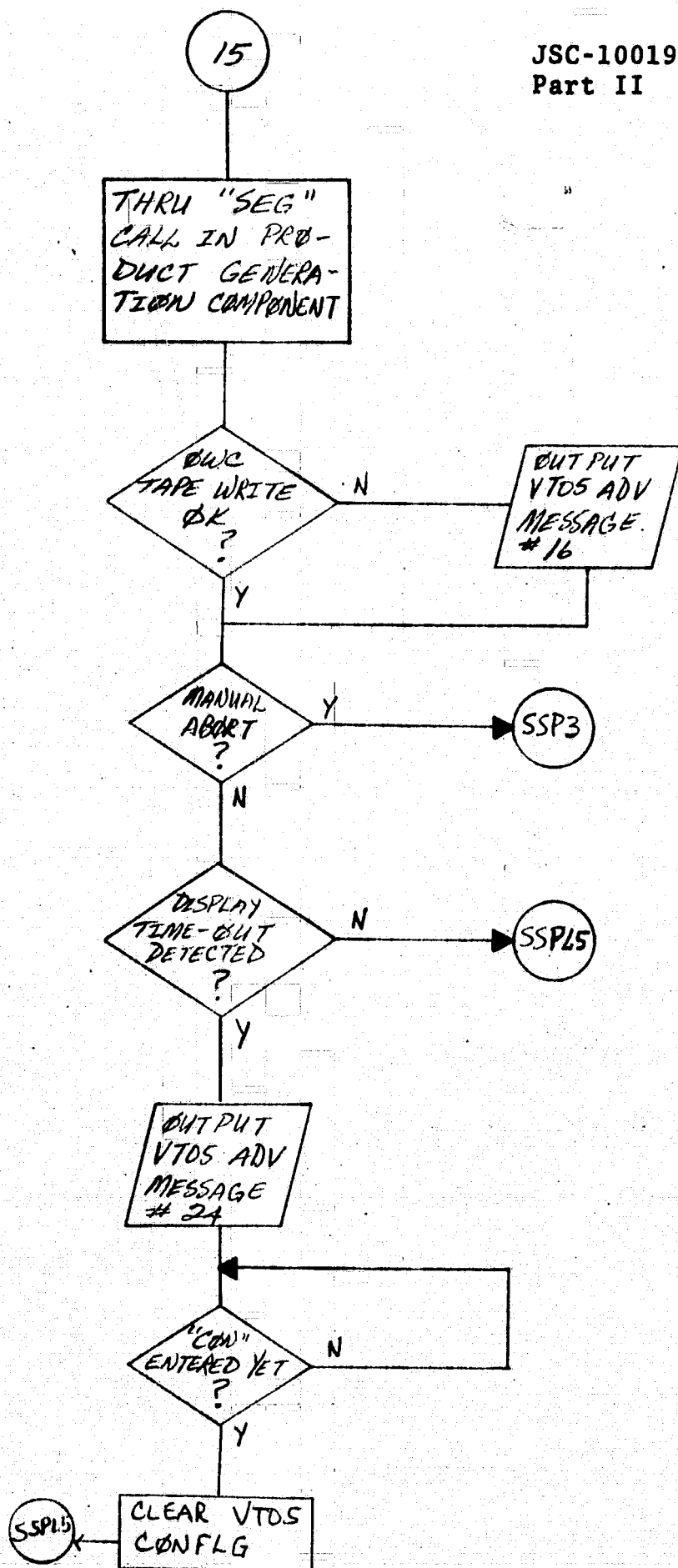


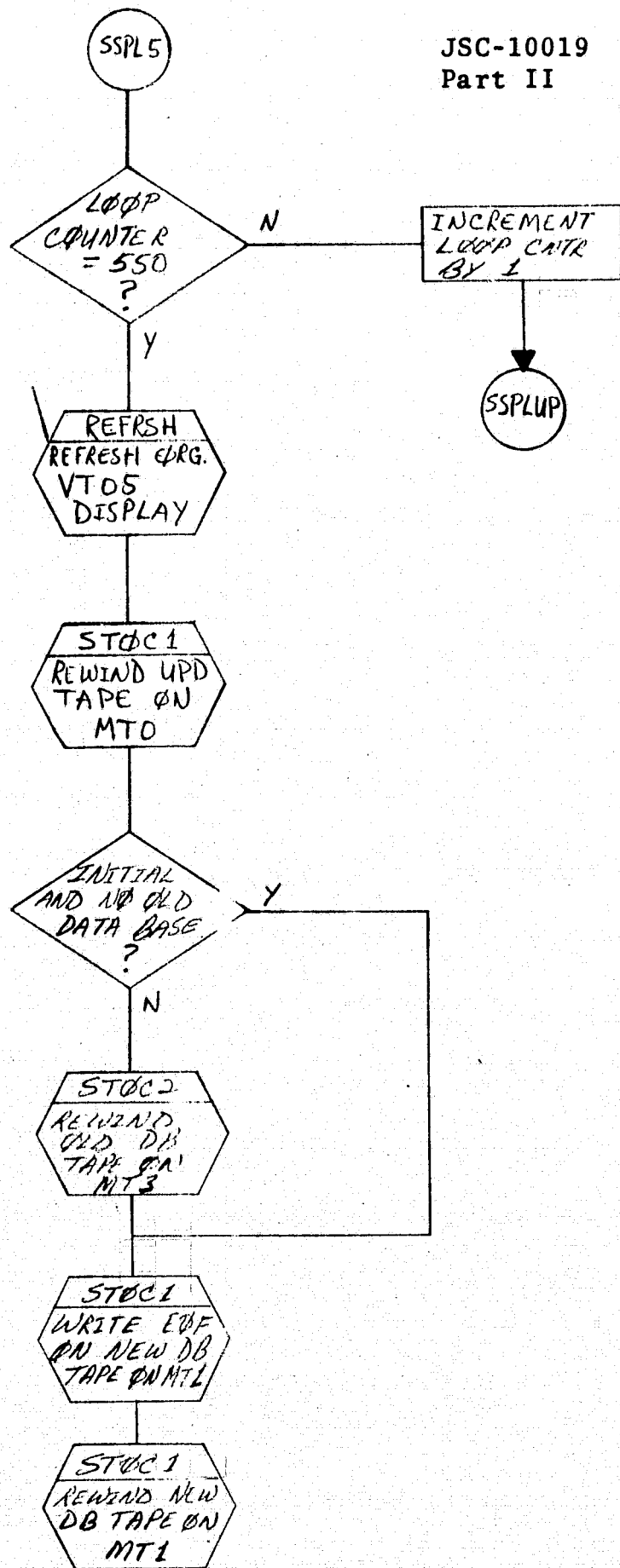


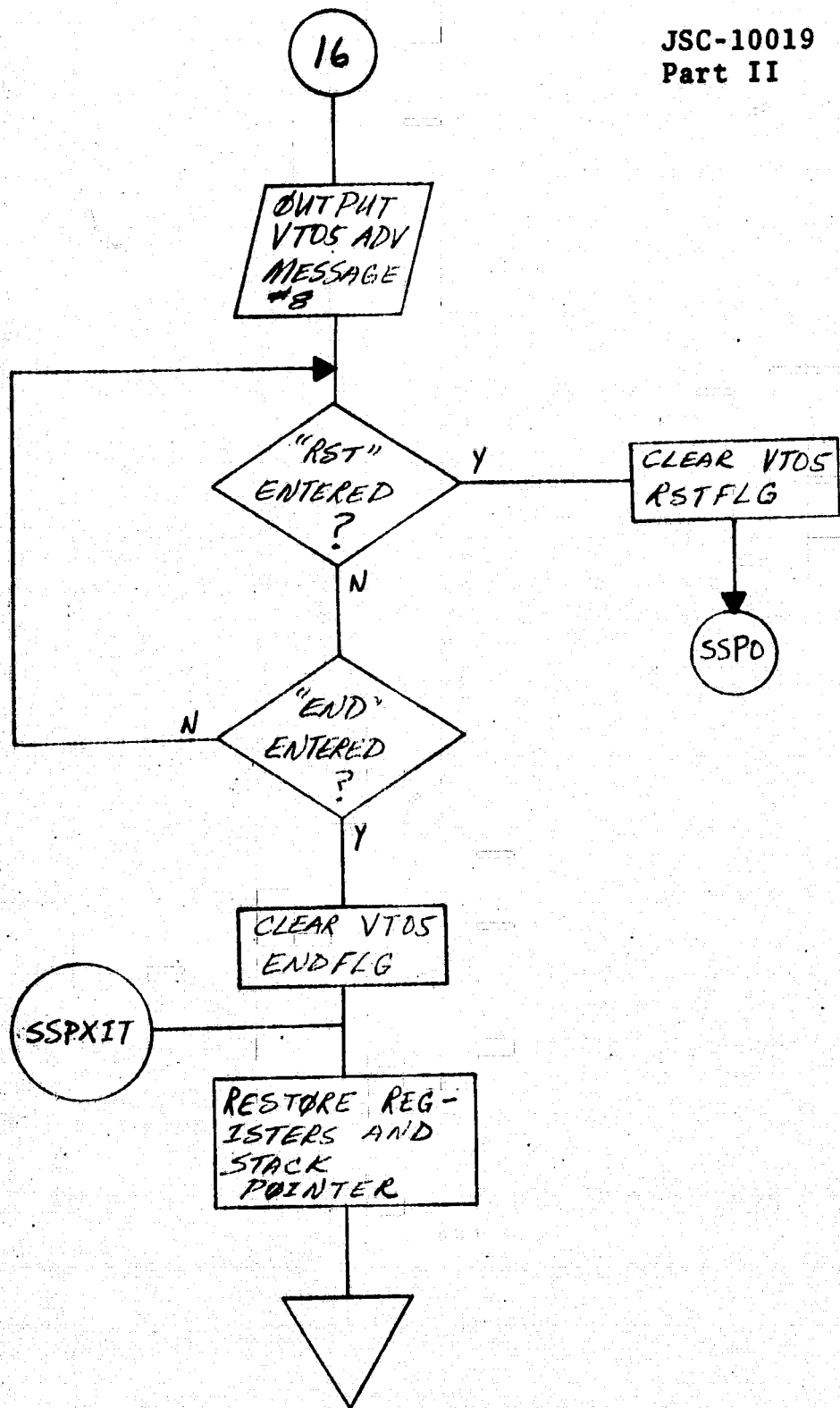






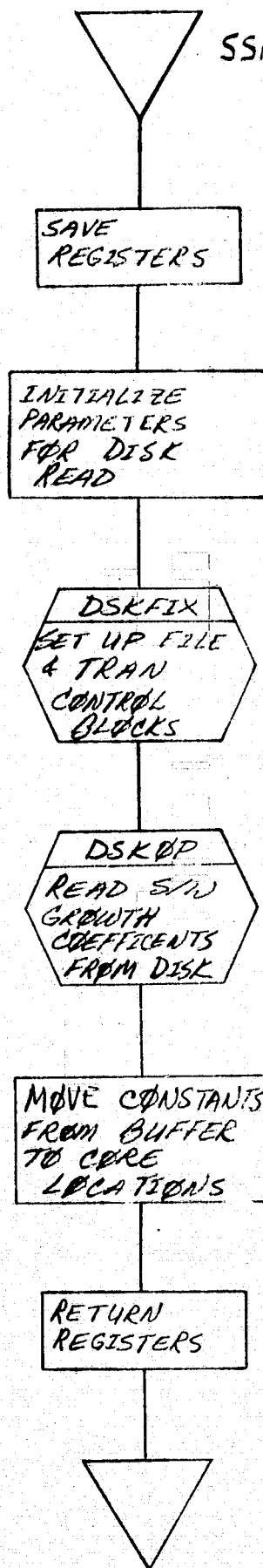






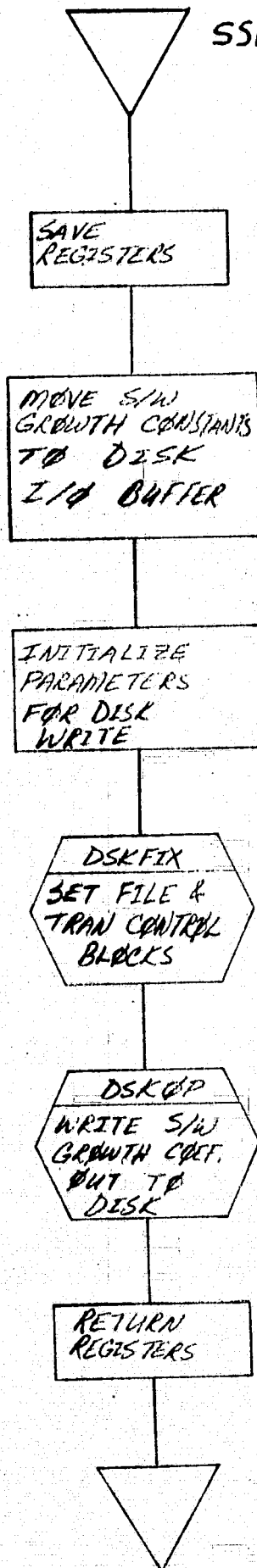
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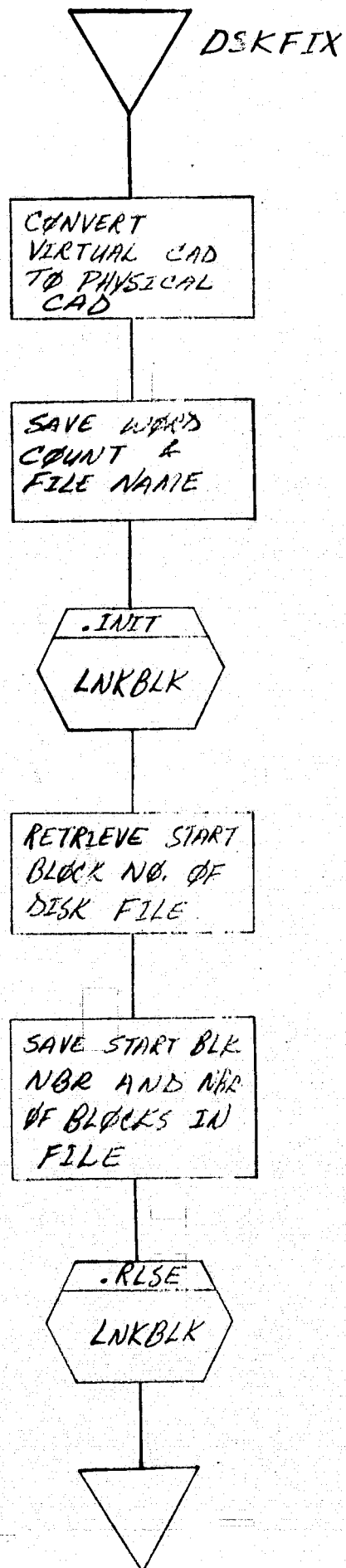
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Part II



SSPDKØ

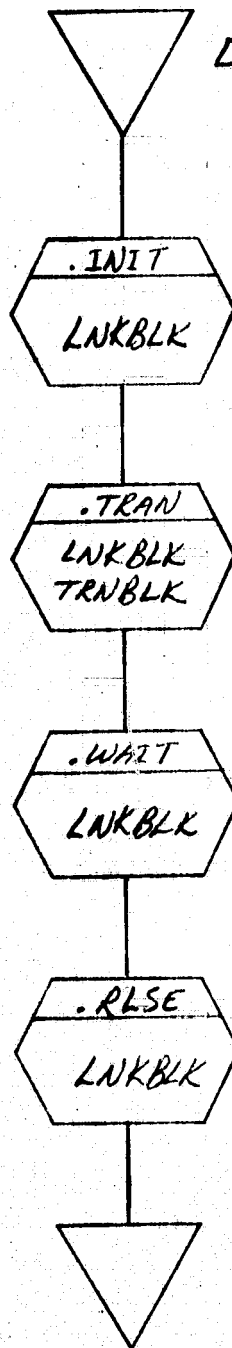
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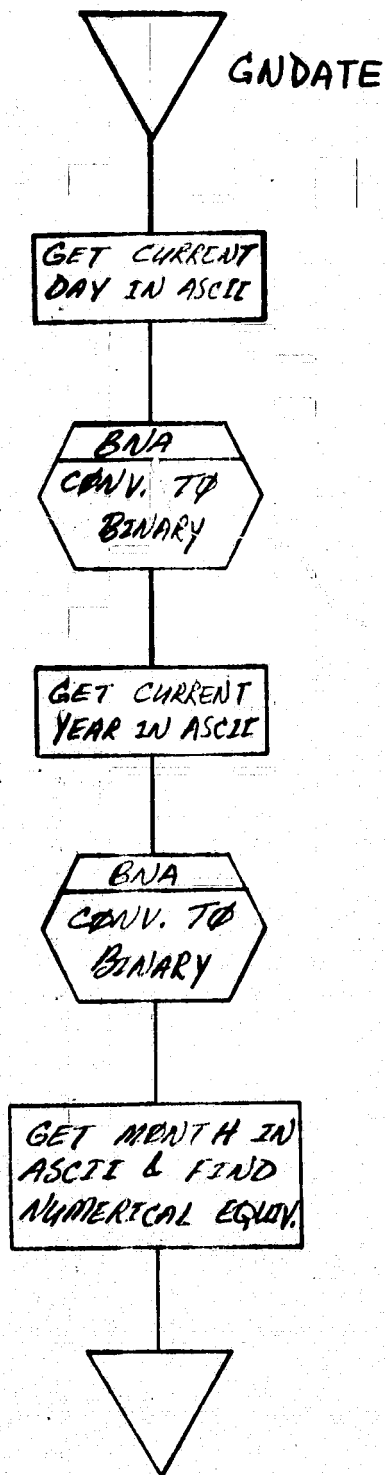




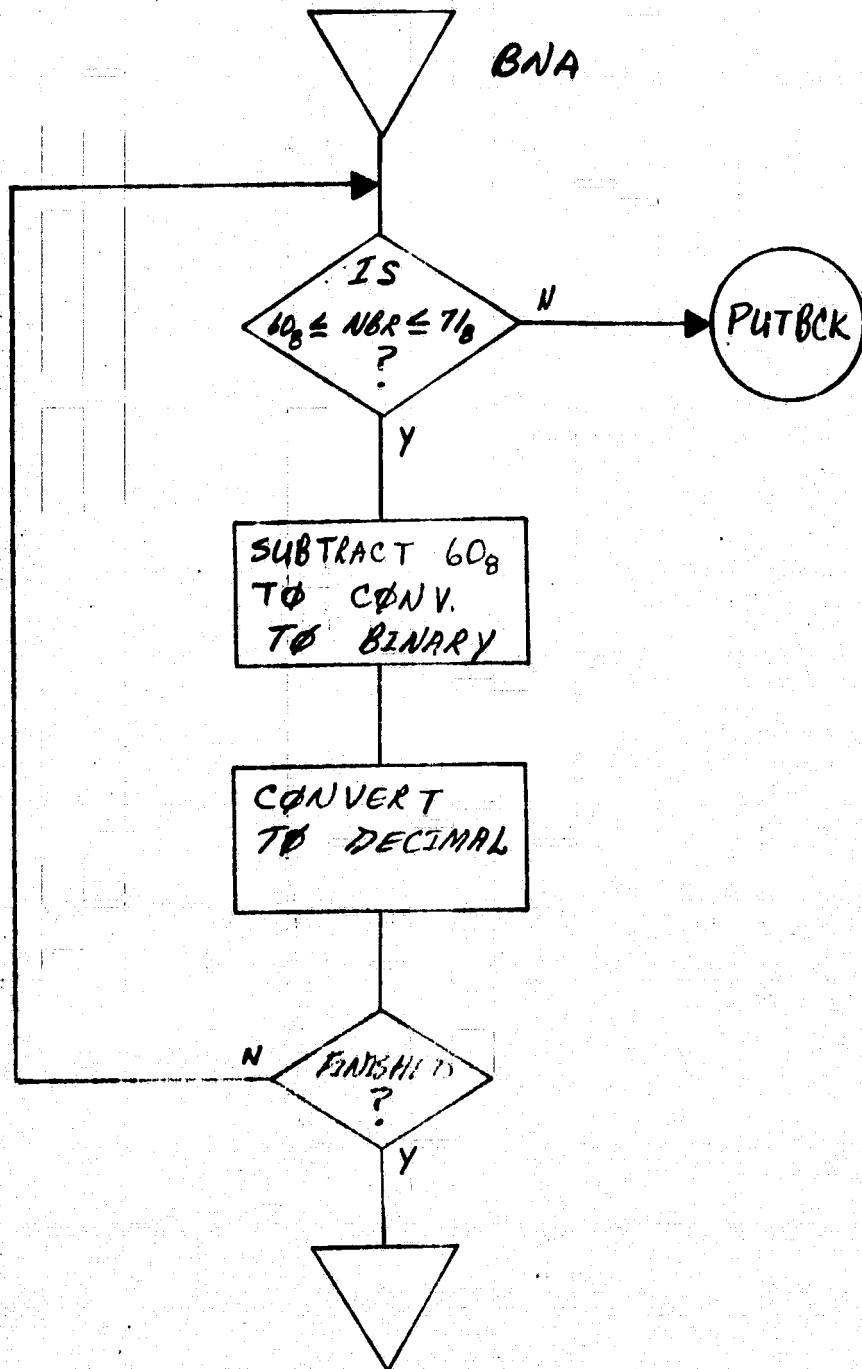
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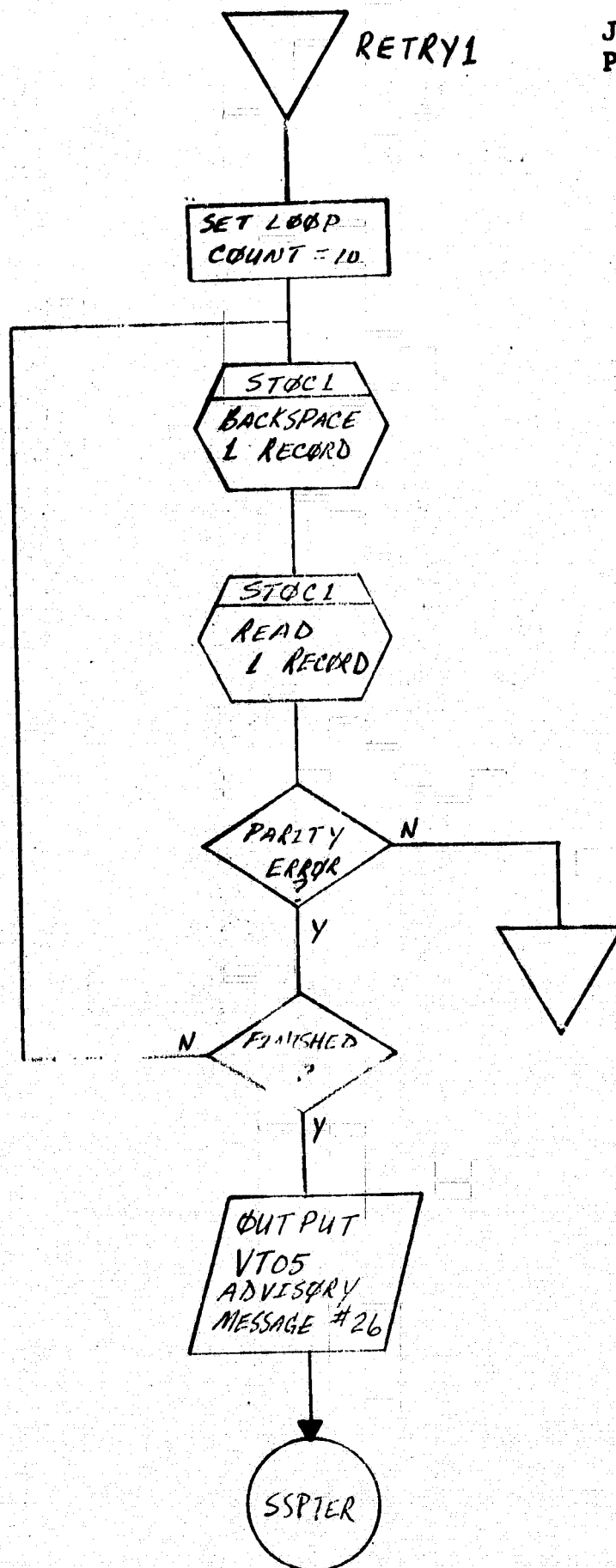
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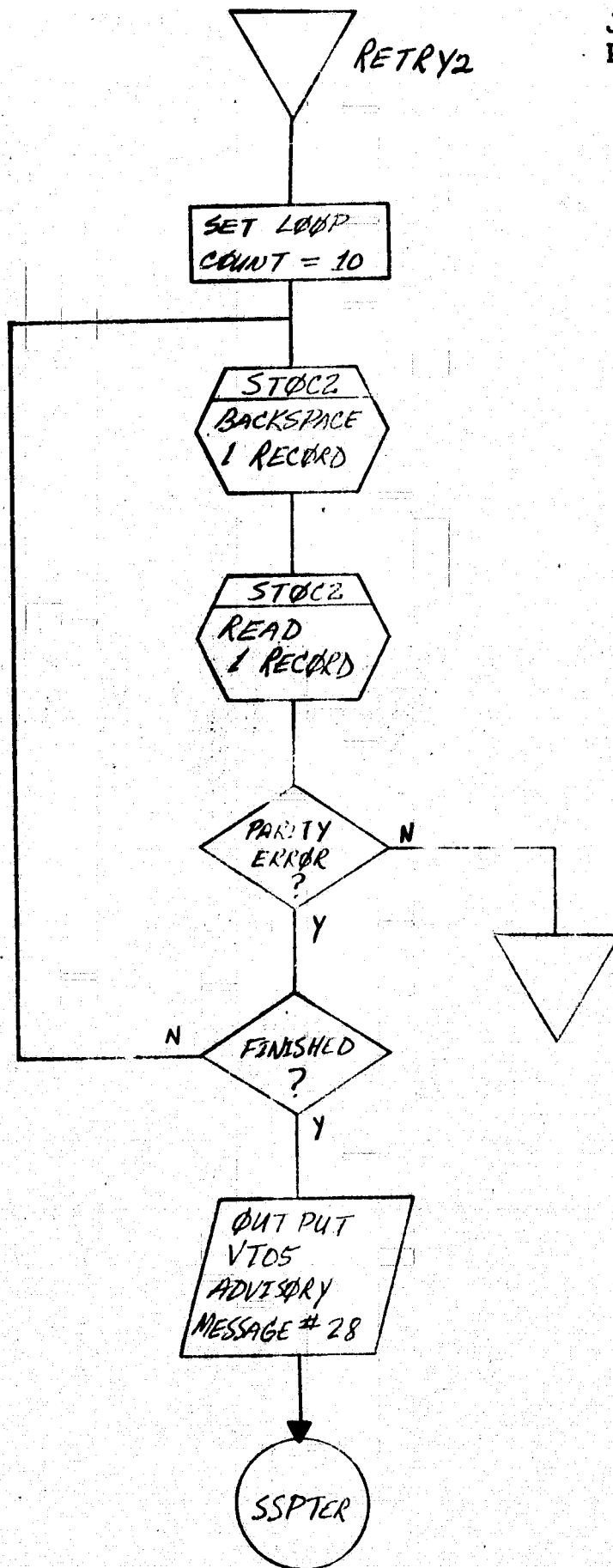


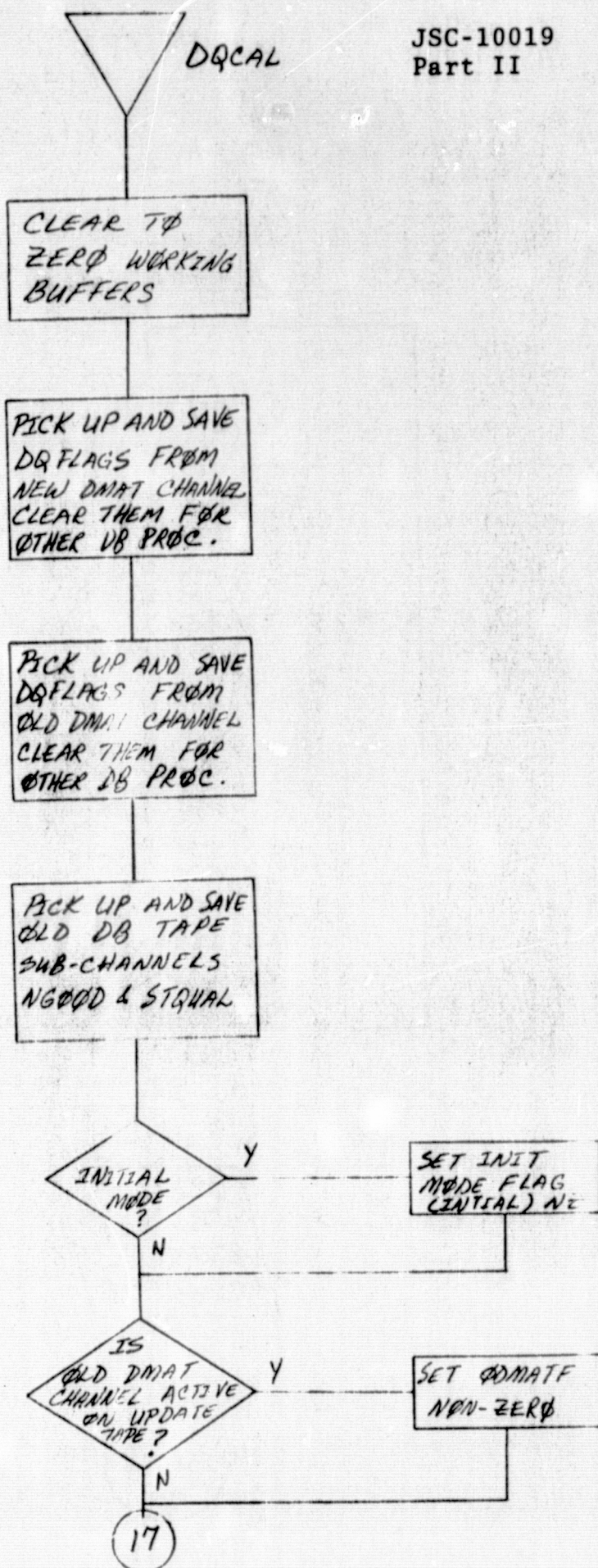


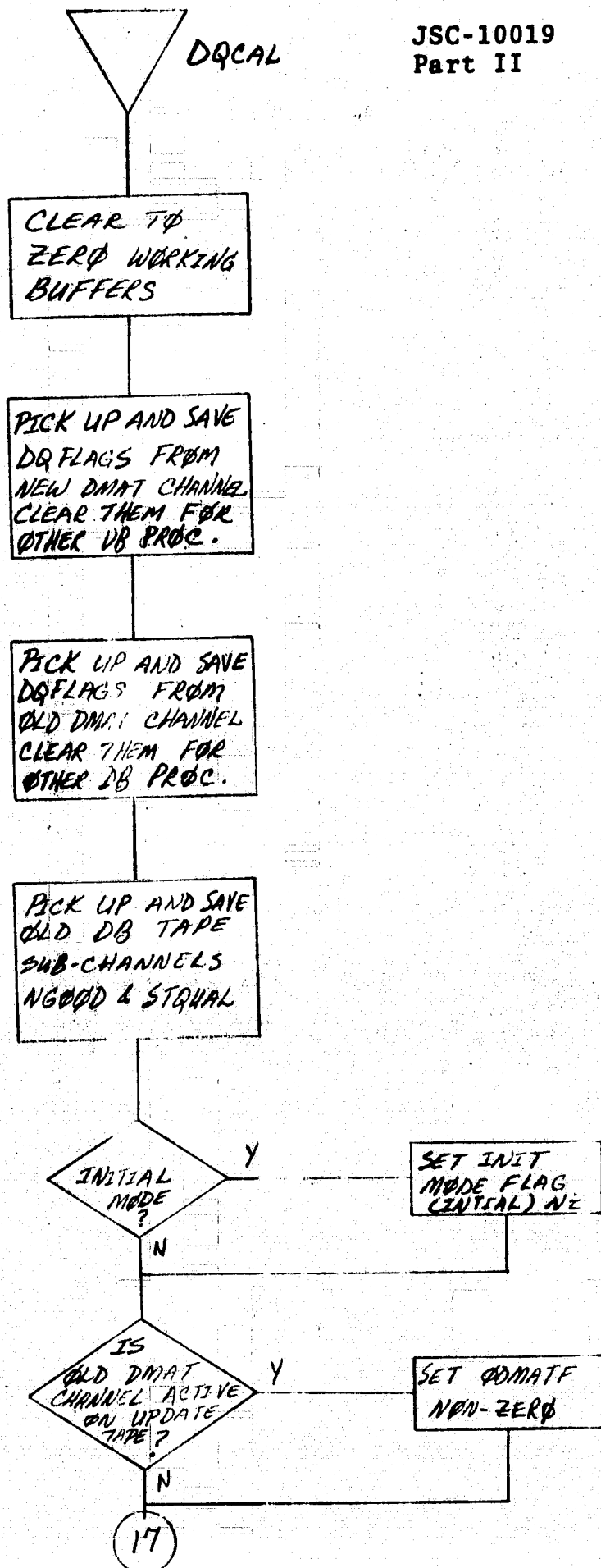
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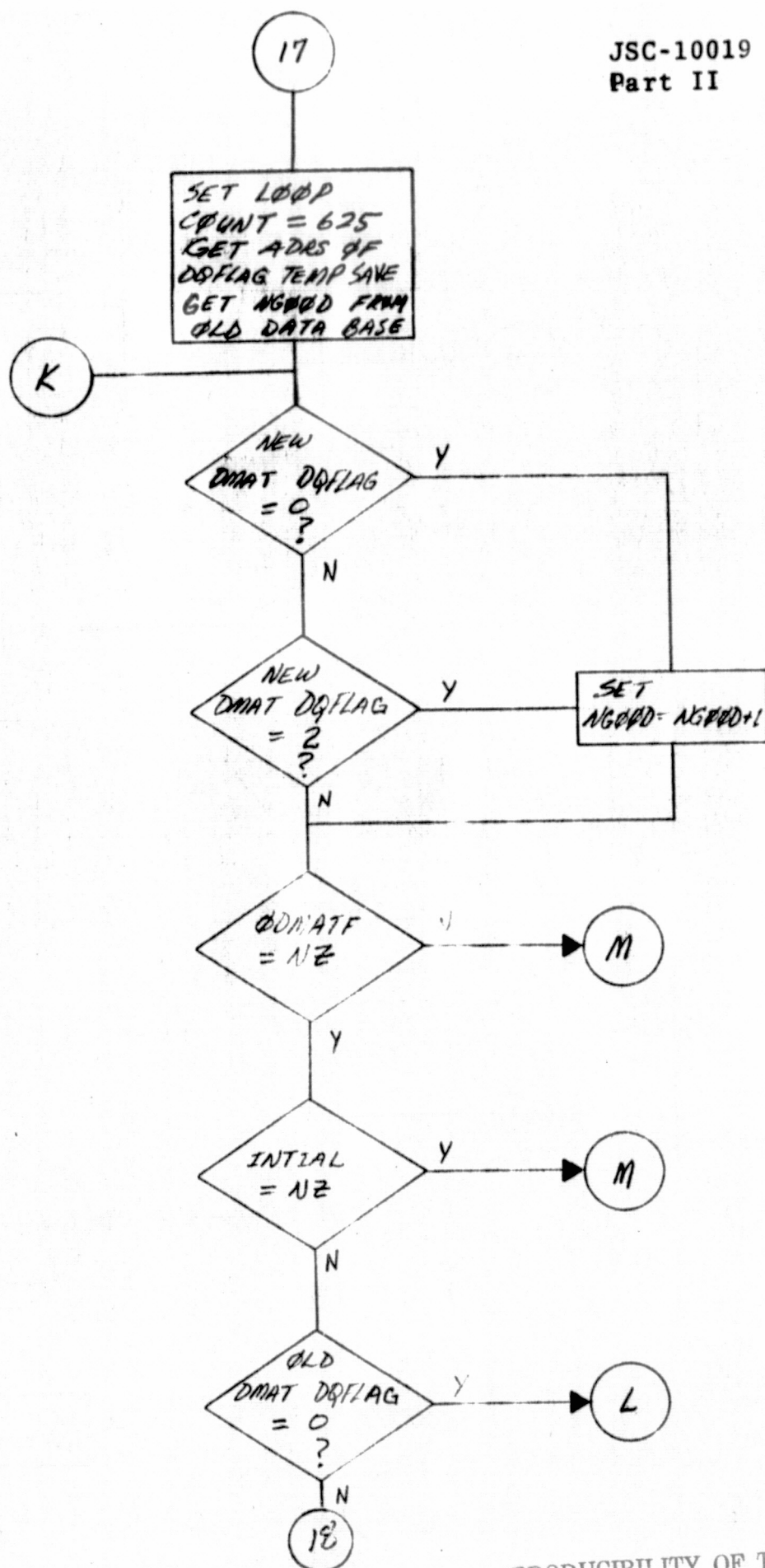




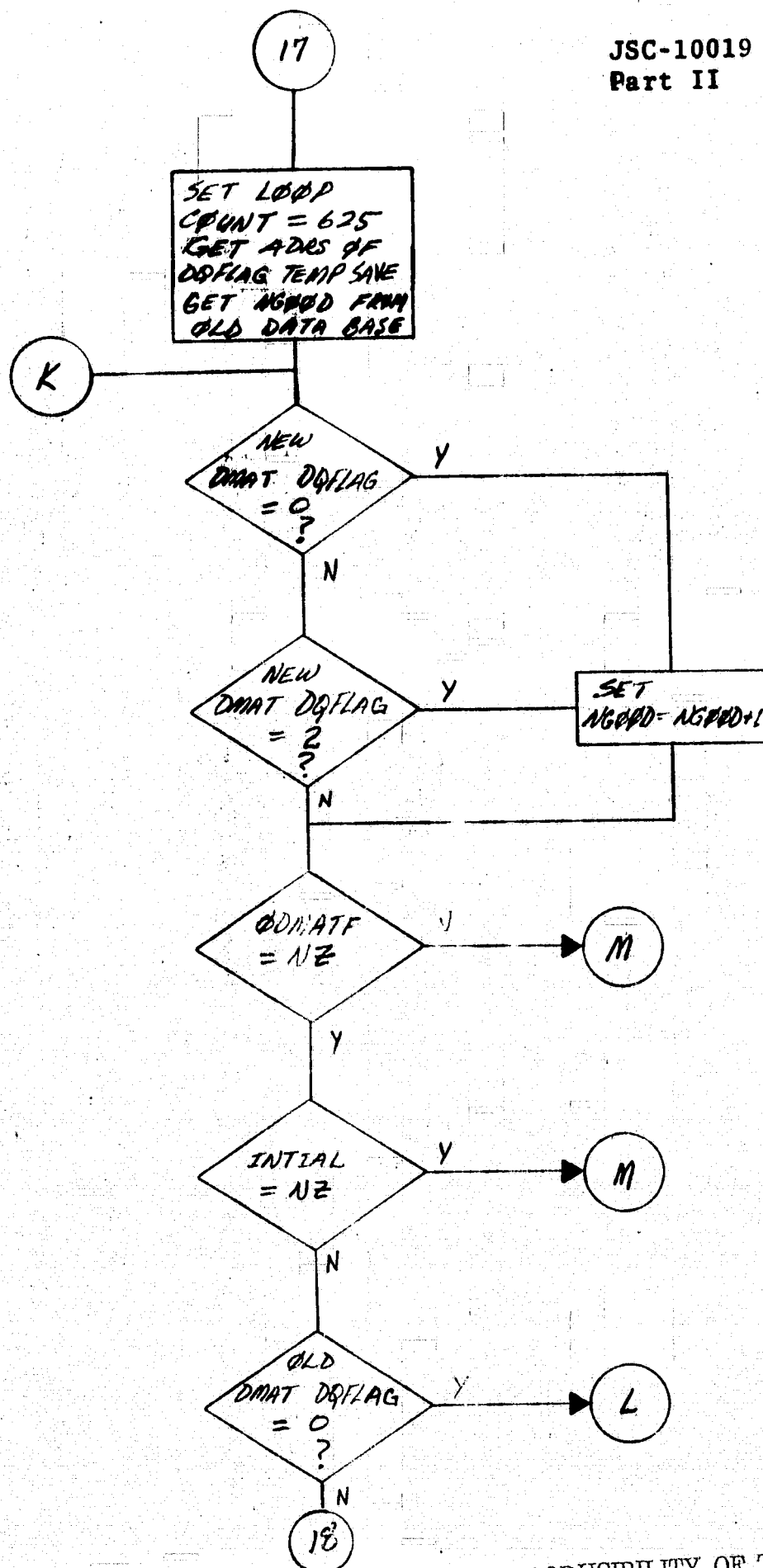




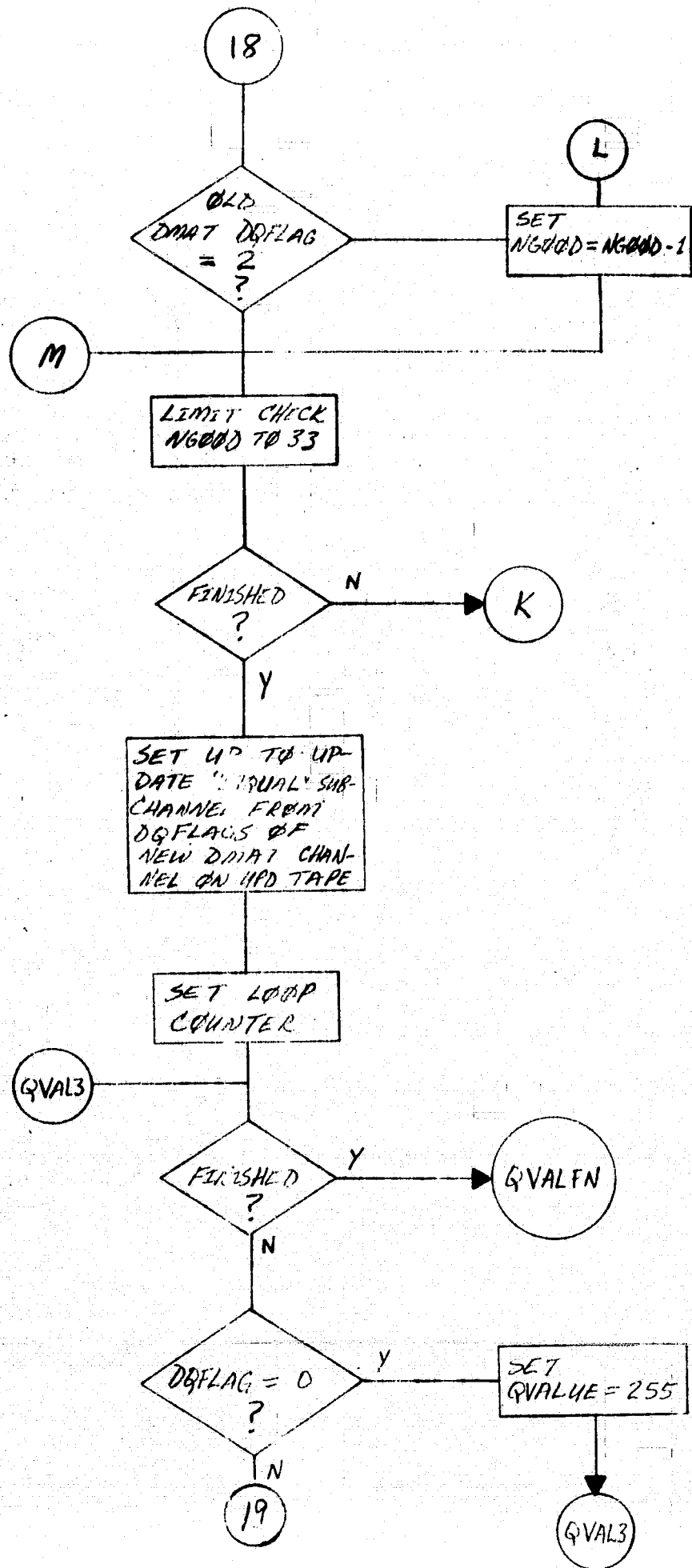


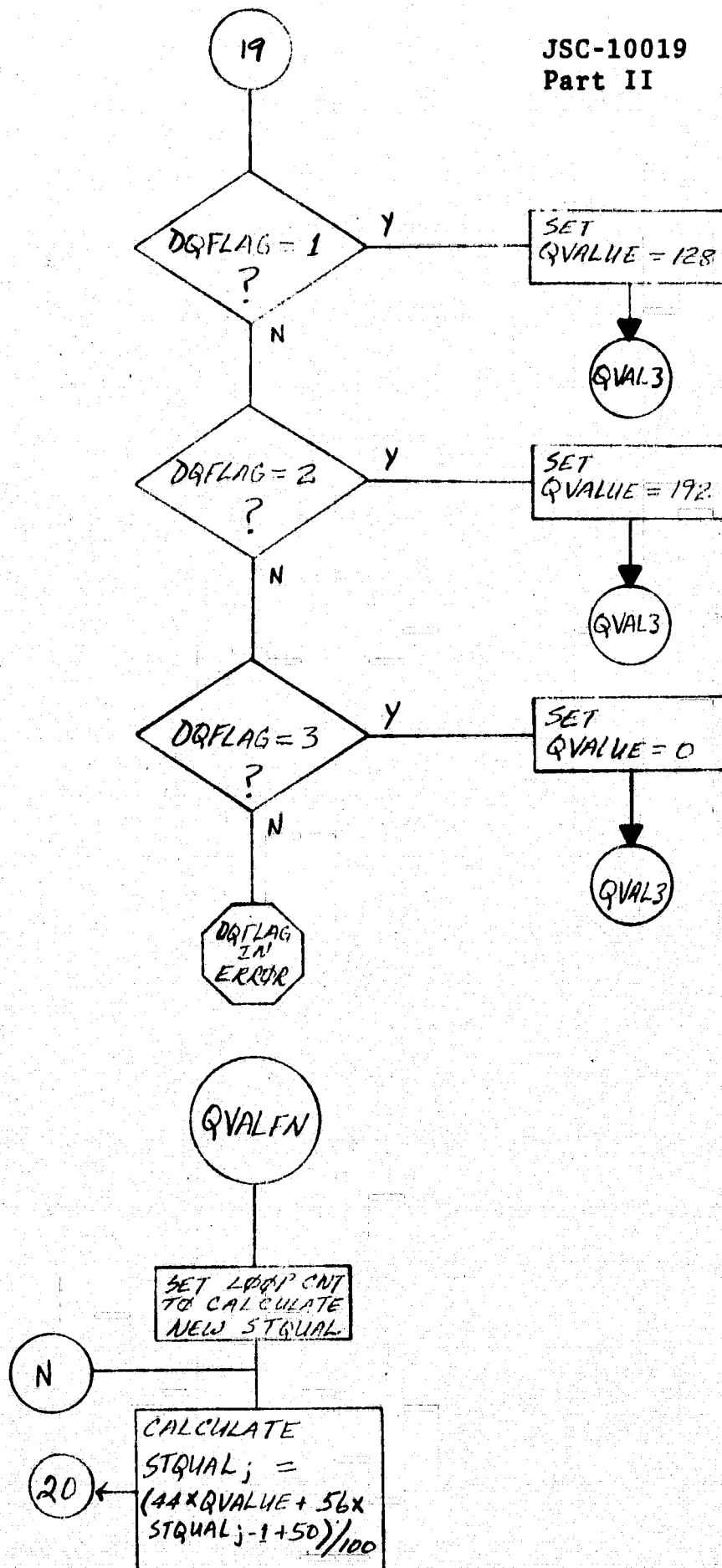


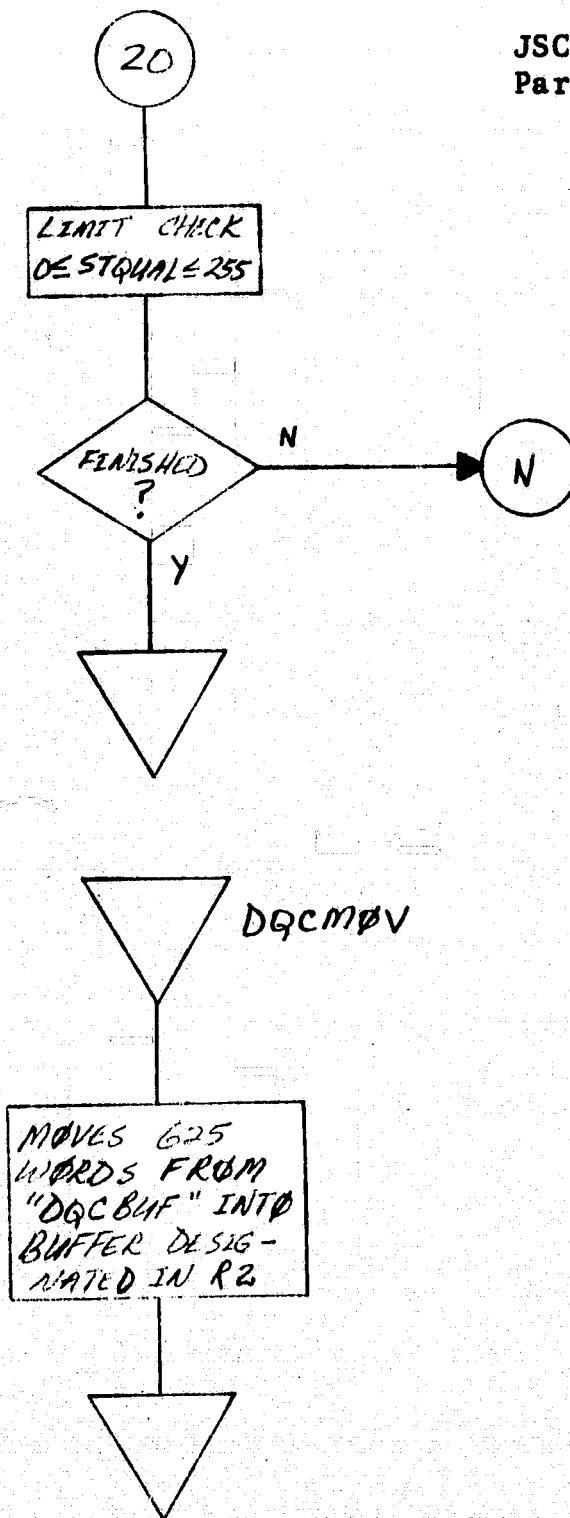
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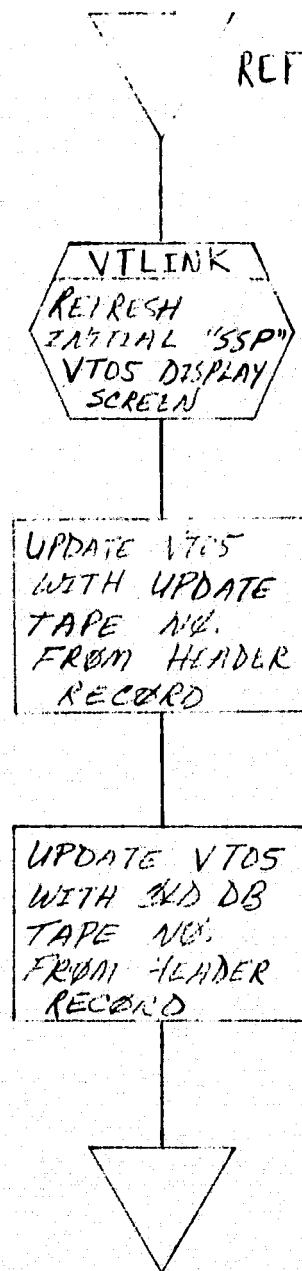


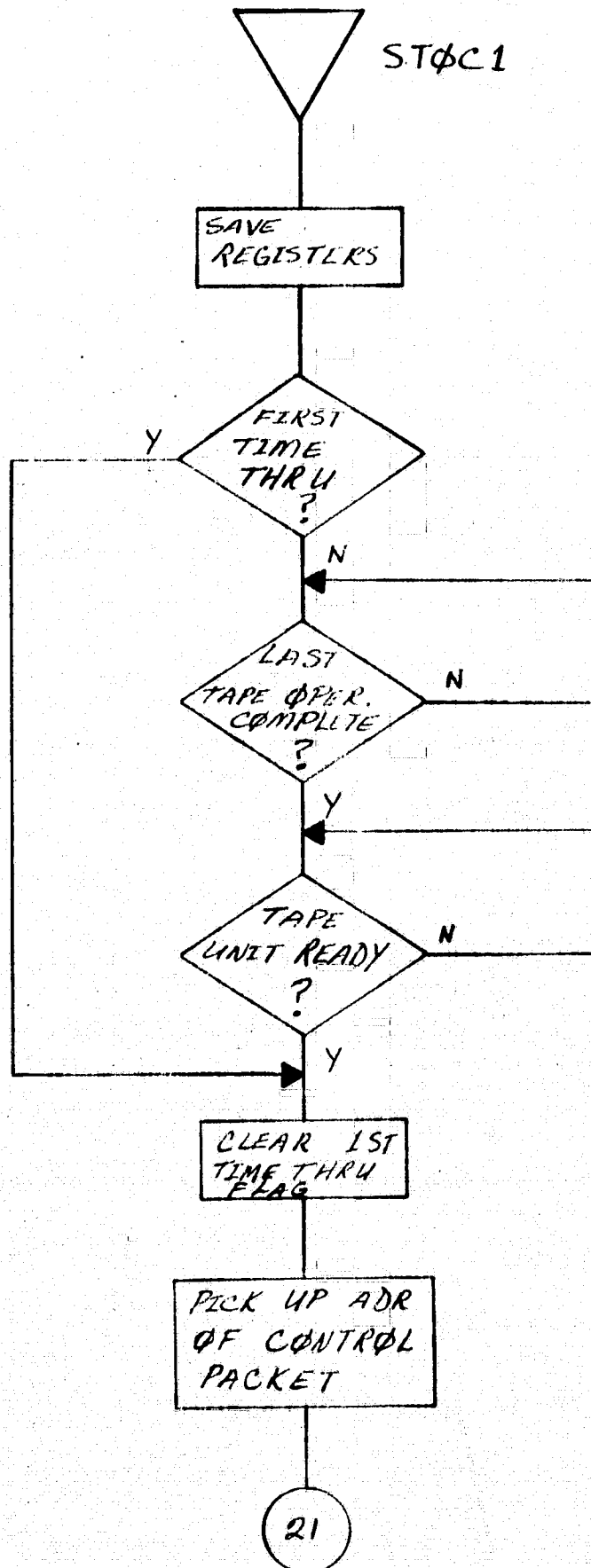
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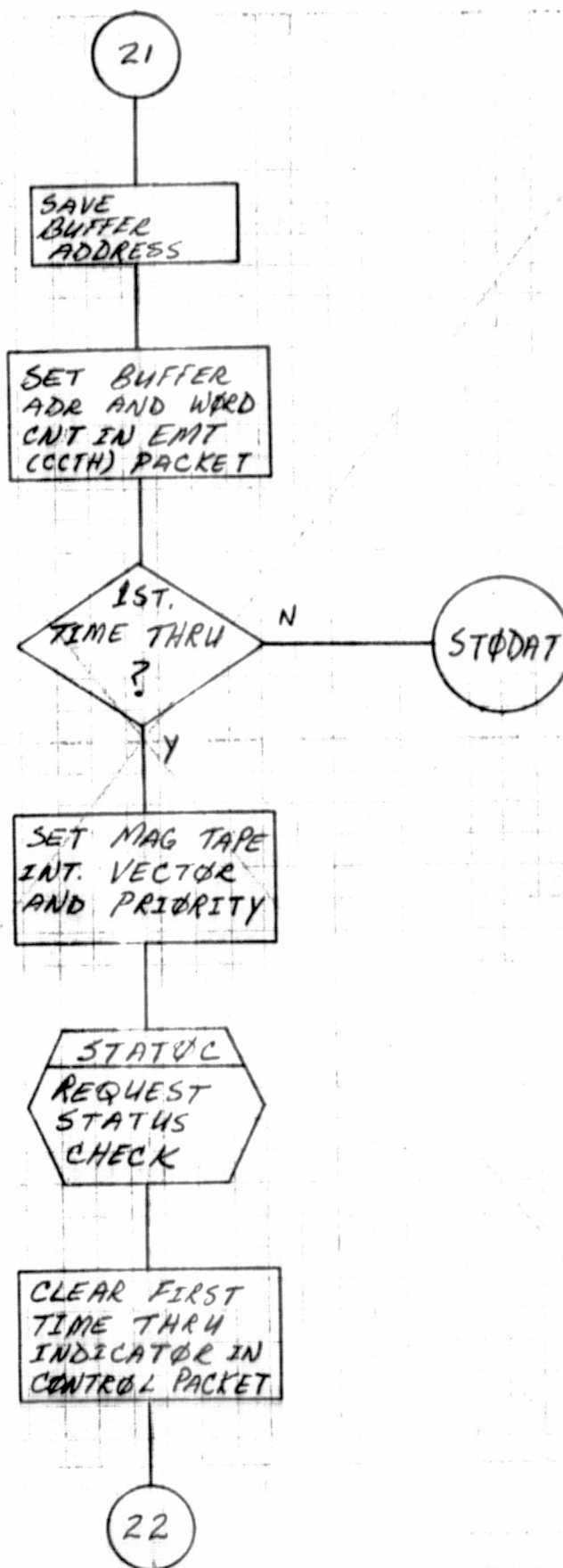


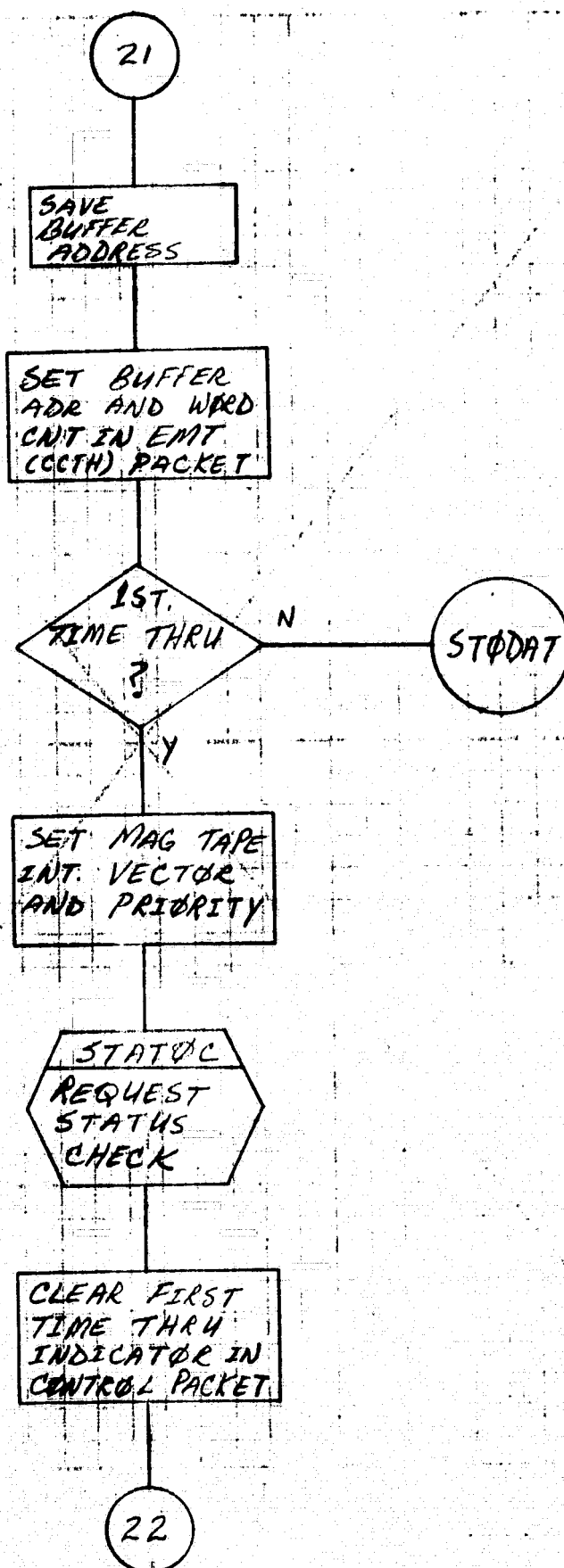


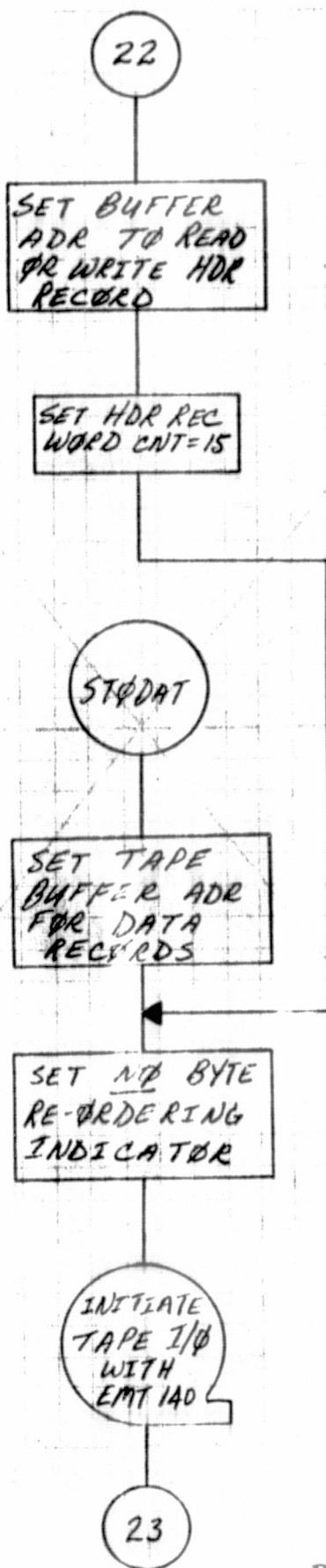




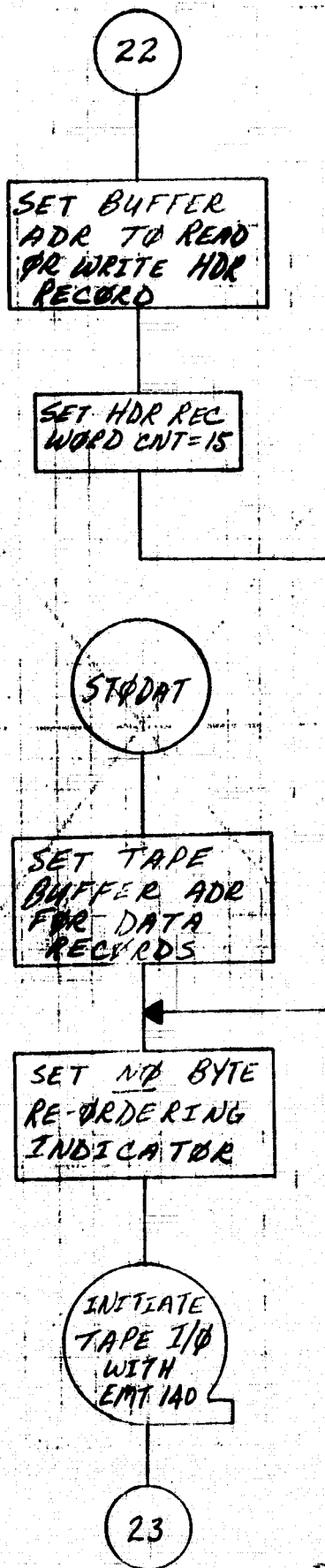




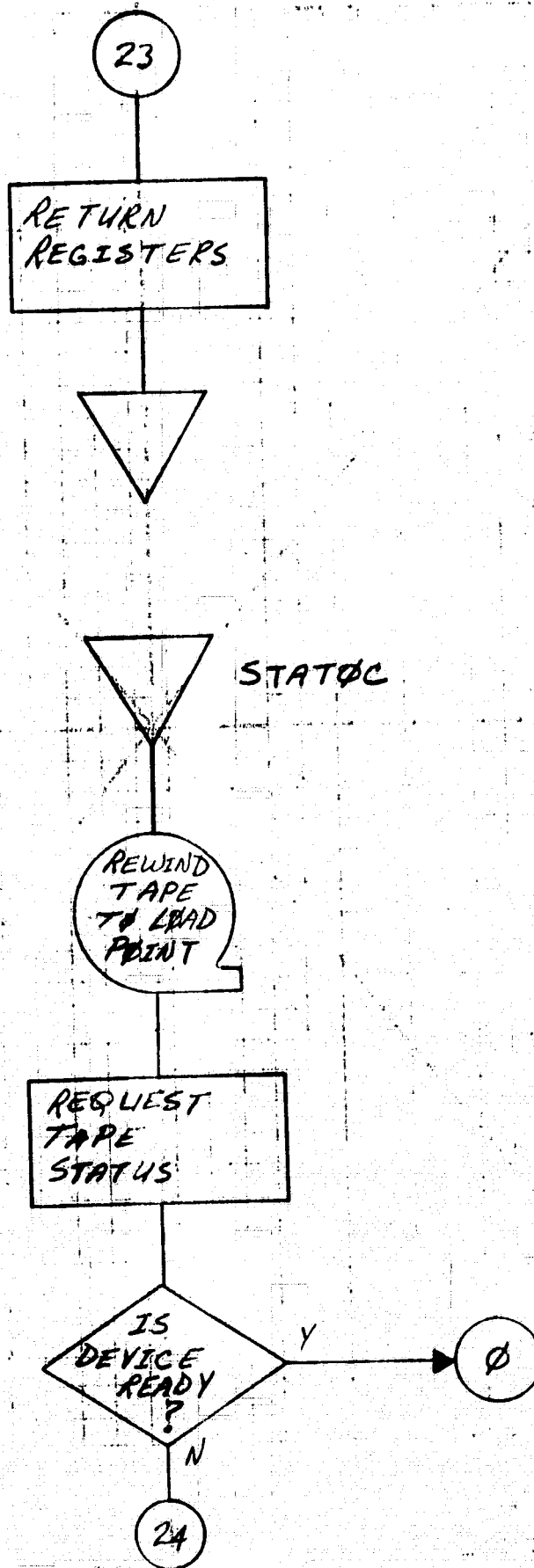


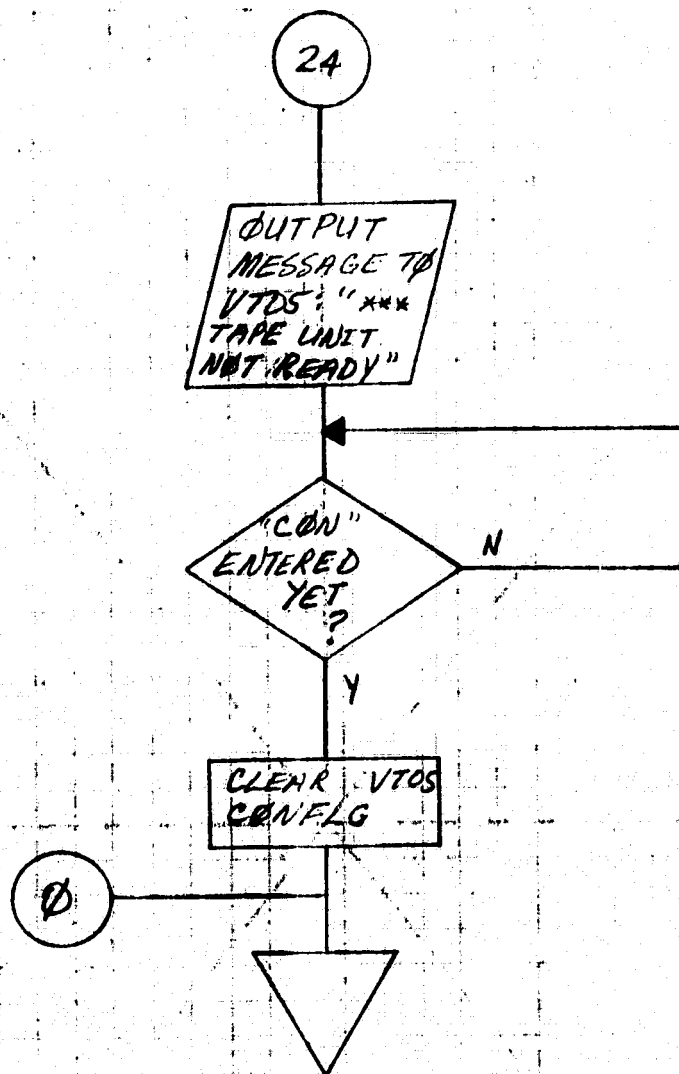


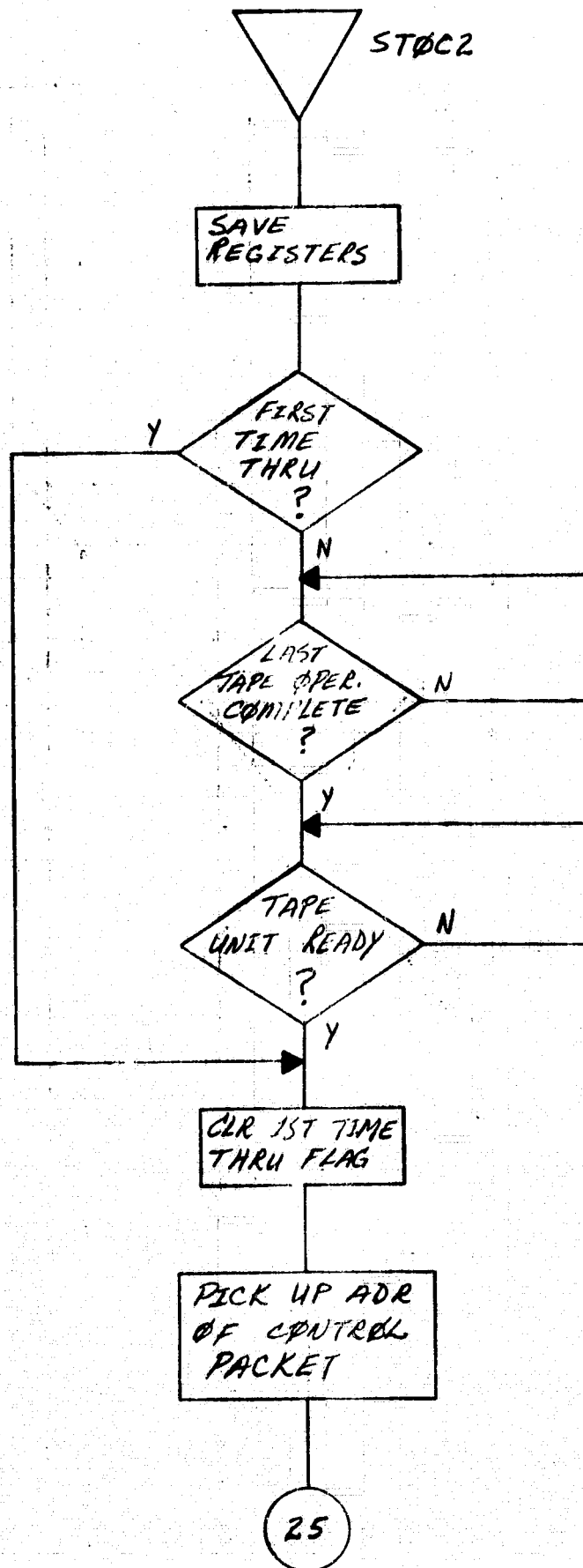
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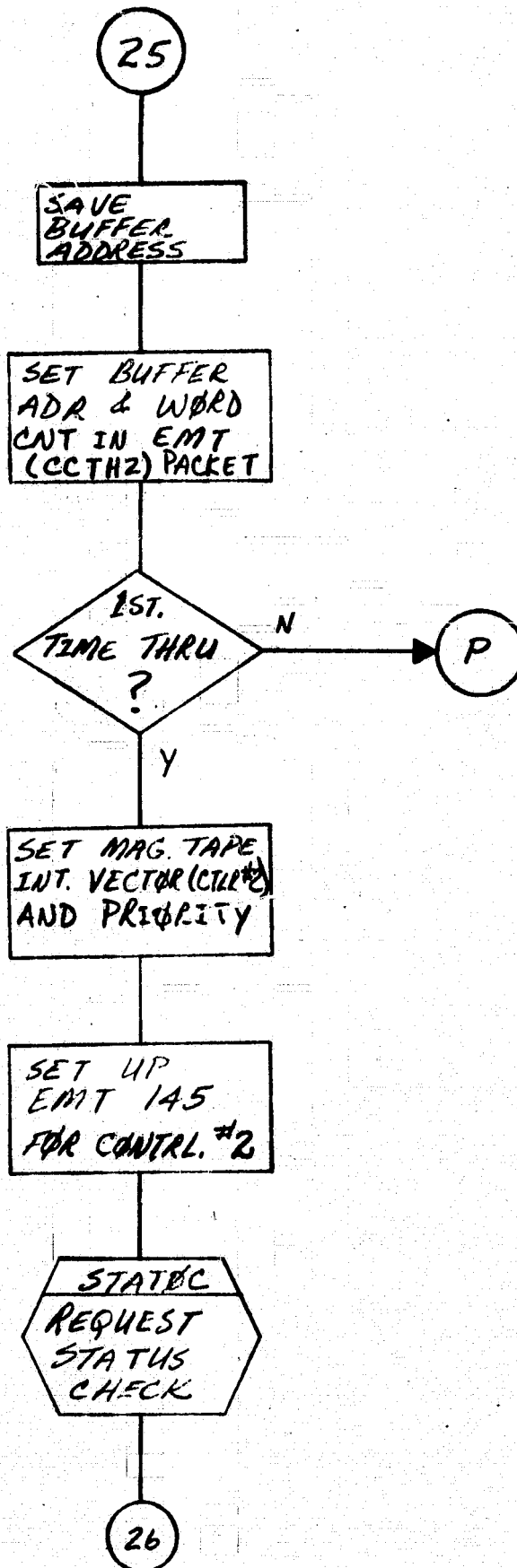


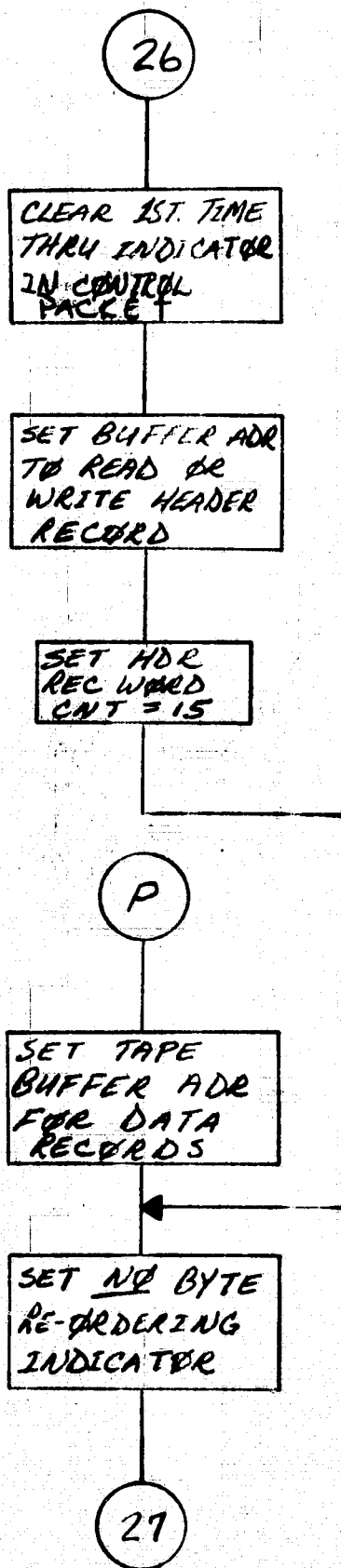
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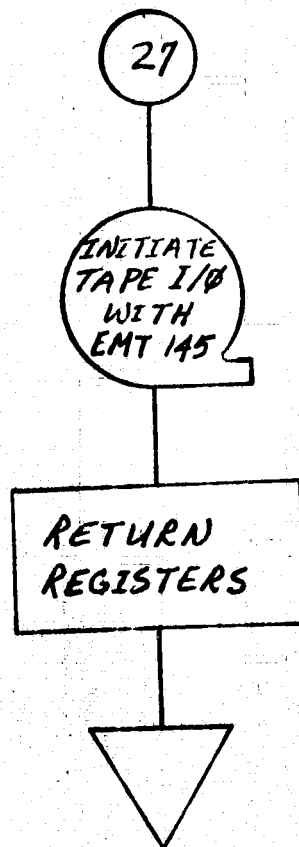












5.2.1.3 Interfaces

- A. Input Data. The input data to SSPDRV comes from three sources--from tape, from the user through VT05, and from disk. Tape inputs are from the data base update and the old data base tapes. The data is stored in the 8K buffer ABUFF, in the format shown by figure 5-4. User inputs are made via the VT05 keyboard into changeable fields. The ALT key is used to position the cursor at such fields. The disk file previously mentioned resides on the system disk under UIC 200,200, and contains the current screwworm growth constants. As shown in figure 5-6, six parameters are required. The 36-word file is described by figure 5-10, and is composed of signs, integers, and fractions from entries in ASCII and binary notation.
- B. Output Data. SSPDRV outputs data from the tape reads to the ISCREW module. In addition, the seven control parameters calculated are passed on for data base calculations, as specified in paragraph 5.1.5,C. Another call packet, defined elsewhere, is set up for the SWPGEN module. New data base information calculated and stored in ABUFF is written out to tape via SSPDRV.

5.2.1.4 Data Organization. The primary internally defined items of SSPDRV are those associated with the VT05 changeable fields. The list, shown in table 5-2, describes initialized or defaulted conditions. The unlisted internal symbols in SSPDRV subroutines are described within the listings.

5.2.1.5 Limitations. Operational restrictions of SSP are the most important limitations. The configuration setup, as shown in figure 5-1, is definitive in that specified input and output tapes must be mounted on designated tape drives. Error analysis of tape reads and writes is pertinent to the FORTRAN data base calculations done in ISCREW. A series of VT05 advisory messages are output to inform the user of existing error conditions. Table 5-3 is a list of numbered messages, referenced in the detailed flow charts.

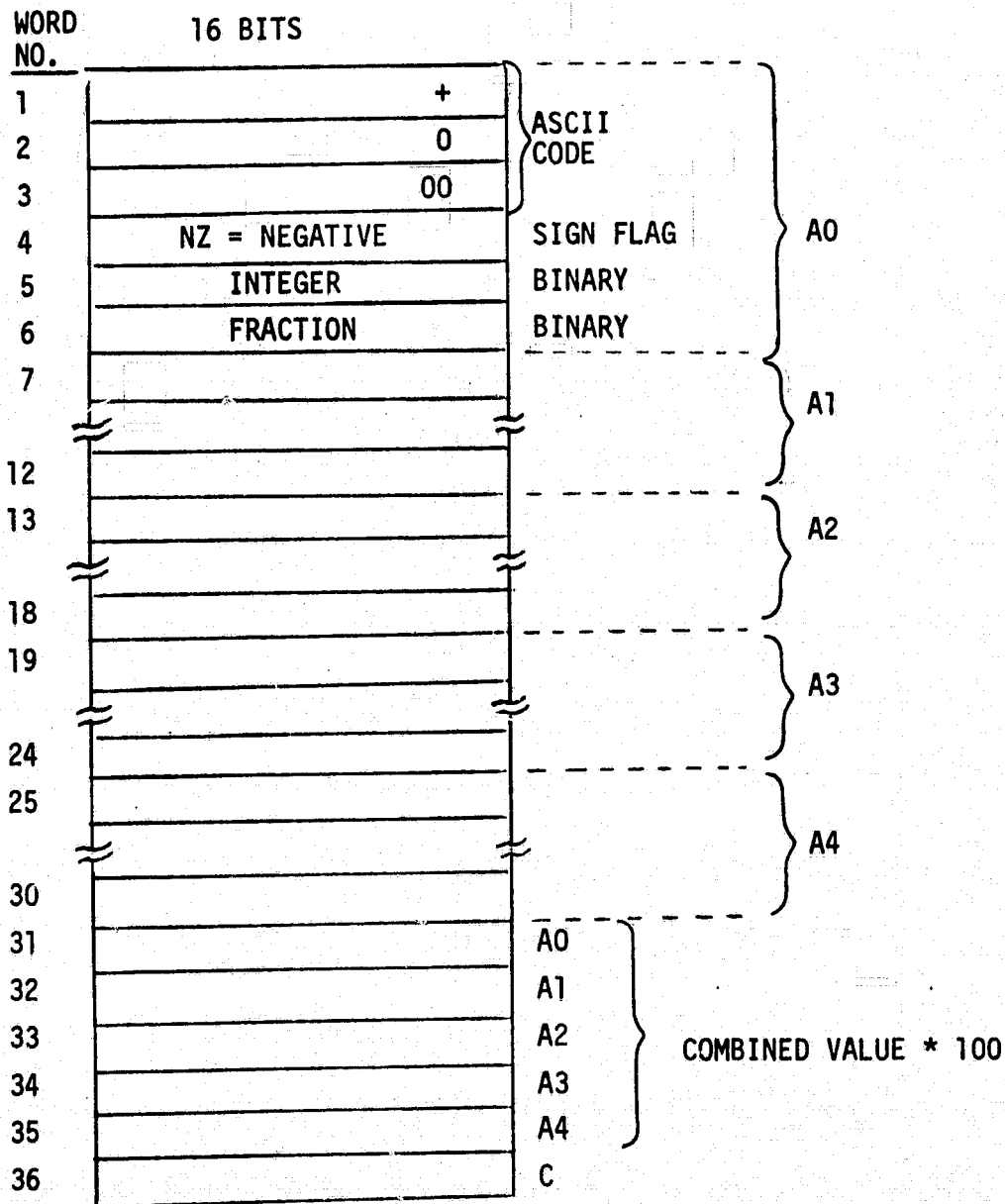


Figure 5-10 AIKSWP.TBL File Format

TABLE 5-2
SSPDRV INTERNALLY DEFINED ITEMS

NAME	TYPE	DEFAULT	LIMIT	DESCRIPTION
DBMODE	ASCII	N	A,D,I,N,Z	DATA BASE PROCESSING MODE
PDDMOD	NUMERIC	3	0-3	PRODUCT GENERATION MODE
NDBLTH	NUMERIC	-----	1-99	NEW DATA BASE LENGTH
UPDNOC	NUMERIC	-----	2 OR 4	NO. OF CHANNELS ACTIVE ON UPDATE TAPE
UPDLTH	NUMERIC	-----	1-99	UPDATE TAPE DATA BASE LENGTH
ODBNOC	NUMERIC	-----	5	NO. OF CHANNELS ON OLD DB TAPE
ODBLTH	NUMERIC	-----	1-99	OLD DATA BASE LENGTH
ORBIT	NUMERIC	-----	0-32767	ORBIT NO. OF DATA
DODATA	NUMERIC	00-00-00	MM-DD-YY	DATE OF DATA FROM UPDATE TAPE
UPDTNO	ASCII	XXXXXX	6 CHARS	UPDATE TAPE NO.
NDBTNO	ASCII	-----	6 CHARS	NEW DATA BASE TAPE NO. (USER INPUT)
SWTNO	ASCII	-----	6 CHARS	OWC TAPE NO. (USER INPUT)
ODBTNO	ASCII	XXXXXX	6 CHARS	OLD DATA BASE TAPE NO.

TABLE 5-3
VT05 ADVISORY MESSAGES

NO.	NAME	MESSAGE
6	PROCMG	ENTER OUTPUT TAPE NBRS & "GO"
8	DBUCMG	DATA BASE UPDATE COMPLETE***
10	ABRTMG	ABORT CONDITION - DO NOT PROCEED
12	ENTNK	ENTER NDBLTH=1 & "GO"
14	SWTERR	***OWC PRODUCTS TAPE ERROR
16	SPRVT	(BLANK LINE)
18	IUPIDM	INVALID UPDATE TAPE ID ON MTU 0
20	IODIDM	INVALID OLD DB TAPE ID ON MTU 2
22	VFMEM	VERIFY MODE ENTRY & ENTER "GO"
24	DPTOM	DISPLAY TIME-OUT * ENTER "CON"
26	TPERRO	TAPE READ PARITY ERROR ON MTU 0
28	TPERR2	TAPE READ PARITY ERROR ON MTU 2
30	TPERR1	TAPE WRITE PARITY ERROR ON MTU 1
32	DSKMAG	RE-INIT S-W GROWTH CONSTANTS?
34	WRTM	WRITE RING MISSING ON MT1

5.2.1.6 CPC Listings. See Part IV of this document, published under separate cover.

5.2.2 ISCREW

5.2.2.1 Subcomponent Description. The data base calculations component of SSP is ISCREW. Its functions have been previously described in paragraph 5.1. The module is composed primarily of a single FORTRAN routine. The linking parameters from SSPDRV are set as shown in table 5-1. Update tape data and old data base tape data is passed in ABUFF. The old data base information is replaced by the new data base calculations in ABUFF on the return to SSPDRV. Product generation data is moved into DBUFF. The data base processing mode established in SSPDRV sets data flow paths for data base maintenance. Four of the five data base channels are calculated in ISCREW, as follows.

- A. STMAT. This is the short-term mean air temperature channel, or channel No. 1, formed from the spatially registered daily mean air temperature (DMAT) values from the data base update tape. Ideally, this channel would contain the arithmetic mean of the last four days DMAT values for a given registered pixel location; however, because that method requires daily access to three historical DMAT channels from the data base, the following low-pass digital filtering procedure is used:

$$STMAT_i = STMAT_{i-1} + K*(DMAT_i - STMAT_{i-1})$$

Where:

$$K = 0.44$$

- B. LTMAT. Channel No. 2 is the long-term mean air temperature, which is saved in the data base as 16-bit running sums for each pixel over the last N days, where N is the long-term averaging period. The normal (N constant) daily procedure is:

$$LTMAT_i = LTMAT_{i-1} + DMAT_i - DMAT_{i-N}$$

When N is incremented by one, the calculation is:

$$\text{LTMAT}_i = \text{LTMAT}_{i-1} + \text{DMAT}_i$$

When N is decremented by one, the calculation is:

$$\text{LTMAT}_i = \text{LTMAT}_i + \text{DMAT}_i - \text{DMAT}_{i-N} - \text{DMAT}_{i-N+1}$$

- C. LTCMI. Channel No. 3 is the long-term mean crop moisture index, a running sum of N CMI values. The normal (N constant) daily update procedure is:

$$\text{LTCMI}_i = \text{LTCMI}_{i-1} + \text{CMI}_i - \text{CMI}_{i-N}$$

When N is incremented by one, the calculation is:

$$\text{LTCMI}_i = \text{LTCMI}_{i-1} + \text{CMI}_i$$

When N is decremented by one, the calculation is:

$$\text{LTCMI}_i = \text{LTCMI}_{i-1} + \text{CMI}_i - \text{CMI}_{i-N} - \text{CMI}_{i-N+1}$$

- D. DDSUM. Channel No. 4 is the degree-day sum values saved as 16-bit running sums for each pixel. The normal (N constant) daily update procedure is:

$$\text{DDSUM}_i = \text{DDSUM}_{i-1} + T'_i - T'_{i-N}$$

Where:

$$T_i = \text{DMAT}_i$$

$$T'_i = T_i - 284 \text{ } ^\circ\text{K}$$

$$T_{i-N} = \text{DMAT}_{i-N}$$

$$T'_{i-N} = T_{i-N} - 284 \text{ } ^\circ\text{K}$$

When N is decremented by one, the calculation is:

$$\text{DDSUM}_i = \text{DDSUM}_{i-1} + T_i'$$

When N is decremented by one, the calculation is:

$$\text{DDSUM}_i = \text{DDSUM}_i \text{ (updated)} - T_{i-N+1}'$$

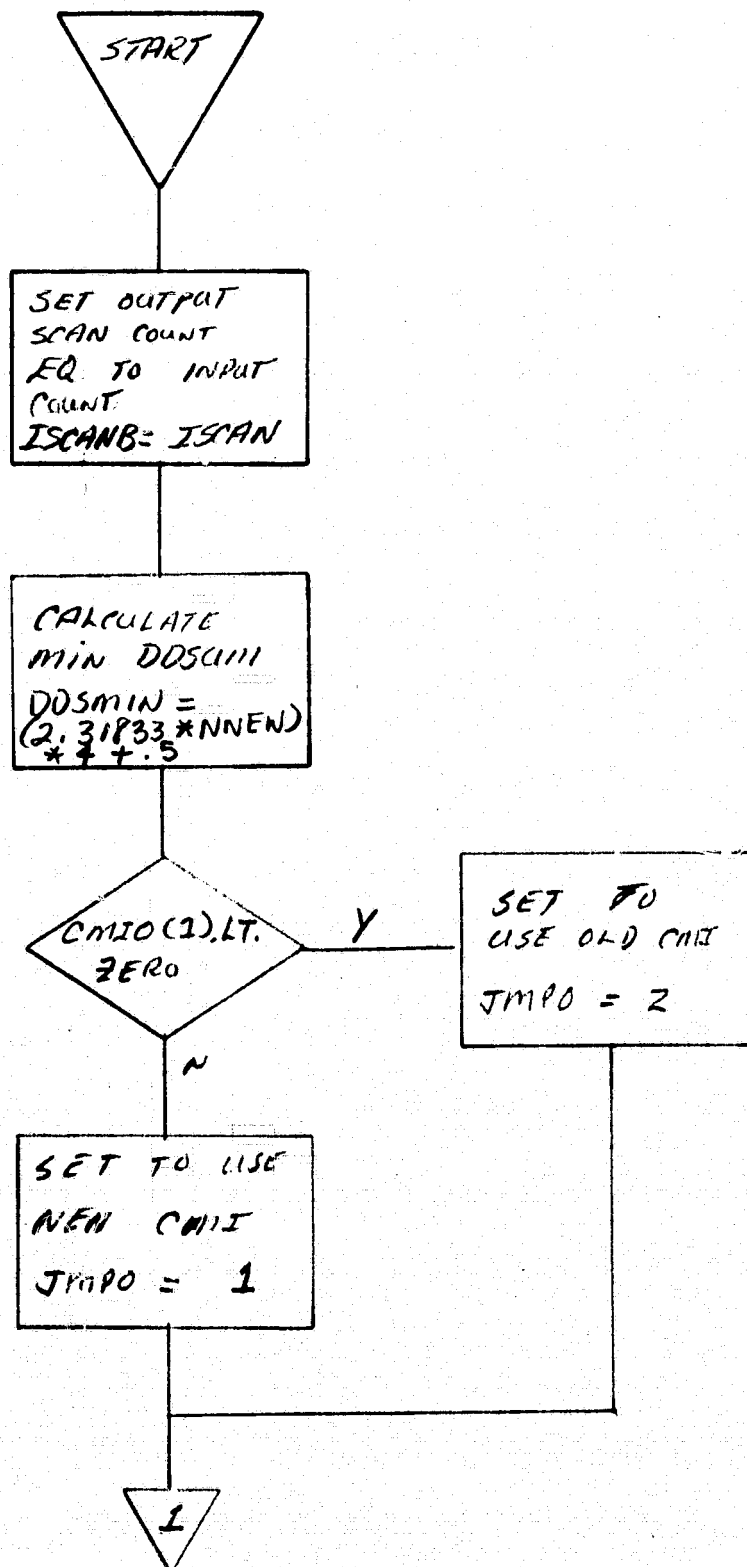
Where:

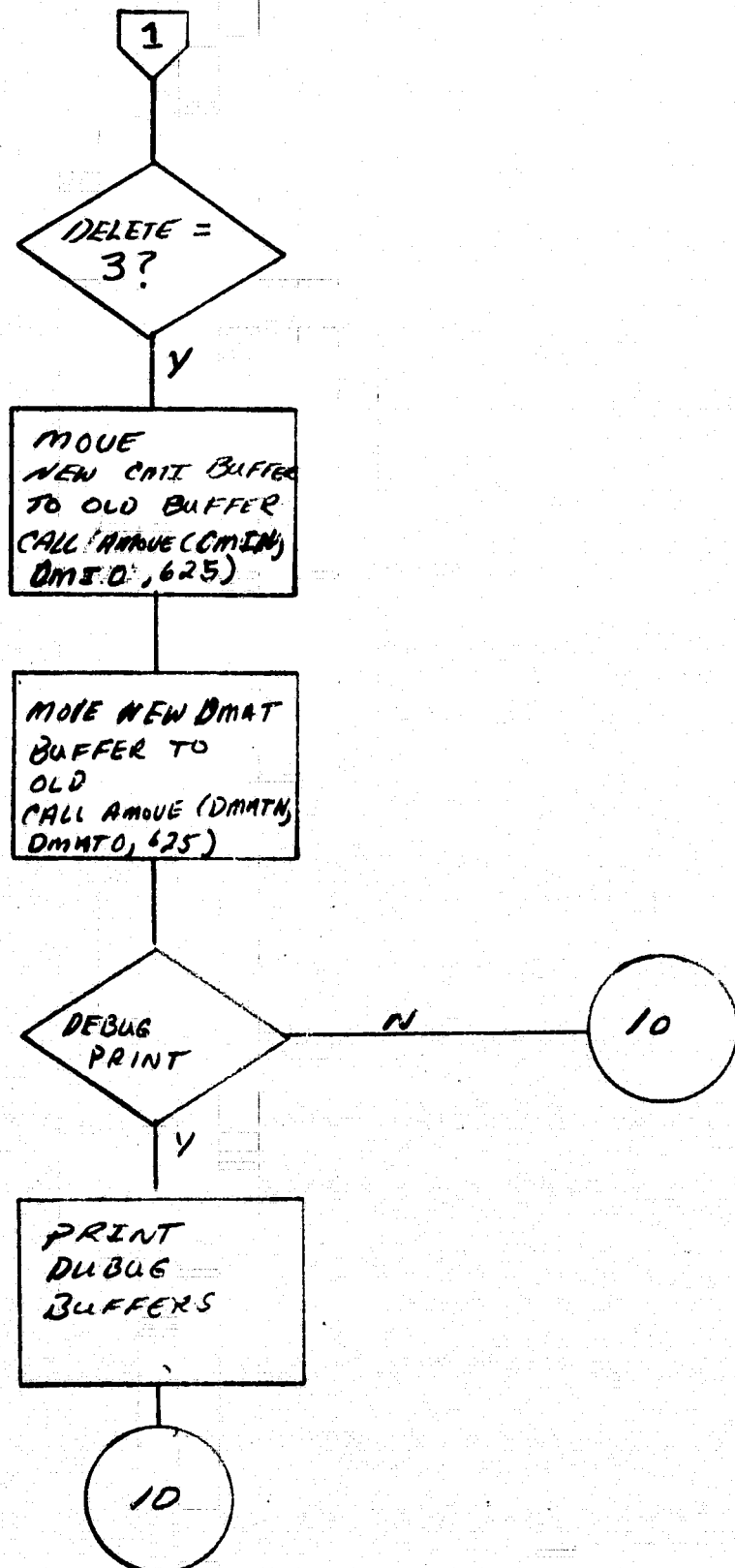
$$T_{i-N+1} = \text{DMAT}_{i-N+1}$$

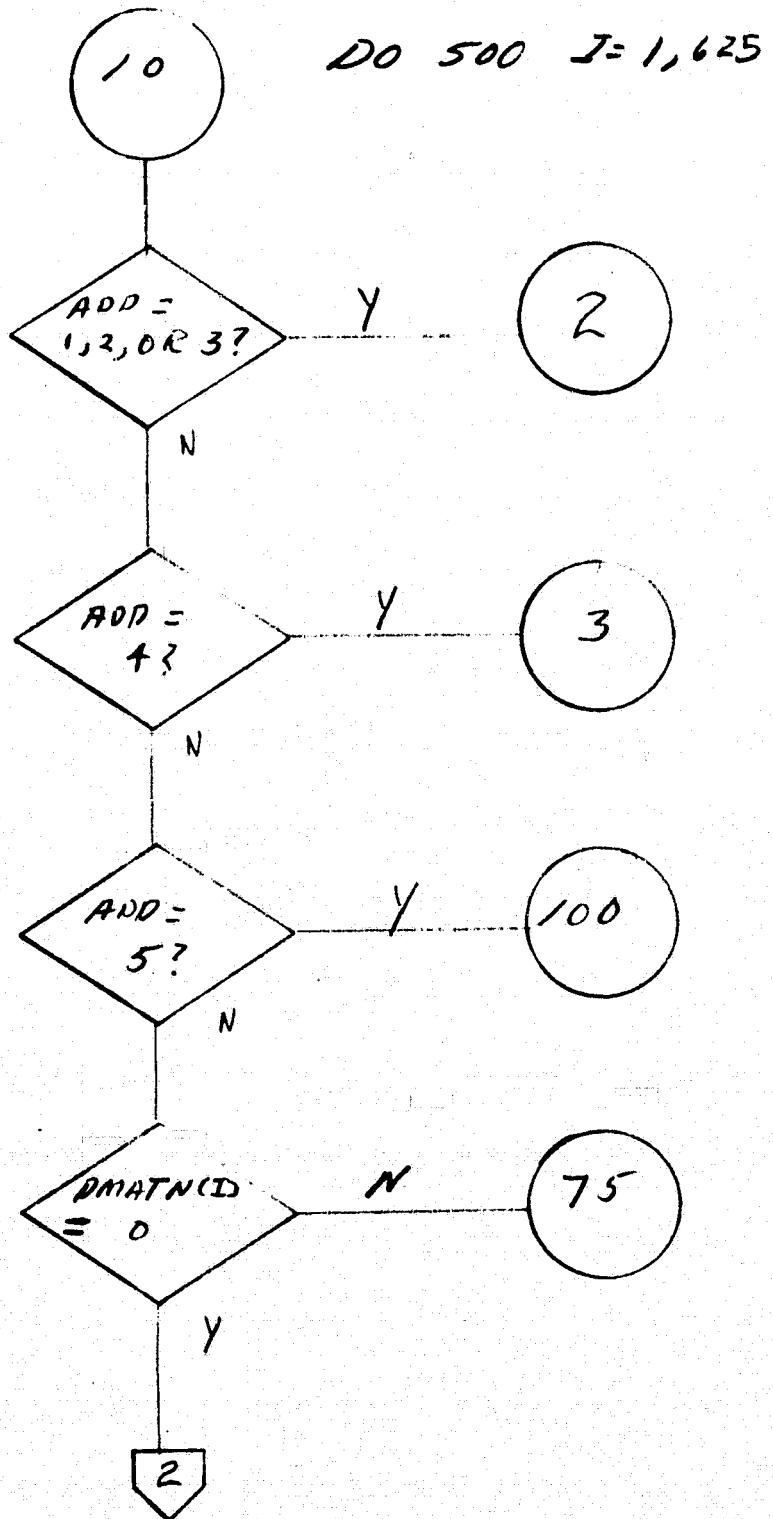
$$T_{i-N+1}' = T_{i-N+1} - 284 \text{ } ^\circ\text{K}$$

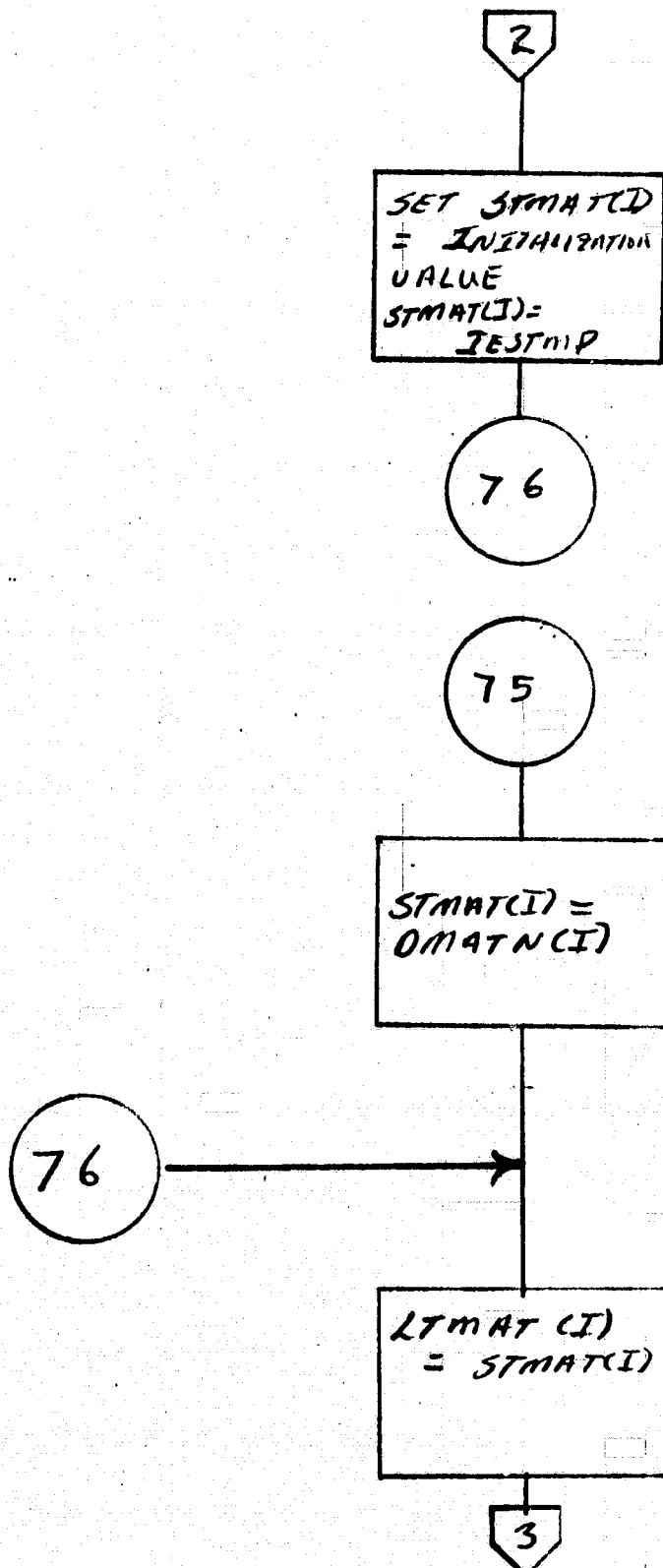
E. DQC. Channel No. 5 is the data quality channel discussed in paragraph 5.2.1.1.

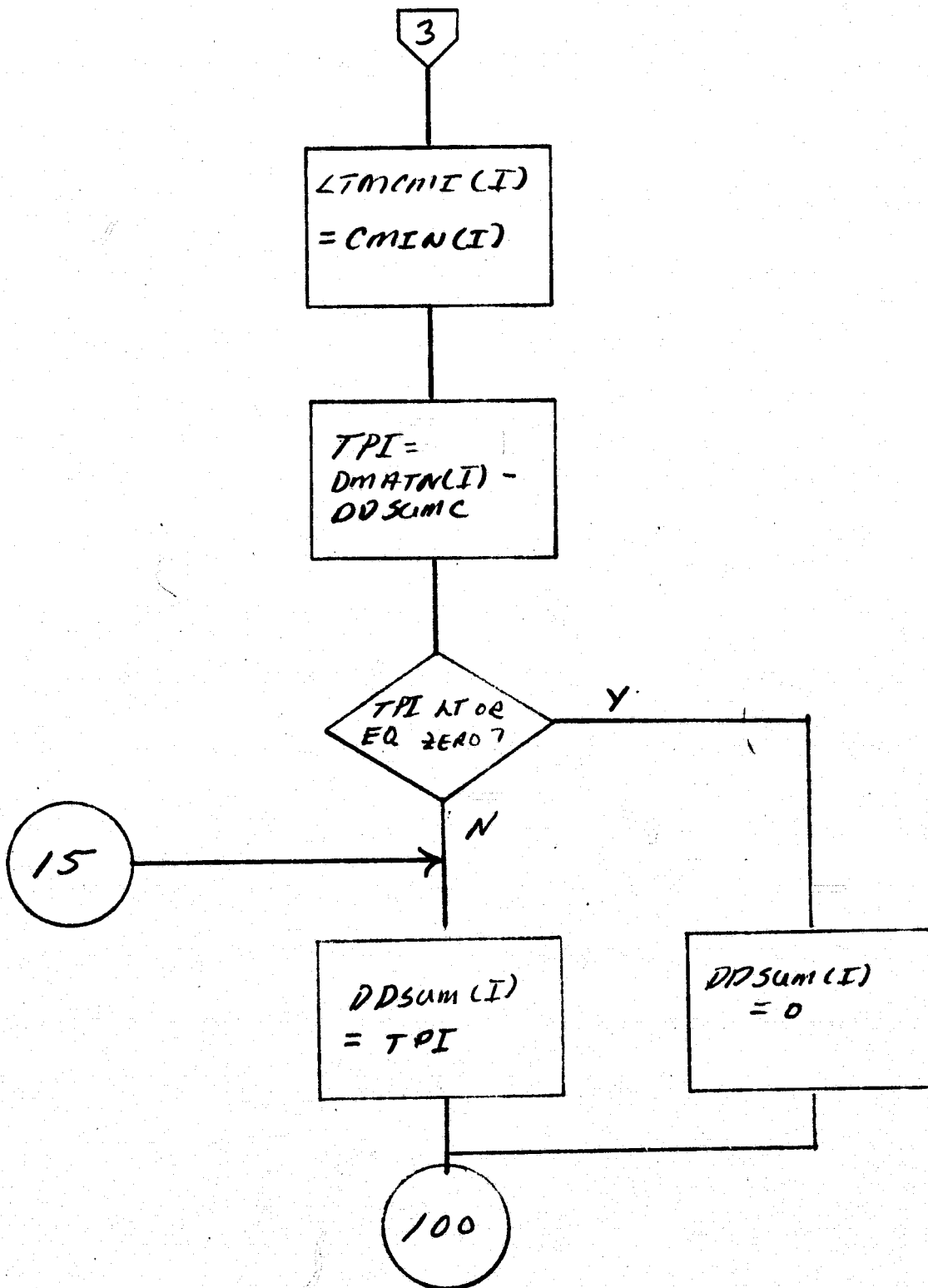
5.2.2.2 Flow Charts. See the following 18 pages.

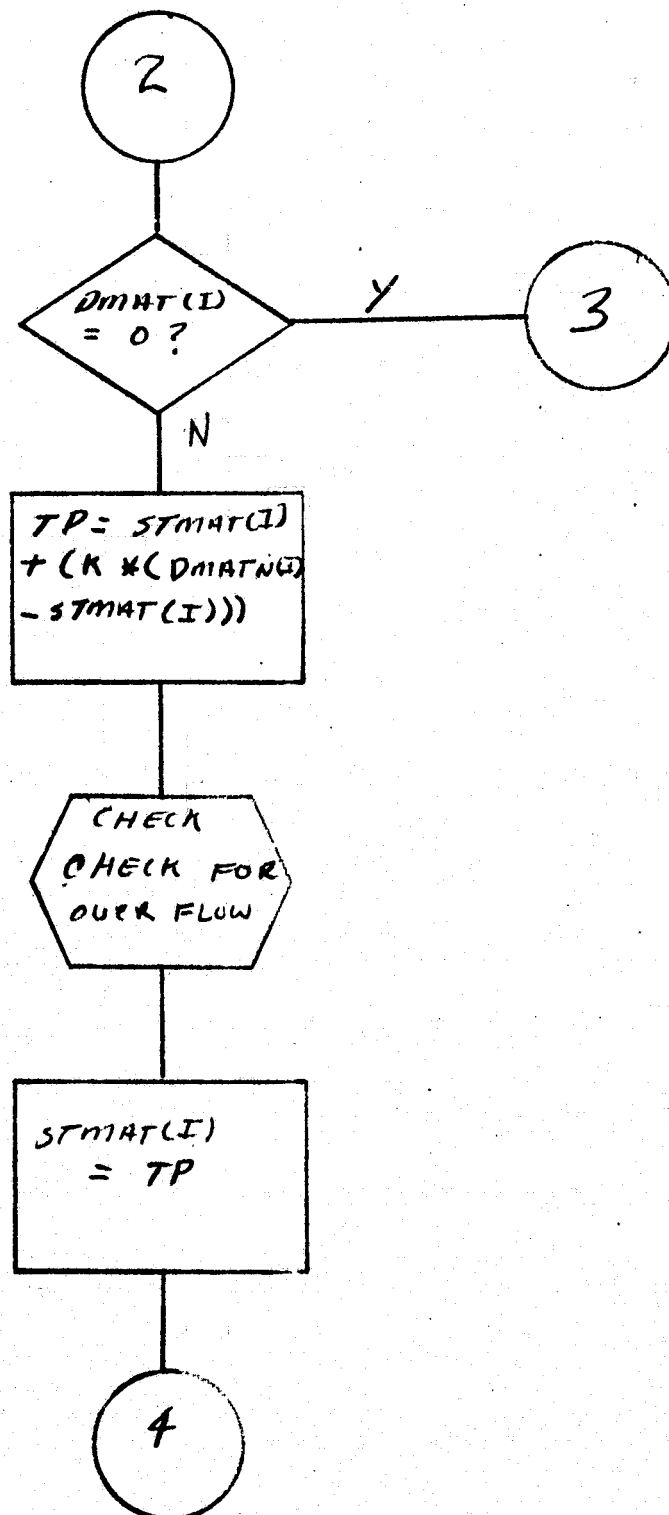


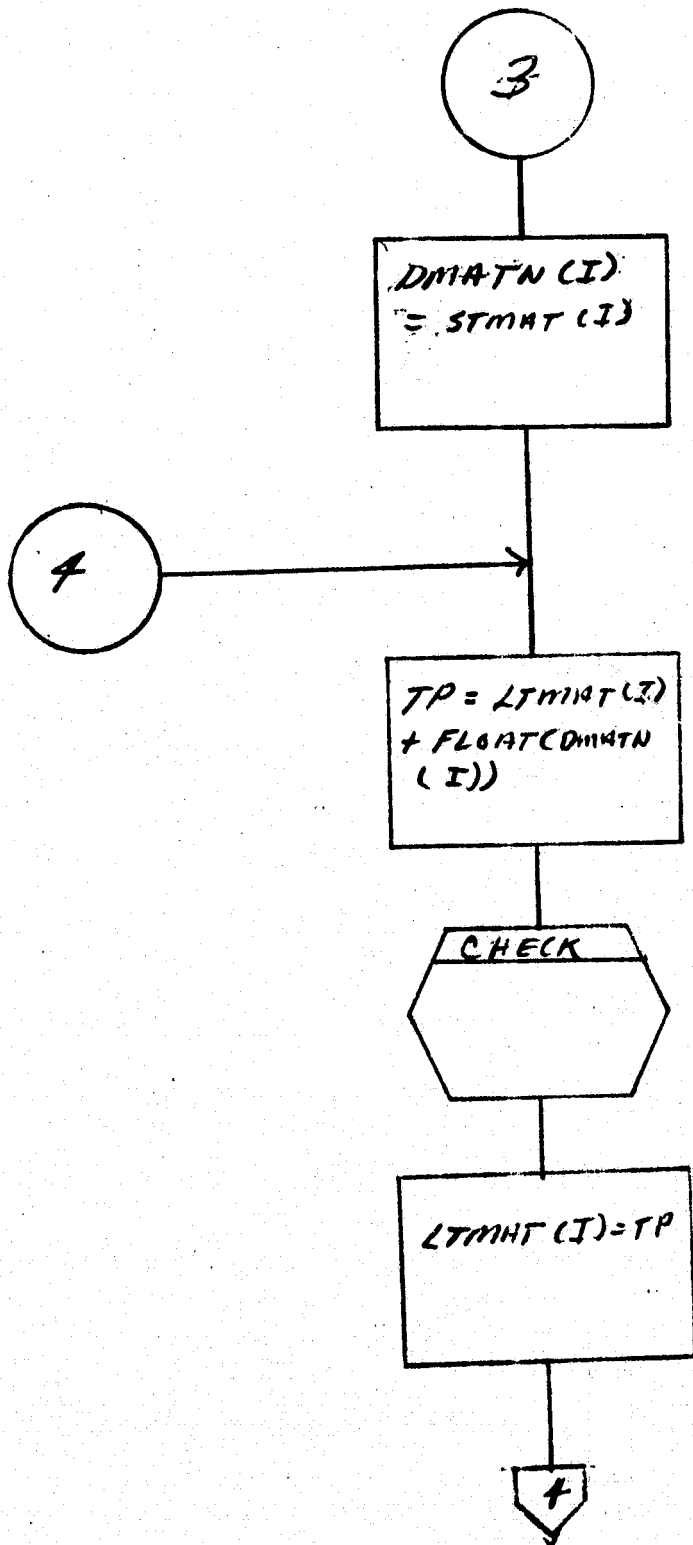


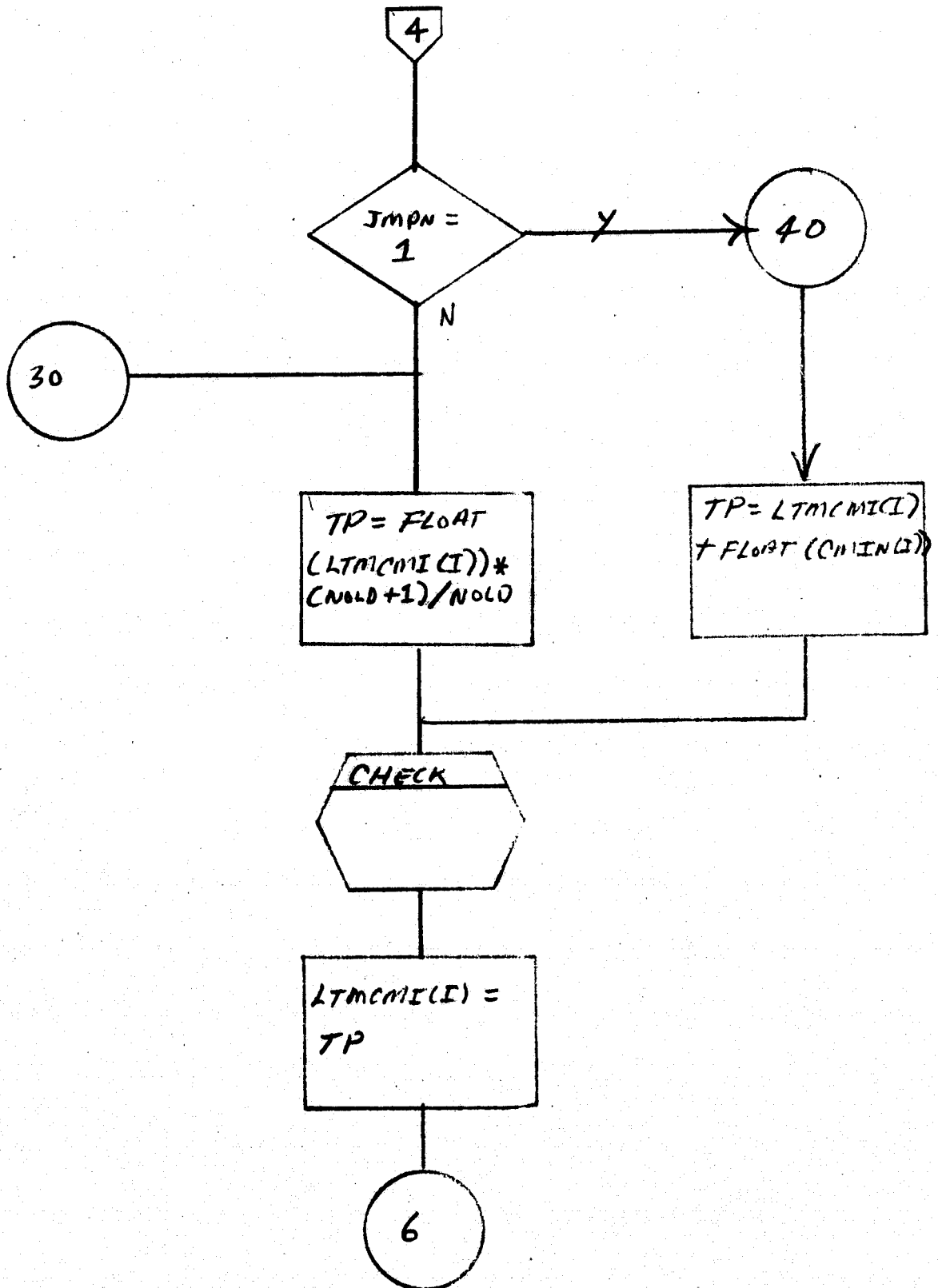


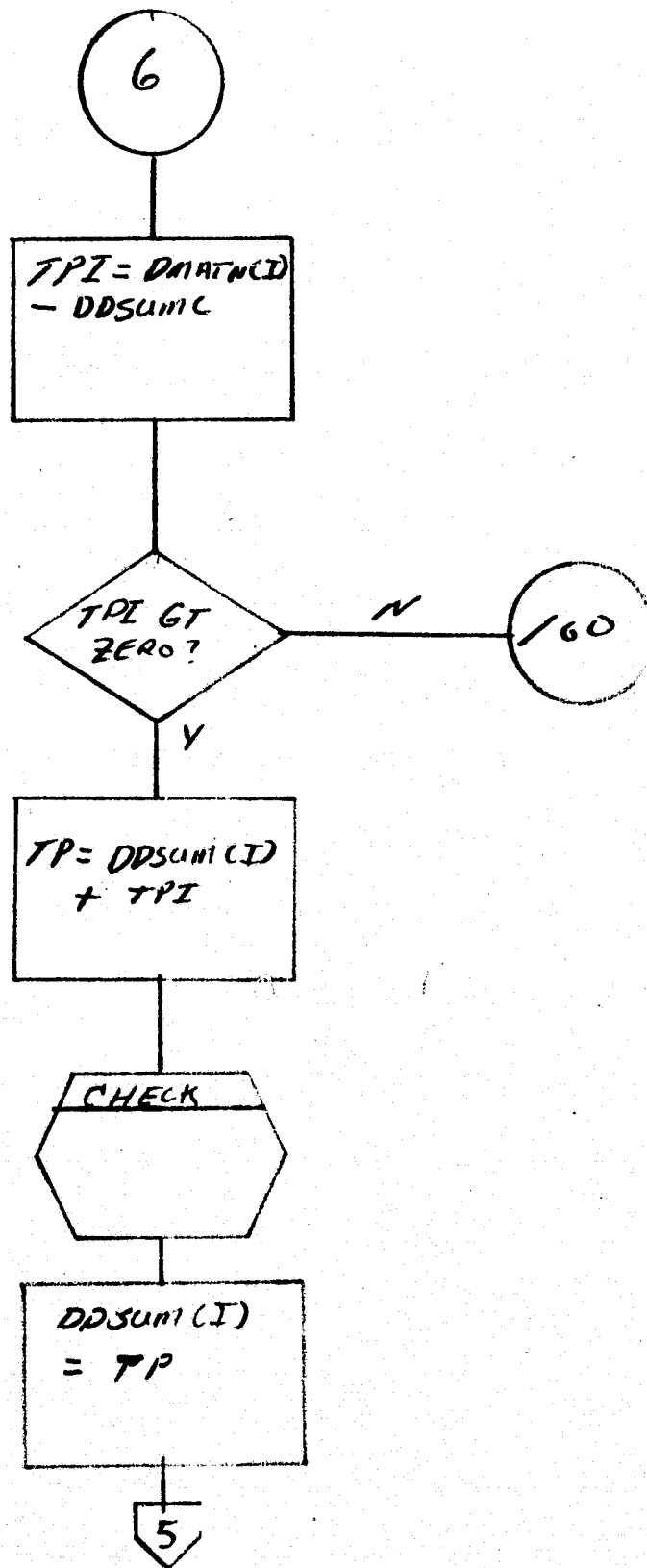


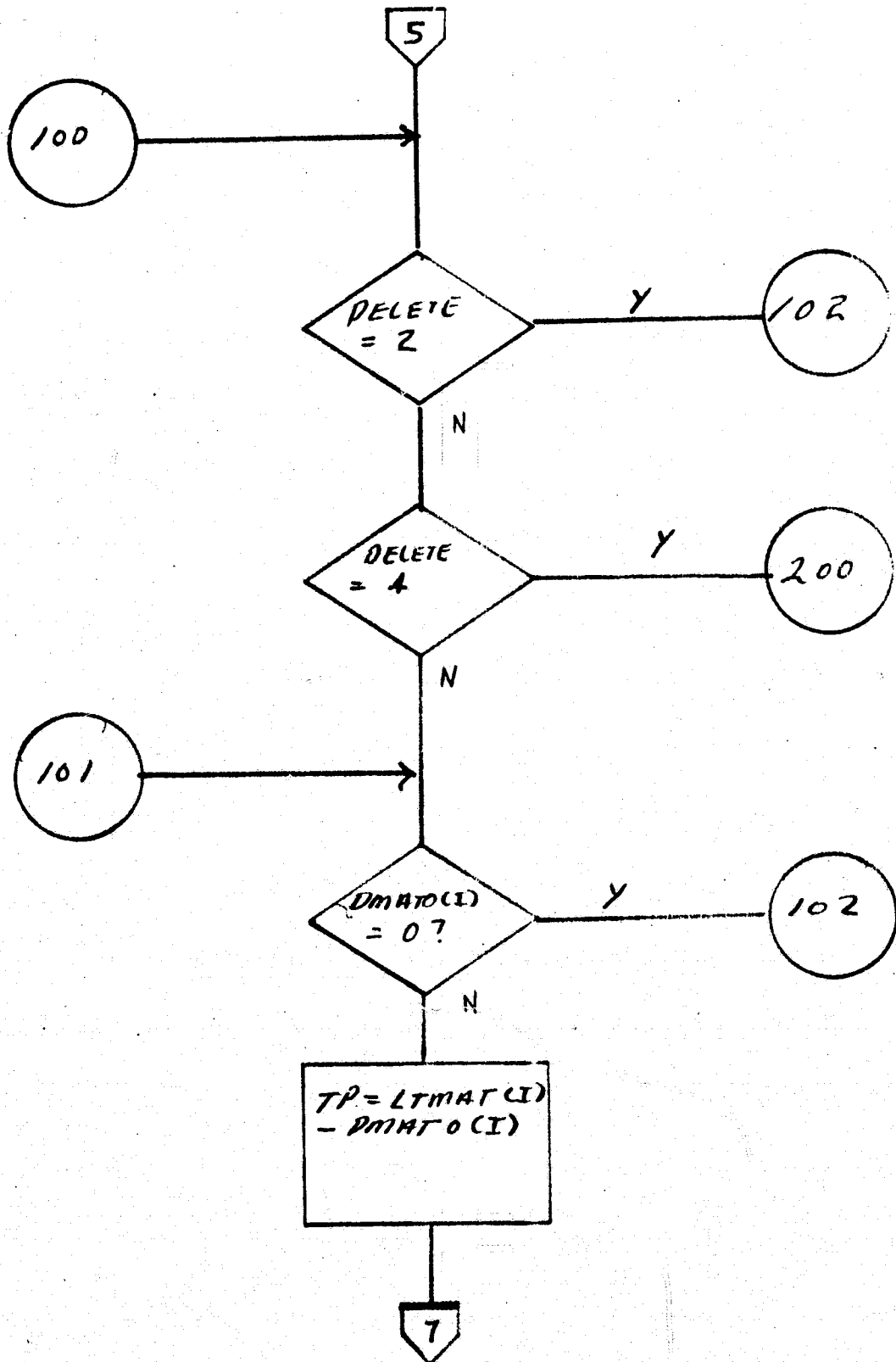


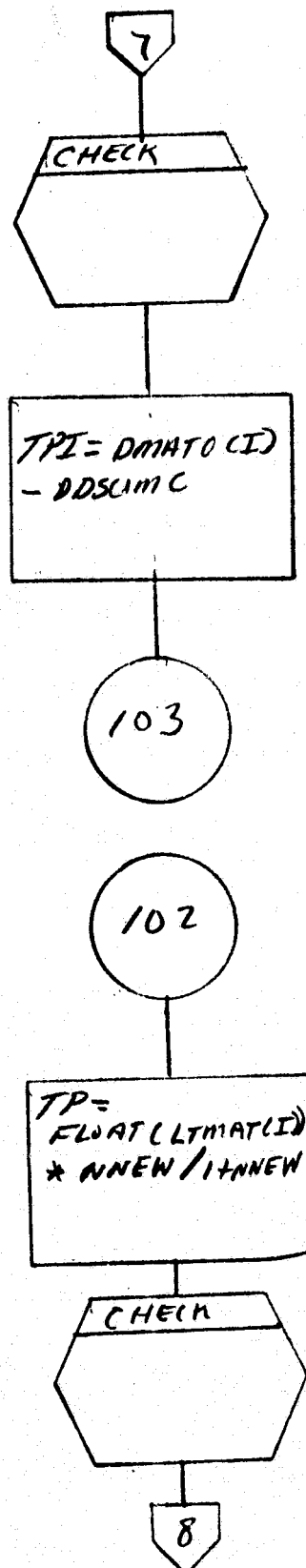


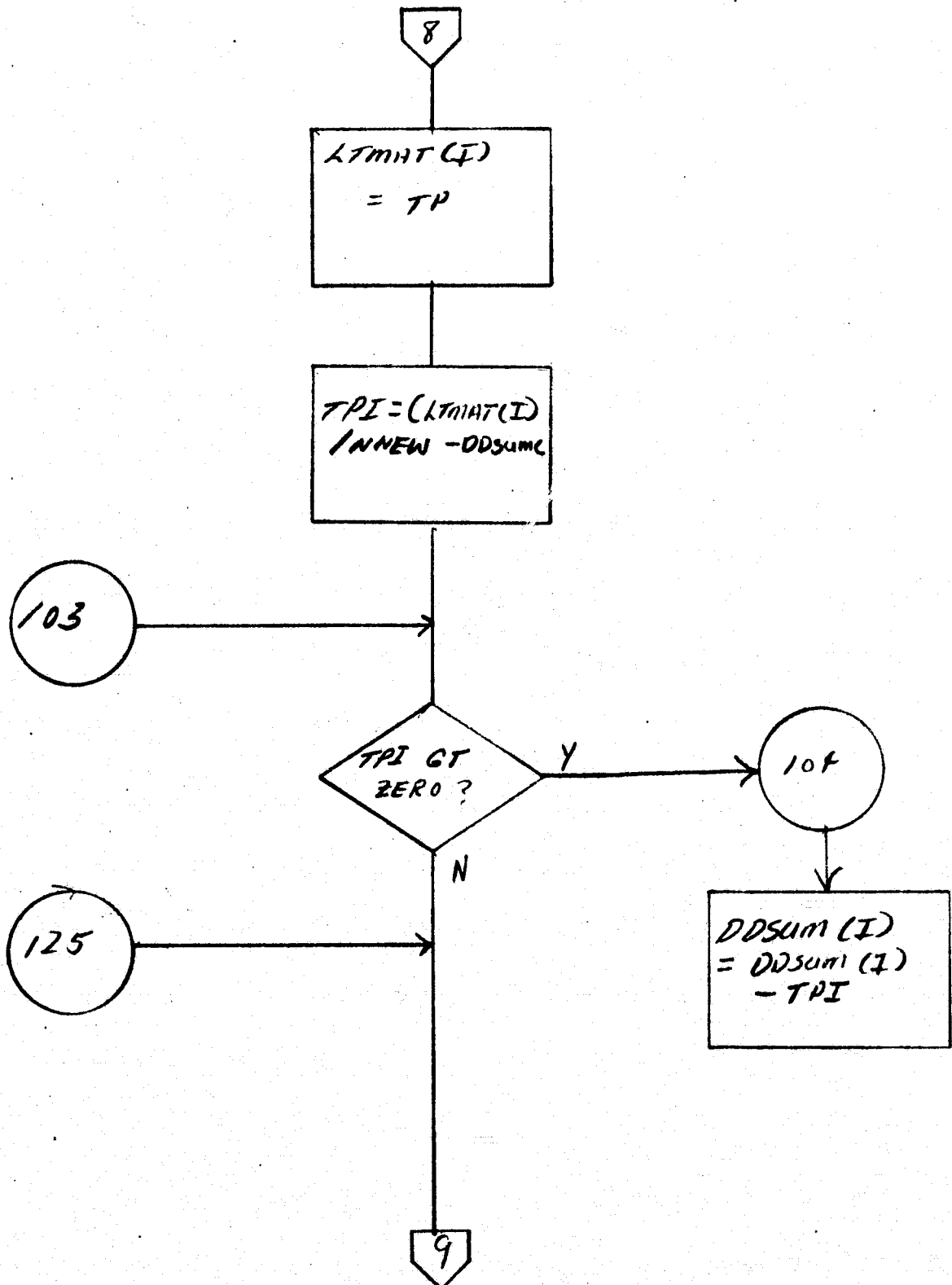


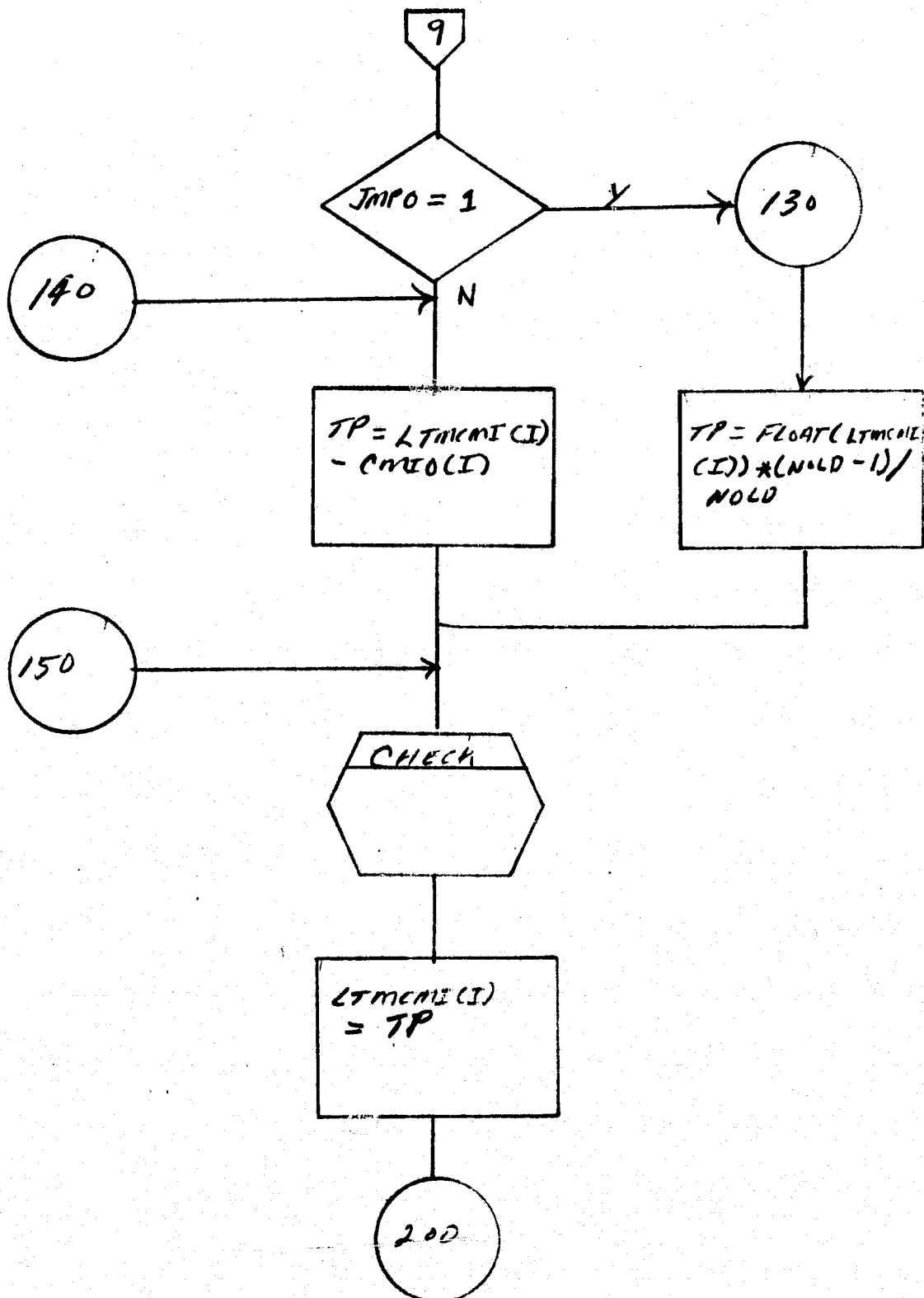


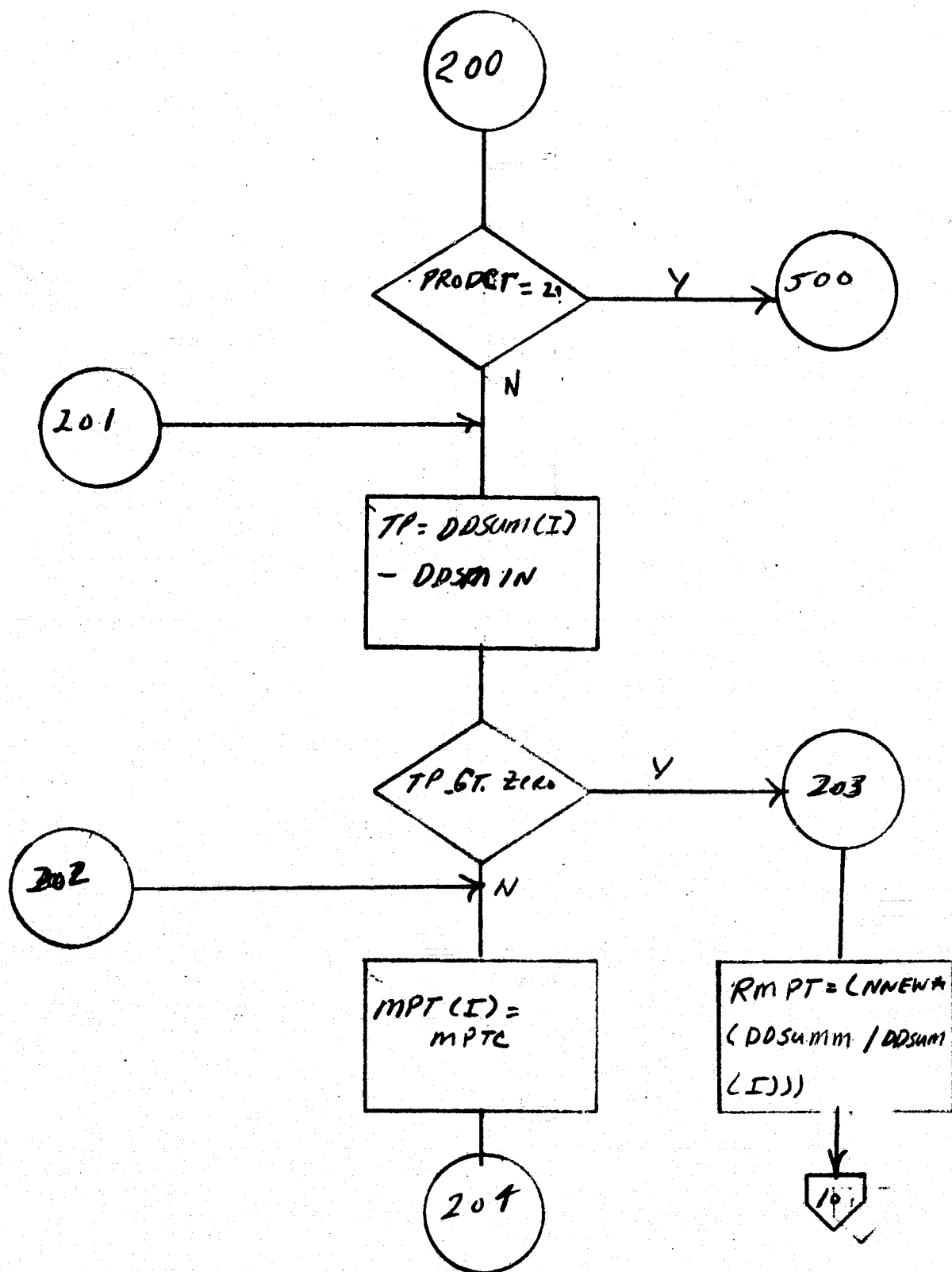


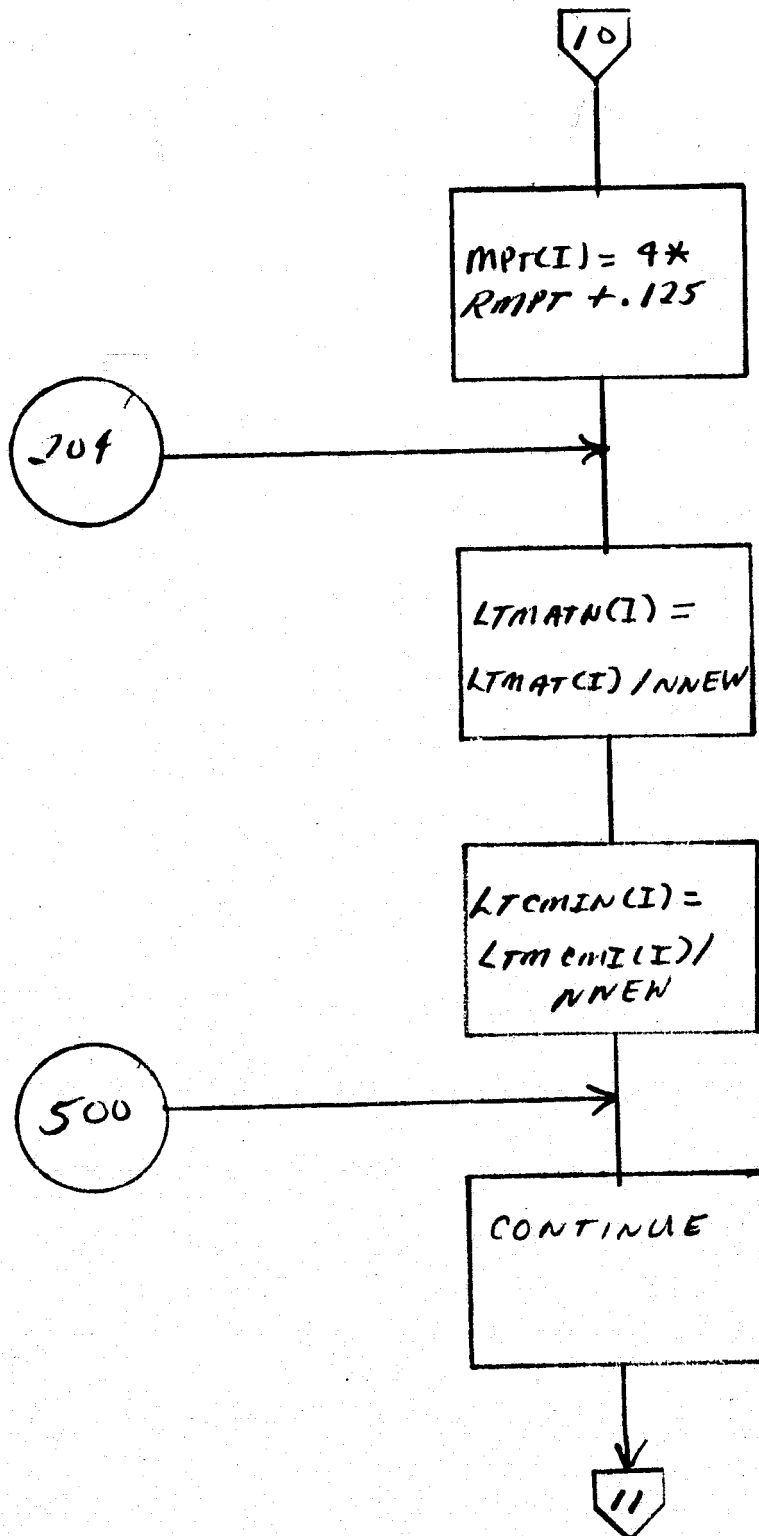


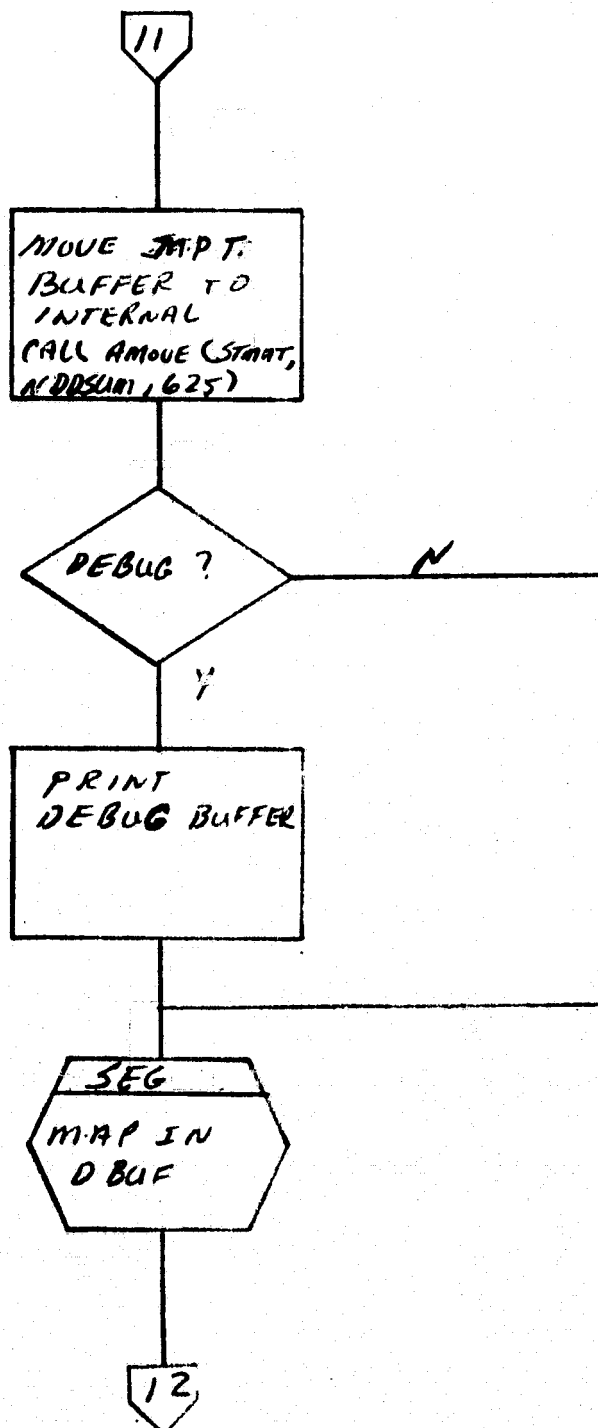


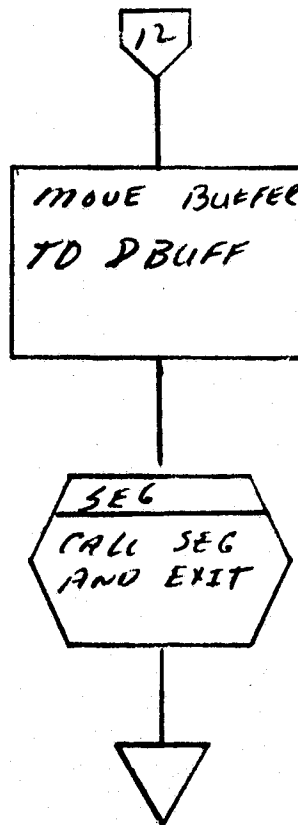






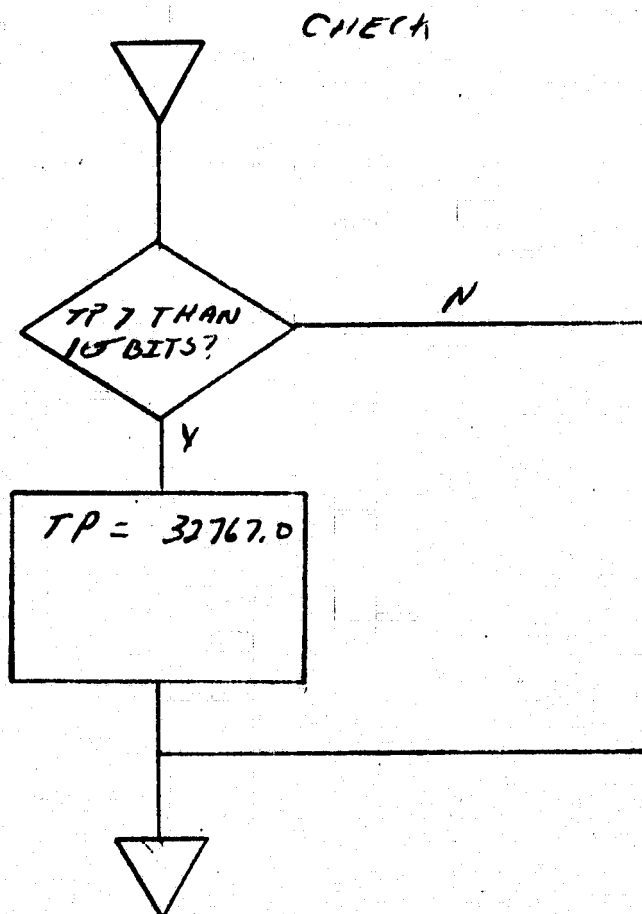






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5.2.2.3 Interfaces

- A. Input Data. The input data to ISCREW comes from an 8K common buffer called ABUFF. The physical layout of this buffer is shown by figure 5-4. As previously described, the upper 4K area of the buffer contains one record from the data base update tape. The lower 4K area contains one record of the corresponding scan line from the previous day's data base tape. The information contained in these two buffers is used to update the SEDS data base and calculate pixel values for the current day's OWC tape images.
- B. Output Data. The new data base values for one scan line are put into the lower 4K area of ABUFF. The OWC images are calculated and in the 4K common buffer called DBUFF. This data is subsequently picked up and used by SWPGEN for product generation.

5.2.2.4 Data Organization. The principle internal data organization of ISCREW consists of fixed constants and intermediate buffers used in the regeneration of the data base, pixel by pixel, within each scan line.

5.2.2.5 Limitations. The major limitation of ISCREW is time. Due to the complexity of some of the data base channel calculations, this program was written in FORTRAN, which inherently runs longer than pure machine language code.

5.2.2.6 CPC Listings. See Part IV of this document, published under separate cover.

5.2.3 SWPGEN. The product generation component of SSP is SWPGEN. Its major functions have been previously discussed in paragraph 5.1. The module is composed of several separate subcomponents; all subroutines are written in PDP-11/45 assembly language.

5.2.3.1 Subcomponent Descriptions

- A. PDGEN. The main subcomponent of SWPGEN is PDGEN. It and SWPGEN's other subcomponents comprise the product generation capability of SEDS. Through the calling sequence to

PDGEN and supporting subroutines, the isothermal, RAP, DPG, and SSP products are calculated, formatted, color coded, and output to tape and/or display. The calling packet to PDGEN may be placed in the user's designated area, or it may be placed in specified memory locations in a SEDS common area named SCOMVT. Figures 5-11 and 5-12 illustrate the two methods. Additional user control through the VT05 is available during initialization for entering items such as tape number and comments. Once program execution has started, input control through the VT05 is lost except for pauses and aborts. A current scan line indicator updates as each line of data is processed. The product generation VT05 display for Data Base Sequence No. 2 (OWC) products is shown in figure 5-13.

- B. OWCPRO. This subroutine is called to calculate, format, and color-assign the eight OWC images of SSP. The input is passed in the data buffer DBUFF as shown by figure 5-4. The first four images in DBUFF are reduced from 16-bit to 8-bit values. This conversion is made through 256-place empirical function tables for growth potential equivalents. The fifth product is a combination of the first four images. The screwworm growth constants displayed on the initial SSP VT05 screen are used in this calculation:

$$S_5 = \frac{A_i}{C} + A_1 S_1 + A_2 S_2 + A_3 S_3 + A_4 S_4$$

Where:

S_1 = Growth potential from STMAT empirical table

S_2 = Growth potential from LTMAT empirical table

S_3 = Growth potential from LTCMI empirical table

S_4 = Growth potential from DDSUM empirical table

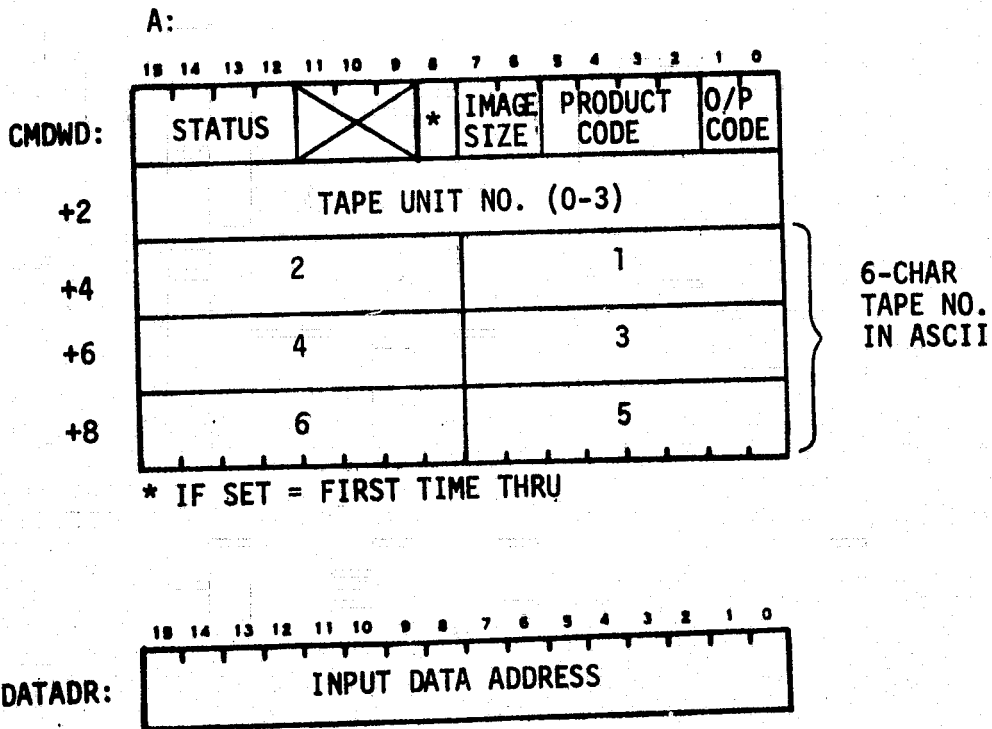
S_5 = Combined growth potential

A_i = Coefficients input via VT05, where $1 \leq A_i \leq +1$

C = Coefficient input via VT05, where $0 < C \leq 200$

NORMAL CALL TO PDGEN:

JSR R5,@#PDGEN
BR A
.WORD CMDWD
.WORD DATADR



OUTPUT CODE (BITS 0, 1):

00 = NONE
01 = DISPLAY
10 = TAPE ONLY
11 = BOTH

IMAGE SIZE (BITS 6-7):

00 = COMPRESSED (625 PIXELS, 550 SCAN LINES)
01 = NORMAL (2500 PIXELS, 2200 SCAN LINES)

STATUS (BITS 12-15):

12 - IF SET, DISPLAY TIME OUT
13 - IF SET, MANUAL ABORT
14 - IF SET, OPERATION COMPLETE
15 - IF SET, INVALID TAPE WRITE

PRODUCT CODE (BITS 2-5):

1000 = ISO DAY (OID)
1001 = ISO NIGHT (OIN)
1010 = CMI
1011 = RAINFALL (ORC)
1100 = SCREWORM (OWC)
1101 = SPECIAL

Figure 5-11 Normal PDGEN Calling Sequence and Packet Format

CALL TO PDGEN:

```

.CSECT  SCOMVT
;
.BLKW  198.
PDGCMD: .BLKW  5  ; CONTROL PACKET
PDGBUF: .BLKW  1  ; INPUT BUFFER ADDRESS
ORBIT:  .BLKW  1  ; ORBIT NUMBER
DODATA: .BLKW  3  ; DATE-OF-DATA
;
.CSECT

```

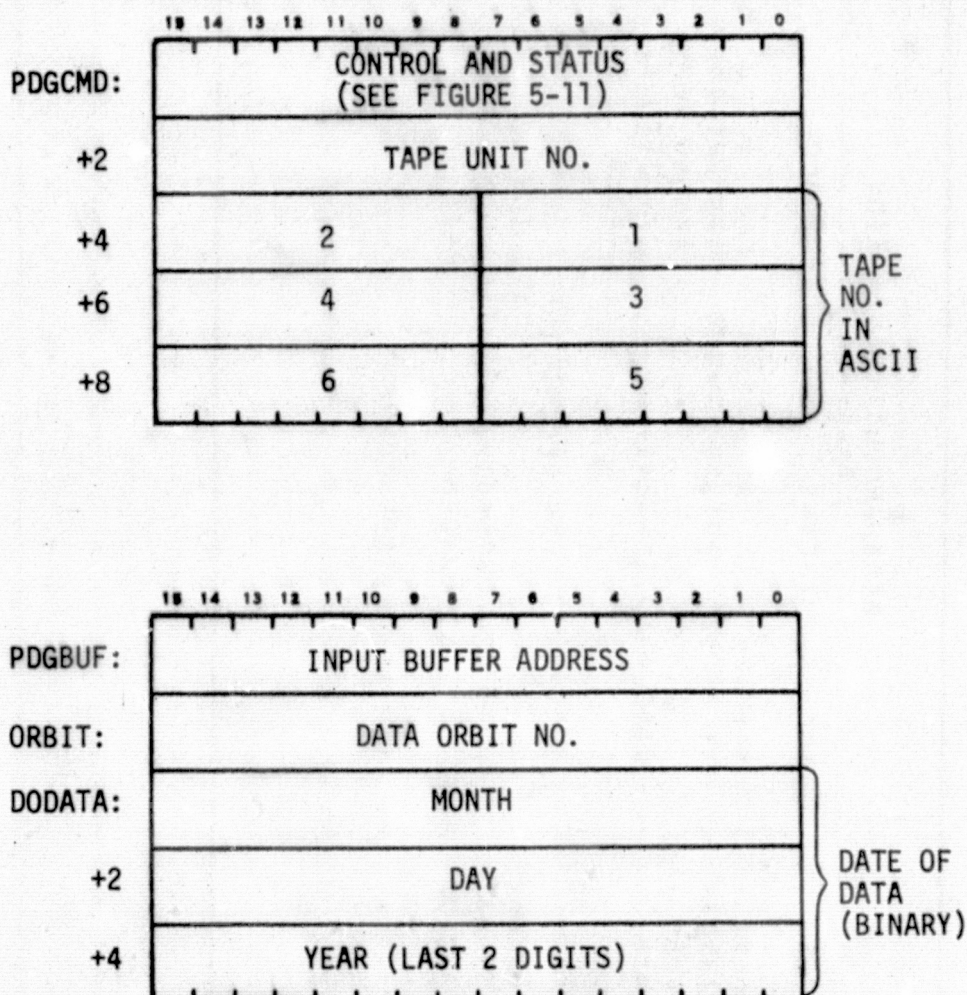


Figure 5-12 Alternate PDGEN Call Packet in Resident Common Area SCOMVT

SEDS PRODUCT GENERATION					DATE: 01-DEC-75	
SCREWWORM					MTU=2	
MODE=3	NBR OF IMAGES=8		COMPRESSED			
0-NONE	NDX	FCT	A	B	* OWC PRODUCTS *	
1-DISPLAY	1	01	+01.00	+000	1=SHORT TERM	5=SCREWWORM
2-TAPE					2=LONG TERM	6=DMAT
3-BOTH	DISPLAYED IMAGES=1			3=MOISTURE	7=NGOOD	
				4=DEGREE DAY	8=STQUAL	
CURRENT=0001						
HDR RECORD INFO						
SYS ID=SFDS		TAPE ID=OWC		SEQ. NO.=01		
SEN ID=NDAA		GEN DATE=01-12-75		TAPE NO=123456		ORBIT=00000
JOB ID=SEDS IMAGE		SCREWWORM		DATE OF DATA=00-00-00		
FILM ANNOTATION COMMENT						

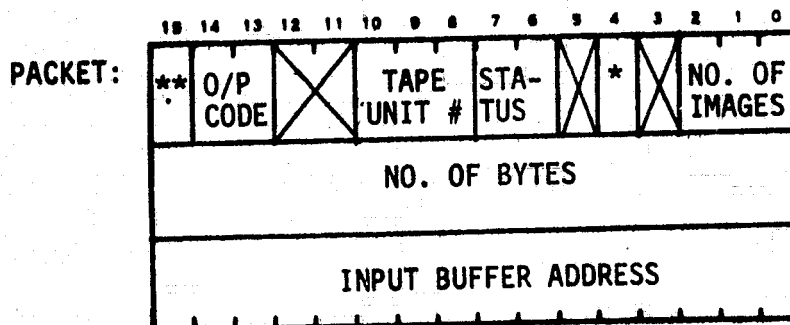
Figure 5-13 PDGEN VT05 Display (OWC)

OWC products 1-5 use the same 256-place table (FCNLS1) for color indexing. Eleven colors are used to represent growth potential measurements between 0.3 and 3.7 in increments of 0.3. The sixth image of SSP is the DMAT from the data base update tape. A 256-place table, DMFCT, containing 28 distinct colors represents temperatures from -3 °C to 40 °C. The seventh and eighth images are from the fifth data base channel. These are NGOOD and STQUAL, discussed previously. The NGOOD image is color indexed from a 15-place table (FCTNGD) representing from 1 to 15 days of good satellite data. The STQUAL image uses another 256-place table, STQFCT, containing 34 colors.

- C. FCGEN. This subroutine is called by PDGEN to do the final color coding and data formatting prior to tape and/or display output. The 6-bit color index is translated via a 64-place table, FCTCVT. At scan line number 492, the product annotation subroutine, OPNOT, is called to overlay the lower part of the images with appropriate alphabetic and numeric annotation for subsequent product identification. The call packet to FCGEN set up by PDGEN is detailed in figure 5-14. The three-word packet is set up internally, based upon the call to PDGEN and VT05 inputs. The number of bytes to be processed for each scan line is 2500 for a normal-sized image, or 625 for a compressed image.
- D. U9WRT. U9WRT is the tape formatter and tape write subroutine called by FCGEN. The subroutine inputs, formats, and outputs data to tape in the Imagery Data Universal Format -- 9-track, 800 bpi, odd parity CCT. As implied by its name, this format can assume many arrangements. Basically, it consists of a header record which defines the format of the following identical tape records. Appendix A explains the universal format in more detail. U9WRT provides a generalized capability to write tapes which are compatible to the Production Film Converter (PFC) for image processing. The set of control arguments required to build the header record and set up an algorithm to set the pattern of the physical tape is shown in figure 5-15. The multiword call packet should be set up on the initial interface with U9WRT, and each successive call should be made for every channel within each scan line.

CALL TO FCGEN:

```
MOV #PACKET,R0 ; PACKET ADR
JSR PC,@#FCGEN ; CALL
```



*ALSO STATUS BIT (SEE BELOW)
**SET IF FIRST TIME THRU

STATUS (BITS 4, 6, 7):

- 4 - SET IF DISPLAY T/O
- 6 - SET IF COMPLETE
- 7 - SET IF TAPE ERROR

OUTPUT CODE (BITS 13, 14):

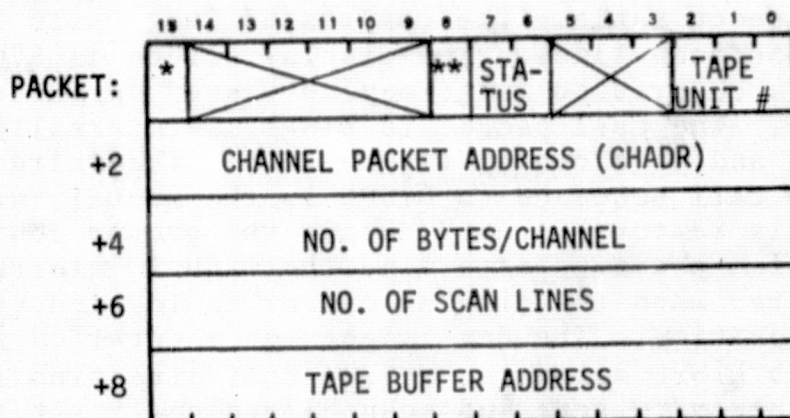
- 00 = NONE
- 01 = DISPLAY
- 10 = TAPE
- 11 = BOTH

Figure 5-14 FCGEN Calling Sequence
and Packet Format

CALL TO U9WRT:

```
JSR      R5,@#U9WRT
BR       A
.WORD    PACKET
.WORD    DATADR
```

A:



*IF SET, NO BYTE REORDERING
**IF SET, WRITE HEADER RECORD

STATUS (BITS 6,7):

6 - SET IF WRITE COMPLETE
7 - SET IF TAPE ERROR

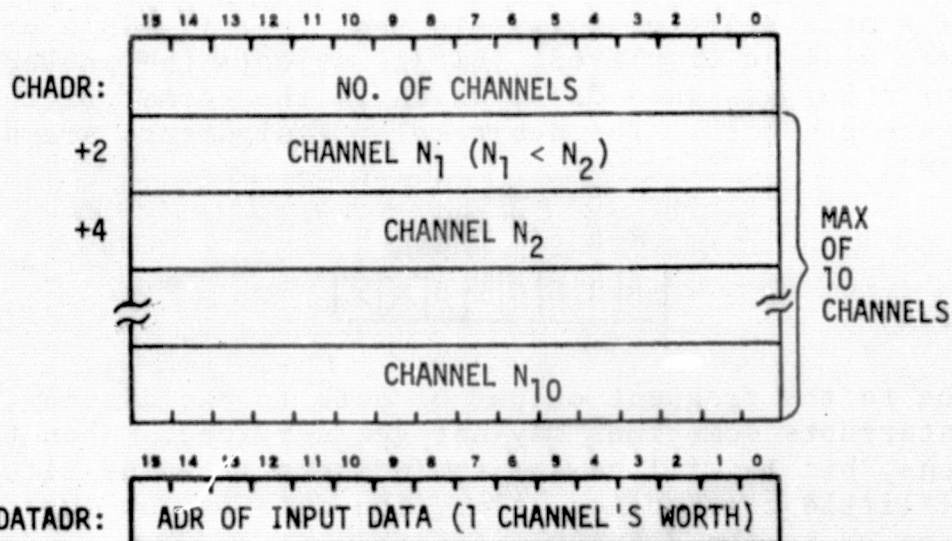


Figure 5-15 U9WRT Calling Sequence and Packet Format

- E. DISPL. This routine is called by FCGEN when the option to output one of the image products to the SEDS display is selected. DISPL interfaces with the display output handler through an EMT call sequence in SEDS. The image data is output to tape first, and then to the display. For a normal image, 2500 pixels by 2200 scan lines, the size is compressed by four in both X and Y directions to preserve the aspect ratio. The compressed image size is 625 pixels by 550 scan lines. The display screen is 576 x 420, so most of a compressed image may be viewed on the display at one time. The call packet to DISPL is internally set up by FCGEN and is shown by figure 5-16. The third parameter of the call sequence to DISPL is the manual interrupt packet. This feature is used during the ground control point location phase to determine the manual interrupt number entered when the display cursor is located at a given X-Y position. The day, night, or annotation data code sent to DISPL determines the scroll direction (top to bottom or bottom to top) and scan direction (right to left or left to right) of the video data as it appears on the display screen. The screen is cleared and the display memory is reset when bit 7 is set for "first time through." Bit 6 does not clear the screen, but outputs five blank lines to the display. In normal display output, the data shift defaults to two and the six LSB's of each byte of data will be displayed in black and white. The data shift counter effects a left shift on the eight bits of data. If a data shift of 0 is selected, the six MSB's of each byte will be displayed. Bit 11 selects the packed mode for color assigned data, which is the format of the SEDS image products. The 6-bit color assignments are as follows:

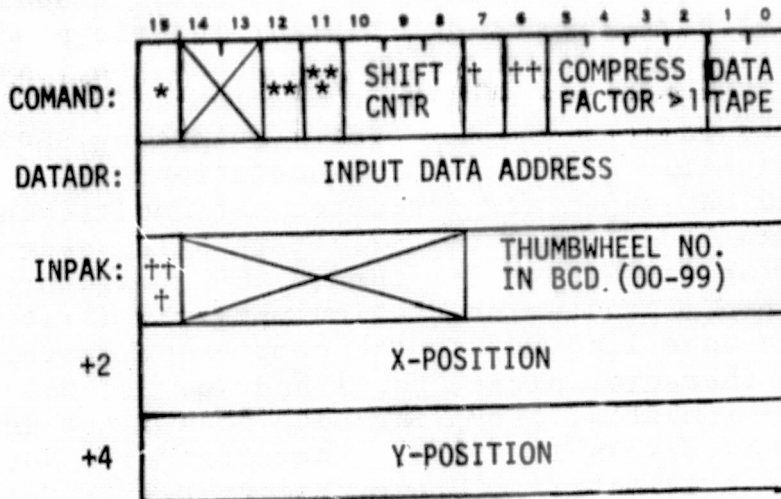
7	6	5	4	3	2	1	0
R	R	G	G	B	B	X	X

Due to the frequent output of data to the display, random interrupts sometimes may not get serviced. When this happens, bit 15 will be set to indicate it. The situation is of little consequence, since the data is not lost to the tape or to the display.

CALL TO DISPL:

```
JSR    R5,@#DISPL
BR      A
.WORD  COMMAND ; INPUT COMMAND
.WORD  DATADR  ; DATA ADDRESS
.WORD  INPAK   ; MANUAL INTERRUPT PACKET
```

A:



*SET IF DISPLAY TIMEOUT
 **SET IF BYPASS INTERRUPT COMPLETE
 ***SET IF PRODUCT IMAGE
 †SET IF FIRST TIME THRU
 ††SET IF RESTART
 †††SET IF INTERRUPT

DATA TYPE (BITS 0-1):

00 = DAY
 01 = NIGHT
 10 = ANNOTATION

Figure 5-16 DISPL Calling Sequence and Packet Format

- F. OPNOT. This routine is called by FCGEN to initiate the output of the image product identification feature. Product annotation for compressed images starts at scan line 492, and for normal-sized images at scan line 1968. The annotation format varies somewhat for each image; generally, it has four character lines. The first contains the image name, data of data, and orbit number; the second contains a color bar scale of the colors represented in the image; the third contains an explanation of the color shades beneath the color bar; and the fourth contains the production date and an optional real-time comment about the image, entered via VT05 prior to program execution. Table 5-4 illustrates the various image products output by SEDS which require alphanumeric and color bar annotation. The images on the ORC and OWC tapes are formatted into multichannel, compressed scan lines. Figures 5-17 thru 5-19 identify the specific annotation layouts for the 15 SEDS image products. The alphanumeric character annotation uses the first 616 pixels of each scan line across the compressed image. There are two character sizes, No. 1 and No. 2. No. 1 resides in a 9×7 matrix, occupying nine scan lines in height and seven pixels in width. Character size No. 2 requires an 18×14 matrix. Using character size No. 2 as the basis, 44 character positions ($44 \times 14 = 616$) account for the width of the annotation. The size of the individual color squares in the color bar scale are set so that correct spacing of character size No. 1 annotation is achieved. The color content in the various color bar scales will be discussed elsewhere in this document. The numbers shown for each color square reflect only a sequential count of the number of distinct colors present. The three annotation lines and color bar scale require 54 scan lines on the compressed images.
- G. ANNOT. This routine is called by the subroutine OPNOT to perform the dot matrix character generation of the annotation feature. In general, the call to ANNOT consists of three items of information, the address of an input character string, the address of the output buffer, and the address of a control word. The input character string must contain ASCII characters terminated by a code of 1338.

TABLE 5-4
SEDS IMAGE PRODUCTS

SEDS PROGRAM	TAPE ID	IMAGE NAME	DESCRIPTION
SRE (REGISTRATION)	OID OIN	ISO DAY ISO NIGHT	TEMP CODED DAY IR CHAN (NORMAL OR COMP) TEMP CODED NIGHT IR CHAN (NORMAL OR COMP)
RAP (DATA BASE SEQ NO. 1)	ORC	1) R/F 2) TGT 3) ΔT 4) TMET (ID) 5) QUAL	COLOR CODED CLOUD DETENTION IMAGE COLOR CODED ESTIMATED GROUND TRUTH TEMP COLOR CODED CURRENT TEMP DIFFERENCE BETWEEN ACTUAL AND ESTIMATED VALUES COLOR CODED DMAT VALUES OF MET STATION REPORTS VIA CARD INPUTS COLOR CODED SOURCE MAP OF TEMP DATA
SSP (DATA BASE SEQ NO. 2)	OWC	1) STMAT 2) LTMAT 3) LTCMI 4) DDSUM 5) S/W 6) DMAT 7) NGOOD 8) STQUAL	SHORT-TERM GROWTH POTENTIAL BASED ON DMAT LONG-TERM GROWTH POTENTIAL BASED ON DMAT GROWTH POTENTIAL BASED ON LONG-TERM CMI GROWTH POTENTIAL BASED ON DEGREE DAY SUM COMBINED GROWTH POTENTIAL MAP COLOR CODED TEMP MAP OF DAILY MEAN AIR TEMP COLOR CODED MAP OF NO. OF DAYS OF SATELLITE DATA IN DATA BASE COLOR CODED MAP OF SHORT-TERM MEAN QUALITY OF DATA

01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44

D A Y I S O T H E R M A L

0 0 - 0 0 - 0 0 N O . 0 0 0 0 0

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28
+4	12	17	21	24	26	27	28	29	30	31	32	33		34		35		36		37		38	39	41	44	49	

PRODUCTION DATE: 00-XXX-00

COMMENT

N I G H T I S O T H E R M A L

0 0 - 0 0 - 0 0 N O . 0 0 0 0 0

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28
- 30	7	12	15	17	19	20	21	22	23	24		25		26		27		28		29	30	31	32	34	38	43	

PRODUCTION DATE: 00-XXX-00

COMMENT

Figure 5-17 OID/OIN Isothermal Image Annotation

01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44

R A I N F A L L

0 0 - 0 0 - 0 0 N O . 0 0 0 0 0 0

WHITE	BLUE	GREEN	YELLOW	RED	VIOLET
NULL	CLR	CD	LR	MR	HR

PRODUCTION DATE: 00-XXX-00

COMMENT

G R D T R U T H T E M P E R A T U R E - T G T 0 0 - 0 0 - 0 0 N O . 0 0 0 0 0 0

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28
-3	0	+3	6	9	12	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	32	34	36	38	40	50

PRODUCTION DATE: 00-XXX-00

COMMENT

C U R R E N T D E L T A T V A L U E S 0 0 - 0 0 - 0 0 N O . 0 0 0 0 0 0

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28
-9	-7	-5	-4	-3	-2	-1	0	+1	+2	+3	+4	+5	+7	+9													

PRODUCTION DATE: 00-XXX-00

COMMENT

M E T S T A R E P O R T S - T M E T (I D) 0 0 - 0 0 - 0 0 N O . 0 0 0 0 0 0

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28
-3	0	+3	6	9	12	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	32	34	36	38	40	50

PRODUCTION DATE: 00-XXX-00

COMMENT

D A T A Q U A L I T Y M A P - Q U A L 0 0 - 0 0 - 0 0 N O . 0 0 0 0 0 0

BLACK	RED	BLUE	GREEN
-------	-----	------	-------

PDHAT & TMET (ID) = 0 ONLY MET STA DATA ONLY SATELLITE DATA SATELLITE & MET DATA

PRODUCTION DATE: 00-XXX-00

COMMENT

JSC-10019
Part II

Figure 5-18 ORC - RAP Image Annotation

SHORT TERM GROWTH

00 - 00 - 00 NO . 000000

PRODUCTION DATE: 00-XXX-00

01	02	03	04	05	06	07	08	09	10	11
0.3	0.7	1.0	1.3	1.7	2.0	2.3	2.7	3.0	3.3	3.7

COMMENT

LONG TERM GROWTH

00 - 00 - 00 NO . 000000

PRODUCTION DATE: 00-XXX-00

01	02	03	04	05	06	07	08	09	10	11
0.3	0.7	1.0	1.3	1.7	2.0	2.3	2.7	3.0	3.3	3.7

COMMENT

MOISTURE INDEX

00 - 00 - 00 NO . 000000

PRODUCTION DATE: 00-XXX-00

01	02	03	04	05	06	07	08	09	10	11
0.3	0.7	1.0	1.3	1.7	2.0	2.3	2.7	3.0	3.3	3.7

COMMENT

DEGREE DAY GROWTH

00 - 00 - 00 NO . 000000

PRODUCTION DATE: 00-XXX-00

01	02	03	04	05	06	07	08	09	10	11
0.3	0.7	1.0	1.3	1.7	2.0	2.3	2.7	3.0	3.3	3.7

COMMENT

SCREW WORM GROWTH

00 - 00 - 00 NO . 000000

PRODUCTION DATE: 00-XXX-00

01	02	03	04	05	06	07	08	09	10	11
0.3	0.7	1.0	1.3	1.7	2.0	2.3	2.7	3.0	3.3	3.7

COMMENT

DAILY MEAN AIR TEMP

00 - 00 - 00 NO . 000000

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28
-3	0	+3	6	9	12	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	32	34	36	38	40	50

COMMENT

PRODUCTION DATE: 00-XXX-00

DAYS OF SATELLITE DATA 00 - 00 - 00 NO . 000000

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
1	2	3	4	5	6	7	8	9	10	11	12	13	14	>14

COMMENT

PRODUCTION DATE: 00-XXX-00

SHORT TERM DATA QUALITY

00 - 00 - 00 NO . 000000

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34

COMMENT

PRODUCTION DATE: 00-XXX-00

Figure 5-19 OWC - SSP Image Annotation

The call packet to ANNOT is internally set up by OPNOT and is shown by figure 5-20. Figure 5-21 illustrates the composition of the legal annotation characters as they are formed in a 5×7 dot matrix. To ensure that proper spacing and bordering is achieved, the characters reside in a 7×9 cross-section rectangle within the character line.

5.2.3.2 Flow Charts. See 105 pages following figures 5-20 and 5-21.

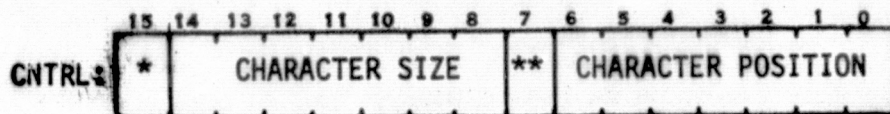
CALL TO ANNOT:

```

JSR    R5,@#ANNOT
BR     A
.WORD  INBUF      ; INPUT STRING ADR
.WORD  OUTBUF     ; OUTPUT BUF ADR
.WORD  CNTRL      ; CONTROL WORD

```

A:



*SCROLL DIRECTION (0 = TOP TO BOTTOM, 1 = BOTTOM TO TOP)
 **SET IF PRODUCT ANNOTATION

Figure 5-20 ANNOT Calling Sequence
and Packet Format

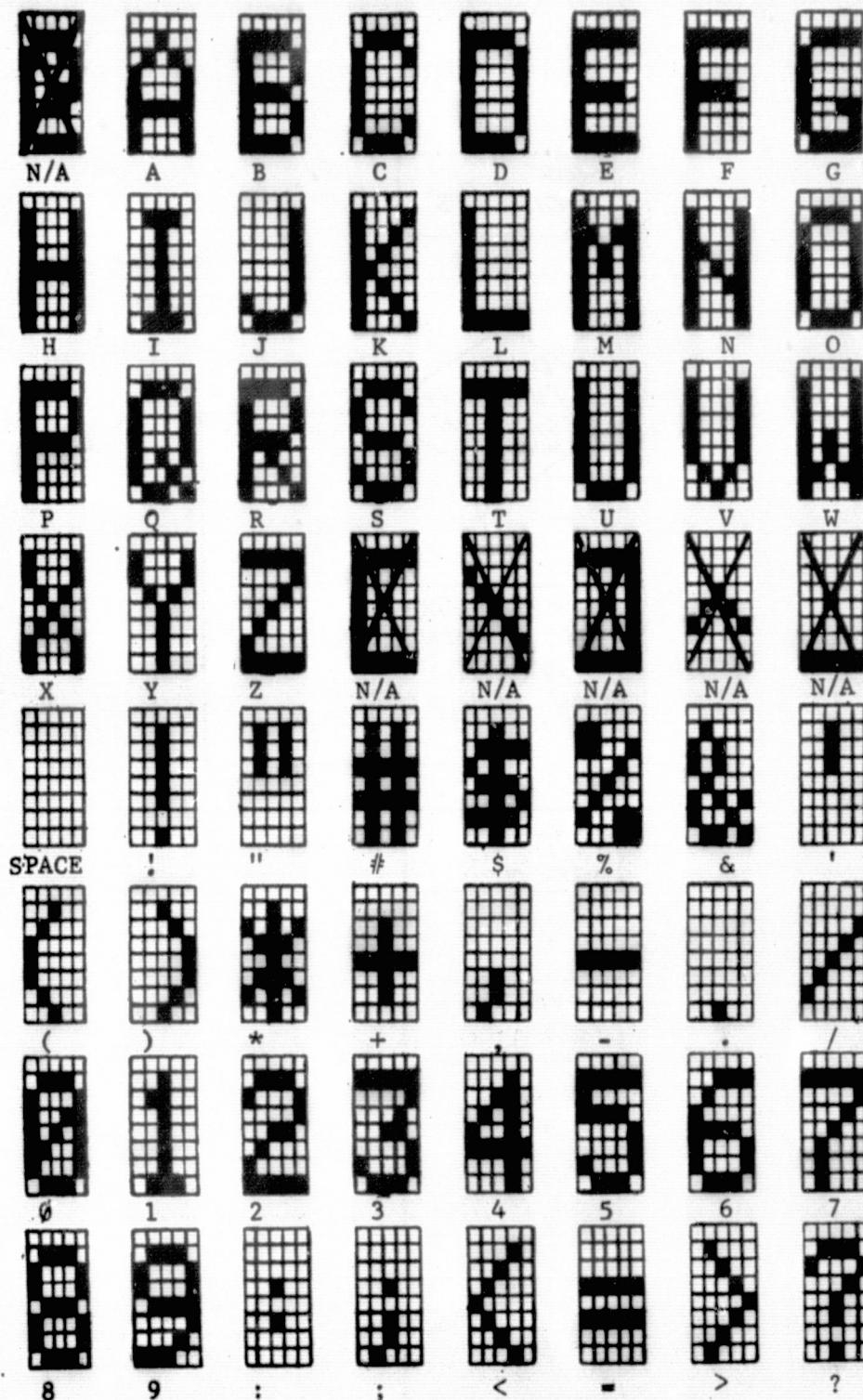
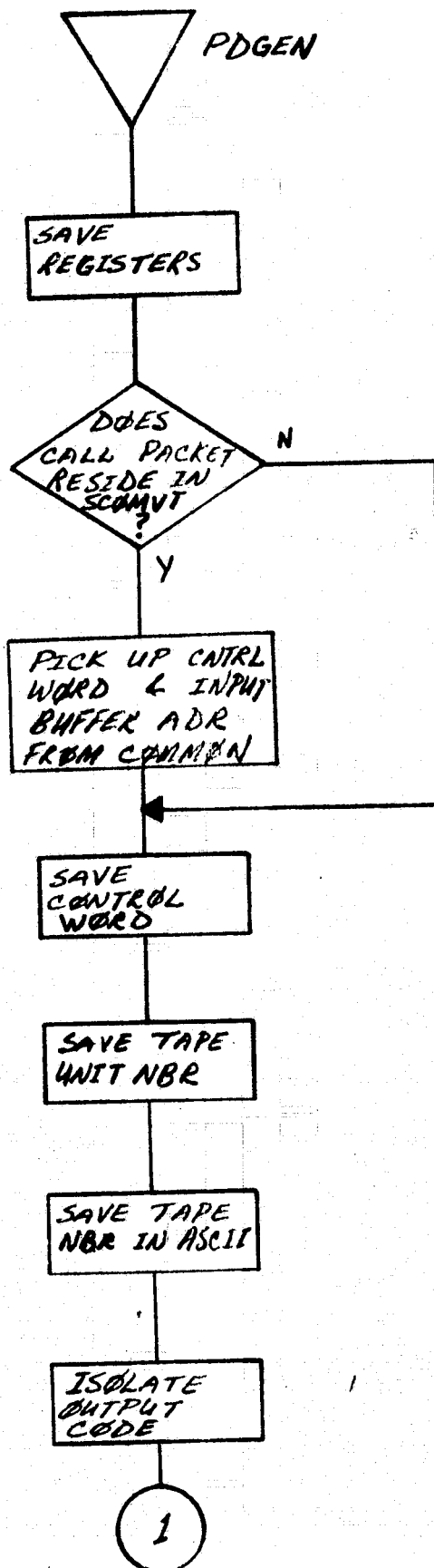
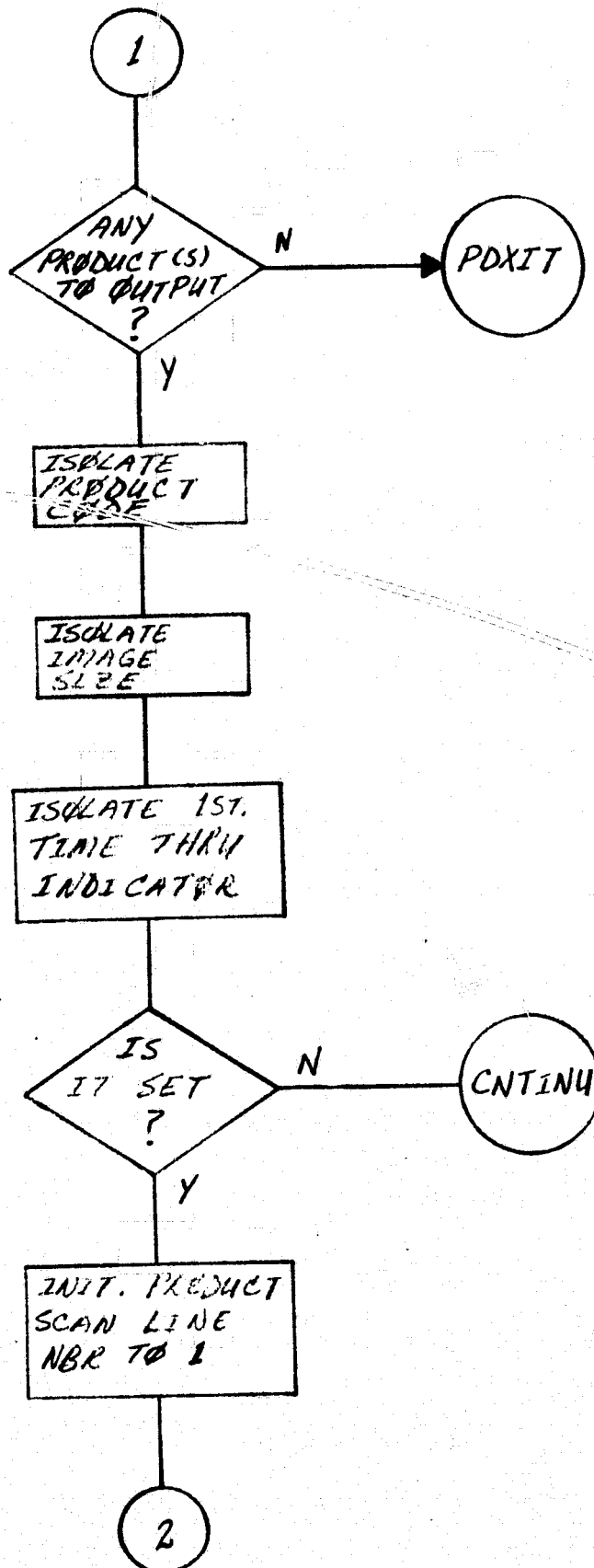
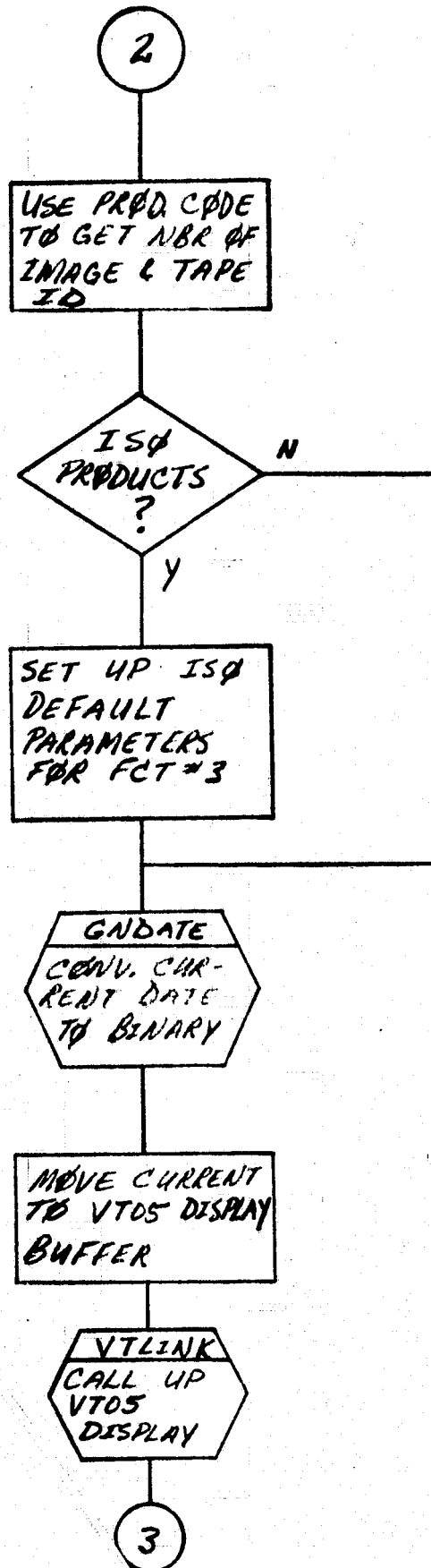


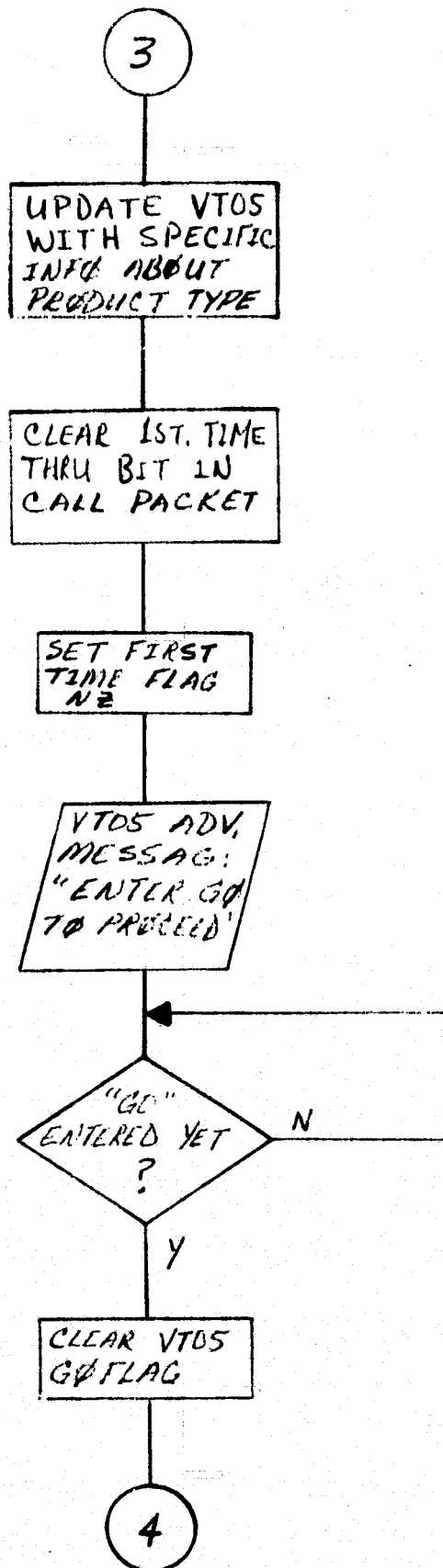
Figure 5-21 Annotation Characters

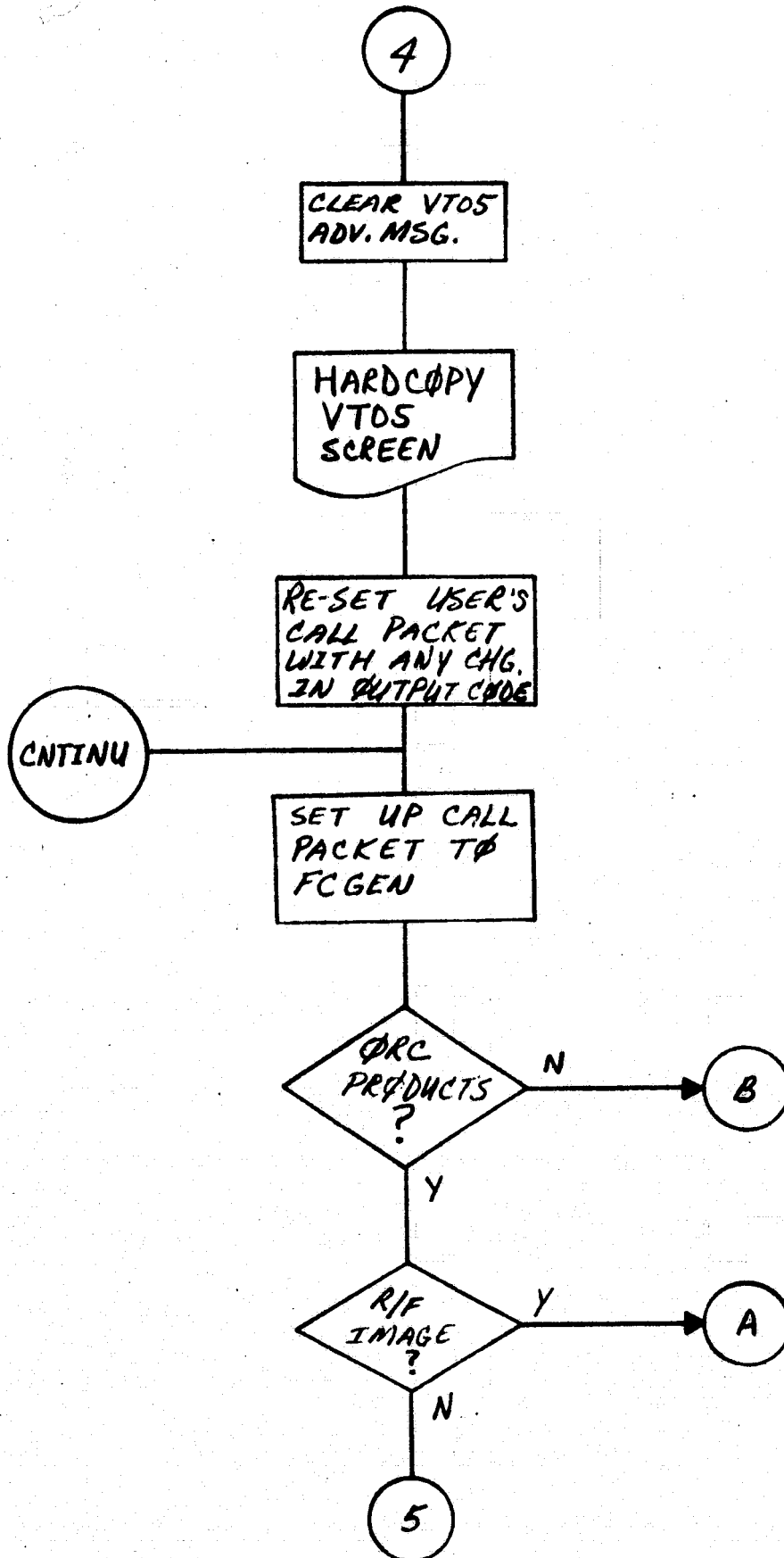
REPRODUCIBILITY OF THE
ORIGINAL PAGE IS POOR

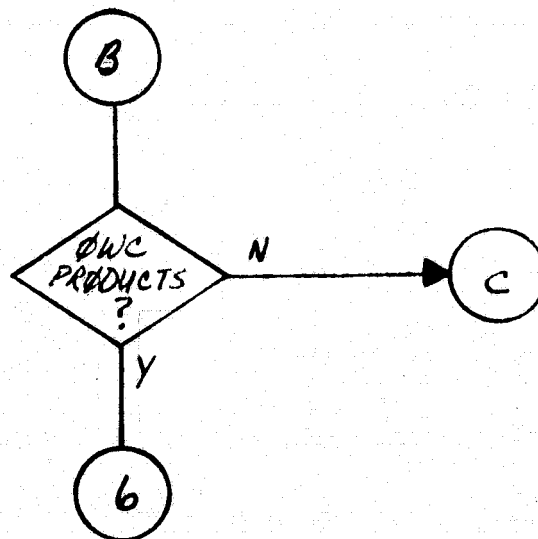
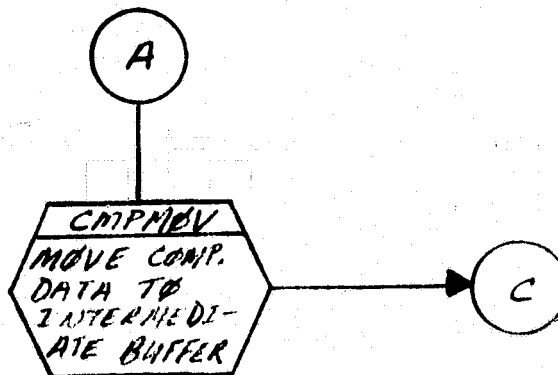
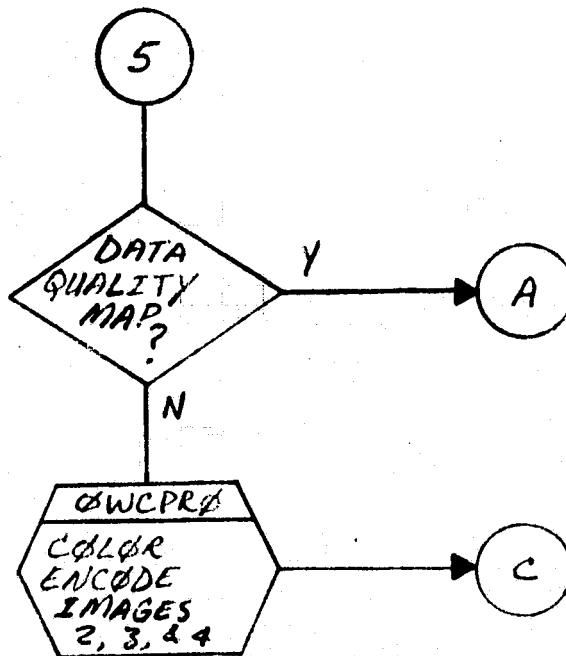


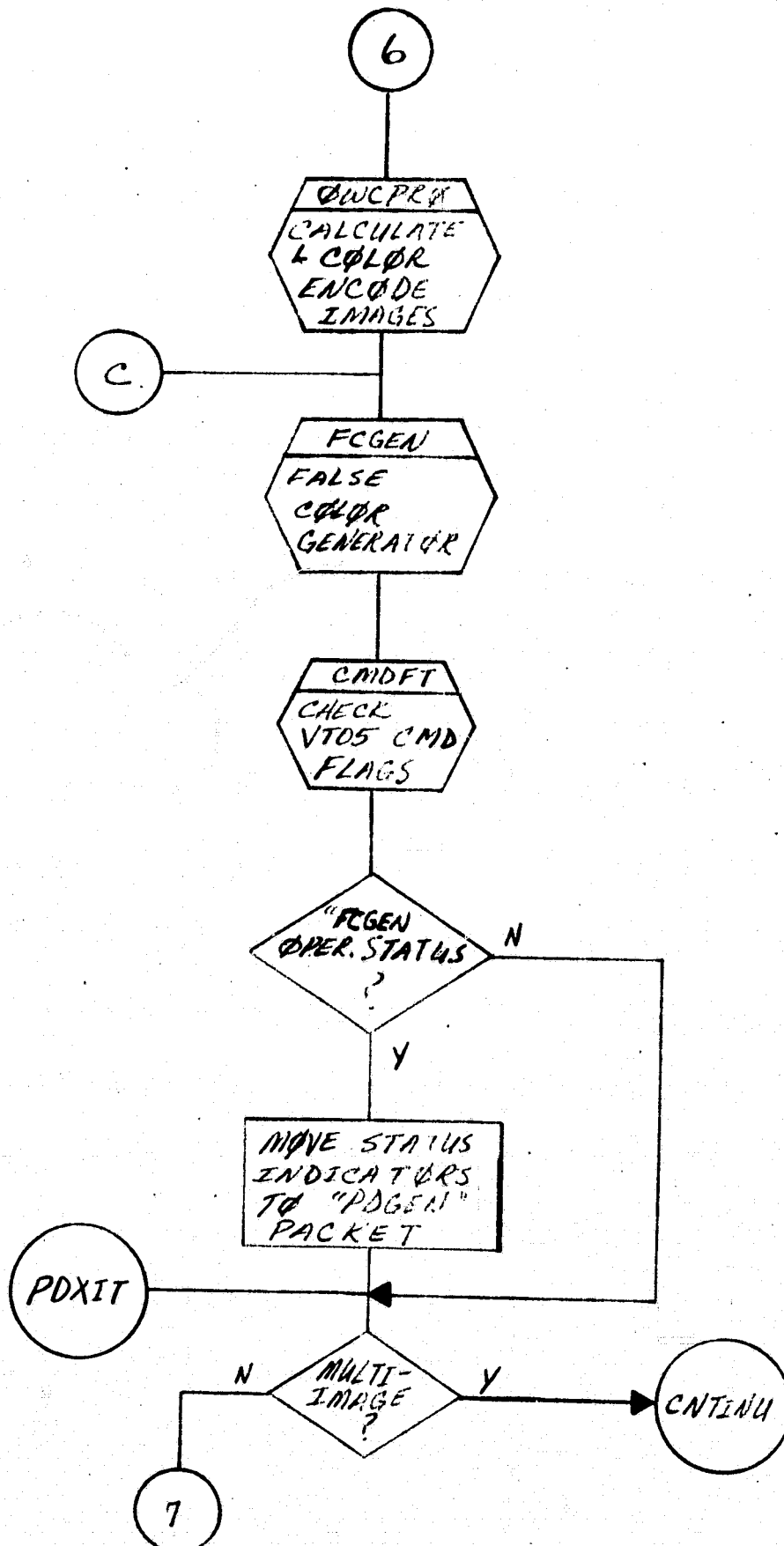


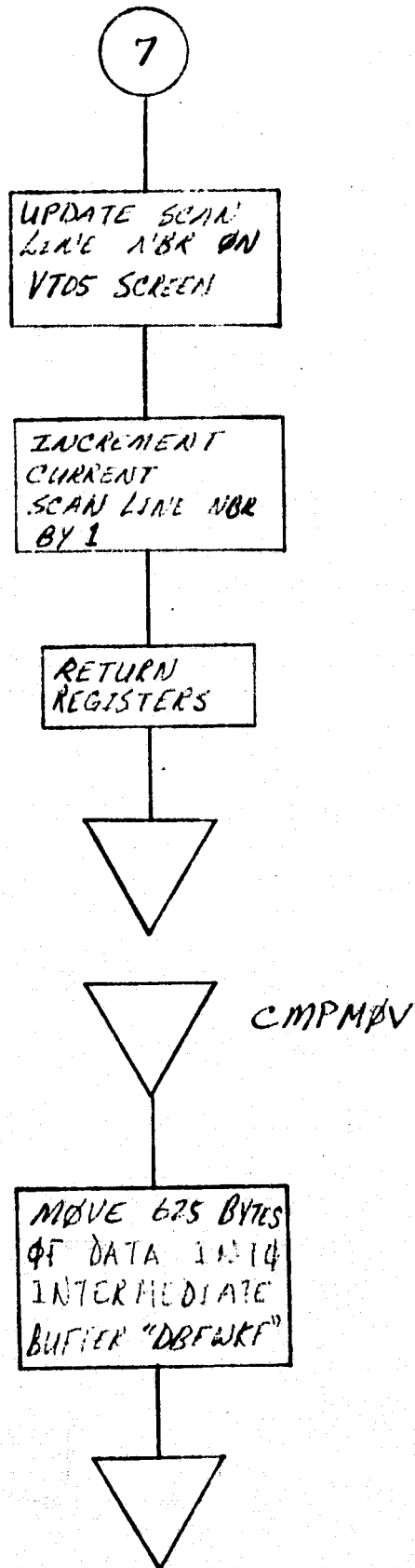


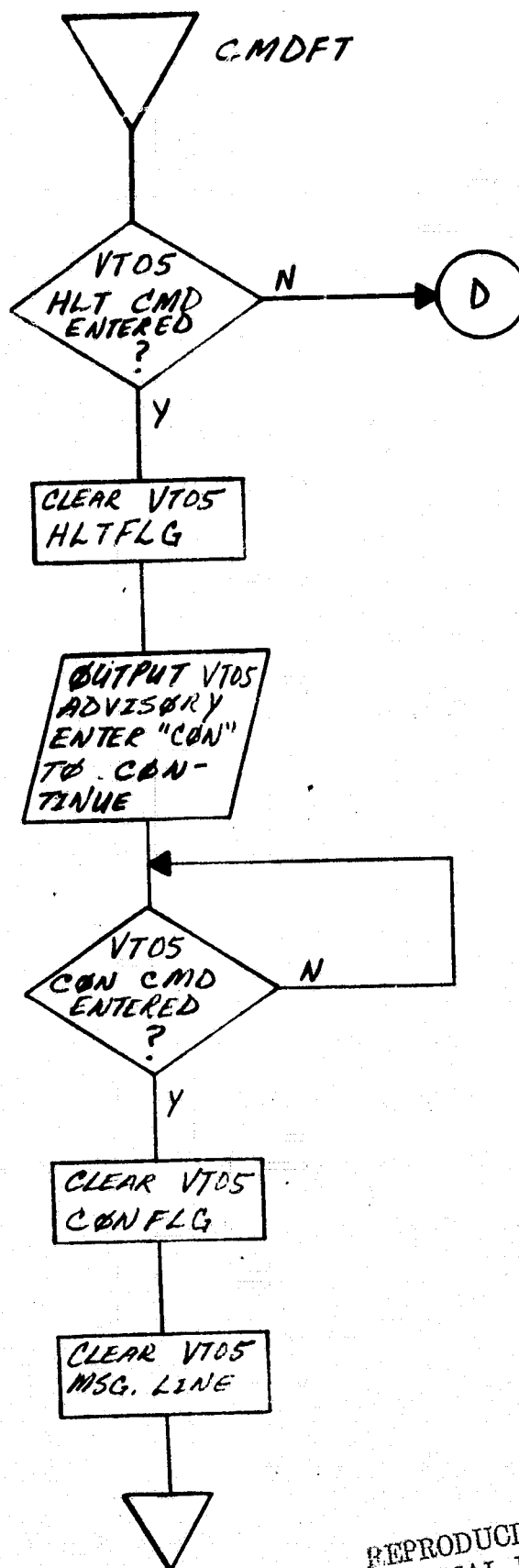




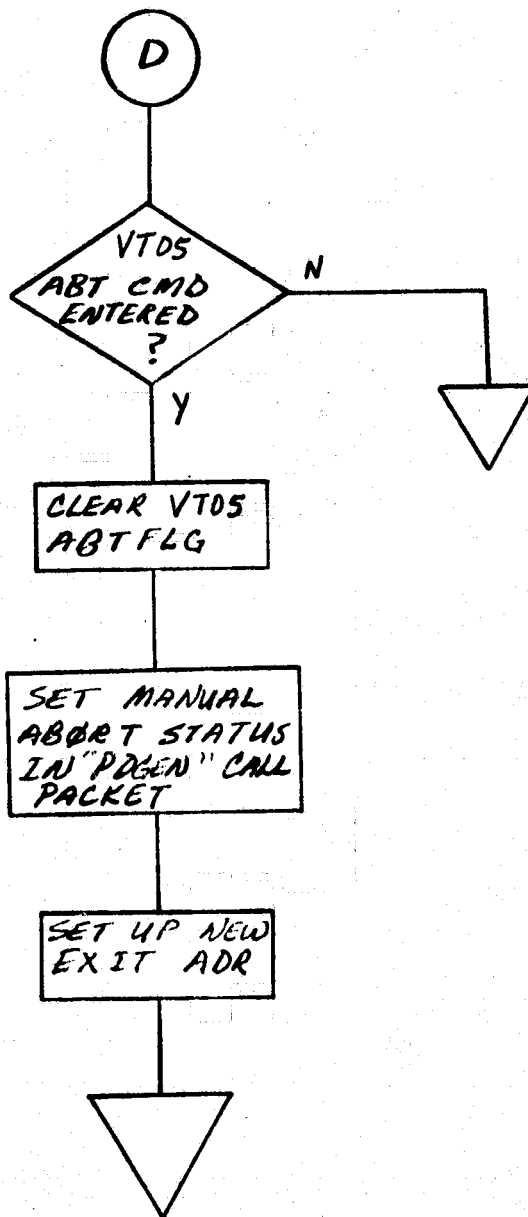


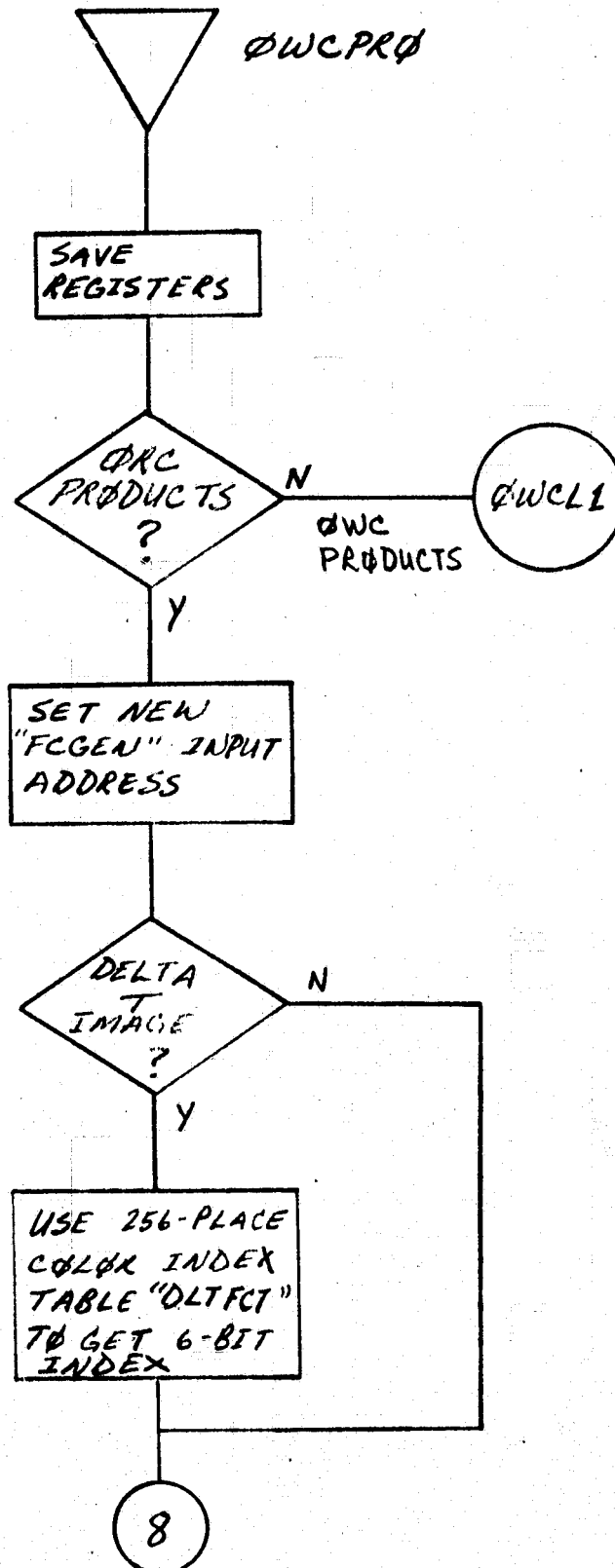


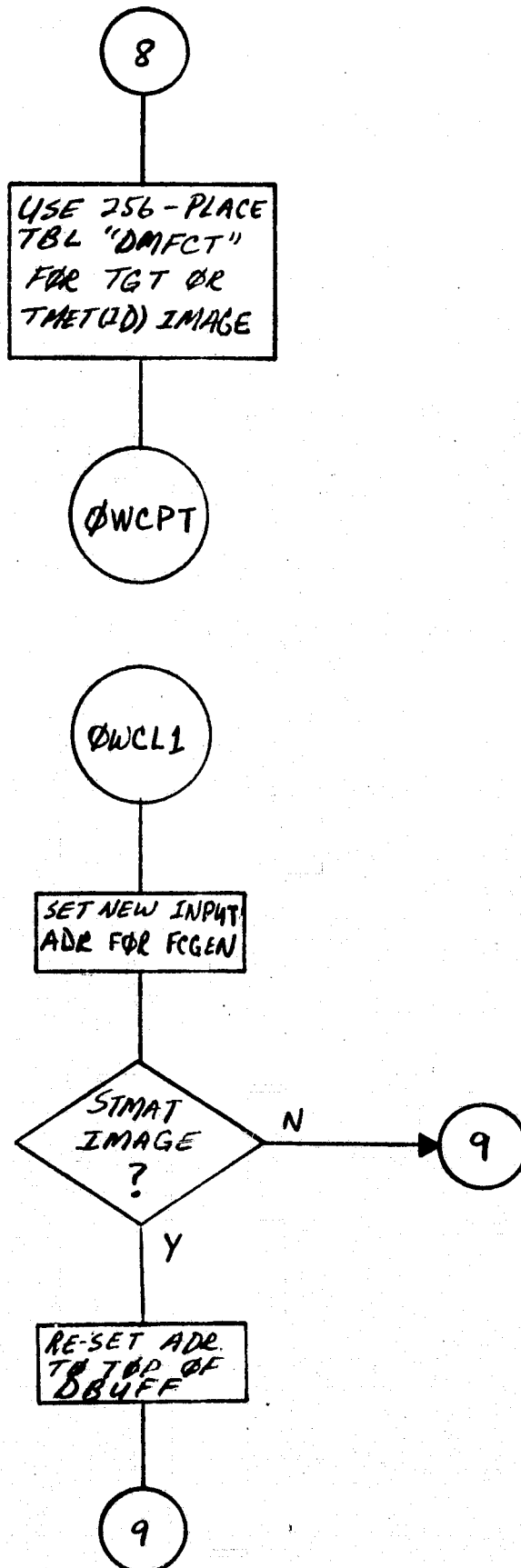


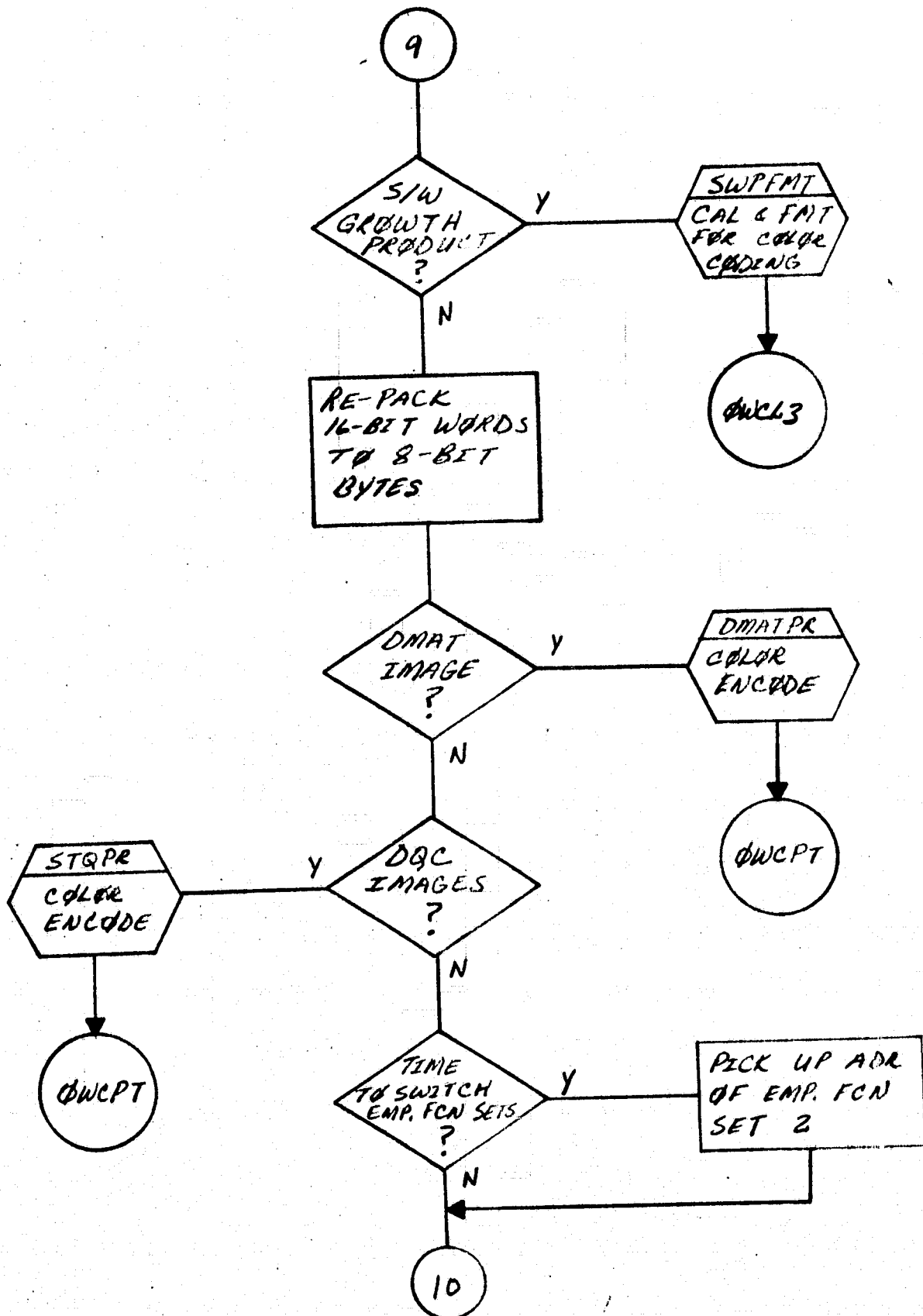


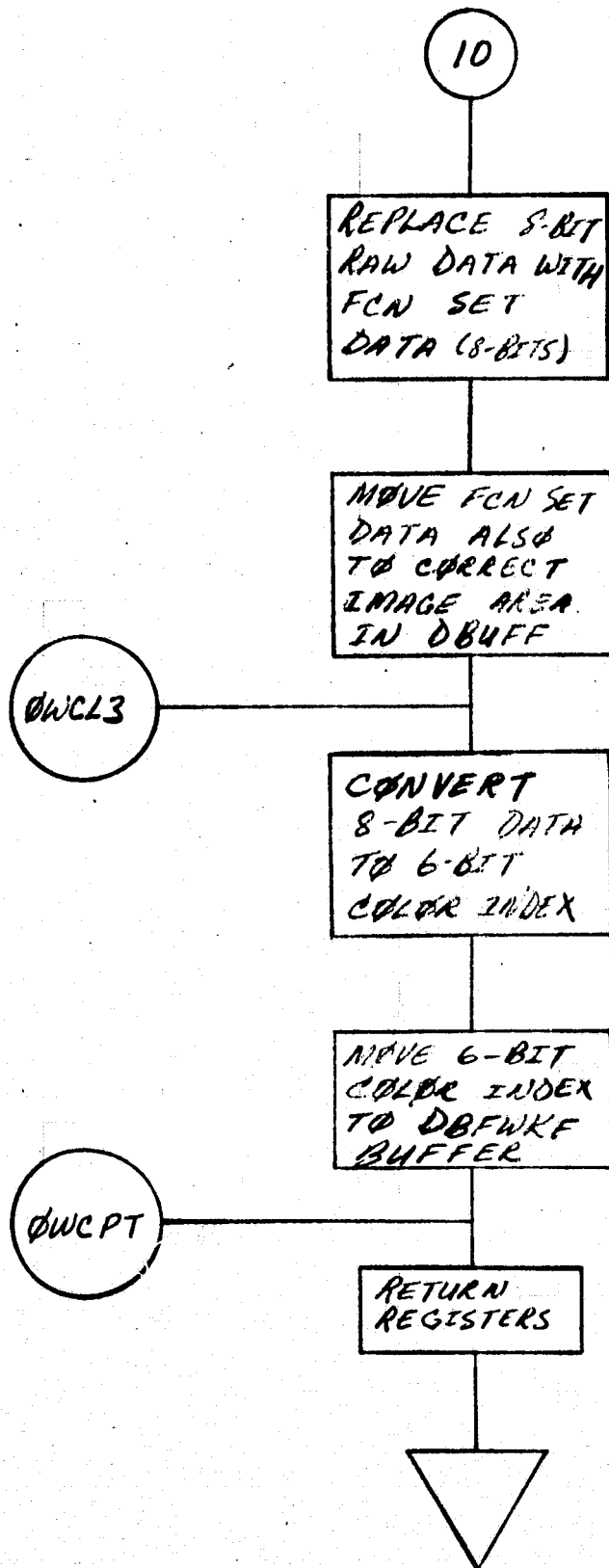
REPRODUCIBILITY OF THE
ORIGINAL PAGE IS POOR

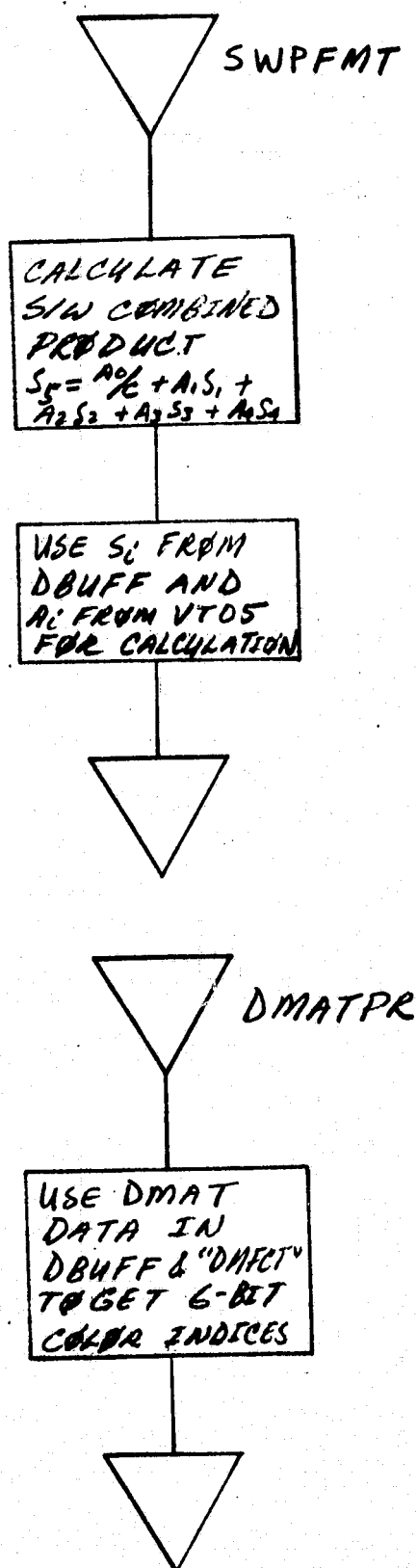




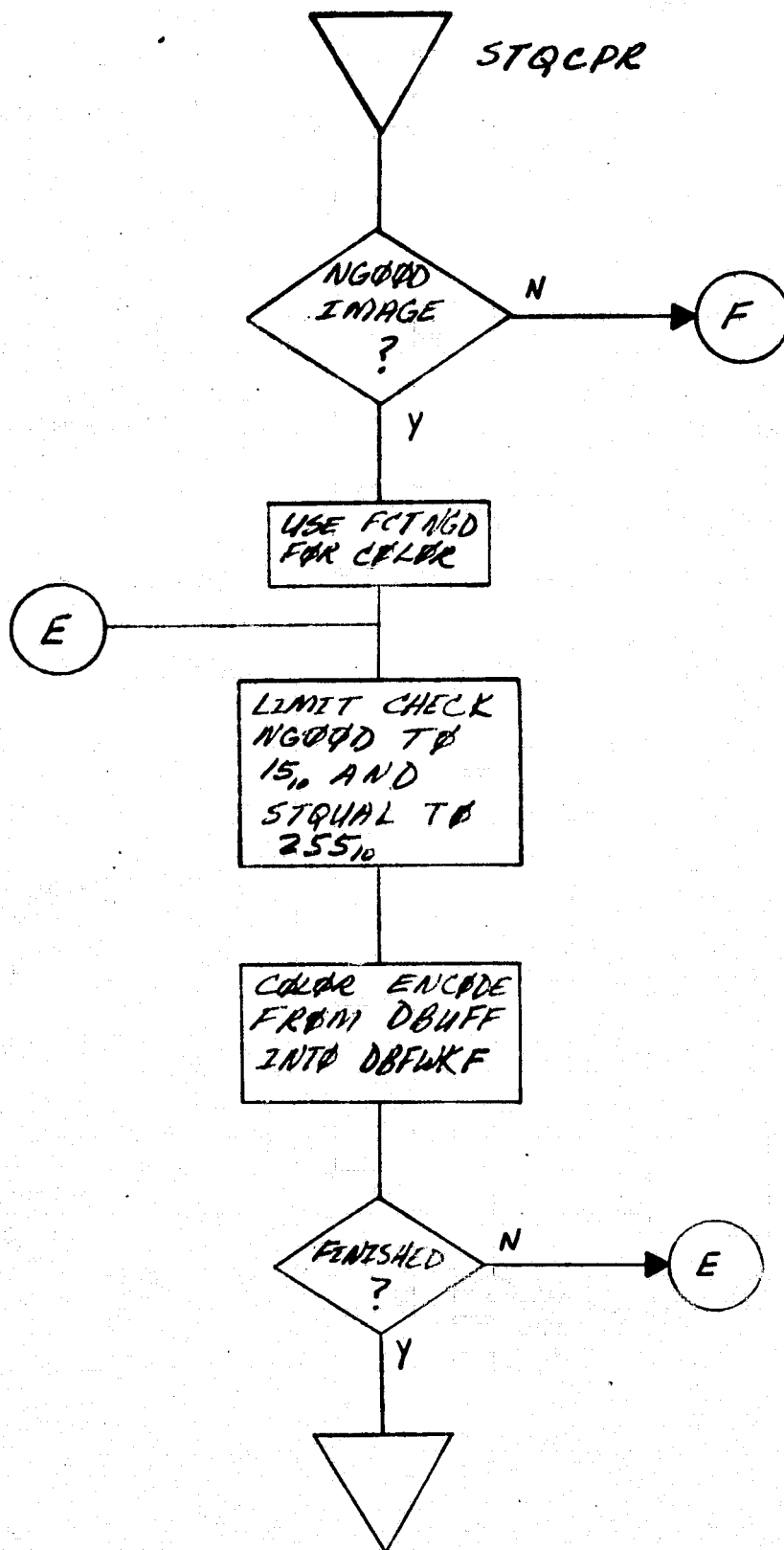


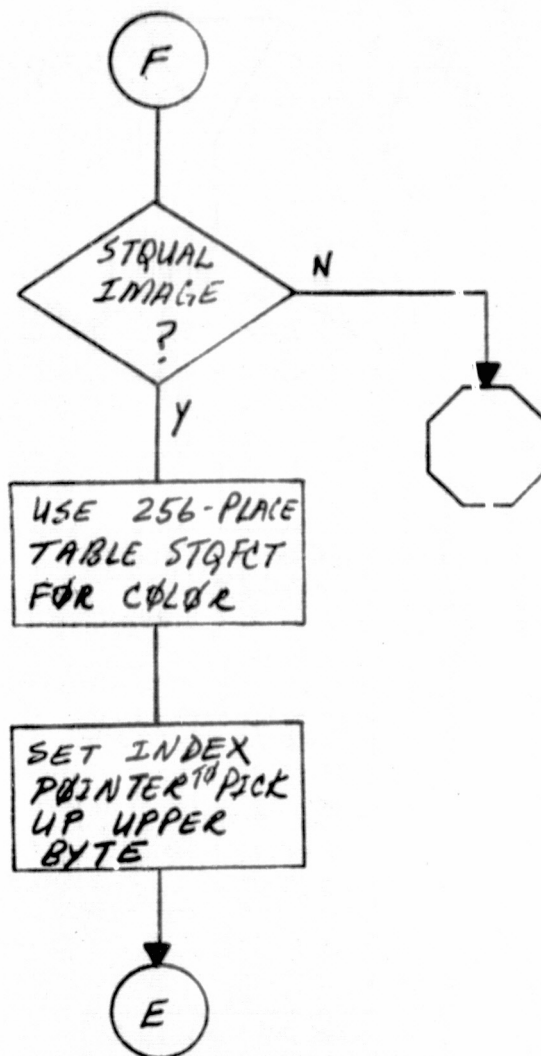


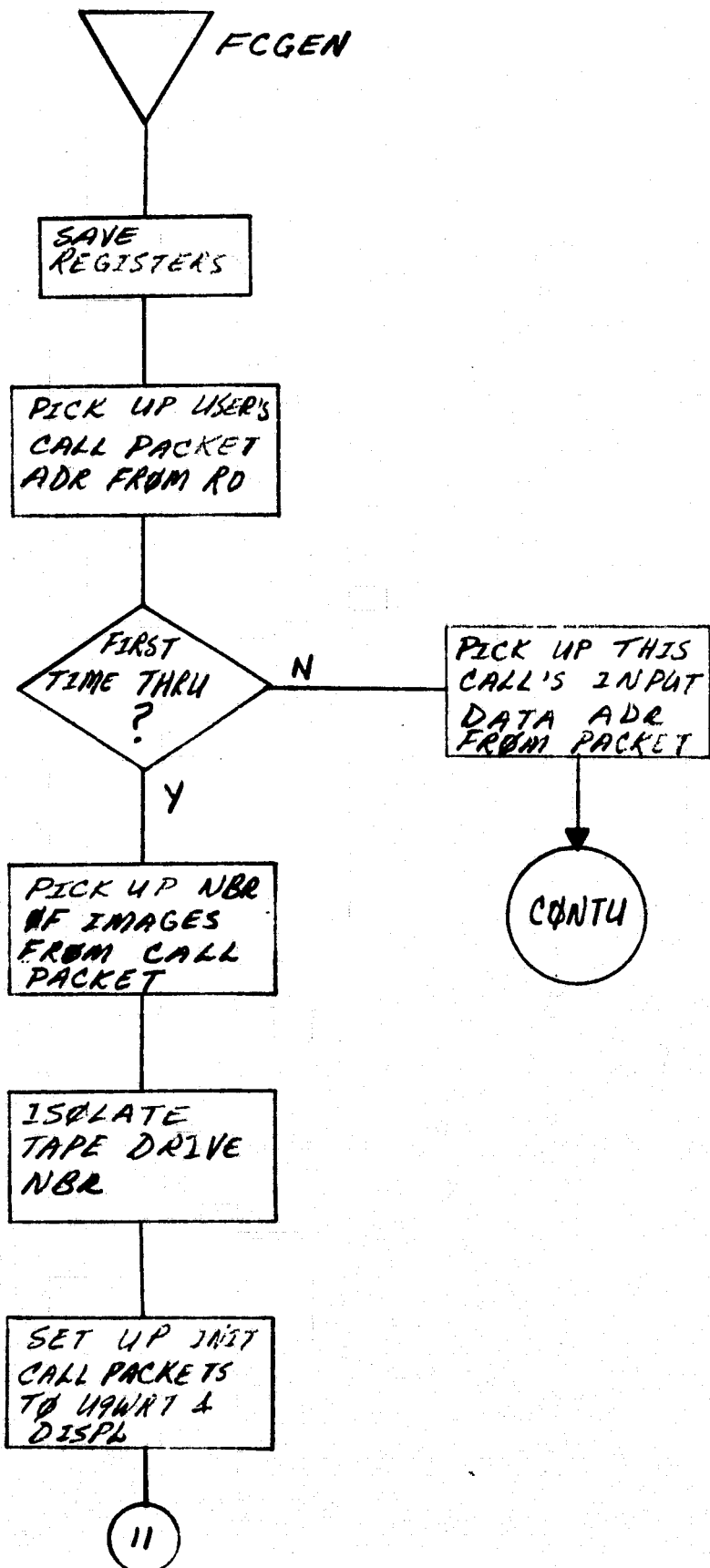


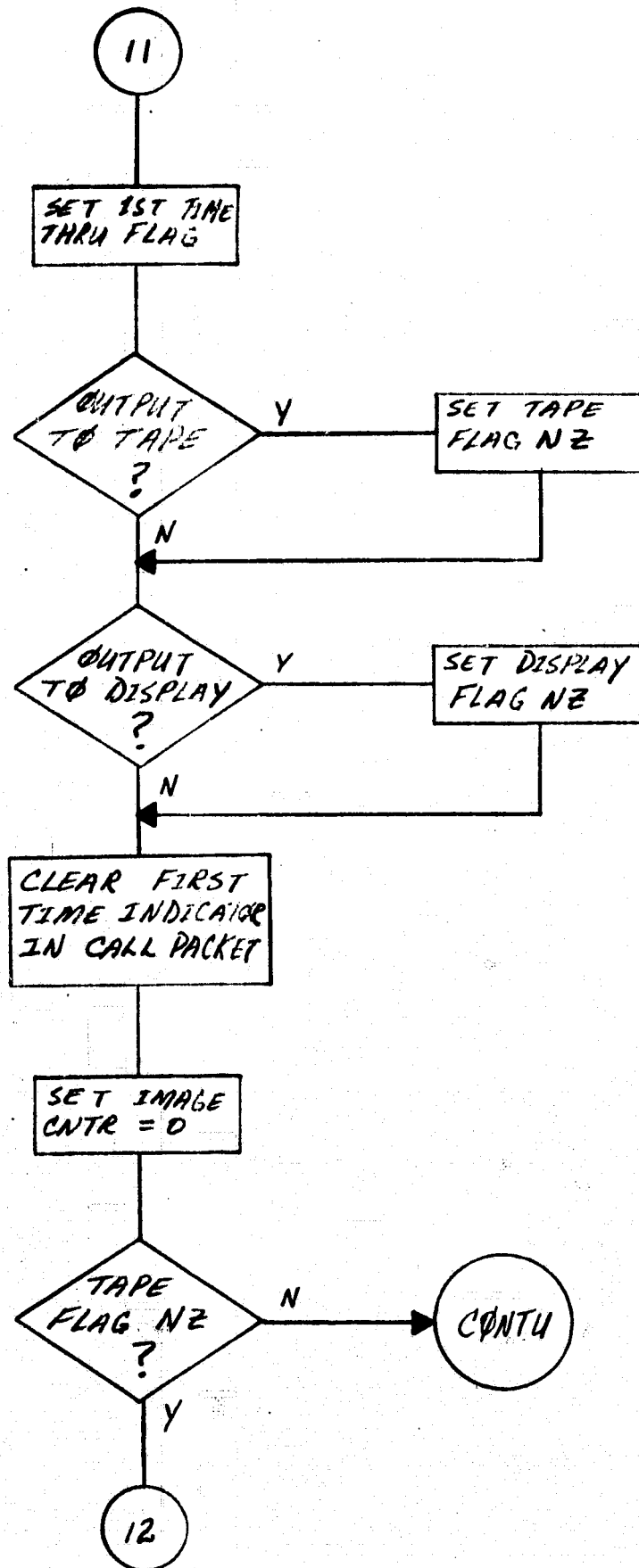


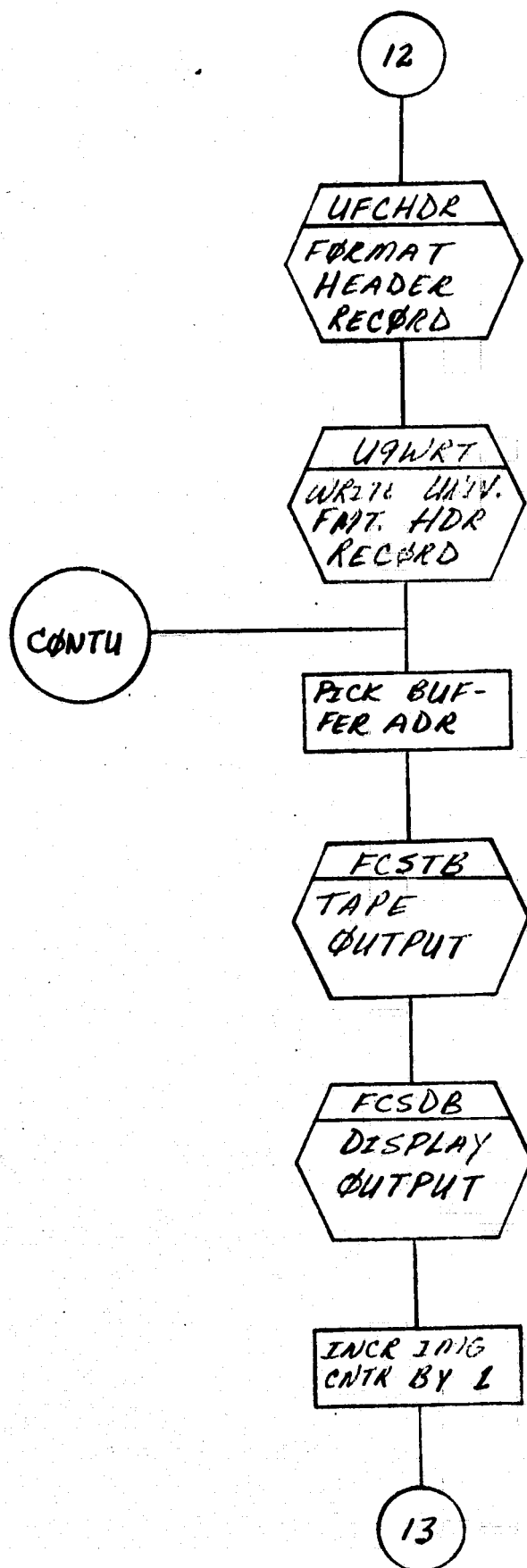
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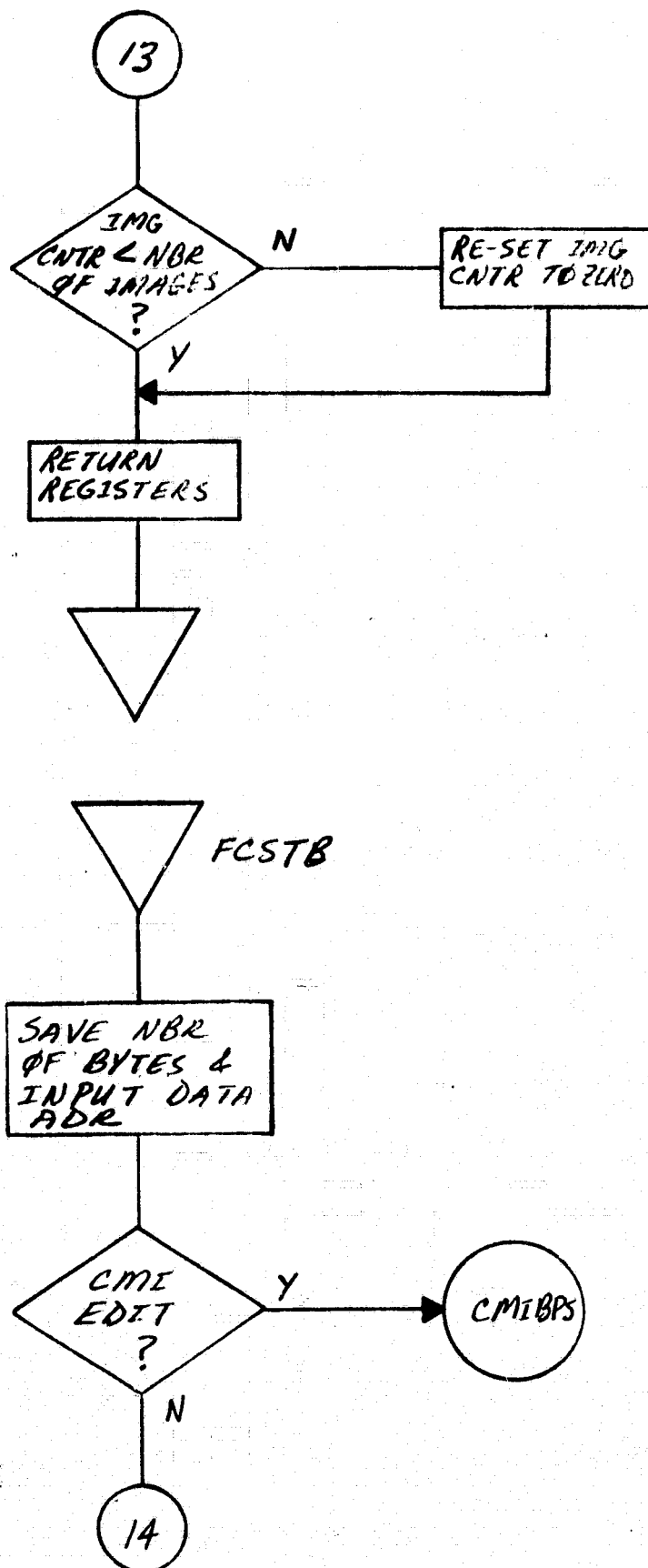


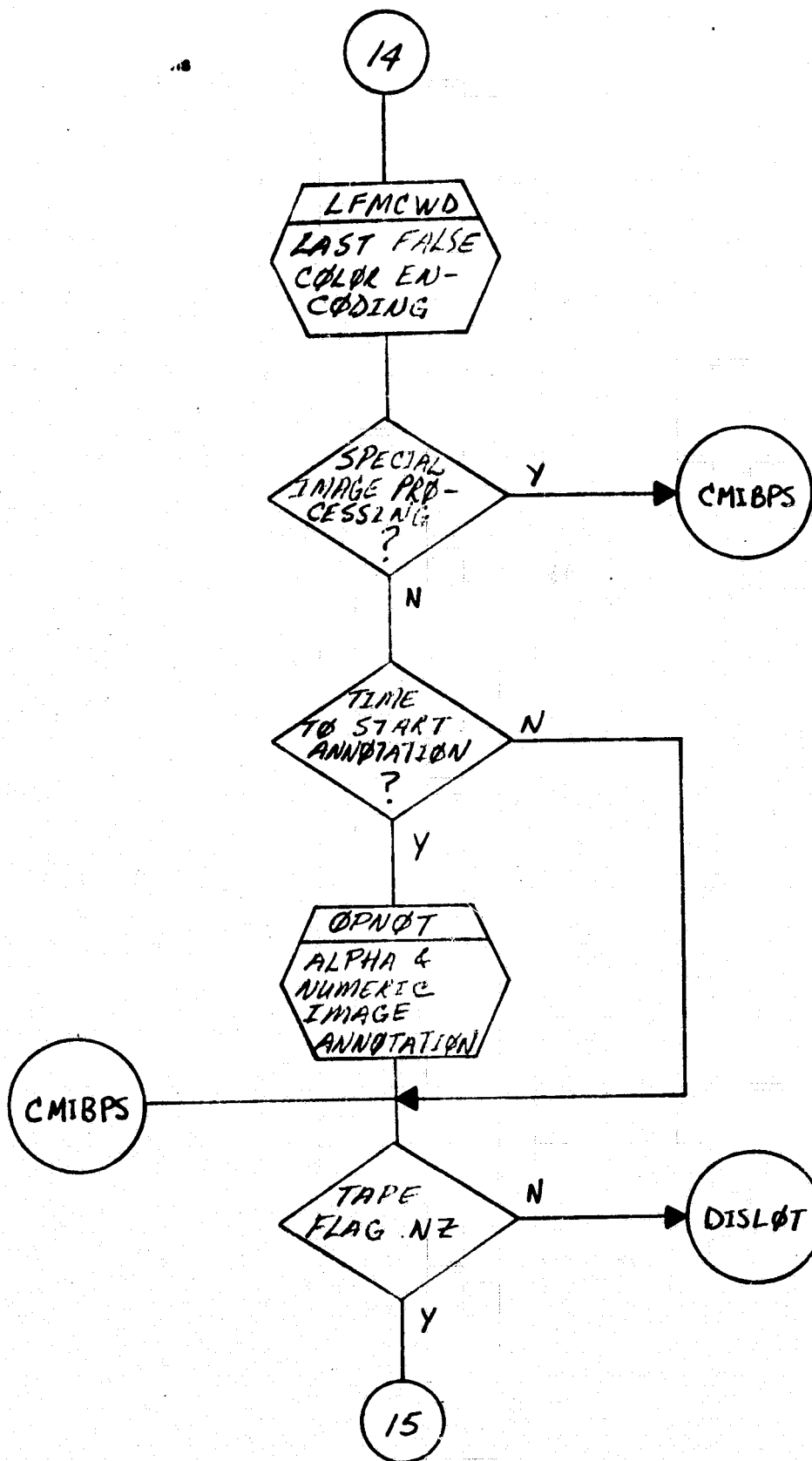


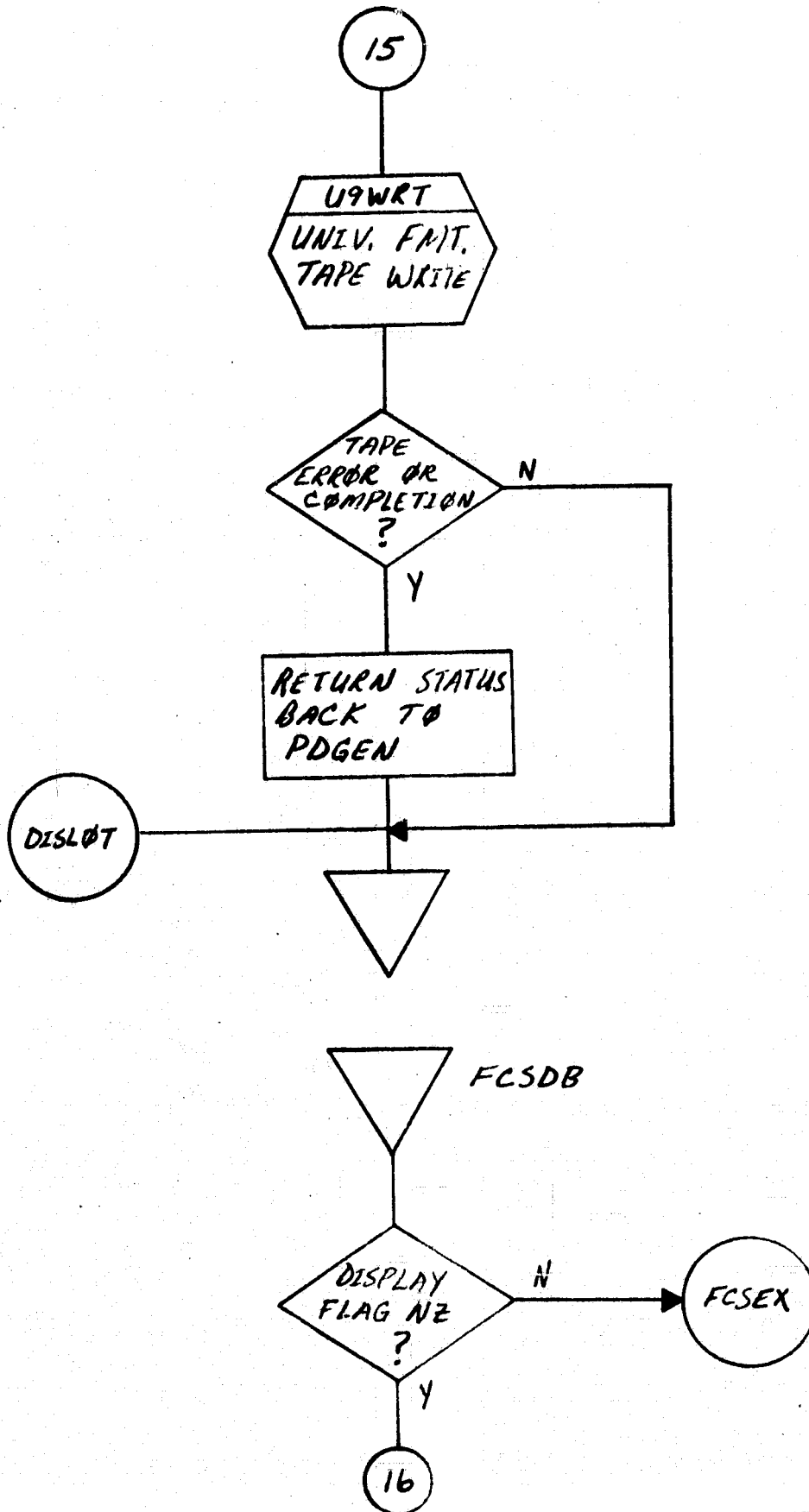




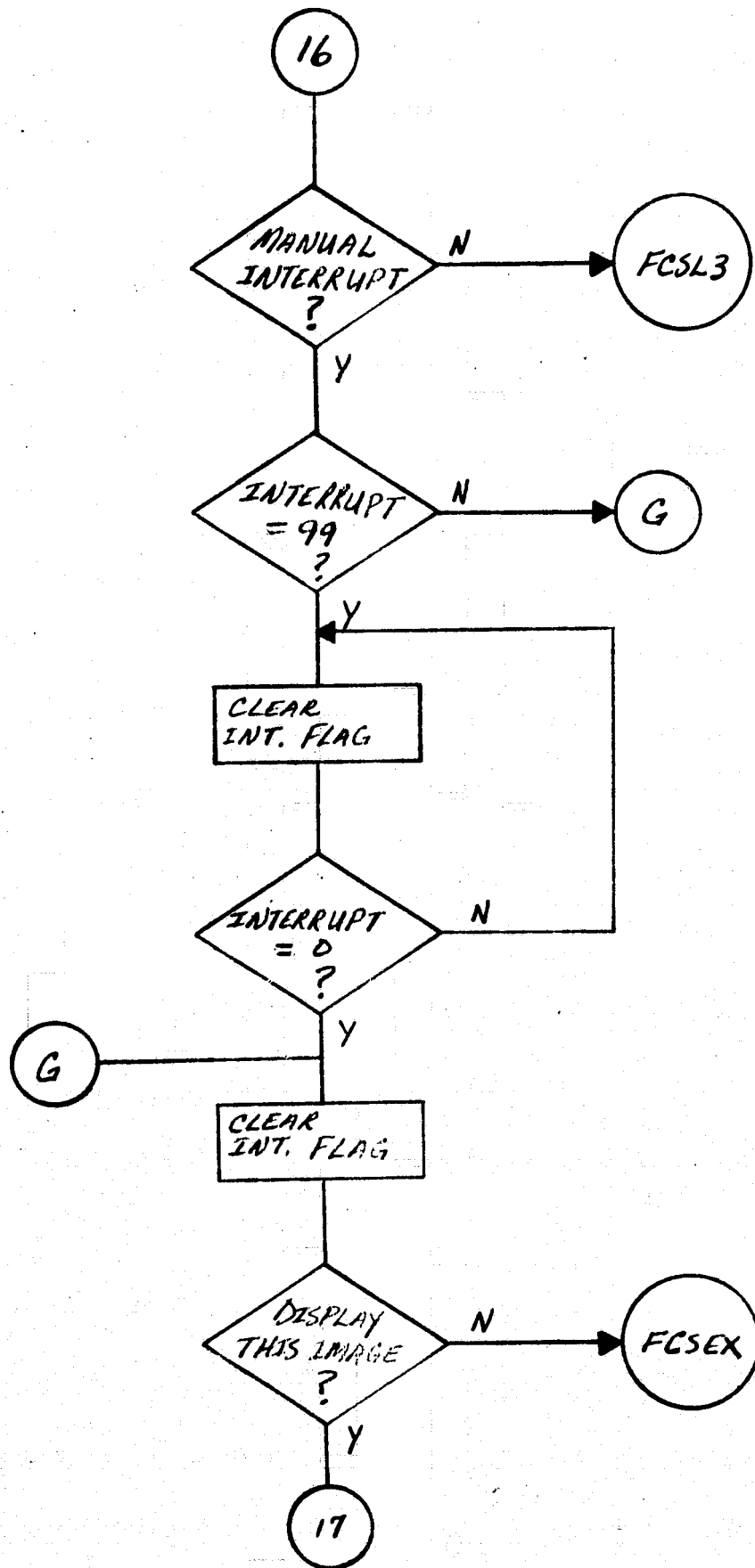


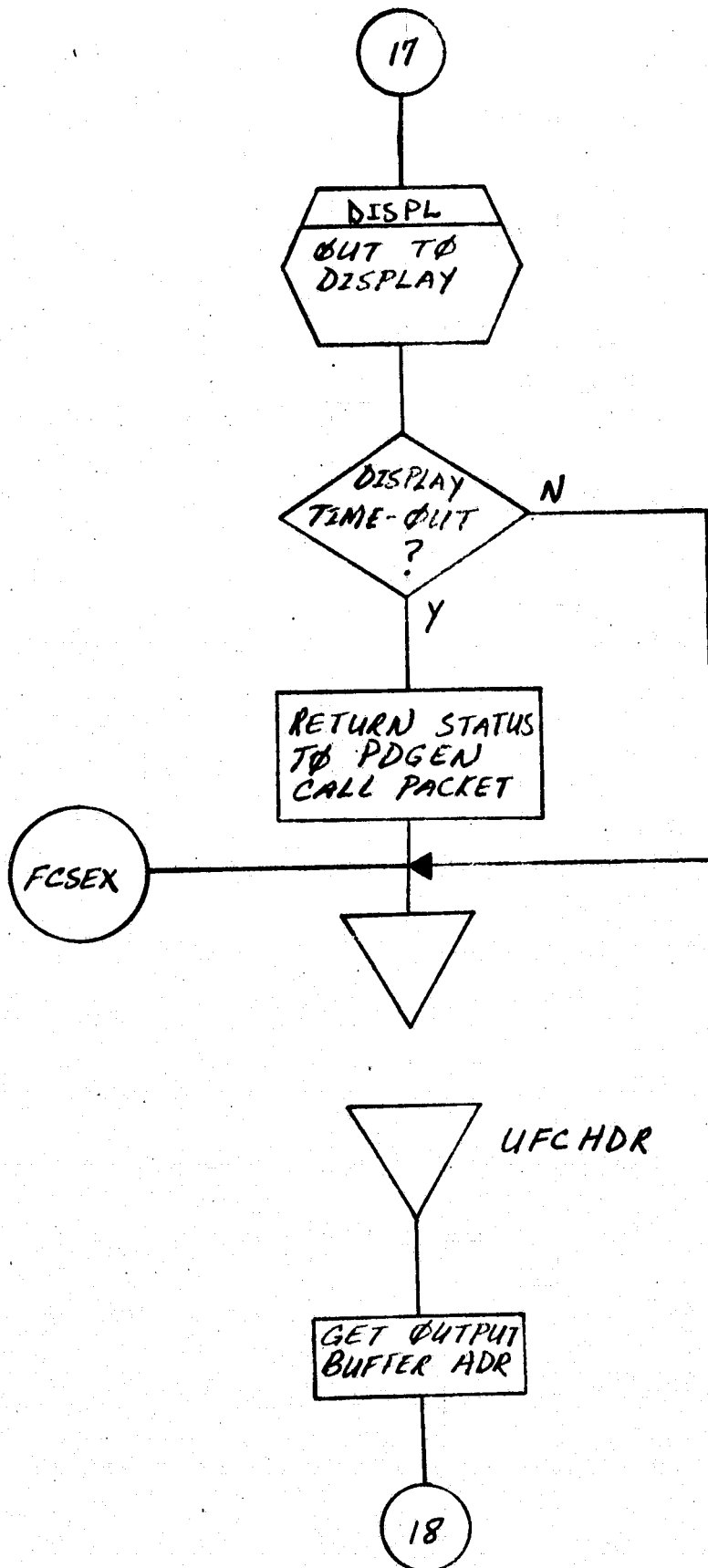


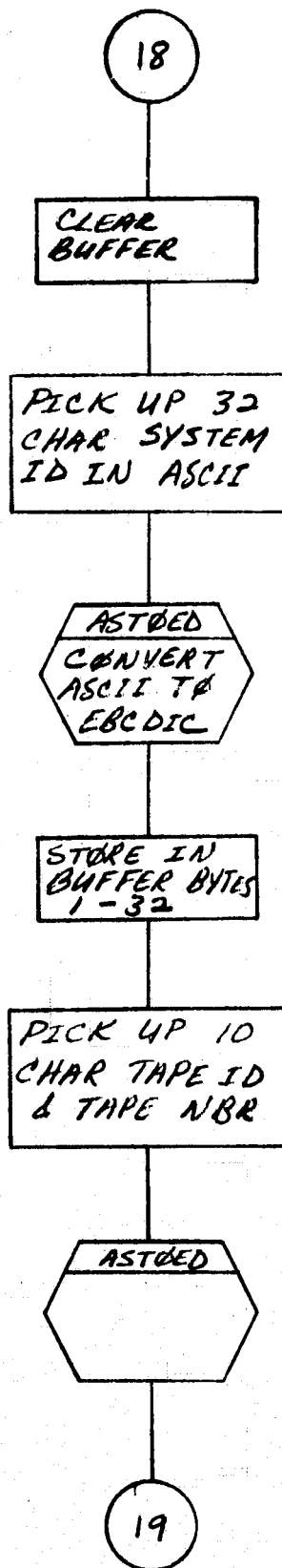


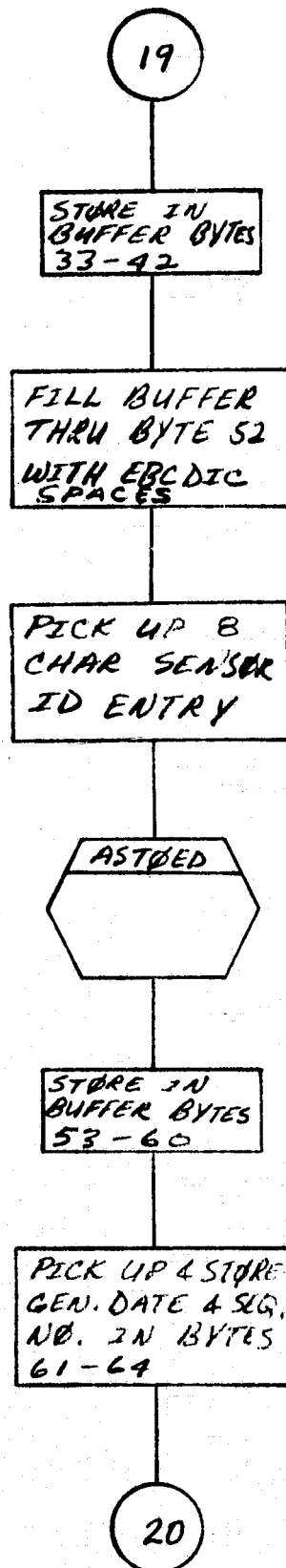


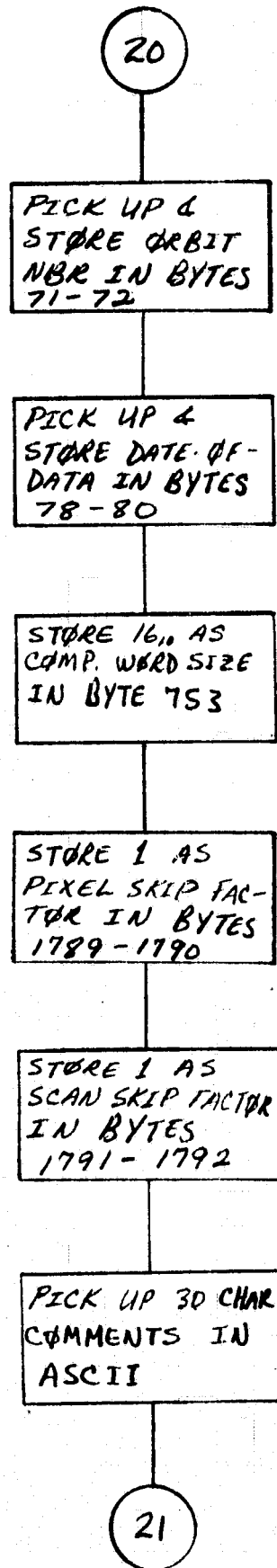
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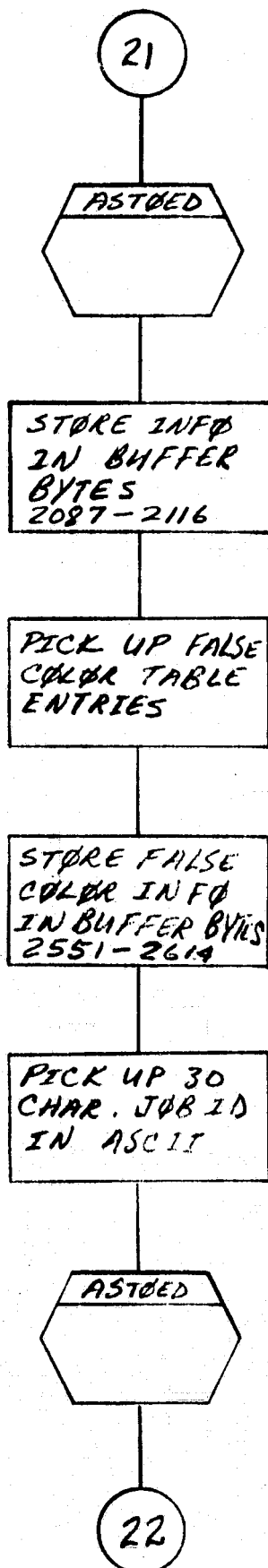


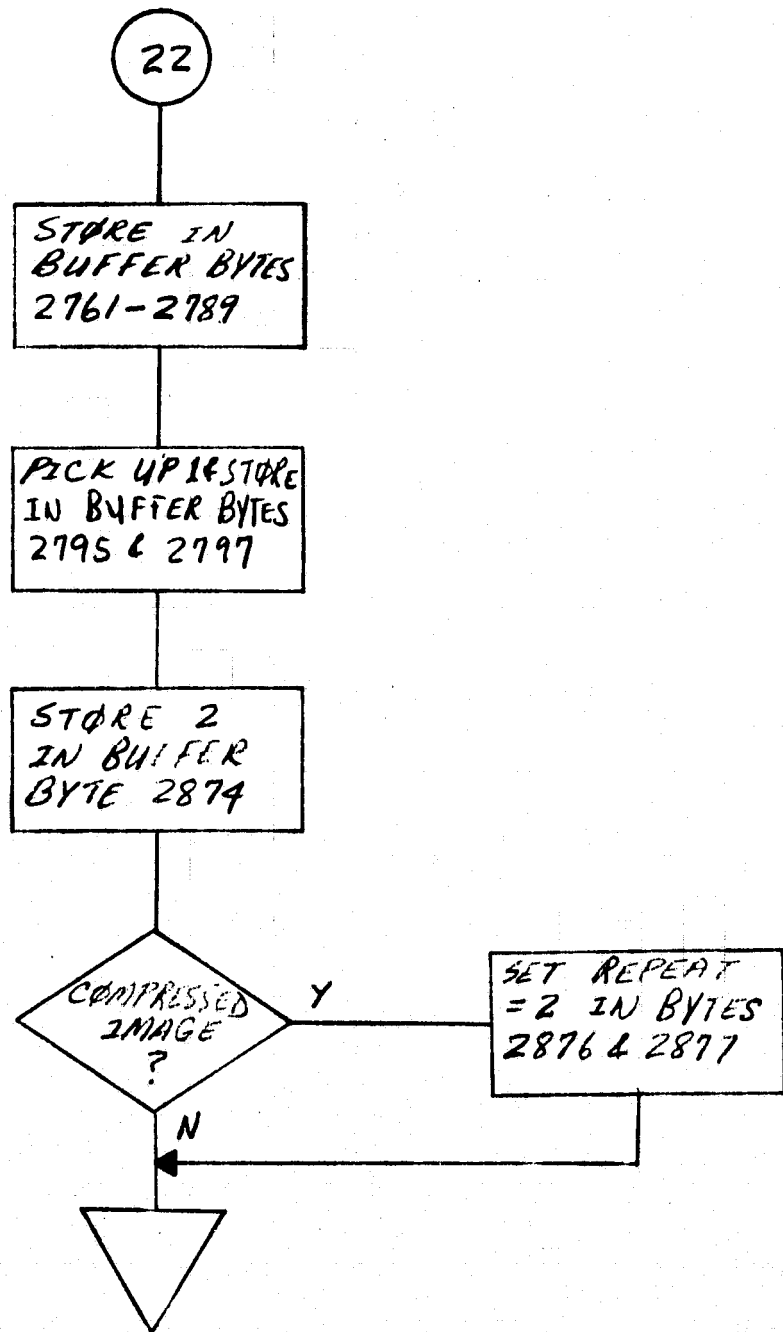


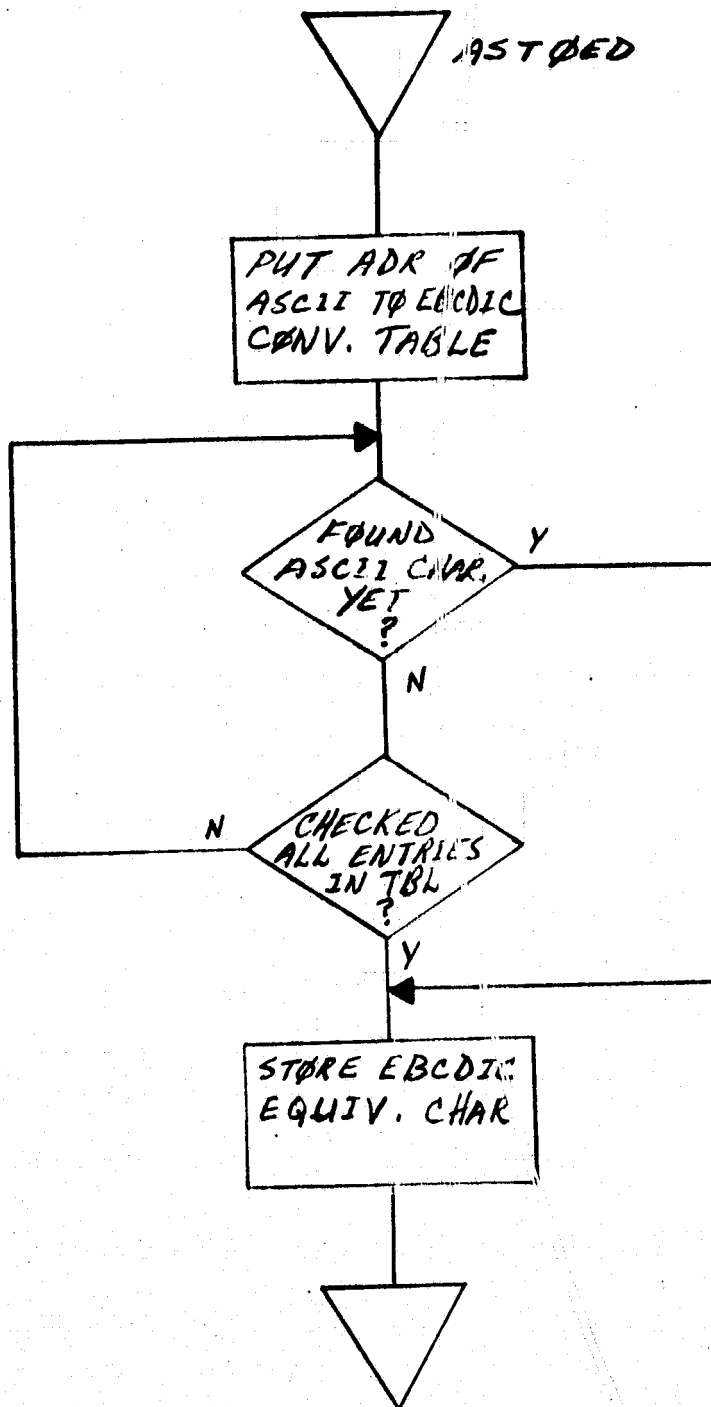


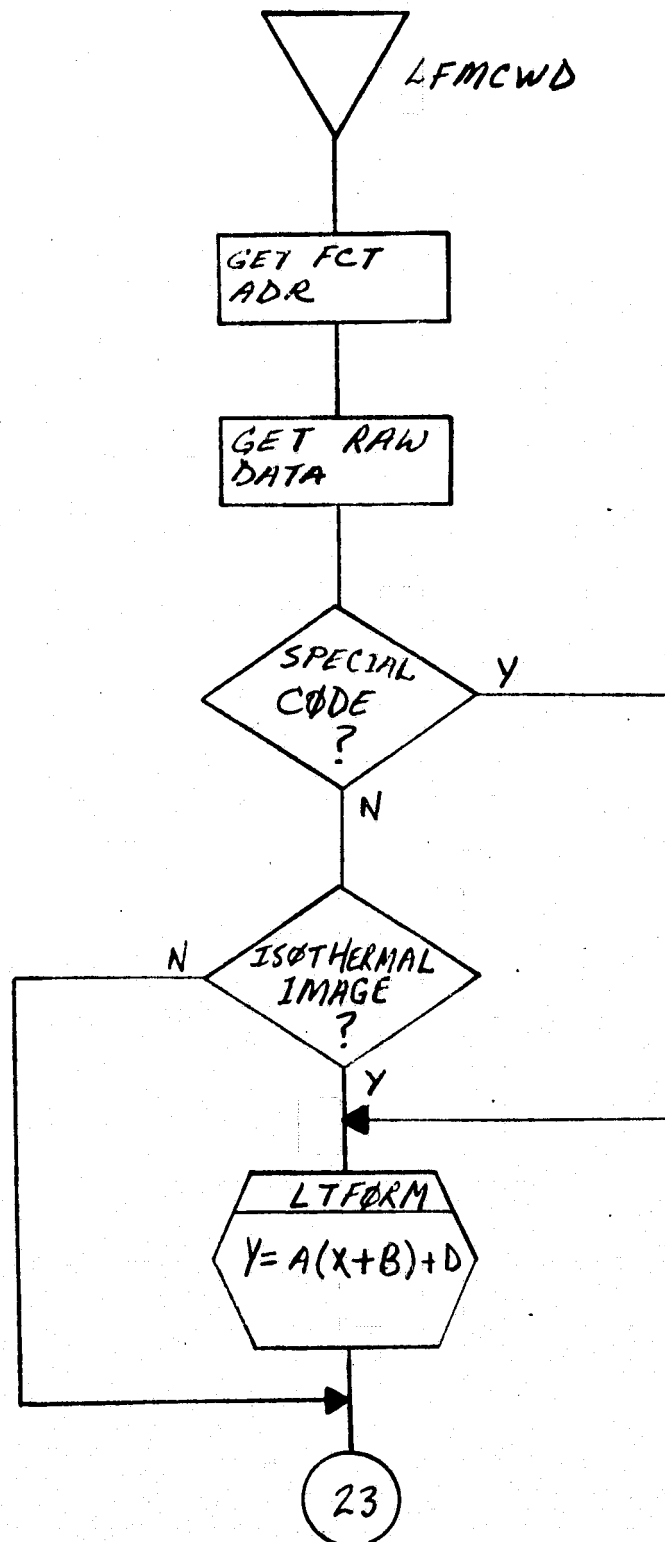


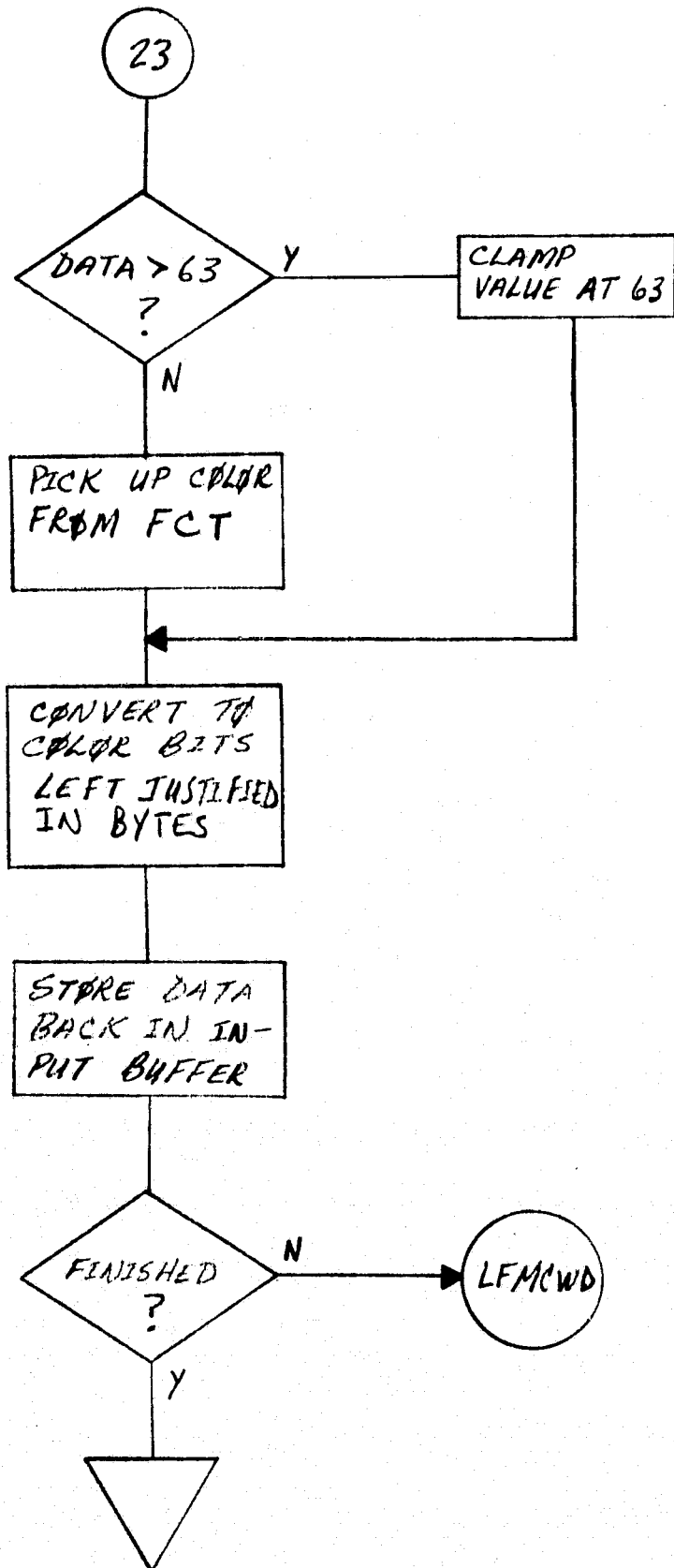




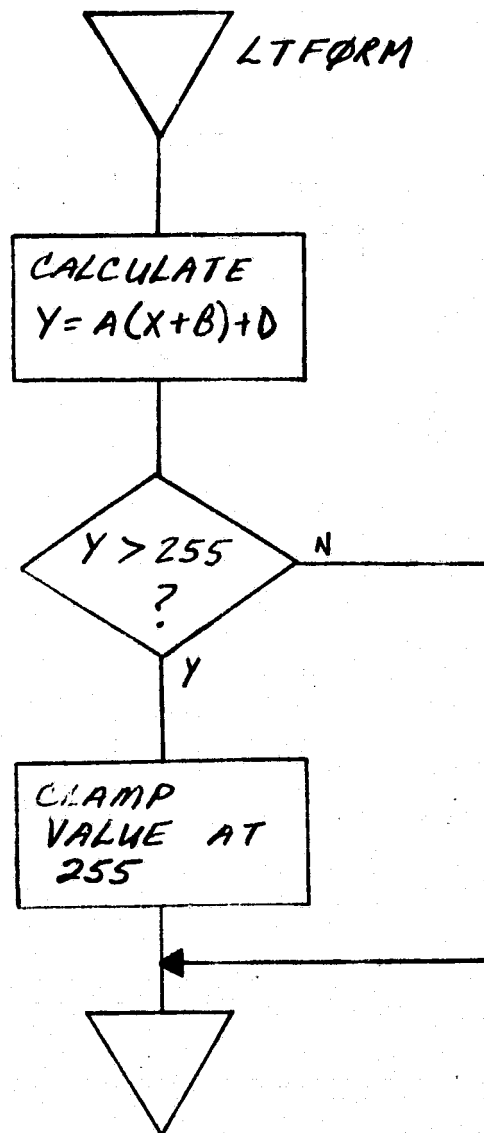


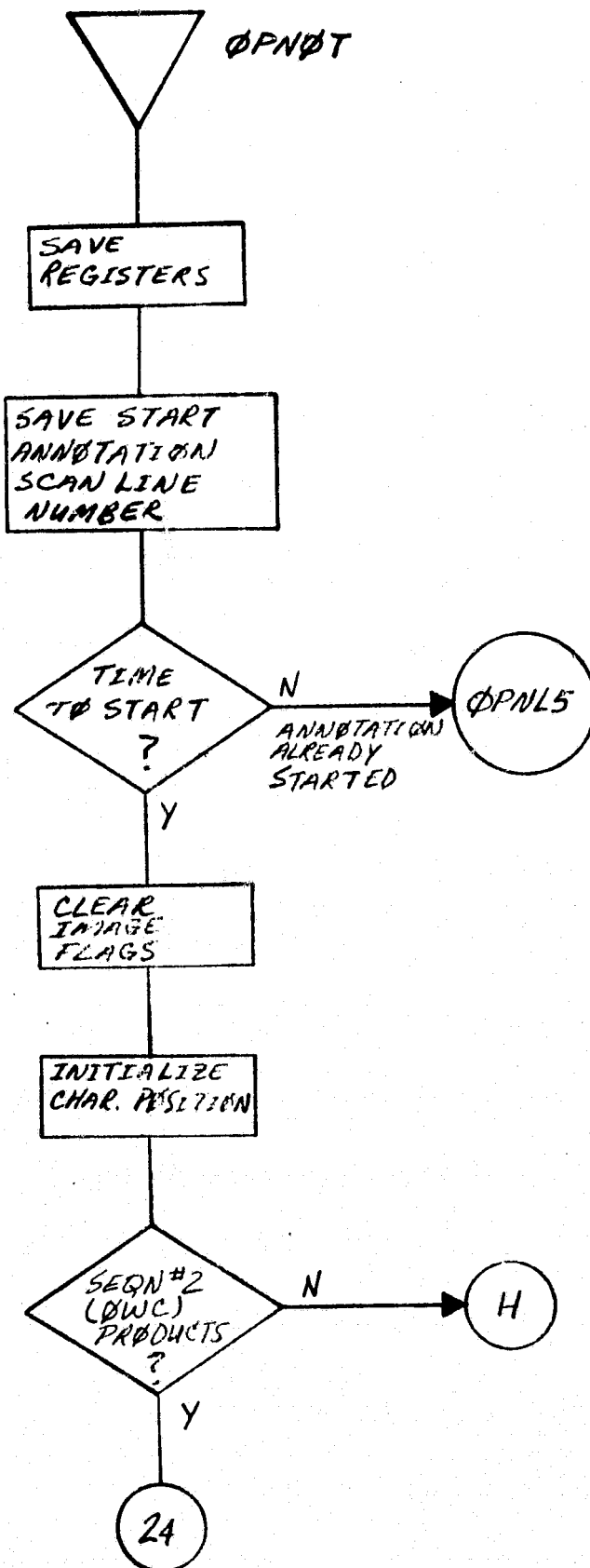


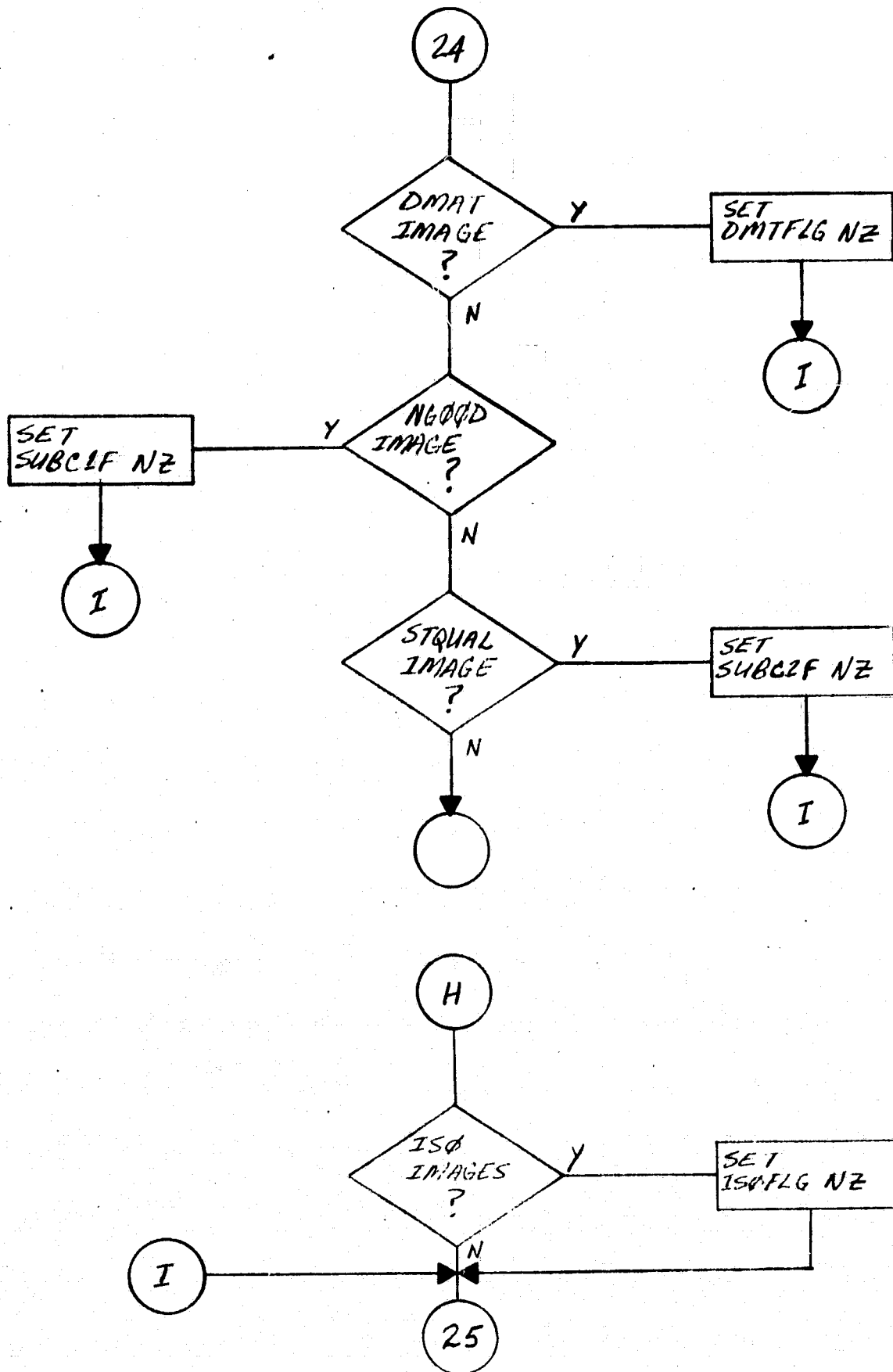


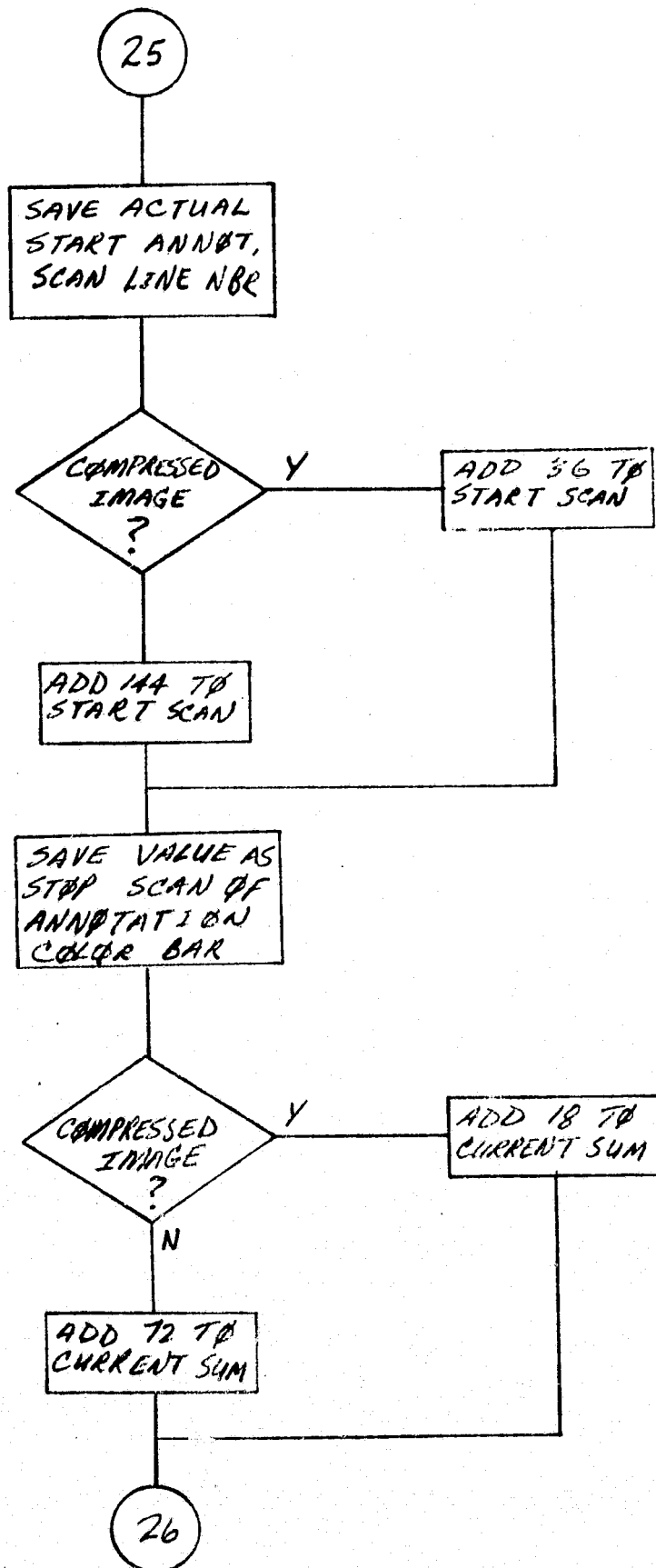


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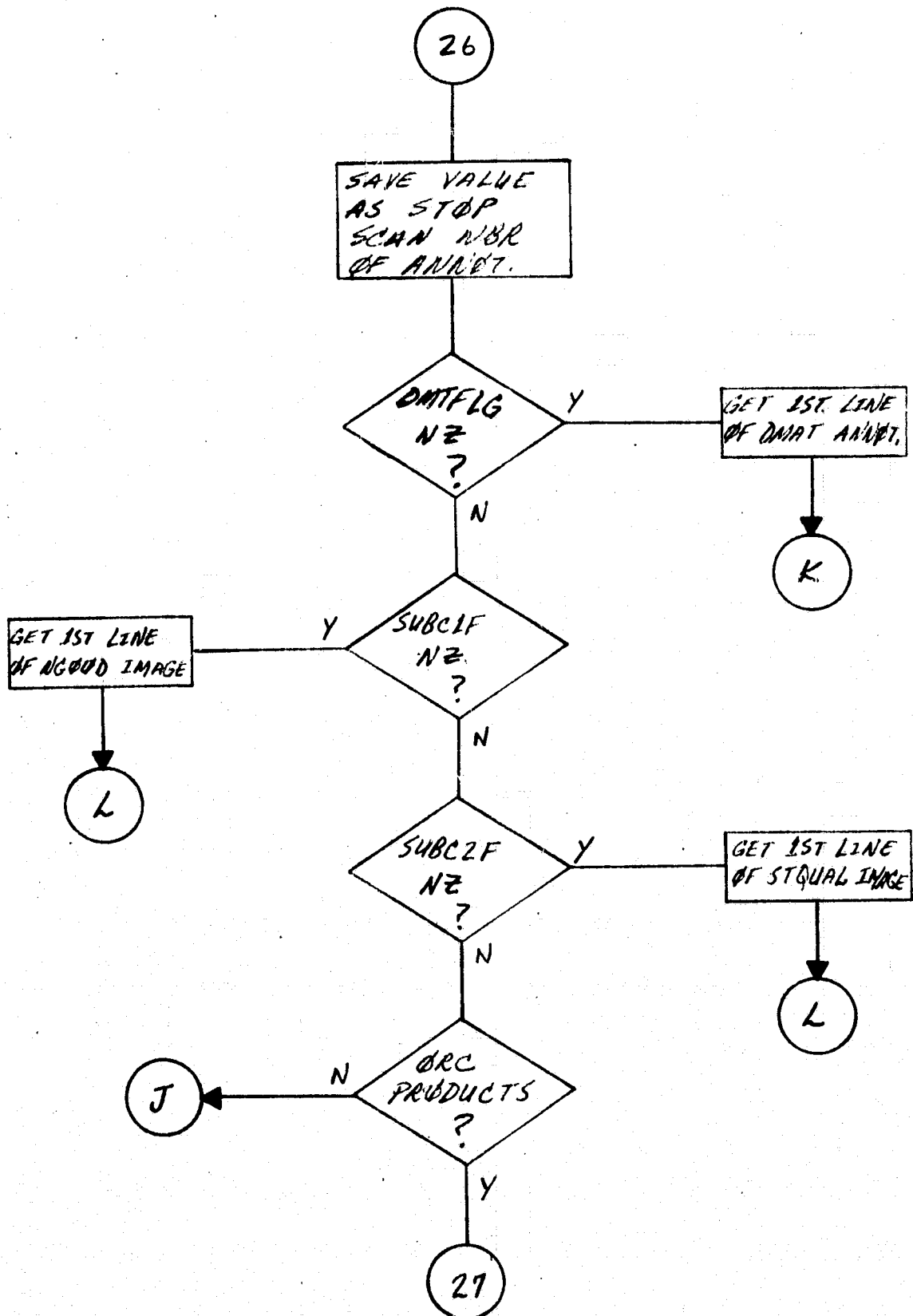


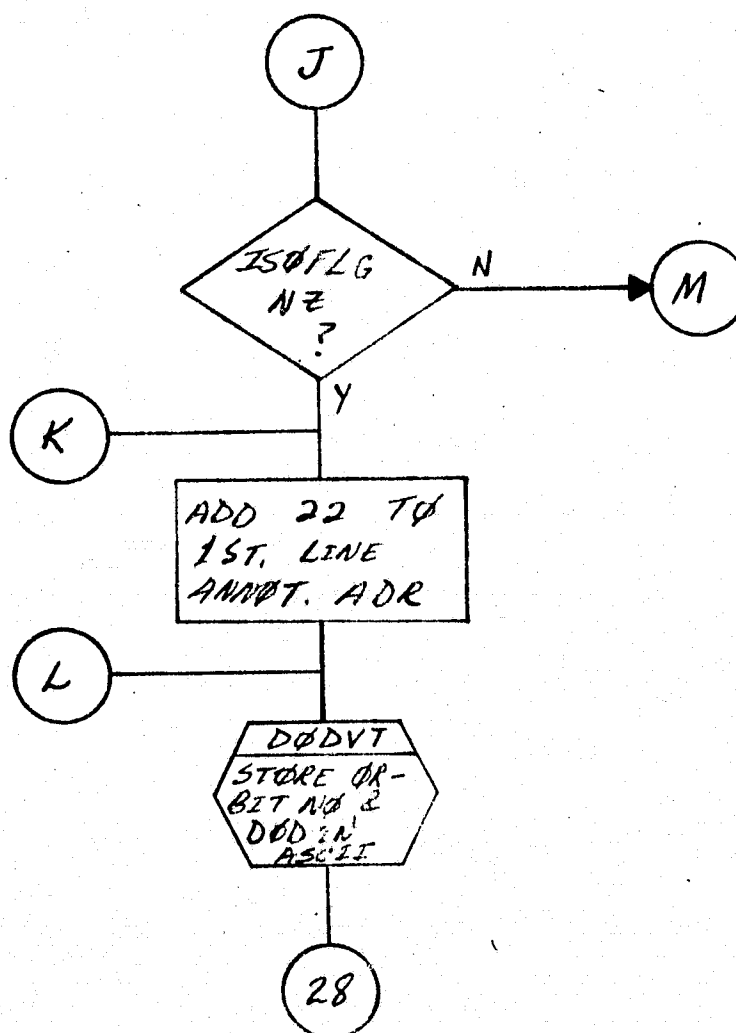
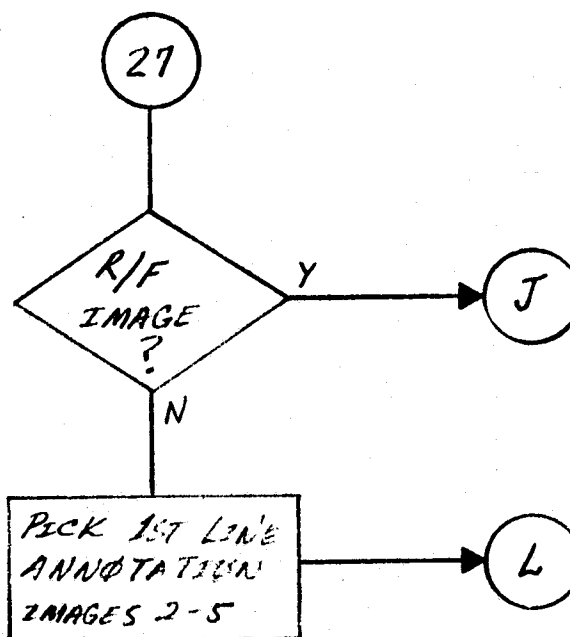


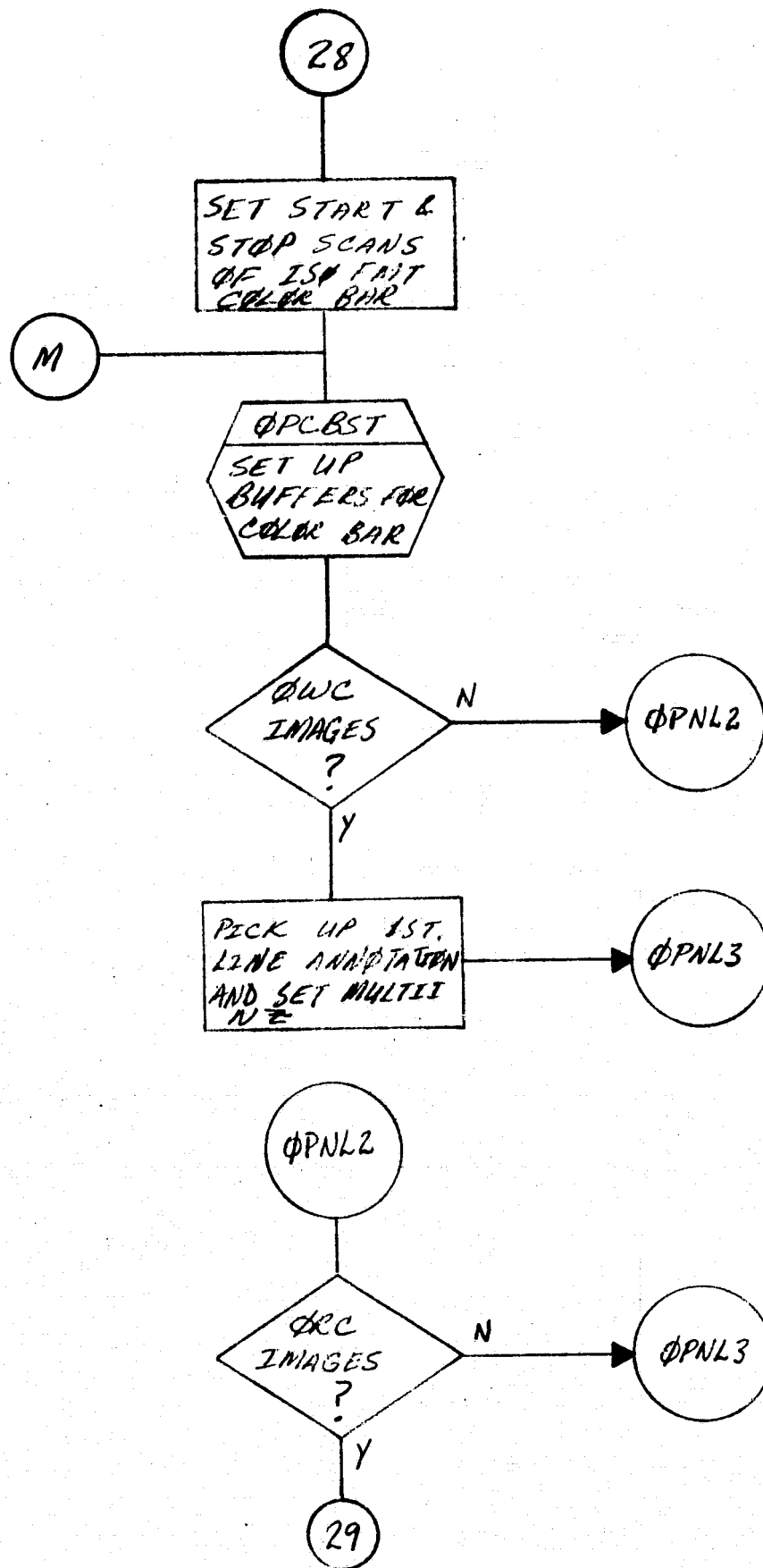


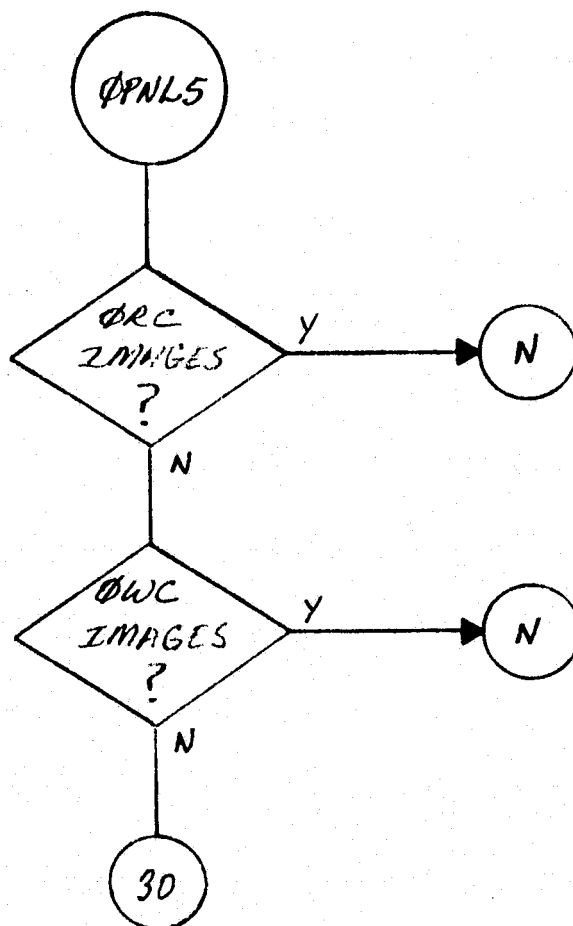
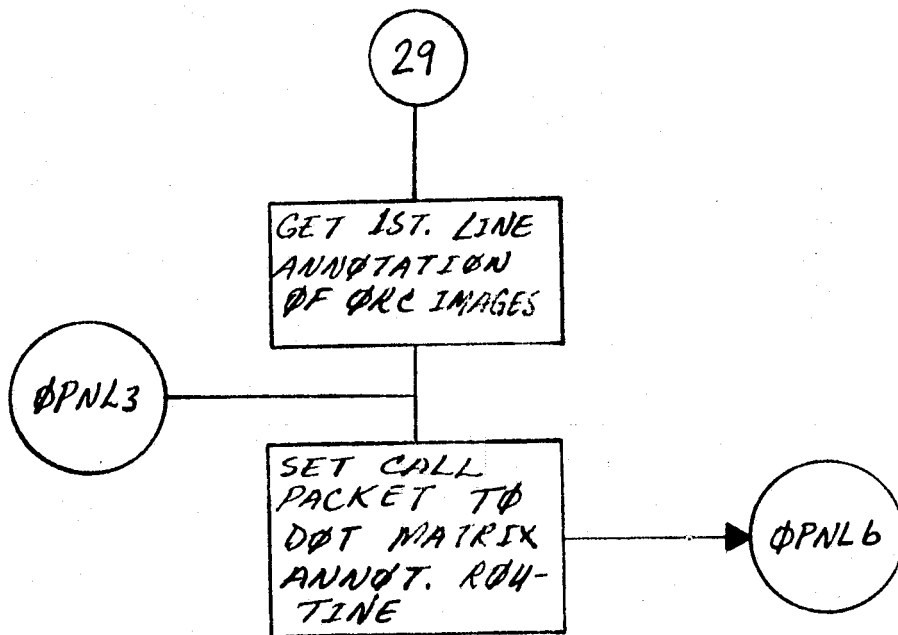


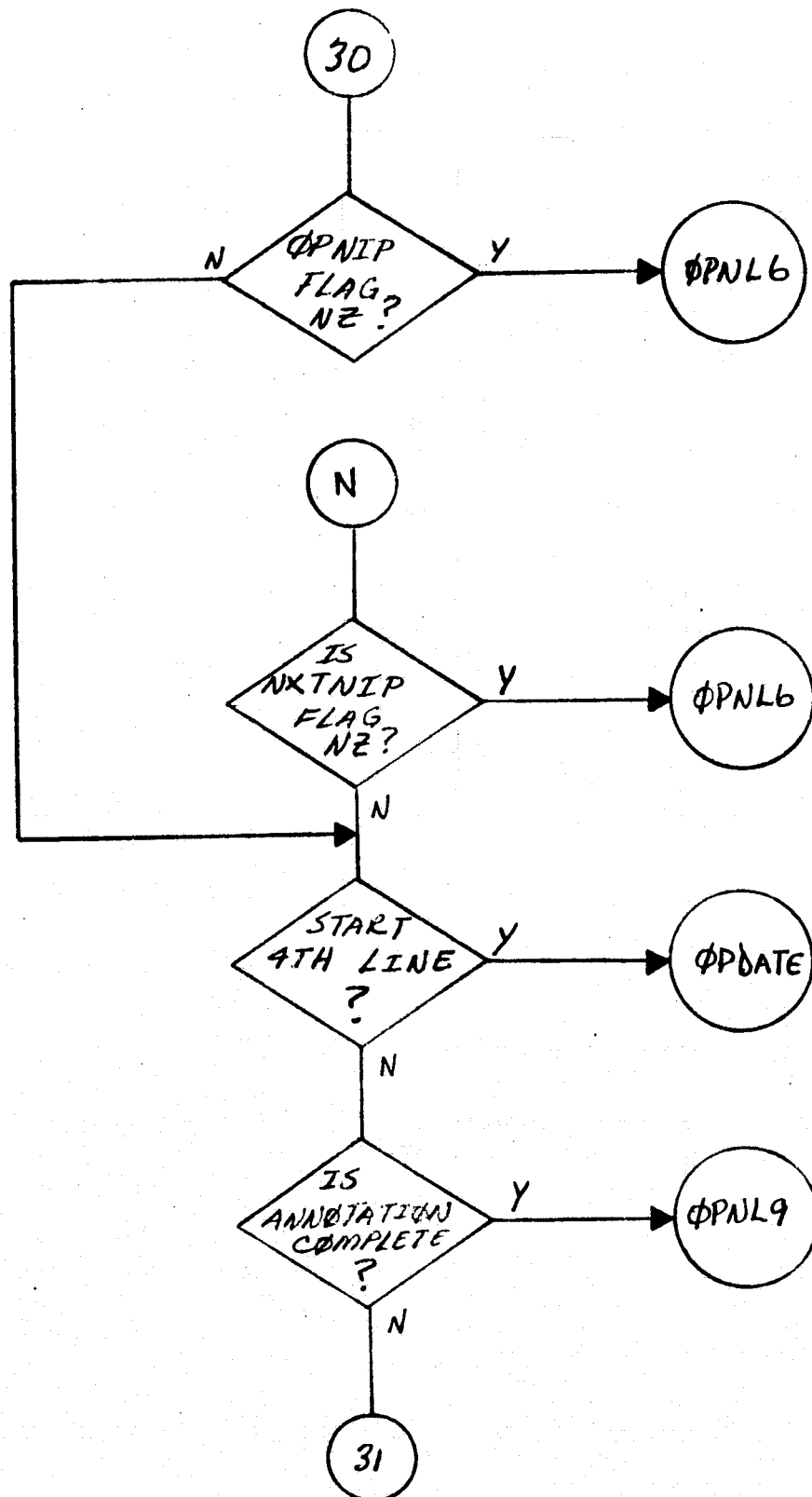
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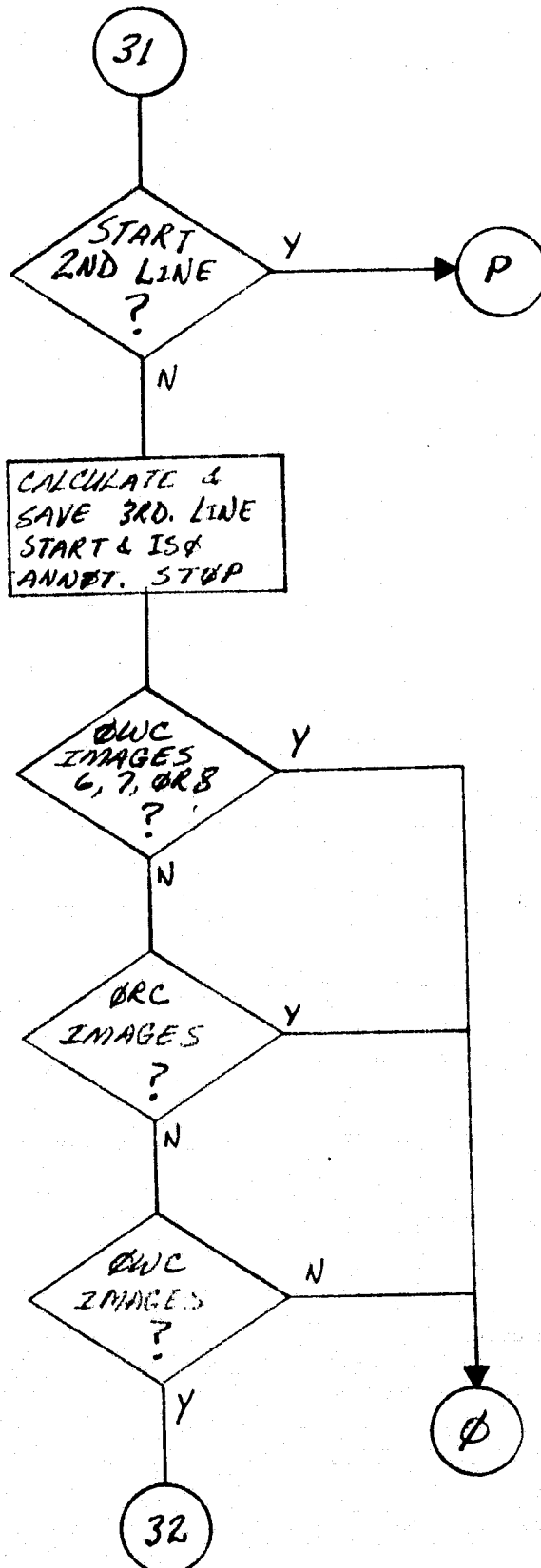


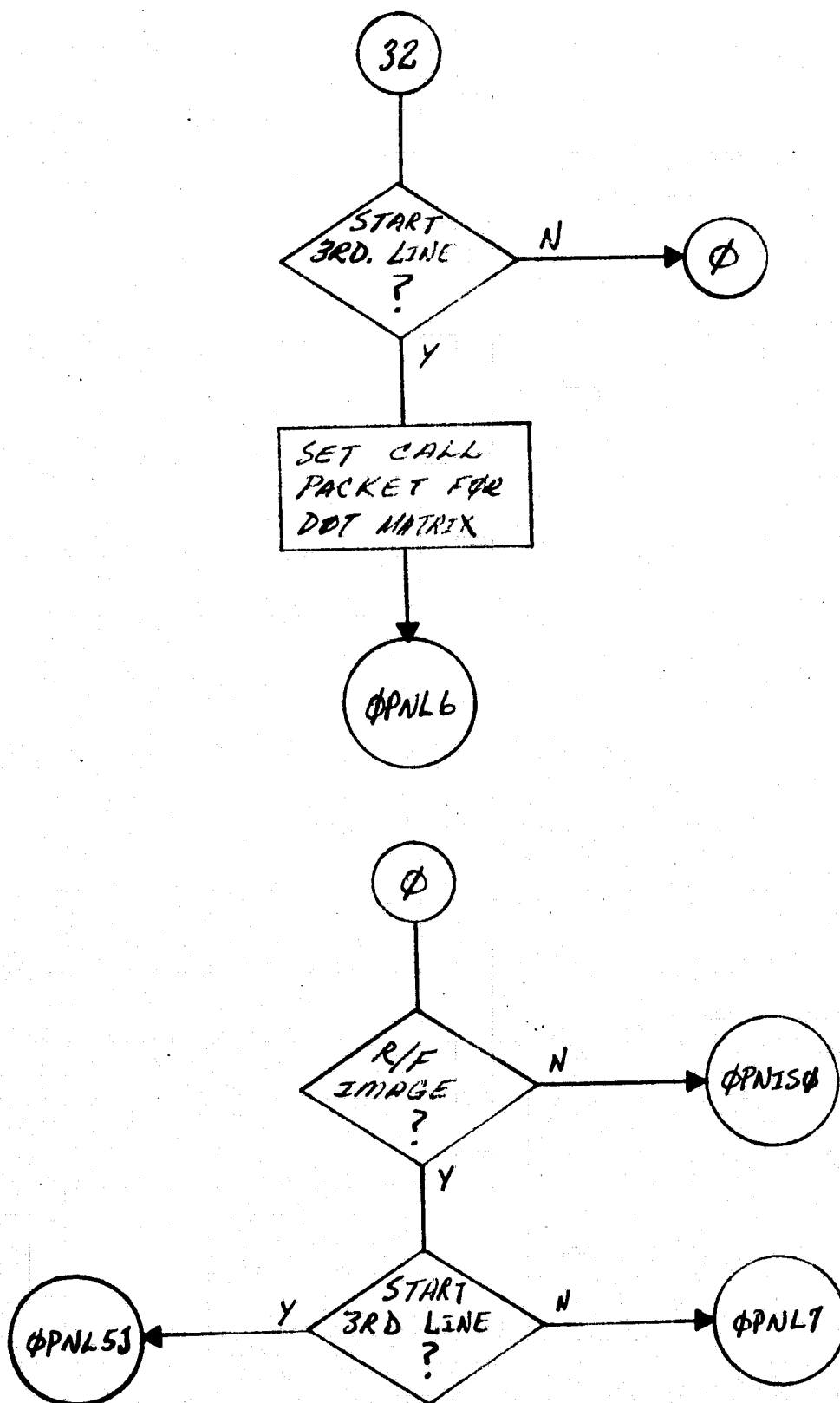


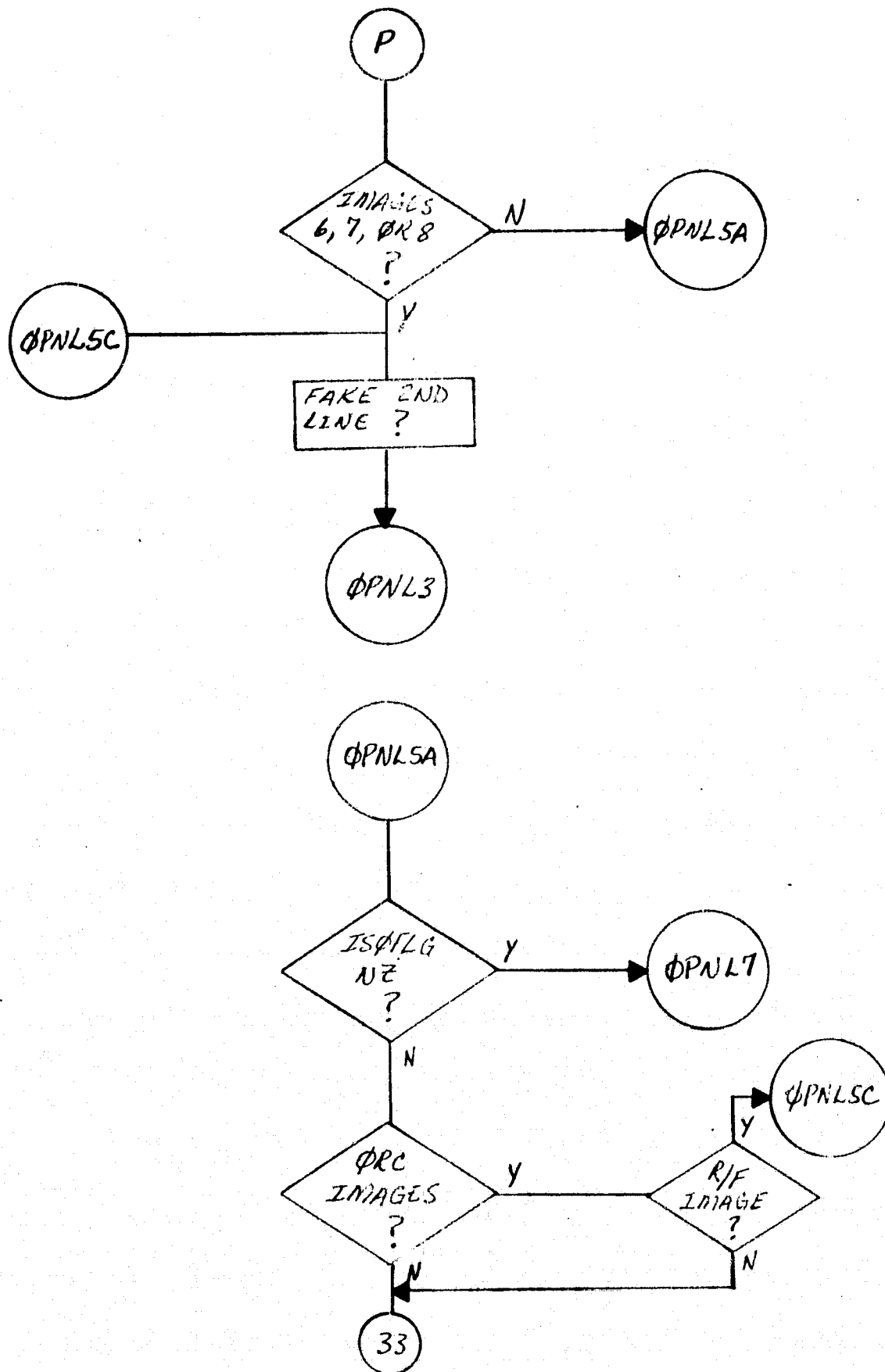


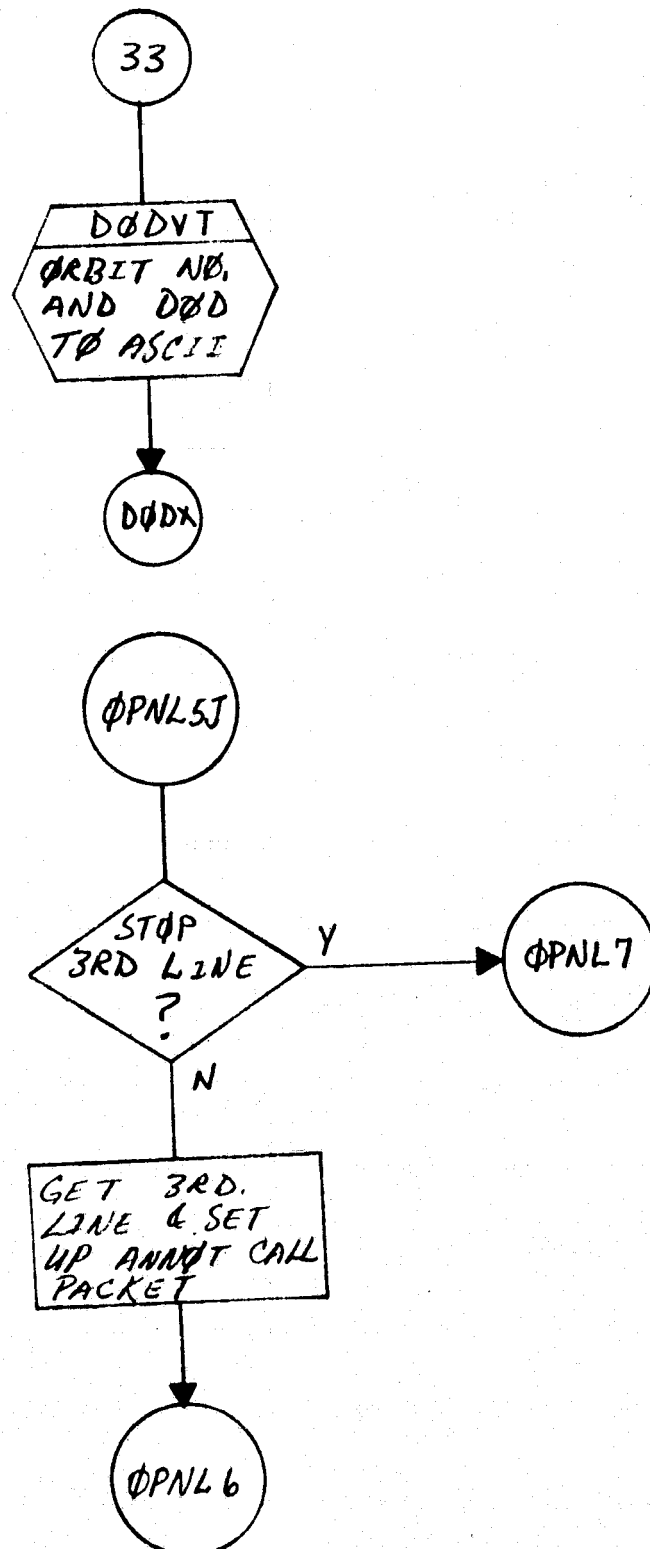


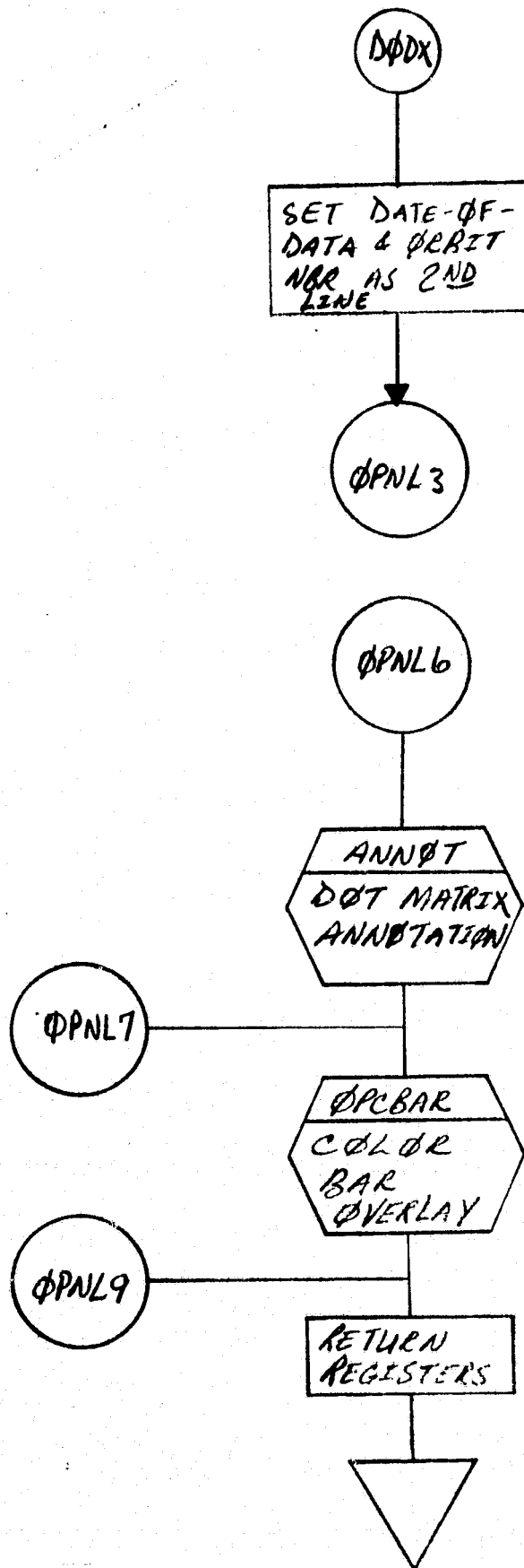


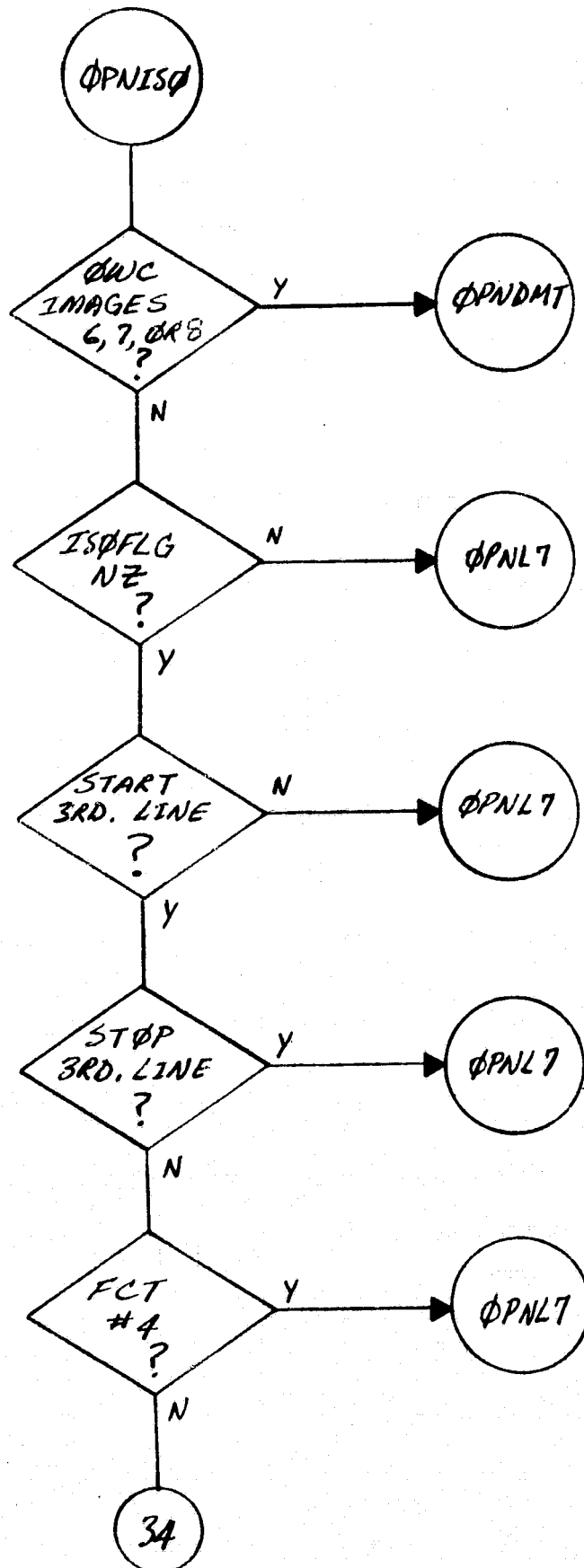


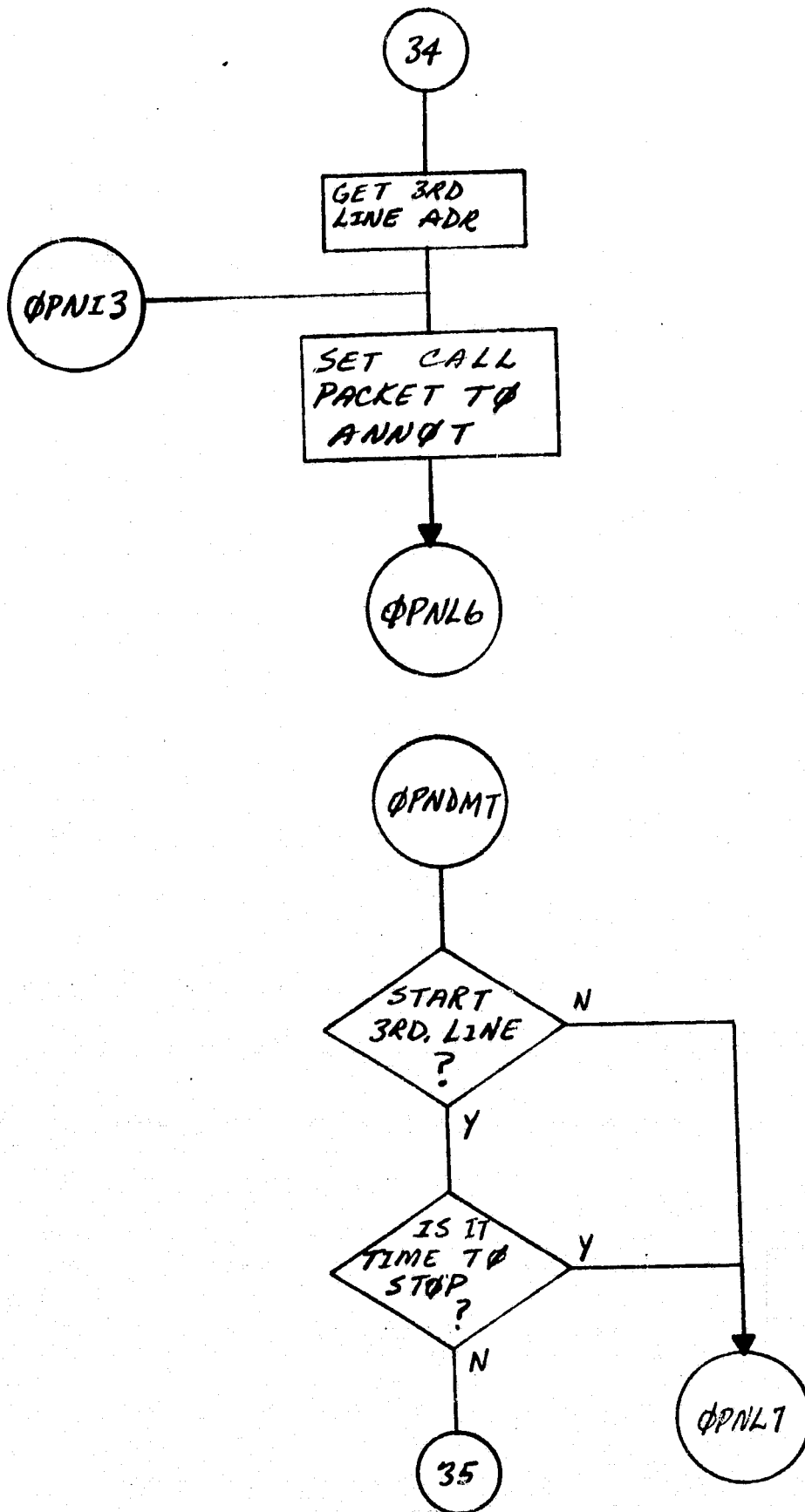


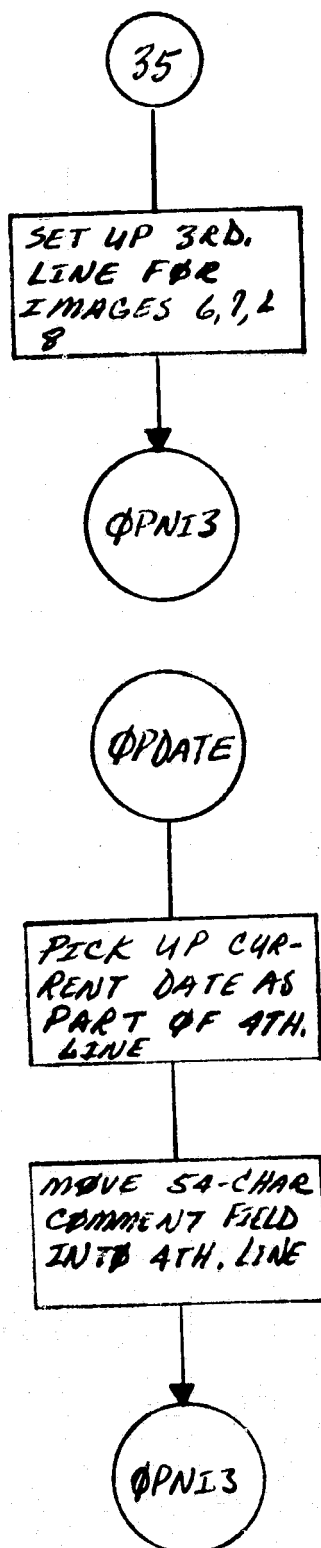


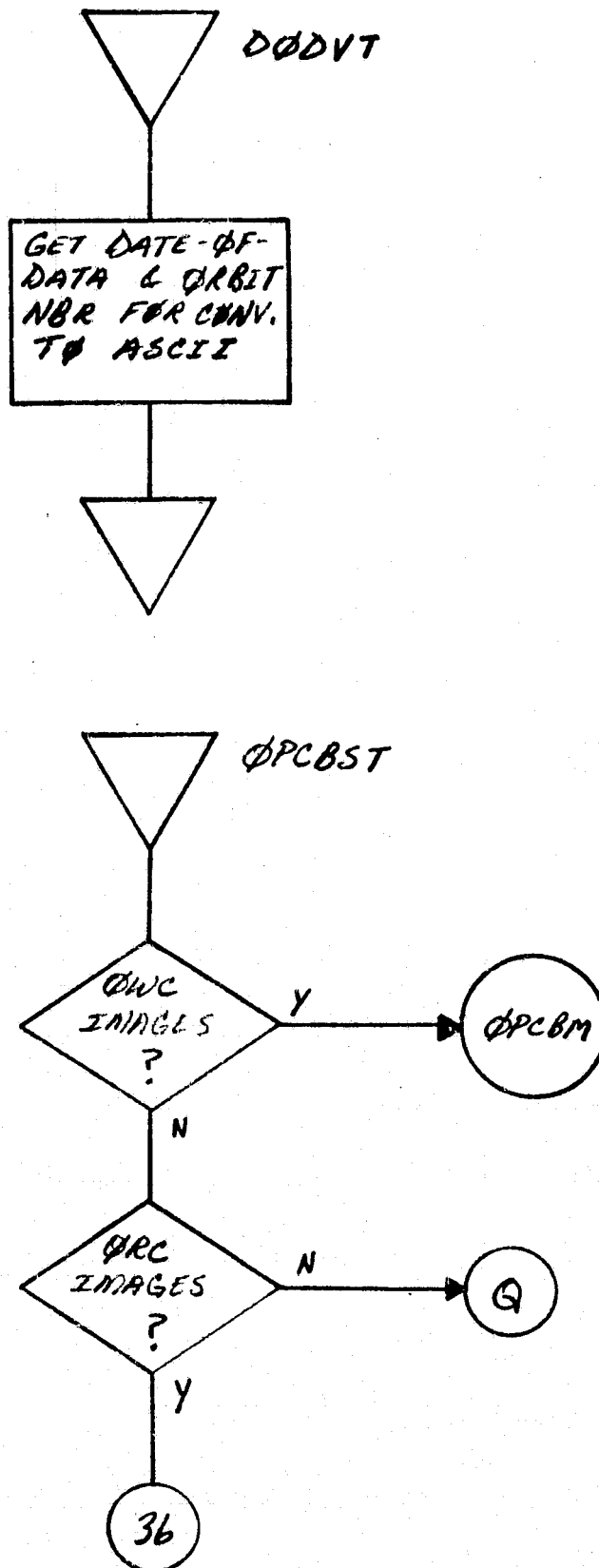


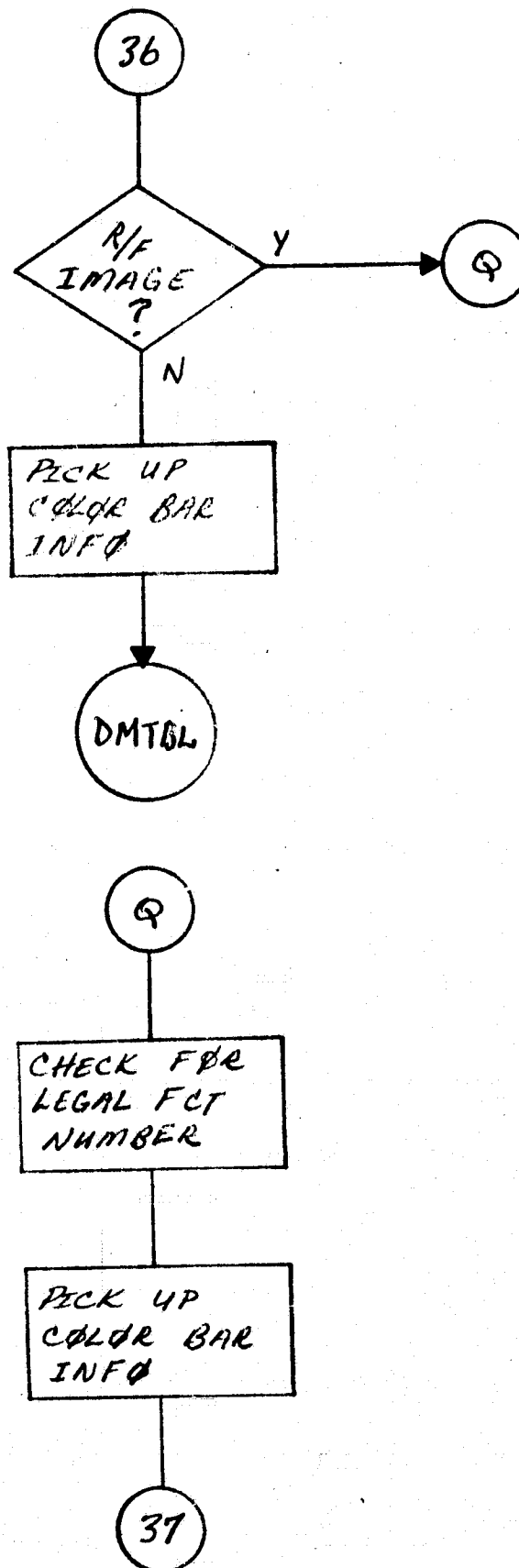


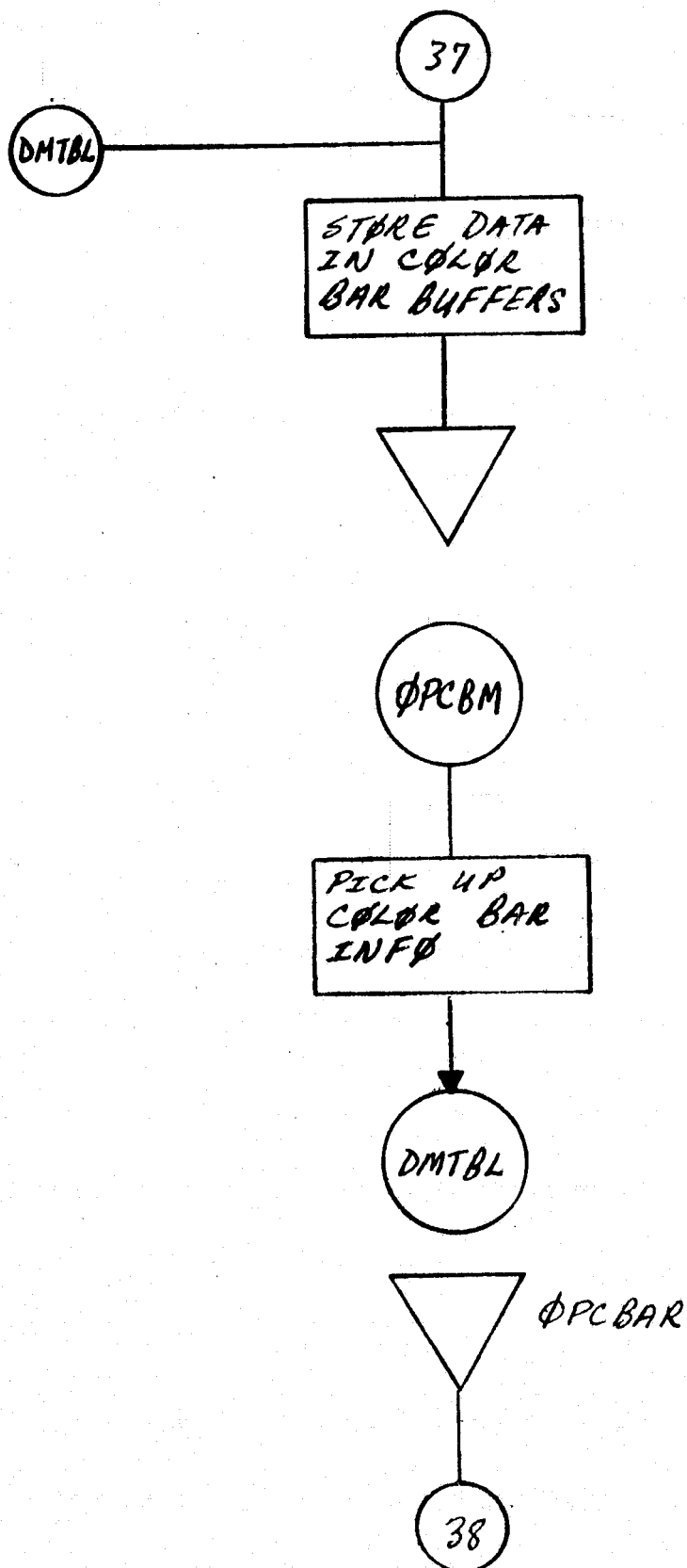


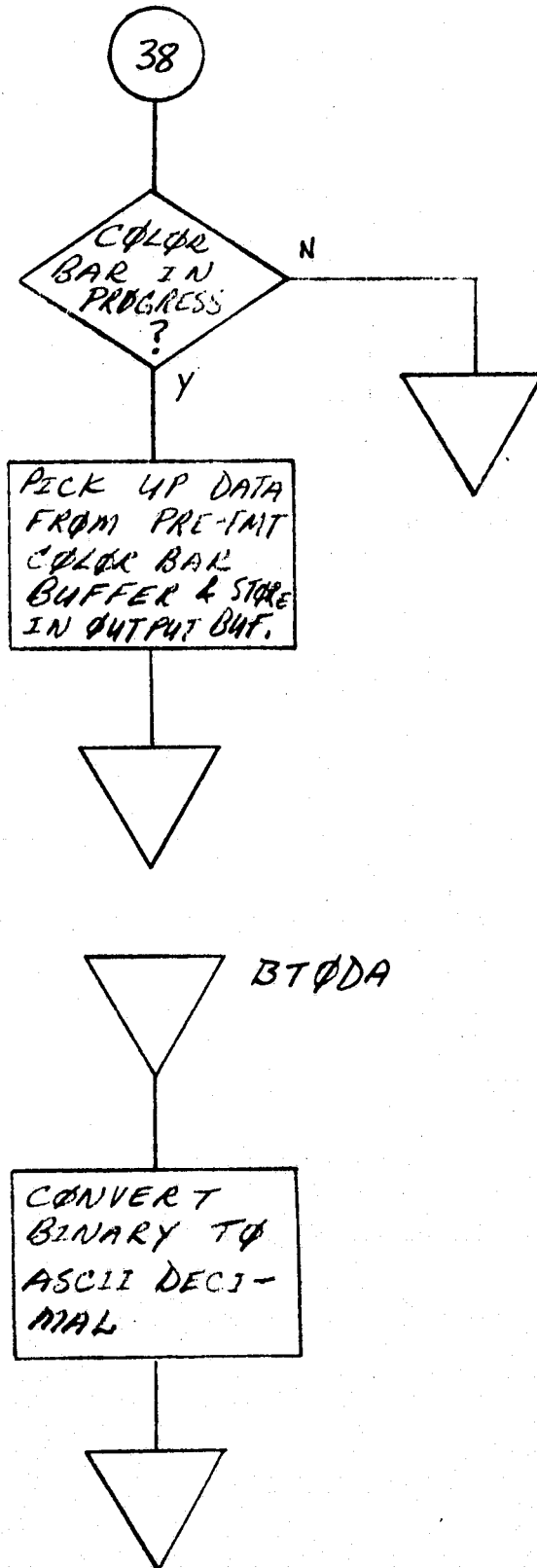


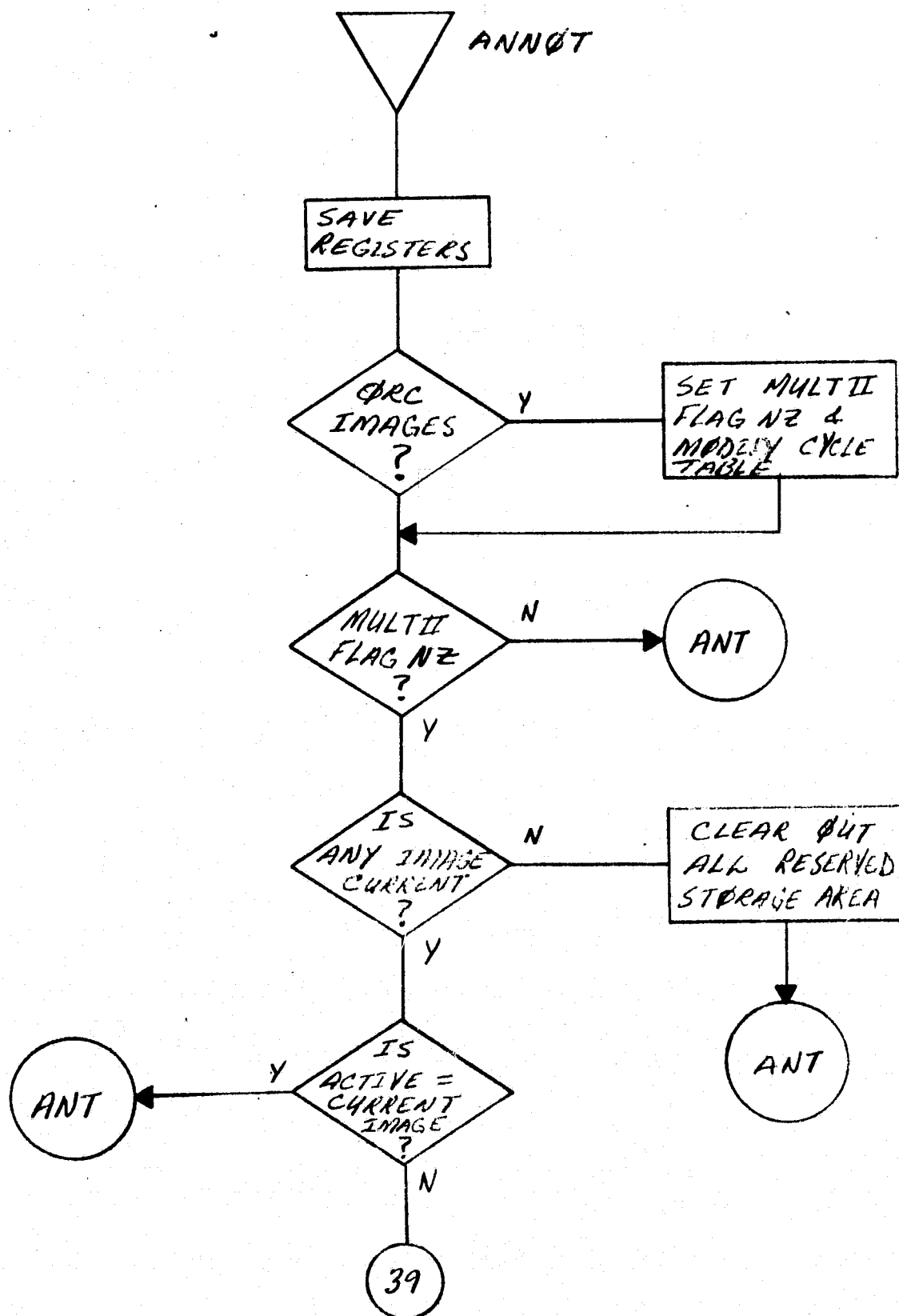




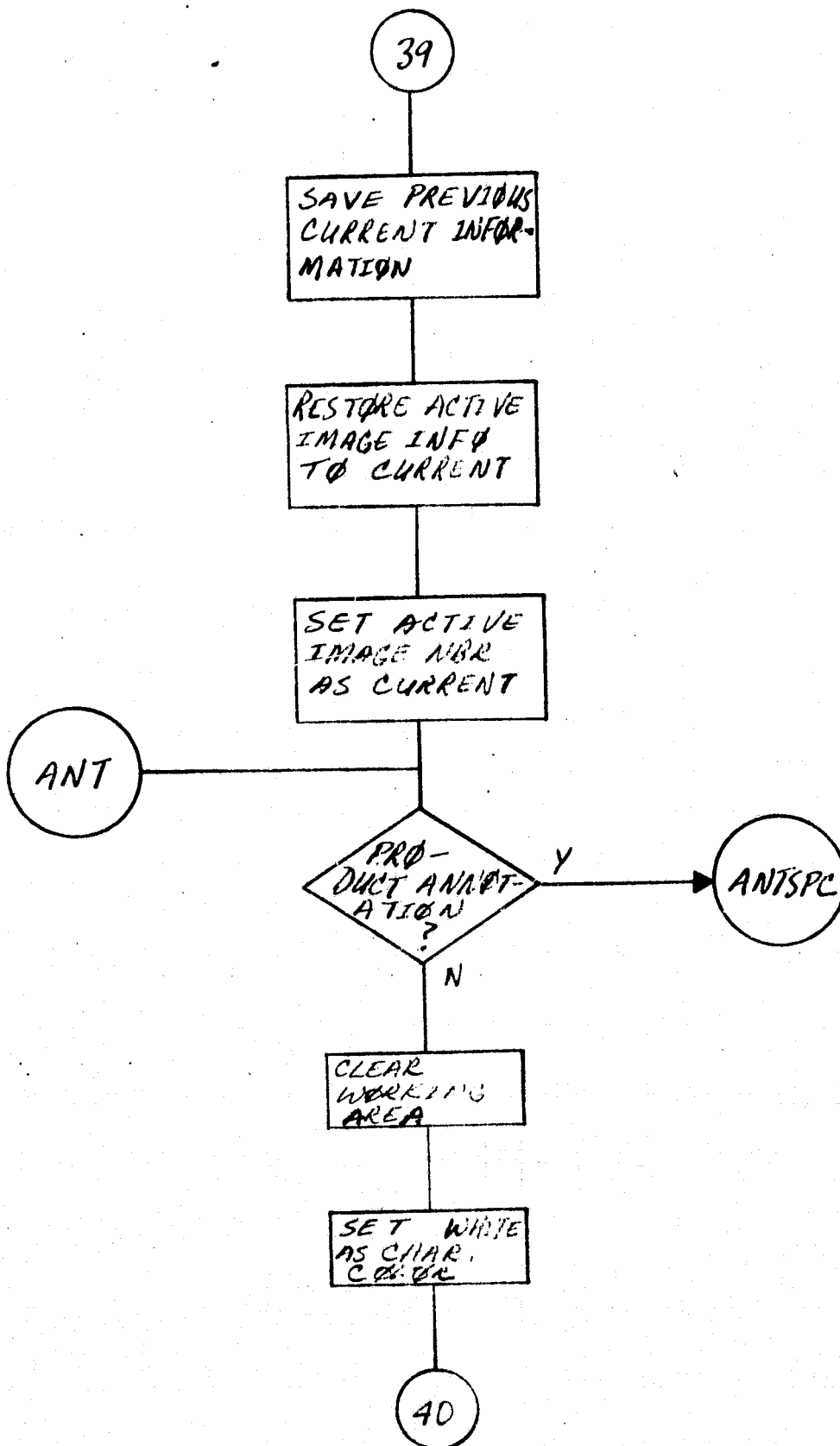


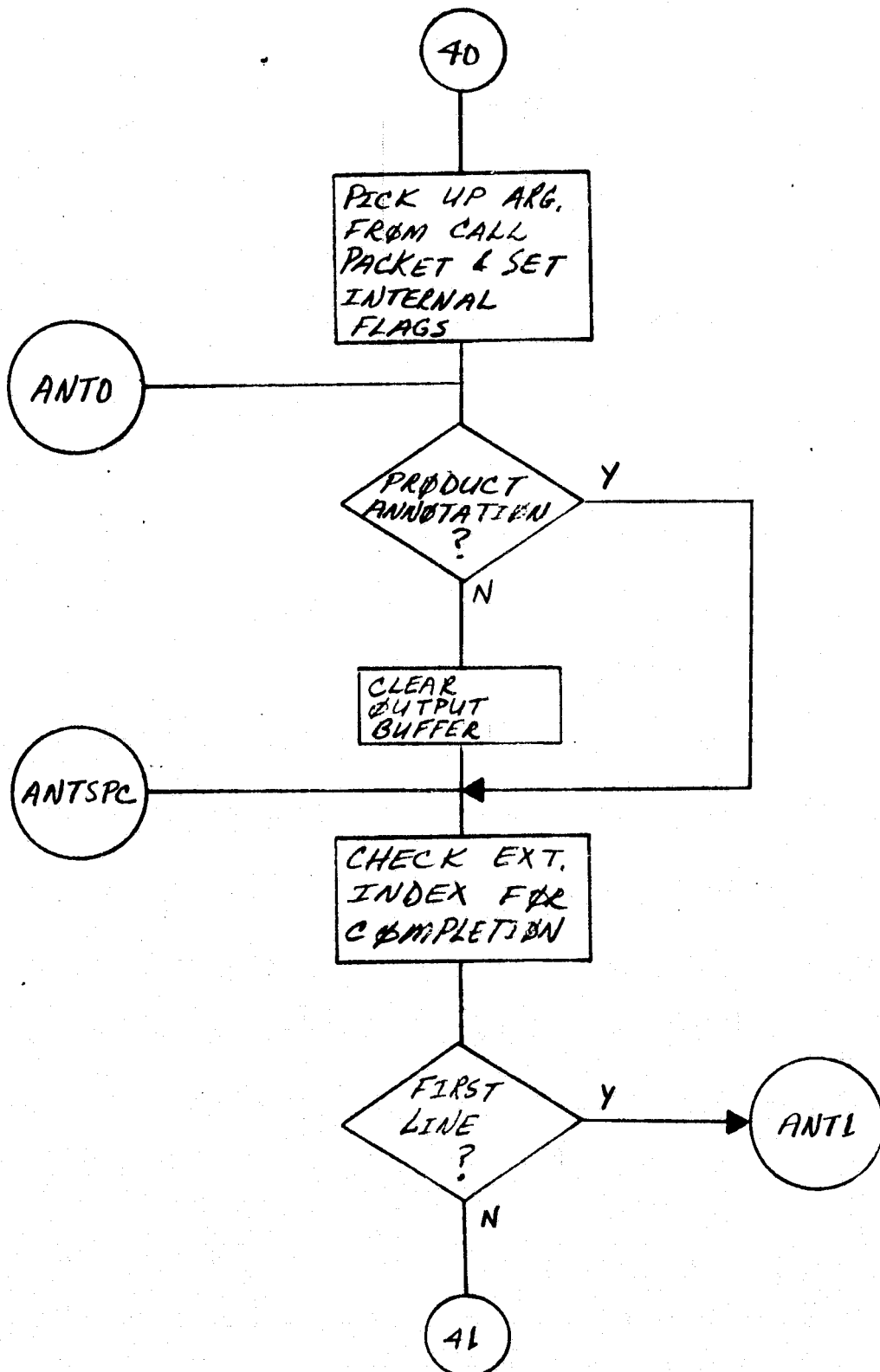


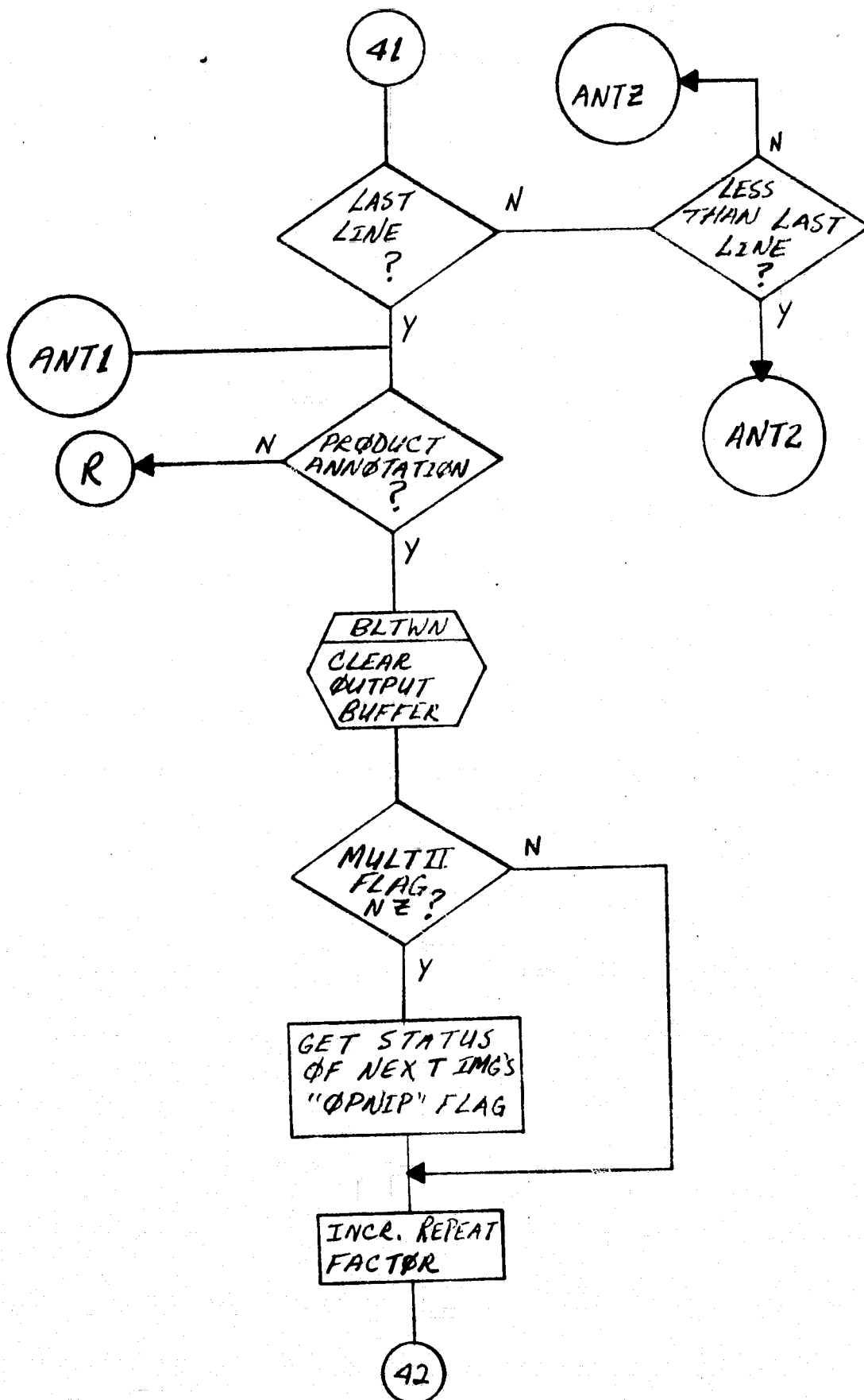


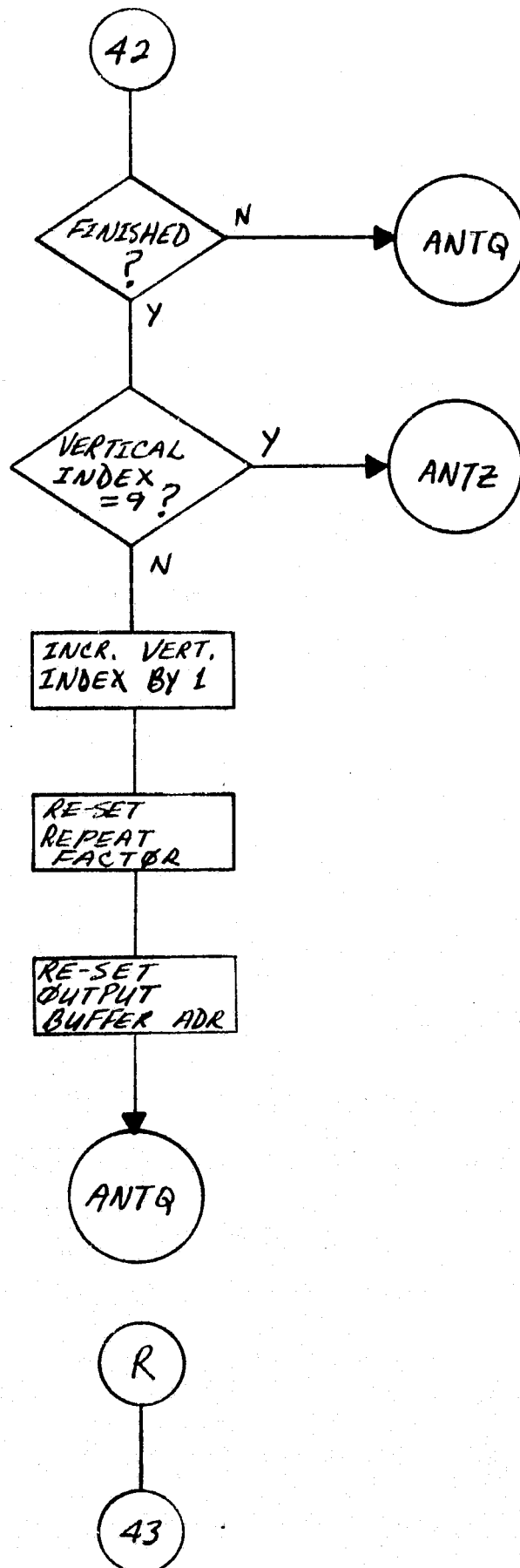


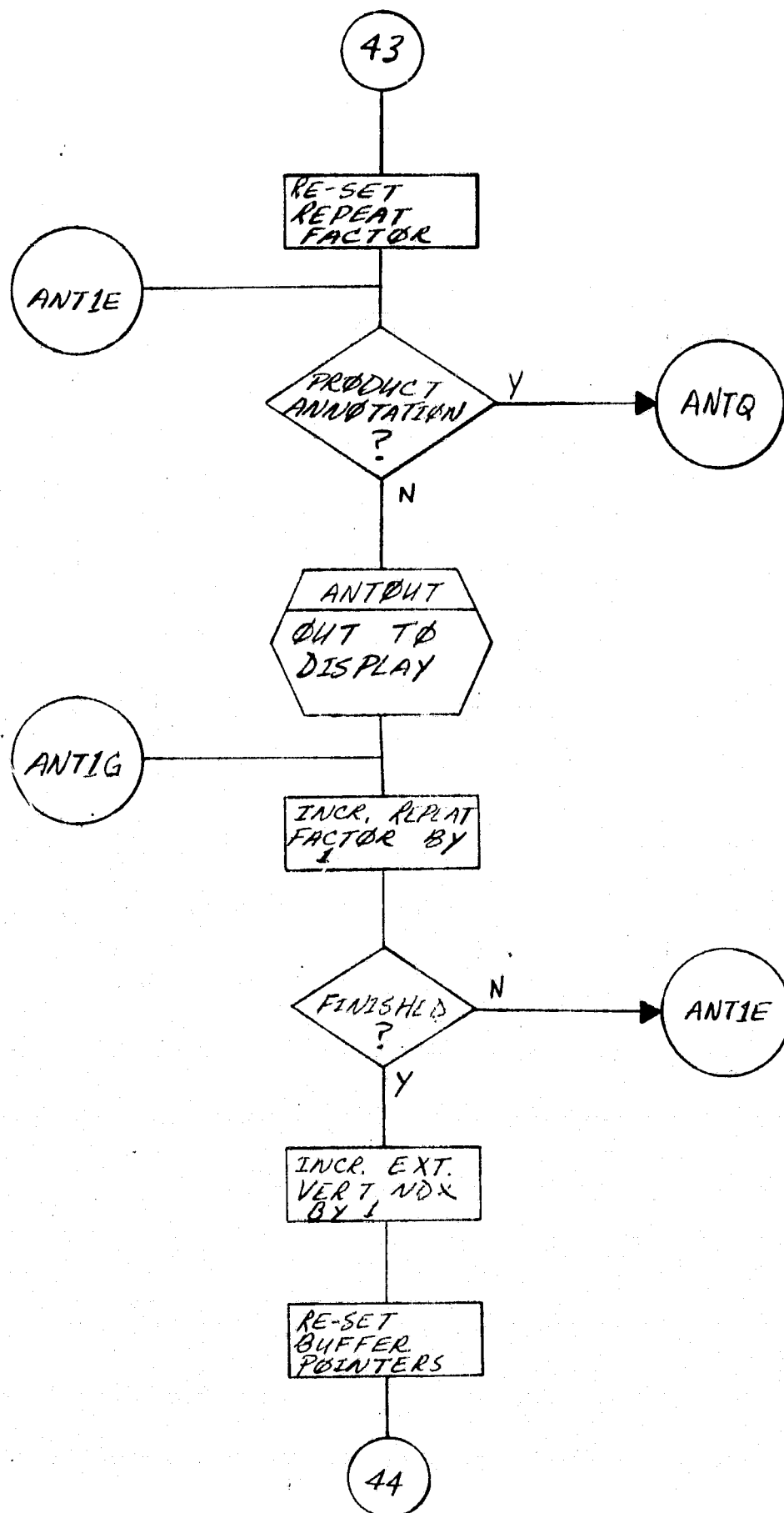
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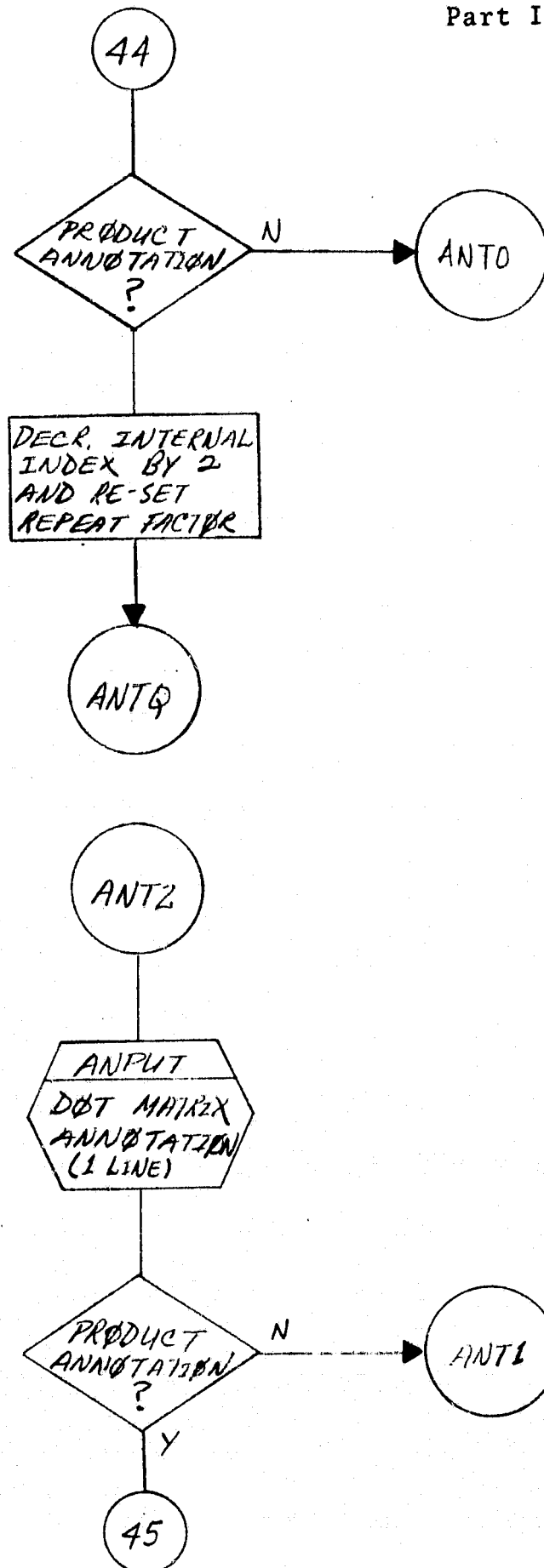


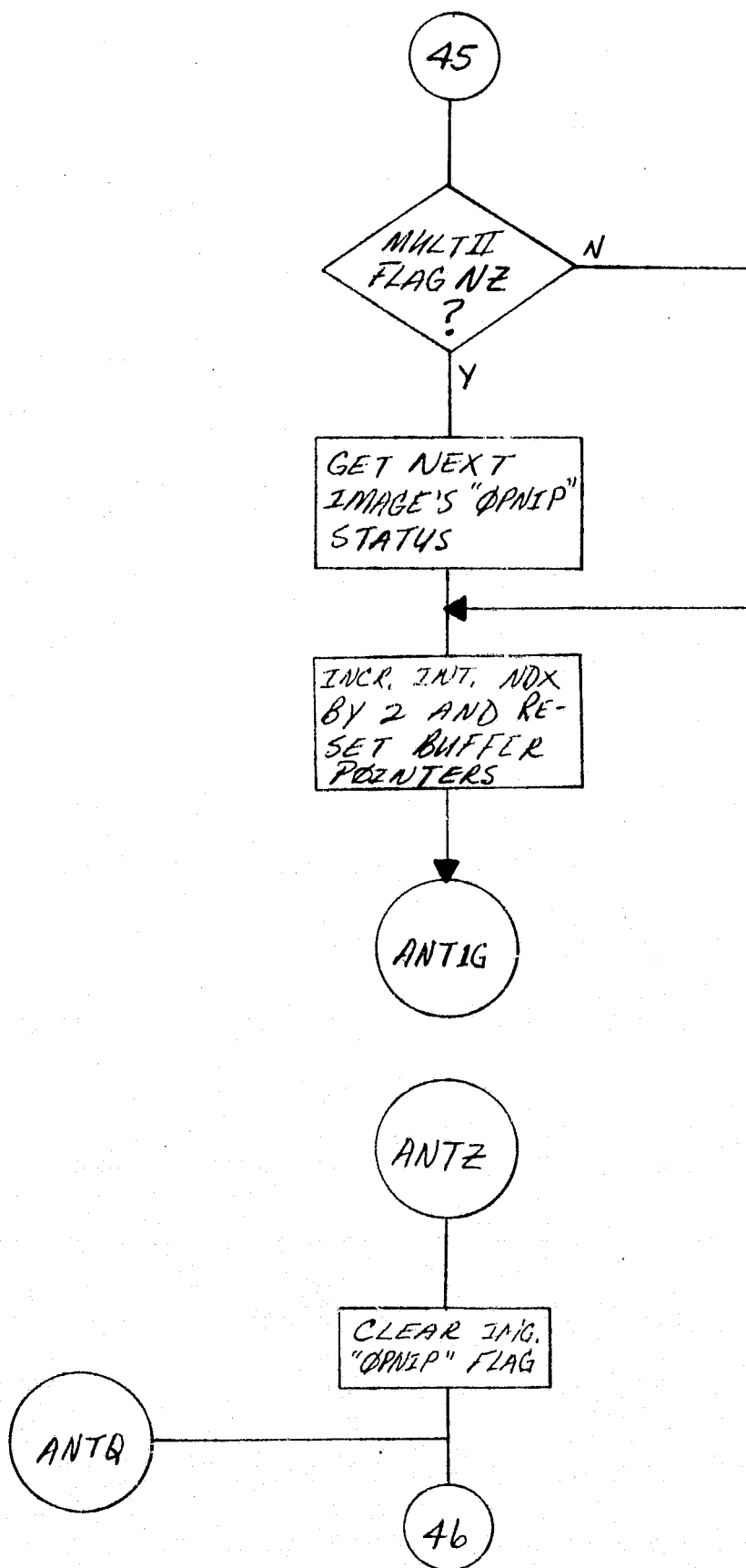


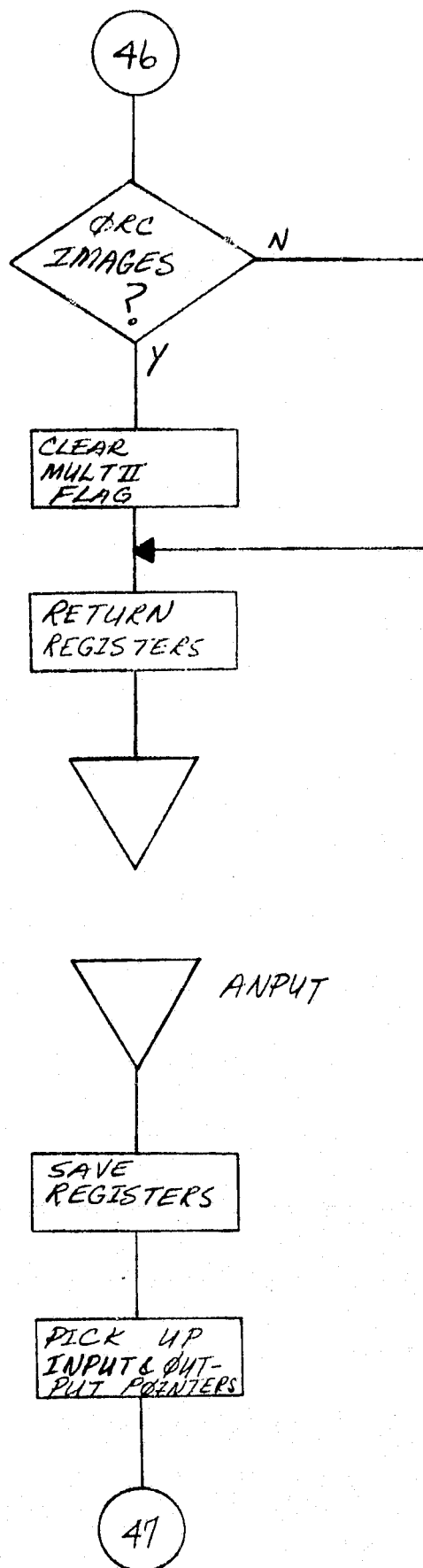


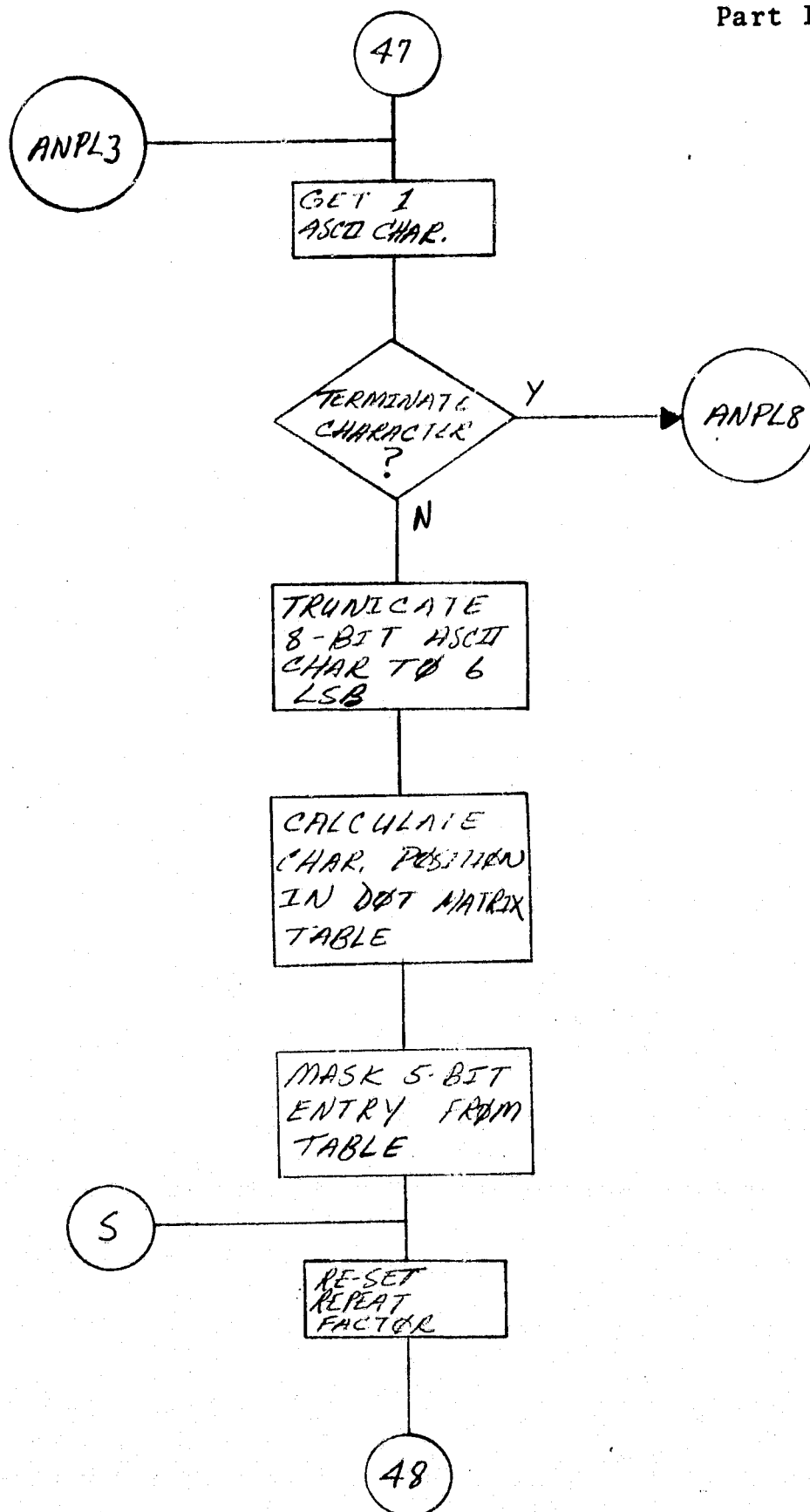


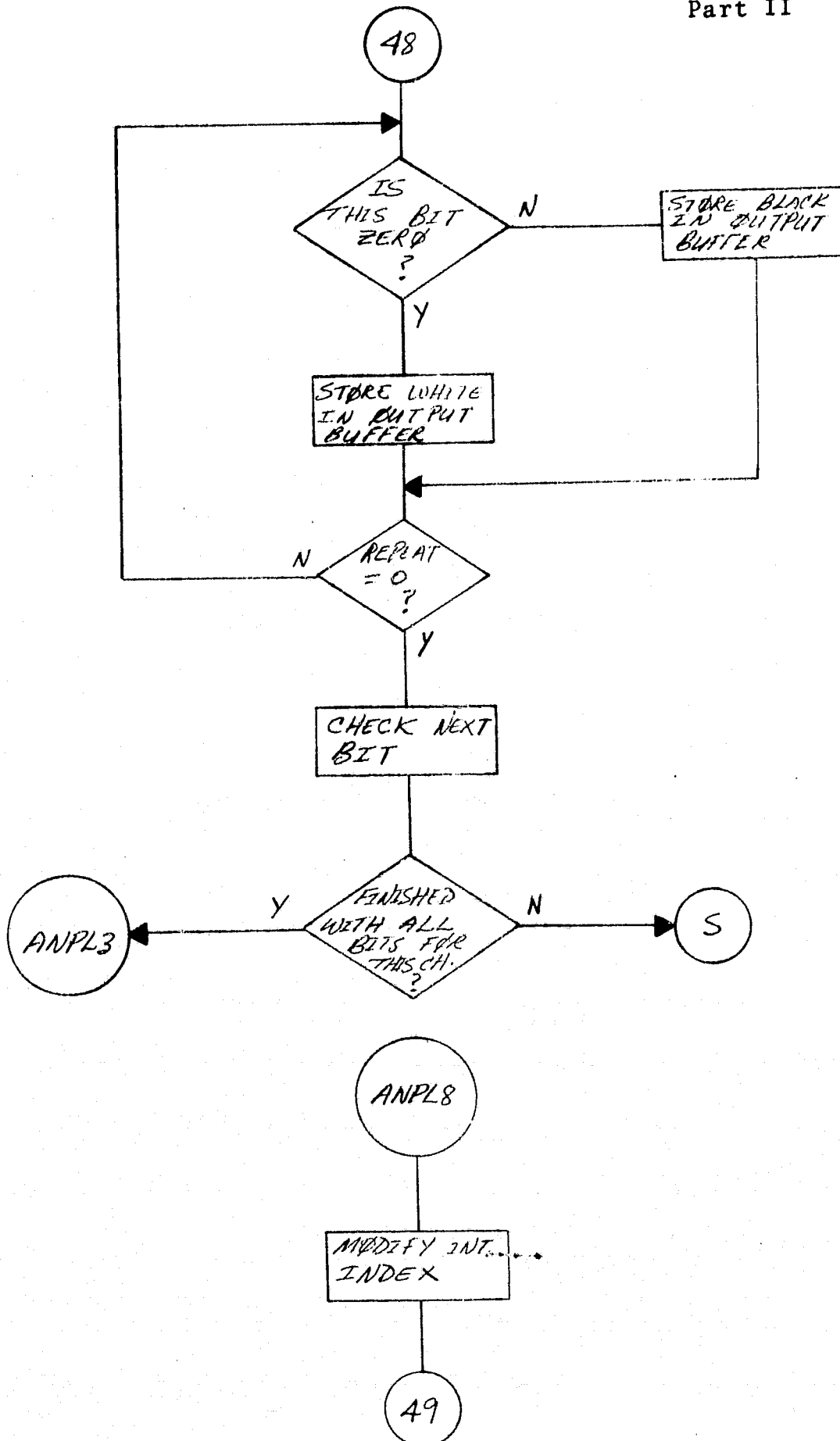


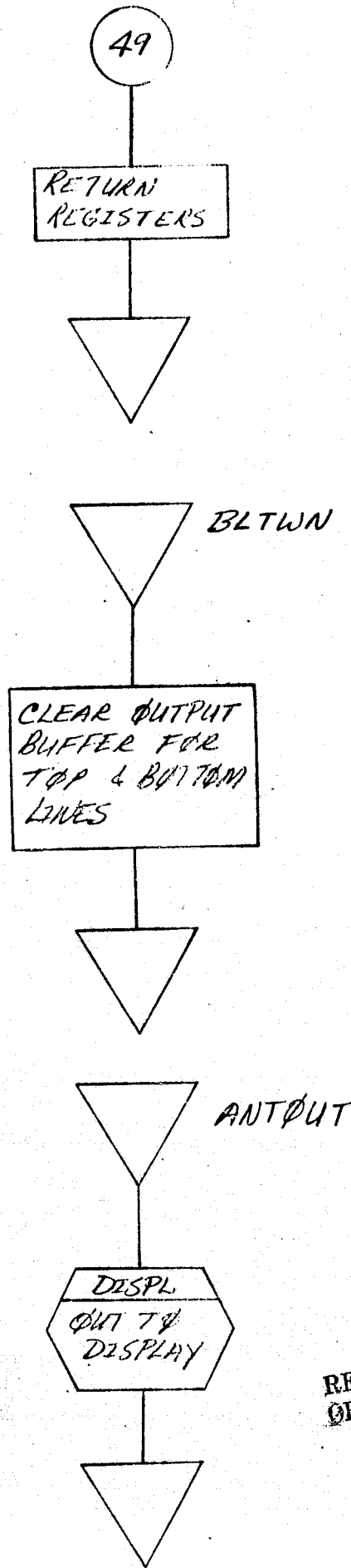




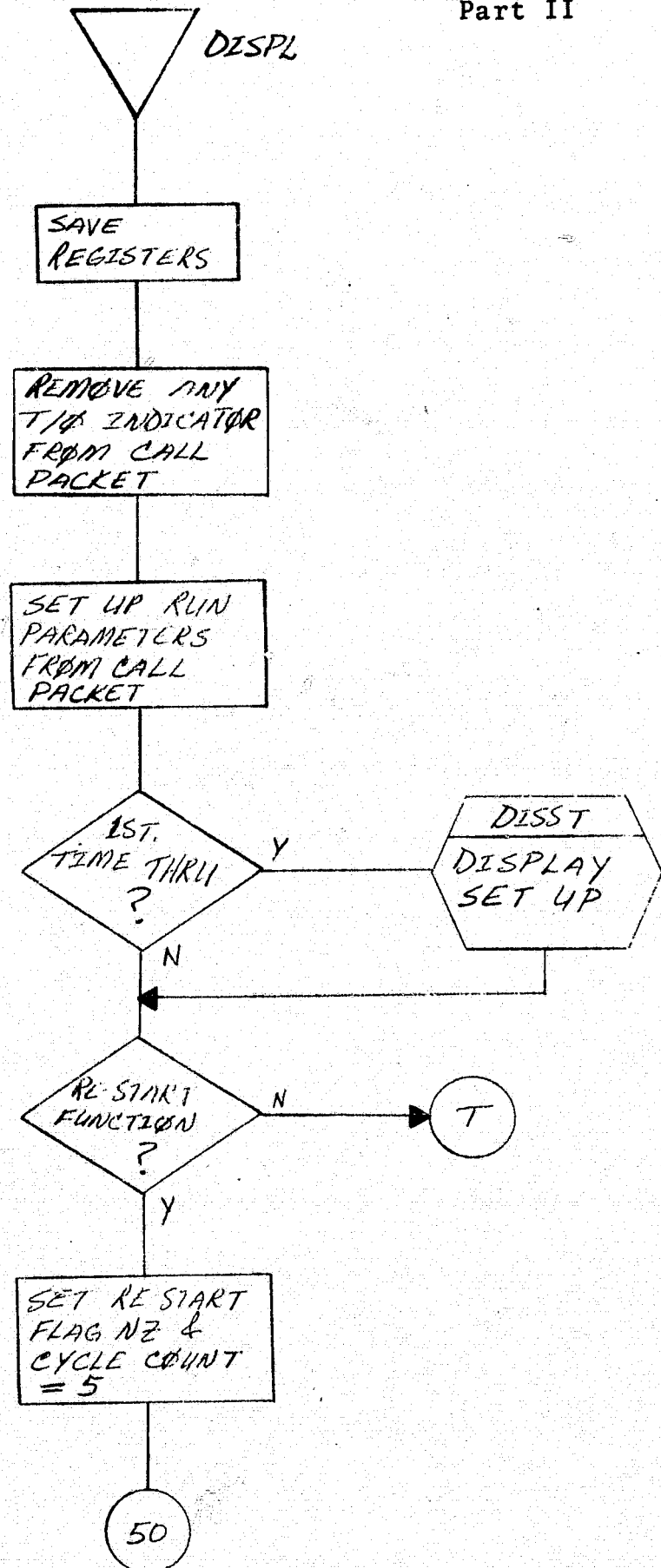


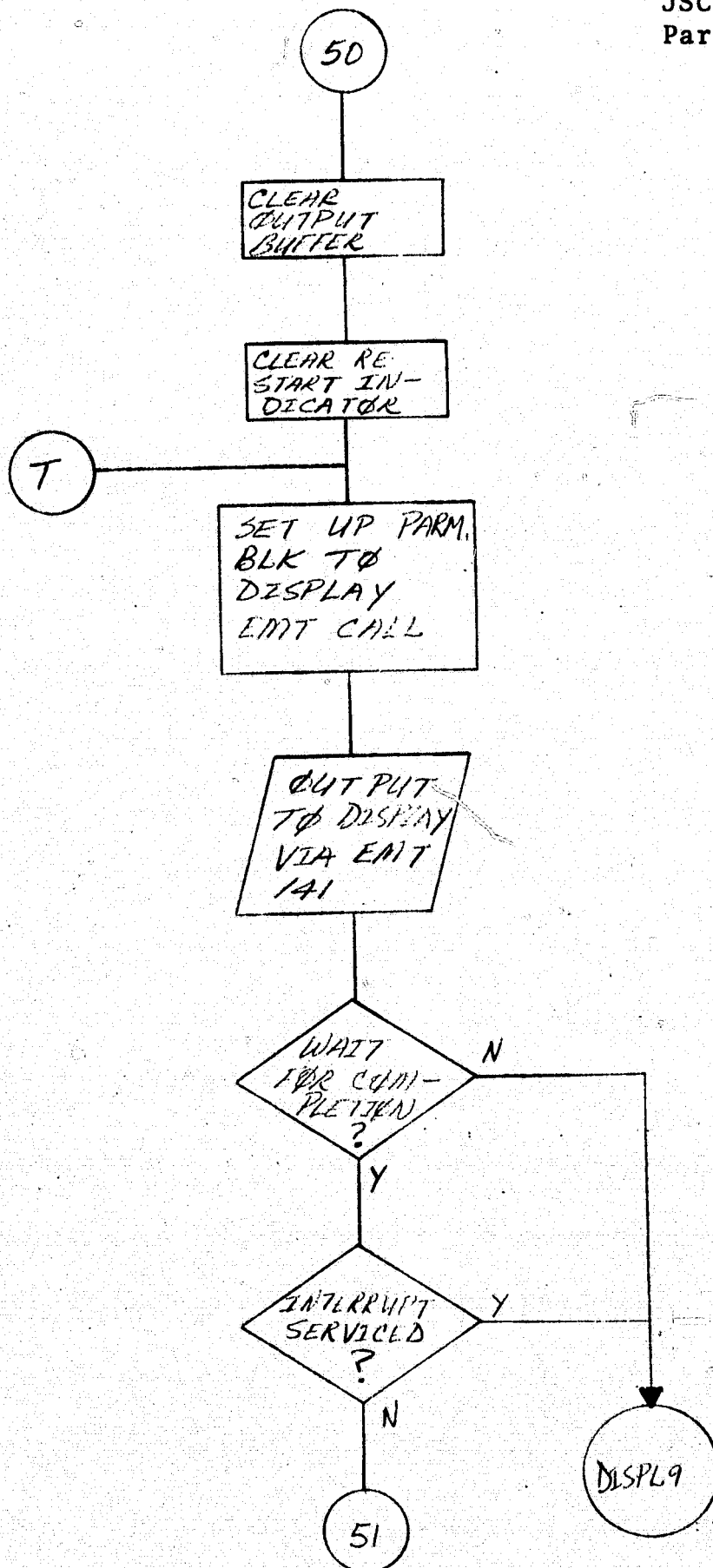


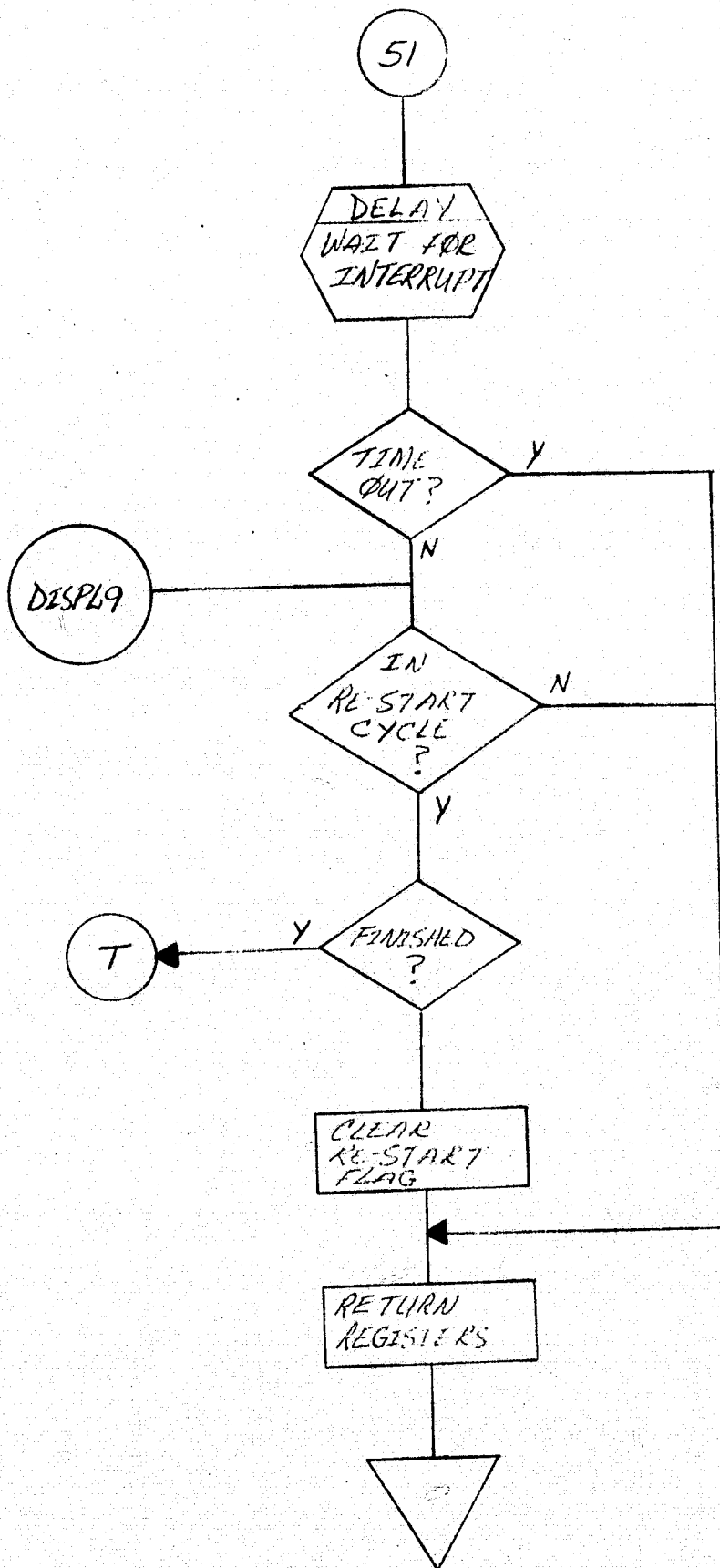


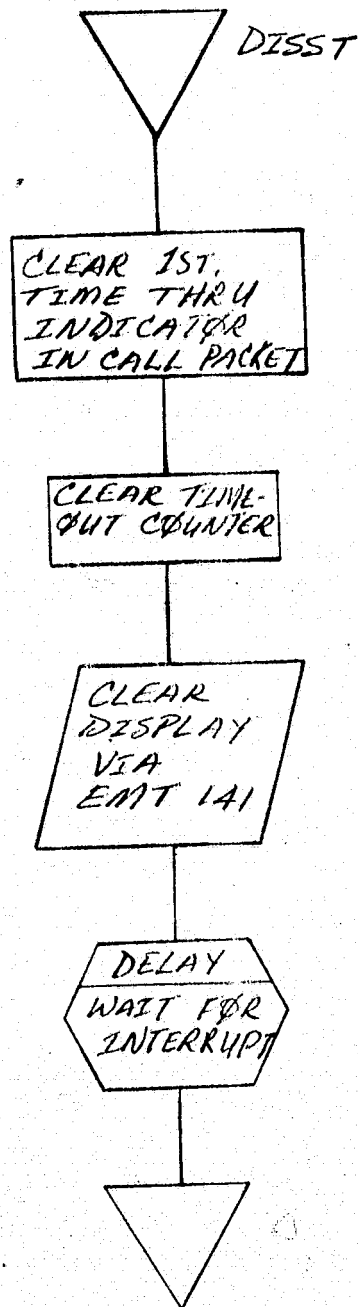


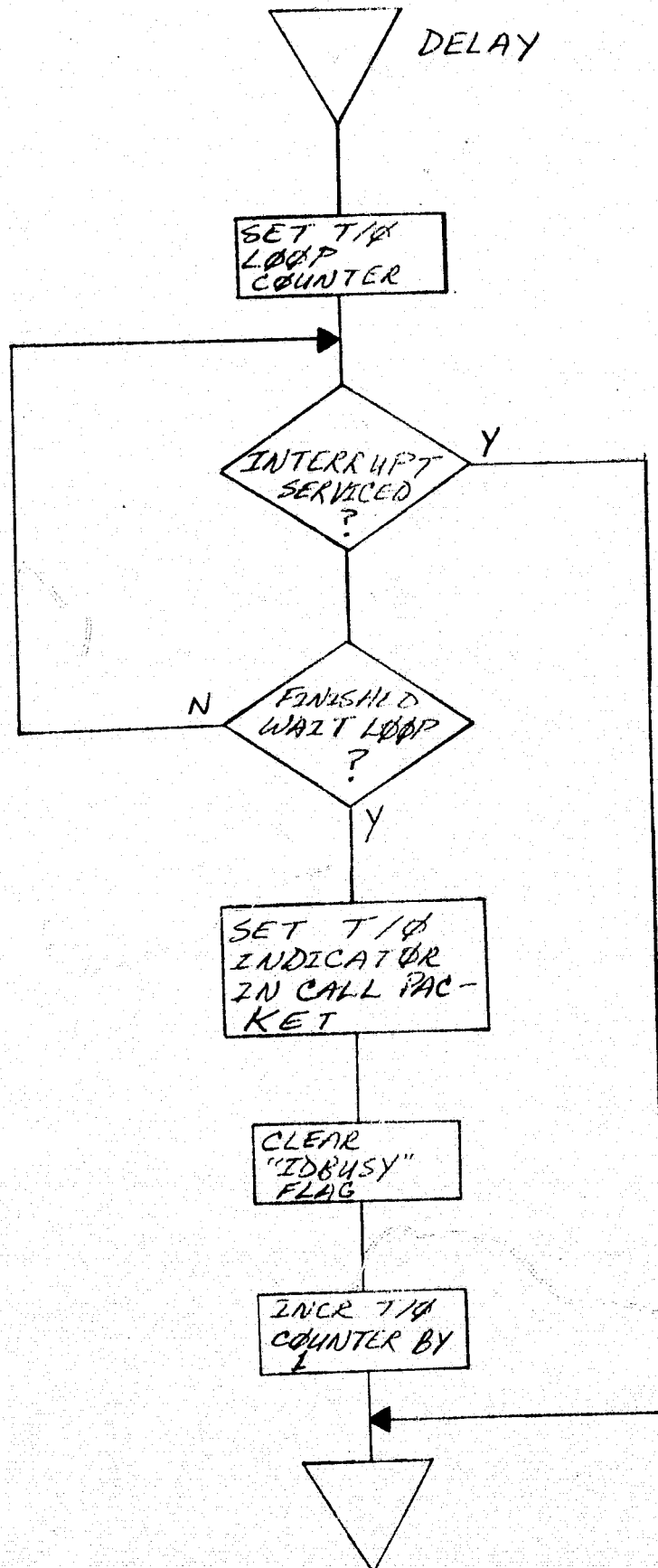
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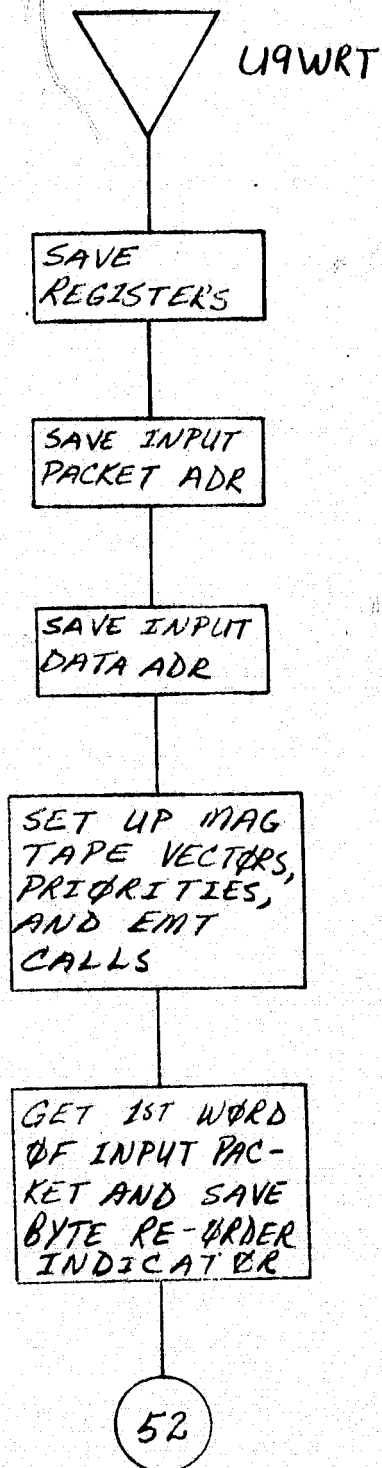


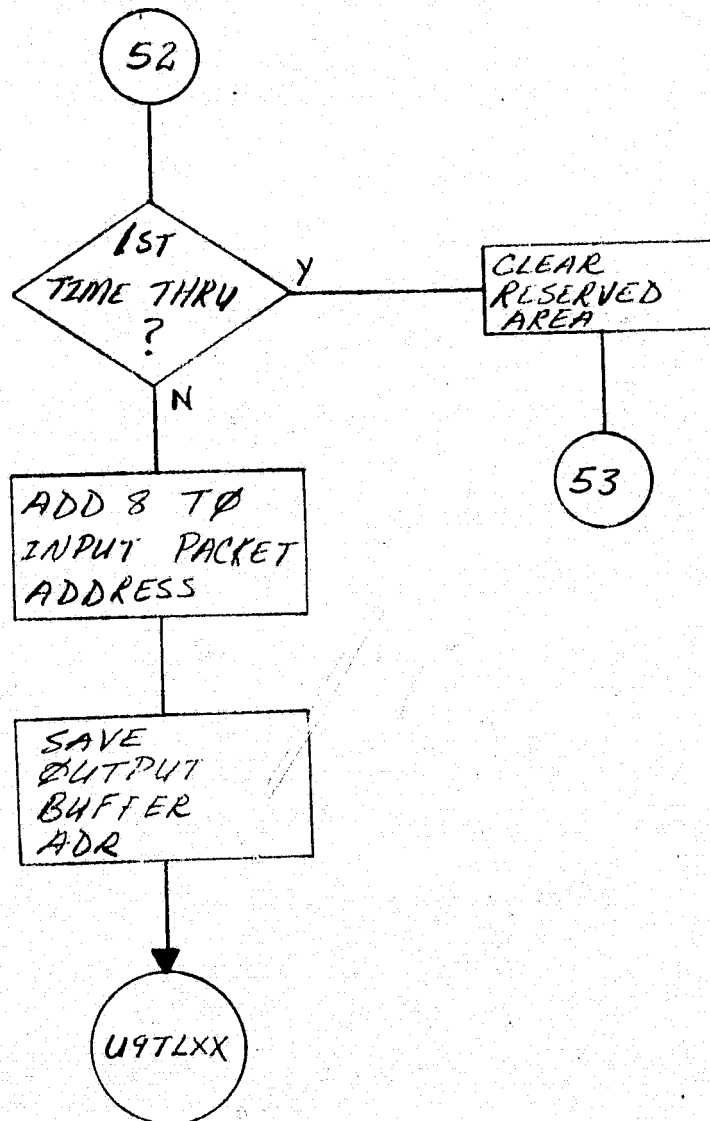






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(53)

GET ADDR OF
INPUT PACKET

CLEAR 1ST. TIME
THRU INDICATOR
(BIT 8) OF 1ST.
WORD IN INPUT
PACKET

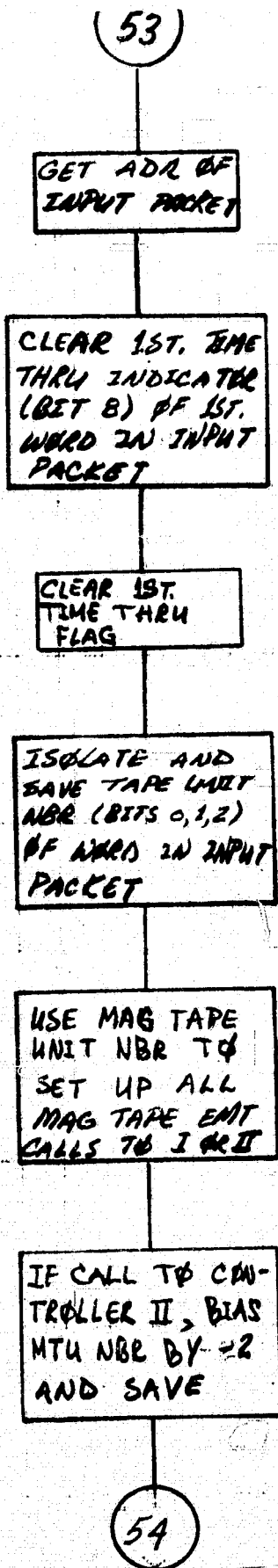
CLEAR 1ST.
TIME THRU
FLAG

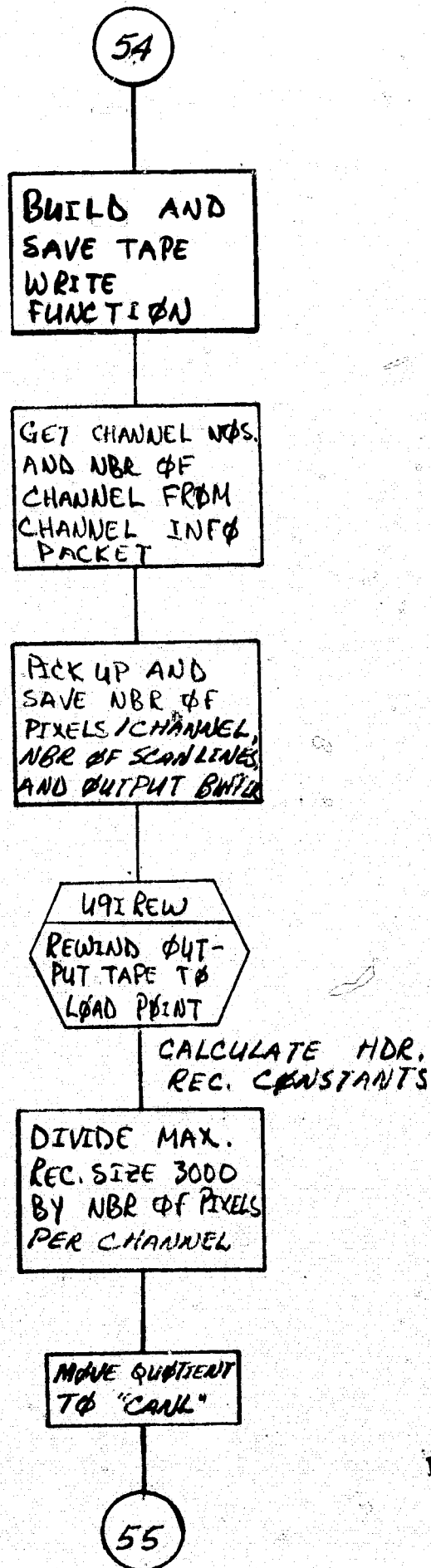
ISOLATE AND
SAVE TAPE UNIT
NBR (BITS 0,1,2)
OF WORDS IN INPUT
PACKET

USE MAG TAPE
UNIT NBR TO
SET UP ALL
MAG TAPE ENIT
CALLS TO I OR II

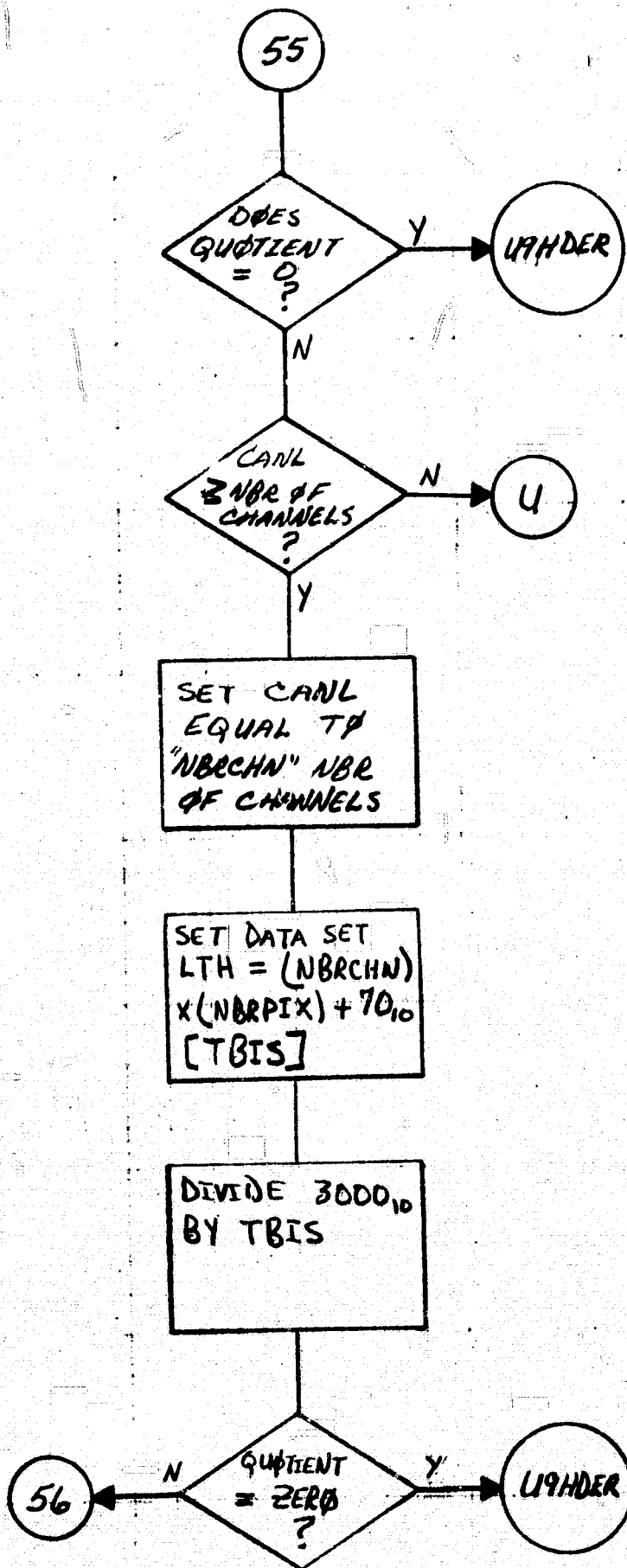
IF CALL TO CON-
TROLLER II, BIAS
MTU NBR BY -2
AND SAVE

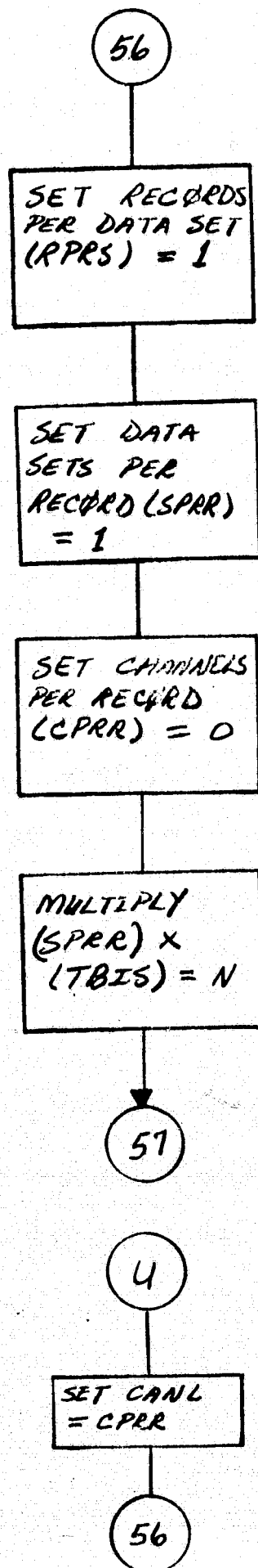
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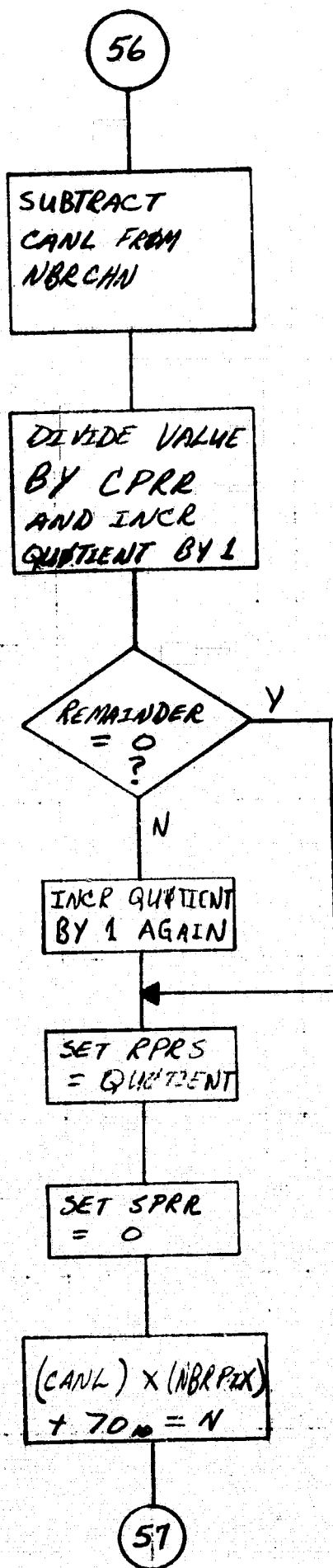




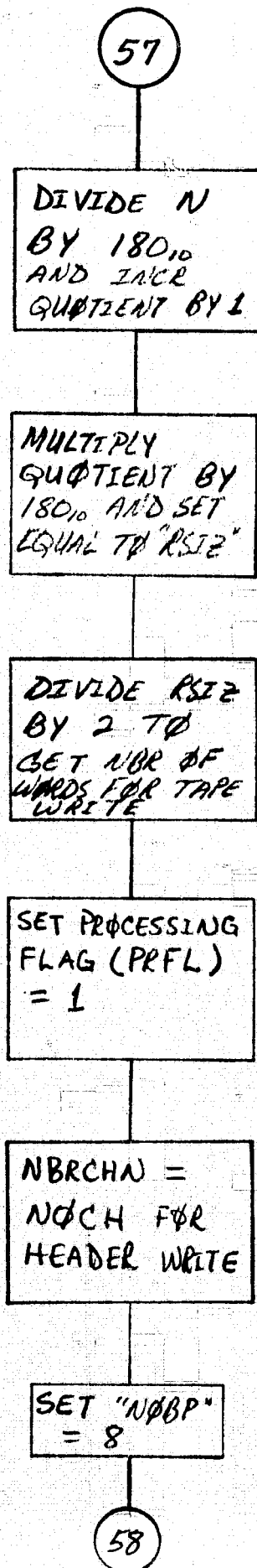
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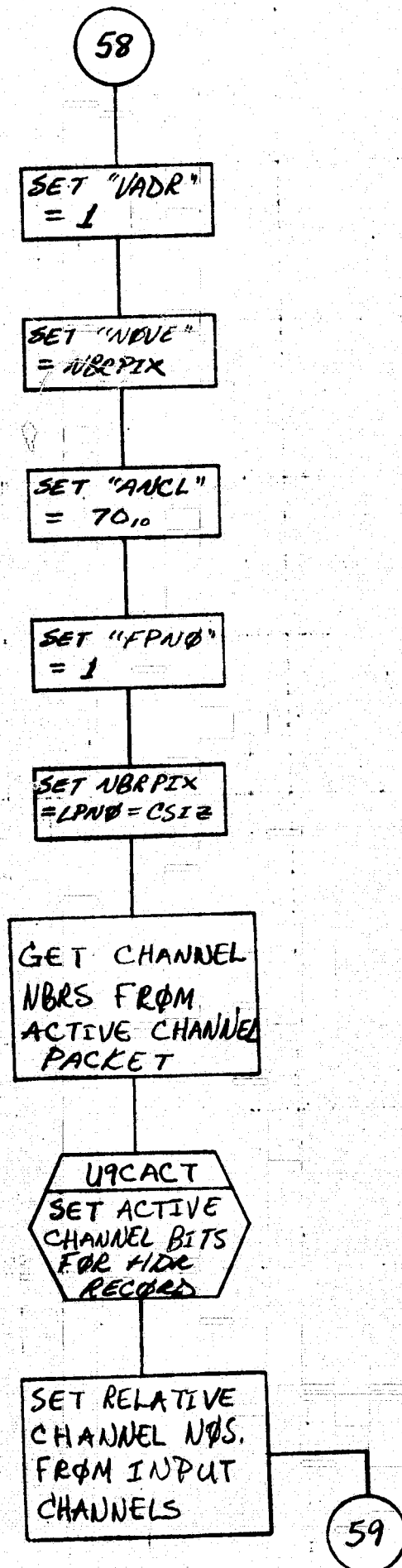


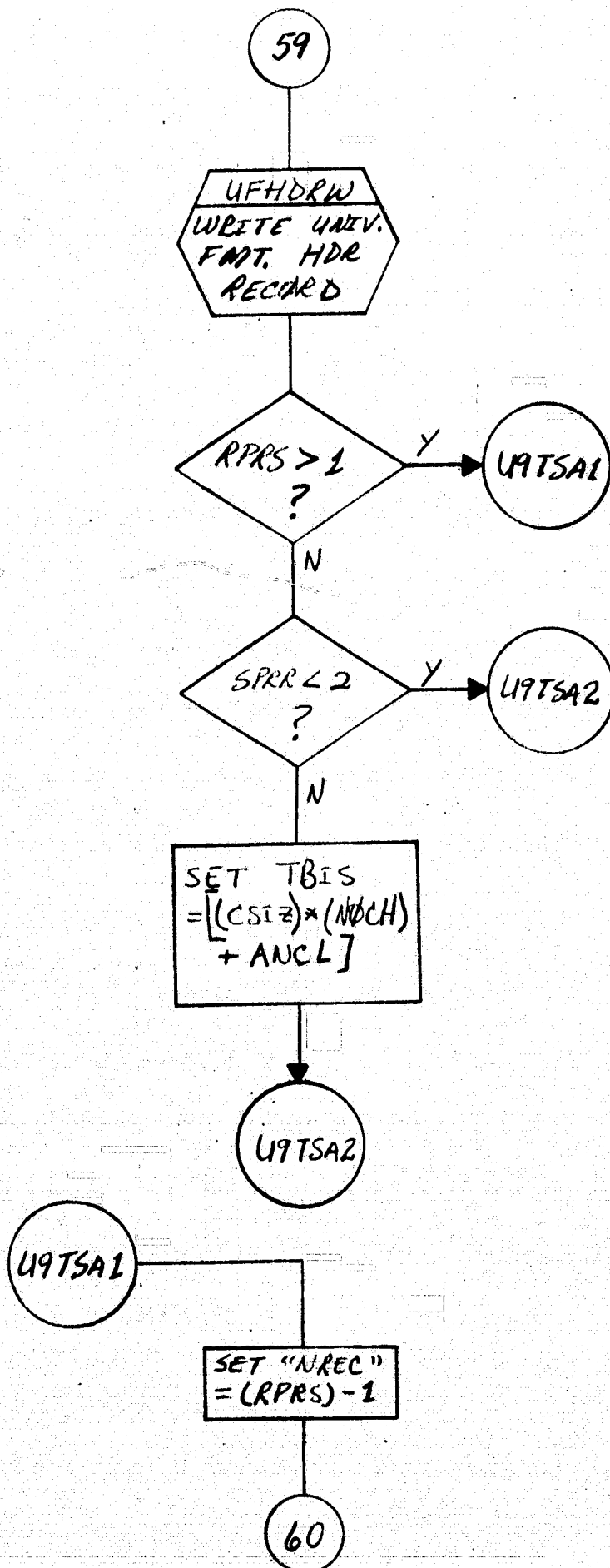


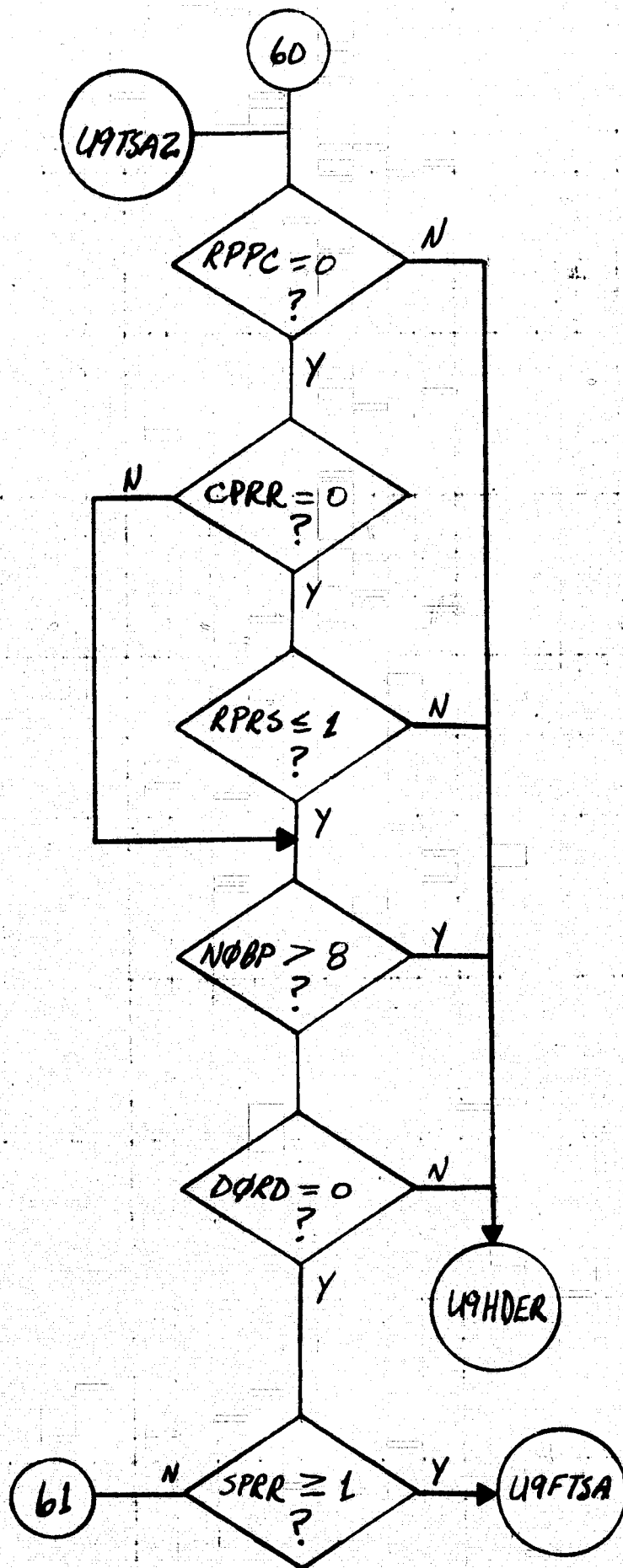


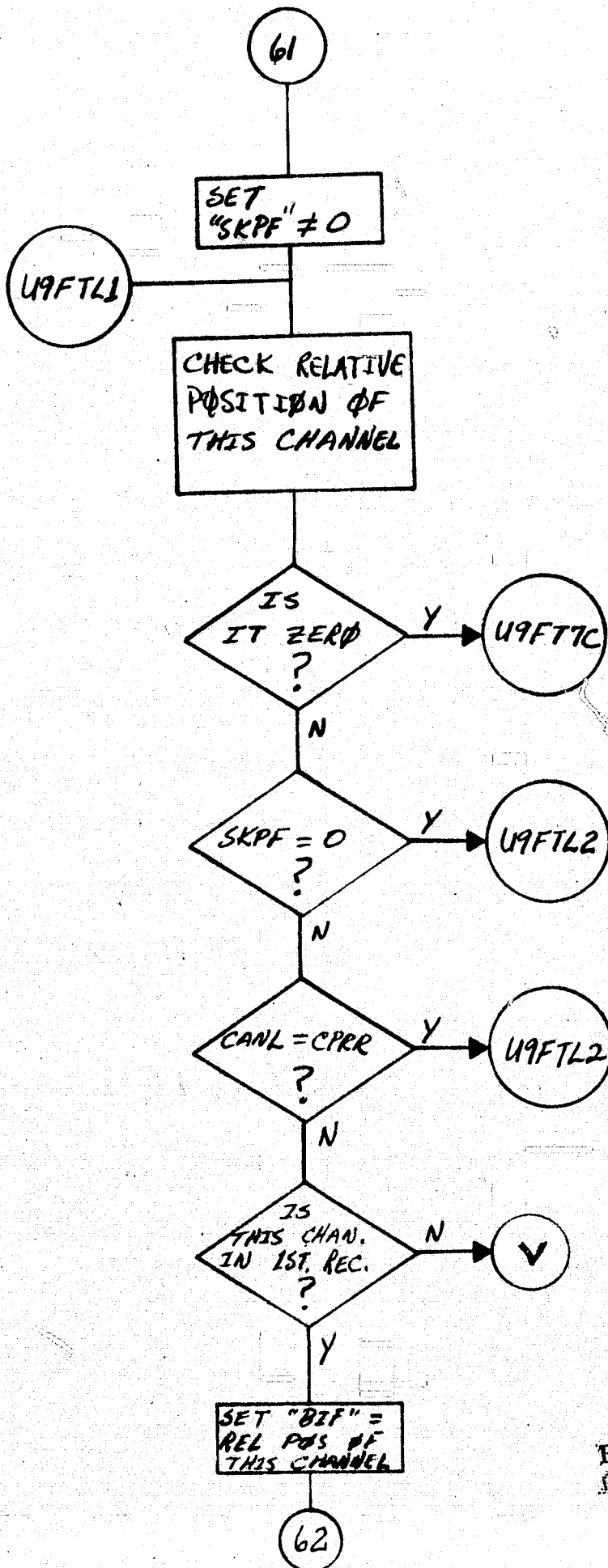
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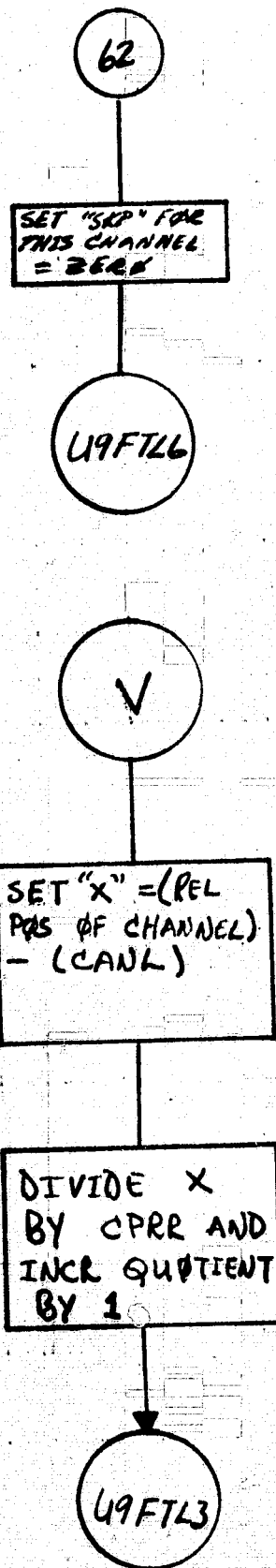


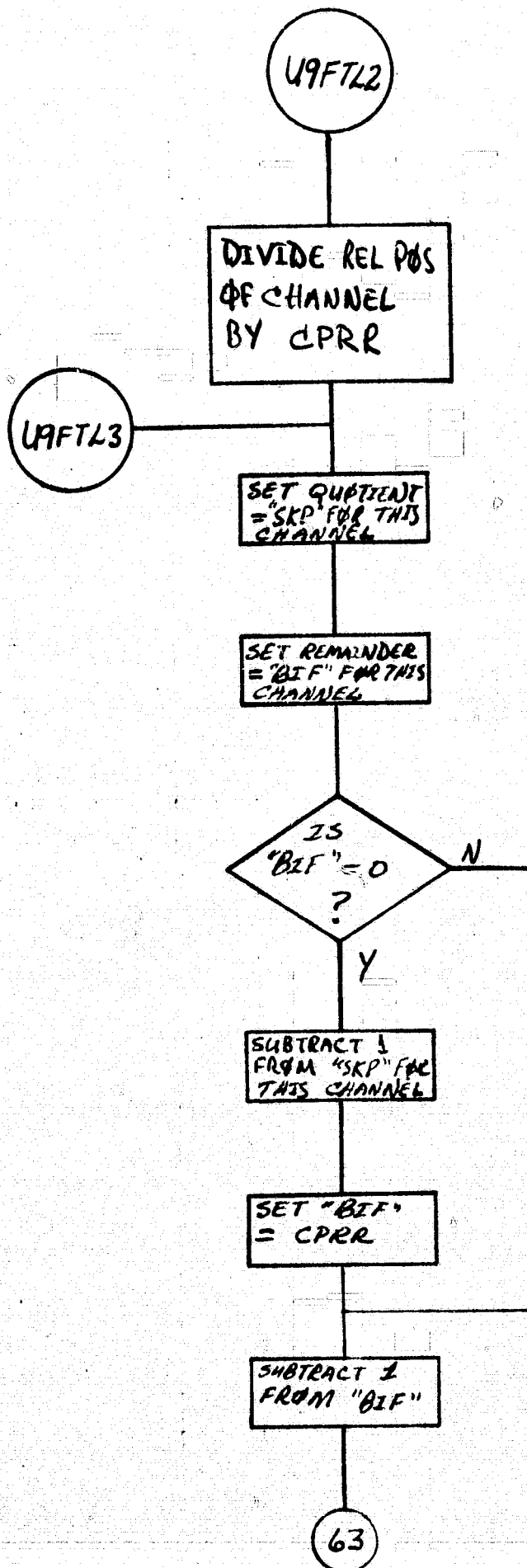


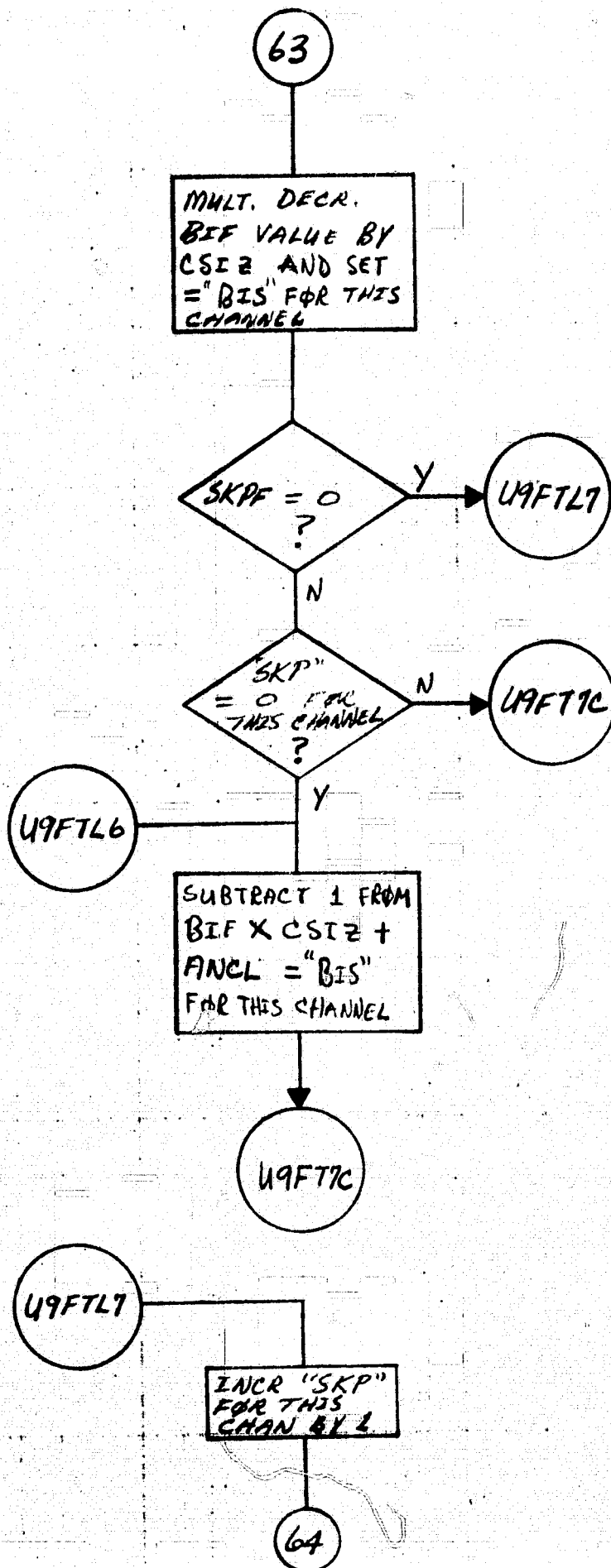


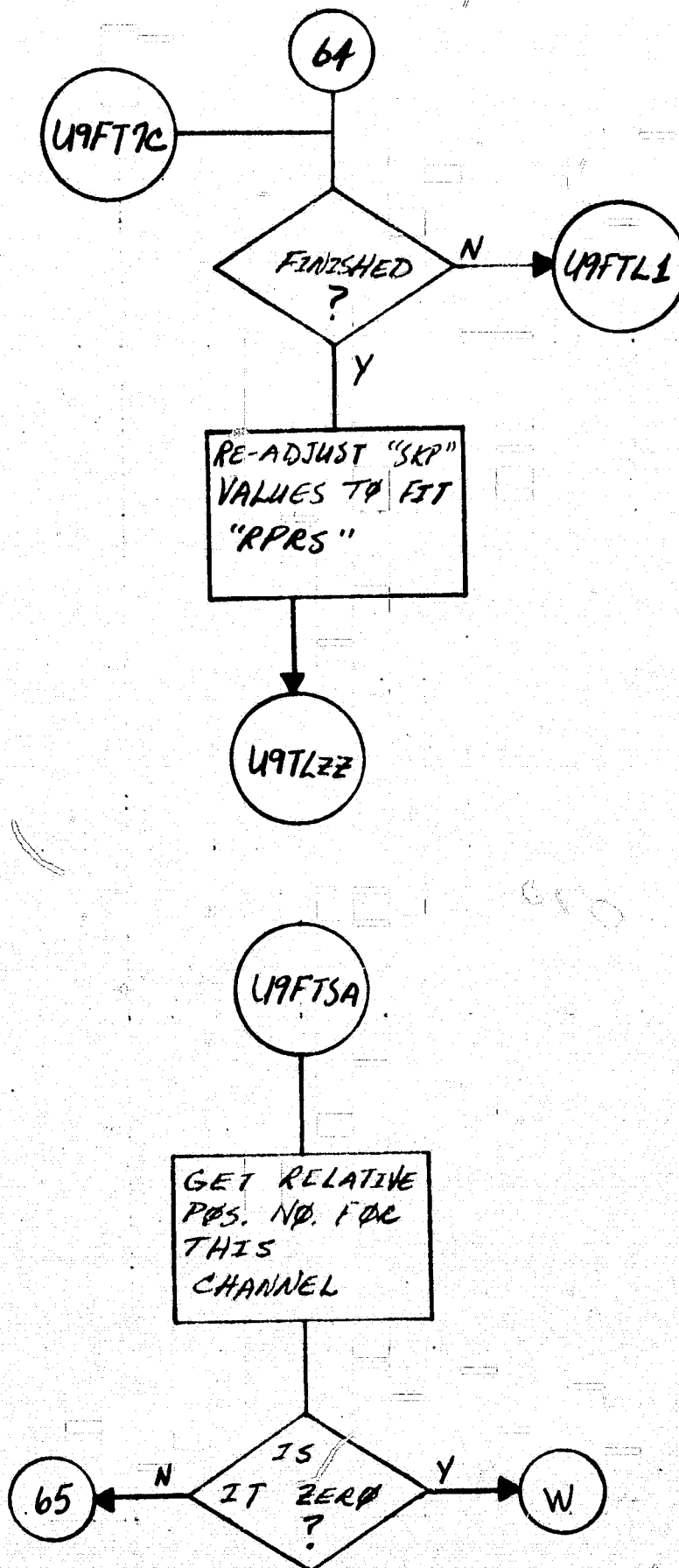


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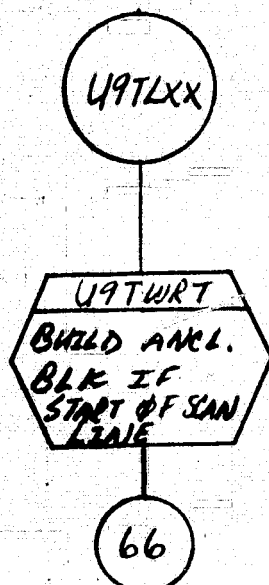
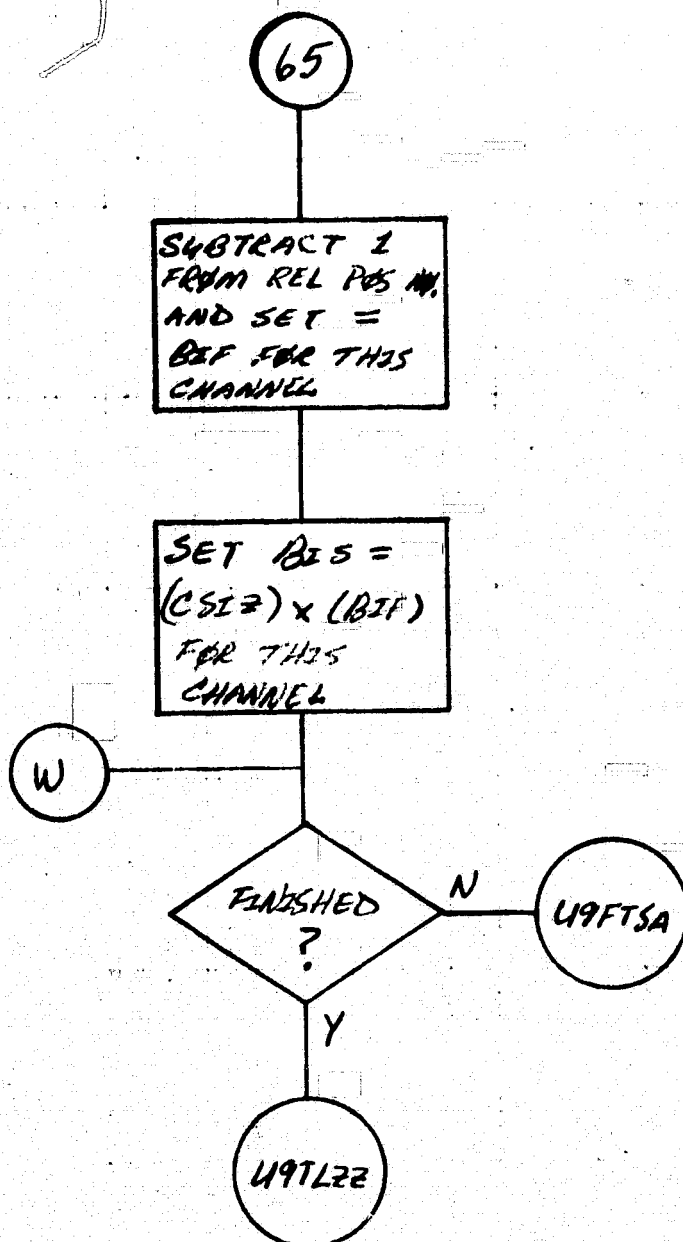


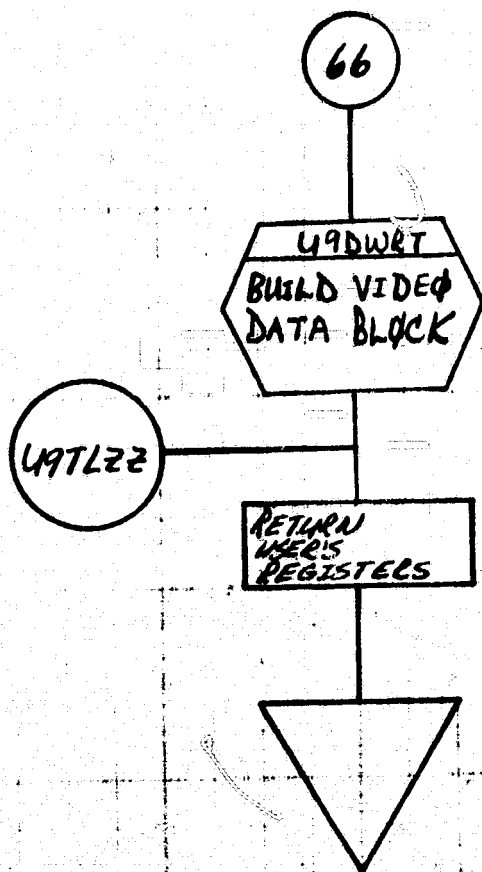






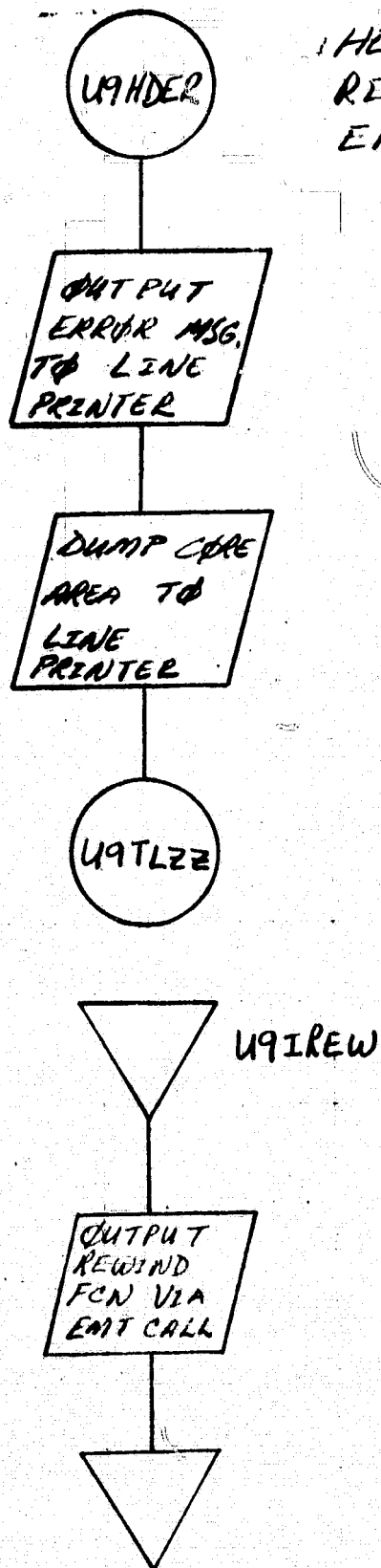
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HEADER
RECORDS
ERROR

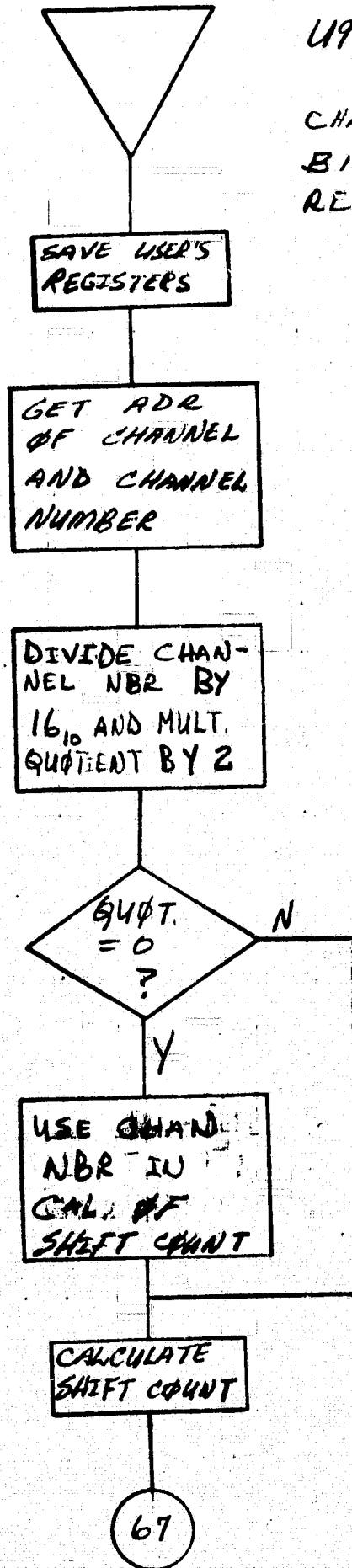
JSC-10019
Part II



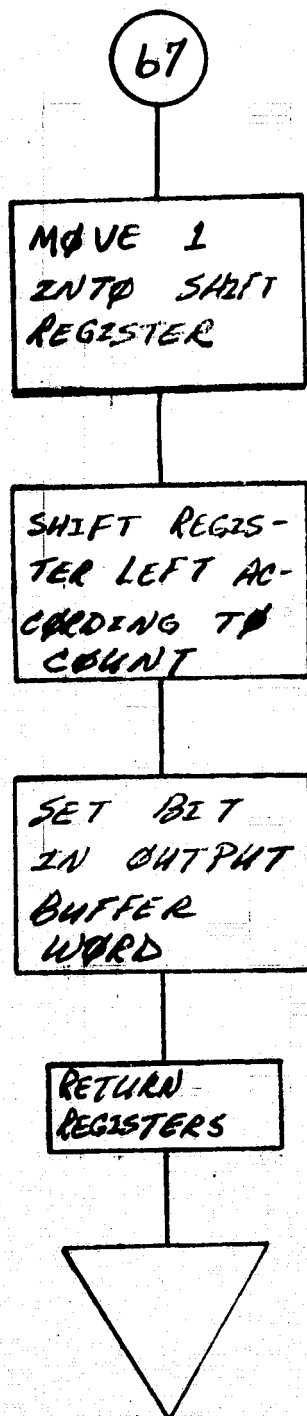
U9CACT

JSC-10019
Part II

CHANNEL ACTIVE
BITS IN HDR
RECORD

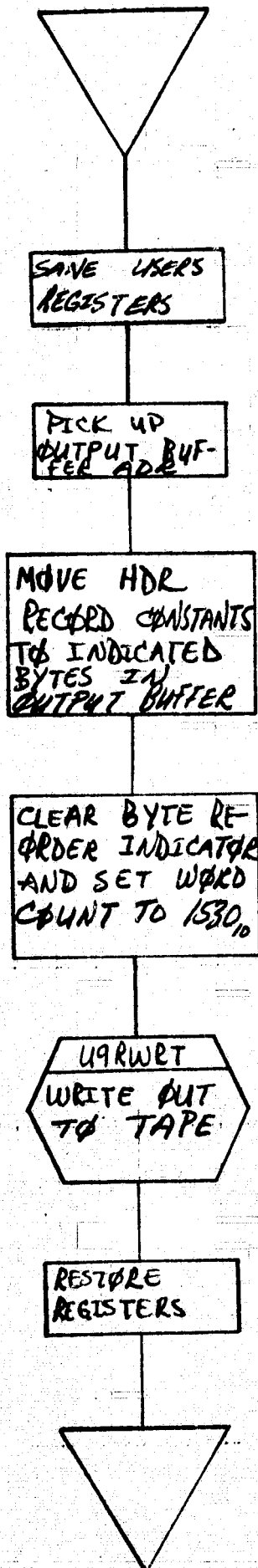


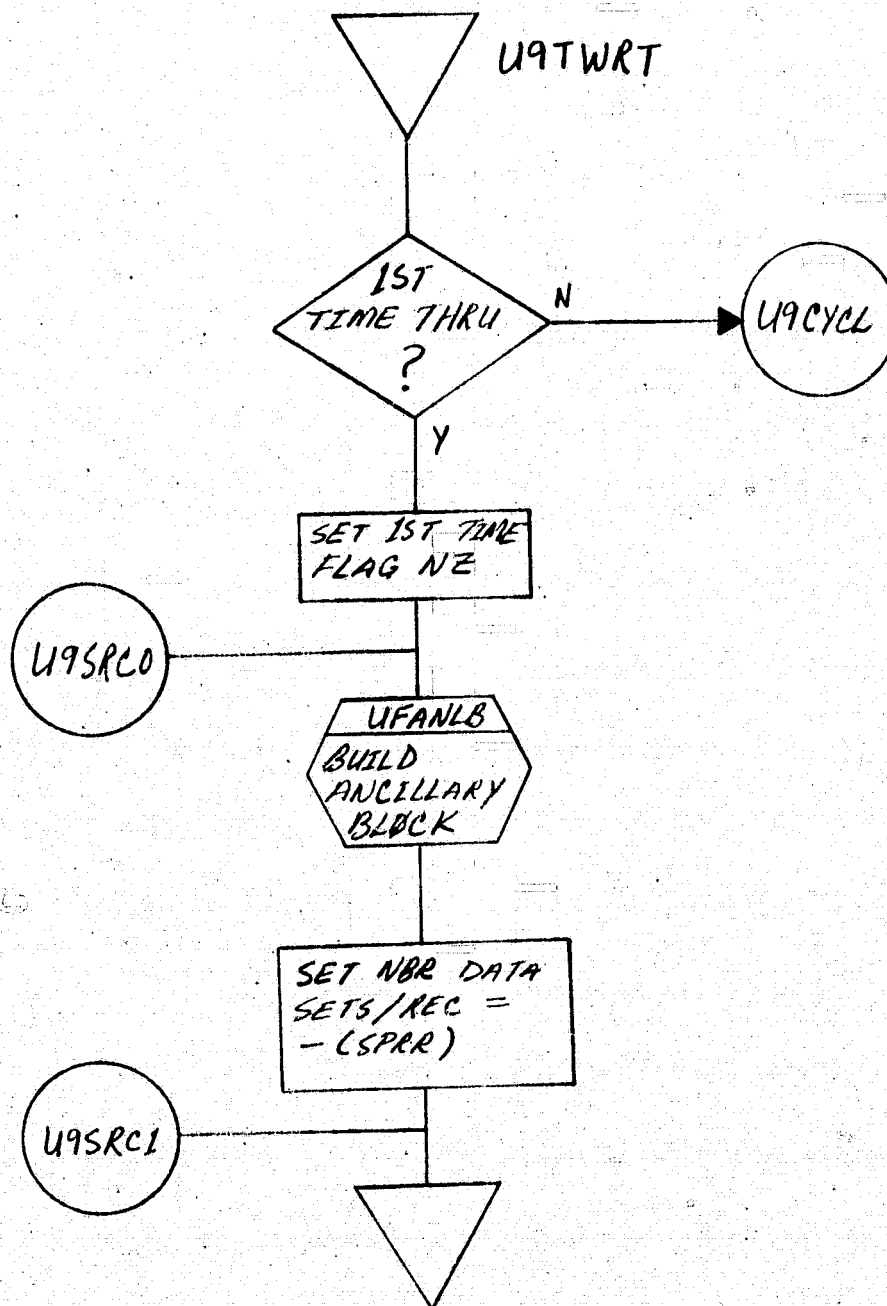
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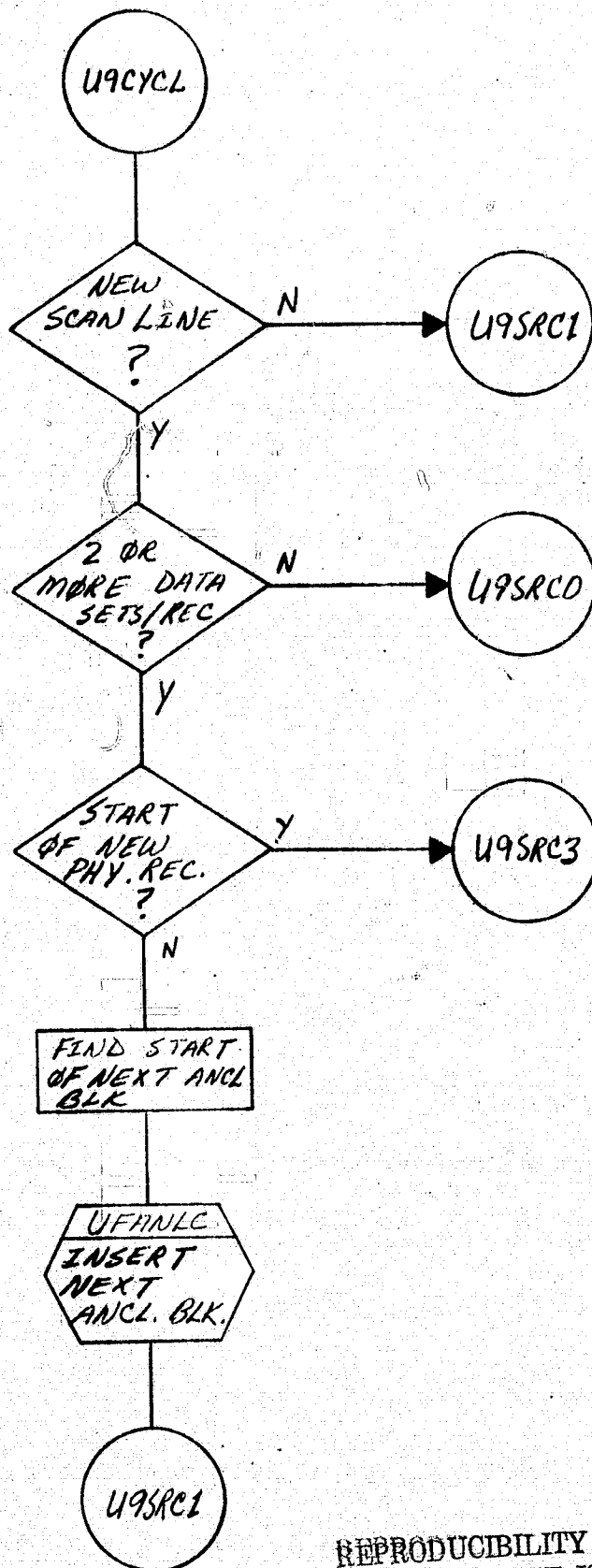


UFHDRW
(UNIV FMT
HDR WRITER)

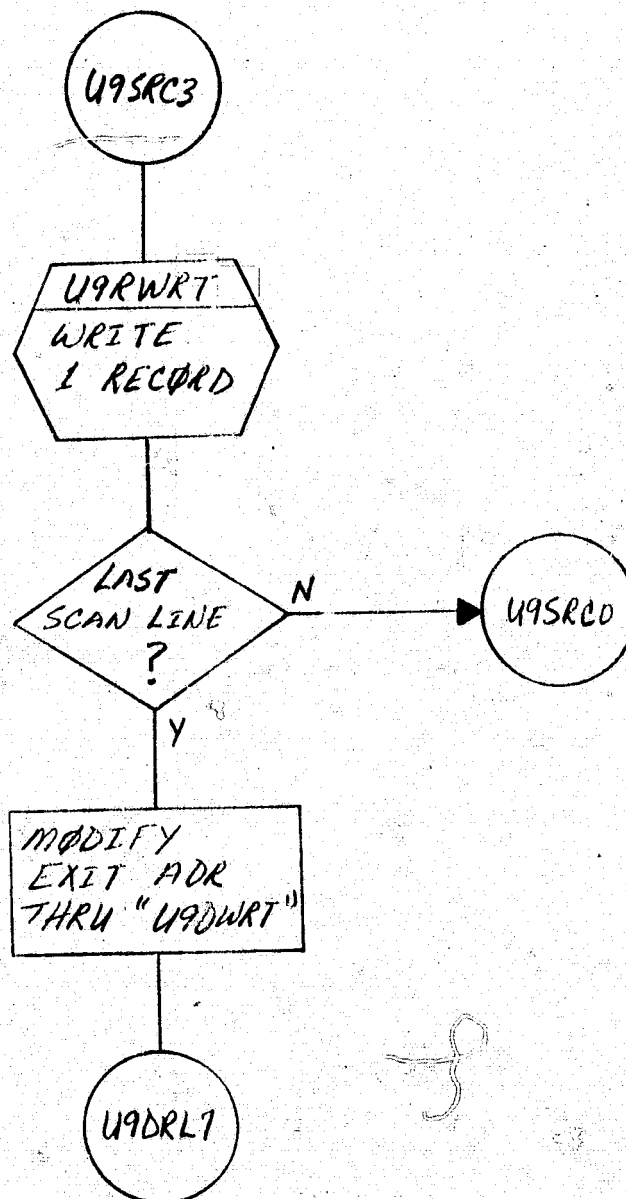
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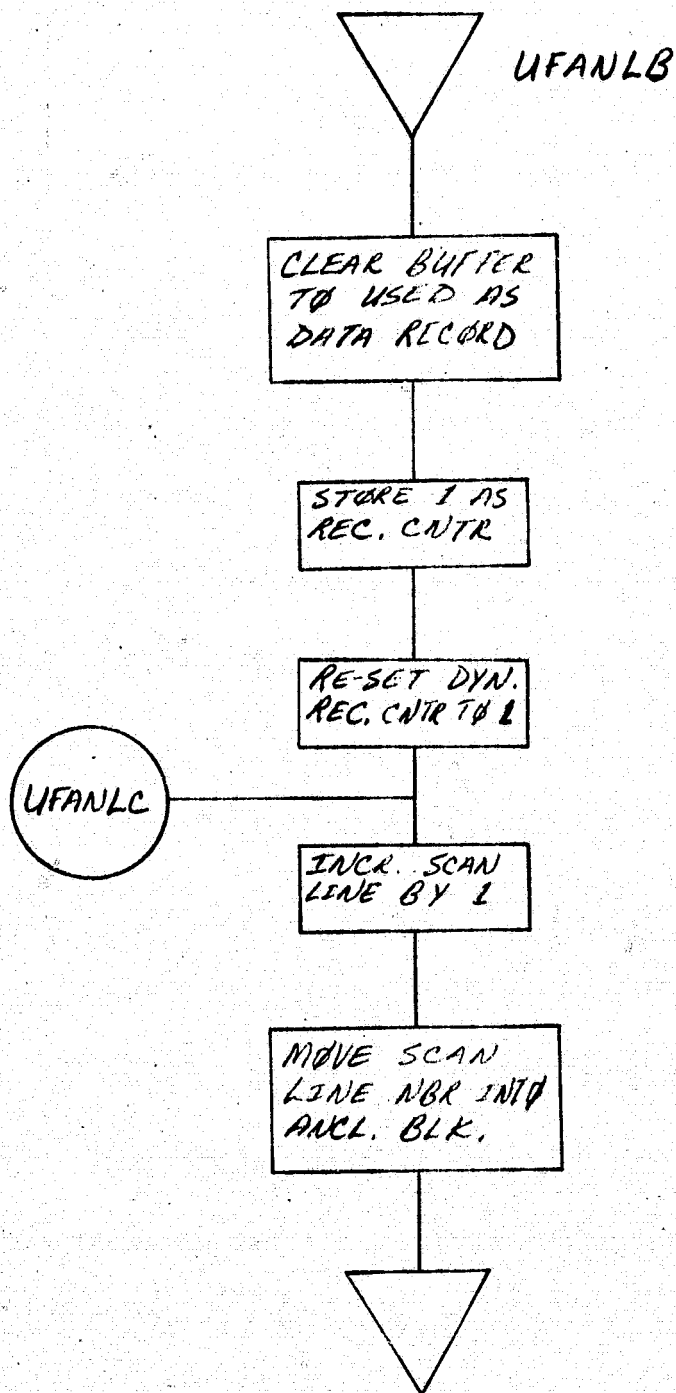


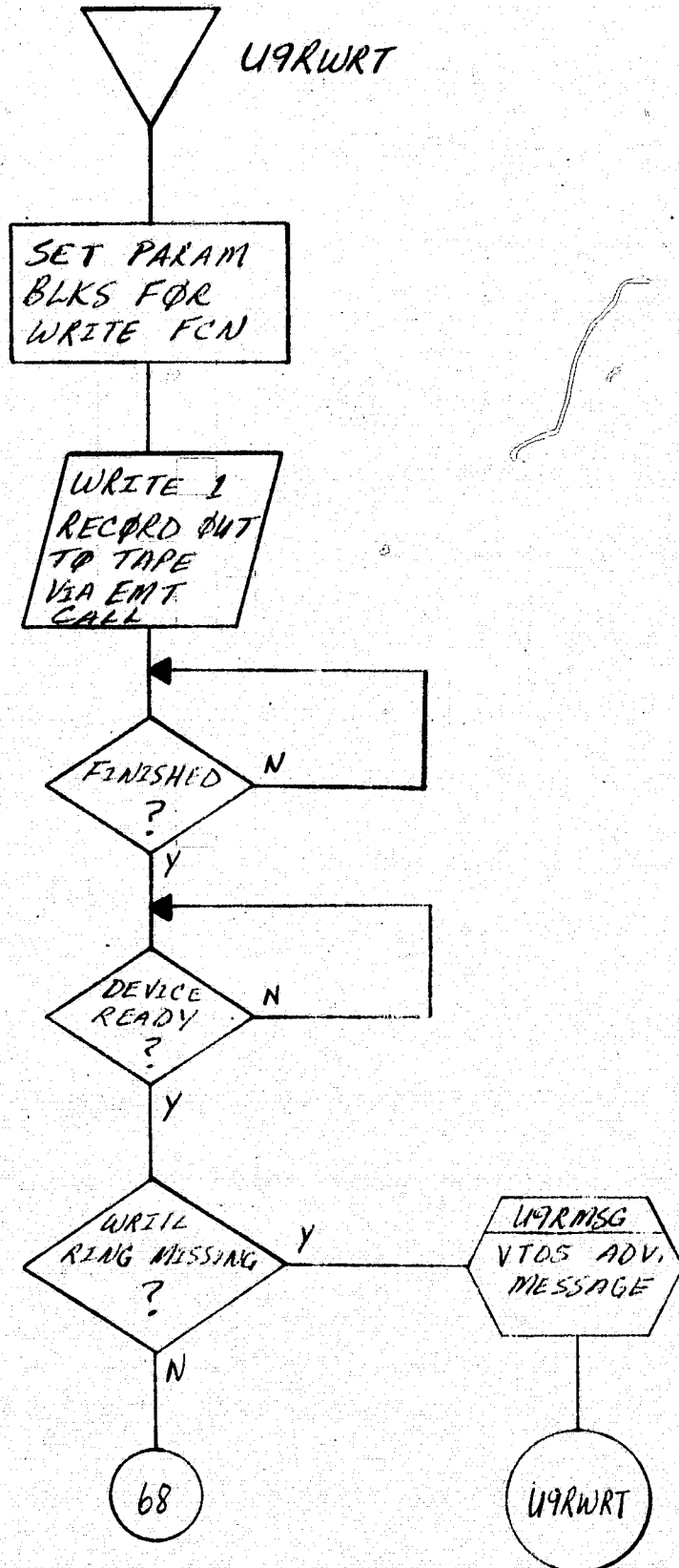


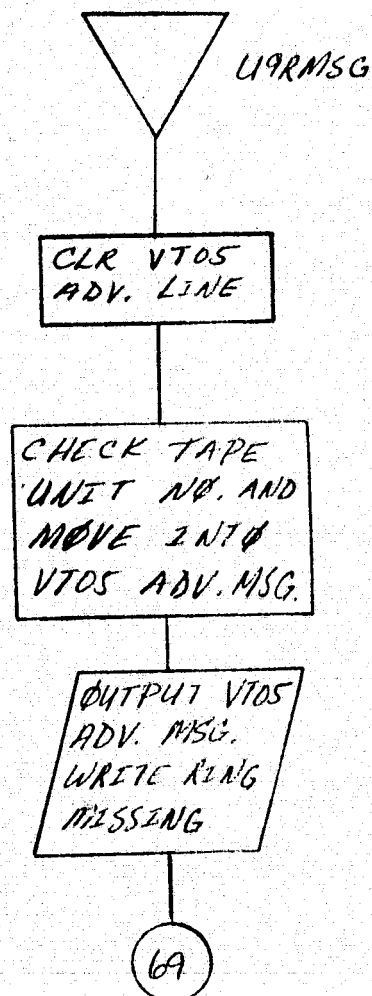
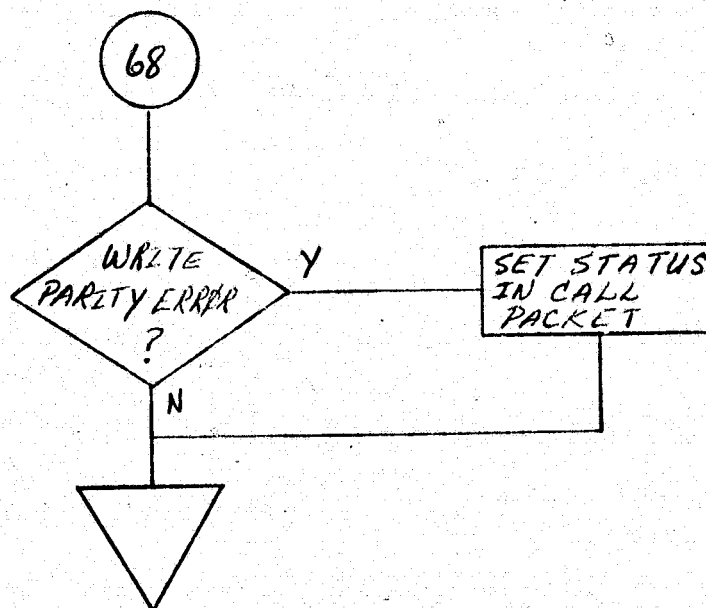


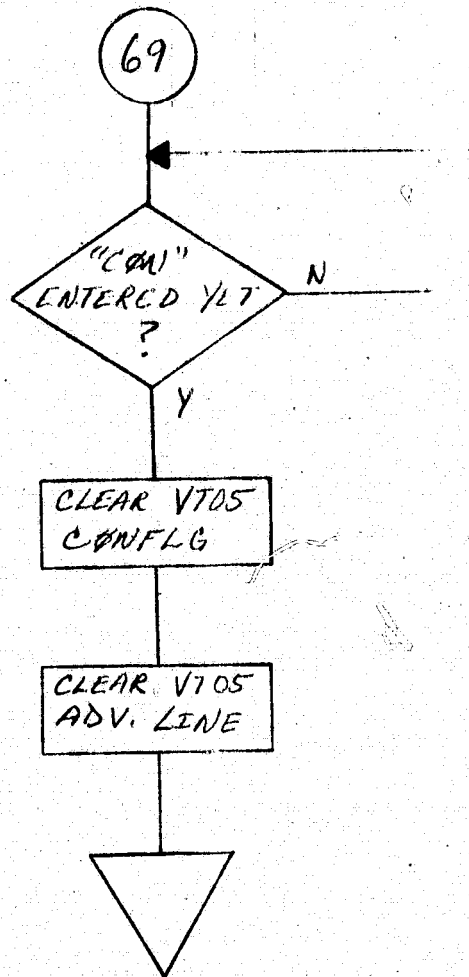
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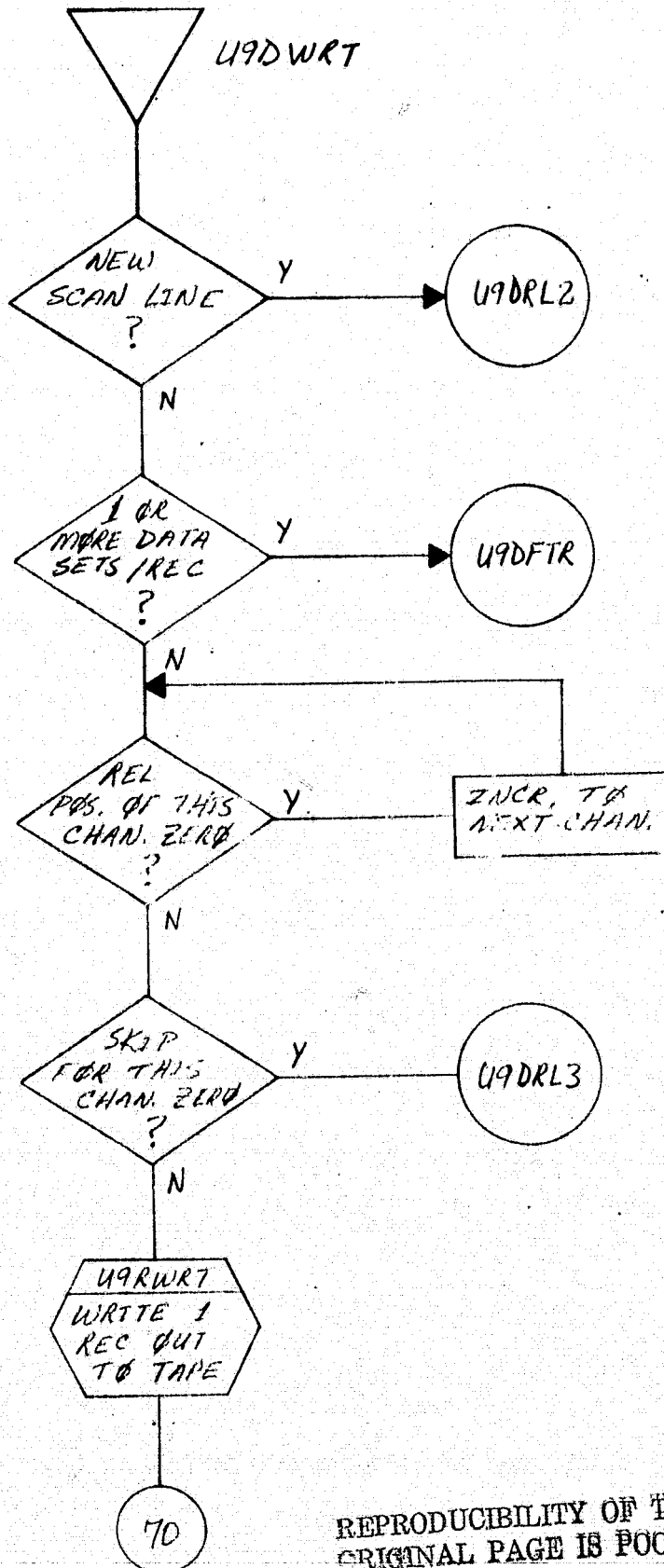




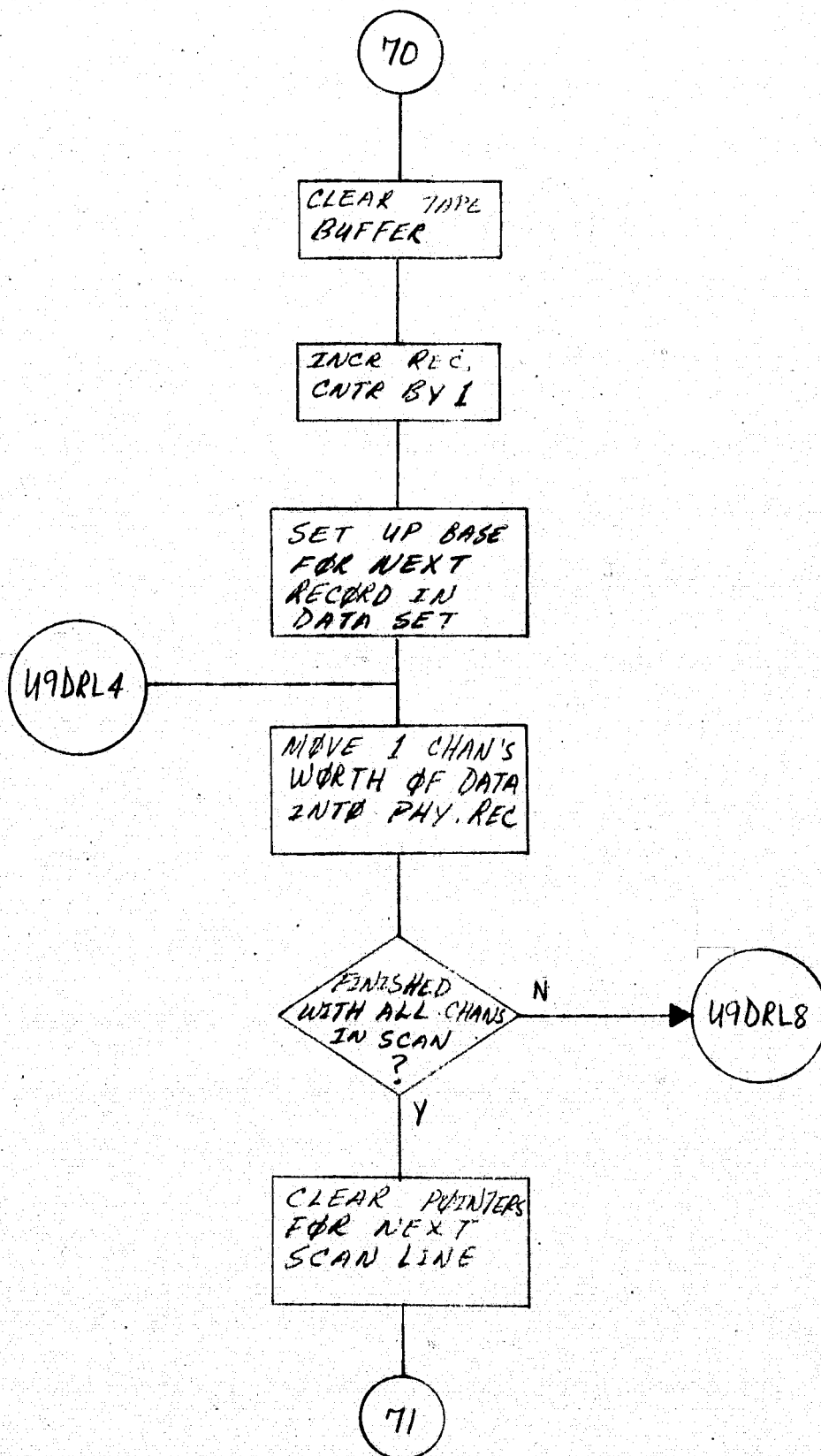


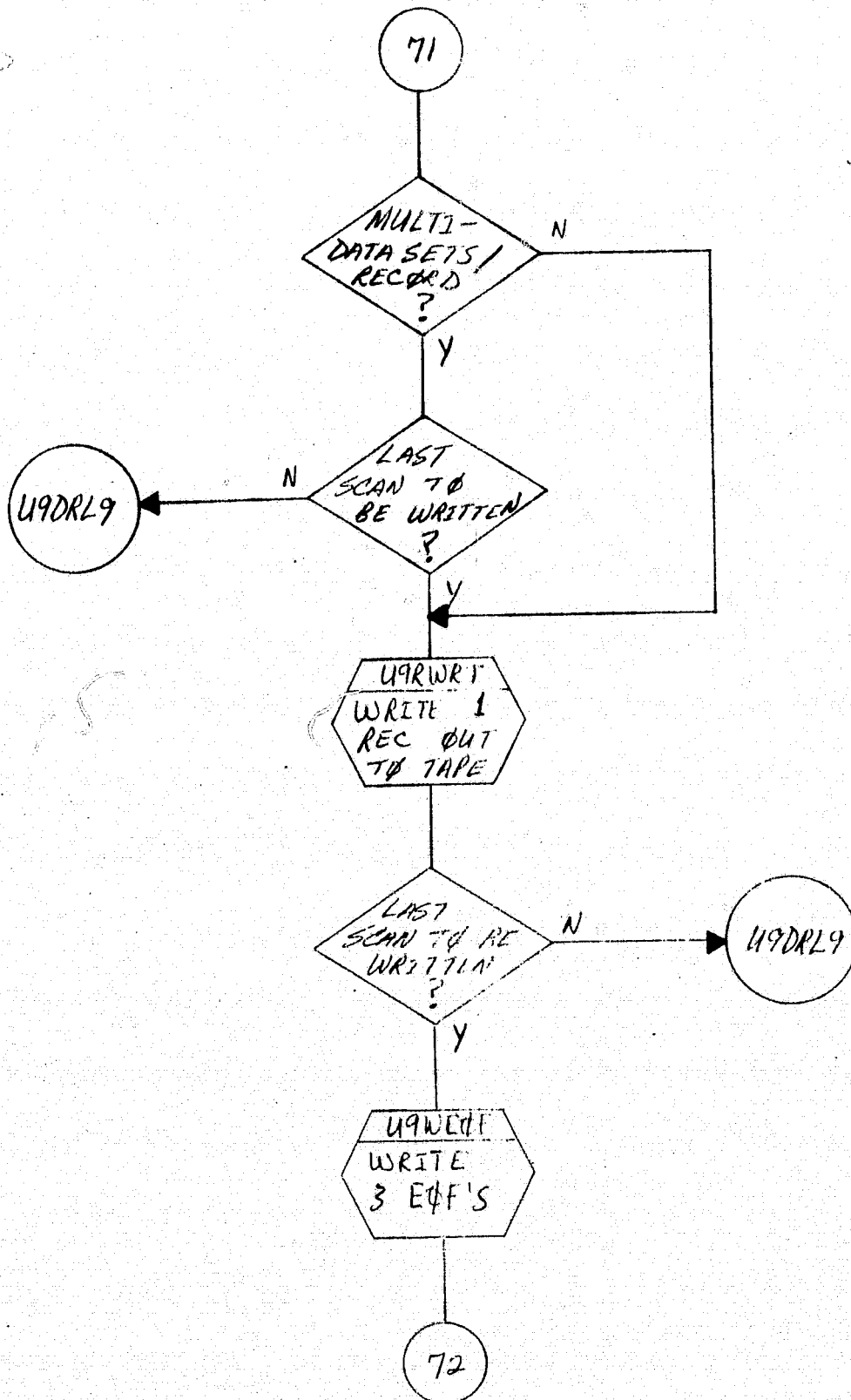


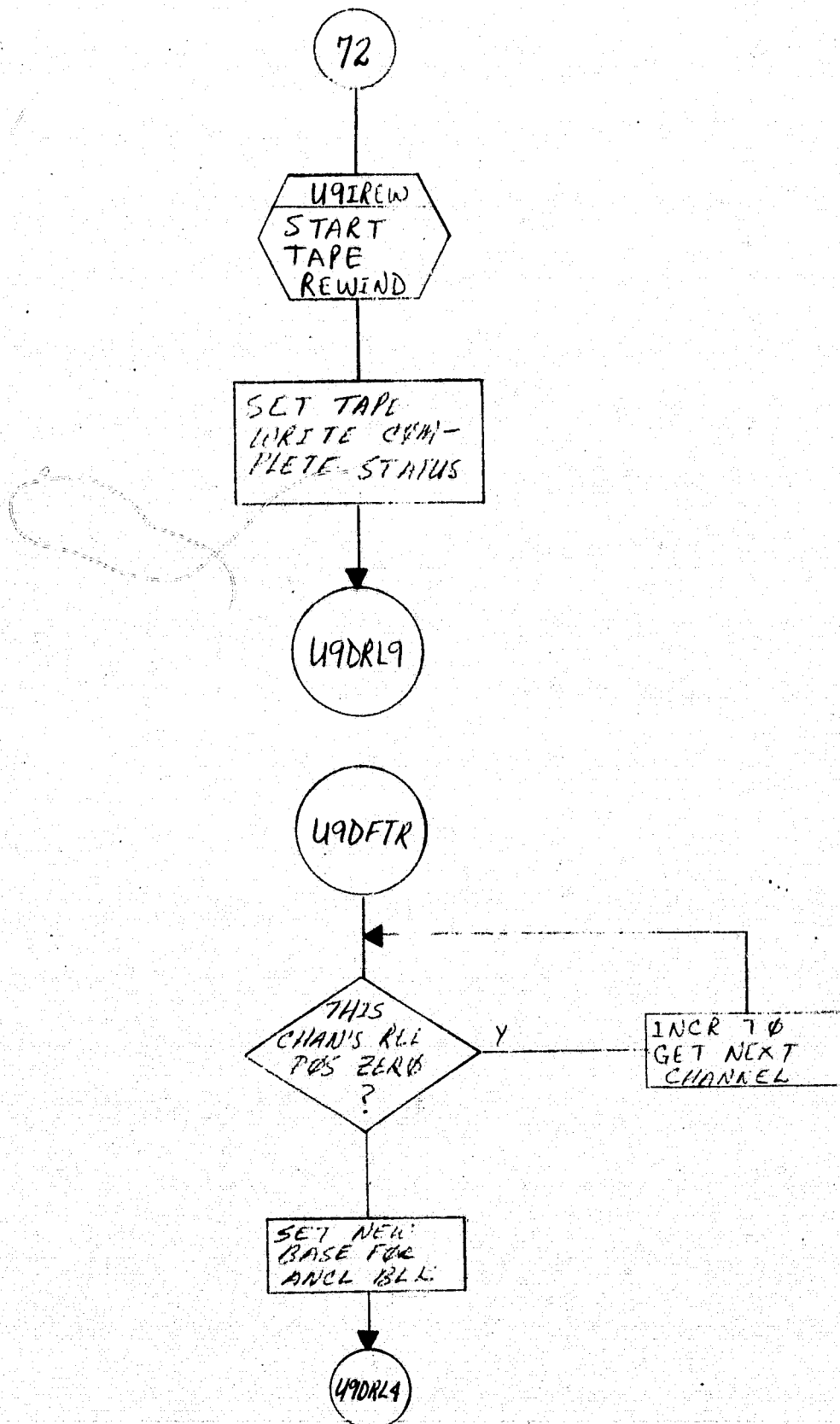


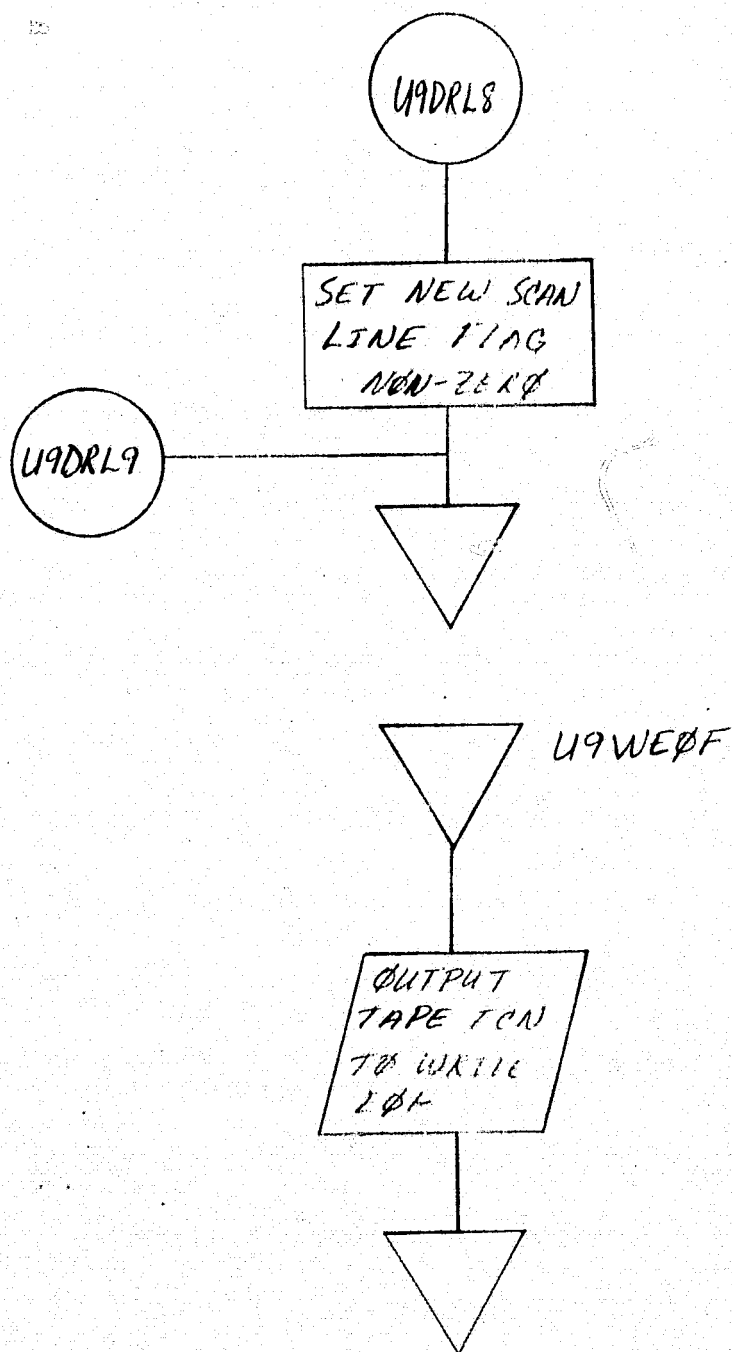


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5.2.3.3 Interfaces. SWPGEN is a set of product generation subroutines for SSP. A similar module containing the same subroutines exists in the registration program (ISOMOD) to build the isothermal products OID and OIN. The Data Base Sequence No. 1 (RAP) module which outputs the ORC products is called RFTGEN. The basic interface of the various product generation subroutines is shown by figure 5-22. One call to the product generation module is made for each scan line. The buffering is set up so that all five images for the ORC products, and the data for generating all eight images of the OWC products, is available for each scan line. The data input to the product generator module (PDGEN) is first converted to a 6-bit color index code and then to the 2:2:2 color format for output to tape and display. The tape formats of the ISO, ORC, and OWC products are illustrated by figures 5-23 thru 5-25, respectively. The isothermal tape formats are blocked in two different ways. The normal-sized image requires one record per scan line totaling 2200 physical records. The compressed image is blocked four scan lines per record for 138 records. The ORC and OWC tape formats require two records per scan line for 1100 records. All tapes are terminated by three end-of-file marks.

The false color tables and growth potential tables used by FCGEN and OWCPRO are 256-place tables containing the 6-bit intermediate color index code. The index code is used to get the final color-formatted 8-bit value (RRGGBBXX) output to the tape and the display. Only OWC images 1-4 require the special additional indexing into the growth potential tables before conversion to the 6-bit color index. Three growth potential or empirical function set tables are used -- STLT, for the STMAT and LTMAT images; CMI, for the LTCMI image; and MPT, for the DDSUM image. The fifth OWC image is a composite of the first four and does not have a separate growth potential table. However, the first five OWC images use the same 256-place color index table called FCNLS1. Eleven separate colors are contained in this table to color code growth potentials of 0.3 to 3.7, as shown in the color bar of figure 5-19. The initial data values (0-255) for each image serve as direct indices into one of the three growth potential tables to get empirical function values (0-255). The data value-to-empirical function value conversion is shown in tables 5-5 through 5-7. Conversion from empirical function set values to a 6-bit color code index is shown in table 5-8 (FCNLS1). The final

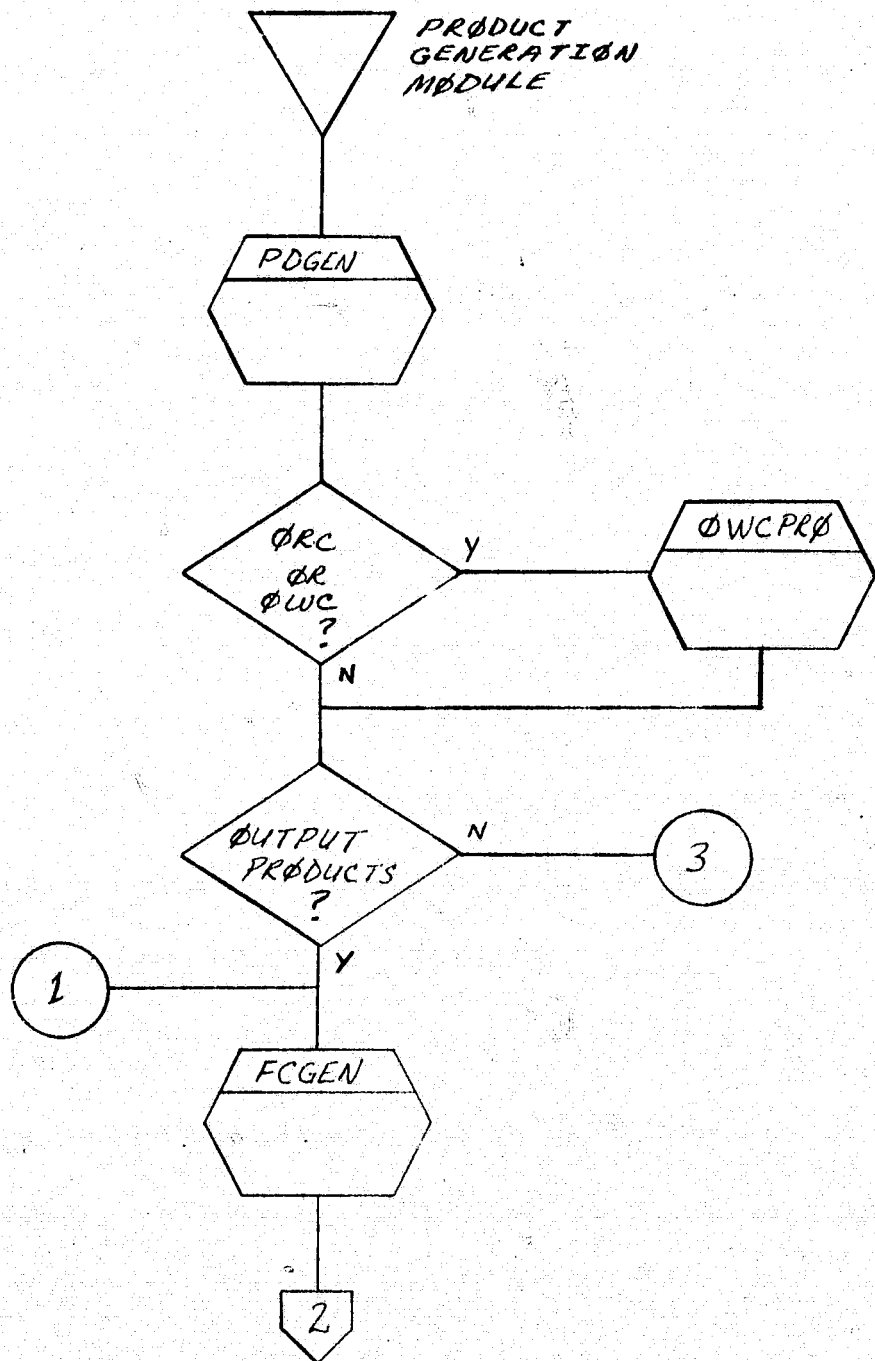
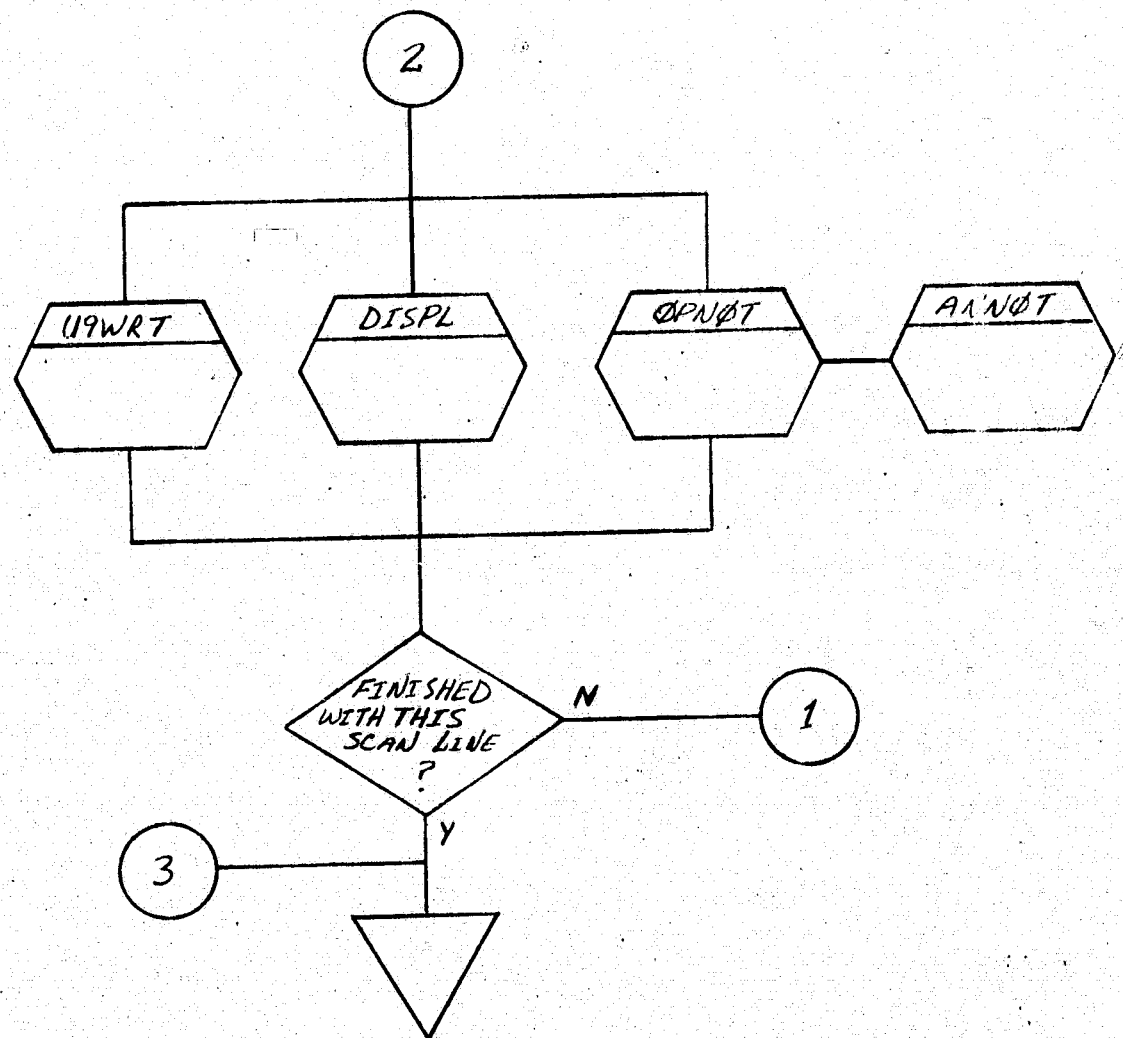


Figure 5-22 Interfaces of Product Generation Subroutines



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ORIGINAL PAGE IS POOR

Figure 5-22 (Cont'd)

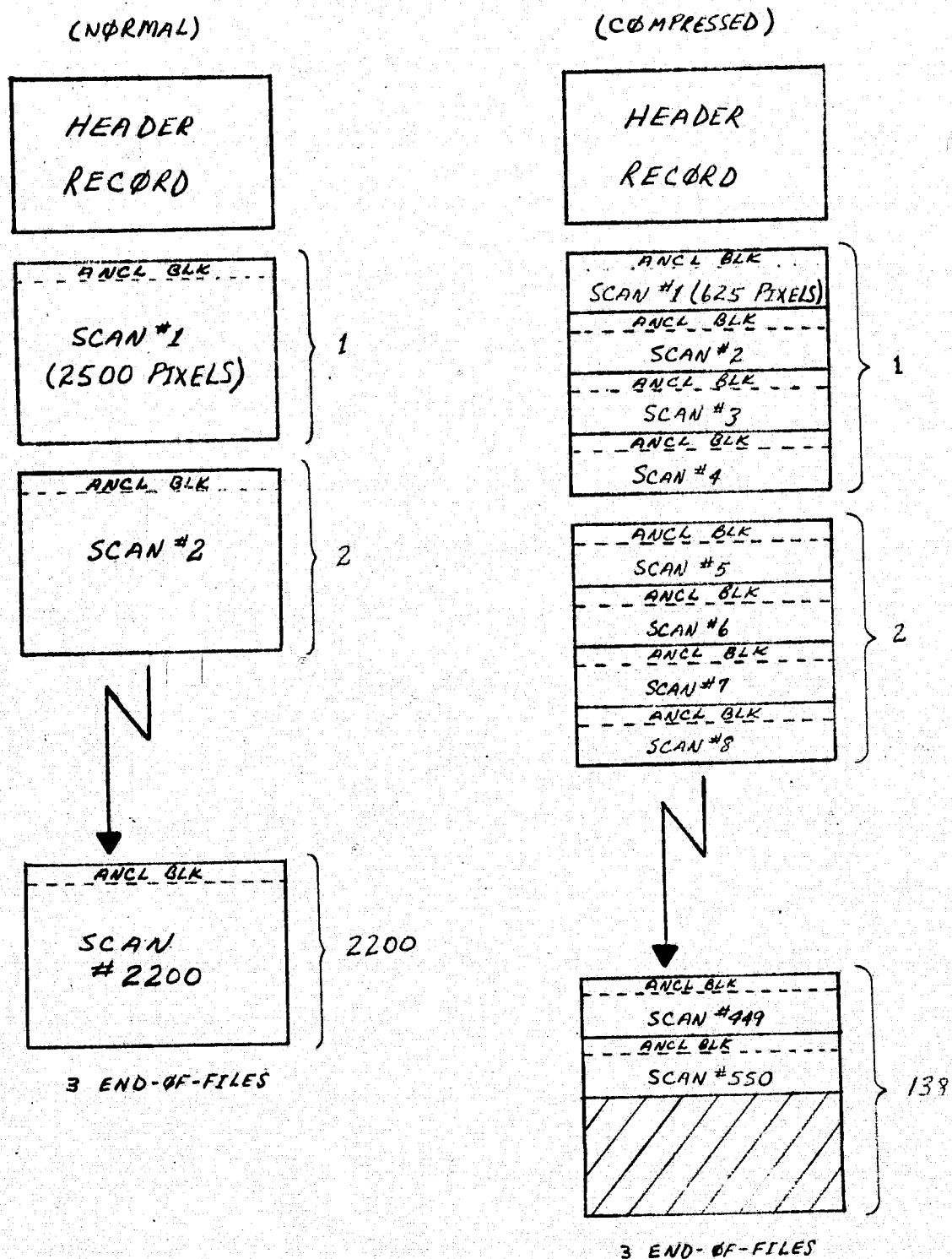


Figure 5-23 Isothermal Tape Formats (OID and OIN)

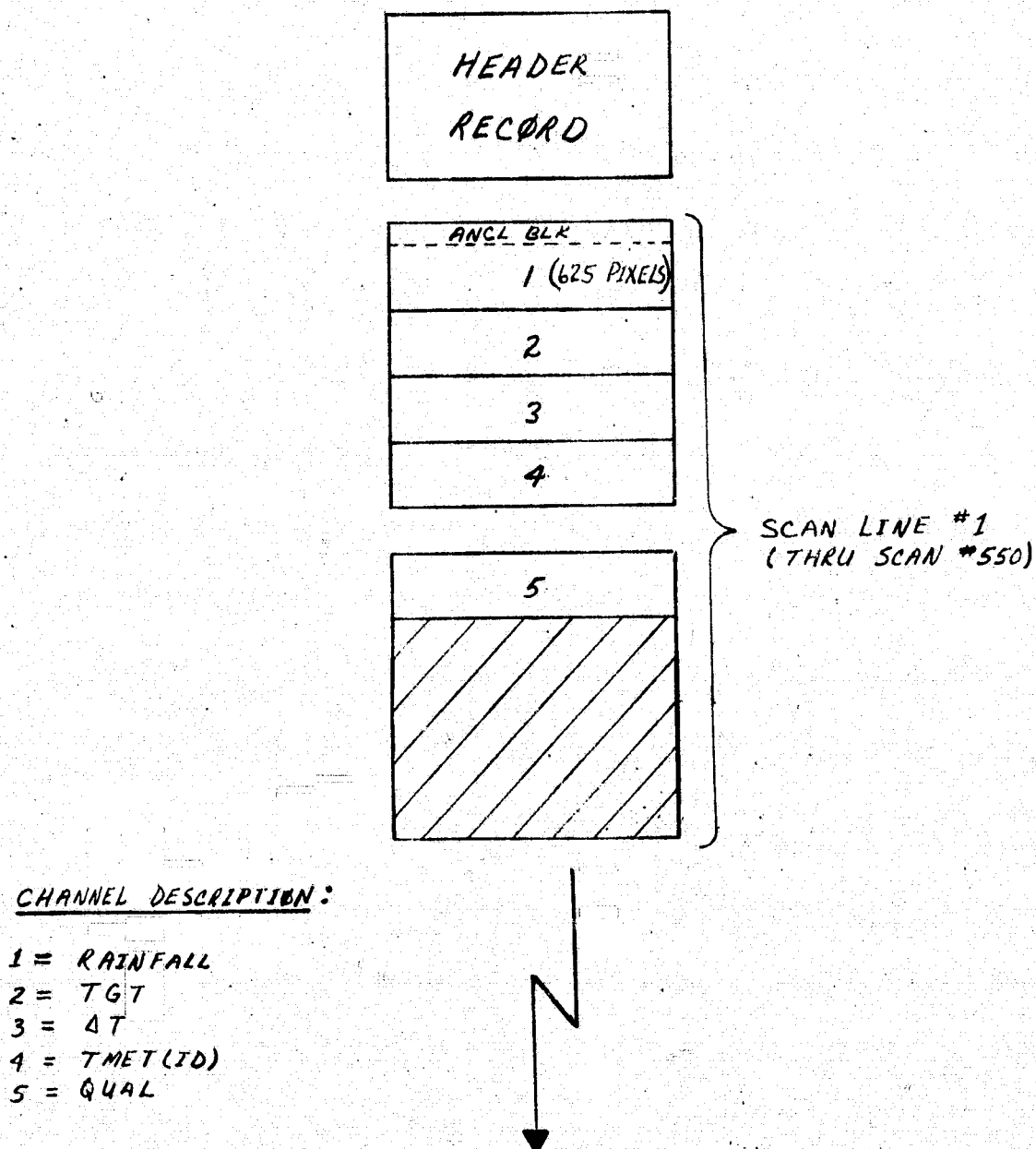


Figure 5-24 RAP Tape Format (ORC)

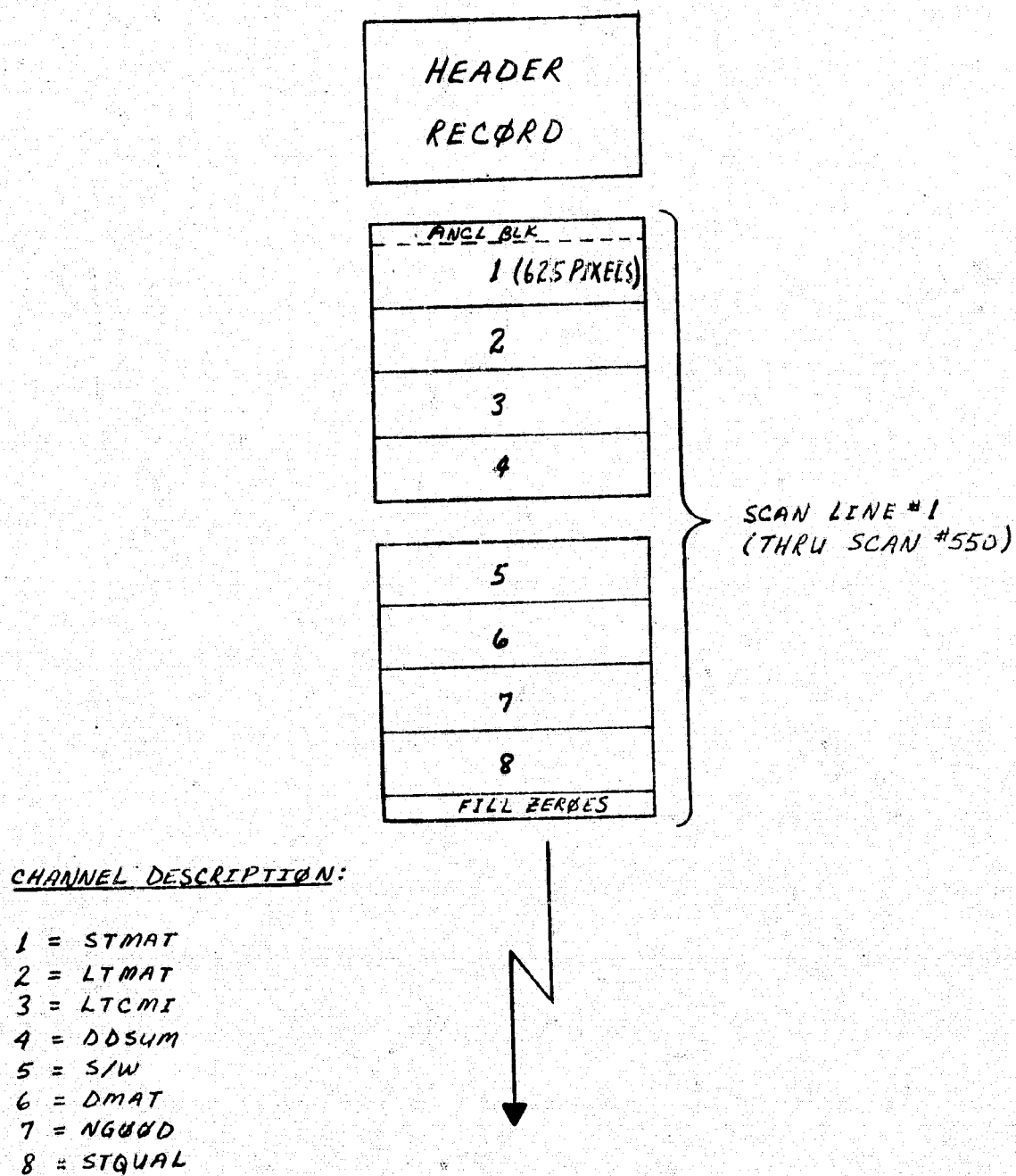


Figure 5-25 SSP Tape Format (OWC)

TABLE 5-5

STMAT & LTMAT DATA TO EMPIRICAL FUNCTION VALUE CONVERSION (STLT)

DATA	EMP FUNC	DATA	EMP FUNC	DATA	EMP FUNC
0-102	0	133	150	168	247
103	4	134	156	169	238
104	8	135	162	170	229
105	16	136	168	171	204
106	23	137	174	172	178
107	30	138	181	173	158
108	36	139	187	174	152
109	42	140	191	175	146
110	48	141	195	176	142
111	52	142	199	177	138
112	55	143	205	178	134
113	59	144	211	179	130
114	64	145	217	180	128
115	68	146	222	181	125
116	73	147	226	182	123
117	77	148	231	183	120
118	83	149	236	184	117
119	88	150	240	185	111
120	91	151	242	186	106
121	95	152	244	187	99
122	98	153	246	188	92
123	103	154	248	189	83
124	108	155	250	190	77
125	114	156	252	191	71
126	119	157	253	192	65
127	124	158	253	193	59
128	128	159	254	194	48
129	133	160	254	195	36
130	139	161-164	255	196	22
131	143	165	253	197	8
132	147	166	252	198	4
		167	250	199-255	0

TABLE 5-6

LTCMI DATA TO EMPIRICAL FUNCTION VALUE CONVERSION (CMI)

DATA	EMP FUNC	DATA	EMP FUNC	DATA	EMP FUNC
0-97	146	130	197	161	214
98-99	147	131	209	162	212
100-101	148	132	215	163	210
102-103	149	133	220	164	207
104-105	150	134	238	165	205
106-107	151	135	243	166	203
108-109	152	136	247	167	201
110-111	153	137	250	168	200
112	154	138	253	169	198
113	155	139-144	255	170	196
114	156	145	252	171	194
115	158	146	249	172	192
116	160	147	246	173	191
117	162	148	243	174	190
118	165	149	241	175	188
119	167	150	239	176	187
120	169	151	237	177	186
121	171	152	234	178	185
122	173	153	231	179	184
123	176	154	228	180	182
124	178	155	225	181	181
125	180	156	223	182	180
126	184	157	221	183	179
127	187	158	219	184-185	178
128	190	159	217	186-188	177
129	194	160	216	189-190	176
				191-255	175

TABLE 5-7

DDSUM DATA TO EMPIRICAL FUNCTION VALUE CONVERSION (MPT)

DATA	EMP FUNC	DATA	EMP FUNC	DATA	EMP FUNC
0-16	57	35	244	54	149
17	63	36	255	55	139
18	69	37	254	56	128
19	75	38	253	57	119
20	81	39	251	58	110
21	90	40	250	59	101
22	99	41	244	60	92
23	108	42	238	61	88
24	117	43	232	62	84
25	126	44	227	63	80
26	135	45	221	64	77
27	144	46	215	65	75
28	154	47	209	66	73
29	168	48	202	67	71
30	182	49	194	68	68
31	196	50	186	69	65
32	211	51	178	70	62
33	222	52	169	71	60
34	233	53	159	72-255	59

TABLE 5-8
EMPIRICAL FUNCTION TO COLOR CODE INDEX VALUE CONVERSION (FCNLS1)

EMP. FUNC	COLOR INDEX (OCTAL)	COLOR BAR NO.
0-17	61	1
18-88	65	2
89-128	21	3
129-157	05	4
158-179	03	5
180-197	57	6
198-213	16	7
214-226	15	8
227-238	04	9
239-248	10	10
249-255	14	11

color conversion for all products occurs by using the 64-place table FCTCVT (see table 5-9) to get the 8-bit color formatted value for output to tape and display.

The sixth image product of the OWC tape (DMAT) and the ORC products No. 2 and No. 4 (TGT and TMET) use the same 256-place color index table, DMFCT, as shown in table 5-10. FTCNGD is the color conversion table used by the seventh OWC image (see table 5-11). The eighth OWC image is color-coded according to STQFCT (see table 5-12). ORC product image No. 3 is DELTA T and uses color conversion table DLTFCT, as shown in table 5-13. ORC product images No. 1 and No. 5 (RAINFALL and QUAL) are color-coded according to the color bars shown in figure 5-18. The color index code is entered at the time of product calculation.

The two isothermal images OID and OIN use two separate 256-place color index tables, as shown in tables 5-14 and 5-15, respectively.

5.2.3.4 Data Organization. The principal internally defined items of the product generator module are those associated with the VT05 display (see figure 5-13 for layout). A list of VT05 variable fields with initialized conditions is shown for the OWC products in table 5-16. The annotation characters output on the lower portion of the SEDS images (see figure 5-21) use a dot matrix table called DMTB. The characters are built in ANNOT from the input ASCII character string, which is specified as one of the three parameters in the call packet. DMTB is indexed using a 6-bit truncated ASCII value. The ASCII characters in the table are in groups of three, with each group requiring seven words. An internal counter keeps track of which line is being generated for a given character. In the binary expansion of the octal words, black is stored for a zero and white is stored for a one. Scroll direction on the screen (i.e., top to bottom or bottom to top) determines whether or not word 1 or word 7 of the three-character group is picked up first. Table 5-17 details the contents of the octal words in DMTB, and figure 5-26 shows the binary expansion of a three-character group and the algorithm to generate the characters. DMTB contains 154 entries or 22 three-character groups, with each group containing seven words ($7 \times 22 = 154$). Each group of three characters is numbered from 0 to 21. To locate a given character's 5×7 dot matrix equivalence, first

TABLE 5-9
FINAL COLOR CONVERSION (FCTCVT)

COLOR INDEX (OCTAL)	COLOR BYTE (OCTAL)	BINARY								COLOR DESCRIPTION
		R	R	G	G	B	B	O	O	
0	000	0	0	0	0	0	0	0	0	BLACK
1	020	0	0	0	1	0	0	0	0	DARK GREEN
2	040	0	0	1	0	0	0	0	0	MED GREEN
3	060	0	0	1	1	0	0	0	0	GREEN
4	100	0	1	0	0	0	0	0	0	DARK RED
5	120	0	1	0	1	0	0	0	0	DARK YELLOW
6	140	0	1	1	0	0	0	0	0	
7	160	0	1	1	1	0	0	0	0	
10	200	1	0	0	0	0	0	0	0	MED RED
11	220	1	0	0	1	0	0	0	0	
12	240	1	0	1	0	0	0	0	0	MED YELLOW
13	260	1	0	1	1	0	0	0	0	
14	300	1	1	0	0	0	0	0	0	RED
15	320	1	1	0	1	0	0	0	0	
16	340	1	1	1	0	0	0	0	0	
17	360	1	1	1	1	0	0	0	0	YELLOW
20	004	0	0	0	0	0	1	0	0	DARK BLUE
21	024	0	0	0	1	0	1	0	0	DARK CYAN
22	044	0	0	1	0	0	1	0	0	
23	064	0	0	1	1	0	1	0	0	
24	104	0	1	0	0	0	1	0	0	DARK MAGENTA
25	124	0	1	0	1	0	1	0	0	GREY
26	144	0	1	1	0	0	1	0	0	
27	164	0	1	1	1	0	1	0	0	
30	204	1	0	0	0	0	1	0	0	
31	224	1	0	0	1	0	1	0	0	
32	244	1	0	1	0	0	1	0	0	
33	264	1	0	1	1	0	1	0	0	
34	304	1	1	0	0	0	1	0	0	
35	324	1	1	0	1	0	1	0	0	

TABLE 5-9 (CONT'D)

COLOR INDEX (OCTAL)	COLOR BYTE (OCTAL)	BINARY								COLOR DESCRIPTION
		R	R	G	G	B	B	0	0	
36	344	1	1	1	0	0	1	0	0	MED BLUE
37	364	1	1	1	1	0	1	0	0	
40	010	0	0	0	0	1	0	0	0	
41	030	0	0	0	1	1	0	0	0	
42	050	0	0	1	0	1	0	0	0	MED CYAN
43	070	0	0	1	1	1	0	0	0	
44	110	0	1	0	0	1	0	0	0	
45	130	0	1	0	1	1	0	0	0	
46	150	0	1	1	0	1	0	0	0	MED MAGENTA
47	170	0	1	1	1	1	0	0	0	
50	210	1	0	0	0	1	0	0	0	
51	230	1	0	0	1	1	0	0	0	
52	250	1	0	1	0	1	0	0	0	MED GREY
53	270	1	0	1	1	1	0	0	0	
54	310	1	1	0	0	1	0	0	0	
55	330	1	1	0	1	1	0	0	0	
56	350	1	1	1	0	1	0	0	0	BLUE
57	370	1	1	1	1	1	0	0	0	
60	014	0	0	0	0	1	1	0	0	
61	034	0	0	0	1	1	1	0	0	
62	054	0	0	1	0	1	1	0	0	CYAN
63	074	0	0	1	1	1	1	0	0	
64	114	0	1	0	0	1	1	0	0	
65	134	0	1	0	1	1	1	0	0	
66	154	0	1	1	0	1	1	0	0	
67	174	0	1	1	1	1	1	0	0	
70	214	1	0	0	0	1	1	0	0	
71	234	1	0	0	1	1	1	0	0	
72	254	1	0	1	0	1	1	0	0	
73	274	1	0	1	1	1	1	0	0	

TABLE 5-9 (CONT'D)

COLOR INDEX (OCTAL)	COLOR BYTE (OCTAL)	BINARY								COLOR DESCRIPTION
		R	R	G	G	B	B	O	O	
74	314	1	1	0	0	1	1	0	0	MAGENTA
75	334	1	1	0	1	1	1	0	0	
76	354	1	1	1	0	1	1	0	0	
77	374	1	1	1	1	1	1	0	0	WHITE

TABLE 5-10
DMAT, TGT, AND TMET* COLOR CONVERSION (DMFCT)

DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.	DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.
0-40	00	1	141-144	41	15
41-52	04	2	145-148	21	16
53-64	10	3	149-152	23	17
65-76	14	4	153-156	03	18
77-88	34	5	157-160	02	19
89-100	74	6	161-164	01	20
101-112	64	7	165-168	07	21
113-116	24	8	169-172	13	22
117-120	20	9	173-180	17	23
121-124	40	10	181-188	15	24
125-128	60	11	189-196	11	25
129-132	62	12	197-204	25	26
133-136	63	13	205-212	52	27
137-140	67	14	213-255	77	28

*DMAT - OWC PRODUCT NO. 6
TGT - ORC PRODUCT No. 2
TMET - ORC PRODUCT No. 4

TABLE 5-11
NGOOD* COLOR CONVERSION (FCTNGD)

NO. OF DAYS (DATA)	COLOR INDEX (OCTAL)	COLOR BAR NO.
0	00	
1	14	1
2	74	2
3	24	3
4	60	4
5	67	5
6	23	6
7	03	7
8	01	8
9	07	9
10	17	10
11	15	11
12	11	12
13	25	13
14	52	14
≥14	77	15

* NGOOD - OWC PRODUCT No. 7

TABLE 5-12
STQUAL* COLOR CONVERSION (STQFCT)

DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.	DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.
0-30	00	1	181-185	22	18
31-45	04	2	186-190	23	19
46-60	10	3	191-195	03	20
61-75	14	4	196-200	02	21
76-90	34	5	201-204	01	22
91-105	74	6	205-208	06	23
106-120	64	7	209-212	07	24
121-135	24	8	213-216	13	25
136-140	20	9	217-220	17	26
141-145	40	10	221-224	15	27
146-150	60	11	225-228	11	28
151-155	61	12	229-232	05	29
156-160	62	13	233-236	25	30
161-165	63	14	237-240	26	31
166-170	67	15	241-244	46	32
171-175	41	16	245-250	52	33
176-180	21	17	251-255	77	34

* STQUAL - OWC PRODUCT No. 8

TABLE 5-13
DELTA T* COLOR CONVERSION (DLTFCT)

DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.	DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.
0-95	00	1	128	31	35
96-99	04	2	129-130	41	15
100-103	10	3	131-132	21	16
104-107	14	4	133-134	23	17
108-109	34	5	135-136	03	18
110-111	74	6	137-138	02	19
112-113	64	7	139-140	01	20
114-115	24	8	141-142	07	21
116-117	20	9	143-144	13	22
118-119	40	10	145-146	17	23
120-121	60	11	147-148	15	24
122-123	62	12	149-152	11	25
124-125	63	13	153-156	25	26
126-127	67	14	157-160	52	27
			161-255	77	28

* ΔT - ORC PRODUCT No. 3

TABLE 5-14
DAY ISOTHERMAL (OID) COLOR CONVERSION (DAYISO)

DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.	DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.
0-149	00	1	209	41	15
150-165	04	2	210	21	16
166-175	10	3	211	23	17
176-183	14	4	212	03	18
184-189	34	5	213	02	19
190-193	74	6	214	01	20
194-195	64	7	215	07	21
196-197	24	8	216	13	22
198-199	20	9	217	17	23
200-201	40	10	218-219	15	24
202-203	60	11	220-223	11	25
204-205	62	12	224-229	25	26
206-207	63	13	230-239	52	27
208	67	14	240-255	77	28

TABLE 5-15
NIGHT ISOTHERMAL (OIN) COLOR CONVERSION (NITISO)

DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.	DATA	COLOR INDEX (OCTAL)	COLOR BAR NO.
0-141	00	1	193	41	15
142-155	04	2	194	21	16
156-165	10	3	195	23	17
166-171	14	4	196	03	18
172-175	34	5	197	02	19
176-179	74	6	198	01	20
180-181	64	7	199	07	21
182-183	24	8	200-201	13	22
184-185	20	9	202-203	17	23
186-187	40	10	204-205	15	24
188-189	60	11	206-209	11	25
190	62	12	210-217	25	26
191	63	13	218-227	52	27
192	67	14	228-255	77	28

TABLE 5-16
PDGEN VT05 VARIABLE FIELDS (EX: SSP)

NAME	TYPE	DEFAULT	LIMIT	DESCRIPTION
OPCODE	NUMERIC	3	0-3	PRODUCT GENERATOR MODE
NBRIMG	NUMERIC	8	1,5,8	TOTAL NO. OF IMAGES OUTPUT TO TAPE
OTDEVN	NUMERIC	2	0-3	TAPE UNIT DEVICE NO.
DISIMG	NUMERIC	1	1-8	IMAGE NO. TO BE OUTPUT TO DISPLAY
PDSCAN	NUMERIC	-----	1-2200	CURRENT SCAN LINE COUNTER
SYSID	ASCII	SEDS	32 CHARS	SYSTEM IDENTIFICATION
TAPID	ASCII	OWC	3 CHARS	OUTPUT TAPE IDENTIFICATION
SEQNO	NUMERIC	01	01-63	TAPE REEL SEQUENCE NO.
SENSID	ASCII	NOAA	8 CHARS	SENSOR IDENTIFICATION
TDATE	NUMERIC	00-00-00	DD-MM-YY	GENERATION DATE OF DATA
ORBIT	NUMERIC	-----	0-32767	ORBIT NO. OF DATA (DAY PASS)
JOBID	ASCII	SEDS IMAGE	28 CHARS	JOB IDENTIFICATION
DODATA	NUMERIC	00-00-00	MM-DD-YY	DATE-OF-DATA (DAY PASS)
COIMGI	ASCII	-----	54 CHARS	COMMENTS ENTERED MANUALLY

TABLE 5-17
ANNOTATION DOT MATRIX TABLE (DMTB)

DATA	CHARS.	DATA	CHARS.	DATA	CHARS.
01076	N/A,A,B (3-CHAR GROUP NO. 0)	41061		42220	
01051		41063		24210	
01751		41265		10204	
01056		41271		24502	
01051		41561		43041	
00511		41061		43077	
00236		35015	O,P,Q	00000	N/A,N/A,N/A
35737	C,D,E	43022		00000	
42460		43025		00000	
40460		43721		00000	
40474		43061		00000	
40460		43061		00000	
42460		35716		00000	
35737		42704	R,S,T	00000	N/A,N/A,SPACE
40761	F,G,H	45044		00000	
41061		50044		00000	
41161		74704		00000	
71037		43004		00000	
41021		43044		00000	
41021		74737		00000	
76761		34221	U,V,W	10011	!,",#
34721	I,J,K	42533		00012	
11062		43065		10037	
10070		43065		10012	
10064		43061		10537	
10062		43061		10512	
34061		43061		10512	
77061	L,M,N	42237	X,Y,Z	10155	,\$,%,&

TABLE 5-17 (CONT'D)

DATA	CHARS.	DATA	CHARS.	DATA	CHARS.
75162		76004		17756	
12425		00002		70010	9,:,,
34210		00001		04004	
50124		00000		02204	
37464		34737	0,1,2	36000	
11410		42220		42204	
00204	',(,)	62210		42000	
00402		52206		34000	
01001		46201		04010	,=,
01001		42621		10004	
11001		34216		21742	
10402		34116	3,4,5	40001	
10204		42121		21742	
10010	*,+,,	03741		10004	
52204		15101		04010	
34204		04536		10000	?
11740		02320		00000	
34200		76137		10000	
52200		34416	6,7,8	10000	
10000		42421		04000	
00200	-.../	42421		42000	
00020		74216		34000	
00020		40121			
00010		20061			

CHARS	DATA (OCTAL)	15-BIT EXPANSION														
		1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
N/A,A,B(0)	01076	0	0	0	0	0	1	0	0	0	1	0	1	1	0	0
	01051	0	0	0	0	0	1	0	0	0	1	0	1	0	0	1
	01751	0	0	0	0	0	1	1	1	1	1	0	1	0	0	1
	01056	0	0	0	0	0	1	0	0	0	1	0	1	1	1	0
	01051	0	0	0	0	0	1	0	0	0	1	0	1	0	0	1
	00511	0	0	0	0	0	1	0	1	0	1	0	1	0	0	1
	00236	0	0	0	0	0	1	0	1	0	1	1	1	1	1	0
		N/A (0)					A (1)					B (2)				
		1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
X,Y,Z(10 ₈)	42237	1	0	0	0	1	0	1	0	1	0	1	1	1	1	1
	42220	1	0	0	0	1	0	1	0	1	0	0	1	0	0	0
	24210	0	1	0	1	0	0	1	0	1	0	0	1	0	0	0
	10204	0	0	1	0	0	0	1	0	1	0	0	0	1	0	0
	24502	0	1	0	1	0	0	1	0	1	0	0	0	1	0	0
	43041	1	0	0	0	1	1	0	0	0	1	0	0	1	0	0
	43077	1	0	0	0	1	1	0	0	0	1	1	1	1	1	1
		X (0)					Y (1)					Z (2)				

ALGORITHM FOR LOCATING CHARACTERS IN DMTB:

1. FIND CHARACTER A (ASCII CODE = 101₈)
6-BIT LSB = 01₈
DIVIDE 01₈ BY 3; QUOTIENT = 0, REMAINDER = 1
A IS LOCATED IN 3-CHAR GROUP NO. 0, INTERNAL POSITION NO. 1
2. FIND CHARACTER Z (ASCII CODE = 132₈)
6-BIT LSB = 32₈
DIVIDE 32₈ BY 3; QUOTIENT = 10₈, REMAINDER = 2
Z IS LOCATED IN GROUP NO. 10₈, INTERNAL POSITION NO. 2

Figure 5-26 Binary Expansion of Selected DMTB Entries

<u>CHARS</u>	<u>DATA (OCTAL)</u>	<u>15-BIT EXPANSION</u>														
		1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
N/A,A,B(0)	01076	0	0	0	0	0	1	0	0	0	1	1	1	1	0	1
	01051	0	0	0	0	0	1	0	0	0	1	0	1	0	0	1
	01751	0	0	0	0	0	1	1	1	1	1	0	1	0	0	1
	01056	0	0	0	0	0	1	0	0	0	1	0	1	1	1	0
	01051	0	0	0	0	0	1	0	0	0	1	0	1	0	0	1
	00511	0	0	0	0	0	0	1	0	0	0	0	1	0	0	1
	00236	0	0	0	0	0	0	0	1	0	0	1	1	1	1	0
		N/A (0)					A (1)					B (2)				
		1	2	3	4	5	1	2	3	4	5	1	2	3	4	5
X,Y,Z(10 ₈)	42237	1	0	0	0	1	0	0	1	0	0	1	1	1	1	1
	42220	1	0	0	0	1	0	0	1	0	0	0	1	0	0	0
	24210	0	1	0	1	0	0	0	1	0	0	0	1	0	0	0
	10204	0	0	1	0	0	0	0	1	0	0	0	0	1	0	0
	24502	0	0	0	1	0	0	0	0	0	0	0	0	1	0	1
	43041	1	0	0	0	1	1	0	0	0	1	0	0	1	0	1
	43077	1	0	0	0	1	1	0	0	0	1	1	1	1	1	1
		X (0)					Y (1)					Z (2)				

ALGORITHM FOR LOCATING CHARACTERS IN DMTB:

1. FIND CHARACTER A (ASCII CODE = 101₈)
6-BIT LSB = 01₈
DIVIDE 01₈ BY 3; QUOTIENT = 0, REMAINDER = 1
A IS LOCATED IN 3-CHAR GROUP NO. 0, INTERNAL POSITION NO. 1
2. FIND CHARACTER Z (ASCII CODE = 132₈)
6-BIT LSB = 32₈
DIVIDE 32₈ BY 3; QUOTIENT = 10₈, REMAINDER = 2
Z IS LOCATED IN GROUP NO. 10₈, INTERNAL POSITION NO. 2

Figure 5-26 Binary Expansion of Selected DMTB Entries

truncate that character's 7-bit ASCII code to its six LSB's. Then divide the 6-bit value by 3. The quotient defines the three-character group number, and the remainder is used to locate the character's position within the group. Internal counters are used to build character vertically and horizontally for a complete seven-line by five-pixel character. Each ASCII input string must be terminated by the octal code of 133₈.

5.2.3.5 Limitations. The major limitations of the SEDS product generation capability is the product output to tape for multi-image runs. For example, the OWC product tape always contains all eight images; the option to output only one or two of these images to tape does not exist. In addition, a restart capability of tape products is available only through reinitialization. Each product or set of products must be processed from scan line 1 to scan line 550, or to scan line 2200 for normal-sized images.

5.2.3.6 CPC Listings. See Part IV of this document, published under separate cover.

SECTION 6

DISPLAY AND PRODUCT GENERATOR (DPG) PROGRAM

6.1 GENERAL PROGRAM CHARACTERISTICS

The DPG Program in SEDS is used to display SEDS image product tapes, to perform universal format tape-to-tape edits, to edit visible channel data from registered data disk to tape, and to build selected SEDS image products. The DPG Program consists of four major components or modules -- DPG, UEDIT, VSTRIP, and DWPGEN.

6.1.1 Functional Allocation. As described in PHO-TN734, DPG provides a comprehensive image screening and editing processing capability. The SEDS operator can view product maps from single or multiimage tapes. This option is especially useful for the multiimage tapes for products not monitored during the product generation phase. All product images may be visually inspected prior to being forwarded to the Production Film Converter for film processing.

6.1.2 Program Flow Chart. See figure 6-1..

6.1.3 Program Timing and Sequencing. DPG is designed to be run at any time following SEDS initialization when image screening or image editing is required. Proper program configuration includes such items as loading the correct 9-track tape or registered disk as input, and the SEDS display and blank tapes for output. Program initialization and control is through selected VT05 entries. Input tape reads are controlled by start and stop scan line numbers, and the displayed image is controlled by start and stop pixel numbers. Visible channel data from registered disk includes 550 scan lines containing 625 elements.

6.1.4 Storage Allocation. The storage requirements for DPG are shown in figure 6-2. As shown in the diagram, all four components of DPG use 12K instruction space. In addition, each module utilizes the 4K segmentation buffer, DBUFF, for tape input/output and linkage between modules. The DPG module (not to be confused with the DPG Program, the name given to this program in SEDS) provides program initialization and control, input tape control and image

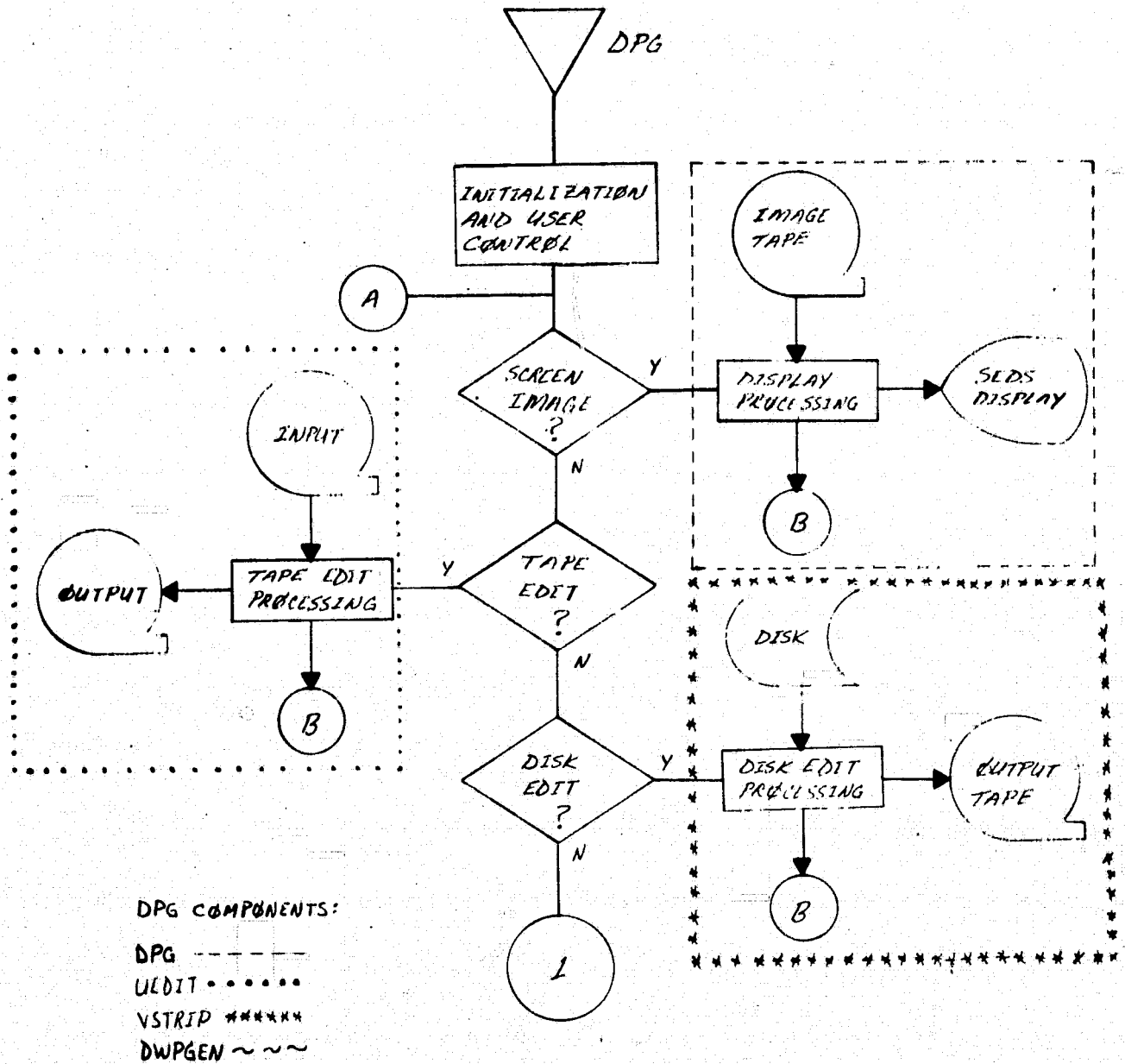


Figure 6-1 DPG Program Flow Chart

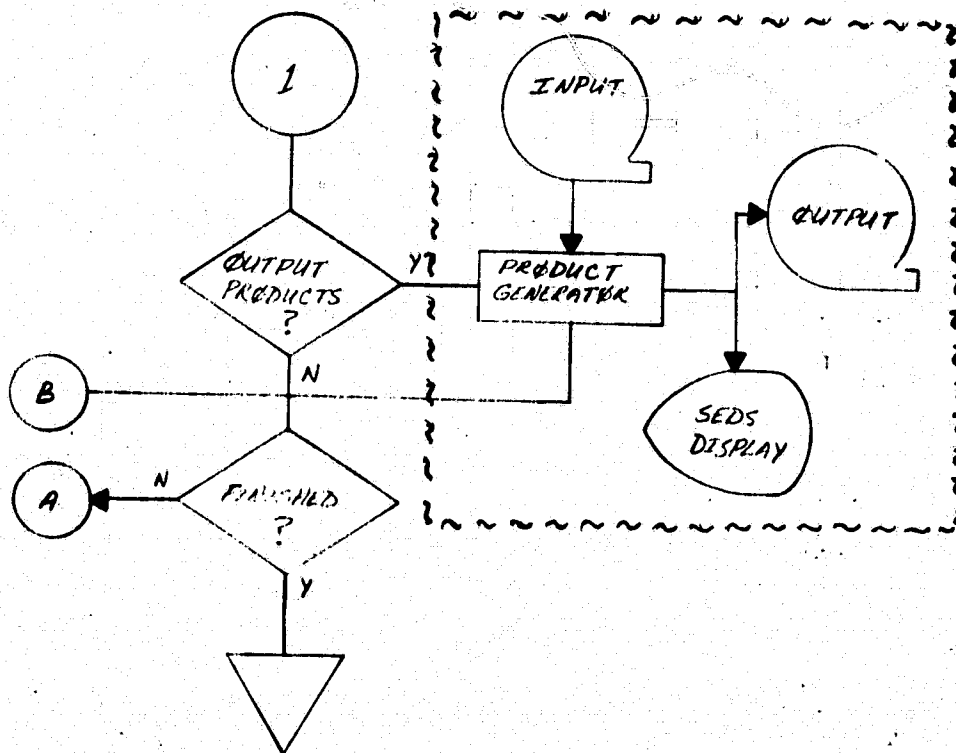


Figure 6-1 (Cont'd)

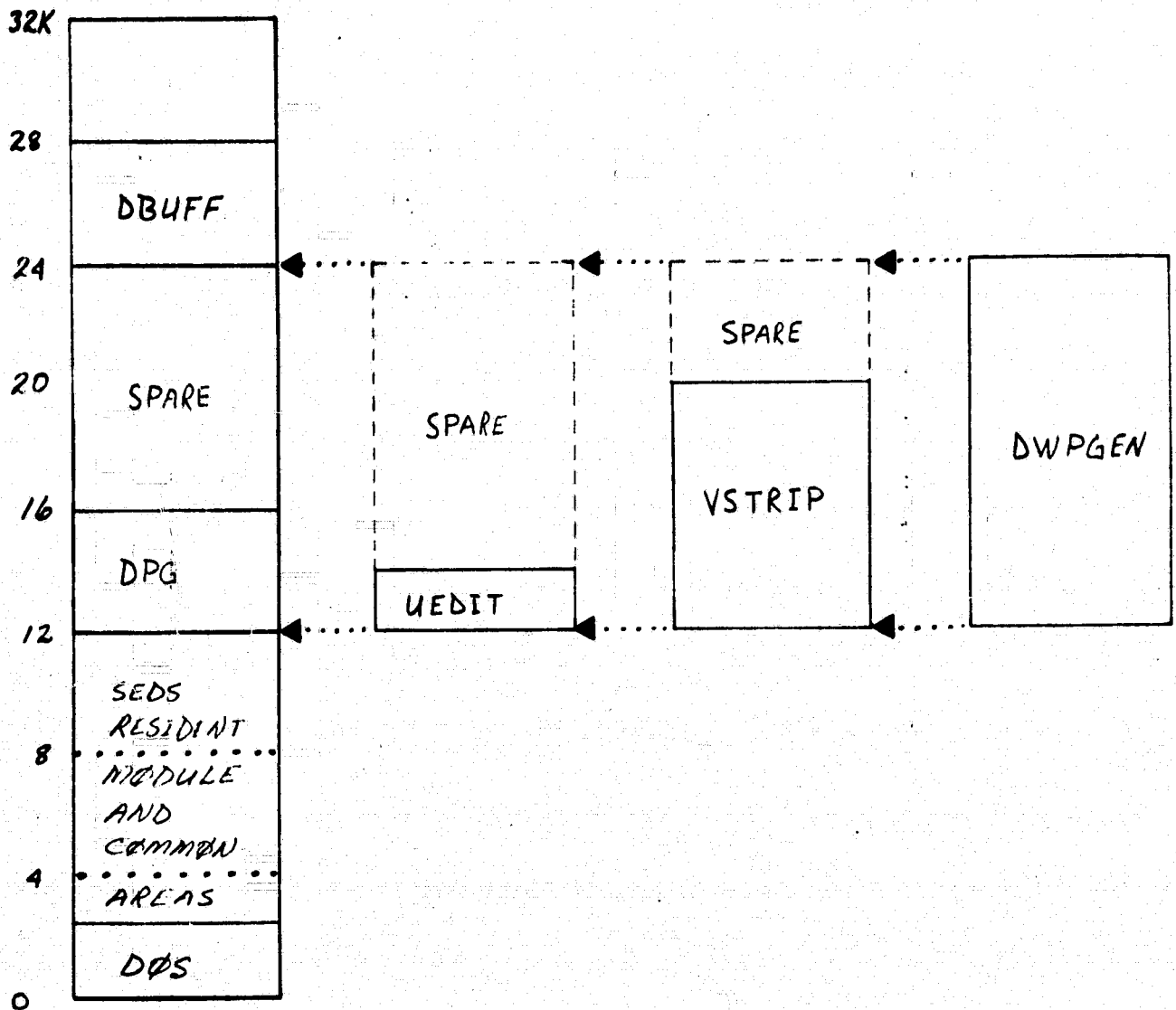


Figure 6-2 DPG Storage Allocation

screening. The UEDIT module of the DPG Program uses the input tape information stored in DBUFF to perform tape-to-tape editing. The VSTRIP module reads the visible channel from the registered disk, and writes a universal format tape which is blocked similarly to the compressed OID/OIN tapes described in figure 5-23. The DWPGEN module is a composite of the same product generator sub-routines described in paragraph 5.2.3 (SWPGEN) of this specification.

6.1.5 Data Base Characteristics

- A. File Description. The common files of DPG consist primarily of DBUFF and SCOMVT. DBUFF is a 4K storage buffer used for tape input/output sequencing between the DPG module and the other three modules. The content of DBUFF assumes the format of header or data records of the 9-track universal format tapes that are being read or written. SCOMVT serves as a 256-word common storage buffer area for linkage to all four modules. Most of the SCOMVT buffer space is used for storage of the header record constants from the input universal format tape.
- B. Program Constants. The following six parameters serve as DPG controlling constants. The last five are controlling parameters for the universal tape format read.
 - MODE - Program operation mode
 - PIXSTR - Start pixel number
 - PIXNBR - Number of pixels
 - SCNSTR - Start scan line number
 - SCNSTP - Stop scan line number
 - CHNL - Channel number

6.2 DPG CPC CHARACTERISTICS

This paragraph contains a detailed technical description of the computer program components identified in paragraph 6.1 of this specification. The instruction listings contained herein, by inclusion or reference, specify the exact configuration of the DPG Program.

6.2.1 DPG Module. The controlling, tape reading, and image screening component of the DPG Program is the DPG module. Its functions have been previously defined in paragraph 6.1. The module is composed of several separate and distinct subcomponents. One subroutine, DPGDRV, is written in PDP-11 FORTRAN and acts as the driver linking the DPG Program with the SEDS system control. The remaining subcomponents of the DPG module are written in PDP-11/45 assembly language.

6.2.1.1 Subcomponent Descriptions

- A. DPGDRV. This subcomponent of the DPG module is the DPG driver routine of SEDS. DPGDRV is necessary because of the system segmentation and overlay software utilized by SEDS.
- B. "DPG." This is the name given to the main subcomponent of the DPG module. As previously stated in this specification, user control, input tape processing, and image screening are the primary functions of the DPG module. User control is through the VT05 alphanumeric display terminal. VTLINK is the routine directly called to set up linkage between the user and the VT05. The DPG-initialized VT05 display is shown in figure 6-3. All error messages and operator advisory instructions are output to the VT05. Tape input is performed through interface with the universal format tape read routine, U9TRD.
- C. U9TRD. This is the subroutine called to read 9-track, universal format, CCT's. User inputs to DPG, such as the start and stop scan line numbers, the start pixel number, and the channel number control tape input sequencing. The call packet to U9TRD is specified in figure 6-4,

SEDS DISPLAY & PRODUCT GENERATOR					
MODE=SD		I N P U T * MTU=1		DATE: 01-MAR-75	
PIXEL	SCAN	CHAN			
STR=0001	STR=00001	01	DATA SHF=2	PRODUCT	
NBR=9999	STP=00550	00	SLD= N	CODE =0	
STP=0000	CUR=00000	00	COMP FACTOR: 111		

6-7

JSC-10019
Part II

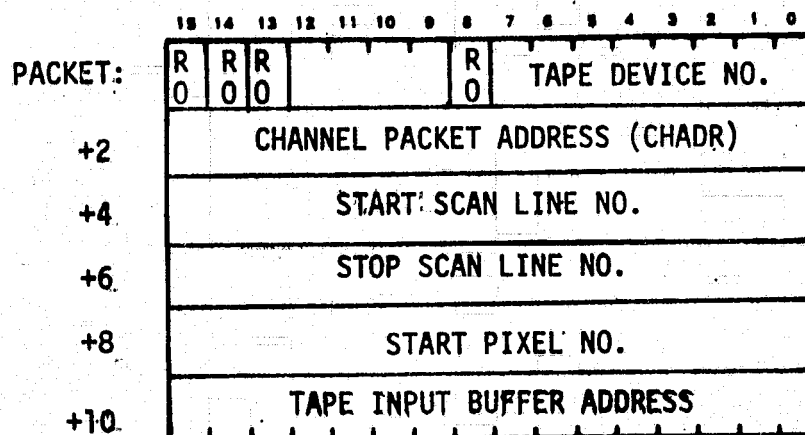
Figure 6-3 DPG Initialized VT05 Display

CALL TO U9TRD:

```
JSR    R5,@#U9TRD
BR      A
.WORD   PACKET      ; INPUT PACKET
.WORD   DATADR      ; RETURNED DATA ADR
.WORD   STATUS      ; RETURNED STATUS CODE
```

A:

- PACKET. 6-WORD BUFFER CONTAINING CONTROL INFORMATION FOR TAPE READ
- DATADR. 16-BIT ADDRESS OF START PIXEL NO. LOCATED WITHIN THE BUFFER SPECIFIED IN 6TH WORD OF PACKET BUFFER (PACKET+10)
- STATUS. CONTAINS RETURNED STATUS CODE FOLLOWING EACH CALL TO U9TRD.



REQUEST OPTION (BITS 8,13-15):

- 8 - SET IF HEADER READ
- 13 - SET IF INHIBIT VT05 MESSAGES
- 14 - SET IF RESTART
- 15 - SET IF NO BYTE REORDERING

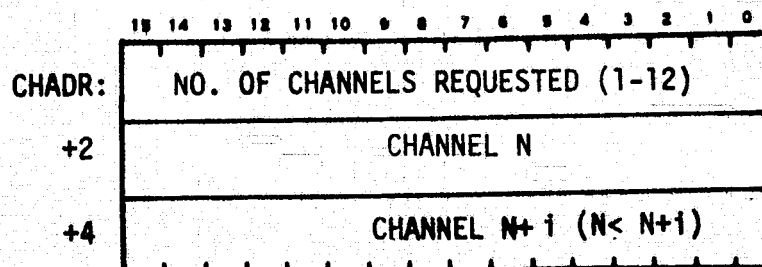


Figure 6-4 U9TRD Calling Sequence and Packet Format

STATUS CODES RETURNED IN USER'S "STATUS" WORD:

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0			
0																	0	= END OF SCAN LINE	
1	ID																1	= HEADER RECORD READ	
*2															1	0	= END OF RUN (FOUND STOP SCAN LINE)		
*3															1	1	= END OF FILE OR END OF TAPE		
4													1	0	0	= PARTIAL SCAN LINE (MULTICHANNEL READ)			
*5													1	0	1	= HEADER RECORD ERROR			
6	N															1	1	0	= TAPE DEVICE ERROR (N = NO. OF SCAN LINES LOST)
~~~~~																			
13													1	1	0	1	= TAPE READ ABORTED (25 CONSECUTIVE SCAN LINES LOST)		

*DENOTES ADVISORY MESSAGE OUTPUT

*DENOTES ADVISORY MESSAGE OUTPUT

NOTES:

- 1) SOME STATUS CODES HAVE HIGHER PRIORITY; E.I., HEADER RECORD ERROR (5) WOULD BE RETURNED OVER CODE 1
- 2) STATUS CODE 6 WILL BE RETURNED WHEN THE NEXT VALID SCAN LINE IS FOUND
- 3) TABLE 6-1 EXPLAINS THE SEDS TAPE ID CODE RETURNED IN THE UPPER BYTE WITH STATUS CODE 1.

Figure 6-4 (Cont'd)

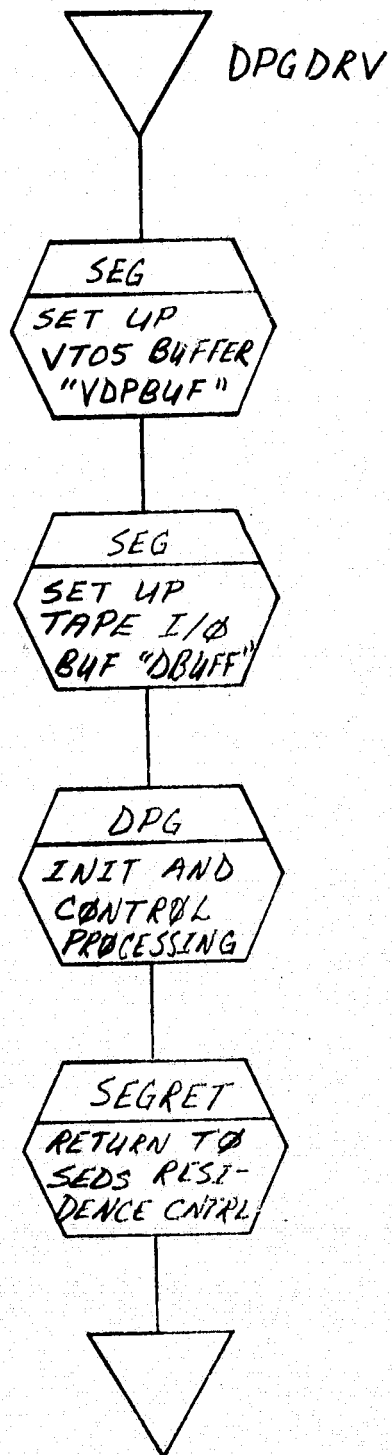
and table 6-1. The segmentation buffer, DBUFF, serves as the tape input buffer. The status codes returned to the user upon each call to U9TRD keeps him informed of the tape read status and requested data location. The user should call U9TRD for each channel's worth of data required. In addition to the various software status codes returned to user, VT05 advisory messages may be output to inform the operator of input status. The initial call to U9TRD should request that the first (or header) record be read. From the information supplied in the header record, a search algorithm is defined to continuously space the tape forward from start to stop scan line. An address is returned to the user specifying where the first pixel of the requested data is located. If the records of a scan line or data set contain parity errors upon read, the scan line or data set is not returned to the user; instead, tape read is tried until 25 scan lines are lost before an abort condition exists.

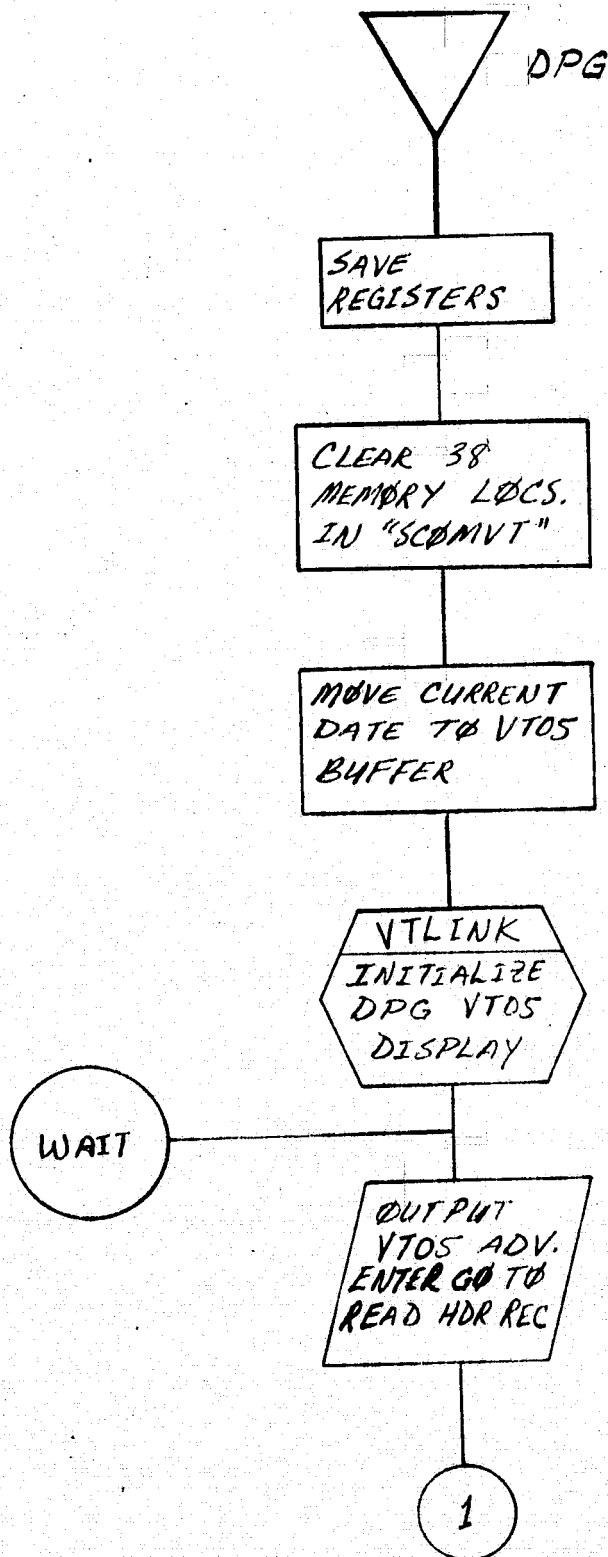
6.2.1.2 Flow Charts. See the 61 pages following table 6-1.

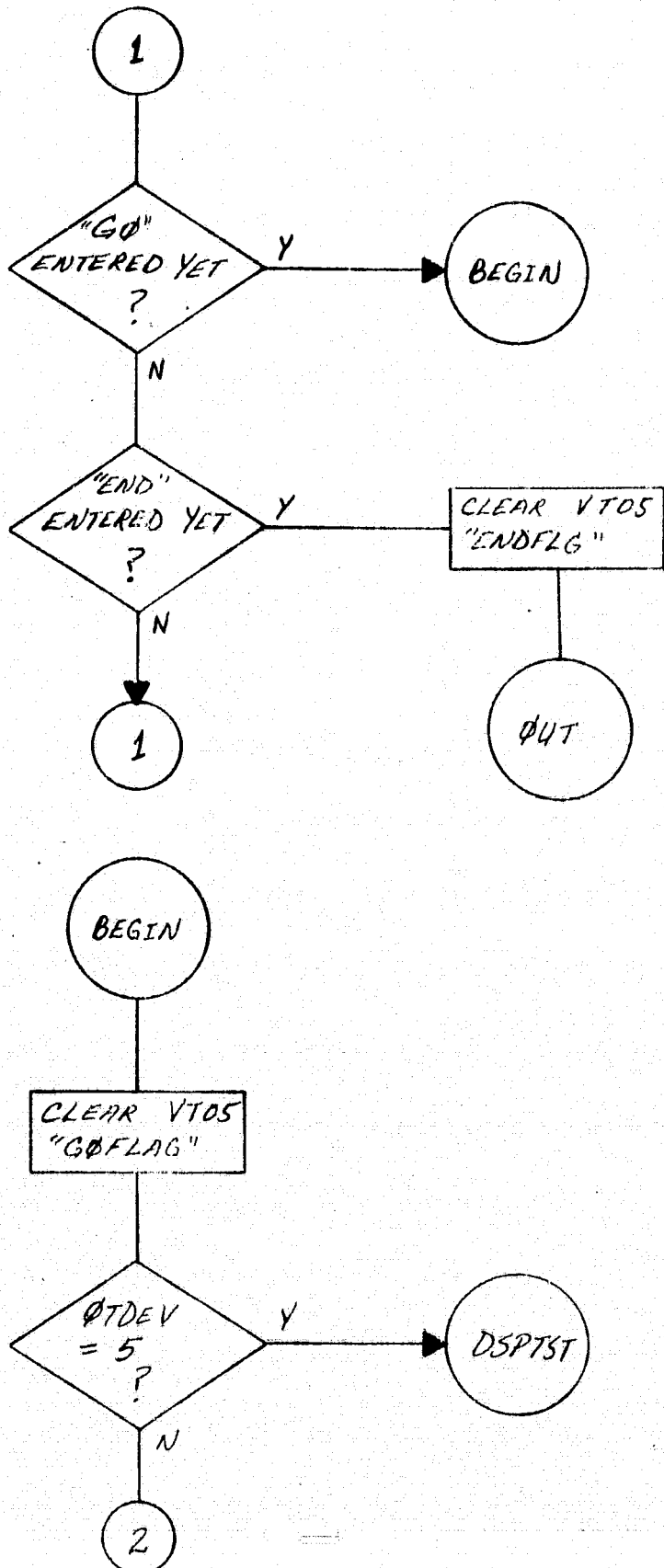
TABLE 6-1  
SEDS 9-TRACK TAPE INFORMATION

TAPE NAME	"U9TRD" ID RETURNED	TAPE ID
REG INTERMEDIATE	0	CRT
RAW PCM DAY	1	SPD
RAW PCM NIGHT	2	SPN
EU DAY	3	SED
EU NIGHT	4	SEN
REG DAY	5	SMD
REG NIGHT	6	SMN
SPARE	7	---
ISOTHERMAL DAY	8	OID*
ISOTHERMAL NIGHT	9	OIN*
DATA BASE	10	OBC
RAINFALL	11	ORC*
SCREWWORM	12	OWC*
MOISTURE INDEX	13	CMI
UPDATE	14	SBC

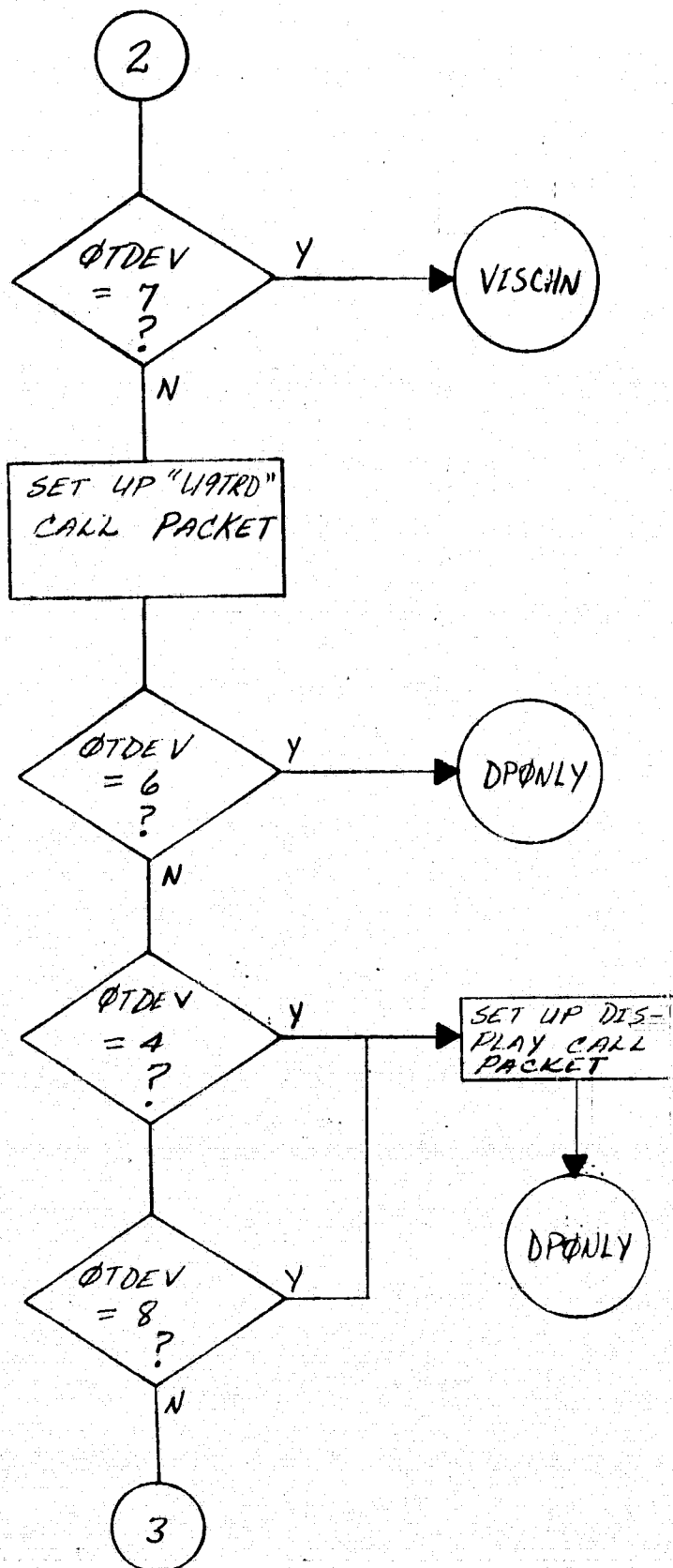
* DENOTES SEDS IMAGERY PRODUCTS TAPES

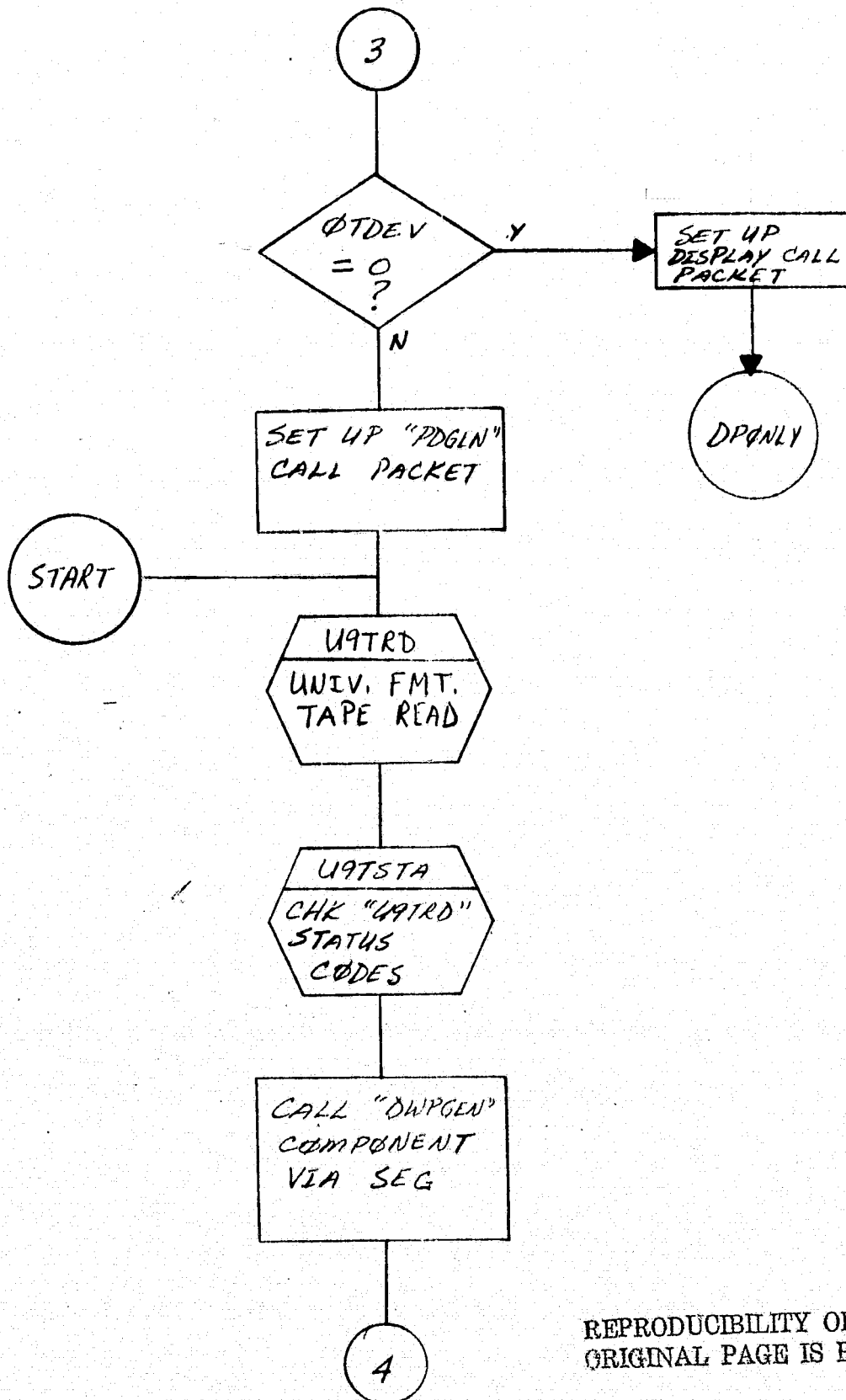




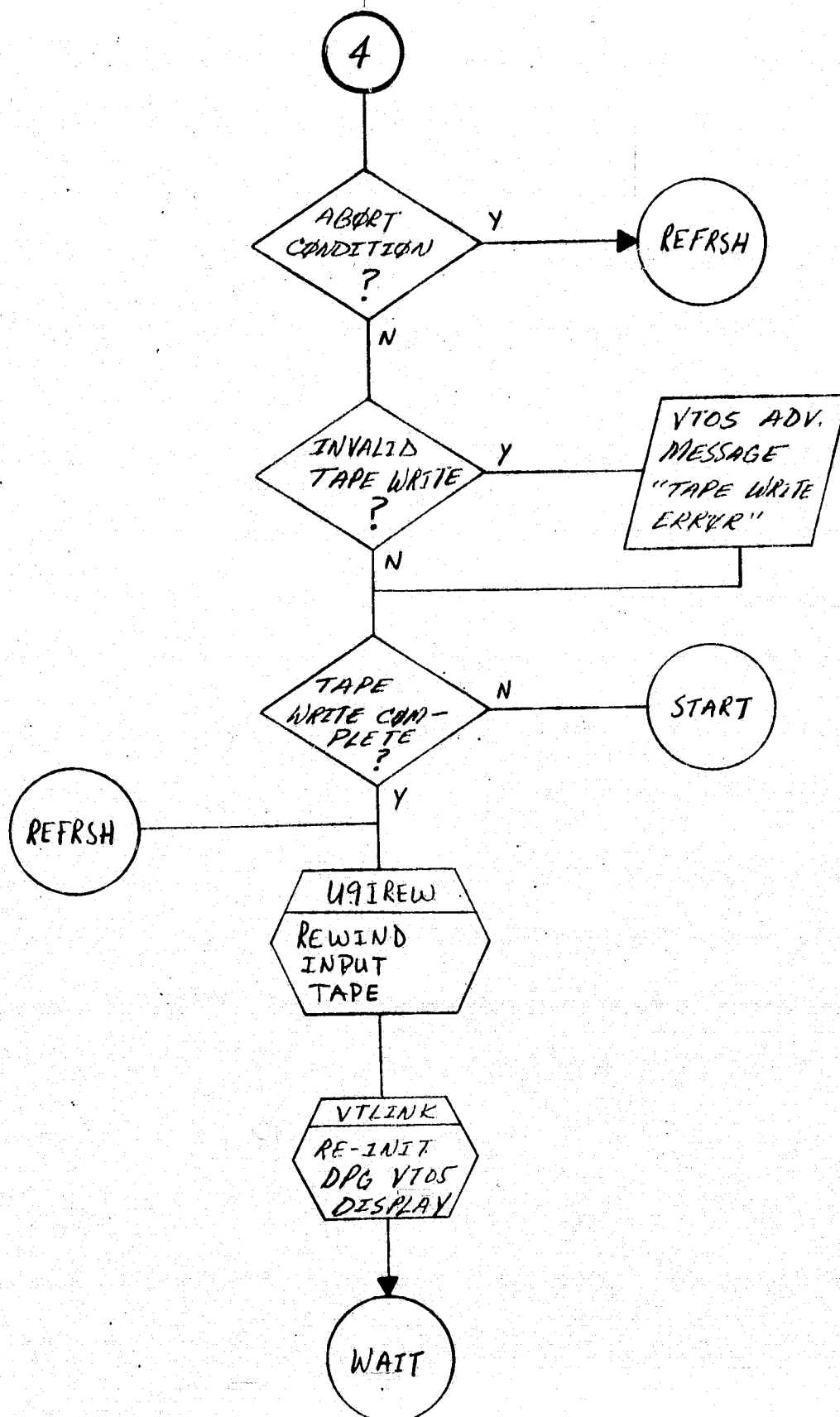


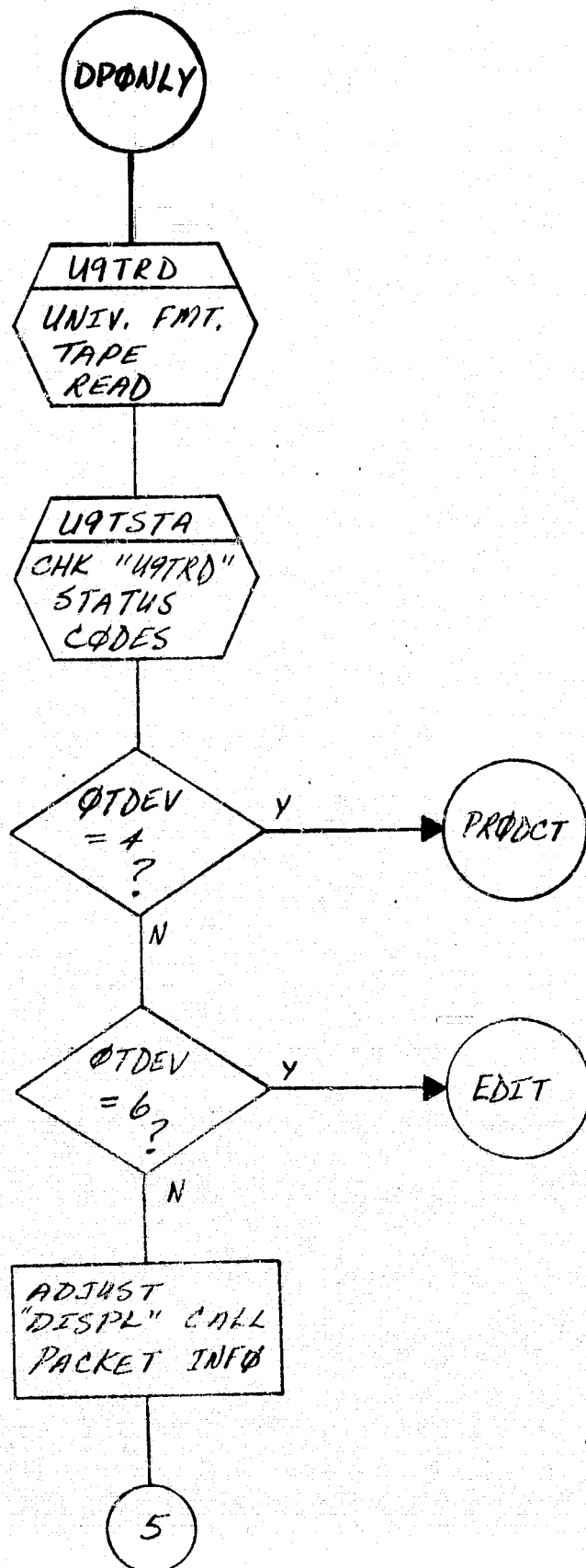


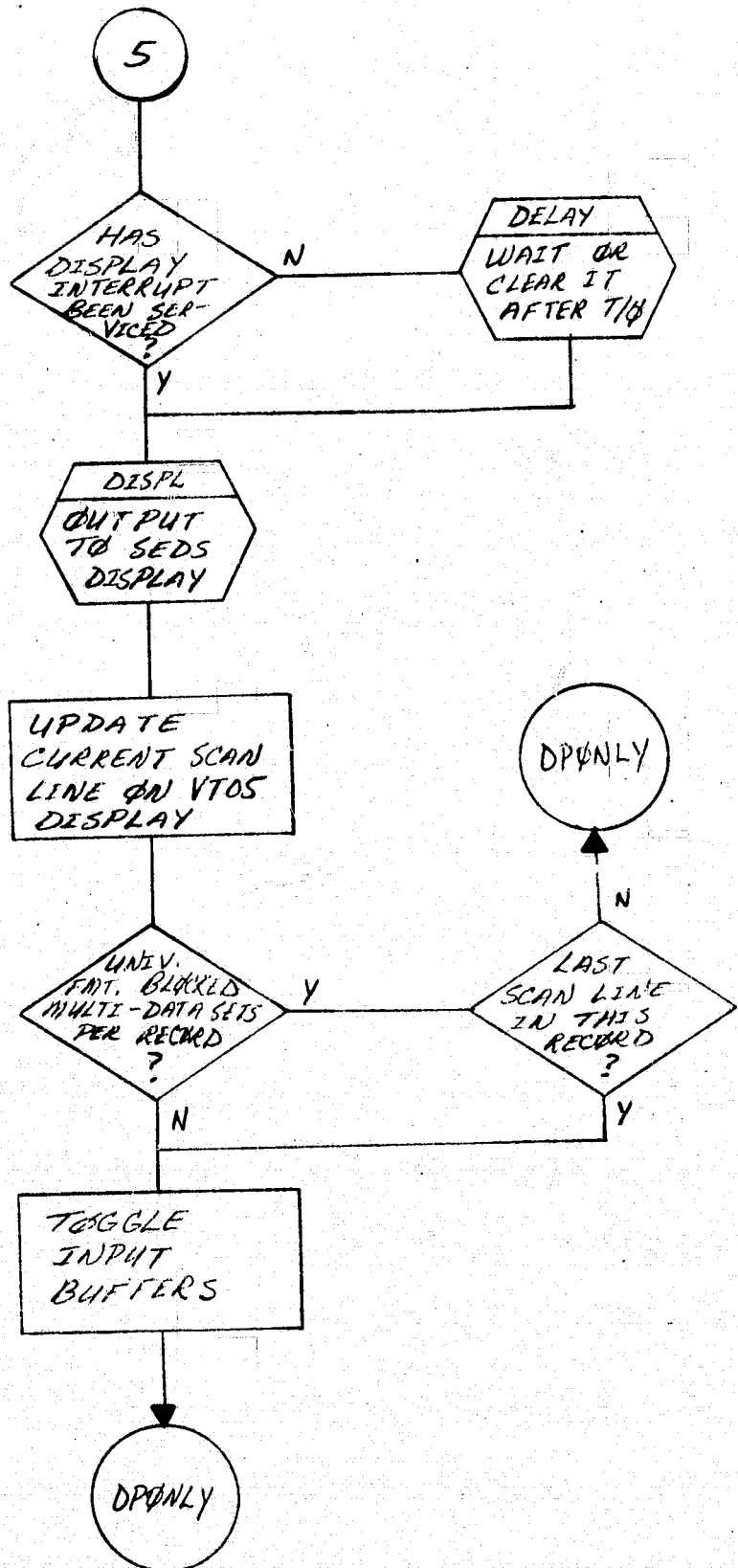


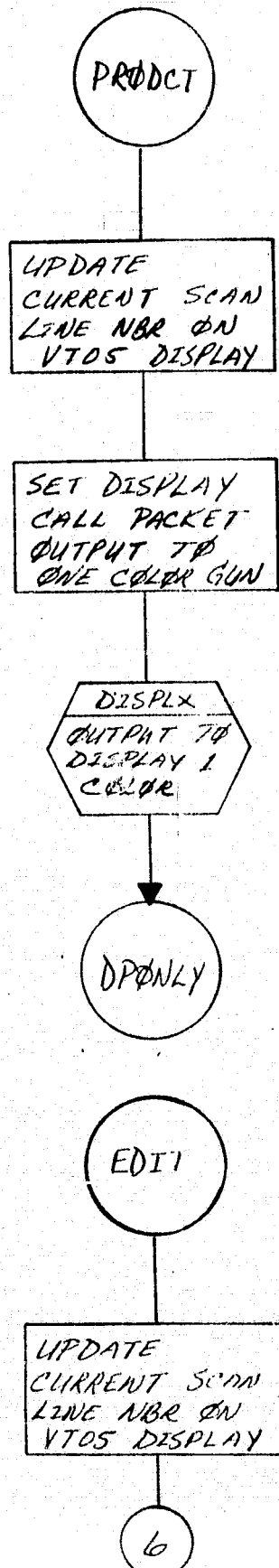


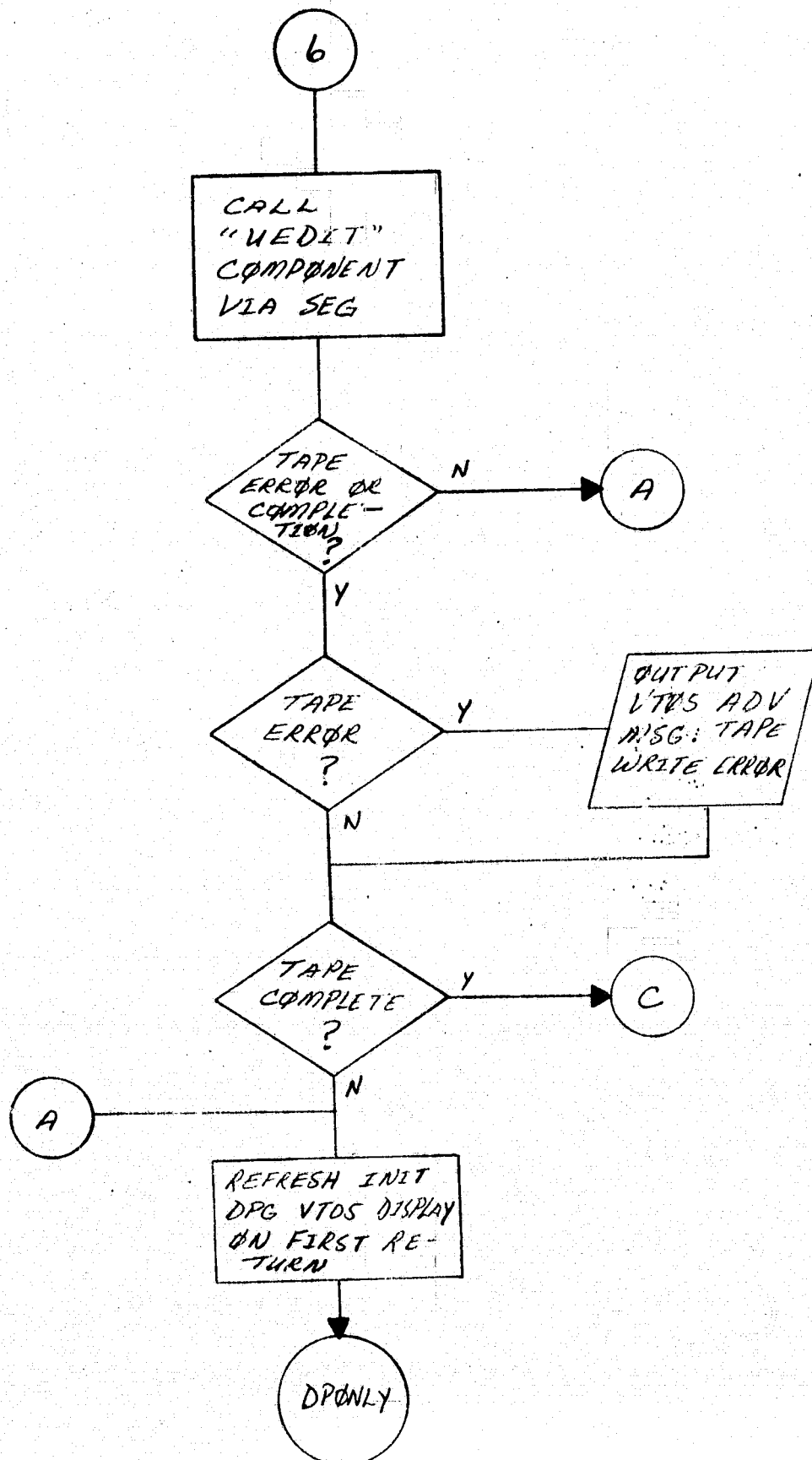
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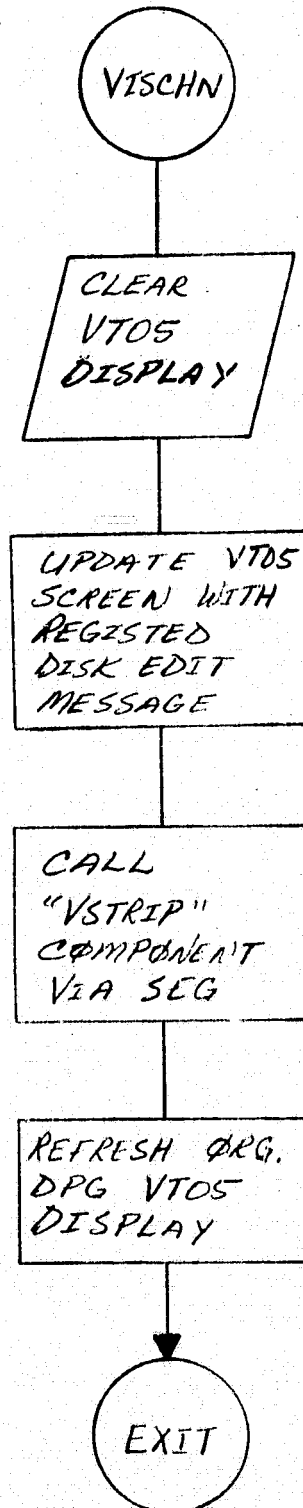






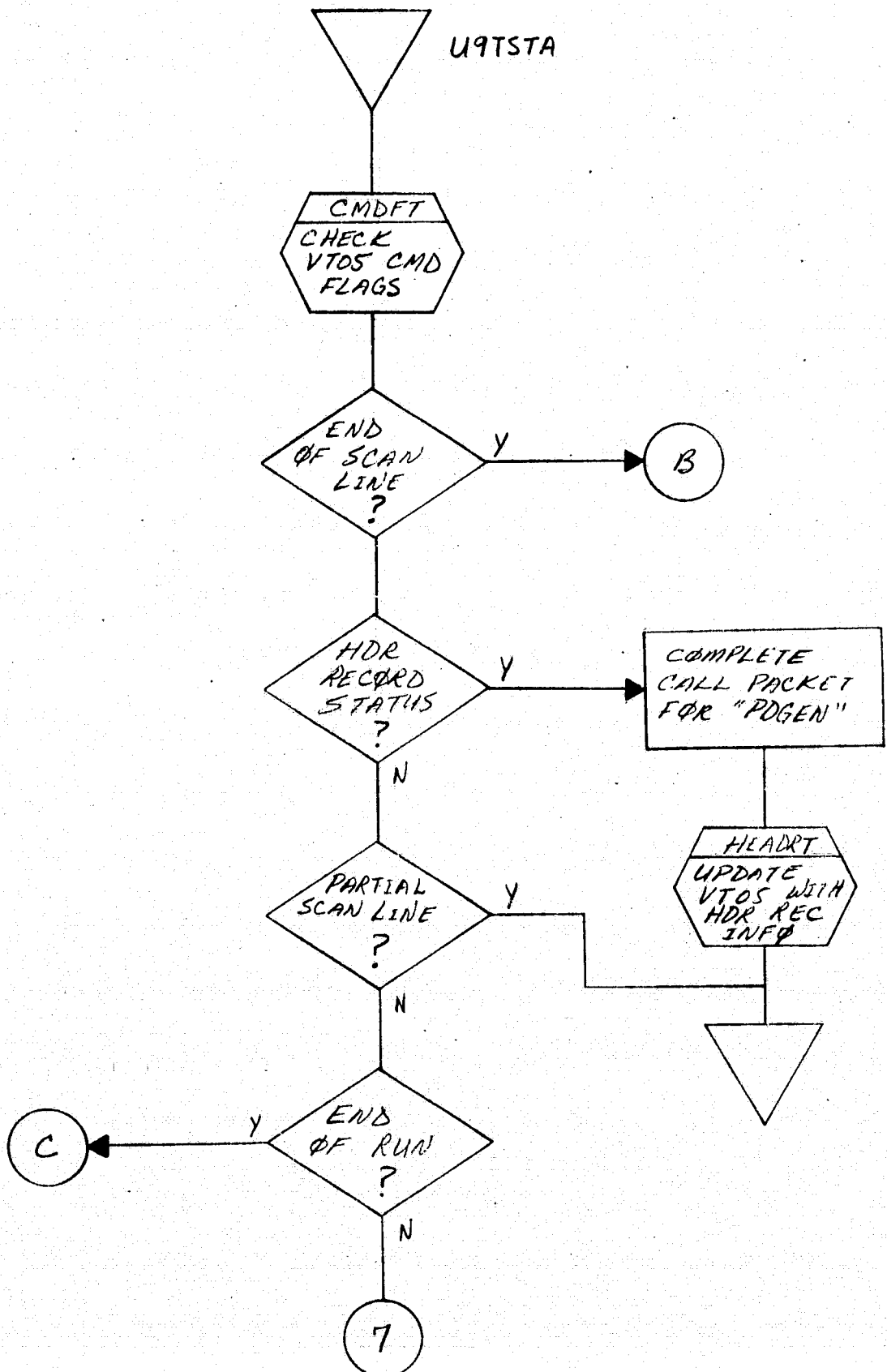


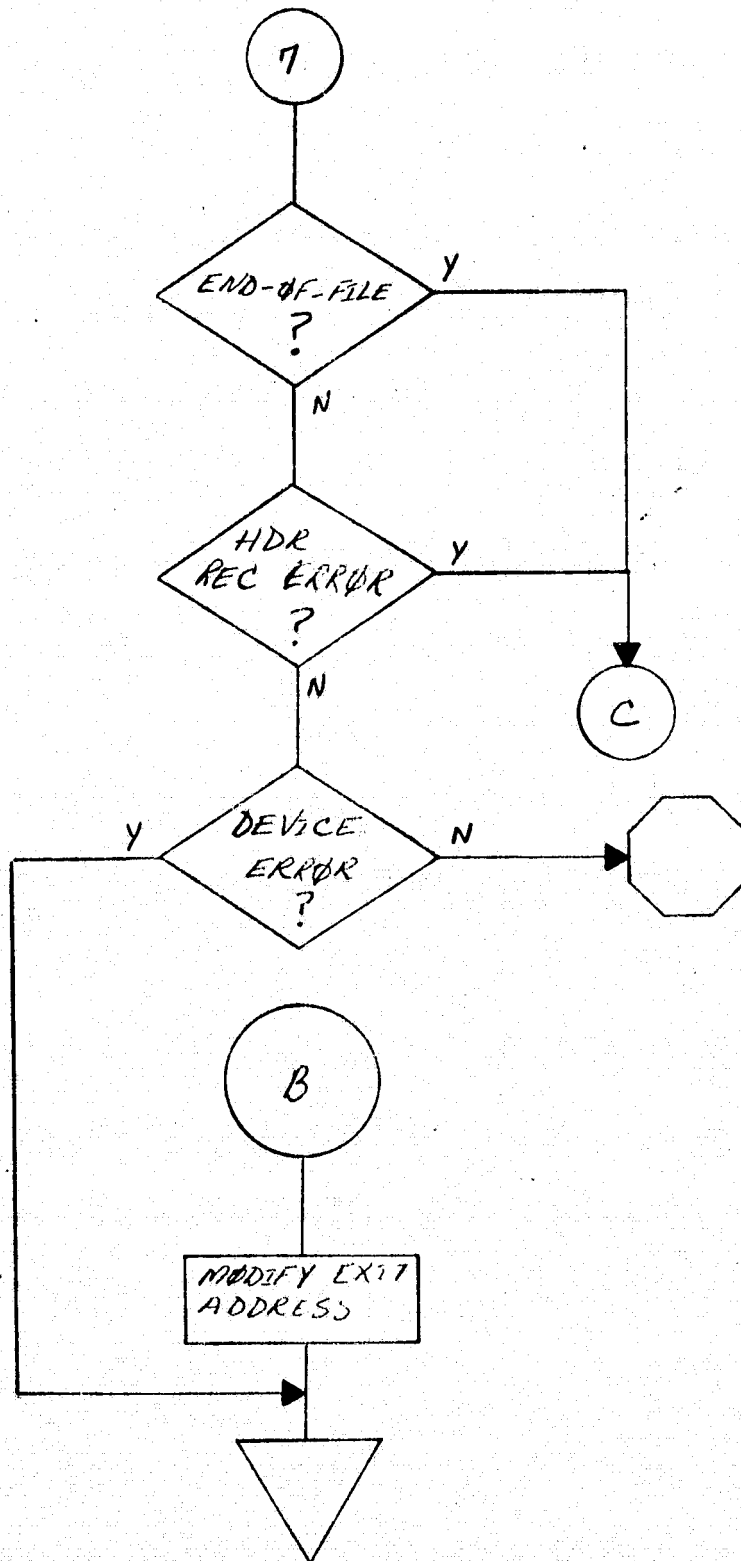


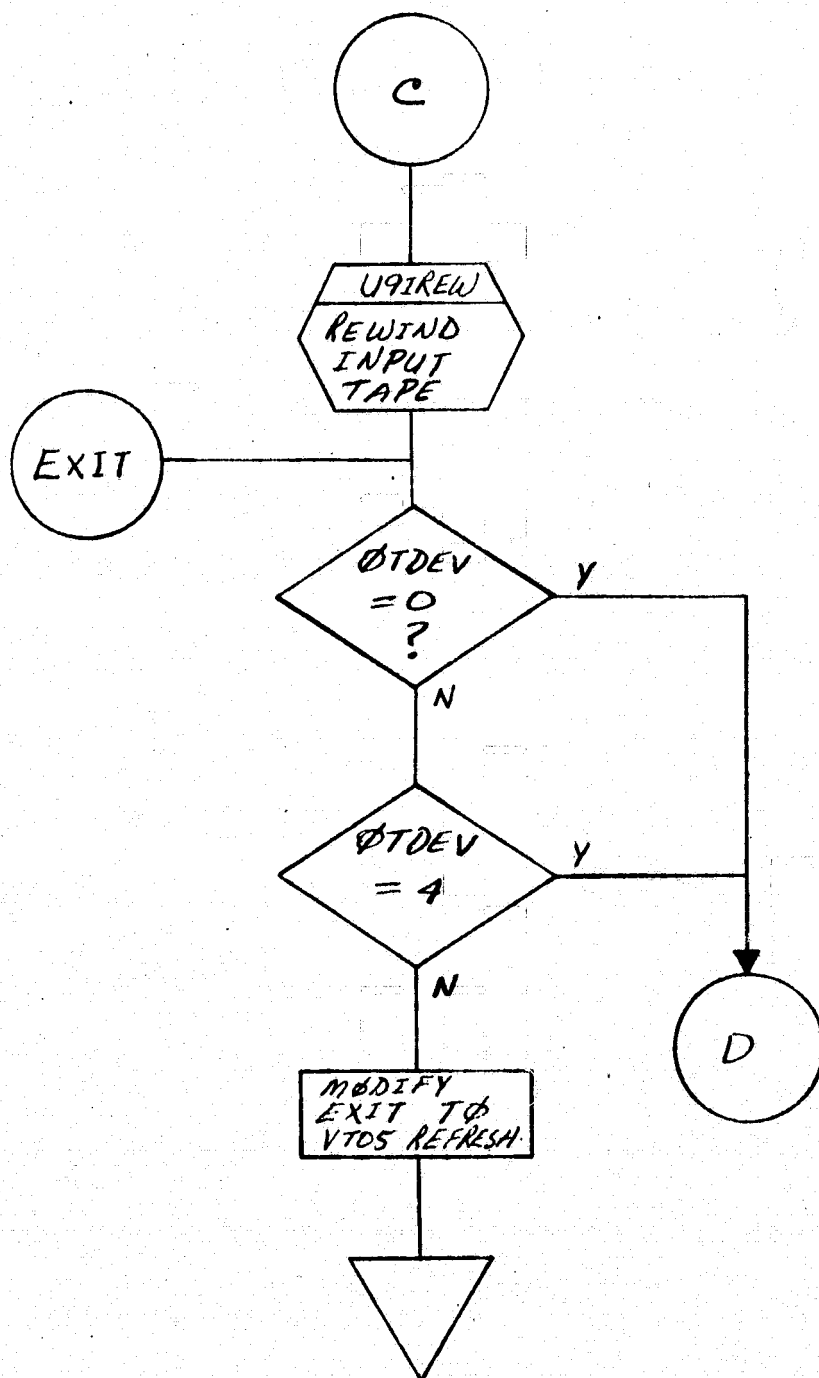


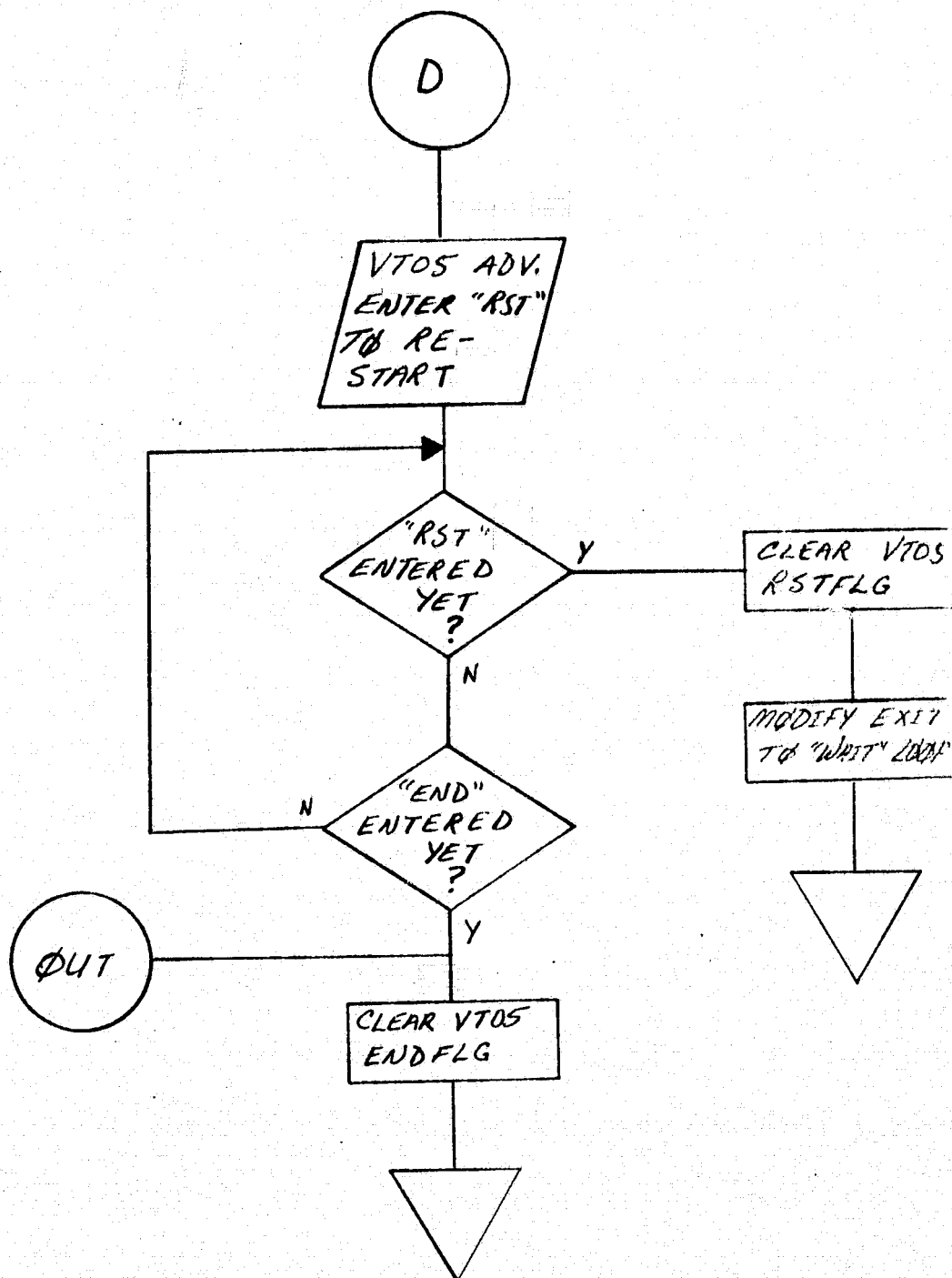
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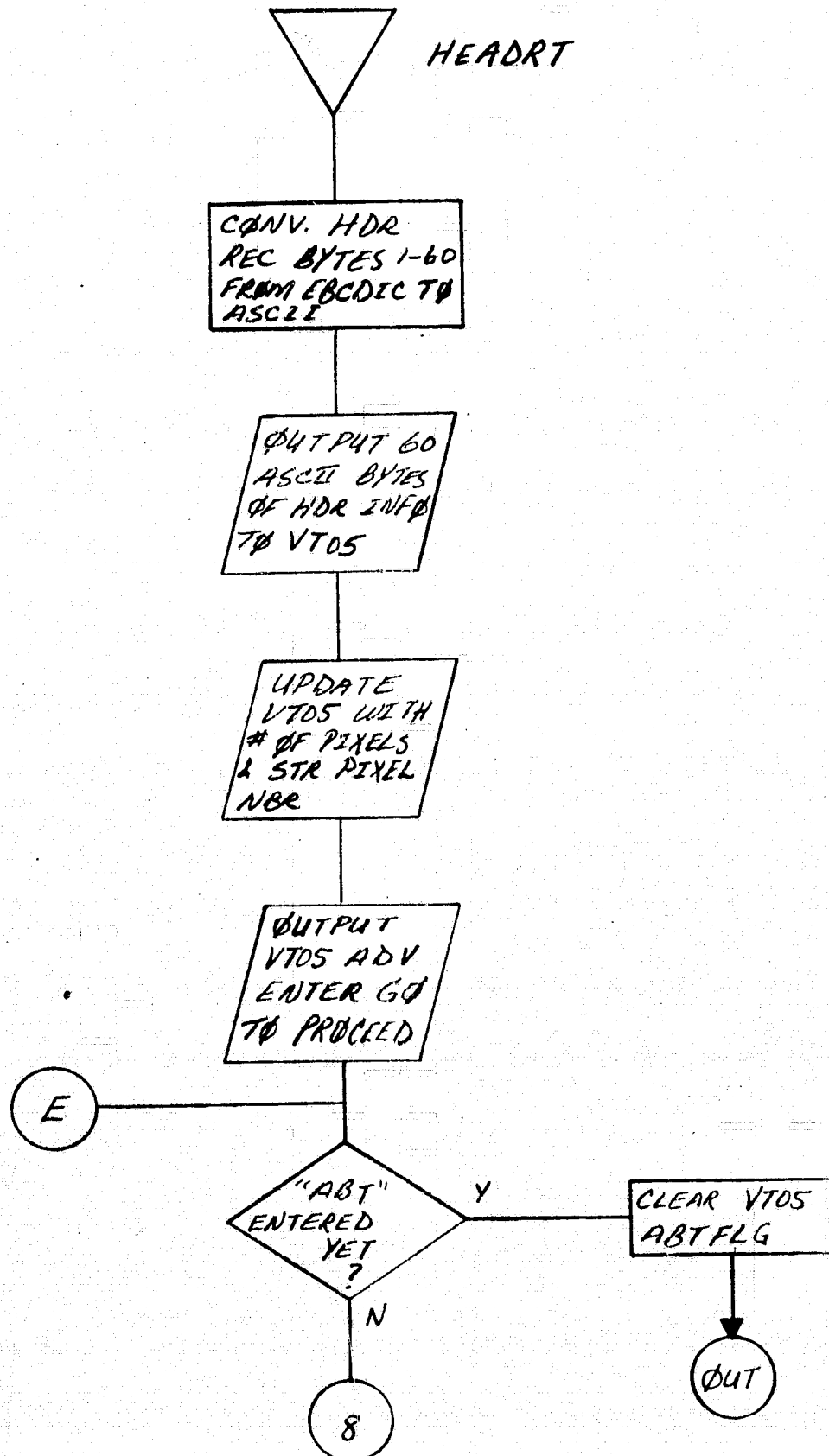


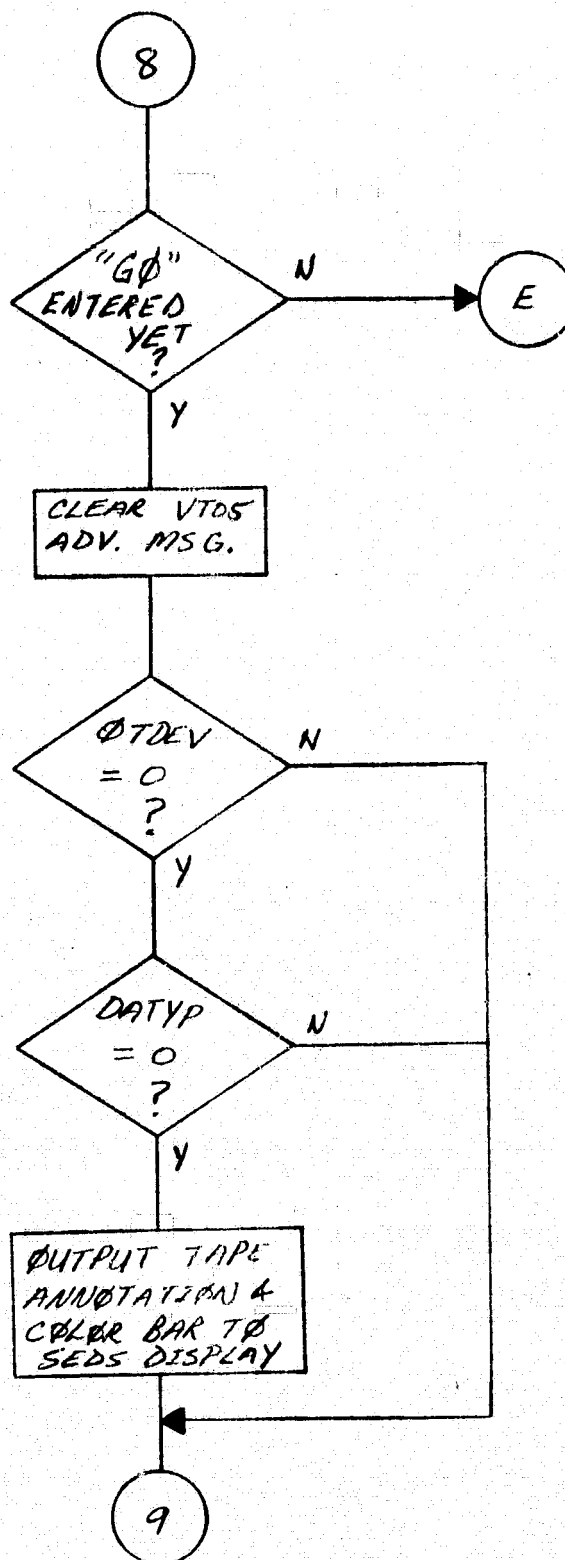


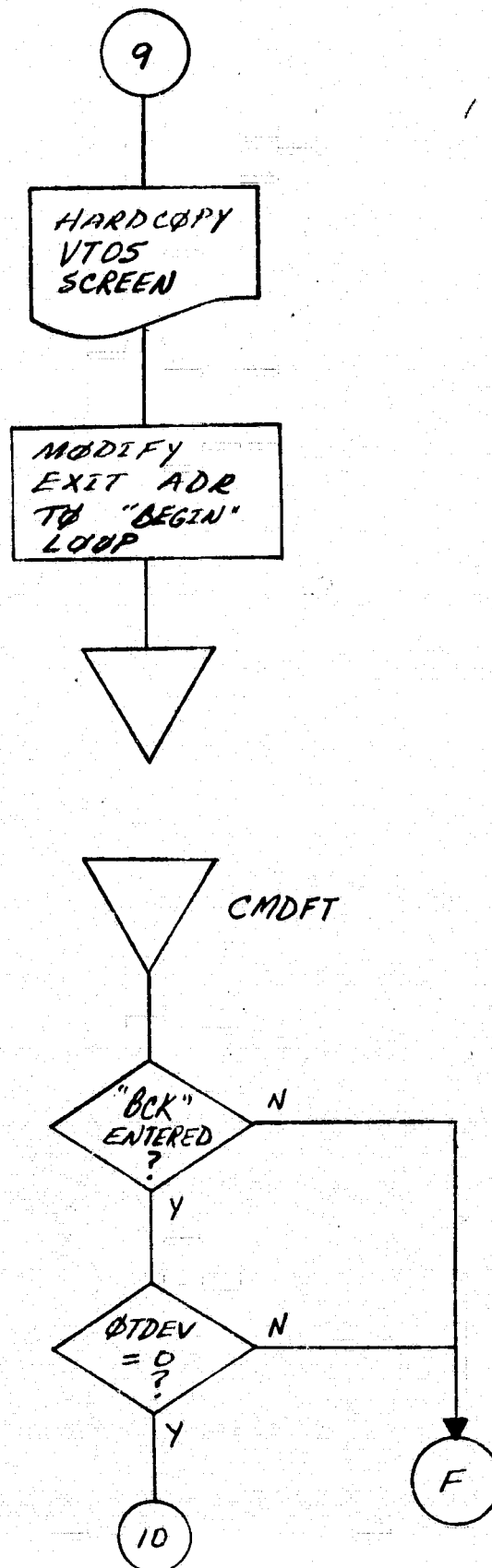


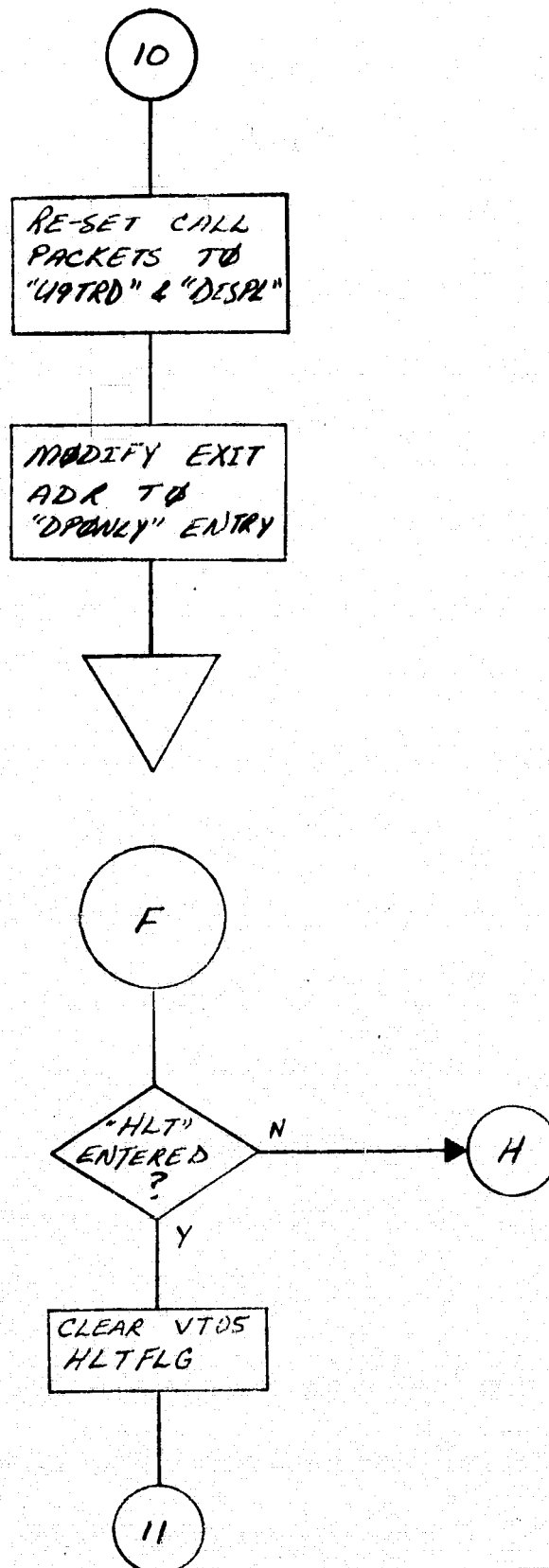




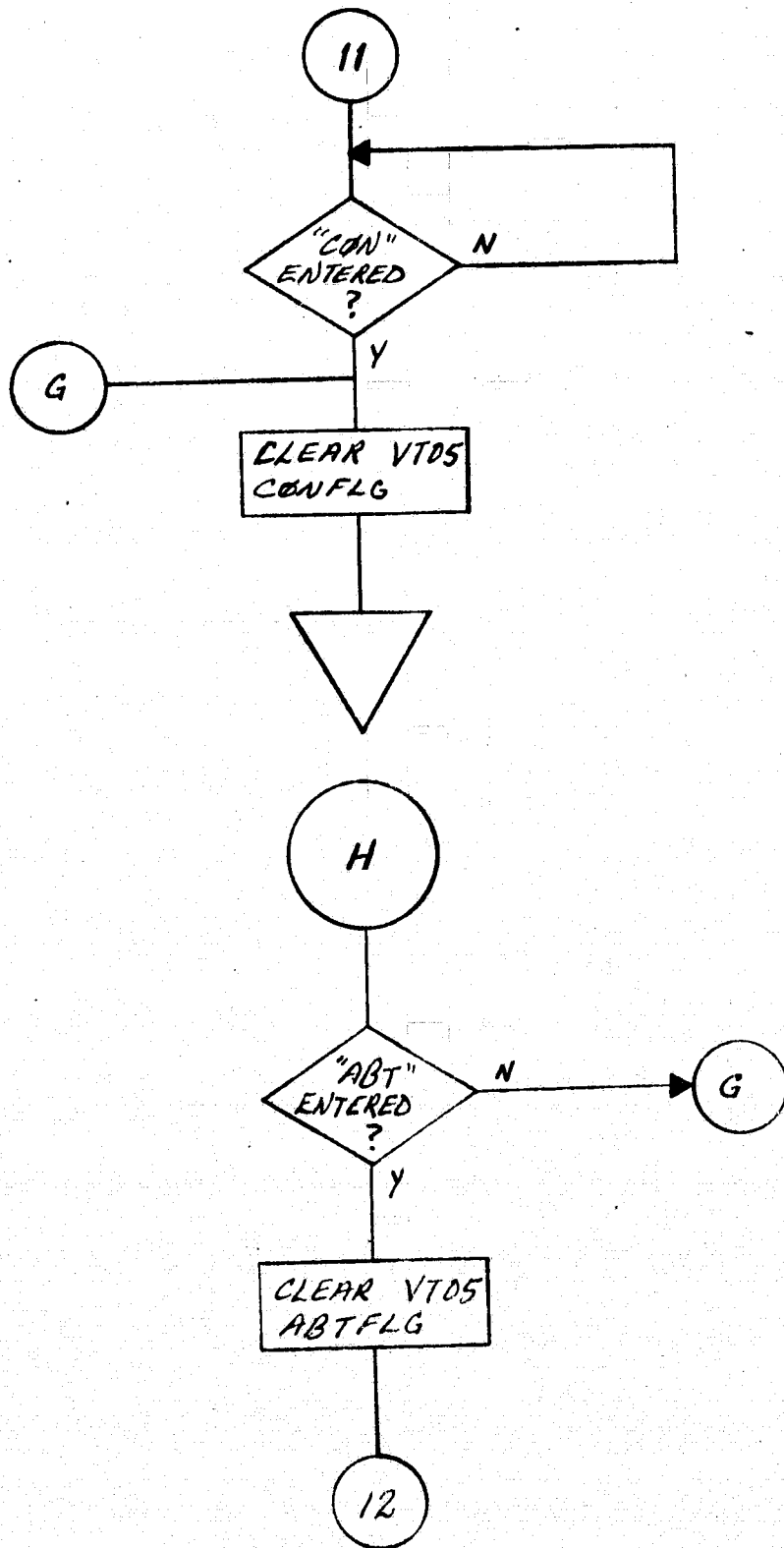


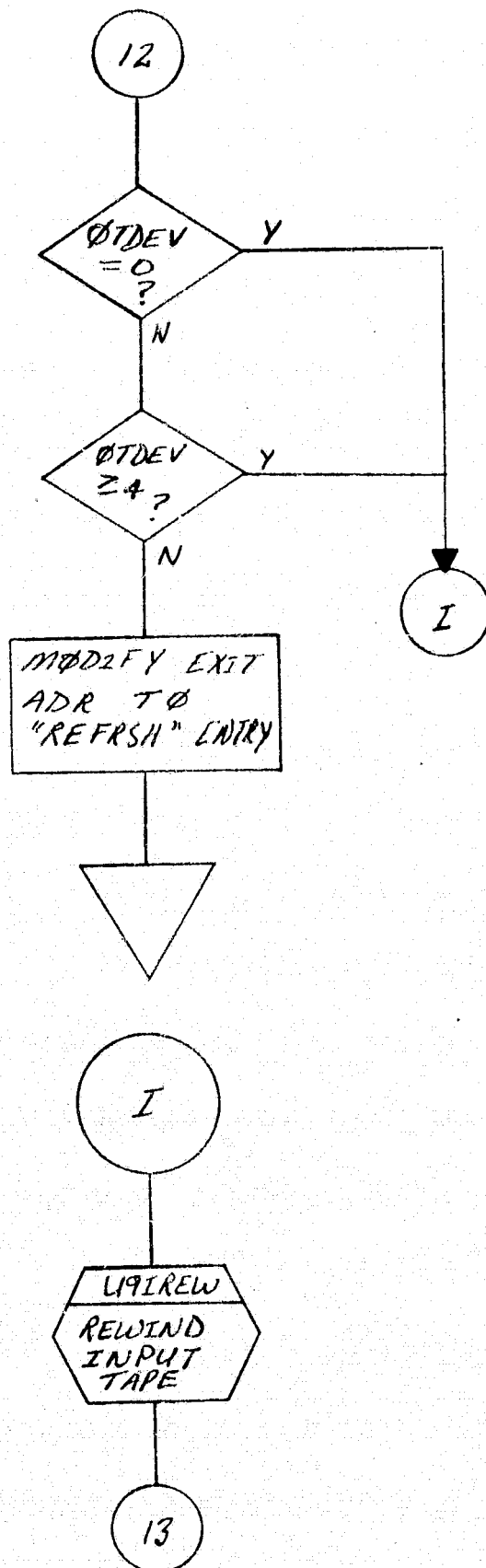


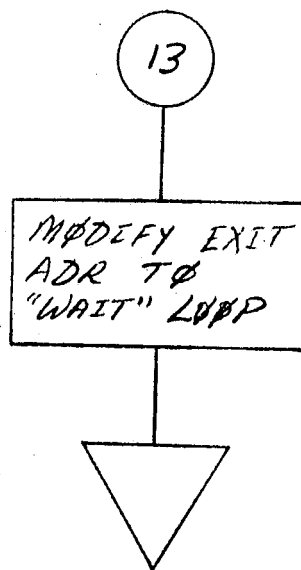


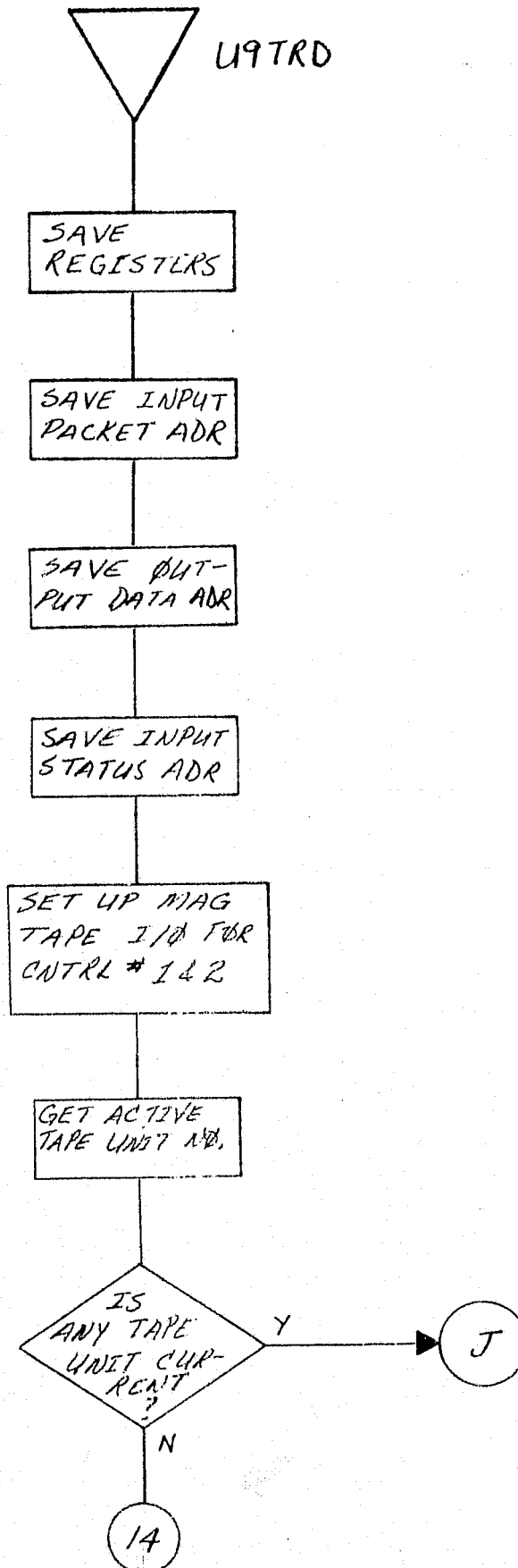


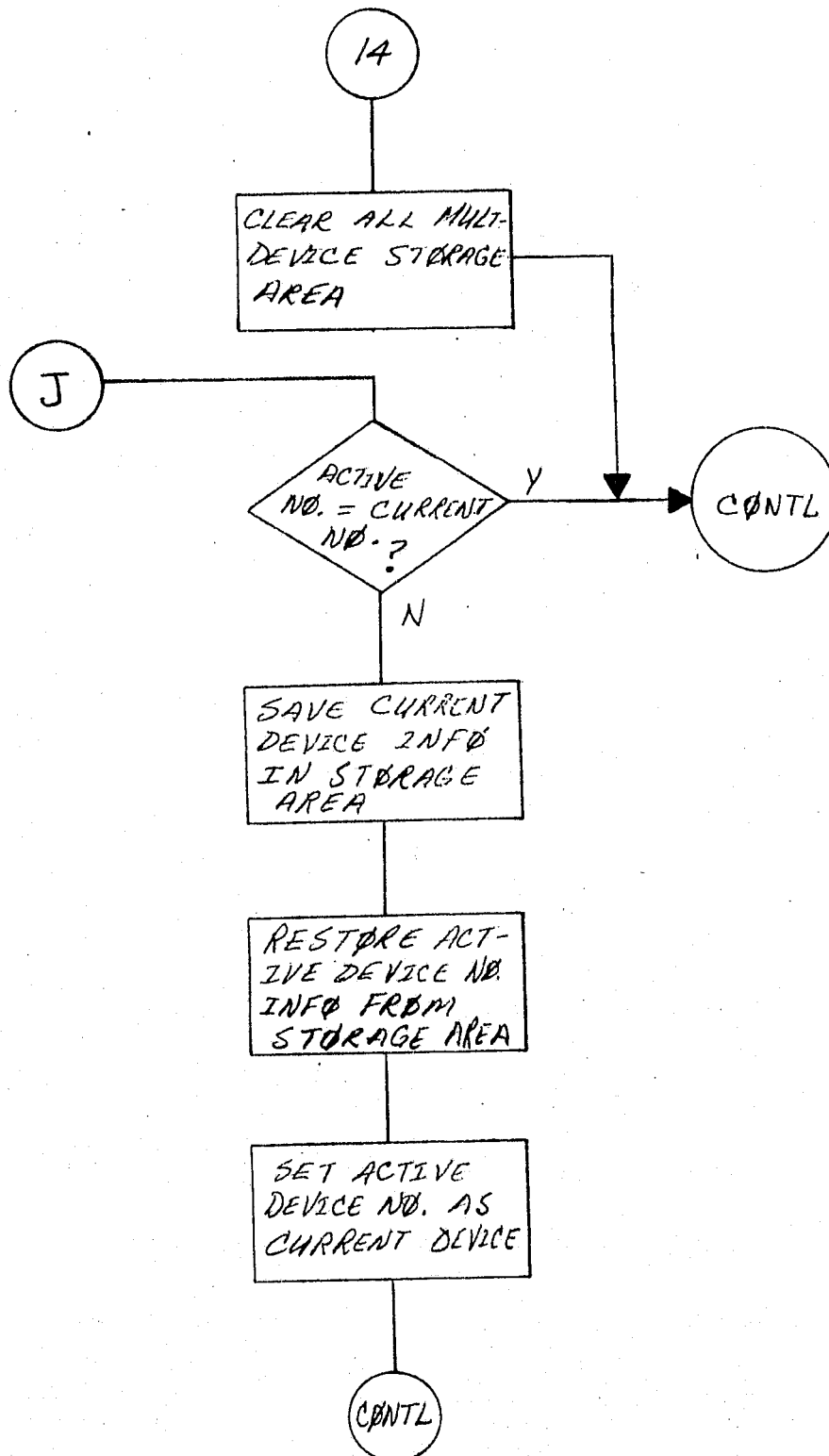


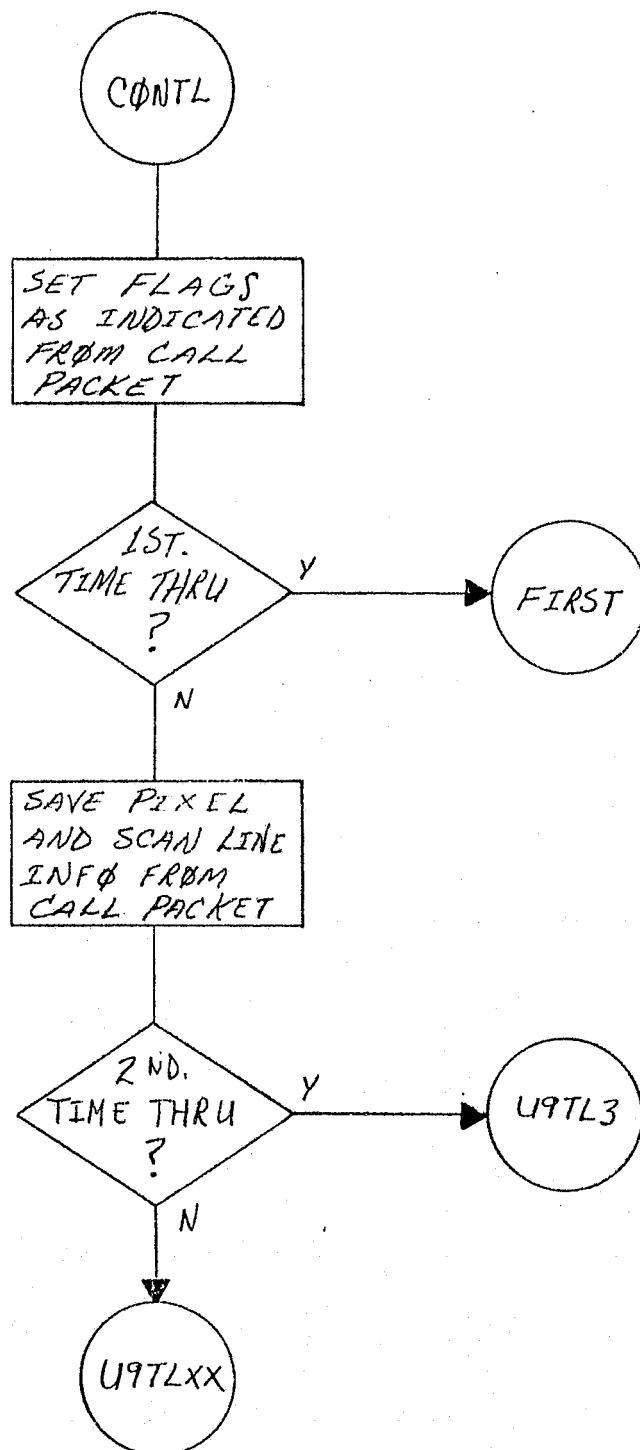


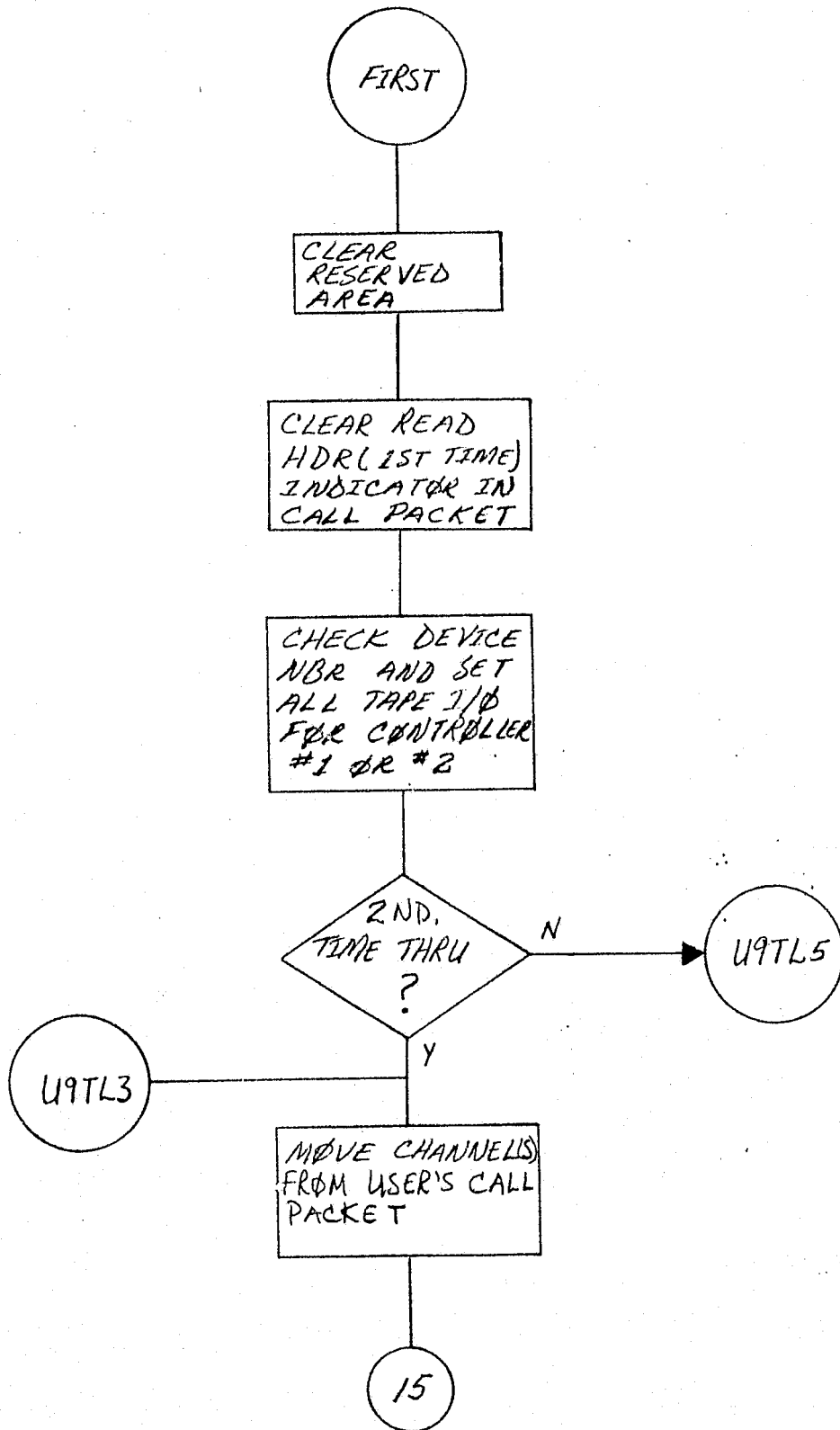


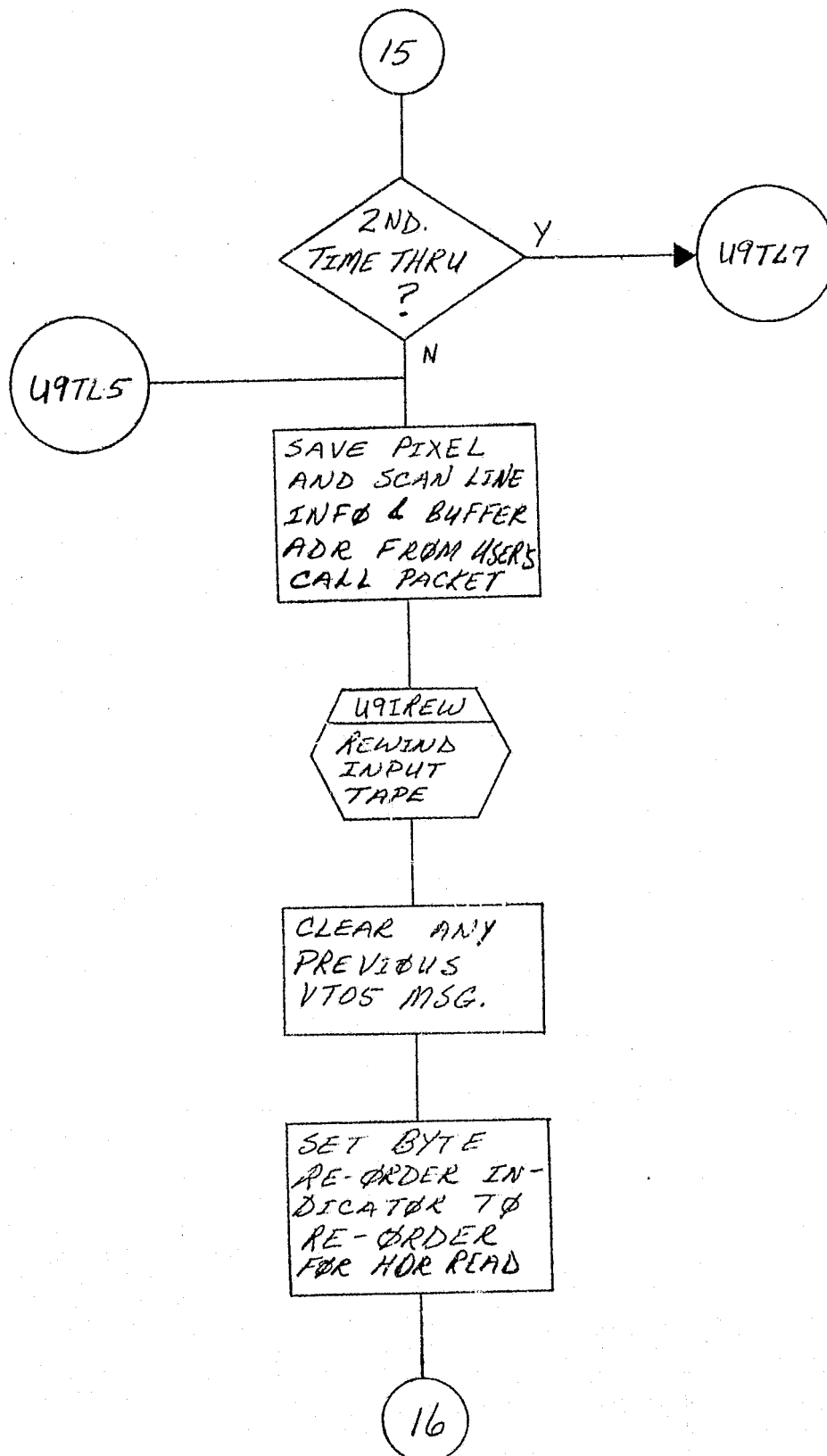




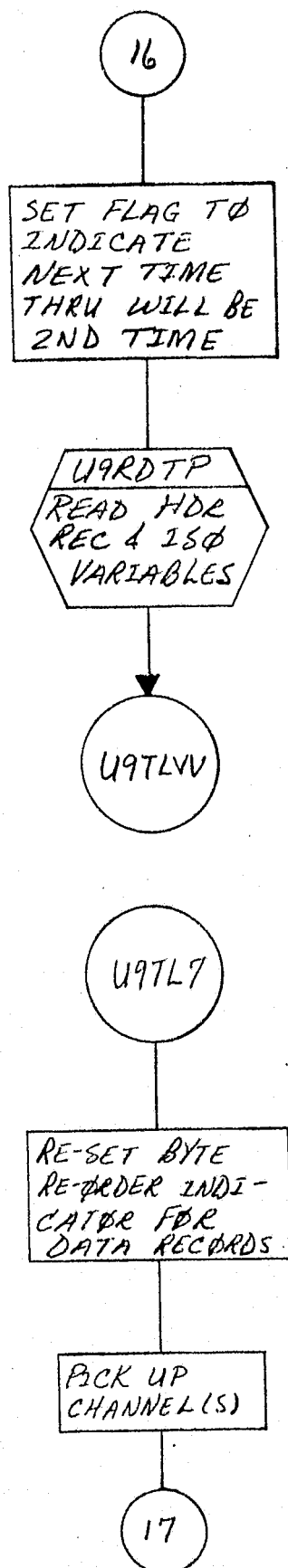


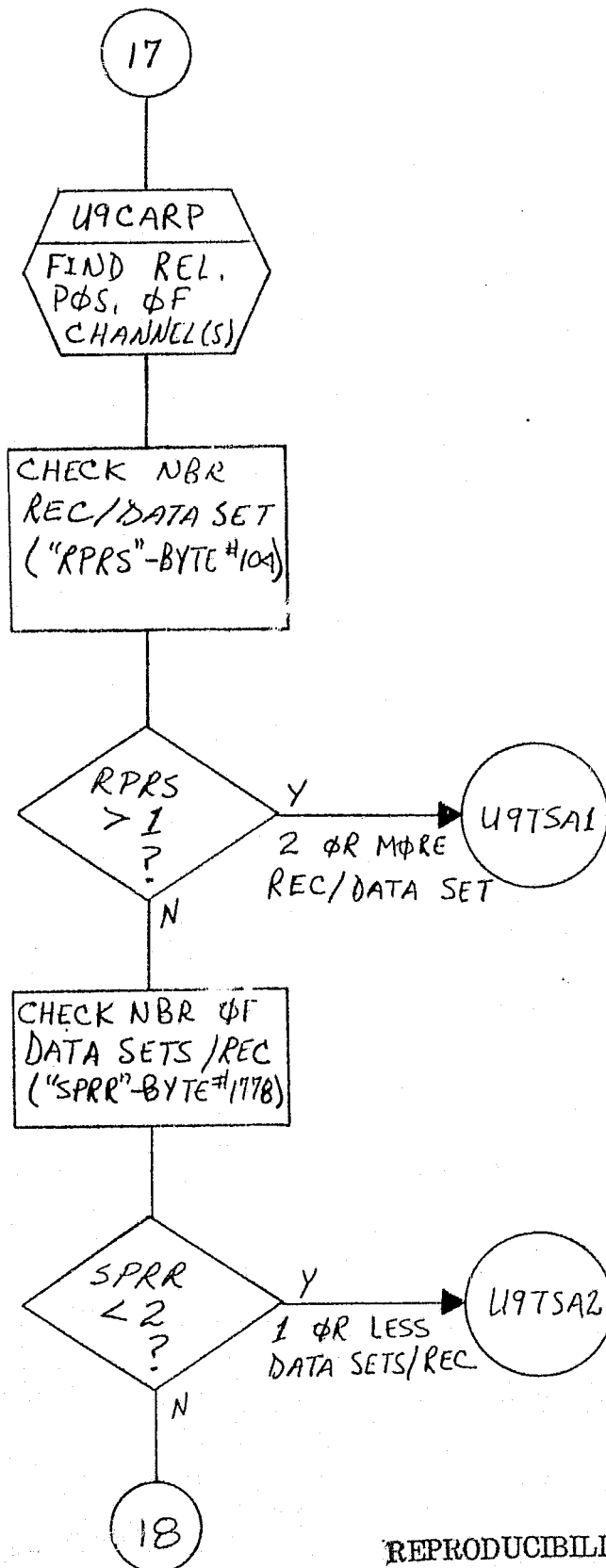




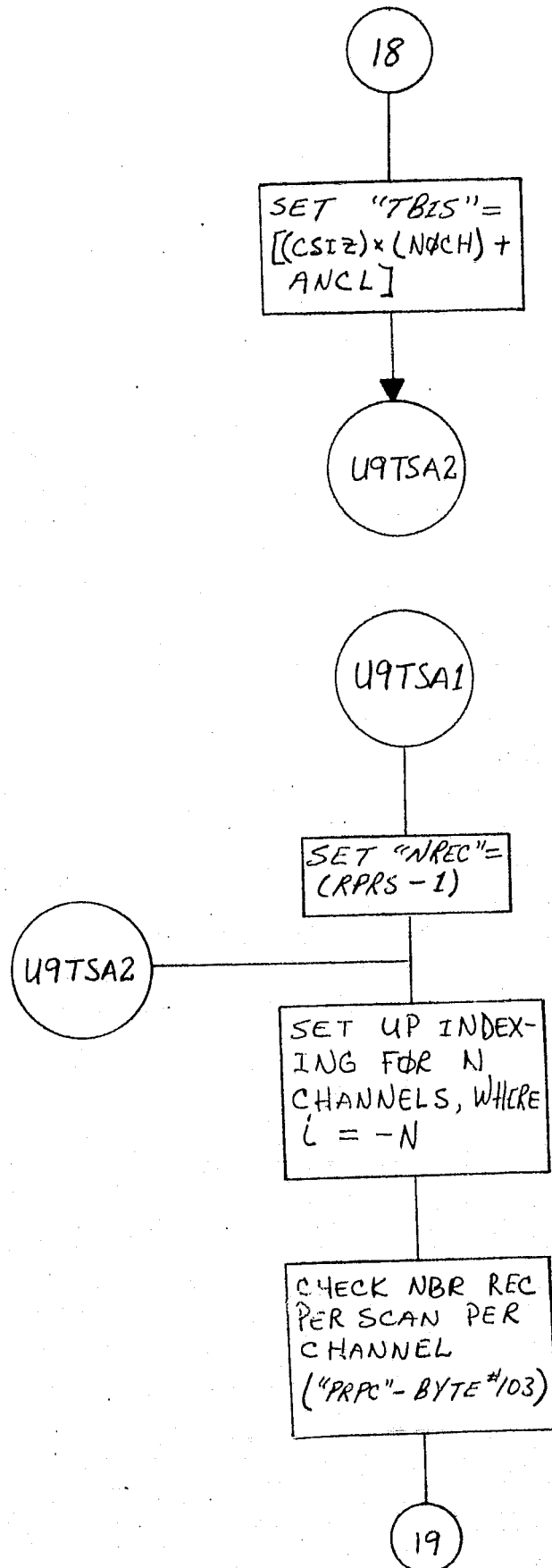


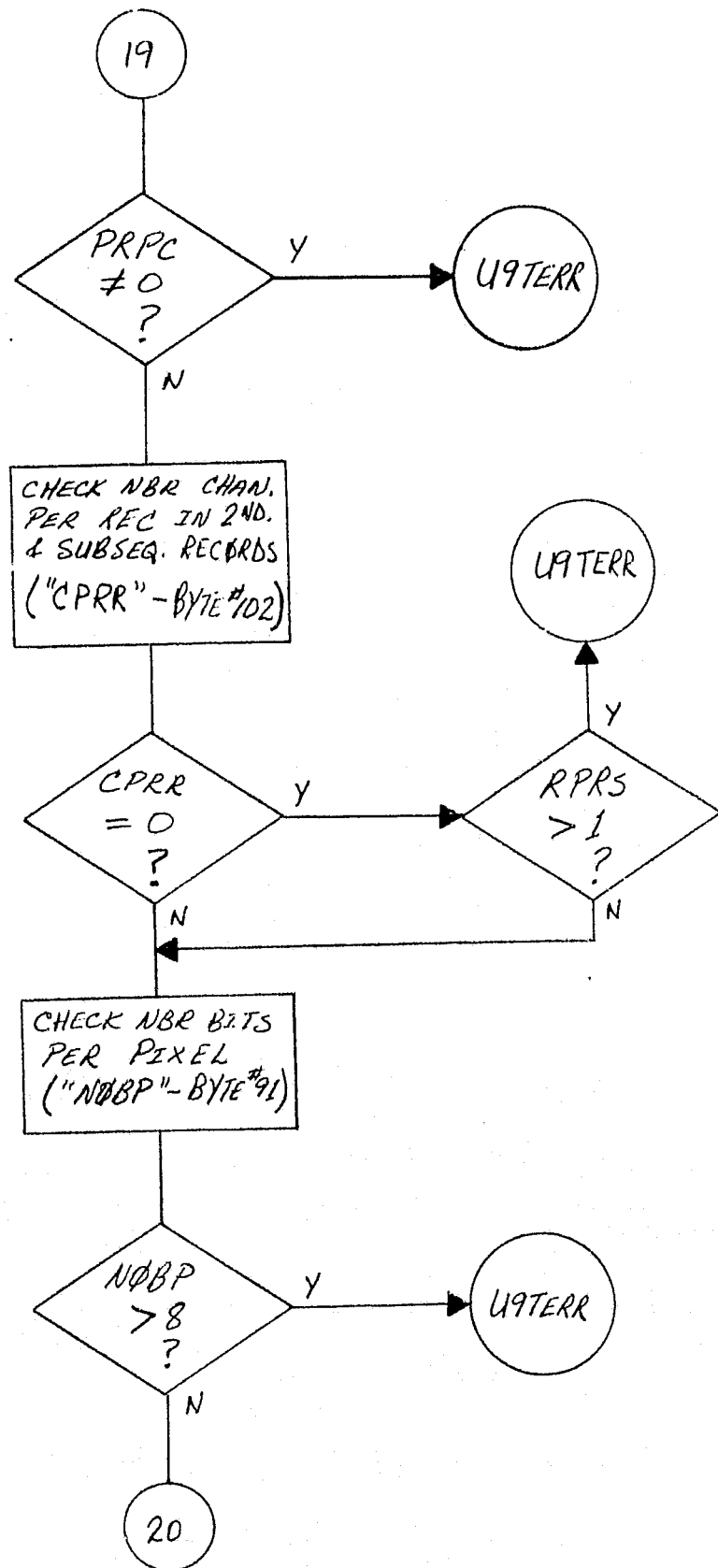


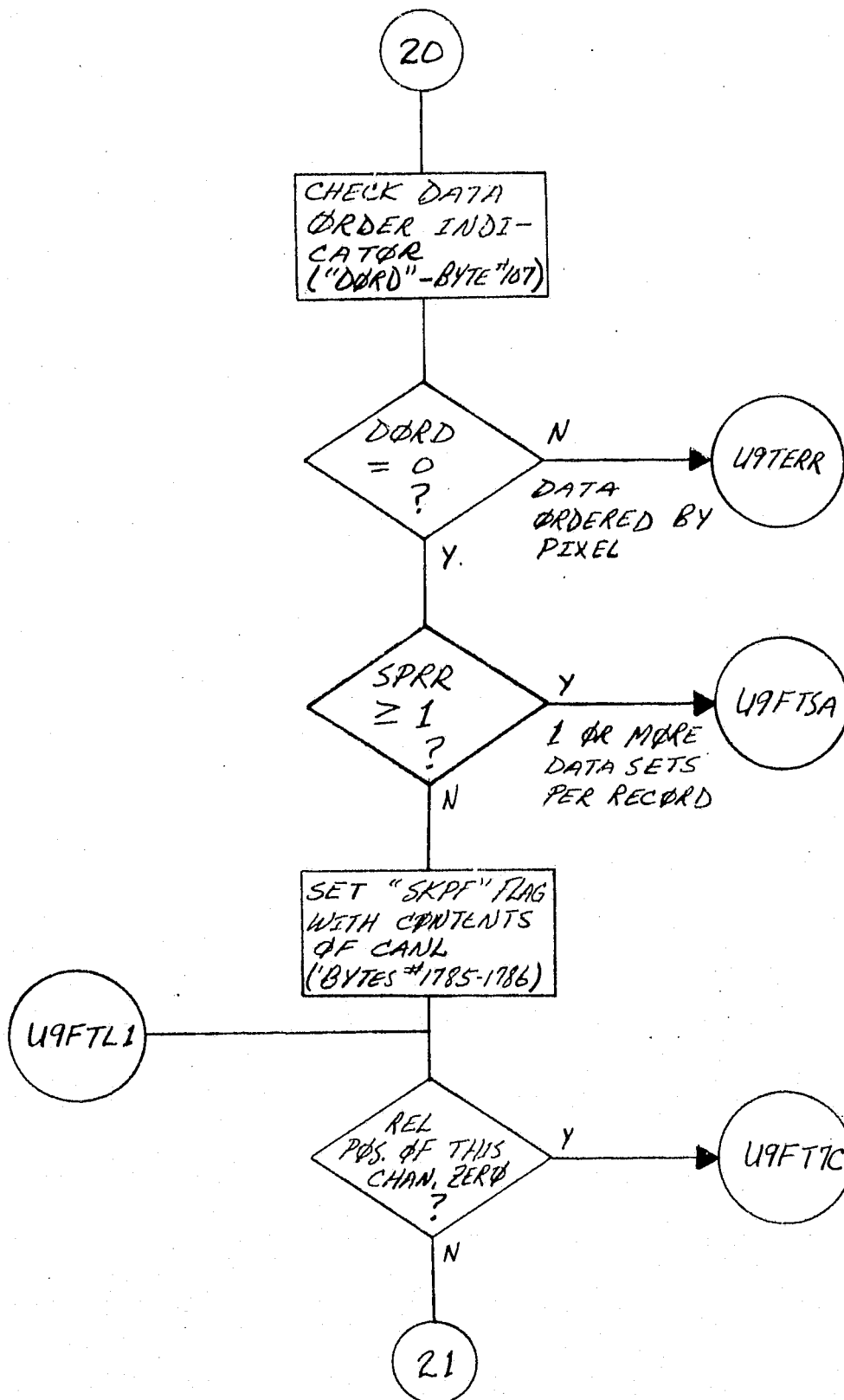


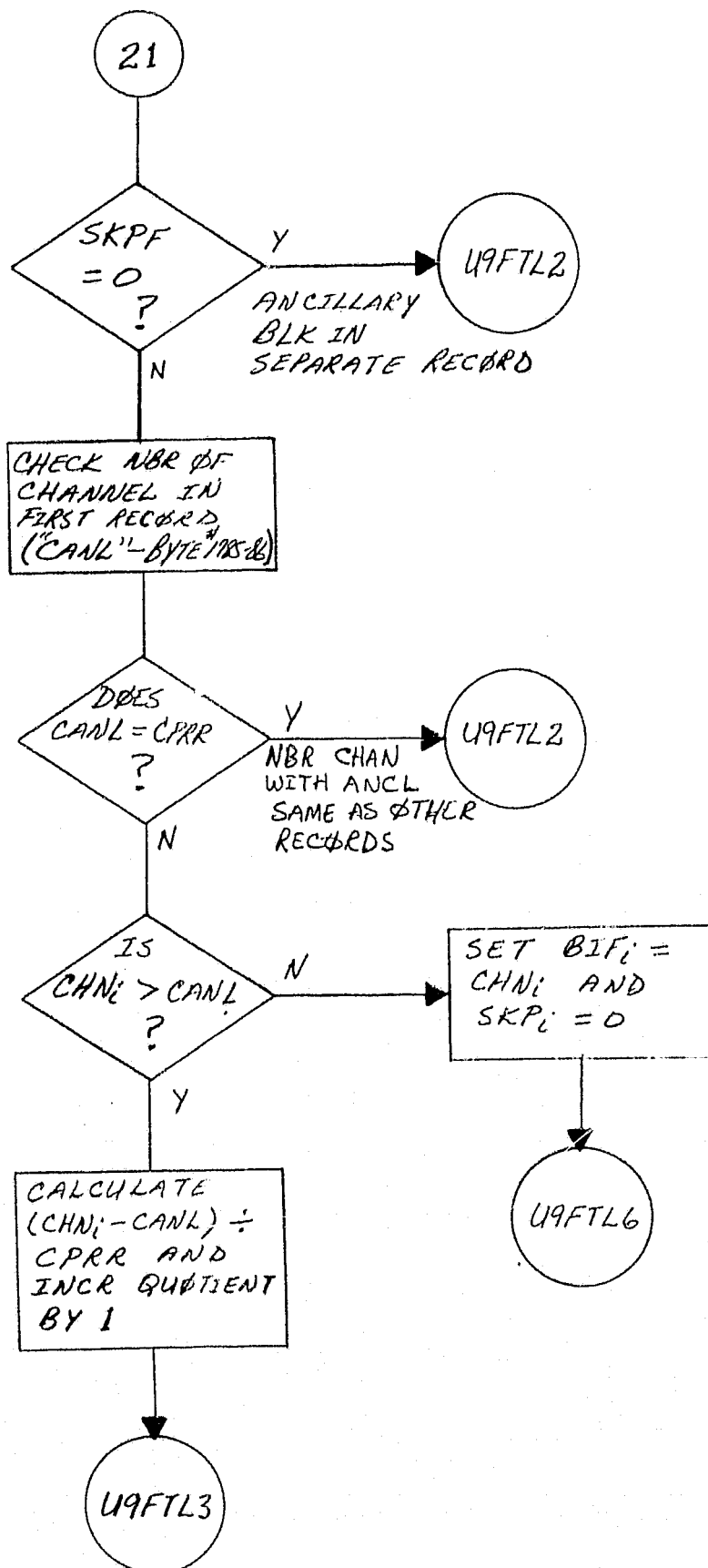


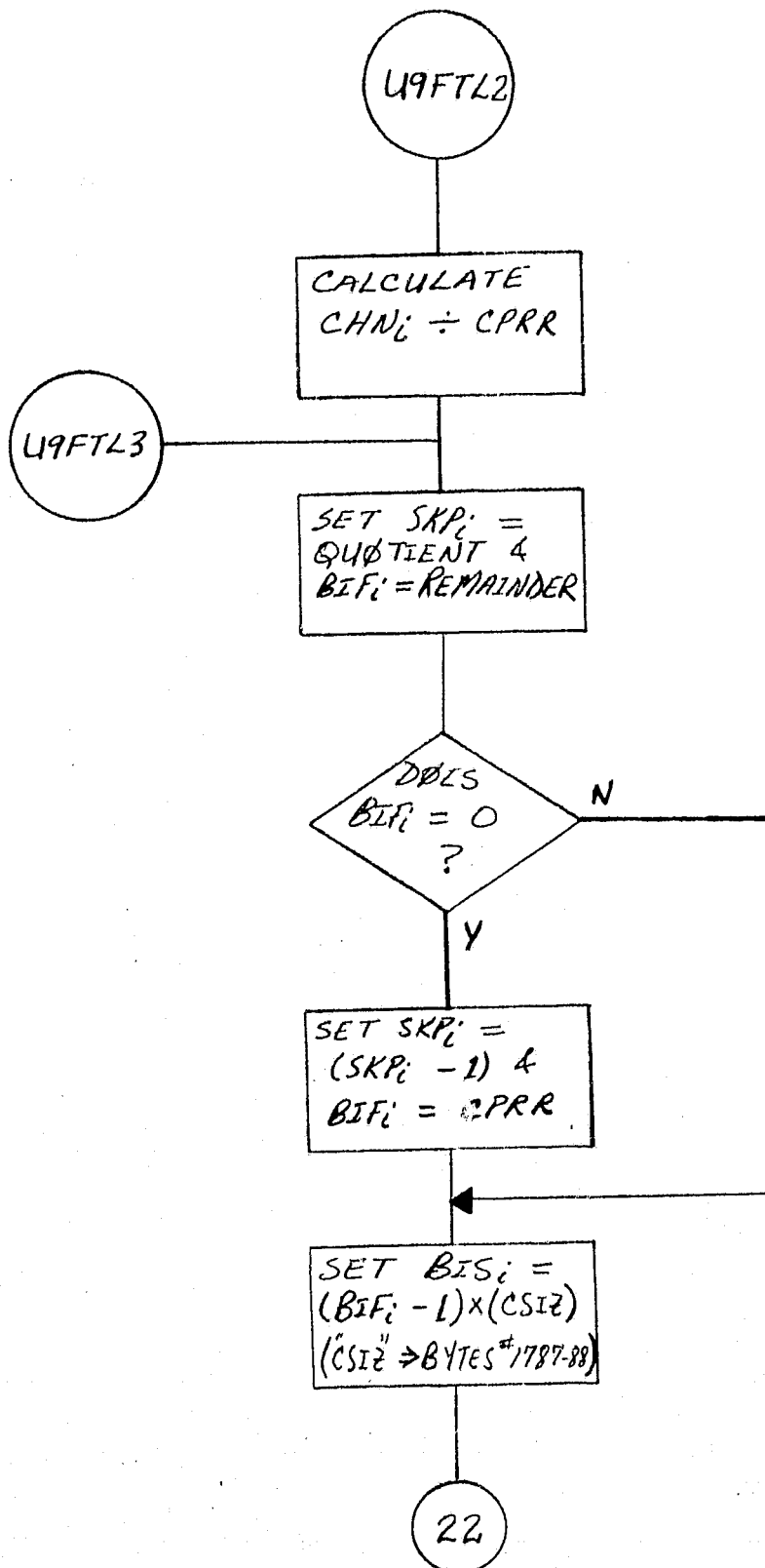
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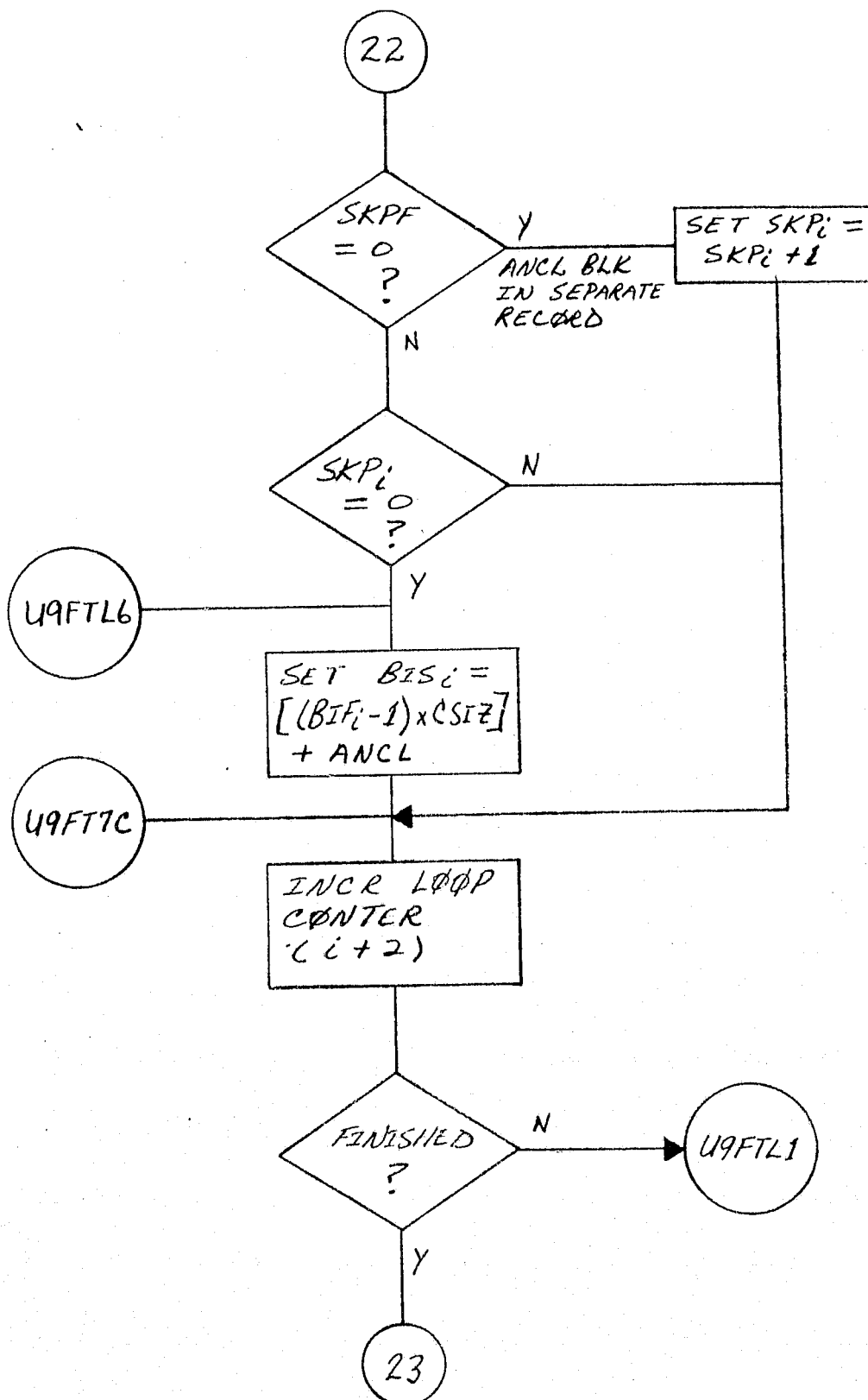




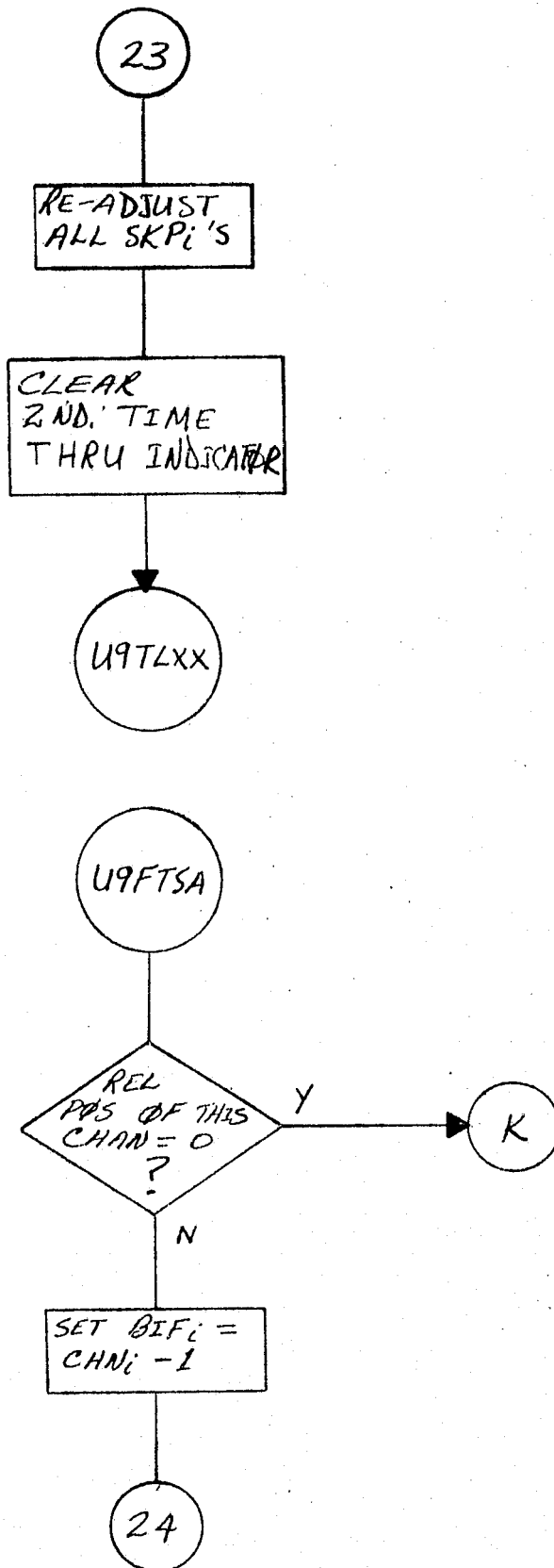


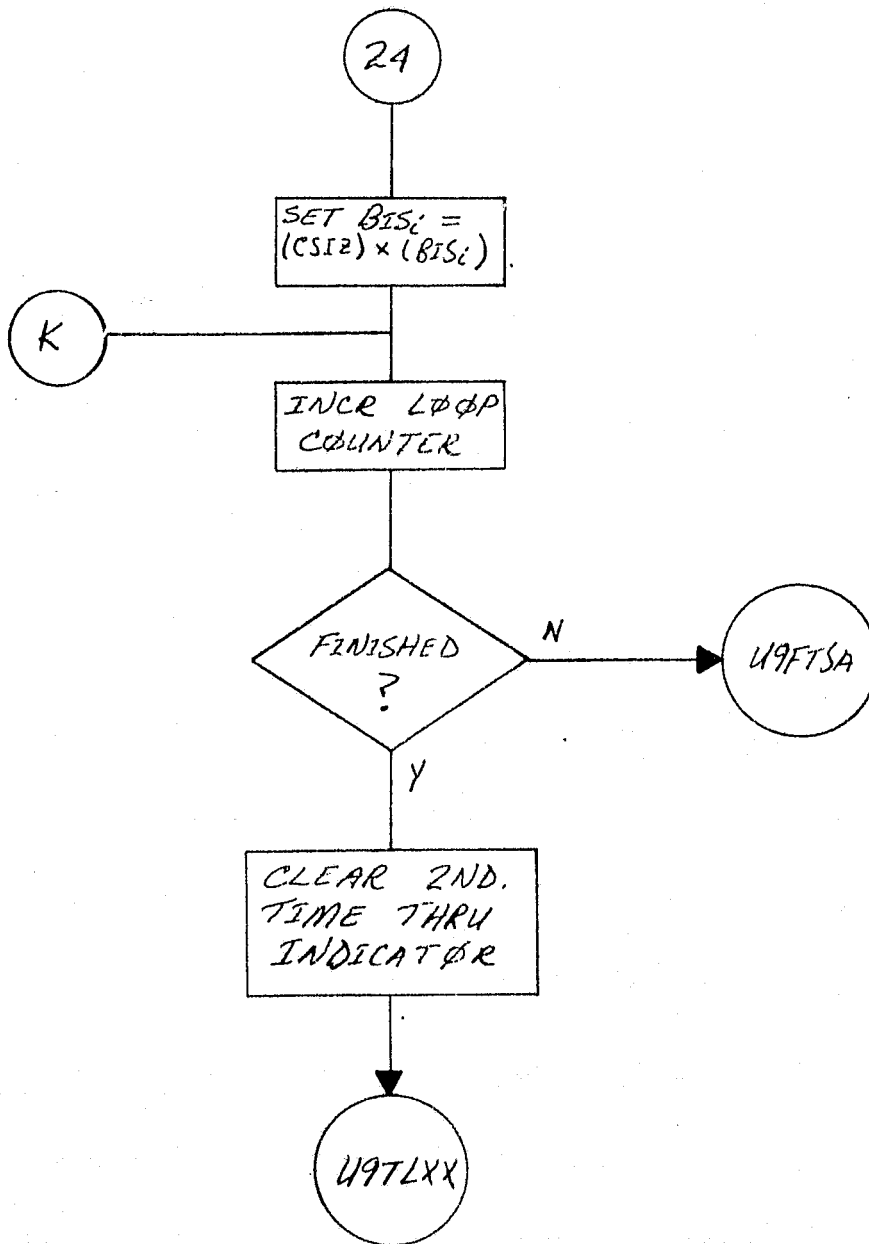


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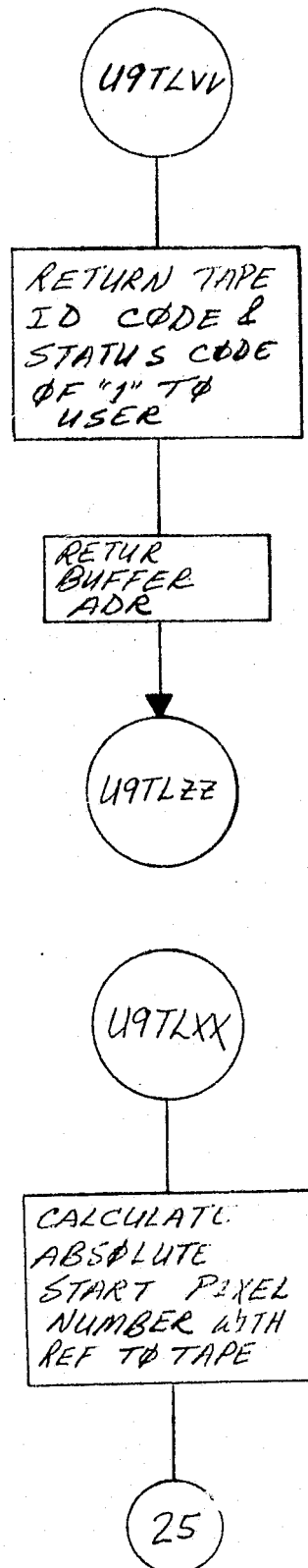


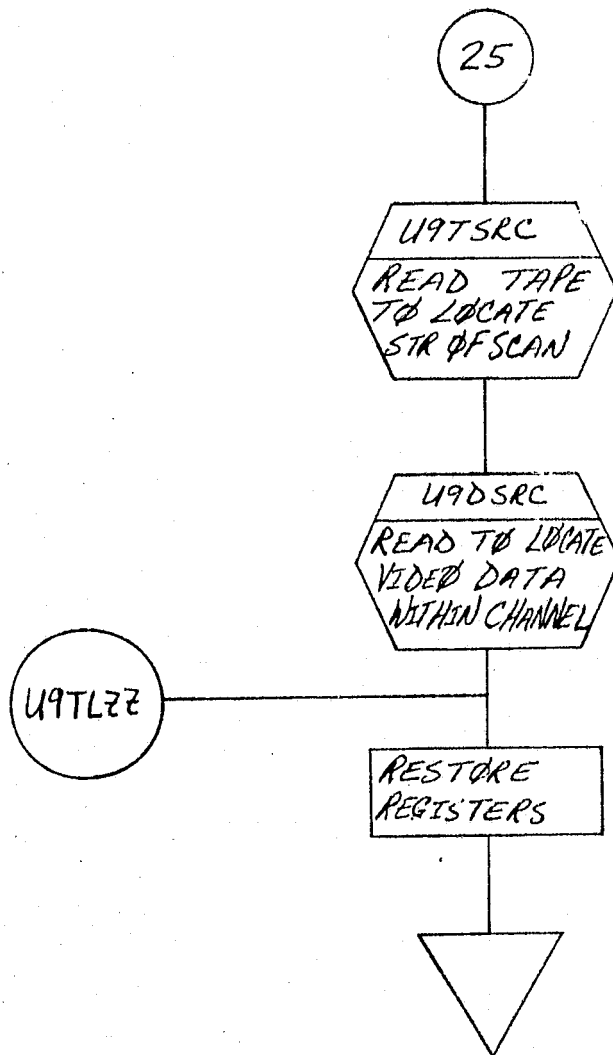


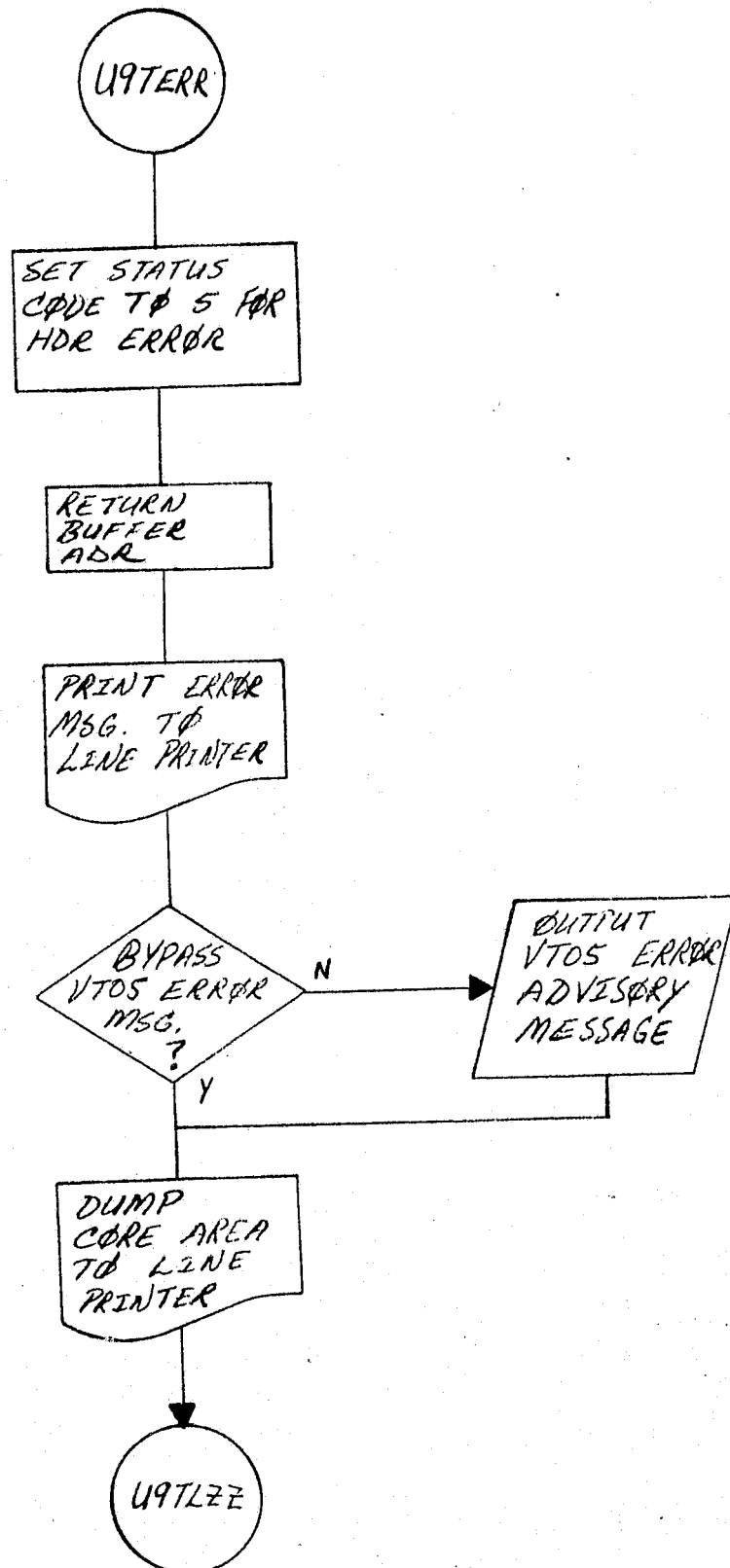


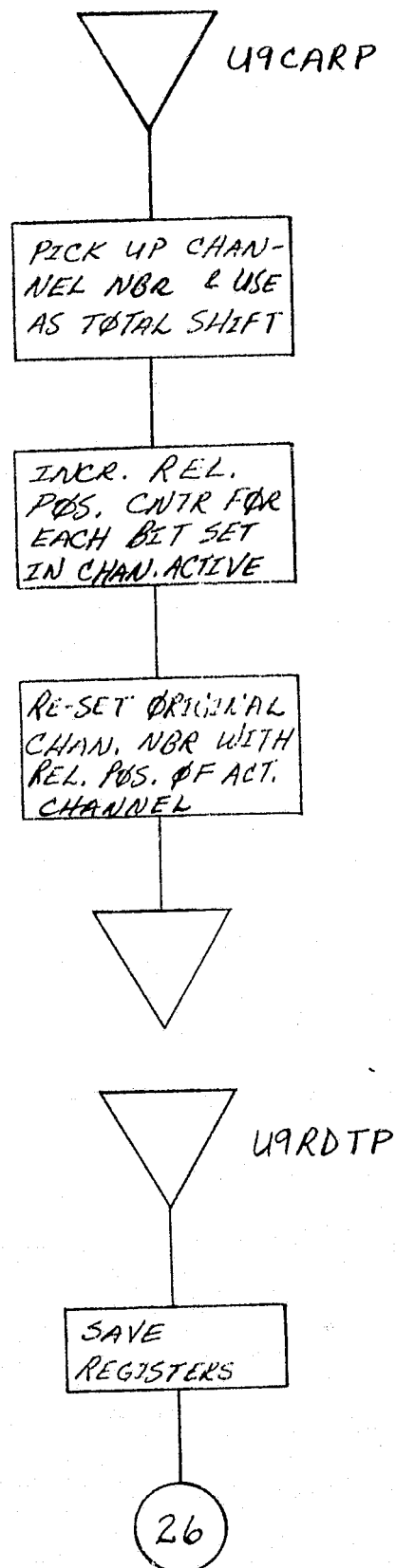


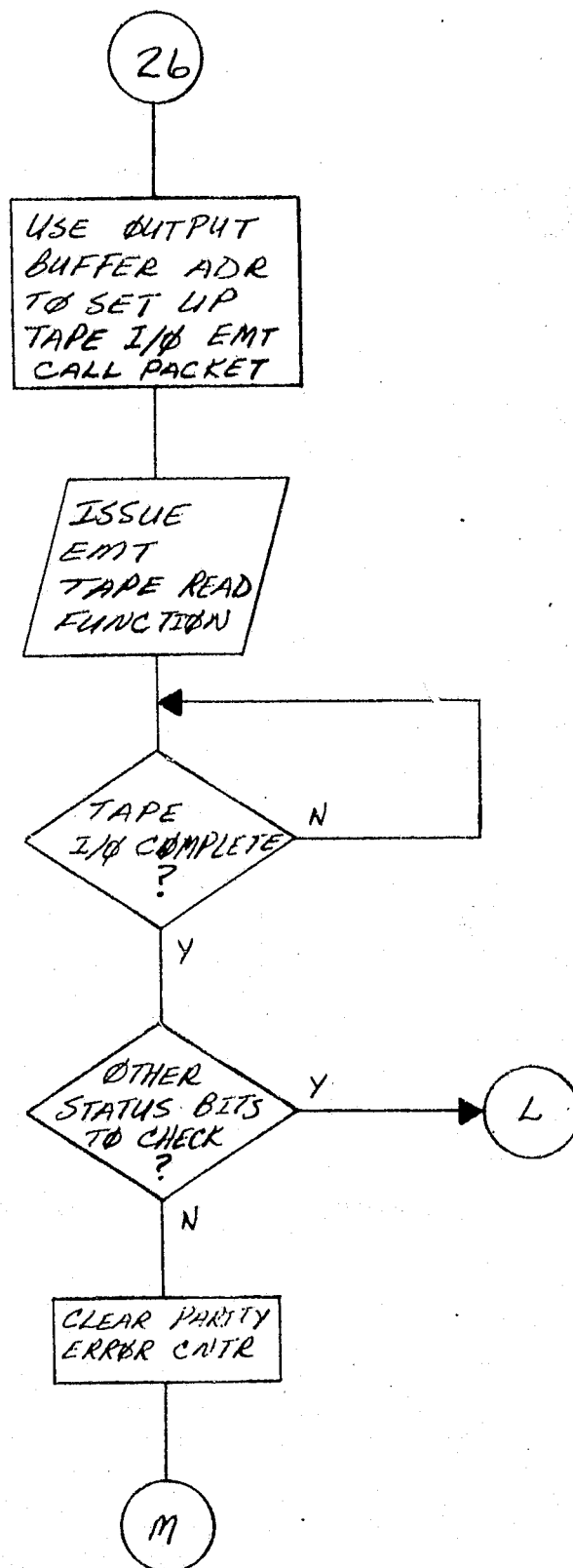
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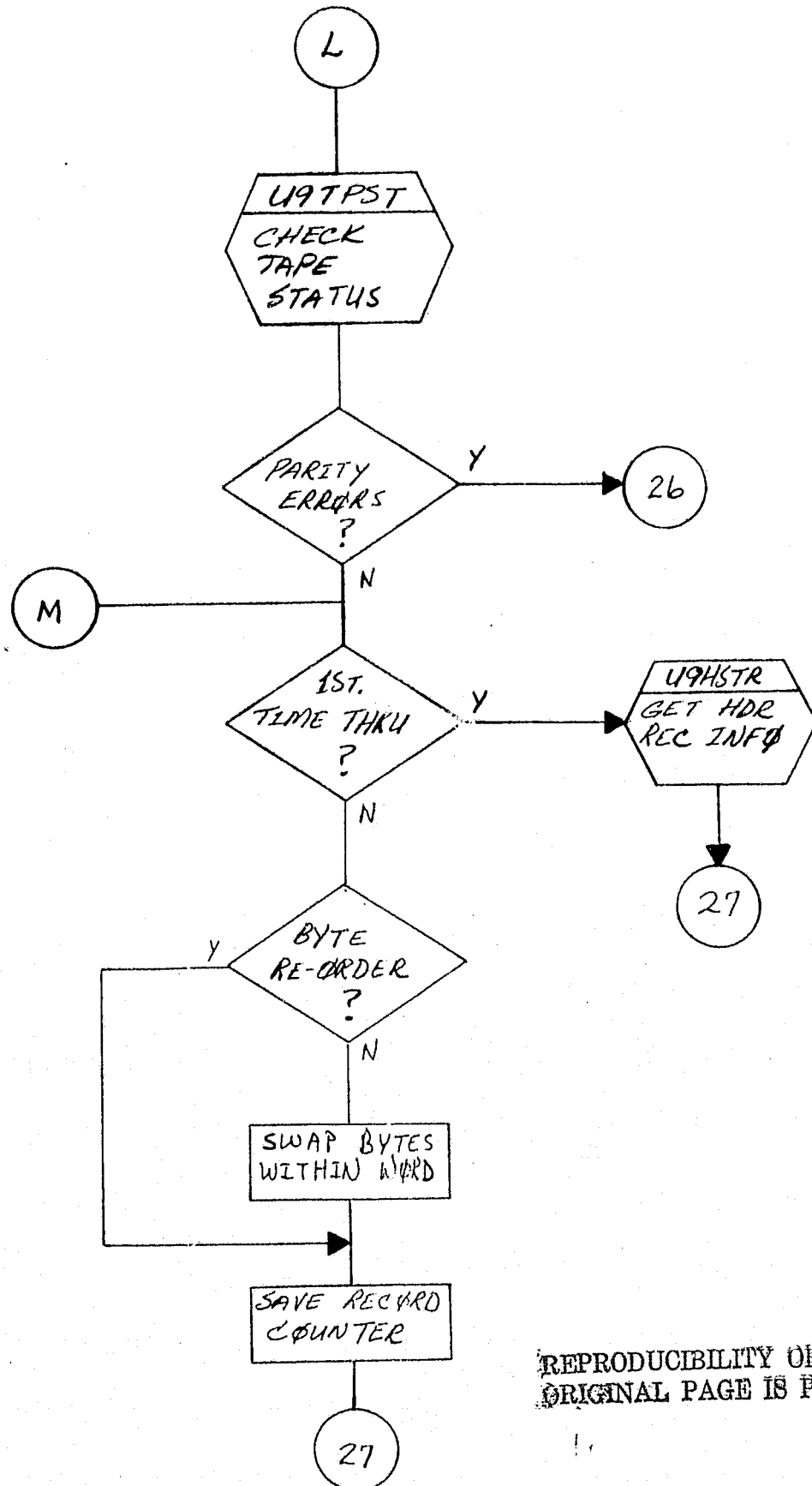






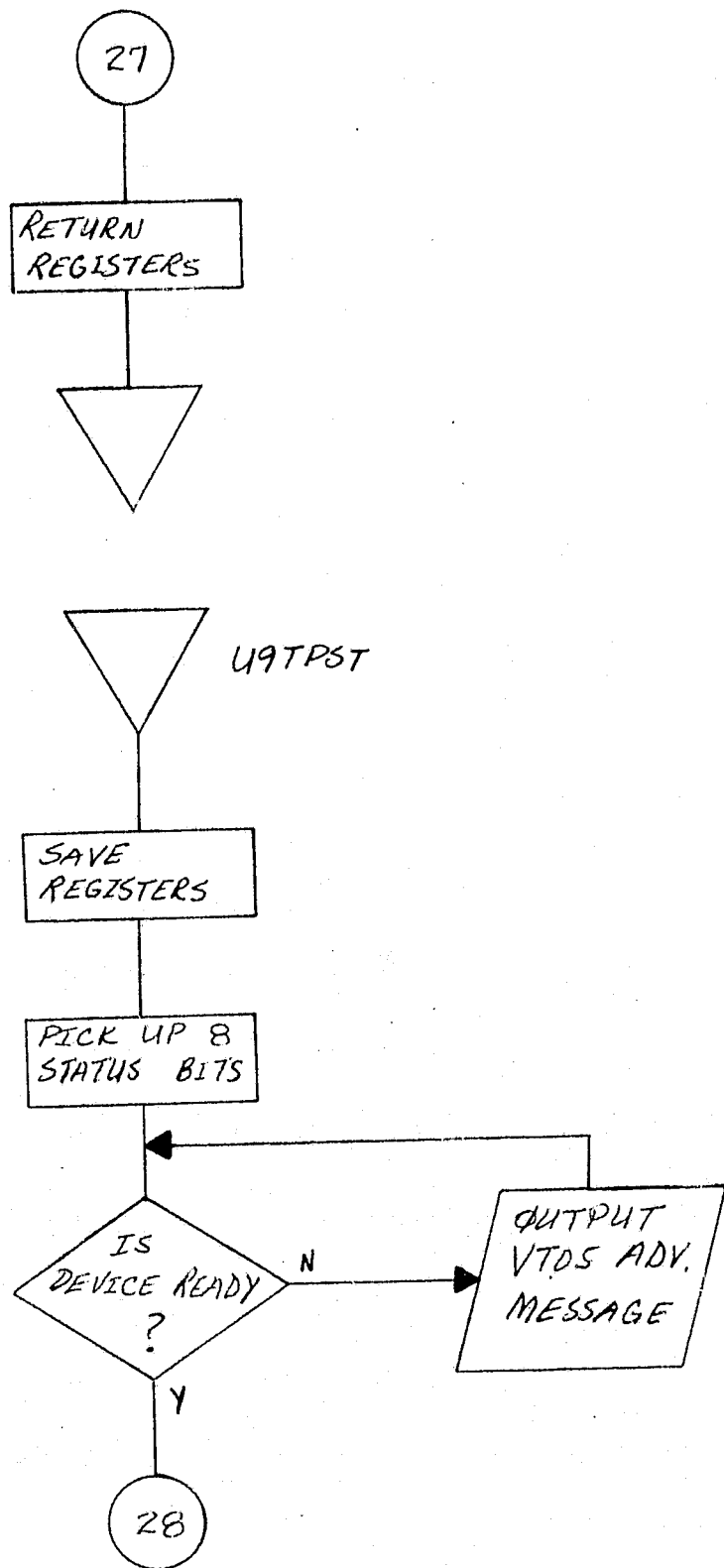


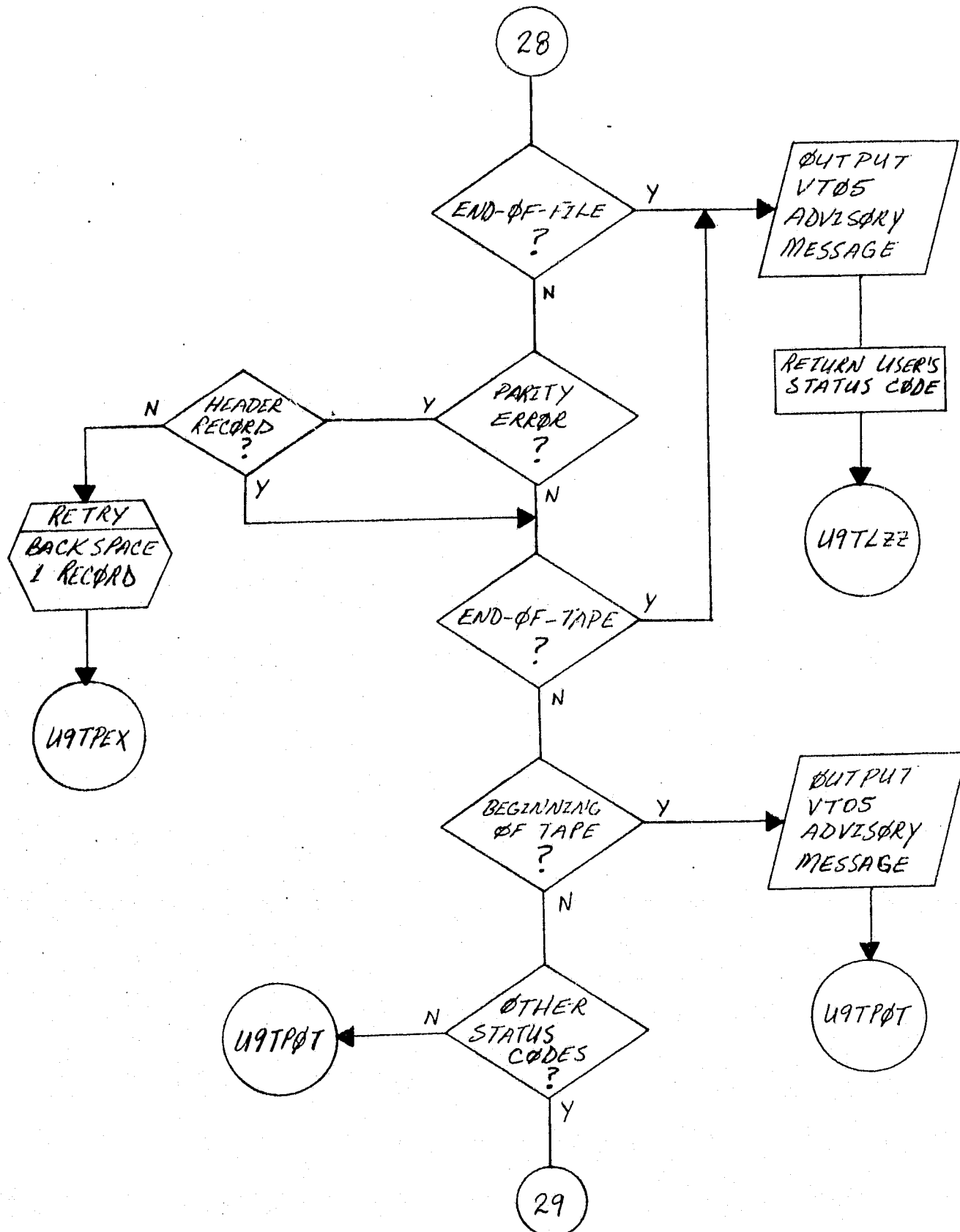


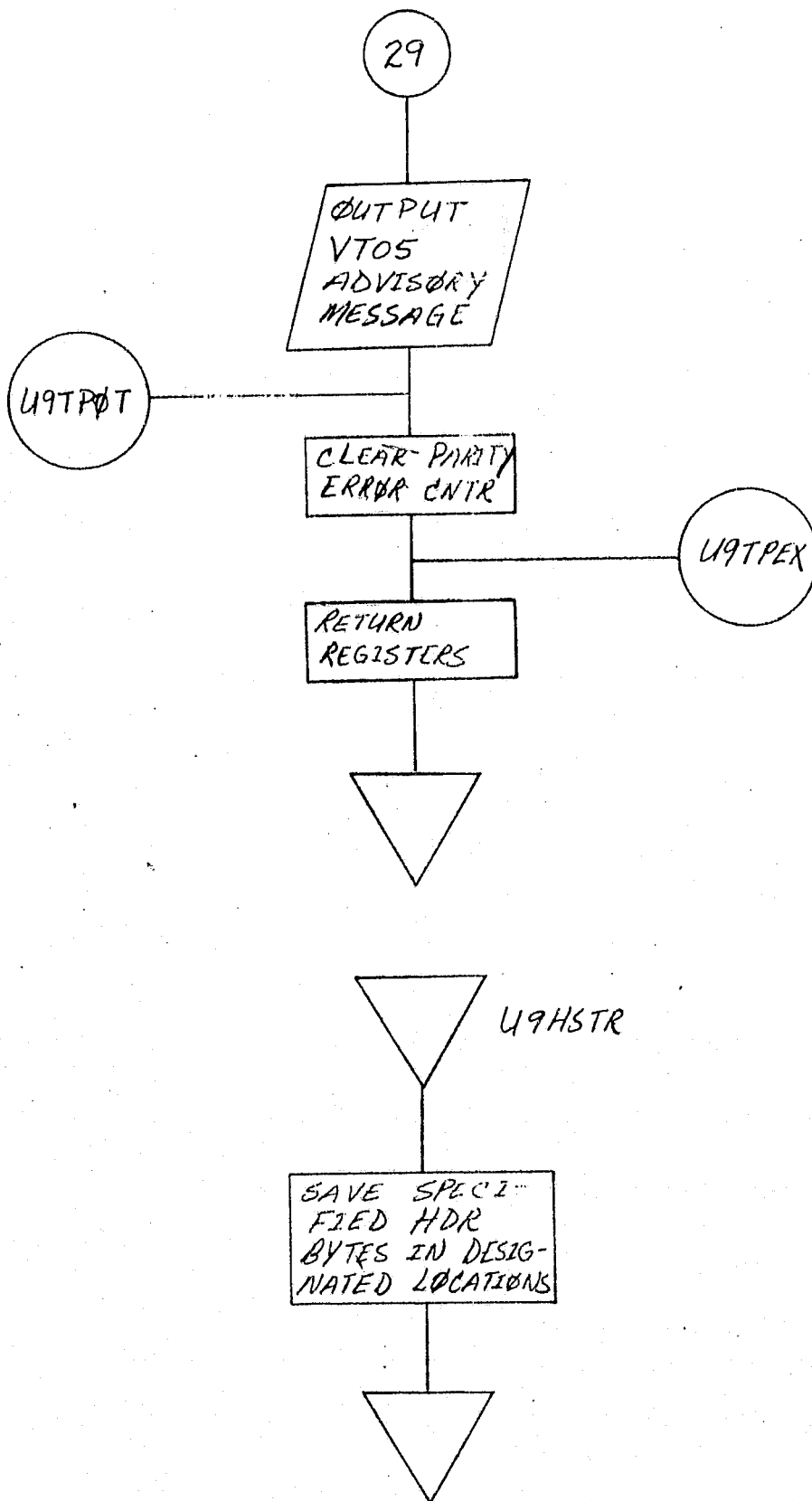


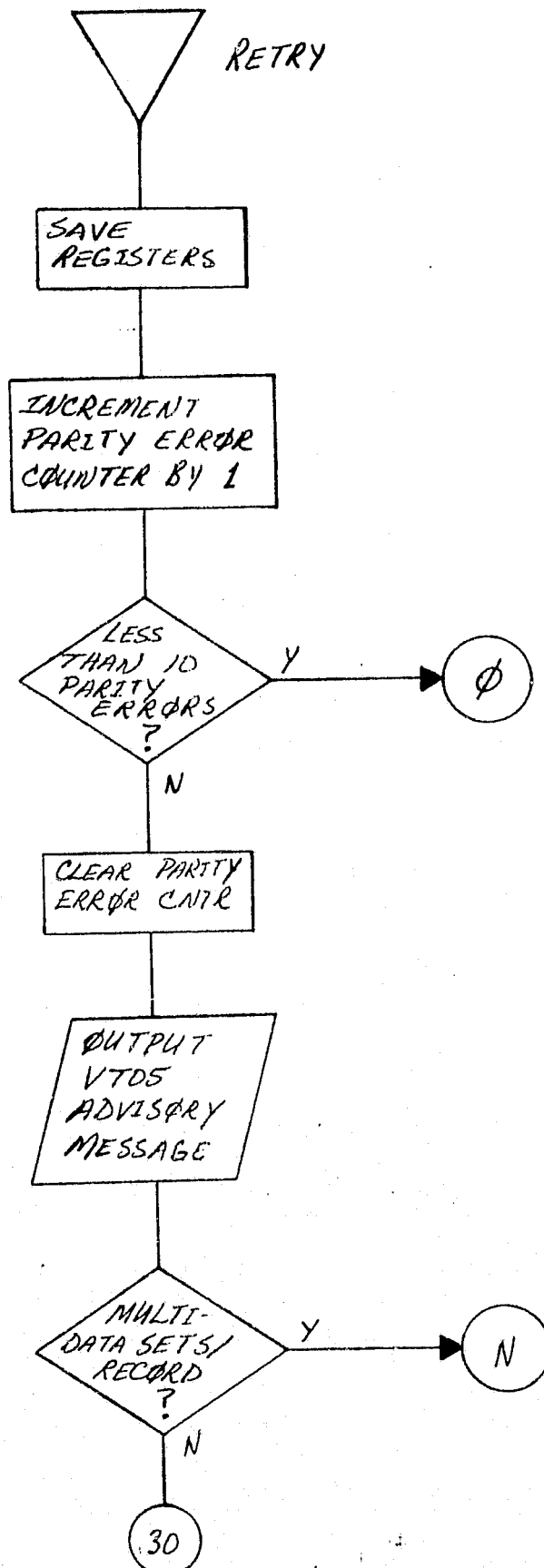
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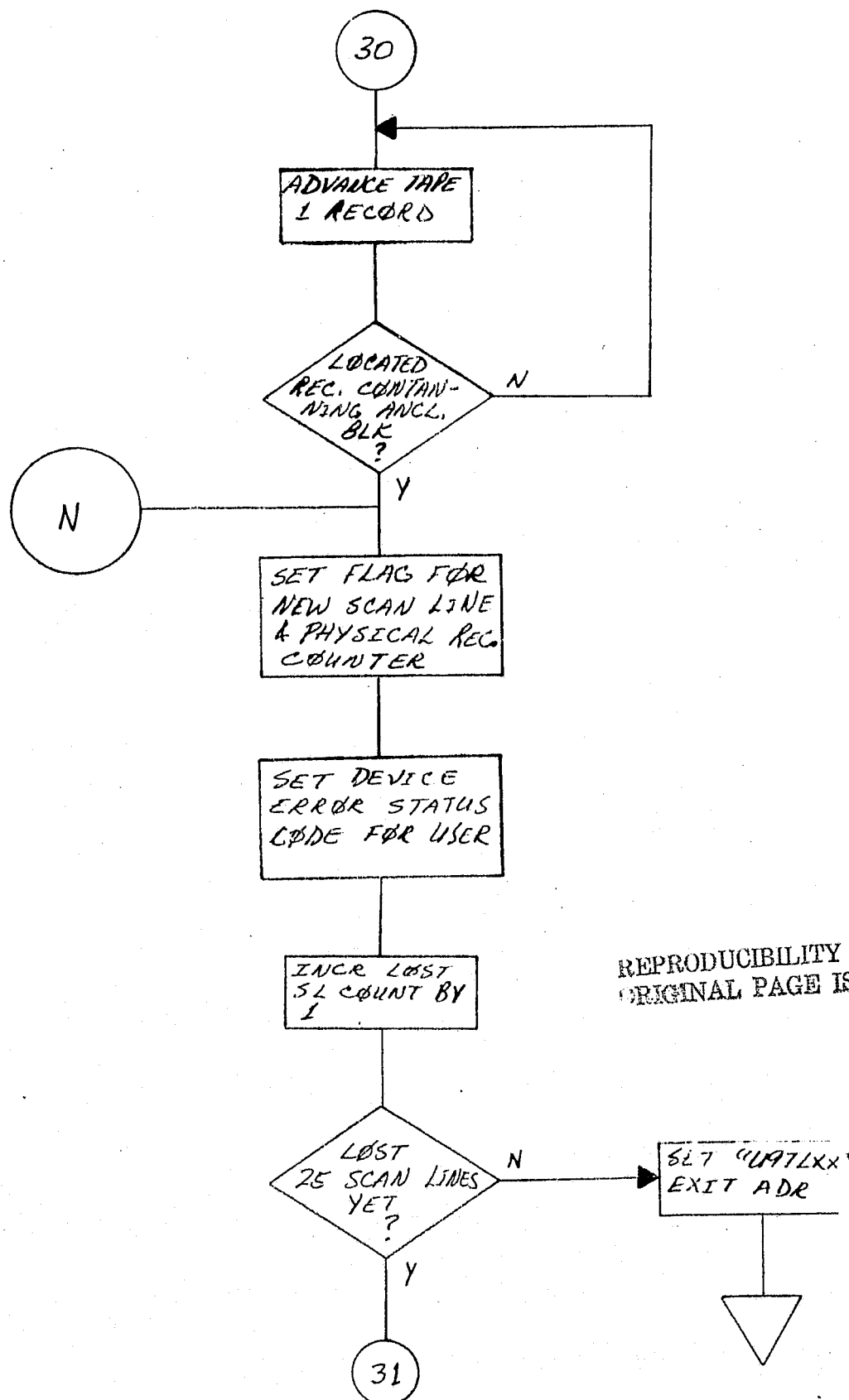


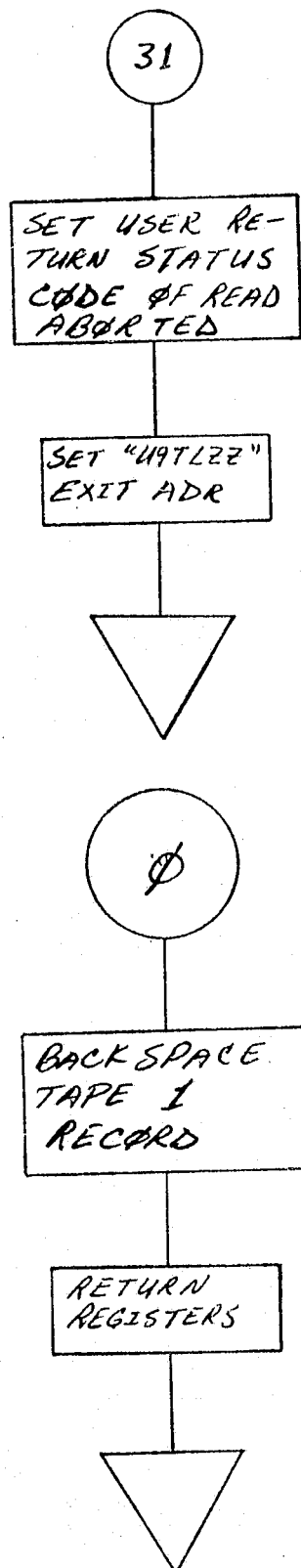


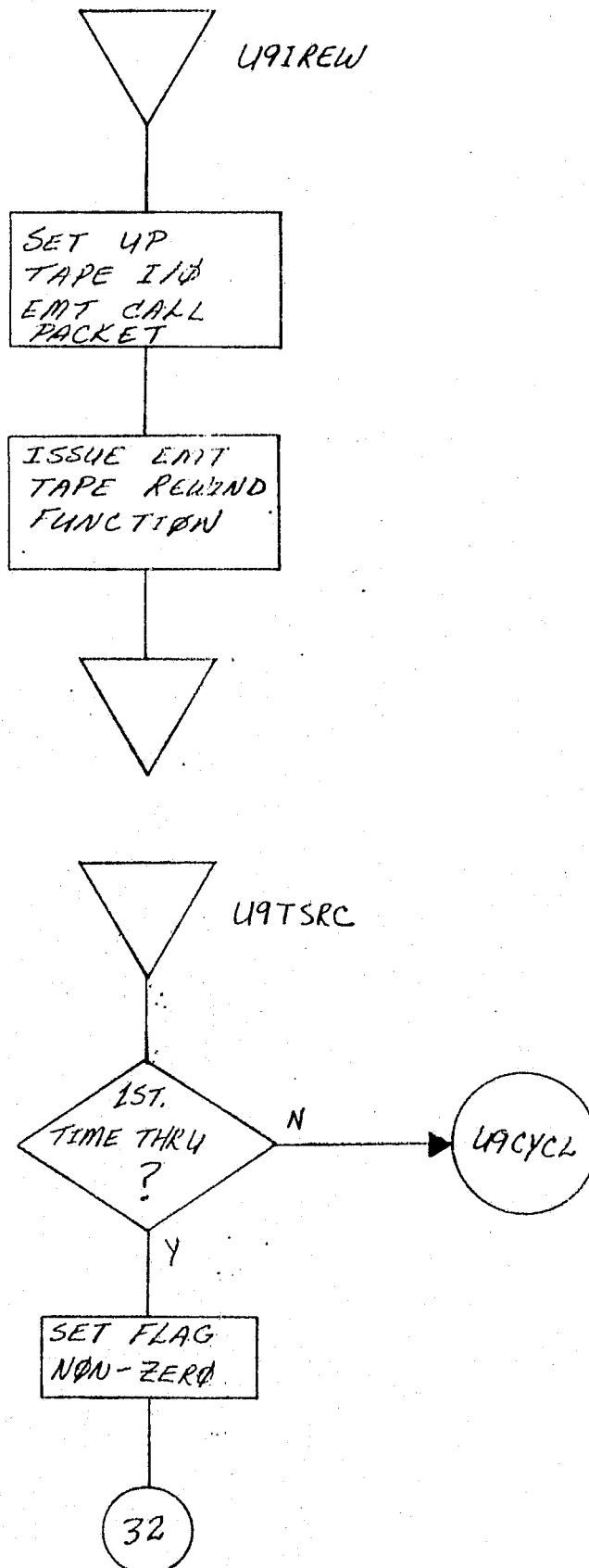


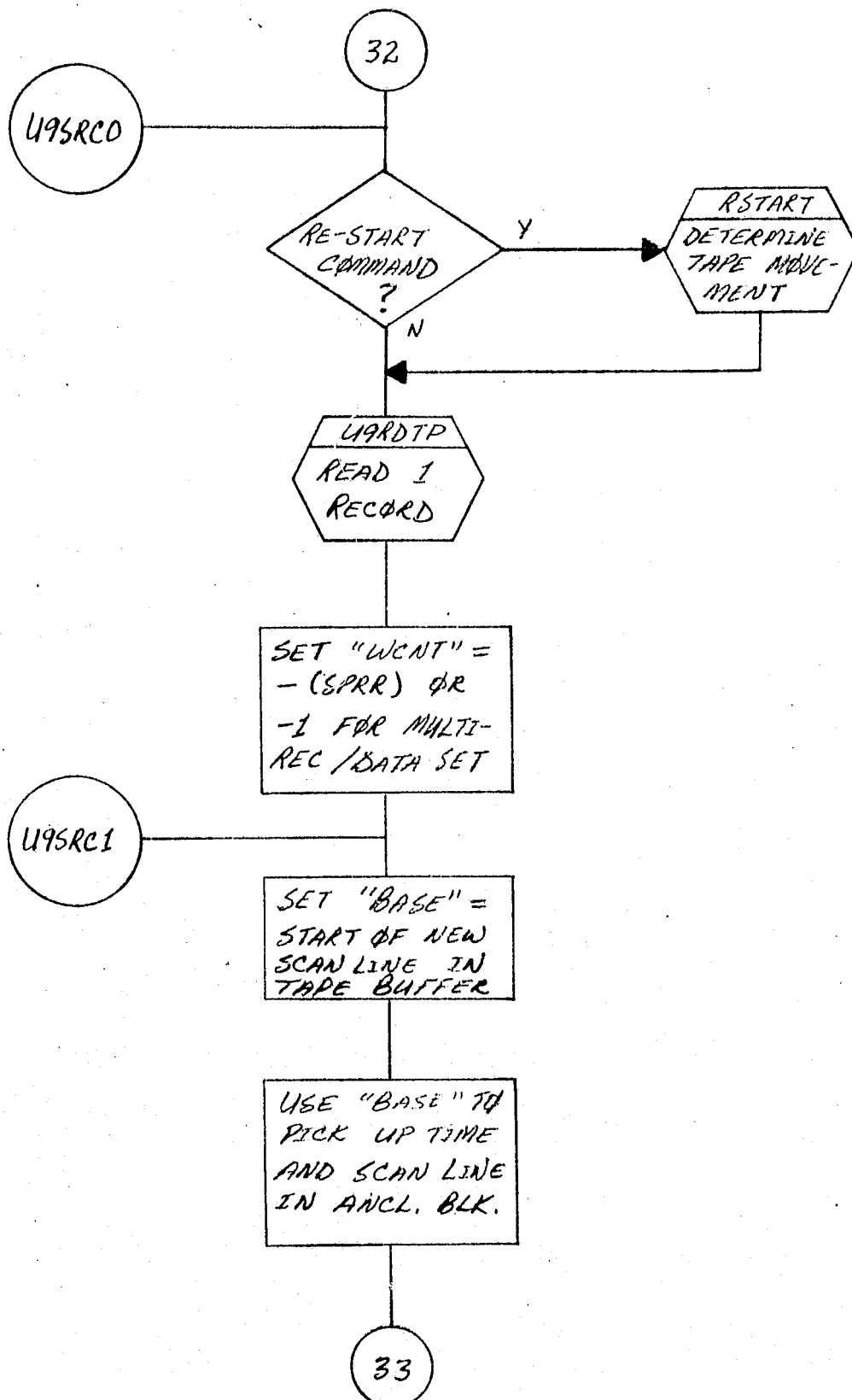




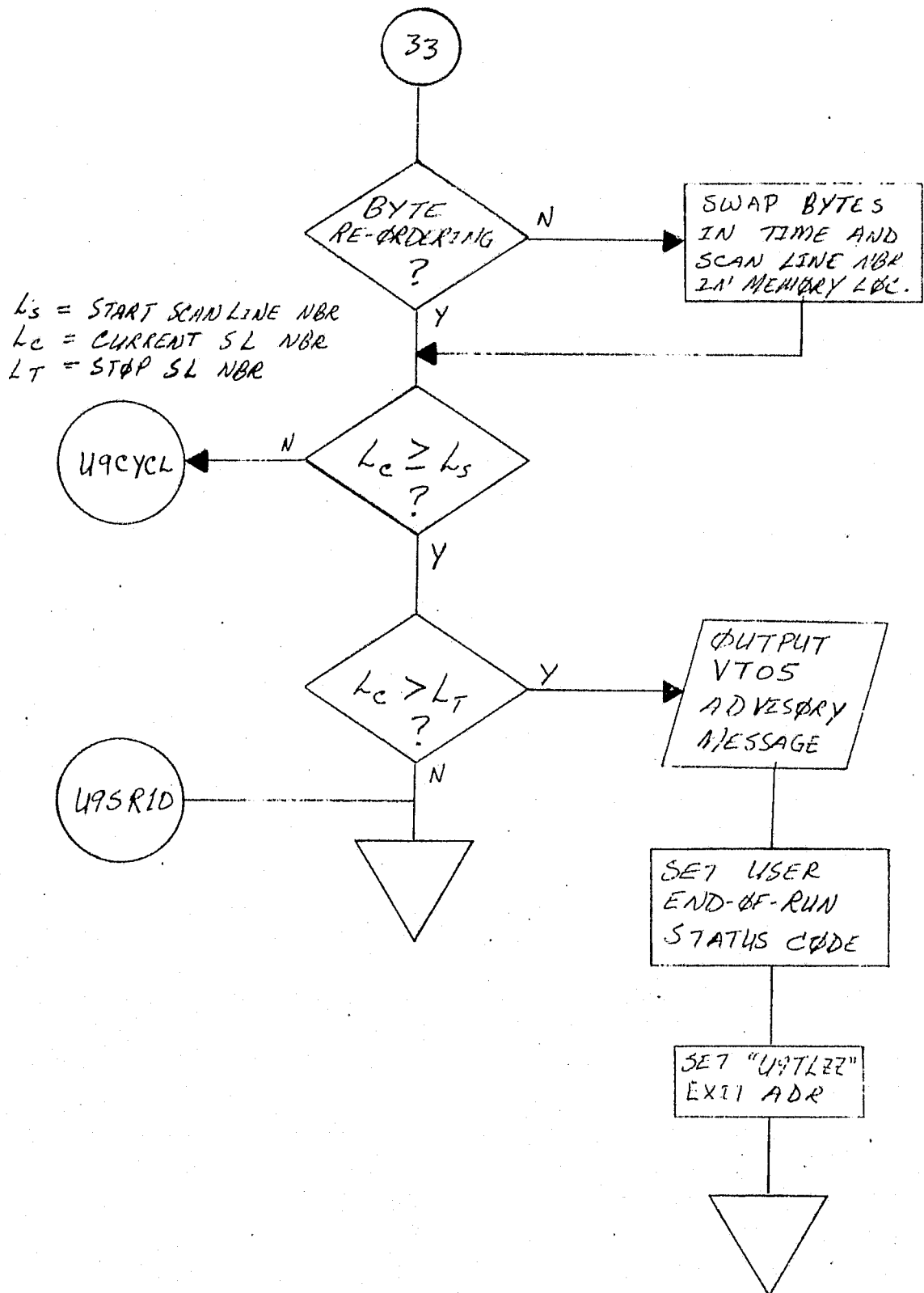


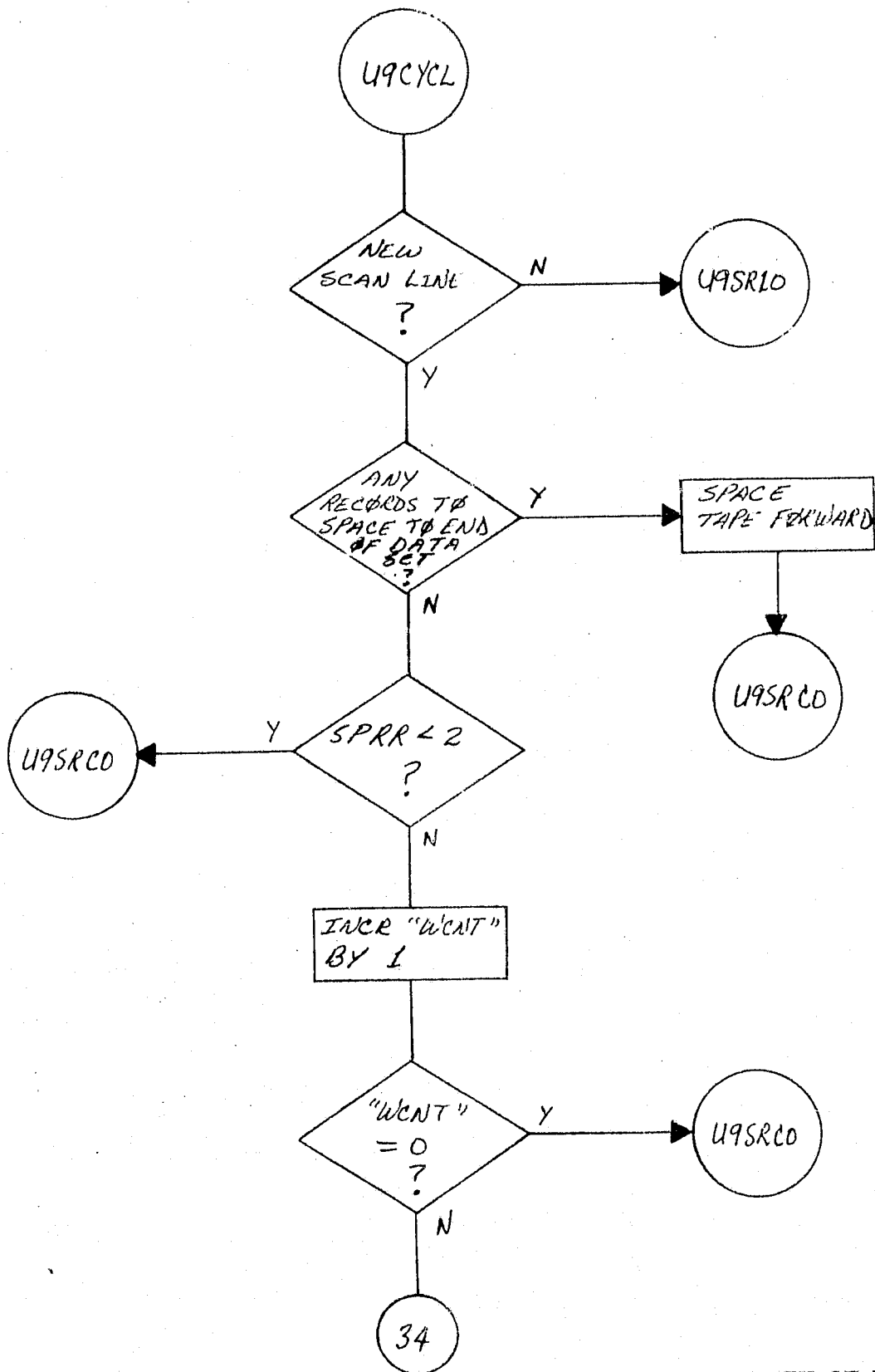




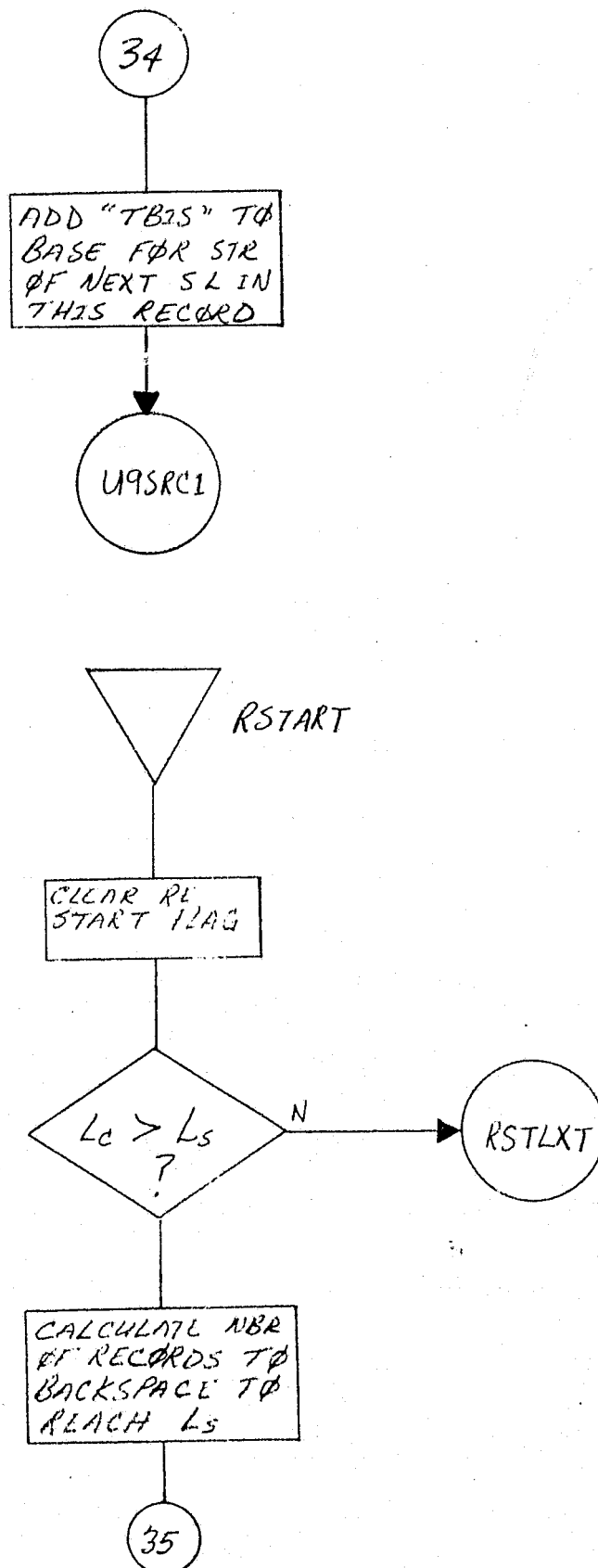


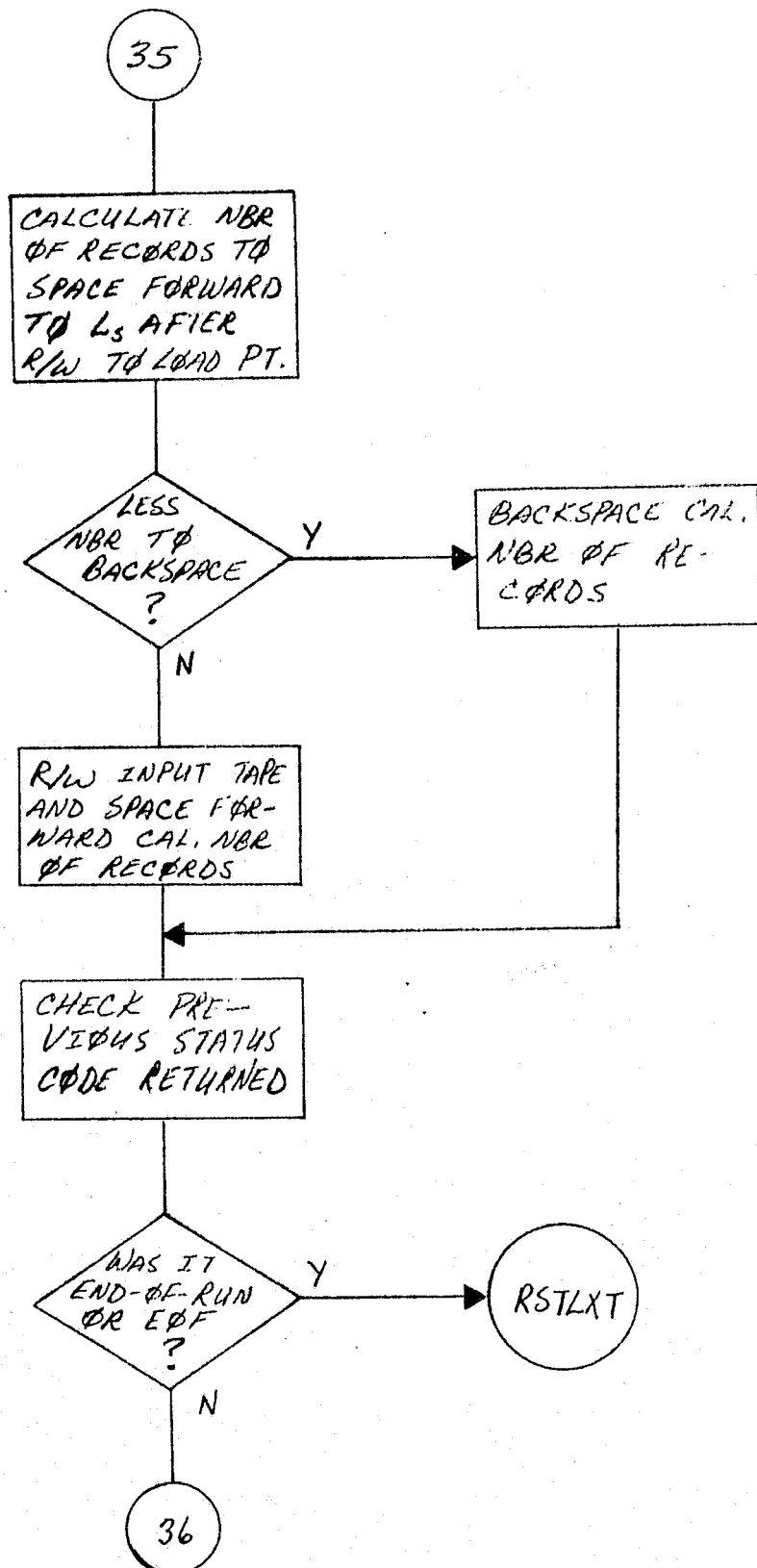


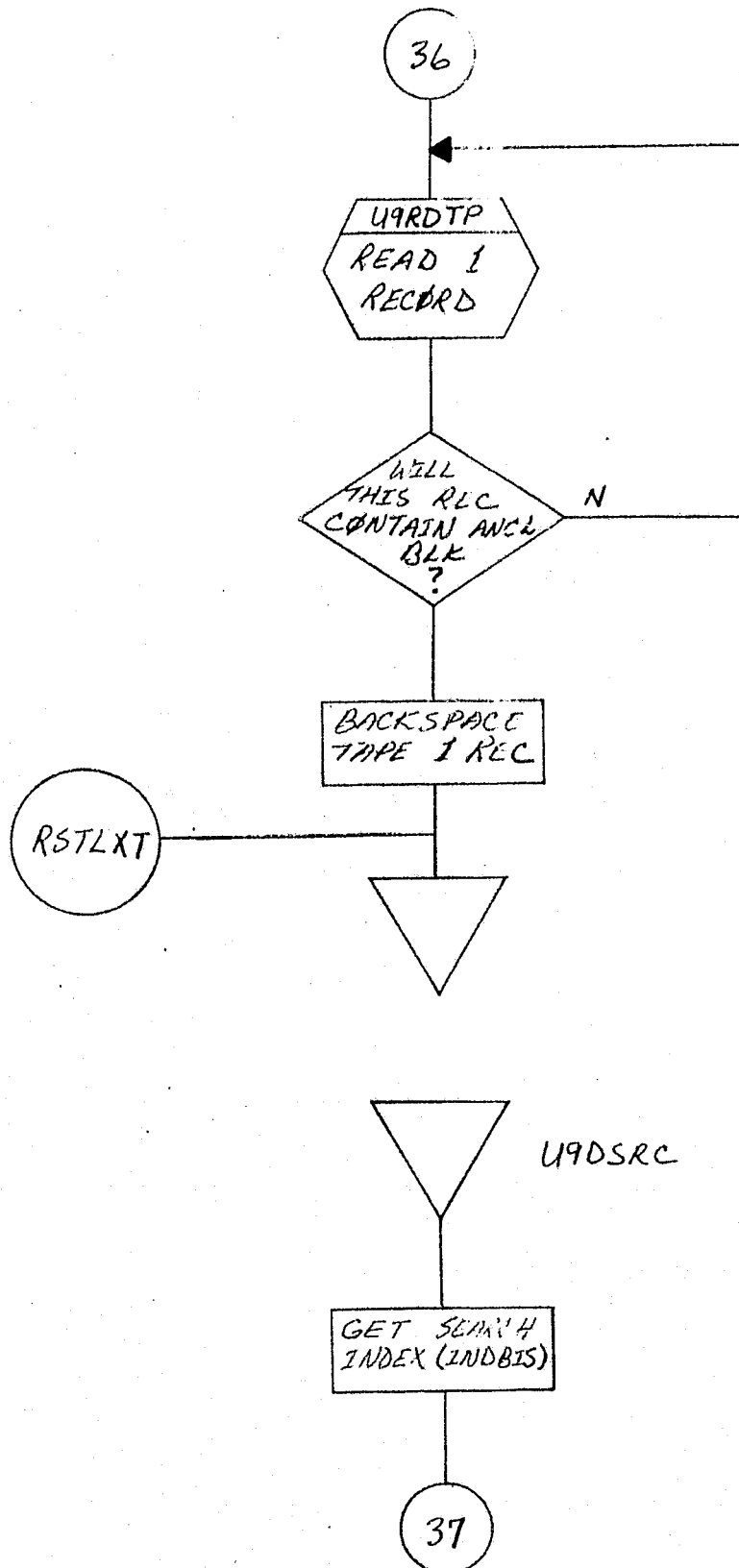


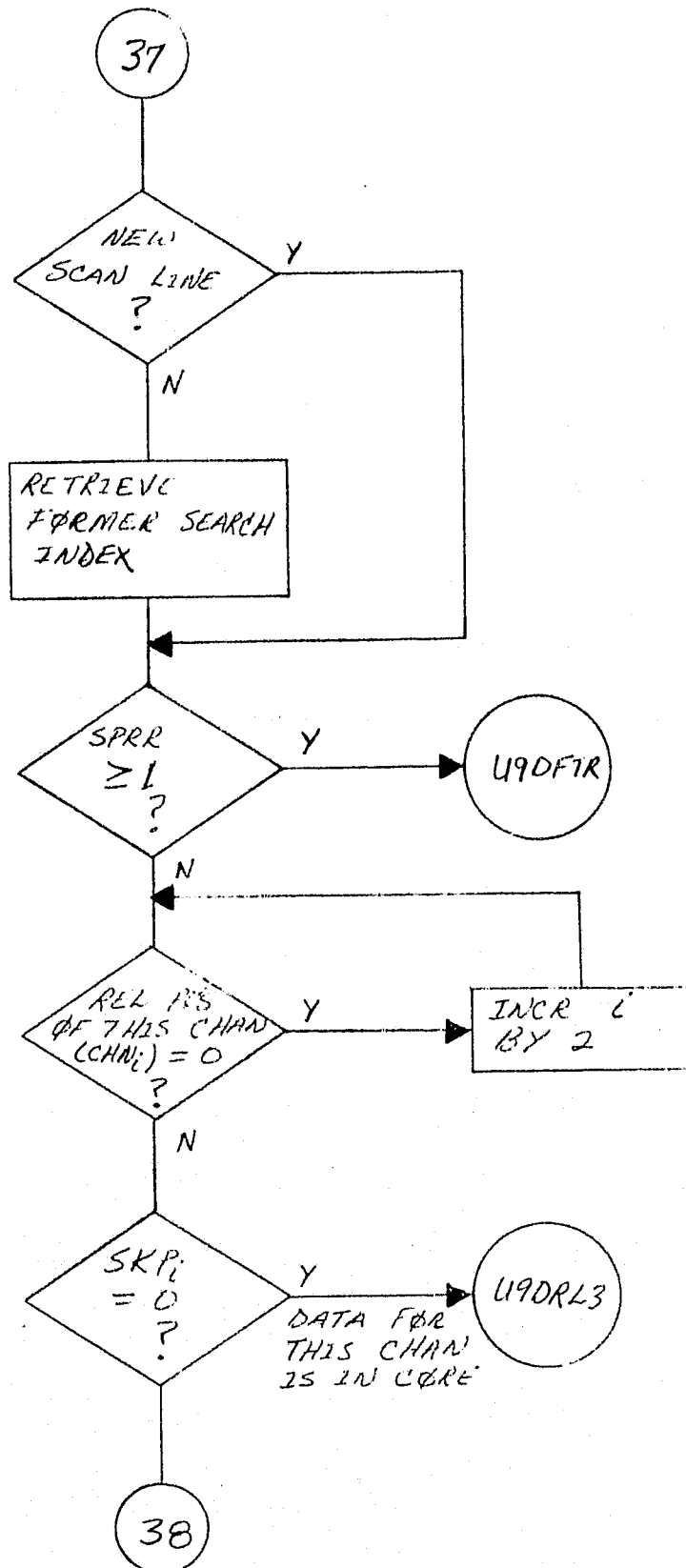


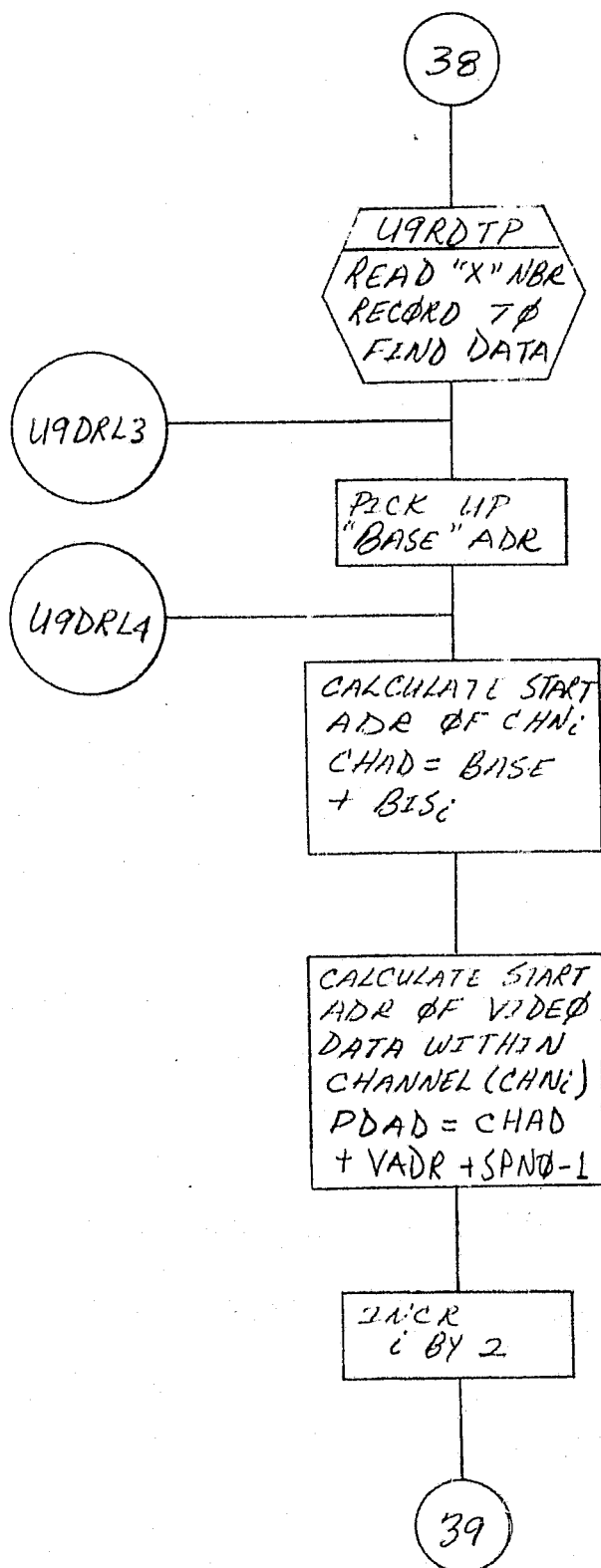
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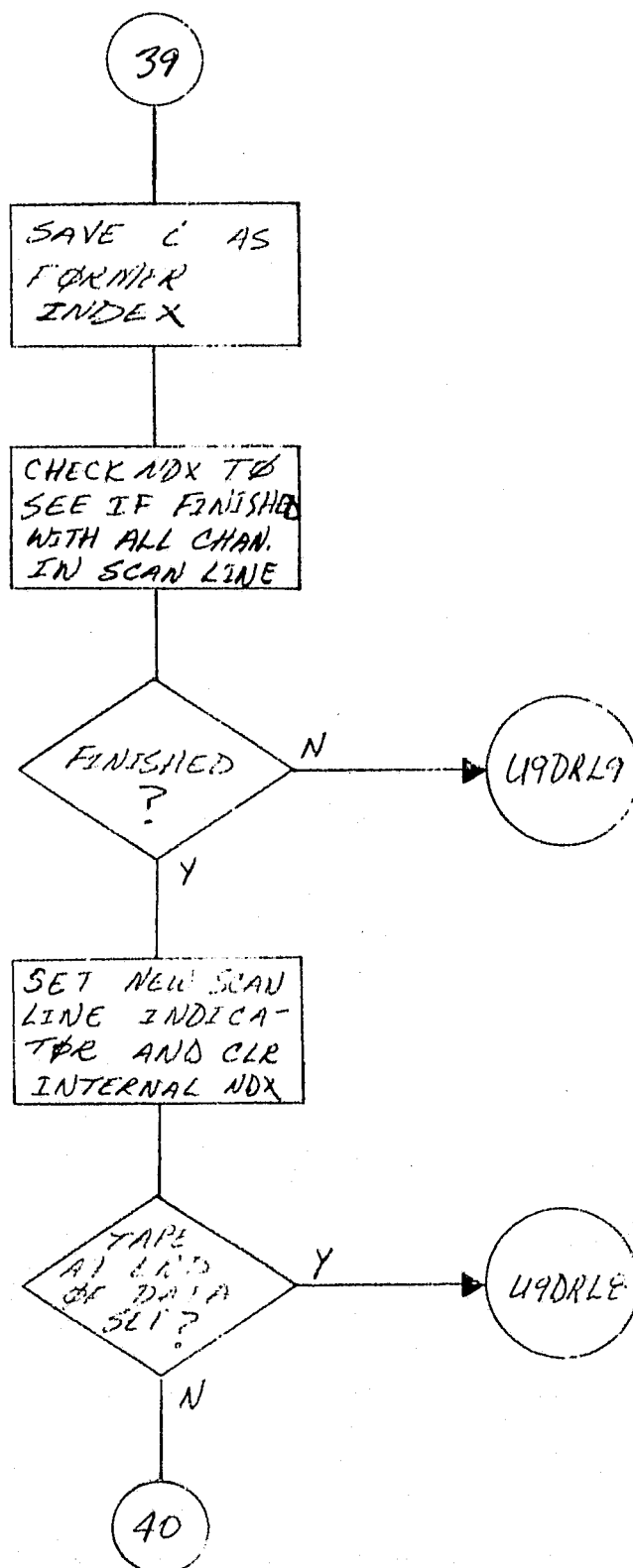




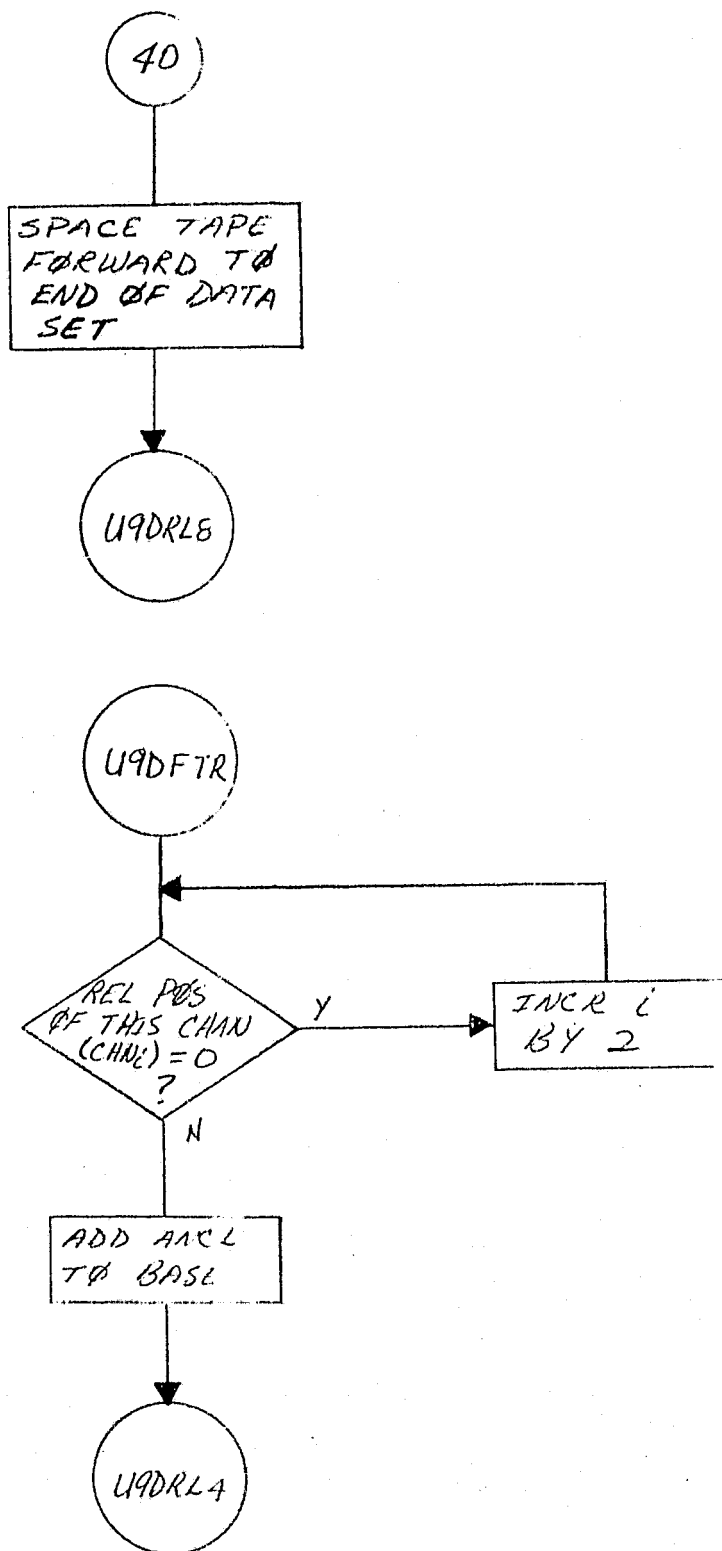


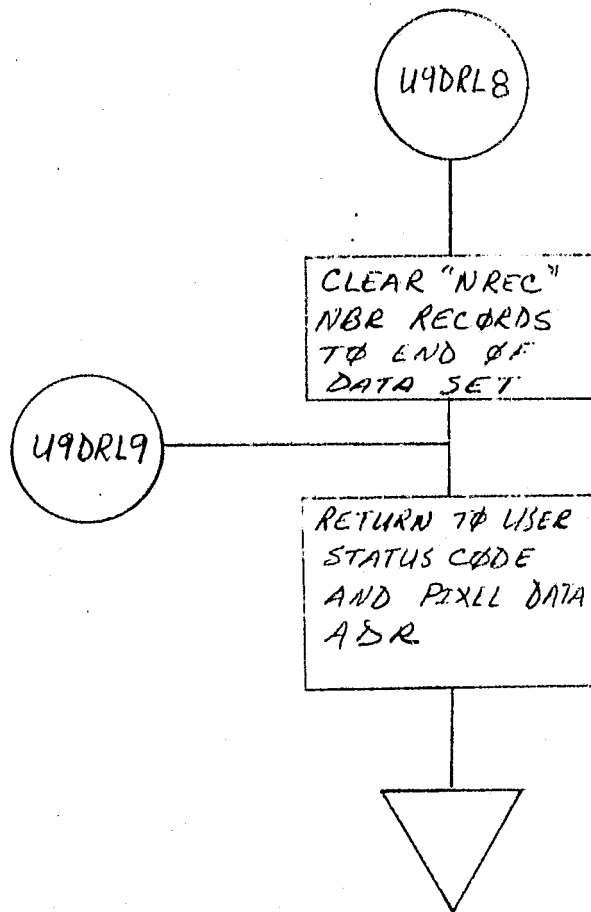












### 6.2.1.3 Interfaces

- A. Input Data. The input to the DPG module is from magnetic tapes. The data records going into DPG take the form of the specific universal format tape being handled by U9TRD. One channel of each scan line is passed to DPG via the tape input buffer.
- B. Output Data. The primary function of the DPG module is to interrogate user inputs via VT05 entries. However, another function exists; it is the display screening capability. The data input from tape is passed on to the SEDS display for line-by-line video screening.

6.2.1.4 Data Organization. The primary internally defined items of interest in the DPG module are those associated with the VT05 display for user input (see figure 6-3). Paragraph 6.1.5,B explains in detail the VT05 constants.

6.2.1.5 Limitations. The major limitation to the screening capability of the DPG module is the speed. Line-by-line image screening time is slowed by the input tape read. Universal format tapes containing several channels per scan line, which require multiple tape records per scan line, must be read and discarded in order to find the record containing the channel being screened. This problem of tape length is somewhat minimized by editing onto another tape only the channels, pixels, and scan lines required for screening.

6.2.1.6 Listings. See Part IV of this document published under separate cover.

6.2.2 UEDIT. This module provides tape-to-tape editing of universal format tapes. Editing to an output tape is accomplished by specifying through VT05 inputs the information required from the input tape. A compression factor is then used to determine the image size. Using the information entered via the VT05 (shown in figure 6-5) as an example, a universal format tape will be written on magnetic tape unit No. 2 containing one channel, 125 pixels, and 110 scan lines. The UEDIT module is composed of several separate and distinct subcomponents. One subroutine,

UNIVERSAL FORMAT TAPE EDIT

NBR OF CHANNELS =1	CHANNELS	OUTPUT
	01	MTU=2
NUMBER OF PIXELS =0625	00	
	00	
NBR OF SCAN LINES=0550		
COMPRESSION 115		

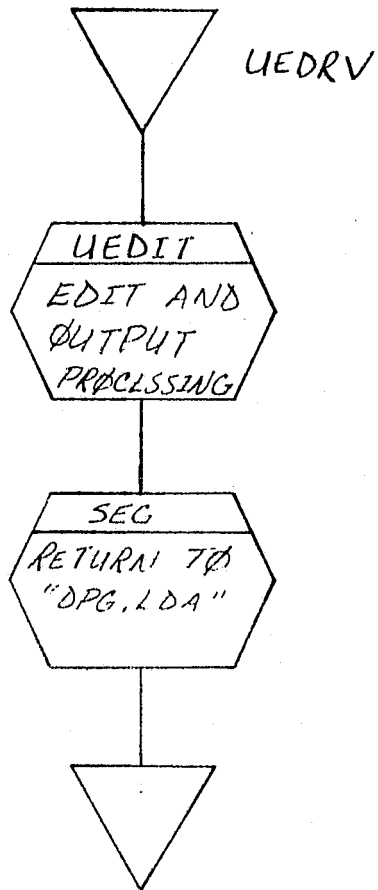
Figure 6-5 UEDIT VT05 Display

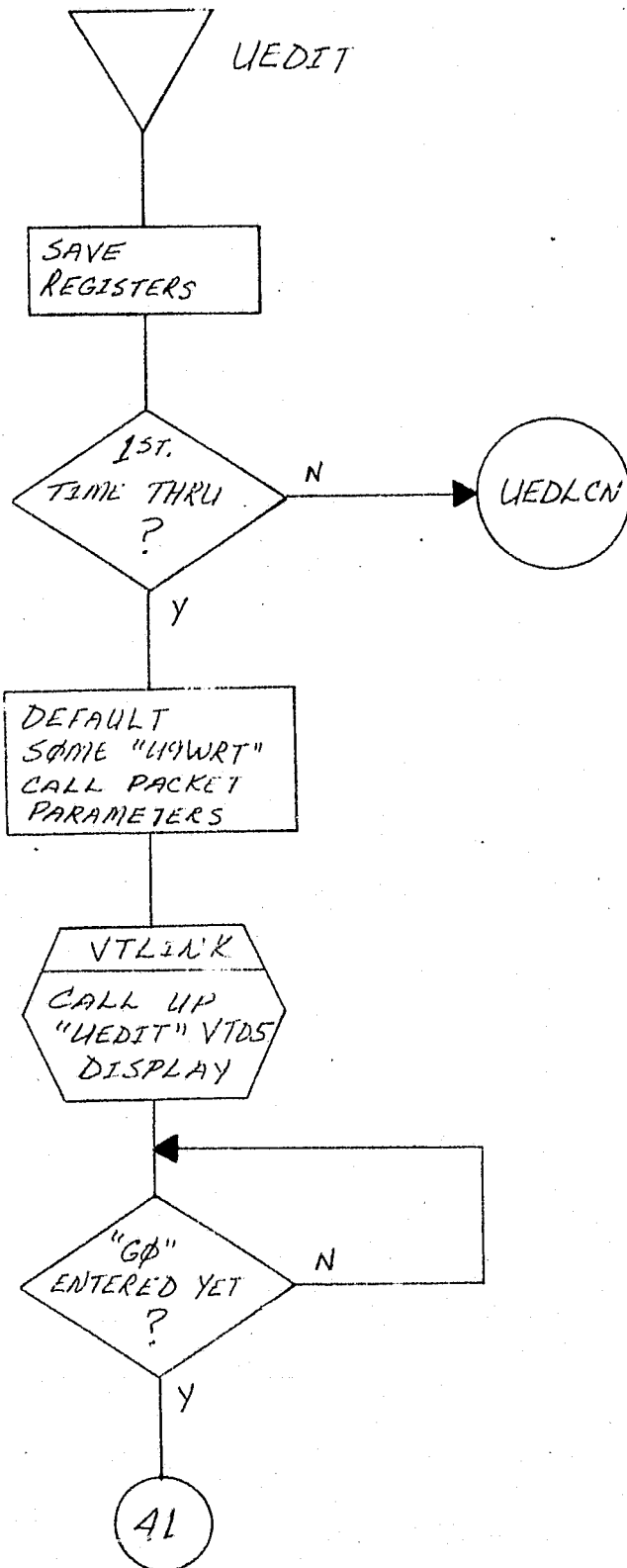
UEDRV, is written in PDP-11 FORTRAN and serves as the linking driver between the UEDIT and DPG modules. The other subcomponent of UEDIT are written in PDP-11/45 assembly language.

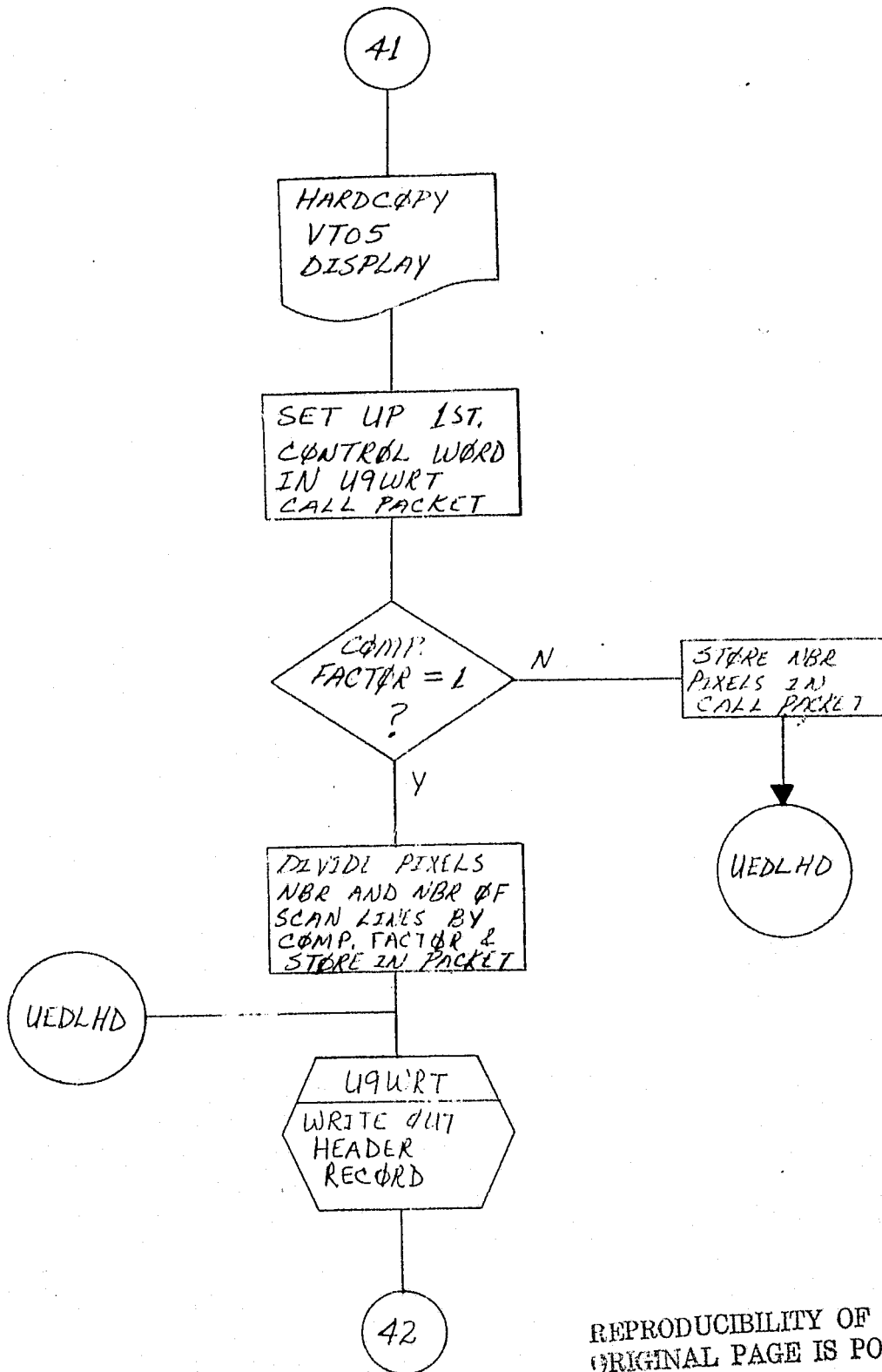
#### 6.2.2.1 Subcomponent Descriptions

- A. UEDRV. This subcomponent of the UEDIT module is the linking driver with the DPG module.
- B. "UEDIT." This is the main subcomponent of the UEDIT module. It accepts user inputs via the VT05 and controls the edited data being output to tape.
- C. U9WRT. This is the universal format write subroutine previously discussed in paragraph 5.2.3.1 of this specification.

#### 6.2.2.2 Flow Charts. See the next five pages.

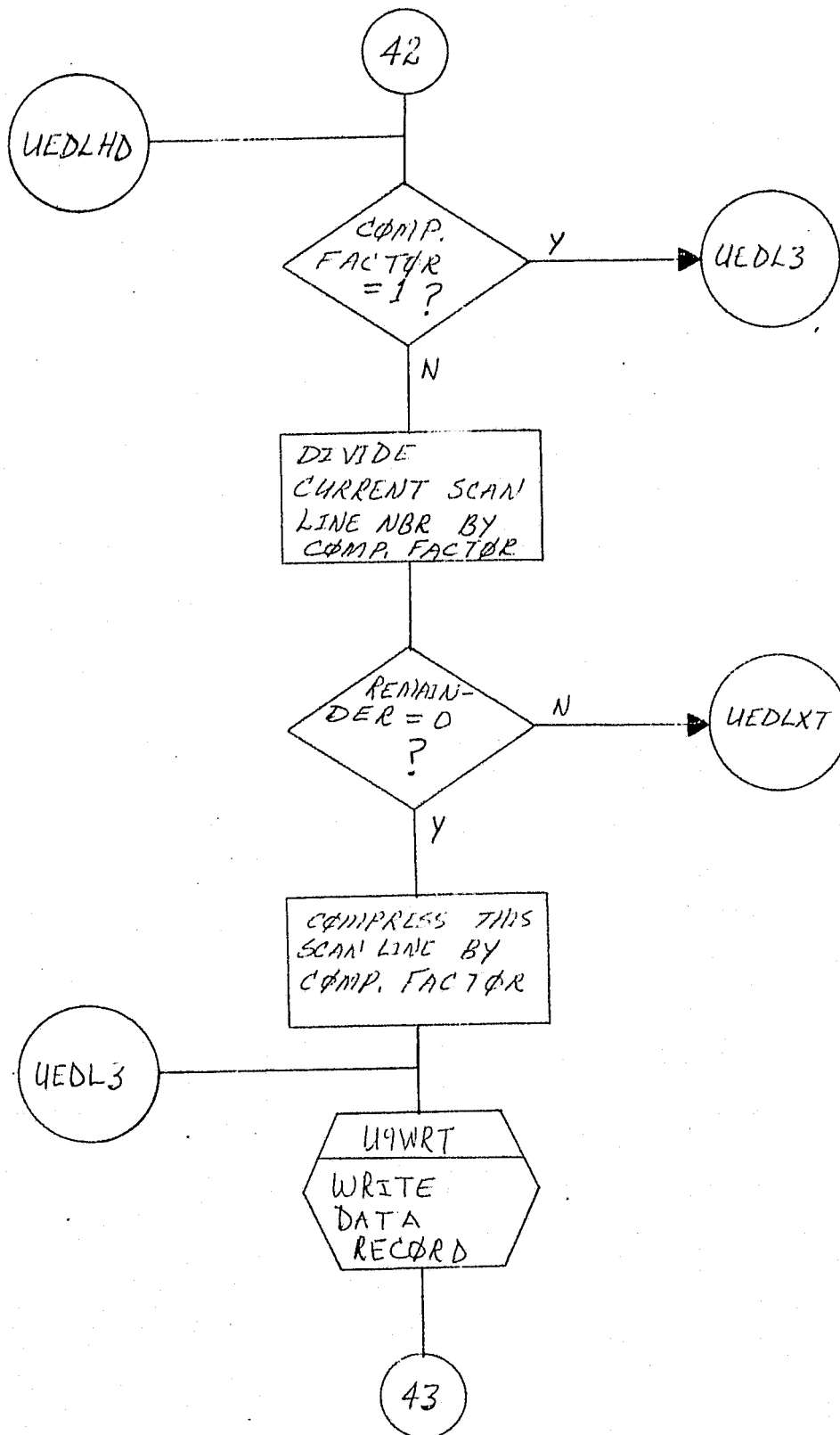


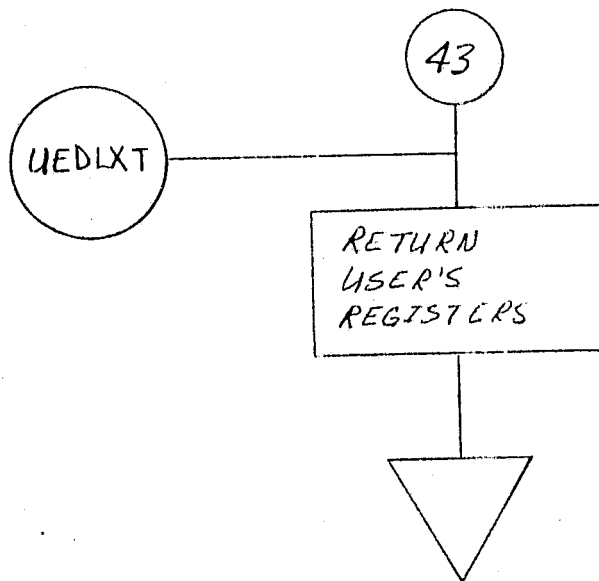




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### 6.2.2.3 Interfaces

- A. Input Data. The input data to the UEDIT module comes via the DPG module from the universal format input tape. A buffer containing one channels worth of data is passed on for editing.
- B. Output Data. The input data is compressed according to specification and output to magnetic tape in the universal format.

6.2.2.4 Data Organization. The principle internally defined items in the UEDIT module are the compression factor and the call packet to U9WRT. The compression factor is an integer ranging from 1-9.

6.2.2.5 Limitations. The tape editing capability in the UEDIT module is limited to three channels at a time. In addition, only a compression function is available; there exists no function for "zooming" or increasing the size of a specified area.

6.2.2.6 Listings. See Part IV of this document published under separate cover.

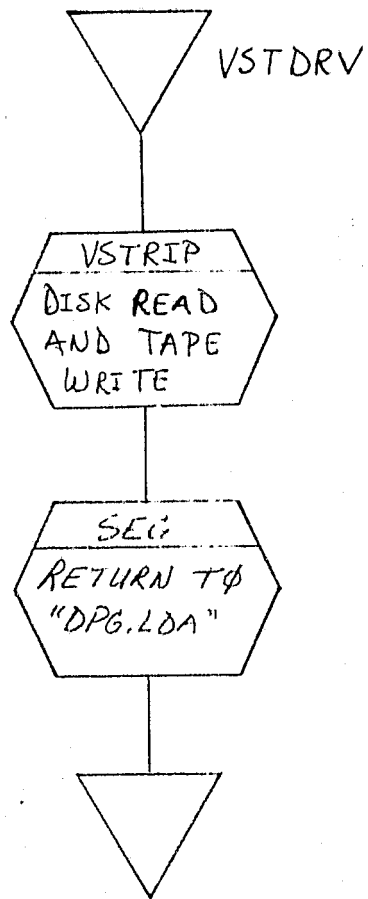
6.2.3 VSTRIP. The VSTRIP module provides the registered disk-to-tape editing function. One of the outputs of the registration phase of SEDS is a disk file containing three images, one of which is called the visible channel. This image contains 550 scan lines with 625 pixels per scan line. The purpose of VSTRIP is to transfer this visible data to tape in the universal format. The VSTRIP module consists of several separate and distinct subcomponents. One subroutine, VSTDRV, is written in PDP-11 FORTRAN and serves as the interface driver between VSTRIP and the DPG module. The other subcomponents of VSTRIP are written in PDP-11/45 assembly language.

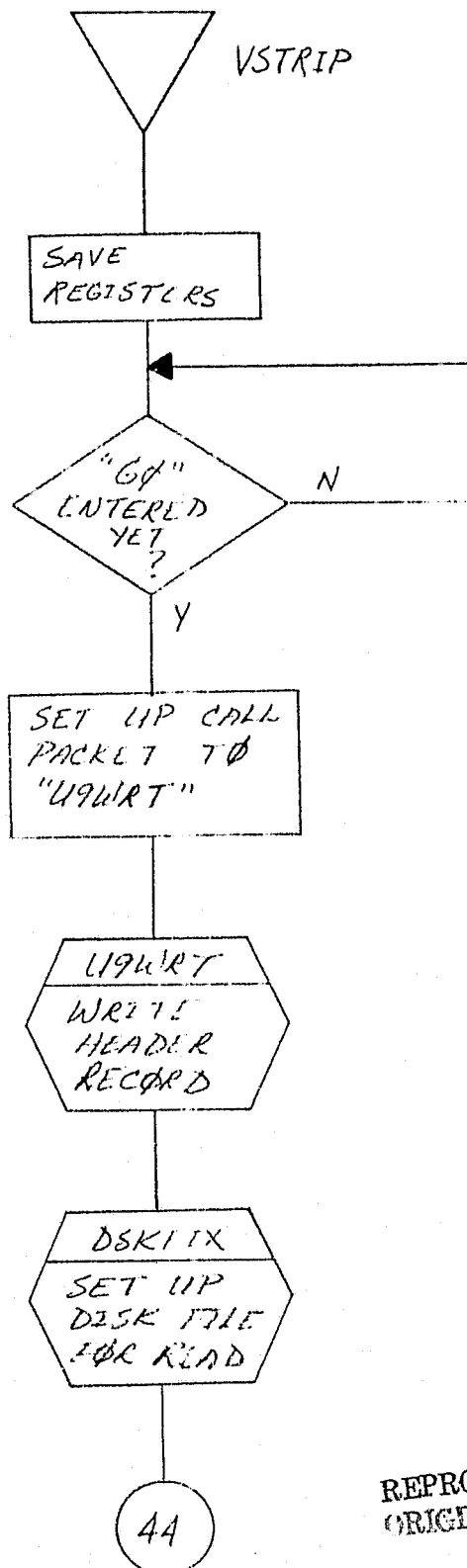
#### 6.2.3.1 Subcomponent Descriptions

- A. VSTDRV. This subcomponent is the linking driver with the DPG module.
- B. "VSTRIP." This is the main subcomponent of the VSTRIP module. It handles the buffer sequencing for the disk reads and the tape writes.

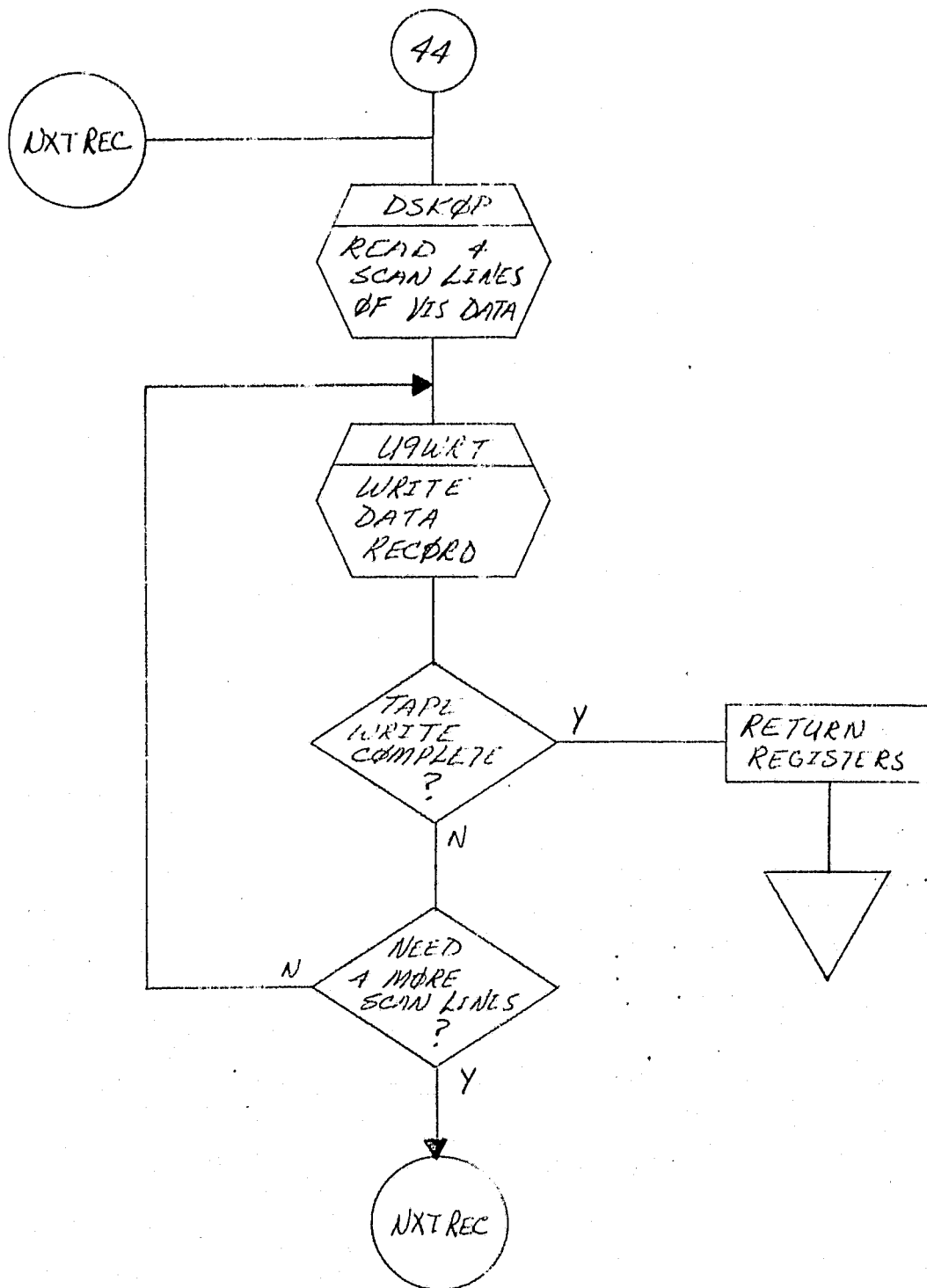
- C. DSKFIX. This subroutine sets up disk file allocation and the read function.
- D. DSKOP. This subroutine is called to read four scan lines at a time of visible channel data from the SEDREG.DAT file on the registered disk.
- E. U9WRT. This is the same universal format tape write subroutine discussed in paragraph 5.2.3.1 of this document.

6.2.3.2 Flow Charts. See the following three pages.





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### 6.2.3.3 Interfaces

- A. Input Data. The input data to VSTRIP resides in the registered disk file SEDREG.DAT. The visible channel data is read from the disk records named DAY VISIBLE DATA as shown by figure 6-6. Every third disk record contains four scan lines of visible data.
- B. Output Data. The output data is passed on to U9WRT for universal format tape write.

6.2.3.4 Data Organization. The internally defined parameters in VSTRIP are the entries required in the call packet to U9WRT. All values are fixed except the input buffer address is variable.

6.2.3.5 Limitations. The limiting feature of VSTRIP is its capability of editing only the visible channel from registered disk to tape. The program run time is good in that it takes only about 2 minutes.

6.2.3.6 Listings. See Part IV of this document published under separate cover.

6.2.4 DWPGEN. This is the product generation module of DPG. Its function is the generation of SEDS output products, display and/or tape. The short circuit feature of product generation has proved useful in the debug and checkout phases of all associated subroutines, as well as the bypass of the standard SEDS production sequence to obtain specific products and results.

6.2.4.1 Subcomponent Descriptions. All of the subcomponents listed and discussed in paragraph 5.2.3.1 of this document are also used in the DWPGEN module. See that paragraph for details of the following subcomponents:

- PDGEN
- OWCPRO
- FCGEN
- U9WRT

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FILE NAME

SEDREG.HDR (5670₈)

SEDREG.DAT  
(625 BYTES/  
SCAN LINE,  
4 SCAN LINES/  
RECORD)

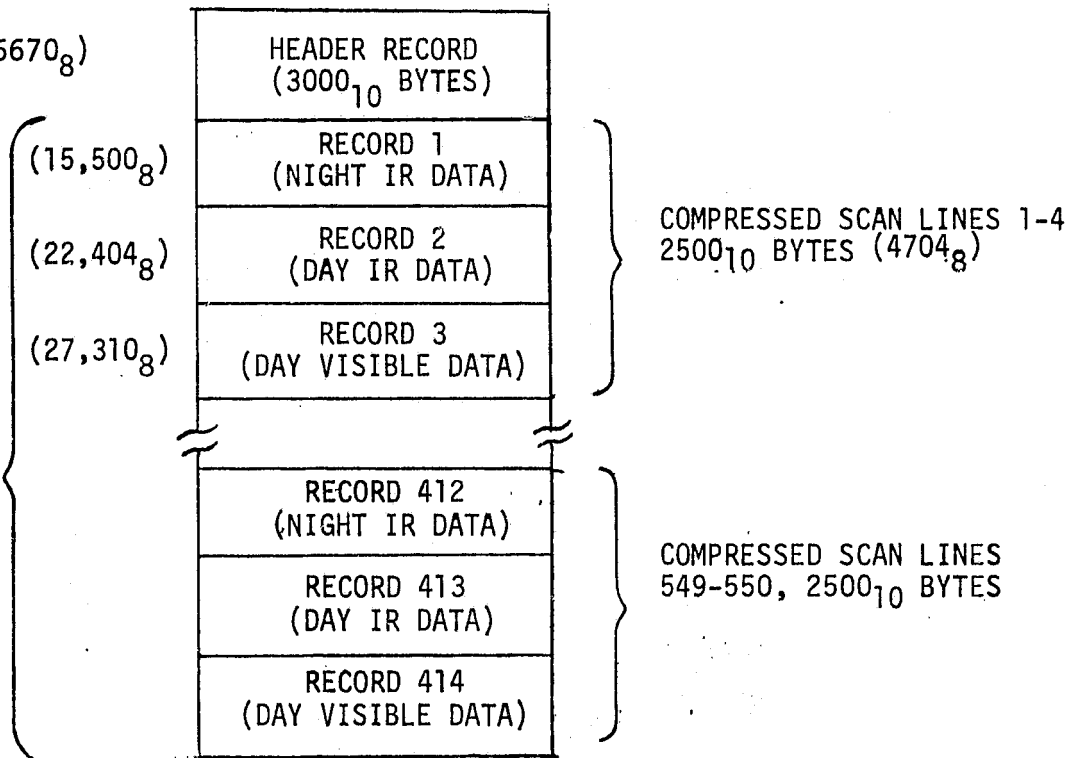


Figure 6-6 SEDS Registered Disk

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- DISPL
- OPNOT
- ANNOT

6.2.4.2 Flow Charts. See flow charts following paragraph 5.2.3.2.

6.2.4.3 Interfaces

- A. Input Data. Unlike input to the SWPGEN module in SSP and the other product generator modules, input to DWPGEN is from tapes. The input tape type depends upon the output product to be generated. For example, an intermediate registered day isothermal tape (SMD) may be read to output a DAY ISOTHERMAL (OID) color-coded image.
- B. Output Data. The output of DWPGEN parallels that of SWPGEN in that it may be output to tape and/or display as color-coded images.

6.2.4.4 Data Organization. The subcomponents of DWPGEN are identical to those of SWPGEN. See paragraph 5.2.3.4 of this document for detailed data organization.

6.2.4.5 Limitations. Due to the complexity of the input data to Data Base Sequences No. 1 and 2, only the false color, tape, and display formats of the ORC and OWC products may be simulated with DWPGEN.

6.2.4.6 Listings. See Part IV of this document published under separate cover.

## SECTION 7

### CHARACTER DENSITY PLOT (CDP) PROGRAM

#### 7.1 GENERAL PROGRAM CHARACTERISTICS

The CDP Program in SEDS is used to generate line printer maps using the registration intermediate tapes (SMD or SMN) as input. The line printer plots may be used in lieu of the film images. In addition, CDP provides an expanded "quick-look" at daily registered data. CDP consists of only one module. Its basic configuration is described by figure 7-1.

7.1.1 Functional Allocation. As defined in PHO-TN734, CDP performs the output of character density maps on the line printer. In order to provide a 1:1 aspect ratio, it is necessary to expand the data along the X axis using a nearest-neighbor value assignment technique.

7.1.2 Program Flow Chart. See figure 7-2.

7.1.3 Timing and Sequencing. The data from tape must be input and must reside within a specified buffer area. The algorithm to preserve the X-Y aspect ratio is executed as the data is converted to printable characters for output. The run time depends upon the tape length and image size to be printed.

7.1.4 Storage Allocation. The storage requirements for CDP are shown in figure 7-3. As illustrated by the diagram, the instruction space, buffers, and conversion tables require only 5K core storage.

7.1.5 Data Base Characteristics. CDP Program constants are located in a SEDS common buffer space called SCOMVT. The common area contains 256 words. The first 100 words are reserved for VT05 input and output control. The next 70 words are reserved for header information from universal format tape reads set up by U9TRD. The remaining words are spares and are used differently by various programs in SEDS. A more detailed description of this common area is shown by the computer program listings of CDP.

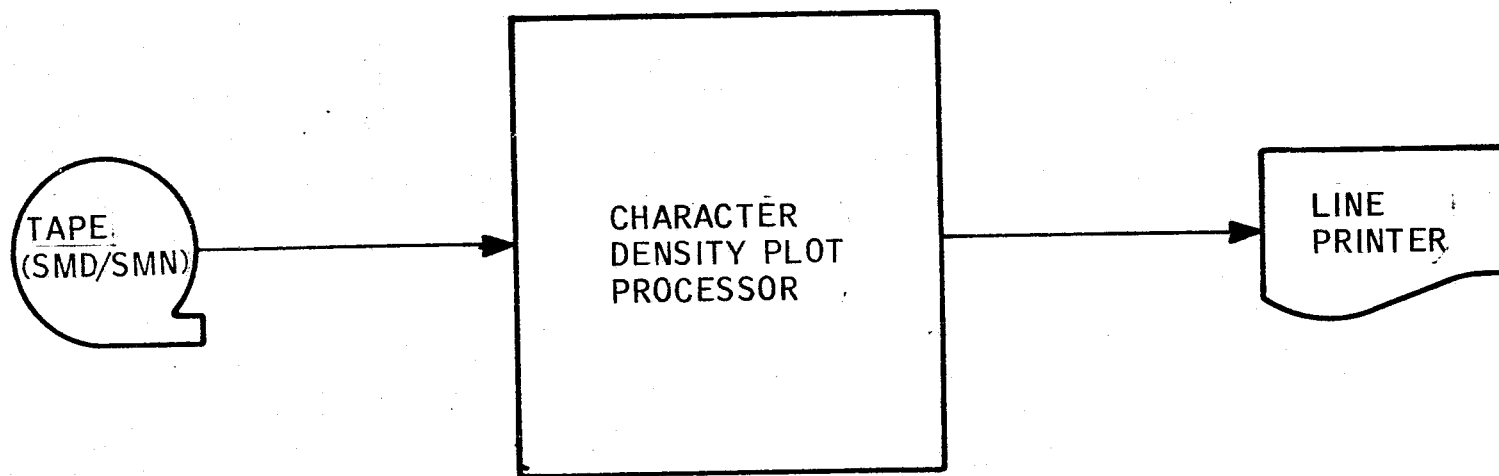


Figure 7-1 CDP Program Basic Configuration

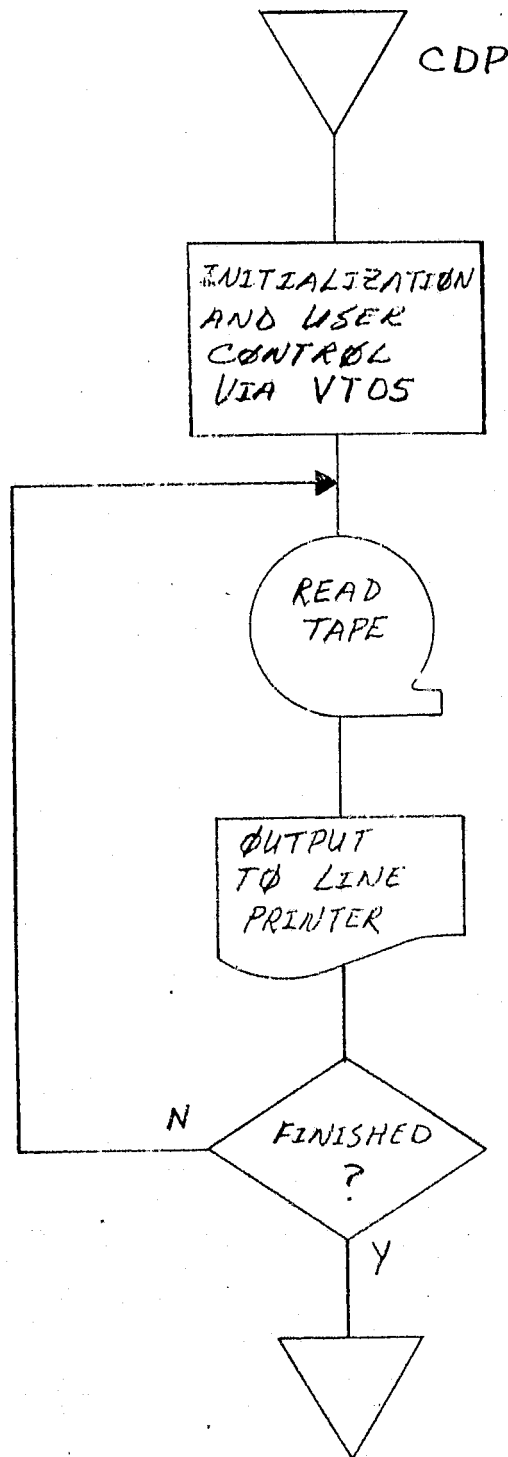
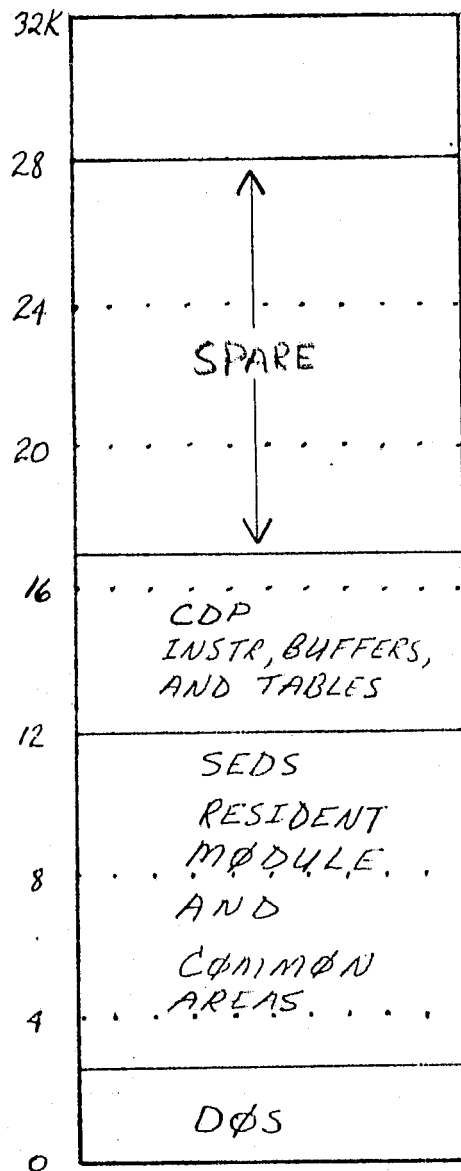


Figure 7-2 CPC Program Flow Chart



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Figure 7-3 CDP Storage Allocation

## 7.2 CDP CPC CHARACTERISTICS (CDPEXC)

Paragraph 7.2 contains a detailed technical description of the CDP Program. The instruction listings contained herein, by inclusion or reference, specify the exact configuration of the CDP Program.

The name of the combined subcomponents of CDP is CDPEXC; its functions have been previously defined in paragraph 7.1. This module is composed of several separate and distinct subcomponents. One subroutine, CDPDRV, is written in PDP-11 FORTRAN and serves as the driver linking the CDP Program with the SEDS system control module. The other subcomponents of CDPEXC are written in PDP-11/45 assembly language.

### 7.2.1 Subcomponent Descriptions

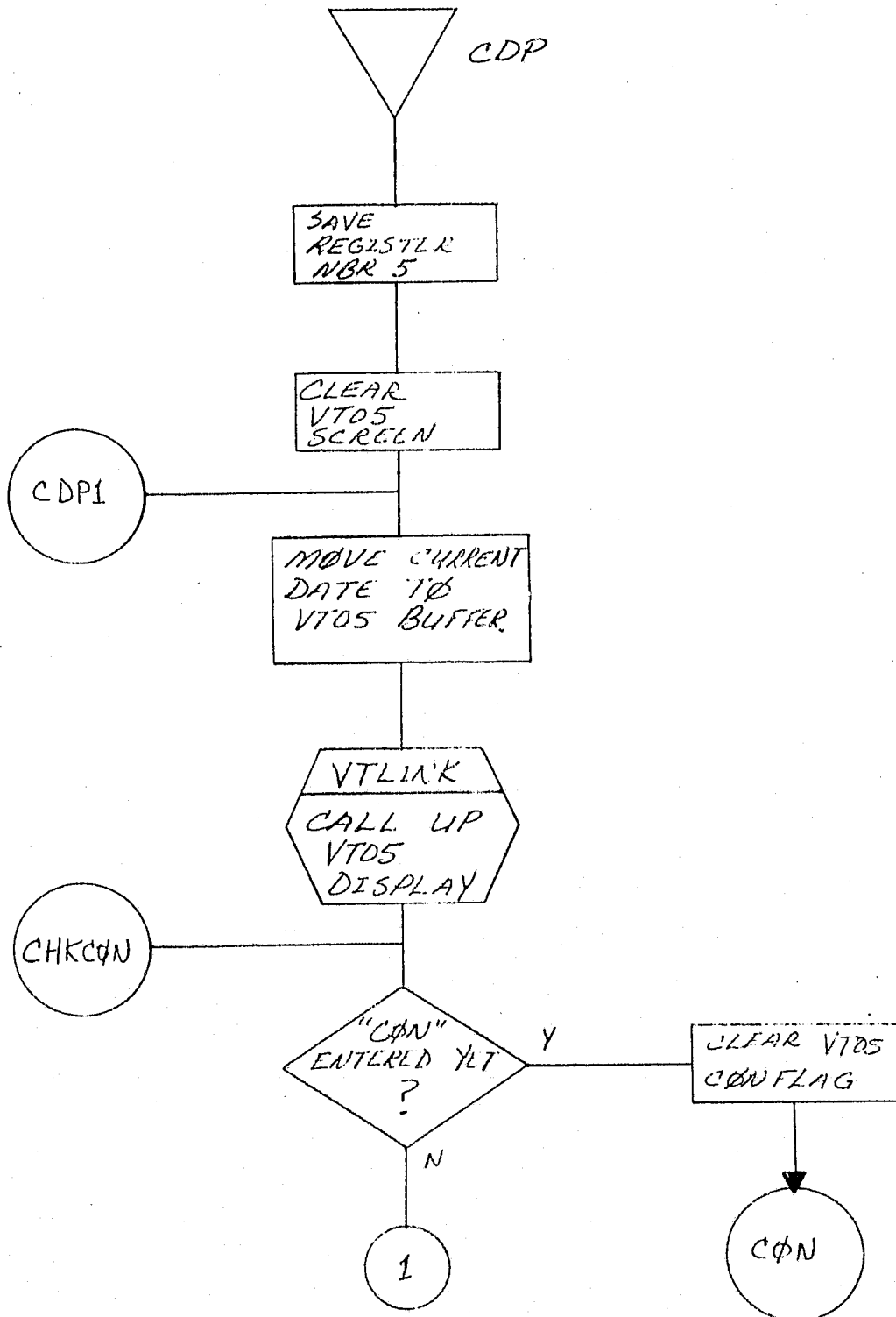
- A. CDPDRV. This subcomponent is the CDP driver routine of SEDS. This routine exists because of the system segmentation and overlay software utilized by SEDS.
- B. "CDP." This is the name of the main subcomponent of the CDPEXC module. This subcomponent provides the initialization, user control, and process sequencing of all functions performed by the CDP Program. User control is accomplished through the VT05, whose initialized state is shown in figure 7-4. Error messages and operator advisory instructions are output to the VT05 display. Tape input is performed through interface with the subroutine U9TRD. The pixel-to-ASCII character conversion table is contained in the TEMTB subcomponent.
- C. TEMTB. This is the ASCII character conversion table. The listings in Part IV of this specification show in detail the content and layout of this 256-item table.
- D. U9TRD. This is the universal format tape read routine described in paragraph 6.2.1.1,C of this document.

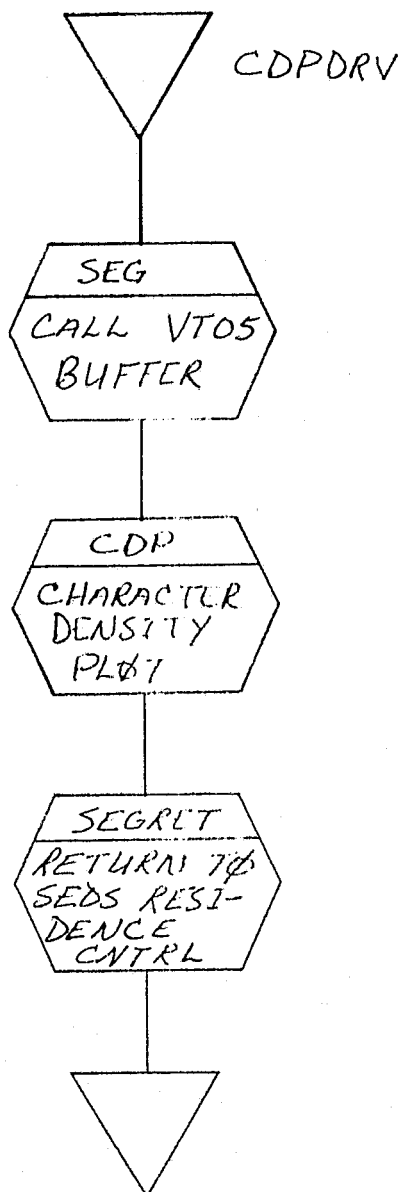
### 7.2.2 Flow Charts. See 16 pages following figure 7-4.

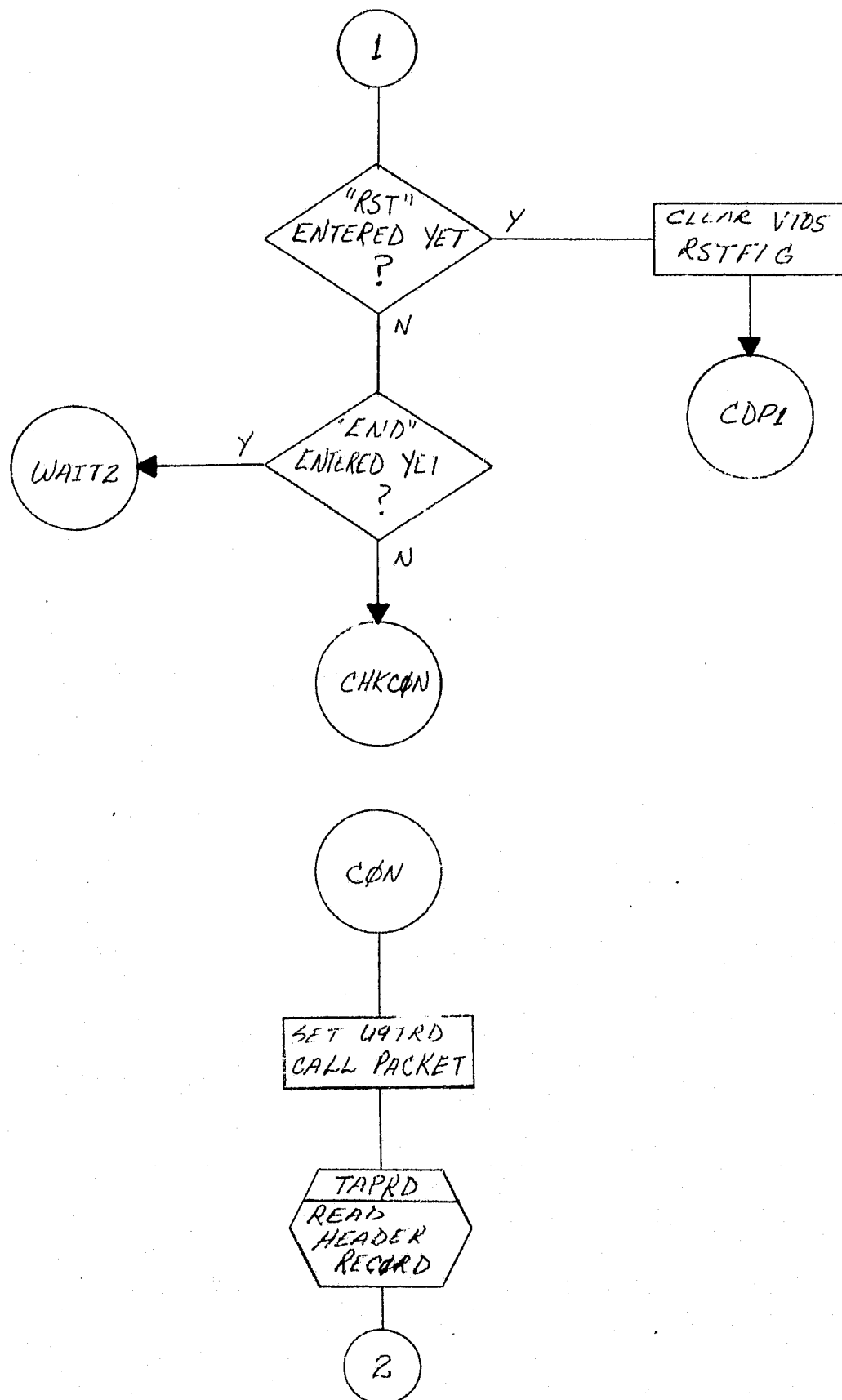
CHARACTER DENSITY PLOT GENERATOR		DATE: 01-MAR-75
0001 = START SCAN LINE	0000 = CURRENT SCAN LINE NO.	
2000 = NUMBER OF SCAN LINES		
0001 = START PIXEL NUMBER	00 = CURRENT SECTOR NO.	
2500 = NUMBER OF PIXELS	00 = END SECTOR NO.	
*****		
0000 = SCAN LINE NO.		
0000 = START PIXEL NO.	01 = MTU NO. SELECTED	
0000 = STOP PIXEL NO.	01 = CHANNEL NO.	
*****		

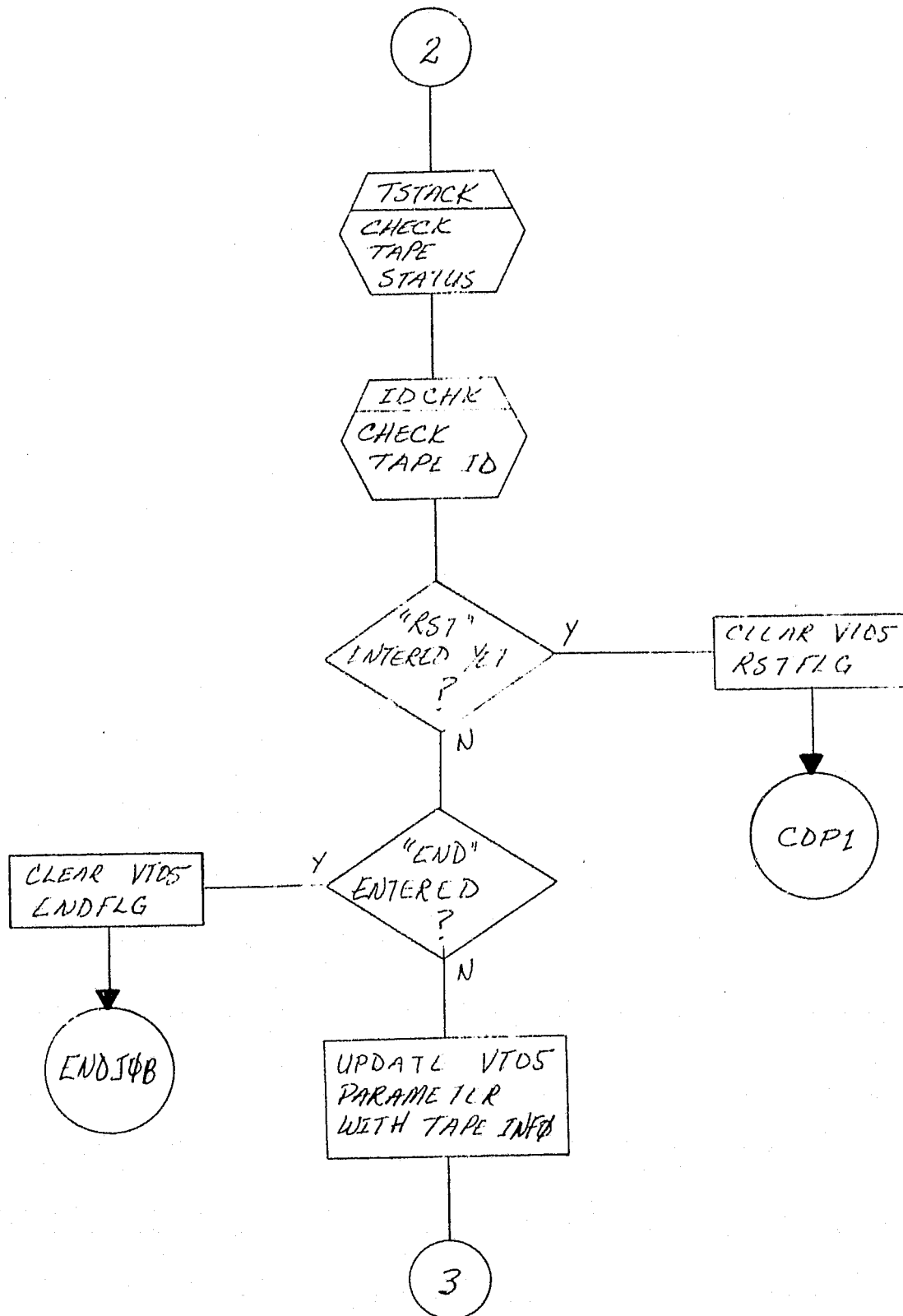
Figure 7-4 CDP Initialized VT05 Display

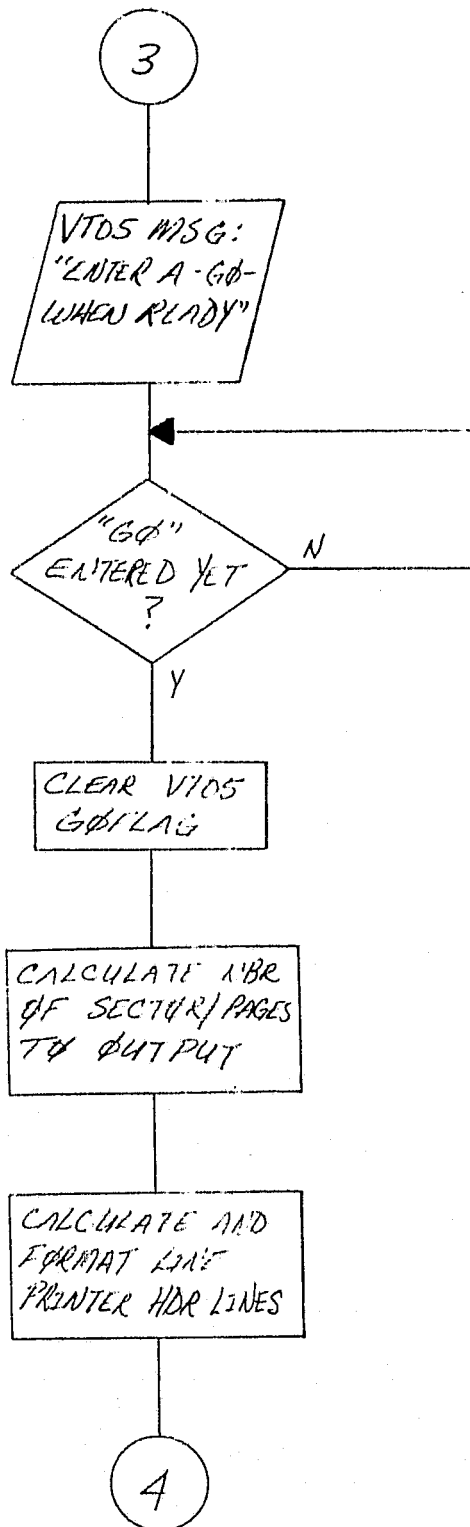


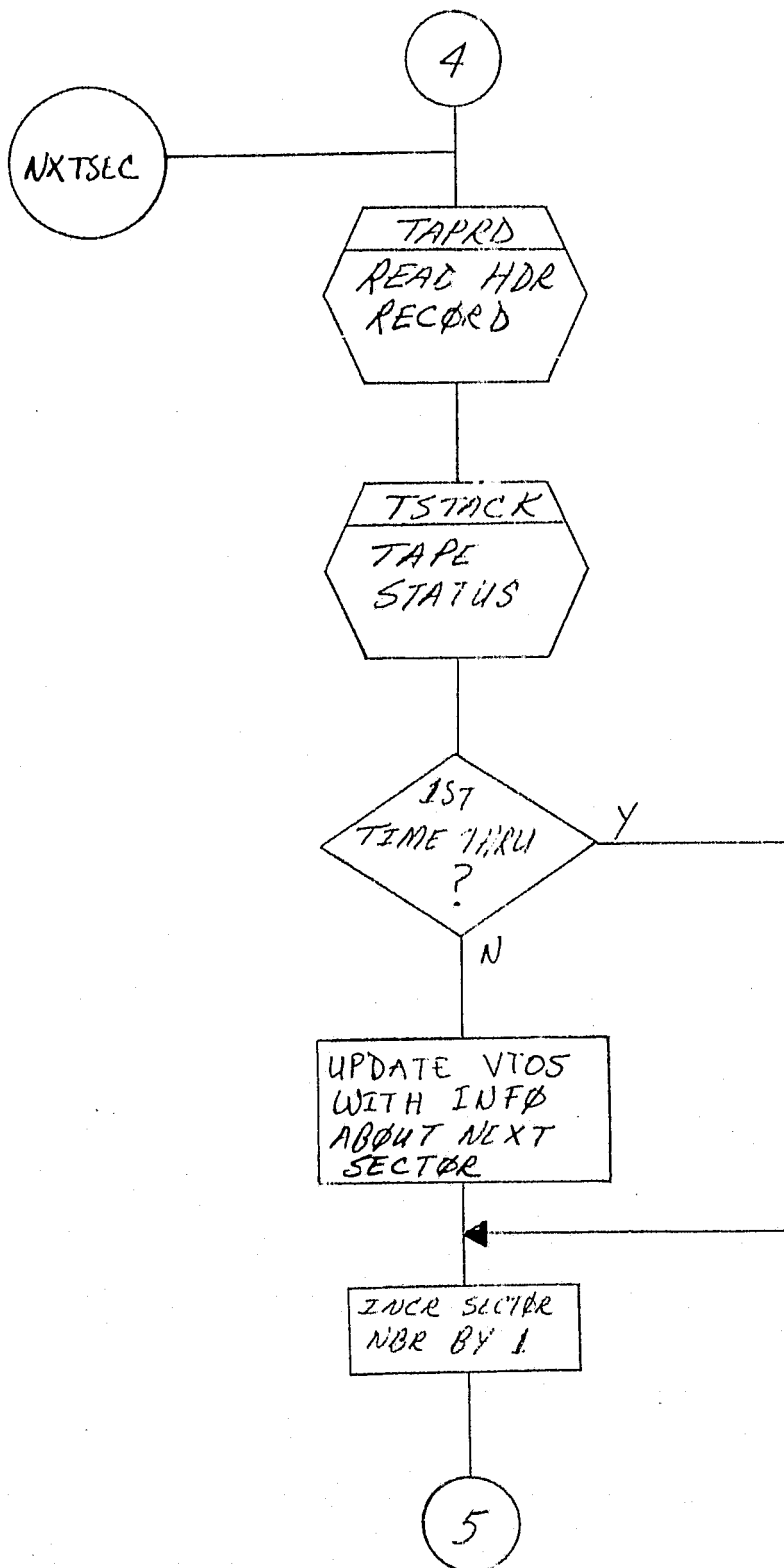


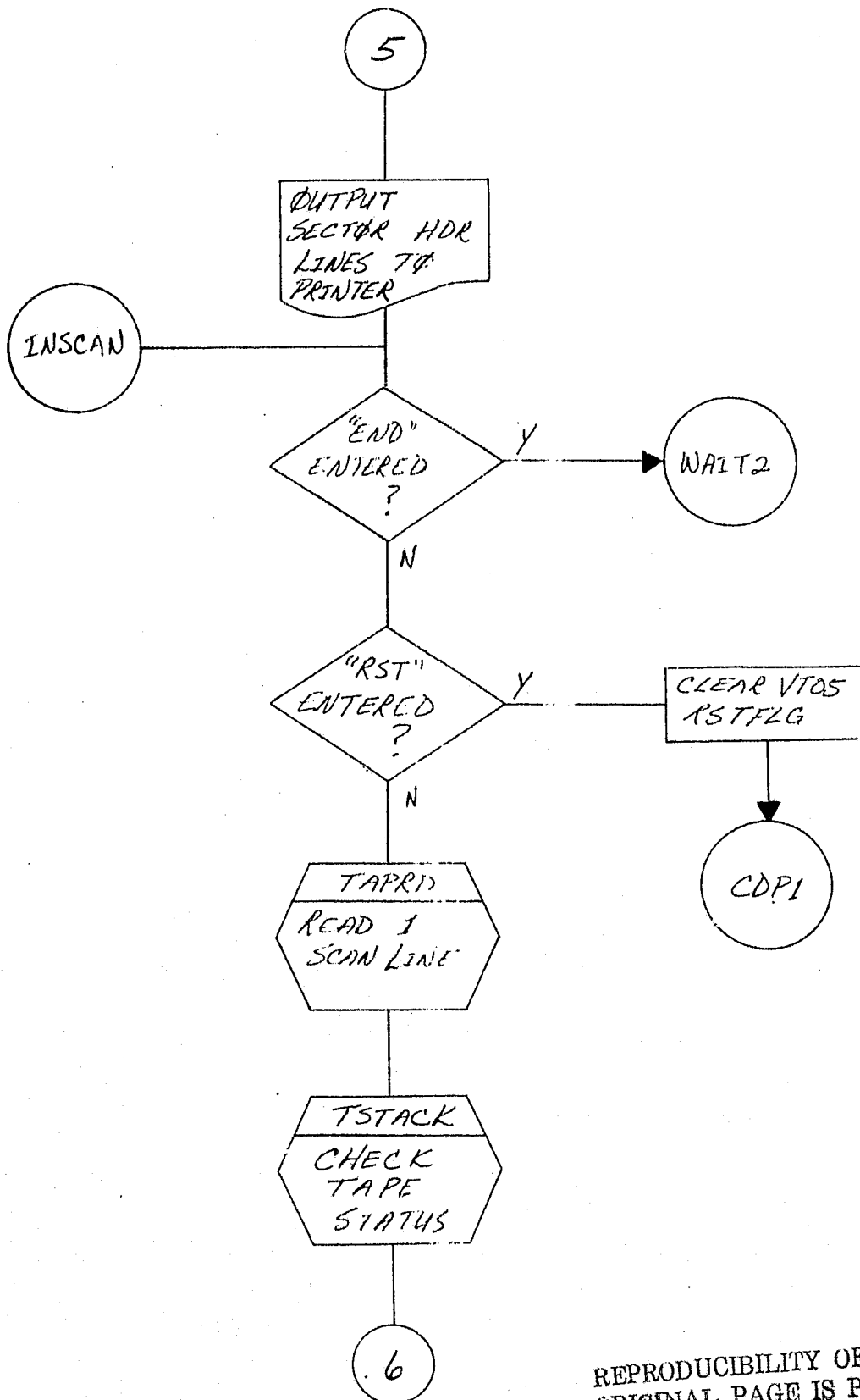




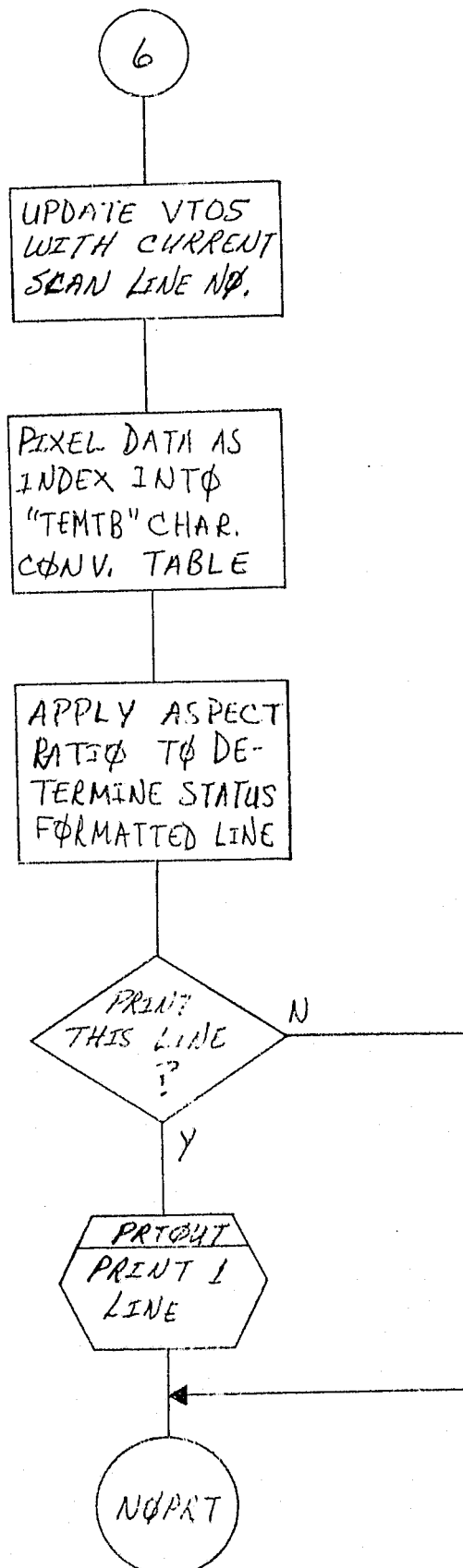




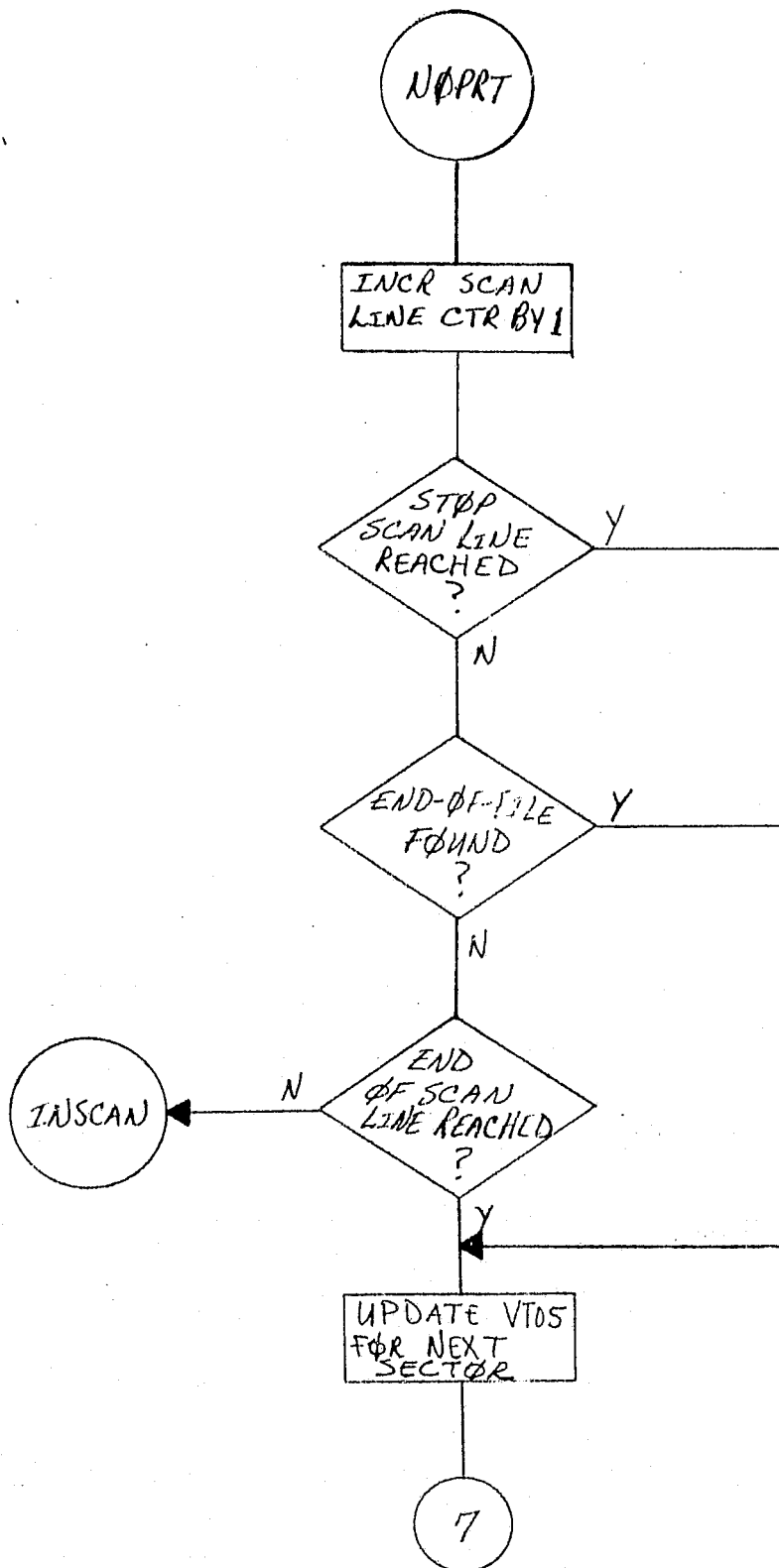


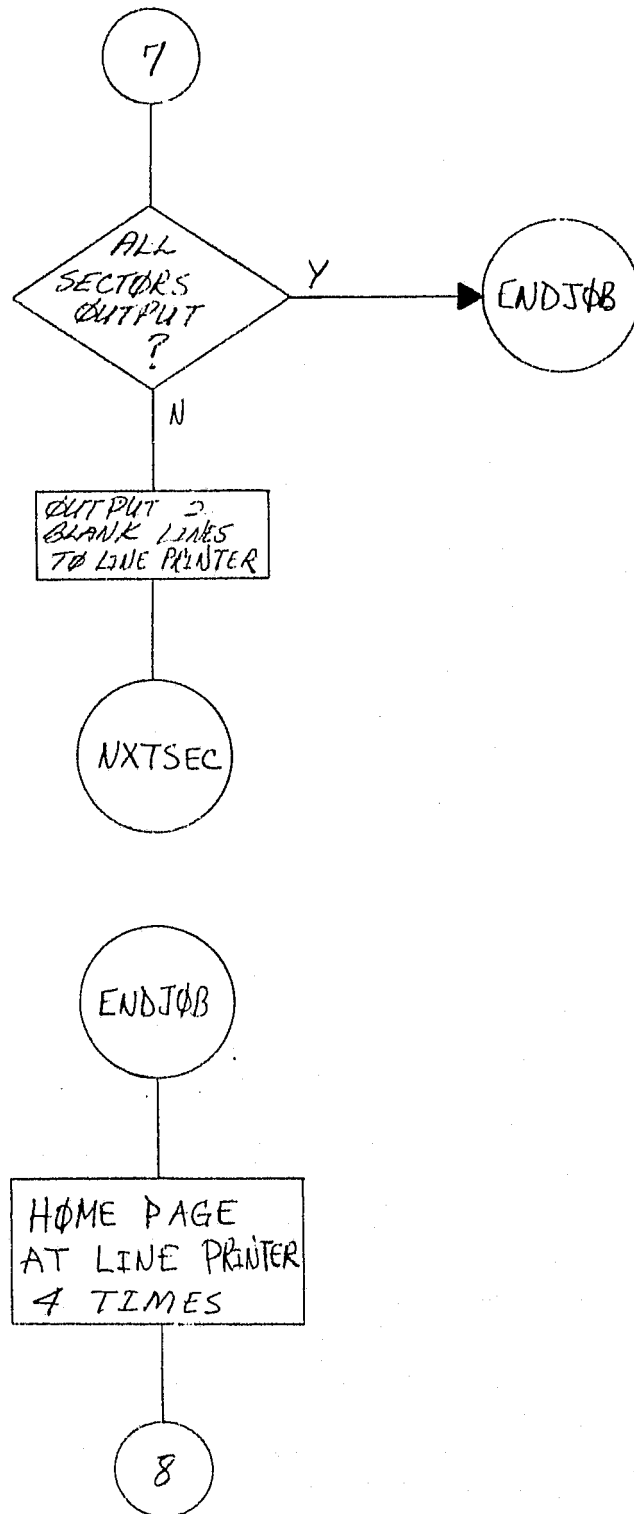


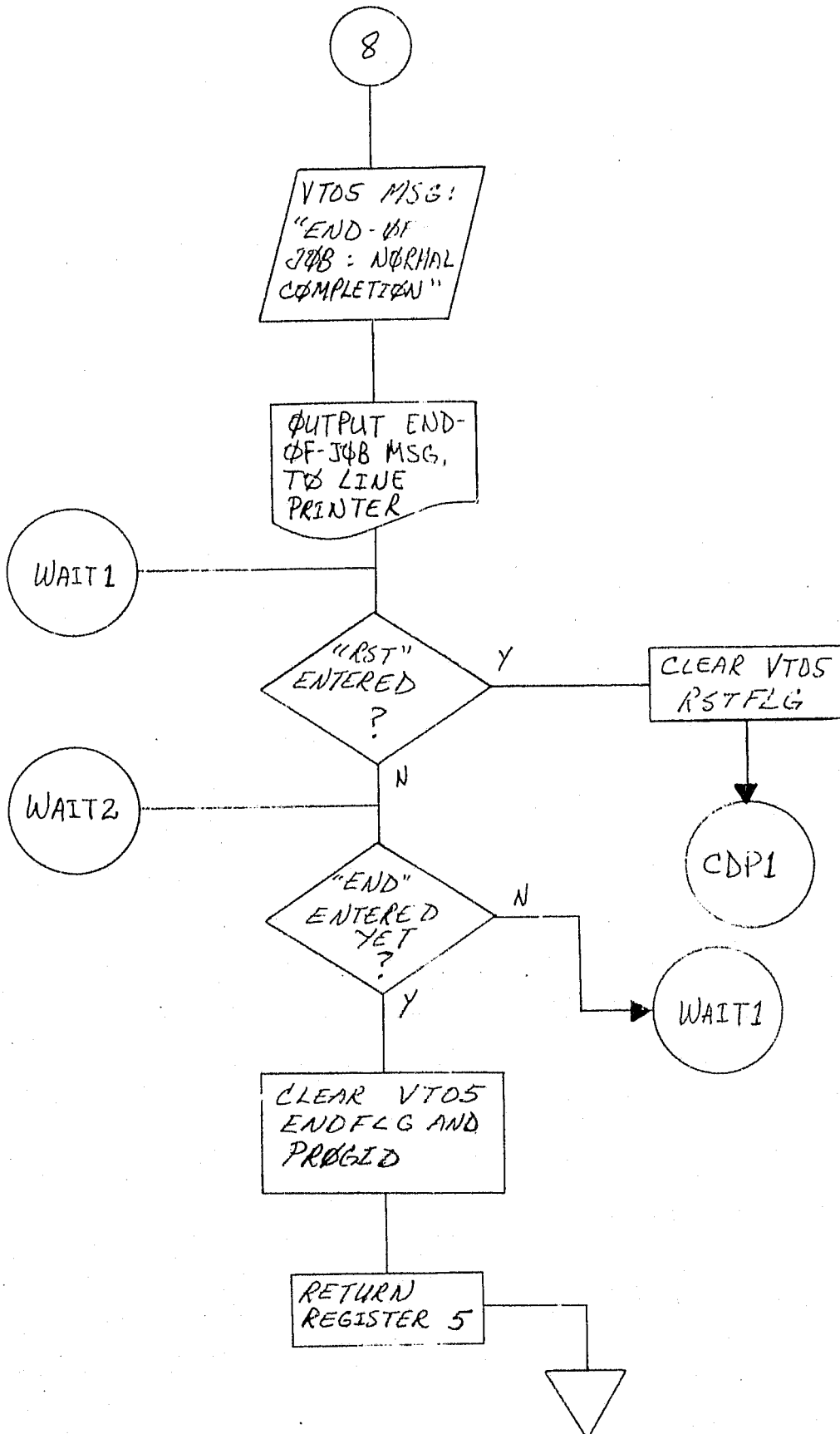
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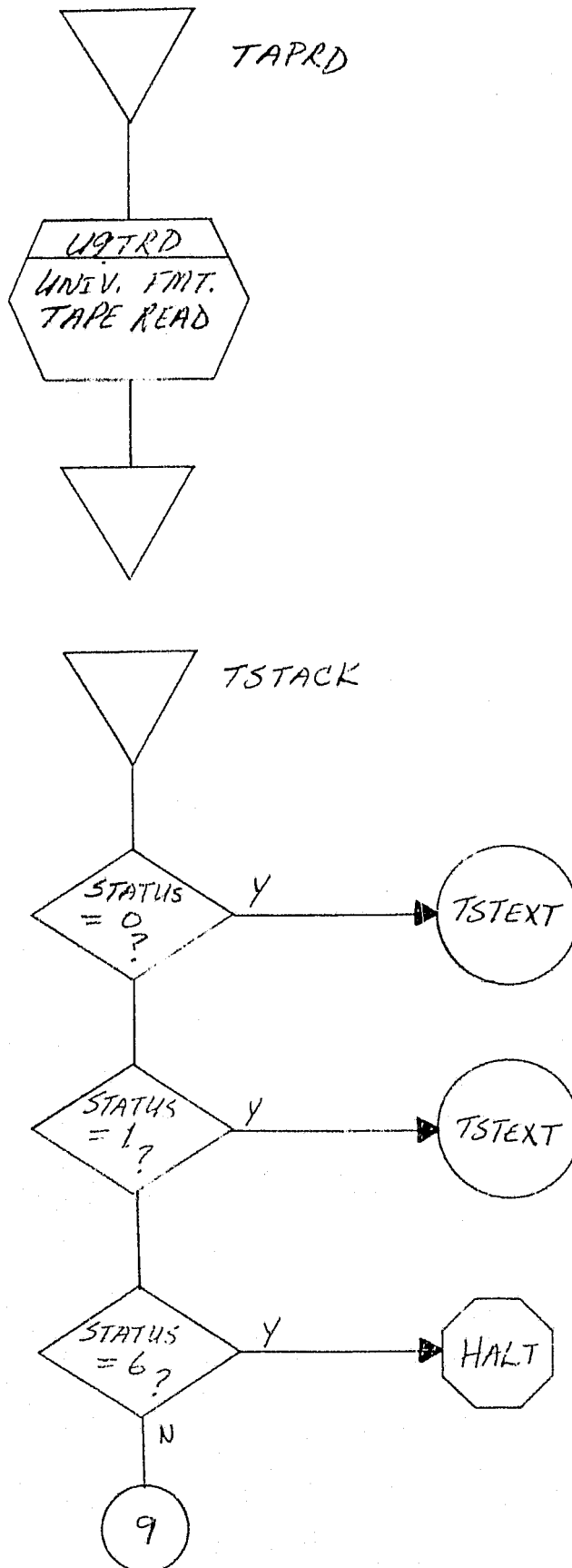


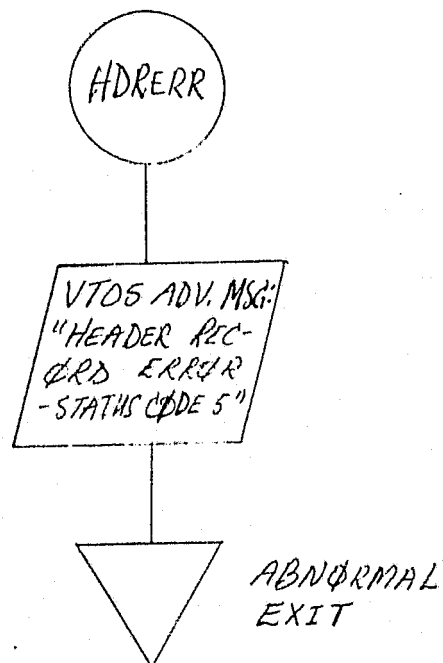
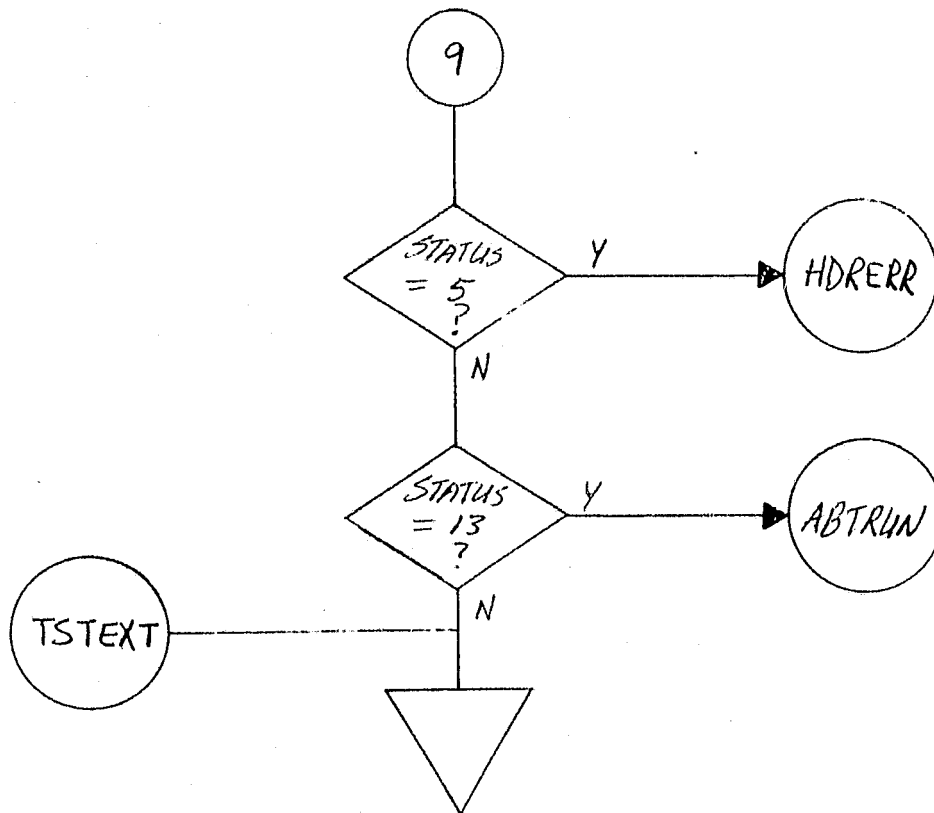


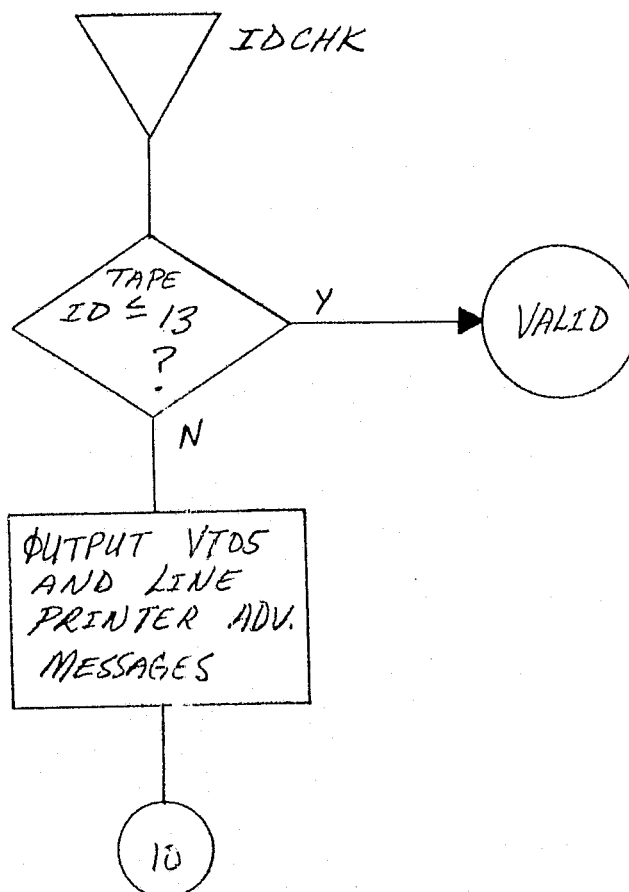
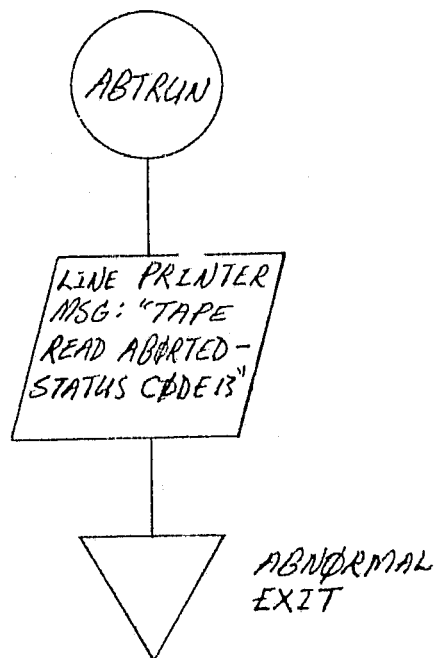


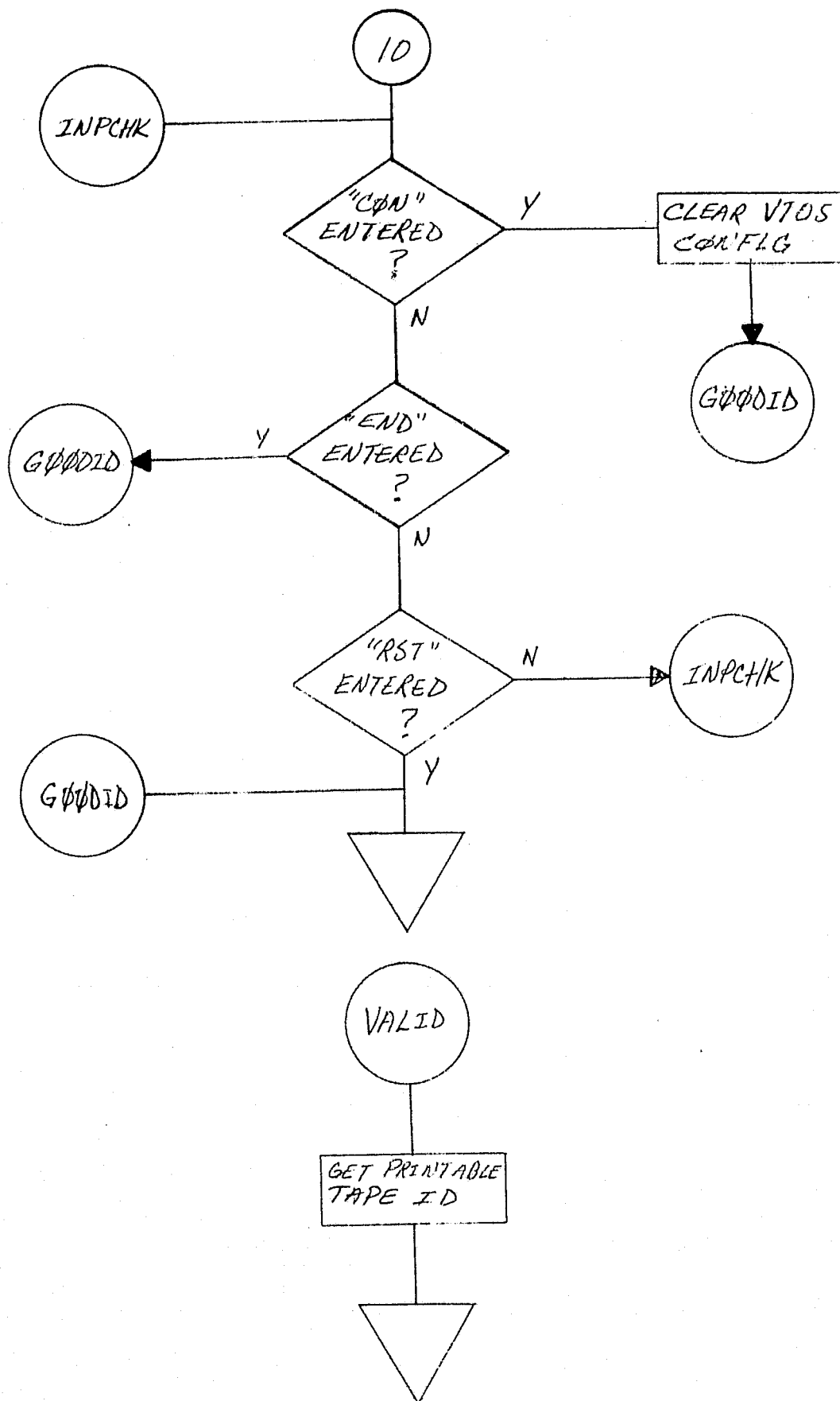


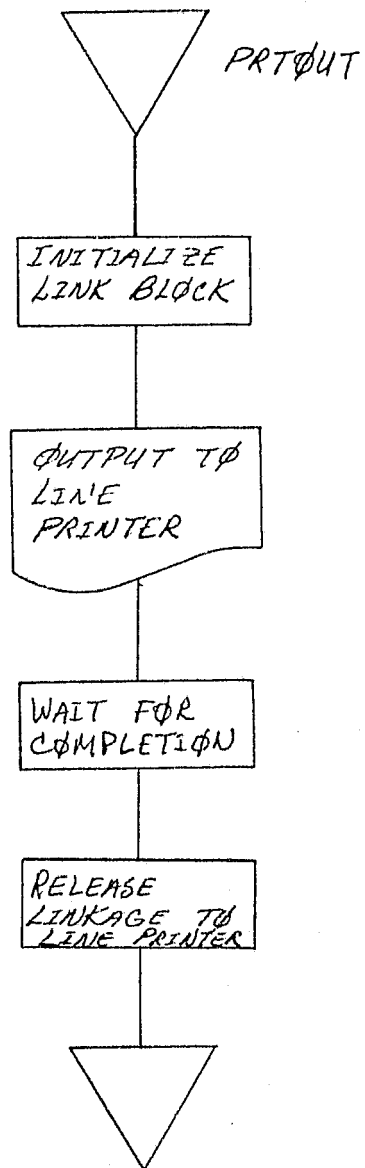














### 7.2.3 Interfaces

- A. Input Data. The input data to CDP is from universal format magnetic tapes. The data records take the form of the specific tape being processed and handled by U9TRD. One channel of each scan is passed to CDP via tape input buffers.
- B. Output Data. The input data is decoded and converted to ASCII characters to be output to the line printer.

7.2.4 Data Organization. The principle internally defined items in CDP are those associated with the VT05 display for user input.

7.2.5 Limitations. The major limitation of CDP is the processing speed. Operation time is affected by the tape read and the time required for line printer output. In addition, the bulk of paper required to output sizable images make CDP inconvenient at times.

7.2.6 Listings. See Part IV of this document published under separate cover.

## SECTION 8

### SYSTEM SOFTWARE

#### 8.1 GENERAL SYSTEM SOFTWARE CHARACTERISTICS

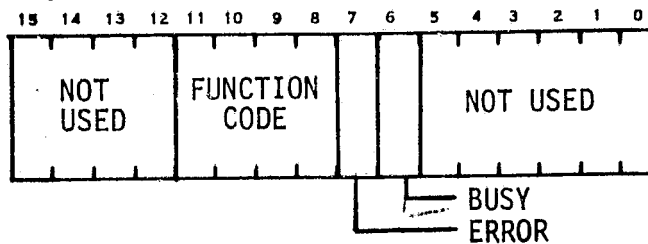
The system software for SEDS consists of three kinds -- the PDP-11 Disk Operating System (DOS) and its associated system programs; the system support software previously developed by SISO for the Preprocessor Subsystem of the Earth Resources Production Processor System (ERPPS); and the newly developed system software provided by SISO for SEDS, which handles the custom built display hardware and associated special needs. The special system software implemented for SEDS will be covered in this section. Refer to PHO-TR545, Section 3, for an explanation of DEC and preprocessor system software.

#### 8.2 SYSTEM SOFTWARE CPC CHARACTERISTICS

##### 8.2.1 Subcomponent Descriptions

- A. VTIN. This is the SEDS VT05 input service routine which handles and services all VT05 keyboard interrupts. The interrogation and disposition of these keyboard interrupts are dependent upon the composition of the static and changeable fields of the VT05 display. The master buffer set up by VTLINK is used as the controlling factor. In addition, special processing is included to interrogate special SEDS VT05 commands and program names, and to route control as requested.
- B. VTOUT. This is the SEDS VT05 display terminal output interrupt service routine. Its purpose is to chain all output requests from the VT05.
- C. VT05H. This is the VT05 display input/output request handler. The communication link between user software and the VT05 is accomplished through a number of defined I/O request packets; these packets and their functions are described in figure 8-1. The length of the call packet to

# STATUS WORD

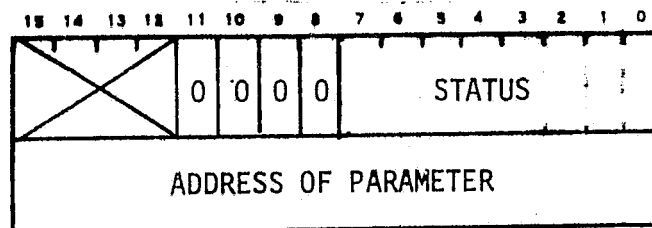


## FUNCTION CODES

- 0 = OUTPUT BY PARAMETER ADDRESS
- 1 = OUTPUT BY LINE/COLUMN NO.
- 2 = OUTPUT/STORE IN MASTER BUFFER BY LINE/COLUMN NO.
- 3 = INPUT BY LINE/COLUMN NO.
- 4 = POSITION (CURSOR) BY LINE/COLUMN NO.
- 5 = INITIALIZE MASTER DISPLAY BUFFER TO SPACES AND ERASE THE SCREEN
- 6 = REFRESH VT05 SCREEN
- 7 = MESSAGE TO LINE 1/COLUMN 41 (MAXIMUM 32 CHARACTERS IN LENGTH)
- 8 = ERASE ERROR MESSAGE
- 9 = MOVE CURSOR TO PARAMETER FIELD
- 10 = ERASE PARAMETER FROM SCREEN

NOTE: ERROR CODE SHOULD BE CHECKED UPON RETURN FROM A VT05 OUTPUT REQUEST. THE REQUESTED FUNCTION IS ABORTED IF AN ERROR IS DETECTED IN THE DISPLAY I/O REQUEST PACKETS.

### CODE 0 - OUTPUT BY PARAMETER ADDRESS



### CODE 1 - OUTPUT BY LINE/COLUMN NO.

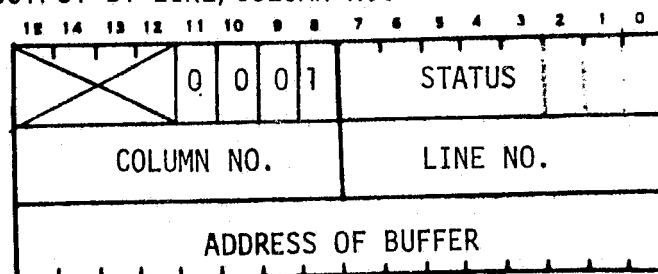
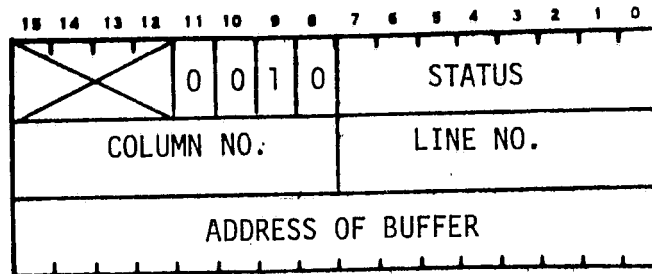
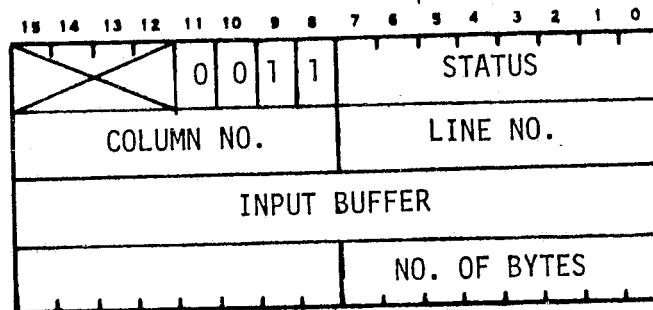


Figure 8-1 VT05 Display I/O Request Packets

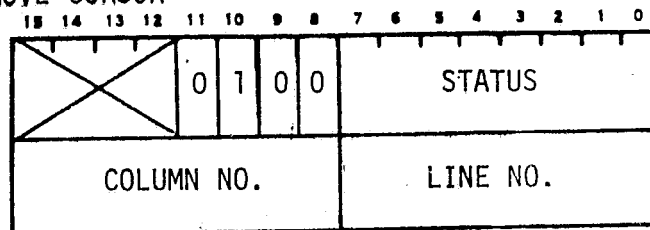
CODE 2 - OUTPUT/STORE IN MASTER BUFFER



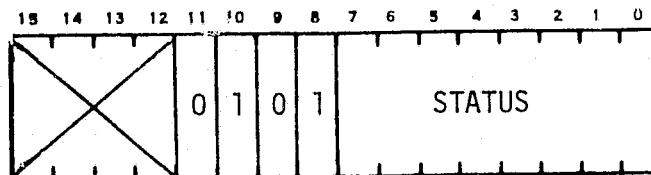
CODE 3 - INPUT BY LINE/COLUMN NO.



CODE 4 - MOVE CURSOR



CODE 5 - ERASE DISPLAY



CODE 6 - REFRESH DISPLAY

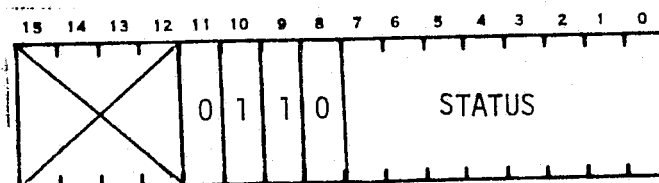
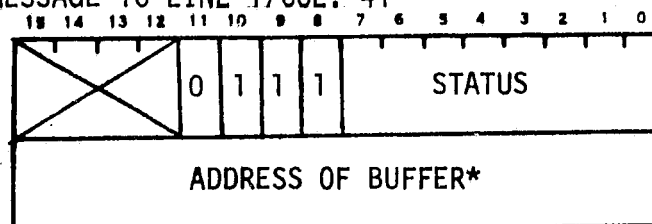


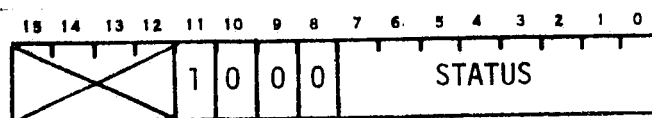
Figure 8-1 (Cont'd)

CODE 7 - MESSAGE TO LINE 1/COL. 41

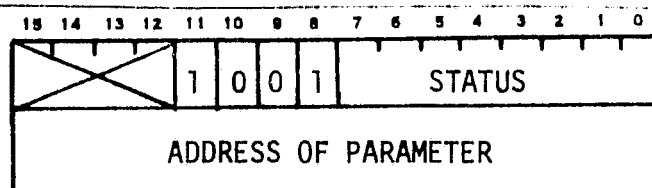


*ASCII CODED MESSAGE MUST BE FOLLOWED BY TWO LINE FEED CHARACTERS ( $12_8$ )

CODE 8 - ERASE ERROR MESSAGE



CODE 9 - MOVE CURSOR TO PARAMETER FIELD



CODE 10 - ERASE PARAMETER FROM SCREEN

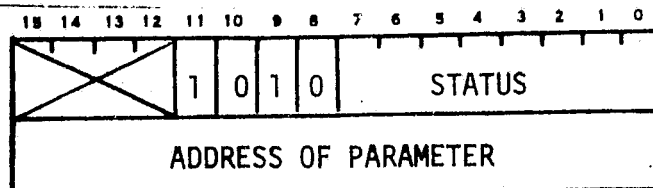


Figure 8-1 (Cont'd)

VT05 varies from one to four words, depending upon the function requested. The call to VT05H is accomplished by placing the address of the packet on the stack and issuing an EMT call, as follows:

```
MOV #PACKET, -(SP)
EMT 142
TSTB PACKET
BNE .-4
```

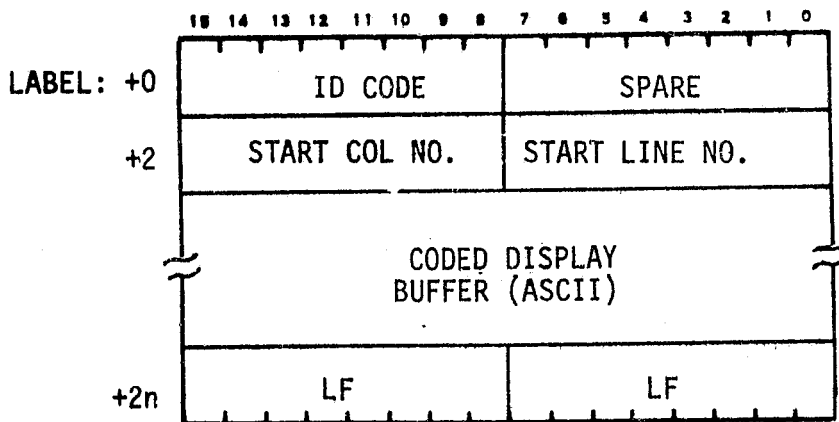
The low byte of the first word is checked for nonzero for busy and error condition.

- D. VTLINK. This is a VT05 routine called directly by the user program to set up VT05 interface and control. A particular VT05 display is initialized and is set up for user changeable and static fields. This capability requires the user to code two tables. The first is called the initialized VT05 display buffer, and may contain up to 1440 ASCII characters (20 lines by 72 characters); it is preceded by a four-byte header and followed by two ASCII line feed characters. The second table must immediately follow the first; the number of entries in this second table is determined by the number of input changeable fields available to the user; each changeable input field requires a three-to-six-word packet with specific information about that particular input entry. This table is terminated with a one-word entry containing a -1. The formats of these two tables are shown in figure 8-2. Six internal VT05 linkage tables are initialized and set up by VTLINK from the initial call. Figure 8-3 shows in detail the content and format of these six internal tables.
- E. CCTH. This is a 9-track tape handler designed to provide a fast interrupt-driven read/write capability outside the DOS for 9-track tape. CCTH is entered from the DOS EMT handler at the address specified in the monitor residency table, MRT. The interrupt portion of CCTH (CCTINT) is entered from the interrupt vector when the done interrupt is to be serviced. The 9-track tape handler requires that the

# VT05 DISPLAY OUTPUT BUFFER FORMAT

CALLING SEQUENCE: MOV #LABEL,R0  
JSR R5,VTLINK

## DISPLAY BUFFER (TABLE 1)



1. CODED DISPLAY BUFFER MUST BE PRECEDED BY FOUR 8-BIT BYTES CONTAINING DISPLAY ID CODE, SPARE, START COLUMN NO., AND START LINE NO., RESPECTIVELY.
2. TO TERMINATE AN ASCII CODED LINE, IF LESS THAN 72 CHARACTERS, FOLLOW CODE WITH ONE LINE FEED (LF). TWO CONSECUTIVE LINE FEED CHARACTERS DESIGNATE THE END OF THE DISPLAY BUFFER.
3. TO OMIT LINE(S), FOLLOW THE LF WITH A CARRIAGE RETURN (CR) INDICATING THAT THE NEXT TWO BYTES CONTAIN THE NEXT LINE NO. AND COLUMN NO.

Figure 8-2 VT05 Display Linkage

INPUT PARAMETER BUFFER (TABLE 2)

.BYTE XX,YY (XX = LINE NO., YY = COLUMN NO.)

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
+0	COL NO.								LINE NO.							
+2	SPECIAL CODE								NO. OF CHARS							
+4	ADDRESS OF PARAM VALUE															
+6	UPPER LIMIT OF PARAM VALUE															
+8	LOWER LIMIT OF PARAM VALUE															
+10	SPECIAL PROCESSING ENTRY POINT															

ADR OF SPECIAL PROCESSOR PACKET

FORMAT

ARRAY

WILL BE DETERMINED BY SPECIAL  
CODE (UPPER BYTE OF WORD +2)

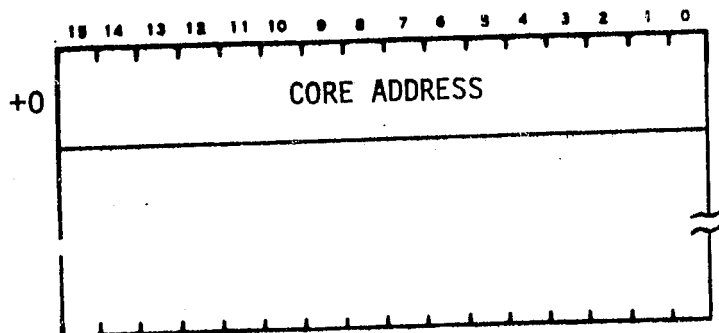
SPECIAL CODES (WORD +2, HIGH BYTE):

- 0 = SET FIELD OPERATOR CHANGEABLE. INITIAL VALUE EXPECTED TO BE IN BINARY.  
INPUT STORED IN BINARY AFTER LIMIT CHECK
- 1 = FIELD NOT OPERATOR CHANGEABLE, OUTPUT ONLY
- 2 = FIELD IS OPERATOR CHANGEABLE. INPUT/OUTPUT IN ASCII. EXPECTS WORD +10 TO BE  
A SPECIAL PROCESSOR ADDRESS OR THE LABEL "VINEXT"
- 3 = FIELD IS OPERATOR CHANGEABLE. SAME AS CODE 2 EXCEPT INPUT/OUTPUT IN BINARY
- 4 = FIELD IS OPERATOR CHANGEABLE. SAME AS CODE 2 EXCEPT INITIAL UPDATE OF  
VT05 SCREEN IS INHIBITED.
- 5 = FIELD IS OPERATOR CHANGEABLE. SAME AS CODE 3 EXCEPT INITIAL UPDATE OF  
VT05 SCREEN INHIBITED

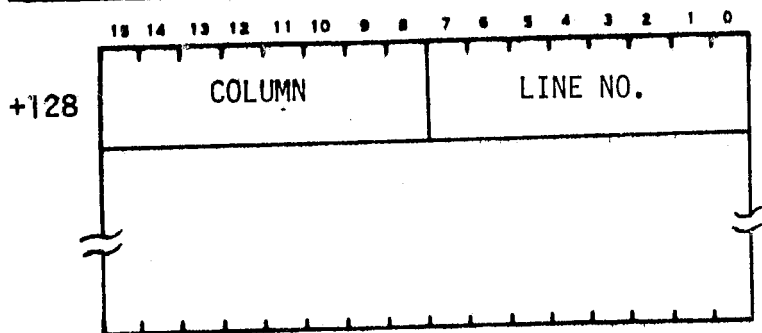
Figure 8-2 (Cont'd)



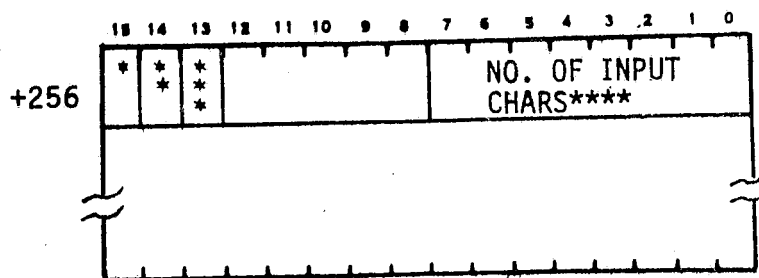
PARAMETER ADDRESS TABLE (PAVTBL)



PARAMETER POSITION TABLE (PPATBL); SAME AS WORD +0



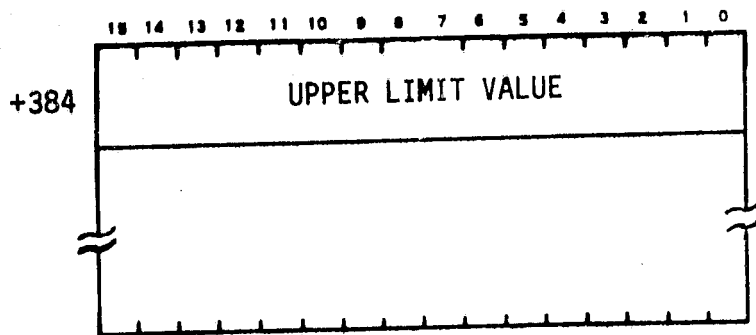
NO. OF CHARACTERS TABLE (NOCTBL)



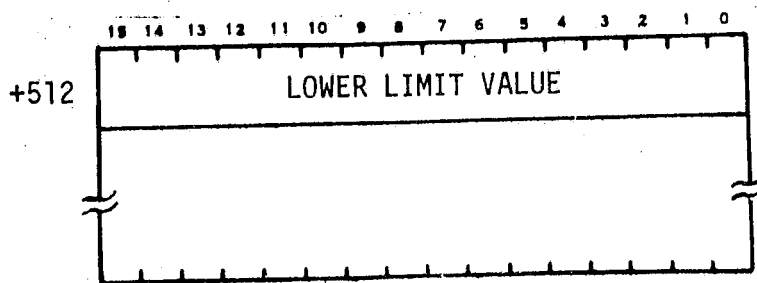
*SPECIAL PROCESSOR (IF SET,  
LOWER 15 BITS CONTAIN OFFSET  
INTO SPECIAL PROCESS TABLE)  
**IF SET, OPERATOR CHANGEABLE  
***IF SET, NOT OPERATOR CHANGE-  
ABLE, OUTPUT ONLY  
****BECOMES OFFSET INTO SPATBL  
WHEN FUNCTION CODE 2 AND 3  
USED

Figure 8-3 VT05 Input Parameter Linkage Tables

UPPER LIMIT TABLE (LLATBL); SAME AS WORD +8



LOWER LIMIT TABLE (LLATBL); SAME AS WORD +8



SPECIAL PROCESS OFFSET TABLE (SPATBL)

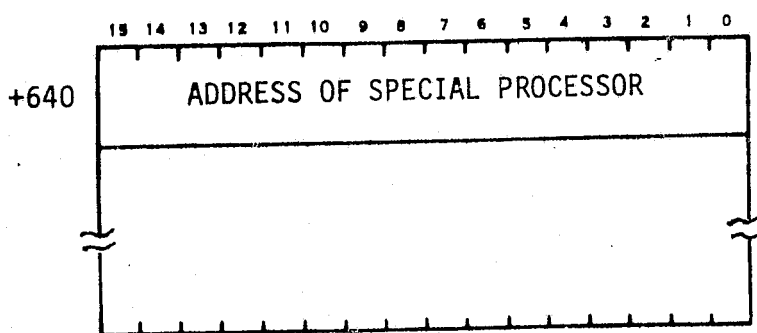


Figure 8-3 (Cont'd)

general registers and processor stack be set up by the DOS EMT handler. Inputs to CCTH are in a parameter block which is defined in figure 8-4. Output from the handler is in the status byte of the PBA, as shown in the same figure. Also saved is the address of the parameter block for the current operation. CCTH is divided into an initialization portion and an interrupt service portion. The initialization portion is called through the EMT handler; it selects the units, initializes the operation, and enables the done interrupt. The interrupt service portion is called for the done interrupt through the 9-track interrupt vector; it checks for all possible conditions which could have occurred during execution of the operation, and reports the status back to the user program in the status byte of the parameter block. The calling program calls CCTH by pushing a PBA onto the processor stack and then executing an EMT instruction which contains an identifier associated with CCTH. For SEDS, the EMT identifier for CCTH and communication for tape units on controller No. 1 is 140. The calling sequence is as follows:

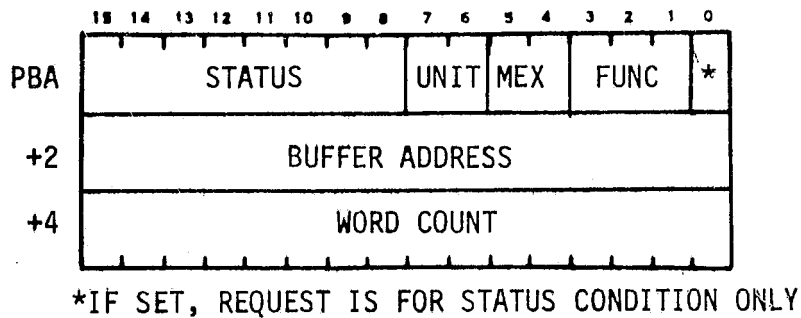
```
MOV #PBA,-(SP)
EMT 140
```

- F. CCTH2. This is a 9-track tape handler identical to CCTH except that tape communication is established for tape units on controller No. 2. The SEDS EMT identifier is 145. The interrupt portion of CCTH2 (CCTNT2) is entered from the interrupt vector when the done interrupt is to be serviced from tape controller No. 2. For SEDS, the EMT identifier for CCTH2 for tape units on controller No. 2 is 145. The calling sequence is as follows:

```
MOV #PBA2,-(SP)
EMT 145
```

- G. IDEH. This is the imagery display equipment handler for SEDS. It provides the interface between the display controller and SEDS user programs, and provides for interrupt servicing and status posting for the controller. The initialization portion of IDEH is entered through the DOS EMT

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FUNCTION (BITS 1-3):

- 0 = OFFLINE
- 1 = READ
- 2 = WRITE
- 3 = WRITE EOF
- 4 = FORWARD SPACE RECORDS (COUNT IN PBA+4)
- 5 = REVERSE SPACE RECORDS (COUNT IN PBA+4)
- 6 = WRITE EXTENDED GAP
- 7 = REWIND

MEX (BITS 4,5):

EXTENDED ADDRESS BITS 17 and 18

UNIT (BITS 6,7):

- 0 = UNIT 0
- 1 = UNIT 1

STATUS (BITS 8-15, SET FOR CONDITION):

- 8 = DRIVE NOT READY
- 9 = PARITY ERROR
- 10 = END-OF-FILE
- 11 = END-OF-TAPE
- 12 = BEGINNING OF TAPE
- 13 = DEVICE FAILURE
- 14 = TAPE UNIT
- 15 = OPERATION NOT COMPLETE (BUSY)

Figure 8-4 Magnetic Tape Drive Parameter Block

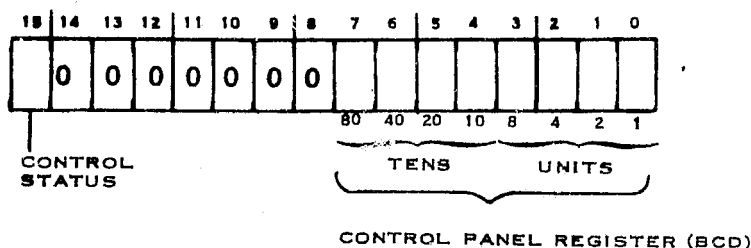
handler at the address specified in the monitor residency table, MRT. The interrupt service portion of the handler, HDINT is entered through the interrupt vector when any one of the three interrupts occur. The program calling IDEH (in SEDS applications programs, the routine is called DISPL) does so by pushing a PBA onto the processor stack and then executing an EMT instruction which contains an identifier associated with IDEH. For SEDS, this identifier is 141. The calling sequence is as follows:

```
MOV #PBA,-(SP)
EMT 141
```

Control is returned by the handler at the instruction following the EMT. The user program must check the busy flag before calling IDEH again for a display function, to ensure that the device is not busy. Figure 8-5 shows in detail the display parameter block for IDEH.

8.2.2 Flow Charts. See the 55 pages following figure 8-5.

# IDPBA (STATUS)

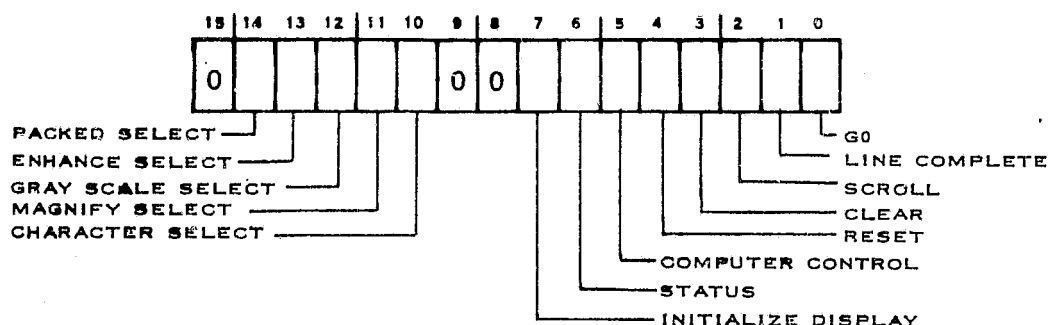


Used only to return status to the user program.

Bit 15 - If set, indicates that format of displayed image is selected from display operator's control panel; if cleared, indicates that format control is being selected by software.

Bits 7-0 - Two BCD digits dialed in at the panel with values of 00-99; used for options and controlled by the operator.

# IDPBA + 2 (FORMAT AND COMMAND)



Bit 15 - If set, the computer control command must be executed before the format can be software-selected.

Bits 14-10 instruct the handler to select the specified display format.

Bit 14 - If set, refresh data is displayed with color assignments following: (LSB & MSB) Bits 2 and 3 = blue; Bits 4 and 5 = green; Bits 6 and 7 = red. This bit may not be used with enhance selected (see bit 13).

Bit 13 - If set, data will be modified by contents of enhancement look-up tables before being displayed.

Figure 8-5 Imagery Display Parameter Block (IDPBA)

Bit 12 - If set, a gray scale or color bar will be displayed across lower 48 lines of displayed image.

Bit 11 - If set, area bracketed by the cursor will be magnified to fill the screen.

Bit 10 - If set, pixel value will be converted to an alphanumeric character and displayed.

Bits 7-0 command the display handler to initiate the described action.

Bit 7 - This command executes in a single call a reset and clear on the display and positions the cursor at the home position

Bit 6 - This command causes no interaction with the display, but simply returns to the parameter block the current display status, control register value and X-Y cursor position.

Bit 5 - Reverts display format control to the user software.

Bit 4 - Initializes display logic that keeps count of even/odd scans for automatic scrolling.

Bit 3 - Erases the refresh memory.

Bit 2 - Scrolls the image in the selected direction, up or down. If scroll mode is selected in the input parameter word (see below), the image will scroll automatically after every other GO.

Bit 1 - Signifies the completion of a scan line that has been constructed one color at a time.

Bit 0 - Indicates a message transfer.

#### IDPBA + 4 (INPUT PARAMETERS)

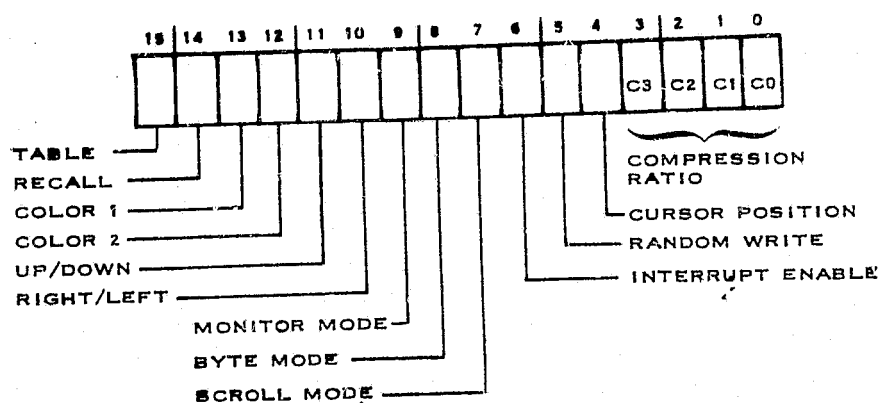


Figure 8-5 (cont'd)

Expands on the type of data transfer that is to take place, specifies the purpose of the data and identifies the mode of operation of the display.

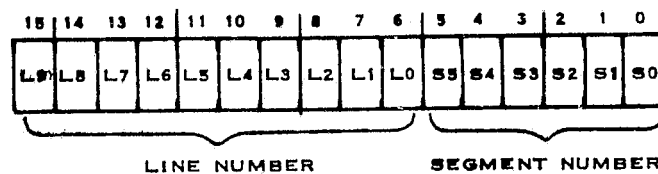
- Bit 15 - Specifies that this message transfer is to one of three enhancement tables (one for each color). Desired table is selected by bits 13 and 12. The format of data for enhancement table must be specific, with the upper byte containing the address in the table to receive the data and the lower byte containing the data value itself. This is accomplished by setting bit 12 in the Format and Command Word and reading a scan line from the color bar which is displayed.
- Bit 14 - Specifies that this message transfer is from the display memory addressed by line and segment.
- Bits 13-12 - In combination, these color tag each message to or from the display unit as follows: 0-1 = red with LSB/MSB 6/7; 1-0 = green with LSB/MSB 4/5; 1-1 = blue with LSB/MSB 2/3; 0-0 = black and white (all 6 bits) with LSB/MSB 2/7.
- Bit 11 - If set, displayed image will move up by two scan lines when a scroll command or condition occurs; if cleared, image will move down.
- Bit 10 - If set, causes update message to be displayed left-to-right; if cleared, data will be displayed right-to-left.
- Bit 9 - Allows display unit to trap data from the UNIBUS for screening; only one call to IDEH is required to display an image in this mode. UNIBUS is monitored by the display hardware for the final word address (IDPBA + 10), then begins trapping data for subsequent addresses until the message length (IDPBA + 12) is satisfied. When it is, the display again monitors UNIBUS for final word address. If SCROLL MODE is selected, image will scroll in the desired direction after every other scan.
- Bit 8 - Causes display unit to discard high order byte of each update message transfer.
- Bit 7 - Allows display to scroll after every other message transfer to the display; i.e., after every other GO.
- Bit 6 - Permits display unit to generate interrupts.
- Bit 5 - Specifies that associated message transfer is to a random line and/or segment on the display; bit is required to keep the update from affecting the scroll and compression logic.

Figure 8-5 (cont'd)



- Bit 4 - In this call only, positions the cursor to the point specified by the X and Y positions passed in the parameter block, IDPBA 14 and 16.
- Bits 3-0 - Applied to every data message sent to the display unit; first pixel will be the Cth byte and every Cth byte following the first displayed pixel.

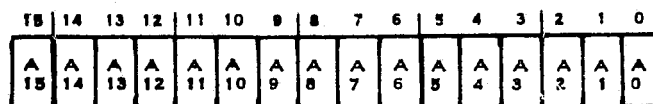
IDPBA + 6 (READ/WRITE LINE AND SEGMENT)



Allows user to address display image as to where a message is output to or recalled from (see figure 3- ).

- Bits 15-6 - Specify image line number to be updated or recalled. For scrolling bottom to top, use line = 0; for scrolling top to bottom, use line = 429.
- Bits 5-0 - Specify image starting segment number to be updated or recalled from. Each line is divided into 19 segments of 32 pixels each, with only 18 segments visible. The 19th scan line in blanking can be updated and recalled, so that it can be used for such things as scan line identification.

IDPBA + 10 (FIRST WORD ADDRESS)



Specifies the 16 least significant bits of the update or recall buffer start address.

IDPBA + 12 (MEMORY EXTENSION BITS AND MESSAGE LENGTH)

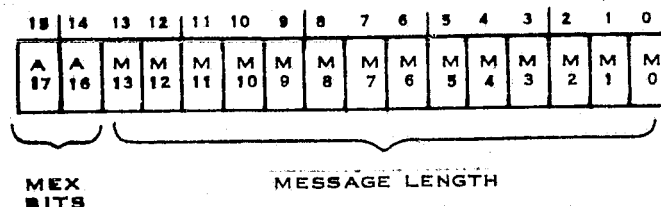


Figure 8-5 (cont'd)

Bits 15-14 - Specify the two most significant bits of the update or recall buffer First Word Address (see above). These bits allow buffer addresses of 18 bits.

Bits 13-0 - Specify the number of 16-bit word transfers in the update or recall message.

IDPBA + 14 (X-POSITION)

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	Y ₈	Y ₇	Y ₆	Y ₅	Y ₄	Y ₃	Y ₂	Y ₁	Y ₀

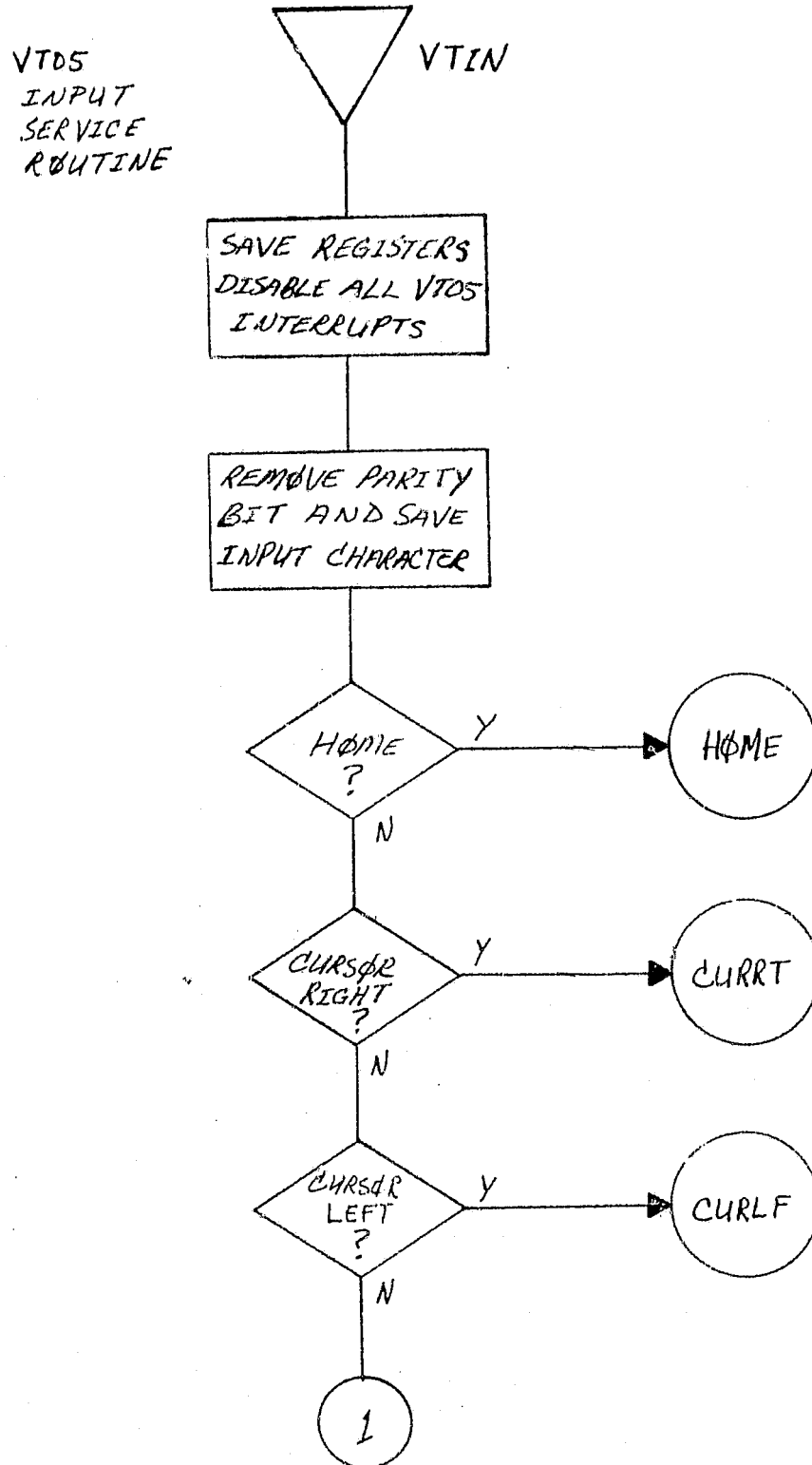
Specifies the binary count horizontal location of the center of the cursor with respect to the displayed image (see figure 2-2). Home position = 1140 (608₁₀). The cursor is two segments (64 pixels) wide.

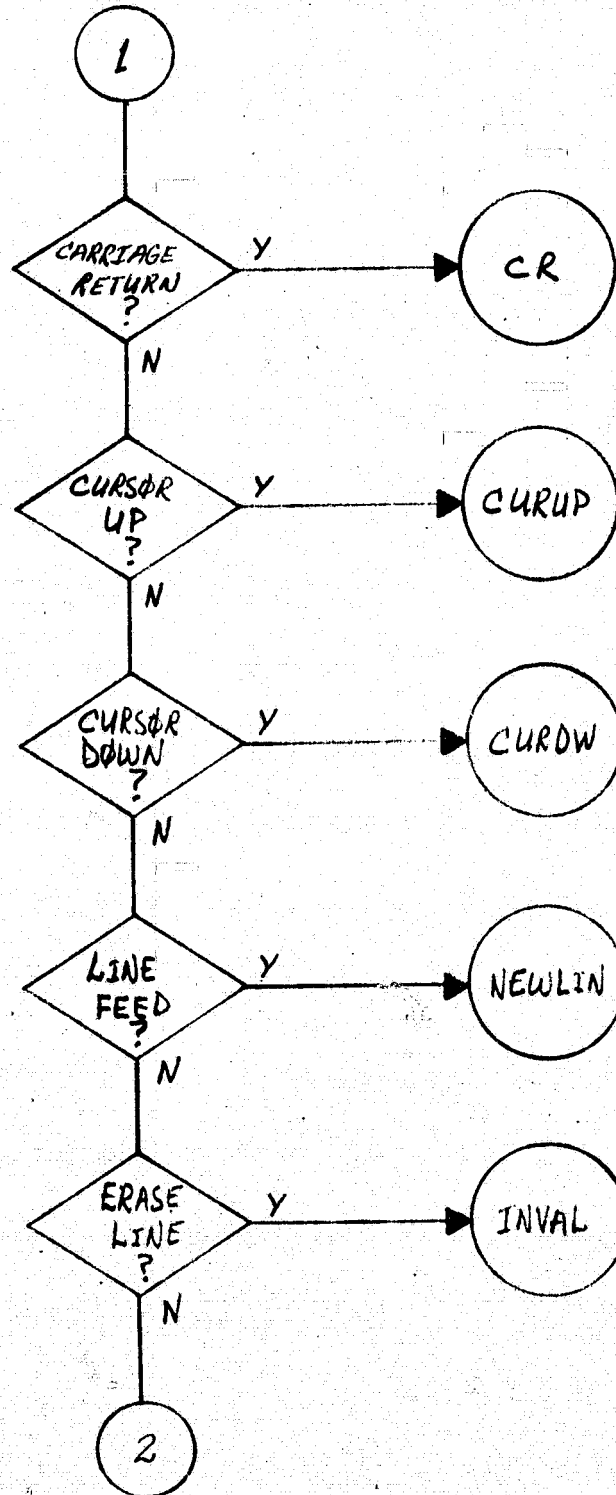
IDPBA + 16 (Y-POSITION)

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	0	X ₈	X ₈	X ₇	X ₆	X ₅	X ₄	X ₃	X ₂	X ₁	X ₀

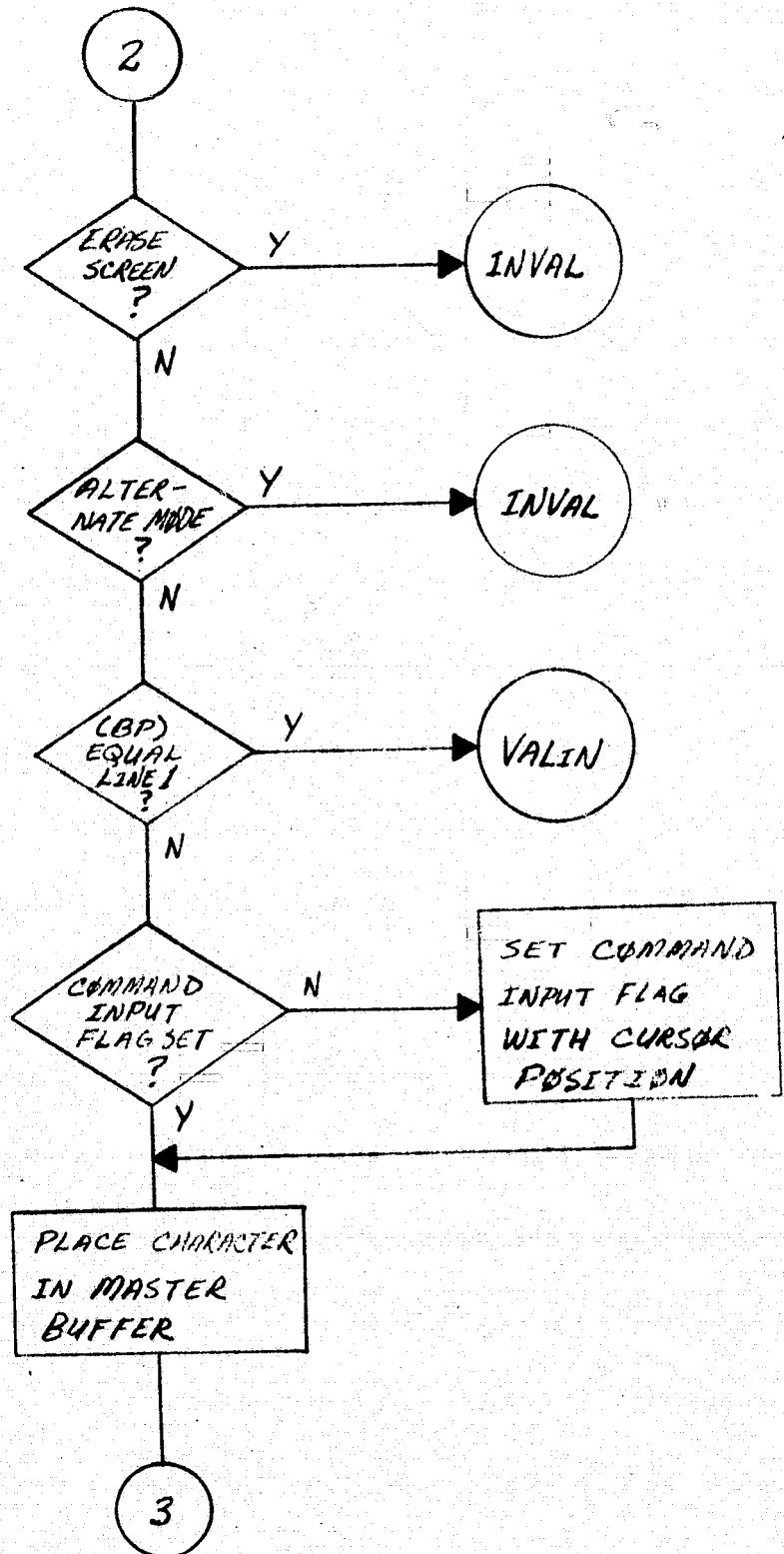
Specifies the binary count vertical location of the center of the cursor with respect to the displayed image (see figure 2-2). Home position = 030 (24₁₀). The cursor is 48 lines high.

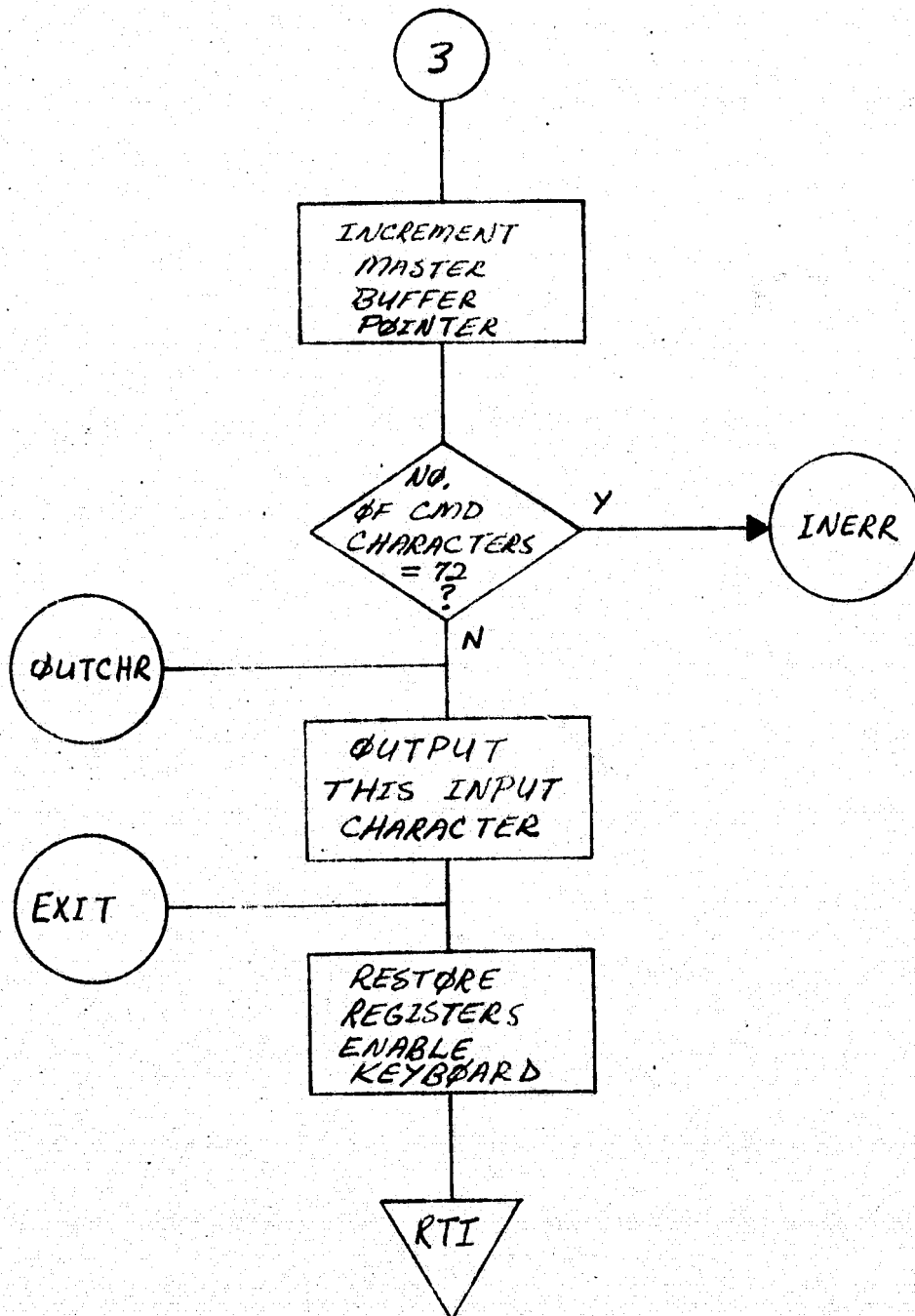
Figure 8-5 (cont'd)

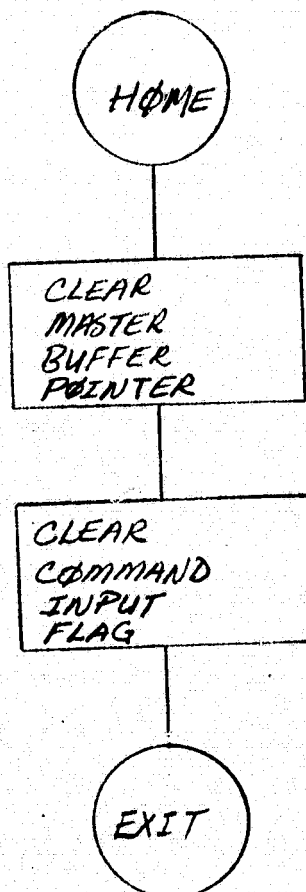
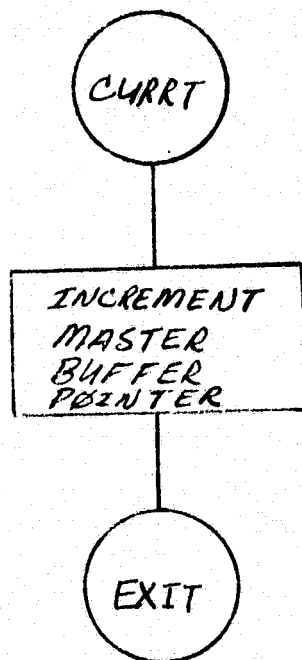


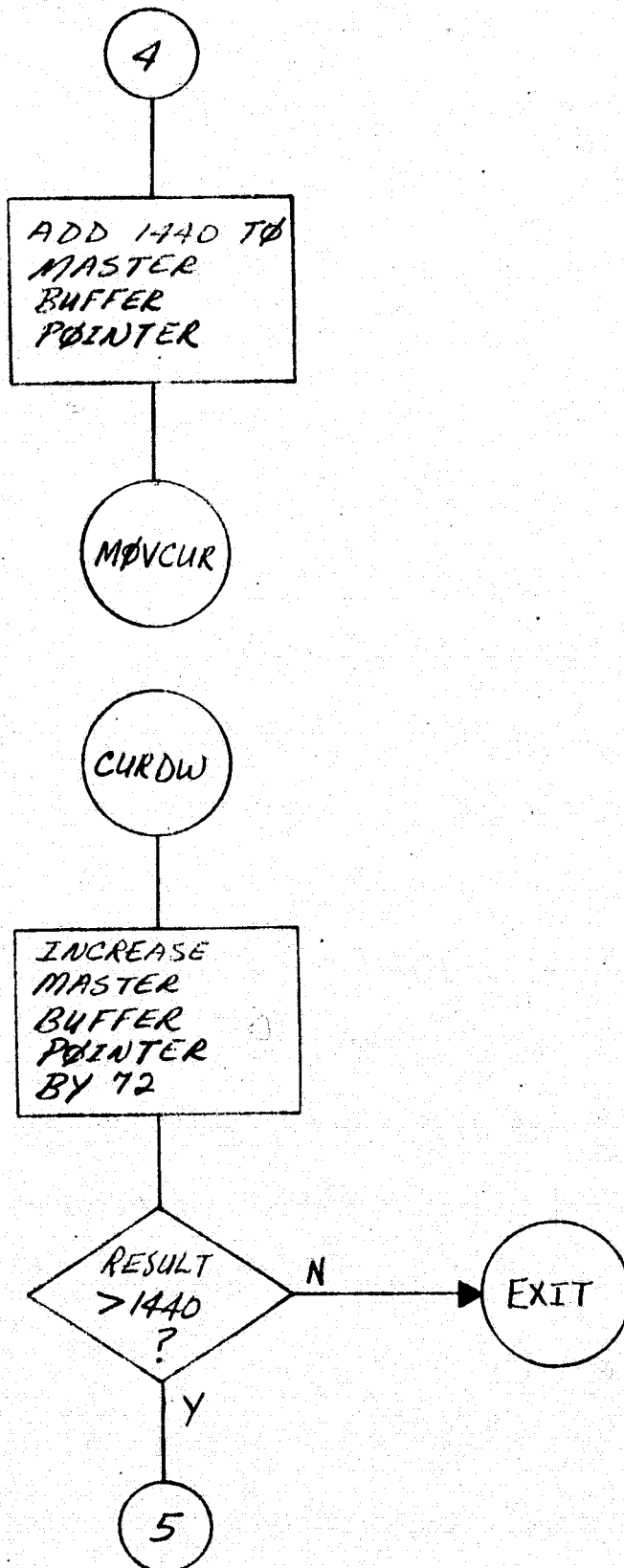


BP = BUFFER POINTER

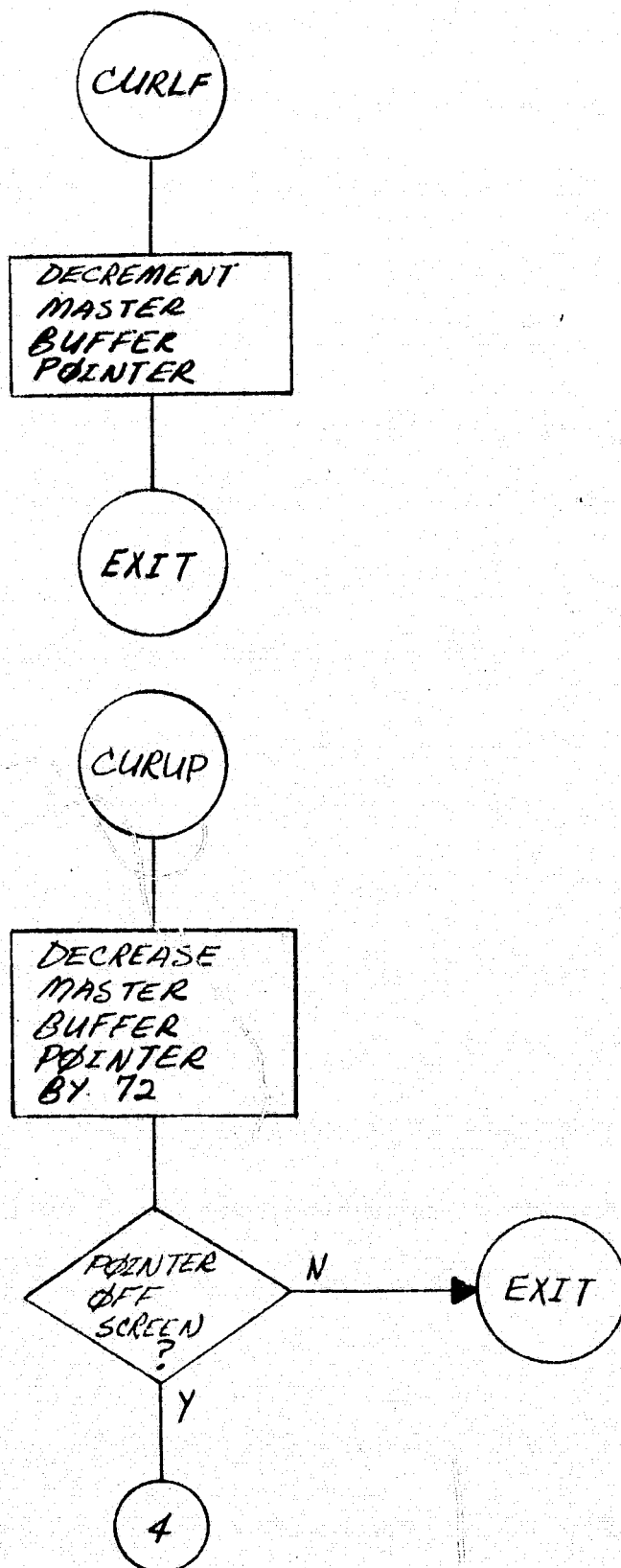


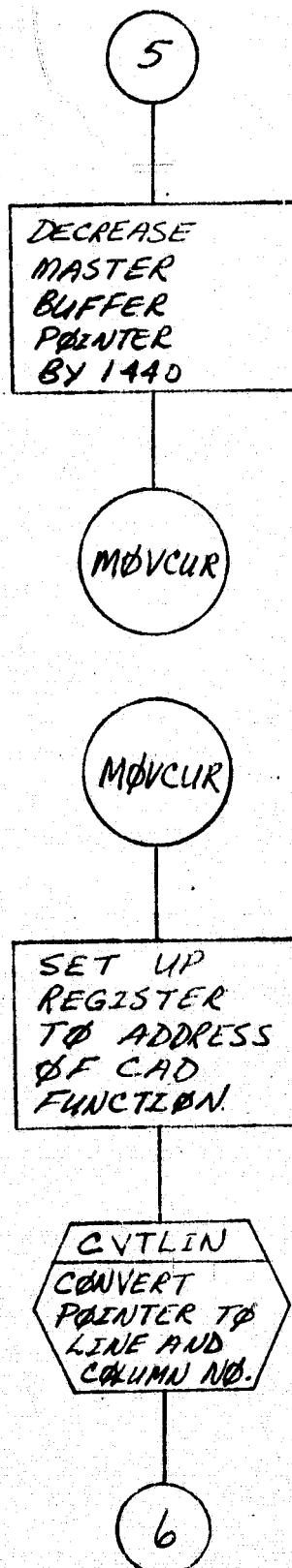


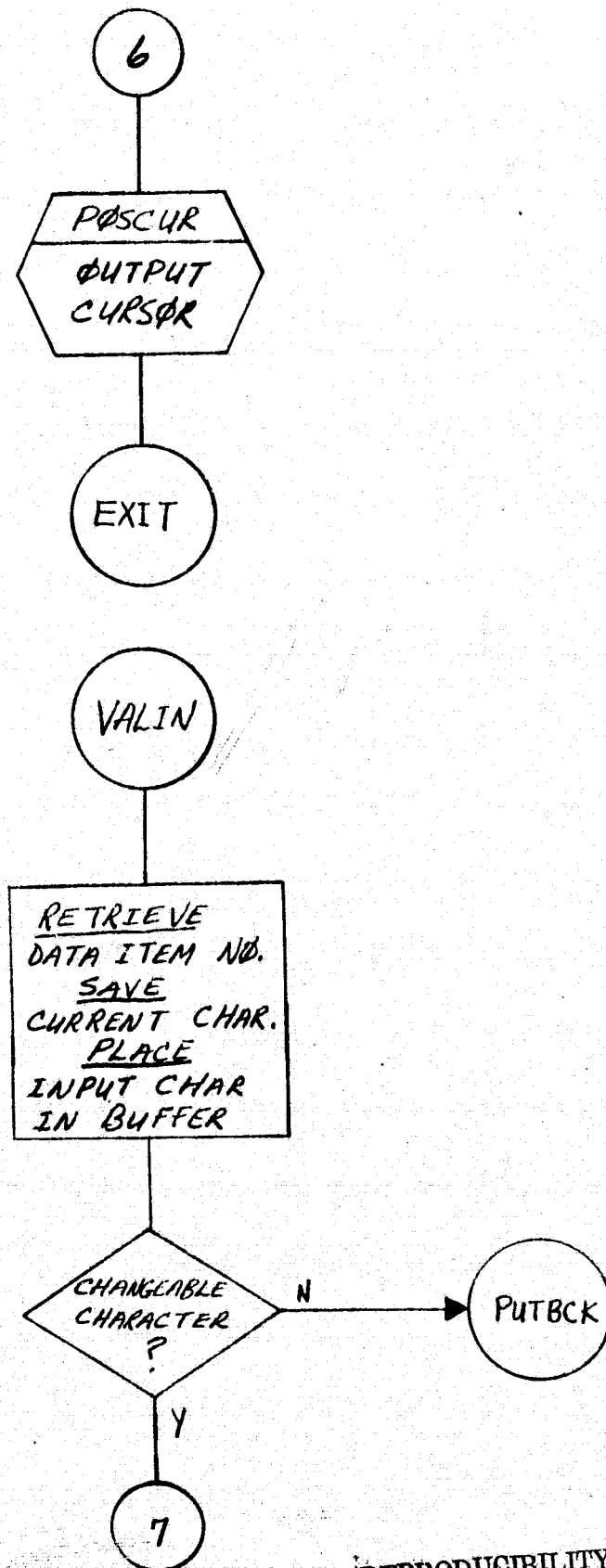


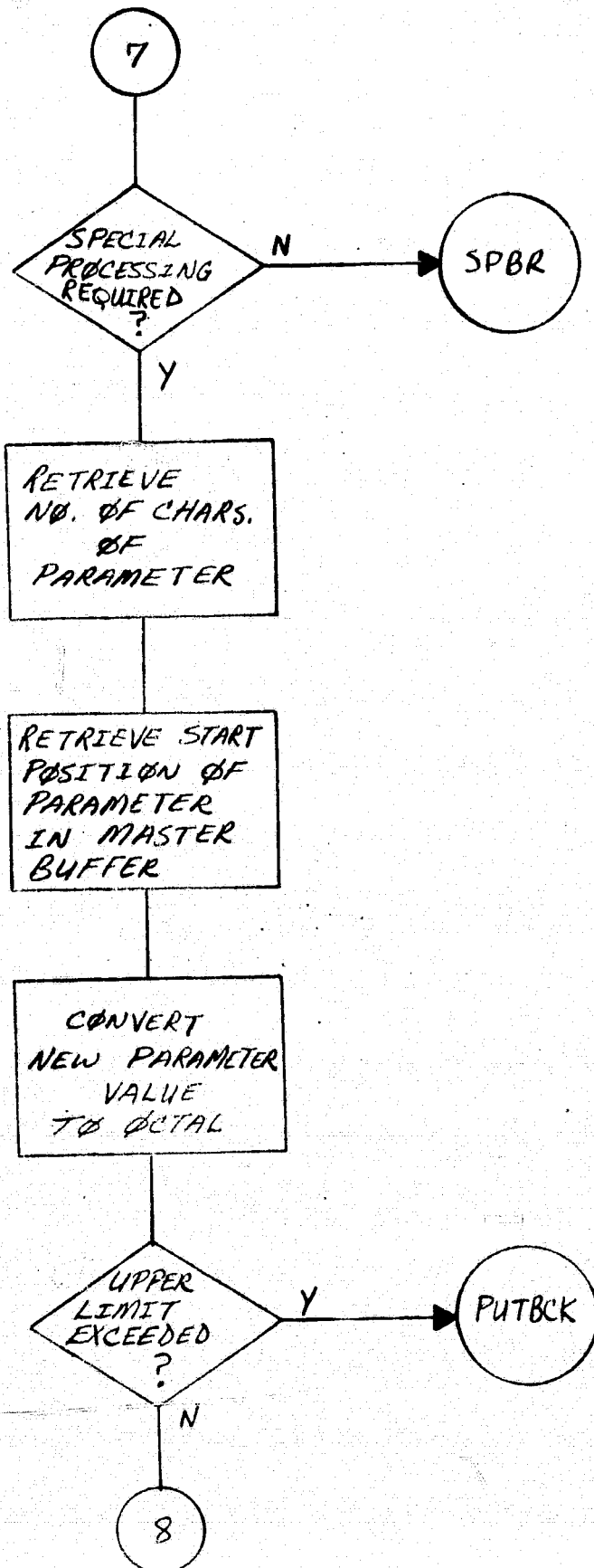


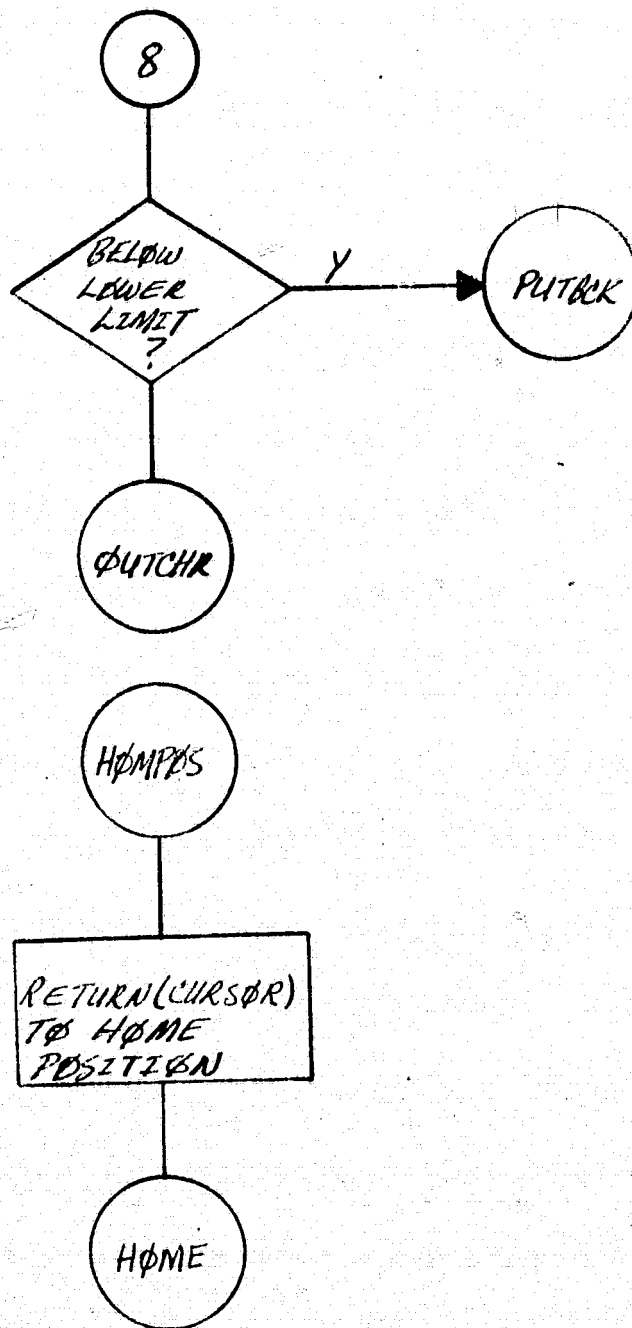


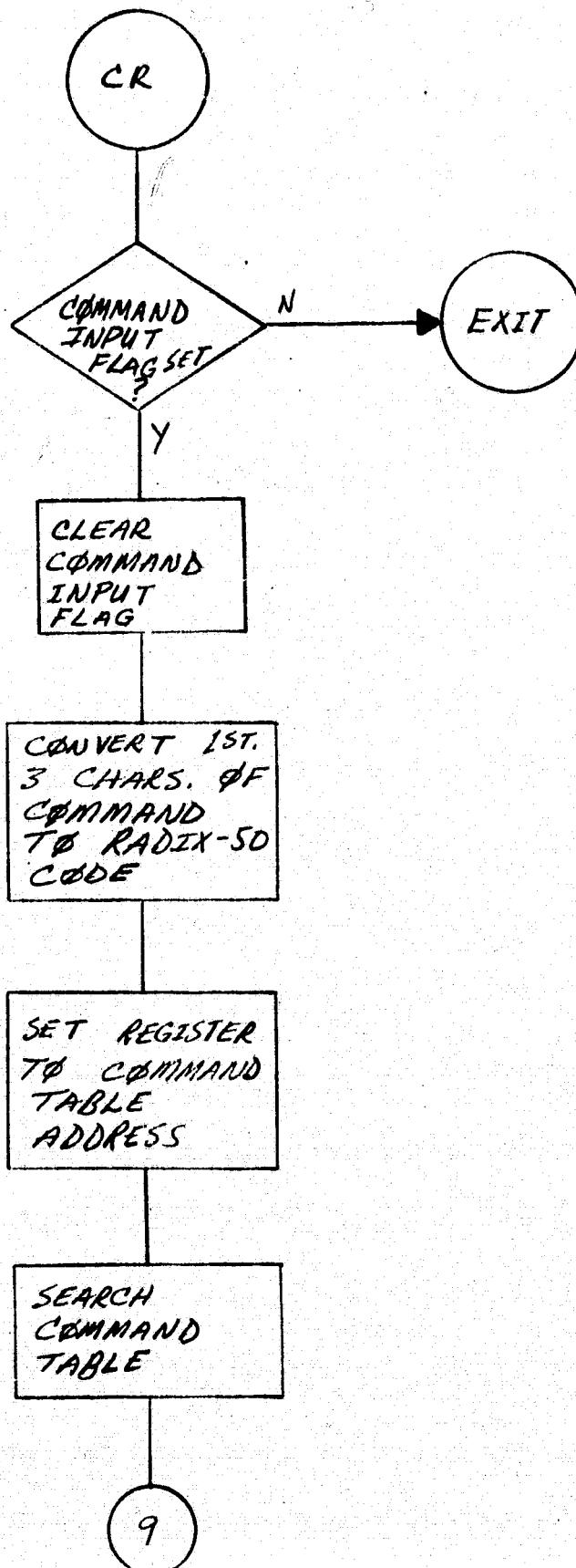


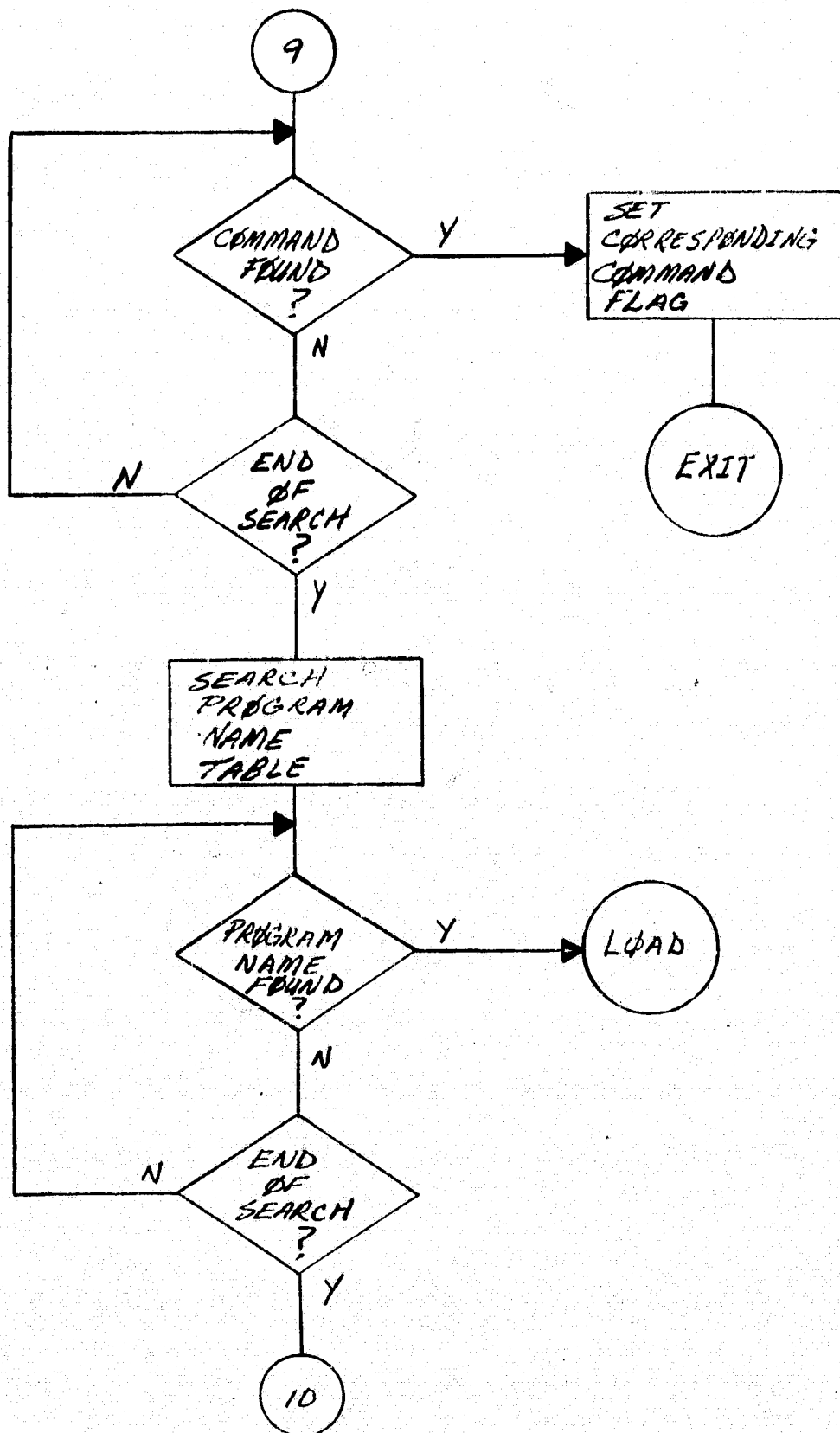




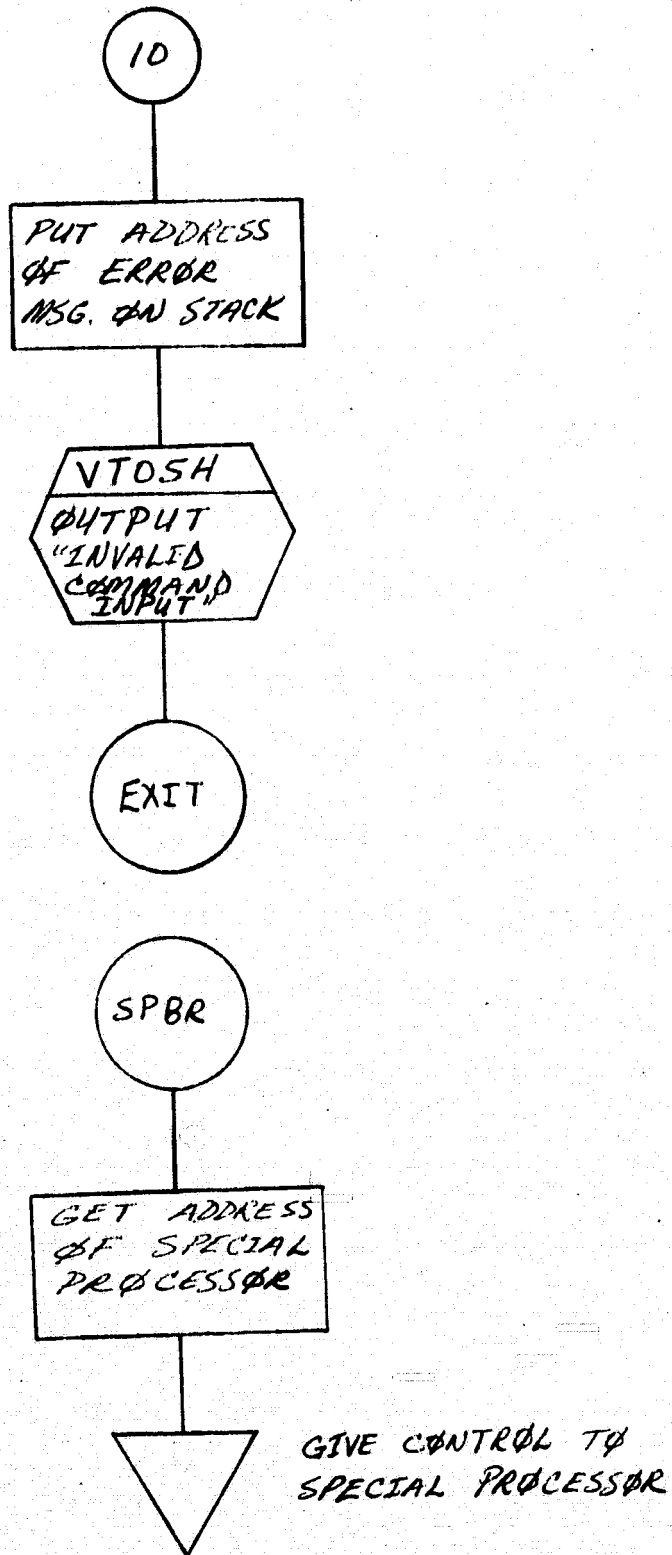




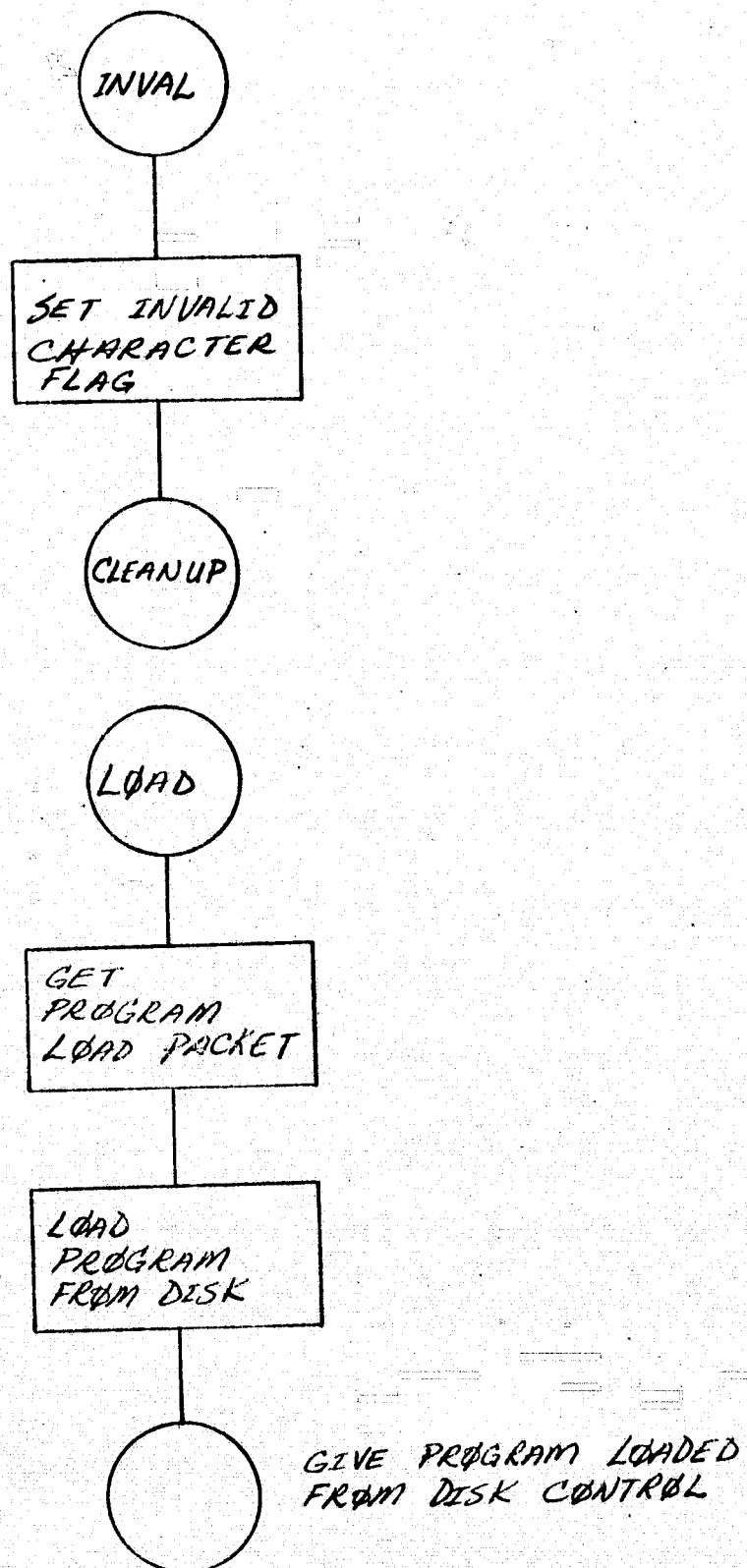


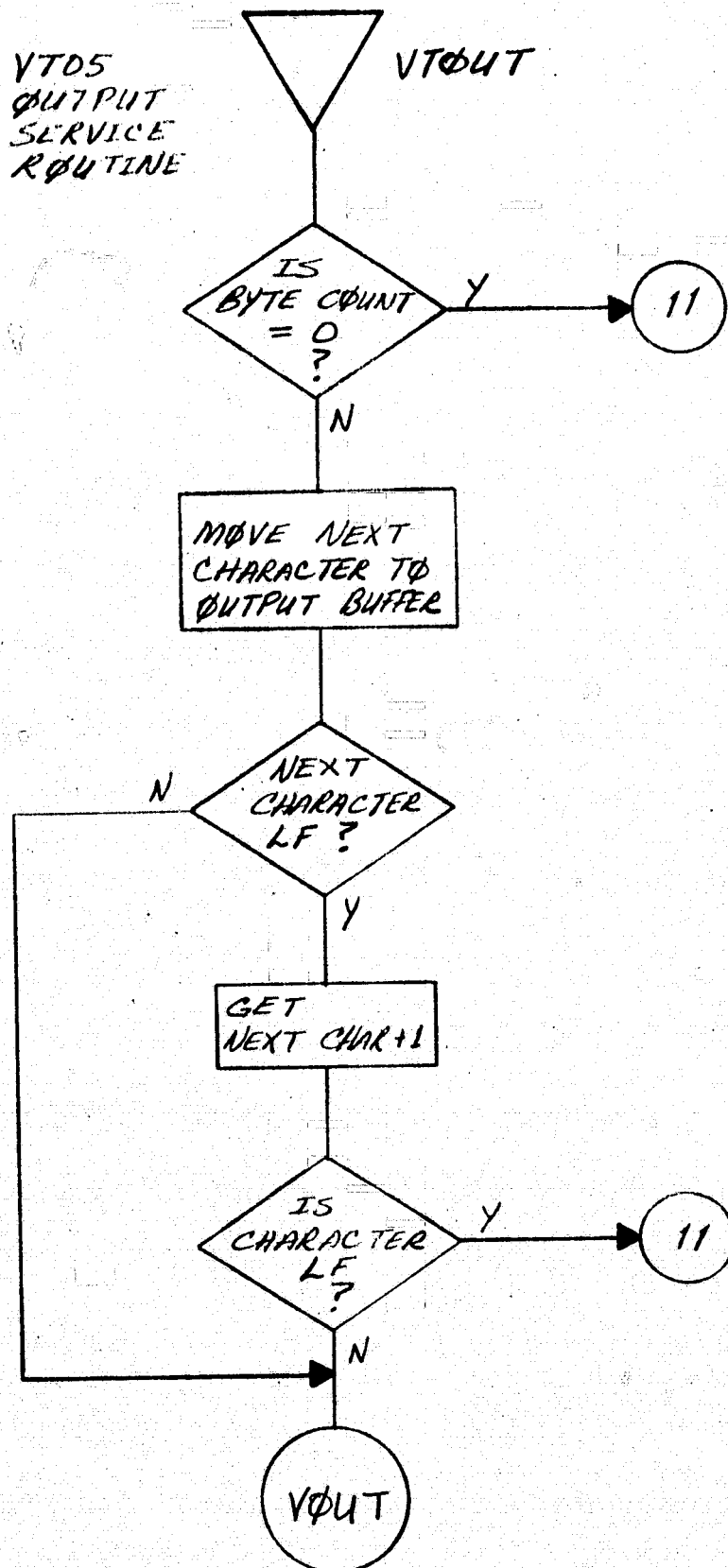


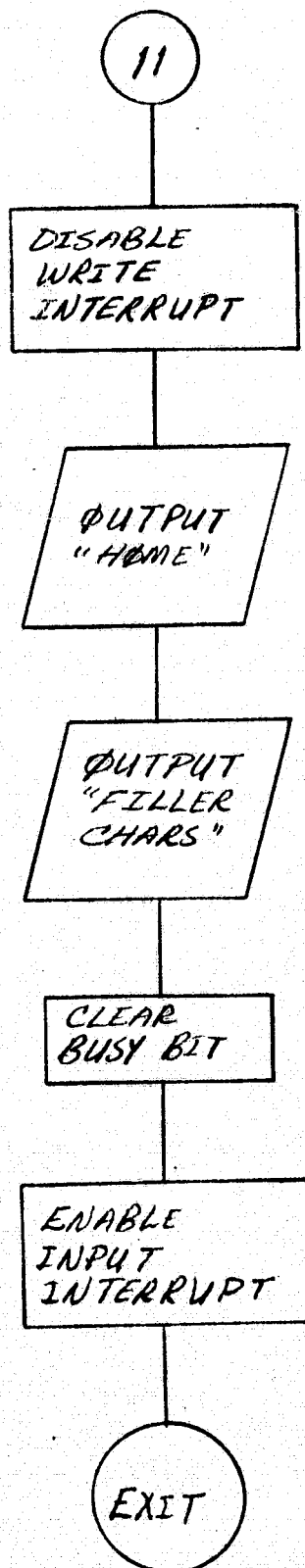
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ORIGINAL PAGE IS POOR

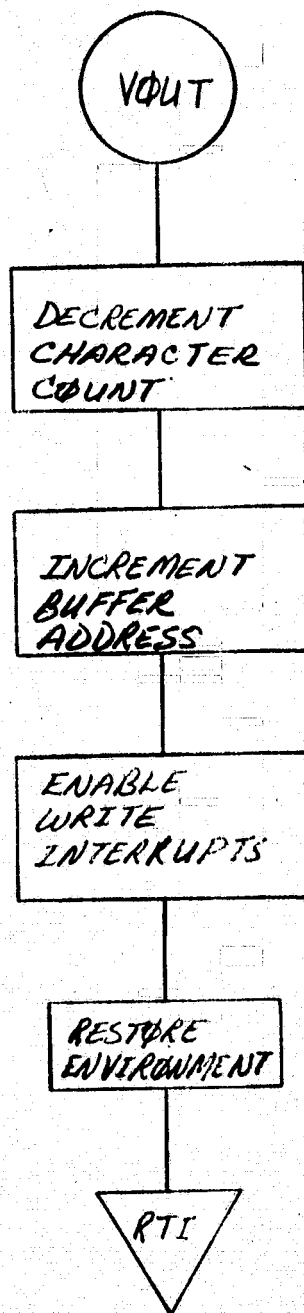


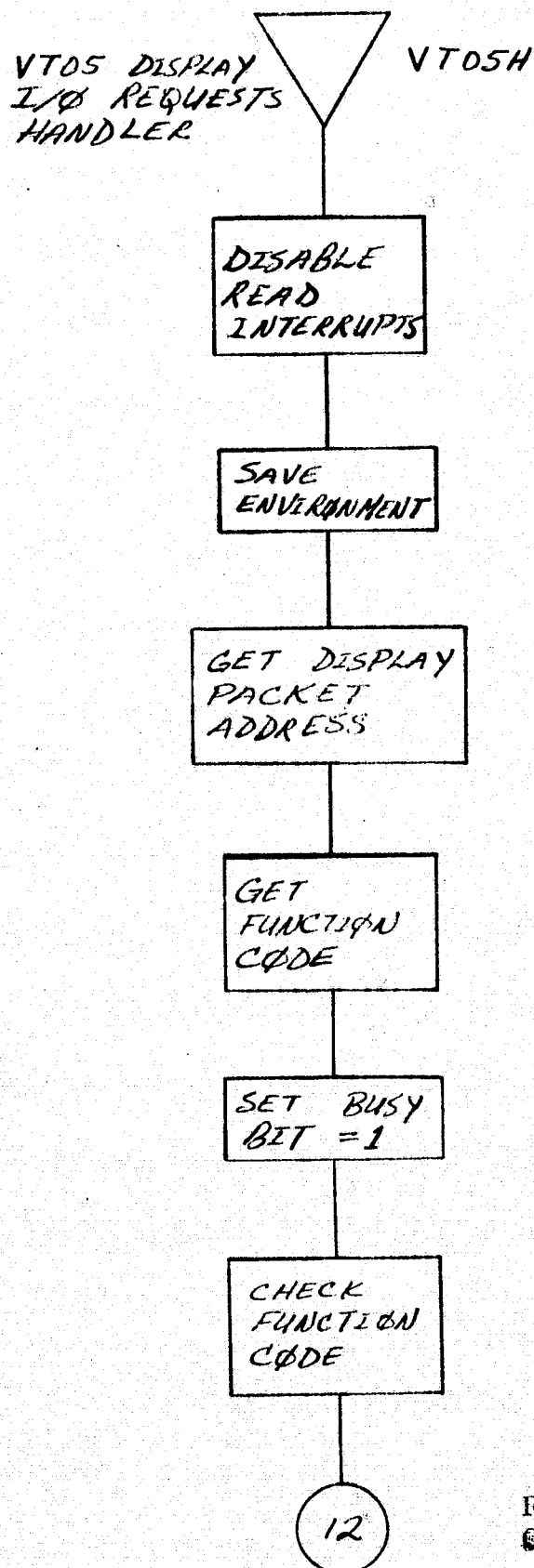




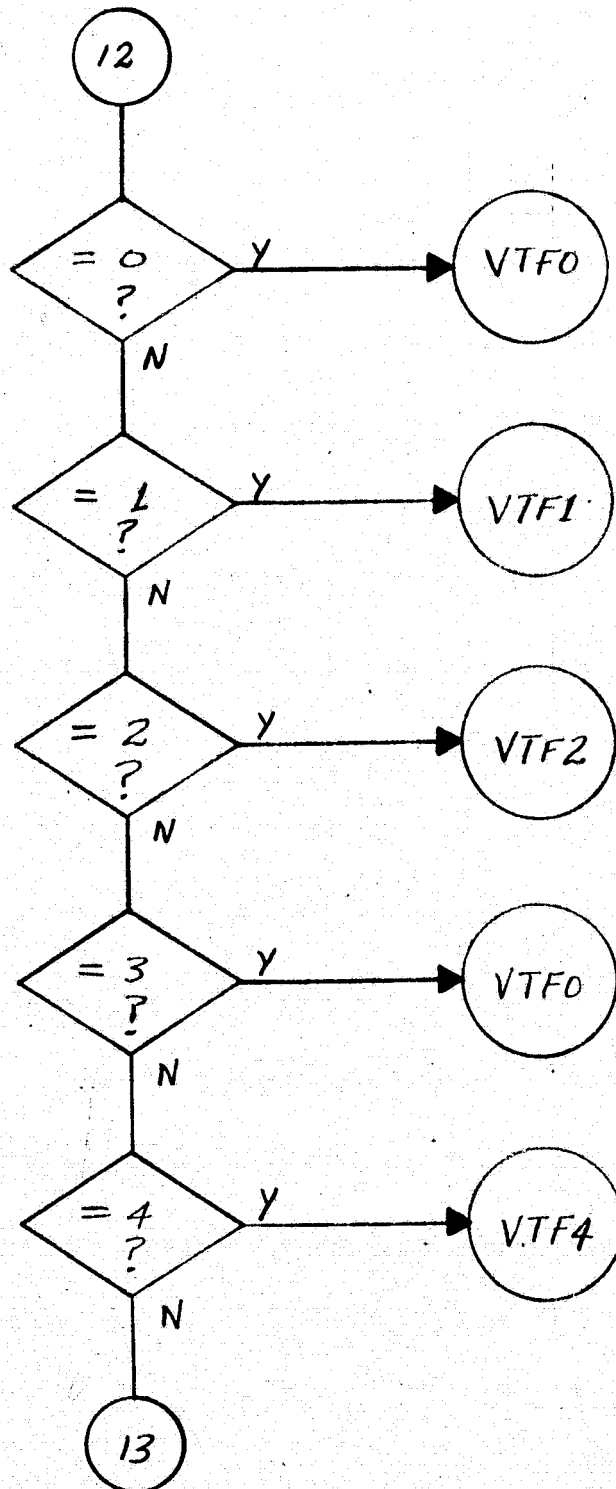


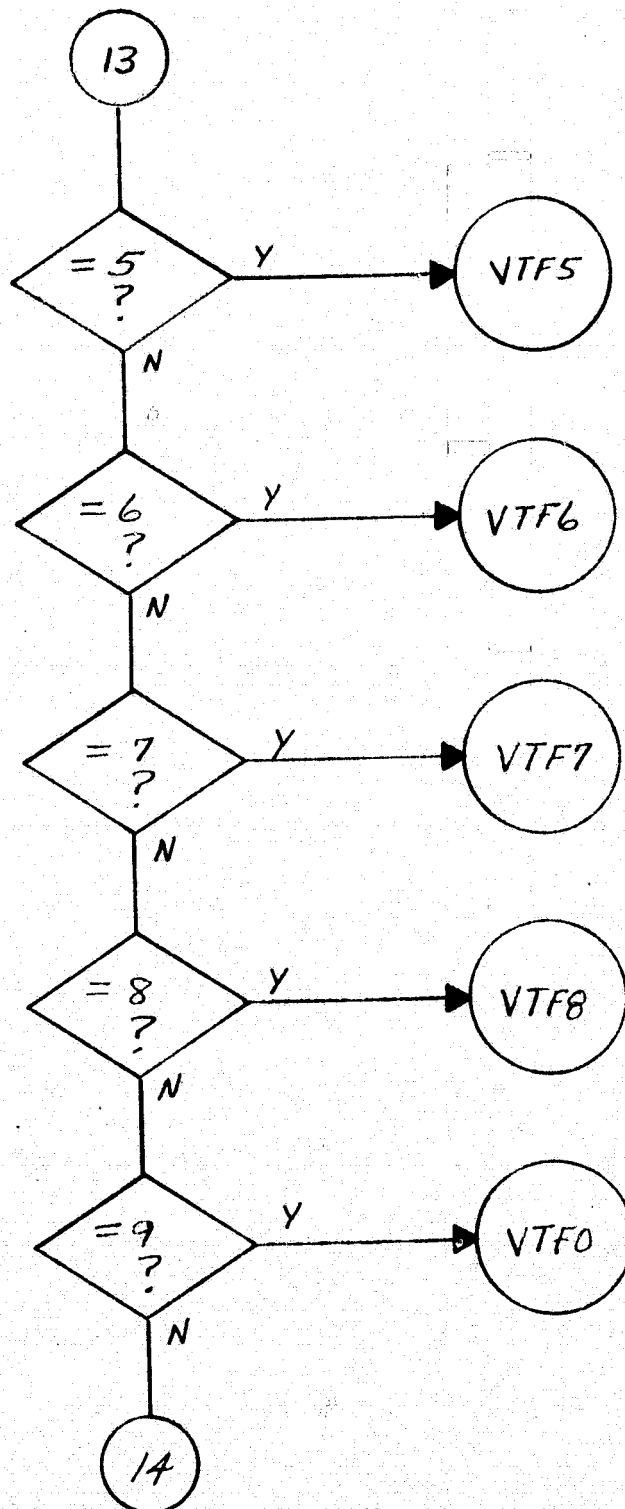


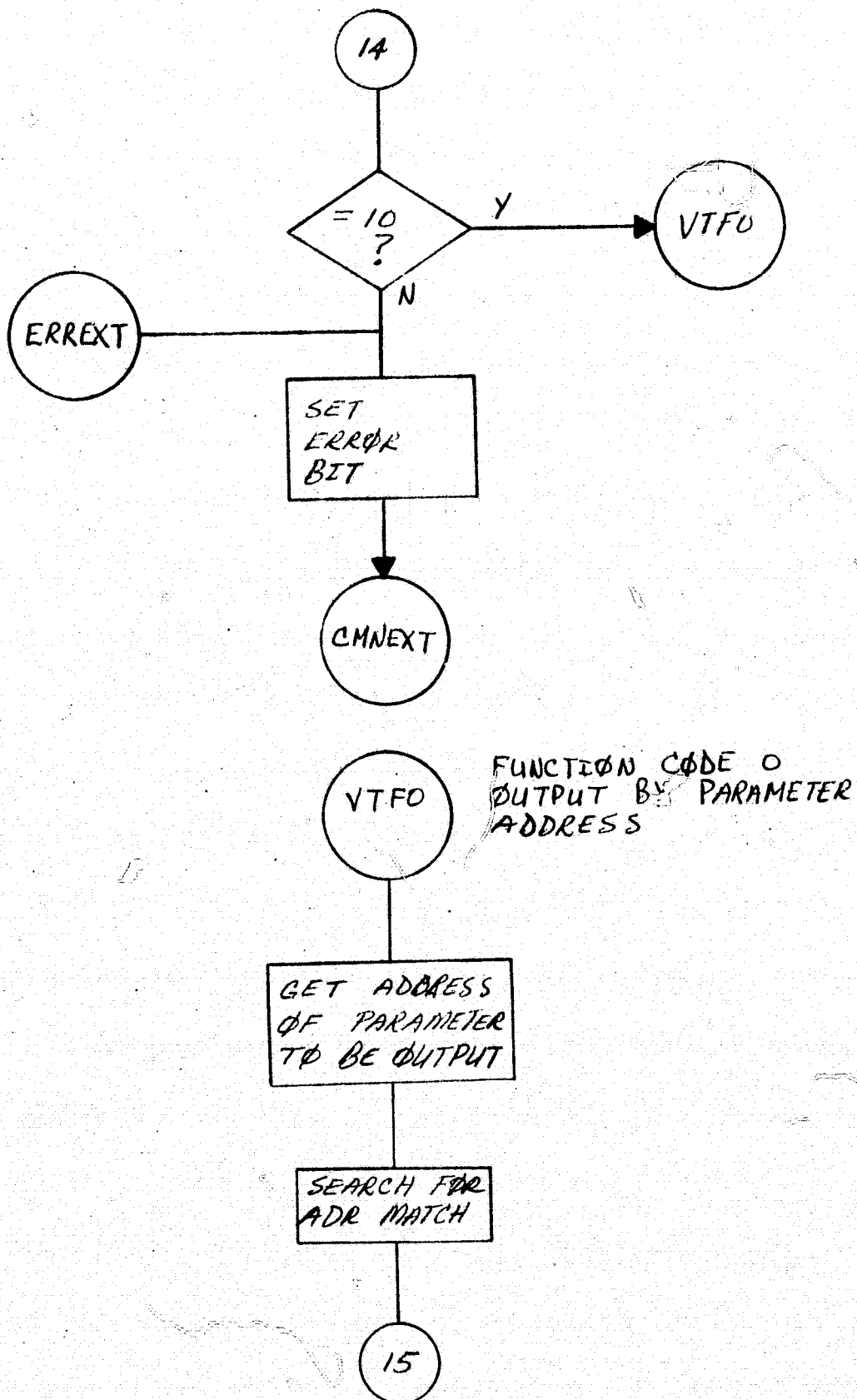




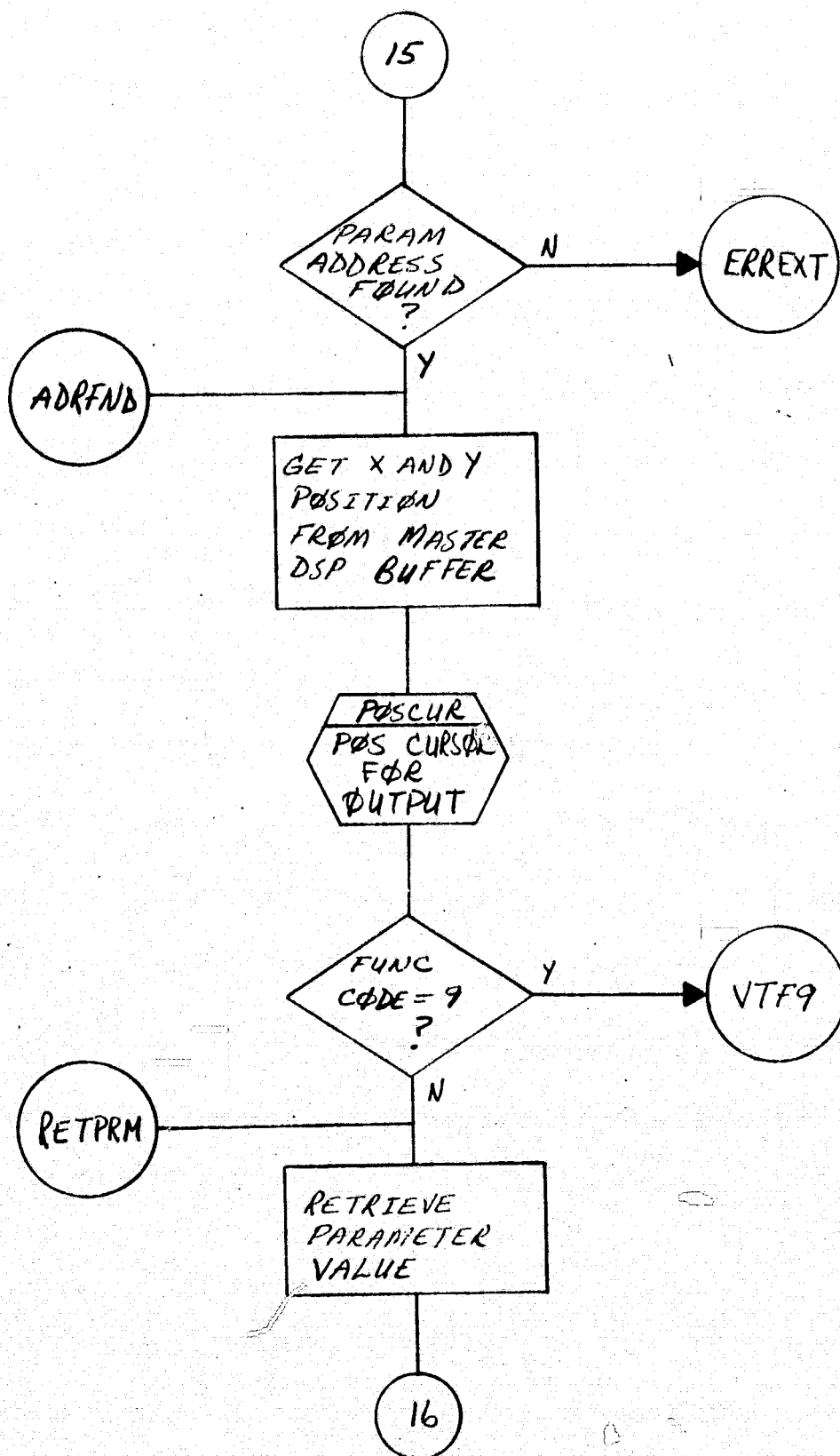
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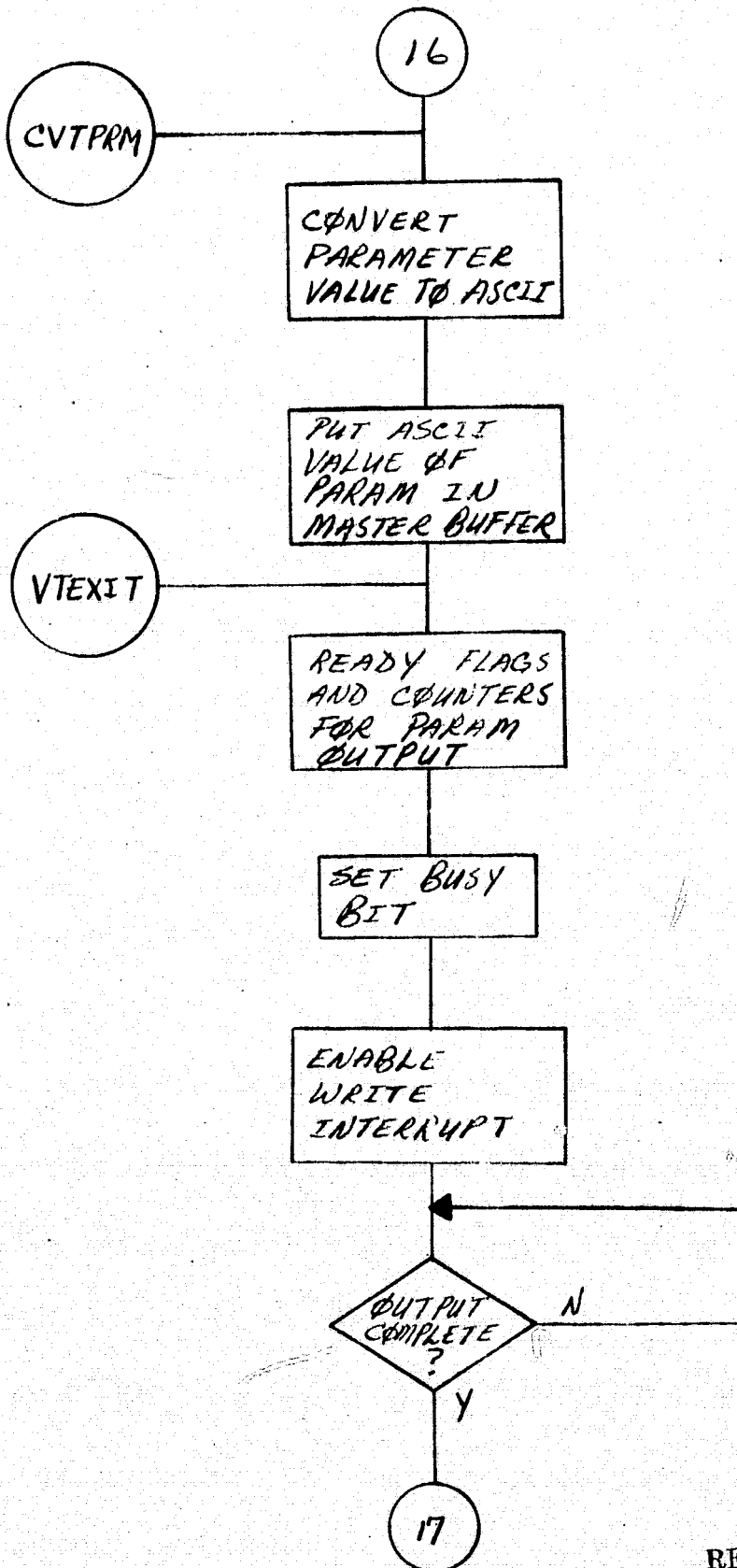


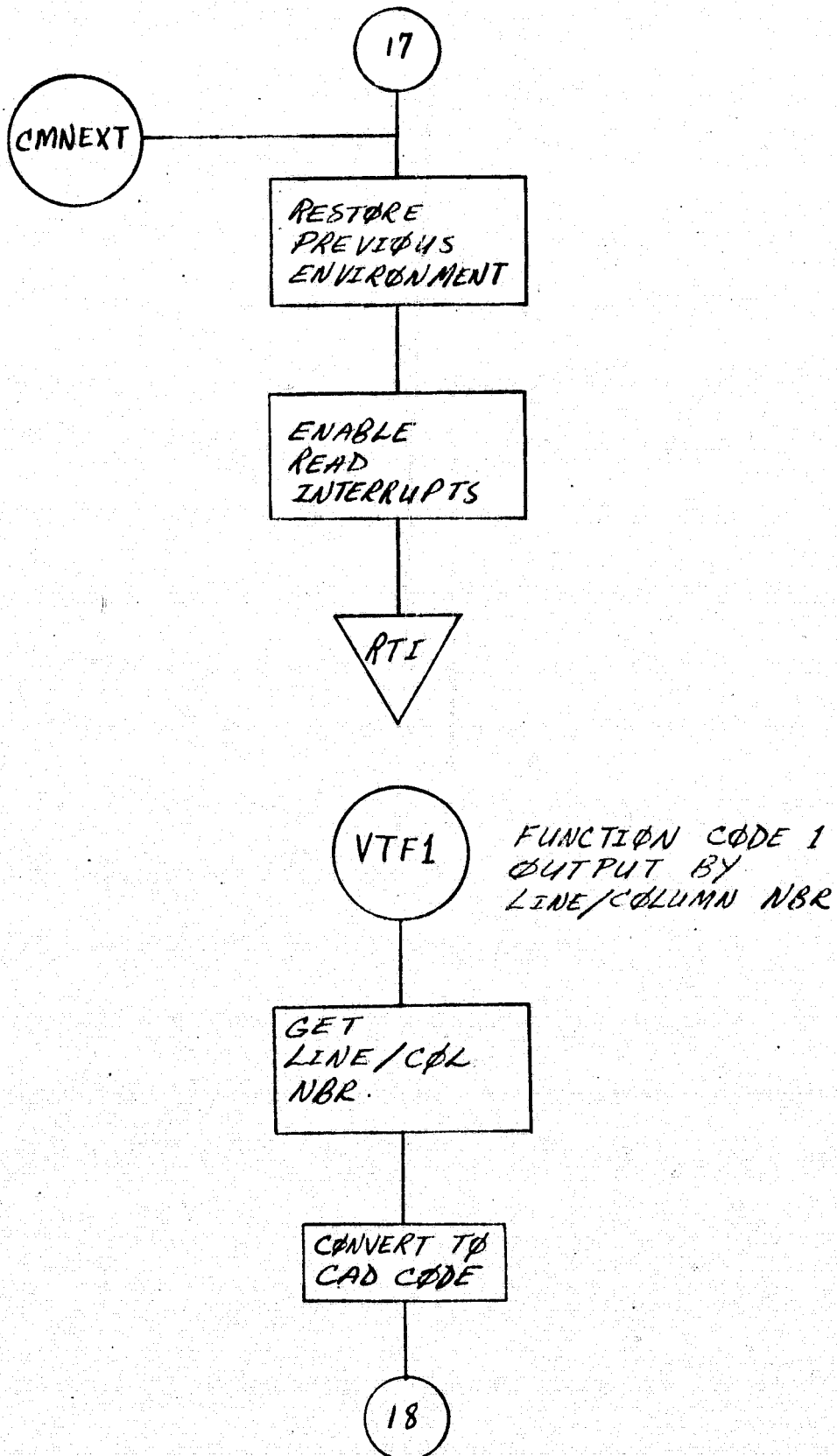


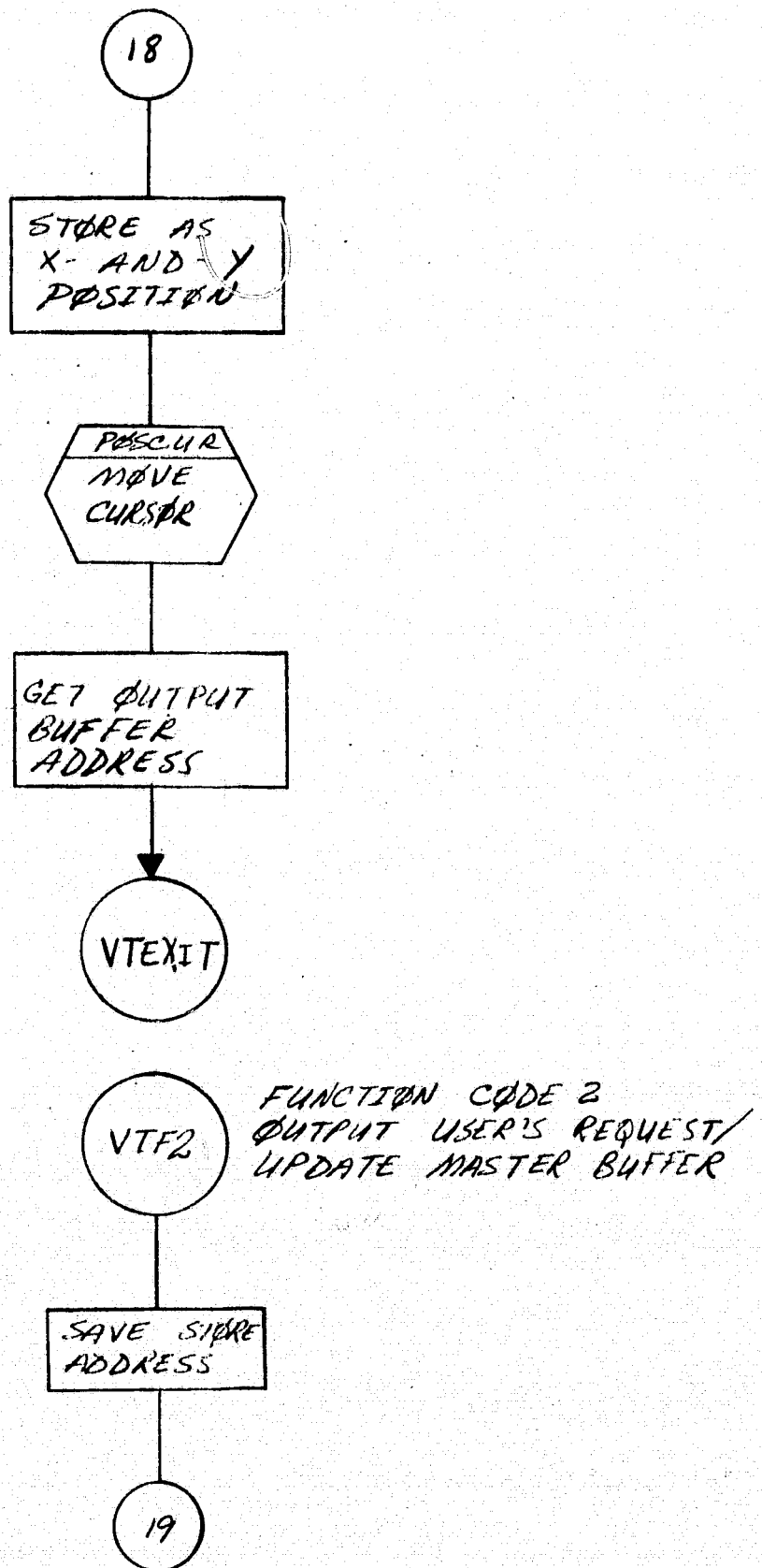


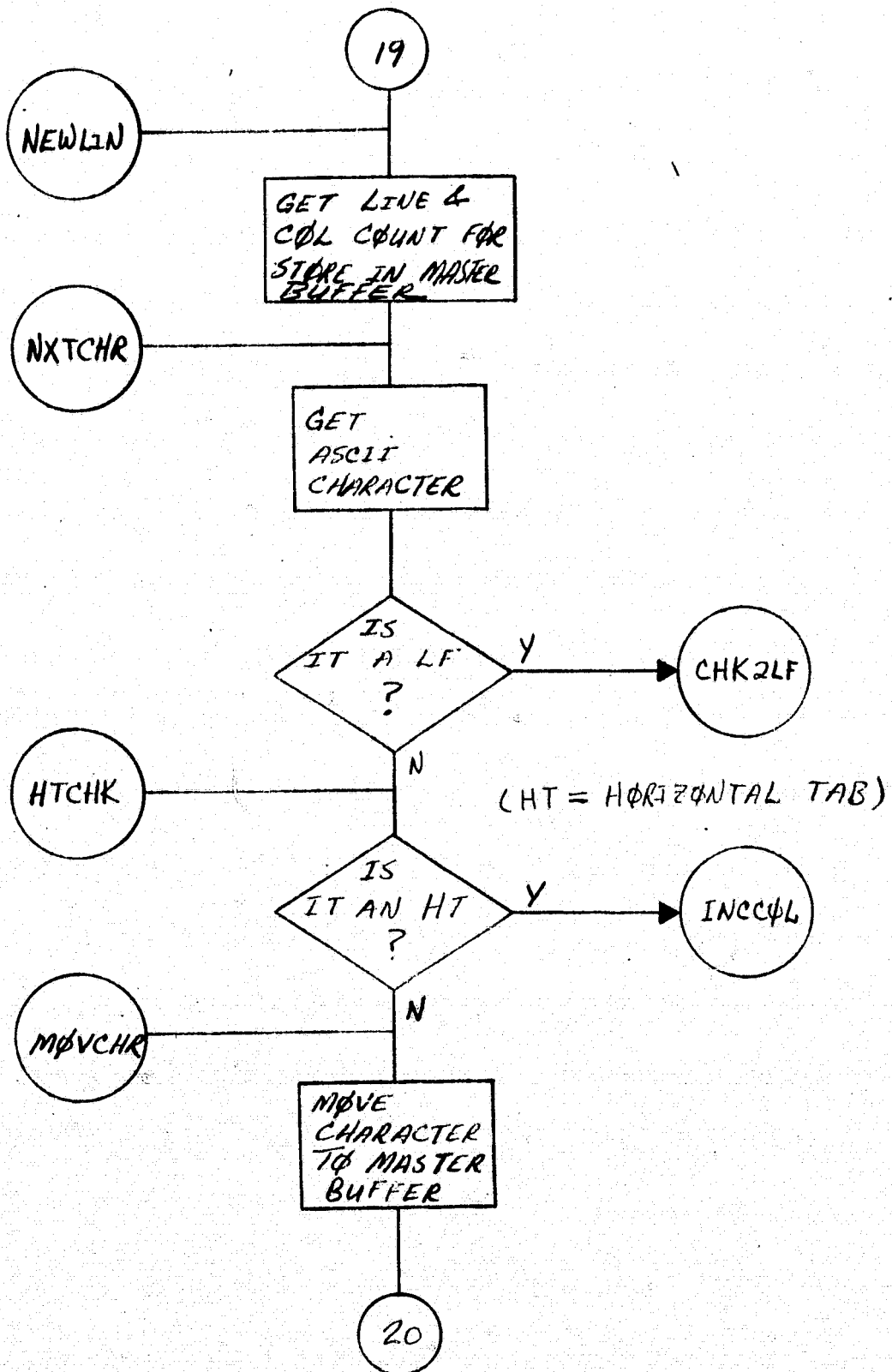


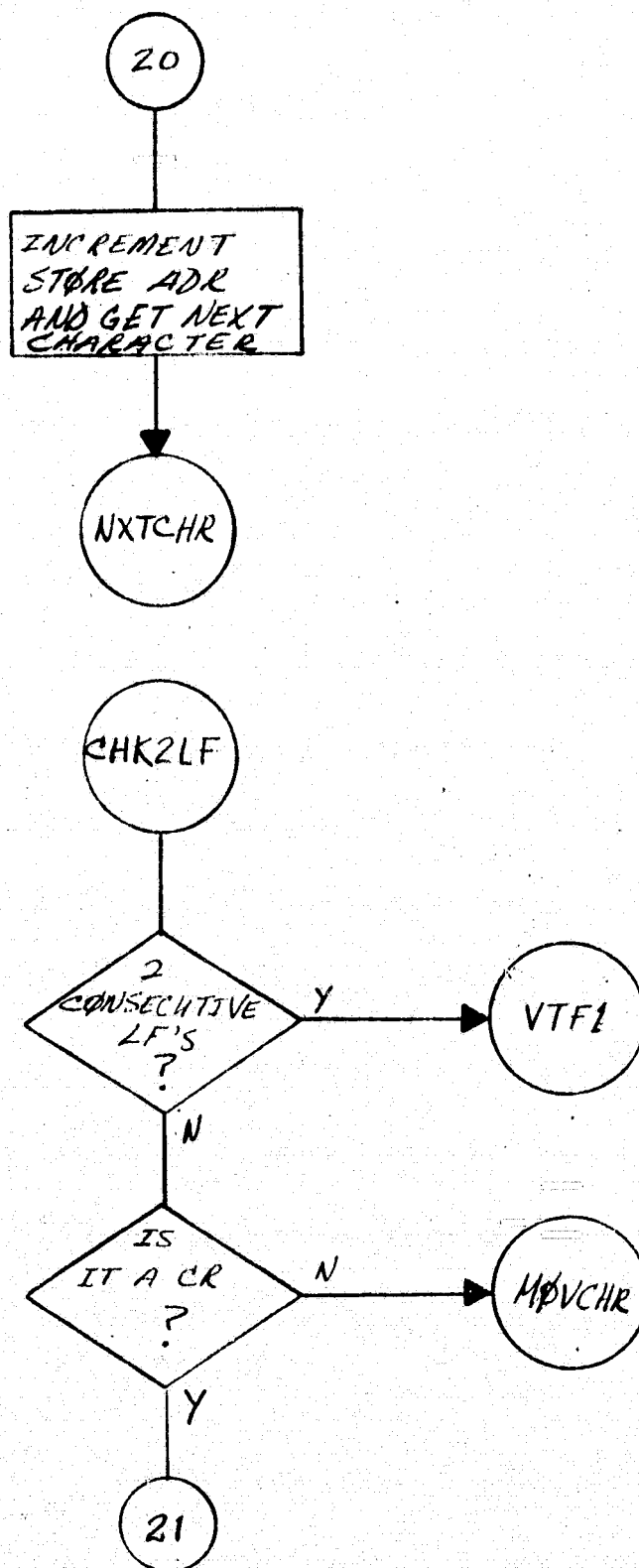




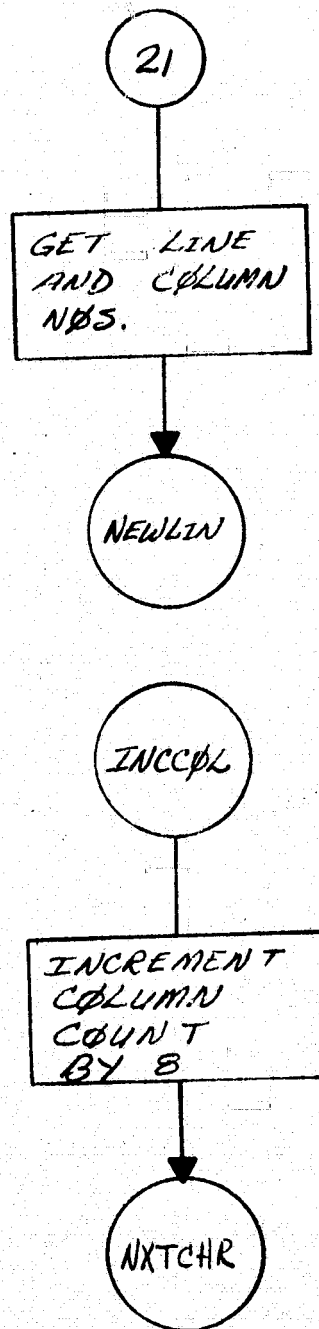


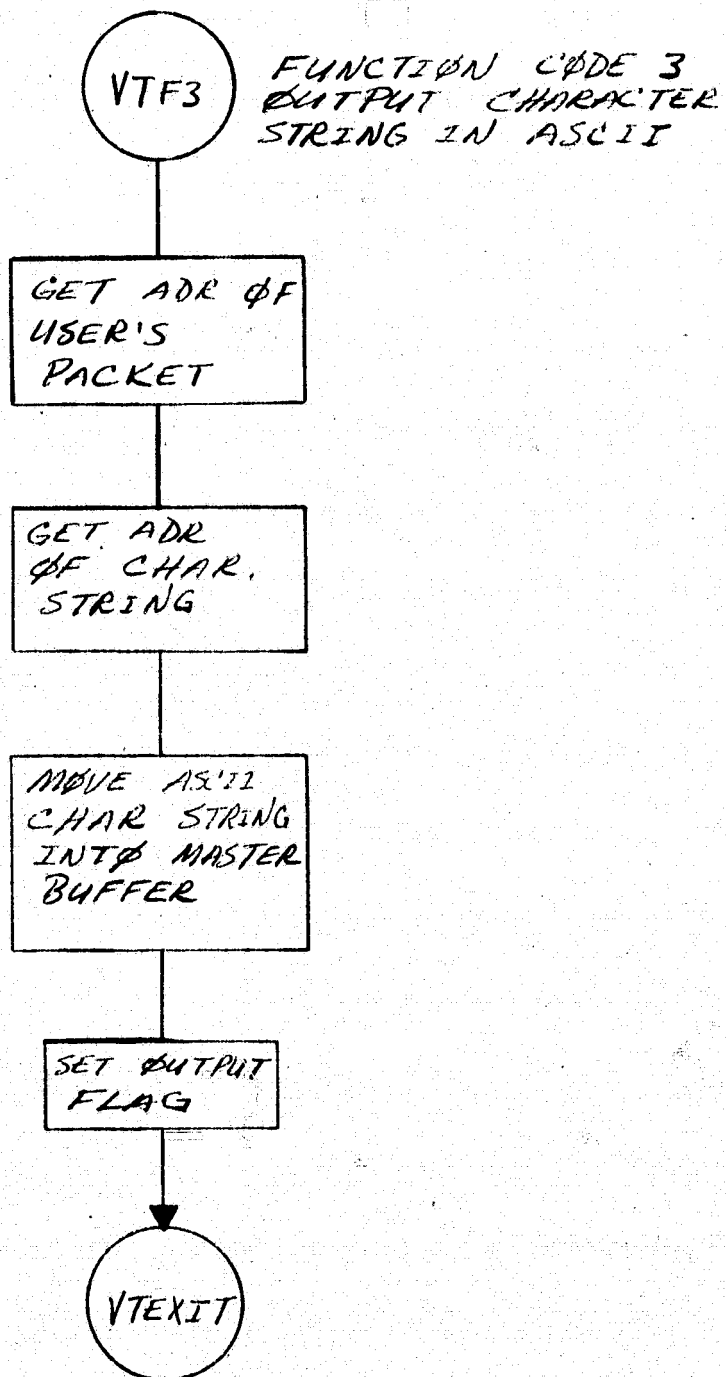




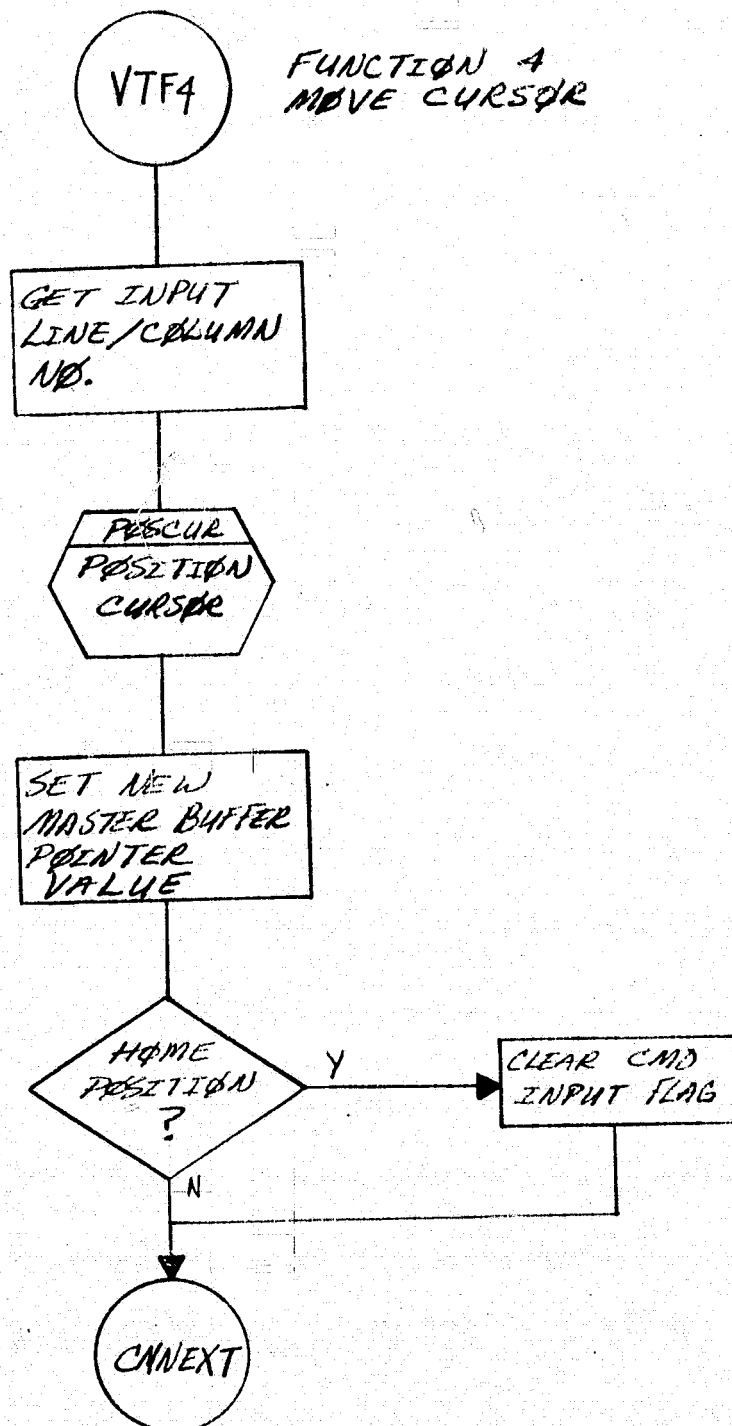


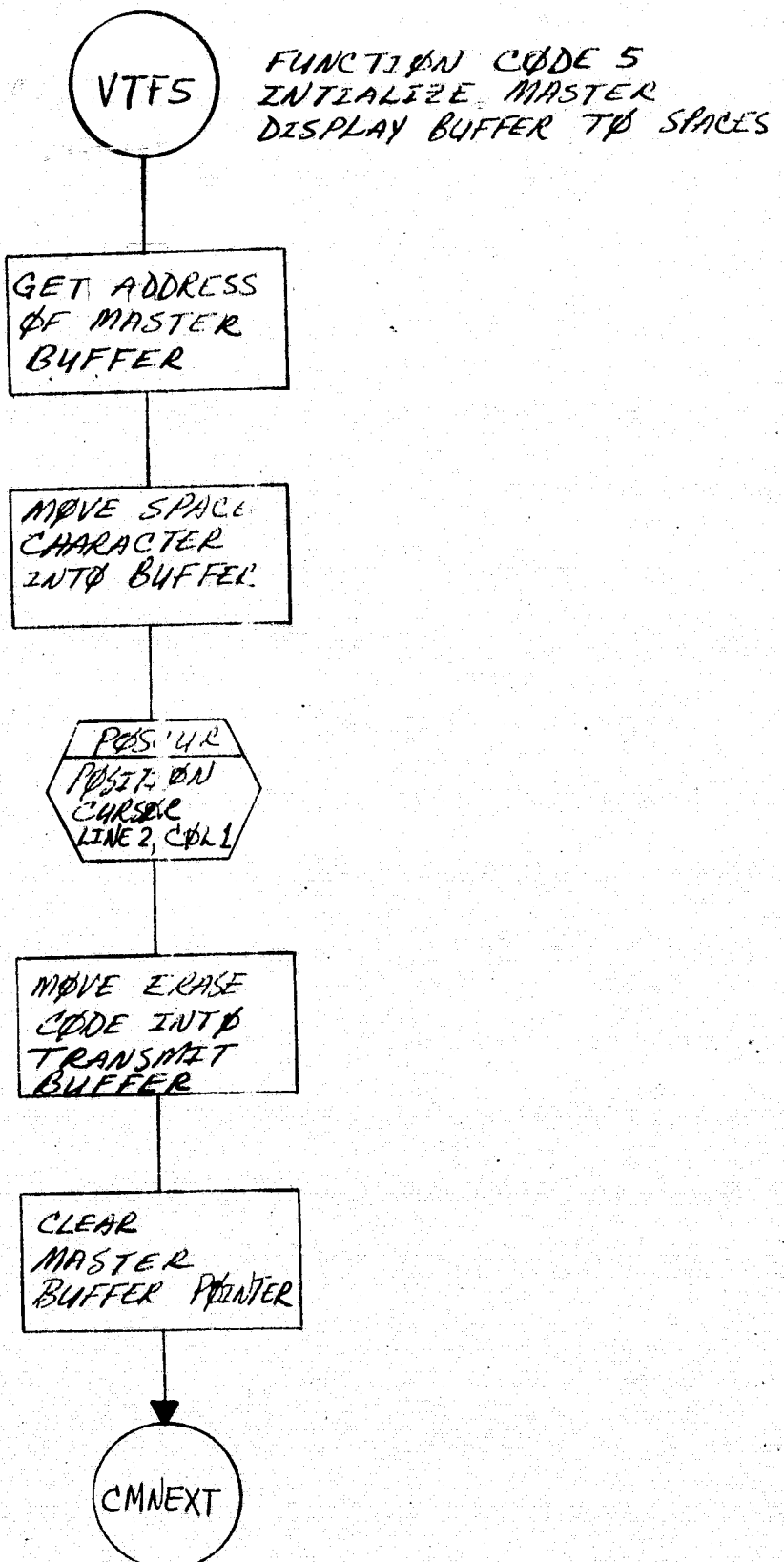
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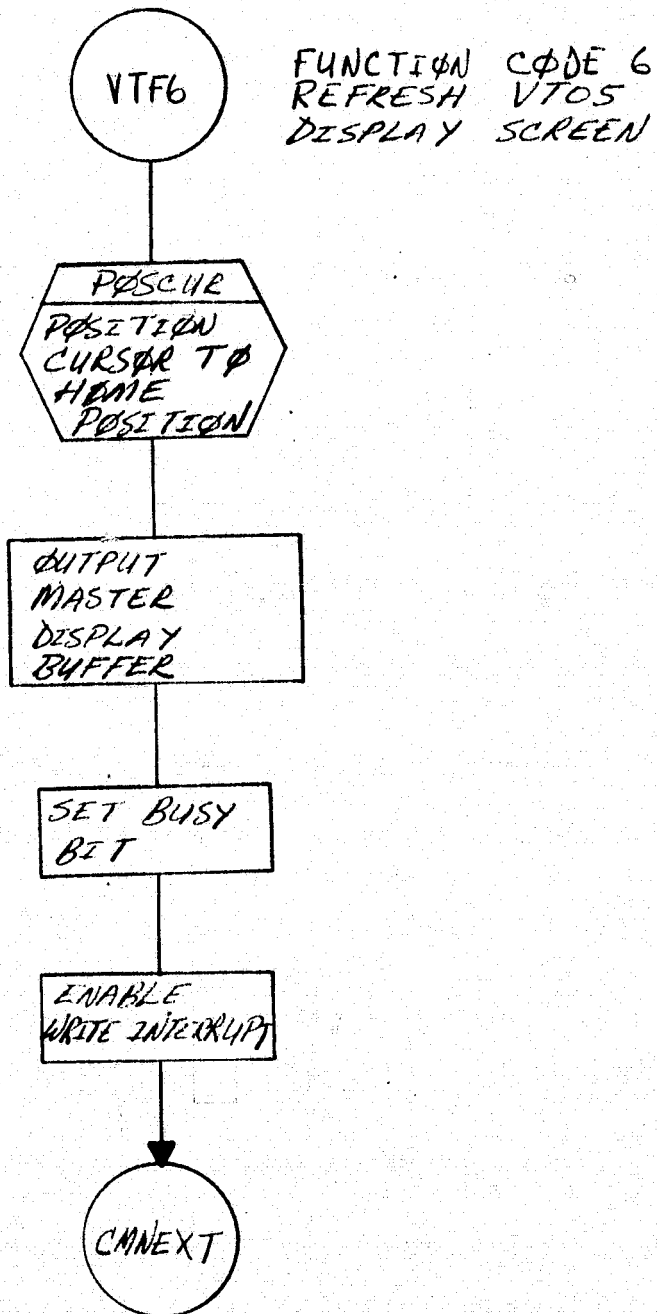


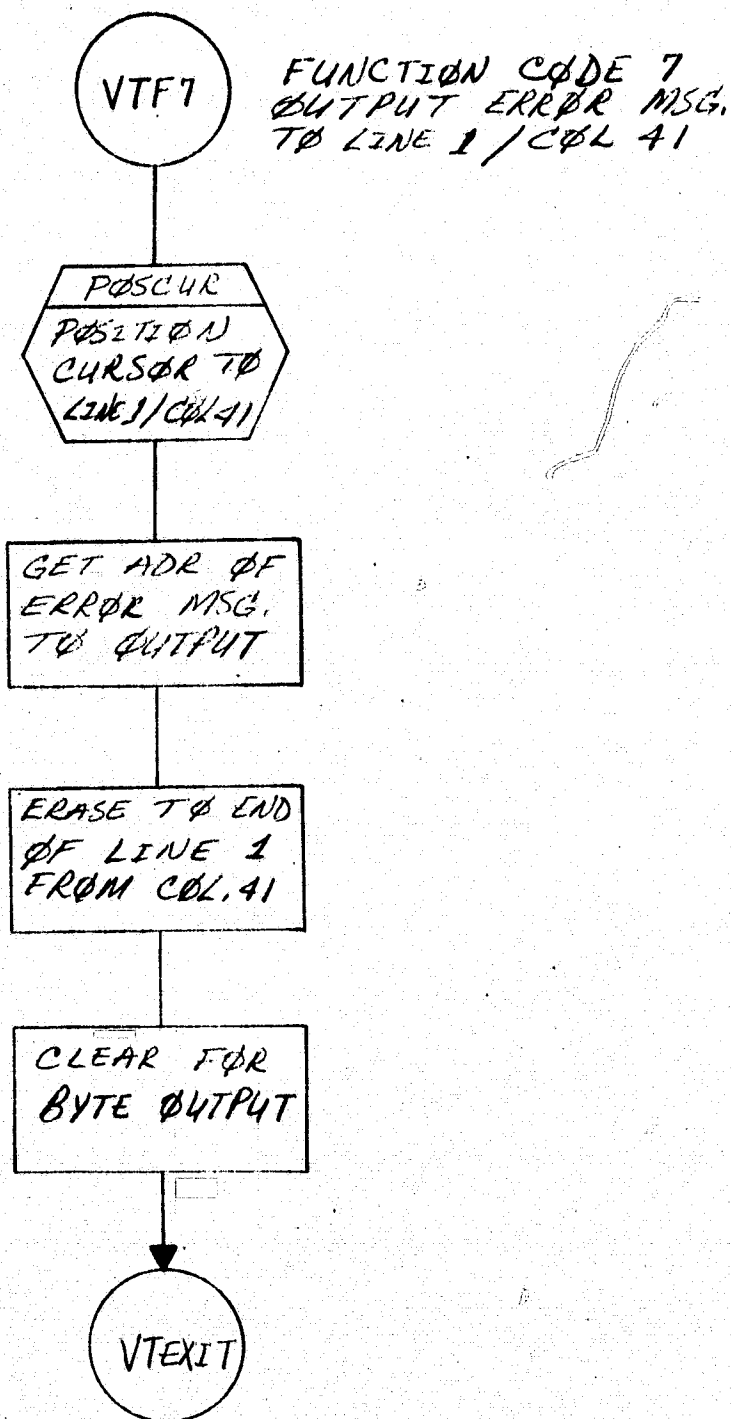


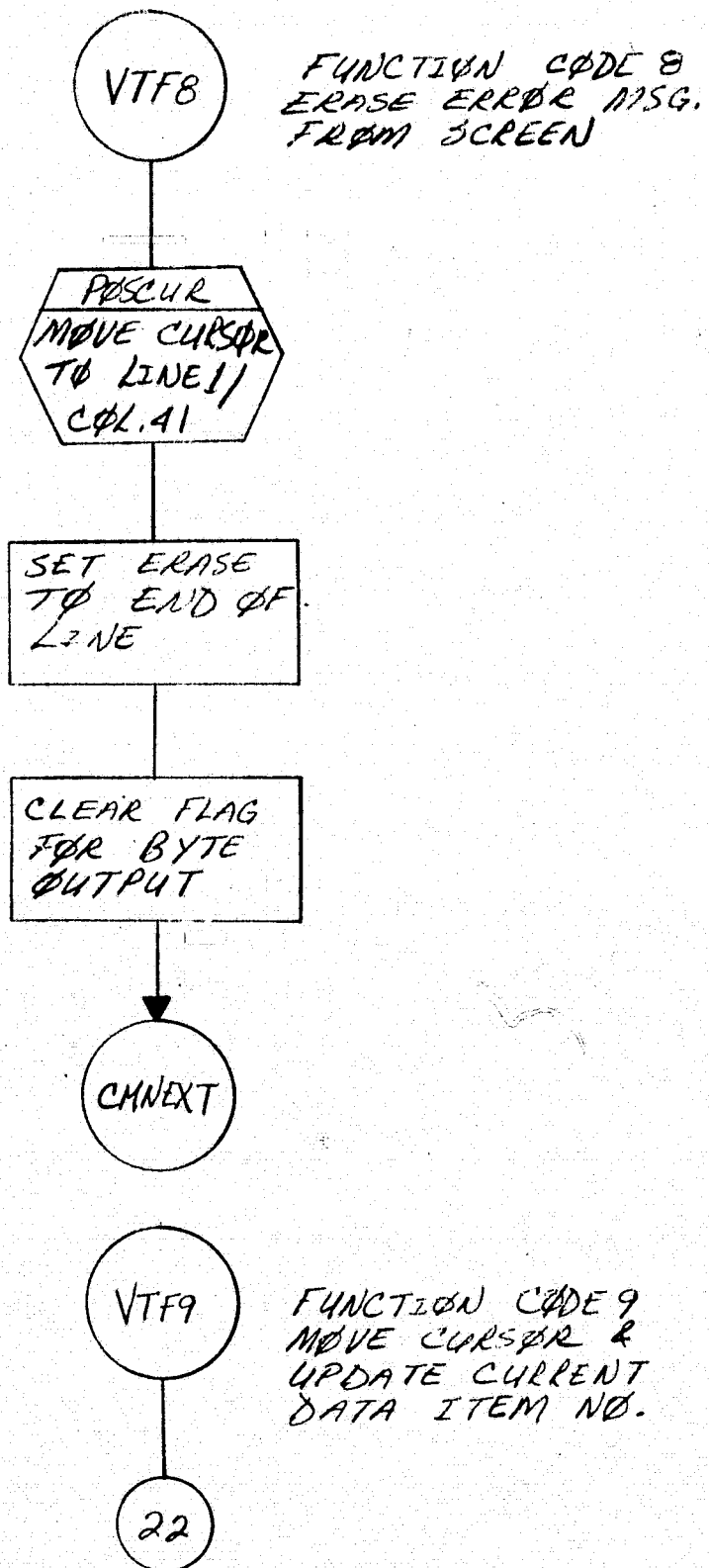


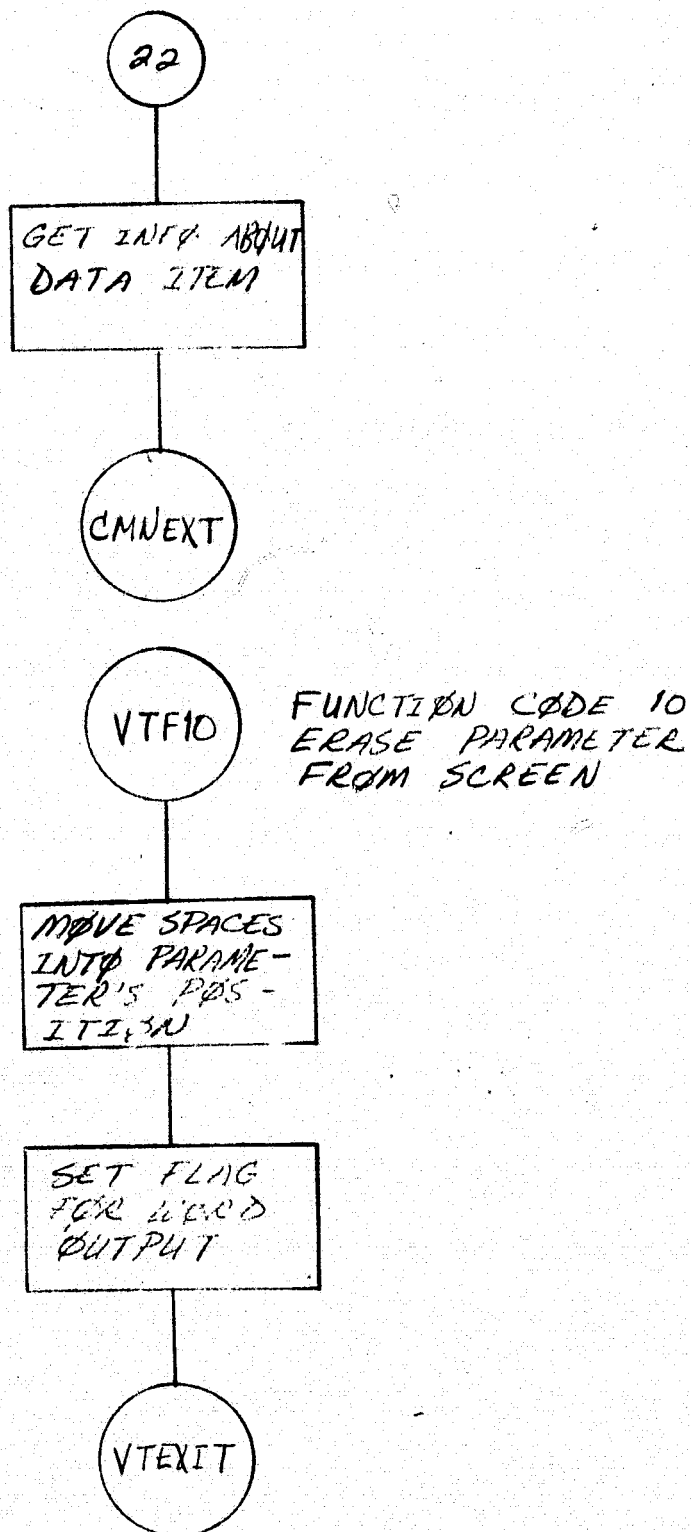


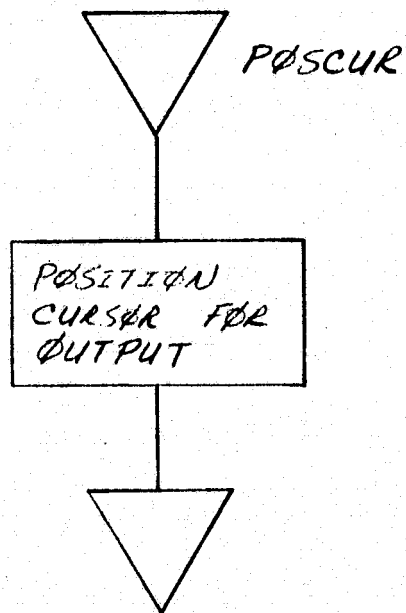




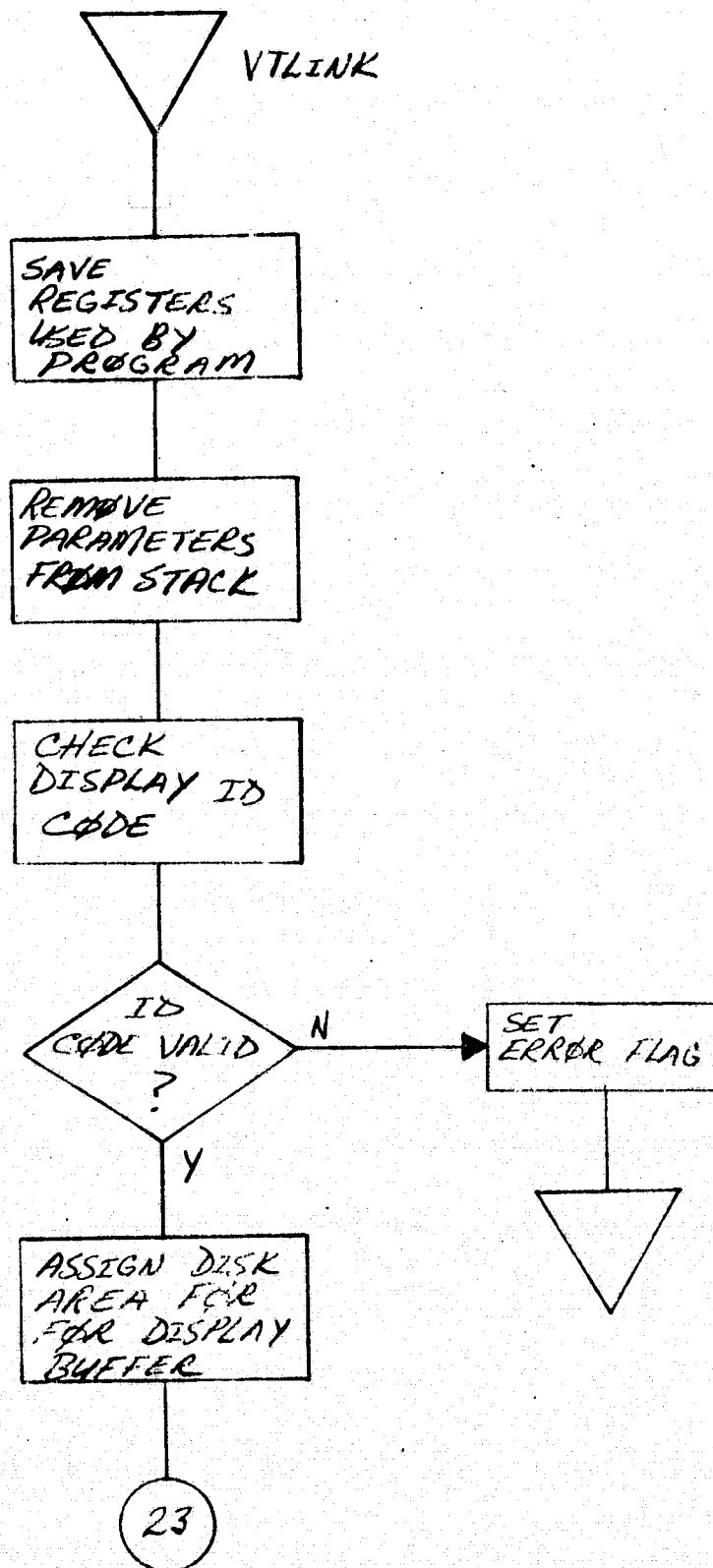




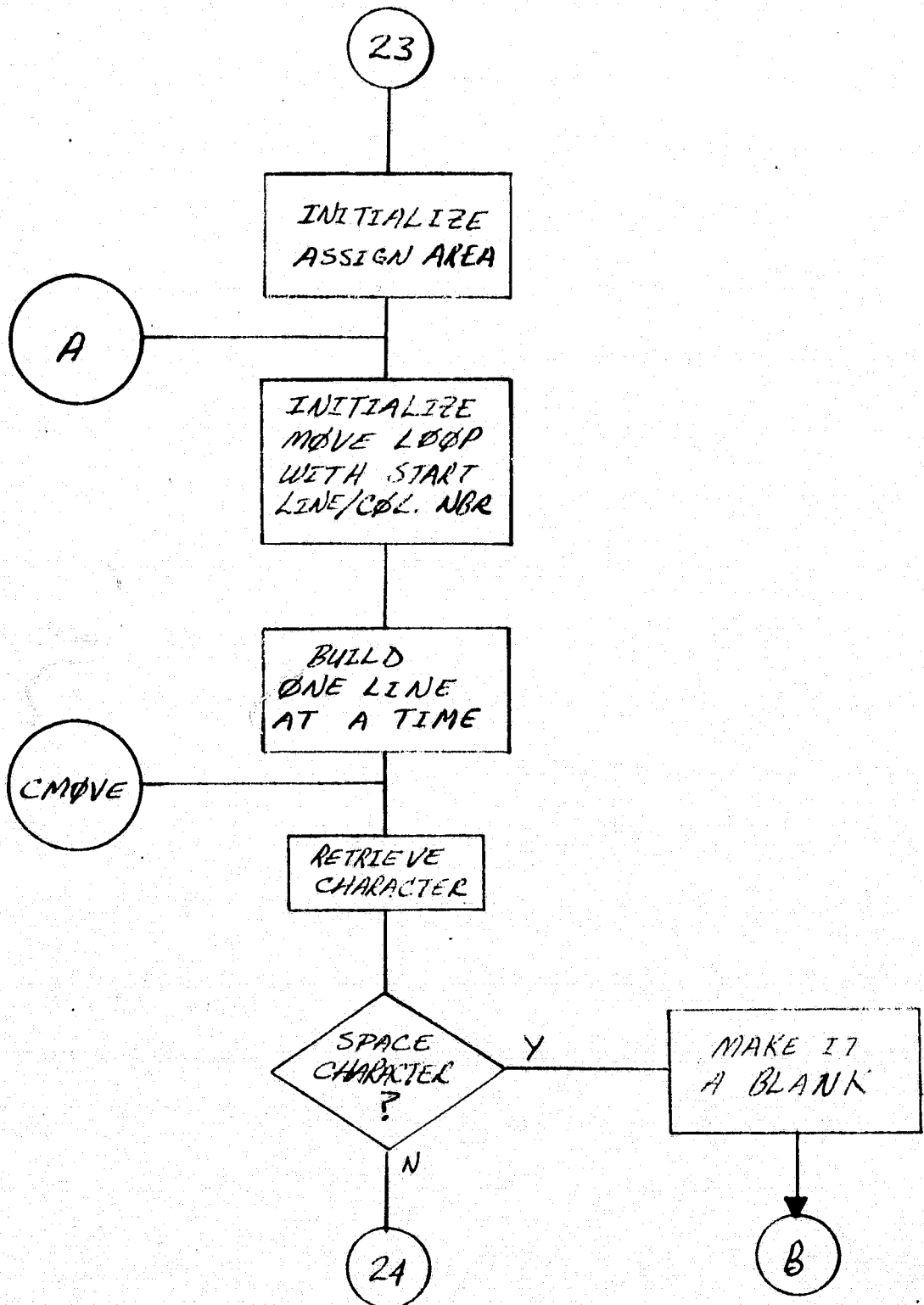


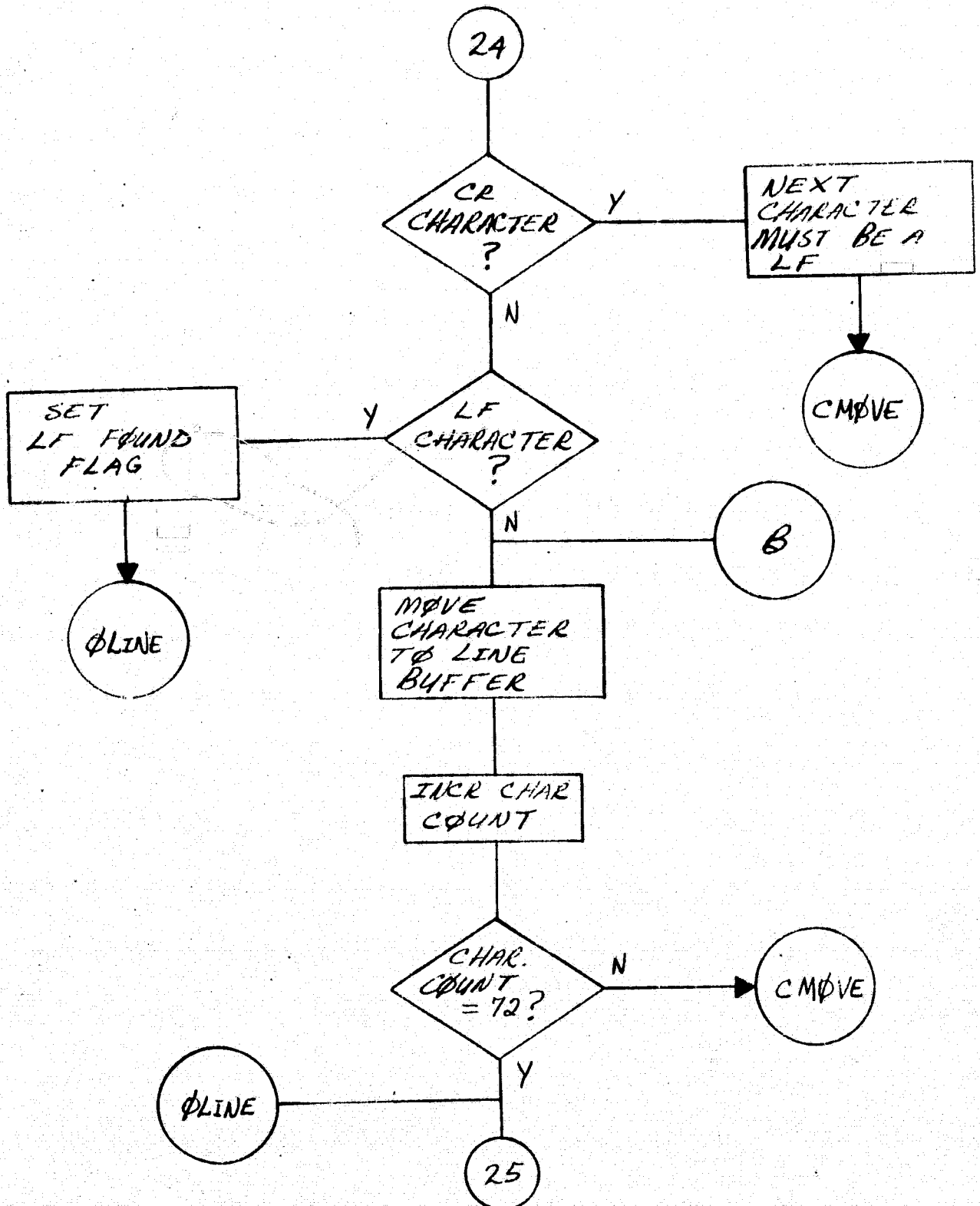


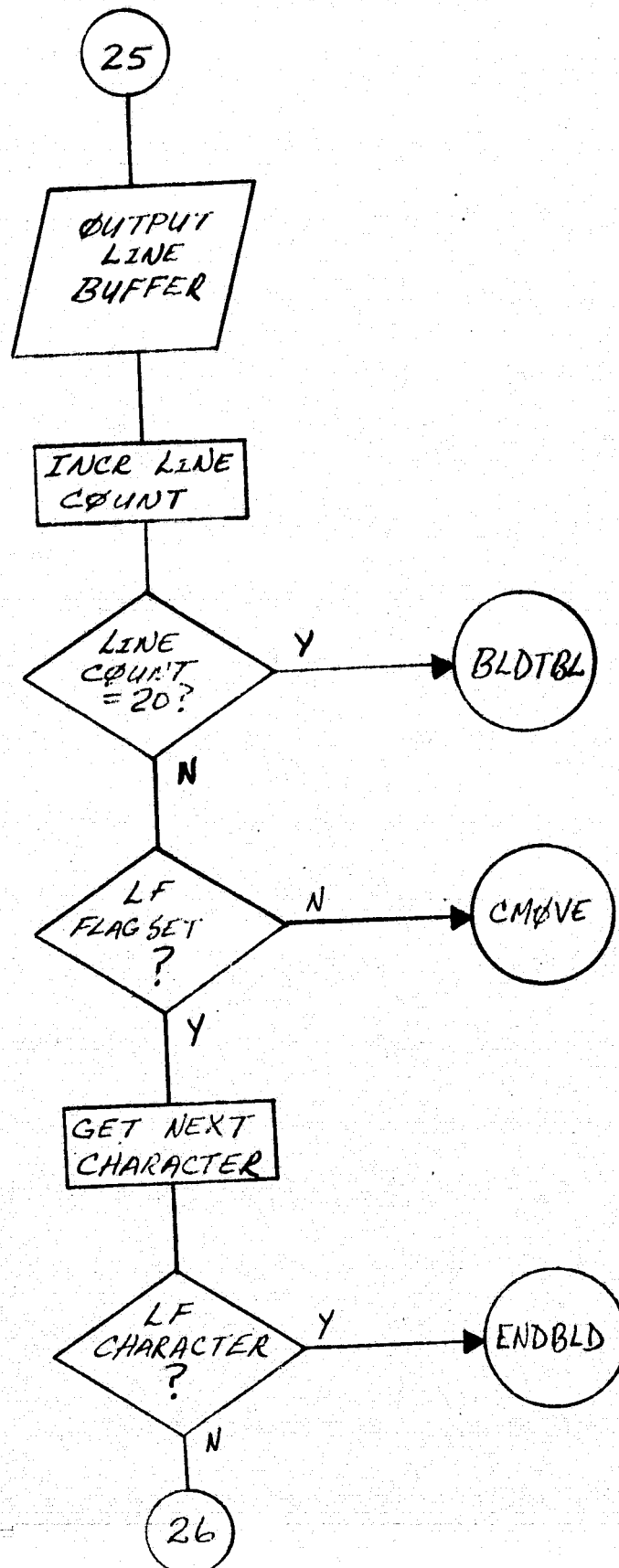
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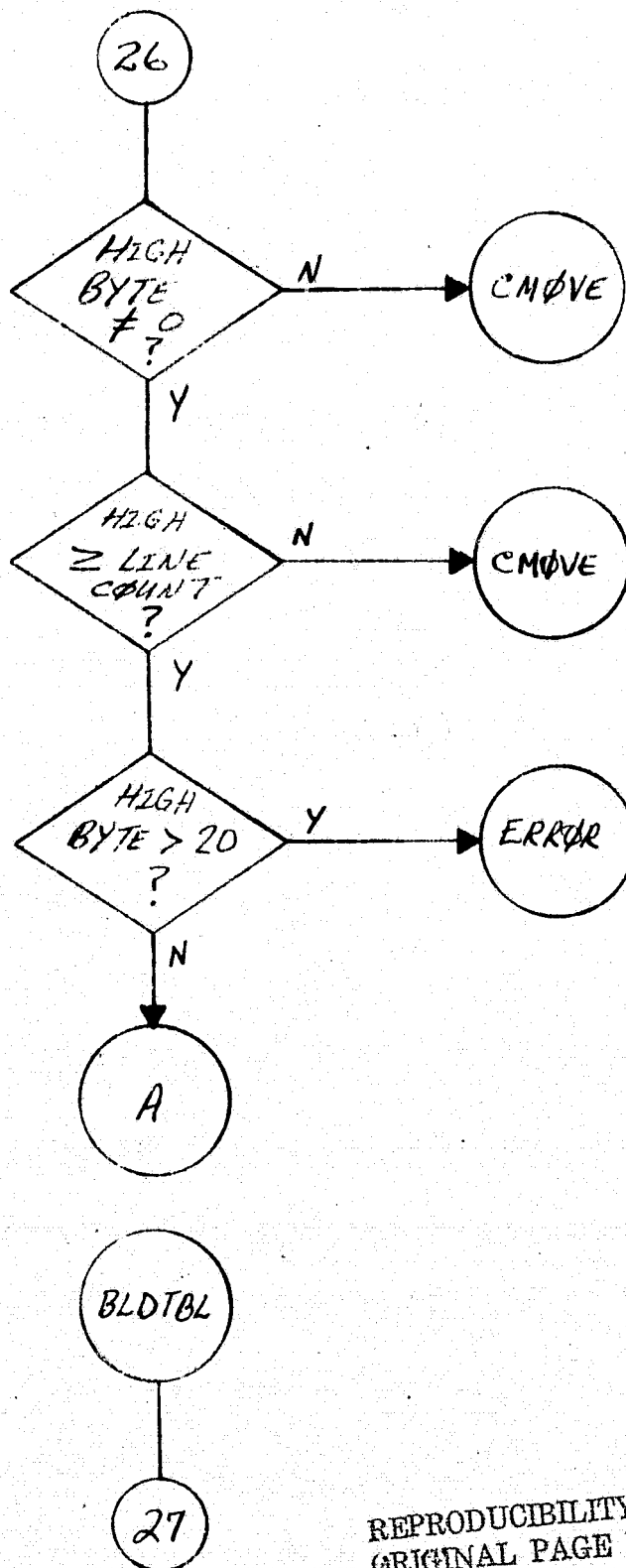




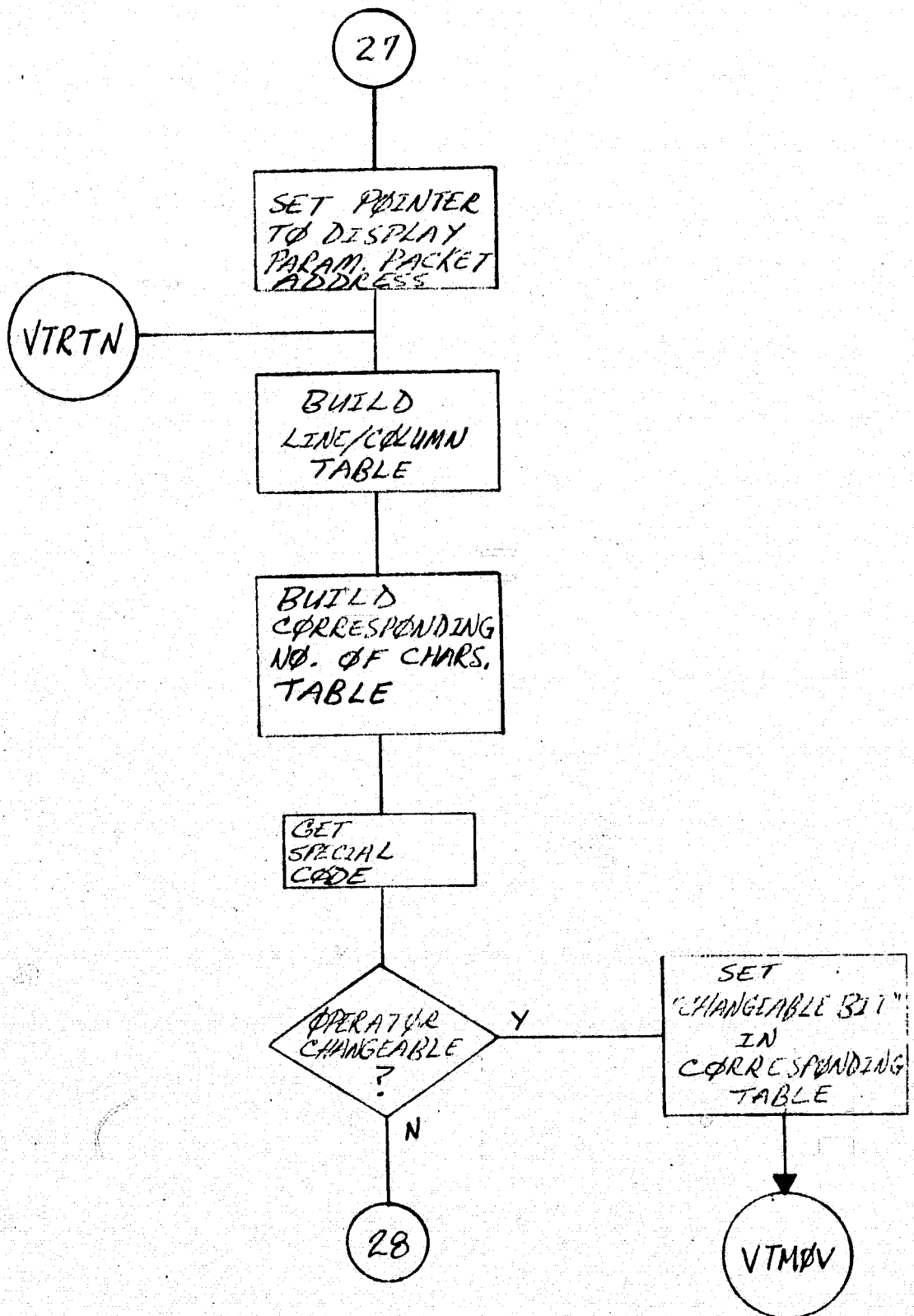


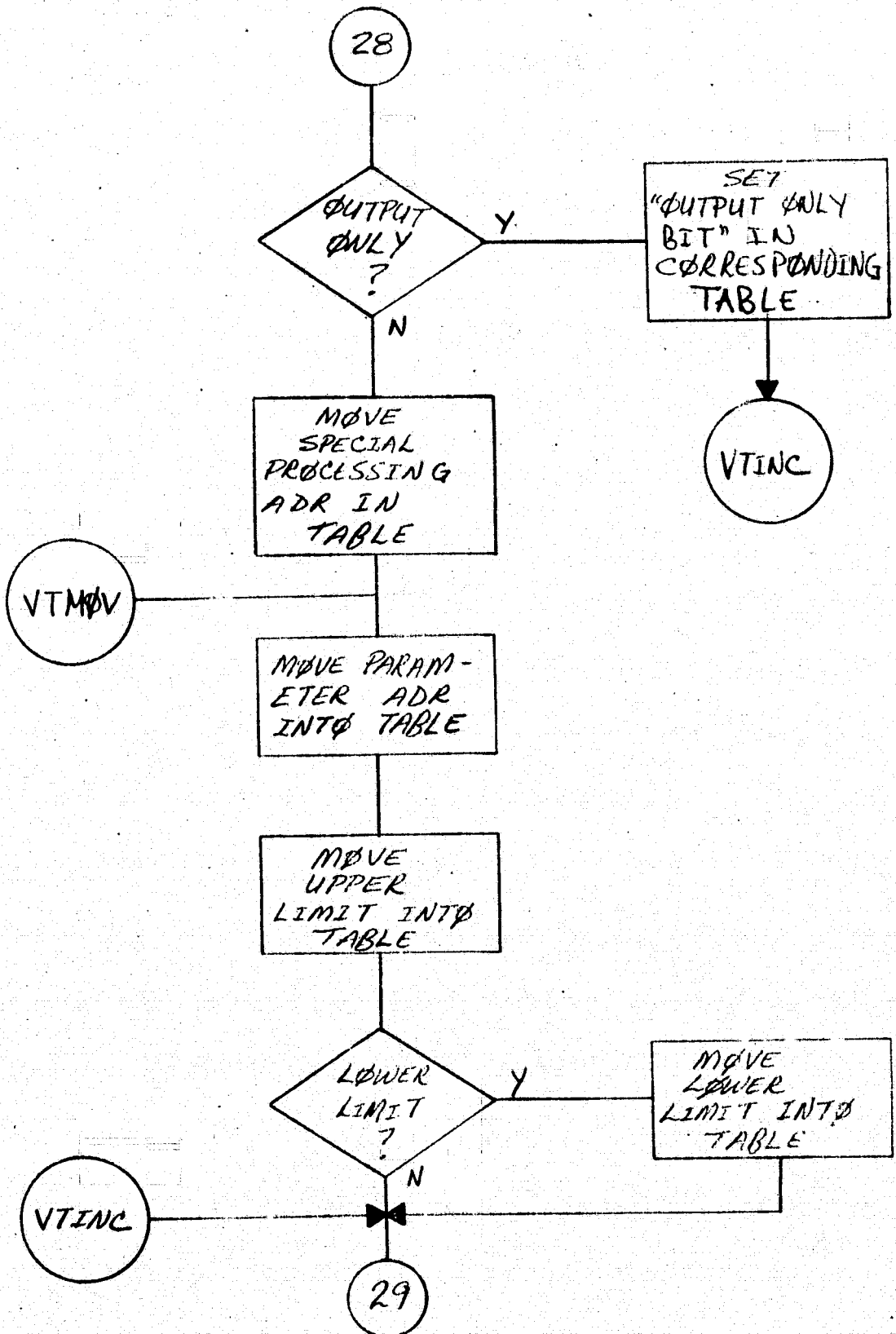


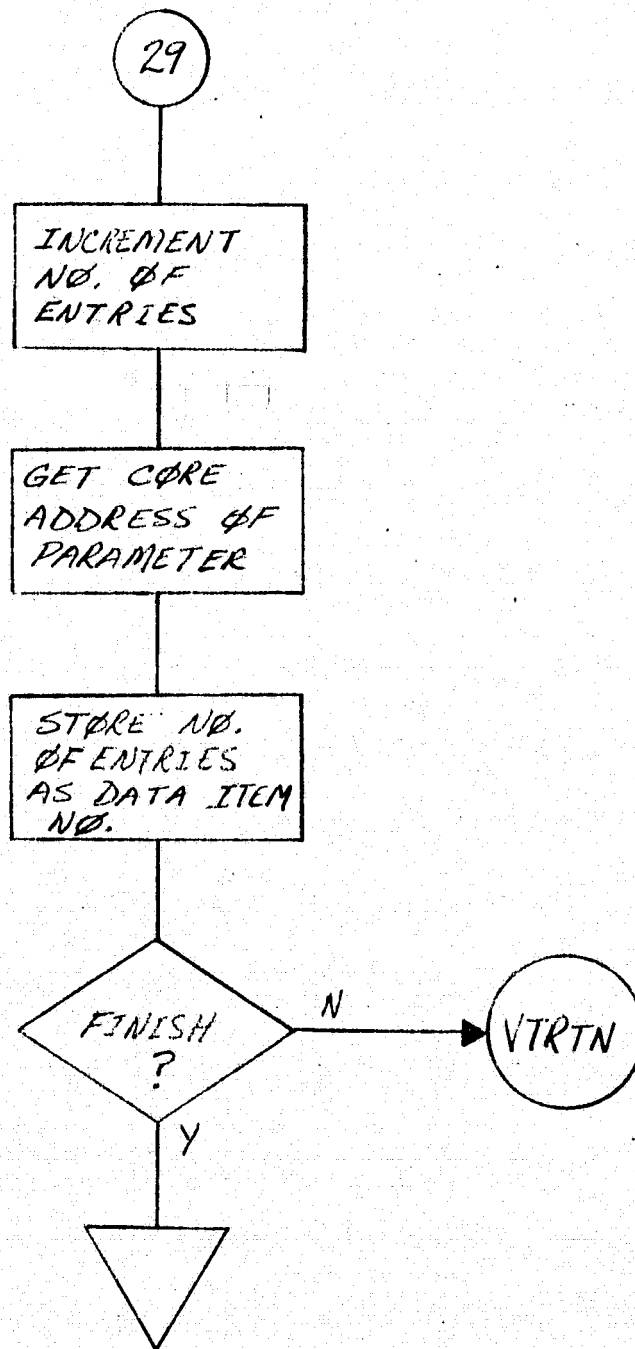


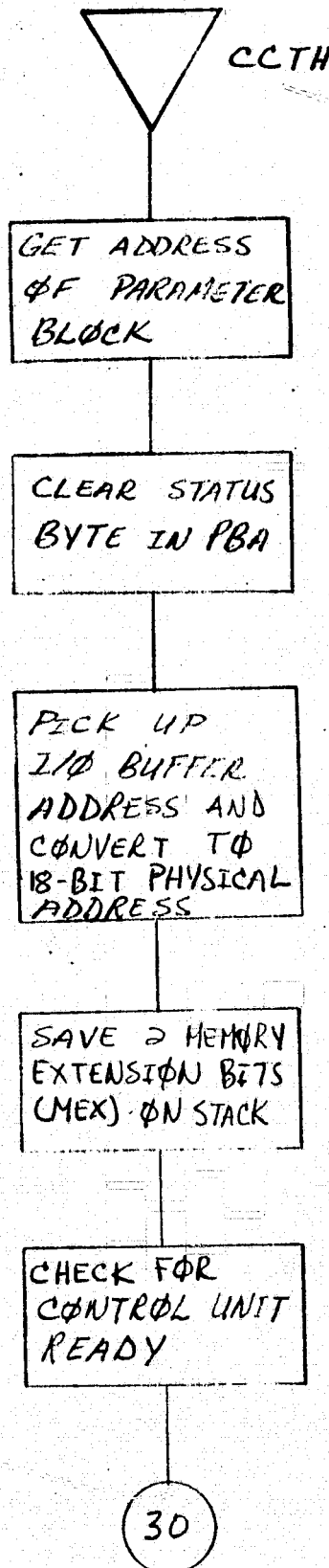


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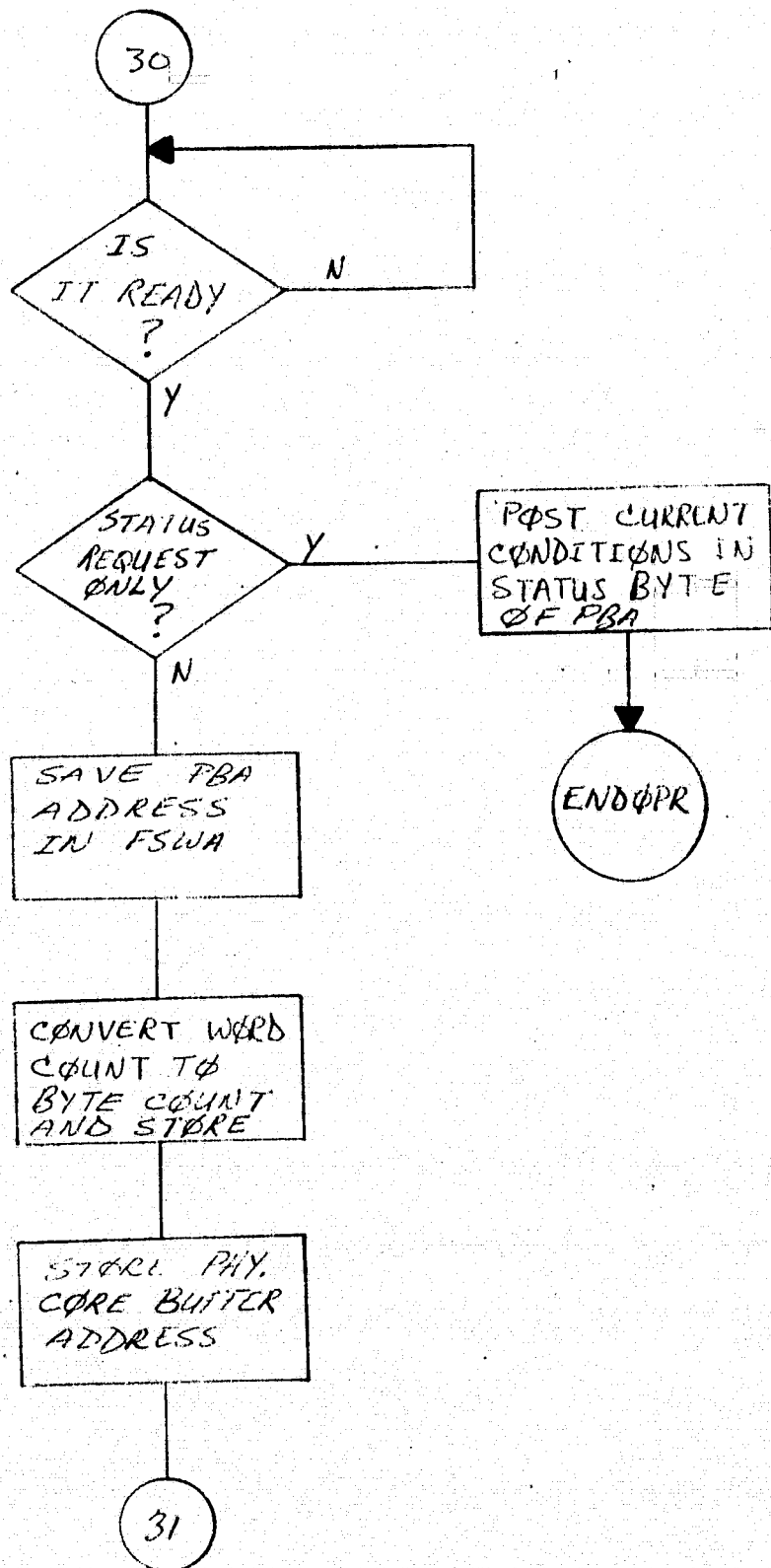


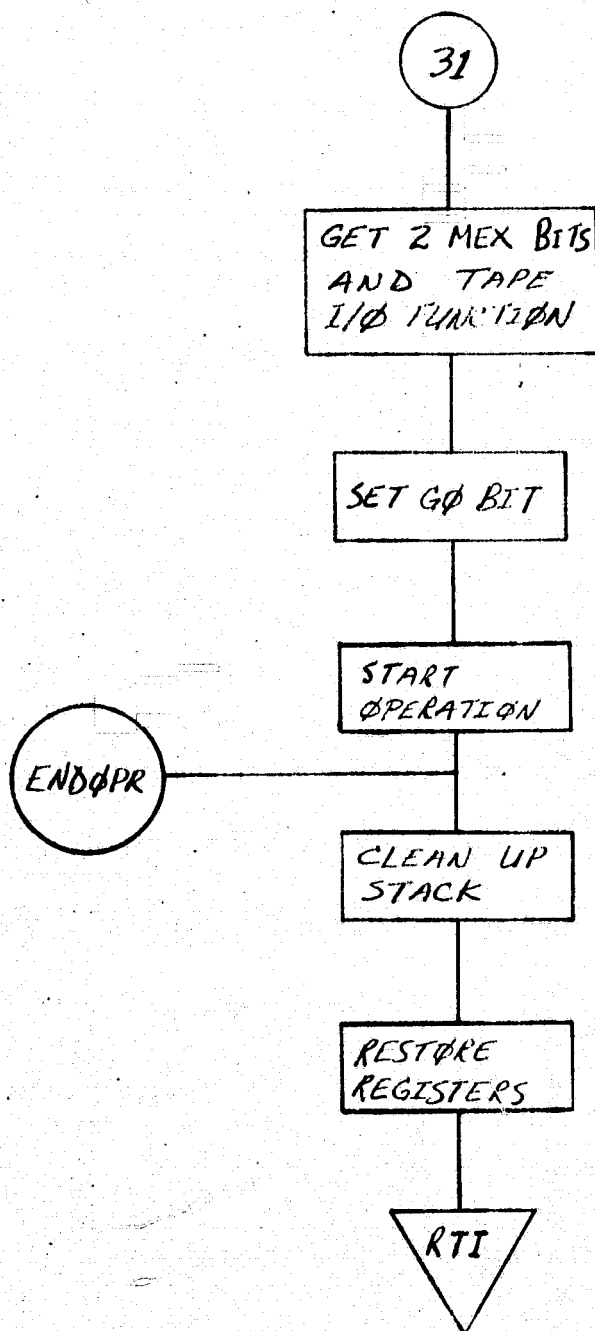


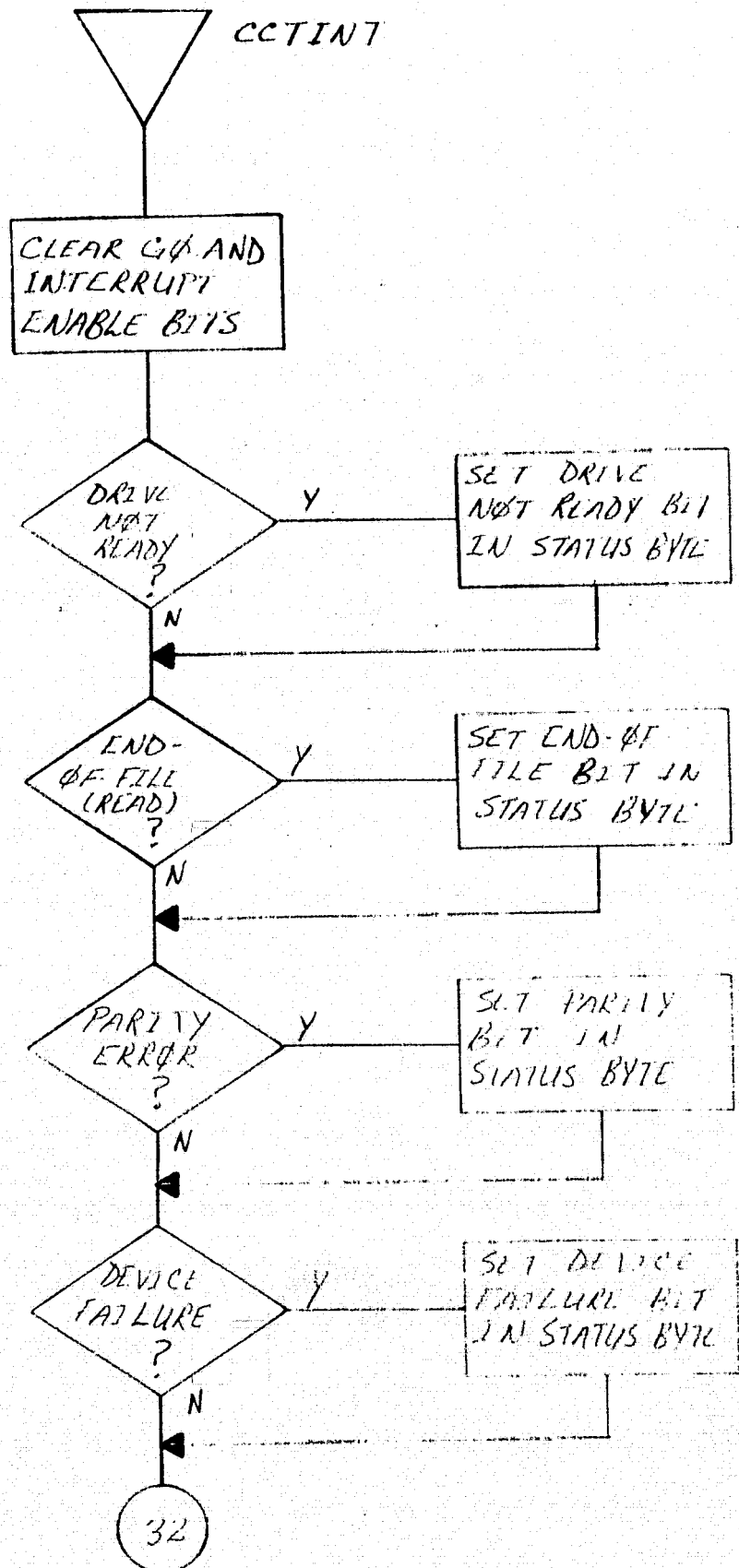


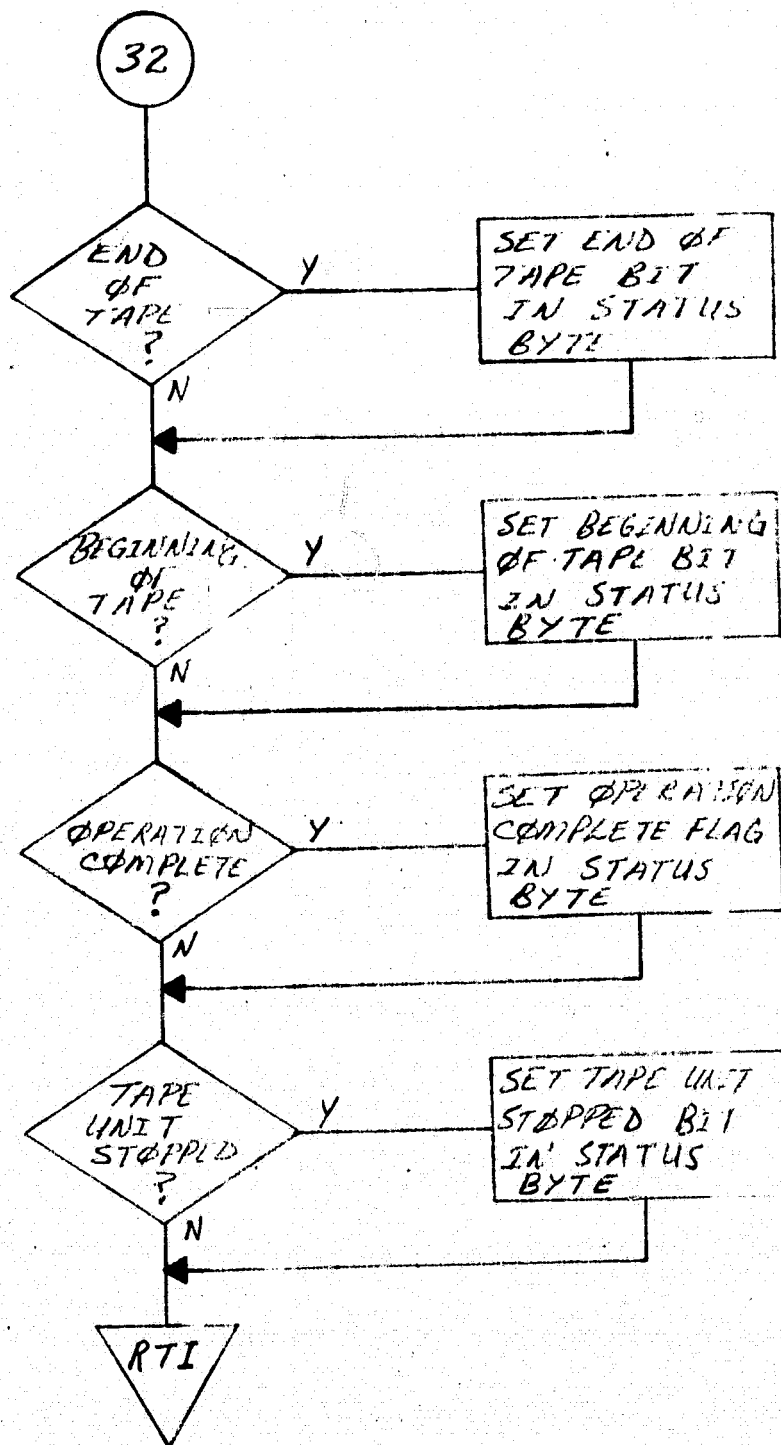


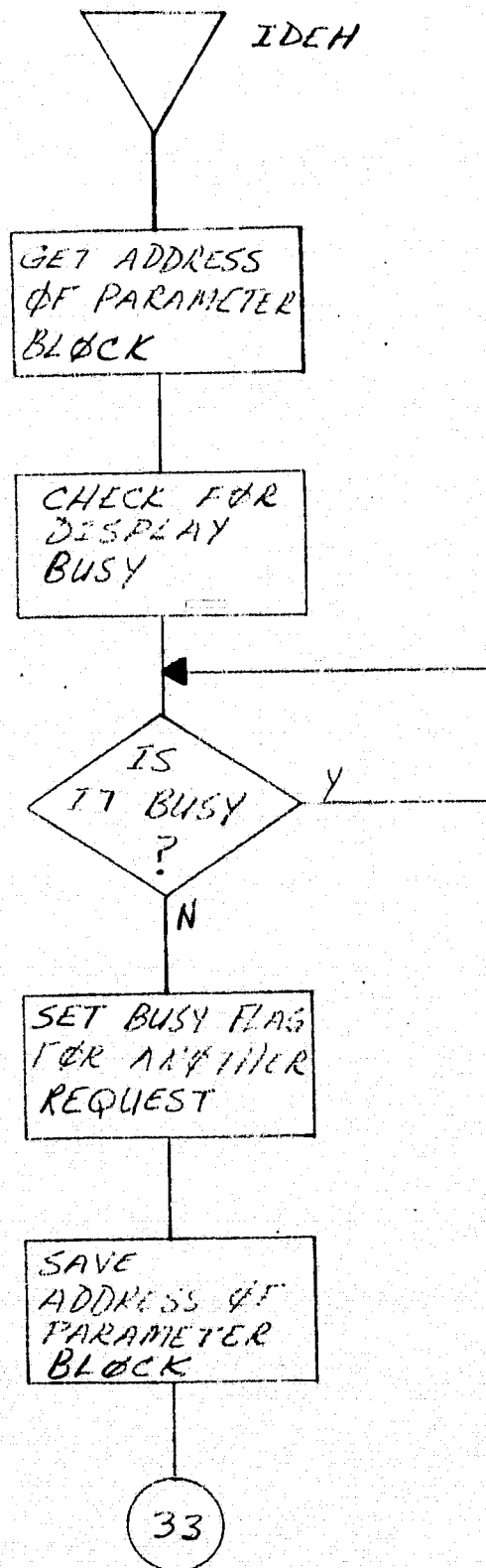




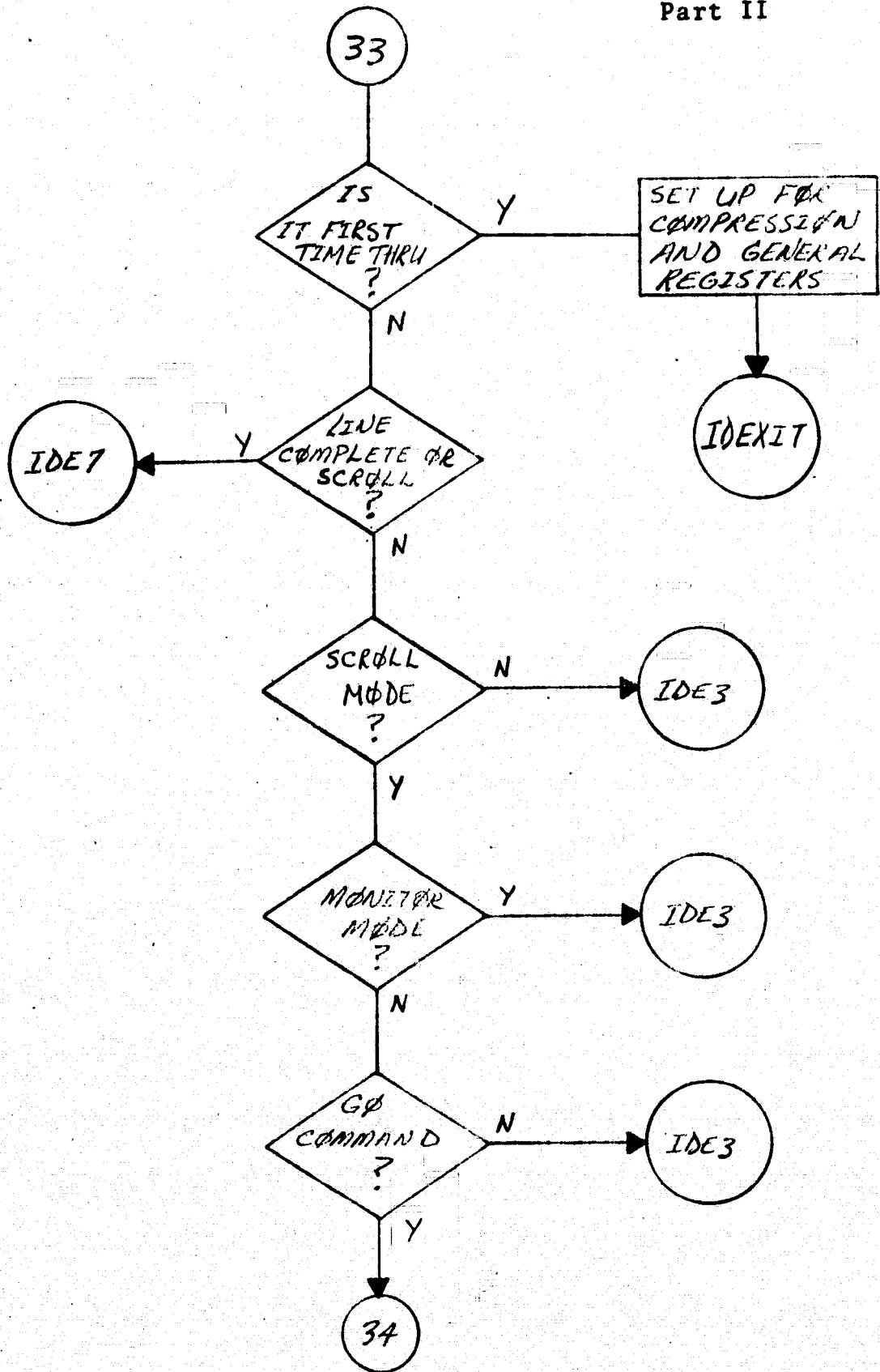


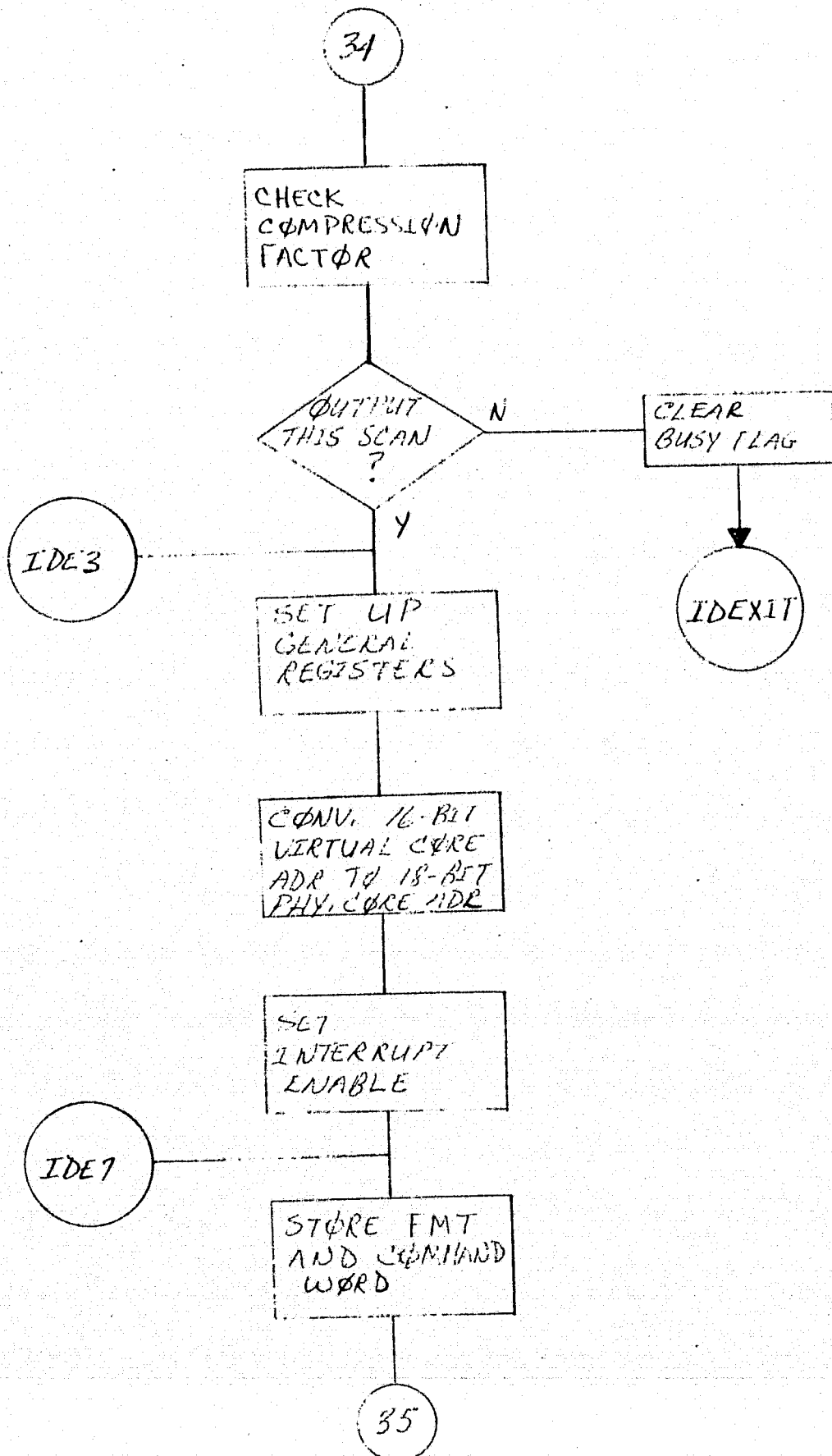


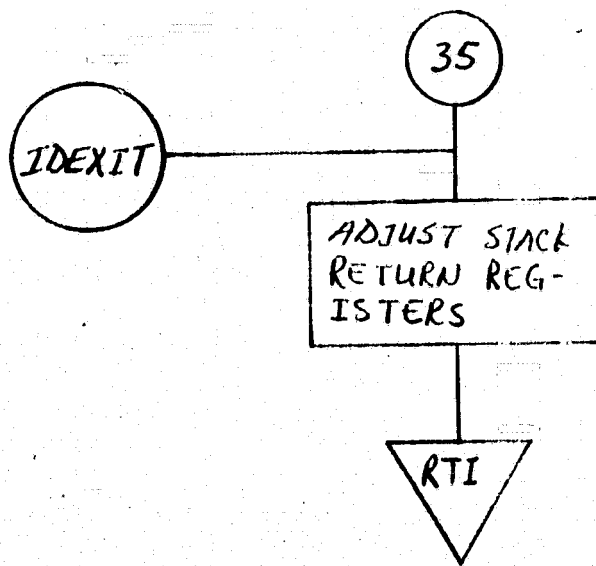




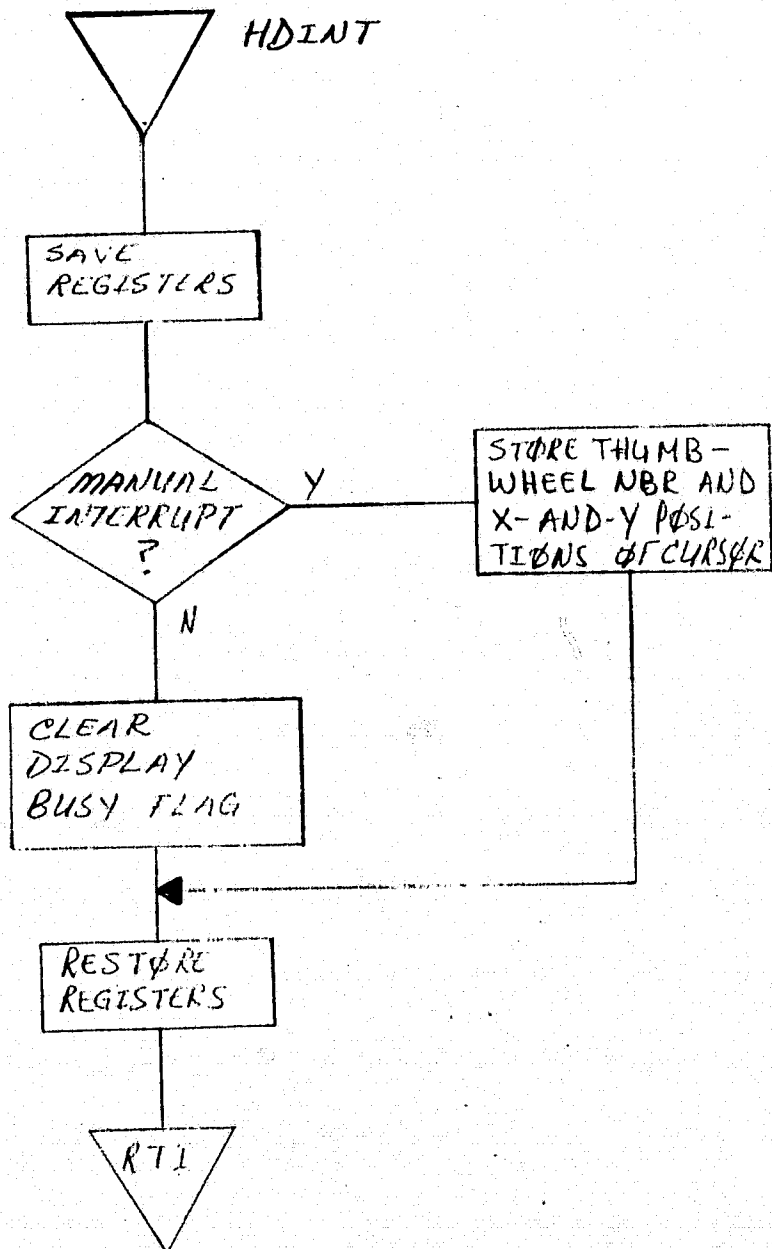
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## SECTION 9

### SUPPORT AND UTILITY SOFTWARE

#### 9.1 GENERAL SUPPORT AND UTILITY SOFTWARE CHARACTERISTICS

The SEDS software package contains various DEC support and utility programs as well as some previously developed by SISO. The special support software implemented for SEDS will be covered in this section. Refer to PHO-TR545, paragraph 3.7, for explanations of other support and utility software.

#### 9.2 CPC CHARACTERISTICS

##### 9.2.1 Component Descriptions

- A. DLOGIT. This is an independent program that will delog both the SEDS SBC (update) and OBC (data base) tapes in easily readable format on the line printer. The program allows the user to select the data channel desired, the start and stop scan line numbers, and the start and stop PIXEL numbers. This control is accomplished through cards input via the card reader. There must be one data card for each data channel, or part of a channel, to be delogged. Also, the start scan line number must be less than or equal to the stop scan line number, and the same is true for the start and stop PIXEL parameters. Figure 9-1 shows a sample card deck for the execution of DLOGIT.

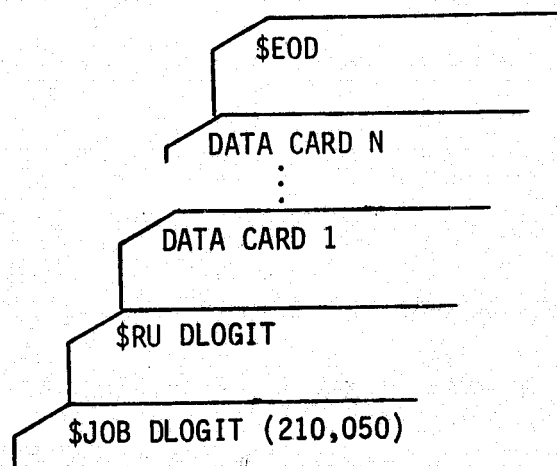
1. Channel Selection. Depending on the kind of tape, one of the following number codes in column 5 of the data card should be punched to select the desired channel:

- a. Update (SBC) Tape

- 1 = New CMI
- 2 = New DMAT

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TO INITIATE THE JOB, THE FOLLOWING JOB CARD DECK SHOULD  
BE INPUT IN THE CARD READER CONTAINING THE DATA CARDS.



ON THE DECWRITER, KEY IN BA CR:, LP: <CR> TO READ THE  
JOB CARD DECK AND BEGIN THE TAPE DELOG PROGRAM.

Figure 9-1 DLOGIT Exection Deck

- 3 = Old CMI
- 4 = Old DMAT

b. Data Base (OBC) Tape

- 1 = STMAT
- 2 = LTMAT
- 3 = LTMCMC
- 4 = DDSUM
- 5 = NGOOD
- 6 = STQUAL

2. Scan Line Selection. To select the start and stop scan line numbers, the user should punch the start scan number, right-justified, in columns 6-10, and punch the stop scan number, right-justified, in columns 11-15 of the data card. From one to 550 scan lines may be delogged for each data channel selected.

3. PIXEL Number Selection. The start and stop PIXEL numbers are entered by punching the start PIXEL number, right-justified, in columns 21-25 of the data card. The range of PIXELS for each scan line is 1 to 625.

B. DUMPIT. This is a program that will dump six kinds of data located in three separate disk files in SEDS. The SEDS registered data is in a disk file named SEDREG.DAT, which contains three types of data: night IR, day IR, and day visible. Header information about this data is contained in the disk file SEDREG.HDR. The delta T ( $\Delta T$ ) data file may be delogged and is in the disk file SEDDLT.DAT. The SEDS ground truth zone map (GTZONE) and altitude map (ALT) is delogged from a disk file named SEDGRD.DAT. The registered data will be preceded by a

dump of the header record. The data from all files will be output to the line printer. The program allows the user to specify the data type and the start and stop record number for each dump desired. Two cards are required for each dump. More than one dump may be done in each run by adding the appropriate data cards.

1. Data Type. To specify the data type, the user should punch one of the following number codes in column 5 of card 1.

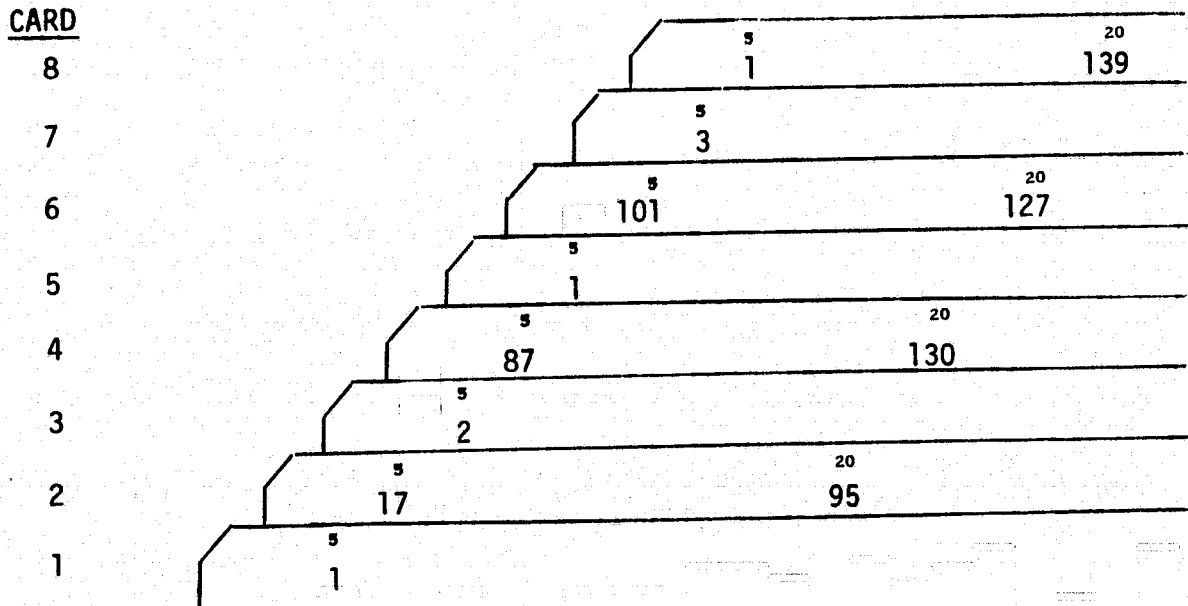
- 1 = Night IR
- 2 = Day IR
- 3 = Day visible
- 4 =  $\Delta T$
- 5 = ALT
- 6 = GTZONE

2. Records for Output. To specify the records for output, a start record number is required. There are four scan lines to each record; therefore, record No. 1 contains scan lines 1-4; record No. 2 contains scan lines 5-8, etc. The user should punch the start record number, right-justified, in columns 1-5 of card 2, and punch the stop record number, right-justified, in columns 15-20 of card 2.

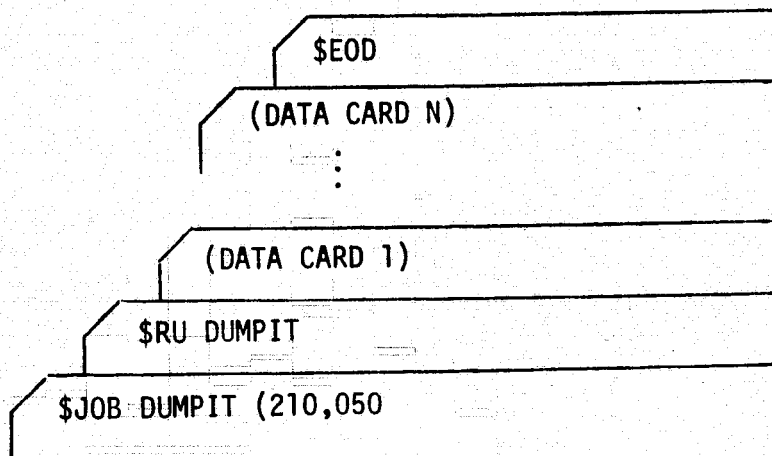
3. Range of Records. The range of 1 to 139 records may be dumped for each data type. Also, the start record number must be less than or equal to the stop record number. Figure 9-2 shows a sample execution run.

- C. MERGE. This is an offline program to merge the SEDS data base tapes. In the current SEDS day-to-day production cycle, one new tape (reel) is required each day for data

TO DUMP RECORDS 17-95 OF NIGHT IR, RECORDS 87-130 OF DAY IR, RECORDS 101-127 OF NIGHT IR, AND RECORDS 1-139 OF DAY VIS, THE FOLLOWING DATA CARD SETUP WOULD BE REQUIRED:



TO INITIATE THE JOB, THE FOLLOWING JOB CARD DECK SHOULD BE INPUT IN THE CARD READER CONTAINING THE DATA CARDS MENTIONED ABOVE:



ON THE DECWRITER, KEY IN BA CR:;LP:<CR> TO READ THE JOB CARD DECK IN AND TO BEGIN THE DUMP PROGRAM

Figure 9-2 DUMPIT Execution Deck

base maintenance. MERGE will allow up to seven tapes to be put onto one tape reel. The data base data remains unchanged except that 7 day's worth of SEDS processing will be catalogued onto a single tape reel. Each processing run is separated by two end-of-file marks except for the last file, which is followed by three end-of-file marks. Figure 9-3 shows the method used in the tape merge.

- D. EPPROC. This program has two functions, each using card input ephemeris data. The first data card contains the date the program is being run and the satellite number, with the format MMbDDbYY bbbbbbbX, where X is the satellite number (i.e., 4 for NOAA-4). The subsequent cards, one card for each orbit, contain the following information: day or night (punch D or N in column 1), the orbit number, Julian day, hour and minute of equator crossing, altitude, and longitude of equator crossing, in the format shown below.

(A2,7X,I6,4X,I4,6X,I2,8X,F5.2,5X,F7.2,3X,F7.2)

The last data card will be an end card with E punched in column 1. The program lists the input cards on the line printer for ease of verification. One of the two primary outputs is a tabulation of the calculated tape start and stop time, and start and stop PIXEL number to be used in editing the preprocessor tape. The second primary output is a tabulation of predicted registration coefficients (A2, B2, A3, and B3) to be used in registration when there are too few ground control points visible for accurate registration. For each orbit, the record of the Julian date, orbit, night or day, longitude and time of equator crossing, altitude, tape start and stop times, and tape start and stop PIXELS, is written on the scratch disk. This disk file is transferred to the production disk with the program EPTRAN. To run the program, the user sets up a batch card deck as shown on page 9-8.

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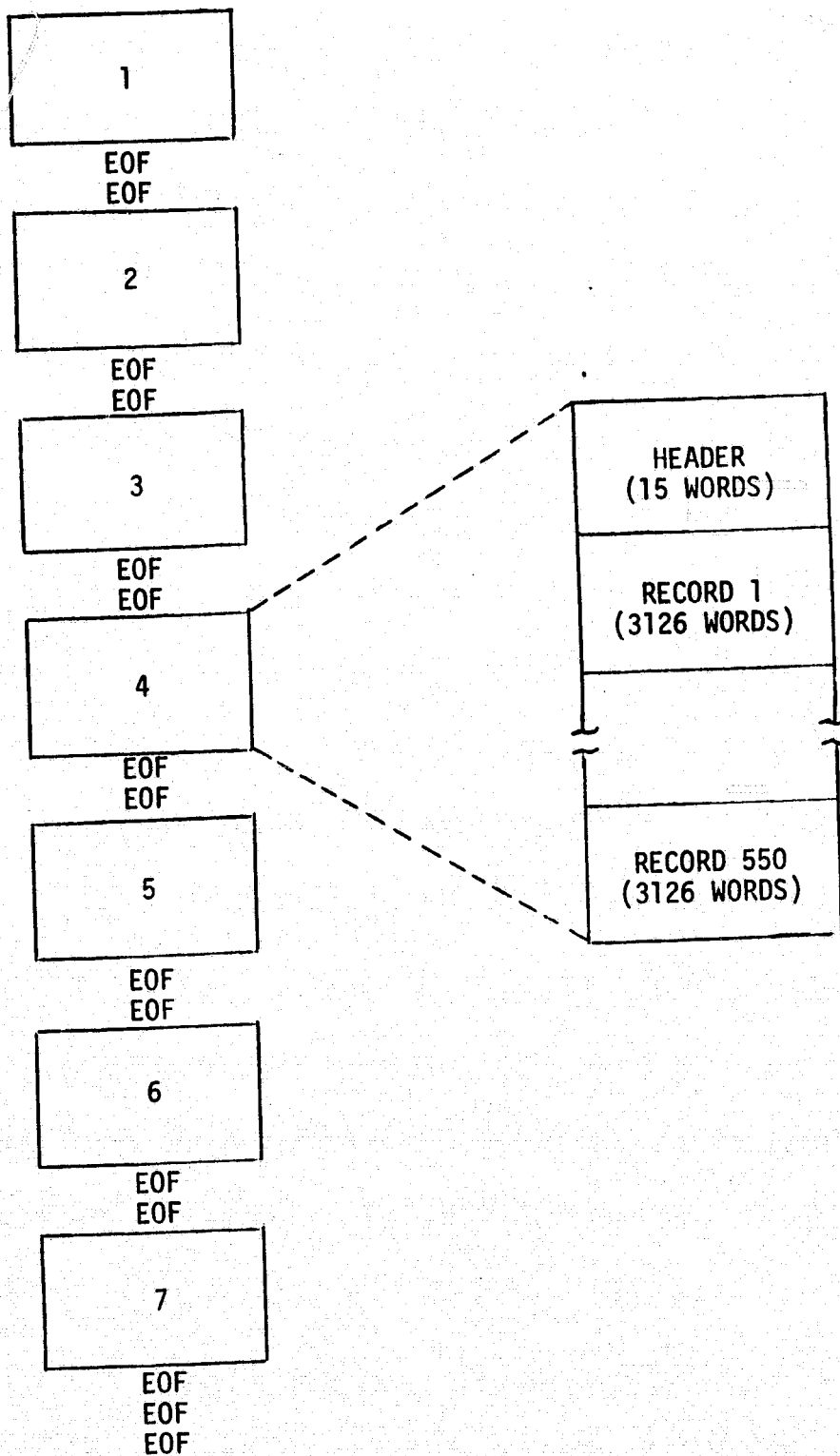


Figure 9-3 Multifile Data Base Tapes Using Merge



```

$EOD
E
ORBIT DATA CARDS
DATE CARD
$RUN EPPROC
$EOD
$AC DKO:NOAA4.TMP¢150,150!,13
$AS DKO:NOAA3.TMP¢150,150!,13
$JOB EPPROC¢150,150!

```

- E. EPTRAN. This program has only one function; to take the disk file written by EPPROC onto the scratch disk (DK1) and transfer it to the production disk (DK0). See item D above. The program is controlled by operator inputs through the DECwriter, in response to messages typed by the program on the DECwriter. To run the program, the user sets up a batch card deck as shown below.

```

$FI
$RUN EPTRAN
$EOD
$AS NOAA4.PRM,16
$AS NOAA4.TEMP,15
$JOB EPTRAN¢150,150!

```

- F. SEDSUM. This Data Base Delog Program allows the calculation of the averages of the values for the five SEDS data base channels over irregularly shaped geographic areas of the SEDS reference grid. Each of these geographic areas is defined by card inputs of the following format.

```

        Area ID (1-256)
1st  { Scan Line Number (1-500)
Set  { Start PIXEL Number (1-625)
      { Stop PIXEL Number (1-625)
      :
      :
Nth  { Scan Line Number
Set  { Start PIXEL Number
      { Stop PIXEL Number
      { Blanks (End of Area).

```

As many cards as necessary may be used to define an area, with six sets of scan line, start PIXEL and stop PIXEL numbers defined per card. All cards with the same area ID are processed together as a single unit. A restriction on the maximum size of these areas is that each area must be completely included within either scan lines 1-300 or scan lines 200-500, without overlapping. The lower 50 scan lines of the latter group are all over the Pacific Ocean. The following 10 parameters are compiled and printed out for each area defined.

- Average STMAT (°C)
- Average ST growth potential
- Average LTMAT (°C)
- Average LT growth potential
- Average LTMCMCMI (CMI units)
- Average CMI growth potential
- Average pupation time (days)
- Average DDSUM growth potential
- Average NGOOD/N (fraction, 0-1)
- Combined average growth potentials

The first 300 scan lines of data from the selected data base tape are read and placed on a scratch disk, and then each of the areas in the first group is processed to completion via separate passes through the data from disk. Lines 200 to 500 of the image are then read onto the disk, and the second group of areas are processed one at a time.

1. SEDSUM Calculations. If  $m$  is the total number of PIXELS ( $i$ ) defined in a given area ID, each of the 10 averages is calculated as follows.

- a. Average STMAT ( $^{\circ}$ C)

$$\overline{ST} = \frac{1}{m} \sum_{i=1}^m \left\{ \left[ \text{STMAT}_i^{\text{(encoded)}} / 4.0 \right] - 13.16 \right\}$$

- b. Average ST Growth Potential

$$\overline{G}_1 = \frac{1}{m} \sum_{i=1}^m \text{GP}_i(\text{ST Temp}_i)$$

- c. Average LTMAT ( $^{\circ}$ C)

$$\overline{LT} = \frac{1}{m} \sum_{i=1}^m \left\{ \left[ \text{LTMAT}_i^{\text{(D. Base)}} / N * 4.0 \right] - 13.16 \right\}$$

where:

$N$  = Data base length in days

$\text{LTMAT}^{\text{(D. Base)}}$  values = running  $N$ -day scans

- d. Average LT Growth Potential

$$\overline{G}_2 = \frac{1}{m} \sum_{i=1}^m \text{GP}_i(\text{LT Temp}_i)$$

e. Average LTMCI (in CMI Units)

$$\overline{G}_2 = \frac{1}{m} \sum_{i=1}^m \left[ \frac{\text{LTMCI}_i^{(D. \text{ Base})}}{N} - 128.0 \right] / 16.0$$

where:

LTMCI^(D. Base) values = encoded running N-day sums

f. Average CMI Growth Potential

$$\overline{G}_3 = \frac{1}{m} \sum_{i=1}^m GP_i (\text{LTMCI}_i)$$

g. Average Pupation Time (Days)

$$\overline{\text{MPT}} = \frac{1}{m} \sum_{i=1}^m \text{MPT}_i$$

where:

$\text{MPT}_i$  (mean pupation time for  $i$ th day)  
= 60 days if  $\text{DDSUM}_i \leq N*2.318333 + 0.5$ , or  
 $\text{MPT}_i = N*556.4/\text{DDSUM}_i$

h. Average DDSUM Growth Potential

$$\overline{G}_4 = \frac{1}{m} \sum_{i=1}^m GP_i (\text{MPT}_i)$$

i. Average NGOOD/N (Fraction, 0-1)

$$\overline{\text{NG}} = \frac{1}{m} \sum_{i=1}^m \frac{\text{NGOOD}_i}{N}$$

j. Combined Average Growth Potential ( $\bar{G}$ )

$$\bar{G} = \bar{G}_1^{C1} \bar{G}_2^{C2} \bar{G}_3^{C3} \bar{G}_4^{C4} \quad (C1+C2+C3+C4 = 1)$$

where:

C1, C2, C3, and C4 = card input combination coefficients;  $\bar{G}_1$ ,  $\bar{G}_2$ ,  $\bar{G}_3$  and  $\bar{G}_4$  = four average growth potentials as calculated above.

The three growth potential tables used in calculating  $\bar{G}_1$ ,  $\bar{G}_2$ ,  $\bar{G}_3$ , and  $\bar{G}_4$  above are the same tables used in generating the five color-coded growth potential images in SEDS Data Base Update Sequence No. 2. The 8-bit encoded values ( $S_i$ ) used for SEDS products are related to growth potentials ( $G_i$ ) as follows:

$$S_i = \text{Integer} (100 \ln G_i + 128.5)$$

The combination algorithm is:

$$S = C1*\bar{G}_1 + C2*\bar{G}_2 + C3*\bar{G}_3 + C4*\bar{G}_4$$

It can be easily shown that this form of the combination algorithm is mathematically equivalent to the form used above as long as  $C1 + C2 + C3 + C4 = 1.0$ .

For any discussion of numerical analysis or the validity of mathematical calculation, contact J. A. Boatright of Aeronutronic Ford Corporation.

2. Operation Procedure. SEDSUM is a standalone tape delog program that uses the SEDS data base tape as an input tape. SEDSUM outputs two products, an online tabulation and a 9-track tape of data averaged from each

active channel in the data base, along with the average of the corresponding growth potential for each channel. The following hardware configuration is required for operation of the SEDSUM program.

- DKO - SEDSPR2 production disk
- DK1 - Scratch disk with at least 3575 contiguous free blocks of core space
- MTX - One magnetic tape unit assigned to logical unit 9 (input)
- MTX - One magnetic tape unit assigned to logical unit 10 (output)
- KB - DECwriter keyboard
- CR - Card reader
- LP - Line printer

A sample run deck is as shown:

```

$JOB NAME [210,50]
$AS MT1: ,9
$AS MT0: ,10
$RU SEDSUM.LDA
      :
DATA CARDS
      :
$FI

```

Table 9-1 gives a lead card setup for SEDSUM.

Table 9-2 gives a cross-reference of sector number and county name.

Figure 9-4 shows a record layout of the output 9-track tape.

TABLE 9-1  
LEAD CARD SETUP FOR SEDSUM

CARD TYPE	MNEMONIC	COLUMNS	FORMAT	RANGE	DESCRIPTION
1	IFILE	1-5	I5	1-32767	REQUESTED FILE NO. OF INPUT TAPE
2*	ISECT	1-3	I3	1-254	SECTOR NO.
	ISCAN (1)	5-7	I3	1-275	SCAN LINE NO.
	ISRT (1)	9-11	I3	1-625	START PIXEL NO.
	ISTP (1)	13-15	I3	1-625	STOP PIXEL NO.
	ISCAN (2)	17-19	I3	1-275	SCAN LINE NO.
	ISRT (2)	21-23	I3	1-625	START PIXEL NO.
	ISTP (2)	25-27	I3	1-625	STOP PIXEL NO.
	ISCAN (3)	29-31	I3	1-275	SCAN LINE NO.
	ISRT (3)	33-35	I3	1-625	START PIXEL NO.
	ISTP (3)	37-39	I3	1-625	STOP PIXEL NO.
	ISCAN (4)	41-43	I3	1-275	SCAN LINE NO.
	ISRT (4)	45-47	I3	1-625	START PIXEL NO.
	ISTP (4)	49-51	I3	1-625	STOP PIXEL NO.
	ISCAN (5)	53-55	I3	1-275	SCAN LINE NO.
	ISRT (5)	57-59	I3	1-625	START PIXEL NO.
	ISTP (5)	61-63	I3	1-625	STOP PIXEL NO.
	ISCAN (6)	65-67	I3	1-275	SCAN LINE NO.
	ISRT (6)	69-71	I3	1-625	START PIXEL NO.
	ISTP (6)	73-75	I3	1-625	STOP PIXEL NO.

*CARD TYPE 2 IS REPEATED FOR EACH SECTOR IN A GIVEN RUN. THE MAXIMUM NUMBER OF SETS OF PIXELS REQUESTED PER SECTOR IS 50; A SET OF PIXEL REQUESTS INCLUDES A SCAN LINE NUMBER, START PIXEL NUMBER, AND STOP PIXEL NUMBER. THE END OF A SECTOR IS DENOTED BY A BLANK OR ZERO VALUE FOR THE SCAN LINE NUMBER OR A SECTOR NUMBER DIFFERENT FROM THE PREVIOUS SECTOR NUMBER READ. THERE IS NO LIMIT TO THE MAXIMUM NUMBER OF SECTORS THAT CAN BE PROCESSED IN A GIVEN RUN. DATA CARDS WILL BE SUPPLIED BY LOCKHEED CORPORATION.

TABLE 9-2

## CROSS REFERENCE OF SECTOR NUMBERS AND COUNTY NAMES

NO.	COUNTY	NO.	COUNTY
1	ANDERSON	44	COLLINGSWORTH
2	ANDREWS	45	COLORADO
3	ANGELINA	46	COMAL
4	ARANSAS	47	COMANCHE
5	ARCHER	48	CONCHO
6	ARMSTRONG	49	COOKE
7	ATASCOSA	50	CORYELL
8	AUSTIN	51	COTTLE
9	BAILEY	52	CRANE
10	BANDERA	53	CROCKETT
11	BASTROP	54	CROSBY
12	BAYLOR	55	CULBERSON
13	BEE	56	DALLAM
14	BELL	57	DALLAS
15	BEXAR	58	DAWSON
16	BLANCO	59	DEAF SMITH
17	BORDEN	60	DELTA
18	BOSQUE	61	DENTON
19	BOWIE	62	DE WITT
20	BRAZORIA	63	DICKENS
21	BRAZOS	64	DIMMIT
22	BREWSTER	65	DONLEY
23	BRISCOE	66	DUVAL
24	BROOKS	67	EASTLAND
25	BROWN	68	ECTOR
26	BURLESON	69	EDWARDS
27	BURNET	70	ELLIS
28	CALDWELL	71	EL PASO
29	CALHOUN	72	ERATH
30	CALLAHAN	73	FALLS
31	CAMERON	74	FANNIN
32	CAMP	75	FAYETTE
33	CARSON	76	FISHER
34	CASS	77	FLOYD
35	CASTRO	78	FOARD
36	CHAMBERS	79	FORT BEND
37	CHEROKEE	80	FRANKLIN
38	CHILDRESS	81	FREESTONE
39	CLAY	82	FRIO
40	COCHRAN	83	GAINES
41	COKE	84	GALVESTON
42	COLEMAN	85	GARZA
43	COLLIN	86	GILLESPIE



TABLE 9-2 (CONT'D)

NO.	COUNTY	NO.	COUNTY
87	GLASSCOCK	130	KENDALL
88	GOLIAD	131	KENEDY
89	GONZALES	132	KENT
90	GRAY	133	KERR
91	GRAYSON	134	KIMBLE
92	GREGG	135	KING
93	GRIMES	136	KINKEY
94	GUADALUPE	137	KLEBERG
95	HALE	138	KNOX
96	HALL	139	LAMAR
97	HAMILTON	140	LAMP
98	HANSFORD	141	LAMPASAS
99	HARDEMAN	142	LA SALLE
100	HARDIN	143	LAVACA
101	HARRIS	144	LEE
102	HARRISON	145	LEON
103	HARTLEY	146	LIBERTY
104	HASKELL	147	LIMESTONE
105	HAYS	148	LIPSCOMB
106	HEMPHILL	149	LIVE OAK
107	HENDERSON	150	LLANO
108	HIDALGO	151	LOVING
109	HILL	152	LUBBOCK
110	HOCKLEY	153	LYNN
111	HOOD	154	MCCULLOCH
112	HOPKINS	155	MCLENNAN
113	HOUSTON	156	MCMULLEN
114	HOWARD	157	MADISON
115	HUDSPETH	158	MARION
116	HUNT	159	MARTIN
117	HUTCHINSON	160	MASON
118	IRION	161	MATAGORDA
119	JACK	162	MAVERICK
120	JACKSON	163	MEDINA
121	JASPER	164	MENARD
122	JEFF DAVIS	165	MIDLAND
123	JEFFERSON	166	MILAM
124	JIM HOGG	167	MILLS
125	JIM WELLS	168	MITCHELL
126	JOHNSON	169	MONTAGUE
127	JONES	170	MONTGOMERY
128	KARNES	171	MOORE
129	KAUFMAN		

TABLE 9-2 (CONT'D)

NO.	COUNTY	NO.	COUNTY
172	MORRIS	214	STARR
173	MOTLEY	215	STEPHENS
174	NACOGDOCHES	216	STERLING
175	NAVARRO	217	STONEWALL
176	NEWTON	218	SUTTON
177	NOLAN	219	SWISHER
178	NUECES	220	TARRANT
179	OCHILTREE	221	TAYLOR
180	OLDHAM	222	TERRELL
181	ORANGE	223	TERRY
182	PALO PINTO	224	THROCKMORTON
183	PANOLA	225	TITUS
184	PARKER	226	TOM GREEN
185	PARMER	227	TRAVIS
186	PECOS	228	TRINITY
187	POLK	229	TYLER
188	POTTER	230	UPSHUR
189	PRESIDIO	231	UPTON
190	RAINS	232	UVALDE
191	RANDALL	233	VAL VERDE
192	REAGAN	234	VAN ZANDT
193	REAL	235	VICTORIA
194	RED RIVER	236	WALKER
195	REEVES	237	WALLER
196	REFUGIO	238	WARD
197	ROBERTS	239	WASHINGTON
198	ROBERTSON	240	WEBB
199	ROCKWALL	241	WHARTON
200	RUNNELS	242	WHEELER
201	RUSK	243	WICHITA
202	SABINE	244	WILBARGER
203	SAN AUGUSTINE	245	WILLACY
204	SAN JACINTO	246	WILLIAMSON
205	SAN PATRICIO	247	WILSON
206	SAN SABA	248	WINKLER
207	SCHLEICHER	249	WISE
208	SCURRY	250	WOOD
209	SCHACKELFORD	251	YOAKUM
210	SHELBY	252	YOUNG
211	SHERMAN	253	ZAPATA
212	SMITH	254	ZAVALA
213	SOMERVELL		

HEADER RECORD											
WORD NO.	15					8 7		0			
1	B					S					TAPE ID(3 CHAR ASCII CODE; SBC = UPDATE, OBC = DATA BASE)
2	NOT USED					C					
3	2					1					TAPE NO. (6 DIGITS IN ASCII)
4	4					3					
5	6					5					
6	NO. OF CHANNELS										BINARY
7	1	2	3	4	5						CHANNELS ACTIVE(0=NOT ACTIVE, 1=ACTIVE)
8	MONTH					DAY					CURRENT DATE (BINARY)
9	NOT USED					YEAR(LAST 2 DIGITS)					
10	DATA BASE LENGTH (N)										BINARY
11	ORBIT NUMBER										
12	MONTH					DAY					DATE OF DATA (BINARY)
13	NOT USED					YEAR(LAST 2 DIGITS)					
14	SPARE										
15	SPARE										

TAPE ID(3 CHAR ASCII CODE;  
SBC = UPDATE, OBC = DATA BASE)

TAPE NO. (6 DIGITS IN ASCII)

BINARY

CHANNELS ACTIVE(0=NOT ACTIVE,  
1=ACTIVE)

CURRENT DATE (BINARY)

BINARY

DATE OF DATA (BINARY)

- DATA BASE UPDATE TAPE (SEQ. NO. 1 - RAP)
- DATA BASE TAPES (SEQ. NO. 2 - SSP)

Figure 9-4 Layout of Output  
9-Track Tape

DATA RECORD									
WORD NO.	15	8	7	0	15	8	7	0	WORD NO.
2	A		D		I		H		1
4			O		G		L		3
6	NOT USED				M		N		5
8	STMAT								7
10	STMAT G/P								9
12	LTMAT								11
14	LTMAT G/P								13
16	LTMCM I								15
18	LTMCM I G/P								17
20	MPT								19
22	MPT G/P								21
24	NGOOD								23
26	NGOOD AVG								25
28	NOT USED								27
30	NOT USED								29

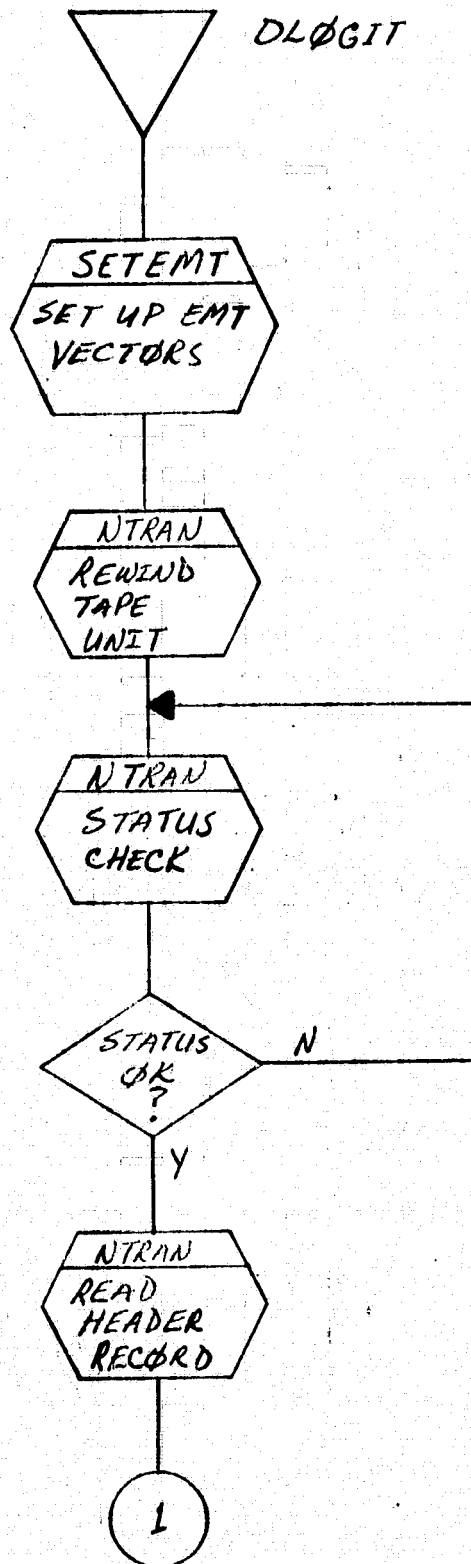
COUNTY LABELS  
IN ASCII

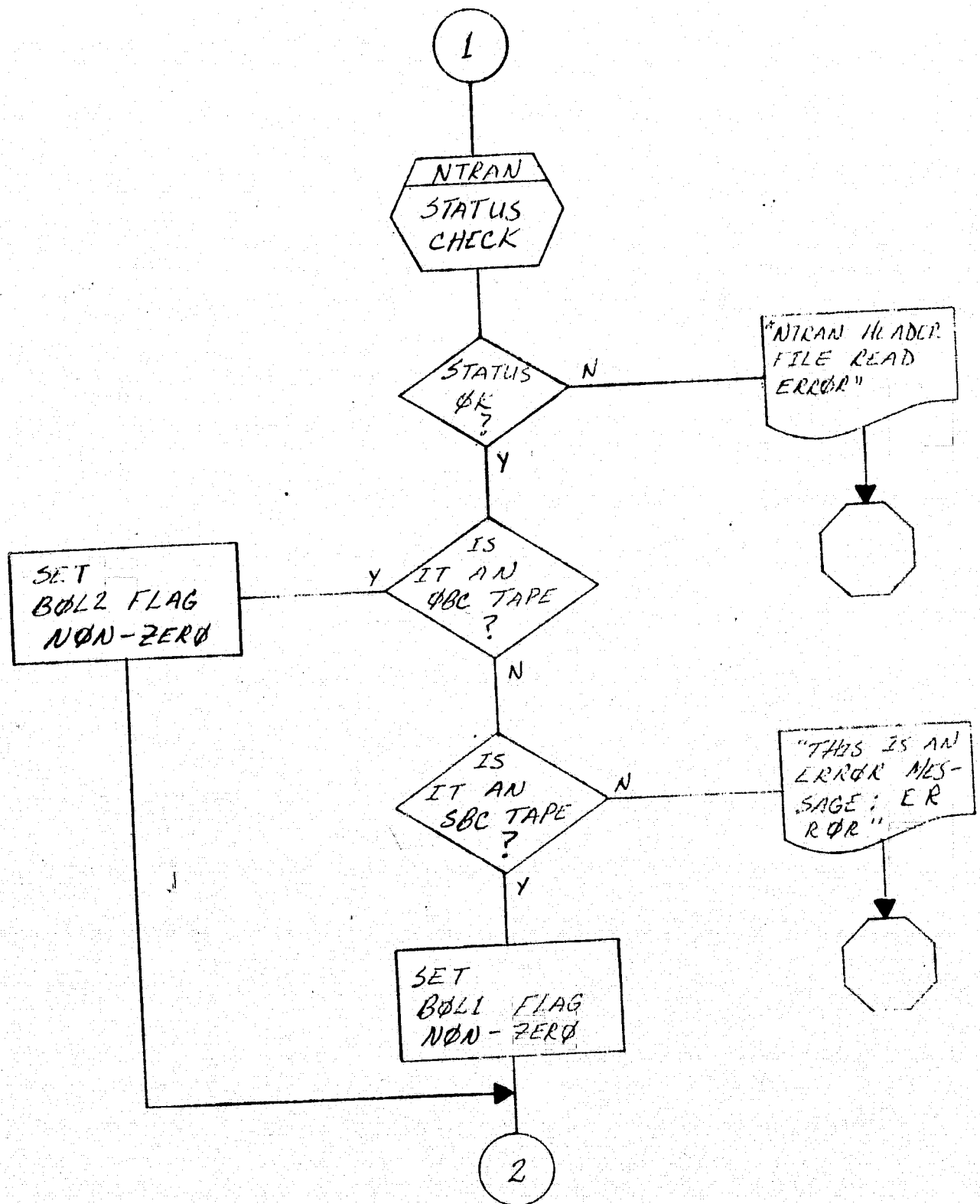
BINARY

Figure 9-4 (Cont'd)

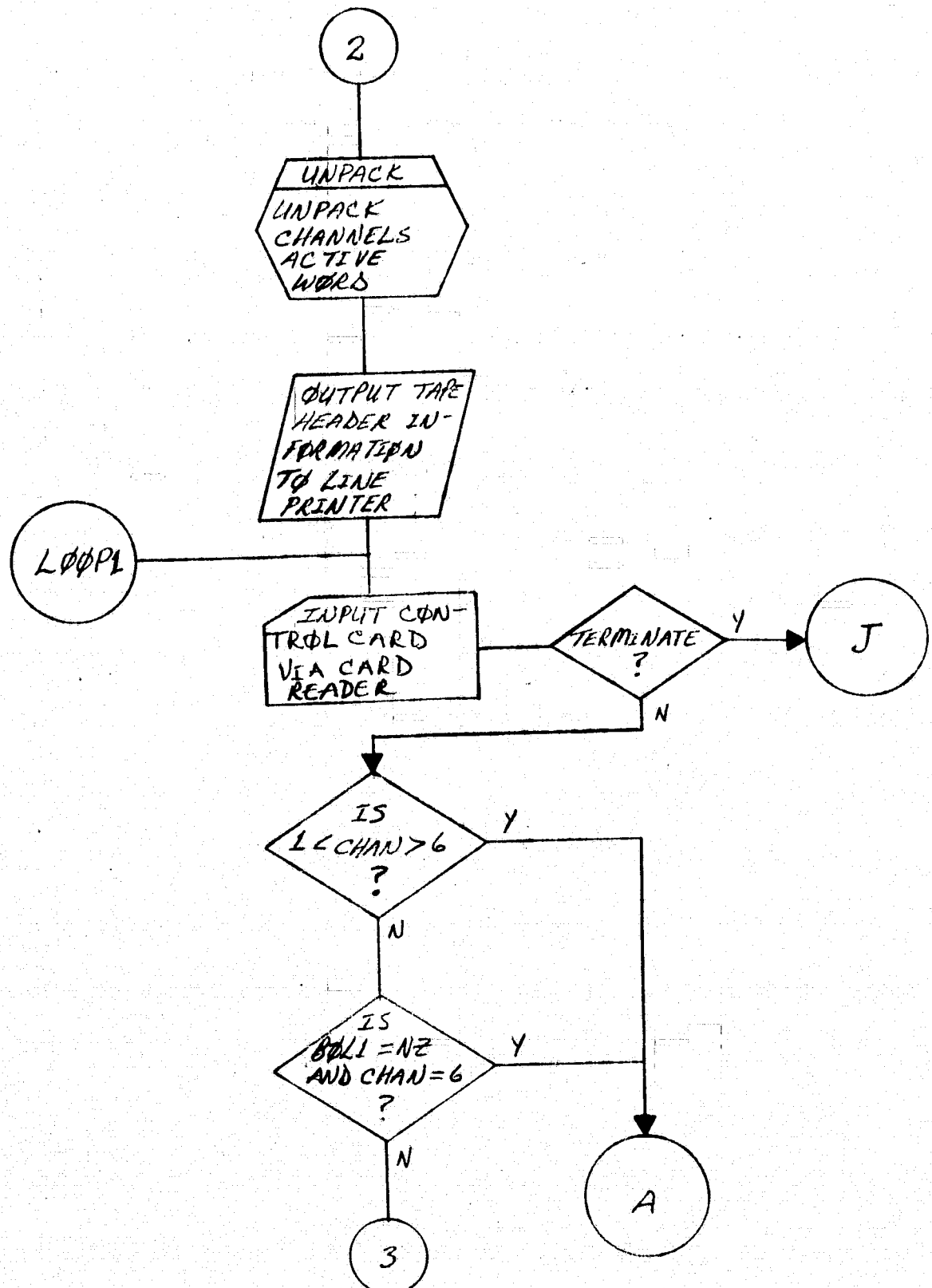
3. Run Time and Error Messages. Run time for a typical job is approximately 5 minutes. Error messages and their causes are listed below. Any of these error conditions will cause program termination, and when errors are corrected, the program must be reinitiated to continue.
- TAPE ID DOES NOT MATCH ID = XXXX (input tape is not an OBC or SBC delog tape)
  - UNABLE TO ALLOCATE DISK FILE BY NTRAN, STAT = XXX (not enough free disk space on DK1)
  - UNABLE TO READ RECORD #, XXX STAT = XXX (number requested is larger than the last record on tape for the file requested)
  - UNABLE TO READ DISK RECORD # XXX STAT = XXX (number requested is larger than the last record on disk for the file requested)
  - NTRAN ERROR STAT = XXX (input tape read error or data transfer error)
  - END OF DISK FILE (end of the disk file was reached before the present scan line was processed)
  - CARD INPUT ERR: START PIXEL # XXXX IS GREATER THAN STOP PIXEL # XXXX OF SECTOR # XXXX (input card error; start PIXEL number is greater than the stop PIXEL number of indicated sector number).

9.2.2 Flow Charts. See following 77 pages.

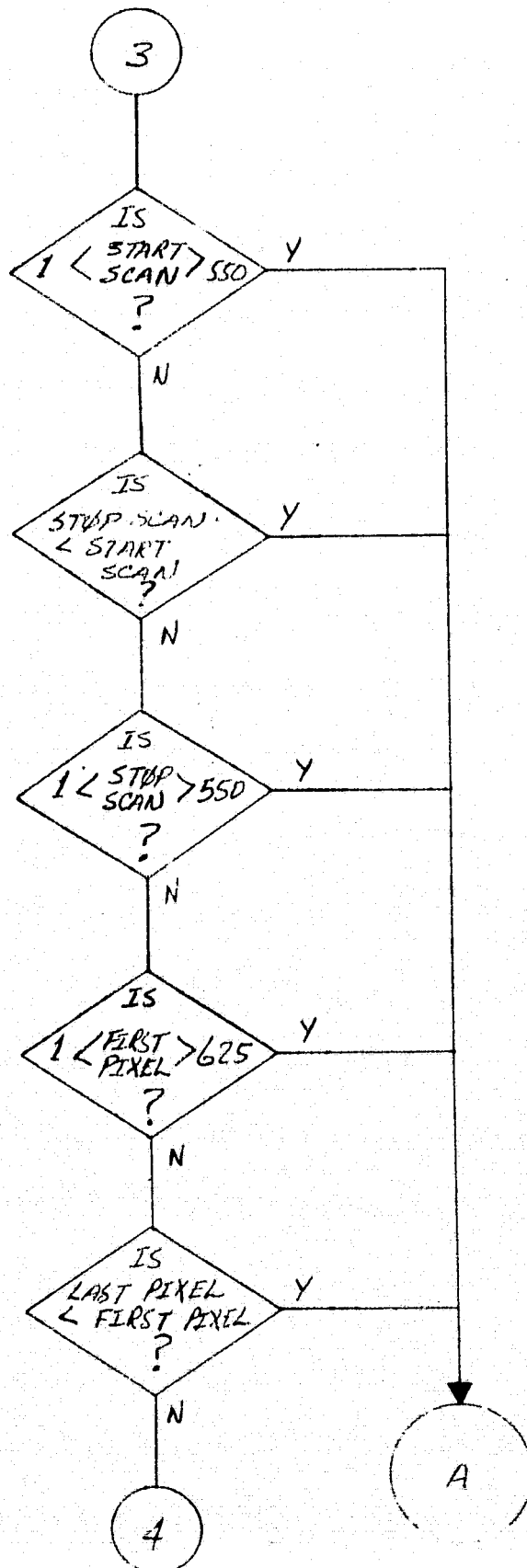


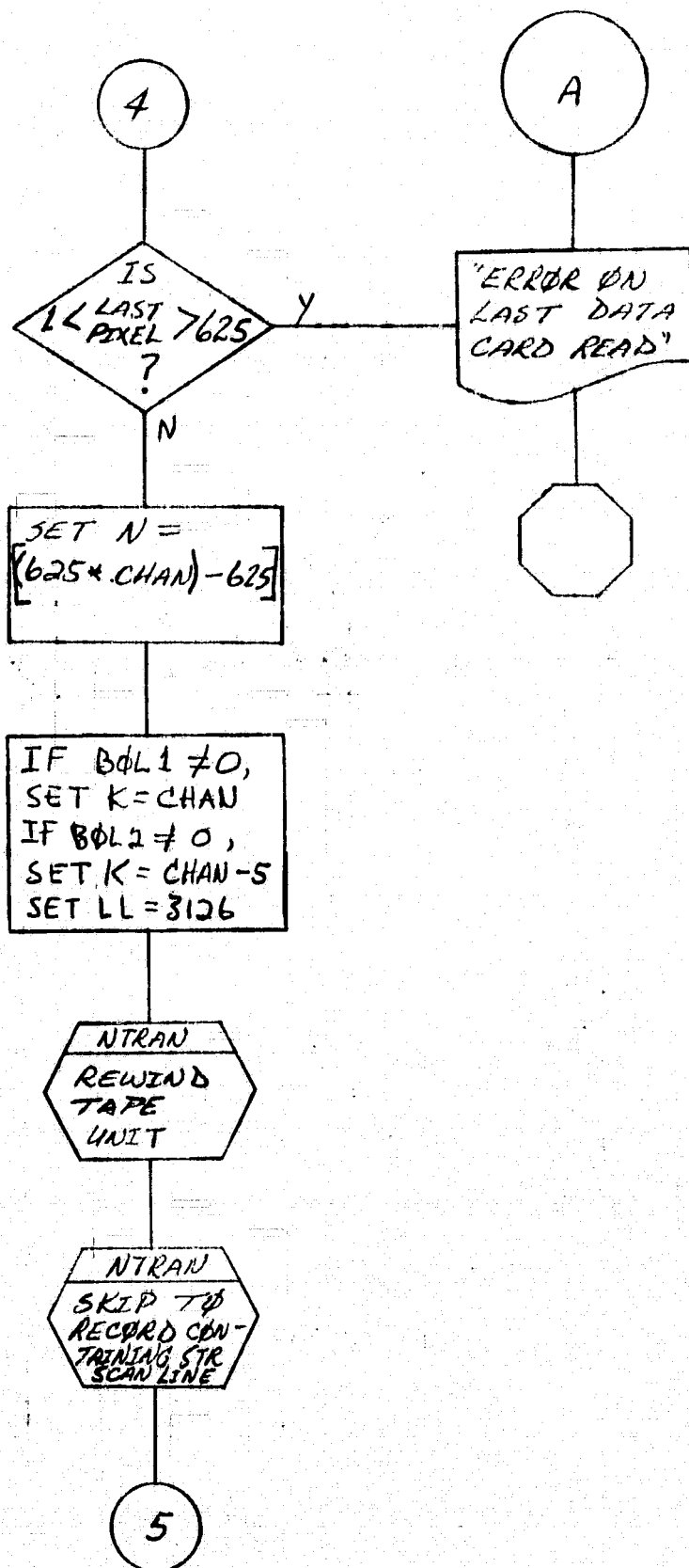


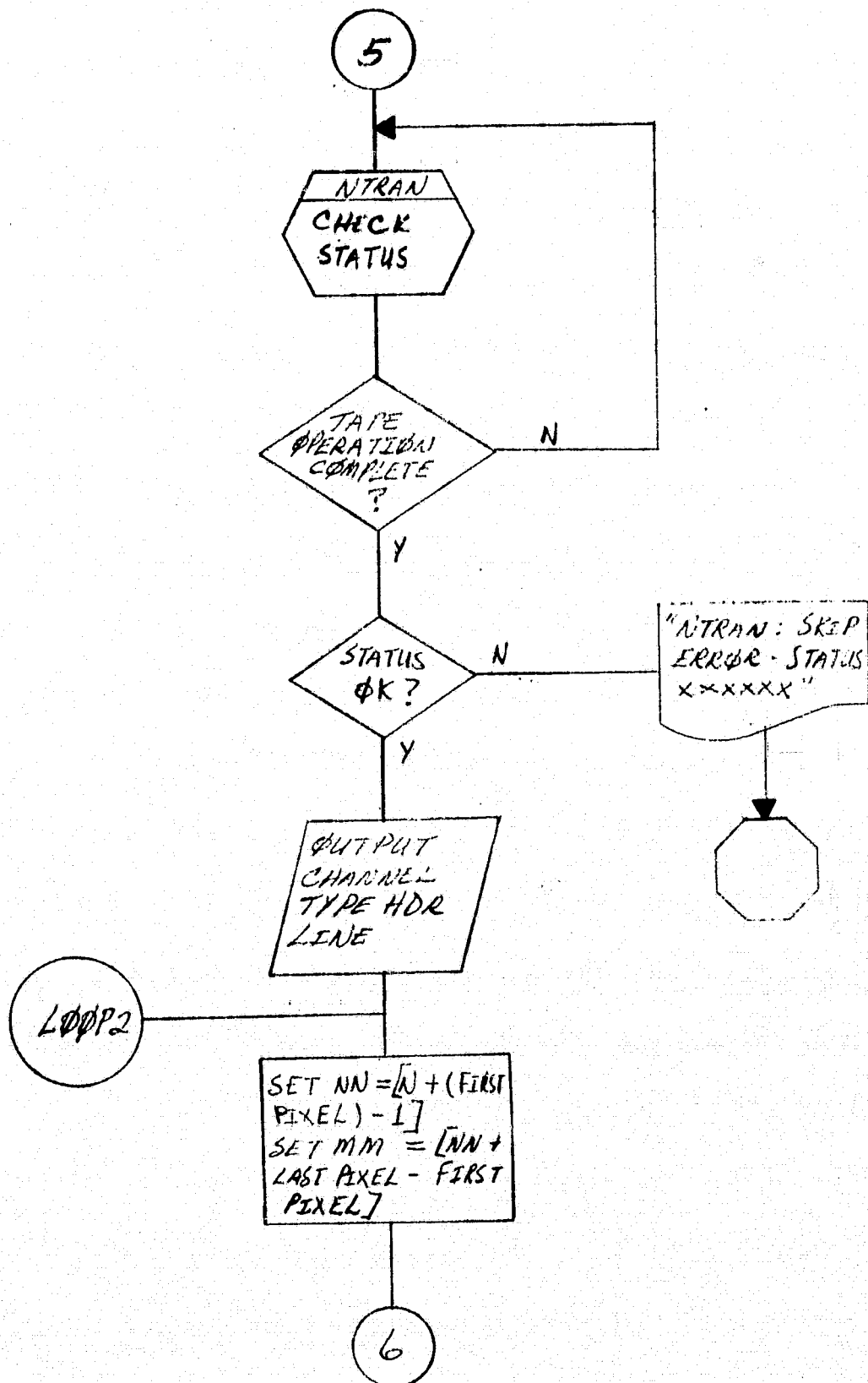
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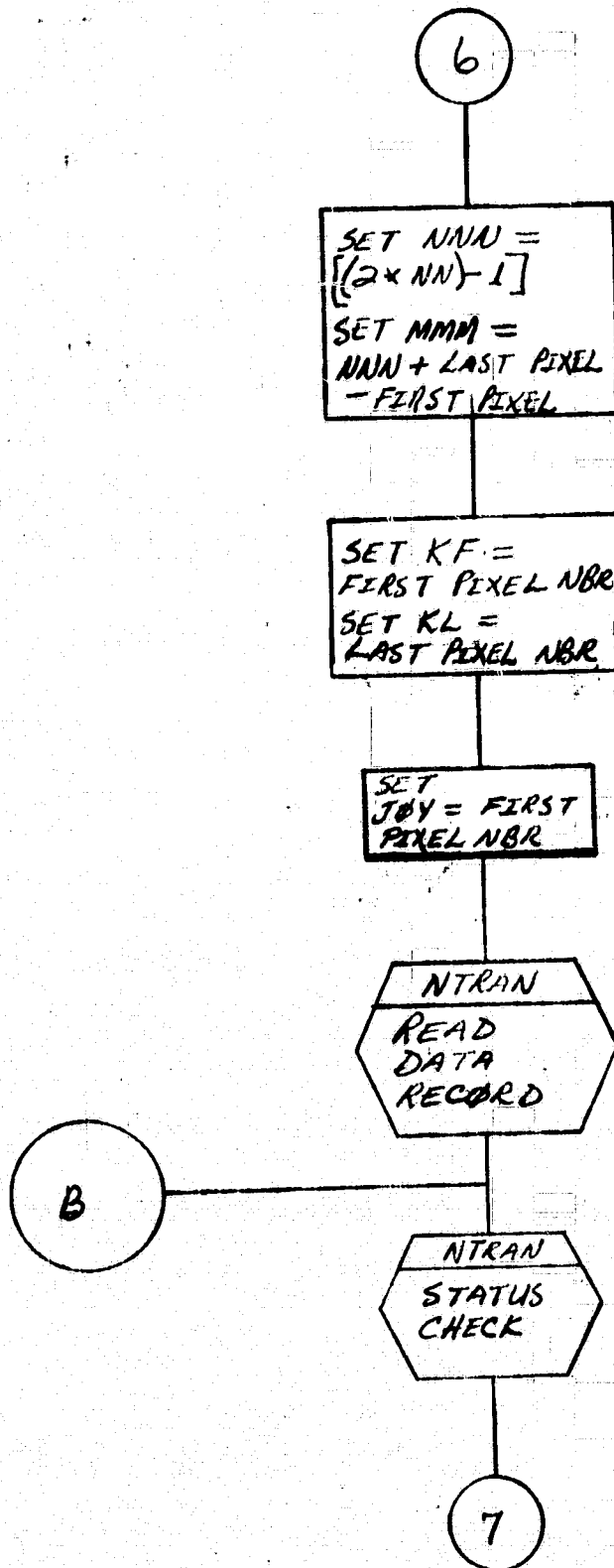


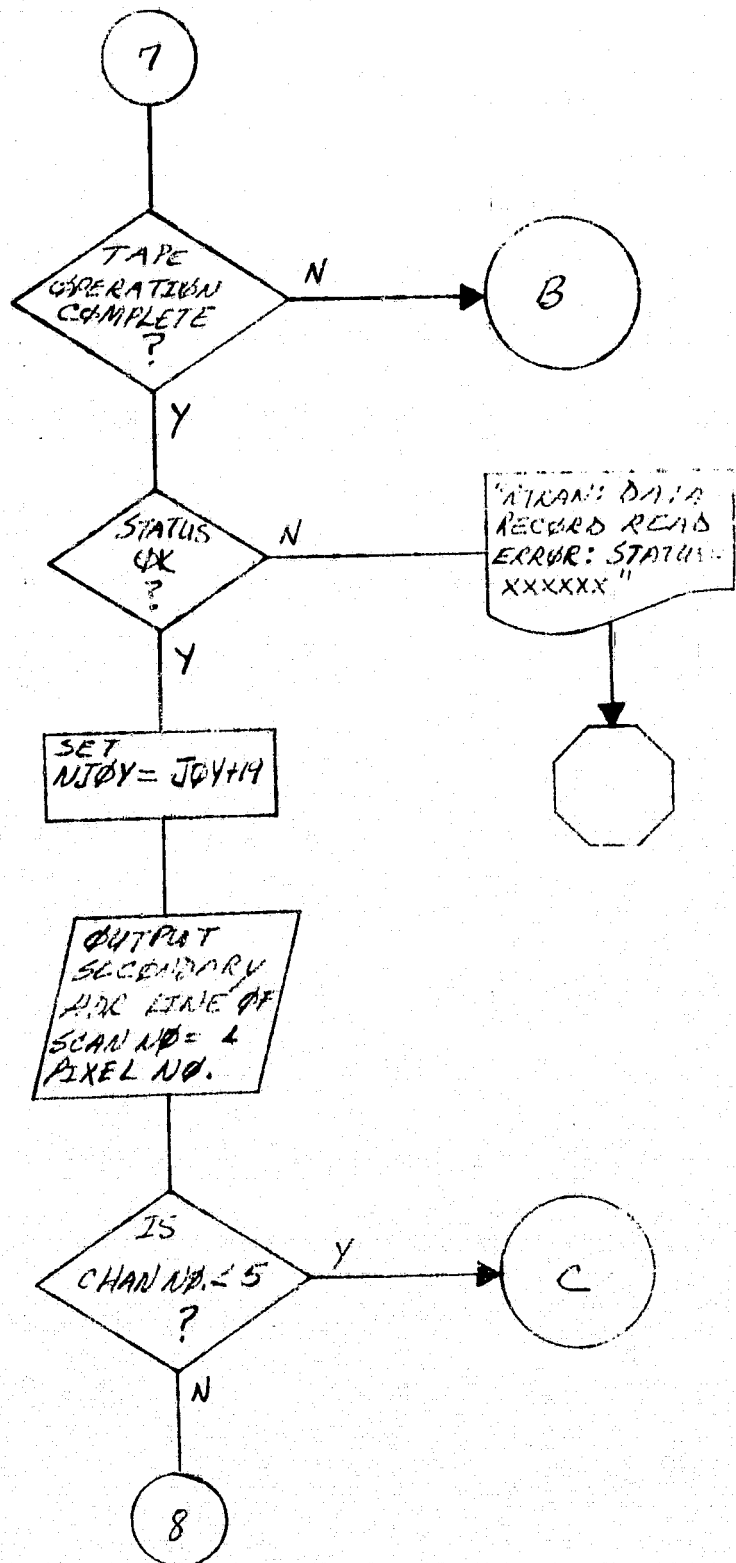




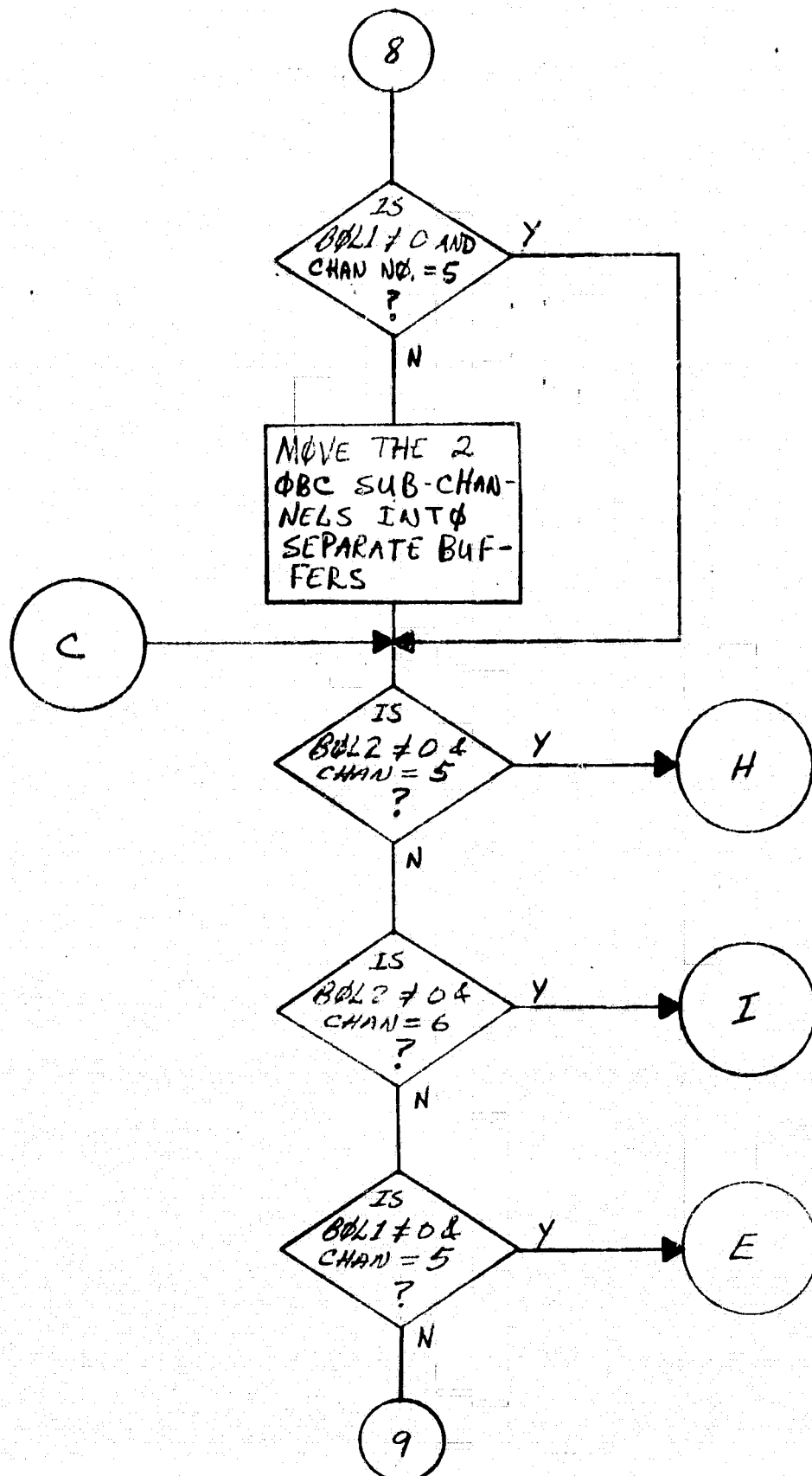


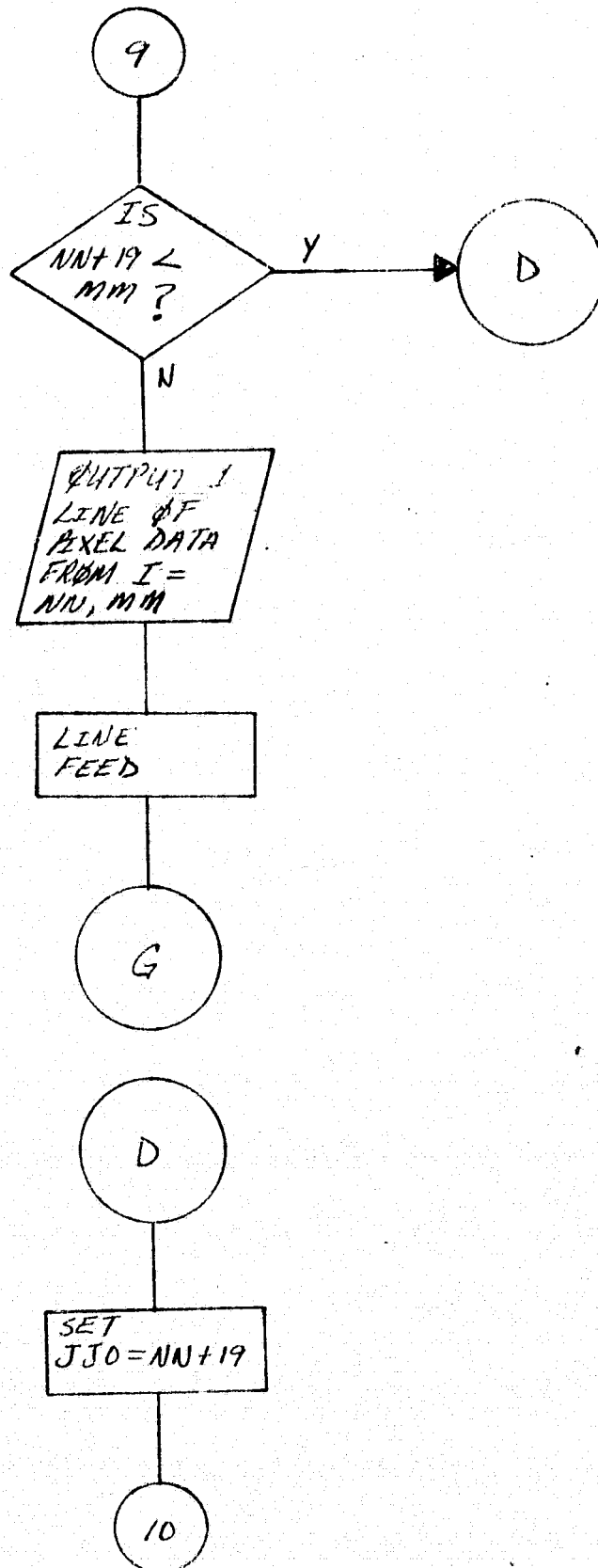


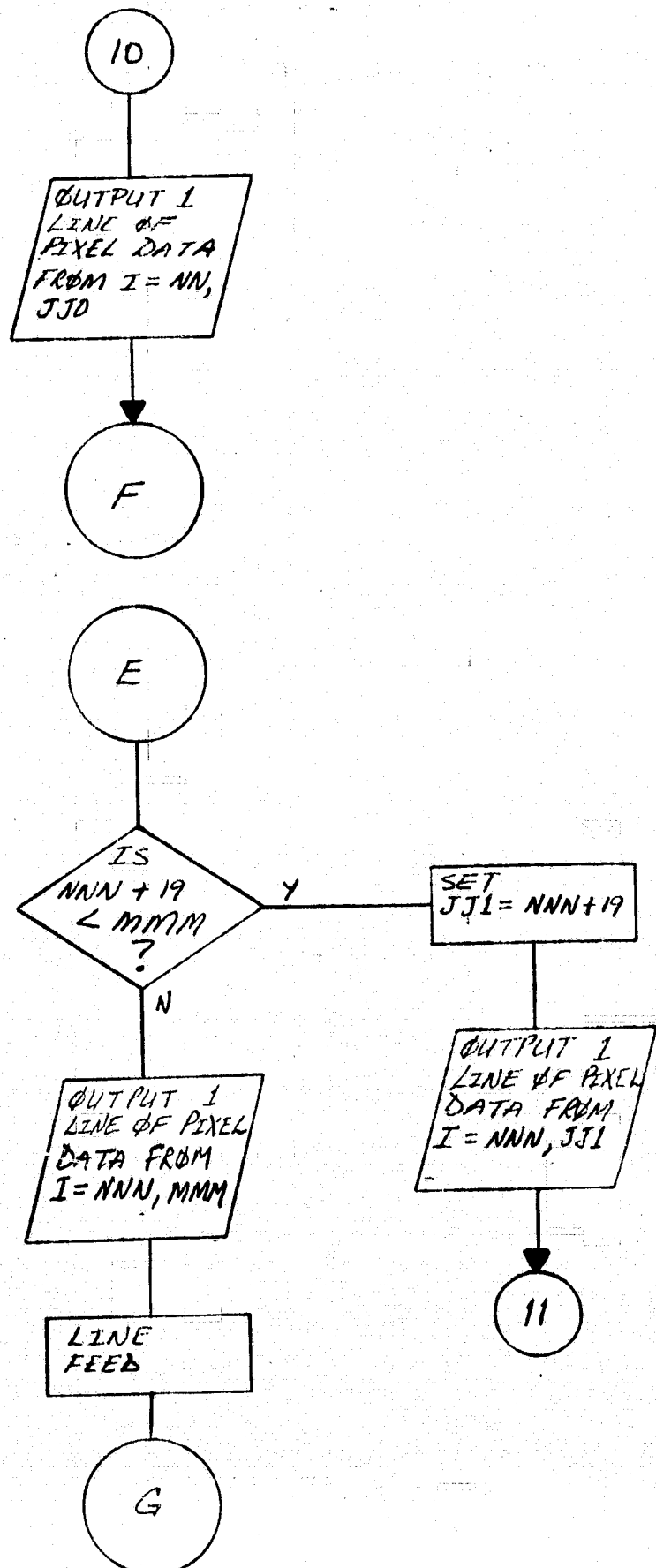




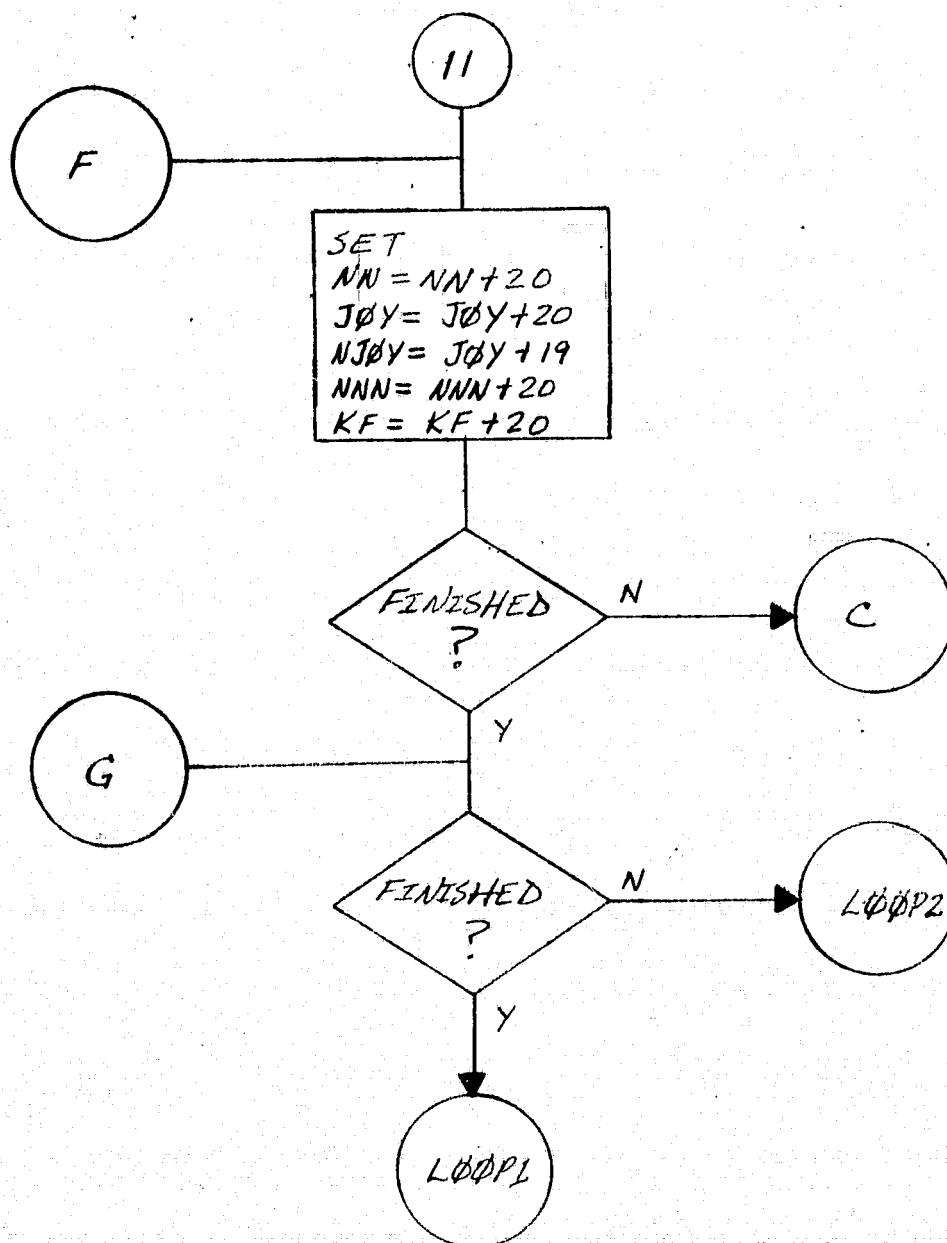
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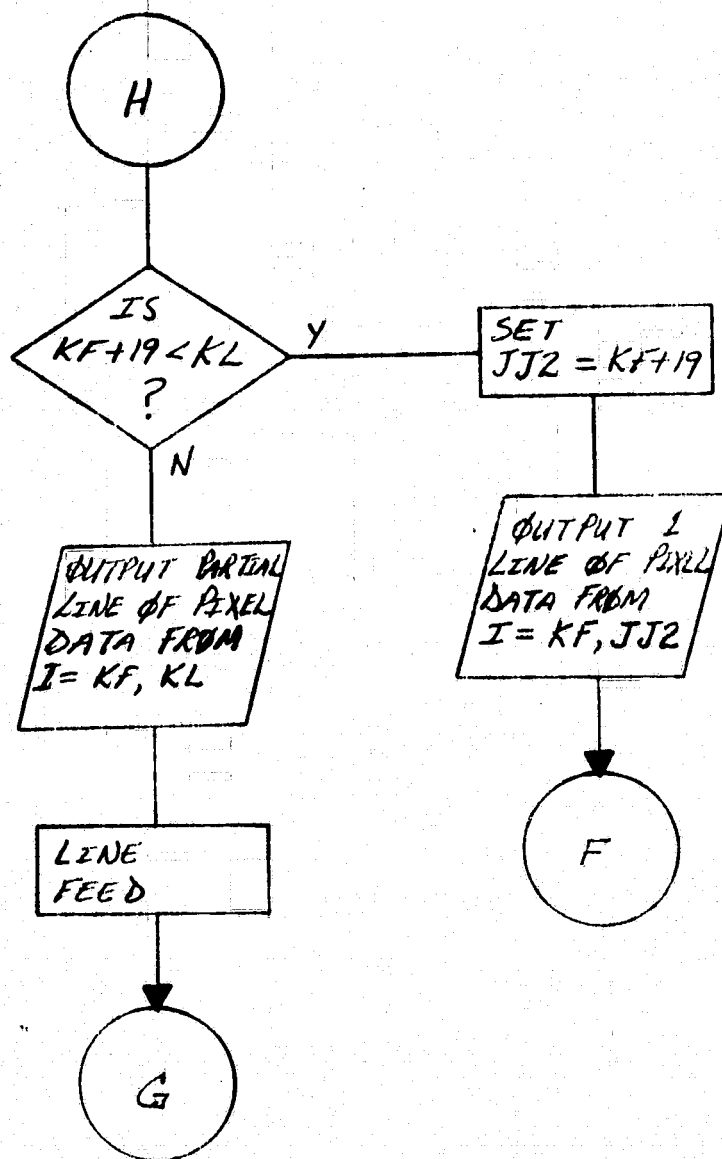


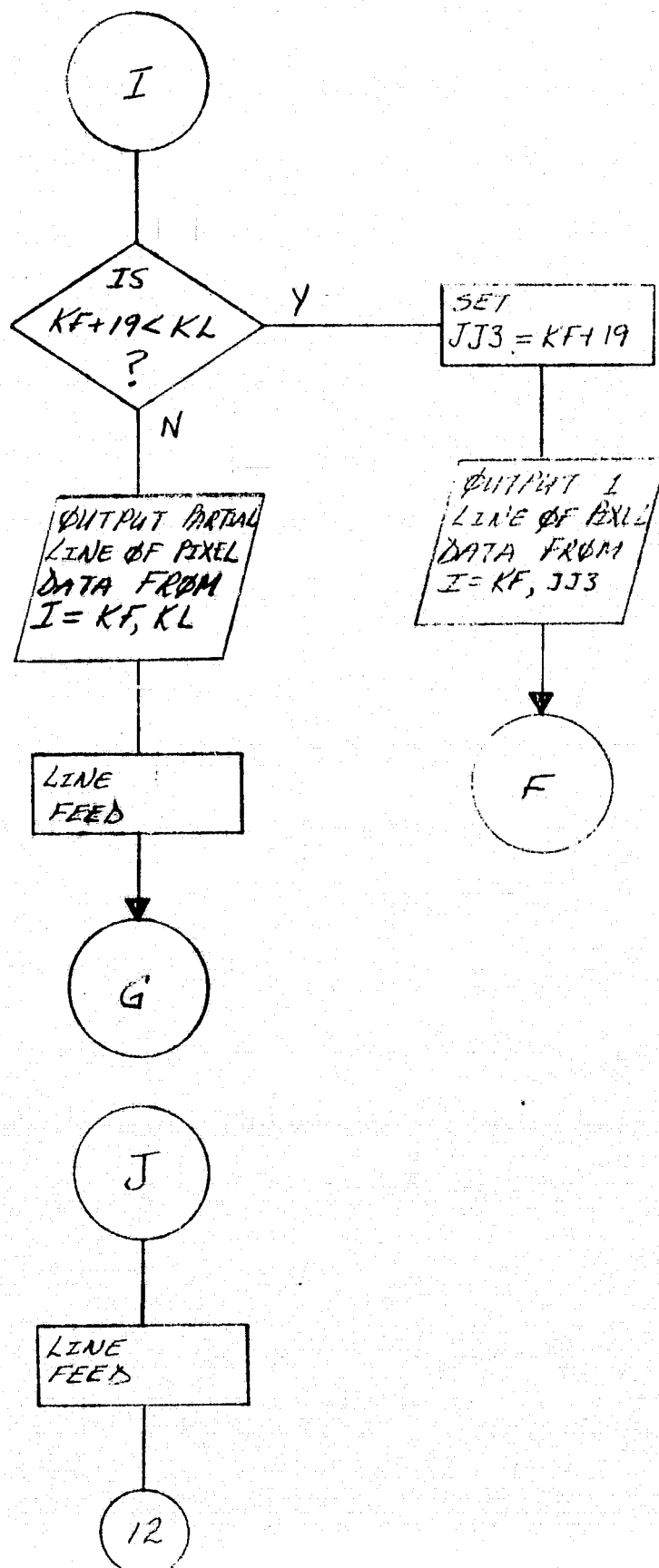


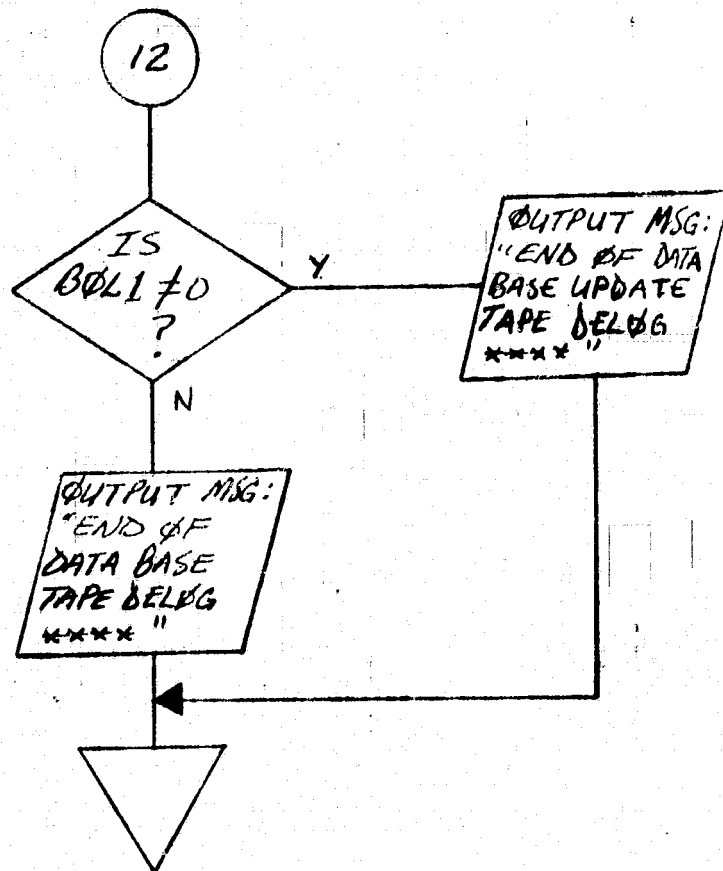


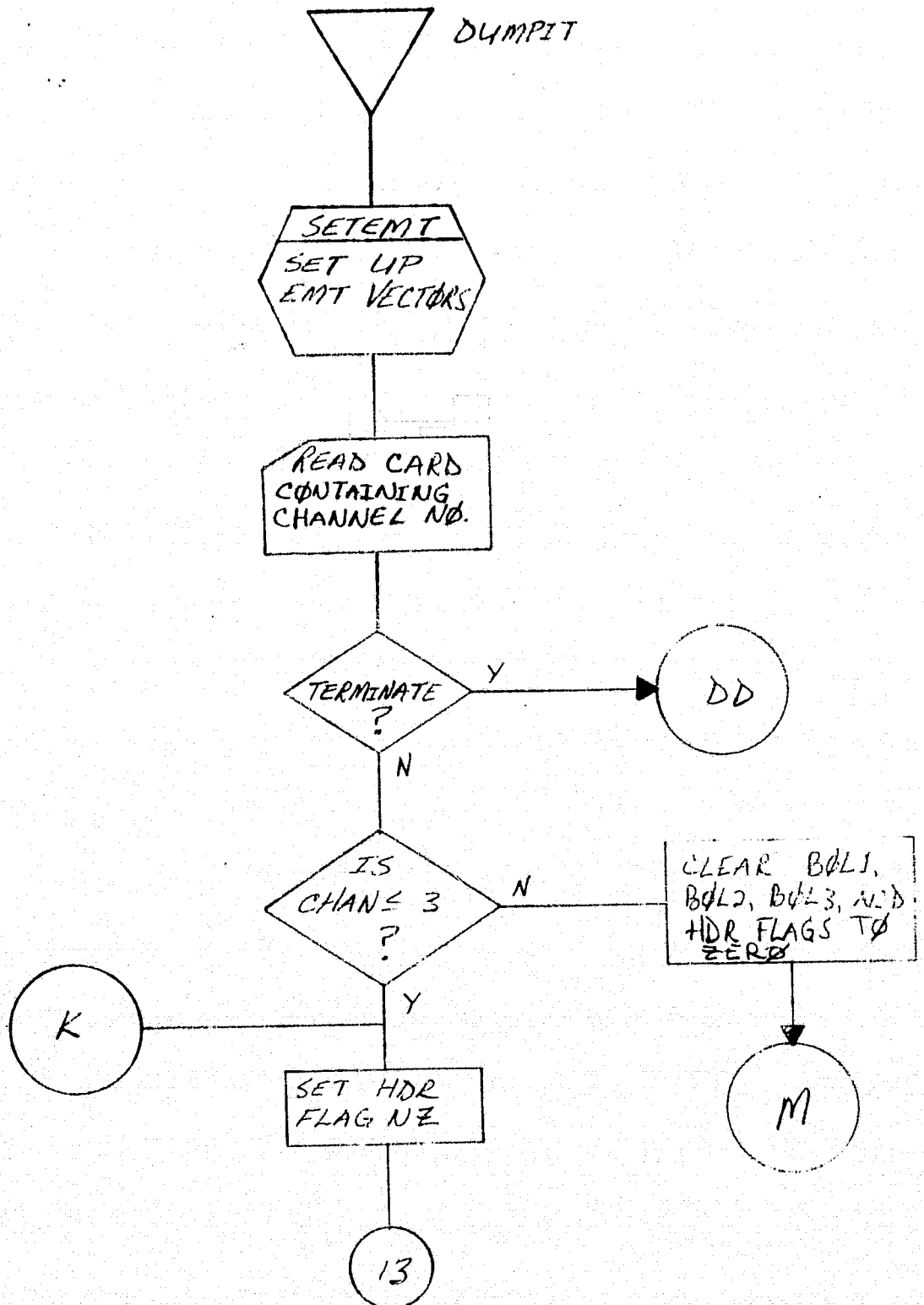


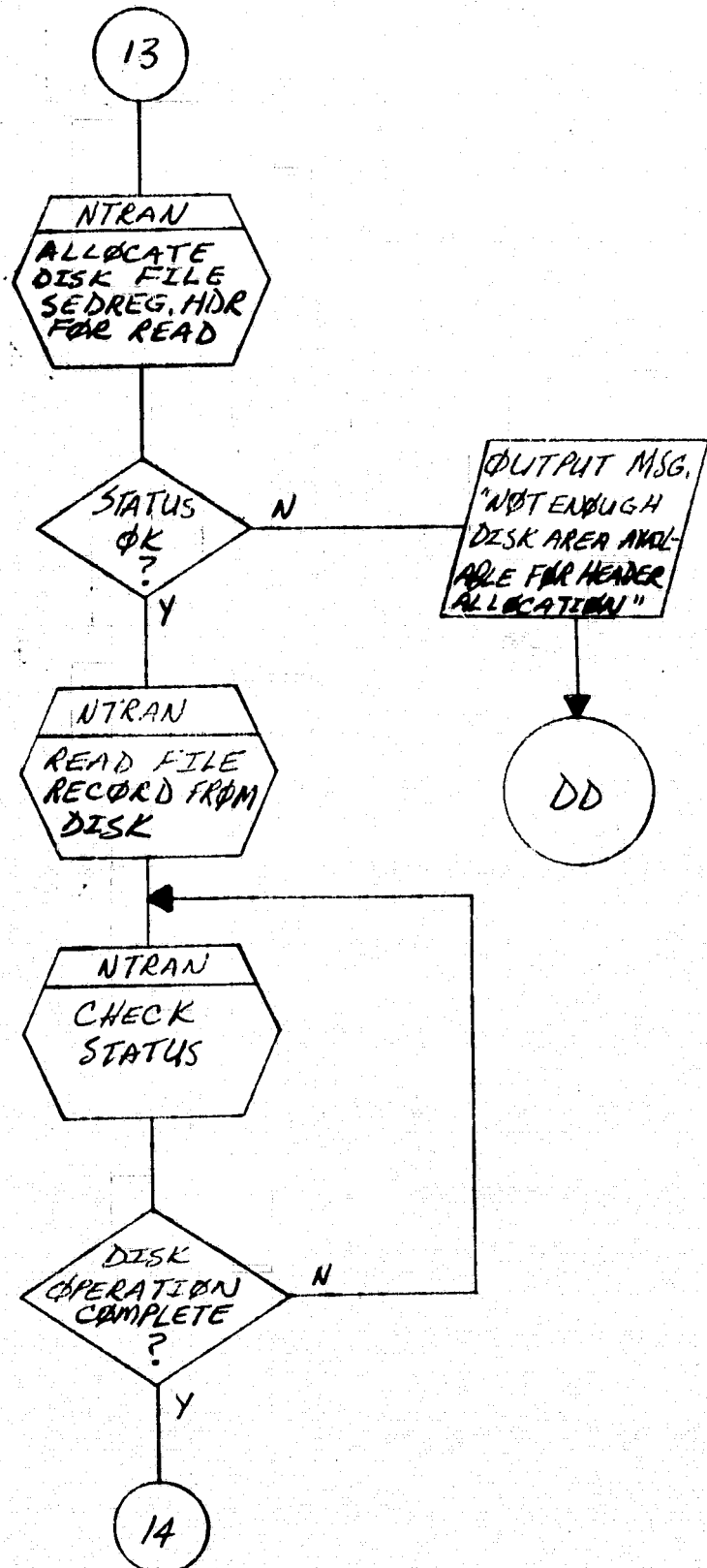


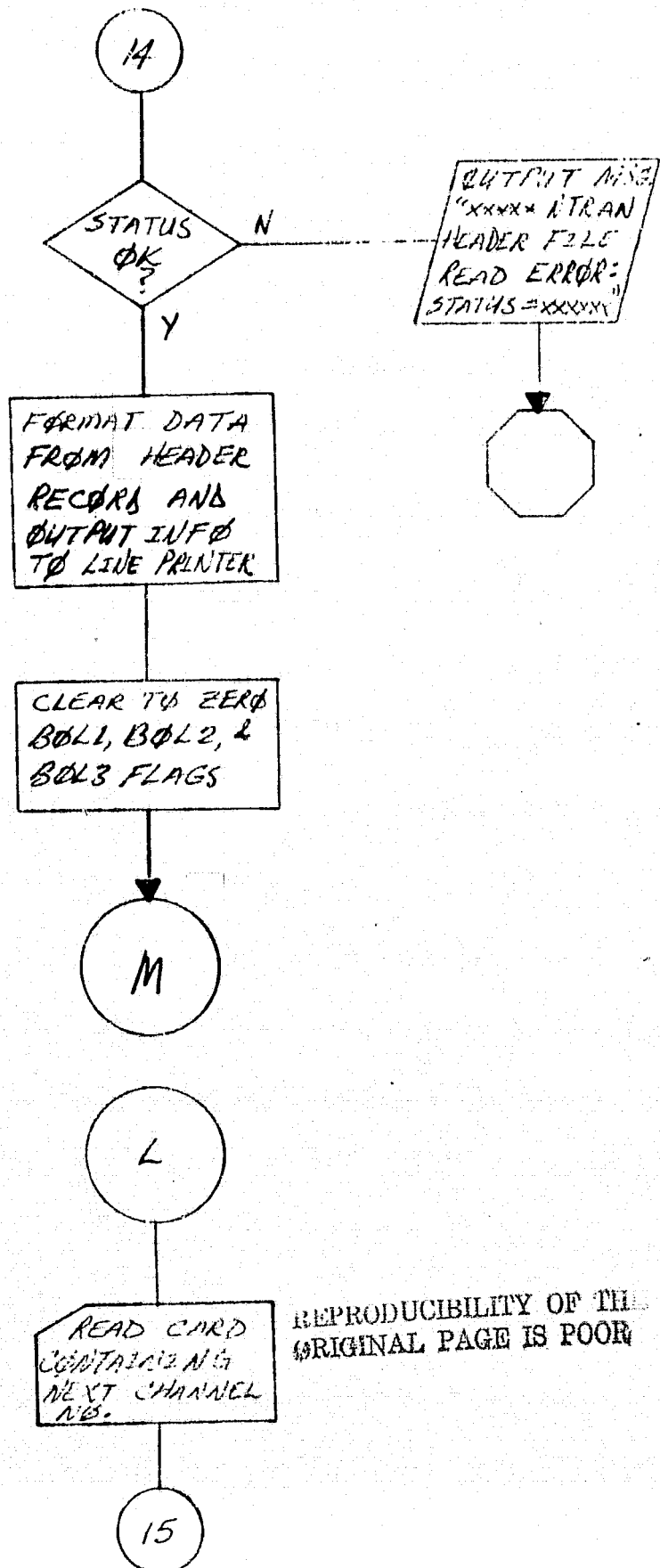




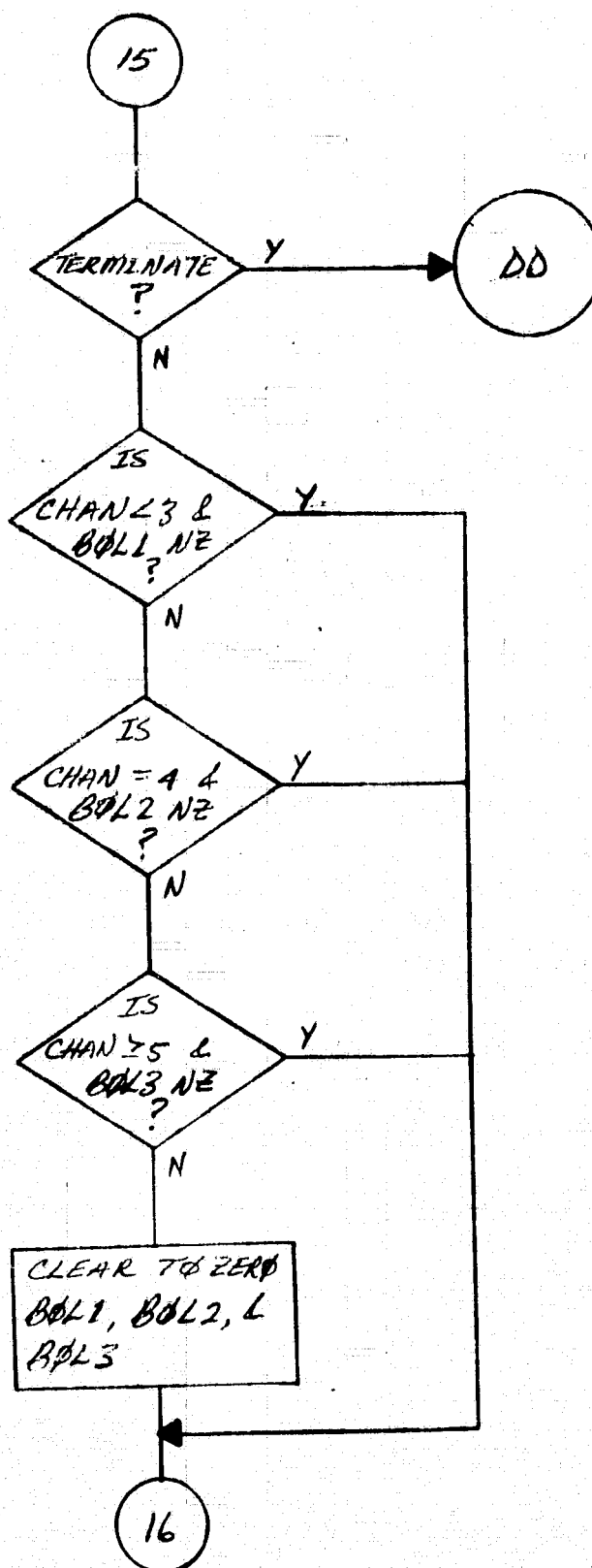




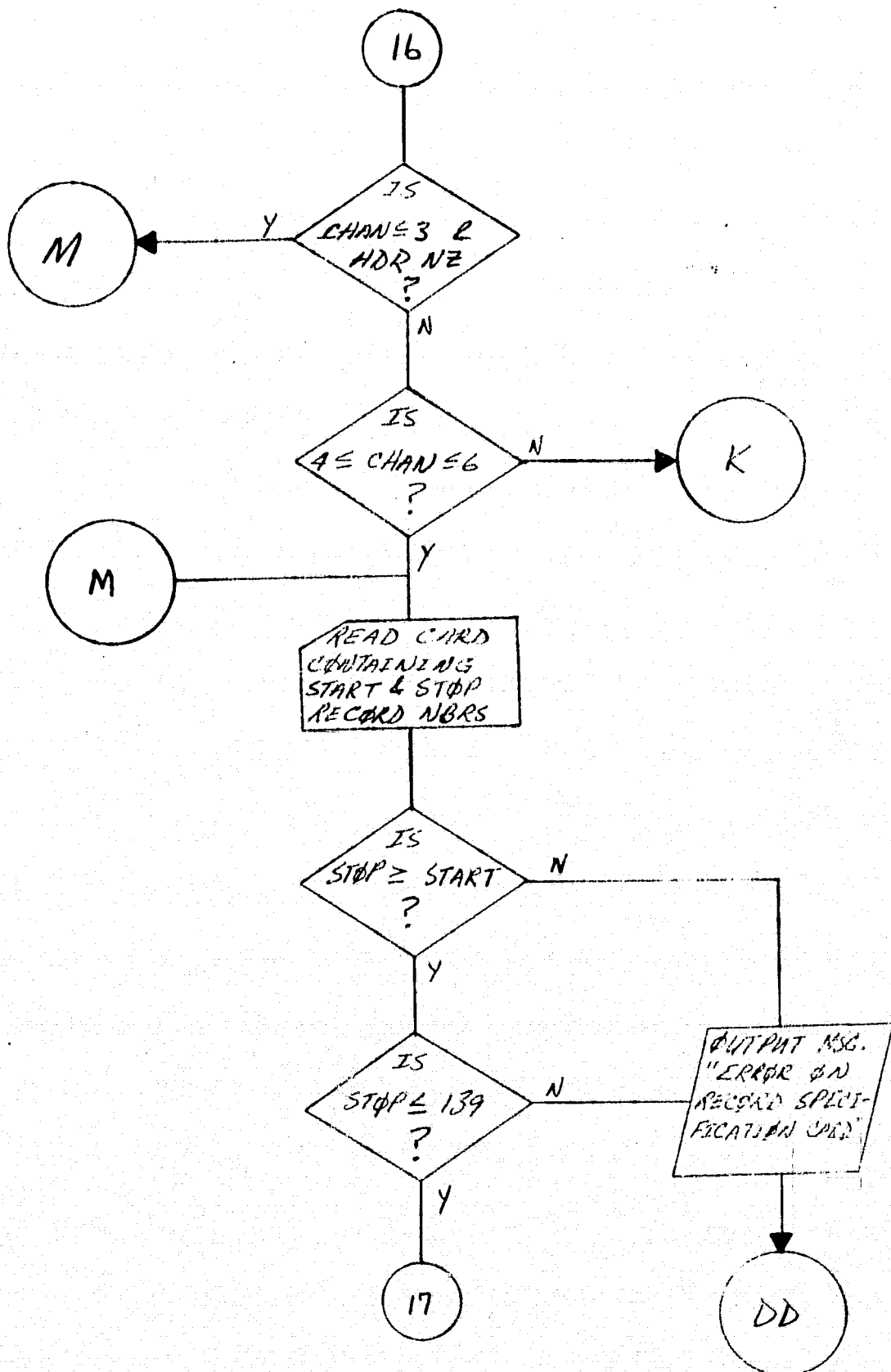


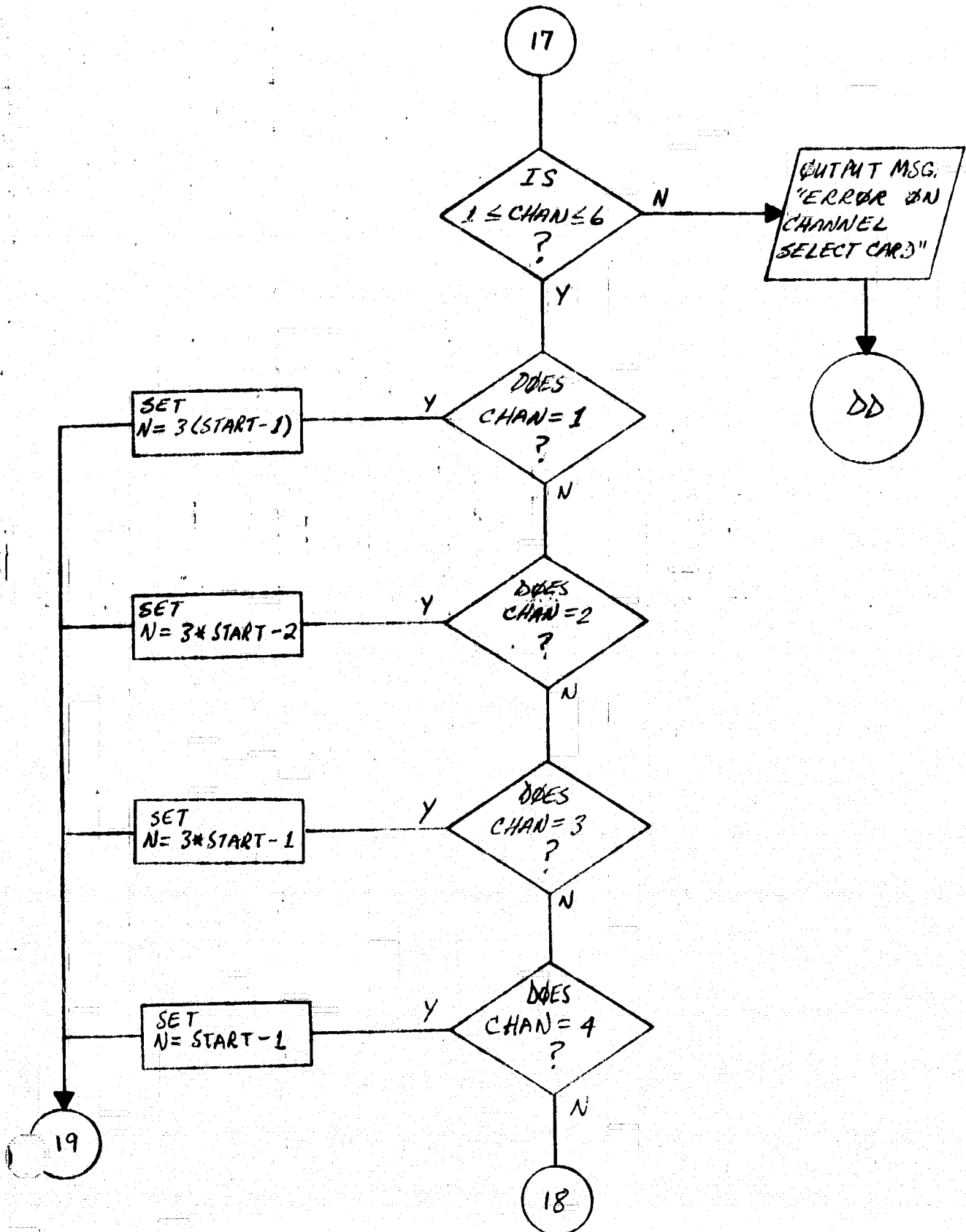


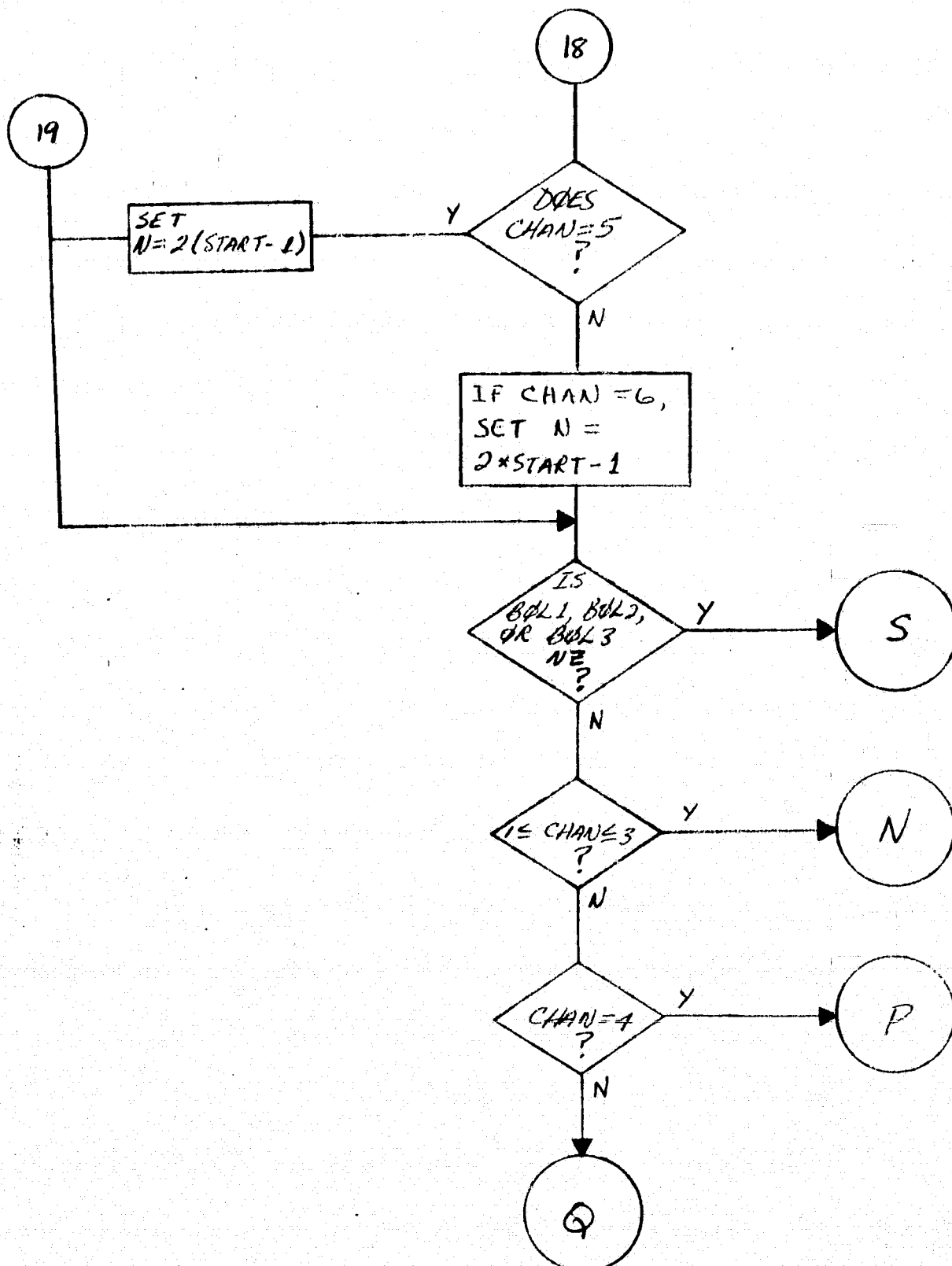
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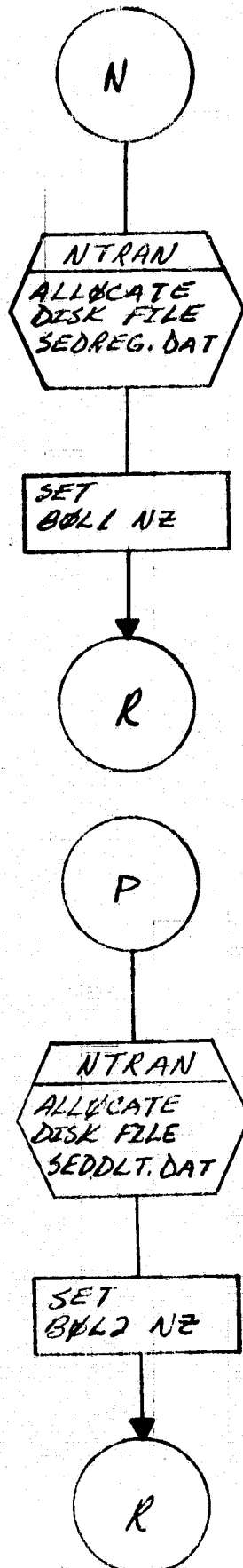


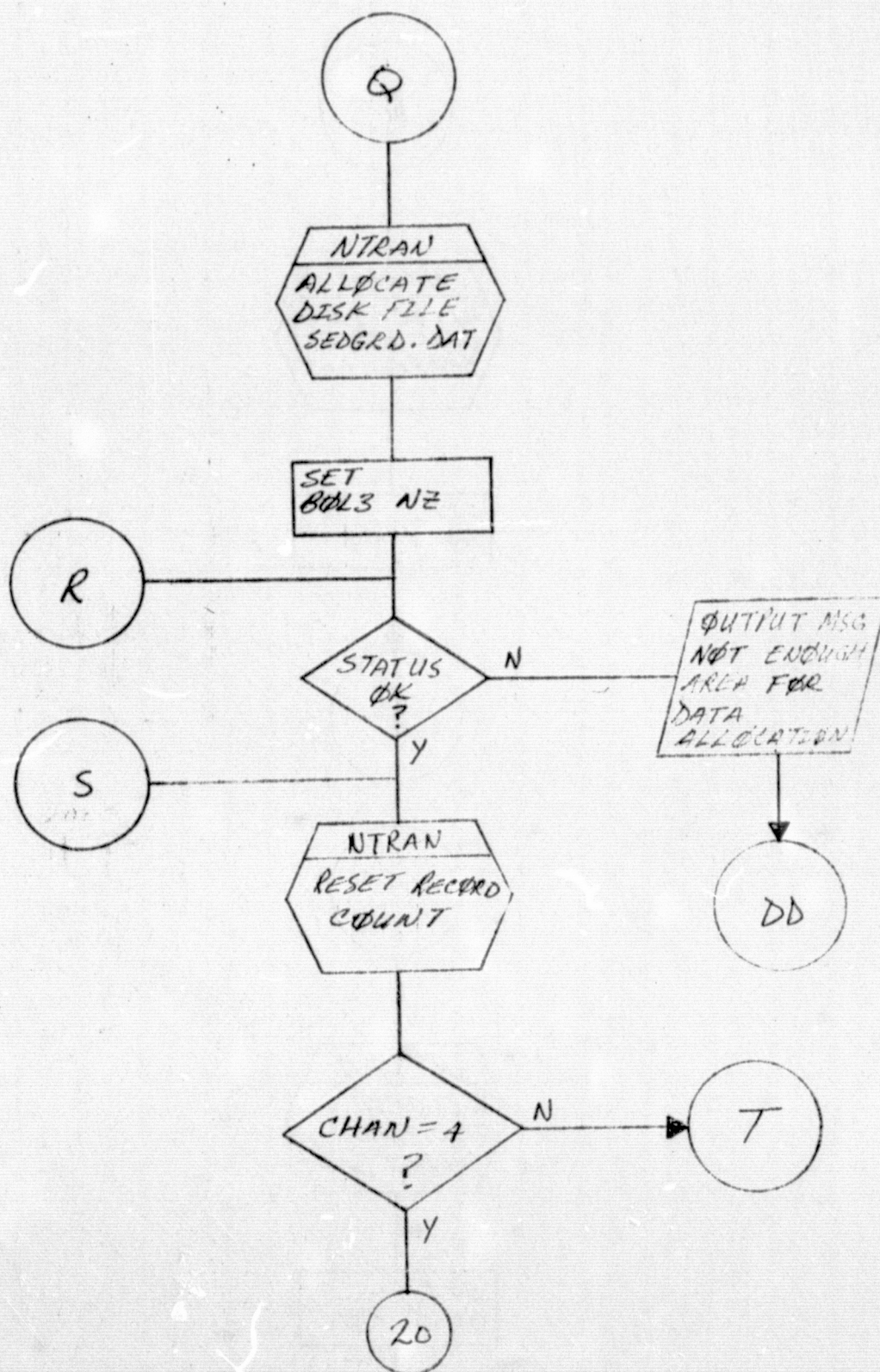




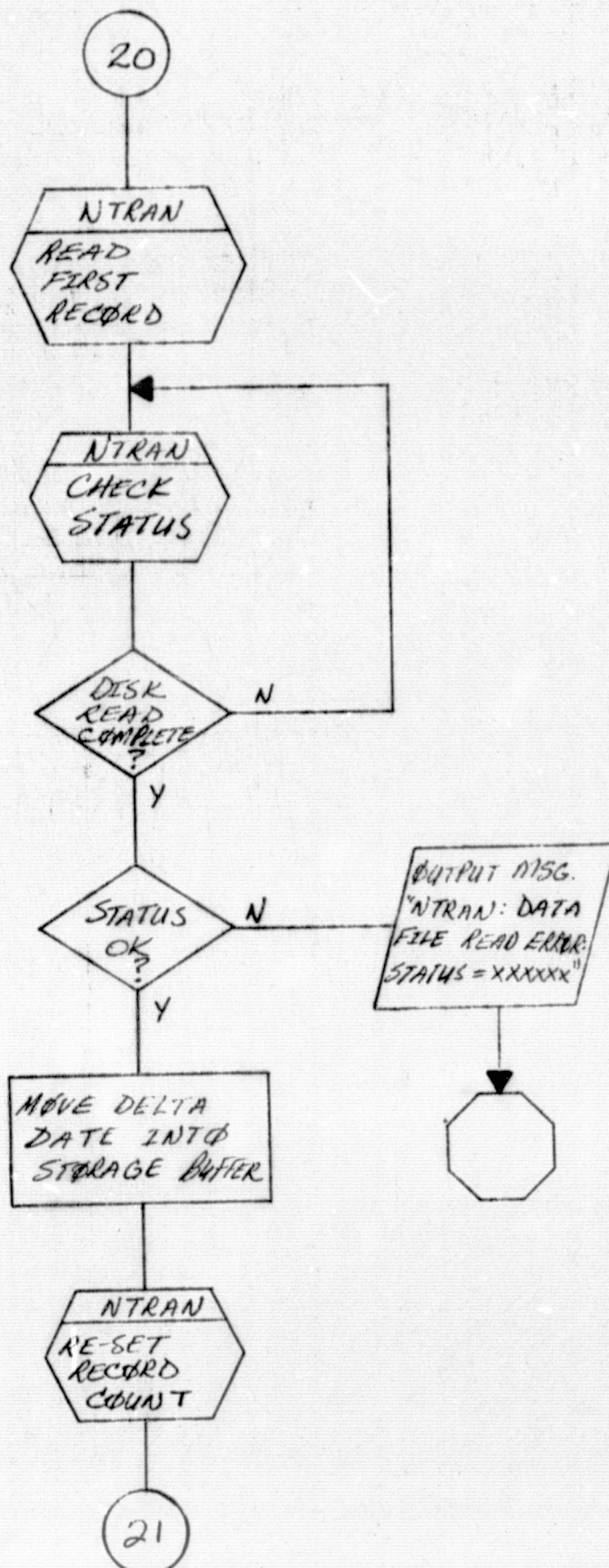




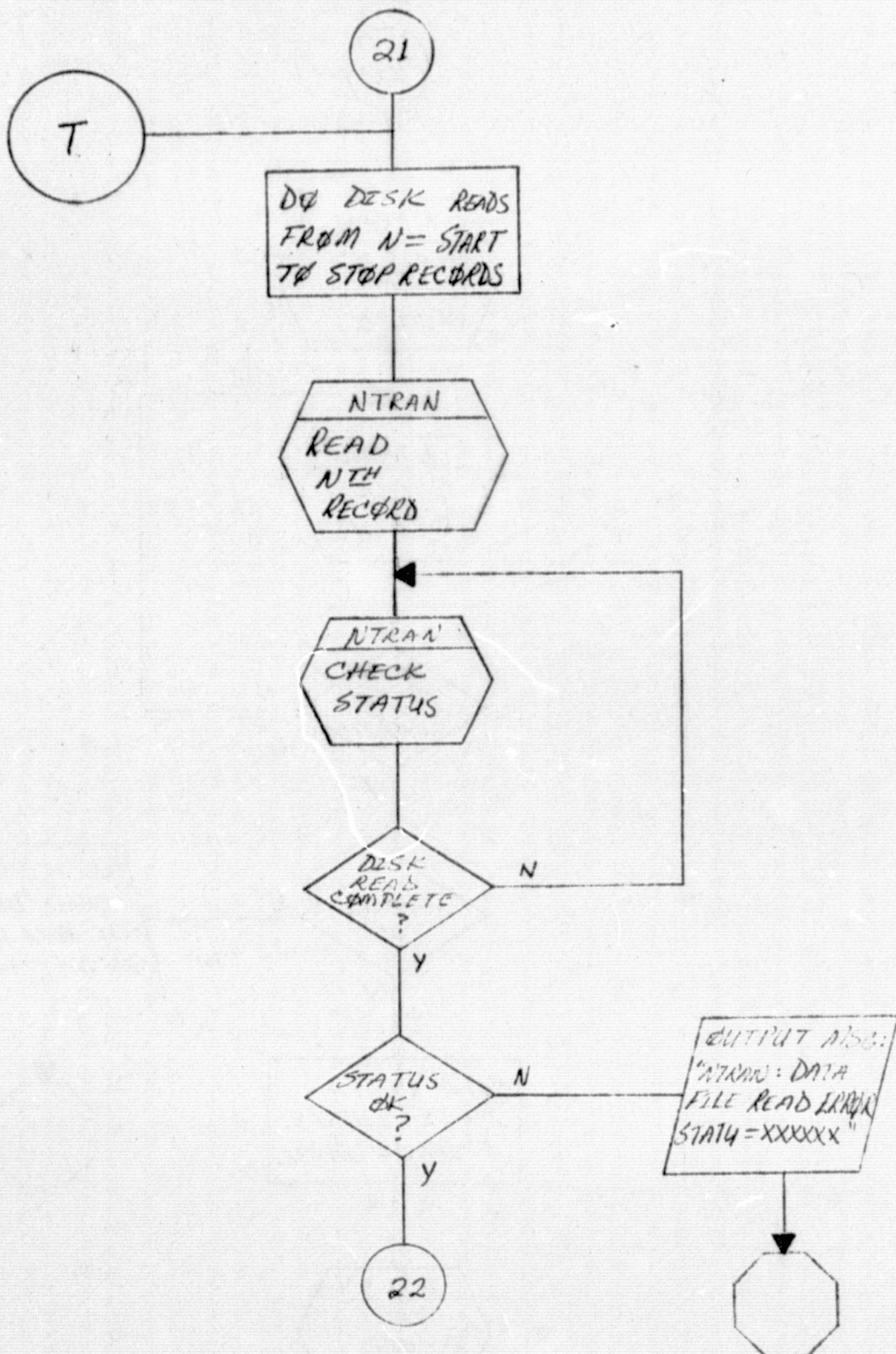


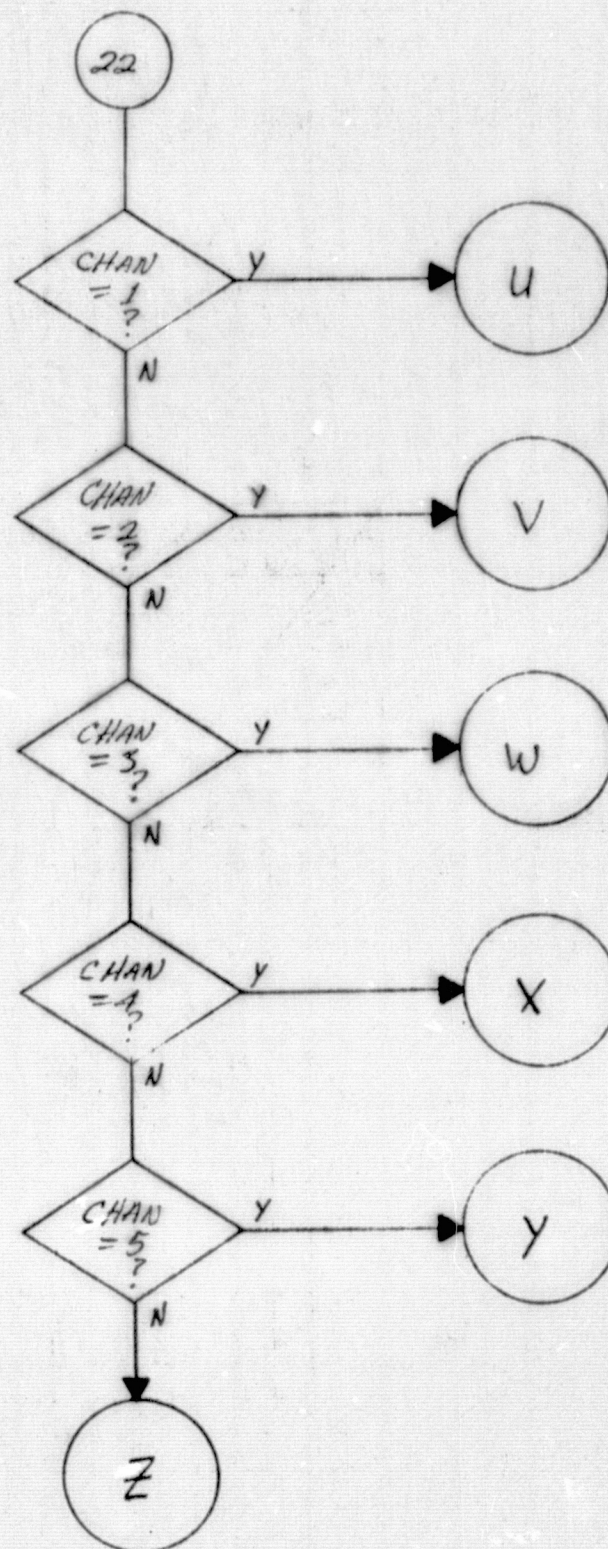


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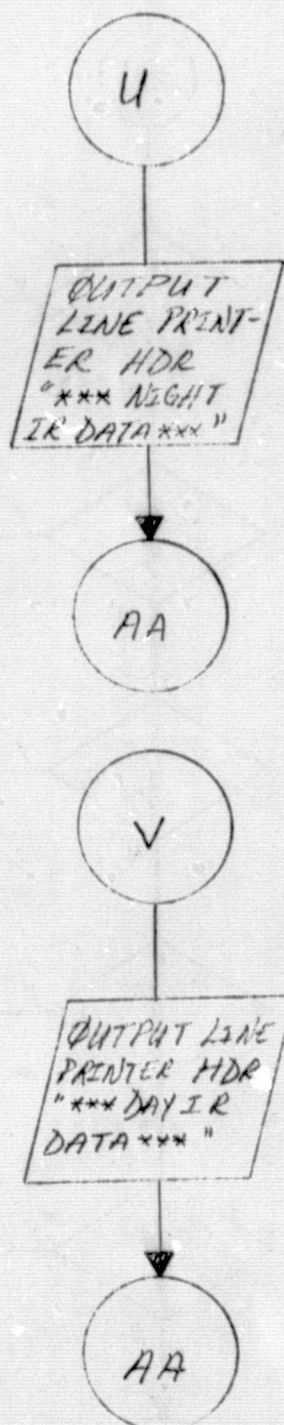




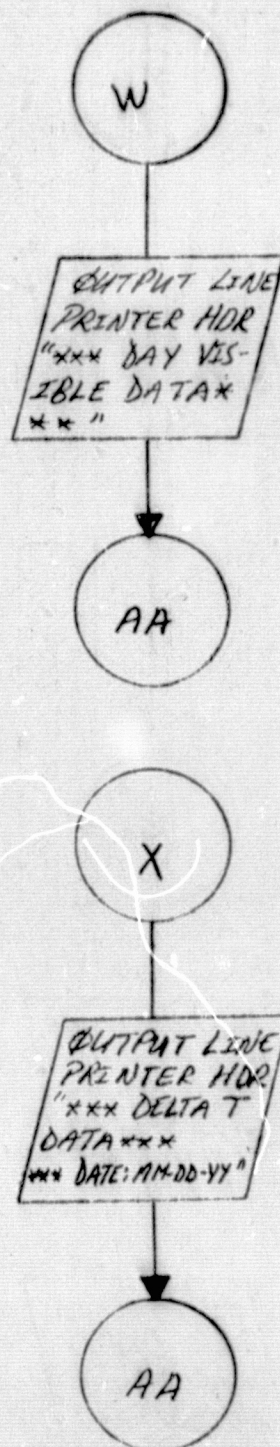




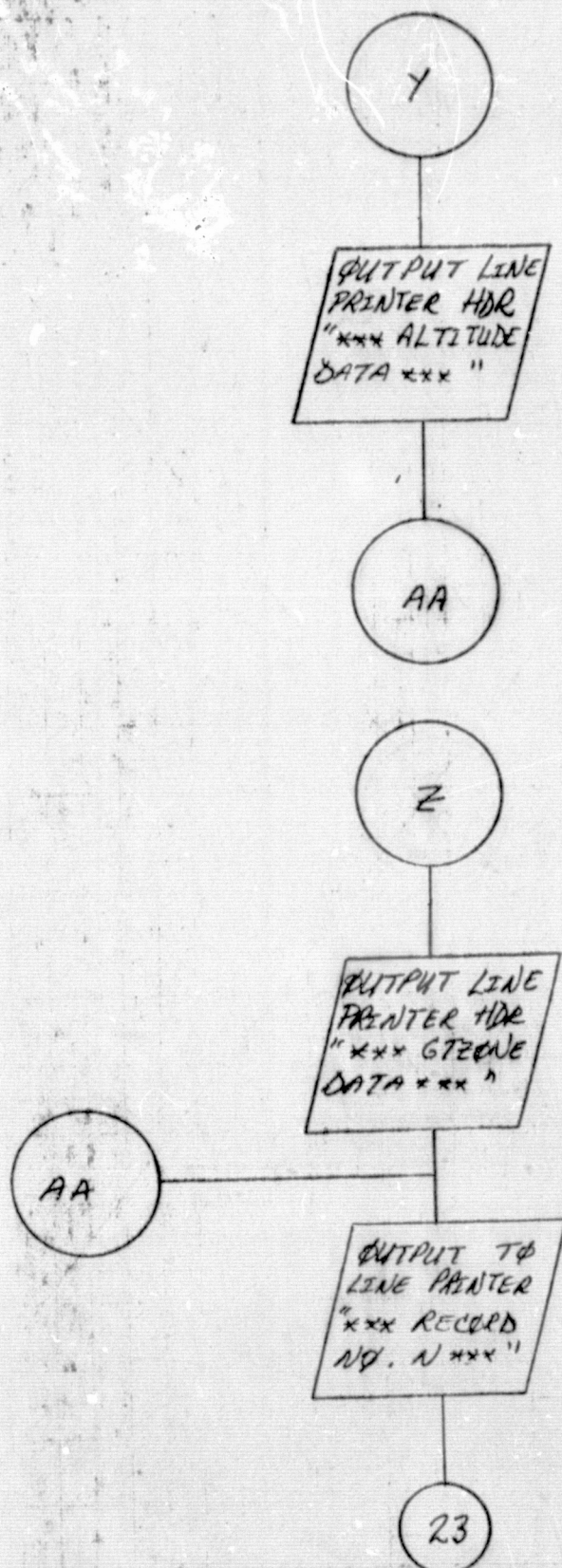


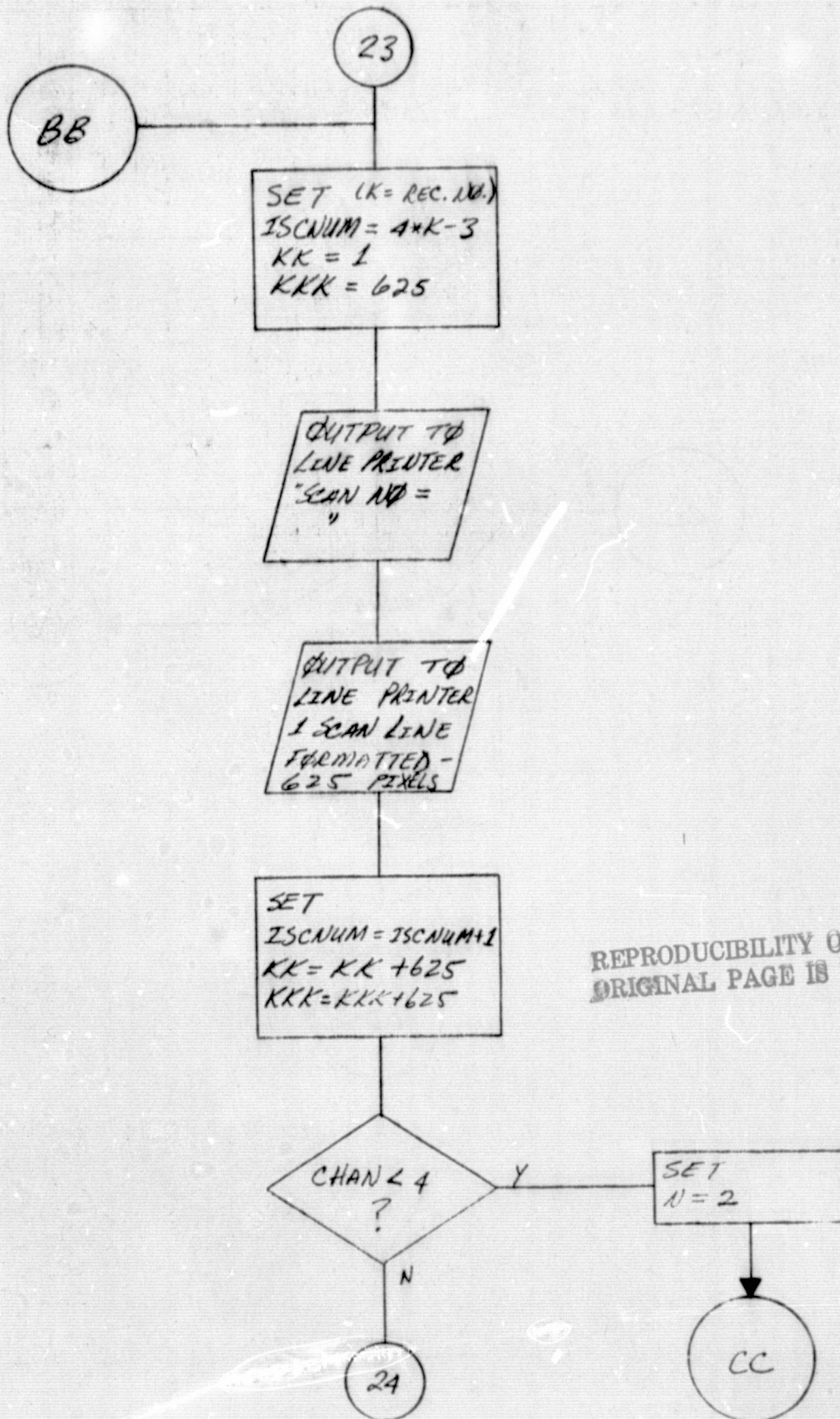


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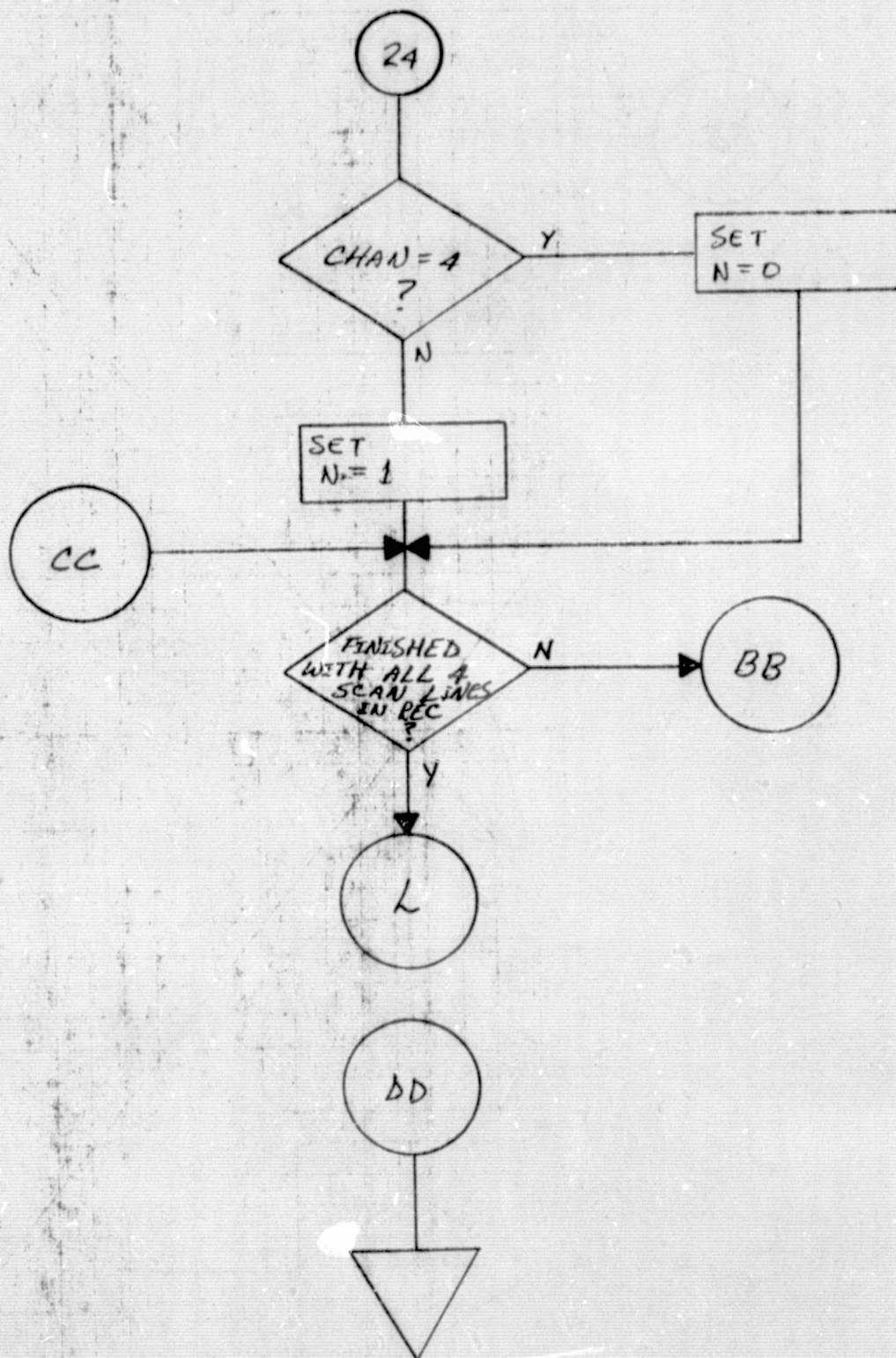


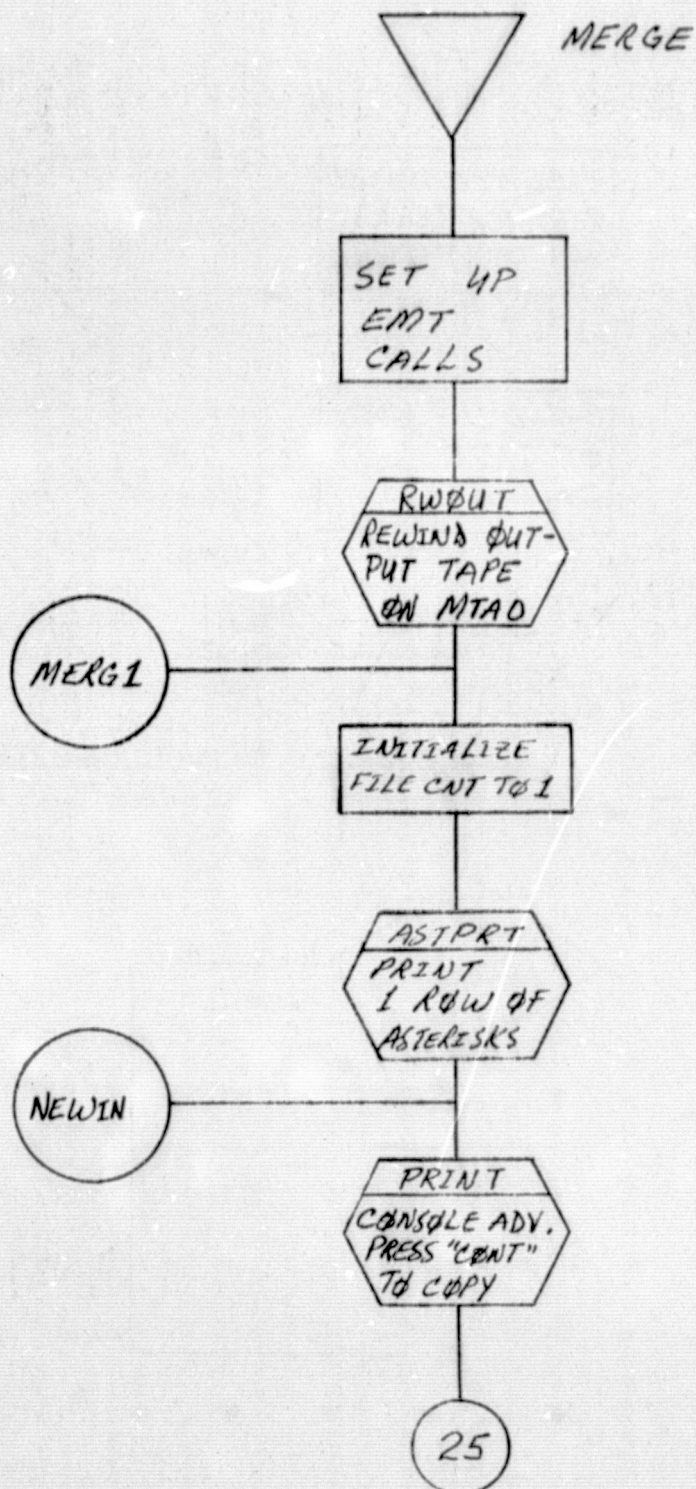




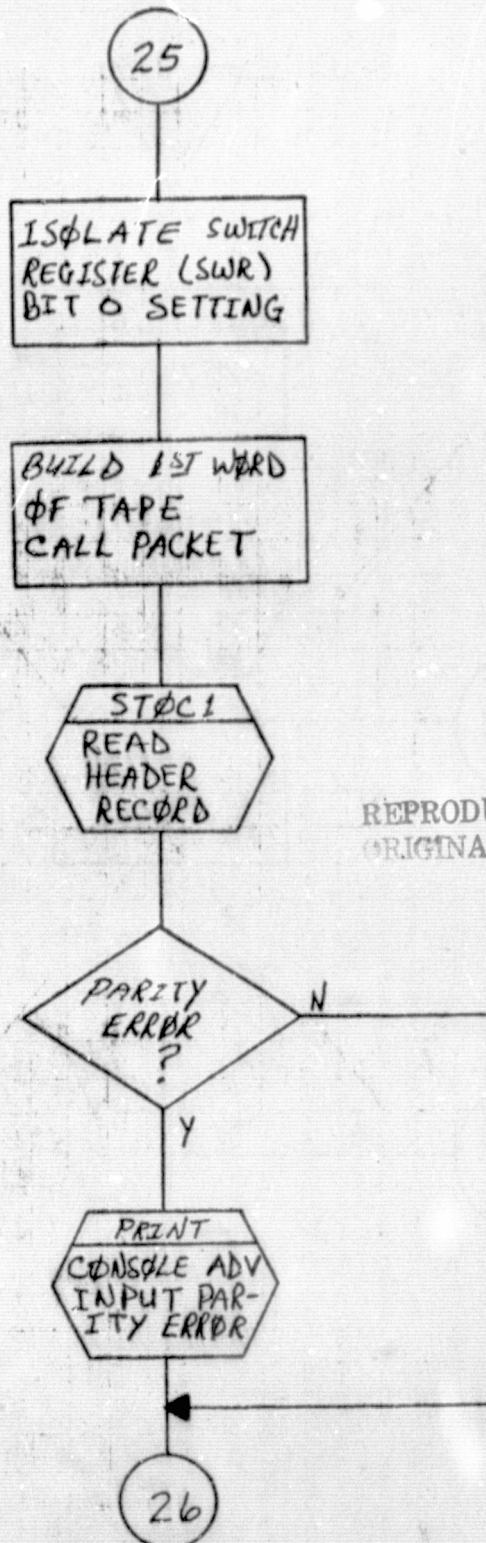
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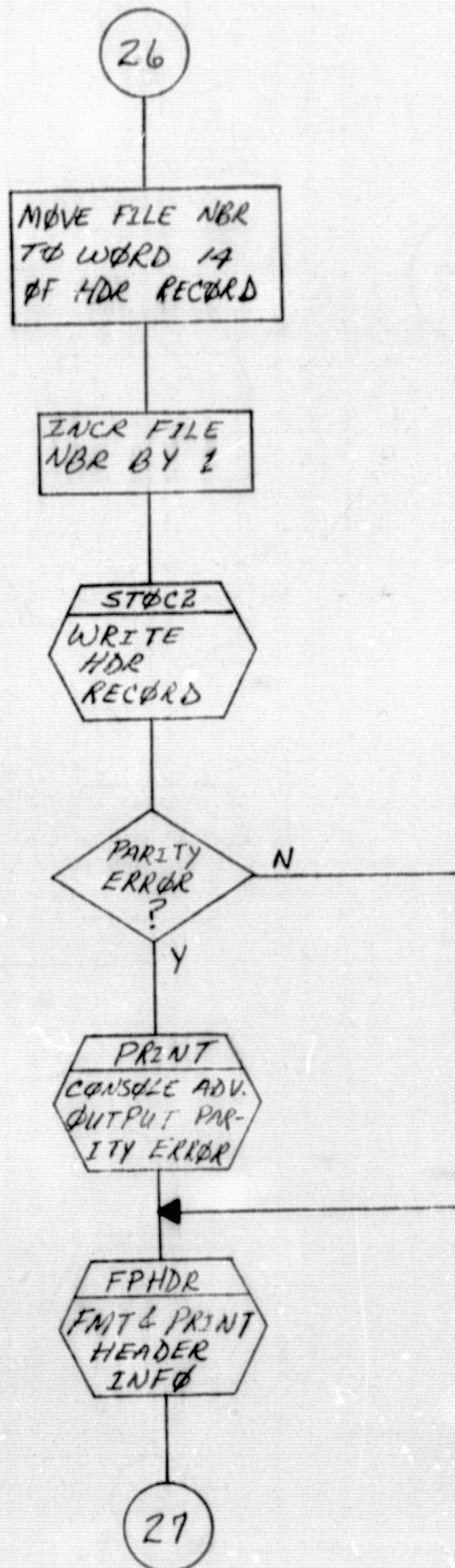




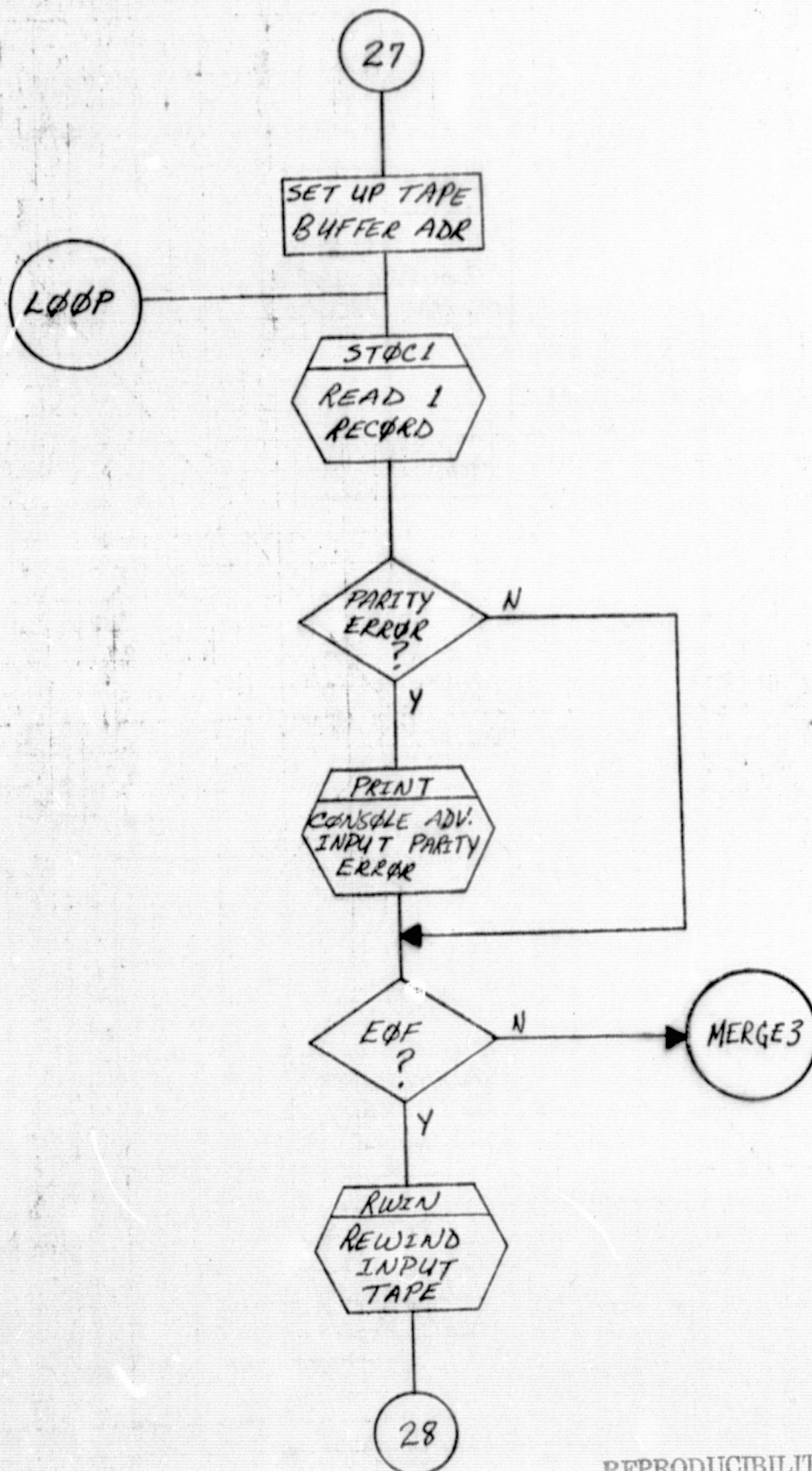


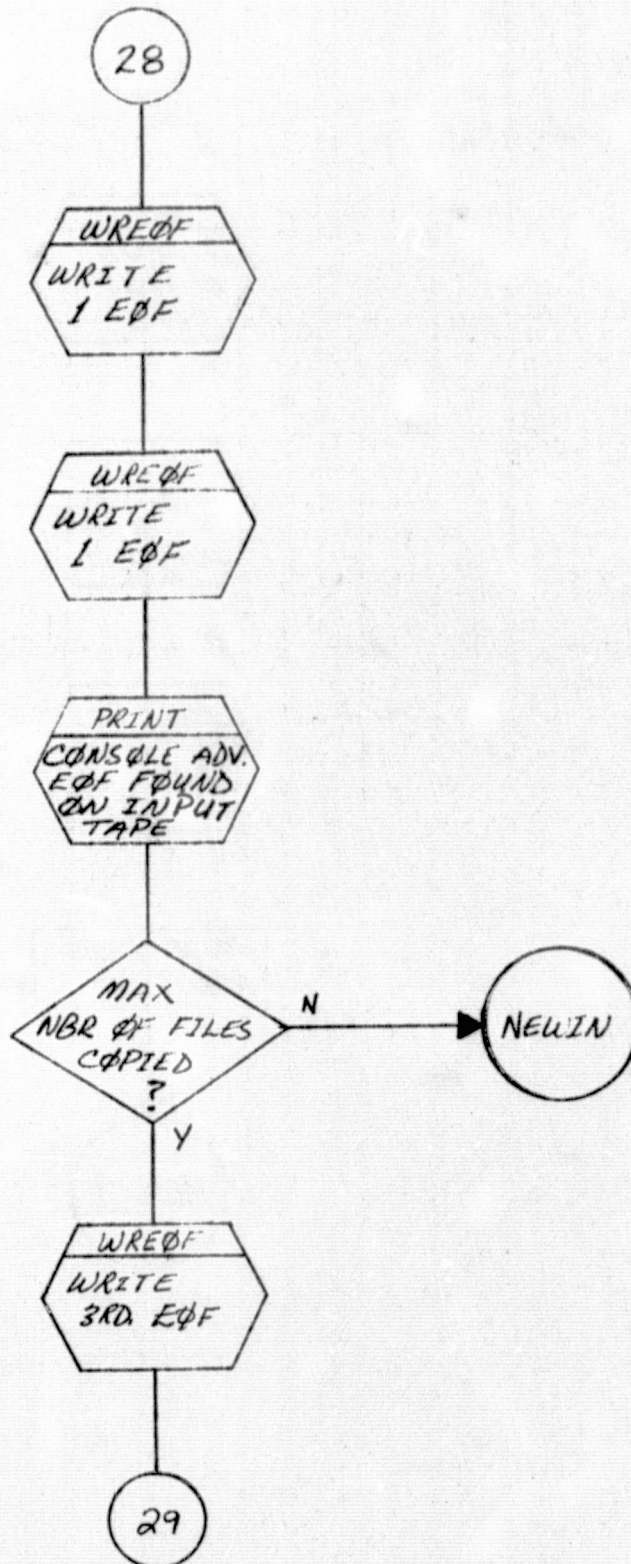


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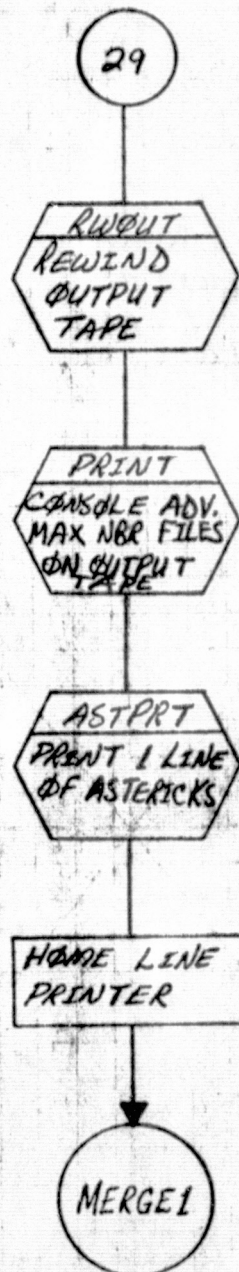


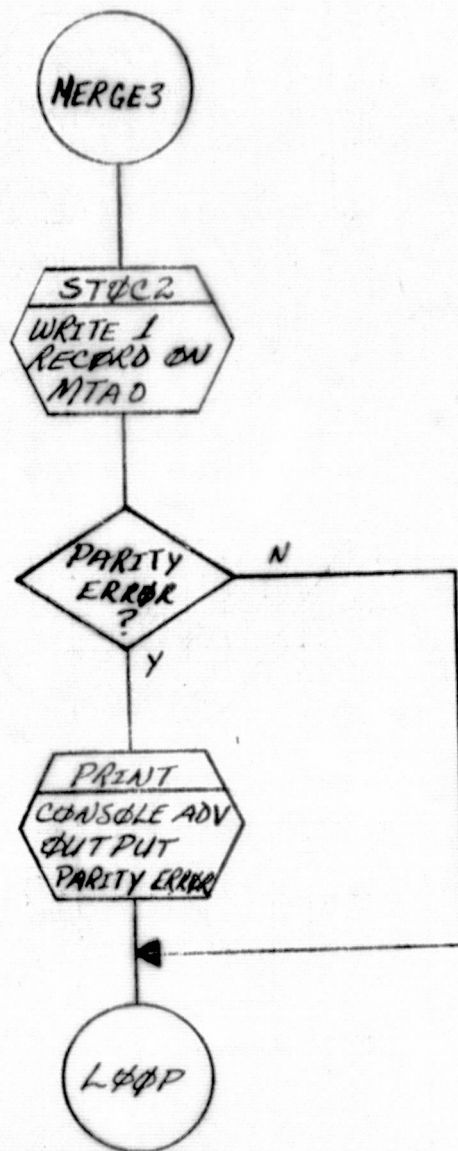










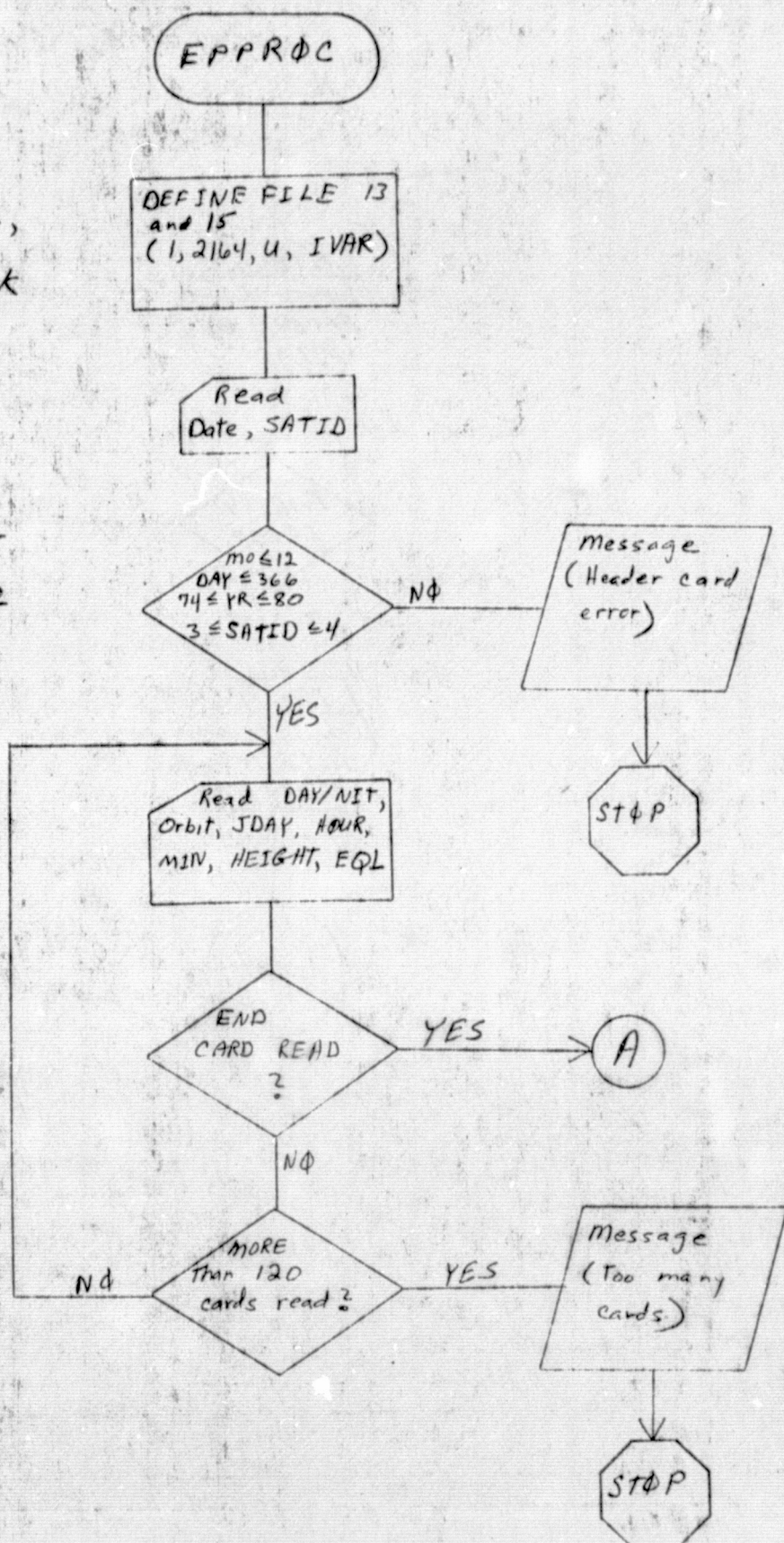


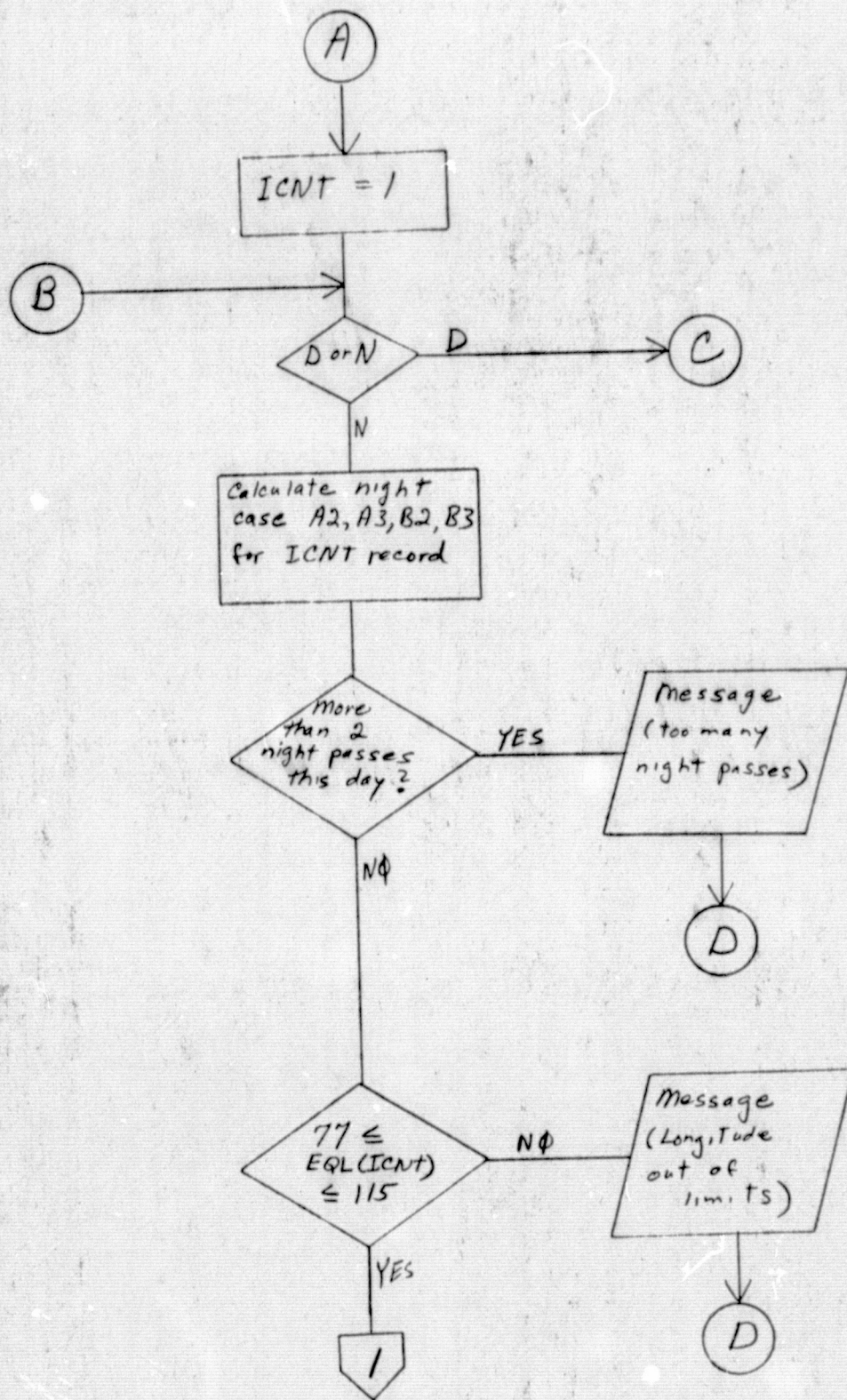


# EPPROC:

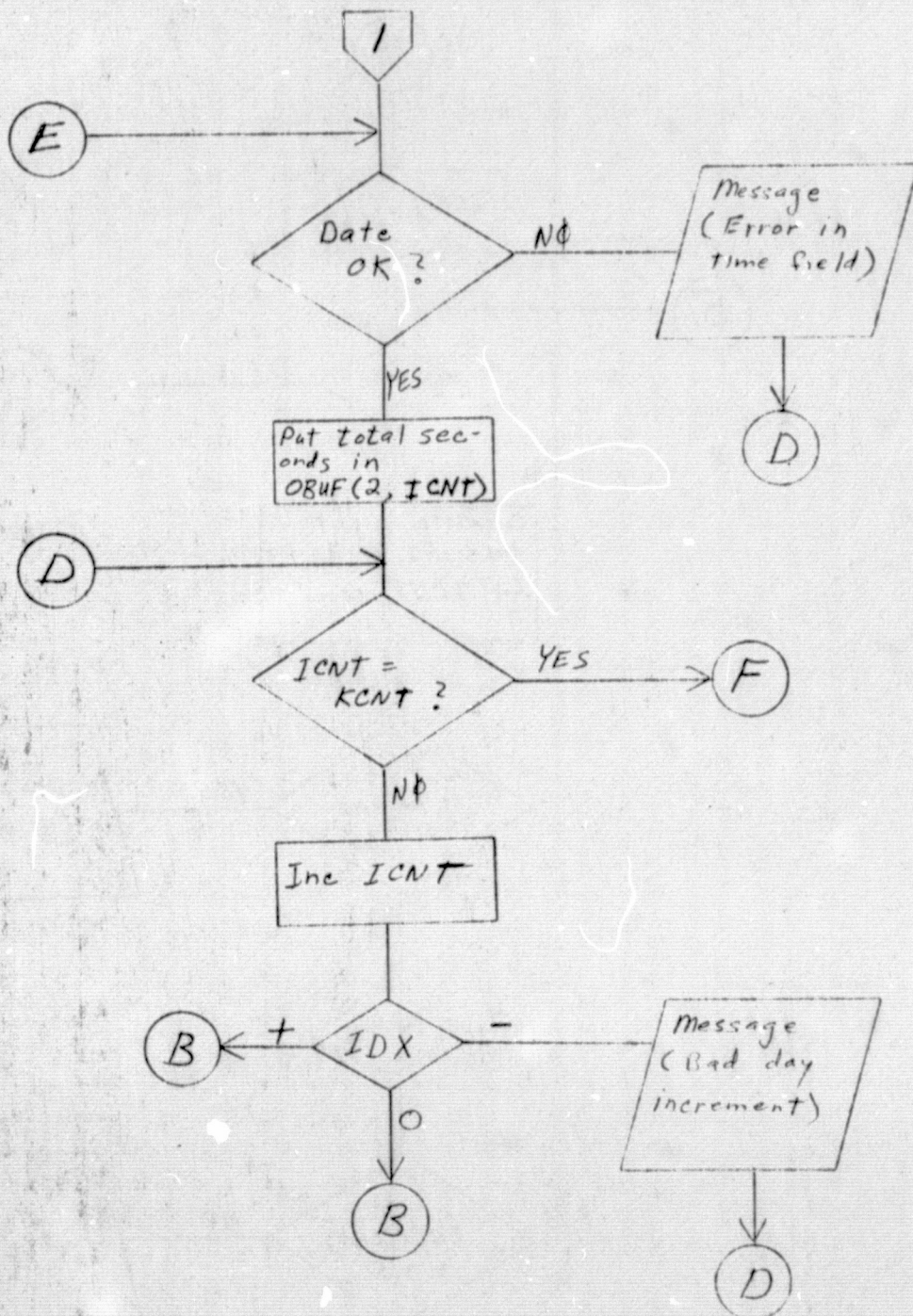
Calculates and  
Tabulates predicted  
A2, A3, B2, B3  
coefficients, start  
and stop tape time,  
start and stop  
pixel. Builds disk  
file.

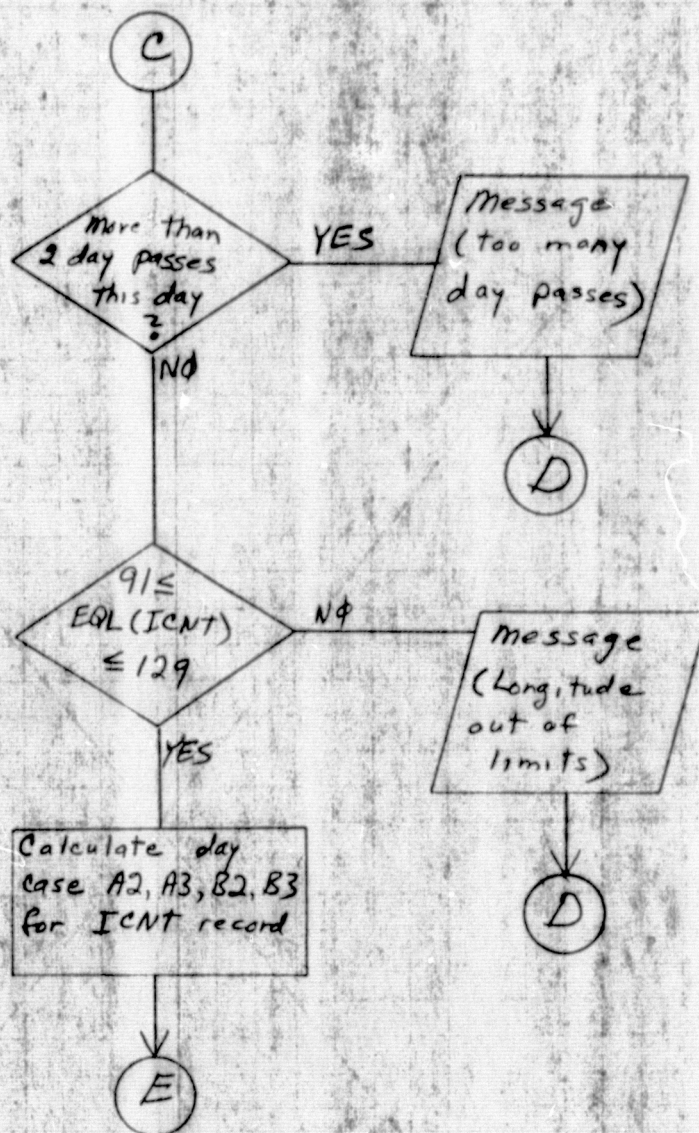
SATID = satellite ID  
ICNT = record counter  
KCNT = total number  
of records  
 $IDX = JDAY(ICNT) - JDAY(ICNT - 1)$   
EQL = Longitude of  
equator crossing





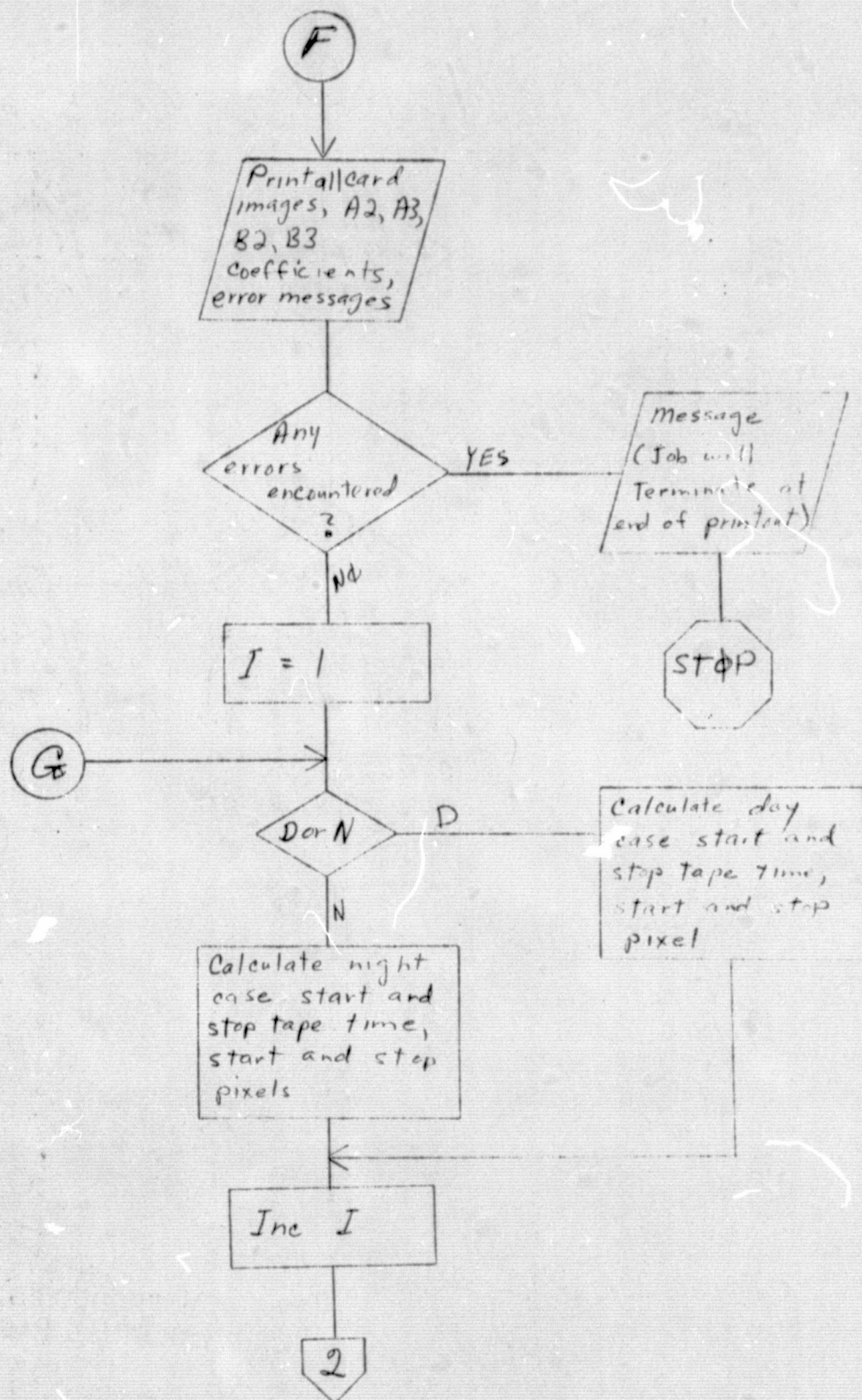




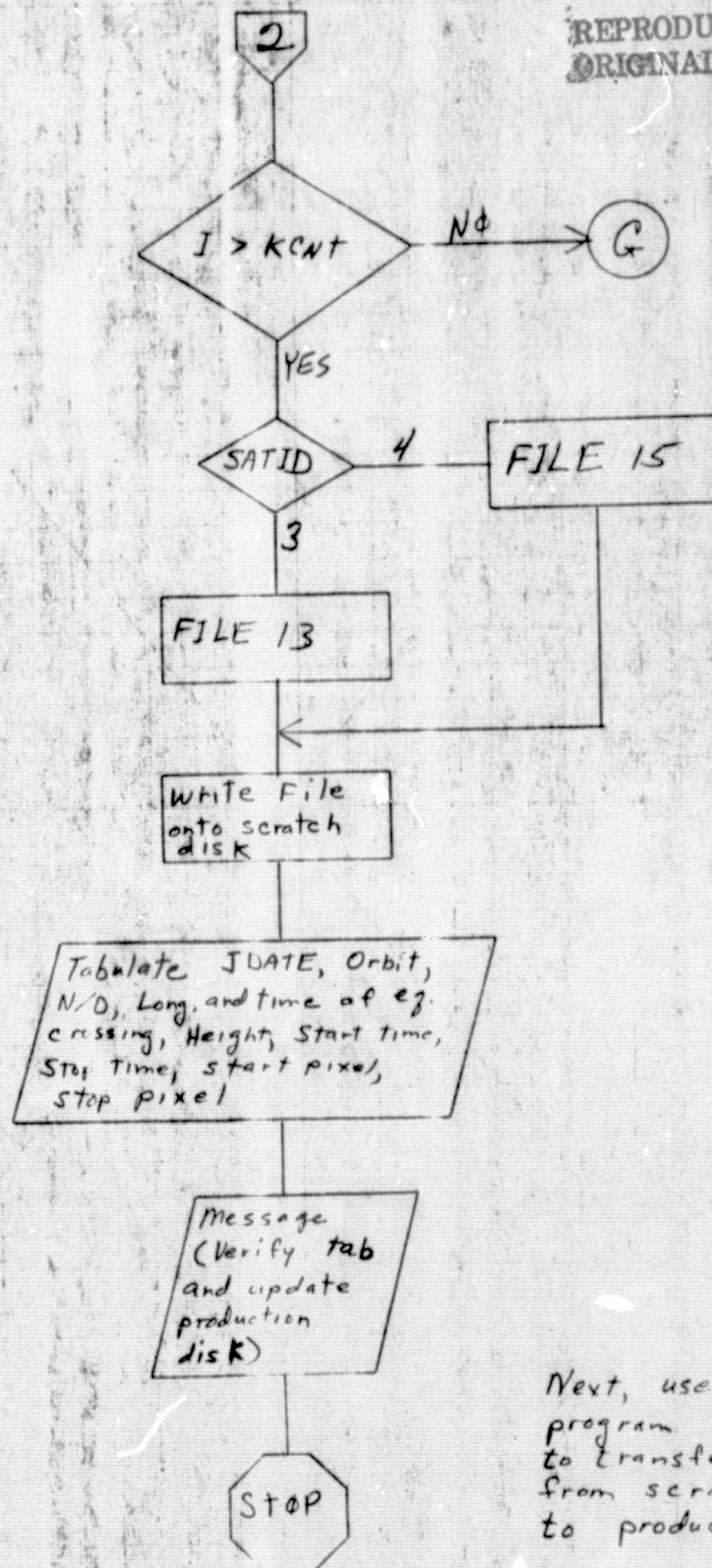


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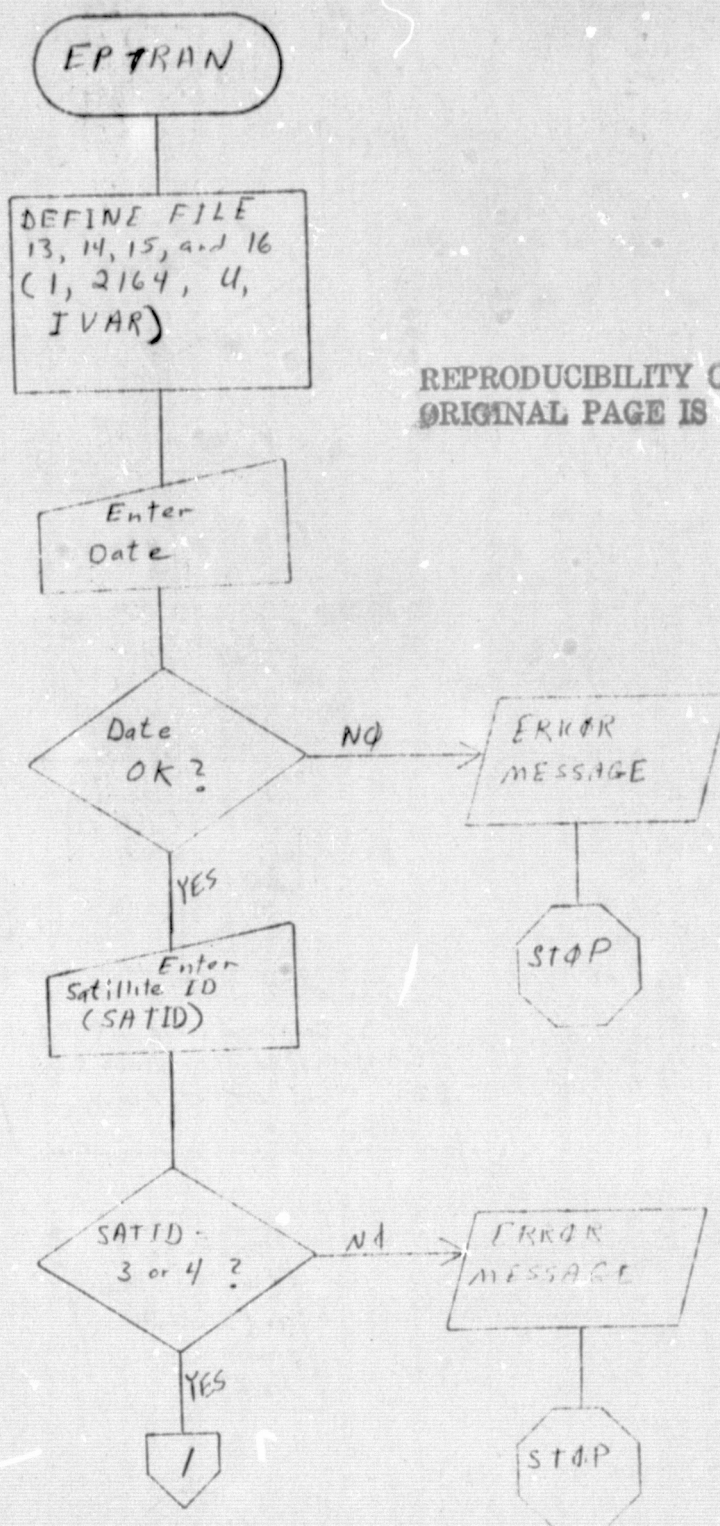


Next, use offline  
program EPTRIN  
to transfer file  
from scratch disk  
to production disk.

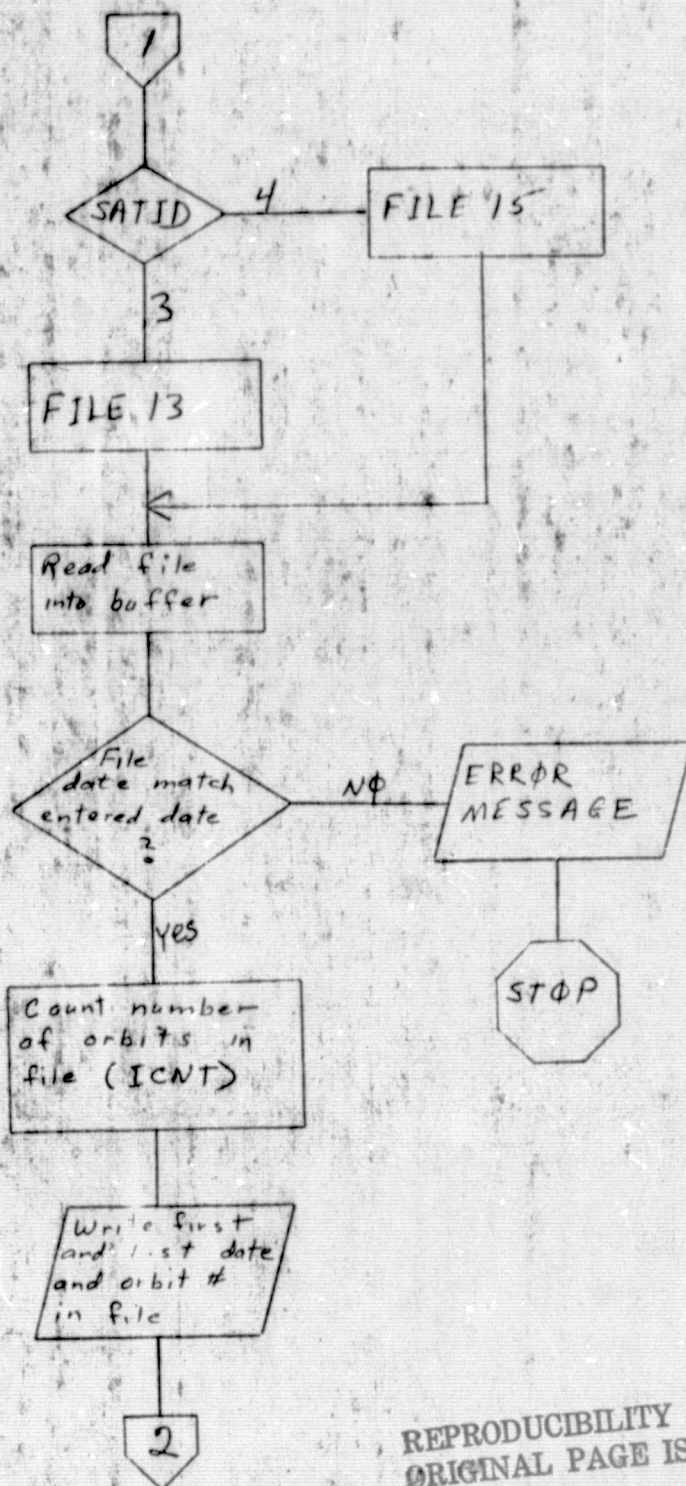


Transfers Ephemeris  
file built by EPPROC  
from scratch disk to  
production disk.

Information in file for  
each card entry:  
Date, Orbit, N/D,  
Long & time of Equator  
Crossing, Height,  
Calculated tape start and  
stop times, start and  
stop pixels.

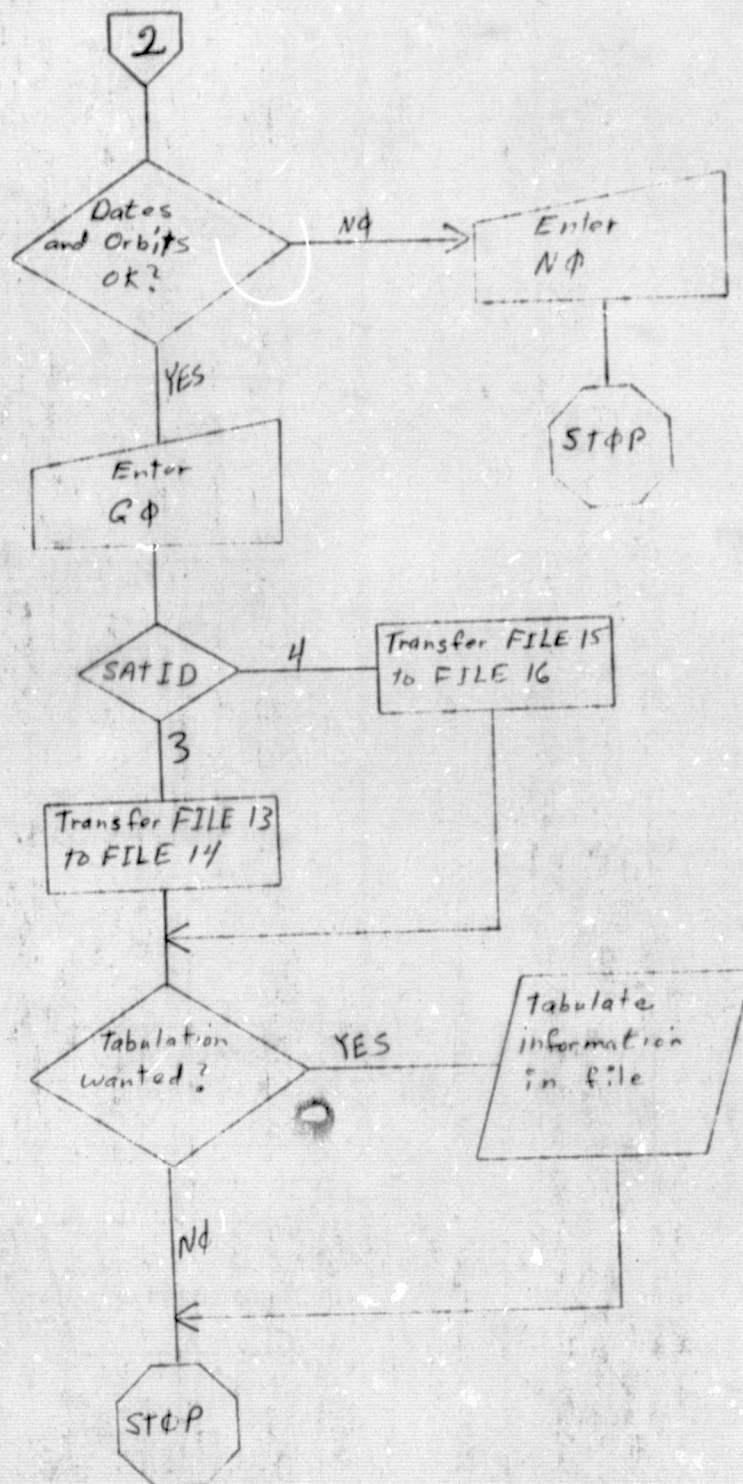


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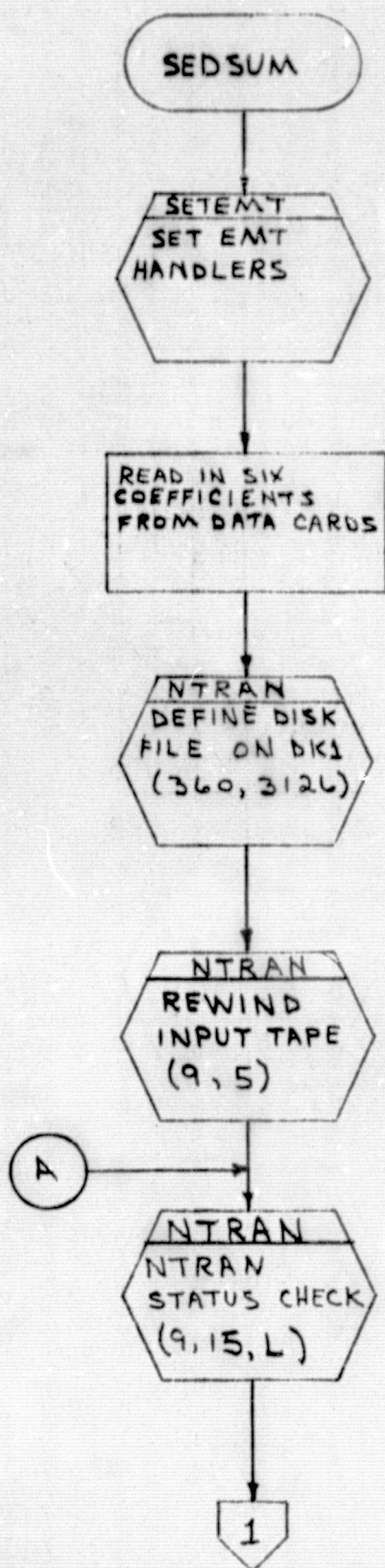


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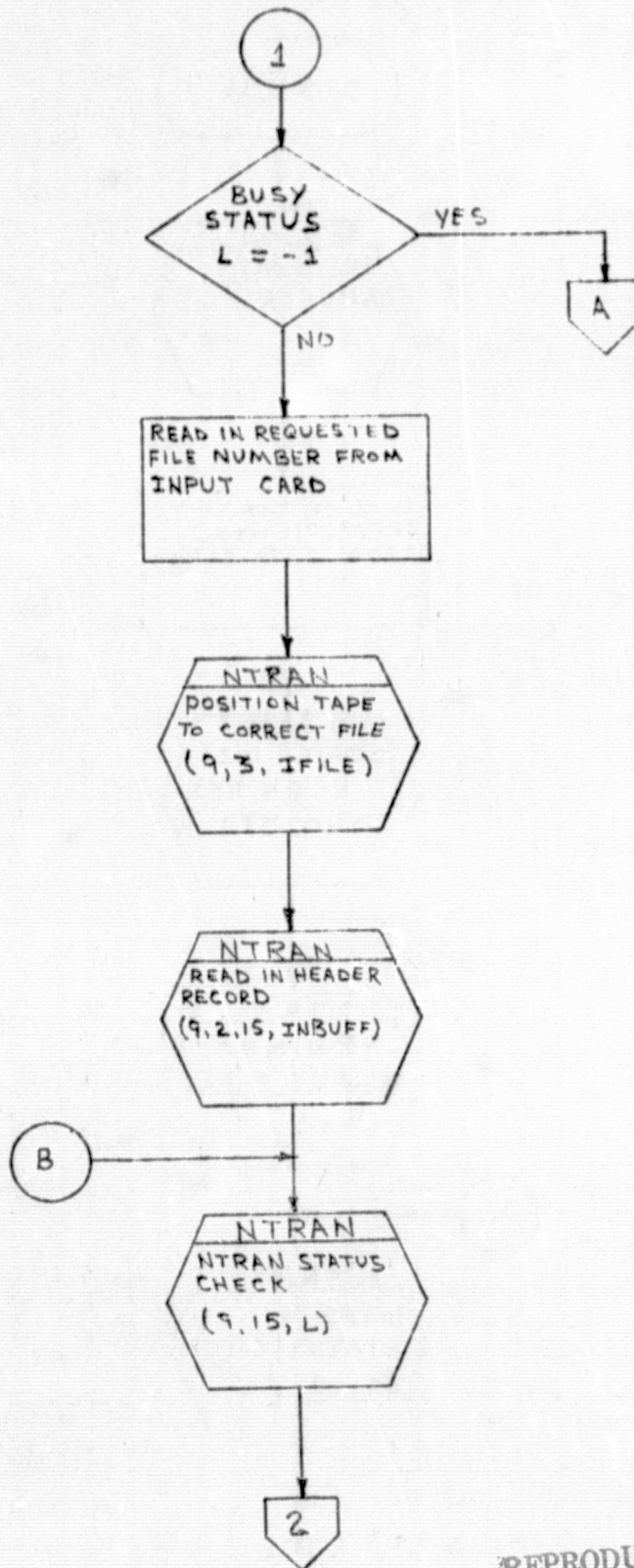


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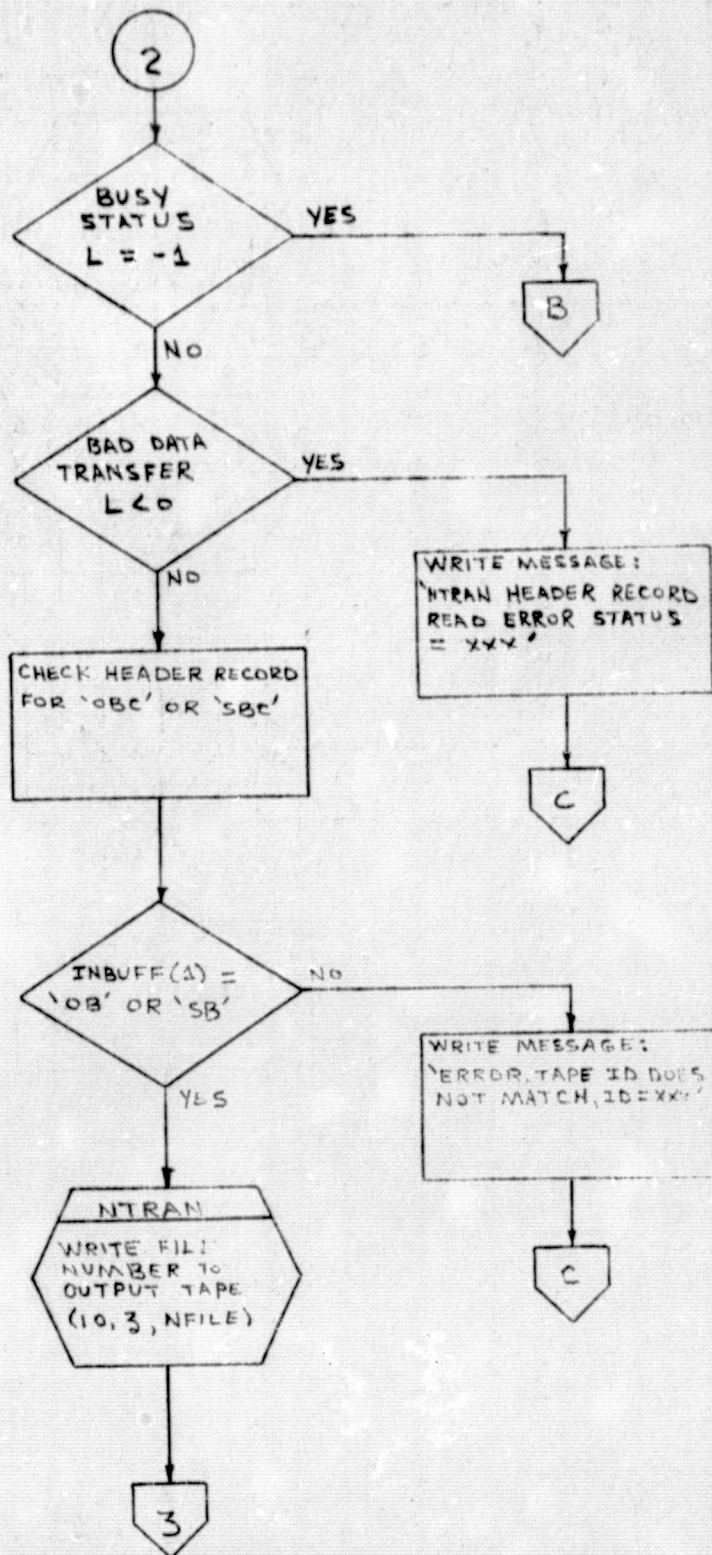


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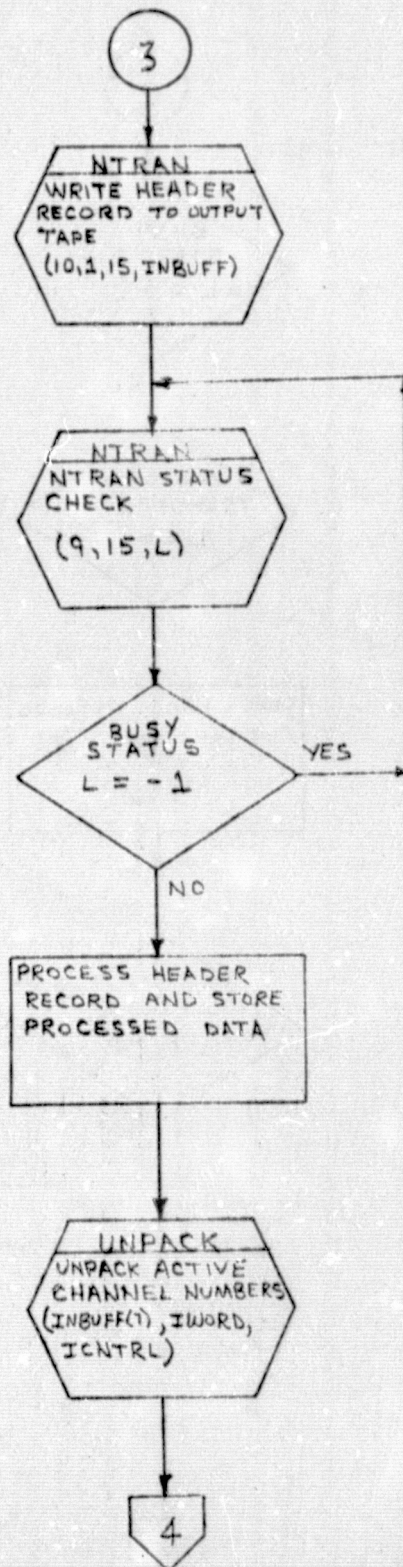


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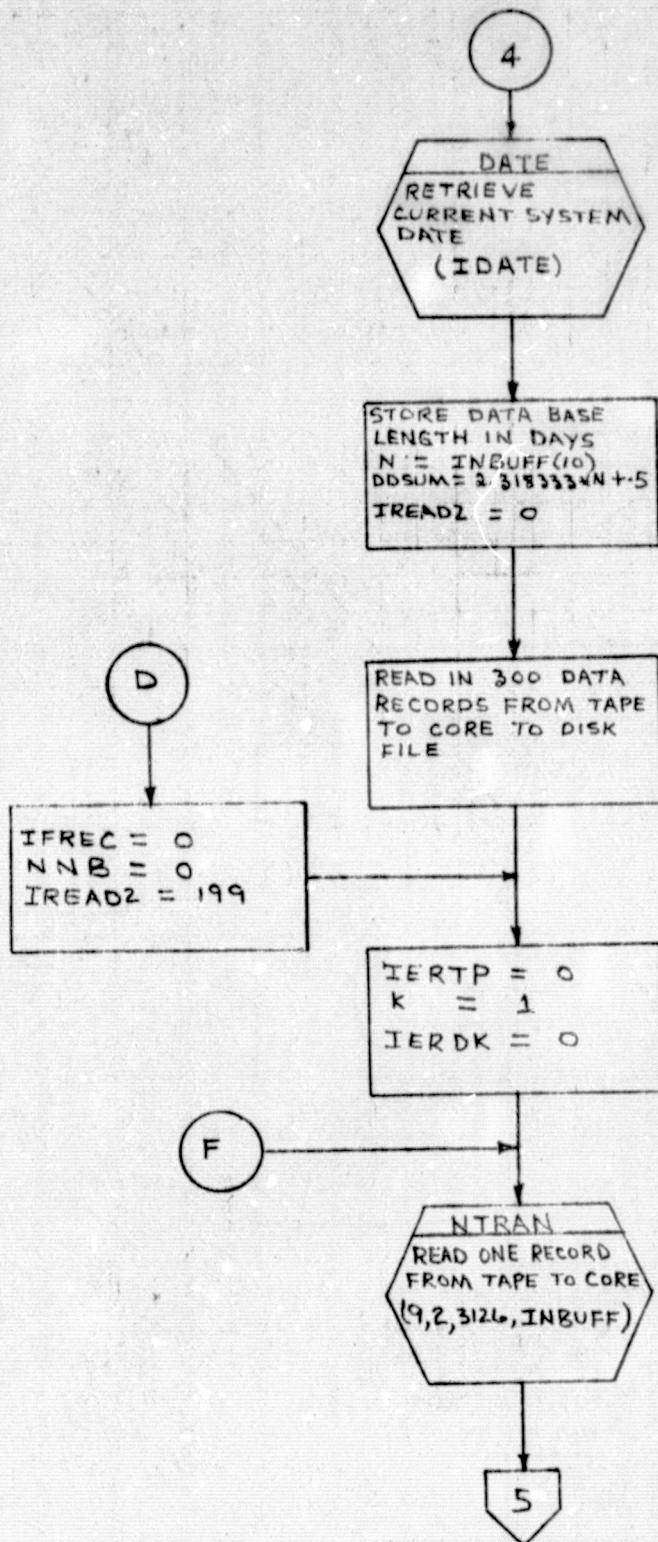


ORIGINAL PAGE IS  
OF POOR QUALITY

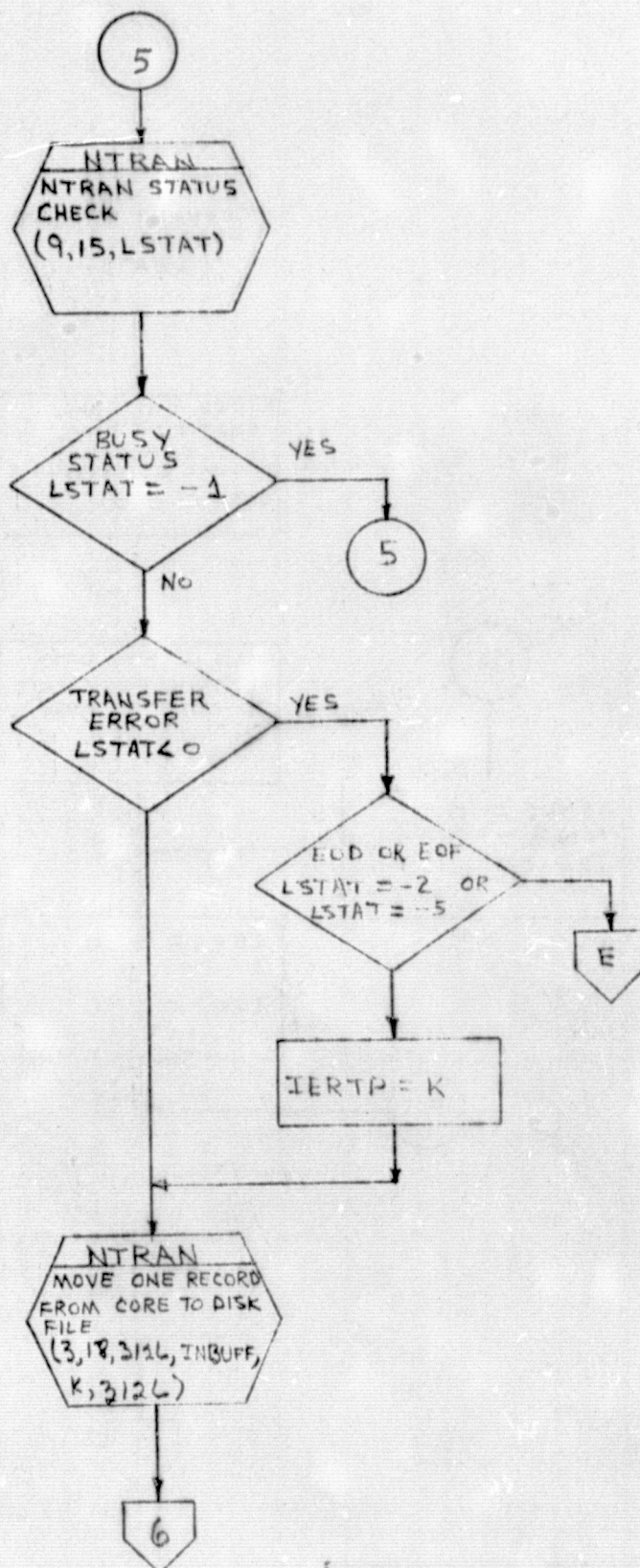




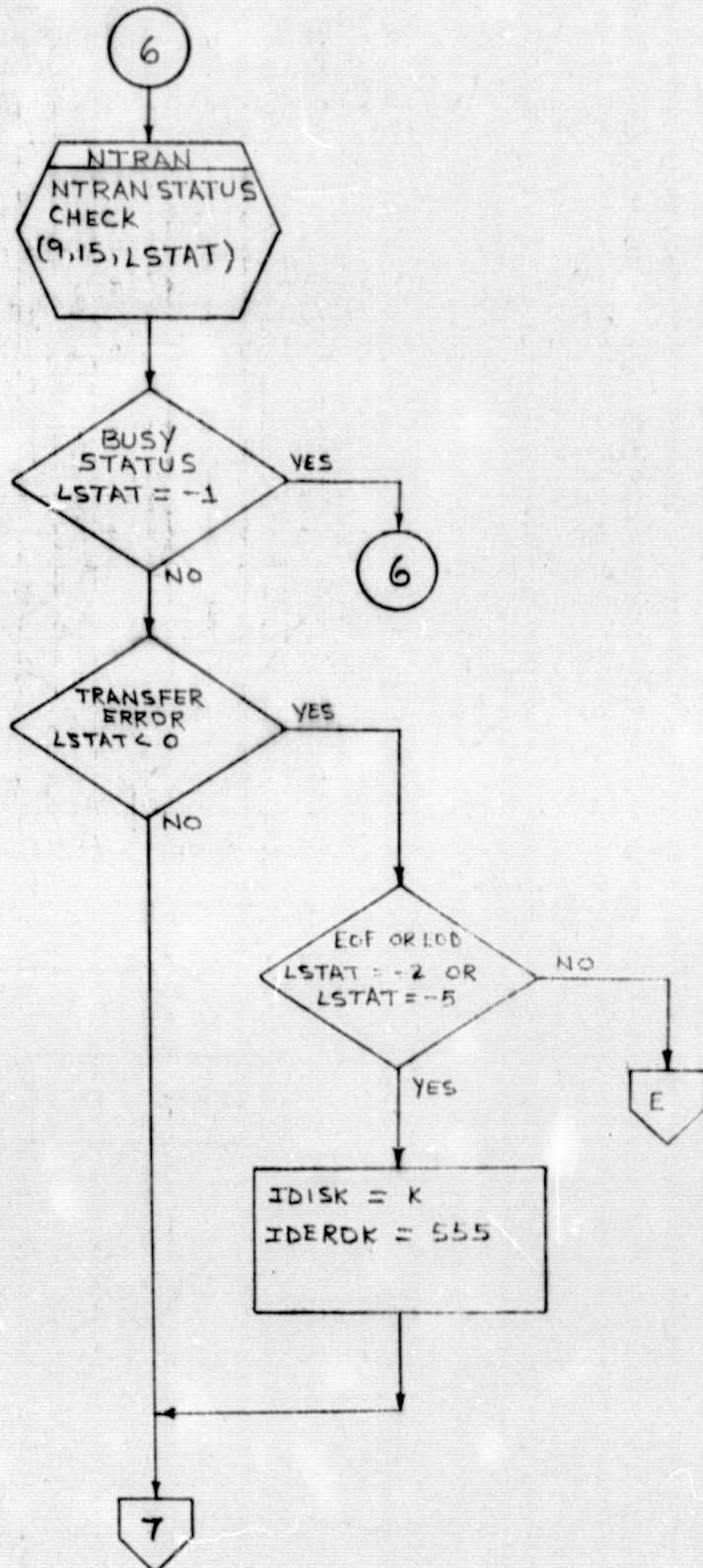
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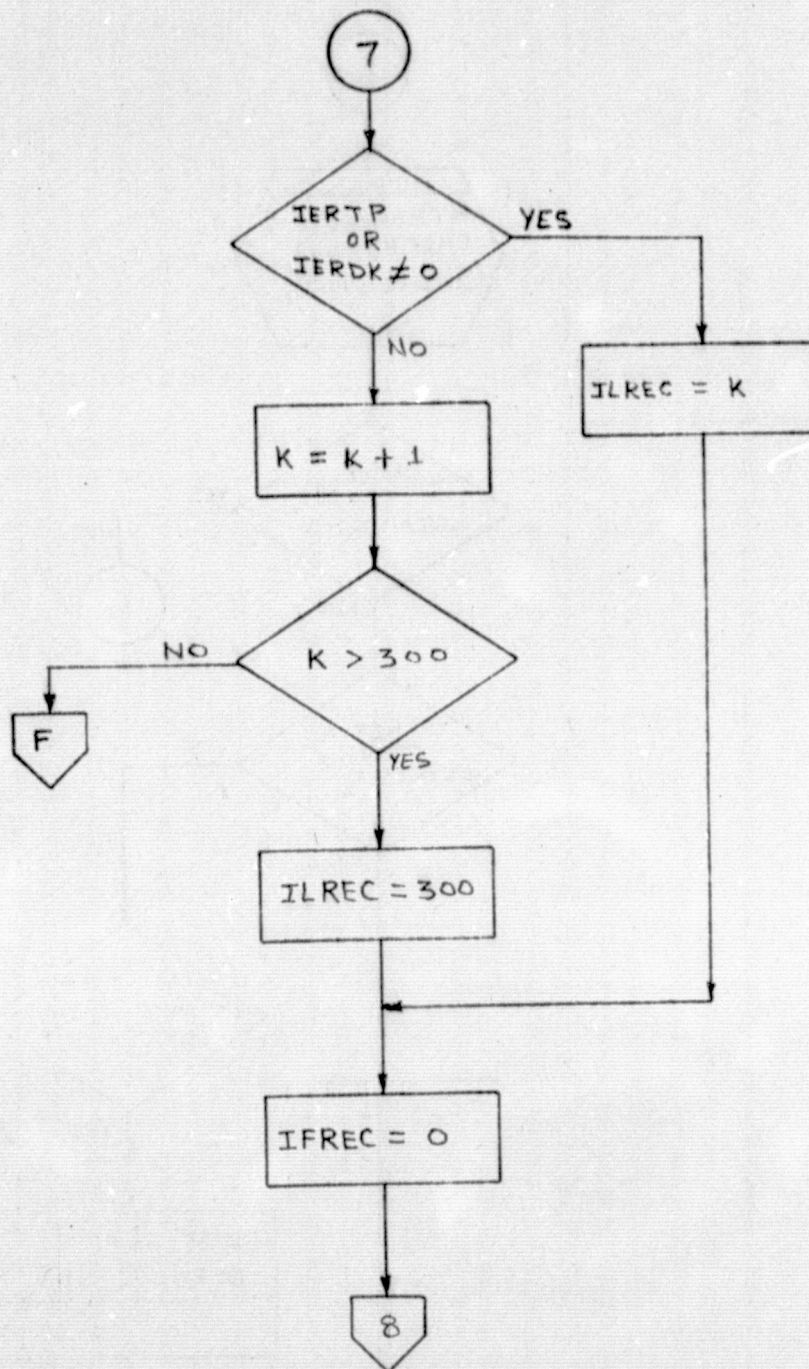




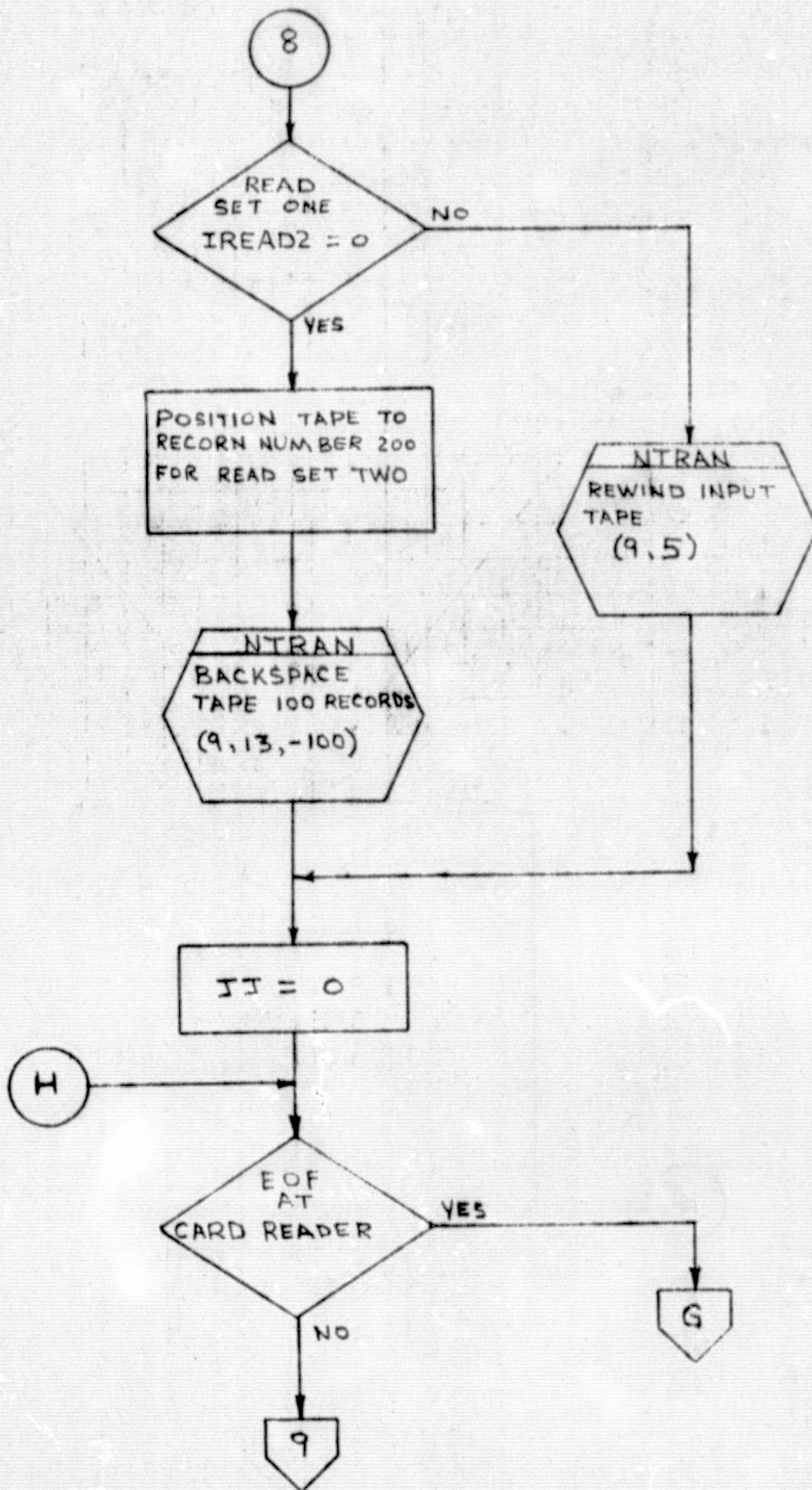
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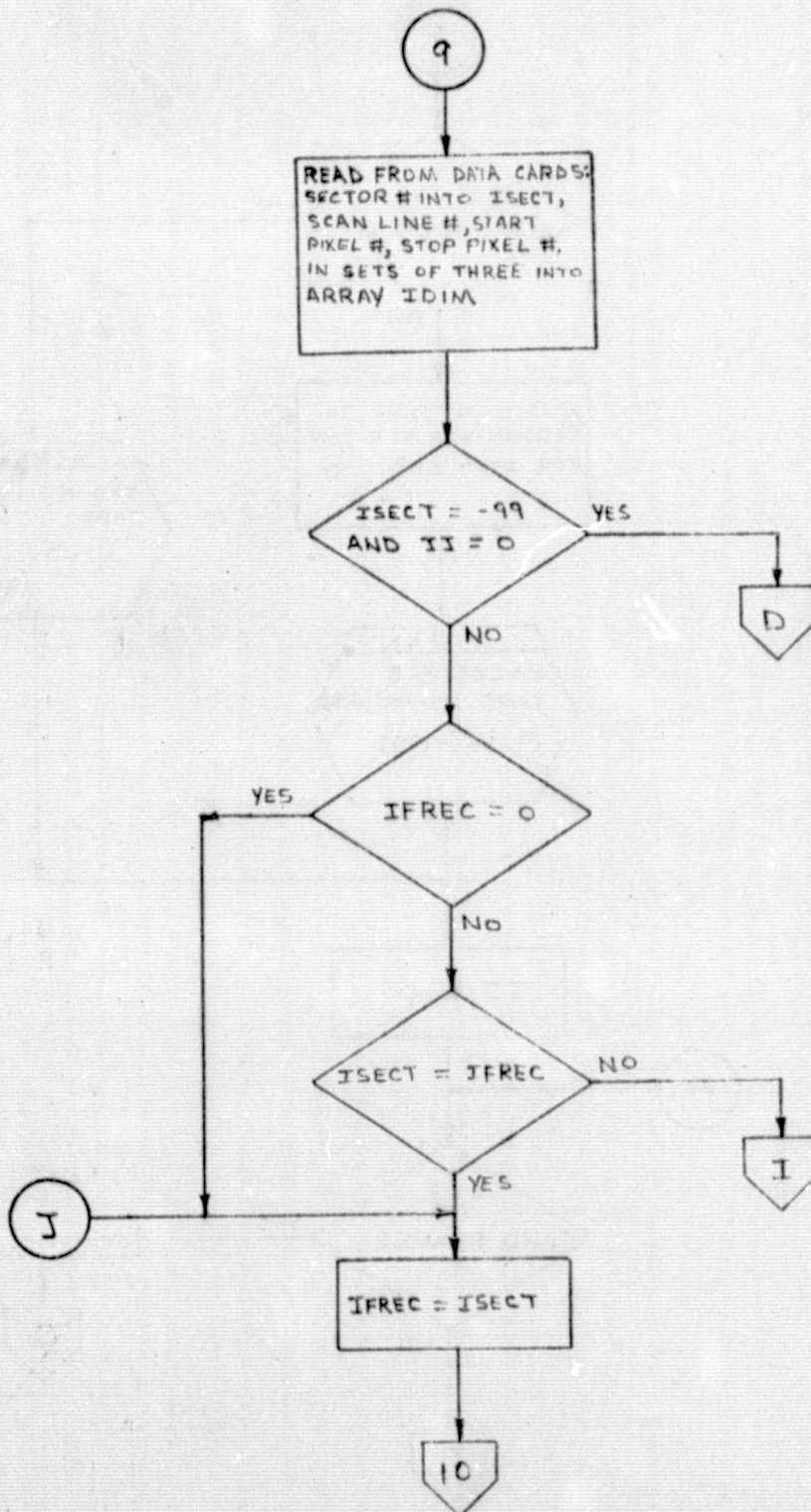




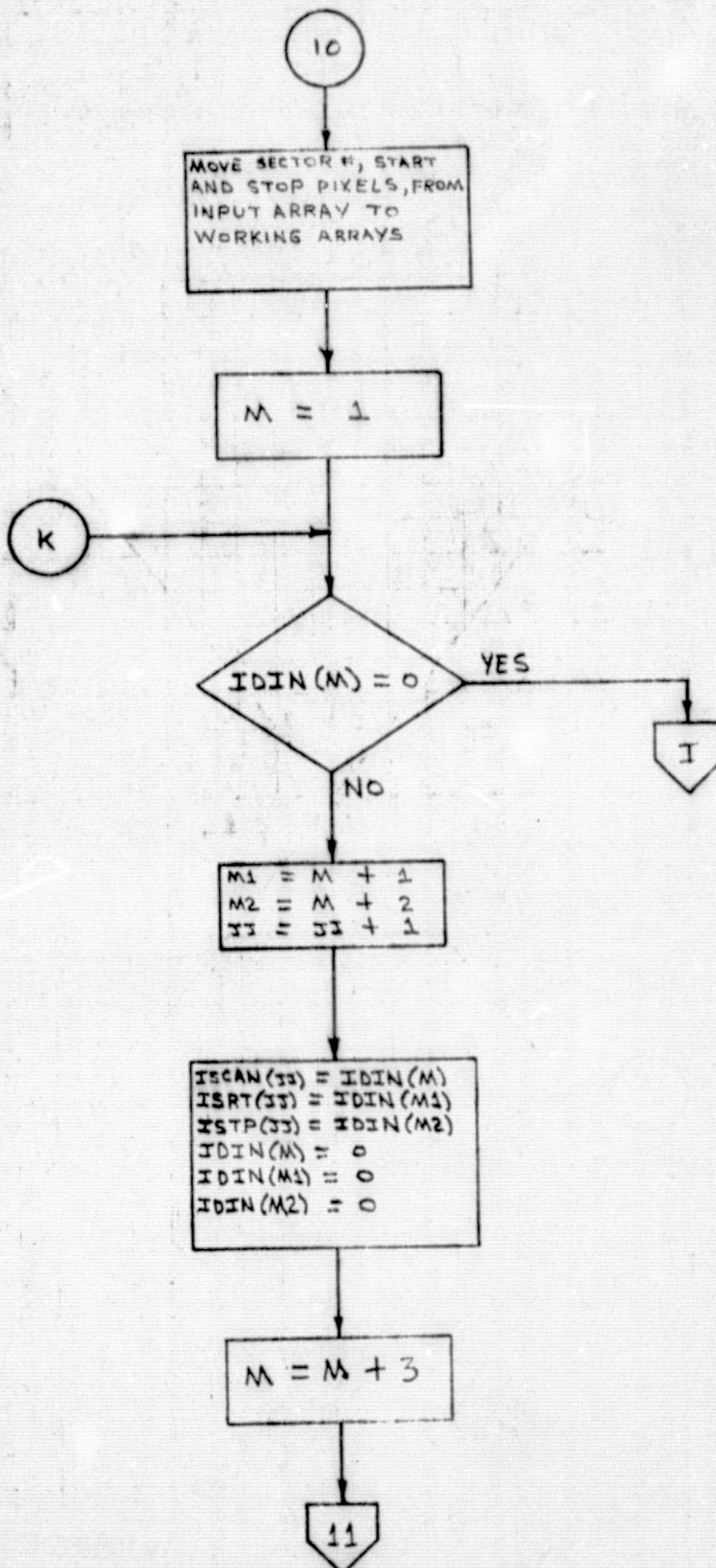
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ORIGINAL PAGE IS POOR



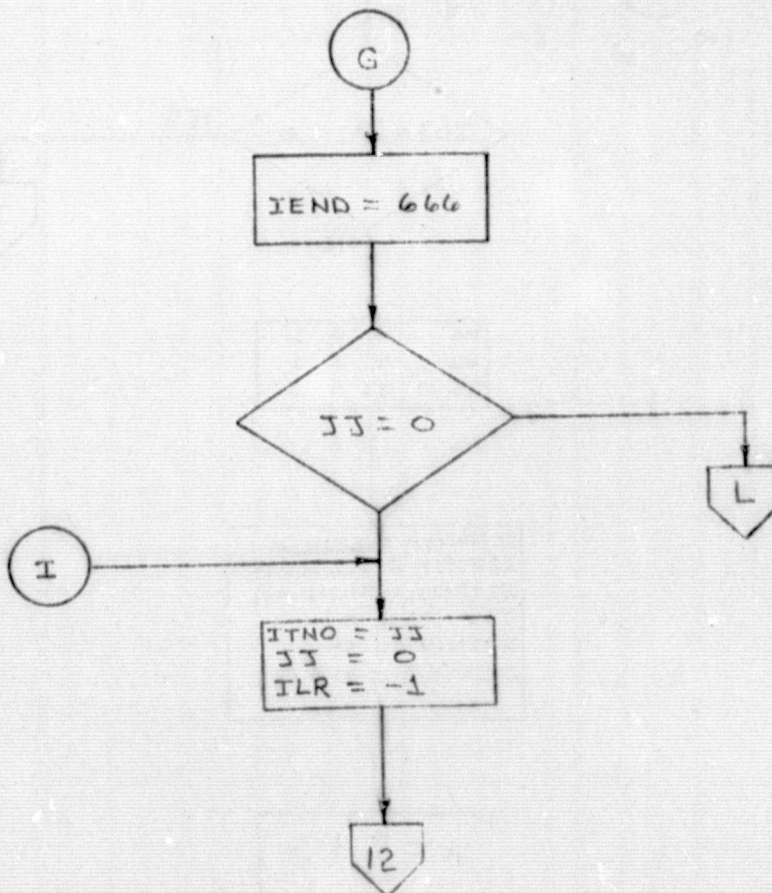
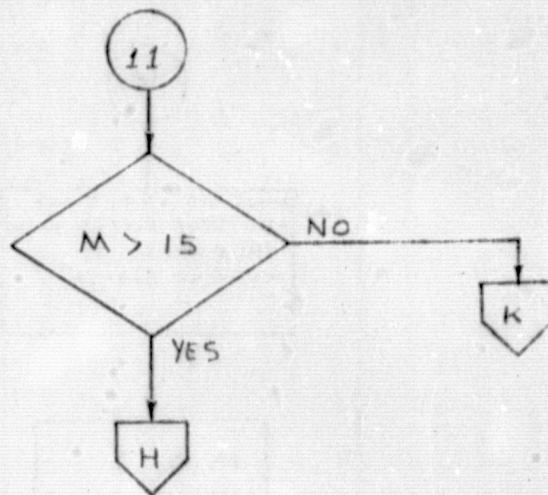




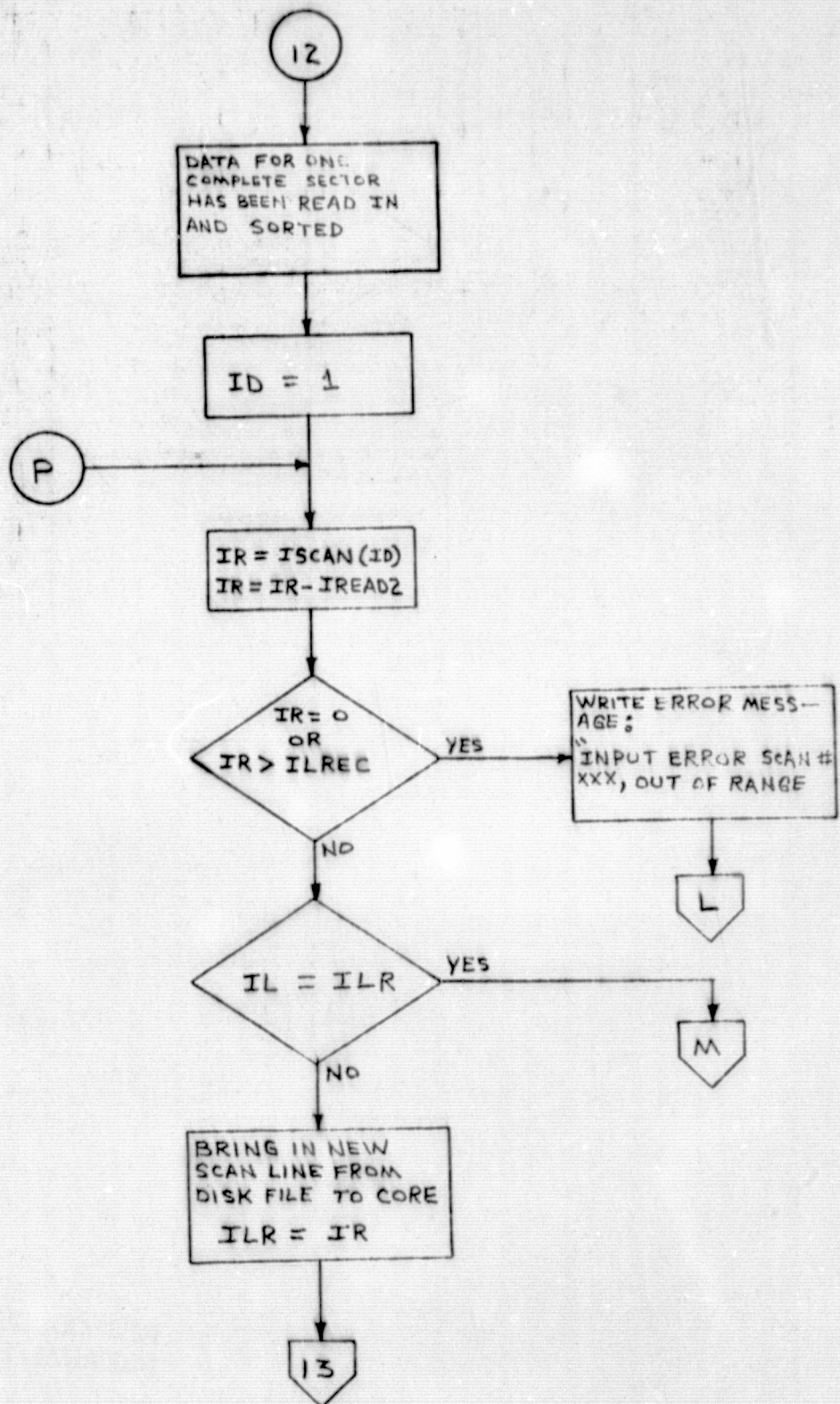
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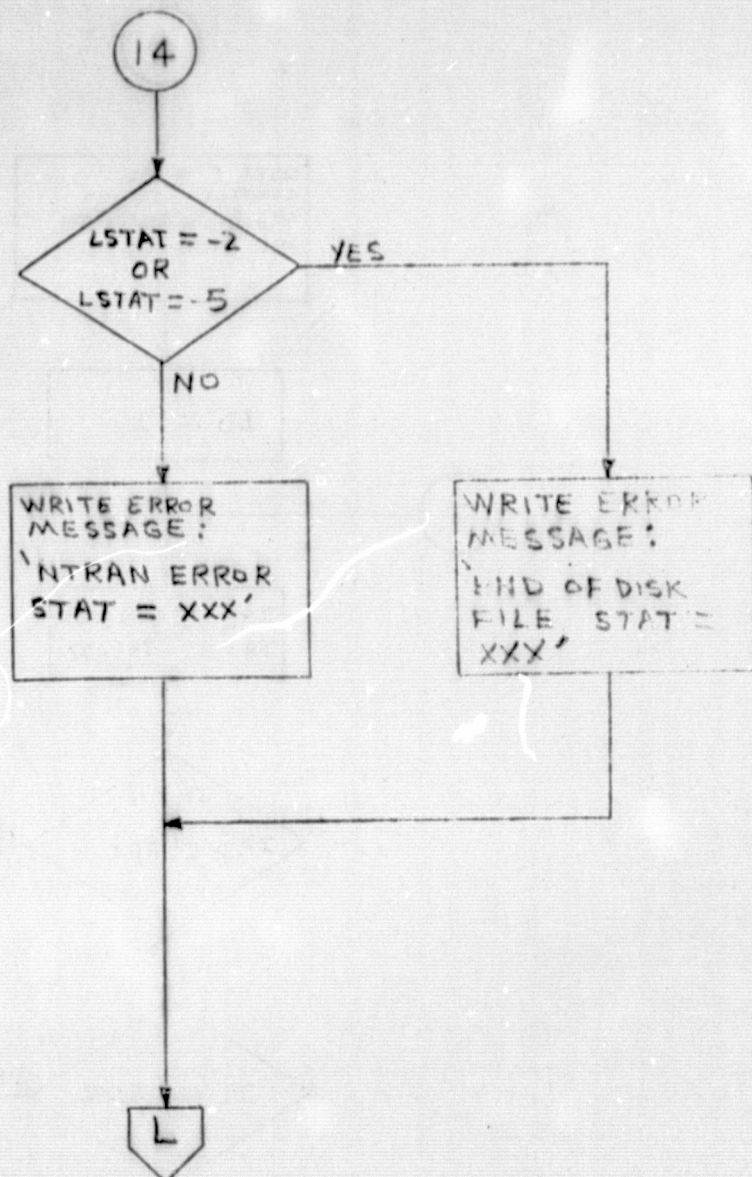




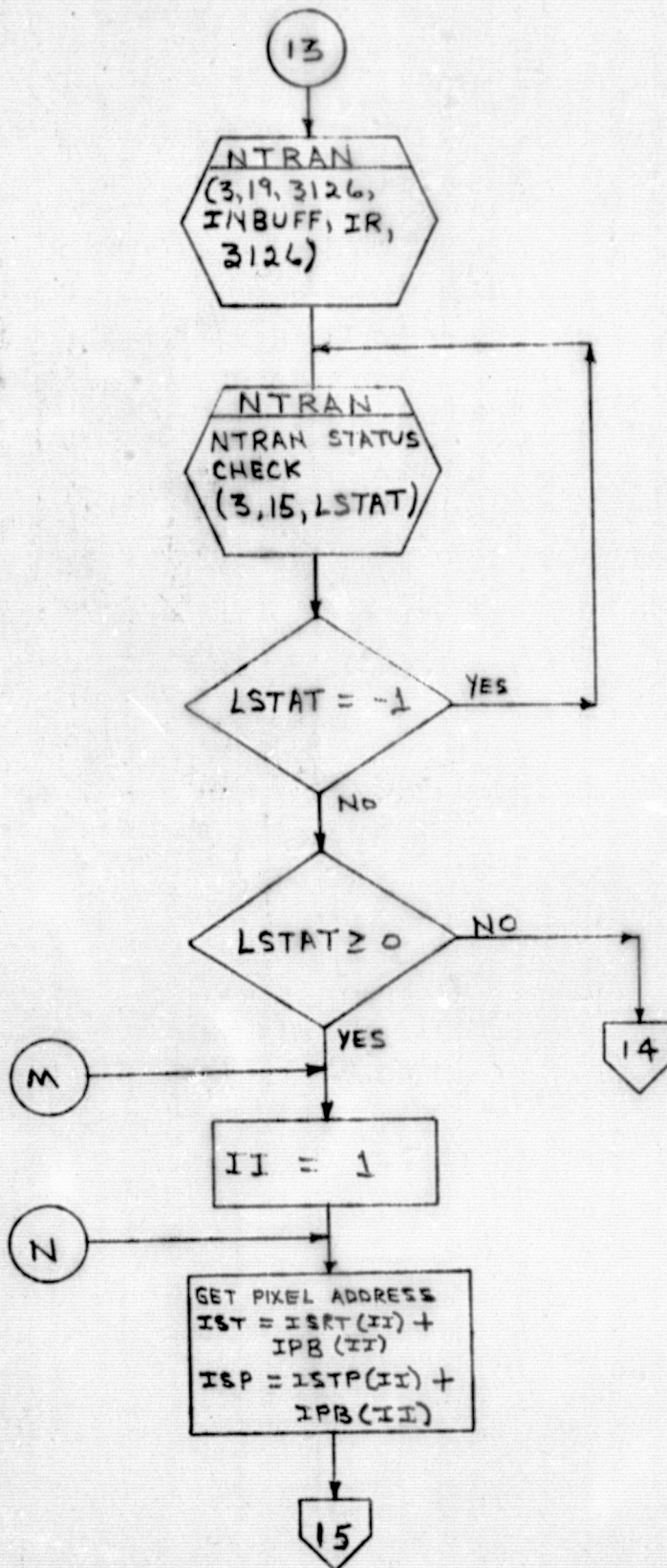
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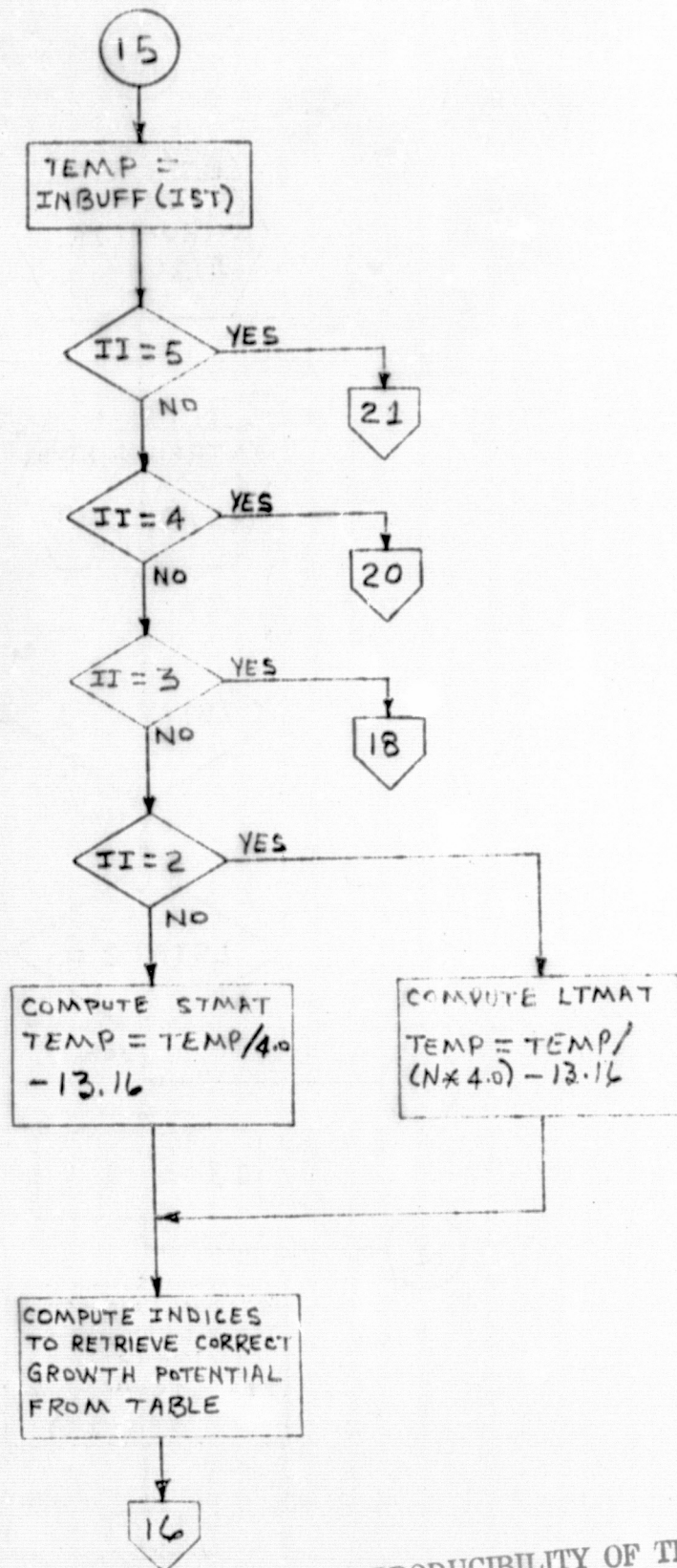




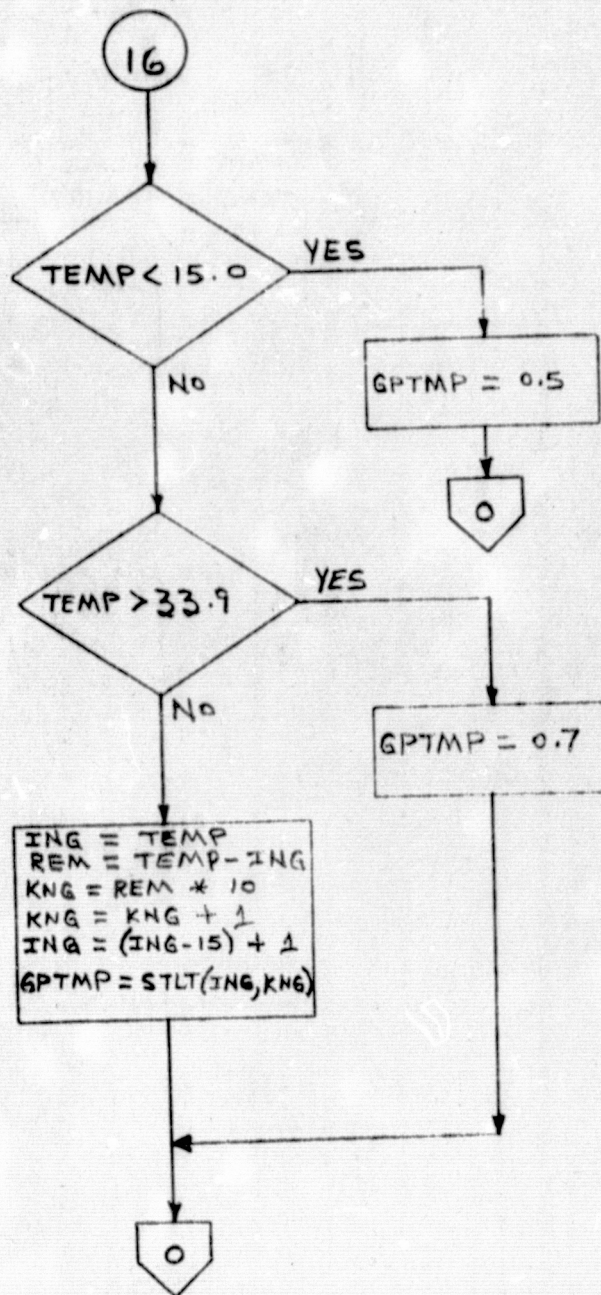
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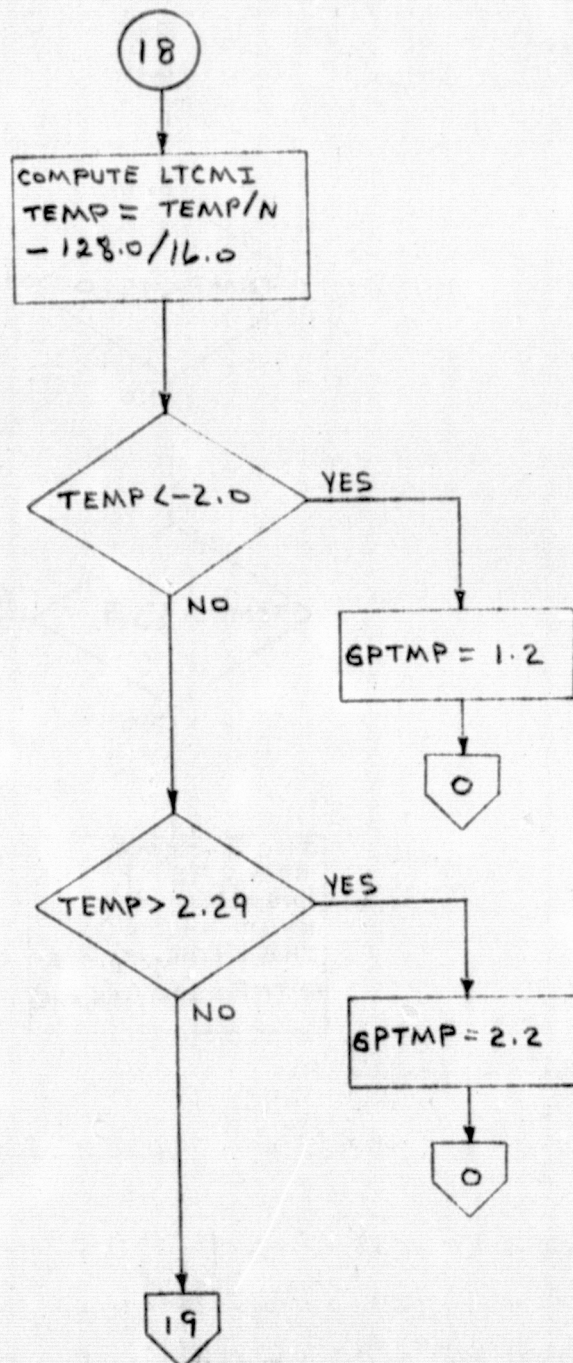




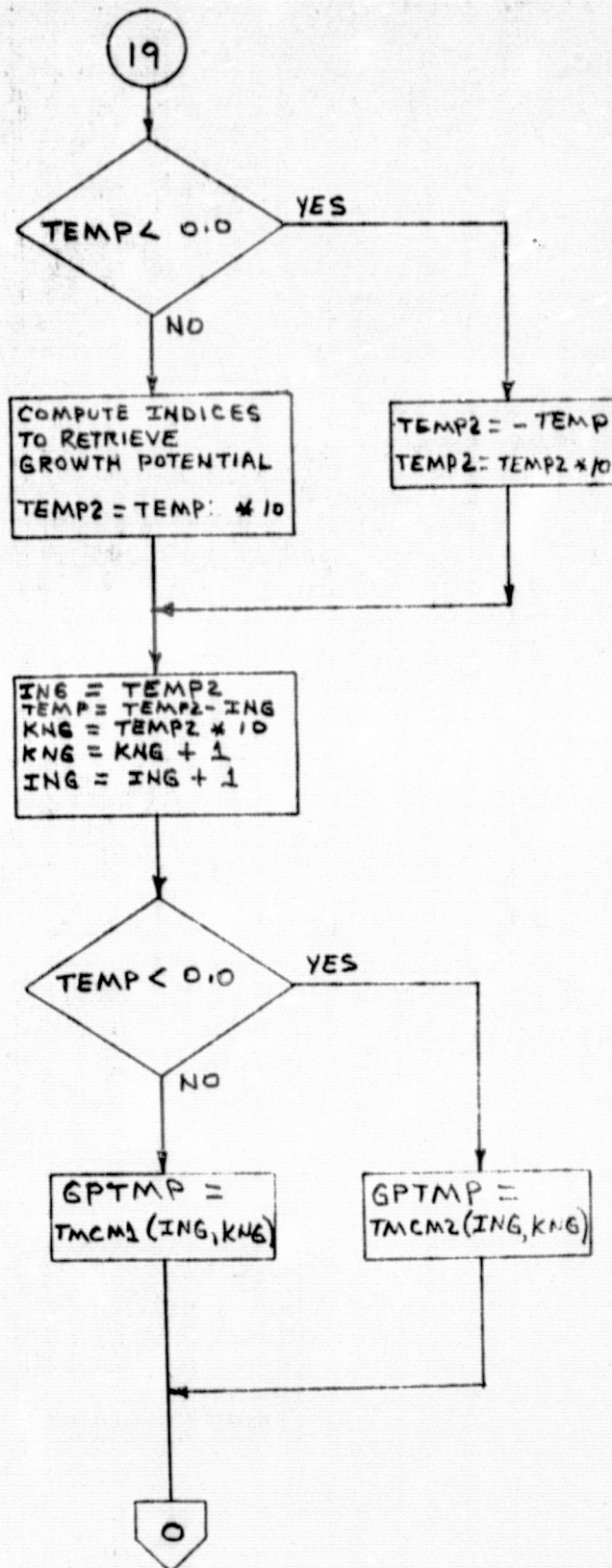
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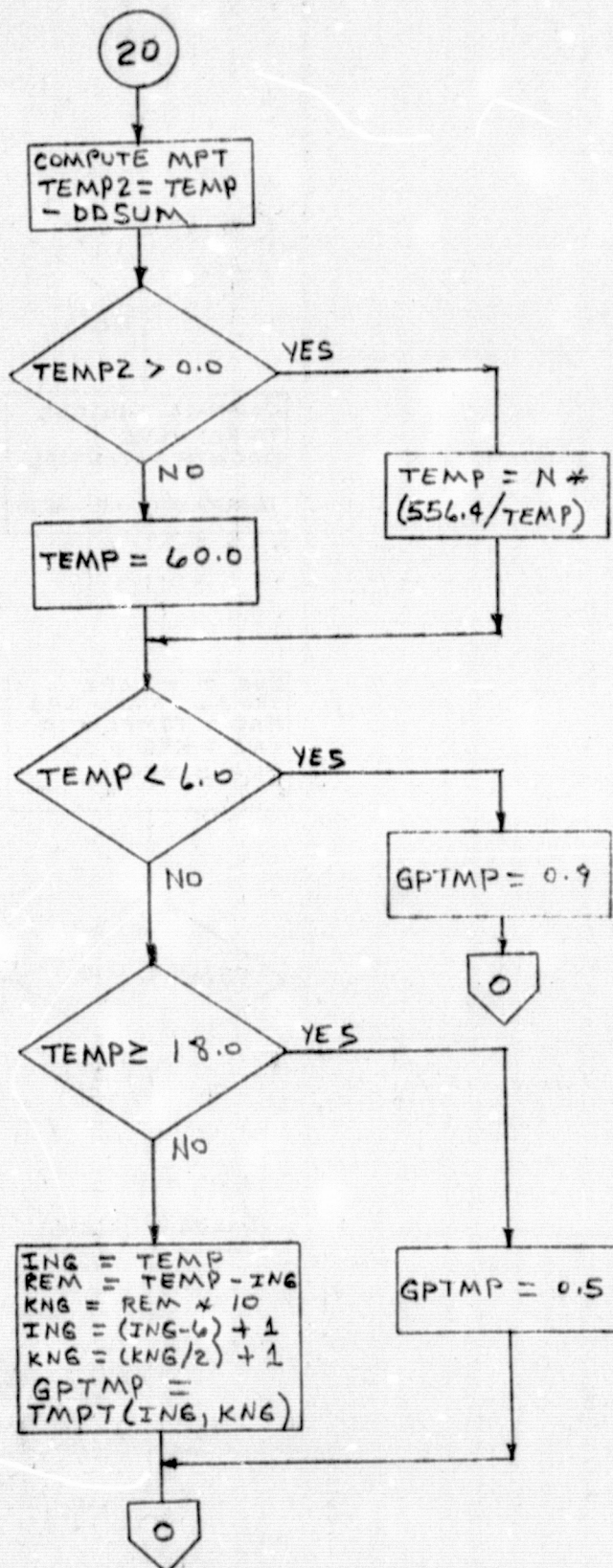




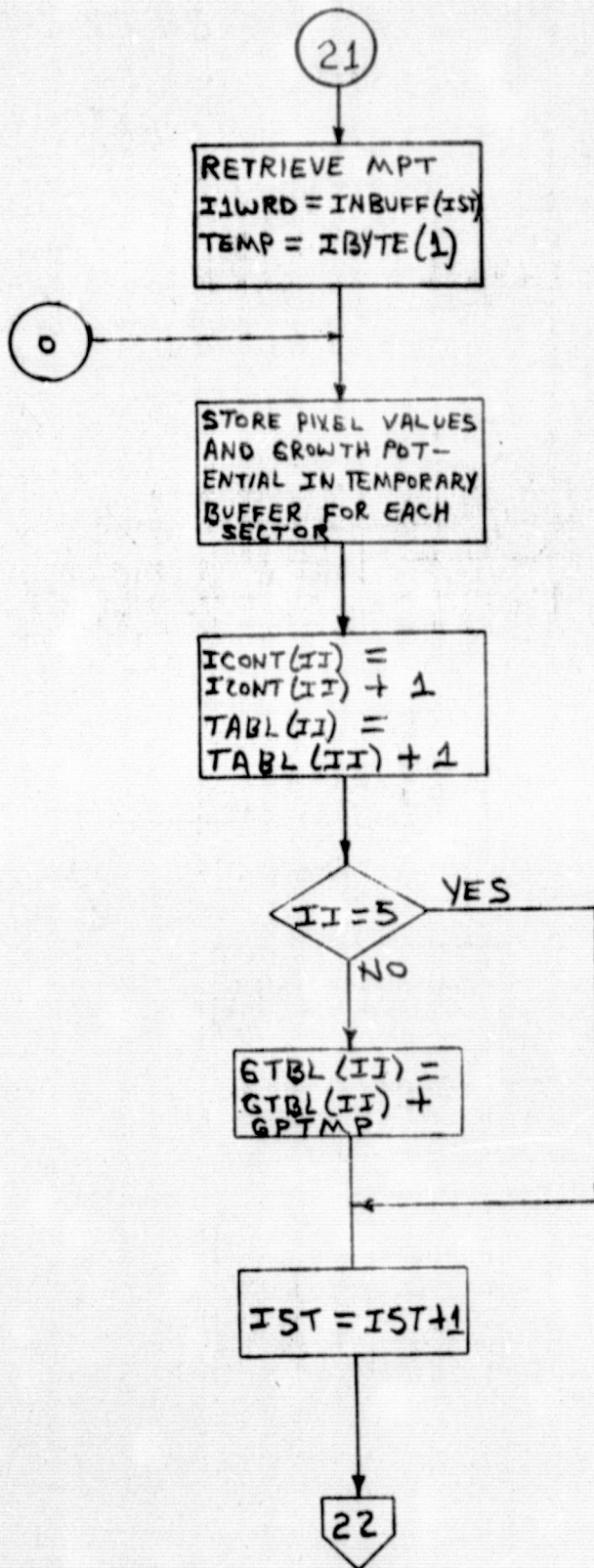
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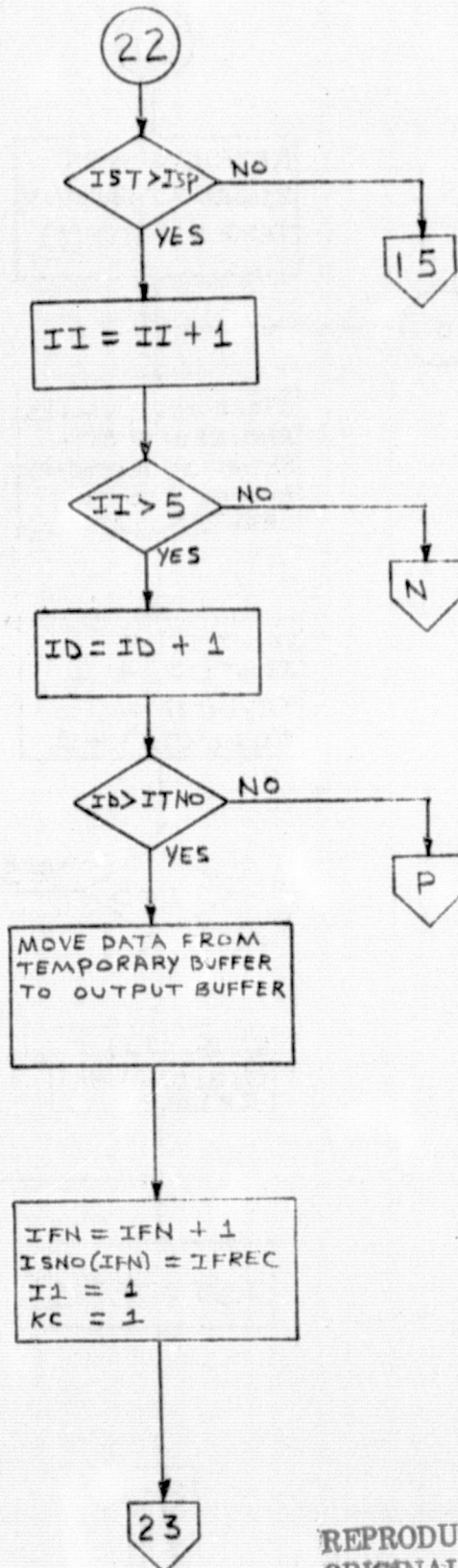




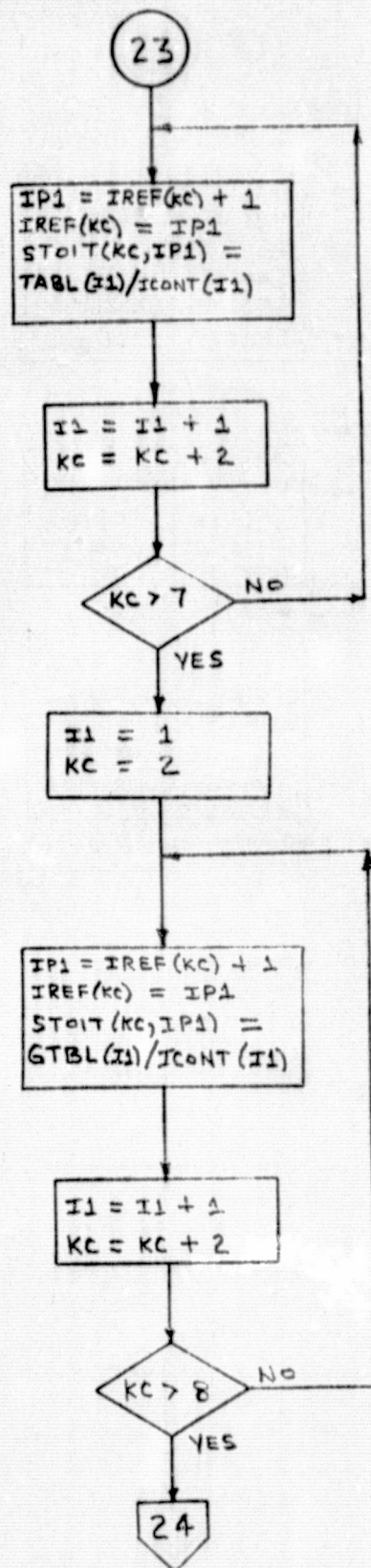
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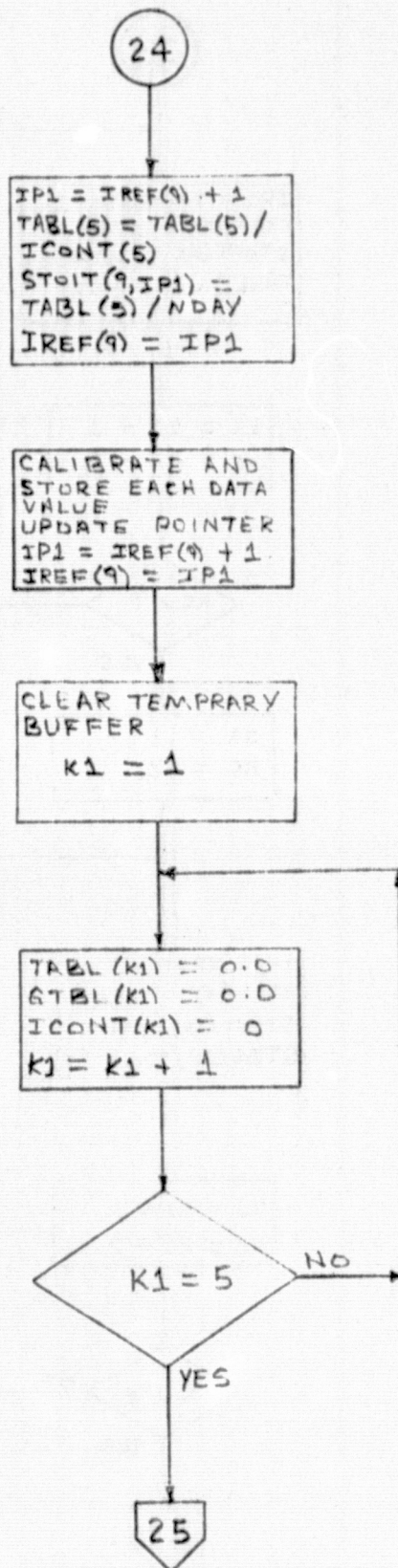


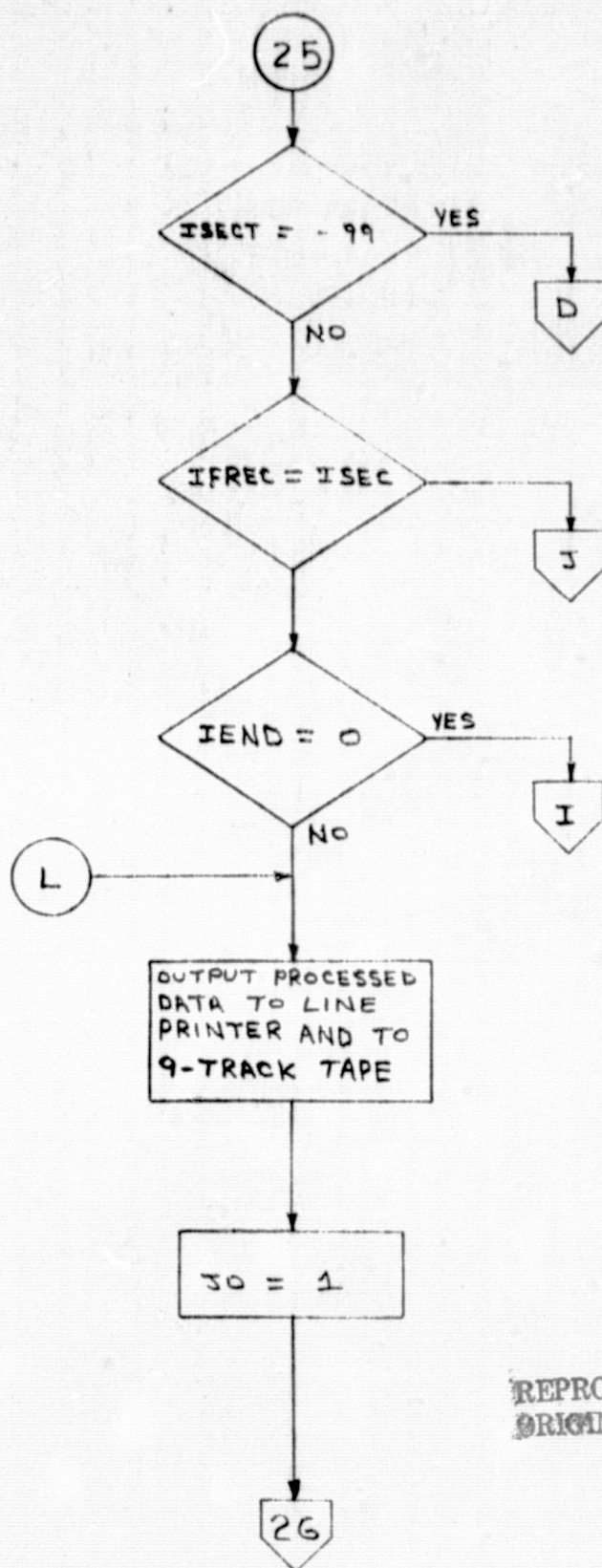


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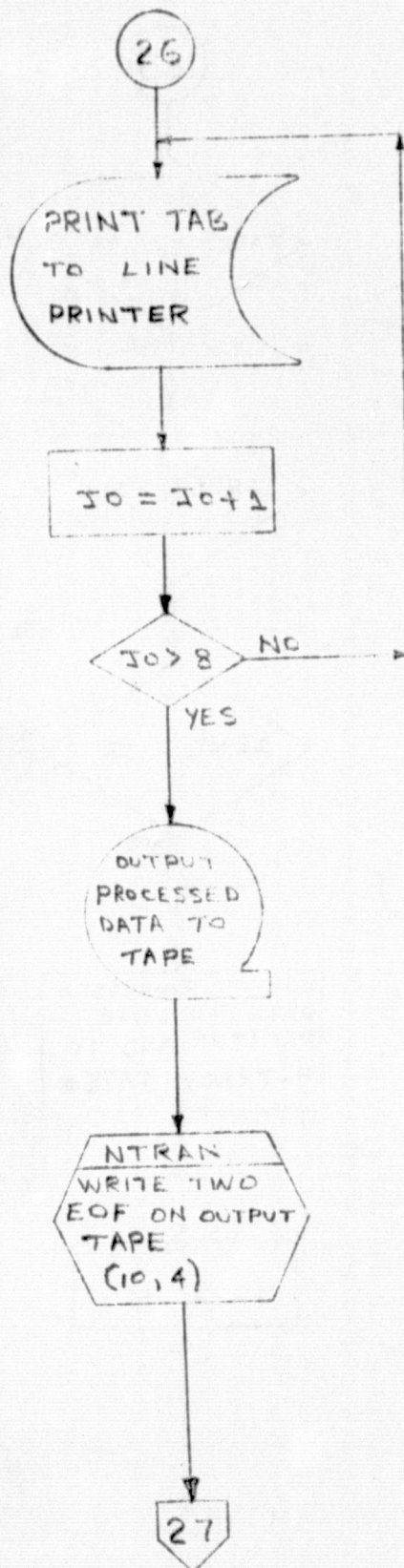




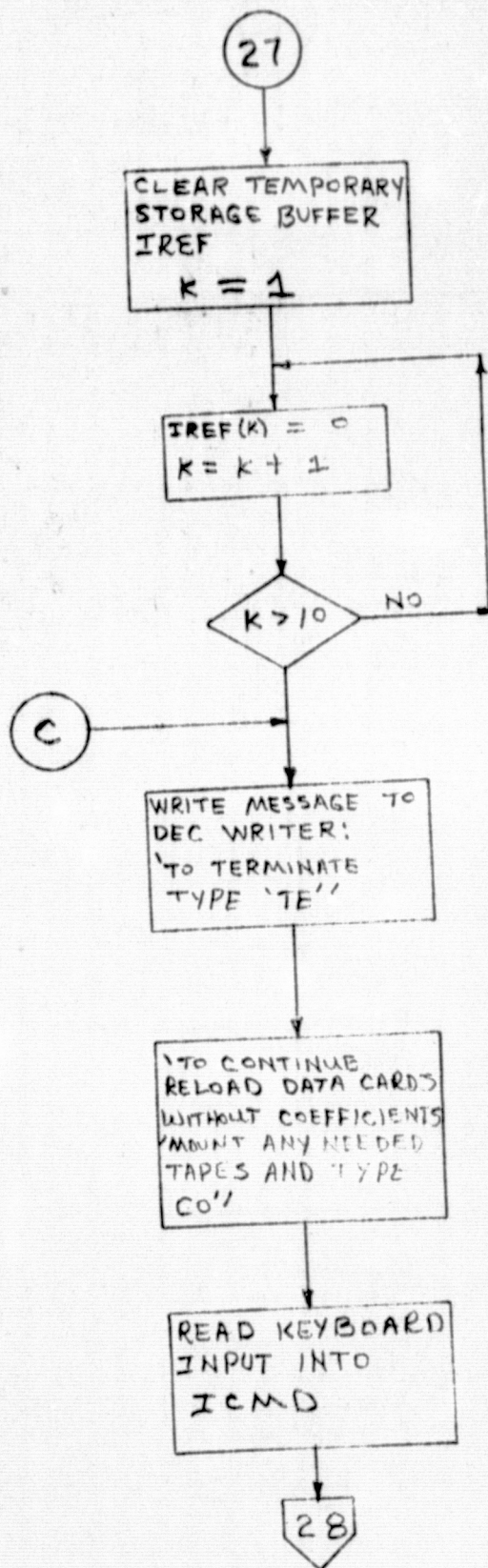




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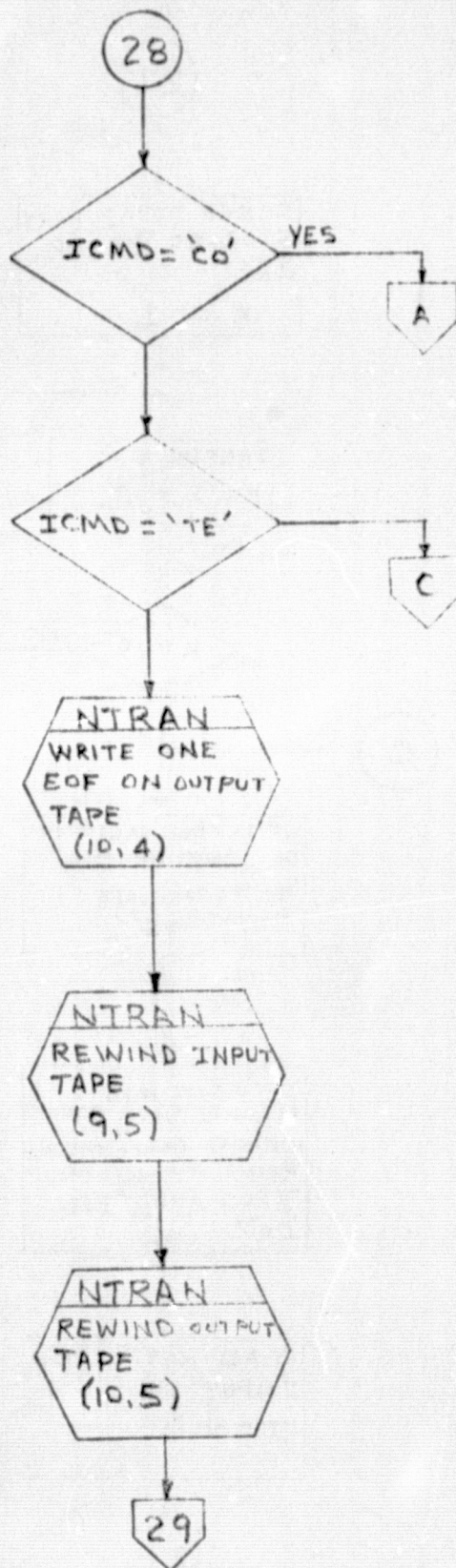


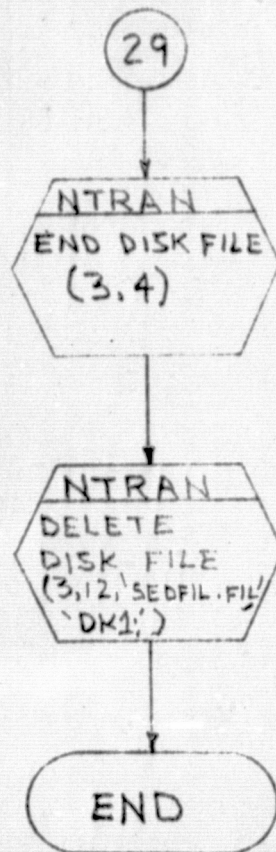




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APPENDIX A

UNIVERSAL FORMAT INFORMATION

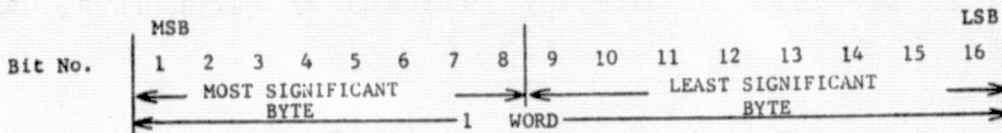
The following data is extracted from PHO-TR543, Vol. 1, Changes 1-3, dated 23 May 1973, 12 October 1973 and 22 March 1974, respectively.



## 6.0.1 IMAGERY DATA UNIVERSAL FORMAT

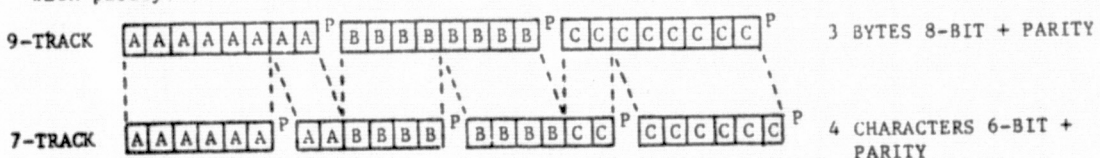
### General Ground Rules

- o Tape will be 9-track, 800 BPI, (or 556 BPI) odd parity CCT or 7-track*
- o 8 bits = 1 byte
- o Basic word size in header = 2 bytes
- o Word format will be as follows:



- o Binary Data is right justified in the field defined.
- o The header record is the first record on a tape.
- o The header record is fixed length equal 3060 bytes.
- o Data following the header will be arranged by data sets, where a data set is defined as the ancillary data and all of the video data for one scan line for all active channels.
- o Data sets will be recorded in variable length physical records, not to exceed 3000 bytes of information per record. Note, since 3000 bytes is not compatible with the word lengths of all computers, the computer generating the tape will add a sufficient number of fill zeros to the end of the data to make the record length divisible by 32, 36, 48, and 60 bits (180 bytes). Therefore, it is possible to have a max physical record length of 3060 bytes, but under no condition will data exceed 3000 bytes.
- o Data sets will be packed into consecutive physical records of equal length. Under no condition will a data set begin in the middle of a physical record unless the data set can be completed in that record. If two or more records are needed for the data set, the data set will be divided but under no condition will the data for a video channel begin in the middle of a physical record unless the data for that video channel can be completed in that record. Consequently, data sets which are lengthy will be divided so that the ancillary block and video data from an integral number of channels will be in one record and remaining video data will follow in succeeding records with an integral number of channels per record. Fill zeros will be supplied at the ends of the records as required to satisfy the equal length constraint noted above.

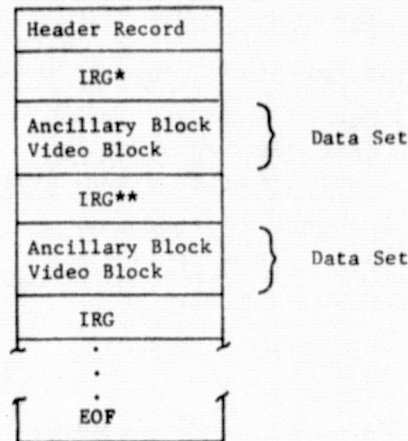
* The universal tape format was designed as though only 9-track tapes would be written and read. If a 7-track tape output is required, the information given in the universal format as 8-bit bytes is translated into 6-bit characters. This is accomplished by converting three 8-bit storage bytes in a serial binary mode into four 6-bit characters and writing them onto the 7-track tape together with parity.



# 6.0.1 IMAGERY DATA UNIVERSAL FORMAT (CONTINUED)

## General Ground Rules (Continued)

- o If multiple data runs are on the same tape, the runs are separated by an EOF. Each run will have its own header.
- o If a run is not completed on a tape, two EOF's are written on the tape and a new header is then written on the next tape.
- o When a run is completed and no other run follows on that tape three EOF's are written.
- o All data in the header record and ancillary blocks will be in binary unless otherwise noted.
- o The tape format will be as follows:



* IRG = Inter Record Gap - always follows the header record.

** An IRG may appear between the ancillary block and the video block so that the recording of a data set requires more than one physical record; or a physical record may contain two or more data sets, not separated by any IRG. See ground rules above and data set description following for criteria determining the placement of IRG's.

TABLE 6.0.1-1 UNIVERSAL FORMAT IMAGERY HEADER RECORD

<u>BYTE NO.</u>	<u>DESCRIPTION</u>	<u>NO. OF BYTES</u>
1-32	Computing System ID - EBCDIC  Computing System producing this tape, i.e., ERIPS, PREPROC., PRODUCTION, etc.	32
33-52	Tape Library ID - EBCDIC	20
53-60	Sensor ID - EBCDIC  S192, MSS, ERTS, etc.	8
61-63	Date of this tape generation  Day of month - Binary Month Number - Binary Year - Last 2 digits - Binary	1 1 1
64	Tape Sequence ID - Binary first tape reel = 1	1
65-66	Mission No. - Binary	2
67-68	Site - Binary	2
69	Line - Binary	1
70	Run - Binary	1
71-72	Orbit - Binary	2
73-80	Time of first scan in this job  Tenths of millisec - Binary Seconds - Binary Minutes - Binary Hours - Binary Day of month - Binary Month Number - Binary Year - Last 2 digits - Binary Contents of these bytes should remain constant throughout job.	2 1 1 1 1 1 1 1
81-88	Channels active in this job - up to 64 channels, 1 BIT/CH starting left to right (MSB to LSB), 1 - active, video data always appears in the order indicated here.	8

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TABLE 6.0.1-1 UNIVERSAL FORMAT IMAGERY HEADER RECORD (Continued)  
Header Record (Continued)

<u>BYTE NO.</u>	<u>DESCRIPTION</u>	<u>NO. OF BYTES</u>
89	Processing flag 0 = Raw Data 1 = Processed data from computing system	1
90	No. of channels in this job	1
91	No. of bits in a picture element	1
92-93	Byte location of start of video data within scan.	2
94-95	Byte location of start of first calibration area within the scan.	2
96-97	No. of video elements per scan within a single channel.	2
98-99	No. of calibration elements in the first calibration area within the scan in a single channel.	2
100-101	Physical record size in bytes This number must be a multiple of 180 bytes.	2
102	No. of channels per physical record This field refers to the second and subsequent records within the recording of a data set. Bytes 1785-1786 give the number of channels of data in the first record of a data set. if no. elements per channel greater than 3K this field will equal 0.	1
103	No. of physical records per scan per channel. This field is used only when the no. of elements per channel is greater than 3K. Otherwise it is equal to 0.	1
104	No. of records to make a complete data set.	1
105-106	Length of ancillary block in bytes	2
107	Data Order Indicator 0 = Video ordered by channel. 1 = Video ordered by pixel	1
108-109	Start Pixel No. Number of the first pixel per scan on this tape referenced to original image. The first pixel in the original image is pixel number one.	2
110-111	Stop Pixel No. Number of the last pixel per scan on this tape referenced to original image.	2

TABLE 6.0.1-1 UNIVERSAL FORMAT IMAGERY HEADER RECORD (Continued)

<u>BYTE NO.</u>	<u>DESCRIPTION</u>	<u>NO. OF BYTES</u>
112-239	A ₀ Coefficient (2 bytes* per channel)	128
240-367	E ₀ Exponent (2 bytes* per channel)	128
368-495	A ₁ Coefficient (2 bytes* per channel)	128
496-623	E ₁ Exponent (2 bytes* per channel)	128
	To convert parameter value (C) to engineering units (Y)	
	$Y = A_0 * 10^{E_0} + C * A_1 * 10^{E_1}$	
624-687	Color Code Information	64
	1 Byte/Channel in same order as 'Channel Active on this Tape' Indicator.	
	0 = Not Active	
	1 = Red	
	2 = Green	
	3 = Blue	
688-751	Scale Factor	64
	1 Byte/Channel in same order as 'Channel Active on this Tape' Indicator.	
752	Offset Constant	1
753	Word size of generating computer	1
	Gives size of smallest quantity in bits that machine can write on tape.	
754-1777	Wavelength of Each Channel	1024
	8 Bytes per limit, 16 Bytes per channel EBCDIC wavelength will be specified in milli-microns.	
1778	Number of Data Sets per Physical Record	1
1779-1780	Address of start of second calibration within scan. If the scan has only one calibration area, this field will contain zeros.	2
1781-1782	Number of calibration elements in the second calibration area within the scan in a single channel. If the scan has only one calibration area, this field will contain zeros.	2
1783	Calibration source indicator	1
	LSB = second calibration area	
	LSB + 1 = first calibration area	
	0 = low calibration source data present	
	1 = high calibration source data present	

* Most significant bit is a sign bit: 0 = +, 1 = -.  
 Remaining 15 bits are straight binary.

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TABLE 6.0.1-1 UNIVERSAL FORMAT IMAGERY HEADER RECORD (Continued)

<u>BYTE NO.</u>	<u>DESCRIPTION</u>	<u>NO. OF BYTES</u>
1784	Fill Zero	1
1785-1786	Number of channels in the first physical record of the data set	2
1787-1788	Total number of bytes per scan per channel	2
1789-1790	Pixel skip factor - the quantity to be added to the number of the last pixel processed to yield the number of the next pixel to be processed; 1 = process every pixel, 2 = process every second pixel, etc.	2
1791-1792	Scan skip factor - the quantity to be added to the number of the last scan processed to yield the number of the next scan to be processed; 1 = process every scan, 2 = process the second scan, etc.	2
1793-2940	General Information Information in EBCDIC generated to satisfy user requirements. Content will be unique for each user and will depend not only on the sensor but also on the specifications of the user for whom the tape is generated. Bytes for which user specifies no requirement will contain fill zeros.	
1793-2184	Fill zeros	758
2185-2550	General Annotation byte assignments for ERIPS (Not Supplied by PDP)	366
2185-2484	User Comments	300
2485-2488	Fill zeros	4
2489-2496	Latitude of pixel 1 of registered image	8
2497-2504	Longitude of line 1 of registered image	8
2505-2512	Latitude scale factor - Deg/Pixel	8
2513-2520	Longitude scale factor - Deg/Pixel	8
2521-2550	Fill zeros	30
2551-2642	General Annotation byte assignments for CYBER 73 at JSC.	92
2643-2758	Fill zeros.	116

TABLE 6.0.1-1 UNIVERSAL FORMAT IMAGERY HEADER RECORD (Continued)

<u>BYTE NO.</u>	<u>DESCRIPTION</u>	<u>NO. OF BYTES</u>
2759-2940	General Annotation Byte Assignments for the Production Film Converter	
2759*	n Thousand scan lines per frame - Binary	1
2760-2789*	Job ID - EBCDIC	30
2790-2792*	Altitude in meters - Binary	3
2793-2794*	Ground speed in meters per second - Binary	2
2795*	Scan Type - Binary	1
	0 = Linear	
	1 = Smoothed	
2796*	Angle of Arc in degrees - Binary	1
2797*	Camera - Binary	1
	0 = 70 mm	
	1 = 5-Inch	
2798*	Input Device - Binary	1
	0 = 9-TRK	
	1 = HDT	
2799*	Truncation - Binary	1
	0 = 2 LO order bits	
	1 = 2 HI order bits	
	2 = NO	
2800-2807*	Channels requested	8
	1 Bit/Channel up to 64 total channels - Binary	
2808*	Processing Mode - Binary	1
	0 = Serially	
	1 = Concurrently	
2809-2873	Overlay Image Factors - Binary	65
	$A_0, A_1, A_2 \dots A_n$ Where n = Channel number up to 64. $A_0$ is the overall factor. There is an implied decimal point to the left of the least significant decimal digit; if the MSB = 1, the number is negative; if = 0, positive.	

If values for A are not provided, the default value of A shall be "1" when processing color, "1/n" when processing gray shade, and  $A_0$  shall be "0" for both. Then the resultant light intensity for pixel P with input light intensity C for channel n is related by:

$$P = A_0 + (A_1 C_1 + A_2 C_2 + \dots + A_n C_n).$$

* Required for Image Processing Calculations.

TABLE 6.0.1-1 UNIVERSAL FORMAT IMAGERY HEADER RECORD (Continued)

<u>BYTE NO.</u>	<u>DESCRIPTION</u>	<u>NO. OF BYTES</u>
2759-2940	General Annotation Byte Assignments for the Production Film Converter (Continued)	
2874*	Color Select - Binary  0 = No Color 1 = Assigned Color 2 = False Color	1
2875*	Image Format - Binary  0 = Single Image 1 = Overlay Images 2 = Abut Images 3 = Offset Images	1
2876*	Repeat of Pixels per Scan - Binary  0 = None 1 = 1 Repeat 2 = 2 Repeat n = n Repeat	1
2877	Repeat of Scan - Binary  0 = None 1 = 1 Repeat 2 = 2 Repeat n = n Repeats	1
2878-2881	Partial Scan - Binary  Zeros to indicate full scan  Byte 2878-2879 = From Pixel No. Byte 2880-2881 = To Pixel No.	4
2882-2883	Sensor scan rate in scans/second - Binary	2
2884	Pixel Size - Binary	1
2885-2886	Angle of Drift - Binary Byte 2885 = $\pm$ Integer Byte 2886 = Fraction	2
2887-2940	Fill zeros	54
2941-3000	ITITLE - User Designated Identification	60
3001-3060	Fill Zeros, makes the record an integral number of computer words. These bytes must <u>never</u> contain data.	60



6.0.1 IMAGERY DATA UNIVERSAL FORMAT (Continued)

Data Sets

- o The first word (2 bytes) of every record is a counter giving the number of the physical record within the video data set. This is primarily intended for use in data sets that are greater than 3000 bytes long and therefore require more than one physical record for recording. This word will always equal "1" for the first record of a data set.
- o The first block of a data set is the ancillary block.
- o The length of the ancillary block is variable, with the number of bytes given in the header record.
- o Bytes 1 through 4 of the ancillary block will contain the current GMT at the start of this data set recorded in tenths of milliseconds.
- o Bytes 5 through 68 will indicate channel status for this scan, one byte per channel, where the LSB = 0 indicates the channel in sync, and the LSB = 1 indicates the channel not in sync.
- o Bytes 69-70 contain the scan line number. This will be an arbitrary but sequential count for each scan line that appears in the data run.
- o Bytes 71 through N will be dependent on whether this job contains raw or processed data. (See byte 89 in the header record.) The value of N will be given in bytes 105 and 106 in the header record and will always be equal to or greater than 70.
- o If this job contains raw data, bytes 71 through N will contain the housekeeping data channel from the sensor, if one is available.
- o A job containing processed data will, in addition to the 70 bytes of ancillary data already described, contain, at a minimum, the following pieces of information:
  - o Latitude of the aircraft or of the center of the image from EREP or satellite in binary.
  - o Longitude of the aircraft or of the center of the image from EREP or satellite in binary.
  - o Altitude in meters recorded in binary.
  - o Heading in tenths of a degree.
  - o Ground speed in meters per second.
  - o Roll - Defined in specific formats, following.
  - o Pitch - Defined in specific formats, following.
  - o Yaw - Defined in specific formats, following.
  - o Sun angle.

The specific formats for each sensor (following in this section) shall provide where this data will appear in the format.

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6.0.1 IMAGERY DATA UNIVERSAL FORMAT (Continued)

Data Sets (Continued)

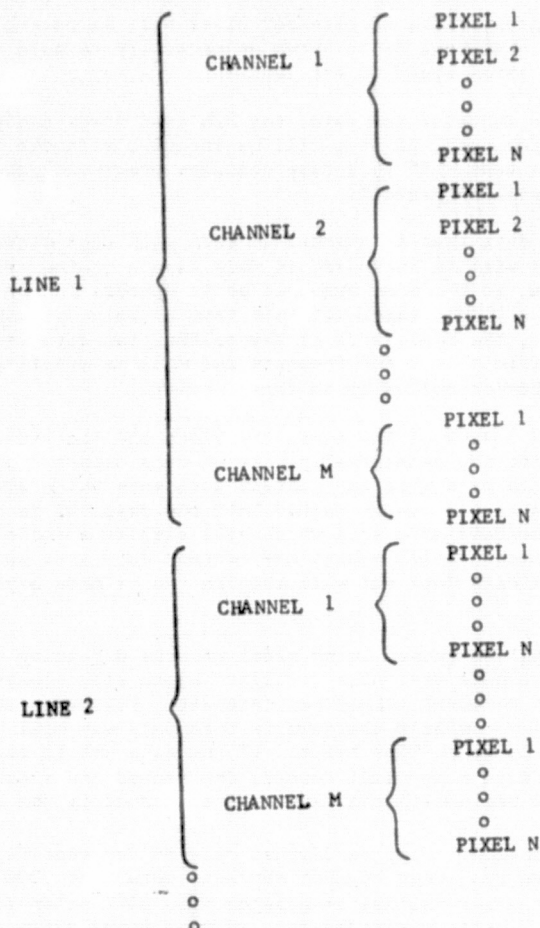
Other parameters may be added, if required, with the length of the ancillary block given in the header.

- o Following the ancillary block in each data set will be the video data from all of the active channels for one scan. The video data from all of the active channels for one scan will comprise a video block.
- o Video blocks within a data run will always contain the same number of video channels.
- o Each video block will be the same number of bytes in length. If video data is not available to fill a block, fill zeros will be added to make it the same length as preceding video blocks.
- o Video data less than 8 bits per pixel will be packed, right justified, in an 8-bit byte with zeros added to the left.
- o Video data greater than 8 bits per pixel will be packed, right justified, in as many 8-bit bytes as necessary to hold the pixel, with zeros added to the left.
- o If this tape contains raw data, the PCM sync words associated with the video data, if any, will be included with the video data on this tape. If this tape contains processed data, no sync words will be present.
- o Calibration data that is associated with each scan within each channel will be included, if this tape contains raw imagery data, in the same sequence as it appears in the data stream on the flight tape. If this tape contains processed imagery data, the appearance of the calibration data will depend on the specific sensor requirements and will be specified in the respective format following in this document.
- o The combined length of the ancillary block and the video block will determine the relationship between data sets and physical records. Some data runs may contain data sets which are so small more than one can be packed into one physical record. Others may contain data sets which will require a whole physical record for each. Still others may contain data sets which are so long that each data set will require two or more physical records.
- o Data sets will be packed in physical records depending on the length of the data set. The ancillary block will always appear in the first physical record per data set. Following the ancillary block, as many complete channels in this data set will be recorded as will fit in up to 3000 bytes. If the data set is too long to be recorded in one physical record, the second and subsequent records will begin with the next active channel in the data set.
- o A video channel will not be divided between two records unless a single scan from that channel contains more than 3000 bytes. If a scan from any channel is greater than 3000 bytes in length, then the scan will be divided into as many equal parts as is necessary to allow each part to equal less than 3000 bytes and therefore, fit into a physical record with max length 3000 bytes.

6.0.1 IMAGERY DATA UNIVERSAL FORMAT (Continued)

Data Sets (Continued)

- o If a video block is divided between more than one record for recording, the number of data channels in the first record may vary from the number of channels in the second and successive records; however, the number of channels in all records following the first per data set will always be the same. The number of channels in the first record and the number in successive records will be given in the header record. In records following the first, if video data is not available so as to allow all records to contain the same number of channels, fill zeros will be added in lieu of the video data in order to make all records the same length. In addition, fill zeros will be added to either the first record or all of the successive records, depending on which is shorter, so as to make all of the records the same length.
- o The normal arrangement of pixels within a scan of data will be by channel. The Universal format* will be as follows:



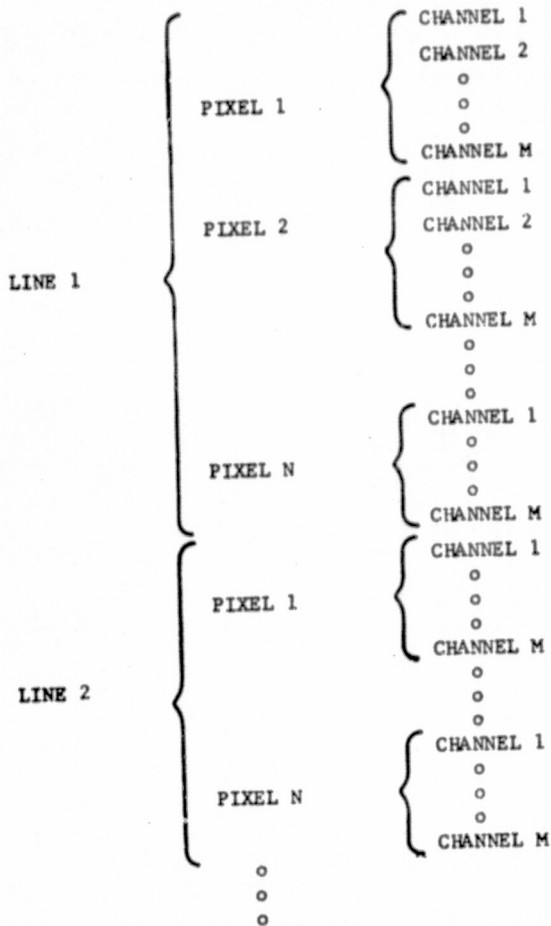
*If this tape contains raw imagery data, the PCM sync words, if any, that are associated with the data on the flight tape will be included with the data.



6.0 1 IMAGERY DATA UNIVERSAL FORMAT (Continued)

Data Sets (Continued)

- o When conflicts arise such that channel arrangement of the scan data can not be accomplished, the data will be arranged by pixel. This arrangement will be discouraged. The Universal format* for this arrangement will be as follows:



* If this tape contains raw imagery data, the PCM sync words, if any, that are associated with the data on the flight tape will be included with the data.